

CAUCHY PROBLEM FOR HYPERBOLIC OPERATORS WITH TRIPLE EFFECTIVE CHARACTERISTICS ON THE INITIAL PLANE

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Abstract

We study the Cauchy problem for effectively hyperbolic operators P with triple characteristics points lying on the initial plane $t = 0$. Under some conditions on the principal symbol of P one proves that the Cauchy problem for P in $[0, T] \times \Omega \subset \mathbb{R}^{n+1}$ is well posed for every choice of lower order terms. Our results improves those in [11] since we do not assume the condition (E) of [11] to be satisfied.

1. Introduction

In this paper we study the Cauchy problem for a differential operator

$$P(t, x, D_t, D_x) = \sum_{k+|\alpha| \leq 3} c_{k,\alpha}(t, x) D_t^k D_x^\alpha, \quad D_t = -i\partial_t, \quad D_{x_j} = -i\partial_{x_j}$$

of order 3 with smooth coefficients $c_{k,\alpha}(t, x)$, $t \in \mathbb{R}$, $x \in \Omega \subset \mathbb{R}^n$, $c_{3,0} \equiv 1$. Denote by

$$p(t, x, \tau, \xi) = \sum_{k+|\alpha|=3} c_{k,\alpha}(t, x) \tau^k \xi^\alpha = \tau^3 + q_1(t, x, \xi) \tau^2 + q_2(t, x, \xi) \tau + q_3(t, x, \xi)$$

the principal symbol of P . Throughout the paper we work with symbols $s(t, x, \xi) \in S_{1,0}^m(\Omega \times \mathbb{R}^n)$ of pseudo-differential operators which depend smoothly on $t \in [0, T]$ and we use the Weyl quantization (see [3])

$$s(t, x, D)u = (\text{Op}^w(s)u)(t, x) = (2\pi)^{-n} \int \int e^{i\langle x-y, \xi \rangle} s\left(t, \frac{x+y}{2}, \xi\right) u(t, y) dy d\xi.$$

We will use the notation $S_{1,0}^m$ for the class of symbols (see [3]) and we abbreviate $S_{1,0}^m$ to S^m and $\text{Op}^w(s)$ to $\text{Op}(s)$.

With a real symbol $\varphi \in S_{1,0}^0$ one can write

$$(1.1) \quad \begin{aligned} P = & (D_t - \text{Op}(\varphi)\langle D \rangle)^3 + \text{Op}(a)\langle D \rangle (D_t - \text{Op}(\varphi)\langle D \rangle)^2 - \text{Op}(b)\langle D \rangle^2 (D_t - \text{Op}(\varphi)\langle D \rangle) \\ & + \text{Op}(c)\langle D \rangle^3 - \sum_{j=0}^2 \text{Op}(b_j)\langle D \rangle^j (D_t - \text{Op}(\varphi)\langle D \rangle)^{2-j} \end{aligned}$$

which is a differential operator in t . Here the symbols $a, b, c \in S_{1,0}^0$ coincide with

$$q_1\langle \xi \rangle^{-1} + 3\varphi, \quad -(q_2\langle \xi \rangle^{-2} + 2\varphi q_1\langle \xi \rangle^{-1} + 3\varphi^2), \quad q_3\langle \xi \rangle^{-3} + \varphi q_2\langle \xi \rangle^{-2} + \varphi^2\langle \xi \rangle^{-1} + \varphi^3,$$

respectively, $b_j \in S^0_{1,0}$, $j = 0, 1, 2$ (see [3]), and $\langle D \rangle$ has symbol $\langle \xi \rangle = (1 + |\xi|^2)^{1/2}$.

First we assume that the principal symbol

$$(1.2) \quad p(t, x, \tau, \xi) = (\tau - \varphi(\xi))^3 + a(\xi)(\tau - \varphi(\xi))^2 - b(\xi)^2(\tau - \varphi(\xi)) + c(\xi)^3$$

is hyperbolic, that is the roots of equation $p = 0$ with respect to τ are real for $(t, x, \xi) \in [0, T] \times \Omega \times \mathbb{R}^n$, where $\Omega \subset \mathbb{R}^n$ is an open set. Recall that an operator is effectively hyperbolic if the fundamental matrix $F_p(z)$ of the principal symbol p has two non-vanishing eigenvalues $\pm\mu(z)$ at every critical point z of p , where $dp(z) = 0$. An effectively hyperbolic operator in $[0, T] \times \Omega$ may have triple characteristics only for $t = 0$ or $t = T$ (see [4, Lemma 8.1]). Second we assume that p has triple characteristic points only on $t = 0$ and P is *effectively hyperbolic* at every triple characteristic points $\rho = (0, x, \tau, \xi)$ which is equivalent (see [4, Lemma 8.1]) to the condition

$$\frac{\partial^2 p}{\partial t \partial \tau}(\rho) < 0.$$

Consequently, at a triple characteristic point $\rho_0 = (0, x_0, 0, \xi_0)$, assuming $\varphi(0, x_0, \xi_0) = 0$, we have $b_t(0, x_0, \xi_0) > 0$. Moreover, at ρ_0 we have $a(0, x_0, \xi_0) = b(0, x_0, \xi_0) = c(0, x_0, \xi_0) = 0$.

Our purpose is to study the Cauchy problem for such P and to prove that under some conditions on p this problem is well posed for every choice of lower order terms (see [11] for the definition of well posed Cauchy problem). This property is called *strong hyperbolicity* and the effective hyperbolicity of P is a necessary condition for it (see [4, Theorem 3]). For operators having only double characteristics every effectively hyperbolic operator is strongly hyperbolic and we refer to [9] for the references and related works. The conjecture is that effectively hyperbolic operators with triple characteristic points on $t = 0$ are strongly hyperbolic (see [4], [6], [1], [11]). On the other hand, for some class of hyperbolic operators with triple characteristics the above conjecture has been proved in [6], [1], [11], but the general case is still an open problem.

In [11] the strong hyperbolicity was established under the condition (E) saying that for some $\delta > 0$ and small $t \geq 0$ we have the lower bound

$$\frac{\Delta}{\langle \xi \rangle^6} \geq \delta t \left(\frac{\Delta_0}{\langle \xi \rangle^2} \right)^2, \quad (x, \xi) \in \Omega \times \mathbb{R}^n.$$

Here $\Delta \in S^6$ is the discriminant of the equation $p = 0$ with respect to τ , while $\Delta_0 \in S^2$ is the discriminant of the equation $\frac{\partial p}{\partial \tau} = 0$ with respect to τ . In [11] it was introduced also a weaker condition (H) saying that with some constant $\delta > 0$ and small $t \geq 0$ we have

$$\frac{\Delta}{\langle \xi \rangle^6} \geq \delta t^2 \frac{\Delta_0}{\langle \xi \rangle^2}, \quad (x, \xi) \in \Omega \times \mathbb{R}^n.$$

We can consider a microlocal version of the conditions (E) and (H) assuming that the above inequalities hold for (t, x, ξ) , $t \geq 0$, in a small conic neighborhood W_0 of every triple characteristic point $(0, x_0, \xi_0)$. The purpose of this paper is to study operators with triple characteristics on the plane $t = 0$ and our main results are stated in Theorem 4.1 and Corollary 4.5. They improve the results in [11] and show that we have a strong hyperbolicity for some operators for which (E) is not satisfied, but (H) holds. In particular, we cover the case of

operators whose principal symbol p admits a microlocal factorization with one smooth root under the condition that there are no double characteristic points of p converging to a triple characteristic point $(0, x, 0, \xi)$ (see Example 1.1).

Concerning the symbols $a(t, x, \xi)$, $b(t, x, \xi)$, $c(t, x, \xi)$, we assume the existence of $\delta_1 > 0$ such that

$$(1.3) \quad \begin{aligned} & b(t, x, \xi) \geq \delta_1 t, \\ & c = \mathcal{O}(b^2), \quad \langle \xi \rangle^\alpha \partial_\xi^\alpha \partial_x^\beta c = \mathcal{O}(b), \quad |\alpha + \beta| = 1, \quad \langle \xi \rangle^\alpha \partial_\xi^\alpha \partial_x^\beta c = \mathcal{O}(\sqrt{b}), \quad |\alpha + \beta| = 2, \\ & \partial_t c = \mathcal{O}(b), \quad \langle \xi \rangle^\alpha \partial_\xi^\alpha \partial_x^\beta (ac) = \mathcal{O}(\sqrt{b}), \quad |\alpha + \beta| = 3. \end{aligned}$$

It is clear that the condition (1.3) are satisfied if

$$(1.4) \quad b(t, x, \xi) \geq \delta_1 t, \quad \langle \xi \rangle^\alpha \partial_t^\gamma \partial_\xi^\alpha \partial_x^\beta c = \mathcal{O}(b^{2-|\alpha+\beta|/2-|\gamma|}) \text{ for } |\alpha + \beta + \gamma| \leq 3, \quad \gamma = 0, 1.$$

In fact, we assume a slightly weaker microlocal conditions formulated in (3.11) and Theorem 4.1.

Below we present two examples of effectively hyperbolic operators with triple characteristics on $t = 0$ satisfying the above assumptions.

EXAMPLE 1.1. Assume $c \equiv 0$. Then the symbol p becomes $p = ((\tau - \varphi(\xi))^2 + a\langle \xi \rangle(\tau - \varphi(\xi)) - b\langle \xi \rangle^2)(\tau - \varphi(\xi))$. Let $\rho = (0, x_0, \varphi(0, x_0, \xi_0)\langle \xi_0 \rangle, \xi_0)$, be a triple characteristic point. For small $t > 0$ we have $b(t, x_0, \xi_0) > 0$. If for some (y, η) sufficiently close to (x_0, ξ_0) we have $b(0, y, \eta) < 0$, then there exists $z = (t^*, x^*, \xi^*)$ with $t^* > 0$ such that $b(z) = 0$ and the equation $(\tau - \varphi(\xi))^2 + a\langle \xi \rangle(\tau - \varphi(\xi)) - b\langle \xi \rangle^2 = 0$ has a root $\varphi(z)\langle \xi^* \rangle$ for z . This implies the existence of a double characteristic point $(t^*, x^*, \varphi(z)\langle \xi^* \rangle, \xi^*)$ of p . We exclude this possibility, assuming $b(0, x, \xi) \geq 0$ for (x, ξ) close to (x_0, ξ_0) .

