# TOPOLOGICAL TRIVIALITY OF FAMILIES OF FUNCTIONS ON ANALYTIC VARIETIES 

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#### Abstract

We present in this paper sufficient conditions for the topological triviality of families of germs of functions defined on an analytic variety $V$. The main result is an infinitesimal criterion based on a convenient weighted inequality, similar to that introduced by T. Fukui and L. Paunescu in [8]. When $V$ is a weighted homogeneous variety, we obtain as a corollary, the topological triviality of deformations by terms of non negative weights of a weighted homogeneous germ consistent with $V$. Application of the results to deformations of Newton non-degenerate germs with respect to a given variety is also given.


## §1. Introduction

Let $V, 0$ be the germ of an analytic subvariety of $k^{n}, k=\mathbb{R}$, or $\mathbb{C}$ and let $\mathcal{R}_{V}$ (respectively $C^{0}-\mathcal{R}_{V}$ ) be the group of germs of diffeomorphisms (respectively homeomorphisms) preserving $V, 0$, acting on germs $h_{0}: k^{n}, 0 \rightarrow k, 0$. The aim of this paper is to study topologically trivial deformations of $\mathcal{R}_{V^{-}}$ finitely determined germs $h_{0}$. The main result is Theorem 3.4 in which we introduce a sufficient condition for the $C^{0}-\mathcal{R}_{V}$-triviality of families of map germs $h: k^{n} \times k, 0 \rightarrow k, 0, h(x, 0)=h_{0}(x)$, based on a convenient weighted inequality, similar to that introduced by T. Fukui and L. Paunescu in [8]. A non weighted version of this result first appeared in [13]. There, the sufficient condition for topological triviality is formulated in terms of the integral closure of the tangent space to the $\mathcal{R}_{V}$-orbit of $h_{t}$.

As an application of the results, when $V$ is a weighted homogeneous analytic variety, we prove that any deformation by non negative weights of an $\mathcal{R}_{V}$-finitely determined weighted homogeneous germ (consistent with $V)$ is topologically trivial. This result was previously proved by J. Damon

[^0]in [6]. In the last section, we obtain sufficient conditions for the $C^{0}-\mathcal{R}_{V^{-}}$ triviality of families $h(x, t)=h_{0}(x)+\operatorname{tg}(x)$, depending only on $h_{0}$. When $h_{0}$ is Newton non-degenerate with respect to the variety $V$ (see Definition 4.4), we describe the topological triviality of $h$ in terms of the Newton diagram of the tangent space to the $\mathcal{R}_{V}$-orbit of $h_{0}$.

For other results related to the subject discussed in this paper, see for instance [1], [6], [13].

## §2. Basic results

Let $\mathcal{O}_{n}$ be the ring of germs of analytic functions $h: k^{n}, 0 \rightarrow k, k=\mathbb{R}$ or $\mathbb{C}$. This is a local ring with maximal ideal $\mathcal{M}_{n}$, the germs with zero target.

A germ of a subset $V, 0 \subset k^{n}, 0$ is the germ of an analytic variety if there exist germs of analytic functions $f_{1}, \ldots, f_{r}$ such that $V=\left\{x: f_{1}(x)=\cdots=\right.$ $\left.f_{r}(x)=0\right\}$.

Our aim is to study map germs $h: k^{n}, 0 \rightarrow k, 0$ under the equivalence relation that preserves the analytic variety $V, 0$. We say that two germs $h_{1}$ and $h_{2}: k^{n}, 0 \rightarrow k, 0$ are $\mathcal{R}_{V}$-equivalent (respectively $C^{0}-\mathcal{R}_{V}$-equivalent) if there exists germ of diffeomorphism (respectively homeomorphism) $\phi$ : $k^{n}, 0 \rightarrow k^{n}, 0$ with $\phi(V)=V$ and $h_{1} \circ \phi=h_{2}$. That is,

$$
\mathcal{R}_{V}=\{\phi \in \mathcal{R}: \phi(V)=V\}
$$

where $\mathcal{R}$ is the group of germs of diffeomorphisms of $k^{n}, 0$.
A one parameter deformation $h: k^{n} \times k, 0 \rightarrow k, 0$ of $h_{0}: k^{n}, 0 \rightarrow k, 0$ is topologically $\mathcal{R}_{V}$-trivial (or $C^{0}-\mathcal{R}_{V}$-trivial) if there exists homeomorphism $\varphi: k^{n} \times k, 0 \rightarrow k^{n} \times k, 0, \varphi(x, t)=(\bar{\varphi}(x, t), t)$, such that $h \circ \varphi(x, t)=h_{0}(x)$ and $\varphi(V \times k)=V \times k$.

We denote by $\theta_{n}$ the set of germs of tangent vector fields in $k^{n}, 0 ; \theta_{n}$ is a free $\mathcal{O}_{n}$ module of rank $n$. Let $I(V)$ be the ideal in $\mathcal{O}_{n}$ consisting of germs of analytic functions vanishing on $V$. We denote by $\Theta_{V}=\left\{\eta \in \theta_{n}\right.$ : $\eta(I(V)) \subseteq I(V)\}$, the submodule of germs of vector fields tangent to $V$ (see [1] for more details).

