# Time-Ordered Products and Schwinger Functions 

J.-P. Eckmann* and H. Epstein<br>Institut des Hautes Etudes Scientifiques, F-91440 Bures-sur-Yvette, France


#### Abstract

It is shown that every system of time-ordered products for a local field theory determines a related system of Schwinger functions possessing an extended form of Osterwalder-Schrader positivity and that the converse is true provided certain growth conditions are satisfied. This is applied to the $\varphi_{3}^{4}$ theory and it is shown that the time-ordered functions and $S$-matrix elements admit the standard perturbation series as asymptotic expansions.


## I. Introduction

The present paper is a sequel to [EEF], in which some of the existing models of field theories in 2 space-time dimensions were considered. In order to study the dependence of the $S$-matrix on the coupling constant, time-ordered functions were constructed in a natural way, by taking essential advantage of the local integrability of the Schwinger functions. (This very property served to define the Schwinger functions as distributions defined everywhere, including coinciding points.) In other models, more singular Schwinger functions occur, and the method of [EEF] cannot be applied. In this paper, a general discussion of the connection between Schwinger functions and time-ordered products is given and applied to the $\varphi_{3}^{4}$ theory. We show that any Wightman theory equipped with timeordered products possesses Schwinger functions (considered as distributions over the whole Euclidean world, including coinciding points) which exhibit "extended Osterwalder-Schrader positivity". Conversely, given a set of Schwinger functions possessing this extended positivity together with growth properties similar to those of [OS2], it is possible to supplement the constructions of [OS 1, OS2, G1] with a construction of time-ordered products, in a canonical manner. Finally we consider the model $\varphi_{3}^{4}$ and, starting from results accumulated in the literature [G2, GJ, Fe, FO, MS1, MS2, B, FR, C], we extend to this model the analysis of [EEF], showing in particular that the time-ordered functions and the $S$-matrix

[^0]elements are $\mathscr{C}^{\infty}$ in the coupling constant near 0 and that their Taylor series at 0 are given by standard perturbation theory.

In the remainder of this introduction we shall state the "axioms" which respectively characterize time-ordered products and Schwinger functions and the theorems relating these two notions. Sections II and III give the proofs of these theorems and in Section IV we discuss the application to $\varphi_{3}^{4}$.

## I.1. Axioms for Time-Ordered Products

(These "axioms" simply restate the standard postulates but, for reasons of convenience we take the anti-time-ordered products as the basic objects.) Here, $\mathbb{R}^{v}$ denotes the $v$-dimensional Minkowski space.

T1) Hilbert Space. $\mathscr{H}$ is a Hilbert space in which a continuous unitary representation $a^{0} \rightarrow U\left(a^{0}, \mathbf{0}\right)$ of the time translation group $\mathbb{R}$ operates. There is a normalized vector $\Omega$ (vacuum) such that $U\left(a^{0}, \mathbf{0}\right) \Omega=\Omega$ for all $a^{0} \in \mathbb{R}$.

T2) Spectrum. $U\left(a^{0}, \mathbf{0}\right)=\operatorname{expia} a^{0} P^{0}, P^{0}=H \geqq 0$.
T3) (Anti)-Time Ordered Products. There is a dense subspace $D_{0}$ of $\mathscr{H}$ containing $\Omega$ and invariant under $U\left(a^{0}, \mathbf{0}\right)$. For every $n>0$ and every $f \in \mathscr{S}\left(\left(\mathbb{R}^{v}\right)^{n}\right)$ a linear operator $\bar{T}(f)$ is defined on $D_{0}$ and $\bar{T}(f) D_{0} \subset D_{0}$. [We also write

$$
\left.\bar{T}(f)=\int \bar{T}\left(x_{1}, \ldots, x_{n}\right) f\left(x_{1}, \ldots, x_{n}\right) d^{v} x_{1} \ldots d^{v} x_{n} \cdot\right]
$$

Furthermore, for every $f \in \mathscr{S}\left(\mathbb{R}^{v n_{r}}\right)$,

$$
\begin{align*}
& \int \bar{T}\left(x_{1}, \ldots, x_{n_{1}}\right) \bar{T}\left(x_{n_{1}+1}, \ldots, x_{n_{2}}\right) \ldots \bar{T}\left(x_{n_{r-1}+1}, \ldots, x_{n_{r}}\right) \\
& f\left(x_{1}, \ldots, x_{n_{r}}\right) d x_{1} \ldots d x_{n_{r}} \psi \tag{1}
\end{align*}
$$

is defined for each $\psi \in D_{0}$, belongs to $D_{0}$, and depends continuously on $f$ in the topology of $\mathscr{S}$. It is assumed that $D_{0}$ is the subspace generated by the vectors of the form (1) with $\psi=\Omega$.
T4) Symmetry. For each $n>1, \bar{T}\left(x_{1}, \ldots, x_{n}\right)$ is symmetric, i.e. for each permutation $\pi$ of $(1, \ldots, n)$,

$$
\bar{T}\left(x_{1}, \ldots, x_{n}\right)=\bar{T}\left(x_{\pi 1}, \ldots, x_{\pi n}\right)
$$

[This will allow us to denote $\bar{T}(X)$ the distribution $\bar{T}\left(x_{j_{1}}, \ldots, x_{j_{r}}\right)$ where $X=\left\{j_{1}, \ldots, j_{r}\right\}$. We denote $\left.\bar{T}(\emptyset)=1.\right]$
T5) (Anti-) Causal Factorization. Let $X=\{1, \ldots, n\}, X=P \cup Q, P \cap Q=\emptyset$. Then (on $D_{0}$ ) the two distributions $\bar{T}(X)$ and $\bar{T}(P) \bar{T}(Q)$ coincide in the open set of $\mathbb{R}^{v n}$ given by

$$
\begin{equation*}
\left\{\left(x_{1}, \ldots, x_{n}\right) \mid \forall j \in P, \forall k \in Q, x_{j}^{0}<x_{k}^{0}\right\} . \tag{2}
\end{equation*}
$$

[We define $T(X)$ (the "time-ordered operators") through the polynomial expression

$$
\begin{equation*}
T(X)=\sum_{1 \leqq p \leqq|X|}(-1)^{|X|+p} \sum_{\left\{I_{j}\right\}}^{*} \bar{T}\left(I_{1}\right) \ldots \bar{T}\left(I_{p}\right), \tag{3}
\end{equation*}
$$

where $\sum^{*}$ runs over the set $\left\{I_{1}, \ldots, I_{p} \neq \emptyset, I_{1} \cup \ldots \cup I_{p}=X, I_{j} \cap I_{k}=\emptyset\right.$ for $\left.j \neq k\right\}$, and $T(\emptyset)=1$.

T6) Hermiticity. On $D_{0}, T(X)^{*}=\bar{T}(X)$.
T7) Time Translation Covariance. For every $f \in \mathscr{S}\left(\mathbb{R}^{v n}\right)$, every $a^{0} \in \mathbb{R}$, every $\psi \in D_{0}$, $U\left(a^{0}, \mathbf{0}\right) \bar{T}(f) U\left(a^{0}, \mathbf{0}\right)^{-1}=\bar{T}\left(f_{a}\right) \psi$ where $f_{a}\left(x_{1}, \ldots, x_{n}\right)=f\left(x_{1}-a, \ldots, x_{n}-a\right), a=\left(a^{0}, \mathbf{0}\right)$.

Remark. Most of the ensueing construction is independent of the underlying Hilbert space structure and could be done for any system of distributions having only the linear properties of ( $\left.\Omega, \bar{T}\left(X_{1}\right) \ldots \bar{T}\left(X_{n}\right) \Omega\right)$.

In relativistically invariant theories additional conditions are imposed:
T8) $U$ extends to a continuous unitary representation of the Poincare group, leaving the vacuum invariant, mapping $D_{0}$ into itself and $T 7$ ) is extended in the usual way.

## I.2. Axioms for Schwinger Functions

A system of Schwinger functions is defined to be a sequence $\left\{S_{n}\right\}_{n \in \mathbb{N}}$ of tempered distributions such that:

S1) $S_{0} \in \mathbb{C}$. For $n \geqq 1, S_{n} \in \mathscr{S}^{\prime}\left(\mathbb{R}^{v n}\right)$. Here $\mathbb{R}^{v n}$ is regarded as $\left(\mathscr{E}^{v}\right)^{n}, \mathscr{E}^{v}$ being the $v$ dimensional Euclidean space in which a special orthogonal basis ( $e_{0}, e_{1}, \ldots, e_{v-1}$ ) has been chosen. A point $y$ in $\mathscr{E}^{v}$ will be specified by its coordinates in this basis $\left(y^{0}, y^{1}, \ldots, y^{v-1}\right)$, usually denoted $\left(y^{0}, \mathbf{y}\right)$. The scalar product is given by $\sum_{j=0}^{v-1} y^{j} y^{\prime j}=y^{0} y^{\prime 0}+\mathbf{y} \mathbf{y}^{\prime}$.
$S 2) S_{n}$ is symmetric, i.e. for every permutation $\pi$ of $\{1, \ldots, n\}$ and every $f \in \mathscr{S}\left(\mathbb{R}^{v n}\right)$,

$$
S_{n}(f)=S_{n}\left(f_{\pi}\right),
$$

where $f_{\pi}\left(y_{1}, \ldots, y_{n}\right)=f\left(y_{\pi 1}, \ldots, y_{\pi n}\right)$.
S3) $S_{n}$ is invariant under Euclidean time-translations, i.e. for all $a=\left(a^{0}, \mathbf{0}\right)$, and for all $f \in \mathscr{S}\left(\mathbb{R}^{v n}\right)$, one has

$$
S_{n}(f)=S_{n}\left(f_{a}\right) .
$$

With the functional notation this reads

$$
S_{n}\left(y_{1}, \ldots, y_{n}\right)=S_{n}\left(a+y_{1}, \ldots, a+y_{n}\right), \quad\left(a=\left(a^{0}, \mathbf{0}\right)\right)
$$

S4) Extended Osterwalder-Schrader Positivity. Let $\left\{\mathrm{f}_{n}\right\}_{n=1,2, \ldots, N}$ be any finite sequence of functions such that
a) $f_{0} \in \mathbb{C}$; for $n \geqq 1, f_{n} \in \mathscr{S}\left(\mathbb{R}^{v n}\right)$.
b) For each $n \geqq 1$, the support of $f_{n}$ is contained in

$$
\left\{\left(y_{1}, \ldots, y_{n}\right) \mid y_{j}^{0} \geqq 0, \forall j=1, \ldots, n\right\}
$$

Then

$$
\begin{gathered}
\sum_{0 \leqq m, n \leqq N} \int \overline{f_{m}\left(\left(-y_{m}^{\prime 0}, \mathbf{y}_{m}^{\prime}\right), \ldots,\left(-y_{1}^{\prime 0}, \mathbf{y}_{1}\right)\right)} f_{n}\left(\left(y_{1}^{0}, \mathbf{y}_{1}\right), \ldots,\left(y_{n}^{0}, \mathbf{y}_{n}\right)\right) \\
d^{v} y_{1}^{\prime} \ldots d^{v} y_{m}^{\prime} d^{v} y_{1} \ldots d^{v} y_{n} S_{m+n}\left(y_{1}^{\prime}, \ldots, y_{m}^{\prime}, y_{1}, \ldots, y_{n}\right) \geqq 0 .
\end{gathered}
$$

In other words if for any $g \in \mathscr{S}\left(\mathbb{R}^{v n}\right)$ we denote

$$
\begin{equation*}
(\Theta g)\left(y_{1}, \ldots, y_{n}\right)=\overline{g\left(\left(-y_{n}^{0}, \mathbf{y}_{n}\right), \ldots,\left(-y_{1}^{0}, \mathbf{y}_{1}\right)\right)} \tag{4}
\end{equation*}
$$

the above condition reads

$$
\begin{equation*}
\sum_{n, m} S_{m+n}\left(\left(\Theta f_{m}\right) \otimes f_{n}\right) \geqq 0 \tag{5}
\end{equation*}
$$

Remark. The only difference between these hypotheses and the O.S. axioms is that O.S. positivity is replaced by extended O.S. positivity. As a consequence many steps in the construction of Section III. 1 are repetitions of those appearing in [OS1, OS2, G1]. They are included for the sake of logical continuity. For related, partly overlapping assumptions and developments see also [H, F, DF, GJ 2, Y]. In particular Condition $S 4$ ) appears in [H, DF, Y].

S5) Full Euclidean Invariance.
The following property will play a crucial role in the reconstruction of time ordered products.

S6) Growth Condition. There are constants $K, L, s$ such that for all $n$ and all $f_{j} \in \mathscr{S}\left(\mathbb{R}^{v}\right), j=1, \ldots, n$,

$$
\left|S_{n}\left(f_{1} \otimes \ldots \otimes f_{n}\right)\right| \leqq K^{n} n!^{L} \prod_{j=1}^{n}\left|\mathrm{f}_{j}\right|_{s}
$$

$\left[|\cdot|_{s}\right.$ denotes the Schwartz norm

$$
\left.|f|_{s}=\sup _{x, 0 \leqq|\alpha|,|\beta| \leqq s}\left|x^{\beta} D^{\alpha} f(x)\right| .\right]
$$

## I.3. Results

Two systems respectively satisfying the " $T$ " and " $S$ " axioms are naturally related if they satisfy the following condition:
$R$ ) If $f \in \mathscr{S}\left(\mathbb{R}^{v n}\right), f_{\lambda}\left(x_{1}, \ldots, x_{n}\right)=f\left(\lambda x_{1}^{0}, \mathbf{x}_{1}, \ldots, \lambda x_{n}^{0}, \mathbf{x}_{n}\right)$ for real $\lambda>0$, and if the map $\lambda \rightarrow f_{\lambda}$ can be extended to a continuous map of the angle $\{\lambda \in \mathbb{C},|\lambda|>0$, $\operatorname{Re} \lambda \geqq 0, \operatorname{Im} \lambda \geqq 0\}$ into $\mathscr{S}\left(\mathbb{R}^{v n}\right)$, analytic in the interior of this angle, then

$$
\begin{align*}
& \int i^{n} f_{i}\left(x_{1}, \ldots, x_{n}\right) S_{n}\left(x_{1}, \ldots, x_{n}\right) d^{v} x_{1} \ldots d^{v} x_{n} \\
& \quad=\int f\left(x_{1}, \ldots, x_{n}\right)\left(\Omega, \bar{T}\left(x_{1}, \ldots, x_{n}\right) \Omega\right) d^{v} x_{1} \ldots d^{v} x_{n} \tag{6}
\end{align*}
$$

Remark. The conventions of this paper differ from those of [EEF] in that
$S\left(x_{1}, \ldots, x_{n}\right)=S_{E E F}\left(-x_{1}^{0}, \mathbf{x}_{1}, \ldots,-x_{n}^{0}, \mathbf{x}_{n}\right)$.
We are now in a position to state

Theorem 1. Given a system of (anti-) time ordered products satisfying T1)-T7) one can construct a unique system of Schwinger functions satisfying $S 1$ )-S4) such that $R$ ) holds.

Conversely, one has
Theorem 2. Given a system of Schwinger functions satisfying $S 1)-S 4$ ) and the growth condition S6) one can construct a unique system of (anti-) time ordered products satisfying T1)-T7) such that R) holds.

Corollary 3. The inclusion of T8) in the assumptions of Theorem 1 implies that S5) holds in its conclusion, and conversely for Theorem 2.

Comment. Our assumptions are formulated for the case of one neutral scalar field $A(x)=\bar{T}(x)=T(x)$, but it is straightforward to extend all our considerations to the case of any number of fields with arbitrary charge, spin, and statistics. [In fact, in the application to $\varphi_{3}^{4}$ we shall need the fields $\varphi, \varphi^{2}, \varphi^{3}, \varphi^{4}$ as basic objects.] The symmetry conditions $T 4$ ) and $S 2$ ) can be recovered by considering all fields to be the components of a single object.

In Section IV we show that the Schwinger functions of the $\varphi_{3}^{4}$ theory satisfy the conditions $S 1$ )-S6).

## II. Proof of Theorem 1

## II.1. Euclidean Time-Ordered Operators

We assume that a system satisfying $T 1$ )-T7) is given. It will be useful to construct, as intermediate objects, operator valued distributions $\mathcal{O}\left(x_{1}, \ldots, x_{n}\right)$ which can formally be thought of as $\bar{T}\left(i x_{1}^{0}, \mathbf{x}_{1}, \ldots, i x_{n}^{0}, \mathbf{x}_{n}\right)$. Let $D_{1}$ be the intersection of the domains of the closures of all finite products $\bar{T}\left(f_{1}\right) \ldots \bar{T}\left(f_{N}\right)$, (initially defined on $\left.D_{0}\right)$, where $f_{j} \in \mathscr{S}\left(\mathbb{R}^{v p_{j}}\right)$. The operators $\mathcal{O}$ shall satisfy:
(1)) If $\psi \in D_{1}$, and if $f \in \mathscr{S}\left(\mathbb{R}^{v n+1}\right)$ has its support in

$$
\begin{equation*}
\left\{\left(x_{1}, \ldots, x_{n}, v\right) \in \mathbb{R}^{v n+1} \mid 0 \leqq x_{j}^{0}<v, j=1, \ldots, n\right\} \tag{7}
\end{equation*}
$$

then

$$
\int \mathcal{O}\left(x_{1}, \ldots, x_{n}\right) e^{-v H} \psi f\left(x_{1}, \ldots, x_{n}, v\right) d x_{1} \ldots d x_{n} d v
$$

is well defined, belongs to $D_{1}$ and depends continuously on $f$.
(O2) For any $f \in \mathscr{S}\left(\mathbb{R}^{v n}\right)$ and $w=u+i v \in \mathbb{C}$ with $v>0$, such that
supp. $f \subset\left\{\left(x_{1}, \ldots, x_{n}\right) \in \mathbb{R}^{v n} \mid \forall j, 0 \leqq x_{j}^{0}<v\right\}$,
and for every $\psi \in D_{1}, \mathcal{O}(f) e^{i w H} \psi$ is defined, belongs to $D_{1}$, depends continuously on $f$ and holomorphically on $w$.
(03) Symmetry. $\mathcal{O}\left(x_{1}, \ldots, x_{n}\right)=\mathcal{O}\left(x_{\pi 1}, \ldots, x_{\pi n}\right)$ for every permutation $\pi$.
[We again introduce the notation $\mathcal{O}(X)$ as for the $\bar{T}$, and we define $\mathcal{O}(\emptyset)=1]$.
(14) Time Translation. For $0 \leqq x_{j}^{0} \leqq v,(1 \leqq j \leqq n)$ and $t \geqq 0$, and all $\psi \in D_{1}$,

$$
e^{-t H} \mathcal{O}\left(x_{1}, \ldots, x_{n}\right) e^{-v H} \psi=\mathcal{O}\left(x_{1}^{\prime}, \ldots, x_{n}^{\prime}\right) e^{-(v+t) H} \psi
$$

with $x_{j}^{\prime 0}=x_{j}^{0}+t, \mathbf{x}_{j}^{\prime}=\mathbf{x}_{j}, 1 \leqq j \leqq n$, with obvious notations.
05) Factorization. In the open set $\left\{\left(y_{1}, \ldots, y_{n}\right) \in \mathbb{R}^{v n} \mid y_{j}^{0}<y_{k}^{0}\right.$ for every $j=1, \ldots, p$ and every $k=p+1, \ldots, n\}$,

$$
\mathcal{O}\left(y_{1}, \ldots, y_{n}\right)=\mathcal{O}\left(y_{1}, \ldots, y_{p}\right) \mathcal{O}\left(y_{p+1}, \ldots, y_{n}\right)
$$

as distributions, on $D_{1}$.
(06) Let $X_{1}, \ldots, X_{r}$ be any partition of $\{1, \ldots, N\}$ and let $Z_{1}, \ldots, Z_{l}$ be any partition of $\{N+1, \ldots, N+p\}$. Then, for every $f \in \mathscr{S}\left(\mathbb{R}^{v(N+p)}\right)$ having support in

$$
\left\{\left(x_{1}, \ldots, x_{N}, z_{N+1}, \ldots, z_{N+p}\right) \mid j \in X_{t}, k \in X_{s}, t<s \Rightarrow 0 \leqq x_{j}^{0} \leqq x_{k}^{0} \leqq b\right\}
$$

the vector

$$
\begin{aligned}
\Phi= & \int e^{i w_{0} H} \mathcal{O}\left(X_{1}\right) \ldots e^{i w_{r-1} H} \mathcal{O}\left(X_{r}\right) e^{\left(i w_{r}-b\right) H} \bar{T}\left(Z_{1}\right) \ldots \bar{T}\left(Z_{l}\right) \Omega \\
& f\left(x_{1}, \ldots, x_{N}, z_{N+1}, \ldots, z_{N+p}\right) d^{v} x_{1} \ldots d^{v} z_{N+p}
\end{aligned}
$$

is well-defined, is in $D_{1}$, depends holomorphically on $w_{0}, \ldots, w_{r}$ for $\operatorname{Im} w_{j}>0$, and for every $\beta$ there is a constant $C_{\beta}$ such that (for $\operatorname{Im} w_{j} \geqq 0$ ),

$$
\left\|D_{w}^{\beta} \Phi\right\| \leqq C_{\beta}(1+|w|)^{L}|f|_{L+|\beta|}
$$

where $L$ depends only on $N+p$, and where $|w|=\sum\left|w_{j}\right|$.
The operators $\mathcal{O}$ are naturally related to the operators $\bar{T}$ by the following condition:
$\left.R^{\prime}\right)$ Let $g \in \mathscr{S}\left(\mathbb{R}^{v n+1}\right)$ have support in (7) and denote, for $\lambda>0, g_{\lambda}\left(x_{1}, \ldots, x_{n}, v\right)$ $=g\left(\lambda x_{1}^{0}, \mathbf{x}_{1}, \ldots, \lambda x_{n}^{0}, \mathbf{x}_{n}, \lambda v\right)$. Assume that the map $\lambda \rightarrow g_{\lambda}$ extends to a continuous map of

$$
\begin{equation*}
\{\lambda \in \mathbb{C}||\lambda|>0, \operatorname{Re} \lambda \geqq 0, \operatorname{Im} \lambda \geqq 0\} \tag{8}
\end{equation*}
$$

into $\mathscr{S}\left(\mathbb{R}^{v n+1}\right)$, holomorphic in the interior of (8). Then for all $\psi \in D_{1}$,

$$
\begin{align*}
& \int \mathcal{O}\left(x_{1}, \ldots, x_{n}\right) e^{-v H} \psi g_{i}\left(x_{1}, \ldots, x_{n}, v\right) i^{n+1} d^{v} x_{1} \ldots d^{v} x_{n} d v \\
& \quad=\int \bar{T}\left(x_{1}, \ldots, x_{n}\right) e^{i v H} \psi g\left(x_{1}, \ldots, x_{n}, v\right) d^{v} x_{1} \ldots d^{v} x_{n} d v . \tag{9}
\end{align*}
$$

