

AMBROSETTI-PRODI-TYPE PROBLEMS FOR QUASILINEAR ELLIPTIC PROBLEMS

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Abstract. We consider nonlinear perturbations of the p -Laplacian depending on a real parameter and subject to zero Dirichlet boundary data; we establish results which guarantee the existence of at least one and at least two solutions for certain parameter ranges.

1. INTRODUCTION

In this paper we consider the Dirichlet boundary-value problem

$$\begin{cases} \Delta_p u + f(u) = |t|^{p-2} t \hat{h} + h & \text{in } \Omega \\ u = 0 & \text{on } \partial\Omega, \end{cases} \quad (1.1)$$

where Ω is a bounded, open set with the smooth boundary in \mathbb{R}^N , $p > 1$, and Δ_p is the p -Laplace operator defined by $\Delta_p u = \operatorname{div}(|\nabla u|^{p-2} \nabla u)$; f is a continuously differentiable function which satisfies the growth conditions

$$\lim_{s \rightarrow -\infty} \frac{f(s)}{|s|^{p-2} s} = \alpha, \quad \text{and} \quad \lim_{s \rightarrow \infty} \frac{f(s)}{s^{p-1}} = \beta;$$

and \hat{h} and h are assumed to be in the space $C(\overline{\Omega})$, $\hat{h} \geq 0$ in $\overline{\Omega}$, $\alpha < \lambda_1$, and $\beta > \lambda_1$, where λ_1 is the smallest eigenvalue of

$$\begin{cases} \Delta_p u + \lambda |u|^{p-2} u = 0 & \text{in } \Omega \\ u = 0 & \text{on } \partial\Omega. \end{cases} \quad (1.2)$$

We first demonstrate the existence of a number $t_h \gg 1$ such that if $t \geq t_h$, (1.1) has a negative solution. If we restrict \hat{h} to be strictly positive in $\overline{\Omega}$ we shall prove that there exists t_l such that (1.1) has no solution if $t \leq t_l$ by using sub-supersolution theorems. We then show that if $\hat{h} > 0$ in $\overline{\Omega}$, then there exist t_1 and t_2 , $t_1 \leq t_2$, such that if $t_1 \leq t \leq t_2$, (1.1) has at least one solution, at least two solutions if $t > t_2$, and no solutions if $t < t_1$. We further show that multiple solutions are possible in the case $\hat{h} \geq 0$ in $\overline{\Omega}$ for a sufficiently large t by using a limiting argument.

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The result obtained in this paper, in some sense, extends the result established by Ambrosetti and Prodi [1]. They consider the case $p = 2$, i.e.,

$$\begin{cases} \Delta u + f(u) = g & \text{in } \Omega \subset \mathbb{R}^N, \\ u = 0 & \text{on } \partial\Omega, \end{cases} \quad (1.3)$$

where $g \in C^{0,\alpha}(\overline{\Omega})$, and their main theorem shows that there exists in the space $C^{0,\alpha}(\overline{\Omega})$, a closed, connected C^1 manifold M of codimension 1 such that $C^{0,\alpha}(\overline{\Omega}) \setminus M$ consists of exactly two connected components, A_1 and A_2 , such that the following hold: (i) if $g \in A_1$, (1.3) has no solution; (ii) if $g \in A_2$, (1.3) has exactly 2 solutions; and (iii) if $g \in M$, (1.3) has a unique solution. This result, when $g = t\phi + h$, where ϕ is a positive principal eigenfunction of Δ subject to zero Dirichlet boundary data, and $\int_{\Omega} \phi h = 0$, gives the manifold M as

$$M = \{g : g = t(h)\phi + h\},$$

where the map $h \mapsto t(h)$ is a C^1 mapping.

For related results and methods we refer to [4] and [16] and their references.

2. PRELIMINARY RESULTS

2.1. The p -Laplace operator and its inverse. It has been shown in [13] that for any $g \in L^q(\Omega)$, $q = \frac{p}{p-1}$, the problem

$$\begin{cases} -\Delta_p u = g(x) & \text{in } \Omega \\ u = 0 & \text{on } \partial\Omega \end{cases}$$

has a unique solution $u \in W_0^{1,p}(\Omega)$. We define $u =: R_p(g)$. Furthermore, using regularity results of [5, 11, 18] it follows that if $g \in L^\infty(\Omega)$, then $u = R_p(g) \in C_0^{1,\alpha}(\overline{\Omega})$ for some $0 < \alpha < 1$. Hence the map $R_p : C(\overline{\Omega}) \rightarrow C_0^{1,\alpha}(\overline{\Omega})$ is well-defined. It follows that

Proposition 2.1. *The map $R_p : C(\overline{\Omega}) \rightarrow C_0^1(\overline{\Omega})$ is completely continuous.*

2.2. The eigenvalue problem and Poincaré's inequality. The eigenvalue problem

$$\begin{cases} \Delta_p u + \lambda|u|^{p-2}u = 0 & \text{in } \Omega \\ u = 0 & \text{on } \partial\Omega \end{cases} \quad (2.1)$$

is known to have a principal eigenvalue, $0 < \lambda_1$, which is isolated, and there are no smaller numbers $\lambda_0 < \lambda_1$ for which (2.1) has a nontrivial solution. An eigenfunction associated with this smallest eigenvalue λ_1 , w_1 , is known to be in $C_0^{1,\alpha}(\overline{\Omega})$ for some $\alpha \in (0, 1)$, $\frac{\partial w_1}{\partial \nu} \neq 0$ (throughout $\frac{\partial}{\partial \nu}$ denotes the inward-normal derivative along the boundary of Ω), and w_1 is one-signed and

does not vanish in Ω . Also, all other eigenfunctions associated with λ_1 are constant multiples of w_1 ; i.e., one may say that λ_1 is a simple eigenvalue. It is also known that if w is an eigenfunction associated with another eigenvalue different from λ_1 , then w has to change sign as follows from the following proposition proved in [12].

Proposition 2.2. *Let $\lambda_1 \leq \lambda'$, where λ' is an eigenvalue of (1.2), and $w > 0$ be an eigenfunction associated with λ' ; then $\lambda' = \lambda_1$.*

(For these results see [2, 12].) Hence, from here on, we take $w_1(x) > 0$ in Ω and $\frac{\partial w_1}{\partial \nu} > 0$ on $\partial\Omega$. The principal eigenvalue λ_1 may be defined by the formula

$$\lambda_1 = \inf_{\substack{u \in W_0^{1,p}(\Omega) \\ \int_{\Omega} |u|^p = 1}} \int_{\Omega} |\nabla u|^p.$$

From this characterization immediately follows Poincaré’s inequality in $W_0^{1,p}(\Omega)$ (see, e.g., [6]),

$$\lambda_1 \int_{\Omega} |u|^p \leq \int_{\Omega} |\nabla u|^p,$$

for all $u \in W_0^{1,p}(\Omega)$.

2.3. Sub- and supersolutions. Under suitable assumptions on f , for $u_0 \in W^{1,p}(\Omega)$, the existence of a solution to a general problem

$$\begin{cases} -\Delta_p u = f(x, u) & \text{in } \Omega \\ u = u_0 & \text{on } \partial\Omega \end{cases} \tag{2.2}$$

may be proven using sub-supersolution techniques (see e.g. [3, 8, 9, 10]).

Definition 2.3. *A weak sub- (super-) solution of (2.2) is a function $u \in W^{1,p}(\Omega)$ such that $u \leq (\geq) u_0$ on $\partial\Omega$ in the sense of traces and*

$$\int_{\Omega} |\nabla u|^{p-2} \nabla u \nabla \phi \leq (\geq) \int_{\Omega} f(x, u) \phi,$$

for all $\phi \in W_0^{1,p}(\Omega)$ and $\phi \geq 0$ almost everywhere in Ω .

Theorem 2.4 (Sub-Supersolution Theorem). *Assume that for the boundary-value problem (2.2) there exist \underline{u} and \bar{u} , sub- and supersolutions, respectively, such that*

$$-\infty < C_1 \leq \underline{u} \leq \bar{u} \leq C_2 < \infty, \text{ a.e. } \Omega,$$

where C_1 and C_2 are constants, and assume that f is a Carathéodory function which also satisfies

$$|f(x, u)| \leq C_3 \text{ a.e. for } (x, u) \in \Omega \times [C_1, C_2].$$

Then the boundary-value problem (2.2) has a weak solution $u \in W^{1,p}(\Omega)$ with $\underline{u} \leq u \leq \bar{u}$ almost everywhere in Ω ; i.e., $u = u_0$ on $\partial\Omega$ in the sense of traces and

$$\int_{\Omega} |\nabla u|^{p-2} \nabla u \nabla \phi = \int_{\Omega} f(x, u) \phi$$

for all $\phi \in W_0^{1,p}(\Omega)$.