The tangent space to the action of the group $\mathcal{R}_{V}$ is $T \mathcal{R}_{V}(h)=d h\left(\Theta_{V}^{0}\right)$, where $\Theta_{V}^{0}$ is the submodule of $\Theta_{V}$ given by the vector fields that are zero at zero. When the point $x=0$ is a stratum in the logarithmic stratification of the analytic variety, this is the case when $V$ has an isolated singularity at the origin (see [1] for details), both spaces $\Theta_{V}$ and $\Theta_{V}^{0}$ coincide.

The group $\mathcal{R}_{V}$ is a geometric subgroup of the contact group, as defined by J. Damon [3], [4], hence the infinitesimal criterion for $\mathcal{R}_{V}$-determinacy holds (see [1] for a proof).

Theorem 2.1. ([1]) The germ $h: k^{n}, 0 \rightarrow k, 0$ is $\mathcal{R}_{V}$-finitely determined if and only if there exists a positive integer $k$ such that $T \mathcal{R}_{V}(h) \supset$ $\mathcal{M}_{n}^{k}$.

The following theorem is the geometric criterion for the $\mathcal{R}_{V}$-finite determinacy.

Theorem 2.2. ([1]) Let $V, 0 \subseteq \mathbb{C}^{n}, 0$ be the germ of an analytic variety and let $h: \mathbb{C}^{n}, 0 \rightarrow \mathbb{C}, 0$ be the germ of an analytic function. Let

$$
V(h)=\left\{x \in \mathbb{C}^{n}: \xi h(x)=0, \forall \xi \in \Theta_{V}\right\} .
$$

Then $h$ is $\mathcal{R}_{V}$-finitely determined if and only if $V(h)=\{0\}$ or $\emptyset$.
As a consequence of this result, it follows that if $h$ is $\mathcal{R}_{V}$-finitely determined, then $h^{-1}(c)$ is transverse to $V$ away from 0 , for sufficiently small values of $c$.

In the real case, the necessary condition remains true, that is, if $h$ is $\mathcal{R}_{V}$-finitely determined then the set $\left\{x \in \mathbb{R}^{n}: \xi h(x)=0, \forall \xi \in \Theta_{V}\right\}$ is $\{0\}$ or $\emptyset$.

## §3. The main result

Let $h_{0}: k^{n}, 0 \rightarrow k, 0$ be a $\mathcal{R}_{V}$-finitely determined germ of analytic function and let $h: k^{n} \times k, 0 \rightarrow k, 0$ be an analytic deformation of $h_{0}$. In the sequel, we shall assume $h(0, t)=0$. The property of being $\mathcal{R}_{V}$-finitely determined is open in the sense that the germ $\left\{x \in k^{n}: d h_{t} \xi(x)=0, \forall \xi \in\right.$ $\left.\Theta_{V}\right\}$ at 0 is $\{0\}$ or empty for sufficiently small values of the parameters (see [1]). However, this does not guarantee the existence of a neighbourhood $U$ of 0 in $k^{n}, 0$ and an open $\varepsilon$-ball, $B_{\varepsilon}$, centered at the origin in $k$ such that the above condition holds $\forall x \in U$ and $\forall t \in B_{\varepsilon}$. We then need the following definition:

Definition 3.1. Let $h_{0}: k^{n}, 0 \rightarrow k, 0$ be a $\mathcal{R}_{V}$-finitely determined germ. We say that a deformation $h: k^{n} \times k, 0 \rightarrow k, 0$ of $h_{0}$ is a good deformation if $V(h) \subseteq\{0\} \times k, 0$, where $V(h)=\left\{(x, t) \in k^{n} \times k, 0: d h_{t}(x) \xi(x)=\right.$ $\left.0, \forall \xi \in \Theta_{V}\right\}$.

Example 3.2. Let $V$ be the $x$-axis in $k^{2} ; \Theta_{V}$ is generated by $(1,0)$ and $(0, y)$. The germ $h_{0}(x, y)=x^{2}+y^{3}$ is $\mathcal{R}_{V}$-finitely determined. The deformation $h_{t}(x, y)=x^{2}+y^{3}+t y^{2}$ of $h_{0}$ has the property that $h_{t}$ is $\mathcal{R}_{V^{-}}$ finitely determined for each fixed $t$, but we cannot find $\varepsilon>0$ such that the above condition holds for all $t \in B_{\varepsilon}$.

In what follows we can assume that $d h_{t} \xi(0)=0, \forall \xi \in \Theta_{V}$. In fact, if $\xi \in \Theta_{V}$, then $d h_{t} \xi \cdot \frac{\partial h}{\partial t}=d h_{t}\left(\frac{\partial h}{\partial t} \cdot \xi\right)$. If $d h_{t} \xi_{0}(0) \neq 0$ for some $\xi_{0}$, then $\frac{\partial h}{\partial t}=$ $d h_{t}\left(\frac{\partial h}{\partial h_{t}} \cdot \xi_{0} \xi_{0}\right)$ and hence the deformation is $C^{\omega}-\mathcal{R}_{V}$-trivial (i.e. analytically trivial). Observe that $\frac{\frac{\partial h}{\partial t} \cdot \xi_{0}}{d h_{t} \xi_{0}} \in \Theta_{V}^{0}$.

