

Margulis Distributions for Anosov Flows

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Abstract. For the strong unstable foliation (or horocycle foliation) of an Anosov flow there exists a unique transverse measure called the Margulis measure. In this paper we extend Margulis' results to more general "transverse distributions" for the foliation. As an application we derive our main result: The non-zero analytic extension to a strip of the Selberg zeta function for compact surfaces of constant negative curvature persists under small perturbations in the metric. There is an equivalent formulation in terms of the Fourier transform of the correlation function.

0. Introduction

In the study of Axiom A flows there are two functions (of a single complex variable) which contain a considerable amount of information on the dynamics of the flow – the zeta function and the Fourier transform of the correlation function (which describes the way in which the flow mixes). Their meromorphic domains influence the asymptotic growth of closed orbit periods (through the zeta function [14]) and the rate of mixing of the flow (through the correlation function [16, 21]).

David Ruelle has gone some way in analysing the residues which occur for the Fourier transform and he has given them some interpretation in terms of "Gibbs distributions" [22] (similar in nature to distributions in the Schwartzian sense, but which are complex valued). However, this does not broach the problem of locating the poles. There is a simple correspondence between poles for the zeta function and poles for the Fourier transform of the correlation function (within appropriate domains) which reduces this to a single problem [16].

In this article we give an approach to determining the location of the poles and to giving them, along with the residues, a clearer interpretation, at least for Anosov flows.

We shall formulate most of our results at the level of three-dimensional Anosov flows. This will be most appropriate for our main application.

Our approach to these problems is to consider transverse distributions (generalising transverse measures) for the natural foliation associated with the

strong stable manifolds of Anosov flows. This approach is motivated by Margulis' very elegant work on transverse measures for horocycle foliations [25], although the techniques we use are very different. (We should remark that Margulis apparently used these measures in obtaining asymptotic estimates for closed geodesic lengths, demonstrating how closely related these concepts are, cf. also [14].)

Bowen profoundly influenced the study of both Axiom A diffeomorphisms and flows with the use of symbolic dynamics [4, 5] (Bowen was obviously inspired by the Russian school [18, 19]). This allowed many problems to be reformulated for subshifts of finite type (in the discrete case) or suspended flows (in the continuous case). For subshifts of finite type a number of powerful results can be proved using techniques originating in statistical mechanics. In particular, the Ruelle operator proves to be a very useful tool [5]. For flows the situation is slightly more involved (not least because of the difficulty in directly applying ideas from statistical mechanics). The Ruelle operator can be used again, although for flows it plays a rather more subtle role [17].

In Sect. 1 we review the basic definitions and ideas connected with Axiom A flows and strong stable (horocycle) foliations. In Sect. 2 we relate this to our working format of suspended flows over subshifts (of finite type) by the use of symbolic dynamics.

In Sect. 3 we give an alternative construction of Margulis (transverse) measures, the unique transverse measure associated with the strong stable foliation. This makes use of the spectrum of (the dual to) the Ruelle operator.

In Sect. 4 we recall some results on the Fourier transform of the correlation function (which describes the rate at which the flow mixes). This is intimately connected with the spectrum of the Ruelle operator, which allows us to relate the existence of poles to the existence of certain "Margulis distributions" generalising Margulis measures.

In Sect. 5 we relate the existence of poles (where the correlation is with respect to the measure of maximal entropy) to the induced action of ϕ_t on an appropriate Banach space (subject to an orientation condition on ϕ_t). The intermediate step is the connection with the Margulis distributions.

The Sect. 6 contains the first version of our main result: *For metrics close to those of constant negative (sectional) curvature the Fourier transform of the correlation function for the geodesic flow (with the measure of maximal entropy) has an analytic extension to a strip.*

In Sect. 7 we give the equivalent formulation of our results in terms of the (dynamical) zeta function. Our main result now becomes: *For metrics close to those of constant negative curvature the zeta function for the geodesic flow has an analytic extension to a strip.*

1. Axiom A Flows and Strong Stable Foliations

We begin by introducing our basic object of study, a C^∞ Axiom A flow on a compact Riemannian manifold, and recall some of the basic definitions and properties.

Let M be a compact C^∞ Riemannian manifold, and let $\phi_t: M \rightarrow M$ be a $C^{1+\varepsilon}$ -flow. We define the *nonwandering set*

$$\Omega = \left\{ x \in M \mid \forall \text{ open neighbourhoods } U \ni x, \exists t_0 > 0 \text{ s.t. } U \cap \left(\bigcup_{t > t_0} \phi_t U \right) \neq \emptyset \right\}.$$

A flow satisfies Axiom A if the non-wandering set is the disjoint union of a finite number of hyperbolic fixed points and a finite number of ϕ_t invariant sets A satisfying:

- 1) $\phi|_A$ has no fixed points and closed orbits of $\phi|_A$ are dense in A .
- 2) $\phi|_A$ is transitive (i.e. A contains a dense orbit).
- 3) $T_A M$ splits into 3 $D\phi_t$ -invariant continuous sub-bundles $T_A M = E \oplus E^u \oplus E^s$ with E tangent to the flow direction and

$$\begin{aligned} \|D\phi_t(v)\| &\leq C e^{-\lambda t} \|v\| \text{ for } v \in E^s, \quad t \geq 0, \\ \|D\phi_{-t}(v)\| &\leq C e^{-\lambda t} \|v\| \text{ for } v \in E^u, \quad t \geq 0. \end{aligned}$$

(Each such A is called a *basic set*.) [27]

We call the flow $\phi_t: A \rightarrow A$ (*topologically*) *weak-mixing* if there are no non-trivial solutions to $F_{\phi_t} = e^{iat} F$ for $F \in C(A)$ and $a > 0$. Not weakmixing flows are topologically conjugate to constant suspensions of Axiom A diffeomorphisms and consequently much of their analysis has already been performed at the level of diffeomorphisms [5]. Thus we shall be interested generally only in weak-mixing Axiom A flows.

We call ϕ_t *Anosov* if we can replace A by M in condition 3), i.e. the entire manifold is hyperbolic.

We call an Anosov flow transitive if $\exists x \in M$ with a dense orbit.

Having established the definitions for the flow we shall now consider the associated ergodic theory.

For any ϕ_t -invariant measure ϱ we define the entropy $h(\varrho)$ of ϕ (with respect to ϱ) to be the entropy of the time-one homeomorphism $\phi_1: A \rightarrow A$. There are an infinite number of (ergodic) invariant measures and their entropies are bounded above. We define the (*topological*) *entropy* by

$$h(\phi) = \sup \{ h(\varrho) \mid \varrho \text{ is } \phi\text{-invariant} \}.$$

The entropy has a number of different definitions and gives a quantitative estimate on the “randomness” of the flow. For Axiom A flows the entropy is always strictly positive and there is a unique ϕ -invariant measure m where the supremum is attained [i.e. $h(m) = h(\phi)$]. This measure m is called the *maximal measure* (or Bowen measure, or measure of maximal entropy) [7].

We now consider some slightly more geometric aspects of the flow. The hyperbolicity condition on the basic set is defined in terms of the tangent bundle $T_A M$ but has a direct influence on the manifold M . For $x \in A$ we can define the *strong unstable* and *strong stable manifolds* as

$$\begin{aligned} W^{su}(x) &= \{ y \in M \mid d(\phi_{-t}x, \phi_{-t}y) \rightarrow 0 \text{ as } t \rightarrow +\infty \}, \\ W^{ss}(x) &= \{ y \in M \mid d(\phi_t x, \phi_t y) \rightarrow 0 \text{ as } t \rightarrow +\infty \} \end{aligned}$$

respectively. [We shall also sometimes use $W_\varepsilon^{ss}(x) = \{y \in M \mid d(\phi_t x, \phi_t y) \leq \varepsilon, \forall t \geq 0\}$ which forms a neighbourhood of x in $W^{ss}(x)$ for $\varepsilon > 0$.]