Remark. The r.h.s. of (9) makes sense.
Proof. With our choice of $D_{1}$, it is clear that $e^{i w H} \psi$ exists for every $\psi \in D_{1}$ and every $w=u+i v \in \mathbb{C}$ with $v \geqq 0$ and is in $D_{1}$. It is $\mathscr{C}^{\infty}$ in $w$ and holomorphic when $v>0$. Moreover there exists, for each $N$ an $L$ and a $C$ such that for any partition $X_{1}, \ldots, X_{r}$ of $\{1, \ldots, N\}$, and any $f \in \mathscr{S}\left(\mathbb{R}^{\nu N}\right)$,

$$
\begin{aligned}
& \| \int f\left(x_{1}, \ldots, x_{N}\right) e^{i w_{0} H} \bar{T}\left(X_{1}\right) e^{i w_{1} H} \ldots e^{i w_{r}-1 H} \bar{T}\left(X_{r}\right) \Omega \\
& \quad d x_{1} \ldots d x_{N} \| \leqq C(1+|w|)^{L}|f|_{L}
\end{aligned}
$$

with $w_{j}=u_{j}+i v_{j}, v_{j} \geqq 0,(0 \leqq j<r)$. This clearly implies

$$
\begin{align*}
& \left\|D_{w}^{\beta} \int f\left(x_{1}, \ldots, x_{N}\right) e^{i w_{0} H} \bar{T}\left(X_{1}\right) \ldots e^{i w_{r-1} H} \bar{T}\left(X_{r}\right) \Omega d x_{1} \ldots d x_{N}\right\| \\
& \quad \leqq C_{|\beta|}(1+|w|)^{L}|f|_{L+|\beta|} . \quad \text { q.e.d. } \tag{10}
\end{align*}
$$

The construction of $\mathcal{O}(X)$ is obtained by an induction on $|X|$. Note that $\mathcal{O}(X)$ has been defined for $X=\emptyset$ as $\mathcal{O}(\emptyset)=1$. We assume that $\mathcal{O}(X)$ has been defined for all $X$ with $|X| \leqq n-1$, with all the properties $\mathcal{O} 1)-\mathcal{O} 6), R^{\prime}$ ) and we construct $\mathcal{O}(X)$ for $X=\{1, \ldots, n\}$. More precisely, let $Z=\{n+1, \ldots, n+p\}$ and $z=\left(z_{n+1}, \ldots, z_{n+p}\right)$, $Z=Z_{1} \cup \ldots \cup Z_{r}$, (with $Z_{j} \cap Z_{k} \neq \emptyset$ for $\left.j \neq k\right)$. We shall define, for all $f \in \mathscr{S}\left(\mathbb{R}^{v n+1+v p}\right)$, with support

$$
\begin{equation*}
\operatorname{supp} f \subset\left\{\left(x_{1}, \ldots, x_{n}, v, z\right), 0 \leqq x_{j}^{0} \leqq v, j \in X\right\} \tag{11}
\end{equation*}
$$

the vector

$$
\begin{gather*}
\int \mathcal{O}(X) e^{-v H} \bar{T}\left(Z_{1}\right) \ldots \bar{T}\left(Z_{r}\right) \Omega f\left(x_{1}, \ldots, x_{n}, v, z\right) \\
d^{v} x_{1} \ldots d^{v} x_{n} d v d^{v} z_{n+1} \ldots d^{v} z_{n+p} . \tag{12}
\end{gather*}
$$

(We shall concentrate on the case $n>1$, the case $n=1$ being a simpler version, left to the reader. We also assume $Z \neq \emptyset$; the case $Z=\emptyset$ is a trivial variant.)

There is in fact no freedom left in defining $\mathcal{O}$ : for a radially analytic testfunction $g, \mathcal{O}(g)$ is determined by $\left.R^{\prime}\right)$; for a test function vanishing at coinciding points, it is determined by the factorization property $\mathcal{O}$ ) and by already constructed operators. We shall see that any test function can be written as a sum of functions of the two preceding types.

We first indicate how to decompose an arbitrary function. For this we use two auxiliary functions which we now define. Denote $y=n^{-1}\left(x_{1}^{0}+\ldots+x_{n}^{0}\right), \xi_{j}=x_{j}^{0}-y$, $1 \leqq j \leqq n$, (so that $\sum_{j \in X} \xi_{j}=0$ ) and let $\xi=\left(\xi_{1}, \ldots, \xi_{n-1}\right)$.

The function $\alpha_{L} . L$ is a positive integer and, for all $t \in \mathbb{R}$,

$$
\begin{equation*}
\alpha_{L}(t)=\theta(t) t^{L} e^{(i-1) t}=\frac{L!}{2 \pi} \int e^{-i p t}(1-i-i p)^{-L-1} d p \tag{13}
\end{equation*}
$$

More generally, for every complex $\lambda$ with $|\lambda|>0$ and $0 \leqq \arg \lambda \leqq \frac{\pi}{2}$,

$$
\begin{equation*}
\alpha_{\lambda, L}(t)=\theta(t) \lambda^{L} t^{L} e^{(i-1) \lambda t}=\frac{L!}{2 \pi} \int e^{-i p t}\left(1-i-i \lambda^{-1} p\right)^{-L-1} \lambda^{-1} d p \tag{14}
\end{equation*}
$$

and, in particular

$$
\begin{equation*}
\alpha_{i, L}(t)=\theta(t) i^{L} t^{L} e^{-(i+1) t}=\frac{L!}{2 \pi} \int e^{-i p t}(1-i-p)^{-L-1}(-i d p) . \tag{15}
\end{equation*}
$$

Note that

$$
\begin{equation*}
\lambda\left(1-i+\lambda^{-1} \frac{\partial}{\partial t}\right)^{L+1} \alpha_{\lambda, L}(t)=L!\delta(t) \tag{16}
\end{equation*}
$$

The Function $w: w(\xi, y)$ is a real function over $\mathbb{R}^{n}$ such that

1) $w$ is homogeneous and of degree 0 , i.e. for all $\varrho>0, w(\varrho \xi, \varrho y)=w(\xi, y)$.
2) $w$ is $\mathscr{C}^{\infty}$ in $\mathbb{R}^{n} \backslash\{0\}$.
3) The support of $w$ is contained in the cone
$\left\{(\xi, y) \mid 0 \leqq y ; 0 \leqq y+n \xi_{j}\right.$ for all $\left.j=1, \ldots, n\right\}$,
(we recall that $\xi_{n}=-\xi_{1}-\ldots-\xi_{n-1}$ ). Expressed in the variables $x_{j}^{0}=y+\xi_{j}$, this reads

$$
\left\{\left(x_{1}^{0}, \ldots, x_{n}^{0}\right) \mid \forall j, x_{j}^{0}-\frac{n-1}{n^{2}} \sum_{k=1}^{n} x_{0}^{k} \geqq 0\right\} .
$$

Note that this implies $x_{j}^{0} \geqq \frac{n-1}{n} y$ hence $x_{j}^{0} \leqq \frac{n^{2}-(n-1)^{2}}{n} y \leqq 2 y$.
4) $0 \leqq w \leqq 1$.
5) $D_{\xi}^{\beta} w(0, y)=0$ for all $|\beta|>1$ and all $y \neq 0: w(0, y)=1$ for all $y>0$.

It is easy to construct such functions: take $w(\xi, 1)$ to be any $\mathscr{C}^{\infty}$ function of $\xi=\left(\xi_{1}, \ldots, \xi_{n-1}\right)$ such that $0 \leqq w(\xi, 1) \leqq 1, w(0,1)=1, D_{\xi}^{\beta} w(0,1)=0$ for all $|\beta| \geqq 1$, and $\operatorname{supp} w(\xi, 1) \subset\left\{\xi: 0 \leqq n \xi_{j}+1\right.$ for all $\left.j=1, \ldots, n-1,0 \leqq 1-n \xi_{1}-\ldots-n \xi_{n-1}\right\}$.
Note that 0 is an interior point of this set. Then define

$$
w(\xi, y)=w(\xi / y, 1) \text { for } y>0, \quad \text { and } \quad w(\xi, y)=0 \text { for } y \leqq 0 .
$$

The Decomposition of $f$. Fix $L$ (to be determined later). Consider any $f \in \mathscr{S}\left(\mathbb{R}^{v n+1+v p}\right)$ with support in $\left\{\left(x_{1}, \ldots, x_{n}, v, z\right) \mid 0 \leqq x_{j}^{0} \leqq v, \forall j \in X\right\}$.

Define $\varphi$ by

$$
\begin{align*}
& \varphi(\xi, \mathbf{x}, y, v, z)=-(L!)^{-2}\left(1-i-i \frac{\partial}{\partial y}-2 i \frac{\partial}{\partial v}\right)^{L+1}\left(1-i-i \frac{\partial}{\partial v}\right)^{L+1} \\
& \quad f\left(\left(\xi_{1}+y, \mathbf{x}_{1}\right), \ldots,\left(\xi_{n}+y, \mathbf{x}_{n}\right), v, z\right) \tag{17}
\end{align*}
$$

where $\xi, y$ have been defined previously.
By Equation (16) it follows that $f$ can be written as

$$
\begin{gather*}
f\left(x_{i}, \ldots, x_{n}, v, z\right)=\int_{\mathbb{R}^{2}} d a d b \varphi(\xi, \mathbf{x}, a, b, z) \\
\alpha_{i, L}(y-a) \alpha_{i, L}(v-2 y-b+2 a) . \tag{18}
\end{gather*}
$$

$\varphi$ is in $\mathscr{S}\left(\mathbb{R}^{v(n+p)+1}\right)$ as a function of all its arguments, and has support in

$$
\left\{(\xi, \mathbf{x}, a, b, z) \mid \xi_{j}+a \geqq 0,(1 \leqq j \leqq n), 0 \leqq a \leqq b\right\}
$$

Furthermore,

$$
|\varphi|_{R} \leqq \text { Const }|f|_{R+2 L+2},
$$

(the constant depending only on $R$ and $L$ ).
We decompose $f$ into two parts, $f=f_{0}+f_{1}$ by defining

$$
\begin{gather*}
f_{1}(x, v, z)=\int d a d b \alpha_{i, L}(y-a) \alpha_{i, L}(v-2 y-b+2 a) \\
{\left[\sum_{|\beta|=0}^{M+1} \frac{\xi^{\beta}}{\beta!} D_{\xi}^{\beta} \varphi(0, \mathbf{x}, a, b, z)\right] w(\xi, y-a) .} \tag{19}
\end{gather*}
$$

$M \geqq 0$ will be chosen later.

Definition of $\mathcal{O}\left(f_{0}\right)$. Denote again $y=n^{-1}\left(x_{1}^{0}+\ldots+x_{n}^{0}\right), \xi_{j}=x_{j}^{0}-y,(1 \leqq j \leqq n)$, $\xi=\left(\xi_{1}, \ldots, \xi_{n-1}\right)$. Let $\mathscr{E}$ be the subspace of $\mathscr{S}\left(\mathbb{R}^{v+1+v p}\right)$ consisting of functions having their support in the set (11), and let $\mathscr{E}_{0} \subset \mathscr{E}$ be the set of functions in $\mathscr{E}$ which vanish in a neighborhood of

$$
\left\{\left(x_{1}, \ldots, x_{n}, v, z\right) \mid \xi=0\right\}
$$

Lemma 4. A function $g \in \mathscr{E}_{0}$ can be written as $g=\sum_{A, B} g_{A, B}, A \cup B=X, A \cap B=\emptyset$, $A, B \neq \emptyset$, with $\operatorname{supp} g_{A, B} \subset\left\{\left(x_{1}, \ldots, x_{n}, v, z\right) \mid x_{j}^{0}<x_{k}^{0}, \forall j \in A, k \in B\right\}$.

The proof is deferred to the end of the subsection.
We now define for $g \in \mathscr{E}_{0}$

$$
\begin{align*}
& \int \mathcal{O}(X) e^{-v H} \bar{T}\left(Z_{1}\right) \ldots \bar{T}\left(Z_{r}\right) \Omega g(x, v, z) d x d v d z \\
& \quad=\sum_{A, B} \int \mathcal{O}(A) \mathcal{O}(B) e^{-v H} \bar{T}\left(Z_{1}\right) \ldots \bar{T}\left(Z_{r}\right) \Omega g_{A, B}(x, v, z) d x d v d z \tag{20}
\end{align*}
$$

This definition is forced by the requirement $\mathcal{O}$ ) (Factorization). The r.h.s. of this equation is well defined according to the induction hypothesis and is bounded in norm by Const $\left|g_{A, B}\right|_{R}$ (the constant and $R$ depend only on $n+p$ ). It is easy to see by standard methods, (see e.g. [EG 1,2]), that there is a $K \geqq 0$ such that (for all $g \in \mathscr{E}_{0}$ ) the expression (20) is bounded in norm by Const. $|g|_{K}$.

The function $f_{1}$ defined by (19) is not $\mathscr{C}^{\infty}$ but it belongs to the completion of $\mathscr{S}\left(\mathbb{R}^{v n+1+v p}\right)$ in the norm $\|_{M}$, and

$$
\left|f_{1}\right|_{M} \leqq \text { Const. }|\varphi|_{2 M+1} \leqq \text { Const. }|f|_{2 M+2 L+3}
$$

provided we have chosen $L \geqq M+1$. Its support is contained in

$$
\left\{\left(x_{1}, \ldots, x_{n}, v, z_{n+1}, \ldots, z_{n+p}\right) \mid \forall j \in X, 0 \leqq x_{j}^{0} \leqq v\right\}
$$

Hence $f_{0}$ has the same properties and, furthermore, vanishes together with its derivatives of order $\leqq M+1$ when $\xi=0$. As a consequence if we replace $f$ by $f_{0}$ in (12), the corresponding vector is well defined by our previous discussion, (formula (20) with $g=f_{0}$ ) and bounded in norm by Const. $\left|f_{0}\right|_{M} \leqq$ Const. $|f|_{2 M+2 L+3}$, provided we choose $M \geqq K$.
Definition of $\mathcal{O}\left(f_{1}\right)$. The function $f_{1}$ can be re-written as

$$
f_{1}(x, v, z)=\int d a d b \varphi_{0}(\xi, y-a, v-b, \mathbf{x}, a, b, z)
$$

where $\varphi_{0}=\varphi_{0,1}$,

$$
\begin{aligned}
\varphi_{0, \lambda}(\xi, y, v, \mathbf{x}, a, b, z)= & {\left[\sum_{|\beta|=0}^{M+1} \frac{\lambda^{|\beta|} \xi^{\beta}}{\beta!} D_{\xi}^{\beta} \varphi(0, \mathbf{x}, a, b, z)\right] w(\xi, y) \alpha_{i, L}(\lambda y) } \\
& \alpha_{i, L}(\lambda v-2 \lambda y)
\end{aligned}
$$

This function is radially analytic (with respect to the variables $\xi, y, v$ ) and has support in (11). Hence the requirements $\mathcal{O 4}$ ) and $R^{\prime}$ ) force the definition:

$$
\begin{align*}
& \int \mathcal{O}(X) e^{-v H} \bar{T}\left(Z_{1}\right) \ldots \bar{T}\left(Z_{r}\right) \Omega \varphi_{0}(\xi, y-a, v-b, \mathbf{x}, a, b, z) d x d v d z \\
& \quad=\int e^{-a H} \bar{T}(X) e^{(i v-b+a) H} \bar{T}\left(Z_{1}\right) \ldots \bar{T}\left(Z_{r}\right) \Omega \\
& \quad n \varphi_{0,-i}(\xi, y, v, \mathbf{x}, a, b, z) i^{-n-1} d \xi d y d v d \mathbf{x} d z \tag{21}
\end{align*}
$$

The r.h.s. of (21) is a well-defined vector: considered as a test function in the variables $\xi, y, v, \mathbf{x}, z$, depending on the parameters $a$ and $b, \varphi_{0,-i}$ belongs to the completion of $\mathscr{S}$ in the norm $\|_{M}$, (with the condition $L \geqq M+1$ ), and is an admissible test-function if $M$ is sufficiently large. Moreover,

$$
\begin{align*}
\sup _{a, b}(1+a+b)^{R}\left|\varphi_{0}(\ldots, a, b)\right|_{M} & \leqq \text { Const. }|\varphi|_{2 M+1+R} \\
& \leqq \text { Const. }|f|_{2 M+R+2 L+3} \tag{22}
\end{align*}
$$

Thus we can integrate (21) over $a$ and b and define

$$
\begin{align*}
& \int \mathcal{O}(X) e^{-v H} \bar{T}\left(Z_{1}\right) \ldots \bar{T}\left(Z_{r}\right) \Omega f_{1}(x, v, z) d x d v d z \\
& \quad=\int e^{-a H} \bar{T}(X) e^{(i v-b+a) H} \bar{T}\left(Z_{1}\right) \ldots \bar{T}\left(Z_{r}\right) \Omega  \tag{23}\\
& \quad n \varphi_{0,-i}(\xi, y, v, \mathbf{x}, a, b, z) i^{-n-1} d \xi d y d v d \mathbf{x} d z d a d b .
\end{align*}
$$

This completes the definition of the vector (12), which is bounded in norm by Const. $|f|_{4 M+8}$.