REMARK 1.1. For the operator in Example 1.1, the discriminant of the equation $p = 0$ has the form $\Delta = b^2(a^2 + 4b)\langle \xi \rangle^6$, while $\Delta_0 = 4(a^2 + 3b)\langle \xi \rangle^2$. Therefore the condition (E) is reduced to

$$b^2(a^2 + 4b) \geq \delta t(a^2 + 3b)^2.$$

If $b = \mathcal{O}(t)$, this inequality yields $b^2 a^2 + 4b^3 \geq \delta t a^4$ and hence $a^2 \leq \mathcal{O}(t^2)/\delta t = \mathcal{O}(t)$ which is not satisfied in any small neighborhood of a triple characteristic point $(0, x_0, \varphi(0, x_0, \xi_0)\langle \xi_0 \rangle, \xi_0)$, unless $a(0, x, \xi) = 0$ for all $(0, x, \xi)$ close to the point $(0, x_0, \xi_0)$. On the other hand, the inequality

$$b^2(a^2 + 4b) \geq \delta t^2(a^2 + 3b)$$

obviously holds ($b \geq \delta_1 t$ is assumed), hence (H) is satisfied.

The Example 1.1 covers the case when the principal symbol p admits a factorization

$$p = (\tau^2 + 2d(t, x, \xi)\tau + f(t, x, \xi))(\tau - \lambda(t, x, \xi))$$

with C^∞ smooth real root $\lambda(t, x, \xi)$ and p has not double characteristic points in a neighborhood of $(0, x_0, \xi_0)$. In fact, we may write

$$p = ((\tau - \lambda)^2 + 2(\lambda + d)(\tau - \lambda) + \lambda^2 + 2d\lambda + f)(\tau - \lambda)$$

and taking $\varphi = \lambda\langle\xi\rangle^{-1}$ we reduce the symbol to Example 1.1. Notice that effectively hyperbolic operators with principal symbols admitting above factorization have been studied by V. Ivrii in [6] who proved the strong hyperbolicity constructing parametrix. Here we present another proof based on energy estimates with weight t^{-N} , assuming P strictly hyperbolic for small $t > 0$.

EXAMPLE 1.2. Consider the operator with principal symbol

$$p = \tau^3 - (t + \alpha(x, \xi))\langle\xi\rangle^2\tau - (t^2b_2 + tb_1 + b_0)\langle\xi\rangle^3,$$

where α, b_0, b_1, b_2 are zero order pseudo-differential operators and $\alpha \geq 0$. This class of operators has been studied in [11] under the condition (E). We write p as follows

$$p = (\tau + b_1\langle\xi\rangle)^3 - 3b_1\langle\xi\rangle(\tau + b_1\langle\xi\rangle)^2 - (t + \alpha - 3b_1^2)\langle\xi\rangle^2(\tau + b_1\langle\xi\rangle) - [t^2b_2 + b_0 - b_1\alpha + b_1^3]\langle\xi\rangle^3.$$

Choosing $\varphi = -b_1(t, x, \xi)$ one reduces the symbol p to the form (1.2) with $a = -3b_1$, $b = t + \alpha - 3b_1^2$, $c = -(t^2b_2 + b_0 - b_1\alpha + b_1^3)$. If $\alpha \geq 3b_1^2$, $b_0 = b_1\alpha - b_1^3$, the condition (1.4) is satisfied, while for $\alpha = 3b_1^2$, $b_0 = b_1\alpha - b_1^3$ the condition (E) is not satisfied for b_1 , unless $b_1(0, x, \xi) \equiv 0$. It is easy to see that with the above choice of b_0 and b_1 , the condition (H) holds.

Notice that if $\rho = (t, x, \tau, \xi)$ with $t > 0$ is a double characteristic point for p , one has $\Delta(\rho) = 0$ and $\Delta_0(\rho) > 0$. Therefore the condition (H) is not satisfied and the analysis of this case is a difficult open problem. The proofs in this work are based on energy estimates with weight t^{-N} with $N \gg 1$ leading to estimates with big loss of regularity. This phenomenon is typical for effectively hyperbolic operators with multiple characteristics (see [4], [6], [1], [11]).

We follow the approach in [11] reducing the problem to the one for first order pseudo-differential system. In Section 2 we construct a symmetrizer S for the principal symbol of the system following a general result (see Lemma 2.1) which has independent interest. Moreover, $\det S = \frac{1}{27}\Delta$ and under our assumptions one shows that $\det S \geq \delta b^2(a^2 + 4b)$, $\delta > 0$. Therefore $\Delta \geq \varepsilon t^2(a^2 + 4b)$, $\varepsilon > 0$, and in general the condition (E) is not satisfied. This leads to difficulties in Section 3, where a more fine analysis of the matrix pseudo-differential operators is needed. As in [11] a detailed examination of the sharp Gårding inequality for matrix pseudo-differential operators with nonnegative definite symbols plays a crucial role in the analysis. In Section 4 we show that the microlocal conditions (1.3) are sufficient for the energy estimates in Theorems 4.1 and 4.2.

2. Symmetrizer

First we recall a general result concerning the existence of a symmetrizer. Let $p(\zeta) = \zeta^m + a_1\zeta^{m-1} + \dots + a_m$ be a monic hyperbolic polynomial of degree m and let $q(\zeta) = p'(\zeta)$. Here $a_j(t, x, \xi)$ depend on (t, x, ξ) but we omit this in the notations below. Let

$$h_{p,q}(\zeta, \bar{\zeta}) = \frac{p(\zeta)q(\bar{\zeta}) - p(\bar{\zeta})q(\zeta)}{\zeta - \bar{\zeta}} = \sum_{i,j=1}^m h_{ij} \zeta^{i-1} \bar{\zeta}^{j-1}$$

be the Bézout form of p and q . It is well known that the matrix $H = (h_{ij})$ is nonnegative definite (see for example [5]).

Consider the Sylvester matrix A_p corresponding to $p(\zeta)$ which has the form

$$A_p = \begin{pmatrix} 0 & 1 & \cdots & 0 \\ \vdots & \vdots & \ddots & \\ 0 & 0 & \cdots & 1 \\ -a_m & -a_{m-1} & \cdots & -a_1 \end{pmatrix}.$$

One has the following result [10, 13] and for the sake of completeness we present the proof.

Lemma 2.1 ([10, 13]). *H is nonnegative definite and symmetrizes A_p and $\det H = \Delta^2$ where Δ is the difference-product of the roots of $p(\tau) = 0$.*

Proof. We first treat the case when $p(\zeta)$ is a strictly hyperbolic polynomial. Let $\lambda_j, j = 1, \dots, m$ be the different roots of the equation $p(\zeta) = 0$. Write $p(\zeta) = \prod_{j=1}^m (\zeta - \lambda_j)$ and set

$$\sigma_{\ell,k} = \sum_{1 \leq j_1 < \dots < j_\ell \leq m, j_p \neq k} \lambda_{j_1} \cdots \lambda_{j_\ell}.$$

Since $p'(\zeta) = \sum_{k=1}^m \prod_{j=1, j \neq k}^m (\zeta - \lambda_j) = \sum_{i=1}^m (-1)^{m-i} \sigma_{m-i,k} \zeta^{i-1}$ it is easy to see

$$h_{ij} = \sum_{k=1}^m (-1)^{i+j} \sigma_{m-i,k} \sigma_{m-j,k}.$$

Denote by R the Vandermonde's matrix having the form

$$R = \begin{pmatrix} 1 & 1 & \cdots & 1 \\ \lambda_1 & \lambda_2 & \cdots & \lambda_m \\ \vdots & \vdots & \ddots & \vdots \\ \lambda_1^{m-1} & \lambda_2^{m-1} & \cdots & \lambda_m^{m-1} \end{pmatrix}.$$

Since $\lambda_i \neq \lambda_j, i \neq j$, the matrix R is invertible and $|\det R| = |\Delta|$. It is clear that

$$A_p R = R \begin{pmatrix} \lambda_1 & & & \\ & \ddots & & \\ & & & \lambda_m \end{pmatrix}.$$

Denote by ${}^{co}R = (r_{ij})$ the cofactor matrix of R and by $\Delta(\lambda_1, \dots, \lambda_k)$ the difference-product of $\lambda_1, \dots, \lambda_k$. It is easily seen that r_{ij} is divisible by $\Delta_i = \Delta(\lambda_1, \dots, \lambda_{i-1}, \lambda_{i+1}, \dots, \lambda_m)$, hence

$$(2.1) \quad r_{ij} = c_{ij}(\lambda_1, \dots, \lambda_{i-1}, \lambda_{i+1}, \dots, \lambda_m) \Delta_i.$$

Since r_{ij} and Δ_i are alternating polynomials in $(\lambda_1, \dots, \lambda_{i-1}, \lambda_{i+1}, \dots, \lambda_m)$ of degree $m(m - 1)/2 - j + 1$ and $(m - 1)(m - 2)/2$ respectively, then c_{ij} is a symmetric polynomial of degree

$$m - j = m(m - 1)/2 - j + 1 - (m - 1)(m - 2)/2.$$

Therefore c_{ij} is a polynomial in fundamental symmetric polynomials of $(\lambda_1, \dots, \lambda_{i-1}, \lambda_{i+1}, \dots, \lambda_m)$. Noting that Δ_i is of degree $m - 2$ and r_{ij} ($j \neq m$) is of degree $m - 1$ respectively with respect to λ_ℓ ($\ell \neq i$), one concludes that c_{ij} is of degree 1 with respect to λ_ℓ ($\ell \neq i$) which proves that

$$(2.2) \quad c_{ij} = (-1)^{i+j} \sigma_{m-j,i}.$$

Thus denoting $C = (c_{ij})$ we have ${}^tCC = (h_{ij}) = H$. In particular, this shows that the symmetric matrix H is nonnegative definite as it was mentioned above.