In accordance with their names $W^{su}(x)$ and $W^{ss}(x)$ form C^∞ -immersed submanifolds of dimensions $n = \dim E^u$ and $m = \dim E^s$ respectively. Furthermore, for $x \in A$ we have $T_x W^{su}(x) = E_x^u$ and $T_x W^{ss}(x) = E_x^s$ (cf. [2]).

For Anosov flows the strong-stable manifolds form a foliation for M in the usual sense. However, although each leaf is C^∞ in general the foliation itself is only Holder continuous.

We shall denote this foliation by F^{ss} (cf. [8]).

We should also consider the effect of the flow $\phi_t: A \rightarrow A$ on these foliations. The main point is that for $x \in A$ we have $\phi_t W^{ss}(x) = W^{ss}(\phi_t x)$ and $\phi_t W^{su}(x) = W^{su}(\phi_t x)$, i.e. the flow preserves the foliation by taking leaves to leaves (without necessarily preserving the individual leaves).

We can use these foliations to generate new foliations F^{wu} and F^{ws} whose leaves are the $(n+1)$ -dimensional *weak unstable manifolds* and $(m+1)$ -dimensional *weak stable manifolds* given by

$$W^{wu}(x) = \bigcup_{t \in \mathbb{R}} W^{su}(\phi_t x) \quad \text{and} \quad W^{ws}(x) = \bigcup_{t \in \mathbb{R}} W^{ss}(\phi_t x),$$

respectively ($x \in A$). For these foliations the individual leaves *are* now invariant under the flow. (The weak unstable manifolds form transverse sections to the foliation F^{ss} .)

An important example is the geodesic flow on the (three-dimensional) unit tangent bundle of a compact surface of strictly negative curvature. This is a transitive Anosov flow for which the leaves of F^{ss} are one dimensional and the leaves of F^{wu} are two dimensional.

For geodesic flows all of these foliations are known to be C^1 (and so in particular Holder continuous with exponent one) [12].

2. The Symbolic Dynamics

To study problems about Axiom A flows it is frequently convenient to reduce them to questions at the level of the simpler symbolic or suspended flows. This approach has been developed by such people as Sinai, Ratner, Bowen, and Ruelle. We shall now give a brief account, explaining only those parts of the theory relevant to subsequent sections (for full details, cf. [4]).

If $\phi_t: M \rightarrow M$ is our Axiom A flow then we construct $(n+m)$ -dimensional differentiable, disjoint closed sections T_1, \dots, T_k transverse to the flow $\phi|_A$. [They can be assumed to lie in the intersection of the interiors of $(n+m)$ -dimensional C^∞ closed discs D_i transverse to the flow and A .] Furthermore, these sections can be chosen arbitrarily small ($\text{Diam } T_i < \varepsilon$, say) and assumed to capture all of the flow in the sense that for any $x \in A$ we can choose sequences $t_p \uparrow +\infty$ and $t_{-q} \downarrow -\infty$ (for $p, q \in \mathbb{Z}^+$) such that $|t_i - t_{i+1}| < \varepsilon$ and $\phi_{t_p} x, \phi_{t_{-q}} x \in T_1 \cup \dots \cup T_k$. With respect to the topology on $\bigcup_i D_i \cap A$ we can consider ∂T_i and $\text{int } T_i, i = 1, \dots, k$. Let $x \in A$ be a point whose orbit under ϕ_t intersects the T_i s in their interiors in the sequence $\dots T_{x_{-1}}, T_{x_0}, T_{x_1}, \dots$, then x gives rise to a sequence $x = (x_n)_{n=-\infty}^{+\infty} \in \prod_{n=-\infty}^{+\infty} \{1, \dots, k\}$.

The sequence \underline{x} records the orbit of the point x (and the zeroth term $x_0 \in \{1, \dots, k\}$ determines the last section traversed by the orbit whilst x is flowing forwards in time). The hyperbolicity of the flow on A permits these sections $\{T_i\}$ to be chosen so that they give very precise information on the corresponding orbit. (In particular, no two distinct orbits in A give rise to the same sequence.) Let $P: \bigcup_i T_i \rightarrow \bigcup_i T_i$ be the Poincaré map given by $P(x) = \phi_\alpha(x)$, where $\alpha = \inf\{t > 0 \mid \phi_t x \in \bigcup_i T_i\}$. We can introduce a $k \times k$ aperiodic matrix with entries either one or zero by

$$A(i, j) = \begin{cases} 1 & \text{if } P(\text{int } T_i) \cap (\text{int } T_j) \neq \emptyset \\ 0 & \text{otherwise.} \end{cases}$$

We define a space of sequences Σ_A by

$$\Sigma_A = \left\{ \underline{x} \in \prod_{n=-\infty}^{+\infty} \{1, \dots, k\} \mid A(x_n, x_{n+1}) = 1, n \in \mathbb{Z} \right\}.$$

Without loss of generality we can assume that the matrix A is aperiodic.

We have a topology on Σ_A induced from the product of the discrete topology on $\{1, \dots, k\}$ and with respect to this topology Σ_A is a compact zero-dimensional space. We define a metric for this topology by

$$d(\underline{x}, \underline{y}) = \sum_{n=-\infty}^{+\infty} \frac{e(x_n, y_n)}{2^{|n|}}, \quad \text{where } e(\alpha, \beta) = \begin{cases} 0 & \text{if } \alpha = \beta \\ 1 & \text{otherwise.} \end{cases}$$

The *shift* $\sigma: \Sigma_A \rightarrow \Sigma_A$ is defined by $(\sigma \underline{x})_n = x_{n+1}$, and with respect to the above topology is a homeomorphism.

The sections $\{T_i\}_{i=1}^k$ can be chosen so that the map $\pi: \Sigma_A \rightarrow \bigcup_{i=1}^k T_i$ with

$$\pi(\underline{x}) = \bigcap_{n=-\infty}^{+\infty} \overline{P^{-n}(\text{int } T_{x_n})}$$

is well-defined. Define $r: \Sigma_A \rightarrow \mathbb{R}$ by

$$r(\underline{x}) = \inf\{t > 0 \mid \phi_t(\pi(\underline{x})) \in T_{x_1}\},$$

then r is strictly positive (and uniformly bounded away from zero).

The sections T_i can be chosen so that $r(\underline{x}) = r(\underline{y})$ whenever $x_n = y_n$ for $n \geq 0$. (Strictly speaking, we can no longer think of D_i as being C^∞ cf. [19] for details.)

We define

$$\Sigma_A^r = \{(x, t) \in \Sigma_A \times \mathbb{R} \mid 0 \leq t \leq r(x)\},$$

where $(x, r(x))$ and $(\sigma x, 0)$ are identified. This space inherits a product topology from Σ_A and \mathbb{R} .

We define the *suspended flow* $\sigma_t^r: \Sigma_A^r \rightarrow \Sigma_A^r$ locally by $\sigma_t^r(x, s) = (x, s + t)$, taking account of the identifications where appropriate. We can extend the map π to $\pi: \Sigma_A^r \rightarrow A$ by $\pi(x, t) = \phi_t \pi(x)$.