Verification of the Properties (01)-06). The vector constructed above is independent of $L \geqq M+1$ because it is easy to check (by using the induction hypothesis) that if $f$ happens to be radially analytic in the variables $\xi, y$ and $v$, then so are $f_{0}$ and $f_{1}$ and the above definition yields exactly

$$
\begin{aligned}
& \int \bar{T}(X) e^{i v H} \bar{T}\left(Z_{1}\right) \ldots \bar{T}\left(Z_{r}\right) \Omega f\left(\left(-i x_{1}^{0}, \mathbf{x}_{1}\right), \ldots,\left(-i x_{n}^{0}, \mathbf{x}_{n}\right),-i v, z\right) \\
& \quad(-i)^{n+1} d^{v} x_{1} \ldots d^{v} x_{n} d v d z_{n+1} \ldots d z_{n+p} .
\end{aligned}
$$

(We omit the details of this verification. An analogous verification is sketched in Section III.) Thus (O1) and $R^{\prime}$ ) are satisfied.

Having defined vectors of the type (12), we now wish to define

$$
\int \mathcal{O}(X) e^{-v H} \bar{T}\left(Z_{1}\right) \ldots \bar{T}\left(Z_{r}\right) \Omega g\left(x_{1}, \ldots, x_{n}, z_{n+1}, \ldots, z_{n+p}\right) d^{v} x_{1} \ldots d^{v} z_{n+p}
$$

where $v>0$ and $g \in \mathscr{S}\left(\mathbb{R}^{v(n+p)}\right)$ has its support in

$$
\left\{\left(x_{1}, \ldots, x_{n}, z\right): \forall j \in X, 0 \leqq x_{j}^{0} \leqq v\right\} .
$$

This can be rewritten, formally, as

$$
\begin{aligned}
& \int \mathcal{O}(X) e^{(i t-v) H} \bar{T}\left(Z_{1}\right) \ldots \bar{T}\left(Z_{r}\right) \Omega g\left(x_{1}, \ldots, x_{n}, z_{n+1}, \ldots, z_{n+p}\right) \\
& \quad(Q!)^{-1}\left(1-i+\frac{\partial}{\partial t}\right)^{Q+1} \alpha_{Q}(t) d t d x d z \\
& =\int \mathcal{O}(X) e^{-v H} \bar{T}\left(Z_{1}\right) \ldots \bar{T}\left(Z_{r}\right) \Omega g\left(x_{1}, \ldots, x_{n}, z_{n+1}^{\prime}, \ldots, z_{n+p}^{\prime}\right) \\
& \quad(Q!)^{-1}\left(1-i+\frac{\partial}{\partial t}\right)^{Q+1} \alpha_{Q}(t) d t d x d z
\end{aligned}
$$

where $z_{k}^{\prime}=\left(z_{k}^{0}-t, \mathbf{x}_{k}\right),(n+1 \leqq k \leqq n+p)$. By integrating by parts over $t$ this becomes

$$
\begin{aligned}
& \int \mathcal{O}(X) e^{(-v+i t) H} \bar{T}\left(Z_{1}\right) \ldots \bar{T}\left(Z_{r}\right) \Omega \\
& \quad K_{Q} g\left(x_{1}, \ldots, x_{n}, z_{n+1}, \ldots, z_{n+p}\right) \alpha_{Q}(t) d t d x d z,
\end{aligned}
$$

where

$$
\begin{aligned}
& K_{Q} g\left(x_{1}, \ldots, x_{n}, z_{n+1}, \ldots, z_{n+p}\right) \\
& \quad=\left.(Q!)^{-1}\left(1-i-\frac{\partial}{\partial t}\right)^{Q+1} g\left(x_{1}, \ldots, x_{n}, z_{n+1}^{\prime}, \ldots, z_{n+p}^{\prime}\right)\right|_{t=0} .
\end{aligned}
$$

By analytic continuation in $t$, this becomes

$$
\int \mathcal{O}(X) e^{-(v+t) H} \bar{T}\left(Z_{1}\right) \ldots \bar{T}\left(Z_{r}\right) \Omega K_{Q} g(x, z) \alpha_{i, Q}(t) i d t d x d z,
$$

and, for $Q$ sufficiently large, this has been defined previously.
The same formulae evidently lead to a consistent definition of

$$
\begin{aligned}
& \int \bar{T}\left(Y_{1}\right) \ldots \bar{T}\left(Y_{s}\right) e^{i \sigma H} \mathcal{O}(X)^{-v H} \bar{T}\left(Z_{1}\right) \ldots \bar{T}\left(Z_{r}\right) \Omega \\
& \quad h\left(\{y\}_{Y_{1} \cup \ldots \cup Y_{s}}, x, v, z\right) d x d x d v d z
\end{aligned}
$$

This shows that all such vectors do belong to $D_{1}$.
This proves $(\mathcal{O})$. The properties $(\mathcal{O}),(\mathcal{O}), \mathcal{O}$ ), 0 ) follow from the construction, from the corresponding properties for the $\bar{T}$, and by analytic continuation. We omit the details of the verification, which are entirely straightforward.

Proof of Lemma 4. We consider, in the space of the variables $\xi$, the "sphere" $\Xi$ consisting of all $\xi$ verifying

$$
\sum_{1 \leqq j<k \leqq n}\left(\xi_{j}-\xi_{k}\right)^{2}=1
$$

(Note that $\left.\sum_{1 \leqq j<k \leqq n}\left(\xi_{j}-\xi_{k}\right)^{2}=n \sum_{1 \leqq j \leqq n} \xi_{j}^{2}\right)$.
For any $\xi \in \Xi$, there is at least one pair of distinct $j$ and $k$, such that $\xi_{j}-\xi_{k}$ $\geqq\left(\frac{1}{2} n(n-1)\right)^{-1 / 2}>2^{1 / 2} n^{-1}$. Thus if $\alpha=\min \left\{\xi_{j}: 1 \leqq j \leqq n\right\}$ and $\beta=\max \left\{\xi_{j}: 1 \leqq j \leqq n\right\}$, we have

$$
2^{1 / 2} n^{-1}<\beta<a \leqq 1 .
$$

The real numbers $\xi_{j}, 1 \leqq j \leqq n$, subdivide the interval $[\alpha, \beta]$ into at most $n-1$ open intervals. At least one of these subintervals say $(\gamma, \delta)$ has a length

$$
\delta-\gamma \geqq(n-1)^{-1} 2^{1 / 2} n^{-1}>2^{1 / 2} n^{-2}
$$

Let

$$
A=\left\{j: 1 \leqq j \leqq n, \xi_{j} \leqq \gamma\right\}, \quad B=\left\{k: 1 \leqq k \leqq n, \xi_{k} \leqq \delta\right\} .
$$

Then $\xi$ belongs to the open set of the sphere defined by

$$
\Omega_{A, B}=\left\{\xi: \forall j \in A, \forall k \in B, \xi_{k}-\xi_{j}>2^{1 / 2} n^{-2}\right\}
$$

itself contained in

$$
\Omega_{A, B}^{\prime}=\left\{\xi: \forall j \in A, \forall k \in B, \xi_{k}-\xi_{j}>n^{-2}\right\} .
$$

Let $\left\{\chi_{A, B}\right\}_{\substack{A \cup B=X \\ A \cup B=0 \\ A, B=\emptyset}}$ be a family of $\mathscr{C}^{\infty}$ functions on $\Xi$ with

$$
\text { supp. } \chi_{A, B} \subset \Omega_{A, B}^{\prime} \quad \text { and } \quad \sum_{A, B} \chi_{A, B}=1
$$

[Example: denote $F_{A, B}(\xi)=\prod_{\substack{j \in A \\ k \in B}} \theta\left(\xi_{k}-\xi_{j}-n^{-2}\right) \exp -\left(\xi_{k}-\xi_{j}-n^{-2}\right)^{-1}$ and $\chi_{A, B}(\xi)$ $=F_{A, B}(\xi)\left[\sum_{C, D} F_{C, D}(\xi)\right]^{-1}$. This is well defined since, on $\Omega_{C, D}, F_{C, D}(\xi)$
$\left.>\exp \left(-n^{4}\left(2^{1 / 2}-1\right)^{-1}\right).\right]$
Then, for general $\xi \neq 0$, denote $\psi_{A, B}(\xi)=\chi_{A, B}\left(\xi\left(n \sum_{j=1}^{n} \xi_{j}^{2}\right)^{-1 / 2}\right)$. If $g \in \mathscr{E}_{0}$, $g=\sum_{A, B} g_{A, B}$ with $g_{A, B}=\psi_{A, B}(\xi) g \in \mathscr{E}_{0}$. This completes the proof.

## II.2. The Construction of Schwinger Functions

The previous construction has led, in particular, to a definition of $(\Omega, \mathcal{O}(X) \Omega)$ as a continuous linear functional over the subspace of $\mathscr{S}\left(\mathbb{R}^{v n}\right)$ consisting of functions with support in $\left\{\left(x_{1}, \ldots, x_{n}\right) \mid x_{j}^{0} \geqq 0, j=1, \ldots, n\right\}$. However this functional is invariant under the translations of the form $\left(x_{1}, \ldots, x_{n}\right) \rightarrow\left(x_{1}+a, \ldots, x_{n}+a\right)$ where $a^{0}>0$, a $=0$, and can be uniquely extended to a continuous linear functional over the whole of $\mathscr{S}\left(\mathbb{R}^{v n}\right)$, by using the translation invariance and a partition of the unit. The tempered distribution $S_{n}$ so defined (also denoted $S$ if $n$ is unambiguous) is symmetric, invariant under time translations, and coincides with $(\Omega, \mathcal{O}(X), \Omega)$ when integrated with test-functions with support in $\left\{\left(x_{1}, \ldots, x_{n}\right) \in \mathbb{R}^{v n} \mid \forall j, x_{j}^{0} \geqq 0\right\}$. Thus it satisfies the properties $S 1$ ), $S 2$ ), $S 3$ ) and $R$ ).

In order to study further properties of $S$, we use some well-known regularization procedures.

The preceding construction of the distributions $\left(\Omega, \mathcal{O}\left(X_{1}\right) \ldots \mathcal{O}\left(X_{r}\right) \Omega\right)$ does not really depend on the Hilbert space structure but only on the linear properties of the distributions $\left(\Omega, \bar{T}\left(X_{1}\right) \ldots \bar{T}\left(X_{1}\right) \Omega\right)$. Thus it can be straight-forwardly adapted to the case of a "linear system of $n$-point functions", i.e. a set of tempered distributions $\left\langle\bar{T}\left(X_{1}\right) \ldots \bar{T}\left(X_{s}\right)\right\rangle$ over $\mathbb{R}^{v n}$ (here $X_{1} \cup \ldots \cup X_{s}=X=\{1, \ldots, n\}, X_{j} \cap X_{k}=\emptyset$ if $j \neq k$, $1 \leqq s \leqq n$ ), having all the linear properties of the $\left(\Omega, \bar{T}\left(X_{1}\right) \ldots \bar{T}\left(X_{s}\right) \Omega\right)$. (These "linear systems" are discussed in [EGS]). Among the "axioms" which are imposed on such a linear system is the spectrum condition: let

$$
\begin{align*}
& \left\langle\bar{T}\left(X_{1}\right) \ldots \bar{T}\left(X_{r}\right)\right\rangle>\sim\left(p_{1}, \ldots, p_{n}\right) \delta\left(\sum_{1 \leqq j \leqq n} p_{j}\right) \\
& \left.\quad=(2 \pi)^{-n v} \int\left(\exp i \sum_{1 \leqq j \leqq n} p_{j} x_{j}\right)\left\langle\bar{T}\left(X_{1}\right) \ldots \bar{T}\left(X_{r}\right)\right\rangle\right\rangle\left(x_{1}, \ldots, x_{n}\right) d^{v} x_{1} \ldots d^{v} x_{n} . \tag{24}
\end{align*}
$$

$\left[\right.$ Here $\left.p_{j} x_{j}=p_{j}^{0} x_{j}^{0}-\mathbf{p}_{j} \mathbf{x}_{j \cdot}\right]$
Denote, for every proper subset $Y$ of $X, p_{Y}=\sum_{k \in Y} p_{k}$. Let $I_{1}=X_{1}, \ldots, I_{s}=\bigcup_{1 \leqq j \leqq s} X_{j}$. Then the support of the distribution (24) is contained in

$$
\left\{\left(p_{1}, \ldots, p_{n}\right) \mid \sum_{j=1}^{n} p_{j}=0, \quad \text { and, for every } \quad s=1, \ldots, r-1, p_{I_{s}} \in \bar{V}^{+}\left(M_{I_{s}}\right)\right\} .
$$

Here $\bar{V}^{+}(M)$ denotes $\left\{p \in \mathbb{R}^{v} \mid p^{0} \geqq 0, p \cdot p \geqq M^{2}\right\}$. (See Remark 1 at the end of this section.) For every proper subset $J$ of $X, M_{J}$ is a fixed real number $\geqq 0$, called the threshold in the channel $J ; M_{J}=M_{X \backslash J}$. If $\left\langle\left\langle\bar{T}\left(X_{1}\right) \ldots \bar{T}\left(X_{r}\right)\right\rangle\right\rangle=\left(\Omega, \bar{T}\left(X_{1}\right) \ldots \bar{T}\left(X_{r}\right) \Omega\right)$, the thresholds are, in general, 0 because of the vacuum contribution. If $\left\langle\bar{T}\left(X_{1}\right) \ldots \bar{T}\left(X_{r}\right)\right\rangle$ is taken to be $\left(\Omega, \bar{T}\left(X_{1}\right) \ldots \bar{T}\left(X_{r}\right) \Omega\right)^{T}$, and if the theory has a unique vacuum and a mass gap, then for all $J, M_{J} \geqq \mu$, where $\mu$ is a fixed minimum mass $>0$.

Given a linear system of $n$-point functions, it is possible to define, by suitable linear combinations, the corresponding "generalized retarded functions" $\left\langle\left\langle R_{\mathscr{\varphi}}\right\rangle\right.$. Their Fourier transforms $\left\langle\left\langle R_{\mathscr{Y}}\right\rangle\right\rangle$, defined by

$$
《 R_{\mathscr{Y}} \gg\left(p_{1}, \ldots, p_{n}\right) \delta\left(\sum_{j} p_{j}\right)=(2 \pi)^{-v n} \int e^{i p x}\left\langle 《 R_{\mathscr{Y}}\right\rangle>\left(x_{1}, \ldots, x_{n}\right) d x^{v n}
$$

are the boundary values from certain tubes of a single function $H$ holomorphic in a certain domain in the "complex momentum space", $\left\{\left(k_{1}, \ldots, k_{n}\right) \in \mathbb{C}^{\nu n} \mid \sum_{j} k_{j}=0\right\}$. The domain of analyticity of $H$ contains the following set:

$$
\begin{aligned}
& \left\{\left(k_{1}, \ldots, k_{n}\right) \in \mathbb{C}^{v n} \mid \sum_{j} k_{j}=0 ; \quad \text { for all } j, \quad \operatorname{Im} \mathbf{k}_{j}=0 ; \quad \text { and },\right. \\
& \left.\quad \forall J \subset X,\left(k_{J}^{0}\right)^{2} \notin M_{J}^{2}+\mathbb{R}^{+}\right\} .
\end{aligned}
$$

Thus, if the thresholds are all strictly positive, the domain of holomorphy of $H$ contains the set $\tilde{E}_{n}$ of all "Euclidean momenta",

$$
\tilde{E}_{n}=\left\{\left(k_{1}, \ldots, k_{n}\right) \in \mathbb{C}^{\mathrm{vn}} \mid \sum_{j} k_{j}=0 \quad \text { and for all } j, \quad \operatorname{Im} \mathbf{k}_{j}=0, \operatorname{Re} k_{j}^{0}=0\right\}
$$

In this case, (all $M_{J} \geqq \mu>0$ ), the distributions $\left\langle\bar{T}\left(X_{1}\right) \ldots \bar{T}\left(X_{r}\right)\right\rangle$ can be unambiguously recovered from the function $H$ by a well-defined linear procedure. This allows the following regularization method.

Let

$$
H^{\mathrm{reg}}(k)=\left[\prod_{j=1}^{n}\left(-k_{j}^{2}+L^{2}\right)^{-R}\right] H(k)
$$

where $R \geqq 0$ is an integer and $L>\max _{J} M_{J}$. This function has all the linear properties of an $n$-point momentum-space analytic function and the above mentioned linear procedure, applied to $H^{\text {reg }}$, yields a new linear system of $n$-point functions, denoted $\left\langle\bar{T}\left(X_{1}\right) \ldots \bar{T}\left(X_{r}\right)\right\rangle{ }^{\text {reg. }}$. They verify

$$
\begin{equation*}
\left.\left[\prod_{j=1}^{n}\left(\square_{x_{j}}+L^{2}\right)^{R}\right]\left\langle\bar{T}\left(X_{1}\right) \ldots \bar{T}\left(X_{r}\right)\right\rangle\right\rangle^{\mathrm{reg}}=\left\langle\left\langle\bar{T}\left(X_{1}\right) \ldots \bar{T}\left(X_{r}\right)\right\rangle\right\rangle \tag{25}
\end{equation*}
$$

For sufficiently large $R$, all $\langle\bar{T} \ldots\rangle\rangle^{\text {reg }}$ become continuous and even finitely differentiable, polynomially bounded functions. Furthermore if $w\left(z_{1}, \ldots, z_{n}\right)$ denotes the value at $\left(z_{1}, \ldots, z_{n}\right) \in \mathbb{C}^{n v}$ of the analytic Wightman function which has as its boundary values the various

$$
w_{\pi}=\left\langle\left\langle\bar{T}\left(\left\{\pi_{1}\right\}\right) \ldots \bar{T}\left(\left\{\pi_{n}\right\}\right)\right\rangle\right\rangle,
$$

and if $w^{\text {reg }}, w_{\pi}^{\text {reg }}$ denotes the corresponding regularized objects, it is easy to see that $w^{\text {reg }}$ is continuous and has finitely many continuous derivatives at the boundaries of the permuted forward tubes. In particular $w^{\text {reg }}$ defines a piecewise continuous function on the Euclidean world. Applying the characteristic property $(R)$, it is then clear that

$$
\begin{equation*}
S^{\mathrm{reg}}\left(y_{1}, \ldots, y_{n}\right)=w^{\mathrm{reg}}\left(\left(i y_{1}^{0}, \mathbf{y}_{1}\right), \ldots,\left(i y_{n}^{0}, \mathbf{y}_{n}\right)\right), \tag{26}
\end{equation*}
$$

and that

$$
\begin{equation*}
S\left(y_{1}, \ldots, y_{n}\right)=\prod_{j=1}^{n}\left(-\Delta_{y_{j}}+L^{2}\right)^{R} S^{\mathrm{reg}}\left(y_{1}, \ldots, y_{n}\right) . \tag{27}
\end{equation*}
$$

The last equation holds in the sense of tempered distributions, and, of course $S$ and $S^{\text {reg }}$ are given by $\langle\mathcal{O}(X)\rangle$ and $\left.\left.《 \mathcal{O}(X)\right\rangle\right\rangle^{\text {reg }}$, respectively. It is well-known [Sy], (and re-proved in [EGS] and [EEF]), that

$$
\begin{align*}
S^{\mathrm{reg}}\left(y_{1}, \ldots, y_{n}\right)= & \int \exp \left(-i \sum_{j} q_{j} y_{j}\right) H^{\mathrm{reg}}\left(\left(-i q_{1}^{0}, \mathbf{q}_{1}\right), \ldots,\left(-i q_{n}^{0}, \mathbf{q}_{n}\right)\right)  \tag{28}\\
& i^{n-1} \delta\left(\sum_{j=1}^{n} q_{j}\right) d q_{1} \ldots d q_{n}
\end{align*}
$$

so that, applying (27), we obtain

$$
\begin{align*}
S\left(y_{1}, \ldots, y_{n}\right)= & \int \exp \left(-i \sum_{j} q_{j} y_{j}\right) H\left(\left(-i q_{1}^{0}, \mathbf{q}_{1}\right), \ldots,\left(-i q_{n}^{0}, \mathbf{q}_{n}\right)\right) \\
& i^{n-1} \delta\left(\sum_{j=1}^{n} q_{j}\right) d q_{1} \ldots d q_{n}, \tag{29}
\end{align*}
$$

