

GLOBAL ASYMPTOTICS TOWARD THE RAREFACTION WAVES FOR SOLUTIONS TO THE CAUCHY PROBLEM OF THE SCALAR CONSERVATION LAW WITH NONLINEAR VISCOSITY

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Abstract

In this paper, we investigate the asymptotic behavior of solutions to the Cauchy problem for the scalar viscous conservation law where the far field states are prescribed. Especially, we deal with the case when the viscosity is of non-Newtonian type, including a pseudo-plastic case. When the corresponding Riemann problem for the hyperbolic part admits a Riemann solution which consists of single rarefaction wave, under a condition on nonlinearity of the viscosity, it is proved that the solution of the Cauchy problem tends toward the rarefaction wave as time goes to infinity, without any smallness conditions.

1. Introduction and main theorems

In this paper, we consider the asymptotic behavior of solutions to the Cauchy problem for a one-dimensional scalar conservation law with nonlinear viscosity

$$(1.1) \quad \begin{cases} \partial_t u + \partial_x (f(u) - \sigma(\partial_x u)) = 0 & (t > 0, x \in \mathbb{R}), \\ u(0, x) = u_0(x) & (x \in \mathbb{R}), \\ \lim_{x \rightarrow \pm\infty} u(t, x) = u_{\pm} & (t \geq 0). \end{cases}$$

Here, $u = u(t, x)$ is the unknown function of $t > 0$ and $x \in \mathbb{R}$, the so-called conserved quantity, the functions f and $-\sigma$ stand for the convective flux and viscous/diffusive one, respectively, u_0 is the initial data, and $u_{\pm} \in \mathbb{R}$ are the prescribed far field states. We suppose that f is a smooth function, and σ is a smooth function satisfying

$$(1.2) \quad \sigma(0) = 0, \quad \sigma'(v) > 0 \quad (v \in \mathbb{R}),$$

and for some $p > 0$

$$(1.3) \quad |\sigma(v)| \sim |v|^p, \quad |\sigma'(v)| \sim |v|^{p-1} \quad (|v| \rightarrow \infty).$$

A typical example of σ in the field of viscous fluid, where u corresponds to the fluid velocity, is

$$(1.4) \quad \sigma(\partial_x u) = \mu \left(1 + |\partial_x u|^2 \right)^{\frac{p-1}{2}} \partial_x u$$

where $\mu > 0$ is a positive constant, which describes a nonlinear relation between the internal stress σ and the deformation velocity $\partial_x u$, and it is noted that the cases $p > 1$, $p = 1$ and $p < 1$ physically correspond to where the fluid is of dilatant type, Newtonian and pseudo-plastic type, respectively (see [3], [4], [5], [14], [23], [26], [27], [38] and so on). We are interested in the global asymptotics for the solution of (1.1), in particular, the pseudo-plastic case $p < 1$, since there seems no results ever on this case. First, when $u_- = u_+ (=:\tilde{u})$, we expect the solution globally tends toward the constant state \tilde{u} as time goes to infinity. In fact, we can show the following

Theorem 1.1. *Assume the far field states satisfy $u_- = u_+ (=:\tilde{u})$, the viscous flux σ , (1.2), (1.3), and $p > 3/7$. Further assume the initial data satisfy $u_0 - \tilde{u} \in H^2$. Then the Cauchy problem (1.1) has a unique global in time solution u satisfying*

$$\begin{cases} u - \tilde{u} \in C^0 \cap L^\infty([0, \infty); H^2), \\ \partial_x u \in L^2(0, \infty; H^2), \end{cases}$$

and the asymptotic behavior

$$\limsup_{t \rightarrow \infty} \sup_{x \in \mathbb{R}} |u(t, x) - \tilde{u}| = 0, \quad \limsup_{t \rightarrow \infty} \sup_{x \in \mathbb{R}} |\partial_x u(t, x)| = 0.$$

REMARK 1.1. Under the same assumptions in Theorem 1.1, if $\|\partial_x u_0\|_{H^1}$ is suitably small, the stability results in Theorems 1.1 follow for any $p > 0$.

Next, we consider the case where the convective flux function f is fully convex, that is,

$$(1.5) \quad f''(u) > 0 \quad (u \in \mathbb{R}),$$

and $u_- < u_+$. Then, since the corresponding Riemann problem (cf. [22], [37])

$$(1.6) \quad \begin{cases} \partial_t u + \partial_x(f(u)) = 0 & (t > 0, x \in \mathbb{R}), \\ u(0, x) = u_0^R(x) := \begin{cases} u_- & (x < 0), \\ u_+ & (x > 0), \end{cases} \end{cases}$$

turns out to admit a single rarefaction wave solution, we expect that the solution of the Cauchy problem (1.1) globally tends toward the rarefaction wave as time goes to infinity. Here, the rarefaction wave connecting u_- to u_+ is given by

$$(1.7) \quad u^r\left(\frac{x}{t}; u_-, u_+\right) = \begin{cases} u_- & (x \leq f'(u_-)t), \\ (f')^{-1}\left(\frac{x}{t}\right) & (f'(u_-)t \leq x \leq f'(u_+)t), \\ u_+ & (x \geq f'(u_+)t). \end{cases}$$

Then we can show the following

Theorem 1.2. *Assume the far field states satisfy $u_- < u_+$, the convective flux f , (1.5), the viscous flux σ , (1.2), (1.3), and $p > 3/7$. Further assume the initial data satisfy $u_0 - u_0^R \in L^2$, and $\partial_x u_0 \in H^1$. Then the Cauchy problem (1.1) has a unique global in time solution u satisfying*

$$\begin{cases} u - u_0^R \in C^0 \cap L^\infty([0, \infty); L^2), \\ \partial_x u \in C^0 \cap L^\infty([0, \infty); H^1) \cap L^2_{\text{loc}}(0, \infty; H^2), \end{cases}$$

and the asymptotic behavior

$$\limsup_{t \rightarrow \infty} \sup_{x \in \mathbb{R}} \left| u(t, x) - u^r \left(\frac{x}{t}; u_-, u_+ \right) \right| = 0,$$

$$\limsup_{t \rightarrow \infty} \sup_{x \in \mathbb{R}} \left| \partial_x u(t, x) - \partial_x U(t, x; u_-, u_+) \right| = 0,$$

where U is a smooth approximation for u^r which is defined by (2.6).

REMARK 1.2. Under the same assumptions in Theorem 1.2, if $|u_- - u_+|$ and

$$\| \partial_x u_0 - \partial_x U(0, \cdot; u_-, u_+) \|_{H^1}$$

are suitably small, the stability results in Theorems 1.2 follow for any $p > 0$.