2.4. Uniqueness. Henceforth, let us denote by

$$u^+ := \max\{u, 0\}, \quad u^- := -\min\{u, 0\}.$$

We have the following uniqueness result:

Proposition 2.5. *Suppose $\alpha < \lambda_1 < \beta$. Then, the problem*

$$\begin{cases} -\Delta_p u = \beta|u|^{p-2}u^+ - \alpha|u|^{p-2}u^- & \text{in } \Omega \\ u = 0 & \text{on } \partial\Omega \end{cases} \quad (2.3)$$

has only the trivial weak solution.

Proof. Suppose $u \in W_0^{1,p}(\Omega)$ is a nontrivial weak solution of the problem and $u^- \not\equiv 0$. Then since u satisfies

$$\int_{\Omega} |\nabla u|^{p-2} \nabla u \nabla \phi = \int_{\Omega} \beta|u|^{p-2}u^+ \phi - \int_{\Omega} \alpha|u|^{p-2}u^- \phi,$$

for all $\phi \in W_0^{1,p}(\Omega)$, and $u^- \in W_0^{1,p}(\Omega)$ ([7]), by letting $\phi = u^-$, we have

$$\int_{\Omega} |\nabla u|^{p-2} \nabla u \nabla (u^-) = - \int_{\Omega} \alpha|u|^{p-2}u^- u^-,$$

or

$$\int_{\Omega} |\nabla u^-|^p = \int_{\Omega} \alpha|u^-|^p. \quad (2.4)$$

On the other hand, by Poincaré's inequality, and since $\alpha < \lambda_1$,

$$\int_{\Omega} |\nabla u^-|^p \geq \lambda_1 \int_{\Omega} |u^-|^p > \alpha \int_{\Omega} |u^-|^p,$$

contradicting (2.4). Hence $u^- \equiv 0$ almost everywhere in Ω . Thus, u is a solution of

$$\begin{cases} -\Delta_p u = \beta|u|^{p-2}u & \text{in } \Omega \\ u = 0 & \text{on } \partial\Omega, \end{cases}$$

and $u \geq 0$ in Ω . Therefore, u satisfies the inequalities

$$\begin{cases} \Delta_p u \leq 0 \\ u \geq 0 \end{cases}$$

in Ω weakly. Then, by the strong maximum principle (see [15]), if there exists $x_0 \in \Omega$ such that $u(x_0) = 0$, it will follow that $u \equiv 0$ in Ω , but we

assumed that u is a nontrivial weak solution. Thus $u > 0$ in Ω . Hence, by Proposition 2.2, $\beta = \lambda_1$, which is a contradiction to $\lambda_1 < \beta$. Therefore (2.3) has only the trivial solution. \square

3. EXISTENCE OF SOLUTIONS FOR LARGE t

In this section we establish, for large $t \in \mathbb{R}$, the existence of a solution to the following Dirichlet boundary-value problem:

$$\begin{cases} \Delta_p u + f(u) = |t|^{p-2} t \hat{h} + h & \text{in } \Omega \\ u = 0 & \text{on } \partial\Omega, \end{cases} \tag{3.1}$$

where $f \in C^1(\mathbb{R})$ satisfies

$$\lim_{s \rightarrow -\infty} \frac{f(s)}{|s|^{p-2} s} = \alpha < \lambda_1 \tag{3.2}$$

and

$$\lim_{s \rightarrow +\infty} \frac{f(s)}{s^{p-1}} = \beta > \lambda_1. \tag{3.3}$$

We assume $\Omega \subset \mathbb{R}^N$, $N \geq 1$ is bounded with a sufficiently smooth boundary, $\hat{h}, h \in C(\bar{\Omega})$, and $\hat{h} \geq 0$ in $\bar{\Omega}$. The following is the main theorem in this section; it will be proved using several auxiliary results.

Theorem 3.1. *Suppose f satisfies conditions (3.2)–(3.3) given above, $\hat{h}, h \in C(\bar{\Omega})$, $\hat{h} \geq 0$, and $\hat{h} \not\equiv 0$ in $\bar{\Omega}$. Then there exists $t_h \gg 1$ such that for each $t \geq t_h$, the problem (3.1) has a solution.*

3.1. Some lemmas and the proof of the theorem. By the conditions (3.2) and (3.3), we can write f as

$$f(u) = \beta|u|^{p-2}u^+ - \alpha|u|^{p-2}u^- + g(u), \tag{3.4}$$

where g is a continuous function which is smooth, except possibly at the origin, and $\lim_{s \rightarrow \pm\infty} g(s)/(|s|^{p-2}s) = 0$. Fixing $t > 0$, we replace f in (3.1) by (3.4), and let $v = \frac{u}{t}$. We thus obtain the equivalent problem

$$\begin{cases} \Delta_p v + \beta|v|^{p-2}v^+ - \alpha|v|^{p-2}v^- + \frac{g(tv)}{t^{p-1}} = \hat{h} + \frac{h}{t^{p-1}} & \text{in } \Omega \\ v = 0 & \text{on } \partial\Omega. \end{cases} \tag{3.5}$$

Thus a weak solution u to problem (3.1) (for $t > 0$) is given by tv , for $t > 0$, where v is a weak solution to (3.5).

Consider the problem

$$\begin{cases} \Delta_p v + \beta|v|^{p-2}v^+ - \alpha|v|^{p-2}v^- = \hat{h} & \text{in } \Omega \\ v = 0 & \text{on } \partial\Omega. \end{cases} \tag{3.6}$$

Since $\bar{v} = 0$ satisfies

$$\int_{\Omega} |\nabla \bar{v}|^{p-2} \nabla \bar{v} \nabla \phi \geq \int_{\Omega} (\beta |\bar{v}|^{p-2} \bar{v}^+ - \alpha |\bar{v}|^{p-2} \bar{v}^- - \hat{h}) \phi$$

for all $\phi \in W_0^{1,p}(\Omega)$ such that $\phi \geq 0$ almost everywhere in Ω , we see that $\bar{v} = 0$ is a weak supersolution for the problem (3.6).

Lemma 3.2. *The problem (3.6) has a negative weak subsolution, $\underline{v} \in C_0^1(\bar{\Omega})$ with $\frac{\partial \underline{v}}{\partial \nu} < 0$ on $\partial\Omega$.*

Proof. Consider the functional $J : W_0^{1,p}(\Omega) \rightarrow \mathbb{R}$ defined by

$$J(u) := \int_{\Omega} \left(\frac{|\nabla u|^p}{p} - \alpha \frac{|u|^p}{p} - 2\hat{h}u \right). \quad (3.7)$$

This functional is bounded below, coercive (because $\alpha < \lambda_1$), and weakly lower semicontinuous, and hence will assume its minimum (see, e.g., [17]). Since the Euler-Lagrange equation associated with the energy functional J is

$$\begin{cases} -\Delta_p u = \alpha |u|^{p-2} u + 2\hat{h} & \text{in } \Omega \\ u = 0 & \text{on } \partial\Omega, \end{cases} \quad (3.8)$$

if u is a minimizer of (3.7) in $W_0^{1,p}(\Omega)$, it is a solution to (3.8).

Suppose u is a weak solution to (3.8). Then

$$\int_{\Omega} |\nabla u|^{p-2} \nabla u \nabla \phi = \int_{\Omega} \alpha |u|^{p-2} u \phi + \int_{\Omega} 2\hat{h} \phi$$

for all $\phi \in W_0^{1,p}(\Omega)$. Suppose $u^- \not\equiv 0$. Then, by taking $\phi = u^-$,

$$\int_{\Omega} |\nabla u|^{p-2} \nabla u \nabla u^- = \int_{\Omega} \alpha |u|^{p-2} u u^- + \int_{\Omega} 2\hat{h} u^-,$$

and

$$- \int_{\Omega} |\nabla u^-|^p + \int_{\Omega} \alpha |u^-|^p = \int_{\Omega} 2\hat{h} u^-. \quad (3.9)$$

Since $\alpha < \lambda_1$, by Poincaré's inequality, the left-hand side of (3.9) is negative while the right-hand side is nonnegative. Therefore $u^- \equiv 0$ in Ω . Hence, if u is a weak solution to (3.8), then $u \geq 0$ in Ω , and u satisfies

$$\int_{\Omega} |\nabla u|^{p-2} \nabla u \nabla \phi = \int_{\Omega} (\alpha |u|^{p-2} u + 2\hat{h}) \phi \geq 0$$

for all $\phi \in W_0^{1,p}(\Omega)$ such that $\phi \geq 0$ almost everywhere in Ω . Therefore, since $u \in C_0^1(\bar{\Omega})$ and since $\Delta_p u = -\alpha |u|^{p-2} u - 2\hat{h} \leq 0$ weakly, and $u \geq 0$ in $\bar{\Omega}$, it follows from maximum principles (see again [15]) that $u > 0$ in Ω , and $\frac{\partial u}{\partial \nu} > 0$ on $\partial\Omega$ since $\hat{h} \not\equiv 0$ implies $u \not\equiv 0$.