Set $D = \text{diag}(\Delta_1, \dots, \Delta_m)$ and note that D is invertible. Moreover it follows from (2.1) that $C = D^{-1}({}^{co}R) = (\det R)D^{-1}R^{-1}$ and hence

$$CA_pC^{-1} = D^{-1}(R^{-1}A_pR)D.$$

It is clear that CA_pC^{-1} is a diagonal matrix because both $R^{-1}A_pR$ and D are diagonal matrices. Then $CA_pC^{-1} = {}^tC^{-1}{}^tA_p{}^tC$ yields ${}^tCCA_p = {}^tA_p{}^tCC$ which proves that HA_p is symmetric. From $C = (\det R)D^{-1}R^{-1}$ it follows that

$$C = \text{diag} \left(\pm \prod_{k \neq 1} (\lambda_1 - \lambda_k), \pm \prod_{k \neq 2} (\lambda_2 - \lambda_k), \dots, \pm \prod_{k \neq m} (\lambda_3 - \lambda_k) \right) R^{-1}$$

and hence $|\det C| = |\prod_{j=1}^m \prod_{k \neq j} (\lambda_k - \lambda_j)| / |\Delta| = |\Delta|$. Consequently, $\det H = \Delta^2$ and this completes the proof for strictly hyperbolic polynomial $p(\zeta)$.

Passing to the general case, introduce the polynomial

$$p_\varepsilon(\zeta) = \left(1 + \varepsilon \frac{\partial}{\partial \zeta}\right)^{m-1} p(\zeta), \quad \varepsilon \neq 0.$$

According to [12], $p_\varepsilon(\zeta)$ is strictly hyperbolic and let $H_\varepsilon = {}^tC_\varepsilon C_\varepsilon$ be the symmetrizer for A_{p_ε} constructed above. Obviously, as $\varepsilon \rightarrow 0$, we have $A_{p_\varepsilon} \rightarrow A_p$ since the coefficients of $p_\varepsilon(\zeta)$ go to the ones of $p(\zeta)$. The roots of $p(\zeta)$ depend continuously on the coefficients and this yields $\lambda_{j,\varepsilon} \rightarrow \lambda_j$, $\lambda_{j,\varepsilon}$ being the roots of $p_\varepsilon(\zeta) = 0$. The equalities (2.2) imply $C_\varepsilon \rightarrow C$ and passing to the limit $\varepsilon \rightarrow 0$, we obtain the result. \square

Note that H is different from the Leray's symmetrizer ([7]) since if B is the Leray's symmetrizer, then $\det B = \Delta^{2(m-1)}$. Now consider

$$\tilde{A}_p = \begin{pmatrix} -a_1 & -a_2 & \cdots & -a_m \\ 1 & 0 & \cdots & 0 \\ \vdots & \ddots & \ddots & \\ 0 & \cdots & 1 & 0 \end{pmatrix}.$$

Corollary 2.1. *Let $J = (\delta_{i,m+1-j})$, where δ_{ij} is the Kronecker's delta. Then $\tilde{H} = JH^tJ$ is nonnegative definite and symmetrizes \tilde{A}_p and $\det \tilde{H} = \Delta^2$.*

Proof. Since $\tilde{A}_p = JA_p{}^tJ$ and ${}^tJJ = I$ the proof is immediate. \square

With $U = {}^t((D_t - \text{Op}(\varphi)\langle D \rangle)^2 u, \langle D \rangle(D_t - \text{Op}(\varphi)\langle D \rangle)u, \langle D \rangle^2 u)$ the equation $Pu = f$ is reduced

$$(2.3) \quad D_t U = \text{Op}(\varphi)\langle D \rangle U + (\text{Op}(A)\langle D \rangle + \text{Op}(B))U + F,$$

where $F = {}^t(f, 0, 0)$ and

$$A(t, x, \xi) = \begin{pmatrix} -a & b & -c \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix}, \quad B(t, x, \xi) = \begin{pmatrix} b_{11} & b_{11} & b_{13} \\ 0 & b_{22} & 0 \\ 0 & 0 & b_{33} \end{pmatrix},$$

where $b_{ij} \in S_{1,0}^0$.

Introduce

$$S(t, x, \xi) = \frac{1}{3} \begin{pmatrix} 3 & 2a & -b \\ 2a & 2(a^2 + b) & -ab - 3c \\ -b & -ab - 3c & b^2 - 2ac \end{pmatrix}$$

which is a representation matrix (conjugated by J in Corollary 2.1) of the Bézout form of $p(\tau) = \tau^3 + a\tau^2 - b\tau + c$ and $p'(\tau)$ (see for example [5], [8]). Therefore S symmetrizes A so that

$$(2.4) \quad S(t, x, \xi)A(t, x, \xi) = \frac{1}{3} \begin{pmatrix} -a & 2b & -3c \\ 2b & ab - 3c & -2ac \\ -3c & -2ac & bc \end{pmatrix}.$$

Note that when $c = 0$ one has

$$S_0(t, x, \xi) = \frac{1}{3} \begin{pmatrix} 3 & 2a & -b \\ 2a & 2(a^2 + b) & -ab \\ -b & -ab & b^2 \end{pmatrix}$$

and hence

$$\det S_0(t, x, \xi) = \frac{1}{27}b^2(a^2 + 4b).$$

Lemma 2.2. *There exist $\bar{\varepsilon} > 0$ and $\delta > 0$ such that*

$$\det S \geq \delta b^2(a^2 + b)$$

if $|ac| \leq \bar{\varepsilon} b^2$ and $|c| \leq \bar{\varepsilon} b^{3/2}$.

Proof. Note that

$$\det S = \det S_0 + \frac{1}{27}\{-4a^3c - 18abc - 27c^2\}.$$

Since

$$|a^3c| \leq \bar{\varepsilon} b^2 a^2, \quad |abc| \leq \bar{\varepsilon} b^3, \quad |c^2| \leq \bar{\varepsilon}^2 b^3$$

choosing $\bar{\varepsilon} = 1/50$ for instance, the assertion is clear. □

Lemma 2.3. *There exist $\bar{\varepsilon} > 0$ and $\varepsilon_1 > 0$ such that*

$$S(t, x, \xi) \gg \varepsilon_1 t \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & b \end{pmatrix} = \varepsilon_1 t J,$$

provided $|ac| \leq \bar{\varepsilon} b^2$ and $|c| \leq \bar{\varepsilon} b^{3/2}$.

Proof. Since

$$3S - \varepsilon_1 t J = \begin{pmatrix} 3 - \varepsilon_1 t & 2a & -b \\ 2a & 2a^2 + 2b - \varepsilon_1 t & -ab - 3c \\ -b & -ab - 3c & b^2 - \varepsilon_1 t b - 2ac \end{pmatrix},$$

one obtains

$$\det(3S - \varepsilon_1 t J) = \det 3S + \varepsilon_1 \mathcal{O}(b^2(b + a^2)).$$

Indeed

$$\begin{aligned} (3 - \varepsilon_1 t)(2a^2 + 2b - \varepsilon_1 t)(b^2 - \varepsilon_1 t b - 2ac) &= 3(2a^2 + 2b)(b^2 - 2ac) + \varepsilon_1 \mathcal{O}(tb(b + a^2)), \\ b^2(2a^2 + 2b - \varepsilon_1 t) &= b^2(2a^2 + 2b) + \varepsilon_1 \mathcal{O}(tb(b + a^2)), \\ 4a^2(b^2 - \varepsilon_1 t b - 2ac) &= 4a^2(b^2 - 2ac) + \varepsilon_1 \mathcal{O}(tba^2), \\ (3 - \varepsilon_1 t)(ab + 3c)^2 &= 3(ab + 3c)^2 + \varepsilon_1 \mathcal{O}(tb^2). \end{aligned}$$

Noting $b \geq \delta_1 t$, one gets the above representation and we deduce $\det(3S - \varepsilon_1 t J) \geq 0$ for small ε_1 . In the same way one treats the principal minors of order 2. For example

$$(3 - \varepsilon_1 t)(2a^2 + 2b - \varepsilon_1 t) - 4a^2 = 2a^2 + 6b - \varepsilon_1 t(2a^2 + 2b) + \varepsilon_1^2 t^2 \geq 2(a^2 + b)(1 - \varepsilon_1 t) \geq 0,$$

$$\begin{aligned} (3 - \varepsilon_1 t)(b^2 - \varepsilon_1 t b - 2ac) - b^2 &= 2b^2 - 6ac - \varepsilon_1 t(b^2 - 2ac + 3b) + \varepsilon_1^2 t^2 b \\ &\geq b^2 - 4ac - 3\varepsilon_1 t b + (b^2 - 2ac)(1 - \varepsilon_1 t) \\ &\geq (1 - 4\bar{\varepsilon})b^2 - 3\varepsilon_1 t b + (1 - 2\bar{\varepsilon})(1 - \varepsilon_1 t)b^2 \geq 0, \end{aligned}$$

$$\begin{aligned} (2a^2 + 2b - \varepsilon_1 t)(b^2 - \varepsilon_1 t b - 2ac) - (ab + 3c)^2 &\geq a^2 b^2 + 2b^3 - 10abc - 9c^2 - 4a^3 c \\ &\quad - 3\varepsilon_1 t b^2 + 2\varepsilon_1 t a c - 2\varepsilon_1 t b a^2 \\ &\geq (1 - 4\bar{\varepsilon})a^2 b^2 + (2 - 10\bar{\varepsilon} - 9\bar{\varepsilon}^2)b^3 - (3\varepsilon_1 + 2\varepsilon_1 \bar{\varepsilon})t b^2 - 2\varepsilon_1 t b a^2 \geq 0 \end{aligned}$$

since all terms involving $\varepsilon_1 t$ can be compensated by $a^2 b^2 + 2b^3$. □

Lemma 2.4. Assume $\langle \xi \rangle^\alpha c_{(\beta)}^{(\alpha)} = \mathcal{O}(\sqrt{b})$ for $|\alpha + \beta| = 2$ and $\langle \xi \rangle^\alpha (ac)_{(\beta)}^{(\alpha)} = \mathcal{O}(\sqrt{b})$ for $|\alpha + \beta| = 3$. There exists $C > 0$ such that for $U \in C^\infty(\mathbb{R}_t : C_0^\infty(\mathbb{R}^n))$ we have

$$\operatorname{Re}(\operatorname{Op}(S)U, U) \geq \varepsilon_1 t \left(\sum_{j=1}^2 \|U_j\|^2 + (\operatorname{Op}(b)U_3, U_3) \right) - Ct^{-1} \|\langle D \rangle^{-1} U\|^2.$$

Proof. We will follow the argument of [11, Section 3] and we use the notation $\partial_\xi^\alpha D_x^\beta Q = Q_{(\beta)}^{(\alpha)}$. Recall that we have the representation

$$(2.5) \quad Q_F - \operatorname{Op}(Q) = \operatorname{Op}\left(\sum_{2 \leq |\alpha + \beta| \leq 3} \psi_{\alpha, \beta}(\xi) Q_{(\beta)}^{(\alpha)} \right) + \operatorname{Op}(R)$$

with $R \in S_{1/2, 0}^{-2}$ and real symbols $\psi_{\alpha, \beta} \in S^{(|\alpha| - |\beta|)/2}$, where Q_F is the Friedrichs part of Q (see [11, Appendix], [2]) and hence $(Q_F U, U) \geq 0$.