DEFINITION 3.3. (a) We assign weights $w_{1}, \ldots, w_{n}, w_{i} \in \mathbb{Z}^{+}, i=$ $1, \ldots, n$ to a given coordinate system $x_{1}, \ldots, x_{n}$ in $k^{n}$. The filtration of a monomial $x^{\beta}=x_{1}^{\beta_{1}} x_{2}^{\beta_{2}} \cdots x_{n}^{\beta_{n}}$ with respect to this set of weights is defined by $\operatorname{fil}\left(x^{\beta}\right)=\sum_{i=1}^{n} \beta_{i} w_{i}$.
(b) We define a filtration in the $\operatorname{ring} \mathcal{O}_{n}$ via the function

$$
\operatorname{fil}(f)=\inf _{|\beta|}\left\{\operatorname{fil}\left(x^{\beta}\right): \frac{\partial^{|\beta|} f}{\partial x^{\beta}}(0) \neq 0\right\}, \quad|\beta|=\beta_{1}+\cdots+\beta_{n} .
$$

The filtration of a map germ $f=\left(f_{1}, \ldots, f_{p}\right): k^{n}, 0 \rightarrow k^{p}, 0$ is $\operatorname{fil}(f)=$ $\left(d_{1}, \ldots, d_{p}\right)$, where $\operatorname{fil}\left(f_{i}\right)=d_{i}$.
(c) We extend the filtration to $\Theta_{V}$, defining $w\left(\frac{\partial}{\partial x_{j}}\right)=-w_{j}$ for all $j=$ $1, \ldots, n$, so that given $\xi=\sum_{j=1}^{n} \xi_{j} \frac{\partial}{\partial x_{j}} \in \Theta_{V}$, then $\operatorname{fil}(\xi)=\inf _{j}\left\{\operatorname{fil}\left(\xi_{j}\right)-w_{j}\right\}$.
(d) Given $\left(w_{1}, \ldots, w_{n}: d_{1}, \ldots, d_{p}\right), w_{i}, d_{j} \in \mathbb{Z}^{+}$, a map germ $f:$ $k^{n}, 0 \rightarrow k^{p}, 0$ is weighted homogeneous of type $\left(w_{1}, \ldots, w_{n}: d_{1}, \ldots, d_{p}\right)$ if for all $\lambda \in k-\{0\}$ :

$$
f\left(\lambda^{w_{1}} x_{1}, \lambda^{w_{2}} x_{2}, \ldots, \lambda^{w_{n}} x_{n}\right)=\left(\lambda^{d_{1}} f_{1}(x), \lambda^{d_{2}} f_{2}(x), \ldots, \lambda^{d_{p}} f_{p}(x)\right)
$$

Let $w=w_{1} w_{2} \cdots w_{n}, \mathbf{w}=\left(w_{1}, \ldots, w_{n}\right)$, and $\|x\|_{\mathbf{w}}=\left(\left|x_{1}\right|^{2 w / w_{1}}+\cdots+\right.$ $\left.\left|x_{n}\right|^{2 w / w_{n}}\right)^{1 / 2 w}$.

In what follows $A \lesssim B$ means there is some positive constant $C$ with $A \leq C B$.

Our main result is the following theorem:

THEOREM 3.4. Let $\mathbf{w}=\left(w_{1}, \ldots, w_{n}\right)$ be an $n$-tuple of positive integers. Let $\alpha_{1}, \ldots, \alpha_{m}$ be a system of generators for $\Theta_{V}^{0}$ and $d_{i}=\operatorname{fil}\left(\alpha_{i}\right), i=$ $1, \ldots, m$. Let $h_{0}: k^{n}, 0 \rightarrow k, 0$ be a $\mathcal{R}_{V}$-finitely determined germ and $h:$ $k^{n} \times k, 0 \rightarrow k, 0$ a good deformation of $h_{0}$. If

$$
\left|\frac{\partial h}{\partial t}\right| \lesssim \sup _{i=1, \ldots, m}\left\{\left|d h_{t}\left(\alpha_{i}\right)\right|\|x\|_{\mathbf{w}}^{-d_{i}}\right\} \quad \text { for } x(\neq 0) \text { near } 0
$$

then $h$ is $C^{0}-\mathcal{R}_{V}$-trivial.

