

A SPECTRAL MAPPING THEOREM FOR POLYNOMIAL OPERATOR MATRICES

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Abstract. Systems of linear evolution equations can be written as a single equation

$$\dot{u}(t) = \mathcal{A}u(t), \tag{*}$$

where u is a function with values in a product space E^n and $\mathcal{A} = (A_{ij})_{n \times n}$ is an operator matrix. Often the entries A_{ij} are polynomials $p_{ij}(A)$ with respect to a single (unbounded) operator A on E (see, e.g., [1], [2], [3], [6], [11]). In order to solve (*) one has to determine the properties of the operator matrix \mathcal{A} . In particular one has to find an appropriate domain $D(\mathcal{A})$ such that \mathcal{A} is closed. This will be discussed in the first part of this paper. Then it is important to compute the spectrum $\sigma(\mathcal{A})$ of \mathcal{A} . One expects a kind of spectral mapping theorem based on the spectrum $\sigma(A)$ of A and the structure of the matrix (p_{ij}) . We show in Part 2 in which sense such a spectral mapping theorem holds. An application to stability theory, i.e., the computation of an estimate for the spectral bound $s(\mathcal{A})$ concludes this paper. In a subsequent paper we discuss which operator matrices $(p_{ij}(A))$ generate strongly continuous semigroups on E^n and give applications to systems of differential equations.

1. How to define an operator matrix? We study $n \times n$ matrices \mathcal{A} whose entries are polynomials $p_{ij}(A)$ in a fixed – possibly unbounded – operator A on some Banach space E .

For bounded A it is obvious that the operator matrix \mathcal{A} defines a bounded operator on the product space $\mathcal{E} := E^n$. The situation for unbounded A is more complicated. In fact, the matrix \mathcal{A} only induces a formal map

$$x = (x_1, \dots, x_n)^t \mapsto \mathcal{A}x = \left(\sum_{i=1}^n p_{1i}(A)x_i, \dots, \sum_{i=1}^n p_{ni}(A)x_i \right)^t,$$

but leaves open a wide choice of possible domains. If one wants “nice” properties of \mathcal{A} , such as closedness for example, then a more careful analysis is necessary.

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Let us consider the following simple example. Take a closed, unbounded operator A with dense domain $D(A)$ in E . If

$$\mathcal{A} = \begin{pmatrix} A & -A \\ 0 & 0 \end{pmatrix},$$

then it might seem reasonable to choose $D(\mathcal{A}) = D(A) \times D(A)$. However, with this domain the operator $(\mathcal{A}, D(\mathcal{A}))$ is not closed. To see this take $x \in E \setminus D(A)$ and let $(x_n) \subset D(A)$ be a sequence converging to x . Set $y_n := \begin{pmatrix} x_n \\ x_n \end{pmatrix}$. Then y_n converges to $y = \begin{pmatrix} x \\ x \end{pmatrix}$ and $\mathcal{A}y_n = 0$ for all $n \in \mathbb{N}$. Clearly $y \notin D(\mathcal{A})$ and hence $(\mathcal{A}, D(\mathcal{A}))$ is not closed. As we will show later a more reasonable domain for \mathcal{A} is $D(\mathcal{A}) = \left\{ \begin{pmatrix} x \\ y \end{pmatrix} \in E^2 : x - y \in D(A) \right\}$.

From this and other examples we see that in general the appropriate domain $D(\mathcal{A})$ of an operator matrix \mathcal{A} will not be “diagonal”, this means, the product of domains in E . This causes a number of difficulties and will be carefully studied in the sequel.

Throughout this paper A denotes a linear, densely defined operator with domain $D(A)$ in some (complex) Banach space E . We also assume that the resolvent set $\rho(A)$ of A is not empty. Before defining operator matrices and their domains we need a functional calculus for certain functions on the spectrum $\sigma(A)$ of A .

Let $\mathbb{C}[x]$ be the ring of polynomials in x over \mathbb{C} , $\mathbb{C}(x)$ its quotient field and $\mathbb{C}_0[x] := \{p \in \mathbb{C}[x] : p(0) = 0\}$. For an element $f = \frac{p}{q} \in \mathbb{C}(x)$ we define $[f] := \deg(p) - \deg(q)$ where $\deg(p)$ is the degree of the polynomial p . For each $\lambda \in \mathbb{C}$ we define the linear polynomial ξ_λ by $\xi_\lambda(x) := x - \lambda$. The polynomial ξ_0 is denoted simply by ξ .

We now consider a class of functions for which a functional calculus for unbounded operators exists.

Definition 1.1. For a given linear operator A we consider the following classes of functions:

$$\mathcal{G} = \mathcal{G}(A) := \{f \in \mathbb{C}(x) : f \text{ holomorphic in a neighborhood of } \sigma(A)\},$$

$$\mathcal{N} = \mathcal{N}(A) := \{f \in \mathcal{G} : [f] \leq 0\}.$$

Then \mathcal{G} is a commutative algebra and \mathcal{N} a subalgebra of \mathcal{G} . Since $\mathcal{G} = \mathbb{C}_0[x] \oplus \mathcal{N}$ it is possible to decompose every $f \in \mathcal{G}$ into a unique sum of an “unbounded” part in $\mathbb{C}_0[x]$ and a “bounded” part in \mathcal{N} . As we have shown in Theorem A.2 it is possible to define $f(A)$ with domain $D(f(A)) := D(A^m)$ for $m = \max\{0, [f]\}$ for all $f \in \mathcal{G}$. Then $f(A)$ is a closed, densely defined operator on E . Moreover the following holds (for the details see the Appendix).

The functional calculus $\Phi : f \mapsto \Phi(f) := f(A)$ is an “algebra homomorphism” from \mathcal{G} into the set of all linear, densely defined, closed operators on E . Moreover, for unbounded A , the operator $f(A)$ is bounded if and only if $f \in \mathcal{N}$.

Concerning matrices we need some further definitions. The ring of all $n \times n$ matrices with entries from a set L is denoted by $M_n(L)$. Thus $M_n(\mathbb{C}[x])$, $M_n(\mathbb{C}(x))$, $M_n(\mathcal{G})$, $M_n(\mathcal{N})$ and so on are all well defined. Clearly $M_n(\mathcal{G})$ and $M_n(\mathcal{N})$ are subrings of $M_n(\mathbb{C}(x))$ and we have $M_n(\mathcal{G}) = M_n(\mathbb{C}_0[x]) \oplus M_n(\mathcal{N})$. Hence, every matrix in $M_n(\mathcal{G})$ can be written as a unique sum of an “unbounded” part in $M_n(\mathbb{C}_0[x])$ and a “bounded” part in $M_n(\mathcal{N})$. For an element $M = \sum_{k=0}^m \xi^k \cdot M_k$ of $M_n(\mathbb{C}[x])$ we call $M_m \in M_n(\mathbb{C})$ the *principal coefficient matrix* of M .