Notice that b is real, hence $(\text{Op}(b)U_3, U_3) = \text{Re}(\text{Op}(b)U_3, U_3)$. Setting $Q = S - 2\varepsilon_1 t J$, we have

$$\text{Re}(\text{Op}(S)U, U) = \text{Re}(\text{Op}(Q)U, U) + 2\varepsilon_1 t \left(\sum_{j=1}^2 \|U_j\|^2 + (\text{Op}(b)U_3, U_3) \right),$$

and it is enough to prove

(2.6)

$$|\text{Re}(\text{Op}\left(\sum_{2 \leq |\alpha+\beta| \leq 3} \psi_{\alpha\beta} Q_{(\beta)}^{(\alpha)}\right)U, U)| \leq \varepsilon_1 t \left(\sum_{j=1}^2 \|U_j\|^2 + (\text{Op}(b)U_3, U_3) \right) + C\varepsilon_1^{-1} t^{-1} \|\langle D \rangle^{-1} U\|^2.$$

Indeed if this is true, then we have

$$\begin{aligned} \text{Re}(\text{Op}(Q)U, U) &\geq (Q_F U, U) - \varepsilon_1 t \left(\sum_{j=1}^2 \|U_j\|^2 + (\text{Op}(b)U_3, U_3) \right) \\ &\quad - C\varepsilon_1^{-1} t^{-1} \|\langle D \rangle^{-1} U\|^2 - C\|\langle D \rangle^{-1} U\|^2 \\ &\geq -\varepsilon_1 t \left(\sum_{j=1}^2 \|U_j\|^2 + (\text{Op}(b)U_3, U_3) \right) - C\varepsilon_1^{-1} t^{-1} \|\langle D \rangle^{-1} U\|^2. \end{aligned}$$

Thus we conclude the assertion.

To prove (2.6), consider $\text{Re}(\text{Op}(\psi_{\alpha\beta} Q_{(\beta)}^{(\alpha)})U, U)$ with $|\alpha+\beta| = 2$. Setting $g = b^2 - \varepsilon t b - 2ac$, one has

$$Q_{(\beta)}^{(\alpha)} = \begin{pmatrix} 0 & S^{-|\alpha|} & S^{-|\alpha|} \\ S^{-|\alpha|} & S^{-|\alpha|} & S^{-|\alpha|} \\ S^{-|\alpha|} & S^{-|\alpha|} & g_{(\beta)}^{(\alpha)} \end{pmatrix}.$$

Here and below S^m denotes some symbol in the class S^m . This yields

$$\psi_{\alpha\beta} Q_{(\beta)}^{(\alpha)} = \begin{pmatrix} 0 & S^{-1} & S^{-1} \\ S^{-1} & S^{-1} & S^{-1} \\ S^{-1} & S^{-1} & \psi_{\alpha\beta} g_{(\beta)}^{(\alpha)} \end{pmatrix}$$

and hence

$$\begin{aligned} |(\text{Op}(\psi_{\alpha\beta} Q_{(\beta)}^{(\alpha)})U, U)| &\leq \varepsilon_1 t \sum_{j=1}^2 \|U_j\|^2 + C\varepsilon_1^{-1} t^{-1} \|\langle D \rangle^{-1} U\|^2 \\ &\quad + |\text{Re}(\text{Op}(\psi_{\alpha\beta} g_{(\beta)}^{(\alpha)})U_3, U_3)|. \end{aligned}$$

Let $T = \psi_{\alpha\beta} g_{(\beta)}^{(\alpha)} \langle \xi \rangle$. Then $\psi_{\alpha\beta} g_{(\beta)}^{(\alpha)} = \text{Re}(T \# \langle \xi \rangle^{-1}) + S^{-2}$ and

$$\text{Re}(\text{Op}(\psi_{\alpha\beta} g_{(\beta)}^{(\alpha)})U_3, U_3) \leq \varepsilon_1 t \|\text{Op}(T)U_3\|^2 + C\varepsilon_1^{-1} t^{-1} \|\langle D \rangle^{-1} U_3\|^2.$$

Note that $\|\text{Op}(T)U_3\|^2 = (\text{Op}(T \# T)U_3, U_3)$ and $T \# T = T^2 + S^{-2}$. Therefore there exists $C > 0$ such that

$$T^2 \leq Cb$$

because $\langle \xi \rangle^\alpha c_{(\beta)}^{(\alpha)} = \mathcal{O}(\sqrt{b})$ and $\langle \xi \rangle^\alpha (b(b - \varepsilon_1 t))_{(\beta)}^{(\alpha)} = \mathcal{O}(\sqrt{b})$ and $b \geq \delta t$. Applying the

Fefferman-Phong inequality for the operator with symbol $Cb - T^2$, one proves the assertion.

For the case $|\alpha + \beta| = 3$ with $T_1 = \psi_{\alpha\beta} \varrho_{(\beta)}^{(\alpha)} \langle \xi \rangle^{3/2}$ we have the inequality

$$T_1^2 \leq Cb$$

with some $C > 0$. Indeed, $\langle \xi \rangle^\alpha (ac)_{(\beta)}^{(\alpha)} = \mathcal{O}(\sqrt{b})$ and $\langle \xi \rangle^\alpha (b(b - \varepsilon_1 t))_{(\beta)}^{(\alpha)} = \mathcal{O}(\sqrt{b})$. Repeating the above argument, we complete the proof. \square

Corollary 2.2. *Let $\tilde{S} = S + \lambda t^{-1} \langle \xi \rangle^{-2} I$. Then there exists $\lambda_0 > 0$ such that for $\lambda \geq \lambda_0$ we have*

$$\begin{aligned} \operatorname{Re}(\operatorname{Op}(\tilde{S})U, U) &= \operatorname{Re}(\operatorname{Op}(S)U, U) + \lambda t^{-1} \|\langle D \rangle^{-1} U\|^2 \\ &\geq \varepsilon_1 t \left(\sum_{j=1}^2 \|U_j\|^2 + (\operatorname{Op}(b)U_3, U_3) \right) + (\lambda/2)t^{-1} \|\langle D \rangle^{-1} U\|^2. \end{aligned}$$

Corollary 2.3. *There exist $\delta_2 > 0$ and $\lambda_0 > 0$ such that*

$$\operatorname{Re}(\operatorname{Op}(\tilde{S})U, U) \geq \delta_2 t^2 \|U\|^2 + (\lambda/2)t^{-1} \|\langle D \rangle^{-1} U\|^2, \quad \lambda \geq \lambda_0.$$

Proof. Since there exists $\delta_1 > 0$ such that $b \geq \delta_1 t$ from the Fefferman-Phong inequality for the scalar symbol $b - \delta_1 t$ one deduces

$$(\operatorname{Op}(b)U_3, U_3) \geq \delta_1 t \|U_3\|^2 - C \|\langle D \rangle^{-1} U_3\|^2$$

which proves the assertion thanks to Corollary 2.2. \square

3. Energy estimates

Consider the energy $(t^{-N} e^{-\gamma t} \operatorname{Op}(\tilde{S})U, U)$, where (\cdot, \cdot) is the $L^2(\mathbb{R}^n)$ inner product and $N > 0, \gamma > 0$ are positive parameters. Then one has

$$\begin{aligned} (3.1) \quad \partial_t(t^{-N} e^{-\gamma t} \operatorname{Op}(\tilde{S})U, U) &= -N(t^{-N-1} e^{-\gamma t} \operatorname{Op}(\tilde{S})U, U) - \gamma(t^{-N} e^{-\gamma t} \operatorname{Op}(\tilde{S})U, U) \\ &\quad + (t^{-N} e^{-\gamma t} \operatorname{Op}(\partial_t S)U, U) - \lambda(N+1)t^{-N-2} e^{-\gamma t} \|\langle D \rangle^{-1} U\|^2 - \lambda \gamma t^{-N-1} e^{-\gamma t} \|\langle D \rangle^{-1} U\|^2 \\ &\quad - 2\operatorname{Im}(t^{-N} e^{-\gamma t} \operatorname{Op}(\tilde{S})(\varphi \langle D \rangle + \operatorname{Op}(A) \langle D \rangle + \operatorname{Op}(B))U, U) - 2\operatorname{Im}(t^{-N} e^{-\gamma t} \operatorname{Op}(\tilde{S})F, U). \end{aligned}$$

Consider $S \# A \# \langle \xi \rangle - \langle \xi \rangle \# A \# S$. Note that

$$S \# A = SA + \sum_{|\alpha+\beta|=1} \frac{(-1)^{|\beta|}}{2i} S_{(\beta)}^{(\alpha)} A_{(\alpha)}^{(\beta)} + \sum_{|\alpha+\beta|=2} \dots + S^{-3}.$$

Writing $S = (s_{ij})$ one has

$$\sum_{|\alpha+\beta|=2} \dots = \sum_{|\alpha+\beta|=2} \dots \left(s_{ij}^{(\alpha)} \right) \begin{pmatrix} -a_{(\alpha)}^{(\beta)} & b_{(\alpha)}^{(\beta)} & -c_{(\alpha)}^{(\beta)} \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} S^{-2} & S^{-2} & \mathcal{O}(\sqrt{b})S^{-2} \\ S^{-2} & S^{-2} & \mathcal{O}(\sqrt{b})S^{-2} \\ S^{-2} & S^{-2} & \mathcal{O}(\sqrt{b})S^{-2} \end{pmatrix},$$

because $c_{(\alpha)}^{(\beta)} = \mathcal{O}(\sqrt{b})$ for $|\alpha + \beta| = 2$. Then

$$(S\#A)\#\langle\xi\rangle = (SA)\#\langle\xi\rangle + \left(\sum_{|\alpha+\beta|=1} \dots\right)\#\langle\xi\rangle + \begin{pmatrix} S^{-1} & S^{-1} & \mathcal{O}(\sqrt{b})S^{-1} \\ S^{-1} & S^{-1} & \mathcal{O}(\sqrt{b})S^{-1} \\ S^{-1} & S^{-1} & \mathcal{O}(\sqrt{b})S^{-1} \end{pmatrix} + S^{-2}.$$