The suspended flow σ^r gives a very accurate model of the original Axiom A flow $\phi_t: M \rightarrow M$. We summarise some of the main results in the following proposition:

Proposition 1 (Bowen) [4]. *There exists a choice of $\{T_i\}$ such that*

- (i) *The map $\pi: \Sigma_A^r \rightarrow A$ is Hölder, surjective, bounded-one and one-one on a residual set.*
- (ii) *The map π is a semi-conjugacy, i.e. $\pi\sigma^r = \phi_1\pi$.*
- (iii) *The map π preserves the maximal measures.*
- (iv) *σ^r and ϕ have the same topological entropy $h = h(\phi) = h(\sigma^r)$.*

We shall denote the Hölder exponent of π by $\alpha > 0$, i.e. $\exists C > 0$ such that $d_M(\pi(x), \pi(y)) \leq C(d(x, y))^\alpha, \forall x, y \in \Sigma_A$, where d_M denotes the metric on M .

Let $S_i = \{\phi_t\pi(x) | x_0 = i, 0 \leq t \leq r(x), i = 1, \dots, k.\}$ Clearly $A = \bigcup_{i=1}^k S_i$ since π is surjective.

Associated to each S_i is a partition \mathcal{F}_i^{ss} . We take each element of \mathcal{F}_i^{ss} to be a set $W_\varepsilon^{ss}(x) \cap S_i$, where $x \in S_i$ and $\varepsilon > 0$ is small with respect to the manifold, but large with respect to the size of the sections T_i . Each element of \mathcal{F}_i^{ss} can be written in the form $\phi_t\pi\{y \in \Sigma_A | x_n = y_n\}, 0 \leq t \leq r(x)$, where $x \in \Sigma_A$ with $x_0 = i$.

In the special case that M is a three dimensional manifold the boundaries ∂T_i (and hence the boundaries ∂S_i) take a special form. Each of the discs D_i is two dimensional and T_i is a “rectangle” whose one dimensional sides lie in either strong stable or weak unstable leaves. We can assume that there are only finitely many orbits (which must therefore all be closed) which are confined to $\bigcup_i \partial S_i$ for all time.

This only requires a slight modification to the construction in [4] (and in particular the lemma on p. 456). We need only require that the projection of strong stable manifolds onto each rectangle T_i should be carried forward into the *interior* of rectangles sufficiently far in the future, and similarly for unstable manifolds projected onto T_i on flowing backwards in time. Bowen first constructs a Markovian cover and then refines it to a Markov partition. The additional property described above is preserved under this procedure. Thus the forward image of the unstable part of the boundaries ∂T_i eventually meet $\bigcup_i \partial T_i$ transversely, i.e. in a finite set of points. Similarly for the backward images of the stable parts of the boundaries.

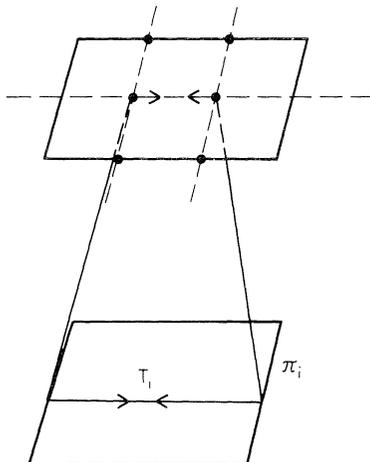


Fig. 1

Remark. A slightly different system to Axiom A flows are expanding semi-flows: Let $\phi_t : M \rightarrow M$ ($t \geq 0$) be a semi-flow on a compact Riemannian manifold and let $TM = E^0 \oplus E^u$, where E^0 is tangent to the flow direction and for $v \in E^u$ we have $\|D\phi_t(v)\| \geq Ce^{\lambda t}\|v\|$, for some $C, \lambda > 0$. In a similar way to Axiom A flows we can construct a symbolic dynamics (involving a one-sided subshift) and adapt the analysis of this paper.

3. The Margulis Measure

In 1970 Margulis published a paper in which he constructed a transverse measure for the strong-stable foliation for an Anosov flow [13]. In this section we shall present another approach to its construction which will generalise to a construction of “transverse distributions” in the next section.

Let $\{K\}$ be the family of compact transversals to the strong-stable foliation \mathcal{F}^{ss} . Let $\nu = \{\nu_K\}_K$ be a family of Borel measures with ν_K having support on K . Let $p : K \rightarrow K'$ be a Borel isomorphism with $x, p(x) \in F_x \in \mathcal{F}^{ss}$. We call ν a *transverse measure* if $\nu_{K'}(pA) = \nu_K(A)$ for all Borel sets $A \subseteq K$.

Margulis’ approach was to construct ν as a linear functional on continuous functions f of compact support K transverse to the strong-stable foliation. He defined an equivalence relation on all such functions by $f \sim g$ if $f \circ p = g$, where $p : K' \rightarrow K$ is a homeomorphism between the supports of g and f respectively such that $p(x) \in F_x$ where $x \in F_x \in \mathcal{F}^{ss}$. Margulis constructed a linear functional ν such that $\nu(f) = \nu(g)$ whenever $f \sim g$.

We shall now reconstruct this linear functional using symbolic dynamics. Much of this approach is implicit in [6].

To avoid confusion we shall restrict ourselves to the case of transitive three dimensional Anosov flows throughout the rest of this section. However, most of the analysis works in greater generality.

We construct a new space Σ_A^+ defined by

$$\Sigma_A^+ = \left\{ x \in \prod_0^\infty \{1, \dots, k\} \mid A(x_n, x_{n+1}) = 1 \text{ for } n \geq 0 \right\}$$

and a *shift* $\sigma : \Sigma_A^+ \rightarrow \Sigma_A^+$ by $(\sigma x)_n = x_{n+1}$, $n \geq 0$ (we have retained the same notation as for $\sigma : \Sigma_A \rightarrow \Sigma_A$ defined in the preceding section).

We define a metric on Σ_A^+ by $d(x, y) = \sum_{n=0}^{+\infty} \frac{e(x_n, y_n)}{2^n}$, where

$$e(i, j) = \begin{cases} 1 & \text{if } i \neq j \\ 0 & \text{if } i = j \end{cases}$$

With this metric Σ_A^+ is a compact, zero-dimensional space and $\sigma : \Sigma_A^+ \rightarrow \Sigma_A^+$ is a local homeomorphism.

Given $\alpha > 0$ let $\mathcal{H}^\alpha = \mathcal{H}^\alpha(\Sigma_A^+, \mathbb{C})$ denote those functions $f : \Sigma_A^+ \rightarrow \mathbb{C}$ which are Hölder continuous with Hölder exponent α . This function space becomes a Banach algebra with respect to the norm.

$$\|f\| = \|f\|_\infty + \sup \left\{ \frac{|f(x) - f(y)|}{[d(x, y)]^\alpha} \mid x \neq y \right\}.$$

(The first term on the right-hand side is the supremum norm, and the second is the best Hölder constant for the exponent α .)

Recall that $r: \Sigma_A \rightarrow \mathbb{R}$ was a function determined by its future co-ordinates [i.e. $r(x) = r(y)$ if $x_n = y_n$ for $n \geq 0$] and therefore it can be considered as an element of $C(\Sigma_A^+, \mathbb{R})$. In fact, $r \in \mathcal{H}^\alpha$ also, for an appropriate choice of $\alpha > 0$ [4].

Let $h > 0$ be the topological entropy of the flow $\phi_t: M \rightarrow M$. We assume the matrix A to be aperiodic.