It is our aim to define a closed operator $M(A)$ for matrices $M = (m_{ik}) \in M_n(\mathcal{G})$. First assume $M \in M_n(\mathcal{N})$. Then by Theorem A.2 the operator matrix $M(A)$ defined by $M(A) :=$

$(m_{ik}(A))$ is bounded on \mathcal{E} .

Now take $M \in M_n(\mathcal{G})$ and $m := \max_{ik}[m_{ik}] > 0$. Let $\lambda \in \rho(A)$ and $U_\lambda := \text{diag}(\xi_\lambda^m, \dots, \xi_\lambda^m)$. Then U_λ has an inverse in $M_n(\mathcal{N})$ and $M = U_\lambda(MU_\lambda^{-1}) =: U_\lambda B_\lambda$ where $B_\lambda \in M_n(\mathcal{N})$. Hence, $B_\lambda(A)$ is bounded on \mathcal{E} . On the other hand $U_\lambda(A)$ with domain $D(U_\lambda(A)) = D(A^m)^n$ is invertible and therefore closed. In the following definition we use this decomposition in order to define $\mathcal{A} := M(A)$ as a closed operator on \mathcal{E} .

Definition 1.2. Let A be a densely defined operator with non-empty resolvent set $\rho(A)$. For a matrix $M = (m_{ik}) \in M_n(\mathcal{G})$ decomposed as $M = U_\lambda \cdot B_\lambda$ for some $\lambda \in \rho(A)$ (see above) the operator matrix \mathcal{A}_λ is defined by

$$\mathcal{A}_\lambda := U_\lambda(A) \cdot B_\lambda(A)$$

with domain

$$D(\mathcal{A}_\lambda) := \{x \in \mathcal{E} : B_\lambda(A)x \in D(U_\lambda(A))\}.$$

Here $D(U_\lambda(A)) = D(A^m)^n$ where $m := \max\{0, [m_{ik}]; i, k = 1, \dots, n\}$.

We show that the above definition is independent of $\lambda \in \rho(A)$ and yields a closed operator.

Proposition 1.3. Let $\lambda \in \rho(A)$ and \mathcal{A}_λ be defined as in Definition 1.2. Then

- (i) $(\mathcal{A}_\lambda, D(\mathcal{A}_\lambda))$ is a closed, densely defined operator and
- (ii) $(\mathcal{A}_\lambda, D(\mathcal{A}_\lambda)) = (\mathcal{A}_\mu, D(\mathcal{A}_\mu))$ for all $\mu \in \rho(A)$.

Proof: (i) The operator $U_\lambda(A)$ is invertible in $\mathcal{L}(\mathcal{E})$ and therefore closed. Thus the product of the operator $U_\lambda(A)$ with the bounded operator $B_\lambda(A)$ is closed (see Chapter III.5, [7]). Since $D(A^l)^n \subset D(A)$ for all $l \in \mathbb{N}$, $l > \max_{i,k}[m_{ik}]$ we have shown (i).

(ii) Take $\mu \in \rho(A)$ and define $C_{\lambda,\mu} := \text{diag}((\frac{\xi_\lambda}{\xi_\mu})^m, \dots, (\frac{\xi_\lambda}{\xi_\mu})^m)$. Apparently $C_{\lambda,\mu}$ and its inverse $C_{\mu,\lambda}$ are elements of $M_n(\mathcal{N})$. From Theorem A.2 it follows that $U_\lambda(A)C_{\mu,\lambda}(A) = U_\mu(A)$ and $C_{\lambda,\mu}(A)B_\lambda(A) = B_\mu(A)$. Hence,

$$\begin{aligned} \mathcal{A}_\lambda &= U_\lambda(A)B_\lambda(A) = (U_\lambda(A)C_{\mu,\lambda}(A)) \cdot (C_{\lambda,\mu}(A)B_\lambda(A)) \\ &= U_\mu(A)B_\mu(A) = \mathcal{A}_\mu. \end{aligned}$$

■

Thus, for all $M \in M_n(\mathcal{G})$ we can define the operator matrix $\mathcal{A} = M(A)$ by $M(A) := U_\lambda(A)B_\lambda(A)$ for some $\lambda \in \rho(A)$. By Φ_n we denote the *functional calculus*

$$\Phi_n : M \mapsto M(A), \quad M \in M_n(\mathcal{G}).$$

We remark that Φ_n assumes its values in the set of all linear, densely defined, closed operators on \mathcal{E} .

Remark. Using the same construction we can also define non-quadratic operator matrices. For example let $R = (r_1, \dots, r_n) \in (\mathbb{C}[x])^n$. If $\lambda \in \rho(A)$, then

$$R = \underbrace{\xi_\lambda^m}_{\in \mathbb{C}[x]} \cdot \underbrace{\left(\frac{r_1}{\xi_\lambda^m}, \dots, \frac{r_n}{\xi_\lambda^m} \right)}_{\in \mathcal{N}^n}$$

for $m := \max\{[r_1], \dots, [r_n]\}$. Since $\xi_\lambda^m(A)$ is closed and $(\frac{r_1}{\xi_\lambda^m}(A), \dots, \frac{r_n}{\xi_\lambda^m}(A))$ is bounded the operator

$$R(A) := \xi_\lambda^m(A) \left(\frac{r_1}{\xi_\lambda^m}(A), \dots, \frac{r_n}{\xi_\lambda^m}(A) \right)$$

with the domain

$$D(R(A)) := \left\{ x \in E^n : \left(\frac{r_1}{\xi_\lambda^m}(A), \dots, \frac{r_n}{\xi_\lambda^m}(A) \right) x \in D(A^m) \right\}$$

is closed.

The next result is central for the following. It shows that in some sense the functional calculus Φ_n is an “algebra” homomorphism.

Proposition 1.4. *Let $S, T, L, M \in M_n(\mathcal{G})$ and set $\mathcal{S} := S(A), \mathcal{T} := T(A), \mathcal{L} := L(A)$ and $\mathcal{A} := M(A)$. Then*

- (i) $(L + M)(A) \supseteq \mathcal{L} + \mathcal{A}$,
- (ii) $(L + M)(A) = \mathcal{L} + \mathcal{A}$ if $L \in M_n(\mathcal{N})$,
- (iii) $(S \cdot M \cdot T)(A) \supseteq \mathcal{S} \cdot \mathcal{A} \cdot \mathcal{T}$,
- (iv) $(S \cdot M \cdot T)(A) = \mathcal{S} \cdot \mathcal{A} \cdot \mathcal{T}$ if $S, S^{-1}, T \in M_n(\mathcal{N})$.

Proof: (i) and (iii) follow immediately from Theorem A.2. Since \mathcal{L} is bounded for $L \in M_n(\mathcal{N})$, (ii) is an easy consequence of (i).