Denoting the third term on the right-hand side by K_2 , repeating the same arguments as before, it is easy to see

$$(3.2) \quad |(\text{Op}(K_2) + \text{Op}(S^{-2}))U, U| \leq C(\|\langle D \rangle^{-1}U\|^2 + \sum_{j=1}^2 \|U_j\|^2 + (\text{Op}(b)U_3, U_3)).$$

Now we turn to the term with $|\alpha + \beta| = 1$. Note

$$S_{(\beta)}^{(\alpha)}A_{(\alpha)}^{(\beta)} = \left(s_{ij(\beta)}^{(\alpha)}\right) \begin{pmatrix} -a_{(\alpha)}^{(\beta)} & b_{(\alpha)}^{(\beta)} & -c_{(\alpha)}^{(\beta)} \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} S^{-1} & S^{-1} & \mathcal{O}(\sqrt{b})S^{-1} \\ S^{-1} & S^{-1} & \mathcal{O}(\sqrt{b})S^{-1} \\ \mathcal{O}(\sqrt{b})S^{-1} & \mathcal{O}(\sqrt{b})S^{-1} & \mathcal{O}(b)S^{-1} \end{pmatrix},$$

since $c_{(\alpha)}^{(\beta)} = \mathcal{O}(\sqrt{b})$ and $b_{(\beta)}^{(\alpha)} = \mathcal{O}(\sqrt{b})$ for $|\alpha + \beta| = 1$ and hence

$$\left(\sum_{|\alpha+\beta|=1} \dots\right)\#\langle\xi\rangle = \begin{pmatrix} S^0 & S^0 & \mathcal{O}(\sqrt{b})S^0 + S^{-1} \\ S^0 & S^0 & \mathcal{O}(\sqrt{b})S^0 + S^{-1} \\ \mathcal{O}(\sqrt{b})S^0 + S^{-1} & \mathcal{O}(\sqrt{b})S^0 + S^{-1} & \mathcal{O}(b)S^0 + \mathcal{O}(\sqrt{b})S^{-1} + S^{-2} \end{pmatrix} = K_1.$$

The same arguments proves

$$|(\text{Op}(K_1)U, U)| \leq C(\|\langle D \rangle^{-1}U\|^2 + \sum_{j=1}^2 \|U_j\|^2 + (\text{Op}(b)U_3, U_3)).$$

Consider $A^*\#S$. We have the representation

$$A^*\#S = A^*S + \sum_{|\alpha+\beta|=1} \frac{(-1)^{|\beta|}}{2i} (A^*)_{(\beta)}^{(\alpha)} S_{(\alpha)}^{(\beta)} + \sum_{|\alpha+\beta|=2} \dots + S^{-3} = A^*S + \tilde{K}.$$

Repeating similar arguments, one gets

$$|(\text{Op}(\langle\xi\rangle\#\tilde{K})U, U)| \leq C(\|\langle D \rangle^{-1}U\|^2 + \sum_{j=1}^2 \|U_j\|^2 + (\text{Op}(b)U_3, U_3)).$$

Since $A^*S = SA$, taking (2.4) into account, we see

$$\begin{aligned} (SA)\#\langle\xi\rangle - \langle\xi\rangle\#(A^*S) &= (SA)\#\langle\xi\rangle - \langle\xi\rangle\#(SA) \\ &= \begin{pmatrix} S^0 & S^0 & \mathcal{O}(\sqrt{b})S^0 + S^{-1} \\ S^0 & S^0 & \mathcal{O}(\sqrt{b})S^0 + S^{-1} \\ \mathcal{O}(\sqrt{b})S^0 + S^{-1} & \mathcal{O}(\sqrt{b})S^0 + S^{-1} & \mathcal{O}(b)S^0 + \mathcal{O}(\sqrt{b})S^{-1} + S^{-2} \end{pmatrix}. \end{aligned}$$

Summarizing the above estimates, we obtain the following

Lemma 3.5. Assume $\langle\xi\rangle^\alpha c_{(\beta)}^{(\alpha)} = \mathcal{O}(\sqrt{b})$ for $|\alpha + \beta| \leq 2$. There is $C > 0$ such that

$$|(\text{Op}(S\#A\#\langle\xi\rangle - \langle\xi\rangle\#A^*\#S)U, U)| \leq C\left(\sum_{j=1}^2 \|U_j\|^2 + (\text{Op}(b)U_3, U_3) + \|\langle D \rangle^{-1}U\|^2\right).$$

Consider $S\#\varphi\#\langle\xi\rangle - \langle\xi\rangle\#\varphi\#S$, where $\varphi \in S^0$ is scalar. Recall

$$S\#\varphi = \varphi S + \sum_{|\alpha+\beta|=1} \frac{(-1)^{|\beta|}}{2i} S_{(\beta)}^{(\alpha)} \varphi_{(\alpha)}^{(\beta)} + \sum_{|\alpha+\beta|=2} \dots + S^{-3}.$$

For $|\alpha + \beta| = 2$ one has

$$S_{(\beta)}^{(\alpha)} \varphi_{(\alpha)}^{(\beta)} = \begin{pmatrix} S^{-2} & S^{-2} & S^{-2} \\ S^{-2} & S^{-2} & S^{-2} \\ S^{-2} & S^{-2} & \mathcal{O}(\sqrt{b})S^{-2} \end{pmatrix}$$

and hence

$$(S\#\varphi)\#\langle\xi\rangle = (\varphi S)\#\langle\xi\rangle + \left(\sum_{|\alpha+\beta|=1} \dots \right)\#\langle\xi\rangle + \begin{pmatrix} S^{-1} & S^{-1} & S^{-1} \\ S^{-1} & S^{-1} & S^{-1} \\ S^{-1} & S^{-1} & \mathcal{O}(\sqrt{b})S^{-1} + S^{-2} \end{pmatrix} + S^{-2}.$$

Denoting the third term on the right-hand side by K_2 , we have the same estimate as (3.2). Similarly one has

$$\langle\xi\rangle\#(\varphi\#S) = \langle\xi\rangle\#(\varphi S) + \langle\xi\rangle\#\left(\sum_{|\alpha+\beta|=1} \dots \right) + \begin{pmatrix} S^{-1} & S^{-1} & S^{-1} \\ S^{-1} & S^{-1} & S^{-1} \\ S^{-1} & S^{-1} & \mathcal{O}(\sqrt{b})S^{-1} + S^{-2} \end{pmatrix} + S^{-2}.$$

Consider the term with $|\alpha + \beta| = 1$ and observe that

$$S_{(\beta)}^{(\alpha)} \varphi_{(\alpha)}^{(\beta)} = \begin{pmatrix} S^{-1} & S^{-1} & \mathcal{O}(\sqrt{b})S^{-1} \\ S^{-1} & S^{-1} & \mathcal{O}(\sqrt{b})S^{-1} \\ \mathcal{O}(\sqrt{b})S^{-1} & \mathcal{O}(\sqrt{b})S^{-1} & g_{(\beta)}^{(\alpha)} \varphi_{(\alpha)}^{(\beta)} \end{pmatrix}$$

with $g = b^2 - 2ac$. Therefore

$$(3.3) \quad \langle\xi\rangle\#(S_{(\beta)}^{(\alpha)} \varphi_{(\alpha)}^{(\beta)}) = \begin{pmatrix} S^0 & S^0 & \mathcal{O}(\sqrt{b})S^0 + S^{-1} \\ S^0 & S^0 & \mathcal{O}(\sqrt{b})S^{-1} + S^{-1} \\ \mathcal{O}(\sqrt{b})S^0 + S^{-1} & \mathcal{O}(\sqrt{b})S^0 + S^{-1} & \mathcal{O}(b)S^0 + \mathcal{O}(\sqrt{b})S^{-1} + S^{-2} \end{pmatrix}$$

because $c_{(\beta)}^{(\alpha)} = \mathcal{O}(b)$ for $|\alpha + \beta| = 1$ and then

$$|(\text{Op}(\langle\xi\rangle\#(S_{(\beta)}^{(\alpha)} \varphi_{(\alpha)}^{(\beta)}))U, U)| \leq C \left(\sum_{j=1}^2 \|U_j\|^2 + (\text{Op}(b)U_3, U_3) + \|\langle D \rangle^{-1}U\|^2 \right).$$

Similar arguments are applied to $|(\text{Op}(\varphi_{(\beta)}^{(\alpha)} S_{(\alpha)}^{(\beta)})U, U)|$. Finally, since

$$\langle\xi\rangle\#(\varphi S) - (\varphi S)\#\langle\xi\rangle = \begin{pmatrix} S^0 & S^0 & \mathcal{O}(\sqrt{b})S^0 + S^{-1} \\ S^0 & S^0 & \mathcal{O}(\sqrt{b})S^{-1} + S^{-1} \\ \mathcal{O}(\sqrt{b})S^0 + S^{-1} & \mathcal{O}(\sqrt{b})S^0 + S^{-1} & \mathcal{O}(b)S^0 + \mathcal{O}(\sqrt{b})S^{-1} + S^{-2} \end{pmatrix},$$

we obtain

Lemma 3.6. *Assume $\langle\xi\rangle^\alpha c_{(\beta)}^{(\alpha)} = \mathcal{O}(b)$ for $|\alpha + \beta| = 1$ and $\langle\xi\rangle^\alpha c_{(\beta)}^{(\alpha)} = \mathcal{O}(\sqrt{b})$ for $|\alpha + \beta| = 2$. Then there exists $C > 0$ such that*

$$|(\text{Op}(S\#\varphi\#\langle\xi\rangle) - \langle\xi\rangle\#\varphi\#S)U, U)| \leq C\left(\sum_{j=1}^2 \|U_j\|^2 + (\text{Op}(b)U_3, U_3) + \|\langle D \rangle^{-1}U\|^2\right).$$

Combining Lemmas 3.5, 3.6 and Corollary 2.2, one concludes that for sufficiently large $N_1 > 0$ we have

$$(3.4) \quad \begin{aligned} & -N_1(\text{Op}(\tilde{S})U, U) - 2t\text{Im}(\text{Op}(S)(\text{Op}(\varphi)\langle D \rangle + \text{Op}(A)\langle D \rangle)U, U) \\ & \leq (-N_1\varepsilon_1 + 2C)t\left(\sum_{j=1}^2 \|U_j\|^2 + (\text{Op}(b)U_3, U_3)\right) + (-N_1(\lambda/2)t^{-1} + 2Ct)\|\langle D \rangle^{-1}U\|^2 \leq 0. \end{aligned}$$

Now we pass to the analysis of the term involving $\partial_t S$.