We define the Ruelle operator $L_{hr}: \mathcal{H}^\alpha \rightarrow \mathcal{H}^\alpha$ by

$$(L_{hr}g)(\underline{x}) = \sum_{y: \sigma^v y = \underline{x}} g(y) \exp -hr(y).$$

This is a bounded linear operator with a dual operator $L_{hr}^*: (\mathcal{H}^\alpha)^* \rightarrow (\mathcal{H}^\alpha)^*$ given by $(L_{hr}^*l)(g) = l(L_{hr}g)$. We summarise some of its relevant properties in the following proposition.

Proposition 2 (Ruelle Operator Theorem) (cf. [23, Sect. 5]).

- (i) L_{hr} has an eigenvalue at 1 with a strictly positive eigenvector in \mathcal{H}^α .
- (ii) The rest of spectrum of L_{hr} is contained in a disc of strictly smaller radius than 1.
- (iii) There exists a (positive) measure μ such that $L_{hr}^*\mu = \mu$.

There are some slight differences between the statement above and the usual version. However, the form that Proposition 2 takes can be easily derived from [23]. [In particular, to show part (i) we need only invoke Abramov's theorem.]

Corollary 2.1. $d\mu\sigma/d\mu = \exp hr$.

Proof. Given $\underline{x} \in \Sigma_A^+$ we let $C_n = \{z | x_i = z_i, 0 \leq i \leq n-1\}$ and let χ_{C_n} be the characteristic function for C_n . Then,

$$\begin{aligned} \mu(C_n) &= \int \chi_{C_n}(z) d\mu(z) \\ &= \int (L_{hr}\chi_{C_n})(z) d\mu(z) \\ &= \int \sum_{i: A(i, z_0)=1} \chi_{C_n}(iz) \cdot \exp -hr(iz) d\mu(z), \end{aligned}$$

where iz denotes the sequence $(i, z_0, z_1, z_2, \dots)$. By the continuity of r we have that for all $\varepsilon > 0$ we can find $N > 0$ so that

$$\mu(\sigma C_n) e^{-(hr(\underline{x}) + \varepsilon)} \leq \mu(C_n) \leq \mu(\sigma C_n) e^{-(hr(\underline{x}) - \varepsilon)}$$

for $n \geq N$. (Here $\sigma C_n = \{z | x_{i+1} = z_i, 0 \leq i \leq n-1\}$.) Thus $(d\mu\sigma/d\mu)(x) = \exp hr(x)$ by letting $\varepsilon \rightarrow 0$.

Recall that we can cover M with compact sets S_i each equipped with a partition \mathcal{F}_i^{ss} constructed using the strong stable foliation.

Let $S_i^+ = \{(x, t) \in \Sigma_A^+ \times \mathbb{R} | x_0 = i, 0 \leq t \leq r(x)\}$. We define a map $\pi_i^+: S_i^+ \rightarrow S_i / \sim$ by $\pi_i^+(x, t) = [\pi(\hat{x}, t)]$, where $x \sim y$ if x and y are in the same element of \mathcal{F}_i^{ss} , $[\]$ is an equivalence class in S_i , and $\hat{x} \in \Sigma_A$ is any element with $\hat{x}_n = x_n$ for $n \geq 0$.

Let $S^+ = \bigcup_{i=1}^k S_i^+$ and define $\pi^+: S^+ \rightarrow \prod_{i=1}^k S_i / \sim$ by $\pi^+|_{S_i^+} = \pi_i^+$.

Let K be a compact transverse section to F^{ss} which supports a continuous (real-valued) function f . We shall assume initially that K lies in some leaf of the strong-stable foliation, i.e. $K \subseteq W^{wu}(x)$ for some $x \in M$.

Let $K_i = K \cap S_i$, $i = 1, \dots, k$. We shall assume that the weak unstable manifold $W^{wu}(x)$ containing K satisfies $W_e^{wu}(z) \cap S_i = \overline{W_e^{wu}(z) \cap \text{int} S_i}$ for $z \in W^{wu}(x) \cap S_i$, $i = 1, \dots, k$. This is certainly true for a dense family of weak unstable leaves $W^{wu}(x)$. There is a natural map $q_i: K_i \rightarrow S_i / \sim$. Without loss of generality we can assume that K is sufficiently small (on the scale of the manifold M) that each q_i is injective.

We define $\hat{f}: S^+ \rightarrow \mathbb{R}$ by $\hat{f}(x, t) = f \circ q_i^{-1} \circ \pi^+(x, t)$ if $q_i^{-1} \pi^+(x, t) \in K_i$ and $\hat{f}(x, t) = 0$ otherwise. Choose $0 < T < \text{infr}$. Define a linear functional on pairs (f, K) by

$$v(f) = \int_{\Sigma_A^+} \int_0^{r(x)} \hat{f}(x, t) e^{-ht} dt d\mu(x). \tag{3.1}$$

Observe that

$$\int_0^{r(x)} \hat{f}(x, t) e^{-ht} dt = \int_0^{r(x)-T} \hat{f}(x, t) e^{-ht} dt + \sum_{i=1}^k \int_{r(x)-T}^{r(x)} \chi_i(x) \hat{f}(x, t) e^{-ht} dt$$

(where χ_i is the characteristic function for $\{x \in \Sigma_A^+ | x_0 = i\}$)

$$\begin{aligned} &= e^{hT} \int_T^{r(x)} \hat{f}(x, t-T) e^{-ht} dt \\ &\quad + e^{hT} e^{-hr(\varrho_j x)} \sum_{i=1}^k \sum_{A(j,i)=1}^T \int_0^T \chi_i(x) \hat{f}(\varrho_j x, r(\varrho_j x) - T + t) e^{-ht} dt, \end{aligned} \tag{3.2}$$

where $\varrho_j: \Sigma_A^+ \rightarrow \{x \in \Sigma_A^+ | x_0 = j\}$ is the local inverse to the shift σ .

For brevity we shall write $\hat{f}^{\hat{0}}(x) = \int_T^{r(x)} \hat{f}(x, t-T) e^{-ht} dt$ and

$$\hat{f}^i(x) = \int_0^T \chi_i(\sigma x) \hat{f}(x, r(x) - T + t) e^{-ht} dt.$$

Then (3.2) becomes $e^{-ht} \left(\hat{f}^{\hat{0}}(x) + \sum_{i=1}^k L_{hr} \hat{f}^i(x) \right)$. Therefore we can rewrite (3.1) as

$$e^{hT} \left(\hat{f}^{\hat{0}}(x) + \sum_{i=1}^k L_{hr} \hat{f}^i(x) \right).$$

Finally we have that

$$v(f) = e^{hT} \int_{\Sigma_A^+} \left(\hat{f}^{\hat{0}}(x) + \sum_{i=1}^k L_{hr} \hat{f}^i(x) \right) d\mu(x) = e^{hT} \int_{\Sigma_A^+} \left(\hat{f}^{\hat{0}}(x) + \sum_{i=1}^k \hat{f}^i(x) \right) d\mu(x), \tag{3.3}$$

since by Proposition 2 (iii) we have that $\int_{\Sigma_A^+} L_{hr} \hat{f}^i d\mu = \int_{\Sigma_A^+} \hat{f}^i d\mu$. By the additional assumption we put on $W^{wu}(x)$ (the weak-unstable leaf containing both K and $\phi_T K$) we have that

$$\int_0^{r(x)} \hat{f} \phi_{-T}(x, t) e^{-ht} dt = \hat{f}^{\hat{0}}(x) + \sum_{i=1}^k \hat{f}^i(x),$$

and so by (3.3) we have that $v(f) = e^{hT}v(f\phi_{-T})$. [By replacing f by $f\phi_T$ gives $v(f\phi_T) = e^{hT}v(f)$.]