It remains to prove (iv). It suffices to show that

$$(SM)(A) = \mathcal{S}\mathcal{A} \text{ if } S, S^{-1} \in M_n(\mathcal{N}) \tag{1.1}$$

and $(MT)(A) = \mathcal{A}\mathcal{T}$ if $T \in M_n(\mathcal{N})$. The second assertion is clear by (iii) and Definition 1.2, thus consider (1.1). Let $\mathcal{A} = \mathcal{U} \cdot \mathcal{B}$, where $\mathcal{U} = \mathcal{U}_\lambda = \text{diag}((A - \lambda)^m, \dots, (A - \lambda)^m)$ and $\mathcal{B} = \mathcal{B}_\lambda \in \mathcal{L}(\mathcal{E})$ as in Definition 1.2. We only have to show that $\mathcal{S} \cdot \mathcal{U} = \mathcal{U} \cdot \mathcal{S}$, i.e., $D(\mathcal{U}) = D(\mathcal{U}\mathcal{S})$. Since $S^{-1} \in M_n(\mathcal{N})$ the operator \mathcal{S} is invertible in $\mathcal{L}(\mathcal{E})$ and we obtain $SD(\mathcal{U}) \subset D(\mathcal{U})$ and $S^{-1}D(\mathcal{U}) \subset D(\mathcal{U})$. Hence, $D(\mathcal{U}) = S^{-1}D(\mathcal{U}) = D(\mathcal{U}\mathcal{S})$. ■

Lemma 1.5. *Let $M \in M_n(\mathcal{G})$. Then there exist invertible matrices $S, T \in M_n(\mathcal{N})$ such that $SMT = D + N$. Here $D \in M_n(\mathbb{C}_0[x])$ is diagonal and N belongs to $M_n(\mathcal{N})$.*

Proof: After multiplication of M with suitable permutation matrices we can suppose $[m_{11}] = \max_{i,k} [m_{ik}]$. By Proposition A.3 there are elements $\alpha_2, \dots, \alpha_n, \beta_2, \dots, \beta_n \in \mathcal{N}$ such that $\alpha_k m_{11} + m_{k1} \in \mathcal{N}$ and $\beta_k m_{11} + m_{1k} \in \mathcal{N}$ for $k = 2, \dots, n$. Set

$$S_1 := \begin{pmatrix} 1 & 0 & \dots & 0 \\ \alpha_2 & \ddots & & \vdots \\ \vdots & 0 & \ddots & 0 \\ \alpha_n & & & 1 \end{pmatrix}, \quad T_1 := \begin{pmatrix} 1 & \beta_2 & \dots & \beta_n \\ 0 & \ddots & & 0 \\ \vdots & & \ddots & \\ 0 & \dots & 0 & 1 \end{pmatrix} \in M_n(\mathcal{N})$$

and $M_1 := S_1 M T_1 = (m_{ij}^{(1)})$. Then $m_{1j}^{(1)}, m_{j1}^{(1)} \in \mathcal{N}$ for $j \neq 1$.

Now we apply the same procedure to the truncated matrix $(m_{ij}^{(1)})_{i,j=2}^n$ and obtain matrices \tilde{S}_2 and $\tilde{T}_2 \in M_{n-1}(\mathcal{N})$. Next define

$$S_2 := \begin{pmatrix} 1 & 0 \\ 0 & \tilde{S}_2 \end{pmatrix} \in M_n(\mathcal{N}) \quad \text{and} \quad T_2 := \begin{pmatrix} 1 & 0 \\ 0 & \tilde{T}_2 \end{pmatrix} \in M_n(\mathcal{N}).$$

Iterating this $(n - 1)$ -times yields matrices

$$S := S_{n-1} \cdot \dots \cdot S_1 \in M_n(\mathcal{N})$$

and

$$T := T_1 \cdot \dots \cdot T_{n-1} \in M_n(\mathcal{N}).$$

Let $L := (l_{ij}) = SMT$; then by construction $l_{ij} \in \mathcal{N}$ for $i \neq j$. Therefore we can decompose $L \in M_n(\mathcal{G}) = M_n(\mathbb{C}_0[x]) \oplus M_n(\mathcal{N})$ into a sum $L = D + N$ where $D \in M_n(\mathbb{C}_0[x])$ is diagonal and N belongs to $M_n(\mathcal{N})$. Since $\det S = \det T = \pm 1$ both S and T are invertible in $M_n(\mathcal{N})$ which completes the proof. ■

Corollary 1.6. *Let $M = (m_{ik}) \in M_n(\mathcal{G})$ and define $\mathcal{A} := M(A)$. If $l \geq \max\{0, [m_{ik}] : 1 \leq i, k \leq n\}$, then $D(A^l)^n \subset D(\mathcal{A})$ is a core of \mathcal{A} . In particular in the situation of Proposition 1.4 we have*

- (i') $(L + M)(A) = \overline{\mathcal{L} + \mathcal{A}}$,
- (iii') $(SMT)(A) = \overline{\mathcal{S}\mathcal{A}\mathcal{T}}$,
- (iv') $(SMT)(A) = \mathcal{S}\mathcal{A}\mathcal{T}$ if $S^{-1}, T \in M_n(\mathcal{N})$.

Proof: First we show that $G := D(A^l)^n$ is a core of \mathcal{A} . Let $SMT = D + N$ as in the previous lemma. Define $\mathcal{S} := S(A)$, $\mathcal{T} := T(A)$ and $\mathcal{D} := \text{diag}(d_1(A), \dots, d_n(A))$ where $D = \text{diag}(d_1, \dots, d_n)$. Then by Proposition 1.4 we have $\mathcal{S}\mathcal{A}\mathcal{T} = \mathcal{D} + N(A)$. Since \mathcal{T} is bounded, invertible and commutes with $\text{diag}(R(\lambda, A)^l, \dots, R(\lambda, A)^l)$ for $\lambda \in \rho(A)$ we obtain that $G = \mathcal{T}^{-1}G$ is contained in the domain $D(\mathcal{D})$ of \mathcal{D} . Using the fact that \mathcal{D} is diagonal and $N(A)$ is bounded it is clear that G is a core of $\mathcal{D} + N(A) = \mathcal{S}\mathcal{A}\mathcal{T}$. This implies that G is a core of $\mathcal{A}\mathcal{T}$. Next we show that $\mathcal{T}G$ is a core of \mathcal{A} : Take $x \in D(\mathcal{A})$, then there exists a sequence $(y_n) \subset G$ such that $y_n \rightarrow \mathcal{T}^{-1}x$ and $(\mathcal{A}\mathcal{T})y_n \rightarrow (\mathcal{A}\mathcal{T})\mathcal{T}^{-1}x = \mathcal{A}x$ as $n \rightarrow \infty$. Now define $x_n := \mathcal{T}y_n$, then $(x_n) \subset \mathcal{T}G$, $x_n \rightarrow x$ and $\mathcal{A}x_n = \mathcal{A}\mathcal{T}y_n \rightarrow \mathcal{A}x$. Therefore $\mathcal{T}G = G$ is a core of \mathcal{A} .