Lemma 3.7. *Assume $\partial_t c = \mathcal{O}(b)$. For $\varepsilon > 0$ sufficiently small we have*

$$S \gg \varepsilon t \partial_t S.$$

Proof. Since $\partial_t c = \mathcal{O}(b)$, one has

$$3S - \varepsilon t \partial_t S = \begin{pmatrix} 3 & 2a + \varepsilon \mathcal{O}(t) & -b + \varepsilon \mathcal{O}(t) \\ 2a + \varepsilon \mathcal{O}(t) & 2a^2 + 2b + \varepsilon \mathcal{O}(t) & -ab - 3c + \varepsilon \mathcal{O}(at) + \varepsilon \mathcal{O}(bt) \\ -b + \varepsilon \mathcal{O}(t) & -ab - 3c + \varepsilon \mathcal{O}(at) + \varepsilon \mathcal{O}(bt) & b^2 - 2ac + \varepsilon \mathcal{O}(bt) \end{pmatrix}.$$

It is not difficult to see that

$$\det(3S - \varepsilon t \partial_t S) = \det 3S + \varepsilon \mathcal{O}(b^2(b + a^2))$$

because $t = \mathcal{O}(b)$. □

Lemma 3.8. *Assume $\partial_t c = \mathcal{O}(b)$, $\langle \xi \rangle^\alpha c_{(\beta)}^{(\alpha)} = \mathcal{O}(\sqrt{b})$ for $|\alpha + \beta| = 2$ and $\langle \xi \rangle^\alpha (ac)_{(\beta)}^{(\alpha)} = \mathcal{O}(\sqrt{b})$ for $|\alpha + \beta| = 3$. There exist $\varepsilon > 0$ and $C > 0$ such that for $U \in C^\infty(\mathbb{R}_t : C_0^\infty(\mathbb{R}^n))$ we have*

$$(3.5) \quad \text{Re}(\text{Op}(S - \varepsilon t \partial_t S)U, U) \geq -\varepsilon t \left(\sum_{j=1}^2 \|U_j\|^2 + (\text{Op}(b)U_3, U_3)\right) - Ct^{-1}\varepsilon^{-1}\|\langle D \rangle^{-1}U\|^2.$$

Proof. Denoting $Q = S - 2\varepsilon t \partial_t S$, it suffices to prove

$$(3.6) \quad \left| \text{Re}(\text{Op}\left(\sum_{2 \leq |\alpha + \beta| \leq 3} \psi_{\alpha\beta} Q_{(\beta)}^{(\alpha)}\right)U, U) \right| \leq \varepsilon t \left(\sum_{j=1}^2 \|U_j\|^2 + (\text{Op}(b)U_3, U_3)\right) + C\varepsilon^{-1}t^{-1}\|\langle D \rangle^{-1}U\|^2.$$

Consider $\text{Re}(\text{Op}(\psi_{\alpha\beta} Q_{(\beta)}^{(\alpha)})U, U)$ with $|\alpha + \beta| = 2$. Note that

$$\psi_{\alpha\beta} Q_{(\beta)}^{(\alpha)} = \begin{pmatrix} 0 & S^{-1} & S^{-1} \\ S^{-1} & S^{-1} & S^{-1} \\ S^{-1} & S^{-1} & \psi_{\alpha\beta}(g_{(\beta)}^{(\alpha)} - \varepsilon t(\partial_t g)_{(\beta)}^{(\alpha)}) \end{pmatrix},$$

where $g = b^2 - 2ac$. Consequently, one deduce

$$\begin{aligned} |(\text{Op}(\psi_{\alpha\beta} Q_{(\beta)}^{(\alpha)})U, U)| & \leq \varepsilon t \sum_{j=1}^2 \|U_j\|^2 + C\varepsilon^{-1}t^{-1}\|\langle D \rangle^{-1}U\|^2 \\ & \quad + |\text{Re}(\text{Op}(\psi_{\alpha\beta}(g_{(\beta)}^{(\alpha)} - \varepsilon t(\partial_t g)_{(\beta)}^{(\alpha)}))U_3, U_3)|. \end{aligned}$$

Setting

$$T = \psi_{\alpha\beta}(g_{(\beta)}^{(\alpha)} - \varepsilon t(\partial_t g)_{(\beta)}^{(\alpha)})\langle \xi \rangle \in S^0,$$

we obtain $\operatorname{Re}(\psi_{\alpha\beta}(g_{(\beta)}^{(\alpha)} - \varepsilon t(\partial_t g)_{(\beta)}^{(\alpha)})) = T\#\langle \xi \rangle^{-1} + S^{-2}$. Therefore

$$\operatorname{Re}(\operatorname{Op}(\psi_{\alpha\beta}(g_{(\beta)}^{(\alpha)} - \varepsilon t(\partial_t g)_{(\beta)}^{(\alpha)}))U_3, U_3) \leq \varepsilon t\|\operatorname{Op}(T)U_3\|^2 + C\varepsilon^{-1}t^{-1}\|\langle D \rangle^{-1}U_3\|^2.$$

Note that $\|\operatorname{Op}(T)U_3\|^2 = (\operatorname{Op}(T\#T)U_3, U_3)$ and $T\#T = T^2 + S^{-2}$. There is $C > 0$ such that

$$T^2 \leq Cb$$

because $t = \mathcal{O}(b)$ and $\langle \xi \rangle^\alpha c_{(\beta)}^{(\alpha)} = \mathcal{O}(\sqrt{b})$ so that $Cb - T^2 \geq 0$. Then applying the Fefferman-Phong inequality, we prove the assertion. Let $|\alpha + \beta| = 3$ then with $T_1 = (\psi_{\alpha\beta}(g_{(\beta)}^{(\alpha)} - \varepsilon t(\partial_t g)_{(\beta)}^{(\alpha)}))\#\langle \xi \rangle^{3/2}$

$$T_1^2 \leq Cb$$

with some $C > 0$ since $t = \mathcal{O}(b)$ and $\langle \xi \rangle^\alpha (ac)_{(\beta)}^{(\alpha)} = \mathcal{O}(\sqrt{b})$ and the proof is similar. □

From (3.5) setting $N_2 = \varepsilon^{-1}$ and dividing by ε , one deduces

$$\operatorname{Re}(\operatorname{Op}(-N_2S + t\partial_t S)U, U) \leq t\left(\sum_{j=1}^2 \|U_j\|^2 + (\operatorname{Op}(b)U_3, U_3)\right) + Ct^{-1}\varepsilon^{-2}\|\langle D \rangle^{-1}U\|^2$$

and applying Corollary 2.2, this implies

$$(3.7) \quad \begin{aligned} & -(N_2 + N_3)\operatorname{Re}(\operatorname{Op}(\tilde{S})U, U) + t\operatorname{Re}(\operatorname{Op}(\partial_t S)U, U) \\ & \leq (-N_3\varepsilon_1 + 1)t\left(\sum_{j=1}^2 \|U_j\|^2 + (\operatorname{Op}(b)U_3, U_3)\right) + t^{-1}(C\varepsilon^{-2} - N_3\lambda)\|\langle D \rangle^{-1}U\|^2. \end{aligned}$$

Fixing ε and N_2 , we choose N_3 sufficiently large and we arrange the right hand side of the above inequality to be negative.

Next we turn to the analysis of $2\operatorname{Im}(\operatorname{Op}(\tilde{S})\operatorname{Op}(B)U, U)$. Recall that $(\operatorname{Op}(\tilde{S})U, U) \gg 0$ by Corollary 2.3. Consequently,

$$(3.8) \quad \begin{aligned} & 2|(\operatorname{Op}(\tilde{S})\operatorname{Op}(B)U, U)| \leq N^{-1/2}(t\operatorname{Op}(\tilde{S})\operatorname{Op}(B)U, \operatorname{Op}(B)U) + N^{1/2}(t^{-1}\operatorname{Op}(\tilde{S})U, U) \\ & = N^{-1/2}(t\operatorname{Op}(B^*)\operatorname{Op}(\tilde{S})\operatorname{Op}(B)U, U) + N^{1/2}(t^{-1}\operatorname{Op}(\tilde{S})U, U) \\ & \leq N^{-1/2}(t^{-1}t^2\operatorname{Op}(B^*)\operatorname{Op}(S)\operatorname{Op}(B)U, U) + N^{1/2}(t^{-1}\operatorname{Op}(\tilde{S})U, U) + C_2\lambda N^{-1/2}\|\langle D \rangle^{-1}U\|^2. \end{aligned}$$

Lemma 3.9. *There exists $N_4 > 0$ depending on T and B such that for $0 \leq t \leq T$ and any $\varepsilon > 0$ there exists $D_\varepsilon > 0$ such that*

$$\operatorname{Re}(\operatorname{Op}(N_4S - t^2B^*SB)U, U) \geq -\varepsilon t\left(\sum_{j=1}^2 \|U_j\|^2 + (cU_3, U_3)\right) - D_\varepsilon t^{-1}\|\langle D \rangle^{-1}U\|^2.$$