(only valid for strictly positive thresholds). Here $q_{j} y_{j}=q_{j}^{0} y_{j}^{0}-\mathbf{q}_{j} \mathbf{y}_{j}$.
Now assume that $0<x_{\pi 1}^{0}<\ldots<x_{\pi r}^{0}$, and $0<x_{\sigma 1}^{\prime 0}<\ldots<x_{\sigma s}^{\prime 0}$, where $r+s=n$ and $\pi$ and $\sigma$ are respectively permutations of $(1, \ldots, r)$ and $(1, \ldots, s)$. Then

$$
w_{1}^{\mathrm{reg}}\left(\left(\mu x_{\sigma s}^{\prime 0}, \mathbf{x}_{\sigma s}^{\prime}\right) \ldots,\left(\mu x_{\sigma 1}^{\prime 0}, \mathbf{x}_{\sigma 1}^{\prime 0}\right),\left(\lambda x_{\pi 1}^{0}, \mathbf{x}_{\pi 1}\right), \ldots,\left(\lambda x_{\pi r}^{0}, \mathbf{x}_{\pi r}\right)\right),
$$

initially defined for $\lambda>0, \mu>0$, can be continued as an analytic function of $\lambda$ and $\mu$ in $\left\{\lambda\left||\lambda| \neq 0,0<\arg \lambda<\frac{\pi}{2}\right\} \times\left\{\mu \| \mu \mid \neq 0,0<-\arg \mu<\frac{\pi}{2}\right\}\right.$, continuous on the boundary of this domain, (with values in the piecewise continuous functions over $\mathbb{R}^{v n}$ ). For $\lambda=i, \mu=-i$ this continuation yields

$$
S^{\mathrm{reg}}\left(\left(-x_{\sigma s}^{\prime 0}, \mathbf{x}_{\sigma s}^{\prime}\right), \ldots,\left(-x_{\sigma 1}^{\prime 0}, \mathbf{x}_{\sigma 1}^{\prime}\right),\left(x_{\pi 1}^{0}, \mathbf{x}_{\pi 1}\right), \ldots,\left(x_{\pi r}^{0}, \mathbf{x}_{\pi r}\right)\right) .
$$

Let $f \in \mathscr{S}\left(\mathbb{R}^{v r}\right)$ and $g \in \mathscr{S}\left(\mathbb{R}^{v s}\right)$ have their supports in $\left\{\left(x_{1}, \ldots, x_{r}\right) \mid \forall j, x_{j}^{0} \geqq 0\right\}$ and $\left\{\left(x_{1}, \ldots, x_{s}\right) \mid \forall j, x_{j}^{0} \geqq 0\right\}$, respectively. Defining, for $\lambda>0, f_{\lambda}\left(x_{1}, \ldots, x_{r}\right)$ $=f\left(\left(\lambda x_{1}^{0}, \mathbf{x}_{1}\right), \ldots,\left(\lambda x_{r}^{0}, \mathbf{x}_{r}\right)\right)$, and similarly $g_{\lambda}$, we suppose that $\lambda \rightarrow f_{\lambda}, \lambda \rightarrow g_{\lambda}$ can be extended to holomorphic maps of $\left\{\lambda \in \mathbb{C} \backslash\{0\} \left\lvert\, 0<\arg \lambda<\frac{\pi}{2}\right.\right\}$, continuous on $\{\lambda \in \mathbb{C} \backslash$ $\left.\{0\} \left\lvert\, 0 \leqq \arg \lambda \leqq \frac{\pi}{2}\right.\right\}$, into $\mathscr{S}\left(\mathbb{R}^{v r}\right)$ and $\mathscr{S}\left(\mathbb{R}^{v s}\right)$, respectively. Then

$$
\begin{align*}
& \int w^{\mathrm{reg}}\left(\left(\mu x_{\sigma s}^{\prime 0}, \mathbf{x}_{\sigma s}^{\prime}\right), \ldots,\left(\mu x_{\sigma}^{\prime 0}, \mathbf{x}_{\sigma 1}^{\prime}\right),\left(\lambda x_{\pi 1}^{0}, \mathbf{x}_{\pi 1}\right), \ldots,\left(\lambda x_{\pi r}^{0}, \mathbf{x}_{\pi r}\right)\right) \\
& \quad \theta\left(x_{\sigma s}^{\prime 0}-x_{\sigma(s-1)}^{\prime 0}\right) \ldots \theta\left(x_{\sigma 2}^{\prime 0}-x_{\sigma 1}^{\prime 0}\right) \theta\left(x_{\pi 2}^{0}-x_{\pi 1}^{0}\right) \ldots \theta\left(x_{\pi r}^{0}-x_{\pi(r-1)}^{0}\right)  \tag{30}\\
& \bar{g}_{\bar{\mu}}\left(x_{1}^{\prime}, \ldots, x_{s}^{\prime}\right) f_{\lambda}\left(x_{1}, \ldots, x_{r}\right) \lambda^{r} \mu^{s} d x_{1}^{\prime} \ldots d x_{s}^{\prime} d x_{1} \ldots d x_{r}
\end{align*}
$$

defines a holomorphic function over $\left\{\lambda \in \mathbb{C} \backslash\{0\} \left\lvert\, 0<\arg \lambda<\frac{\pi}{2}\right.\right\} \times\{\mu \in \mathbb{C} \backslash\{0\} \mid 0$ $\left.<-\arg \mu<\frac{\pi}{2}\right\}$, (with continuity at the boundaries except $\lambda=0$ or $\mu=0$ ). But, for $\lambda>0$ and $\mu>0$, this integral is independent of $\lambda$ and $\mu$. Hence it remains constant for complex $\lambda$ and $\mu$ and, by continuity, we get, for $\lambda=\bar{\mu}=i$,

$$
\begin{aligned}
& \int S^{\mathrm{reg}}\left(\left(-x_{\sigma s}^{\prime 0} \mathbf{x}_{\sigma s}^{\prime}\right), \ldots,\left(-x_{\sigma 1}^{\prime 0}, \mathbf{x}_{\sigma 1}^{\prime}\right),\left(x_{\pi 1}^{0}, \mathbf{x}_{\pi 1}\right), \ldots,\left(x_{\pi r}^{0}, \mathbf{x}_{\pi r}\right)\right) \\
& \quad \theta\left(x_{\sigma s}^{\prime 0}-x_{\sigma(s-1)}^{\prime 0}\right) \ldots \theta\left(x_{\sigma 2}^{\prime 0}-x_{\sigma 1}^{\prime 0}\right) \theta\left(x_{\pi 2}^{0}-x_{\pi 1}^{0}\right) \ldots \theta\left(x_{\pi r}^{0}-x_{\pi(r-1)}^{0}\right) \\
& \quad f_{i}\left(x_{1}, \ldots, x_{r}\right) \overline{g_{i}\left(x_{1}^{\prime}, \ldots, x_{s}^{\prime}\right)} i^{r-s} d^{v} x_{1}^{\prime} \ldots d^{v} x_{s}^{\prime} d^{v} x_{1} \ldots d^{v} x_{r} \\
& =\int w_{1}^{\mathrm{reg}}\left(x_{\sigma s}^{\prime}, \ldots, x_{\sigma 1}^{\prime}, x_{\pi 1}, \ldots, x_{\pi r}\right) \theta\left(x_{\sigma s}^{\prime 0}-x_{\sigma(s-1)}^{\prime 0}\right) \ldots \theta\left(x_{\sigma 1}^{\prime 0}\right) \\
& \quad \theta\left(x_{\pi 2}^{0}-x_{\pi 1}^{0}\right) \ldots \theta\left(x_{\pi r}^{0}-x_{\pi(r-1)}^{0}\right) f\left(x_{1}, \ldots, x_{r}\right) \bar{g}\left(x_{1}^{\prime}, \ldots, x_{s}^{\prime}\right) d x_{1} \ldots d x_{s}^{\prime} .
\end{aligned}
$$

Using the symmetry of $S^{\text {reg }}$, and summing on both sides over $\sigma$ and $\pi$, we obtain

$$
\begin{align*}
& \int S^{\mathrm{reg}}\left(\left(-x_{s}^{\prime 0}, \mathbf{x}_{s}^{\prime}\right), \ldots,\left(-x_{1}^{\prime 0}, \mathbf{x}_{1}^{\prime}\right), x_{1}, \ldots, x_{r}\right) \overline{g_{i}\left(x_{1}^{\prime}, \ldots, x_{s}^{\prime}\right)} \\
& f_{i}\left(x_{1}, \ldots, x_{r}\right) d x_{1} \ldots d x_{s}^{\prime} \\
= & \left.\left.\int \ll T\left(x_{1}^{\prime}, \ldots, x_{s}^{\prime}\right) \bar{T}\left(x_{1}, \ldots, x_{r}\right)\right\rangle\right\rangle^{\mathrm{reg}} \bar{g}\left(x_{1}^{\prime}, \ldots, x_{s}^{\prime}\right) f\left(x_{1}, \ldots, x_{r}\right) \\
& d x_{1} \ldots d x_{s}^{\prime} . \tag{31}
\end{align*}
$$

By using (27) and (25) we obtain the

## Lemma 5.

$$
\begin{align*}
& \int S\left(\left(-x_{s}^{\prime 0}, \mathbf{x}_{s}^{\prime}\right), \ldots,\left(-x_{1}^{\prime 0}, \mathbf{x}_{1}^{\prime}\right), x_{1}, \ldots, x_{r}\right) \bar{g}_{i}\left(x_{1}^{\prime}, \ldots, x_{s}^{\prime}\right) f_{i}\left(x_{1}, \ldots, x_{r}\right) d x_{1} \ldots d x_{s}^{\prime} \\
= & \int\left\langle T\left(x_{1}^{\prime}, \ldots, x_{s}^{\prime} \bar{T}\left(x_{1}, \ldots, x_{r}\right)\right\rangle \bar{g}\left(x_{1}^{\prime}, \ldots, x_{s}^{\prime}\right) f\left(x_{1}, \ldots, x_{r}\right) d x_{1} \ldots d x_{s}^{\prime} .\right. \tag{32}
\end{align*}
$$

Proof. We have already shown that this formula holds for all linear systems with strictly positive thresholds. We extend it to all linear systems of $n$-point functions. Note that both sides of Equation (32) have a well defined meaning even in the case of zero thresholds, since the construction of $S$ as a tempered distribution remains valid. Starting from a linear system of $n$-point functions with possibly zero thresholds, we approximate it by a new system, with strictly positive thresholds, by the following method. For every $z \in \mathbb{C}^{v}$ with $(z \cdot z) \notin A^{2}+\mathbb{R}^{+}$, we define

$$
\begin{equation*}
F(z ; A)=\exp \left(i A^{-1}\left[(z \cdot z)-A^{2}\right]^{1 / 2}+1\right) . \tag{33}
\end{equation*}
$$

Here $A$ is strictly positive; the function $\zeta \rightarrow\left(\zeta-A^{2}\right)^{1 / 2}$ is defined in $\mathbb{C} \backslash\left(A^{2}+\mathbb{R}^{+}\right)$by the condition $\operatorname{Im}\left(\zeta-A^{2}\right)^{1 / 2}>0$. We also denote

$$
\begin{align*}
F^{ \pm}(x ; A) & =\lim _{\substack{y \in V^{+} \\
y \rightarrow 0}} F(x \mp i y ; A), \\
F^{c}(x ; A) & =\theta\left(x^{0}\right) F^{+}(x ; A)+\theta\left(-x^{0}\right) F^{-}(x ; A),  \tag{34}\\
F^{a c}(x ; A) & =\theta\left(-x^{0}\right) F^{+}(x ; A)+\theta\left(x^{0}\right) F^{-}(x ; A) .
\end{align*}
$$

Note that $|F(z ; A)| \leqq e$ for all $z$ such that $(z \cdot z) \notin A^{2}+\mathbb{R}^{+}$and $F(z ; A)$ has continuous boundary values at the boundaries of this domain. For any pair $(j, k)$ with $j<k, j$
and $k \in\{1, \ldots, n\}$, we can define a linear system of $n$-point functions, as explained in [EGS, §6.3], by

$$
\begin{aligned}
\left.\left\langle\bar{T}\left(X_{1}\right) \ldots \bar{T}\left(X_{r}\right)\right\rangle\right\rangle^{\prime}= & \left.F^{+}\left(x_{j}-x_{k}\right)\left\langle\bar{T}\left(X_{1}\right) \ldots \bar{T}\left(X_{r}\right)\right\rangle\right\rangle \\
& \text { if } j \in X_{a}, k \in X_{b}, a<b, \\
= & \left.F^{-}\left(x_{j}-x_{k}\right)\left\langle\bar{T}\left(X_{1}\right) \ldots \bar{T}\left(X_{r}\right)\right\rangle\right\rangle \\
& \text { if } j \in X_{a}, k \in X_{b}, b<a, \\
= & F^{a c}\left(x_{j}-x_{k}\right)\left\langle\bar{T}\left(X_{1}\right) \ldots \bar{T}\left(X_{r}\right)\right\rangle \\
& \text { if } j \text { and } k \text { belong to the same } X_{a} .
\end{aligned}
$$

The reasons for which this is possible and leads to a linear system are given in [EGS, §6]. By repeating this procedure, we obtain a new linear system of $n$-point functions given by

$$
\begin{equation*}
\left.\left.\left\langle\bar{T}\left(X_{1}\right) \ldots \bar{T}\left(X_{r}\right)\right\rangle\right\rangle_{A}^{\text {new }}=\left(\prod_{j<k} F^{(+,-, a c)}\left(x_{j}-x_{k}\right)\right)\left\langle\bar{T}\left(X_{1}\right) \ldots \bar{T}\left(X_{r}\right)\right\rangle\right\rangle . \tag{35}
\end{equation*}
$$

In particular

$$
\begin{equation*}
w_{A}^{\mathrm{new}}\left(z_{1}, \ldots, z_{n}\right)=\left(\sum_{j<k} \exp \left(i A^{-1}\left[\left(z_{j}-z_{k}\right)^{2}-A^{2}\right]^{1 / 2}+1\right)\right) w\left(z_{1}, \ldots, z_{n}\right) \tag{36}
\end{equation*}
$$

This decreases exponentially at infinity in any direction strictly contained in a permuted tube. In fact the Fourier transform

$$
\tilde{F}^{ \pm}(p ; A)=\int e^{i p x} F^{ \pm}(x ; A) d^{v} x
$$

has its support in $\bar{V}^{ \pm}\left(A^{-1}\right)$, and hence the thresholds of the new system are all above $A^{-1}$.

When $A$ tends to $\left.\infty,\left\langle\bar{T}\left(X_{1}\right) \ldots \bar{T}\left(X_{r}\right)\right\rangle\right\rangle_{A}^{\text {new }}$ tends, in the sense of tempered distributions, to $\left\langle\bar{T}\left(X_{1}\right) \ldots \bar{T}\left(X_{r}\right)\right\rangle$ and, (since the construction of the $\left\langle\mathcal{O}\left(X_{1}\right) \ldots\right\rangle$ depends continuously on the $\left.\left.\left\langle\bar{T}\left(X_{1}\right) \ldots \bar{T}\left(X_{r}\right)\right\rangle\right\rangle\right), S_{A}^{\text {new }} \rightarrow S$ in the sense of tempered distributions. This limiting process yields (32) in the general case. Moreover since (29) holds for $S_{A}^{\text {new }}$ and $H_{A}^{\text {new }}$, and since $S_{A}^{\text {new }} \rightarrow S$ in $\mathscr{S}^{\prime}$ as $A \rightarrow \infty$, the Fourier transform of $S_{A}^{\text {new }}$ also tends (in the sense of $\mathscr{S}^{\prime}$ ) to that of $S$. On the other hand $H_{A}^{\text {new }}(k)$ tends to $H(k)$ uniformly in every compact of the tubes associated with the $\left\langle\left\langle R_{\mathscr{Y}}\right\rangle\right.$; the union of these tubes always contains

$$
\begin{aligned}
& \left\{k=\left(k_{1}, \ldots, k_{n}\right) \mid \sum_{j=1}^{n} k_{j}=0 ; \forall j, k_{j}^{0}=i q_{j}^{0}, \mathbf{k}_{j}=\mathbf{q}_{j},\right. \\
& q_{j}^{0} \text { and } \mathbf{q}_{j} \text { real, and for every proper subset } J \text { of }\{1, \ldots, n\}, \\
& \left.q_{J}^{0}\left(\equiv \sum_{j \in J} q_{j}^{0}\right) \neq 0\right\} .
\end{aligned}
$$

At all such $q$, the Fourier transform of $S$ thus coincides with $H\left(-i q^{0}, \mathbf{q}\right) \delta\left(\sum q_{j}\right)$.
Remarks. 1. In discussing "linear systems of $n$-point functions" we have used notations adapted to the relativistic case. However the regularization procedures described above also hold in the non relativistic case and, in particular, Equation (32) remains valid.
2. As noted before, in a field theory with unique vacuum and a mass gap, the time ordered functions have zero thresholds but the truncated time ordered functions have strictly positive thresholds. In this case, Equation (29) is satisfied not by $S$ but its truncated version, $S^{T}$.

We return to the study of a field theory equipped with (anti-) time ordered products in a Hilbert space $\mathscr{H}$, i.e. we assume all the hypotheses T1)-T7). Then the distributions $S$ verify the positivity condition S 4 ).

Proof. In the 1.h.s. of Equation (5), we first replace each $f_{n}$ by a corresponding $g_{n, i}$, given by

$$
g_{n, \lambda}\left(y_{1}, \ldots, y_{n}\right)=\int_{0}^{\infty} \varrho\left(a ;-i \lambda \mu^{-1}\right) \frac{d \mu}{\mu} f_{n}\left(\left(\mu y_{1}^{0}, \mathbf{y}_{1}\right), \ldots,\left(\mu y_{n}^{0}, \mathbf{y}_{n}\right)\right) .
$$

$\varrho(a ; \zeta)$ is defined in the Appendix. Here $|\lambda|>0,0 \leqq \arg \lambda \leqq \frac{\pi}{2}$. According to (32), the lefthand side of (5) is then equal to

$$
\left\|\sum_{n} \int g_{n, 1}\left(x_{1}, \ldots, x_{n}\right) \bar{T}\left(x_{1}, \ldots, x_{n}\right) \Omega d x_{1} \ldots d x_{n}\right\|^{2}
$$

and is positive. If we let a tend to $+\infty, g_{n, i}$ tends to $f_{n}$ in $\mathscr{S}\left(\mathbb{R}^{v n}\right)$ and the inequality (5) is obtained in the limit $a \rightarrow \infty$ (see Appendix).

## III. Proof of Theorem 2

In this section, we start from a set of "Schwinger functions" satisfying $S 1$ ), $\ldots, S 4$ ) and construct first the operators $\mathcal{O}\left(y_{1}, \ldots, y_{n}\right)$. Then the growth condition S6) is used to define the distribution $\left(\Omega, \mathcal{O}\left(X_{1}\right) e^{i w_{1} H} \ldots e^{i w_{r-1} H} \mathcal{O}\left(X_{r}\right) \Omega\right)$ from which the anti-time-ordered distributions can be obtained by a purely linear operation (although the vector formalism will be used for notational simplicity).