To extend this to arbitrary $t > 0$ choose $T = t/n < \inf r$, for a sufficiently large positive integer n . Then $v(f\phi_t) = v(f\phi_{nT}) = e^{hT}v(f\phi_{(n-1)T})$. The result follows by induction.

We want to show that for $f \sim g$ then $v(f) = v(g)$. If $p: K' \rightarrow K$ is a homeomorphism with $x, p(x) \in S_i \cap W_\varepsilon^{ss}(x)$ [for some $i = i(x)$] then this is clearly true by the construction. More generally we proceed as follows. Since we have assumed that M is three dimensional there are at most a finite number of (closed) orbits intersecting $\bigcup_{i=1}^k \partial T_i$. Furthermore since π is bounded to one these correspond to a finite number N , say, of sequences $\{x^{(i)}\}_{i=1}^N$ in Σ_A^+ . For each $i = 1, \dots, N$ let

$$C^i = C^i(Q) = \{z \in \Sigma_A^+ | z_j = x_j^{(i)} \text{ for } j = 1, \dots, Q\} \quad \text{and} \quad C = \bigcup_{i=1}^k C^i,$$

where Q is a large integer. The set

$$K(Q) = \bigcup_{i=1}^k q_i^{-1} \circ \pi_i^+ \{(z, t) | z \in C, 0 \leq t \leq r(x)\}$$

is a neighbourhood in K around the projection onto K of the closed orbits intersecting $\bigcup_{i=1}^k \partial T_i$. Corresponding to $f_{K(Q)}$ and $f_{K-K(Q)}$, we have

$$v(f) = \int_C \int_0^{r(x)} \hat{f}(x, t) e^{-ht} dt d\mu(x) + \int_{\Sigma_A^+ - C} \int_0^{r(x)} \hat{f}(x, t) e^{-ht} dt d\mu(x), \tag{3.4}$$

and

$$v(g) = \int_{p(C)} \int_0^{r(x)} g(x, t) e^{-ht} dt d\mu(x) + \int_{\Sigma_A^+ - p(C)} \int_0^{r(x)} g(x, t) e^{-ht} dt d\mu(x). \tag{3.5}$$

We can equate the second terms in (3.4) and (3.5). To see this let $x = \pi^+(x, t)$ and $y = \pi^+(y, s)$, where $x \notin C$ then there exists $t_0 > 0$ such that $\phi_{t_0}(x), \phi_{t_0}(y)$ both lie in the same set S_i ($i = i(x, t_0)$). This is because the orbit of x cannot always be confined to $\bigcup_{i=1}^k \partial S_i$ else it would correspond to a periodic orbit, contradicting our assumption that $x \notin C$. If x and y are sufficiently close, then when $\phi_{t_0}x \in \text{int } S_i$, say, then we can assume that $\phi_{t_0}y$ lies in the same set. Furthermore, we can choose a neighbourhood $C(x) \times (t - \varepsilon, t + \varepsilon)$ about (x, t) such that this remains true for all points in this set. By considering $\phi_{t'}C(x) \times (t - \varepsilon, t + \varepsilon)$ for a range of values of t' close to t_0 we can establish the equality of the second terms in (3.4) and (3.5) with C replaced by $C(x)$. But by a compactness argument we can cover C by only finitely many such $C(x)$. Summing gives the desired result.

It remains to deal with the first terms in (3.4) and (3.5). We shall show that these terms tend to zero as $Q \rightarrow +\infty$. Since μ is a positive measure we have

$$\left| \int_C \int_0^{r(x)} \hat{f}(x, t) e^{-ht} dt d\mu(x) \right| \leq \mu(C) \|\hat{f}\|_\infty \|r\|_\infty.$$

However, $\mu(C) \leq \mu(\sigma^Q C) \cdot (\|d\mu/d\mu\sigma\|)_\infty^Q$ which tends to zero as Q tends to infinity since by Corollary 2.1 we know that $\|d\mu/d\mu\sigma\|_\infty \leq \exp -(\text{infr}) < 1$.

The condition we imposed on $W^{wu}(x)$ is unimportant, since we have established the result on a dense set of transversals. Given a function supported on any other compact transversal we can project it onto a transversal of the form considered above (after localising with a partition of unity if necessary).

We have now established a version of the following theorem due to Margulis [13]:

Theorem 1 (Margulis). *Let $\phi_t : M \rightarrow M$ be a (three dimensional) transitive Anosov flow with topological entropy $h > 0$. There exists a transverse measure to the strong-stable foliation \mathcal{F}^{ss} of M which satisfies $\phi_t^* \nu = e^{ht} \nu$.*

Remark. If F^1 denotes the smooth 1-forms on M , then a *current* is a continuous linear map $F^1 \rightarrow \mathbb{C}$. Given a transverse measure ν there is an associated current, called the Ruelle-Sullivan current C [25], defined as follows: Choose a cover for M by interiors of the images of sets of the form $D_i^T \times D_i$, where D_i^T corresponds to a transverse section and D_i corresponds to neighbourhoods on each leaf. Assume that w_i is a smooth 1-form with support on $D_i^T \times D_i$, then we define

$$C(w_i) = \int_{D_i^T} \left\{ \int_{\{x\} \times D_i} w_i \right\} d\nu_{D_i^T}(x),$$

and extend to all smooth 1-forms using a partition of unity. (The inner integral is along leaves of the foliation and they are weighted in the outer integral by the transverse measure supported on D_i^T .) The integral on a leaf has to be with respect to an orientation. Ruelle and Sullivan showed this defines a closed current i.e. $C \circ d = 0$ (d is the exterior derivative on forms) and so we can consider $[C] \in H^2(M, \mathbb{C})$ [25]. The condition $\phi_t^* \nu = e^{ht} \nu$ gives that $\phi_t^*[C] = e^{-ht}[C]$, provided the orientation on leaves is respected by ϕ_t . However, since ϕ_t is homotopic to the identity we have that, for $t > 0$, e^{-ht} cannot be an eigenvalue of ϕ_t^* and we conclude that $[C] = 0$.

Following Schwartzman [26] (as interpreted by Sullivan [28]) we have the following: Given $x \in D$ let α be a loop formed by a segment of the foliation leaf starting at x of length L and with the ends linked by a geodesic. This gives $[\alpha_L] \in H_1(M, \mathbb{R})$. For $a \cdot a \cdot (\nu)x \in D$ we have $[\alpha_L] \rightarrow 0$ (corresponding to $[C] = 0$).

4. Rates of Mixing and Margulis Distributions

In this section we shall recall some results on the rate of mixing of an Axiom A flow and describe its connection with certain generalisations of the Margulis measure.