We now let $\underline{v} = -u$. Then \underline{v} is a negative weak solution for

$$\Delta_p \underline{v} = -\alpha |\underline{v}|^{p-2} \underline{v} + 2\hat{h}.$$

Hence, since $\underline{v} < 0$ in Ω , it solves

$$\Delta_p \underline{v} + \beta |\underline{v}|^{p-2} \underline{v}^+ - \alpha |\underline{v}|^{p-2} \underline{v}^- = 2\hat{h}$$

in a distributional sense. Thus we have

$$-\int_{\Omega} |\nabla \underline{v}|^{p-2} \nabla \underline{v} \nabla \phi + \int_{\Omega} (\beta |\underline{v}|^{p-2} \underline{v}^+ - \alpha |\underline{v}|^{p-2} \underline{v}^-) \phi = \int_{\Omega} 2\hat{h} \phi \geq \int_{\Omega} \hat{h} \phi,$$

for all $\phi \in W_0^{1,p}(\Omega)$ such that $\phi \geq 0$ almost everywhere in Ω . Therefore \underline{v} is a negative strict weak subsolution of (3.6). A similar existence result can be found in Huang [8]. In addition to the existence of a positive solution to (3.8), he also proves the uniqueness of the solution in [8]. \square

From here on, we choose \underline{v} to be the negative weak subsolution found above.

Define the map $\Psi : C_0^1(\overline{\Omega}) \rightarrow C(\overline{\Omega})$ by

$$\Psi(v) := \beta |v|^{p-2} v^+ - \alpha |v|^{p-2} v^- - \hat{h},$$

and $\tilde{\Psi} : C_0^1(\overline{\Omega}) \rightarrow C(\overline{\Omega})$ by

$$\tilde{\Psi}(v) := \begin{cases} \Psi(0) & \text{if } v \geq 0 \\ \Psi(v) & \text{if } \underline{v} < v < 0 \\ \Psi(\underline{v}) & \text{if } v \leq \underline{v}, \end{cases}$$

and the subset D of $C_0^1(\overline{\Omega})$ by

$$D := \left\{ u \in C_0^1(\overline{\Omega}) : \underline{v} < u < 0 \text{ in } \Omega, \frac{\partial v}{\partial \nu} < \frac{\partial u}{\partial \nu} < 0 \text{ on } \partial\Omega, \|u\|_{C_0^1(\overline{\Omega})} < M \right\},$$

where $M > C$, and C is defined by the following straightforward lemma.

Lemma 3.3. *Solutions for (3.6) such that*

$$\underline{v} \leq u \leq 0 \text{ in } \Omega$$

are uniformly bounded in $C_0^1(\overline{\Omega})$.

It is also straightforward to verify that $\Psi : C_0^1(\overline{\Omega}) \rightarrow C(\overline{\Omega})$ maps bounded sets into bounded sets, and $\tilde{\Psi} : C_0^1(\overline{\Omega}) \rightarrow C(\overline{\Omega})$ maps any set into a bounded set, and both are continuous. Furthermore, the map $R : C_0^1(\overline{\Omega}) \rightarrow C_0^1(\overline{\Omega})$ defined as $R(u) = R_p(\Psi(u))$ is completely continuous, as is the mapping $\tilde{R} : C_0^1(\overline{\Omega}) \rightarrow C_0^1(\overline{\Omega})$ defined as $\tilde{R}(u) := R_p(\tilde{\Psi}(u))$. The next lemma may be proved using variational principles and also follows from a result in [8].

Lemma 3.4. *Suppose $\hat{h} \neq 0$ in $\bar{\Omega}$. If $v \in C_0^1(\bar{\Omega})$ is a weak solution to (3.6) such that $\underline{v} \leq v \leq 0$ in Ω and $\frac{\partial v}{\partial \nu} \leq \frac{\partial \underline{v}}{\partial \nu} \leq 0$ on $\partial\Omega$, then $\underline{v} < v < 0$ in Ω and $\frac{\partial v}{\partial \nu} < \frac{\partial \underline{v}}{\partial \nu} < 0$ on $\partial\Omega$.*

Lemma 3.5. *Solving the problem (3.6) on the set D is equivalent to solving*

$$\begin{cases} -\Delta_p v &= \tilde{\Psi}(v) & \text{in } \Omega \\ v &= 0 & \text{on } \partial\Omega. \end{cases} \quad (3.10)$$

Proof. If v solves (3.6) on D , then $\underline{v} < v < 0$ in Ω ; hence, it solves (3.10).

Suppose v solves (3.10), and the Lebesgue measure of

$$\Omega' := \{x \in \Omega : v(x) \geq 0\}$$

is positive. Since v satisfies

$$\int_{\Omega} |\nabla v|^{p-2} \nabla v \nabla \phi = \int_{\Omega} \tilde{\Psi}(v) \phi, \quad (3.11)$$

and

$$\int_{\Omega} \Psi(0) \phi \leq 0 \quad (3.12)$$

for all $\phi \in W_0^{1,p}(\Omega)$, $\phi \geq 0$ almost everywhere in Ω , by adding (3.11) and (3.12), and reorganizing the terms in the resulting inequality, we get

$$\int_{\Omega} |\nabla v|^{p-2} \nabla v \nabla \phi \leq \int_{\Omega} (\tilde{\Psi}(v) - \Psi(0)) \phi, \quad (3.13)$$

for all $\phi \in W_0^{1,p}(\Omega)$, $\phi \geq 0$ almost everywhere in Ω . If we let $\phi = v^+$ in (3.13), then

$$\int_{\Omega} |\nabla v|^{p-2} \nabla v \nabla v^+ = \int_{\Omega'} |\nabla v|^p \geq 0$$

and

$$\int_{\Omega} (\tilde{\Psi}(v) - \Psi(0)) v^+ = \int_{\Omega'} (\tilde{\Psi}(v) - \Psi(0)) v^+ = 0.$$

Thus

$$\int_{\Omega'} |\nabla v|^p = 0;$$

hence, $v \leq 0$ in Ω .

To show that $v \geq \underline{v}$ in Ω , suppose v is a solution to (3.10), and the Lebesgue measure of $\Omega'' := \{x \in \Omega : v \leq \underline{v}\}$ is positive. Then v and \underline{v} , respectively, satisfy

$$\int_{\Omega} |\nabla v|^{p-2} \nabla v \nabla \phi = \int_{\Omega} \tilde{\Psi}(v) \phi, \quad (3.14)$$

$$\int_{\Omega} |\nabla \underline{v}|^{p-2} \nabla \underline{v} \nabla \phi \leq \int_{\Omega} \Psi(\underline{v}) \phi, \tag{3.15}$$

for all $\phi \in W_0^{1,p}(\Omega)$, $\phi \geq 0$ almost everywhere in Ω . By subtracting (3.14) from (3.15), we have

$$\int_{\Omega} (|\nabla \underline{v}|^{p-2} \nabla \underline{v} - |\nabla v|^{p-2} \nabla v) \nabla \phi \leq \int_{\Omega} (\Psi(\underline{v}) - \tilde{\Psi}(v)) \phi,$$

for all $\phi \in W_0^{1,p}(\Omega)$, $\phi \geq 0$ almost everywhere in Ω . By letting $\phi = (\underline{v} - v)^+$, we have

$$\int_{\Omega} (|\nabla \underline{v}|^{p-2} \nabla \underline{v} - |\nabla v|^{p-2} \nabla v) \nabla (\underline{v} - v)^+ \leq \int_{\Omega} (\Psi(\underline{v}) - \tilde{\Psi}(v)) (\underline{v} - v)^+.$$