Proof. We choose non negative integers $e_{i}, i=1, \ldots, m$ so that $d_{i}+e_{i}$ is a constant $s$. We define a function $\rho$ by $\rho^{2}=\sum_{i=1}^{m}\left|\rho_{i}\right|^{2}\|x\|_{\mathbf{w}}^{2 e_{i}}$, where $\rho_{i}=d h_{t}\left(\alpha_{i}\right), i=1, \ldots, m$. Since $h$ is a good deformation it follows that $V(\rho(x, t))=\{0\} \times k$. From the equation $\rho^{2} \frac{\partial h}{\partial t}=d h_{t}\left(\frac{\partial h}{\partial t} \sum_{i=1}^{m} \overline{\rho_{i}}\|x\|_{\mathbf{w}}^{2 e_{i}} \alpha_{i}\right)$, we obtain $d h(X)=0$, where $X$ is the vector field in $k^{n} \times k, 0$ defined by

$$
X(x, t)= \begin{cases}-\frac{1}{\rho^{2}} \frac{\partial h}{\partial t}\left(\overline{\rho_{1}}\|x\|_{\mathbf{w}}^{2 e_{1}} \alpha_{1}+\cdots+\overline{\rho_{m}}\|x\|_{\mathbf{w}}^{2 e_{m}} \alpha_{m}\right)+\frac{\partial}{\partial t} & \text { if } x \neq 0 \\ \frac{\partial}{\partial t} & \text { if } x=0\end{cases}
$$

The vector field $X(x, t)$ is real analytic away from $\{0\} \times k$. For $j=1, \ldots, n$ and $i=1, \ldots, m$, let $X_{j}$ denote the $j$-th component of $X$, and let $\alpha_{i j}$ denote the $j$-th component of $\alpha_{i}$. Then

$$
X_{j}(x, t)=-\frac{1}{\rho^{2}} \frac{\partial h}{\partial t}\left(\overline{\rho_{1}}\|x\|_{\mathbf{w}}^{2 e_{1}} \alpha_{1 j}+\cdots+\overline{\rho_{m}}\|x\|_{\mathbf{w}}^{2 e_{m}} \alpha_{m j}\right)
$$

Since $\operatorname{fil}\left(\alpha_{i}\right)=d_{i}$, we have $\operatorname{fil}\left(\alpha_{i j}\right) \geq d_{i}+w_{j}$, thus $\left|\alpha_{i j}\right| \lesssim\|x\|_{\mathbf{w}}^{d_{i}+w_{j}}$. Then,

$$
\begin{aligned}
\left|X_{j}(x, t)\right| & \lesssim \frac{1}{\rho}\left|\frac{\partial h}{\partial t}\right|\|x\|_{\mathbf{w}}^{e_{\mathbf{w}}}\|x\|_{\mathbf{w}}^{d_{1}+w_{j}}+\cdots+\frac{1}{\rho}\left|\frac{\partial h}{\partial t}\right|\|x\|_{\mathbf{w}}^{e_{m}}\|x\|_{\mathbf{w}}^{d_{m}+w_{j}} \\
& \lesssim \frac{1}{\rho}\left|\frac{\partial h}{\partial t}\right|\|x\|_{\mathbf{w}}^{s}\|x\|_{\mathbf{w}}^{w_{j}} \lesssim \frac{1}{\rho} \sup _{i}\left\{\left|\rho_{i}\right|\|x\|_{\mathbf{w}}^{-d_{i}}\right\}\|x\|_{\mathbf{w}}^{s}\|x\|_{\mathbf{w}}^{w_{j}} \lesssim\|x\|_{\mathbf{w}}^{w_{j}}
\end{aligned}
$$

It follows that $\left|X_{j}(x, t)\right| \leq C\|x\|_{\mathrm{w}}^{w_{j}}$, for $j=1, \ldots, n$ and this implies that the vector field $X$ is integrable. In the real case a proof follows from $[8$, p. 87]. For completeness we include below a proof which holds both for the real and complex case.

Lemma 3.5. Let

$$
X(x, t)= \begin{cases}\sum_{j=1}^{n} X_{j}(x, t) \frac{\partial}{\partial x_{j}}+\frac{\partial}{\partial t} & \text { if } x \neq 0 \\ \frac{\partial}{\partial t} & \text { if } x=0\end{cases}
$$

be a vector field in $k^{n} \times k, 0$, such that $X_{j}$ are real analytic away from $0 \times k$ and there exists $C>0$ with $\left|X_{j}(x, t)\right| \leq C\|x\|_{\mathbf{w}}^{w_{j}}$ for all $j=1, \ldots, n$. Then $X(x, t)$ is locally integrable in a neighbourhood of $(0,0) \in k^{n} \times k$.

Proof. The vector field $X$ is real analytic away from $0 \times k$. We only need to prove the uniqueness of the solutions at $(0, t)$. In fact, $\phi(\tau)=(0, \tau+t)$ is an integral curve of $X$ such that $\phi(0)=(0, t)$. Let $\varphi(\tau)=(x(\tau), t(\tau))$, be another integral curve with initial condition $\varphi(0)=(0, t)$. Since $x(0)=0$, $x_{j}(0)=0$, for all $j=1, \ldots, n$. Then

$$
x_{j}(\tau)=\int_{0}^{\tau} \frac{\partial \varphi_{j}}{\partial s} d s=\int_{0}^{\tau} X_{j}(x(s), t(s)) d s
$$

and

$$
\left|x_{j}(\tau)\right| \leq \int_{0}^{\tau}\left|X_{j}(x(s), t(s))\right| d s \leq \int_{0}^{\tau} C\|x(s)\|_{\mathbf{w}}^{w_{j}} d s
$$