It should be emphasized again that as far as the global asymptotic stability for either constant states or rarefaction waves, there have been no results for the case $p < 1$ (pseudo-plastic type viscosity). For the case $p = 1$ (Newtonian type viscosity), global nonlinear stability of both rarefaction wave and viscous shock wave were first obtained by Il'in-Oleĭnik [13]. For the case $p > 1$ (dilatant type viscosity), when the convective flux satisfies (1.5) and viscous flux is even the Ostwald-de Waele type (p -Laplacian type, see [6], [35]), that is,

$$(1.8) \quad \sigma(v) = \mu |v|^{p-1} v.$$

Matsumura-Nishihara [30] proved that if the far field states satisfy $u_- = u_+ (=:\tilde{u})$, then the solution globally tends toward the constant state \tilde{u} , and if $u_- < u_+$, then toward the rarefaction wave. Yoshida [43] also obtained the precise time-decay estimates of the solution toward the constant state and the single rarefaction wave. For $p \geq 1$, it is further considered a case where the flux function f is smooth and convex on the whole \mathbb{R} except a finite interval $I := (a, b) \subset \mathbb{R}$, and linearly degenerate on I , that is,

$$(1.9) \quad \begin{cases} f''(u) > 0 & (u \in (-\infty, a] \cup [b, \infty)), \\ f''(u) = 0 & (u \in (a, b)). \end{cases}$$

Under the conditions $p \geq 1$, $u_- < u_+$, (1.8), and (1.9), it is proved that the unique global in time solution to the Cauchy problem (1.1) globally tends toward the multiwave pattern of the combination of the viscous contact wave and the rarefaction waves as time goes to infinity, where the viscous contact wave is constructed by the linear heat kernel for $p = 1$ by Matsumura-Yoshida ([32]) (see also [47]), and also by the Barenblatt-Kompaneec-Zel'dovič solution (see also [1], [2], [11], [15], [39], [40], [48]) of the porous medium equation for $p > 1$ by Yoshida ([43], [44]). Yoshida ([41], [42], [45]) also obtained the precise time-decay estimates for these stability results. On the other hand, under the Rankine-Hugoniot condition

$$(1.10) \quad -s(u_+ - u_-) + f(u_+) - f(u_-) = 0,$$

and Oleĭnik's shock condition

$$(1.11) \quad -s(u - u_{\pm}) + f(u) - f(u_{\pm}) \begin{cases} < 0 & (u \in (u_+, u_-)), \\ > 0 & (u \in (u_-, u_+)), \end{cases}$$

the local asymptotic stability of viscous shock waves is proved for $p = 1$ by Matsumura-Nishihara ([31]), and very recently for any $p > 0$, more generally, for the case where smooth σ satisfies

$$(1.12) \quad \sigma(0) = 0, \quad \sigma'(v) > 0 \quad (v \in \mathbb{R}), \quad \lim_{v \rightarrow \pm\infty} \sigma(v) = \pm\infty,$$

by Yoshida ([46]), though the global asymptotic stability is still open.

The proofs of Theorem 1.1 and Theorem 1.2 are given by a technical energy method, and a Sobolev type inequality motivated by an idea in Kanel' ([16]). Because the proof of Theorem 1.1 and the proof of Theorem 1.2 with $p \geq 1$ are much easier than that of Theorem 1.2 with $0 < p < 1$, we only show Theorem 1.2 under the assumption $0 < p < 1$ in the present paper.

This paper is organized as follows. In Section 2, we prepare the basic properties of the rarefaction wave. In Section 3, we reformulate the problem in terms of the deviation from the asymptotic state. Also, in order to show the global solution in time and its asymptotic behavior for the reformulated problem, we show the strategy how the local existence and the *a priori* estimates are combined. In the remaining Section 4, Section 5, and Section 6, we give the proof of the *a priori* estimates step by step by using a technical energy method.

Some Notations. We denote by C generic positive constants unless they need to be distinguished. In particular, use $C_{\alpha, \beta, \dots}$ when we emphasize the dependency on α, β, \dots . For function spaces, $L^p = L^p(\mathbb{R})$ and $H^k = H^k(\mathbb{R})$ denote the usual Lebesgue space and k -th order Sobolev space on the whole space \mathbb{R} with norms $\|\cdot\|_{L^p}$ and $\|\cdot\|_{H^k}$, respectively.

2. Preliminaries

In this section, we prepare a couple of lemmas concerning with the basic properties of the rarefaction wave. Since the rarefaction wave u^r is not smooth enough, we need some smooth approximated one. We start with the rarefaction wave solution w^r to the Riemann problem for the non-viscous Burgers equation:

$$(2.1) \quad \begin{cases} \partial_t w + \partial_x \left(\frac{1}{2} w^2 \right) = 0 & (t > 0, x \in \mathbb{R}), \\ w(0, x) = w_0^R(x; w_-, w_+) := \begin{cases} w_+ & (x > 0), \\ w_- & (x < 0), \end{cases} \end{cases}$$

where $w_{\pm} \in \mathbb{R}$ are the prescribed far field states satisfying $w_- < w_+$. The unique global weak solution $w = w^r(x/t; w_-, w_+)$ of (2.1) is explicitly given by

$$(2.2) \quad w^r\left(\frac{x}{t}; w_-, w_+\right) = \begin{cases} w_- & (x \leq w_- t), \\ \frac{x}{t} & (w_- t \leq x \leq w_+ t), \\ w_+ & (x \geq w_+ t). \end{cases}$$

Next, under the condition $f''(u) > 0$ ($u \in \mathbb{R}$) and $u_- < u_+$, the rarefaction wave solution $u = u^r(x/t; u_-, u_+)$ of the Riemann problem (1.6) for hyperbolic conservation law is exactly

given by

$$(2.3) \quad u^r \left(\frac{x}{t}; u_-, u_+ \right) = (\lambda)^{-1} \left(w^r \left(\frac{x}{t}; \lambda_-, \lambda_+ \right) \right)$$

which is nothing but (1.7), where $\lambda(u) := f'(u)$ and $\lambda_{\pm} := \lambda(u_{\pm}) = f'(u_{\pm})$. We define a smooth approximation of $w^r(x/t; w_-, w_+)$ by the unique classical solution

$$w = w(t, x; w_-, w_+) \in C^\infty([0, \infty) \times \mathbb{R})$$

to the Cauchy problem for the following non-viscous Burgers equation

$$(2.4) \quad \begin{cases} \partial_t w + \partial_x \left(\frac{1}{2} w^2 \right) = 0 & (t > 0, x \in \mathbb{R}), \\ w(0, x) = w_0(x) := \frac{w_- + w_+}{2} + \frac{w_+ - w_-}{2} K_q \int_0^x \frac{dy}{(1+y^2)^q} & (x \in \mathbb{R}), \end{cases}$$

where K_q is a positive constant such that

$$K_q \int_0^\infty \frac{dy}{(1+y^2)^q} = 1 \quad \left(q > \frac{1}{2} \right).$$

By applying the method of characteristics, we get the following formula

$$(2.5) \quad \begin{cases} w(t, x) = w_0(x_0(t, x)) = \frac{\lambda_- + \lambda_+}{2} + \frac{\lambda_+ - \lambda_-}{2} K_q \int_0^{x_0(t, x)} \frac{dy}{(1+y^2)^q}, \\ x = x_0(t, x) + w_0(x_0(t, x))t. \end{cases}$$

By making use of (2.5) similarly as in [29], we obtain the properties of the smooth approximation $w(t, x; w_-, w_+)$ in the next lemma.

Lemma 2.1. *Assume $w_- < w_+$. Then the classical solution $w = w(t, x; w_-, w_+)$ given by (2.5) satisfies the following properties:*

- (1) $w_- < w(t, x) < w_+$ and $\partial_x w(t, x) > 0$ ($t > 0, x \in \mathbb{R}$).
- (2) For any $q > 1/2$ and $r \in [1, \infty]$, there exists a positive constant $C_{q,r}$ such that

$$\begin{aligned} \|\partial_x w(t)\|_{L^r} &\leq C_{q,r} (1+t)^{-1+\frac{1}{r}} \quad (t \geq 0), \\ \|\partial_x^2 w(t)\|_{L^r} &\leq C_{q,r} (1+t)^{-1-\frac{1}{2q}(1-\frac{1}{r})} \quad (t \geq 0), \\ \|\partial_x^3 w(t)\|_{L^r} &\leq C_{q,r} (1+t)^{-1-\frac{1}{2q}(2-\frac{1}{r})} \quad (t \geq 0). \end{aligned}$$

$$(3) \quad \limsup_{t \rightarrow \infty} \sup_{x \in \mathbb{R}} \left| w(t, x) - w^r \left(\frac{x}{t} \right) \right| = 0.$$

We now define the approximation for the rarefaction wave $u^r(x/t; u_-, u_+)$ by

$$(2.6) \quad U(t, x; u_-, u_+) = (\lambda)^{-1}(w(t, x; \lambda_-, \lambda_+)).$$

Noting the assumption of the smooth flux function f , we have the next lemma.