Next consider (i'), (iii') and (iv'). Since $D(A^l)^n \subset D(\mathcal{L} + \mathcal{A})$ and $D(A^l)^n \subset D(\mathcal{S}\mathcal{A}\mathcal{T})$ for $l \in \mathbb{N}$ big enough we obtain from Proposition 1.4 the assertions (i') and (iii'). To prove (iv') note that $\mathcal{S}\mathcal{A}$ is closed whenever \mathcal{S} is invertible with bounded inverse. (see [7], Chapter III.2). ■

In the next step we want to obtain more precise information on the size of the domain $D(\mathcal{A})$. It is clear that $D(\mathcal{A})$ depends only on the unbounded part of $\mathcal{A} = M(A)$. So let us assume $M \in M_n(\mathbb{C}_0[x])$. Then it is possible to write $M = \sum_{k=1}^m \xi^k \cdot M_k$ where $M_k \in M_n(\mathbb{C})$ and $m = \max_{i,k} [m_{ik}]$. After the canonical identification of E^n with $E \otimes \mathbb{C}^n$ we obtain $\mathcal{A} = \sum_{k=1}^m A^k \otimes M_k$. Now the following holds.

Proposition 1.7. *Let $M = \sum_{k=1}^m \xi^k \cdot M_k \in M_n(\mathbb{C}[x])$ and $\mathcal{A} := M(A)$. Then*

$$D := \bigcap_{k=1}^m D(A^k \otimes M_k) \subset D(\mathcal{A}) \subset D(A \otimes M_m).$$

If the principal coefficient matrix M_m of M is invertible, then $D(\mathcal{A}) = D(A^m)^n$.

Proof: Assuming $0 \in \rho(A)$ we decompose

$$\mathcal{A} = (A^m \otimes Id) \cdot \left(\sum_{k=1}^m A^{k-m} \otimes M_k \right) = \mathcal{U} \cdot \mathcal{B}$$

as in Definition 1.2 and obtain $D(\mathcal{A}) = \{x \in \mathcal{E} : \mathcal{B}x \in D(A^m)^n\}$. First we show that $\mathcal{B}D \subset D(A^m)^n$. For $x \in D$ it follows that $(Id \otimes M_k)x \in D(A^k)^n$ for all $k = 1, \dots, m$. Therefore $(A^{k-m} \otimes M_k)x \in D(A^m)^n$ and $\mathcal{B}x \in D(A^m)^n$. To show the second inclusion take $x \in D(\mathcal{A})$. Then we have

$$\underbrace{\sum_{k=1}^{m-1} (A^{k-m} \otimes M_k)x + (Id \otimes M_m)x}_{\in D(\mathcal{A})^n} \in D(A^m)^n.$$

Therefore $(Id \otimes M_m)x \in D(\mathcal{A})^n$, i.e., $x \in D(A \otimes M_m)$.

Assume now M_m to be invertible and $x \in D(\mathcal{A})$. By the same arguments as above we obtain $(Id \otimes M_m)x \in D(A)^n$ and conclude, after left multiplication by $(Id \otimes M_m^{-1})$, that $x \in D(A)^n$. Let $x \in D(A^l)^n$ for some $l = 1, \dots, m - 1$. Then from

$$(A^l \otimes Id)\mathcal{B}x = \underbrace{\sum_{k=1}^{m-1} (A^{k+l-m} \otimes M_k)x}_{\in D(A)^n} + (A^l \otimes M_m)x \in D(A^{m-l})^n$$

it follows that $(A^l \otimes M_m)x \in D(A)^n$. As above we deduce $x \in D(A^{l+1})^n$ and by induction $D(\mathcal{A}) = D(A^m)^n$. ■

Example. Take

$$M = \begin{pmatrix} \xi^2 & \xi \\ 0 & 0 \end{pmatrix} = \xi^2 \cdot \underbrace{\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}}_{=:M_2} + \xi \cdot \underbrace{\begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}}_{=:M_1}$$

and

$$\mathcal{A} = \begin{pmatrix} A^2 & A \\ 0 & 0 \end{pmatrix}.$$

An easy computation shows

$$D(\mathcal{A}) = \left\{ \begin{pmatrix} x \\ y \end{pmatrix} \in E^2 : x \in D(A), Ax + y \in D(A) \right\}.$$

Since $D(A \otimes M_2) = D(A) \times E$ and $D(A^2 \otimes M_2) \cap D(A \otimes M_1) = D(A^2) \times D(A)$, we have

$$D = \left(D(A^2 \otimes M_2) \cap D(A \otimes M_1) \right) \neq D(\mathcal{A}) \neq D(A \otimes M_2).$$

2. The spectral mapping theorem for operator matrices. In this part we will calculate the spectrum $\sigma(\mathcal{A})$ of the operator \mathcal{A} with domain $D(\mathcal{A})$ as defined in Part 1. Moreover we give a formula for the resolvent $R(\lambda, \mathcal{A})$ if $\lambda \in \rho(\mathcal{A})$ and derive an estimate for the spectral bound $s(\mathcal{A})$ of \mathcal{A} .

The main tool in the sequel is the operator-valued determinant $\Delta(\mathcal{A})$ which we define first. Recall that for the fixed operator A on E we have

$$\mathcal{G} = \{f \in \mathbb{C}(x) : f \text{ holomorphic in a neighborhood of } \sigma(A)\} \text{ and } \mathcal{N} = \{f \in \mathcal{G} : [f] \leq 0\}.$$

Definition 2.1. Consider $M \in M_n(\mathcal{G})$ and its determinant $\det M$ which is an element of \mathcal{G} . If $\mathcal{A} = M(A)$, then we call the operator

$$\Delta(\mathcal{A}) := (\det M)(A)$$

on E the determinant of \mathcal{A} .

Next we will show that for bounded A the operator matrix \mathcal{A} is invertible in $\mathcal{L}(\mathcal{E})$ if and only if $\Delta(\mathcal{A})$ is invertible in $\mathcal{L}(E)$. More generally we consider bounded operator matrices with commuting entries.

Lemma 2.2. *Let $\mathcal{B} = (B_{ik}) \in \mathcal{L}(\mathcal{E})$ be an operator matrix with commuting entries. Then \mathcal{B} is invertible in $\mathcal{L}(\mathcal{E})$ if and only if $\det \mathcal{B}$ is invertible in $\mathcal{L}(E)$.*

Proof: Let $\det \mathcal{B}$ be invertible in $\mathcal{L}(E)$. Then $\mathcal{B}^{-1} = (\det \mathcal{B})^{-1} \text{Adj}(\mathcal{B})$ by [8], Proposition 8, p.334, where $\text{Adj}(\mathcal{B})$ denotes the co-factor matrix of \mathcal{B} .