Therefore

$$
\begin{aligned}
\|x(\tau)\|_{\mathbf{w}}^{2 w} & =\sum_{j=1}^{n}\left|x_{j}(\tau)\right|^{2 w / w_{j}} \leq \sum_{j=1}^{n}\left(\int_{0}^{\tau}\|x(s)\|_{\mathbf{w}}^{w_{j}} d s\right)^{2 w / w_{j}} \\
& \leq n \int_{0}^{\tau}\|x(s)\|_{\mathbf{w}}^{2 w} d s .
\end{aligned}
$$

By the Gronwall's inequality, it follows that $x(\tau)=0$. Thus $\varphi(\tau)=$ $(0, t(\tau))$. However,

$$
\frac{d}{d \tau}(\phi(\tau)-\varphi(\tau))=X(0, \tau+t)-X(0, t(\tau))=0
$$

therefore $t(\tau)=\tau+t$ and $\varphi \equiv \phi$.
The following corollary of Theorem 3.4 follows when we consider the trivial filtration $w_{i}=1, i=1, \ldots, n$ in $k^{n}$.

Corollary 3.6. Let $h_{0}: k^{n}, 0 \rightarrow k, 0$ be a $\mathcal{R}_{V}$-finitely determined germ and $h: k^{n} \times k, 0 \rightarrow k, 0$ a good deformation of $h_{0}$. If $\left|\frac{\partial h}{\partial t}\right| \lesssim$ $\sup _{i}\left\{\left|d h_{t}\left(\alpha_{i}\right)\right|\right\}$, then $h$ is $C^{0}-\mathcal{R}_{V}$-trivial.

This result first appeared in [13], but there the sufficient condition for topological triviality was formulated in terms of the integral closure of the ideal $\left\langle d h_{t}\left(\alpha_{i}\right)\right\rangle$.

Definition 3.7. A germ of an analytic variety $V, 0 \subseteq k^{n}, 0$ is weighted homogeneous if it is defined by a weighted homogeneous map germ $f$ : $k^{n}, 0 \rightarrow k^{p}, 0$. A set of generators $\left\{\alpha_{1}, \ldots, \alpha_{m}\right\}$ of $\Theta_{V}$ is weighted homogeneous of type $\left(w_{1}, \ldots, w_{n}: d_{1}, \ldots, d_{m}\right)$ if $\alpha_{i j}(i=1, \ldots, m, j=1, \ldots, n)$ are weighted homogeneous polynomials of type $\left(w_{1}, \ldots, w_{n}: d_{i}+w_{j}\right)$ whenever $\alpha_{i j} \neq 0$, where $\alpha_{i}=\sum_{j=1}^{n} \alpha_{i j} \frac{\partial}{\partial x_{j}}$.

When $V$ is a weighted homogeneous variety, we can always choose weighted homogeneous generators for $\Theta_{V}$ (see [7]).

Definition 3.8. ([5]) Let $V$ be defined by weighted homogeneous polynomials. We say that $h$ is weighted homogeneous consistent with $V$ if $h$ is weighted homogeneous with respect to the same set of weights assigned to $V$.

Example 3.9. Let $V=\phi^{-1}(0) \subset k^{3}$ where $\phi(x, y, z)=2 x^{2} y^{2}+y^{3}-$ $z^{2}+x^{4} y$. We have $\phi$ is weighted homogeneous with respect to the weights $w_{1}=1, w_{2}=2, w_{3}=3$. Let $h(x, y, z)=x^{3}+x y+z$ and $f(x, y, z)=$ $x^{3}+x y+z^{2}$. Then $h$ is consistent with $V, f$ is weighted homogeneous but not consistent with $V$.

The following result was previously proved by J. Damon in [6]. We include it here as a corollary of Theorem 3.4.

Corollary 3.10. Let $V$ be a weighted homogeneous subvariety of $k^{n}, 0$ and let $h_{0}: k^{n}, 0 \rightarrow k, 0$ be weighted homogeneous consistent with $V$ and $\mathcal{R}_{V}$-finitely determined. Then any deformation $h$ of $h_{0}$ by terms of filtration greater than or equal to the filtration of $h_{0}$ is $C^{0}-\mathcal{R}_{V}$-trivial.

Proof. Let $\left\{\alpha_{1}, \ldots, \alpha_{m}\right\}$ be a set of weighted homogeneous generators of $\Theta_{V}$, and $d_{i}=\operatorname{fil}\left(\alpha_{i j}\right)-w_{j}$. Under the above conditions, $d h_{0}\left(\alpha_{i}\right)$ and $\rho^{2}(x, 0)=\sum_{i=1}^{m}\left|d h_{0}\left(\alpha_{i}\right)\right|^{2}\|x\|_{\mathbf{w}}^{2 e_{i}}$ are both weighted homogeneous. Since $h_{0}$
is $\mathcal{R}_{V}$-finitely determined, it follows that $\rho^{2}(x, 0)$ has isolated singularity at zero in $k^{n}$. Moreover, $\rho^{2}(x, t)$ is a deformation of $\rho^{2}(x, 0)$ by terms of filtration greater than or equal to the filtration $h_{0}$. Then there exist positive constants $c_{1}, c_{2}$ such that $c_{1} \rho^{2}(x, 0) \leq \rho^{2} \leq c_{2} \rho^{2}(x, 0)$ and thus $h$ is a good deformation of $h_{0}$ (see [11, Lemma 3]), for $t$ sufficiently close to zero.