Proof. Recall

$$3S - \varepsilon t^2 B^* S B = \begin{pmatrix} 3 + \varepsilon \mathcal{O}(t^2) & 2a + \varepsilon \mathcal{O}(t^2) & -b + \varepsilon \mathcal{O}(t^2) \\ 2a + \varepsilon \mathcal{O}(t^2) & 2(a^2 + b) + \varepsilon \mathcal{O}(t^2) & -ab - 3c + \varepsilon \mathcal{O}(t^2) \\ -b + \varepsilon \mathcal{O}(t^2) & -ab - 3c + \varepsilon \mathcal{O}(t^2) & b^2 - 2ac + \varepsilon \mathcal{O}(t^2) \end{pmatrix}$$

which proves $3S - \varepsilon t^2 B^* S B \gg 0$ with some $\varepsilon = \varepsilon(T) > 0$. To justify this, notice that the terms $\varepsilon \mathcal{O}(t^2 b)$, $\varepsilon \mathcal{O}(t^2 c)$, $\varepsilon \mathcal{O}(t^2 a^2)$, $\varepsilon \mathcal{O}(t^4 a)$ can be absorbed by $\det S$ because $b \geq \delta_1 t$. For example,

$$\varepsilon t^4 |a| \leq \frac{1}{2} \varepsilon (t^5 + t^3 a^2) \leq C \varepsilon t b^2 (a^2 + b).$$

Choosing $\varepsilon(T)$ small enough, we obtain the result. Then the rest of the proof is just a repetition of the proof of Lemma 3.8. \square

According to Lemma 3.9 and (3.8), one has

$$(3.9) \quad 2|(\text{Op}(\tilde{S})\text{Op}(B)U, U)| \leq 2N_4^{1/2} t^{-1} |(\text{Op}(\tilde{S})U, U)| + \varepsilon t \left(\sum_{j=1}^2 \|U_j\|^2 + (\text{Op}(b)U_3, U_3) \right) - N_4^{1/2} \lambda t^{-2} \| \langle D \rangle^{-1} U \|^2 + D_\varepsilon t^{-1} \| \langle D \rangle^{-1} U \|^2 + C_2 \lambda N_4^{-1/2} \| \langle D \rangle^{-1} U \|^2.$$

Combining the estimates (3.4), (3.7), (3.9), it follows that

$$\begin{aligned} \partial_t \text{Re}(t^{-N} e^{-\gamma t} \text{Op}(\tilde{S})U, U) &\leq -2\text{Im}(t^{-N} e^{-\gamma t} \text{Op}(\tilde{S})F, U) \\ &\quad - (N - N_1 - N_2 - N_3 - 2N_4^{1/2}) t^{-N-1} e^{-\gamma t} \text{Re}(\text{Op}(\tilde{S})U, U) \\ &\quad + [C_\varepsilon - \lambda(N + 1 + N_4^{1/2} - \lambda C \varepsilon^{-1})] t^{-N-2} e^{-\gamma t} \| \langle D \rangle^{-1} U \|^2 \\ &\quad + \varepsilon t^{-N} e^{-\gamma t} \left(\sum_{j=1}^2 \|U_j\|^2 + (\text{Op}(b)U_3, U_3) \right) \\ &\quad - (\gamma - D_\varepsilon - C_1 \lambda - C t \lambda N_4^{-1/2}) t^{-N-1} e^{-\gamma t} \| \langle D \rangle^{-1} U \|^2. \end{aligned}$$

Note that

$$\begin{aligned} 2|(t^{-N} e^{-\gamma t} \text{Op}(\tilde{S})F, U)| &\leq 2(t^{-N+1} e^{-\gamma t} \text{Op}(\tilde{S})F, F)^{1/2} (t^{-N-1} e^{-\gamma t} \text{Op}(\tilde{S})U, U)^{1/2} \\ &\leq (t^{-N+1} e^{-\gamma t} \text{Op}(\tilde{S})F, F) + (t^{-N-1} e^{-\gamma t} \text{Op}(\tilde{S})U, U). \end{aligned}$$

Denote $N^* = N_1 + N_2 + N_3 + 2N_2^{1/2} + 2$ and we choose $0 < \varepsilon \leq \varepsilon_1$. We fix ε and $\lambda > 2C_\varepsilon$. Next we fix N_4 so that

$$N_4^{1/2} > \lambda C \varepsilon^{-1} + 1.$$

Then the term with $t^{-N-2} e^{-\gamma t} \| \langle D \rangle^{-1} U \|^2$ is absorbed. Finally we choose $N > N^*$ and γ such that $\gamma - D_\varepsilon - C_1 \lambda - C \lambda N_4^{-1/2} T \geq 0$. Then we have

$$(3.10) \quad \partial_t \text{Re}(t^{-N} e^{-\gamma t} \text{Op}(\tilde{S})U, U) \leq (t^{-N+1} e^{-\gamma t} \text{Op}(\tilde{S})F, F) - (N - N^*) \text{Re}(t^{-N-1} e^{-\gamma t} \text{Op}(\tilde{S})U, U).$$

Integrating (3.10) in τ from $\varepsilon > 0$ to t and taking Corollary 2.3 into account, one obtains

Proposition 3.1. *Assume that*

$$(3.11) \quad \begin{aligned} b &\geq \delta_1 t, \quad |ac| \leq \bar{\varepsilon} b^2, \quad |c| \leq \bar{\varepsilon} b^{3/2}, \\ \langle \xi \rangle^\alpha c_{(\beta)}^{(\alpha)} &= \mathcal{O}(b) \text{ for } |\alpha + \beta| = 1, \quad \langle \xi \rangle^\alpha c_{(\beta)}^{(\alpha)} = \mathcal{O}(\sqrt{b}) \text{ for } |\alpha + \beta| = 2, \\ \langle \xi \rangle^\alpha (ac)_{(\beta)}^{(\alpha)} &= \mathcal{O}(\sqrt{b}), \quad |\alpha + \beta| = 3, \quad \partial_t c = \mathcal{O}(b) \end{aligned}$$

hold globally where $\bar{\varepsilon}$ is given in Lemmas 2.2 and 2.3. Then there exist $\delta_2 > 0, \gamma_0 > 0, N \in \mathbb{N}$ and $C > 0$ such that for $\gamma \geq \gamma_0, 0 < \varepsilon \leq t \leq T$ and for any $U \in C^\infty(\mathbb{R}_t : C_0^\infty(\mathbb{R}^n))$ we have

$$\begin{aligned} &\delta_2 t^{-N+2} e^{-\gamma t} \|U(t)\|^2 + \delta_2 (N - N^*) \int_\varepsilon^t \tau^{-N+1} e^{-\gamma \tau} \|U(\tau)\|^2 d\tau \\ &\leq C \varepsilon^{-N-1} e^{-\gamma \varepsilon} \|U(\varepsilon)\|^2 + \int_\varepsilon^t \tau^{-N+1} e^{-\gamma \tau} (\text{Op}(\tilde{S})F(\tau), F(\tau)) d\tau. \end{aligned}$$

4. Microlocal energy estimates

First we prove the following

Lemma 4.10. *Assume that (1.3) is satisfied in $[0, T] \times \tilde{W}$ where \tilde{W} is a conic neighborhood of (x_0, ξ_0) . Then there exist extensions $\tilde{a}(t, x, \xi) \in S^0, \tilde{b}(t, x, \xi) \in S^0$ and $\tilde{c}(t, x, \xi) \in S^0$ of a, b and c such that (3.11) holds globally.*

Proof. Assume that (1.3) is satisfied in $[0, T] \times \tilde{W}$. Choose conic neighborhoods U, V, W of (x_0, ξ_0) such that $U \Subset V \Subset W \Subset \tilde{W}$. Take $0 \leq \chi(x, \xi) \in S^0, 0 \leq \tilde{\chi}(x, \xi) \in S^0$ such that $\chi = 1$ on V and $\chi = 0$ outside W and $\tilde{\chi} = 0$ on U and $\tilde{\chi} = 1$ outside V . Choosing W and T small one can assume that χb is small as we please in $[0, T] \times \mathbb{R}^{2n}$ because $b(0, x_0, \xi_0) = 0$. We define the extensions of a, b, c by

$$\tilde{a} = \chi a, \quad \tilde{b} = \chi^2 b + M \tilde{\chi}, \quad \tilde{c} = \chi^3 c$$

where $M > 0$ is a positive constant which we will choose below. Note that

$$\begin{aligned} |\tilde{a}\tilde{c}| &= \chi^4 |ac| \leq C |a| \chi^4 b^2 \leq \bar{\varepsilon} (\chi^2 b)^2 \leq \bar{\varepsilon} \tilde{b}^2, \\ |\tilde{c}| &= \chi^3 |c| \leq C \chi^3 b^2 = C b^{1/2} (\chi^2 b)^{3/2} \leq \bar{\varepsilon} \tilde{b}^{3/2} \end{aligned}$$

taking $a(0, x_0, \xi_0) = 0, b(0, x_0, \xi_0) = 0$ into account and choosing W small.

If $(x, \xi) \in V$ then $\tilde{b}(t, x, \xi) = b + M \tilde{\chi} \geq \delta_1 t$ and if (x, ξ) is outside V then $\tilde{b}(t, x, \xi) = \chi^2 b + M \geq \delta_1 t$ for $[0, T] \times \mathbb{R}^{2n}$ choosing M so that $M \geq \delta_1 T$. Thus we have

$$\tilde{b}(t, x, \xi) \geq \delta_1 t \quad (t, x, \xi) \in [0, T] \times \mathbb{R}^{2n}.$$

We turn to estimate derivatives of \tilde{c} and $\tilde{a}\tilde{c}$. For $|\alpha + \beta| = 1$ it is clear that

$$\langle \xi \rangle^{|\alpha|} |\tilde{c}_{(\beta)}^{(\alpha)}| = \langle \xi \rangle^{|\alpha|} |(\chi^3 c)_{(\beta)}^{(\alpha)}| \leq C (\chi^2 b^2 + \chi^3 b) \leq C_1 \chi^2 b \leq C_1 \tilde{b}.$$

Similarly for $|\alpha + \beta| = 2$ one sees

$$\langle \xi \rangle^{|\alpha|} |(\chi^3 c)_{(\beta)}^{(\alpha)}| \leq C (\chi b^2 + \chi^2 b + \chi^3 \sqrt{b}) \leq C_1 \chi \sqrt{b} = C_1 (\chi^2 b)^{1/2} \leq C_1 \tilde{b}^{1/2}.$$

For $|\alpha + \beta| = 3$, taking $\langle \xi \rangle^\alpha (ac)_{(\beta)}^{(\alpha)} = \mathcal{O}(\sqrt{b})$ into account, one has

$$\langle \xi \rangle^{|\alpha|} |(\tilde{a}\tilde{c})_{(\beta)}^{(\alpha)}| = \langle \xi \rangle^{|\alpha|} |(\chi^4 ac)_{(\beta)}^{(\alpha)}|$$

$$\leq C(\chi b^2 + \chi^2 b + \chi^3 \sqrt{b} + \chi^4 \sqrt{b}) \leq C_1 \chi \sqrt{b} \leq C_1 \tilde{b}^{1/2}.$$

Since $|\partial_t \tilde{c}| = |\chi^3 \partial_t c| \leq C \chi^3 b \leq C \tilde{b}$ is obvious the proof is complete. \square

REMARK 4.2. In the proof of Lemma 4.10 replacing \tilde{b} by $\chi^2 b + M\tilde{\chi} + M'\chi_0(\xi)$ where $\chi_0(\xi) \in C_0^\infty(\mathbb{R}^n)$ which is 1 near $\xi = 0$ and $M' > 0$ is a suitable positive constant it suffices to assume that (1.3) is satisfied in $[0, T] \times \tilde{W}$ for $|\xi| \geq 1$.