## III. 1. Construction of the Operators $\mathcal{O}(Y)$

Let $\left\{S_{n}\right\}$ be a sequence of tempered distributions satisfying $S 1$ ) to $S 4$ ). Let $\mathscr{S}$ denote the vector space of finite sequences $\left\{f_{n}\right\}$ (with arbitrary length) with $f_{n} \in \mathscr{S}\left(\mathbb{R}^{v n}\right)$, equipped with the natural (direct topological sum) topology. $\mathscr{S}_{+}$will denote the subspace of $\mathscr{S}$ consisting of the finite sequences $\left\{f_{n}\right\}$ such that, for each $n \geqq 1$

$$
\text { supp. } f_{n} \subset\left\{\left(y_{1}, \ldots, y_{n}\right): y_{1}^{0} \geqq 0, \ldots, y_{n}^{0} \geqq 0\right\}
$$

For each real $t$, we denote $L_{t}$ the operator defined on $\mathscr{S}$ by

$$
\left(L_{t} f\right)_{n}\left(y_{1}, \ldots, y_{n}\right)=f_{n}\left(\left(y_{1}^{0}-t, \mathbf{y}_{1}\right), \ldots,\left(y_{n}^{0}-t, \mathbf{y}_{n}\right)\right)
$$

When $t$ is $\geqq 0, L_{t}$ maps $\mathscr{S}_{+}$into itself, and $t \rightarrow L_{t},(t \geqq 0)$ is a continuous semi-group of continuous operators on $\mathscr{S}_{+}$.

$$
\text { If } f=\left\{f_{n}\right\} \text { is an element of } \mathscr{S} \text { we denote } S(f)=\sum_{n=0}^{\infty} S_{n}\left(f_{n}\right) \text {. If } g \text { is also an element }
$$ of $\mathscr{S}$, we denote

$$
\Theta g=\left\{\Theta g_{n}\right\},\left(\Theta g_{n}\right)\left(y_{1}, \ldots, y_{n}\right)=\overline{g_{n}\left(\left(-y_{n}^{0}, \mathbf{y}_{n}\right), \ldots,\left(-y_{1}^{0}, \mathbf{y}_{1}\right)\right)} .
$$

We also write

$$
(g \otimes f)_{n}\left(y_{1}, \ldots, y_{n}\right)=\sum_{p+q=n} g_{p}\left(y_{1}, \ldots, y_{p}\right) f_{q}\left(y_{p+1}, \ldots, y_{p+q}\right)
$$

and note the following algebraic rules:
$L_{s}(g \otimes f)=L_{s} g \otimes L_{s} f$ for all $s \in \mathbb{R}, f$ and $g$ in $\mathscr{S}$,
$L_{s} \Theta f=\Theta L_{-s} f$ for all $s \in \mathbb{R}, f$ in $\mathscr{S}$.
The map from $\mathscr{S}_{+} \times \mathscr{S}_{+}$into $\mathbb{C}$ defined by

$$
(g, f) \rightarrow S(\Theta g \otimes f)
$$

is continuous, sesquilinear, and by $S 4$ ), positive in the sense that

$$
S(\Theta f \otimes f) \geqq 0 \quad \text { for all } \quad f \in \mathscr{S}_{+} .
$$

Let $\mathscr{N}$ be the subspace of all $f \in \mathscr{S}_{+}$such that for all $g \in \mathscr{S}_{+}$,

$$
S(\Theta f \otimes g)=0 .
$$

Because of the Schwarz inequality

$$
|S(\Theta f \otimes g)|^{2} \leqq S(\Theta f \otimes f) S(\Theta g \otimes g)
$$

so that

$$
\mathscr{N}=\left\{f \in \mathscr{S}_{+}: S(\Theta f \otimes f)=0\right\}
$$

For all $s \in \mathbb{R}, f$ and $g$ in $\mathscr{S}$ we have

$$
\begin{equation*}
S\left(\Theta g \otimes L_{s} f\right)=S\left(L_{-s}\left(\Theta g \otimes L_{s} f\right)\right)=S\left(L_{-s} \Theta g \otimes f\right)=S\left(\Theta L_{s} g \otimes f\right) \tag{37}
\end{equation*}
$$

Hence for $s \geqq 0, L_{s} \mathcal{N} \subset \mathscr{N}$.
The space $\mathscr{S}_{+} / \mathscr{N}$ is a separated pre-Hilbert space and can be completed into a Hilbert space $\mathscr{H}$. We denote $\Psi$ the canonical map of $\mathscr{S}_{+}$into $\mathscr{H}$, and, in particular, $\Psi\left(\left\{f_{0}=1, \ldots, f_{n}=0, \ldots\right\}\right)=\Omega$. By definition $\Psi\left(\mathscr{S}_{+}\right)$is dense in $\mathscr{H}$ and for $f, g$ in $\mathscr{S}_{+}$:
$(\Psi(g), \Psi(f))=S(\Theta g \otimes f)$.
The map $\Psi$ is continuous from $\mathscr{S}^{+}$to $\mathscr{H}$. Since $L_{t} \mathcal{N} \subset \mathscr{N}$ for any $t \geqq 0$, we can define, for each $t \geqq 0$, an operator $P_{t}$ on $\Psi\left(\mathscr{S}_{+}\right)$with the properties

$$
\begin{aligned}
P_{t} \Psi(g) & =\Psi\left(L_{t} g\right) \quad \text { for all } \quad g \in \mathscr{S}_{+}, \\
P_{t+s} & =P_{t} P_{s} \quad \text { for all } \quad s \geqq 0, t \geqq 0, \\
\left(\Psi(g), P_{t} \Psi(f)\right) & \left.=\left(P_{t} \Psi(g), \Psi(f)\right) \quad \text { (all } t \geqq 0, f \text { and } g \text { in } \mathscr{S}_{+}\right), \\
\left\|P_{t} \Psi(f)\right\| & \leqq(1+t)^{B(f)} C(f) \quad\left(\text { all } t \geqq 0, f \in \mathscr{S}_{+}\right) .
\end{aligned}
$$

Moreover $t \rightarrow P_{t} \Psi(f)$ is a continuous map of $[0, \infty)$ into $\mathscr{H}$ for every fixed $f \in \mathscr{S}_{+}$.
Following Osterwalder and Schrader we conclude that, for all $t \geqq 0$ and all $f \in \mathscr{S}_{+}$,

$$
\begin{aligned}
\left(\Psi(f), P_{t} \Psi(f)\right) & \leqq\|\Psi(f)\|\left(\Psi(f), P_{2 t} \Psi(f)\right)^{\frac{1}{2}} \\
& \leqq \ldots \leqq\|\Psi(f)\|^{1+\frac{1}{2}+\ldots+2^{-r}}\left(\Psi(f), P_{2^{r+1} t} \Psi(f)\right)^{2-r-1}
\end{aligned}
$$

and, passing to the limit:

$$
\left(\Psi(f), P_{t} \Psi(f)\right) \leqq\|\Psi(f)\|^{2}
$$

It follows that $P_{t}$ can be extended by continuity to all of $\mathscr{H}$ and defines a continuous contraction semi-group. In particular
$P_{t}=e^{-t H}$
where $H$ is a positive self adjoint operator whose domain contains $\Psi\left(\mathscr{S}_{+}\right)$. (In fact $\Psi\left(\mathscr{S}_{+}\right)$contains all vectors of the form

$$
e^{-t H} \Psi(g)=\Psi\left(L_{t} g\right), \quad t>0
$$

These are a dense set of analytic vectors for $H$, and thus a core for $H$.) In particular

$$
P_{t} \Omega=\Omega, \quad H \Omega=0
$$

If $\Phi_{1}$ and $\Phi_{2}$ are vectors in $\mathscr{H}$, we can define

$$
\left(\Phi_{1}, e^{i(u+i v) H} \Phi_{2}\right)
$$

provided $v \geqq 0$; this is a holomorphic function of $u+i v$ for $v>0$, continuous for $v=0$; if $\Phi_{2}$ (or $\left.\Phi_{1}\right)$ is in $\Psi\left(\mathscr{S}_{+}\right)$this function is even $C^{\infty}$ in the closed upper half plane. We also note that for $t \geqq 0, e^{-t H}$ is invertible, its inverse $e^{t H}$ having as its domain precisely $e^{-t H} \mathscr{H}$.

Let $g \in \mathscr{P}$. The projected support of $g$, denoted Proj. supp. $g$ is the closed subset of $\mathbb{R}$ defined as the closure of

$$
\left\{t \in \mathbb{R}: \exists m>0, \exists\left(y_{1}, \ldots, y_{m}\right) \in \operatorname{supp} . g_{m}, \exists 1 \leqq j \leqq m \text { with } y_{j}^{0}=t\right\}
$$

For any $t \in \mathbb{R}$, the condition $g \in L_{t} \mathscr{S}_{+}$is equivalent to
$t \leqq$ inf Proj. supp. $g$
and the condition $\Theta g \in L_{-t} \mathscr{S}_{+}$is equivalent to
sup Proj. supp. $g \leqq t$.
Let $f, g$, and $h$ belong to $\mathscr{S}_{+}$, with
$0<$ supp. Proj. supp. $g=T<\infty$.
For any $s \geqq T$,

$$
\begin{aligned}
S\left(\Theta h \otimes g \otimes L_{s} f\right) & =S\left(L_{-s}\left(\Theta h \otimes g \otimes L_{s} f\right)\right) \\
& =S\left(L_{-s} \Theta h \otimes L_{-s} g \otimes f\right)=S\left(\Theta L_{s} h \otimes L_{-s} g \otimes f\right) \\
& =S\left(\Theta\left(\Theta L_{-s} g \otimes L_{s} h\right) \otimes f\right)=S\left(\Theta\left(L_{s} \Theta g \otimes L_{s} h\right) \otimes f\right) .
\end{aligned}
$$

This shows that, for fixed $g$ and $s$, the map from $\mathscr{S}_{+}$to $\mathscr{S}_{+}$

$$
f \rightarrow g \otimes L_{s} f
$$

maps $\mathcal{N}$ into itself. We therefore define an operator $\Psi\left(\mathscr{S}_{+}\right) \rightarrow \Psi\left(\mathscr{S}_{+}\right)$by:

$$
\begin{equation*}
\mathcal{O}_{s}(g) \Psi(f)=\Psi\left(g \otimes L_{s} f\right) \tag{38}
\end{equation*}
$$

Note that the right hand side is a continuous function of $(s, g, f)$; it is even $\mathscr{C}^{\infty}$ in $s$ for $s \geqq T$. Furthermore the adjoint of this operator also maps $\Psi\left(\mathscr{S}_{+}\right)$into itself. It is given, on $\Psi\left(\mathscr{S}_{+}\right)$, by

$$
\mathcal{O}_{s}(g)^{*} \Psi(h)=\Psi\left(L_{s} \Theta g \otimes L_{s} h\right)=\mathcal{O}_{s}\left(L_{s} \Theta g\right) \Psi(h) .
$$

Clearly, for $t \geqq 0$,

$$
\mathcal{O}_{s}(g) e^{-t H}=\mathcal{O}_{s+t}(g) \quad \text { on } \quad \Psi\left(\mathscr{S}_{+}\right) .
$$

It is possible to write $\mathcal{O}_{s}(g)=\mathcal{O}(g) e^{-s H}$, where $\mathcal{O}(g)$ is defined on $e^{-s H} \Psi\left(\mathscr{S}_{+}\right)$. Indeed $e^{-s H} \Psi\left(\mathscr{S}_{+}\right)=\Psi\left(L_{s} \mathscr{S}_{+}\right)$.

Any $u \in L_{s} \mathscr{S}_{+}$can be written uniquely as $L_{s} v, v \in \mathscr{S}_{+}$and $u \in \mathscr{N} \Leftrightarrow \Psi(u)=0 \Leftrightarrow \forall g$, $\left(\Psi(g), e^{-s H} \Psi(v)\right)=0 \Rightarrow \Psi(v)=0$. Thus $u \in \mathcal{N} \Leftrightarrow v \in \mathcal{N}$ and we can define

$$
\begin{equation*}
\mathcal{O}(g) \Psi(u)=\mathcal{O}_{s}(g) \Psi(v)=\Psi(g \otimes u) . \tag{39}
\end{equation*}
$$

We shall verify that these operators satisfy the properties (01)-O6), with $D_{1}$ replaced by a new domain $D_{2}$ to be defined later.

It will be convenient to use the notation

$$
\int \mathcal{O}\left(y_{1}, \ldots, y_{n}\right) f\left(y_{1}, \ldots, y_{n}\right) d y_{1} \ldots d y_{n}
$$

for $\mathcal{O}(g)$ when $g=\{0, \ldots, f, 0, \ldots\}$, and similarly

$$
\mathcal{O}_{s}\left(y_{1}, \ldots, y_{n}\right)=\mathcal{O}\left(y_{1}, \ldots, y_{n}\right) e^{-s H}
$$

The construction of these operators does not depend on the symmetry property $S 2$ ). If $S 2$ ) holds, for every permutation $\pi$ of $(1, \ldots, n)$,

$$
\left.\mathcal{O}\left(y_{1}, \ldots, y_{n}\right)=\mathcal{O}\left(y_{\pi 1}, \ldots, y_{\pi n}\right),(\text { this is } \mathcal{O} 3)\right) .
$$

This will allow us to use the abbreviated notation $\mathcal{O}(Y)$ as before.
It is also clearly possible to define,

$$
\begin{align*}
& G_{f}\left(i v_{0}, \ldots, i v_{r-1}\right)=\int e^{-v_{0} H} \mathcal{O}\left(Y_{1}\right) e^{-v_{1} H} \mathcal{O}\left(Y_{2}\right) \ldots e^{-v_{r-1} H} \mathcal{O}\left(Y_{r}\right) \Omega  \tag{40}\\
& \quad f\left(y_{1}, \ldots, y_{N}\right) d y_{1} \ldots d y_{N} .
\end{align*}
$$

Here $v_{0}, \ldots, v_{r-1}$, are all $\geqq 0 ; \quad Y_{1}=\left\{1, \ldots, n_{1}\right\}, \quad Y_{2}=\left\{n_{1}+1, \ldots, n_{2}\right\}, \ldots, Y_{r}$ $=\left\{n_{r-1}+1, \ldots, n_{r}=N\right\}$, are disjoint non empty subsets of $\{1, \ldots, N\}$ with union $\{1, \ldots, N\} . f \in \mathscr{S}\left(\mathbb{R}^{v n}\right)$ has its support in

$$
\begin{equation*}
\left\{\left(y_{1}, \ldots, y_{N}\right) \in \mathbb{R}^{v N}: y_{j}^{0} \leqq y_{k}^{0} \quad \text { if } \quad j \in Y_{t} \quad \text { and } \quad k \in Y_{u} \quad \text { with } \quad t<u\right\} \tag{41}
\end{equation*}
$$

The precise definition of (40) is $\Psi(g)$ where $g_{p}=\delta_{p N} g_{N}$ and

$$
\begin{align*}
& g_{N}\left(y_{1}, \ldots, y_{N}\right)=f\left(\left(y_{1}^{0}-v_{0}, \mathbf{y}_{1}\right), \ldots,\left(y_{n_{1}}^{0}-v_{0}, \mathbf{y}_{n_{1}}\right)\right. \\
& \left.\quad\left(y_{n_{1}+1}^{0}-v_{0}-v_{1}, \mathbf{y}_{n_{1}+1}\right), \ldots,\left(y_{N}^{0}-v_{0}-\ldots-v_{r-1}, \mathbf{y}_{N}\right)\right) \tag{42}
\end{align*}
$$

It will prove convenient to use an adaptation of the method of [OS2] for regularizing the behavior of $S_{n}\left(x_{1}, \ldots, x_{n}\right)$ at large distances, based on the following remark.

If $\left\{S_{n}^{\prime}\right\}$ and $\left\{S_{n}^{\prime \prime}\right\}$ are two systems of distributions satisfying $S 1$ ), $S 3$ ), $S 4$ ), and if it is possible to define the pointwise product $S_{n}^{\prime \prime \prime}\left(x_{1}, \ldots, x_{n}\right)=S_{n}^{\prime}\left(x_{1}, \ldots, x_{n}\right) S_{n}^{\prime \prime}\left(x_{1}, \ldots, x_{n}\right)$,
(e.g. as a limit of $S_{n}^{\prime} \cdot\left(S_{n}^{\prime \prime} * \varrho\right)$ as $\varrho \rightarrow \delta$ ), then $\left\{S_{n}^{\prime \prime \prime}\right\}$ also satisfies $\left.S 1\right), S 3$ ), $S 4$ ). Indeed, for every finite sequence $\left\{f_{n}\right\}$ such that $f_{n} \in \mathscr{S}\left(\mathbb{R}^{\nu n}\right)$ and supp. $f_{n} \subset\left\{\left(x_{1}, \ldots, x_{n}\right) \mid 0 \leqq x_{j}^{0}, 1 \leqq j\right.$ $\leqq n\}$,

$$
\begin{aligned}
& \sum_{n, m} S_{n+m}^{\prime \prime \prime}\left(\Theta f_{m} \otimes f_{n}\right)=\sum_{m, n} \int\left(\left[\mathcal{O}^{\prime}\left(x_{1}, \ldots, x_{m}\right) \otimes \mathcal{O}^{\prime \prime}\left(x_{1}, \ldots, x_{m}\right)\right] \Omega^{\prime} \otimes \Omega^{\prime \prime},\right. \\
& \left.\quad\left[\mathcal{O}^{\prime}\left(y_{1}, \ldots, y_{n}\right) \otimes \mathcal{O}^{\prime \prime}\left(y_{1}, \ldots, y_{n}\right)\right] \Omega^{\prime} \otimes \Omega^{\prime \prime}\right) \overline{f_{m}\left(x_{1}, \ldots, x_{m}\right)} f_{n}\left(y_{1}, \ldots, y_{n}\right) \\
& \quad d x_{1} \ldots d x_{m} d y_{1} \ldots d y_{n} .
\end{aligned}
$$

An example $\left\{\Xi_{n}\right\}$ of a sequence of distributions satisfying $S 1$ ), S3), and almost $S 4$ ) is given by

$$
\Xi_{N}\left(x_{1}, \ldots, x_{N}\right)=F_{N}\left(x_{1}^{0}-x_{N}^{0}\right), \quad N \geqq 2,
$$

where, for every real $t$,

$$
F_{N}(t)=\int_{0}^{\infty} e^{-p|t|} h(p)^{N} \sigma(p) d p
$$

and where $h$ and $\sigma$ are real functions, $\sigma \geqq 0$, so chosen that the above integral is absolutely convergent and continuous in $t$ on $[0, \infty)$.

Indeed one finds, for all finite sequences $\left\{f_{n}\right\}$ as above, with $f_{0}=0$,

$$
\sum_{m, n} \Xi_{m+n}\left(\Theta f_{m} \otimes f_{n}\right)=\sum_{m, n} \int_{0}^{\infty} d p \sigma(p) \overline{c_{m}(p)} c_{n}(p)=\int_{0}^{\infty} d p \sigma(p)\left|\sum_{n} c_{n}(p)\right|^{2},
$$

where
$c_{n}(p)=\int e^{-p x_{n}^{0}} h(p)^{n} f_{n}\left(x_{1}, \ldots, x_{n}\right) d x_{1} \ldots d x_{n}$.
More specifically, we choose $\sigma(p)=e^{-p}, h(p)=p^{R}, R \geqq 0$, so that

$$
F_{N}(t)=(R N)!(|t|+1)^{-R N-1} .
$$

With this choice, we denote $\mathscr{H}_{0}, \Psi_{0}^{\prime}(f), \mathcal{O}_{0}\left(x_{1}, \ldots, x_{n}\right) \equiv \mathcal{O}_{0}\left(x_{1}^{0}, \ldots, x_{n}^{0}\right), H_{0}$ the objects obtained from $\left\{\Xi_{n}\right\}$ by the preceding construction.

We return to the original sequence $\left\{S_{n}\right\}$ satisfying $S 1$ ),,$S 4$ ) and the growth condition $S 6$ ). For every $N>1$ and $f \in \mathscr{S}\left(\mathbb{R}^{v n j}\right), n_{j} \geqq 1$, Proj. supp. $f_{j}$ $\leqq$ Proj. supp. $f_{j+1},(j=1, \ldots, r-1)$, and $\left(v_{1}, \ldots, v_{r-1}\right) \in[0, \infty)^{r-1}$, we denote:

$$
S_{N}\left(f_{1}, \ldots, f_{r} ; i v_{1}, \ldots, i v_{r-1}\right)=S_{N}\left(f_{1} \otimes L_{v_{1}} f_{2} \otimes \ldots \otimes L_{v_{1}+\ldots+v_{r-1}} f_{r}\right)
$$

and

$$
\begin{align*}
& \hat{S}_{N}\left(f_{1}, \ldots, f_{r} ; i v_{1}, \ldots, i v_{r-1}\right)=\int S_{N}\left(x_{1}, \ldots, x_{N}\right) F_{N}\left(y_{1}-y_{r}\right) \\
& \quad\left(f_{1} \otimes L_{v_{1}} f_{2} \otimes \ldots \otimes L_{v_{1}+\ldots+v_{r-1}} f_{r}\right)\left(x_{1}, \ldots, x_{N}\right) d x_{1} \ldots d x_{N} \tag{43}
\end{align*}
$$

where $y_{j}=n_{j}^{-1}\left(x_{n_{1}+\ldots+n_{j-1}+1}^{0}+\ldots+x_{n_{1}+\ldots+n_{j}}^{0}\right), \quad 1 \leqq j \leqq r$.
If, in particular $0 \leqq$ Proj.supp. $f_{1} \leqq T_{1}$, the expression (43) is equal to

$$
\left(\Psi^{\prime}\left(L_{T_{1}} \Theta f_{1}\right), e^{-v_{1} H^{\prime}} \mathcal{O}^{\prime}\left(L_{-T_{1}} f_{2}\right) \ldots e^{-v_{r}-1 H^{\prime}} \Psi^{\prime}\left(L_{-T_{1}} f_{r}\right)\right),
$$

with $H^{\prime}=H \otimes 1+1 \otimes H_{0}$, and

$$
\mathcal{O}^{\prime}(f)=\int \mathcal{O}\left(x_{1}, \ldots, x_{n}\right) \otimes \mathcal{O}_{0}\left(\frac{1}{n} \sum_{j=1}^{n} x_{j}^{0}\right) f\left(x_{1}, \ldots, x_{n}\right) d x_{1} \ldots d x_{n},
$$

and similarly, for $\Psi^{\prime}(f)$.