Conversely assume \mathcal{B} to be invertible with inverse $\mathcal{B}^{-1} = (J_{ik}) \in \mathcal{L}(\mathcal{E})$. First we show that all entries of \mathcal{B} and \mathcal{B}^{-1} commute. Take $j, l \in \{1, \dots, n\}$ and define $\mathcal{D}_1 := \text{diag}(B_{jl}, \dots, B_{jl}) \in \mathcal{L}(\mathcal{E})$. Since the entries of \mathcal{B} commute we have $\mathcal{D}_1 \mathcal{B} = \mathcal{B} \mathcal{D}_1$. This implies $\mathcal{B}^{-1} \mathcal{D}_1 = \mathcal{D}_1 \mathcal{B}^{-1}$, i.e., every entry of \mathcal{B}^{-1} commutes with B_{jl} . Thus every entry of \mathcal{B} commutes with all entries of \mathcal{B}^{-1} . Using this we obtain $\mathcal{D}_2 \mathcal{B} = \mathcal{B} \mathcal{D}_2$ where $\mathcal{D}_2 := \text{diag}(J_{jl}, \dots, J_{jl})$ for some fixed $j, l \in \{1, \dots, n\}$. This yields $\mathcal{B}^{-1} \mathcal{D}_2 = \mathcal{D}_2 \mathcal{B}^{-1}$, i.e., the entries of \mathcal{B}^{-1} commute. Now by [8], Proposition 7, p.334 we conclude $Id = \det(\mathcal{B}) \det(\mathcal{B}^{-1}) = \det(\mathcal{B}^{-1}) \det(\mathcal{B})$, i.e., $\det \mathcal{B}$ is invertible with inverse $\det(\mathcal{B}^{-1})$. ■

For A unbounded the situation is more complicated. Take, for example, $M = \begin{pmatrix} \xi & 1 \\ 1 & 0 \end{pmatrix}$ and $\mathcal{A} = \begin{pmatrix} A & Id \\ Id & 0 \end{pmatrix}$. Here $\Delta(\mathcal{A}) = -Id$ is invertible while the “formal” inverse $\begin{pmatrix} 0 & Id \\ Id & -A \end{pmatrix}$ is unbounded and hence \mathcal{A} does not have a bounded inverse. The following theorem shows how to deal with this situation.

Theorem 2.3. *Let A be a linear unbounded operator on E . For $M \in M_n(\mathcal{G})$ and $\mathcal{A} := M(A)$ the following assertions are equivalent.*

- (a) \mathcal{A} is invertible in $\mathcal{L}(\mathcal{E})$
- (b) M is invertible in $M_n(\mathcal{N})$
- (c) (i) $\frac{1}{\det M} \in \mathcal{N}$ and
 (ii) $\lim_{\alpha \rightarrow \infty} M^{-1}(\alpha)$ exists in $M_n(\mathbb{C})$.

Proof: (a) \iff (b): Let $SMT = D + N$ be a decomposition as in Lemma 1.5. Since S and T are invertible in $M_n(\mathcal{N})$ the bounded operator matrices $S(A)$ and $T(A)$ are also invertible with bounded inverse. From this and Proposition 1.4 we deduce that \mathcal{A} is invertible if and only if $S(A) \mathcal{A} T(A) = (SMT)(A)$ is invertible in (\mathcal{E}) . Therefore we may restrict ourselves to consider $\mathcal{A} = M(A)$ where M is given by a sum $M = D + N$. Here N is contained in $M_n(\mathcal{N})$ and $D = (d_{ik}) \in M_n(\mathbb{C}_0[x])$ is diagonal.

Take some fixed number $\lambda \in \rho(A)$. Then $U := \text{diag}(\xi_\lambda^{\nu_1}, \dots, \xi_\lambda^{\nu_n})$ where $\nu_k := [d_{kk}]$ for $k = 1, \dots, n$ is invertible in $M_n(\mathcal{N})$. By definition of U we have $B := MU^{-1} \in M_n(\mathcal{N})$ and $D(U(A)) = D(A)$. Hence, $\mathcal{A} = B(A)U(A)$ by Proposition 1.4 (iii). Since $U(A)$ is invertible in $\mathcal{L}(\mathcal{E})$ this implies that \mathcal{A} is invertible if and only if $B(A)$ is invertible. Using the fact that all entries of $B(A)$ are bounded and commute we obtain from Lemma 2.2, that $B(A)$ is invertible if and only if $\Delta(B(A)) = (\det(B))(A)$ is invertible in $\mathcal{L}(E)$. By Theorem A.2 (v) this is equivalent to $\frac{1}{\det(B)} \in \mathcal{N}$. Thus the inversion formula for matrices implies that $B(A)$ is invertible in $\mathcal{L}(\mathcal{E})$ if and only if B is invertible in $M_n(\mathcal{N})$. The only thing that remains to be proved is that B is invertible in $M_n(\mathcal{N})$ if and only if $M = BU$ is invertible in $M_n(\mathcal{N})$.

Let $B^{-1} \in M_n(\mathcal{N})$. Then $M^{-1} = U^{-1}B^{-1} \in M_n(\mathcal{N})$. For the converse implication note that $[m_{kk}] = \nu_k$ where m_{kk} denotes the k -th diagonal entry of M . If M^{-1} exists it is given by $M^{-1} = (\det M)^{-1} \cdot (\tilde{m}_{ik})$ where $(\tilde{m}_{ik}) = \text{Adj}(M)$. Here $\text{Adj}(M)$ denotes the co-factor matrix of M (see[8], p.334). Since $[\det M] = \sum_{k=1}^n \nu_k$ and $[\tilde{m}_{ik}] \leq \sum_{j \neq i, k} \nu_j$ we conclude $B^{-1} = U \cdot M^{-1} \in M_n(\mathcal{N})$.

(b) \iff (c): First assume (b). The assertion (c.i) follows from the multiplicativity of the determinant while (c.ii) is clear by the definition of \mathcal{N} . If (c) is true, then M is invertible in $M_n(\mathcal{G})$ by (c.i). The second hypothesis now implies $M^{-1} \in M_n(\mathcal{N})$. ■

From the proof of Theorem 2.3 we also obtain an explicit matrix representation for the resolvent $R(\mu_0, \mathcal{A})$.

Corollary 2.4. For $\mu_0 \in \rho(\mathcal{A})$ the resolvent $R(\mu_0, M)$ is an element of $M_n(\mathcal{N})$ and

$$R(\mu_0, \mathcal{A}) = R(\mu_0, M)(A).$$

In the above counter-example $\mathcal{A} = \begin{pmatrix} A & Id \\ Id & 0 \end{pmatrix}$ we have $\det M = -1$ which is invertible in \mathcal{N} but $M^{-1}(\alpha) = \begin{pmatrix} 0 & 1 \\ 1 & -\alpha \end{pmatrix}$ has no limit for $\alpha \rightarrow \infty$. Still, condition 2.3(c) seems to be artificial and not very useful. In order to arrive at a concrete description of the spectrum $\sigma(\mathcal{A})$ we first state some consequences of the above considerations.