Now fil $\left(\frac{\partial h}{\partial t}\right) \geq \operatorname{fil}\left(h_{0}\right)$ and

$$
\operatorname{fil}\left(d h_{t}\left(\alpha_{i}\right)\|x\|_{\mathbf{w}}^{-d_{i}}\right)=\operatorname{fil}\left(h_{0}\right)-w_{j}+\left(d_{i}+w_{j}\right)+\left(-d_{i}\right)=\operatorname{fil}\left(h_{0}\right)
$$

Since $h$ is a good deformation of $h_{0}$, it follows that

$$
\left|\frac{\partial h}{\partial t}\right| \lesssim \sup _{i}\left\{\left|d h_{t}\left(\alpha_{i}\right)\right|\|x\|_{\mathbf{w}}^{-d_{i}}\right\}
$$

and result follows by Theorem 3.4.

Example 3.11. Let $V, 0 \subset \mathbb{R}^{3}, 0$ (or $\left.\mathbb{C}^{3}, 0\right)$ be defined by $\varphi(x, y, z)=$ $2 x^{k+1} y^{2}+y^{3}-z^{2}+x^{2(k+1)} y=0$. This is the implicit equation for the $S_{k^{-}}$ singularities classified by D. Mond [10]. The function germ $\varphi$ is weighted homogeneous of weights $2,2 k+2$ and $3 k+3$ for $x, y$ and $z$ respectively. We have that $h(x, y, z)=y+a_{k+1} x^{k+1}$ is $\mathcal{R}_{V}$-finitely determined for $a_{k+1} \neq 0,1$ and consistent with $V$. Therefore deformations of $h$ by terms of order higher than or equal to $\operatorname{fil}(h)$ are $C^{0}-\mathcal{R}_{V}$-trivial. For $k$ odd, $h_{1}(x, y, z)=$ $z+a x^{3(k+1) / 2}$ and $h_{2}(x, y, z)=z+b x^{(k+1) / 2} y$ are consistent with $V$ and $\mathcal{R}_{V}$-finite for all $a^{2} \neq-4 / 27$ and $b \neq \pm 2$. Thus deformations of $h_{1}$ and $h_{2}$, respectively by terms of order higher than or equal to $\operatorname{fil}\left(h_{1}\right)$ and $\operatorname{fil}\left(h_{2}\right)$ are $C^{0}-\mathcal{R}_{V}$-trivial.

The following example shows that the hypothesis in Corollary 3.10 can hold even when the condition $\left|\frac{\partial h}{\partial t}\right| \lesssim \sup _{i}\left\{\left|d h_{t}\left(\alpha_{i}\right)\right|\right\}$ does not hold.

Example 3.12. Taking $k=1$ in the above example, the module $\Theta_{V}$ is generated by $\alpha_{1}=(2 x, 4 y, 6 z), \alpha_{2}=\left(0,2 z, x^{4}+4 x^{2} y+3 y^{2}\right), \alpha_{3}=$ $\left(x^{2}+3 y,-4 x y, 0\right)$ and $\alpha_{4}=\left(z, 0,2 x^{3} y+2 x y^{2}\right)$. Any deformation of the germ $h_{0}(x, y, z)=y+a x^{2}, a \neq 0,1$ by terms of filtrations higher than or equal to fil $\left(h_{0}\right)=2$ are $\mathcal{R}_{V}$-topologically trivial. In particular $h(x, y, z, t)=$ $y+(a+t) x^{2}$ is $\mathcal{R}_{V}$-topologically trivial. However the condition $\left|\frac{\partial h}{\partial t}\right|=$ $\left|x^{2}\right| \lesssim \sup _{i}\left\{\left|d h_{t}\left(\alpha_{i}\right)\right|\right\}$ does not hold. In fact, one can easily check that it fails along the curve $\phi: k, 0 \rightarrow k^{4}, 0, \phi(s)=\left(s,-a s^{2}, 0,0\right)$.

## §4. Topological triviality and Newton polyhedron

In this section, we study the $C^{0}-\mathcal{R}_{V}$-triviality of deformations $h(x, t)=$ $h_{0}(x)+t g(x)$ of a $\mathcal{R}_{V}$-finitely determined germ $h_{0}$. Our sufficient conditions depend only on $h_{0}$, so they can be handled more easily than the hypothesis of Theorem 3.4.