We shall restrict our attention to the case when all $n_{j}$ are bounded by a fixed integer $Q$. In that case it follows from the growth condition $S 6$ ) and from a repeated use of the theorem in [OS2, appendix], that there exist constants $C, K, S$, independent of $N$, such that, for all $N>1, r>1,(N \leqq Q r), f_{1}, \ldots, f_{r}$, (with supports as above),

$$
\left|\hat{S}_{N}\left(f_{1}, \ldots, f_{r} ; 0, \ldots, 0\right)\right| \leqq C^{N}(N!)^{K}\left(\prod_{1<j<r}\left|f_{j}\right| S\right)\left|\frac{f_{1} \otimes f_{r}}{\left(1+\left|y_{1}-y_{r}\right|\right)^{N R+1}}\right|_{S}
$$

Since the l.h.s. is invariant under simultaneous translations of all arguments, we can evaluate it by first performing a time translation such that Proj. supp. $f_{1} \leqq 0 \leqq$ Proj. supp. $f_{r}$. In that situation, the r.h.s. can be rewritten as

$$
C^{N}(N!)^{K} \sup _{\substack{x \\ \text { and } \\\left(\alpha_{j} \beta_{j}^{j} \leq \leq S \\ \boldsymbol{\beta}_{j} \text { restricted }\right)}}\left[\left.\prod_{1<j<r}\left|x^{\alpha_{j}} D^{\beta_{j}} f_{j}(x)\right|| | x^{\alpha_{1}} x^{\alpha_{r}} D^{\beta_{1}} D^{\beta_{r}} \frac{\left(f_{1} \otimes f_{r}\right)(x)}{\left(1+y_{r}-y_{1}\right)^{N R+1}} \right\rvert\, .\right.
$$

Since $\left|D^{\beta_{1}} D^{\beta_{r}}\left(1+y_{r}-y_{1}\right)^{-N R-1}\right| \leqq(N R+2 S)^{2 S}\left(1+y_{r}-y_{1}\right)^{-N R-1}$ and since

$$
Q y_{1} \leqq x_{j}^{0} \leqq Q y_{r}, \quad \text { i.e. } \quad\left|x_{j}^{0}\right| \leqq Q\left(1+y_{r}-y_{1}\right)
$$

if we choose $R=S$, there are new constants independent of $N$, such that

$$
\left|\hat{S}_{N}\left(f_{1}, \ldots, f_{r} ; 0, \ldots, 0\right)\right| \leqq C^{\prime N}(N!)^{K^{\prime}} \prod_{j=1}^{r} \sup _{\substack{x \\
|\alpha| \\
\left\lvert\, \begin{array}{l}
x \\
\leqq S S
\end{array}\right.}}\left|\mathbf{x}^{\alpha} D^{\beta} f_{j}(x)\right| .
$$

Since these new norms are invariant under time translations, this inequality remains valid when the $f_{j}$ are (time-) translated back to their original position, and, for all $v_{j} \geqq 0,(1 \leqq j \leqq r-1)$,

$$
\begin{aligned}
&\left.\left|\hat{S}_{N}\left(f_{1}, \ldots, f_{r} ; v_{1}, \ldots, v_{r-1}\right)\right| \leqq C_{N}^{\prime}(N!)^{K^{\prime}} \prod_{j=1}^{r}\right\} f_{j} \xi_{S}, \\
& \xi f \xi_{S}=\sup _{\substack{x \\
x \\
|\alpha| \leq S \\
\mid>S}}\left|\mathbf{x}^{\alpha} D^{\beta} f_{j}(x)\right| .
\end{aligned}
$$

This bound and the positivity which $\left\{\hat{S}_{N}\right\}$ inherits from $\left\{S_{N}\right\}$ allow us to follow the method of [G1,OS2] and to obtain an analytic function

$$
\left(w_{1}, \ldots, w_{r-1}\right) \rightarrow \hat{S}_{N}\left(f_{1}, \ldots, f_{r} ; w_{1}, \ldots, w_{r-1}\right)
$$

continuing $\hat{S}_{N}\left(f_{1}, \ldots, f_{r} ; i v_{1}, \ldots, i v_{r-1}\right)$ in the topological product of $r-1$ upper half planes.

To do this in a systematic way we consider a sequence $f_{1}, \ldots, f_{r}$ such that $0 \leqq T_{j-1} \leqq$ Proj. supp. $f_{j} \leqq T_{j}$. Then

$$
\begin{align*}
& \left(\Psi^{\prime}(g), e^{-v_{0} H^{\prime}} \mathcal{O}^{\prime}\left(f_{1}\right) e^{-v_{1} H^{\prime}} \mathcal{O}^{\prime}\left(f_{2}\right) \ldots e^{-v_{r-1} H^{\prime}} \Psi^{\prime}\left(f_{r-1}\right)\right) \\
& \quad=\left(\mathcal{O}^{\prime}\left(L_{T_{j}} \Theta f_{j}\right) e^{-v_{j-1} H^{\prime}} \ldots e^{-v_{1} H^{\prime}} \mathcal{O}^{\prime}\left(L_{T_{j}} \Theta f_{1}\right) e^{-\left(v_{0}+T_{j}\right) H^{\prime}} \Psi^{\prime}(g),\right.  \tag{44}\\
& \left.\quad e^{-v_{j} H^{\prime}} \mathcal{O}^{\prime}\left(L_{-T_{j}} f_{j+1}\right) \ldots e^{-v_{r-1} H^{\prime}} \Psi^{\prime}\left(L_{-T} T_{j} f_{r}\right)\right)
\end{align*}
$$

The r.h.s. continues to make sense if $e^{-v_{j} H^{\prime}}$ is replaced by $e^{i w_{j} H^{\prime}}$ with $\operatorname{Im} w_{j}>0$. Thus the l.h.s. is analytically continuable in each $v_{j}$ while the others are kept fixed so that as a function of $i v_{0}, \ldots, i v_{r-1}$, it has an analytic continuation in

$$
C_{r}^{(1)}=\left\{\left(w_{0}, \ldots, w_{r-1}\right)| | \operatorname{Arg}-i w_{j} \mid<\Theta_{j}, \sum \Theta_{j} \leqq \frac{\pi}{2}\right\}
$$

Moreover the methods of [G1, OS2] show that in a smaller domain $D_{r}^{(1)}$ it is bounded by Const. $\left\|\Psi^{\prime}(g)\right\|$ and thus it defines a vector valued holomorphic function on $D_{r}^{(1)}$ denoted

$$
G_{f_{1} \otimes \ldots \otimes f_{r}}^{\prime}\left(w_{0}, \ldots, w_{r-1}\right)=e^{i w_{0} H^{\prime}} \mathcal{O}^{\prime}\left(f_{1}\right) \ldots e^{i w_{r-1} H^{\prime}} \Psi^{\prime}\left(f_{r-1}\right)
$$

The formula (44) can be analytically continued to:

$$
\begin{aligned}
\left(\Psi^{\prime}(g)\right. & \left., e^{i w_{0} H^{\prime}} \mathcal{O}^{\prime}\left(f_{1}\right) \ldots e^{i w_{r-1} H^{\prime}} \Psi^{\prime}\left(f_{r}\right)\right) \\
= & \left(\mathcal{O}^{\prime}\left(L_{T_{j}} \Theta f_{j}\right) e^{-i \bar{w}_{j-1} H^{\prime}} \mathcal{O}^{\prime}\left(L_{T_{j}} \Theta f_{j-1}\right) \ldots e^{-i \bar{w}_{1} H^{\prime}} \mathcal{O}^{\prime}\left(L_{T_{j}} \Theta f_{1}\right) e^{-\left(i \bar{w}_{0}+T_{j}\right) H^{\prime}} \Psi^{\prime}(g)\right. \\
& \left.e^{i w_{J} H^{\prime}} \mathcal{O}^{\prime}\left(L_{-T_{J}} f_{j+1}\right) \ldots e^{i w_{r-1} H^{\prime}} \Psi^{\prime}\left(L_{-T_{J}} f_{r}\right)\right)
\end{aligned}
$$

(Here $\Psi^{\prime}(g)$ is also supposed to be of the form $\mathcal{O}^{\prime}\left(g_{0}\right) e^{-s_{1} H^{\prime}} \ldots e^{-s_{p} H^{\prime}} \Psi^{\prime}\left(g_{p}\right)$ ). Hence one can iterate the procedure and eventually obtain the analyticity of the vector $G^{\prime}$ in the topological product of $r$ upper half planes. To obtain bounds on its norm in this domain, it is necessary to apply the Schwarz inequality at each iteration. This involves, as in [OS2] a doubling of the number of variables and also a doubling of the number of $f_{j}$ 's which also have to be time-translated. However, since the norms $\left.\} f_{j}\right\}_{S}$ occurring in the initial bounds are invariant under these time-translations, the result is the same as in [OS2]:

The vector $G_{f_{1} \otimes \ldots \otimes f_{n}}^{\prime}\left(w_{0}, \ldots, w_{r-1}\right)$ is analytic in the product of upper halfplanes and is bounded there by

$$
\left\|G_{f_{1} \otimes \ldots \otimes f_{r}}^{\prime}\left(w_{0}, \ldots, w_{r-1}\right)\right\|<B_{N}^{\prime} \prod_{j=1}^{r} \xi f_{j} \xi s(1+|w|)^{K_{N}^{\prime}}\left(\prod_{j=1}^{r-1} v_{j}^{-K_{N}^{\prime}}\right)
$$

where $|w|=\sum_{j=0}^{r-1}\left|w_{j}\right|$ and $v_{j}=\operatorname{Im} w_{j}$. Using again [OS2, Appendix] this implies for every $f$ with support in (41)

$$
\left\|G_{f}^{\prime}\left(w_{0}, \ldots, w_{r-1}\right)\right\|<B_{N}^{\prime \prime} \xi f\left\{\xi_{s^{\prime}(N)}(1+|w|)^{K_{N}^{\prime}}\left(\prod_{j=1}^{r-1} v_{j}^{-K_{N}^{\prime}}\right)\right.
$$

Going back to the original functions (cf. (40)), we get:
There are constants $K_{N}$ and $B_{N}$ such that, for all $\left(w_{0}, \ldots, w_{r-1}\right)$ with $w_{j}=u_{j}+i v_{j}$, $v_{j}>0$

$$
\left\|G_{f}\left(w_{0}, \ldots, w_{r-1}\right)\right\|<B_{N}|f|_{K_{N}}\left(\sup _{a \leqq j \leqq r-1} v_{j}^{-K_{N}}\right)(1+|w|)^{K_{N}}
$$

However if $f$ is sufficiently regular, differentiation in $w_{0}, \ldots, w_{r}$ can be transferred to $f$ so that

$$
\left\|D_{w}^{\alpha} G_{f}\left(w_{0}, \ldots, w_{r-1}\right)\right\|<A_{N}^{\prime}|f|_{K_{N}+|a|}\left(\sup _{j} v_{j}^{-K_{N}}\right)(1+|w|)^{K_{N}}
$$

and, reintegrating $K_{N}+1$ times we find new constants such that

$$
\left\|D_{w}^{\alpha} G_{f}\left(w_{0}, \ldots, w_{r-1}\right)\right\|<A_{N}|f|_{2 K_{N}+|\alpha|+1}(1+|w|)^{K_{N}} .
$$

(In particular if $f \in \mathscr{S}, G$ is $\mathscr{C}^{\infty}$ in $w_{0}, \ldots, w_{r-1}$ in the topological product of $r$ closed upper half planes). The vector $G_{f}\left(w_{0}, \ldots, w_{r-1}\right)$ will also be denoted

$$
\int e^{i w_{0} H} \mathcal{O}\left(Y_{1}\right) e^{i w_{1} H} \ldots e^{i w_{r}-1 H} \mathcal{O}\left(Y_{r}\right) \Omega \quad f\left(y_{1}, \ldots, y_{N}\right) d y_{1} \ldots d y_{N}
$$

This notation is justified since it is easy to show that this vector is in the domain of the closure of $\mathcal{O}(g)$ (provided $g \otimes f$ is sufficiently smooth and has the correct support), and that we have $(\mathcal{O}(g)$ being identified with its closure, as we shall always do in the sequel),

$$
\begin{aligned}
& e^{i w H} \mathcal{O}(g)\left\{\int e^{i w_{0} H} \mathcal{O}\left(Y_{1}\right) \ldots e^{i w_{r-1} H} \mathcal{O}\left(Y_{r}\right) \Omega f\left(y_{1}, \ldots, y_{N}\right) d y_{1} \ldots d y_{N}\right\} \\
&= \int e^{i w H} \mathcal{O}\left(\xi_{1}, \ldots, \xi_{R}\right) e^{i w_{0} H} \mathcal{O}\left(Y_{1}\right) \ldots e^{i w_{r}-1} \mathcal{O}\left(Y_{r}\right) \Omega \\
& g_{R}\left(\xi_{1}, \ldots, \xi_{R}\right) f\left(y_{1}, \ldots, y_{N}\right) d \xi_{1} \ldots d \xi_{R} d y_{1} \ldots d y_{N} .
\end{aligned}
$$

Also in the domain of the closure of $\mathcal{O}(g)$ are the vectors obtained from the preceding by integrating over the $w_{j}$ along paths with suitable test-functions etc. The intersection of the domains of the closures of all finite products $\mathcal{O}\left(f_{1}\right) e^{i w_{1} H} \ldots e^{i w_{r}-1 H} \mathcal{O}\left(f_{r}\right)$ is denoted $D_{2}$. It is straightforward to verify that the system
 domain $D_{2}$.

## III. 2. Inductive Construction of $\bar{T}(X)$

Starting from the operators $\mathcal{O}(X)$ obtained in III.1, the construction of the $\bar{T}(X)$ will be carried out by induction on $\{X \mid$. In fact, the requirements of causal factorization $T$ ), translational invariance $T 7$ ) and the relation $R^{\prime}$ ) will leave no freedom in this construction. The procedure very closely parallels that of II.1.

The induction hypothesis postulates that the operators $\bar{T}(X)$, for $\{X \mid \leqq n-1$, have already been constructed so as to satisfy the above requirements, and that any finite product of such operators can be applied to vectors of the domain $D_{2}$, which it maps into itself. (The domain $D_{2}$ has been defined at the end of III.1).

Let $X=\{1, \ldots, n\}$ and $Z=Z_{1} \bigcup \ldots \bigcup Z_{r}=\{n+1, \ldots, n+p\}$. Denote $x=\left(x_{1}, \ldots, x_{n}\right)$, $z=\left(z_{n+1} \ldots, z_{n+p}\right)$. For any $f \in \mathscr{S}\left(\mathbb{R}^{v(n+p)+1}\right)$ with support in

$$
\begin{equation*}
\left\{(x, v, z) \mid \text { for every } j \in Z_{a}, k \in Z_{b}, \text { with } a<b, z_{j}^{0} \leqq z_{k}^{0}\right\} \tag{45}
\end{equation*}
$$

for every $\left(w_{0}, \ldots, w_{r-1}\right) \in \mathbb{C}^{r}$ with $\operatorname{Im} w_{j} \geqq 0$ for all $j$, we propose to define the vector:

$$
\begin{align*}
& \int f\left(x_{1}, \ldots, x_{n}, v, z_{n+1}, \ldots, z_{n+p}\right) \bar{T}(X) e^{i\left(w_{0}+v\right) H} \mathcal{O}\left(Z_{1}\right)  \tag{46}\\
& \quad e^{i w_{1} H} \ldots e^{i w_{r-1} H} \mathcal{O}\left(Z_{r}\right) \Omega d x_{1} \ldots d x_{n} d v d z_{n+1} \ldots d z_{n+p} .
\end{align*}
$$

We concentrate on the case $n>1, Z \neq \emptyset$. The other cases are straightforward simplifications. Let $\mathscr{F}$ denote the subspace of $\mathscr{S}\left(\mathbb{R}^{v(n+p)+1}\right)$ consisting of functions having their support in (45). Denote, as in II.1,

$$
y=n^{-1}\left(x_{1}^{0}+\ldots+x_{n}^{0}\right), \quad \xi_{j}=x_{j}^{0}-y, \quad(1 \leqq j \leqq n), \quad \xi=\left(\xi_{1}, \ldots, \xi_{n-1}\right)
$$

and define $\mathscr{F}_{0}$ as the space of functions $f \in \mathscr{F}$ vanishing in a neighborhood of

$$
\left\{\left(x_{1}, \ldots, x_{n}, v, z\right): \xi=0\right\}
$$

Any function $f \in \mathscr{F}$ can be written in the form:

$$
\begin{equation*}
f\left(x_{1}, \ldots, x_{n}, v, z\right)=\int_{\mathbb{R}^{2}} d a d b \varphi(\xi, \mathbf{x}, a, b, z) \quad \alpha_{L}(y-a) \alpha_{L}(v-2 y-b+2 a) . \tag{47}
\end{equation*}
$$

Here, $\alpha_{L}$ is the function defined by (13) and, as previously, we find $\varphi$ is given by

$$
\begin{align*}
& \varphi(\xi, \mathbf{x}, y, v, z)=(L!)^{-2}\left(1-i+\frac{\partial}{\partial y}+2 \frac{\partial}{\partial v}\right)^{L+1}\left(1-i+\frac{\partial}{\partial v}\right)^{L+1} \\
& f\left(\left(\xi_{1}+y, \mathbf{x}_{1}\right), \ldots,\left(\xi_{n}+y, \mathbf{x}_{n}\right), v, z\right) . \tag{48}
\end{align*}
$$

The constant $L$ will be chosen later.
Just as in II.1, we decompose $f$ into $f=f_{0}+f_{1}$, with

$$
\begin{align*}
f_{1}(x, v, z)= & \int d a d b \alpha_{L}(y-a) \alpha_{L}(v-2 y-b+2 a)  \tag{49}\\
& \cdot\left[\sum_{|\beta|=0}^{M+1} \frac{\xi^{\beta}}{\beta!} D_{\xi}^{\beta} \varphi(0, \mathbf{x}, a, b, z)\right] w(\xi, y-a),
\end{align*}
$$

where $w$ is the auxiliary function used in II.1. and $M \geqq 0$ will be chosen later. Again,

$$
\left|f_{1}\right|_{M} \leqq \text { Const. }|f|_{2 M+2 L+3}, \quad(L \geqq M+1) .
$$

$f_{0}$ has the same property and vanishes together with its derivatives of order $\leqq M+1$ when $\xi=0$. Hence it is in the closure of $\mathscr{F}_{0}$ in the norm $\|_{M}$.