Let $V \Subset V_1 \Subset \Omega$ and $u \in C^\infty(\mathbb{R}_t : C_0^\infty(V))$. Let $\{\chi_\alpha\}$ be a finite partition of unity with $\chi_\alpha(x, \xi) \in S^0$ so that

$$\sum_\alpha \chi_\alpha^2(x, \xi) = \chi^2(x),$$

where $\chi(x) = 1$ on \bar{V} and $\text{supp } \chi \subset V_1$. We can suppose that $\text{supp } \chi_\alpha \subset V_1$. We repeat the argument in [11, Section 4], studying a system

$$D_t U_\alpha = (\text{Op}(\varphi)\langle D \rangle + \text{Op}(A)\langle D \rangle + \text{Op}(B))U_\alpha + F_\alpha$$

with $U_\alpha = {}^t((D_t - \text{Op}(\varphi)\langle D \rangle)^2 \chi_\alpha u, \langle D \rangle(D_t - \text{Op}(\varphi)\langle D \rangle)\chi_\alpha u, \langle D \rangle^2 \chi_\alpha u)$. One extends the coefficients a, b, c and φ outside the support of χ_α and one can assume that (3.11) are satisfied globally. Thus we obtain the following

Theorem 4.1. *Let $Y \Subset \Omega$. Assume that for every point $(x_0, \xi_0) \in T^*\Omega \setminus \{0\}$ there exist a conic neighborhood $W \subset T^*\Omega \setminus \{0\}$ and $T(x_0, \xi_0) > 0$ such that the estimates (3.11) are satisfied for $0 \leq t \leq T(x_0, \xi_0)$ and $(x, \xi) \in W$. Then there exist $c > 0, T_0 > 0, \gamma_0 > 0, C > 0$ and $N \in \mathbb{N}$ such that for $\gamma \geq \gamma_0, 0 < \varepsilon < t \leq T_0$ and for any $U \in C^\infty(\mathbb{R}_t : C_0^\infty(Y))$ we have*

$$(4.1) \quad c t^{-N+2} e^{-\gamma t} \|U(t)\|^2 + c \int_\varepsilon^t \tau^{-N+1} e^{-\gamma \tau} \|U(\tau)\|^2 d\tau \\ \leq C \varepsilon^{-N-1} e^{-\gamma \varepsilon} \|U(\varepsilon)\|^2 + C \int_\varepsilon^t \tau^{-N+1} e^{-\gamma \tau} \|f(\tau)\|^2 d\tau.$$

Corollary 4.4. *Let $Y \Subset \Omega$. Assume that for every point $(x_0, \xi_0) \in T^*\Omega \setminus \{0\}$ there exist a conic neighborhood $W \subset T^*\Omega \setminus \{0\}$ and $T(x_0, \xi_0) > 0$ such that the estimates (1.3) are satisfied for $0 \leq t \leq T(x_0, \xi_0)$ and $(x, \xi) \in W$. Then the same assertion as in Theorem 4.1 holds.*

The same argument can be applied for the adjoint operator P^* . With

$$V = {}^t((D_t - \text{Op}(\varphi)\langle D \rangle)^2 v, \langle D \rangle(D_t - \text{Op}(\varphi)\langle D \rangle)v, \langle D \rangle^2 v)$$

the equation $P^*v = g$ is reduced to

$$(4.2) \quad D_t V = \text{Op}(\varphi)\langle D \rangle V + (\text{Op}(A)\langle D \rangle + \text{Op}(\tilde{B}))V + G,$$

with $G = {}^t(g, 0, 0)$. Here the principal symbol is the same, while the lower order terms change. To study the Cauchy problem for P^* in $0 < t < T$ with initial data on $t = T$ one considers

$$(4.3) \quad -\partial_t(t^N e^{\gamma t} \text{Op}(\tilde{S})V, V) = -N(t^{N-1} e^{\gamma t} \text{Op}(\tilde{S})V, V) - \gamma(t^N e^{\gamma t} \text{Op}(\tilde{S})V, V) \\ - (t^N e^{\gamma t} \text{Op}(\partial_t \tilde{S})V, V) - \lambda(N-1)t^{N-2} e^{\gamma t} \|\langle D \rangle^{-1} U\|^2 - \lambda \gamma t^{N-1} e^{\gamma t} \|\langle D \rangle^{-1} U\|^2 \\ + 2\text{Im}(t^N e^{\gamma t} (\text{Op}(\tilde{S})(\text{Op}(\varphi)\langle D \rangle + \text{Op}(A)\langle D \rangle + \text{Op}(\tilde{B}))V, V)) + 2\text{Im}(t^N e^{\gamma t} \text{Op}(\tilde{S})G, V).$$

Repeating the argument of Section 3, one obtains the following

Theorem 4.2. *Let $Y \Subset \Omega$. Assume that for every point $(x_0, \xi_0) \in T^*\Omega \setminus \{0\}$ there exist a conic neighborhood $W \subset T^*\Omega \setminus \{0\}$ and $T(x_0, \xi_0) > 0$ such that the estimates (3.11) are satisfied for $0 \leq t \leq T(x_0, \xi_0)$ and $(x, \xi) \in W$. Then there exist $c > 0, T_0 > 0, \gamma_0 > 0, C > 0$ and $N \in \mathbb{N}$ such that for $\gamma \geq \gamma_0, 0 < \varepsilon < t \leq T_0$ and for any $V \in C^\infty(\mathbb{R}_t : C_0^\infty(Y))$ we have*

$$(4.4) \quad \begin{aligned} & c t^{N+2} e^{\gamma t} \|V(t)\|^2 + c \int_t^{T_0} \tau^{N+1} e^{\gamma \tau} \|V(\tau)\|^2 d\tau \\ & \leq C T_0^{N-1} e^{\gamma T_0} \|V(T_0)\|^2 + C \int_t^{T_0} \tau^{N+1} e^{\gamma \tau} \|g(\tau)\|^2 d\tau. \end{aligned}$$

Following the argument in [11], we may absorb the weight τ^{-N} and obtain energy estimates with a loss of derivatives. For the sake of completeness we recall this argument. Consider $Pu = f$ for $u \in C^\infty(\mathbb{R}_t : C_0^\infty(\mathbb{R}^n))$. Assume $u(\varepsilon, x) = u_t(\varepsilon, x) = u_{tt}(\varepsilon, x) = 0$. Differentiating $Pu = f$ with respect to t , we determine the functions $D_t^j u(\varepsilon, x) = u_j(x) \in C_0^\infty(\mathbb{R}^n)$ and set

$$u_M(t, x) = \sum_{j=0}^M \frac{1}{j!} u_j(x) (i(t - \varepsilon))^j, \quad 0 < \varepsilon \leq t \leq T_0.$$

Therefore $w = u - u_M \in C^\infty(\mathbb{R}_t : C_0^\infty(\mathbb{R}^n))$ satisfies $Pw = f_M$ with

$$D_t^j f_M(\varepsilon, x) = 0, \quad j = 0, 1, \dots, M - 3, \quad D_t^j w(\varepsilon, x) = 0, \quad j = 0, 1, \dots, M.$$

Consequently, from Theorem 4.1 one deduce the existence of $N \in \mathbb{N}$ and $C > 0$ such that for $\varepsilon > 0$, and a solution $u \in C^\infty([\varepsilon, T_0] \times C_0^\infty(Y))$ to the equation $Pu = f$ with

$$u(\varepsilon, x) = u_t(\varepsilon, x) = u_{tt}(\varepsilon, x) = 0$$

we have

$$(4.5) \quad \sum_{j+|\alpha| \leq 2} \int_\varepsilon^t \|\partial_t^j \partial_x^\alpha u(s, x)\|^2 ds \leq C \int_\varepsilon^t \sum_{j+|\alpha| \leq N} \|\partial_t^j \partial_x^\alpha Pu(s, x)\|^2 ds,$$

where C is independent of ε . We can obtain a similar estimates for higher order derivatives.

Note that under the assumptions of Theorem 4.1 the symbol p is strictly hyperbolic for $0 < t \leq T_0$ with some $T_0 > 0$. Indeed the fact that p is strictly hyperbolic for $0 < t \leq T_0$, is equivalent to $\Delta > 0$ for $0 < t \leq T_0$, Δ being the discriminant of the equation $p = 0$ with respect to τ . On the other hand, $\Delta = 27 \det S$ (see also Corollary 2.1) and $\det S > 0$ for $t > 0$ by Lemma 2.2. Therefore applying the estimate (4.5) and repeating the argument in [3, Theorem 23.4.5] one can find $Z \Subset \Omega$ and $T^* > 0$ such that for $f \in C_0^\infty([0, T_0] \times \Omega)$ there exists $u \in C_0^\infty([0, T_0] \times \Omega)$ satisfying $Pu = f$ in $[0, T^*] \times Z$. The local uniqueness of the solution of the Cauchy problem for P can be obtained taking into account Theorem 4.2 for the adjoint operator P^* and using the argument of [3, Theorem 23.4.5]. We leave the details to the reader.

Finally, we deduce

Corollary 4.5. *Under the assumptions of Theorem 4.1 the Cauchy problem for P is C^∞ well posed in $[0, T^*] \times Z$ for all lower order terms.*

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