Thus,

$$\begin{aligned} & \int_{\Omega} (|\nabla \underline{v}|^{p-2} \nabla \underline{v} - |\nabla v|^{p-2} \nabla v) \nabla (\underline{v} - v)^+ \\ &= \int_{\Omega''} (|\nabla \underline{v}|^{p-2} \nabla \underline{v} - |\nabla v|^{p-2} \nabla v) (\nabla \underline{v} - \nabla v) \geq 0. \end{aligned}$$

Also

$$\int_{\Omega} (\Psi(\underline{v}) - \tilde{\Psi}(v)) (\underline{v} - v)^+ = \int_{\Omega''} (\Psi(\underline{v}) - \Psi(v)) (\underline{v} - v)^+ = 0.$$

Therefore, we have

$$\int_{\Omega''} (|\nabla \underline{v}|^{p-2} \nabla \underline{v} - |\nabla v|^{p-2} \nabla v) (\nabla \underline{v} - \nabla v) = 0.$$

It therefore follows, after some computation, that

$$\int_{\Omega''} |\nabla \underline{v}|^p = \int_{\Omega''} |\nabla v|^p,$$

and further that

$$\int_{\Omega''} |\nabla \underline{v}|^{p-2} \nabla \underline{v} \cdot \nabla v - |\nabla \underline{v}|^{p-1} |\nabla v| = 0;$$

i.e.,

$$\nabla \underline{v} \cdot \nabla v = |\nabla \underline{v}| |\nabla v| \text{ a.e. in } \Omega''.$$

One quickly concludes that Ω'' has measure zero, and therefore $v \geq \underline{v}$ in Ω . Some of the arguments and computations used in this step can be found in [10]. □

The next lemma is easy to verify.

Lemma 3.6. *The set D is open in $C_0^1(\bar{\Omega})$.*

Lemma 3.7. *There does not exist $u \in \partial D$ such that $u = R(u)$ or $u = \tilde{R}(u)$.*

Proof. Suppose $u \in \bar{D}$ such that $u = R(u)$. Then $\underline{v} \leq u \leq 0$ in Ω , $\frac{\partial v}{\partial \nu} \leq \frac{\partial u}{\partial \nu} \leq 0$ on $\partial\Omega$, and $\|u\|_{C_0^1(\bar{\Omega})} \leq M$. If $\underline{v} \leq u \leq 0$ in Ω , by Lemma 3.3, $\|u\|_{C_0^1(\bar{\Omega})} < M$. Also, by Lemma 3.4, if u satisfies $\underline{v} \leq u \leq 0$ in Ω and $\frac{\partial v}{\partial \nu} \leq \frac{\partial u}{\partial \nu} \leq 0$ on $\partial\Omega$, then $\underline{v} < u < 0$ in Ω and $\frac{\partial v}{\partial \nu} < \frac{\partial u}{\partial \nu} < 0$ on $\partial\Omega$. By Lemma 3.5, if $u = \tilde{R}(u)$, then $u = R(u)$ on \bar{D} ; hence, $u \notin \partial D$. \square

Lemma 3.8. *The Leray-Schauder degree*

$$\deg(id - R(\cdot), D, 0) \quad (3.16)$$

is defined in $C_0^1(\bar{\Omega})$ where id is the identity map in $C_0^1(\bar{\Omega})$.

Proof. The mapping $id - R(\cdot)$ is a completely continuous perturbation of the identity. By Lemma 3.6, D is open in $C_0^1(\bar{\Omega})$. Lemma 3.7 shows that there are no solutions of $u - R(u) = 0$ on the boundary of D . Therefore, the degree in (3.16) is defined. \square

Lemma 3.9. *The Leray-Schauder degree*

$$\deg(id - \tilde{R}(\cdot), D, 0) \quad (3.17)$$

is defined in $C_0^1(\bar{\Omega})$.

Proof. The degree in (3.17) is defined, since $R \equiv \tilde{R}$ on D . \square

Lemma 3.10. *The Leray-Schauder degree given by (3.17) is 1.*

Proof. Let U be any bounded, open set such that $\bar{D} \subset U$. If $u = \tilde{R}(u)$, then $u \in D$; hence, $u \notin \bar{U} \setminus D$. Thus the Leray-Schauder degree

$$\deg(id - \tilde{R}(\cdot), U, 0)$$

is defined in $C_0^1(\bar{\Omega})$. By the excision property of the Leray-Schauder degree, it follows that (see [14])

$$\deg(id - \tilde{R}(\cdot), U, 0) = \deg(id - \tilde{R}(\cdot), D, 0).$$

For example, since $\bar{D} \subset B_M(0)$, the ball of radius M centered at 0, we observe that all solutions of the problem (3.10) are contained in D by Lemma 3.7; hence, there are no solutions on the boundary of $B_{M'}(0)$ for all $M' \geq M$. Thus, $\deg(id - \tilde{R}(\cdot), B_{M'}(0), 0)$ is defined in $C_0^1(\bar{\Omega})$, and constant for all M' sufficiently large.

The mapping defined by $(\xi, u) \mapsto \xi \tilde{R}(u)$ is completely continuous from $[0, 1] \times C_0^1(\bar{\Omega}) \rightarrow C_0^1(\bar{\Omega})$ and is zero free on $\partial B_{M'}(0)$. We hence obtain (using the homotopy property of the degree (see again [14])) the result. \square

Lemma 3.11.

$$\deg(id - R(\cdot), D, 0) = 1.$$

Proof. By Lemmas 3.5, 3.8, and 3.9,

$$\deg(id - R(\cdot), D, 0) = \deg(id - \tilde{R}(\cdot), D, 0).$$

By Lemma 3.10,

$$\deg(id - R(\cdot), D, 0) = \deg(id - \tilde{R}(\cdot), B_{M'}(0), 0) = \deg(id, B_{M'}(0), 0).$$

Hence, the conclusion follows. \square

Next, one may easily show, using the continuous perturbation property of the Leray-Schauder degree ([14]) that there exists $t_h \gg 1$ such that if $t \geq t_h$,

$$\deg(id - R(\cdot), D, 0) = \deg(id - R'(\cdot), D, 0), \tag{3.18}$$

where $R'(u) := R_p \left(\beta|u|^{p-2}u^+ - \alpha|u|^{p-2}u^- + g(tu)/t^{p-1} - \hat{h} - h/t^{p-1} \right)$.

Lemma 3.12. *There exists $t_h \gg 1$ such that for $t \geq t_h$, (3.18) holds.*

The above auxiliary results now allow us to prove Theorem 3.1.

Proof. By Lemma 3.11 and Lemma 3.12, there exists t_h such that for all $t \geq t_h$, we have

$$\deg(id - R'(\cdot), D, 0) = 1.$$

Hence, there exists a solution $v \in D$ of (3.6) for each $t \geq t_h$. Therefore, (3.5) has a solution $u = tv$ for each $t \geq t_h$. \square

4. SOLUTION BOUNDS

In this section we first show that if $\hat{h} > 0$ in $\bar{\Omega}$, and if (t, u) solves (3.1), then $t \geq t_l$ for some $t_l < 0$. Next, we show that if t is in some compact interval $[a, b]$, and (t, u) solves (3.1), then there exists a constant $M_0 = M_0([a, b]) > 0$ such that $\|u\|_{C_0^1(\bar{\Omega})} < M_0$.

4.1. Nonexistence of solutions for large negative t . In this section $\hat{h} > 0$ in $\bar{\Omega}$. In Section 3 it was only required that $\hat{h} \geq 0$ in $\bar{\Omega}$ to show the existence of a solution for a large positive t .