Corollary 2.5. Let A be a linear unbounded operator on E . For $M \in M_n(\mathcal{G})$ and $\mathcal{A} := M(A)$ the following assertions are equivalent.

- (a) $\mu_0 \in \rho(\mathcal{A})$
- (b) (i) $\Delta(\mu_0 - \mathcal{A})$ is invertible in $\mathcal{L}(\mathcal{E})$ and
 (ii) $Q := \lim_{\alpha \rightarrow \infty} R(\mu_0, M)(\alpha)$ exists in $M_n(\mathbb{C})$.

If one of the assertions (a) or (b) is valid, then $Q = \lim_{n \rightarrow \infty} R(\mu_0, M)(\alpha_n)$ for every sequence $(\alpha_n) \subset \mathbb{C}$ with limit ∞ .

Proof: We have to show that $\Delta(\mu_0 - \mathcal{A})$ is invertible in $\mathcal{L}(E)$ if and only if $\frac{1}{\det(\mu_0 - M)} \in \mathcal{N}$. This is valid by the definition of the determinant Δ and Theorem A.2 (v). ■

Lemma 2.6. Let $S \in M_n(\mathbb{C}(x))$. Then the matrix S is invertible in $M_n(\mathbb{C}(x))$ if and only if there exists some $\alpha \in \mathbb{C}$ such that the complex matrix $S(\alpha)$ is invertible in $M_n(\mathbb{C})$.

Proof: Let S be invertible, i.e., $\det(S) \neq 0$. Then there are infinitely many α such that $(\det(S))(\alpha) \neq 0$. Since $\det(S)$ has, as a non-zero rational function, only finitely many zeros and poles we may assume that $S(\alpha)$ is defined. Using $\det(S(\alpha)) = (\det(S))(\alpha) \neq 0$ we obtain the assertion. Conversely assume that there is some $\alpha \in \mathbb{C}$ such that the complex matrix $S(\alpha)$ is invertible. Then from $0 \neq \det(S(\alpha)) = (\det(S))(\alpha)$ we conclude that $\det(S) \neq 0$, hence S is invertible in $M_n(\mathbb{C}(x))$. ■

In order to handle condition 2.3(c.ii) we now give a different characterization of this property.

Lemma 2.7. Let $\mu_0 \in \mathbb{C}$ such that $Q := \lim_{\alpha \rightarrow \infty} R(\mu_0, M)(\alpha)$ exists. For $\lambda_0 \in \mathbb{C}$ the following assertions are equivalent.

- (a) (i) $(\lambda_0 - M)$ is invertible in $M_n(\mathbb{C}(x))$ and
 (ii) $\lim_{\alpha \rightarrow \infty} R(\lambda_0, M)(\alpha)$ exists.
- (b) $\lambda_0 \notin \{\mu_0 - \lambda^{-1} : \lambda \in \sigma(Q), \lambda \neq 0\}$.

Proof: The lemma holds for $\lambda_0 = \mu_0$, hence assume $\lambda_0 \neq \mu_0$.

(a) \Rightarrow (b): We have to show $(\mu_0 - \lambda_0)^{-1} \notin \sigma(Q)$. Using the resolvent equation one easily verifies that $(\mu_0 - \lambda_0) + (\mu_0 - \lambda_0)^2 R(\lambda_0, M)$ gives the inverse of $(\mu_0 - \lambda_0)^{-1} - R(\mu_0, M)$. Hence assumption (a) implies that

$$\begin{aligned} (\mu_0 - \lambda_0) + (\mu_0 - \lambda_0)^2 \lim_{\alpha \rightarrow \infty} R(\lambda_0, M)(\alpha) &= \lim_{\alpha \rightarrow \infty} ((\mu_0 - \lambda_0)^{-1} - R(\mu_0, M)(\alpha))^{-1} \\ &= R((\mu_0 - \lambda_0)^{-1}, Q) \end{aligned}$$

exists. This shows $(\mu_0 - \lambda_0)^{-1} \notin \sigma(Q)$.

(b) \Rightarrow (a): By hypothesis $((\mu_0 - \lambda_0)^{-1} - Q)$ is invertible, hence $(\mu_0 - \lambda_0)^{-1} - R(\mu_0, M(\alpha))$ is invertible in $M_n(\mathbb{C})$ for α sufficiently large. Now the identity

$$(\mu_0 - \lambda_0)^{-2} ((\mu_0 - \lambda_0) - R(\mu_0, M)(\alpha))^{-1} - (\mu_0 - \lambda_0) = R(\lambda_0, M(\alpha))$$

combined with Lemma 2.6 and the continuity of the inversion implies (a). ■

The above lemma yields a characterization of $\sigma(\mathcal{A})$ in the form of a *spectral mapping theorem*. To be more precise, we show that $\sigma(\mathcal{A})$ consists of a set $\sigma_1(\mathcal{A})$ obtained via a “spectral mapping” from the spectra $\sigma(\mathcal{A})$ and $\sigma(M(\alpha))$ and an “exceptional” set.

Theorem 2.8. *Let $M \in M_n(\mathcal{G})$ and $\mathcal{A} := M(A)$. If for some $\mu_0 \in \mathbb{C}$ the limit $Q := \lim_{\alpha \rightarrow \infty} R(\mu_0, M(\alpha)) \in M_n(\mathbb{C})$ exists (e.g., $\mu_0 \in \rho(\mathcal{A})$), then the spectrum $\sigma(\mathcal{A})$ of \mathcal{A} is given by*

$$\sigma(\mathcal{A}) = \sigma_1(\mathcal{A}) \cup \sigma_2(\mathcal{A}),$$

where

$$\sigma_1(\mathcal{A}) := \bigcup_{\mu \in \sigma(\mathcal{A})} \sigma(M(\mu)) = \sigma(M(\sigma(\mathcal{A})))$$

and

$$\sigma_2(\mathcal{A}) := \{\mu_0 - \lambda^{-1} : \lambda \in \sigma(Q), \lambda \neq 0\}.$$

Proof: The existence of Q for $\mu_0 \in \rho(\mathcal{A})$ was already shown in Corollary 2.5. Lemma 2.7 in combination with Corollary 2.5 shows that $\lambda \in \sigma(\mathcal{A})$ if and only if $\lambda \in \sigma_2(\mathcal{A})$ or $\Delta(\lambda - \mathcal{A})$ is not invertible in $\mathcal{L}(E)$. This last property is equivalent to $0 \in \sigma(p_\lambda(A))$ where $p_\lambda := \det(\lambda - M) \in \mathcal{G}$. By the spectral mapping theorem for elements in \mathcal{G} (see Theorem A.2 (vi)) we obtain

$$\sigma(p_\lambda(A)) = p_\lambda(\sigma(A)) = \{\det(\lambda - M(\mu)) : \mu \in \sigma(A)\}.$$

But $0 \in \bigcup_{\mu \in \sigma(A)} \sigma(\lambda - M(\mu))$ is equivalent to $\lambda \in \bigcup_{\mu \in \sigma(A)} \sigma(M(\mu)) = \sigma_1(\mathcal{A})$. ■

As a first observation we state that the spectrum of \mathcal{A} consists either of the whole complex plane \mathbb{C} or of the set $\sigma_1(\mathcal{A})$ and at most finitely many “exceptional” points in $\sigma_2(\mathcal{A})$. In fact, $|\sigma_2(\mathcal{A})| \leq n - 1$ since Q is never invertible. In the following corollaries we give more precise information on the location of $\sigma_2(\mathcal{A})$.