For any $g$ in $\mathscr{F}_{0}$ the vector (46) with $f$ replaced by $g$ is well defined by virtue of the induction hypothesis and the requirement of causal factorization. The proof is identical to the corresponding one in II.1. The resulting vector is bounded in norm by :

$$
\text { Const. }|g|_{K}(1+|w|)^{K}, \quad|w|=\sum_{j}\left|w_{j}\right| .
$$

As a consequence, if we choose $M \geqq K$, the vector obtained by replacing $f$ by $f_{0}$ in (46) is well-defined and bounded in norm by Const. $|f|_{2 M+2 L+3}(1+|w|)^{M}$. On the other hand, if we denote

$$
\begin{aligned}
\varphi_{0, \lambda}(\xi, y, v, \mathbf{x}, a, b, z)= & {\left[\sum_{|\beta|=0}^{M+1} \frac{(\lambda \xi)^{\beta}}{\beta!} D_{\xi}^{\beta} \varphi(0, \mathbf{x}, a, b, z)\right] } \\
& \cdot w(\xi, y) \alpha_{\lambda, L}(y) \alpha_{\lambda, L}(v-2 y),
\end{aligned}
$$

translational invariance requires, for sufficiently large $M$ and $L$

$$
\begin{align*}
& \int \bar{T}(X) e^{i\left(w_{0}+v\right) H} \mathcal{O}\left(Z_{1}\right) e^{i w_{1} H} \ldots e^{i w_{r-1} I I} \mathcal{O}\left(Z_{r}\right) \Omega \\
& \quad \varphi_{0,1}(\xi, y-a, v-b, \mathbf{x}, a, b, z) d x d v d z \\
& =\int e^{i a H} \bar{T}(X) e^{i\left(w_{0}+v+b-a\right) H} \mathcal{O}\left(Z_{1}\right) e^{i w_{1} H} \ldots e^{i w_{r-1} H} \mathcal{O}\left(Z_{r}\right) \Omega \\
& \quad n \varphi_{0,1}(\xi, y, v, \mathbf{x}, a, b, z) d v d \xi d y d \mathbf{x} d z \tag{50}
\end{align*}
$$

The radial analyticity of $\varphi_{0.1}$ and the condition $R^{\prime}$ ) require that (50) should be equal to:

$$
\begin{gather*}
\int e^{i a H} \mathcal{O}(X) e^{-v H} e^{i\left(w_{0}+b-a\right) H} \mathcal{O}\left(Z_{1}\right) \ldots e^{i w_{r}-1 H} \mathcal{O}\left(Z_{r}\right) \Omega  \tag{51}\\
n i^{n+1} \varphi_{0, i}(\xi, y, v, \mathbf{x}, a, b, z) d v d \xi d y d \mathbf{x} d z
\end{gather*}
$$

This is a well defined vector, depending continuously on $a$ and $b$, and bounded in norm by

$$
\text { Const. }(1+|a|+|b|)^{-3}|f|_{3 M+2 L+6}(1+|w|)^{M}
$$

We can integrate over $a$ and $b$ and define:

$$
\begin{align*}
& \int \bar{T}(X) e^{i\left(w_{0}+v\right) H} \mathcal{O}\left(Z_{1}\right) e^{i w_{1} H} \ldots \mathcal{O}\left(Z_{r}\right) \Omega f_{1}(x, v, z) d x d v d z \\
= & \int d a d b e^{i a H} \mathcal{O}(X) e^{\left(-v+i w_{0}+i b-i a\right) H} \mathcal{O}\left(Z_{1}\right) e^{i w_{1} H} \ldots \mathcal{O}\left(Z_{r}\right) \Omega  \tag{52}\\
& n \varphi_{0, i}(\xi, y, v, \mathbf{x}, a, b, z) i^{n+1} d \xi d y d v d \mathbf{x} d z
\end{align*}
$$

The definition of (46) is now the sum of (52) and of the known result for $f_{0} ; L$ must be $\geqq M+1$, and the resulting vector is bounded in norm by Const. $|f|_{3 M+2 L+6}(1+|w|)^{M}$.

It is now easy to check that, if $f$ happens to be radially analytic in the variables $x_{1}^{0}, \ldots, x_{n}^{0}, v$ and has support in $\left\{x, v, z: \forall j \in X, 0 \leqq x_{j}^{0} \leqq v\right\}$, this definition is such that $R^{\prime}$ ) is satisfied. We only give a brief sketch of this verification.

Suppose that $f \in \mathscr{F}$ is of the form (47) and

$$
f_{\lambda}(x, v, z)=f\left(\left(\lambda x_{1}^{0}, \mathbf{x}_{1}\right), \ldots,\left(\lambda x_{n}^{0}, \mathbf{x}_{n}\right), \lambda v, z\right), \quad(\lambda>0)
$$

can be analytically continued in $\lambda$ in the angle $0<\arg \lambda<\frac{\pi}{2}$, with continuity at the boundary. Then the same is true (by virtue of (48)) of

$$
\varphi_{\lambda}(\xi, \mathbf{x}, y, v, z)=\varphi(\lambda \xi, \mathbf{x}, \lambda y, \lambda v, z),
$$

(which also has support in $\left\{\left(x_{1}, \ldots, x_{n}, v, z\right) \mid \forall j \in X, 0 \leqq x_{j}^{0} \leqq v\right\}$ ), and of

$$
\begin{aligned}
f_{1, \lambda}(x, v, z)= & \lambda^{2} \int d a d b \alpha_{\lambda, L}(y-a) \alpha_{\lambda, L}(v-2 y-b+2 a) \\
& \cdot\left[\sum_{|\beta|=0}^{M+1} \frac{(\lambda \xi)^{\beta}}{\beta!} D_{\xi}^{\beta} \varphi(0, \mathbf{x}, \lambda a, \lambda b, z)\right] w(\xi, y-a) .
\end{aligned}
$$

As a consequence the l.h.s. of (52) should be equal to

$$
\begin{aligned}
& \int \mathcal{O}(X) e^{\left(i w_{0}-v\right) H} \mathcal{O}\left(Z_{1}\right) \ldots \mathcal{O}\left(Z_{r}\right) \Omega f_{1, i}(x, v, z) i^{n+1} d x d v d z \\
& =-\int d a d b e^{-a H} \mathcal{O}(X) e^{\left(i w_{0}-v-b+a\right) H} \mathcal{O}\left(Z_{1}\right) \ldots \mathcal{O}\left(Z_{r}\right) \Omega \\
& i^{n+1_{n}} \alpha_{i, L}(y) \alpha_{i, L}(v-2 y)\left[\sum_{|\beta|=0}^{M+1} \frac{(i \xi)^{\beta}}{\beta!} D_{\xi}^{\beta} \varphi(0, \mathbf{x}, i a, i b, z)\right] w(\xi, y) d \xi d \mathbf{x} d y d z d v .
\end{aligned}
$$

Noting that $D_{\xi}^{\beta} \varphi(0, \mathbf{x}, \lambda a, \lambda b, z)$ can be analytically continued in $\lambda$ (and has support in $\{b-a \geqq 0\}$ ), we can rotate the contours in $a$ and $b$ and obtain exactly (52). As to the part of (45) corresponding to $f_{0}$, it satisfies the contour-rotation condition $R^{\prime}$ ) by virtue of the induction hypothesis.

Having defined expressions of the form (45), we can now suppress the integration over $v$ by the same method as in II.1 i.e. by essentially using

$$
\psi=\int \alpha_{Q}(v) e^{i v H}(Q!)^{-1}(1-i-i H)^{Q+1} \psi d v
$$

and

$$
H \psi=\left.\left(-\frac{d}{d t}\right) e^{-t H} \psi\right|_{t=0}
$$

This allows us to use the definition

$$
\begin{gather*}
\int \bar{T}(X) e^{i w_{0} H} \mathcal{O}\left(Z_{1}\right) e^{i w_{1} H} \ldots e^{i w_{r-1} H} \mathcal{O}\left(Z_{r}\right) \Omega \\
\quad g\left(x_{1}, \ldots, x_{n}, z_{n+1}, \ldots, z_{n+p}\right) d x_{1} \ldots d x_{n} d z_{n+1} \ldots d z_{n+p} \\
=\int \bar{T}(X) e^{i\left(w_{0}+v\right) H} \mathcal{O}\left(Z_{1}\right) e^{i w_{1} H} \ldots e^{i w_{r-1} H} \mathcal{O}\left(Z_{r}\right) \Omega \\
\quad K_{Q} g(x, z) \alpha_{Q}(v) d v d x_{1} \ldots d x_{n} d z_{n+1} \ldots d z_{n+p} .  \tag{53}\\
\\
K_{Q} g(x, z)=\left.(Q!)^{-1}\left(1-i+i \frac{\partial}{\partial t}\right)^{Q+1} g\left(x, z_{t}\right)\right|_{t=0},
\end{gather*}
$$

where $z_{t}$ is given by: $\mathbf{z}_{t, j}=\mathbf{z}_{j}, z_{t, j}^{0}=z_{j}^{0}-t,(j=n+1, \ldots, n+p)$. We again omit straightforward verifications.

## III.3. Poincaré Covariance

Up to this point, only the invariance under time-translations of the $S_{n}$ has been used. If the $S_{n}$ are invariant under space and time translations, it is clear that the generalized (anti-)time ordered functions have the same property.

Let $\hat{m}^{0 \mu}, \mathbf{m}^{0 \mu}, p_{\mu},(\mu=1, \ldots, \nu-1)$, be the differential operators defined on $\mathscr{S}$ by

$$
\begin{aligned}
\left(\hat{m}^{0 \mu} f\right)_{n}\left(x_{1}, \ldots, x_{n}\right) & =\sum_{j=1}^{n}\left(x_{j}^{\mu} \frac{\partial}{\partial x_{j}^{0}}-x_{j}^{0} \frac{\partial}{\partial x_{j}^{\mu}}\right) f_{n}\left(x_{1}, \ldots, x_{n}\right), \\
\left(\mathbf{m}^{0 \mu} f\right)_{n}\left(x_{1}, \ldots, x_{n}\right) & =\sum_{j=1}^{n}\left(x_{j}^{\mu} \frac{\partial}{\partial x_{j}^{0}}-x_{j}^{0} \frac{\partial}{\partial x_{j \mu}}\right) f_{n}\left(x_{1}, \ldots, x_{n}\right), \\
\left(p_{\mu} f\right)_{n}\left(x_{1}, \ldots, x_{n}\right) & =\sum_{j=1}^{n} \frac{\partial f}{\partial x_{j}^{\mu}}\left(x_{1}, \ldots, x_{n}\right) .
\end{aligned}
$$

(Note that $\frac{\partial}{\partial x_{j \mu}}=-\frac{\partial}{\partial x_{j}^{\mu}}$.) These operators satisfy

$$
\mathbf{m}^{0 \mu} L_{t} f=L_{t} \mathbf{m}^{0 \mu} f+t p_{\mu} L_{t} f
$$

Assuming the $\left\{S_{n}\right\}$ to be invariant under the full Euclidean group implies
$S\left(\hat{m}^{0 \mu} f\right)=0$ for all $\mu=1, \ldots, v-1$ and all $f$.
Let $X=\{1, \ldots, n\}$ and $f \in \mathscr{P}\left(\mathbb{R}^{v n}\right)$ with support in $\left\{\left(x_{1}, \ldots, x_{n}\right) \mid x_{j}^{0} \geqq 0\right.$ for all $\left.j\right\}$. Suppose that $f$ is radially analytic in the angle $\left\{\lambda \left\lvert\, 0<\arg \lambda<\frac{\pi}{2}\right.\right\}$. Then
$\left(\Omega, \bar{T}\left(\mathbf{m}^{0 \mu} f\right) \Omega\right)=i^{n} S_{n}\left(\left(\mathbf{m}^{0 \mu} f\right)_{i}\right)$
and, since $\left(\mathbf{m}^{0 \mu} f\right)_{i}=-i \hat{m}^{0 \mu} f_{i}$, this vanishes. By the density of radially analytic functions and translational invariance of $(\Omega, \bar{T}(X) \Omega)$ it follows that, for all $f \in \mathscr{S}\left(\mathbb{R}^{v n}\right)$,
$\left(\Omega, \bar{T}\left(\mathbf{m}^{0 \mu} f\right) \Omega\right)=0$.
Suppose now that $f=f_{1} \otimes L_{v_{1}} f_{2} \otimes \ldots \otimes L_{v_{1}+\ldots+v_{r-1}} f_{r}$ and that all $f_{j}$ have compact support. Then, for sufficiently large positive $v_{1}, \ldots, v_{r-1}$,

$$
\begin{aligned}
0= & \left(\Omega, \bar{T}\left(\mathbf{m}^{0 \mu} f\right) \Omega\right)=\sum_{j=1}^{r}\left(\Omega, \bar{T}\left(f_{1}\right) \bar{T}\left(L_{v_{1}} f_{2}\right) \ldots \bar{T}\left(\mathbf{m}^{0 \mu} L_{v_{1}+\ldots+v_{j-1}} f_{j}\right) \ldots\right. \\
& \left.\ldots \bar{T}\left(L_{v_{1}+\ldots+v_{r-1}} f_{r}\right) \Omega\right) \\
= & \sum_{j=1}^{r}\left(\Omega, \bar{T}\left(f_{1}\right) e^{i v_{1} H} \ldots \bar{T}\left(f_{j-1}\right) e^{i v_{j-1} H}\left[\bar{T}\left(\mathbf{m}^{0 \mu} f_{j}\right)\right.\right. \\
& \left.\left.+\left(\sum_{k=1}^{j-1} v_{k}\right) \bar{T}\left(p_{\mu} f_{j}\right)\right] e^{i v_{j} H} \ldots \bar{T}\left(f_{r}\right) \Omega\right) .
\end{aligned}
$$

By analytic continuation this remains true for all real $v_{1}, \ldots, v_{r-1}$ so that

$$
\sum_{j=1}^{r-1}\left(\Omega, \bar{T}\left(f_{1}\right) \ldots \bar{T}\left(\mathbf{m}^{0 \mu} f_{j}\right) \ldots \bar{T}\left(f_{r}\right) \Omega\right)=0
$$

for all $f_{1}, \ldots, f_{r}$ with compact support. This proves the Lorentz invariance of all $\left(\Omega, \bar{T}\left(X_{1}\right) \ldots \bar{T}\left(X_{r}\right) \Omega\right)$. This in turn implies, as it is well known, the relativistic form of the causal factorization property.

## IV. Application to the $\varphi_{3}^{4}$ Quantum Field Theory

The purpose of this section is to show that perturbation theory holds for the weakly coupled $\varphi^{4}$ quantum field theory in 3 space-time dimensions. This statement will be substantiated below, but we first want to give a short account of existing work. The existence of the $\varphi_{3}^{4}$ interaction as a quantum field theory satisfying all the Wightman axioms was proved in [FO, MS1, MS2], based on the earlier work in [G2, GJ, Fe]. We shall assume that the reader is more or less acquainted with the definitions and results of [FO] on which our analysis below will be based. The papers [FO, MS1] contain proofs of the differentiability of the Schwinger functions in the bare parameters, i.e. in the coupling constant and the bare mass. In [MS2] it was even shown that the Schwinger functions are Borel summable in the coupling constant so that the theory is uniquely determined by perturbation theory.

Two interesting further developments in a direction similar to our aims are described in [FR] and [C]. In [FR], the question of field equations is addressed and it is shown that generalized Schwinger functions for the $\varphi$ and $\varphi^{3}$ fields can be defined in non-coinciding points as tempered distributions. Similarly, in order to prove the non-triviality of the $S$-matrix for the $\varphi_{3}^{4}$ theory at small coupling, it was shown in [C] that truncated generalized Schwinger functions for the $\varphi, \varphi^{2}$ and $\varphi^{3}$ fields exist as tempered distributions, coinciding points included.

Since some confusion might arise about the definition of generalized Schwinger functions, we repeat here the canonical definition known from perturbation theory for the case of the $\varphi^{4}$ theory.

We consider the cutoff Euclidean interaction

$$
\begin{equation*}
\sum_{j=1}^{4} \int d^{3} x: \varphi_{\kappa}^{j}:(x) \lambda_{j} g_{j}(x) \tag{54}
\end{equation*}
$$

where $\varphi_{\kappa}$ is some free Euclidean field with bare mass $m_{0}$ and cutoff $\kappa$. The renormalization procedure tells us how to associate to the "Euclidean Lagrangian" (54) a renormalized one, called $\mathscr{L}_{\kappa}$. It is well-known that in the case of the superrenormalizable theories $\mathscr{L}_{\kappa}$ can be found in the form of a polynomial in the $\lambda_{i}$ with coefficients which tend to infinity as the cutoff $\kappa$ is removed. The natural definition of the truncated generalized Schwinger functions of the fields $\varphi_{I}^{\nu_{k}}(x)\left(k=1, \ldots, n, v_{k}=1,2,3,4\right)$ is not the truncation of

$$
\begin{equation*}
\lim _{g_{J}(x) \rightarrow 1} \lim _{\kappa \rightarrow \infty}\left\langle\prod_{k=1}^{n}\left\{\frac{\delta}{\lambda_{v_{k}} \delta g_{v_{k}}\left(x_{k}\right)} \mathscr{L}_{\kappa}\right\} e^{-\mathscr{L}_{\kappa}}\right\rangle_{0}\left\langle e^{-\mathscr{L}_{\kappa}}\right\rangle_{0}^{-1} \tag{55}
\end{equation*}
$$

where $\left\rangle_{0}\right.$ is the free Euclidean expectation with bare mass $m_{0}$. We shall rather adopt the following definition.

Let $f_{j, k} \in \mathscr{S}\left(\mathbb{R}^{3}\right), j=1, \ldots, 4, k=1, \ldots, n$, let $g_{j} \in \mathscr{S}\left(\mathbb{R}^{3}\right), j=1, \ldots, 4$. Then the generalized truncated Schwinger functions $S_{v_{1}, \ldots, v_{n}}^{T}\left(x_{1}, \ldots, x_{n}\right)$ are defined as distributions by the formula

$$
\begin{align*}
& \sum_{\substack{v_{k}=1, \ldots, 4 \\
k=1, \ldots, n}} \int \prod_{k=1}^{n} d^{3} x_{k} f_{v_{k}, k}\left(x_{k}\right) S_{v_{1}, \ldots, v_{n}}^{T}\left(x_{1}, \ldots, x_{n}\right) \\
& \quad=\lim _{\substack{g_{j}(x) \rightarrow 1 \\
j=1, \ldots, 4}} \lim _{k \rightarrow \infty} \sum_{\substack{v_{k}=1, \ldots, 4 \\
k=1, \ldots, n}} \prod_{k=1}^{n} \frac{\partial}{\partial \mu_{v_{k}, k}}  \tag{56}\\
& \left.\quad \log \left\langle e^{-\mathscr{L}_{k}(g, f, \lambda, \mu)}\right\rangle_{0}\right|_{\substack{\mu_{v_{k}}=0 \\
k=1, \ldots, n}},
\end{align*}
$$

where $\mathscr{L}_{\kappa}(g, f, \lambda, \mu)$ is the renormalized Euclidean Lagrangian associated to

$$
\begin{equation*}
\sum_{j=1}^{4} \int d^{3} x: \varphi_{k}^{j}:(x)\left[\lambda_{j} g_{j}(x)+\sum_{k=1}^{n} \mu_{j, k} f_{j, k}(x)\right] . \tag{57}
\end{equation*}
$$

We shall describe below why the existence of the objects described in (56) is an easy variant of results contained in the earlier work on $\varphi_{3}^{4}$.

The Equations (55) and (56) define distributions which are equal on noncoinciding points, but only (56) defines a natural extension to coinciding arguments in the sense of local field theory. When (56) happens to define a locally integrable function (as is the case for the $\varphi_{I}$ and $\varphi_{I}^{2}$ field in the $\varphi_{3}^{4}$ theory, or for all Wick powers in the $P(\varphi)_{2}$ theories) then the natural extension to coinciding arguments of (55) (as an integrable function) agrees with (56) everywhere. This observation (which follows from the very construction of the models) was basic to the papers [EEF, OSe, O].

The main point of the preceding discussion is to emphasize that the definition (56) is suitable from an axiomatic point of view. In particular, it is for the untruncated generalized Schwinger functions $S_{v_{1} \ldots v_{n}}$, obtained from the $S_{v_{1} \ldots v_{n}}^{T}$ in the standard way, that we shall prove the extended O.S. positivity, and the distributional bounds.

Theorem 6. The generalized Schwinger functions are, as distributions, infinitely differentiable with respect to $\lambda_{1}, \ldots, \lambda_{4}$ and $m_{0}>0$ in a region of the form $0 \leqq \lambda_{4} m_{0}^{-1}<\varepsilon,\left|\lambda_{j}\right| m_{0}^{j / 2-3}<\varepsilon \lambda_{4} m_{0}^{-1}, j=1,2,3$, for some $\varepsilon>0$. The derivatives are (finite) sums of truncated generalized Schwinger functions, integrated over some of their arguments.

For an illustration of this last statement, see [EEF, Lemma 6a, 6b].
Theorem 7. The family of generalized Schwinger functions satisfies the conditions S1)-S6).