Lemma 2.2. *Assume $u_- < u_+$ and $f''(u) > 0$ ($u \in \mathbb{R}$). Then we have the following:*

- (1) $U(t, x)$ defined by (2.6) is the unique smooth global solution to the Cauchy problem

$$\begin{cases} \partial_t U + \partial_x(f(U)) = 0 & (t > 0, x \in \mathbb{R}), \\ U(0, x) = (\lambda)^{-1} \left(\frac{\lambda_- + \lambda_+}{2} + \frac{\lambda_+ - \lambda_-}{2} K_q \int_0^x \frac{dy}{(1+y^2)^q} \right) & (x \in \mathbb{R}), \\ \lim_{x \rightarrow \pm\infty} U(t, x) = u_{\pm} & (t \geq 0). \end{cases}$$

(2) $u_- < U(t, x) < u_+$ and $\partial_x U(t, x) > 0$ ($t > 0, x \in \mathbb{R}$).

(3) For any $q > 1/2$ and $r \in [1, \infty]$, there exists a positive constant $C_{q,r}$ such that

$$\begin{aligned} \|\partial_x U(t)\|_{L^r} &\leq C_{q,r} (1+t)^{-1+\frac{1}{r}} \quad (t \geq 0), \\ \|\partial_x^2 U(t)\|_{L^r} &\leq C_{q,r} (1+t)^{-1-\frac{1}{2q}(1-\frac{1}{r})} \quad (t \geq 0), \\ \|\partial_x^3 U(t)\|_{L^r} &\leq C_{q,r} (1+t)^{-1-\frac{1}{2q}(2-\frac{1}{r})} \quad (t \geq 0). \end{aligned}$$

(4) $\limsup_{t \rightarrow \infty} \sup_{x \in \mathbb{R}} \left| U(t, x) - u^r \left(\frac{x}{t} \right) \right| = 0.$

Because the proofs of them are well-known, we omit the proofs here (see [9], [10], [25], [29], [32], [41], and so on).

3. Reformulation of the problem

In this section, we reformulate our problem (1.1) in terms of the deviation from the asymptotic state. Now letting

(3.1) $u(t, x) = U(t, x) + \phi(t, x),$

we reformulate the problem (1.1) in terms of the deviation ϕ from U as

$$(3.2) \quad \begin{cases} \partial_t \phi + \partial_x(f(U + \phi) - f(U)) - \partial_x(\sigma(\partial_x U + \partial_x \phi) - \sigma(\partial_x U)) \\ \quad = \partial_x(\sigma(\partial_x U)) & (t > 0, x \in \mathbb{R}), \\ \phi(0, x) = \phi_0(x) := u_0(x) - U(0, x) & (x \in \mathbb{R}), \\ \lim_{x \rightarrow \pm\infty} \phi(t, x) = 0 & (t \geq 0). \end{cases}$$

Then we look for the unique global in time solution ϕ which has the asymptotic behavior

(3.3) $\sup_{x \in \mathbb{R}} (|\phi(t, x)| + |\partial_x \phi(t, x)|) \rightarrow 0 \quad (t \rightarrow \infty).$

Here we note that $\phi_0 \in H^2$ by the assumptions on u_0 , and Lemma 2.2. Then the corresponding theorem for ϕ to Theorem 1.2 we should prove is as follows.

Theorem 3.1. *Assume the far field states satisfy $u_- < u_+$, the convective flux f , (1.5), the viscous flux σ , (1.2), (1.3), and $p > 3/7$. Further assume the initial data satisfy $\phi_0 \in H^2$. Then the Cauchy problem (3.2) has a unique global in time solution u satisfying*

$$\begin{cases} \phi \in C^0 \cap L^\infty([0, \infty); H^2), \\ \partial_x \phi \in L^2(0, \infty; H^2), \end{cases}$$

and the asymptotic behavior

$$\limsup_{t \rightarrow \infty} \sup_{x \in \mathbb{R}} (|\phi(t, x)| + |\partial_x \phi(t, x)|) = 0.$$

Theorem 3.1 is shown by combining the local existence of the solution together with the *a priori* estimates as in the previous papers. To state the local existence precisely, the Cauchy problem at general initial time $\tau \geq 0$ with the given initial data $\phi_\tau \in H^2$ is formulated:

$$(3.4) \quad \begin{cases} \partial_t \phi + \partial_x (f(U + \phi) - f(U)) - \partial_x (\sigma (\partial_x U + \partial_x \phi) - \sigma (\partial_x U)) \\ \quad = \partial_x (\sigma (\partial_x U)) \quad (t > \tau, x \in \mathbb{R}), \\ \phi(\tau, x) = \phi_\tau(x) := u_\tau(x) - U(\tau, x) \quad (x \in \mathbb{R}), \\ \lim_{x \rightarrow \pm \infty} \phi(t, x) = 0 \quad (t \geq \tau). \end{cases}$$

Theorem 3.2 (local existence). *For any $M > 0$, there exists a positive constant $t_0 = t_0(M)$ not depending on τ such that if $\phi_\tau \in H^2$ and $\|\phi_\tau\|_{H^2} \leq M$, then the Cauchy problem (3.4) has a unique solution ϕ on the time interval $[\tau, \tau + t_0(M)]$ satisfying*

$$\phi \in C^0([\tau, \tau + t_0]; H^2) \cap L^2(\tau, \tau + t_0; H^3).$$

The proof of Theorem 3.2 is given by standard iterative method with the aid of the semigroup theory by Kato [17], [18]. Because the proof is similar to the one in Yoshida [47], we omit the details here (cf. [21], [24], [43], [44]). The *a priori estimates* we establish in Section 4, Section 5 and Section 6 are the following.