The first result is the following theorem.
ThEOREM 4.1. Let $\mathbf{w}=\left(w_{1}, \ldots, w_{n}\right)$ be an $n$-tuple of positive integers. Let $\alpha_{1}, \ldots, \alpha_{m}$ be a system of generators for $\Theta_{V}^{0}$ and $d_{i}=\operatorname{fil}\left(\alpha_{i}\right), i=$ $1, \ldots, m$. Let $h(x, t)=h_{0}(x)+t g(x)$ be a deformation of a $\mathcal{R}_{V}$-finitely determined germ $h_{0}$ satisfying the following conditions:
(a) $|g| \lesssim \sup _{i}\left\{\left|d h_{0}\left(\alpha_{i}\right)\right|\|x\|_{\mathbf{w}}^{-d_{i}}\right\} ;$
(b) $\left|d g\left(\alpha_{j}\right)\right| \lesssim \sup _{i}\left\{\left|d h_{0}\left(\alpha_{i}\right)\right|\|x\|_{\mathbf{w}}^{-d_{i}}\right\}$ for $x(\neq 0)$ near 0 and all $j=$ $1, \ldots, m$.
Then $h$ is $C^{0}-\mathcal{R}_{V}$-trivial.
The proof of the theorem will follow from the Theorem 3.4 and the Lemma below.

Lemma 4.2. Let $h$ be as above. If $\left|d g\left(\alpha_{j}\right)\right| \lesssim \sup _{i}\left\{\left|d h_{0}\left(\alpha_{i}\right)\right|\|x\|_{\mathbf{w}}^{-d_{i}}\right\}$ for $x(\neq 0)$ near 0 and all $j=1, \ldots, m$, then $h$ is a good deformation of $h_{0}$. Moreover, if $|g| \lesssim \sup _{i}\left\{\left|d h_{0}\left(\alpha_{i}\right)\right|\|x\|_{\mathbf{w}}^{-d_{i}}\right\}$ then $|g| \lesssim \sup _{i}\left\{\left|d h_{t}\left(\alpha_{i}\right)\right|\|x\|_{\mathbf{w}}^{-d_{i}}\right\}$.

Proof. By hypothesis there exist a neighbourhood $U$ of 0 in $k^{n}$ and a constant $C>0$ such that

$$
|t|\left|d g\left(\alpha_{j}\right)\right| \leq|t| C \sup _{i}\left\{\left|d h_{0}\left(\alpha_{i}\right)\right|\|x\|_{\mathbf{w}}^{-d_{i}}\right\}
$$

On the other hand,

$$
\begin{aligned}
\sup _{i}\left\{\left|d h_{t}\left(\alpha_{i}\right)\right|\|x\|_{\mathbf{w}}^{-d_{i}}\right\} & =\sup _{i}\left\{\left|d h_{0}\left(\alpha_{i}\right)+t d g\left(\alpha_{i}\right)\right|\|x\|_{\mathbf{w}}^{-d_{i}}\right\} \\
& \geq \sup _{i}\left\{\left|d h_{0}\left(\alpha_{i}\right)\right|\|x\|_{\mathbf{w}}^{-d_{i}}\right\}-|t| \sup _{i}\left\{\left|d g\left(\alpha_{i}\right)\right|\|x\|_{\mathbf{w}}^{-d_{i}}\right\} \\
& \geq \sup _{i}\left\{\left|d h_{0}\left(\alpha_{i}\right)\right|\|x\|_{\mathbf{w}}^{-d_{i}}\right\}-|t| C \sup _{i}\left\{\left|d h_{0}\left(\alpha_{i}\right)\right|\|x\|_{\mathbf{w}}^{-d_{i}}\right\} \\
& \geq(1-\beta) \sup _{i}\left\{\left|d h_{0}\left(\alpha_{i}\right)\right|\|x\|_{\mathbf{w}}^{-d_{i}}\right\}
\end{aligned}
$$

for some $0<\beta<1$ and $|t| \leq \beta / C$. Thus,

$$
\sup _{i}\left\{\left|d h_{t}\left(\alpha_{i}\right)\right|\|x\|_{\mathbf{w}}^{-d_{i}}\right\} \geq K \sup _{i}\left\{\left|d h_{0}\left(\alpha_{i}\right)\right|\|x\|_{\mathbf{w}}^{-d_{i}}\right\}
$$

for $t$ sufficiently small and $K>0$ and this implies the result.

Before stating the next result, we recall the basic notions of Newton polyhedron of an ideal.

The Newton polyhedron of an ideal in $\mathcal{O}_{n}$ is defined as follows (see [9], [12]). We fix a coordinate system $x$ in $k^{n}$, so that $\mathcal{O}_{n}$ is identified with the ring $k\{x\}$ of convergent power series. For each germ $g(x)=\sum a_{r} x^{r}$, we define supp $g=\left\{r \in \mathbb{Z}^{n}: a_{r} \neq 0\right\}$.