Corollary 2.9. *If the principal coefficient matrix M_m of the unbounded part of M is invertible, then $\sigma_2(\mathcal{A}) = \emptyset$ and therefore the following spectral mapping formula holds:*

$$\sigma(\mathcal{A}) = \sigma(M(\sigma(A))).$$

Proof: It suffices to show that $\lim_{\alpha \rightarrow \infty} R(0, M)(\alpha) = 0$. Using simple matrix theory it follows from the hypothesis that $[\det M] = n \cdot m$. On the other hand, every element of $\text{Adj}(M)$, the co-factor matrix of M (see [8]), has degree at most $n \cdot (m - 1)$ and we conclude that

$$\lim_{\alpha \rightarrow \infty} R(0, M)(\alpha) = \left((\det M)^{-1} \text{Adj}(M) \right) (\alpha) = 0. \quad \blacksquare$$

Corollary 2.10. *If $\sigma(A)$ is bounded and $\lim_{\alpha \rightarrow \infty} R(\mu_0, M(\alpha))$ exists for some $\mu_0 \in \mathbb{C}$, then $\sigma(A)$ is also bounded. More precisely, $\sigma(A)$ is the union of $\sigma(M(\sigma(A)))$ and finitely many isolated points.*

Proof: This follows from the observation that $\sigma_1(A)$ is compact whenever $\sigma(A)$ is bounded.

Corollary 2.11. *If $\sigma(A)$ is unbounded and $Q := \lim_{\alpha \rightarrow \infty} R(\mu_0, M(\alpha))$ exists for some $\mu_0 \in \mathbb{C}$, then*

$$\sigma(A) = \overline{\sigma_1(A)}.$$

Proof: Let $\lambda_0 \in \sigma_2(A)$, i.e., $(\mu_0 - \lambda_0)^{-1} \in \sigma(Q)$. Since $\sigma(A)$ is unbounded there exists a sequence $(\lambda_k) \subset \sigma(A)$ converging to ∞ . Then $Q_k := R(\mu_0, M)(\lambda_k)$ exists for all except finitely many k and converges to Q . By Theorem 5.1, p.107 [7] we can find a sequence $(\mu_k) \subset \mathbb{C}$ such that $\mu_k \in \sigma(Q_k) = \sigma(\mu_0 - M(\lambda_k))^{-1}$ and $\mu_k \rightarrow (\mu_0 - \lambda_0)^{-1}$. Therefore $(\mu_0 - \mu_k^{-1}) \in \sigma(M(\lambda_k)) \subset \sigma_1(A)$ and $(\mu_0 - \mu_k^{-1})$ converges to λ_0 for $k \rightarrow \infty$. ■

This last corollary is particularly useful since it allows us to determine the spectrum of A by calculating the eigenvalues of the matrices $M(\mu)$, $\mu \in \sigma(A)$, without worrying about the “exceptional” spectral values in $\sigma_2(A)$.

Next we consider some typical examples. For $M \in M_n(\mathbb{C}[x])$ we use as usual the notation $A = M(A)$. Moreover we assume that A is unbounded.

Examples. (1) Let

$$M = \begin{pmatrix} \xi^2 & \xi^3 \\ 1 & \xi \end{pmatrix} \in M_2(\mathbb{C}[x]).$$

Since

$$R(\lambda, M) = \frac{1}{\lambda^2 - \lambda(\xi^2 + \xi)} \begin{pmatrix} \xi & -\xi^3 \\ -1 & \xi^2 \end{pmatrix}$$

for $\lambda \in \mathbb{C} \setminus \{0\}$ there is no $\lambda \in \mathbb{C}$ such that $\lim_{\alpha \rightarrow \infty} R(\lambda, M)(\alpha)$ exists. Using Corollary 2.5 we conclude that $\sigma(A) = \mathbb{C}$.

(2) Let

$$M = \begin{pmatrix} \xi^3 & \xi^2 \\ \xi & -\xi^3 \end{pmatrix} \in M_2(\mathbb{C}[x]).$$

Since the principal coefficient matrix

$$M_3 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

is invertible we obtain from Theorem 2.8 that

$$\sigma(A) = \left\{ \pm \sqrt{\mu^6 + \mu^3} : \mu \in \sigma(A) \right\}.$$

(3) Let $q \in \mathbb{C}[x]$, $q(x) = \sum_{k=0}^n a_k x^k$. For $\epsilon \in \mathbb{C}$ define

$$M_\epsilon := \begin{pmatrix} 0 & 1 \\ q & \epsilon \xi^n \end{pmatrix} \quad \text{and} \quad \mathcal{A}_\epsilon := M_\epsilon(A).$$

Then for $\epsilon \neq 0$ we have

$$\sigma_1(\mathcal{A}_\epsilon) = \left\{ \frac{\epsilon \mu^n \pm \sqrt{\epsilon^2 \mu^{2n} + 4q(\mu)}}{2} : \mu \in \sigma(A) \right\} \quad \text{and} \quad \sigma_2(\mathcal{A}_\epsilon) = \left\{ -\frac{a_n}{\epsilon} \right\}.$$

Note that for unbounded $\sigma(A)$ we have $\frac{-a_n}{\epsilon} \in \overline{\sigma_1(\mathcal{A}_\epsilon)}$. This can be shown by using the binomial series expansion of $\sqrt{1+\lambda}$ for $|\lambda| < 1$. If $\epsilon = 0$, then

$$\sigma(\mathcal{A}_0) = \sigma_1(\mathcal{A}_0) = \left\{ \pm\sqrt{q(\mu)} : \mu \in \sigma(A) \right\}.$$

For applications to stability theory the *spectral bound*

$$s(\mathcal{A}) := \sup\{\operatorname{Re} \lambda : \lambda \in \sigma(\mathcal{A})\}$$

is of special interest (see [10]). Matrix techniques in combination with the above corollary yield an interesting and simple upper estimate for $s(\mathcal{A})$.