Theorem 3.3 (*a priori estimates*). *Under the same assumptions in Theorem 3.1, for any initial data $\phi_0 \in H^2$, there exists a positive constant C_{ϕ_0} such that if the Cauchy problem (3.2) has a solution ϕ on a time interval $[0, T]$ satisfying*

$$\phi \in C^0([0, T]; H^2) \cap L^2(0, T; H^3)$$

for some constant $T > 0$, then it holds that

$$(3.5) \quad \begin{aligned} \|\phi(t)\|_{H^2}^2 + \int_0^t \|(\sqrt{\partial_x U} \phi)(\tau)\|_{L^2}^2 d\tau \\ + \int_0^t (\|\partial_x \phi(\tau)\|_{H^2}^2 + \|\partial_t \partial_x \phi(\tau)\|_{L^2}^2) d\tau \leq C_{\phi_0} \quad (t \in [0, T]). \end{aligned}$$

Once Theorem 3.3 is established, by combining the local existence Theorem 3.2 with $M = M_0 := \sqrt{C_{\phi_0}}$, $\tau = n t_0(M_0)$, and $\phi_\tau = \phi(n t_0(M_0))$ ($n = 0, 1, 2, \dots$) together with the *a priori* estimates with $T = (n + 1) t_0(M_0)$ inductively, the unique solution of (3.3) $\phi \in C^0([0, n t_0(M_0)]; H^2) \cap L^2(0, n t_0(M_0); H^3)$ for any $n \in \mathbb{N}$ is easily constructed, that is, the global solution in time $\phi \in C^0([0, \infty); H^2) \cap L^2_{\text{loc}}(0, \infty; H^3)$. Then, the *a priori* estimates again assert that

$$(3.6) \quad \sup_{t \geq 0} \|\phi(t)\|_{H^2} < \infty, \quad \int_0^\infty (\|\partial_x \phi(t)\|_{H^2}^2 + \|\partial_t \partial_x \phi(t)\|_{L^2}^2) dt < \infty,$$

which easily gives

$$(3.7) \quad \int_0^\infty \left| \frac{d}{dt} \|\partial_x \phi(t)\|_{L^2}^2 \right| dt < \infty.$$

Hence, it follows from (3.6) and (3.7) that

$$\|\partial_x \phi(t)\|_{L^2} \rightarrow 0 \quad (t \rightarrow \infty).$$

Due to the Sobolev inequality, the desired asymptotic behavior in Theorem 3.1 is obtained as

$$\sup_{x \in \mathbb{R}} |\phi(t, x)| \leq \sqrt{2} \|\phi(t)\|_{L^2}^{\frac{1}{2}} \|\partial_x \phi(t)\|_{L^2}^{\frac{1}{2}} \rightarrow 0 \quad (t \rightarrow \infty),$$

$$\sup_{x \in \mathbb{R}} |\partial_x \phi(t, x)| \leq \sqrt{2} \|\partial_x \phi(t)\|_{L^2}^{\frac{1}{2}} \|\partial_x^2 \phi(t)\|_{L^2}^{\frac{1}{2}} \rightarrow 0 \quad (t \rightarrow \infty).$$

Thus, Theorem 3.1 is shown by combining Theorem 3.2 together with Theorem 3.3. In the following sections, we give the proof of the *a priori* estimates, Theorem 3.3. To do that, in the whole remaining sections we assume $\phi \in C^0([0, T]; H^2) \cap L^2(0, T; H^3)$ is a solution of (3.2) for some $T > 0$, and for simplicity we use the notation C_0 to denote positive constants which may depend on the initial data $\phi_0 \in H^2$, and the shape of the equation but not depend on T .

4. A priori estimates I

In this section, we show the following basic L^2 -energy estimate for ϕ .

Proposition 4.1. *For $0 < p < 1$, there exists a positive constant C_0 such that*

$$\|\phi(t)\|_{L^2}^2 + \int_0^t \int |\phi|^2 \partial_x U \, dx d\tau + \int_0^t \int \langle \partial_x \phi \rangle^{p-1} |\partial_x \phi|^2 \, dx d\tau \leq C_0 \quad (t \in [0, T]),$$

where $\langle s \rangle := (1 + s^2)^{1/2}$ ($s \in \mathbb{R}$).

Here and after the range $(-\infty, \infty)$ will be abbreviated without confusion, that is,

$$\int_{-\infty}^{\infty} dx = \int dx.$$

To obtain Proposition 4.1, we first show the uniform boundedness of $\|\phi\|_{L^\infty}$ by using the L^q ($q \geq 2$) energy estimates as follows (cf. [12], [21], [24]).

Lemma 4.1. *There exists a positive constant C_0 such that*

$$\|\phi(t)\|_{L^\infty} \leq C_0 \quad (t \in [0, T]).$$

Proof of Lemma 4.1. For $r \geq 1$, multiplying the equation in (3.2) by $|\phi|^{r-1} \phi$, and integrating the resultant formula with respect to x , we have, after integration by parts,

$$\begin{aligned} (4.1) \quad & \frac{1}{r+1} \frac{d}{dt} \|\phi(t)\|_{L^{r+1}}^{r+1} + r \int \int_0^\phi (f'(\eta + U) - f'(U)) |\eta|^{r-1} \partial_x U \, d\eta \, dx \\ & + r \int |\phi|^{r-1} \partial_x \phi (\sigma(\partial_x U + \partial_x \phi) - \sigma(\partial_x U)) \, dx \\ & = \int |\phi|^{r-1} \phi \partial_x (\sigma(\partial_x U)) \, dx. \end{aligned}$$

We estimate the right-hand side of (4.1) by the Hölder inequality as

$$(4.2) \quad \left| \int |\phi|^{r-1} \phi \partial_x (\sigma(\partial_x U)) \, dx \right| \leq \|\phi\|_{L^{r+1}}^r \|\partial_x (\sigma(\partial_x U))\|_{L^{r+1}}.$$

Note that by the assumptions (1.2), (1.5) on f and σ , the second and third terms on the left side of (4.1) are non-negative. Then, substituting (4.2) into (4.1), we have

$$(4.3) \quad \frac{d}{dt} \|\phi(t)\|_{L^{r+1}} \leq \|\partial_x(\sigma(\partial_x U))(t)\|_{L^{r+1}}.$$

Integrating (4.3) with respect to t , we have for any compact set $K \subset \mathbb{R}$,

$$(4.4) \quad \|\phi(t)\|_{L^{r+1}(K)} \leq \|\phi(t)\|_{L^{r+1}} \leq \|\phi_0\|_{L^{r+1}} + \int_0^t \|\partial_x(\sigma(\partial_x U))(\tau)\|_{L^{r+1}} d\tau.$$

Taking the limit $r \rightarrow \infty$ in (4.4), we immediately have

$$(4.5) \quad \max_{x \in K} |\phi(t, x)| \leq \|\phi_0\|_{L^\infty} + \int_0^t \left\| (\sigma'(\partial_x U) \partial_x^2 U)(\tau) \right\|_{L^\infty} d\tau.$$

Because the compact set $K \subset \mathbb{R}$ is arbitrary, we obtain

$$(4.6) \quad \sup_{x \in \mathbb{R}} |\phi(t, x)| \leq \|\phi_0\|_{L^\infty} + C \int_0^t \|\partial_x^2 U(\tau)\|_{L^\infty} d\tau.$$

Since $\|\partial_x^2 U(\cdot)\|_{L^\infty} \in L^1_t(0, \infty)$ by Lemma 2.2, the proof of Lemma 4.1 is completed. \square

Proof of Proposition 4.1. Taking $r = 1$ in (4.1), and using the assumptions (1.2), (1.3), (1.5) together with Lemma 4.1, we have

$$(4.7) \quad \begin{aligned} \frac{1}{2} \frac{d}{dt} \|\phi(t)\|_{L^2}^2 + C_0^{-1} \int \phi^2 \partial_x U dx + C_0^{-1} \int \langle \partial_x \phi \rangle^{p-1} |\partial_x \phi|^2 dx \\ \leq \left| \int \phi \partial_x(\sigma(\partial_x U)) dx \right|. \end{aligned}$$

In order to estimate the right hand side of (4.7), we prepare the following \square