Definition 4.3. (i) Let $I$ be an ideal in $\mathcal{O}_{n}$, define

$$
\operatorname{supp} I=\bigcup\{\operatorname{supp} g: g \in I\}
$$

(ii) The Newton polyhedron of $I$, denoted by $\Gamma_{+}(I)$, is the convex hull in $\mathbb{R}_{+}^{n}$ of the set

$$
\bigcup\left\{r+v: r \in \operatorname{supp} I, v \in \mathbb{R}_{+}^{n}\right\} .
$$

(iii) $\Gamma(I)$ is the union of all compact faces of $\Gamma_{+}(I)$.
(iv) $I=\left\langle g_{1}, \ldots, g_{s}\right\rangle$ is Newton non-degenerate if for each compact face $\triangle \subset \Gamma(I)$, the equations $g_{1 \triangle}(x)=g_{2 \triangle}(x)=\cdots=g_{s \triangle}(x)=0$ have no common solution in $(k-\{0\})^{n}$, where $g_{i \triangle}$ is the restriction of $g_{i}$ to the face $\triangle$, that is, if $g_{i}(x)=\sum a_{r} x^{r}$ then $g_{i \Delta}(x)=\sum_{r \in \triangle} a_{r} x^{r}$.

Definition 4.4. Let $h_{0}$ be $\mathcal{R}_{V}$-finitely determined and $J_{0}=$ $\left\langle d h_{0}\left(\alpha_{i}\right)\right\rangle_{i=1, \ldots, m}$. If $J_{0}$ is Newton non-degenerate we say that $h_{0}$ is Newton non-degenerate with respect to $V$.

We denote by $C\left(\overline{J_{0}}\right)$ the convex hull in $\mathbb{R}_{+}^{n}$ of the set $\left\{r:\left|x^{r}\right| \lesssim\right.$ $\left.\sup _{i}\left|d h_{0}\left(\alpha_{i}\right)\right|\right\}$. When $h_{0}$ is Newton non-degenerate with respect to $V$, it follows from Theorem 3.4 in [12] that $C\left(\overline{J_{0}}\right)=\Gamma_{+}\left(J_{0}\right)$. Taking the trivial filtration $w_{i}=1, i=1, \ldots, n$ in $k^{n}$ in the Theorem 4.1, then we get the following result:

ThEOREM 4.5. Let $h_{0}$ be Newton non-degenerate with respect to $V$. Let $h(x, t)=h_{0}(x)+\operatorname{tg}(x)$ be a deformation of the germ $h_{0}$ with $\Gamma_{+}(g) \subset$ $\Gamma_{+}\left(J_{0}\right)$ and $\Gamma_{+}\left(d g\left(\alpha_{i}\right)\right) \subset \Gamma_{+}\left(J_{0}\right)$. Then $h$ is $C^{0} \mathcal{R}_{V}$-trivial.

EXAMPLE 4.6. Let $V, 0 \subseteq \mathbb{C}^{2}, 0$ be defined by $\varphi(x, y)=x^{3}-y^{2}=0$. The module $\Theta_{V}$ is generated by $\alpha_{1}=(2 x, 3 y)$ and $\alpha_{2}=\left(2 y, 3 x^{2}\right)$. In [2, Theorem 4.9], the $\mathcal{R}_{V}$ classification of germs $h: \mathbb{C}^{2}, 0 \rightarrow \mathbb{C}, 0$ is given, and we find the following normal form $h_{t}(x, y)=y^{2}+a x^{n}+t x^{n+1}, n \geq 4$,
which is finitely determined for $a \neq 0$. Let $h_{0}(x, y)=y^{2}+a x^{n}$. Then $J_{0}=$ $\left\langle 2 a n x^{n}+6 y^{2}, 2 a n x^{n-1} y+6 x^{2} y\right\rangle$ is non-degenerate, hence $C\left(\overline{J_{0}}\right)=\Gamma_{+}\left(J_{0}\right)$. From Theorem 4.5, it follows that $h_{t}$ is $C^{0}-\mathcal{R}_{V}$-trivial.

Example 4.7. Let $V, 0 \subseteq \mathbb{C}^{3}, 0$ be the swallowtail parameterized by $\left(x,-4 y^{3}-2 x y,-3 y^{4}-x y^{2}\right)$. The module $\Theta_{V}$ is generated by $\eta_{1}=$ $(2 x, 3 y, 4 z), \eta_{2}=\left(6 y,-2 x^{2}-8 z, x y\right)$ and $\eta_{3}=\left(-4 x^{2}-16 z,-8 x y, y^{2}\right)$. The $\mathcal{R}_{V}$ classification of germs $h: \mathbb{C}^{3}, 0 \rightarrow \mathbb{C}, 0$ given by Theorem 4.10 in [2], gives the normal form $h_{t}(x, y, z)=z+a x^{n}+t x^{n+1}, n \geq 2$ which is finitely determined for $a \neq 0, n \neq 2$, and $a \neq 0, a \neq 1 / 12, n=2$. Let $h_{0}(x, y, z)=$ $z+a x^{n}, J_{0}=\left\langle 2 a n x^{n}+4 z, 6 a n x^{n-1} y+x y,-4 a n x^{n+1}-16 a n x^{n-1} z+y^{2}\right\rangle$. From Theorem 4.5, $h_{t}$ is $C^{0}-\mathcal{R}_{V}$-trivial.

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