We first establish

Proposition 4.1. *Assume that f satisfies conditions (3.2)–(3.3), that $h, \hat{h} \in C(\bar{\Omega})$, and $\hat{h} > 0$ in $\bar{\Omega}$. Then there exists $t_- \in \mathbb{R}$ such that for all $t \leq t_-$, weak solutions $u \in C_0^1(\bar{\Omega})$ of (3.1) must satisfy $u \geq 0$ in Ω .*

Proof. The requirements imposed on f imply that there exist α' and a positive constant $C = C(\alpha')$ such that $\alpha < \alpha' < \lambda_1$ and

$$f(s) \geq \alpha'|s|^{p-2}s - C, \quad \forall s \in \mathbb{R}. \quad (4.1)$$

Suppose that the conclusion of the proposition does not hold. Then there exist sequences $\{u_n\}_{n=1}^\infty \subset C_0^1(\overline{\Omega})$ and $\{t_n\}_{n=1}^\infty \subset \mathbb{R}$ such that $t_n \rightarrow -\infty$, (u_n, t_n) satisfies (3.1) in a distributional sense, and $u_n^- \not\equiv 0$ for each $n = 1, 2, 3, \dots$. Therefore

$$-\int_{\Omega} |\nabla u_n|^{p-2} \nabla u_n \cdot \nabla \phi + \int_{\Omega} f(u_n) \phi = \int_{\Omega} (|t_n|^{p-2} t_n \hat{h} + h) \phi, \quad (4.2)$$

for all $\phi \in W_0^{1,p}(\Omega)$. Hence, by (4.1) and (4.2), we have

$$-\int_{\Omega} |\nabla u_n|^{p-2} \nabla u_n \nabla \phi + \int_{\Omega} \alpha' |u_n|^{p-2} u_n \phi \leq \int_{\Omega} (|t_n|^{p-2} t_n \hat{h} + h + C) \phi, \quad (4.3)$$

for all $\phi \in W_0^{1,p}(\Omega)$ such that $\phi \geq 0$ almost everywhere in Ω . Since $\hat{h} > 0$ in $\overline{\Omega}$, there exists $\epsilon > 0$ such that $\hat{h} \geq \epsilon$ in $\overline{\Omega}$. Then,

$$|t_n|^{p-2} t_n \hat{h} \leq |t_n|^{p-2} t_n \epsilon.$$

We also have

$$h + C \leq \max_{\overline{\Omega}} h + C \leq C_1$$

in $\overline{\Omega}$ for some constant C_1 , and there exists $N_0 > 0$ such that for all $n \geq N_0$,

$$|t_n|^{p-1} \epsilon \geq C_1.$$

Thus, for those n ,

$$|t_n|^{p-2} t_n \hat{h} + h + C \leq 0$$

in $\overline{\Omega}$, and

$$\int_{\Omega} (|t_n|^{p-2} t_n \hat{h} + h + C) \phi \leq 0,$$

for all $n \geq N_0$ and for all $\phi \in W_0^{1,p}(\Omega)$ such that $\phi \geq 0$ almost everywhere in Ω .

Hence, for each $n \geq N_0$, u_n satisfies

$$-\int_{\Omega} |\nabla u_n|^{p-2} \nabla u_n \nabla \phi + \int_{\Omega} \alpha' |u_n|^{p-2} u_n \phi \leq 0,$$

for all $\phi \in W_0^{1,p}(\Omega)$ such that $\phi \geq 0$ almost everywhere in Ω . Therefore, u_n is a weak supersolution for

$$\begin{cases} \Delta_p u + \alpha' |u|^{p-2} u = 0 & \text{in } \Omega \\ u = 0 & \text{on } \partial\Omega. \end{cases} \quad (4.4)$$

We now fix $n \geq N_0$.

Suppose w is a negative eigenfunction associated with the principal eigenvalue, λ_1 , of the eigenvalue problem (2.1). Then, by the homogeneity of the p -Laplacian, discussed in Section 2.2, any positive constant multiple of w is a negative eigenfunction associated with λ_1 . Also, since $\frac{\partial w}{\partial \nu} < 0$ on $\partial\Omega$, we can find a constant multiple of w , γw , such that $\gamma w \leq u_n$ in Ω and $\gamma w = 0 = u_n$ on $\partial\Omega$. Since $\alpha' < \lambda_1$, γw satisfies

$$\begin{aligned} 0 &= - \int_{\Omega} |\nabla(\gamma w)|^{p-2} \nabla(\gamma w) \nabla \phi + \int_{\Omega} \lambda_1 |(\gamma w)|^{p-2} (\gamma w) \phi \\ &\leq - \int_{\Omega} |\nabla(\gamma w)|^{p-2} \nabla(\gamma w) \nabla \phi + \int_{\Omega} \alpha' |(\gamma w)|^{p-2} (\gamma w) \phi, \end{aligned}$$

for all $\phi \in W_0^{1,p}(\Omega)$ such that $\phi \geq 0$ almost everywhere in Ω . Thus γw is a weak subsolution for the problem (4.4). Since we have $\gamma w \leq u_n$ in Ω , by using Theorem 2.4, there exists a solution for (4.4), u , such that $\gamma w \leq u \leq u_n$ in Ω . As a consequence, since $u_n^- \not\equiv 0$ in Ω , we have $u^- \not\equiv 0$.

Now, since u satisfies

$$- \int_{\Omega} |\nabla u|^{p-2} \nabla u \nabla \phi + \int_{\Omega} \alpha' |u|^{p-2} u \phi = 0,$$

for all $\phi \in W_0^{1,p}(\Omega)$, and since $u^- \in W_0^{1,p}(\Omega)$ (see [6]), by letting $\phi = u^-$, we have

$$- \int_{\Omega} |\nabla u|^{p-2} \nabla u \nabla u^- + \int_{\Omega} \alpha' |u|^{p-2} u u^- = 0.$$

Then u^- satisfies

$$- \int_{\Omega} |\nabla(-u^-)|^{p-2} \nabla(-u^-) \nabla u^- + \int_{\Omega} \alpha' |-u^-|^{p-2} (-u^-) u^- = 0;$$

hence, we have

$$\int_{\Omega} |\nabla u^-|^p - \int_{\Omega} \alpha' |u^-|^p = 0.$$

However, if $u^- \not\equiv 0$, then, since $\alpha' < \lambda_1$, we obtain

$$\int_{\Omega} |\nabla u^-|^p = \int_{\Omega} \alpha' |u^-|^p < \int_{\Omega} \lambda_1 |u^-|^p,$$

which contradicts the Poincaré inequality. Consequently, we must have $u^- \equiv 0$. Therefore, (4.4) has only the trivial solution, which is a contradiction to $u^- \not\equiv 0$ and hence to the assumption. Therefore, there exists $t_- (= t_{N_0}) < 0$ such that if $t \leq t_-$, and u is a solution for (3.1) corresponding to such t , it must be the case that $u \geq 0$ in Ω . \square

Theorem 4.2. *Suppose f satisfies the conditions (3.2)–(3.3), $h, \hat{h} \in C(\overline{\Omega})$, and $\hat{h} > 0$ in $\overline{\Omega}$; then there exists $t_l \in \mathbb{R}$ such that for all $t \leq t_l$, (3.1) has no weak solution.*

Proof. First suppose $t'_- < 0$ is such that if $t \leq t'_-$,

$$|t|^{p-2}t < \frac{f(0) - \max_{\overline{\Omega}} h}{\max_{\overline{\Omega}} \hat{h}}.$$

Then, since $\hat{h} > 0$,

$$|t|^{p-2}t < \frac{f(0) - \max_{\overline{\Omega}} h}{\max_{\overline{\Omega}} \hat{h}} \leq \frac{f(0) - h(x)}{\hat{h}(x)},$$

for all $x \in \overline{\Omega}$; i.e.,

$$|t|^{p-2}t\hat{h}(x) + h(x) - f(0) < 0,$$

for all $x \in \overline{\Omega}$. Then, $u \equiv 0$ cannot be a solution for (3.1).

Let $\epsilon > 0$ be such that $\beta - \epsilon > \lambda_1$. Since $\lim_{s \rightarrow \pm\infty} \frac{g(s)}{|s|^{p-2}s} = 0$, for this ϵ , there exists $\delta > 0$ such that

$$-g(s) - \epsilon s^{p-1} < 0$$

for all $s > \delta$, and for ϵ and δ , there exists $C > 0$ such that

$$-g(s) - \epsilon s^{p-1} \leq C$$

for all $0 \leq s \leq \delta$ since g is piecewise smooth.

For this C , since $\hat{h} > 0$ in $\overline{\Omega}$, there exists $t''_- < 0$ such that

$$\int_{\Omega} (|t|^{p-2}t\hat{h} + h + C)\phi \leq 0, \quad (4.5)$$

for all $t \leq t''_-$, and $\phi \in W_0^{1,p}(\Omega)$ such that $\phi \geq 0$ almost everywhere in Ω .