Lemma 4.2. For $g \in H^2$, it holds that

$$(4.8) \quad \|g\|_{L^\infty} \leq C Q_g^{\frac{1}{4}} \|g\|_{L^2}^{\frac{1}{2}} + C Q_g^{\frac{1}{3p+1}} \|g\|_{L^2}^{\frac{2p}{3p+1}},$$

where

$$Q_g := \int \langle \partial_x g \rangle^{p-1} |\partial_x g|^2 dx.$$

Proof of Lemma 4.2. We first note that

$$(4.9) \quad Q_g \sim \int_{|\partial_x g| \leq 1} |\partial_x g|^2 dx + \int_{|\partial_x g| > 1} |\partial_x g|^{p+1} dx.$$

By simple calculation, we have

$$(4.10) \quad \|g\|_{L^\infty}^2 \leq \int 2|g| |\partial_x g| dx = \int_{|\partial_x g| \leq 1} + \int_{|\partial_x g| > 1} =: I_1 + I_2.$$

We estimate each I_i ($i = 1, 2$) by using the Hölder and Young inequalities as follows:

$$(4.11) \quad I_1 \leq 2 \left(\int_{|\partial_x g| \leq 1} |\partial_x g|^2 dx \right)^{\frac{1}{2}} \left(\int_{|\partial_x g| \leq 1} |g|^2 dx \right)^{\frac{1}{2}} \leq C Q_g^{\frac{1}{2}} \|g\|_{L^2};$$

$$\begin{aligned}
 (4.12) \quad I_2 &\leq 2 \left(\int_{|\partial_x g| > 1} |\partial_x g|^{p+1} dx \right)^{\frac{1}{p+1}} \left(\int_{|\partial_x g| > 1} |g|^{\frac{p+1}{p}} dx \right)^{\frac{p}{p+1}} \leq C Q_g^{\frac{1}{p+1}} \|g\|_{L^2}^{\frac{2p}{p+1}} \|g\|_{L^\infty}^{\frac{1-p}{p+1}} \\
 &\leq \epsilon \|g\|_{L^\infty}^2 + C_\epsilon Q_g^{\frac{2}{3p+1}} \|g\|_{L^2}^{\frac{4p}{3p+1}} \quad (\epsilon > 0).
 \end{aligned}$$

Thus, substituting (4.11) and (4.12) into (4.10), and choosing ϵ suitably small, we complete the proof of Lemma 4.2. □

Let us turn to the estimate of the right hand side of (4.7) by using Lemma 2.2 and Lemma 4.2 as

$$\begin{aligned}
 (4.13) \quad \left| \int \phi \partial_x (\sigma(\partial_x U)) dx \right| &\leq C \|\phi\|_{L^\infty} \|\partial_x^2 U\|_{L^1} \\
 &\leq \epsilon Q_\phi + C_\epsilon \|\phi\|_{L^2}^{\frac{2}{3}} \left(\|\partial_x^2 U\|_{L^1}^{\frac{4}{3}} + \|\partial_x^2 U\|_{L^1}^{\frac{3p+1}{3p}} \right) \\
 &\leq \epsilon Q_\phi + C_\epsilon (1 + \|\phi\|_{L^2}^2) (1+t)^{-\frac{4}{3}} \quad (\epsilon > 0).
 \end{aligned}$$

Substituting (4.13) into (4.7), choosing ϵ suitably small, and using the Gronwall inequality, we obtain the desired *a priori* estimate for ϕ . Thus, the proof of Proposition 4.1 is completed.

5. A priori estimates II

In this section, we proceed to the *a priori* estimate for the derivative $\partial_x \phi$.

Proposition 5.1. *For $0 < p < 1$, there exists a positive constant C_0 such that*

$$\begin{aligned}
 \int <\partial_x \phi>^{p-1} |\partial_x \phi|^2 dx + \int_0^t \int <\partial_x \phi>^{2(p-1)} |\partial_x^2 \phi|^2 dx d\tau \\
 \leq C_0 \ll \partial_x \phi \gg_\infty^{1-p} \quad (t \in [0, T]),
 \end{aligned}$$

where

$$\ll v \gg_\infty := \operatorname{ess\,sup}_{t \in [0, T], x \in \mathbb{R}} <v(t, x)>.$$

Proof of Proposition 5.1. Multiplying the equation in (3.2) by

$$-\partial_x (\sigma(\partial_x U + \partial_x \phi) - \sigma(\partial_x U)),$$

and integrating the resultant formula with respect to x , we have, after integration by parts,

$$\begin{aligned}
 (5.1) \quad &\frac{d}{dt} \int \int_0^{\partial_x \phi} (\sigma(\partial_x U + \eta) - \sigma(\partial_x U)) d\eta dx \\
 &- \int \partial_x (f(U + \phi) - f(U)) \partial_x (\sigma(\partial_x U + \partial_x \phi) - \sigma(\partial_x U)) dx \\
 &- \int (\sigma(\partial_x U + \partial_x \phi) - \sigma(\partial_x U) - \sigma'(\partial_x U) \partial_x \phi) \partial_t \partial_x U dx \\
 &+ \int |\partial_x (\sigma(\partial_x U + \partial_x \phi) - \sigma(\partial_x U))|^2 dx \\
 &= - \int \partial_x (\sigma(\partial_x U + \partial_x \phi) - \sigma(\partial_x U)) \partial_x (\sigma(\partial_x U)) dx.
 \end{aligned}$$

By using the Young inequality, we estimate the second term on the left-hand side of (5.1) as

$$(5.2) \quad \left| \int \partial_x(f(U + \phi) - f(U)) \partial_x(\sigma(\partial_x U + \partial_x \phi) - \sigma(\partial_x U)) dx \right| \\ \leq \epsilon \int |\partial_x(\sigma(\partial_x U + \partial_x \phi) - \sigma(\partial_x U))|^2 dx + C_\epsilon \int |\partial_x(f(U + \phi) - f(U))|^2 dx \quad (\epsilon > 0).$$

Similarly, the right-hand side of (5.1) is estimated as

$$(5.3) \quad \left| \int \partial_x(\sigma(\partial_x U + \partial_x \phi) - \sigma(\partial_x U)) \partial_x(\sigma(\partial_x U)) dx \right| \\ \leq \epsilon \int |\partial_x(\sigma(\partial_x U + \partial_x \phi) - \sigma(\partial_x U))|^2 dx + C_\epsilon \int |\partial_x^2 U|^2 dx \quad (\epsilon > 0).$$

The third term on the left side of (5.1) is estimated by the Taylor formula, the uniform boundedness of σ' for $0 < p < 1$, and Lemma 2.1 as

$$(5.4) \quad \left| \int (\sigma(\partial_x U + \partial_x \phi) - \sigma(\partial_x U) - \sigma'(\partial_x U) \partial_x \phi) \partial_t \partial_x U dx \right| \\ \leq \int |(\sigma'(\partial_x U + \theta \partial_x \phi) - \sigma'(\partial_x U))| |\partial_x \phi| |\partial_t \partial_x U| dx \\ \leq C \int |\partial_x \phi|^2 dx \quad (\exists \theta = \theta(t, x) \in (0, 1)).$$

Substituting (5.2), (5.3) and (5.4) into (5.1), and choosing ϵ suitably small, we have

$$(5.5) \quad \frac{d}{dt} \int \int_0^{\partial_x \phi} (\sigma(\partial_x U + \eta) - \sigma(\partial_x U)) d\eta dx + \int |\partial_x(\sigma(\partial_x U + \partial_x \phi) - \sigma(\partial_x U))|^2 dx \\ \leq C \int |\partial_x(f(U + \phi) - f(U))|^2 dx + C \int (|\partial_x^2 U|^2 + |\partial_x \phi|^2) dx.$$