The basic problem is as follows: Let $\phi_t : A \rightarrow A$ be a weak-mixing Axiom A flow and let $F, G : A \rightarrow \mathbb{C}$ be Hölder continuous and let m be the maximal measure. It is known that $\int F \phi_t \cdot G dm \rightarrow \int F dm \cdot \int G dm$ as $t \rightarrow +\infty$. We want to describe the rate of this convergence

We set

$$\varrho(t) = \begin{cases} \int F_t \cdot G dm - \int F dm \cdot \int G dm & \text{for } t \geq 0 \\ 0 & \text{for } t \leq 0 \end{cases}$$

and approach the problem by studying its Fourier transform $\hat{\varrho}(s) = \int_{-\infty}^{+\infty} e^{ist} \varrho(t) dt$. One result in this direction is the following:

Proposition 3 [16, 21]. *The function $\hat{\varrho}(s)$ has a meromorphic extension to a half-plane $\text{Im}(s) > -c$ (for some $c > 0$).*

The behaviour of $\varrho(t)$ is considerably influenced by the domain of $\hat{\varrho}(s)$ and, in particular, by the location of its poles. These in turn are closely related to the Ruelle operator through the symbolic dynamics.

For $z \in \mathbb{C}$ we have the Ruelle operator $L_{zr} : \mathcal{H}^\alpha \rightarrow \mathcal{H}^\alpha$, where \mathcal{H}^α denotes the Banach algebra of α -Hölder continuous complex valued functions $f : \Sigma_A^+ \rightarrow \mathbb{C}$.

The following proposition was proved in [17].

Proposition 4 (Complex Ruelle Operator Theorem). *There exists $C > 0$ such that for $\text{Re}(z) > h - C$ the essential spectrum of $L_{zr} : \mathcal{H}^\alpha \rightarrow \mathcal{H}^\alpha$ is contained in the disc $\{w \in \mathbb{C} \mid |w| < 1\}$.*

We recall that the essential spectrum of an operator is that part of the spectrum that remains after removing isolated eigenvalues of finite multiplicity which correspond to finite dimensional eigenspaces.

The relationship between the poles for $\hat{\varrho}(s)$ and the spectrum of the operator L_{zr} is given by the following (cf. [16, 21]).

Proposition 5. *If we write $z = h - i$ is then the following are equivalent in the range $\text{Im}(s) > -c$ (for some $c > 0$).*

- (a) *For $z = z_0$, 1 is in the spectrum of $L_{zr} : \mathcal{H}^\alpha \rightarrow \mathcal{H}^\alpha$ (and $\lambda_i(z_0) = 1$ is an isolated eigenvalue of multiplicity $m \geq 1$).*
- (b) *For $s = s_0$, $\hat{\varrho}(s)$ has a pole.*

As before we shall now confine our attention to three dimensional transitive Anosov flows.

An important feature of Anosov flows is that the strong stable foliation \mathcal{F}^{ss} is Hölder continuous. We shall assume that the Hölder exponent is 1.

Let F be a complex valued function which is compactly supported on a weak unstable leaf $W^{wu}(x)$. Furthermore we assume that F is α -Hölder continuous. We shall call two functions F, G related if there exists a homeomorphism $p : K' \rightarrow K$ between the compact supports of F and G with $F \circ p = G$ such that if $x \in F_x \in \mathcal{F}^{ss}$ then $p(x) \in K' \cap W_e^{ss}(x)$. We shall call a linear functional ν on such functions a “transverse distribution” if $\nu(F) = \nu(G)$ whenever $F \sim G$. (We should observe that if we want all related functions to have the same Hölder exponent it will generally be necessary to assume that the Hölder exponent of the strong-stable foliation is unity.)

Given F as above we define $\hat{F} : \{(x, t) \in \Sigma_A^+ \times \mathbb{R} \mid 0 \leq t \leq r(x)\} \rightarrow \mathbb{C}$ as in the previous section. We then define $f \in \mathcal{H}^\alpha(\Sigma_A^+, \mathbb{C})$ by $f(x) = \int_0^{r(x)} \hat{F}(x, t) e^{zt} dt$, where $z \in \mathbb{C}$.

Assume that 1 is an isolated eigenvalue for $L_{zr} : \mathcal{H}^\alpha \rightarrow \mathcal{H}^\alpha$ with $L_{zr}^* \mu = \mu$, with $\mu \in [\mathcal{H}^\alpha(\Sigma_A^+, \mathbb{C})]^*$.

Without loss of generality we shall assume, as in the previous section, that $W_z^{\text{wu}}(z) \cap S_i = \overline{W_z^{\text{wu}}(z)} \cap \text{int} S_i$ for $z \in K \cap S_i$. Under these conditions we define $v(F) = \mu(f)$.

Let $0 < T < \text{infr}$.

Let $g(x) = \int_0^{r(x)} \widehat{F} \phi_T e^{zt} dt$, then

$$g(x) = \int_0^{r(x)} \widehat{F} \phi_T(x, t) e^{zt} dt = \int_T^{r(x)} \widehat{F}(x, t - T) e^{zt} dt \\ + \sum_i \sum_{A(j, \bar{i})=1}^T \int_0^T \chi_i(x) \widehat{F}(Q_j x, r(Q_j x) - T + t) e^{zt} dt$$

(where χ_i is the characteristic function for $\{x | x_0 = i\}$ and $Q_j : \{x | x_0 = j\} \rightarrow \Sigma_A^+$ is the local inverse to $\sigma : \Sigma_A^+ \rightarrow \Sigma_A^+$). Therefore:

$$g(x) = e^{zT} \int_0^{r(x)-T} \widehat{F}(x, t) e^{zt} dt \\ + \sum_i \sum_{A(j, \bar{i})=1} \left\{ \int_{T-r(Q_j x)}^{r(Q_j x)} \chi_i(x) \widehat{F}(Q_j x, t) e^{zt} dt \right\} e^{zT} e^{-zr(Q_j x)} \\ = e^{zT} \left[f^0(x) + \sum_i \sum_{A(j, \bar{i})=1} f^i(Q_j x) e^{-zr(Q_j x)} \right]$$

[where $f^0(x) = \int_0^{r(x)-T} \widehat{F}(x, t) e^{zt} dt$; $f^i(y) = \int_{T-r(y)}^{r(y)} \chi_i(\sigma y) \widehat{F}(y, t) e^{zt} dt$]. In particular, $g(x) = e^{zT} (f^0(x) + \sum_i L_{sr} f^i(x))$ and

$$\mu(g) = e^{zT} \left(\mu(f^0) + \sum_i \mu(f^i) \right) = e^{zT} \cdot \mu \left(f^0 + \sum_i f^i \right) = e^{zT} \cdot \mu(f).$$

Thus we may conclude that $v(F \phi_T) = e^{zT} \cdot v(F)$.

The argument to show that related functions F and G give the same value $v(F) = v(G)$ follows the same lines as the proof for the Margulis measure in the previous section. The only additional feature is in proving that the contribution to $\mu(f)$ and $\mu(g)$ “from C^i ” are the same. Assume that $f(x^i) = 0$. Since f is Holder continuous we have $\|f|_{C^i}\|_\infty \rightarrow 0$ as $Q \rightarrow +\infty$. Furthermore we have that μ is a bounded linear functional on $\mathcal{H}^{\alpha'}(\Sigma_A^+, \mathbb{C})$ for some $\alpha' < \alpha$. (Changing the exponent α has the effect of changing the constant c in Proposition 3.) If $\|\cdot\|_\alpha$ and $\|\cdot\|_{\alpha'}$ are the corresponding Holder semi-norms on for the spaces of Holder continuous functions with exponents α and α' , respectively, then $\|f|_{C^i}\|_{\alpha'} \leq \|f\|_{\alpha} (\frac{1}{2})^{(\alpha-\alpha')Q}$. Thus $|\mu(f|_{C^i})| \leq \|\mu\|_{\alpha'} (\|f|_{C^i}\|_{\alpha'} + \|f|_{C^i}\|_\infty) \rightarrow 0$ as $Q \rightarrow +\infty$. Hence $v(F) = v(G)$.