Proposition 4.1 implies that, if $\alpha < \lambda_1$, then there exists t_- such that for all $t \leq t_-$, (3.1) has only nonnegative solutions. Suppose $t \leq \min\{t_-, t'_-, t''_-\}$ and let $u \geq 0$ be a solution to (3.1). Then, (u, t) satisfies

$$-\int_{\Omega} |\nabla u|^{p-2} \nabla u \nabla \phi + \beta \int_{\Omega} u^{p-1} \phi = \int_{\Omega} (|t|^{p-2}t\hat{h} + h)\phi - \int_{\Omega} g(u)\phi; \quad (4.6)$$

thus, by (4.5) and (4.6), u satisfies

$$-\int_{\Omega} |\nabla u|^{p-2} \nabla u \nabla \phi + \beta \int_{\Omega} u^{p-1} \phi \leq \int_{\Omega} (-g(u) - C)\phi, \quad (4.7)$$

for all $\phi \in W_0^{1,p}(\Omega)$ such that $\phi \geq 0$ almost everywhere in Ω . By subtracting $\int_{\Omega} \epsilon u^{p-1} \phi$ from both sides of the equation in (4.7), we obtain

$$- \int_{\Omega} |\nabla u|^{p-2} \nabla u \nabla \phi + (\beta - \epsilon) \int_{\Omega} u^{p-1} \phi \leq \int_{\Omega} (-g(u) - \epsilon u^{p-1} - C) \phi. \tag{4.8}$$

If $\Omega_1 := \{x \in \Omega : u(x) > \delta\}$ and $\Omega_2 := \{x \in \Omega : 0 \leq u(x) \leq \delta\}$,

$$\begin{aligned} & \int_{\Omega} (-g(u) - \epsilon u^{p-1} - C) \phi \\ &= \int_{\Omega_1} (-g(u) - \epsilon u^{p-1} - C) \phi + \int_{\Omega_2} (-g(u) - \epsilon u^{p-1} - C) \phi \leq 0. \end{aligned}$$

Hence,

$$- \int_{\Omega} |\nabla u|^{p-2} \nabla u \nabla \phi + (\beta - \epsilon) \int_{\Omega} u^{p-1} \phi \leq 0,$$

and thus u is a weak supersolution of

$$\begin{cases} \Delta_p u + (\beta - \epsilon) |u|^{p-2} u = 0 & \text{in } \Omega \\ u = 0 & \text{on } \partial\Omega. \end{cases} \tag{4.9}$$

Also, since $u \geq 0$ in Ω , and

$$- \int_{\Omega} |\nabla u|^{p-2} \nabla u \nabla \phi \leq -(\beta - \epsilon) \int_{\Omega} u^{p-1} \phi \leq 0,$$

for all $\phi \in W_0^{1,p}(\Omega)$ such that $\phi \geq 0$ almost everywhere in Ω , $\Delta_p u \leq 0$ weakly. Then it follows from maximum principles that $u > 0$ in Ω , and that $\frac{\partial u}{\partial \nu} > 0$ on $\partial\Omega$ since $u \not\equiv 0$.

Suppose w is a positive eigenfunction associated with the principal eigenvalue of (1.2). Then, since any constant multiple of w is an eigenfunction, we can find $\eta > 0$ such that $u \geq \eta w > 0$ in Ω . Then u is a positive supersolution, and ηw is a positive subsolution of (4.9) such that $u \geq \eta w > 0$ in Ω . Thus, by Theorem 2.4, there exists a positive solution, \tilde{u} , such that $u \leq \tilde{u} \leq \eta w$ in Ω for (4.9) and \tilde{u} is a nontrivial weak solution to

$$\begin{cases} \Delta_p u + (\beta - \epsilon) |u|^{p-2} u = 0 & \text{in } \Omega \\ u = 0 & \text{on } \partial\Omega, \end{cases}$$

contradicting Proposition 2.2. Therefore, if $t \leq t'_-$, (3.1) does not possess nonnegative solutions. Thus, if $t \leq t_l := \min\{t_-, t'_-, t''_-\}$, then (3.1) does not have a solution. \square

4.2. Solution bounds for $t \in [a, b]$.

Theorem 4.3. *Given a compact interval $[a, b]$ and a number $C > 0$, there exists a constant $M_0 = M_0([a, b], C)$ such that if (t, u) is a solution of (3.1) with $t \in [a, b]$ and $\|\hat{h}\|_{C(\bar{\Omega})} \leq C$, then $\|u\|_{C_0^1(\bar{\Omega})} \leq M_0$.*

In order to prove the theorem, we first note the following lemma.

Lemma 4.4. *Let $\{u_n\}_{n=1}^\infty$ be a sequence in $C_0^1(\bar{\Omega})$ such that $\|u_n\|_{C_0^1(\bar{\Omega})} \rightarrow \infty$ as $n \rightarrow \infty$, $v_n = u_n/\|u_n\|_{C_0^1(\bar{\Omega})}$, and $\{t_n\}_{n=1}^\infty \subset [a, b]$ for some a and b such that $a \leq b$, where (t_n, u_n) solves (3.1) for each $n = 1, 2, 3, \dots$. Assume that $\hat{h}, h \in C(\bar{\Omega})$, $\|\hat{h}\|_{C(\bar{\Omega})} \leq C$, and that $g \in C^1(\mathbb{R})$ is such that $\lim_{|s| \rightarrow \infty} \frac{g(s)}{|s|^{p-2}s} = 0$. Then the sequence $\{\tilde{v}_n\}_{n=1}^\infty$ given by*

$$\tilde{v}_n := \beta|v_n|^{p-2}v_n^+ - \alpha|v_n|^{p-2}v_n^- + \frac{g(t_nv_n)}{\|u_n\|_{C_0^1(\bar{\Omega})}^{p-1}} - \frac{|t_n|^{p-2}t_n}{\|u_n\|_{C_0^1(\bar{\Omega})}^{p-1}}\hat{h} - \frac{h}{\|u_n\|_{C_0^1(\bar{\Omega})}^{p-1}}$$

is bounded in $C(\bar{\Omega})$.

We now give the proof of Theorem 4.3.

Proof. Suppose the conclusion of Theorem 4.3 does not hold. Then there exist sequences $\{t_n\}_{n=1}^\infty \subset [a, b]$, $\{\hat{h}_n\}_{n=1}^\infty \subset C(\bar{\Omega})$, and $\{u_n\}_{n=1}^\infty \subset C_0^1(\bar{\Omega})$ such that $\|\hat{h}_n\|_{C(\bar{\Omega})} \leq C$ for some $C > 0$ and $\|u_n\|_{C_0^1(\bar{\Omega})} \rightarrow +\infty$ as $n \rightarrow +\infty$, and that u_n is a weak solution of the problem (3.1) corresponding to $t = t_n$, and $\hat{h} = \hat{h}_n$. Thus, u_n satisfies

$$u_n = R_p(\beta|u_n|^{p-2}u_n^+ - \alpha|u_n|^{p-2}u_n^- + g(u_n) - |t_n|^{p-2}t_n\hat{h}_n - h). \quad (4.10)$$

By dividing both sides of (4.10) by $\|u_n\|_{C_0^1(\bar{\Omega})}$ and using the homogeneity of R_p , we obtain that the sequence $\{v_n\}$, where $v_n = u_n/\|u_n\|_{C_0^1(\bar{\Omega})}$, by passing to a subsequence, if necessary, converges, say, $v_n \rightarrow v_0$, for $v_0 \in C_0^1(\bar{\Omega})$, which must be a solution of

$$\begin{cases} -\Delta_p v &= \beta|v|^{p-2}v^+ - \alpha|v|^{p-2}v^- & \text{in } \Omega \\ v &= 0 & \text{on } \partial\Omega, \end{cases}$$

which has only the trivial solution, by Proposition 2.5. Since $\|v_n\|_{C_0^1(\bar{\Omega})} = 1$ for all $n \in \mathbb{N}$, $\|v_0\|_{C_0^1(\bar{\Omega})} = 1$, contradicting that $v_0 = 0$ in $\bar{\Omega}$. Hence, the result follows. \square

5. MULTIPLICITY RESULT: $\hat{h} > 0$ IN $\overline{\Omega}$

The results of Sections 3 and 4 may be combined to show that, in the case $\hat{h} > 0$ in $\overline{\Omega}$, there are regions in $\mathbb{R} \times C_0^1(\overline{\Omega})$ where there are no solutions of (3.1), a region where there are multiple solutions possible, and a region where there is at least one solution. Using properties of the Leray-Schauder degree, and the following set of lemmas, we shall obtain such an existence and multiplicity result (cf. [16] for corresponding results and methods for ordinary differential equations).