By Lemma 2.2 and Lemma 4.1, we estimate the first term on the right-hand side of (5.5) as

$$(5.6) \quad \int |\partial_x(f(U + \phi) - f(U))|^2 dx \leq C \int (\phi^2 \partial_x U + |\partial_x \phi|^2) dx.$$

Similarly, the second term on the left-hand side of (5.5) is estimated as

$$(5.7) \quad \int |\partial_x(\sigma(\partial_x U + \partial_x \phi) - \sigma(\partial_x U))|^2 dx \geq \int |\sigma'(\partial_x U + \partial_x \phi)|^2 |\partial_x^2 \phi|^2 dx \\ - \int |\sigma'(\partial_x U + \partial_x \phi) - \sigma'(\partial_x U)|^2 |\partial_x^2 U|^2 dx \\ \geq \int |\sigma'(\partial_x U + \partial_x \phi)|^2 |\partial_x^2 \phi|^2 dx - C \int |\partial_x^2 U|^2 dx.$$

Furthermore, by the assumptions (1.2), (1.3), it holds

$$(5.8) \quad \int |\sigma'(\partial_x U + \partial_x \phi)|^2 |\partial_x^2 \phi|^2 dx \sim \int \langle \partial_x \phi \rangle^{2(p-1)} |\partial_x^2 \phi|^2 dx,$$

and

$$(5.9) \quad \int_0^t \int_0^{\partial_x \phi} (\sigma(\partial_x U + \eta) - \sigma(\partial_x U)) d\eta dx \sim \int \langle \partial_x \phi \rangle^{p-1} |\partial_x \phi|^2 dx.$$

Hence, substituting (5.6) and (5.7) into (5.5), and integrating with respect to t , we have

$$(5.10) \quad \int \langle \partial_x \phi \rangle^{p-1} |\partial_x \phi|^2 dx + \int_0^t \int \langle \partial_x \phi \rangle^{2(p-1)} |\partial_x^2 \phi|^2 dx d\tau \\ \leq C_0 \left(1 + \int_0^t \int (\phi^2 \partial_x U + |\partial_x \phi|^2 + |\partial_x^2 U|^2) dx d\tau \right).$$

Finally, by Lemma 2.1 and Proposition 4.1, it holds that

$$(5.11) \quad \int_0^t \int (\phi^2 \partial_x U + |\partial_x^2 U|^2) dx d\tau \leq C_0,$$

and

$$(5.12) \quad \int_0^t \int |\partial_x \phi|^2 dx d\tau \leq \int_0^t \int \ll \partial_x \phi \gg_\infty^{1-p} \langle \partial_x \phi \rangle^{p-1} |\partial_x \phi|^2 dx d\tau \\ \leq C_0 \ll \partial_x \phi \gg_\infty^{1-p}.$$

Substituting (5.11) and (5.12) into (5.10), we obtain the desired *a priori* estimate for $\partial_x \phi$. Thus, the proof of Proposition 5.1 is completed. \square

6. A priori estimates III

In this section, we further show the *a priori* estimate for $\partial_x^2 \phi$, establish the uniform boundedness of $\|\partial_x \phi\|_{L^\infty}$, and then accomplish the proof of Theorem 3.3.

Proposition 6.1. *For $0 < p < 1$, there exists a positive constant C_0 such that*

$$\int \langle \partial_x \phi \rangle^{2(p-1)} |\partial_x^2 \phi|^2 dx + \int_0^t \int \langle \partial_x \phi \rangle^{p-1} |\partial_t \partial_x \phi|^2 dx d\tau \\ \leq C_0 \ll \partial_x \phi \gg_\infty^{3(1-p)} \quad (t \in [0, T]).$$

Proof of Proposition 6.1. Differentiating the equation in (3.2) once with respect to x gives

$$(6.1) \quad \partial_t \partial_x \phi + \partial_x^2 (f(U + \phi) - f(U)) - \partial_x^2 (\sigma(\partial_x U + \partial_x \phi) - \sigma(\partial_x U)) = \partial_x^2 (\sigma(\partial_x U)).$$

Multiplying (6.1) by

$$\partial_t (\sigma(\partial_x U + \partial_x \phi) - \sigma(\partial_x U)),$$

and integrating the resultant formula with respect to x , we obtain, after integration by parts,

$$(6.2) \quad \frac{1}{2} \frac{d}{dt} \int |\partial_x (\sigma(\partial_x U + \partial_x \phi) - \sigma(\partial_x U))|^2 dx \\ + \int \partial_t \partial_x \phi \partial_t (\sigma(\partial_x U + \partial_x \phi) - \sigma(\partial_x U)) dx \\ + \int \partial_x^2 (f(U + \phi) - f(U)) \partial_t (\sigma(\partial_x U + \partial_x \phi) - \sigma(\partial_x U)) dx \\ = \int \partial_t (\sigma(\partial_x U + \partial_x \phi) - \sigma(\partial_x U)) \partial_x^2 (\sigma(\partial_x U)) dx.$$

First, we estimate the second term on the left-hand side of (6.2)

$$(6.3) \quad \begin{aligned} & \int \partial_t \partial_x \phi \partial_t (\sigma(\partial_x U + \partial_x \phi) - \sigma(\partial_x U)) dx \\ &= \int \sigma'(\partial_x U + \partial_x \phi) |\partial_t \partial_x \phi|^2 dx \\ & \quad + \int \partial_t \partial_x \phi (\sigma'(\partial_x U + \partial_x \phi) - \sigma'(\partial_x U)) \partial_t \partial_x U dx, \end{aligned}$$

where note that

$$(6.4) \quad \int \sigma'(\partial_x U + \partial_x \phi) |\partial_t \partial_x \phi|^2 dx \sim \int \langle \partial_x \phi \rangle^{p-1} |\partial_t \partial_x \phi|^2 dx.$$

The second term on the right-hand side of (6.3) is estimated by the Young inequality as

$$(6.5) \quad \begin{aligned} & \left| \int \partial_t \partial_x \phi (\sigma'(\partial_x U + \partial_x \phi) - \sigma'(\partial_x U)) \partial_t \partial_x U dx \right| \\ & \leq C \int |\partial_x \phi| |\partial_t \partial_x \phi| |\partial_t \partial_x U| dx \\ & \leq \epsilon \int \langle \partial_x \phi \rangle^{p-1} |\partial_t \partial_x \phi|^2 dx + C_\epsilon \int \langle \partial_x \phi \rangle^{1-p} |\partial_x \phi|^2 |\partial_t \partial_x U|^2 dx \\ & \leq \epsilon \int \langle \partial_x \phi \rangle^{p-1} |\partial_t \partial_x \phi|^2 dx + C_\epsilon \llbracket \partial_x \phi \rrbracket_\infty^{2(1-p)} \int \langle \partial_x \phi \rangle^{p-1} |\partial_x \phi|^2 dx. \end{aligned}$$