Proposition 2.12. *Let $M_0, \dots, M_m \in M_n(\mathbb{C})$ be normal matrices. If $M = \sum_{k=0}^m \xi^k M_k$ and $\mathcal{A} := M(A)$, then*

$$s(\mathcal{A}) \leq \sup_{\mu \in \sigma(A)} \sum_{k=0}^m \sup_{\alpha_k \in \sigma(M_k)} \operatorname{Re}(\mu^k \alpha_k) \leq \sup_{\alpha_k \in \sigma(M_k)} \sum_{k=0}^m s(\alpha_k A^k). \tag{2.1}$$

Proof: For the numerical range $V(S) := \{(Sy, y) : \|y\|_2 = 1\}$ of a matrix $S \in M_n(\mathbb{C})$ it is known that $\sigma(S) \subset V(S)$. But for normal matrices S one has $\operatorname{co}(\sigma(S)) = V(S)$, where “co(.)” denotes the convex hull (see [9]). From these facts we obtain

$$\sigma(M(\mu)) \subset V(M(\mu)) \subset \sum_{k=0}^m \mu^k V(M_k) = \sum_{k=0}^m \mu^k \operatorname{co}(\sigma(M_k)).$$

This implies that

$$\begin{aligned} \sup_{\mu \in \sigma(A)} \operatorname{Re}(\sigma(M(\mu))) &\leq \sup_{\mu \in \sigma(A)} \sum_{k=0}^m \sup \operatorname{Re}(\mu^k \operatorname{co}(\sigma(M_k))) \\ &= \sup_{\mu \in \sigma(A)} \sum_{k=0}^m \sup \operatorname{Re}(\mu^k (\sigma(M_k))) \\ &= \sup_{\mu \in \sigma(A)} \sum_{k=0}^m \sup_{\alpha_k \in \sigma(M_k)} \operatorname{Re}(\mu^k \alpha_k) \\ &\leq \sum_{k=0}^m \sup_{\alpha_k \in \sigma(M_k)} s(\alpha_k A^k). \end{aligned}$$

We have used here the abbreviations $K+L = \{z+w : z \in K, w \in L\}$ and $\operatorname{Re}(K) = \{\operatorname{Re}(z) : z \in K\}$ for any two subsets K, L of \mathbb{C} . ■

Appendix: The functional calculus. In the following we will provide some results concerning the functional calculus. Let A be a densely defined operator on some Banach space E with non-empty resolvent set $\rho(A)$. We recall the definitions from part 1:

$$\begin{aligned} \mathcal{G} &= \mathcal{G}(A) := \{f \in \mathbb{C}(x) : f \text{ is holomorphic in a neighborhood of } \sigma(A)\}, \\ \mathcal{N} &= \mathcal{N}(A) := \{f \in \mathcal{G}(A) : [f] \leq 0\} \quad \text{and} \\ \mathbb{C}_0[x] &:= \{f \in \mathbb{C}[x] : f(0) = 0\}. \end{aligned}$$

Since $\mathcal{G} = \mathbb{C}_0[x] \oplus \mathcal{N}$ it is possible to decompose every $f \in \mathcal{G}$ into a unique sum $f = p + q$ where $p \in \mathbb{C}_0[x]$ and $q \in \mathcal{N}$. For polynomials there is a well known functional calculus Φ_1 specified by

$$\Phi_1 : p \mapsto \Phi_1(p) = p(A), \quad p \in \mathbb{C}[x],$$

where, by definition, $D(p(A)) := D(A^m)$, with $m = [p]$. Similarly, there is a functional calculus Φ_2 for functions in \mathcal{N} where $\Phi_2 : \mathcal{N} \rightarrow \mathcal{L}(E)$ is the homomorphism given by

$$\Phi_2 : q \mapsto \Phi_2(q) = q(A) = r(A)s^{-1}(A), \quad q = \frac{r}{s} \in \mathcal{N}.$$

For details we refer to [4].

Next we combine these two maps in order to obtain a functional calculus Φ on \mathcal{G} .

Definition A.1. *Let $f = p + q \in \mathcal{G}$ where $p \in \mathbb{C}_0[x]$ and $q \in \mathcal{N}$. Then we define*

$$\Phi(f) := \Phi_1(p) + \Phi_2(q) = f(A)$$

with domain $D(f(A)) = D(A^m)$ where $m = \max\{[f], 0\}$.

Theorem A.2. *The map*

$$\Phi : f \mapsto \Phi(f) = f(A), \quad f \in \mathcal{G}$$

is an “algebra homomorphism” in the the following sense.

- (i) $\Phi(f + g) = \overline{\Phi(f) + \Phi(g)}$ for all $f, g \in \mathcal{G}$, in particular,
 $\Phi(f + g) = \Phi(f) + \Phi(g)$ if $g \in \mathcal{N}$,
- (ii) $\Phi(fg) = \Phi(f)\Phi(g) = \overline{\Phi(g)\Phi(f)}$ for all $f, g \in \mathcal{G}$ if $[g] \leq [f]$.

Moreover, if A is unbounded, then

- (iii) $\Phi(f) \in \mathcal{L}(E) \iff f \in \mathcal{N}$,
- (iv) $\Phi(f) = 0 \iff f = 0$,
- (v) $\Phi(f)$ is invertible in $\mathcal{L}(E) \iff \frac{1}{f} \in \mathcal{N}$,
in particular, $\Phi(f)^{-1} \in \Phi(\mathcal{N})$,
- (vi) $\sigma(\Phi(f)) = f(\sigma(A)) \cup \sigma_f$ where

$$\sigma_f = \begin{cases} \emptyset & \text{if } [f] > 0 \\ \{f(\infty)\} & \text{if } [f] \leq 0 \end{cases}.$$

The routine proof can be found in [5]. For the proof of Lemma 1.3 the following result is needed.

Proposition A.3. *Let $b, c \in \mathbb{C}[x]$ and $[b] \geq [c]$. Then there exists $f \in \mathcal{N}$ such that $bf + c \in \mathcal{N}$.*

Proof: To simplify the notation we assume that $0 \in \rho(A)$, i.e., that $j \in \mathcal{N}$ where $j(x) := 1/x$. If $b = 0$, then $c = 0$ and we may choose $f = 0$. Therefore assume $b \neq 0$.

Define $\tilde{f} := -\frac{c}{b} \in \mathbb{C}(x)$. Since $[b] \geq [c]$ we have $[\tilde{f}] \leq 0$. For $C > 0$ big enough \tilde{f} has no poles in $\{x \in \mathbb{C} : |x| \geq C\}$ and we can expand \tilde{f} into a Laurent series $\tilde{f}(x) = \sum_{k=0}^{\infty} \alpha_k x^{-k}$

for $|x| \geq C$. Let f be the expansion of \tilde{f} up to order $m := [b] - 1$, i.e., $f := \sum_{k=0}^m \alpha_k j^k$ and $d := \tilde{f} - f$. Then $f \in \mathcal{N}$ and $[d] \leq -(m+1) = -[b]$. Moreover we have

$$bf + c = b(\tilde{f} - d) + c = b\tilde{f} + c - bd = -bd.$$

Since $[bd] \leq 0$ and $bf + c \in \mathcal{G}$ we conclude that $bf + c \in \mathcal{N}$. ■

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