Lemma 5.1. *Suppose f satisfies the conditions (3.2)–(3.3), $\hat{h}, h \in C(\overline{\Omega})$, $\hat{h} \geq 0$, and $\hat{h} \not\equiv 0$ in $\overline{\Omega}$. If (3.1) has a solution for $t = \tau$ for some $\tau \in \mathbb{R}$, then (3.1) has a solution for each $t \geq \tau$.*

Proof. Suppose (3.1) has a solution for $t = \tau$, and denote it by u_τ . Then, since $\hat{h} \geq 0$ for any $t \geq \tau$, we have

$$-\int_{\Omega} |\nabla u_\tau|^{p-2} \nabla u_\tau \nabla \phi + \int_{\Omega} f(u_\tau) \phi = \int_{\Omega} (|\tau|^{p-2} \tau \hat{h} + h) \phi \leq \int_{\Omega} (|t|^{p-2} t \hat{h} + h) \phi,$$

for all $\phi \in W_0^{1,p}(\Omega)$ such that $\phi \geq 0$ almost everywhere in Ω . Therefore, u_τ is a supersolution for (3.1) for any $t \geq \tau$.

Now, define

$$\tilde{h} = \begin{cases} \max_{\overline{\Omega}} h & \text{if there exists } x \text{ such that } h(x) > 0 \text{ in } \Omega \\ 0 & \text{if } h(x) \leq 0 \text{ for all } x \in \Omega, \end{cases}$$

and consider the problem

$$\begin{cases} \Delta_p u + \alpha' |u|^{p-2} u = |t|^{p-2} t \hat{h} + \tilde{h} + C & \text{in } \Omega \\ u = 0 & \text{on } \partial\Omega, \end{cases} \tag{5.1}$$

where α' and C are as defined in the proof of Proposition 4.1, i.e., such that

$$f(s) \geq \alpha' |s|^{p-2} s - C \text{ for all } s \in \mathbb{R}.$$

Then, since $\alpha' \in (\alpha, \lambda_1)$, and $|t|^{p-2} t \hat{h} + \tilde{h} + C \geq 0$ in Ω for $t \geq 0$, by replacing $2\hat{h}$ in the proof of Lemma 3.2 with $|t|^{p-2} t \hat{h} + \tilde{h} + C$, we obtain a negative solution for (5.1) for any $t \geq 0$. Fix $t \geq \tau$ and let $\tau_1 \geq t$. Then, if u_{τ_1} is a negative solution for (5.1) for $t = \tau_1$, u_{τ_1} satisfies

$$-\int_{\Omega} |\nabla u_{\tau_1}|^{p-2} \nabla u_{\tau_1} \nabla \phi + \int_{\Omega} \alpha' |u_{\tau_1}|^{p-2} u_{\tau_1} \phi = \int_{\Omega} (|\tau_1|^{p-2} \tau_1 \hat{h} + \tilde{h} + C) \phi, \tag{5.2}$$

for all $\phi \in W_0^{1,p}(\Omega)$. Also notice that by multiplying (5.2) by γ^{p-1} where $\gamma \geq 1$ and using the homogeneity of the p -Laplacian, we get

$$\begin{aligned} & - \int_{\Omega} |\nabla(\gamma u_{\tau_1})|^{p-2} \nabla(\gamma u_{\tau_1}) \nabla \phi + \int_{\Omega} \alpha' |\gamma u_{\tau_1}|^{p-2} (\gamma u_{\tau_1}) \phi \quad (5.3) \\ & = \gamma^{p-1} \int_{\Omega} (|\tau_1|^{p-2} \tau_1 \hat{h} + \tilde{h} + C) \phi \geq \int_{\Omega} (|\tau_1|^{p-2} \tau_1 \hat{h} + \tilde{h} + C) \phi, \end{aligned}$$

for all $\phi \in W_0^{1,p}(\Omega)$ such that $\phi \geq 0$ almost everywhere in Ω . Then, we have

$$\begin{aligned} & - \int_{\Omega} |\nabla(\gamma u_{\tau_1})|^{p-2} \nabla(\gamma u_{\tau_1}) \nabla \phi + \int_{\Omega} (\alpha' |\gamma u_{\tau_1}|^{p-2} (\gamma u_{\tau_1}) - C) \phi \\ & \geq \int_{\Omega} (|\tau_1|^{p-2} \tau_1 \hat{h} + \tilde{h}) \phi. \end{aligned}$$

Then, since

$$\begin{aligned} & - \int_{\Omega} |\nabla(\gamma u_{\tau_1})|^{p-2} \nabla(\gamma u_{\tau_1}) \nabla \phi + \int_{\Omega} f(\gamma u_{\tau_1}) \phi \quad (5.4) \\ & \geq - \int_{\Omega} |\nabla(\gamma u_{\tau_1})|^{p-2} \nabla(\gamma u_{\tau_1}) \nabla \phi + \int_{\Omega} (\alpha' |\gamma u_{\tau_1}|^{p-2} (\gamma u_{\tau_1}) - C) \phi, \end{aligned}$$

and

$$\int_{\Omega} (|\tau_1|^{p-2} \tau_1 \hat{h} + \tilde{h}) \phi \geq \int_{\Omega} (|t|^{p-2} t \hat{h} + h) \phi,$$

for all $\phi \in W_0^{1,p}(\Omega)$ such that $\phi \geq 0$ almost everywhere in Ω , we have

$$- \int_{\Omega} |\nabla(\gamma u_{\tau_1})|^{p-2} \nabla(\gamma u_{\tau_1}) \nabla \phi + \int_{\Omega} f(\gamma u_{\tau_1}) \phi \geq \int_{\Omega} (|t|^{p-2} t \hat{h} + h) \phi,$$

for all $\phi \in W_0^{1,p}(\Omega)$ such that $\phi \geq 0$ almost everywhere in Ω . Therefore, for any $\gamma \geq 1$, γu_{τ_1} is a negative subsolution for (3.1).

The inequalities above imply

$$- \int_{\Omega} |\nabla(\gamma u_{\tau_1})|^{p-2} \nabla(\gamma u_{\tau_1}) \nabla \phi + \int_{\Omega} \alpha' |\gamma u_{\tau_1}|^{p-2} (\gamma u_{\tau_1}) \phi \geq 0,$$

which can be used to show $u_{\tau_1} \leq 0$ in Ω as in the proof of Lemma 3.2. Also from this inequality above, we obtain

$$- \int_{\Omega} |\nabla(\gamma u_{\tau_1})|^{p-2} \nabla(\gamma u_{\tau_1}) \nabla \phi \geq 0. \quad (5.5)$$

As in the proof of Lemma 3.2, we may use (5.5) and maximum principles to obtain $u_{\tau_1} < 0$ in Ω , and $\frac{\partial u_{\tau_1}}{\partial \nu} < 0$ on $\partial\Omega$ since $u_{\tau_1} = 0$ on $\partial\Omega$. Hence, we can find some $\gamma \geq 1$ such that $u_{\tau} \geq \gamma u_{\tau_1}$ in Ω . Therefore, by Theorem 2.4, (3.1)

has a solution for $\tau \leq t \leq \tau_1$. However, the proof works for any $\tau_1 \geq 0$, and thus (3.1) has a solution for all $t \geq \tau$ if (3.1) has a solution for $t = \tau$. \square

Theorem 5.2. *Suppose f and h satisfy the conditions in Lemma 5.1, and $\hat{h} > 0$ in $\bar{\Omega}$. Then there exist t_1 and t_2 , $t_1 \leq t_2$, such that the problem (3.1) has no solution if $t < t_1$, at least one solution if $t_1 \leq t \leq t_2$, and at least two solutions if $t > t_2$.*

Proof. Define the mapping

$$\begin{aligned}
 F(u, t) &:= \begin{cases} R_1(u, t), & t \leq 1 \\ R_2(u, t), & t \geq 1 \end{cases} \\
 &:= \begin{cases} R_p(\beta|u|^{p-2}u^+ - \alpha|u|^{p-2}u^- + g(u) - |t|^{p-2}t\hat{h} + h), \\ R_p\left(\beta|u|^{p-2}u^+ - \alpha|u|^{p-2}u^- + \frac{g(tu)}{t^{p-1}} - \hat{h} + \frac{h}{t^{p-1}}\right). \end{cases}
 \end{aligned}$$

Then we may study the problem $u = F(u, t)$ instead of the problem (3.1), since the number of solutions to $u = F(u, t)$ is the same as the number of solutions to (3.1); viz., if (u, t) solves (3.1) for $t \leq 1$, by definition, $u = R_1(u, t)$, and if (u, t) solves $u = R_2(u, t)$, then tu solves (3.1).

We first note that $F : C_0^1(\bar{\Omega}) \times \mathbb{R} \rightarrow C_0^1(\bar{\Omega})$ is a completely continuous map.