Next, we estimate the third term on the left-hand side of (6.2). Noting

$$(6.6) \quad \begin{aligned} & \left| \partial_x^2 (f(U + \phi) - f(U)) \right| \\ & \leq C \left(|\partial_x \phi|^2 + |\partial_x \phi| |\partial_x U| + |\partial_x^2 \phi| + |\phi| |\partial_x U|^2 + |\phi| |\partial_x^2 U| \right), \end{aligned}$$

and

$$(6.7) \quad \left| \partial_t (\sigma(\partial_x U + \partial_x \phi) - \sigma(\partial_x U)) \right| \leq C \langle \partial_x \phi \rangle^{p-1} |\partial_t \partial_x \phi| + C |\partial_x \phi| |\partial_t \partial_x U|,$$

we have

$$(6.8) \quad \begin{aligned} & \left| \int \partial_x^2 (f(U + \phi) - f(U)) \partial_t (\sigma(\partial_x U + \partial_x \phi) - \sigma(\partial_x U)) dx \right| \\ & \leq C \int \langle \partial_x \phi \rangle^{p-1} |\partial_t \partial_x \phi| \\ & \quad \times \left(|\partial_x \phi|^2 + |\partial_x \phi| |\partial_x U| + |\partial_x^2 \phi| + |\phi| (|\partial_x U|^2 + |\partial_x^2 U|) \right) dx \\ & \quad + C \int |\partial_x \phi| |\partial_t \partial_x U| \\ & \quad \times \left(|\partial_x \phi|^2 + |\partial_x \phi| |\partial_x U| + |\partial_x^2 \phi| + |\phi| (|\partial_x U|^2 + |\partial_x^2 U|) \right) dx \\ & =: I_1 + I_2. \end{aligned}$$

Let us estimate each I_i ($i = 1, 2$). By using the Young inequality, we have

$$(6.9) \quad I_1 \leq \epsilon \int \langle \partial_x \phi \rangle^{p-1} |\partial_t \partial_x \phi|^2 dx$$

$$+ C_\epsilon \int \langle \partial_x \phi \rangle^{p-1} \left(|\partial_x \phi|^4 + |\partial_x \phi|^2 |\partial_x U|^2 + |\partial_x^2 \phi|^2 + |\phi|^2 (|\partial_x U|^4 + |\partial_x^2 U|^2) \right) dx.$$

By using Lemma 2.2, Lemma 4.1, Proposition 4.1, and the Sobolev inequality, each term in the second term on the right-hand side of (6.9) is estimated as follows:

(6.10)

$$\begin{aligned} \int \langle \partial_x \phi \rangle^{p-1} |\partial_x \phi|^4 dx &\leq \|\partial_x \phi\|_{L^\infty}^2 \int \langle \partial_x \phi \rangle^{p-1} |\partial_x \phi|^2 dx \\ &\leq C_0 \|\partial_x \phi\|_{L^2} \|\partial_x^2 \phi\|_{L^2} \ll \langle \partial_x \phi \rangle_\infty^{1-p} \\ &\leq C_0 \ll \langle \partial_x \phi \rangle_\infty^{\frac{5}{2}(1-p)} \left(\int \langle \partial_x \phi \rangle^{p-1} |\partial_x \phi|^2 dx \right)^{\frac{1}{2}} \left(\int \langle \partial_x \phi \rangle^{2(p-1)} |\partial_x^2 \phi|^2 dx \right)^{\frac{1}{2}}; \end{aligned}$$

$$(6.11) \quad \int \langle \partial_x \phi \rangle^{p-1} |\partial_x \phi|^2 |\partial_x U|^2 dx \leq C \int \langle \partial_x \phi \rangle^{p-1} |\partial_x \phi|^2 dx;$$

$$(6.12) \quad \int \langle \partial_x \phi \rangle^{p-1} |\partial_x^2 \phi|^2 dx \leq \ll \langle \partial_x \phi \rangle_\infty^{1-p} \int \langle \partial_x \phi \rangle^{2(p-1)} |\partial_x^2 \phi|^2 dx;$$

(6.13)

$$\begin{aligned} \int \langle \partial_x \phi \rangle^{p-1} |\phi|^2 (|\partial_x U|^4 + |\partial_x^2 U|^2) dx &\leq \int |\phi|^2 (|\partial_x U|^4 + |\partial_x^2 U|^2) dx \\ &\leq C_0 (\|\partial_x U\|_{L^\infty}^4 + \|\partial_x^2 U\|_{L^\infty}^2) \leq C_0(1+t)^{-2}. \end{aligned}$$

Similarly, each term in I_2 is estimated as follows:

$$\begin{aligned} (6.14) \quad \int |\partial_x \phi|^3 |\partial_t \partial_x U| dx &\leq 2 \|\partial_x \phi\|_{L^2}^2 \|\partial_x^2 \phi\|_{L^2} \|\partial_t \partial_x U\|_{L^2} \\ &\leq C \ll \langle \partial_x \phi \rangle_\infty^{2(1-p)} \left(\int \langle \partial_x \phi \rangle^{p-1} |\partial_x \phi|^2 dx \right) \left(\int \langle \partial_x \phi \rangle^{2(p-1)} |\partial_x^2 \phi|^2 dx \right)^{\frac{1}{2}} \\ &\leq C \ll \langle \partial_x \phi \rangle_\infty^{\frac{5}{2}(1-p)} \left(\int \langle \partial_x \phi \rangle^{p-1} |\partial_x \phi|^2 dx \right)^{\frac{1}{2}} \left(\int \langle \partial_x \phi \rangle^{2(p-1)} |\partial_x^2 \phi|^2 dx \right)^{\frac{1}{2}}; \end{aligned}$$

$$(6.15) \quad \int |\partial_x \phi|^2 |\partial_t \partial_x U| |\partial_x U| dx \leq C \ll \langle \partial_x \phi \rangle_\infty^{1-p} \int \langle \partial_x \phi \rangle^{p-1} |\partial_x \phi|^2 dx;$$

$$\begin{aligned} (6.16) \quad \int |\partial_x \phi| |\partial_x^2 \phi| |\partial_t \partial_x U| dx &\leq C \left(\|\partial_x \phi\|_{L^2}^2 + \|\partial_x^2 \phi\|_{L^2}^2 \right) \\ &\leq C \ll \langle \partial_x \phi \rangle_\infty^{1-p} \int \langle \partial_x \phi \rangle^{p-1} |\partial_x \phi|^2 dx \\ &\quad + C \ll \langle \partial_x \phi \rangle_\infty^{2(1-p)} \int \langle \partial_x \phi \rangle^{2(p-1)} |\partial_x^2 \phi|^2 dx; \end{aligned}$$

$$\begin{aligned} (6.17) \quad \int |\phi| |\partial_x \phi| |\partial_t \partial_x U| (|\partial_x U|^2 + |\partial_x^2 U|) dx \\ \leq C \int (|\partial_x \phi|^2 + |\phi|^2 |\partial_t \partial_x U|^2 (|\partial_x U|^4 + |\partial_x^2 U|^2)) dx \end{aligned}$$

$$\leq C \ll \partial_x \phi \gg_\infty^{1-p} \int \langle \partial_x \phi \rangle^{p-1} |\partial_x \phi|^2 dx + C_0 (1+t)^{-2}.$$

We finally estimate the right-hand side of (6.2) by (6.7) and the Young inequality as

$$(6.18) \quad \left| \int \partial_t (\sigma(\partial_x U + \partial_x \phi) - \sigma(\partial_x U)) \partial_x^2 (\sigma(\partial_x U)) dx \right| \\ \leq C \int \langle \partial_x \phi \rangle^{p-1} |\partial_t \partial_x \phi| |\partial_x^2 (\sigma(\partial_x U))| dx \\ + C \int |\partial_x \phi| |\partial_t \partial_x U| |\partial_x^2 (\sigma(\partial_x U))| dx.$$