If $f(x^{(i)}) \neq 0$ then we replace f by $f - f(x^{(i)})$. The limit then becomes $f(x^{(i)})\mu(1)$, and so again the expressions $v(F)$ and $v(G)$ can be seen to be the same by taking limits.

As before we can remove the condition on $W^{\text{wu}}(x)$ by projecting onto one of the dense family of leaves satisfying this condition. (Again we note that unless we assume that the Holder coefficient for the strong-stable foliation is unity then this may involve a modification in the exponent.)

We summarize below

Theorem 2. *Let $\phi_t: M \rightarrow M$ be a three dimensional Anosov flow whose strong stable foliation has Holder exponent unity. If $s = s_0$ is a pole for the complex function $\hat{q}(s)$ (for $\text{Im}(s) > -C$, say) then there exists a linear functional v on the class of α -Holder continuous transverse functions, for $\alpha \leq 1$, such that $\phi_t^* v = e^{zt} v$, where $z = h - is$ (i.e. a transverse distribution).*

By analogy with the case of Margulis measures we call the transverse distributions in the above theorem *Margulis Distributions*.

The assumption that the foliations should have Holder exponent unity will not prove necessary in applications, since we shall generally need to deal with a finite family of transversals. We should remark that it is true for geodesic flows for surfaces of strictly negative curvature where the foliation is even C^1 .

5. Location of Poles

We have analysed the meromorphic domains of Fourier transforms of correlation functions (for the maximal measure) and characterised the poles in terms of transverse Margulis distributions. We now want to use this to get concrete information on the location of poles during this section and the next. Let $\phi_t: M \rightarrow M$ be a transitive three dimensional Anosov Flow.

Let v be a C^α Margulis distribution transverse to the strong-stable foliation \mathcal{F}^{ss} . The Banach space of complex C^α -forms tangent to the foliation will be denoted by C_s^α , and let $(C_s^\alpha)^*$ denote its dual. We want to define an element m in $(C_s^\alpha)^*$ using the Margulis distribution v . Given a C^1 -form w tangent to the foliation, assume that w has support (as in Sect. 3) on $D^T \times D$, where D^T supports the transverse distribution v_D . We have a C^α -function defined on D^T by $x \rightarrow \int_{D \times \{x\}} w$, i.e. integrating the form across the leaf $D \times \{x\}$. We define $m \in (C_s^\alpha)^*$ by

$$m(w) = \int_{D^T} \left\{ \int_{D \times \{x\}} w \right\} dv_{D^T}(x)$$

and a C^∞ -partition of unity. (This definition is obviously motivated by the Ruelle-Sullivan current.) The bundles E^u and E^s are automatically oriented and so $x \rightarrow \int_{D \times \{x\}} w$ can be defined with a consistent choice of sign.

By definition we know that $\phi_t^* v = e^{zt} v$. We therefore have that $\phi_t^* m = e^{-zt} m$, i.e. m is an eigenfunction for $\phi_t^*: (C_s^\alpha)^* \rightarrow (C_s^\alpha)^*$ with eigenvalue e^{-zt} . (We shall assume that $t > 0$ is fixed throughout this argument.)

We know that $\phi_t^*: (C_s^\alpha)^* \rightarrow (C_s^\alpha)^*$ is the dual operator to the ϕ_t -induced operator $\phi_{t*}: C_s^\alpha \rightarrow C_s^\alpha$, and as such shares the same spectrum. We then conclude that e^{-zt} lies in the spectrum of $\phi_{t*}: C_s^\alpha \rightarrow C_s^\alpha$. We state this as a theorem:

Theorem 3. *Let $\phi_t: M \rightarrow M$ be a transitive three dimensional Anosov flow and let $\phi_{t*}: C_s^\alpha \rightarrow C_s^\alpha$ be the induced operator on C^α -forms tangent to the strong stable foliation.*

There exist $C, \alpha > 0$ such that if $s = s_0$, $\text{Im}(s) > -c$, is a pole for $\hat{q}(s)$ (with respect to the maximal measure), then $e^{-z_0 t}$ is in the spectrum of ϕ_{t} , where $z_0 = h - is_0$. (There is a similar version of this result for $\phi_{-t*}: C_u^\alpha \rightarrow C_u^\alpha$ for the unstable foliation.)*

Let $\phi_t: M \rightarrow M$ be an Anosov flow for which spectrum of $\phi_{t*}: C_s^z \rightarrow C_s^z$ is contained in a single circle. We call such a flow *homogeneous*. Examples of homogeneous flows are geodesic flows on surfaces of constant negative curvature and suspensions by constant functions of hyperbolic toral automorphisms $f: T^2 \rightarrow T^2$. To see this we have only to apply the standard equation on the transformation of forms under the action of a diffeomorphism. This corresponds to scalar multiplication by $\exp ht$ and the result follows from the spectral radius theorem.

A flow is weak-mixing if there are no non-trivial solutions to the equation $F(\phi_t) = e^{iat}F$, with $a > 0$ and $F \in C(M)$.

A direct application of Theorem 3 gives:

Corollary 3.1. *For any homogeneous weak-mixing flow, $\hat{q}(s)$ is analytic for $\text{Im}(s) > -C$ (for some $C > 0$).*

This result is known already for geodesic flows on surfaces of constant negative curvature (cf. [20]).

6. Geodesic Flows

In this section we restrict our attention to the very important case of geodesic flows on manifolds of negative (sectional) curvature.

Let M be a compact manifold with Riemannian metric \langle, \rangle of negative sectional curvatures. We define a geodesic flow on the unit tangent bundle in the usual way: Given $(x, v) \in R_1M$, let $\gamma: \mathbb{R} \rightarrow M$ be the unique unit speed geodesic through x in the direction v at time $t=0$ [i.e. $\gamma(0) = x, \dot{\gamma}(0) = v$] then set $\phi_t(x, v) = (\gamma(t), \dot{\gamma}(t))$. This defines the geodesic flow $\phi_t: T_1M \rightarrow T_1M$.

To understand better $D\phi_t: T(T_1M) \rightarrow T(T_1M)$ we follow Eberlein [9]. The map $\pi: TM \rightarrow M, \pi(x, v) = x$ gives the derivative $D\pi: T_{(x, v)}(TM) \rightarrow T_xM$. We can construct a second linear map $K: T_{(x, v)}(TM) \rightarrow T_xM$ by first choosing for $\xi \in T_{(x, v)}(TM)$ a curve $Z: (-\varepsilon, \varepsilon) \rightarrow TM$ tangent to ξ at time $t=0$. We then have a curve $\alpha = \pi \circ Z: (-\varepsilon, \varepsilon) \rightarrow M$ and set $K\xi = \nabla_\alpha Z$, i.e. the covariant derivative of Z along α at time $t=0$. It is known that for all $(x, v) \in TM$ we can decompose $T_{(x, v)}(TM)$ as $T_{(x, v)}(TM) = (\text{Ker } D\pi) \oplus (\text{Ker } K)$. The Riemannian metric \langle, \rangle_x for M then prompts the definition of a metric for TM by $\langle \xi, \eta \rangle_{(x, v)} = \langle D\pi\xi, D\pi\eta \rangle_x + \langle K\xi, K\eta \rangle_x$, for $\xi, \eta \in T_{(x, v)}(TM)$. We proceed to consider the evolution of the flow ϕ_t . For every point $(x, v) \in TM$ we have an associated geodesic γ with $\gamma(0) = x$ and $\dot{\gamma}(0) = v$. Given any $\xi \in T_{(x, v)}(TM)$ we associate with it the Jacobi field Y_ξ on γ such that $Y_\xi(x) = D\pi\xi, \nabla_\alpha Y(x) = K\xi$. This map $\xi \rightarrow Y_\xi$ gives a linear isomorphism from $T_{(x, v)}(TM)$ to the Jacobi fields on γ [for (x, v)]. The map $D\phi_t: T(TM) \rightarrow T(TM)$ is related to this geometric construction by: $D\pi D\phi_t(\xi) = Y_\xi(\gamma(t))$ and $DK D\phi_t(\xi) = (\nabla_\gamma Y_\xi)(\gamma(t))$.