It follows from Theorem 4.2 that there exists t_l such that if $t \leq t_l$, problem (3.1) does not have a solution. Then, by Theorem 3.1, there exists a number $t_h \gg 1$ such that the problem (3.1) has a solution if $t \geq t_h$ by noting that the degree

$$\deg(id - R'(\cdot), D, 0) = 1,$$

where $R'(u) = R_p(\beta|u|^{p-2}u^+ - \alpha|u|^{p-2}u^- + \frac{g(tu)}{t^{p-1}} - \hat{h} + \frac{h}{t^{p-1}})$, and D is the subset of $C_0^1(\bar{\Omega})$ defined in Section 3; i.e.,

$$\deg(id - F(\cdot, t_h), D, 0) = 1.$$

Also, we have shown that solutions to (3.1) for all t in each compact interval $[a, b]$ are uniformly bounded (see Theorem 4.3); thus, there exists $C_1 > 0$ such that if u solves (3.1) for $t \in [t_l, t_h]$, then $\|u\|_{C_0^1(\bar{\Omega})} < C_1$. Since, if $t \geq 1$, solutions for (3.1) may be given by tv where (v, t) is a solution to $v = R_2(v, t)$, $\|tv\|_{C_0^1(\bar{\Omega})} < C_1$ implies $\|v\|_{C_0^1(\bar{\Omega})} < \frac{1}{t}C_1 \leq C_1$. Therefore, all solutions to $u = F(u, t)$ for $t \leq t_h$ are contained in $B_{C_1}(0) \times [t_l, t_h] \subset C_0^1(\bar{\Omega}) \times \mathbb{R}$; hence, $\bar{D} \subset B_{C_1}(0)$ and

$$\deg(id - F(\cdot, t), B_{C_1}(0), 0) = 0, \quad t \leq t_h.$$

Therefore, by the excision principle and the additivity and solution properties of the degree, another solution of (3.1) (outside D) must exist for $t = t_h$.

Now, by Lemma 5.1, we may define

$$t_1 := \inf\{t : \text{there exists a solution of (3.1)}\},$$

and

$$t_2 := \inf\{t_h : \text{there exist at least two solutions for (3.1) if } t \geq t_h\}.$$

Then we have the following:

1. There is no solution for (3.1) if $t < t_1$.
2. (3.1) has at least one solution if $t_1 \leq t \leq t_2$.
3. There are at least two solutions for (3.1) if $t > t_2$. □

6. MULTIPLICITY RESULT: $\hat{h} \geq 0$ IN $\overline{\Omega}$

In Section 4, we found that multiple solutions are possible for (3.1) when $\hat{h} > 0$ in $\overline{\Omega}$. In this section, we address the same problem for the case $\hat{h} \geq 0$ by using a limiting argument.

Theorem 6.1. *Suppose f satisfies conditions (3.2)–(3.3), $\hat{h}, h \in C(\overline{\Omega})$, and $\hat{h} \geq 0$, but $\hat{h} \not\equiv 0$ in $\overline{\Omega}$. Then there exists \hat{t} such that if $t \geq \hat{t} \geq -\infty$, the problem*

$$\begin{cases} \Delta_p u + f(u) = |t|^{p-2} t \hat{h} + h & \text{in } \Omega \\ u = 0 & \text{on } \partial\Omega \end{cases} \quad (6.1)$$

has at least two solutions.

Proof. By Theorem 3.1, there exists \hat{t} such that if $t \geq \hat{t}$, the problem

$$\begin{cases} \Delta_p u + \beta|u|^{p-2}u^+ - \alpha|u|^{p-2}u^- + \frac{g(tu)}{t^{p-1}} = \hat{h} + \frac{h}{t^{p-1}} & \text{in } \Omega \\ u = 0 & \text{on } \partial\Omega \end{cases} \quad (6.2)$$

has a solution in the set

$$D = \left\{ u \in C_0^1(\overline{\Omega}) : \underline{v} < u < 0 \text{ in } \Omega, \frac{\partial \underline{v}}{\partial \nu} < \frac{\partial u}{\partial \nu} < 0 \text{ on } \partial\Omega, \|u\|_{C_0^1(\overline{\Omega})} < M \right\},$$

where \underline{v} is a solution for

$$\begin{cases} \Delta_p u + \beta|u|^{p-2}u^+ - \alpha|u|^{p-2}u^- = 2\hat{h} & \text{in } \Omega \\ u = 0 & \text{on } \partial\Omega, \end{cases} \quad (6.3)$$

which is a strict subsolution for

$$\begin{cases} \Delta_p u + \beta|u|^{p-2}u^+ - \alpha|u|^{p-2}u^- = \hat{h} & \text{in } \Omega \\ u = 0 & \text{on } \partial\Omega, \end{cases} \quad (6.4)$$

and M is as defined in Lemma 3.3.

Fix $t \in [\hat{t}, \infty)$ and let $\{\hat{h}_n\}_{n=1}^\infty$ be such that $\hat{h}_n > 0$ in $\bar{\Omega}$, $\hat{h}_n \rightarrow \hat{h}$ in $C(\bar{\Omega})$, and

$$R'_n(u) := R_p \left(\beta|u|^{p-2}u^+ - \alpha|u|^{p-2}u^- - \hat{h}_n + \frac{g(tu)}{t^{p-1}} - \frac{h}{t^{p-1}} \right).$$

Since $\hat{h}_n \rightarrow \hat{h}$ in $C(\bar{\Omega})$, for given $r > 0$, there exists $N_0 > 0$ such that

$$\|R'_n(u) - R'(u)\|_{C^1_0(\bar{\Omega})} < r$$

if $n \geq N_0$. Therefore, by Leray-Schauder degree properties

$$1 = \deg(id - R'(\cdot), D, 0) = \deg(id - R'_n(\cdot), D, 0) \tag{6.5}$$

for r small, and hence $u = R'_n(u)$ has a solution in D and no solutions on ∂D if $n \geq N_0$.

By applying the arguments in the proof of Theorem 5.2, we conclude that if $n \geq N_0$, then the problem

$$\begin{cases} \Delta_p u + \beta|u|^{p-2}u^+ - \alpha|u|^{p-2}u^- + \frac{g(tu)}{t^{p-1}} &= \hat{h}_n + \frac{h}{t^{p-1}} & \text{in } \Omega \\ u &= 0 & \text{on } \partial\Omega \end{cases} \tag{6.6}$$

has at least two solutions, at least one in D and one in $C^1_0(\bar{\Omega}) \setminus \bar{D}$.

Let $n_j := N_0 - j + 1$ and let $\{u_{n_j}\}_{j=1}^\infty$ be such that $u_{n_j} \in C^1_0(\bar{\Omega}) \setminus \bar{D}$ is a solution for $u = R'_{n_j}(u)$ for each $j = 1, 2, 3, \dots$. Then, u_{n_j} satisfies

$$u_{n_j} = R'_{n_j}(u_{n_j}). \tag{6.7}$$

Therefore, by Theorem 4.3, since t is fixed, solutions for (6.6) are uniformly bounded for all $j \in \mathbb{N}$.

Since R_p is completely continuous, by passing to a subsequence, if necessary, we may assume that $u_{n_j} \rightarrow \hat{u}$ as $j \rightarrow \infty$, for some $\hat{u} \in C^1_0(\bar{\Omega})$. By a limiting argument we obtain that \hat{u} is a solution for (6.2).

We saw above that $\{u_{n_j}\}_{j=1}^\infty \subset C^1_0(\bar{\Omega}) \setminus \bar{D}$; hence, $\hat{u} \in C^1_0(\bar{\Omega}) \setminus \bar{D}$. Therefore, there exists \hat{t} such that if $t \geq \hat{t}$, (6.2) has at least two solutions, one in D and another one in $C^1_0(\bar{\Omega}) \setminus \bar{D}$. Consequently, (6.1) has at least two solutions. \square

In case that $\hat{h} \equiv 0$ in $\bar{\Omega}$, as the following example shows, (6.1) may not possess any solutions.

Proposition 6.2. *Suppose $k > 0$, $\beta > \lambda_1$, and $\alpha < \lambda_1$; then*

$$\begin{cases} \Delta_p u + \beta|u|^{p-2}u^+ - \alpha|u|^{p-2}u^- &= -k & \text{in } \Omega \\ u &= 0 & \text{on } \partial\Omega \end{cases} \tag{6.8}$$

has no solution.

Proof. We can use the same arguments as in the proof of Proposition 4.1 and that of Theorem 4.2. \square

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