Each term on the right-hand side of (6.18) is estimated as

$$(6.19) \quad \int \langle \partial_x \phi \rangle^{p-1} |\partial_t \partial_x \phi| |\partial_x^2 (\sigma(\partial_x U))| dx \\ \leq \epsilon \int \langle \partial_x \phi \rangle^{p-1} |\partial_t \partial_x \phi|^2 dx + C_\epsilon \|\partial_x^2 (\sigma(\partial_x U))(t)\|_{L^2}^2 \\ \leq \epsilon \int \langle \partial_x \phi \rangle^{p-1} |\partial_t \partial_x \phi|^2 dx + C_\epsilon (1+t)^{-2},$$

and

$$(6.20) \quad \int |\partial_x \phi| |\partial_t \partial_x U| |\partial_x^2 (\sigma(\partial_x U))| dx \\ \leq C \ll \partial_x \phi \gg_\infty^{1-p} \int \langle \partial_x \phi \rangle^{p-1} |\partial_x \phi|^2 dx + C (1+t)^{-2}.$$

Then, substituting all the estimates (6.5)~(6.20) into (6.2), choosing ϵ suitably small, and integrating the resultant formula with respect to t , we arrive at

$$(6.21) \quad \int |\partial_x (\sigma(\partial_x U + \partial_x \phi) - \sigma(\partial_x U))|^2 dx + \int_0^t \int \langle \partial_x \phi \rangle^{p-1} |\partial_t \partial_x \phi|^2 dx d\tau \\ \leq C_0 \ll \partial_x \phi \gg_\infty^{3(1-p)} \quad (t \in [0, T]),$$

where we used the estimate

$$(6.22) \quad \int_0^t \left(\int \langle \partial_x \phi \rangle^{p-1} |\partial_x \phi|^2 dx d\tau \right)^{\frac{1}{2}} \left(\int \langle \partial_x \phi \rangle^{2(p-1)} |\partial_x^2 \phi|^2 dx \right)^{\frac{1}{2}} d\tau \\ \leq \left(\int_0^t \int \langle \partial_x \phi \rangle^{p-1} |\partial_x \phi|^2 dx d\tau \right)^{\frac{1}{2}} \left(\int_0^t \int \langle \partial_x \phi \rangle^{2(p-1)} |\partial_x^2 \phi|^2 dx d\tau \right)^{\frac{1}{2}} \\ \leq C_0 \ll \partial_x \phi \gg_\infty^{\frac{1}{2}(1-p)}.$$

Finally, if we note the estimates (5.7) and (5.8) imply

$$\int \langle \partial_x \phi \rangle^{2(p-1)} |\partial_x^2 \phi|^2 dx \leq C \int |\partial_x (\sigma(\partial_x U + \partial_x \phi) - \sigma(\partial_x U))|^2 dx + C,$$

the estimate (6.21) immediately implies the desired *a priori* estimate for $\partial_x^2 \phi$. Thus the proof of Proposition 6.1 is completed. \square

Now, combining Proposition 4.1, Proposition 5.1, and Proposition 6.1, we show the the following uniform boundedness of $\|\partial_x \phi\|_{L^\infty}$ which plays the essential role to control the

nonlinearity of σ . The proof is motivated by an idea in Kanel' [16].

Lemma 6.1. *For $3/7 < p < 1$, there exists a positive constant C_0 such that*

$$\|\partial_x \phi(t)\|_{L^\infty} \leq C_0 \quad (t \in [0, T]).$$

Proof of Lemma 6.1. By the Cauchy-Schwarz inequality, we have for $a > 0$

$$\begin{aligned} (6.23) \quad & \langle \partial_x \phi(t, x) \rangle^a = 1 + \int_{-\infty}^x \frac{\partial}{\partial y} \langle \partial_x \phi(t, y) \rangle^a dy \\ & \leq 1 + a \int \langle \partial_x \phi \rangle^{a-2} |\partial_x \phi| |\partial_x^2 \phi| dx \\ & \leq 1 + a \left(\int \langle \partial_x \phi \rangle^{p-1} |\partial_x \phi|^2 dx \right)^{\frac{1}{2}} \left(\int \langle \partial_x \phi \rangle^{2a-3-p} |\partial_x^2 \phi|^2 dx \right)^{\frac{1}{2}}. \end{aligned}$$

If we choose $a = (3p + 1)/2$, (6.23) gives

$$(6.24) \quad \ll \partial_x \phi \gg_{\infty}^{\frac{3p+1}{2}} \leq 1 + C \left(\int \langle \partial_x \phi \rangle^{p-1} |\partial_x \phi|^2 dx \right)^{\frac{1}{2}} \left(\int \langle \partial_x \phi \rangle^{2(p-1)} |\partial_x^2 \phi|^2 dx \right)^{\frac{1}{2}},$$

which deduces from Proposition 5.1 and Proposition 6.1 that

$$(6.25) \quad \ll \partial_x \phi \gg_{\infty}^{\frac{3p+1}{2}} \leq C_0 \ll \partial_x \phi \gg_{\infty}^{2(1-p)}.$$

Hence, if we assume

$$\frac{3p+1}{2} > 2(1-p) \quad \left(\Leftrightarrow p > \frac{3}{7} \right),$$

we obtain for $3/7 < p < 1$

$$(6.26) \quad \ll \partial_x \phi \gg_{\infty} \leq C_0.$$

Thus, the proof of Lemma 6.1 is completed. \square

By Proposition 4.1, Proposition 5.1, and Proposition 6.1 with the aid of Lemma 6.1, we obtain the energy estimate

$$\begin{aligned} (6.27) \quad & \|\phi(t)\|_{H^2}^2 + \int_0^t \left\| (\sqrt{\partial_x U} \phi)(\tau) \right\|_{L^2}^2 d\tau \\ & + \int_0^t (\|\partial_x \phi(\tau)\|_{H^1}^2 + \|\partial_t \partial_x \phi(\tau)\|_{L^2}^2) d\tau \leq C_0 \quad (t \in [0, T]). \end{aligned}$$

Therefore, in order to accomplish the proof of Theorem 3.3, it suffices to show the following *a priori* estimate:

$$(6.28) \quad \int_0^t \|\partial_x^3 \phi(\tau)\|_{L^2}^2 d\tau \leq C_0 \quad (t \in [0, T]).$$

The estimate (6.28) is directly obtained by the equation (6.1) and the estimate (6.27) as follows. The equation (6.1) is rewritten as

$$\begin{aligned} \sigma'(\partial_x U + \partial_x \phi) \partial_x^3 \phi &= \partial_t \partial_x \phi + \partial_x^2 (f(U + \phi) - f(U)) \\ &\quad - \sigma''(\partial_x U + \partial_x \phi) |\partial_x U + \partial_x \phi|^2 - \sigma'(\partial_x U + \partial_x \phi) \partial_x^3 U. \end{aligned}$$

Then, by the estimate (6.27), Lemma 2.2, and the Sobolev inequality, it holds

$$\begin{aligned} \int_0^t \|\partial_x^3 \phi\|_{L^2}^2 \, d\tau &\leq C_0 + C_0 \int_0^t \int |\partial_x^2 \phi|^4 \, dx d\tau \\ &\leq C_0 + C_0 \int_0^t \|\partial_x^2 \phi\|_{L^2}^3 \|\partial_x^3 \phi\|_{L^2} \, d\tau \\ &\leq C_0 + \frac{1}{2} \int_0^t \|\partial_x^3 \phi\|_{L^2}^2 \, d\tau + C_0 \int_0^t \|\partial_x^2 \phi\|_{L^2}^2 \, d\tau, \end{aligned}$$

which implies (6.28). Thus, the proof of Theorem 3.3 is completed.

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