To understand this characterisation of $D\phi_t$, we consider the following view of Jacobi fields (due to Green [10]). For the geodesic γ let $e_1(t), \dots, e_n(t)$ be a system of parallel orthonormal vector fields along γ with γ tangent to $e_n(t)$ at $t=0$. (This is called an *adapted frame field*.) A vector field Y on γ can be identified with $(n-1)$ -tuple $(y_1(t), \dots, y_{n-1}(t))$ of C^∞ functions $y_i: \mathbb{R} \rightarrow \mathbb{R}$, where $Y(t) = \sum_i y_i(t)e_i(t)$. The covariant derivative becomes $\nabla_\gamma Y = \sum_i y_i'(t)e_i(t) = Y'(t)$.

Let R be the curvature tensor for M (i.e. $R(X, Y)Z = [V_x Y, V_Y X]Z - V_{[X, Y]}Z$), then we can define an $(n - 1) \times (n - 1)$ matrix $R(t) = (R_{ij}(t))$ by

$$R_{ij}(t) = \langle R(e_n(t), e_i(t))e_n(t), e_j(t) \rangle .$$

A perpendicular Jacobi vector field on γ is defined by $t \rightarrow Y(t)x$, where $x \in \mathbb{R}^{n-1}$ and $Y(t)$ is a solution of the matrix differential equation

$$Y''(t) + R(t)Y(t) = 0 .$$

[For a surface this reduces to a single differential equation where $R(t)$ is the curvature at $\gamma(t)$.]

We can conclude from the above that smooth changes in the metric will cause a smooth change in the operator $D\phi_t: T(T_1 M) \rightarrow T(T_1 M)$ and $\phi_{t*}: C^\alpha \rightarrow C^\alpha$ for the associated geodesic flows. (Here a Riemannian metric is a smooth section in the fibre bundle of positive definite inner products for the tangent space. A smooth change in the topology of sections should correspond to a smooth change in the curvature tensor and so to a smooth change in the Jacobi vector fields. Similarly a smooth change in the metric should give a smooth change in the derivative of the Jacobi vector fields. Together these induce a smooth change in $D\phi_t$ by the decomposition described above.) When the manifolds have constant sectional curvatures $K = -k^2$, then the flow is homogeneous and the spectrum is contained in a circle of radius $\exp -tk$. For smooth perturbations in the metric the spectrum of $\phi_{t*}: C_s^\alpha \rightarrow C_s^\alpha$ is contained in an annulus with inner and outer radii close to $\exp -ht$ [where $h = h(\phi)$ is the topological entropy of the flow].

We may assume that the width of the meromorphic extension is constant (since the factors that determine this – the roof function, the expansiveness of the flow, and the geometric constraints on the transverse sections – vary continuously with the metric cf. [17]). Together these two observations give the following.

Theorem 4. *Let \langle , \rangle be a metric of constant negative (sectional) curvature on a compact manifold and let \langle , \rangle' be a C^∞ -close metric, then the Fourier transform of a corresponding correlation function $\hat{q}(s)$ has an analytic extension to a half-plane $\text{Im}(s) > -\delta$, for some $\delta > 0$.*

7. The Zeta Function

So far we have confined ourselves to the relationship between Margulis distributions and the Fourier transform of the correlation function. This analysis is squarely based on the connection of the spectrum of the Ruelle operator with the meromorphic domain of the Fourier transform. However, there is a parallel theory for the meromorphic extension of a certain zeta function associated with the Axiom A flow. Here the poles are again determined by the spectrum of the zeta function [17]. We shall now turn our attention to the relationship between this zeta function and Margulis distributions.

Let $\phi_t: M \rightarrow M$ be an Axiom A flow and let A be an attractor. For each closed orbit τ we denote its least period by $\lambda(\tau)$. We define the *zeta function* for ϕ by

$$\zeta(s) = \prod_{\tau} (1 - \exp -s\lambda(\tau))^{-1} ,$$

where $s \in \mathbb{C}$. (The Euler product converges to a non-zero, analytic function for $\text{Re}(s) > h$ [24].) We know the following about the domain of $\zeta(s)$:

Proposition 6 [17]. *The zeta function $\zeta(s)$ has a non-zero meromorphic extension to a half-plane $\text{Re}(s) > h - c$, for some $c > 0$. Furthermore, $s = s_0$ is a pole for $\zeta(s)$ if and only if 1 is an eigenvalue for $L_{-s_0r} : \mathcal{H}^\alpha \rightarrow \mathcal{H}^\alpha$, for some $\alpha > 0$.*

The constant $c > 0$ is dictated not only by the constraints of the associated suspended flow but also by the need to take into account difficulties with closed orbits which pass through the boundaries of the transverse sections (although when $\dim M = 3$ there are only finitely many such orbits). There is a simple pole at $s = h$ which corresponds to 1 being an eigenvalue for L_{hr} , by the Ruelle operator theorem. The condition that ϕ is weak-mixing is equivalent to $\zeta(s)$ being analytic on the line $\text{Re}(s) = h$, except for $s = h$. If ϕ is not weak-mixing then $\zeta(s)$ has period ia , for some $a > 0$ [14].

Parallel to Theorem 3 for correlation functions we have the following:

Theorem 5. *Let $\phi_t : M \rightarrow M$ be a transitive three dimensional Anosov flow and let $\phi_{t*} : C_s^\alpha \rightarrow C_s^\alpha$ be the induced operator on C^α -forms along the stable manifold. There exists $c > 0$, such that if $s = s_0$, with $\text{Re}(s) > h - c$, is a pole for $\zeta(s)$, then $e^{-s_0 t}$ is in the spectrum of ϕ_{t*} .*

The usefulness of this theorem depends on our information on the spectrum of ϕ_{t*} as before. Corresponding to Corollary 3.1 we have:

Corollary 5.1. *For any homogeneous flow $\zeta(s)$ is analytic for $\text{Re}(s) > h - c$ (for some $c > 0$), except for a simple pole at $s = h$ if ϕ is weak-mixing or simple poles at $h + nia$ ($n \in \mathbb{Z}$) if ϕ is not weak-mixing.*

This is applicable to geodesic flows for surfaces of constant negative curvature and constant suspensions of hyperbolic toral automorphisms.

The most interesting case is that of the geodesic flow. In this context we have the following:

Theorem 6. *Let \langle , \rangle be a metric of constant negative curvature on a compact surface. For geodesic flows corresponding to metrics $\langle , \rangle' \in C^\infty$ close to \langle , \rangle we have that $\zeta_{\langle , \rangle'}(s)$ is analytic in a half plane $\text{Re}(s) > h - c$, except for a simple pole at $s = h$, for some $c > 0$ (where h is the entropy of the geodesic flow for \langle , \rangle').*

The case of constant curvature surfaces has been extensively studied cf., for example, [11].

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