The proofs of these two theorems will be sketched below. Given the very detailed accounts of [FO, MS1, 2] we refrain from repeating the whole construction of the $\varphi_{3}^{4}$ theory for just proving one additional estimate, which seems to us implicitly contained in the aforementioned papers.

The conclusions of Theorems 6 and 7, combined with the results of the preceding sections imply the existence of time-ordered products for the fields $\varphi^{v} ; v=1, \ldots, 4$.

Theorem 8. The generalized analytic momentum space functions $H_{v_{1} \ldots v_{n}}\left(k ; m_{0}, \lambda_{1}, \ldots, \lambda_{4}\right)$ of the $\varphi_{3}^{4}$ theory are $\mathscr{C}^{\infty}$ functions in $m_{0}, \lambda_{1}, \ldots, \lambda_{4}$ in the region described in Theorem 6 and analytic in $k$ in the $n$ point axiomatic domain with single particle poles at $k_{j}^{2}=m^{2}\left(m_{0}, \lambda_{1}, \ldots, \lambda_{4}\right)$ and thresholds above $2 m_{0}^{2}-0(\varepsilon)$.
Proof. By the analysis of the preceding sections and by Theorem 2, Equation (29) $H_{v_{1} \ldots v_{n}}$ is for imaginary time components of $k$ the Fourier transform of $S_{v_{1} \ldots v_{n}}^{T}$. The proof of differentiability follows then in the same way as for Theorem 7 of [EEF]. The existence of an isolated one particle singularity has been shown for the $\varphi_{3}^{4}$ theory by Burnap [B].
(Note: in perturbation theory, the renormalization is often performed so that the physical mass coincides with the parameter $m$, given in advance, which occurs in the free propagators. In constructive theory the bare mass $m_{0}$ is given; renormalization is performed by introducing only those counterterms necessary to compensate the divergences of the primitively divergent graphs: since these are in finite number for superrenormalizable theories $\mathscr{L}_{\kappa}$ is then a polynomial in the $\lambda_{j}$. This determines the physical mass $m$, as a function of $m_{0}$ and the $\lambda_{j}$. We can now repeat almost verbatim the analysis done in [EEF], and we restate three relevant results.

Theorem 9. (=Theorem 8 in [EEF]). There is an $\varepsilon_{1}, 0<\varepsilon_{1}<\varepsilon$ and for each $a>0 a \mathscr{C}^{\infty}$ function $\lambda=\left(\lambda_{1}, \ldots, \lambda_{4}\right) \rightarrow m_{0}(a, \lambda)$ on $0 \leqq \lambda_{4} a^{-1}<\varepsilon_{1},\left|\lambda_{j}\right| a^{j / 2-3}<\varepsilon_{1} \lambda_{4} a^{-1}$, $j=1,2,3$ such that one has in the above region

$$
m\left(m_{0}(a, \lambda), \lambda\right)=a
$$

(Note that in 3 dimensions, the mass satisfies due to scaling $m\left(m_{0}, \lambda_{1}, \ldots, \lambda_{4}\right)$ $=m_{0} u\left(\lambda_{1} m_{0}^{1 / 2-3}, \ldots, \lambda_{4} m_{0}^{4 / 2-3}\right)$.)

Theorem 10. (=Theorem 10 in [EEF]).
(i) For $\varphi_{3}^{4}$ theories with physical mass $m>0$ and bare coupling constants $\lambda_{j}$ satisfying $\left|\lambda_{j} m^{j / 2-3}\right| \leqq \varepsilon_{1} \lambda_{4} m^{-1}, j=1,2,3,0 \leqq \lambda_{4} m^{-1}<\varepsilon_{1}$ the function

$$
G\left(k_{1}, \ldots, k_{n} ; m, \lambda\right)=\left\{\prod_{j=1}^{n}\left(k_{j}^{2}-m^{2}\right)\right\} H_{1 \ldots 1}\left(k_{1}, \ldots, k_{n} ; m_{0}(m, \lambda), \lambda_{1}, \ldots, \lambda_{4}\right)
$$

is $\mathscr{C}^{\infty}$ in the $\lambda_{j}$ and holomorphic in $k_{1}, \ldots, k_{n}\left(\right.$ with $\left.\sum k_{j}=0\right)$ in the axiomatic domain, with thresholds above $2 m-0\left(\varepsilon_{1}\right)$ and no single particle poles (at $k_{j}^{2}=m^{2}$ ).
(ii) The Taylor expansion of $G(k ; m, \lambda)$ in $\lambda_{j}$ at $\lambda_{j}=0, j=1, \ldots, 4$, for $k$ taken in the axiomatic domain (as described above), is given by standard renormalized perturbation theory.

Theorem 11. ( $=$ Theorem 12 in [EEF]). At non-overlapping points of the real massshell the S-matrix elements of a $\varphi_{3}^{4}$ theory with fixed physical mass $m>0$ and coupling constants as in Theorem 10 are $\mathscr{C}^{\infty}$ in $\lambda_{j}, j=1, \ldots, 4$ in that region as tempered distributions in the momenta. Their Taylor expansion at $\lambda_{j}=0, j=1, \ldots, 4$ is given by standard renormalized perturbation theory.

In particular, we recover the non-triviality of the $S$-matrix for $\lambda_{4}>0$ sufficiently small, $\lambda_{1}=\lambda_{2}=\lambda_{3}=0$, [C].

Proof of Theorem 6. This theorem is in a sense already contained in the proofs of the existence and differentiability in $\lambda$ of the ordinary Schwinger functions. We therefore only show how these proofs have to be read in order to arrive at the statement of Theorem 6. We shall adopt the terminology and notations of [FO], but [MS1, MS2] could serve just as well, and we assume the reader is familiar with [FO].

To explain our point, we first refer to $\S 2.1$ of [FO], (graph norms). A graph is a Wick monomial $G$ of degree $E_{i}(G)$ with a kernel $K(G)\left(z_{1}, \ldots, z_{E i(G)}\right)$, where we consider all "legs" as "initial legs". For all $\delta>2 \alpha>0$, a norm $\|G\|_{\delta, \alpha}$ is defined ([FO, Eq. (2.6)]). The importance of these norms stems from the fact that all bounds and convergence statements are made with respect to them for suitable $\delta$ and $\alpha$. As an example, in Theorem 4.6 of [FO] we have the bound

$$
\begin{equation*}
\left|Z(\Lambda)^{-1}\langle G\rangle_{1, t_{m}, \chi_{A g}}\right| \leqq \prod_{\Delta}(n(\Delta)!)\|G\|_{\delta, \alpha} \tag{58}
\end{equation*}
$$

where $n(\Delta)$ is the number of arguments of $K(G)$ localized in the unit cube $\Delta$ (the support of $K(G)$ is assumed here to be a product of such unit cubes), and $Z(\Lambda)$ is the "partition function". In the case at hand, the space cutoff is not the function $g$, but the family of functions, cf. Equation (57),

$$
\left\{\lambda_{j} g_{j}+\sum_{k=1}^{n} \mu_{j, k} f_{j, k} j=1, \ldots, 4\right\}
$$

and it is clear from the definition of the norms $\left\|\|_{\delta, \alpha}\right.$ that in our case we will have a bound on the 1.h.s. of (58) of the form

$$
\prod_{\Delta}(n(\Delta)!)\|G\|_{\delta, \alpha}^{0} \sum_{j}\left\{\left|\lambda_{j}\right|\left|g_{j}\right|_{s}+\sum_{k=1}^{n}\left|\mu_{j k}\right|\left|f_{j k}\right|_{s}\right\}^{0\left(\sum n(\Delta)\right)} O(1)
$$

where $\|G\|_{\delta, \alpha}^{0}$ is bounded by the norm $\|G\|_{\delta, \alpha}$ for a $g$ whose Fourier transform is bounded by $|k|^{-1}$ at infinity (cf. [Fe, page 97]), and $\|_{s}$ is a fixed Schwartz norm.

The differentiability follows now as in Corollary 4.6b of [FO]. A more detailed outline of the proof is given in [MS2, page 270], where it is sketched how the derivatives combine to sums of graphs whose $\|G\|_{\delta, \alpha}^{0}$ norms are finite. For the case of the $\varphi^{3}$ derivatives this is done in great detail in [FR, pages 215-217], where it is shown how the crucial perturbation formula [FO, Eqs. (2.37)-(2.39), (3.2), (3.3)] is used in this procedure. The next important point of the proof is to realize that the $\left\|\|_{\delta, \alpha}^{0}\right.$ norms of the graphs produced through this procedure are bounded, for $S_{v_{1} \ldots v_{n}}^{T}$ by $\prod_{j=1}^{n}\left|f_{v_{j}, j}\right|_{s} n!^{K^{\prime}}$ for some universal constant $K^{\prime}$ and Schwartz norm $\|\left.\right|_{s}$. This is due to the superrenormalizability of the theory, and proved through the mechanism of "estimating big graphs as products of small graphs" which was discovered by Glimm [G2].

We therefore get a bound

$$
\begin{align*}
& \text { |f } S_{v_{1} \ldots v_{n}}^{T}\left(x_{1}, \ldots, x_{n}\right) f_{1}\left(x_{1}\right) \ldots f_{n}\left(x_{n}\right) d^{3} x_{1} \ldots d^{3} x_{n} \mid \\
& \leqq J n!^{K} \prod_{j=1}^{n}\left\{\left(L\left|f_{j}\right| s\right)\left(L+\sum_{i=1}^{n}\left|f_{i}\right| s\right)^{M}\right\} \tag{59}
\end{align*}
$$

for a universal Schwartz norm $\ \|_{s}$ and universal constants $J, K, L, M$, provided the coupling constants are in a region of the form described in the statement of Theorem 6 (this is used to bound the exponential of $-\mathscr{L}_{\kappa}$ ).

Similarly, we get for the derivatives the equality

$$
\left.\begin{array}{l}
\prod_{j=1}^{4}\left(\frac{\partial}{\partial \lambda_{j}}\right)^{n_{j}} \int S_{v_{1} \ldots v_{n}}^{T}\left(x_{1}, \ldots, x_{n}\right) f_{1}\left(x_{1}\right) \ldots f_{n}\left(x_{n}\right) d^{3} x_{1} \ldots d^{3} x_{n} \\
=\int S_{v_{1} \ldots v_{n},}^{\underbrace{1 \ldots 1}_{n_{1}}}, \ldots \underbrace{4}_{n_{4}} \ldots 4 \tag{60}
\end{array} x_{1}, \ldots, x_{n}, y_{1}, \ldots, y_{\sum n_{j}}\right) f_{1}\left(x_{1}\right) \ldots f_{n}\left(x_{n}\right) d^{3} x_{1} \ldots d^{3} y_{\sum n_{j}} .
$$

and the bound

$$
J\left(n+\sum_{j=1}^{4} n_{j}\right)!^{K}\left(\prod_{j=1}^{n}\left(L\left|f_{j}\right|_{s}\right)\right)\left(L+\sum_{i=1}^{n}\left|f_{i}\right|_{s}\right)^{M\left(n+\sum_{j=1}^{4} n_{j}\right)}
$$

Since a distribution is a linear functional, we find, writing $f_{j}=\left(f_{j} /\left(\left|f_{j}\right| s\right)\right)\left|f_{j}\right|_{s}$,

$$
\begin{align*}
& \left|\prod_{j=1}^{4}\left(\frac{\partial}{\partial \lambda_{j}}\right)^{n_{j}} \int S_{v_{1} \ldots v_{n}}^{T}\left(x_{1}, \ldots, x_{n}\right) f_{1}\left(x_{1}\right) \ldots f_{n}\left(x_{n}\right) d^{3} x_{1} \ldots d^{3} x_{n}\right| \\
& \quad \leqq J\left(n+\sum_{j=1}^{4} n_{j}\right)!{ }^{K} L^{n}(L+n)^{M\left(n+\sum_{j=1}^{4} n_{j}\right)} \prod_{j=1}^{n}\left|f_{j}\right|_{s} . \tag{61}
\end{align*}
$$

The Equations (60), (61) are more than enough to prove Theorem 6, in fact, we have already proven the growth condition of Theorem 7.

Proof of Theorem 7. All axioms are obviously satisfied for the generalized (extended) Schwinger functions defined by (56), as in [FO, MS1] except for the growth condition which we just proved and the extended O.S. positivity which we prove now.

Time-ordered products can be defined for a cutoff theory, since for $\kappa<\infty$ (as in [Fe]), and a cutoff of the form $g_{i}\left(x^{0}, \mathbf{x}\right)=\chi_{[-T, T]}\left(x^{0}\right) \cdot h_{i}(\mathbf{x})$, we have a Hamiltonian theory in which sharp time fields are defined. Hence we have extended O.S. positivity in this case by Theorem 1 . This carries over to the limits, of which we have already shown existence. The proof of Theorem 7 is complete.

## Appendix

## Radially Analytic Functions

Let $f$ belong to $\mathscr{S}\left(\mathbb{R}^{N}\right)$. For all real $\lambda>0, f_{\lambda}(x)=f(x)$ defines another element of $\mathscr{S}\left(\mathbb{R}^{N}\right)$ and the map

$$
(f, \lambda) \rightarrow f_{\lambda}
$$

from $\mathscr{S}\left(\mathbb{R}^{N}\right) \times(0, \infty)$ to $\mathscr{S}\left(\mathbb{R}^{N}\right)$ is continuous and $\mathscr{C}^{\infty}$ in $\lambda$. We shall say that $f$ is radially analytic and continuous in the angle $\left\{\lambda \in \mathbb{C}:|\lambda|>0, \theta_{1} \leqq \arg \lambda \leqq \theta_{2}\right\}$ (when $\theta_{1} \leqq 0 \leqq \theta_{2}$ ) if there exists a continuous $\operatorname{map}(f, \lambda) \rightarrow f_{\lambda}$ from $\mathscr{S}\left(\mathbb{R}^{N}\right) \times($ this angle $)$ into $\mathscr{S}\left(\mathbb{R}^{N}\right)$, holomorphic in $\lambda$ in the interior of the angle, such that, for $\lambda$ real $>0$, $f_{\lambda}(x)=f(\lambda x)$.

It is easy to construct examples of radially analytic functions. Denote, for instance, for any real $a>0$,

$$
\varrho(a, \lambda)=c(a) \exp \left(-a\left(\lambda^{-1 / 2}+\lambda^{1 / 2}\right)\right), \quad c(a)^{-1}=\int_{0}^{\infty} \frac{d \lambda}{\lambda} \exp \left(-a\left(\lambda^{-1 / 2}+\lambda^{1 / 2}\right)\right)
$$

where $\lambda \rightarrow \lambda^{1 / 2}$ is the holomorphic function over $\mathbb{C} \backslash \mathbb{R}_{-}$equal to $|\lambda|^{1 / 2}$ for $\lambda>0$. Note that the restriction of this function to any closed half plane of the form $\left\{\lambda: \operatorname{Re} e^{-i \theta} \lambda \geqq 0\right\},-\frac{\pi}{2}<\theta<\frac{\pi}{2}$ is $\mathscr{C}^{\infty}$ and vanishes at 0 with all its derivatives.

Let $F$ be a continuous function on $(0, \infty)$ with

$$
|F(\lambda)|<A\left(\lambda^{1 / 2}+\lambda^{-1 / 2}\right)^{L}, \quad L \geqq 0 .
$$

Then (with new integration variables $\lambda=e^{2 \varphi}, y=\operatorname{ch} \varphi$ )

$$
\begin{aligned}
& \int_{0}^{\infty} \frac{d \lambda}{\lambda} F(\lambda) \exp -a\left(\lambda^{1 / 2}+\lambda^{-1 / 2}\right)=2 \int_{-\infty}^{\infty} e^{-2 a c h \varphi} F\left(e^{2 \varphi}\right) d \varphi \\
& 2 \int_{0}^{\infty} e^{-2 a c h \varphi} F\left(e^{2 \varphi}\right) d \varphi=2 \int_{1}^{\infty} e^{-2 a y} F\left(\left(y+\left(y^{2}-1\right)^{1 / 2}\right)^{2}\right) d y\left(y^{2}-1\right)^{-1 / 2}
\end{aligned}
$$

and the last expression shows that, since $|F(\lambda)|<A(2 y)^{L}$, the integrals converge absolutely. In particular

$$
\begin{aligned}
c(a)^{-1} & =4 \int_{1}^{\infty} e^{-2 a y}\left(y^{2}-1\right)^{-1 / 2} d y \\
& >4 \int_{2 a}^{4 a} e^{-y} \frac{d y}{y} \\
& >a^{-1} e^{-2 a}\left(1-e^{-2 a}\right) .
\end{aligned}
$$

Thus, if $a \geqq 1, c(a)^{-1} \geqq(2 a)^{-1} e^{-2 a}$, i.e. $c(a) \leqq 2 a e^{2 a}$.
On the other hand, if $\varphi_{0}>0$,

$$
\begin{aligned}
& \left|c(a) \int_{\varphi_{0}}^{\infty} F\left(e^{2 \varphi}\right) e^{-2 a c h \varphi} d \varphi\right| \\
& \quad \leqq 2 a e^{2 a} A \int_{\varphi_{0}}^{\infty}(2 c h \varphi)^{L} e^{-2 a c h \varphi} d \varphi \\
& \quad \leqq 2^{L+1} a A \int_{\varphi_{0}}^{\infty} d \varphi \exp \left(-a \varphi^{2}-a \frac{\varphi^{4}}{12}+L \varphi\right) \\
& \quad \leqq 2^{L+1} a A e^{-a \varphi_{0}^{2}} \int_{\varphi_{0}}^{\infty} d \varphi \exp \left(-a \frac{\varphi^{4}}{12}+L \varphi\right)
\end{aligned}
$$

If $a \geqq 1$ this is less than

$$
\begin{aligned}
& 2^{L+1} A a e^{-a \varphi z} \int_{0}^{\infty} d \varphi \exp \left(-a \frac{\varphi^{4}}{12}+L a^{1 / 4} \varphi\right) \\
& \quad=2^{L+1} A a^{3 / 4} e^{-a \varphi_{0}^{2}}(12)^{1 / 4} \int_{0}^{\infty} \exp -\left(\theta^{4}-(12)^{1 / 4} L \theta\right) d \theta
\end{aligned}
$$

From this it follows that

$$
\int_{\substack{|\lambda-1|>\varepsilon \\ \lambda>0}} \varrho(a, \lambda) F(\lambda) \frac{d \lambda}{\lambda}
$$

tends to zero as $a \rightarrow \infty$. On the other hand $\int_{0}^{\infty} \varrho(a, \lambda) \frac{d \lambda}{\lambda}=1$. Since $F$ is continuous, for every $\eta>0$ we can find $a>0$ so large that

$$
\left|\int_{0}^{\infty}(F(\lambda)-F(1)) \varrho(a, \lambda) \frac{d \lambda}{\lambda}\right|<\eta .
$$

Hence $\frac{1}{\lambda} \varrho(a, \lambda)$ is, when $a \rightarrow \infty$, an approximation of $\delta(\lambda-1)$.
Suppose that $\varphi \in \mathscr{S}\left(\mathbb{R}^{N}\right)$. Then

$$
f(x)=\int_{0}^{\infty} \varrho(a, \lambda) \frac{d \lambda}{\lambda} \varphi\left(\lambda^{-1} x\right)
$$

defines a new function also belonging to $\mathscr{S}\left(\mathbb{R}^{N}\right)$. In fact

$$
x^{\beta} D^{\alpha} f(x)=\int_{0}^{\infty} \varrho(a, \lambda) \frac{d \lambda}{\lambda} \lambda^{|\beta|-|\alpha|}\left(\lambda^{-1} x\right)^{\beta} D^{\alpha} \varphi\left(\lambda^{-1} x\right)
$$

so that we can apply the preceding extimate with $L=|\beta|+|\alpha|$ and obtain an inequality of the type

$$
\sup _{x}\left|x^{\beta} D^{\alpha} f(x)\right| \leqq C(\alpha, \beta, a) \sup _{x}\left|x^{\beta} D^{\alpha} \varphi(x)\right| .
$$

Furthermore, as $a \rightarrow \infty, f$ tends to $\varphi$ in the strong topology of $\mathscr{S}$, and uniformly if $\varphi$ varies in a bounded set of $\mathscr{S}\left(\mathbb{R}^{N}\right)$. For $\lambda>0$, denoting $f_{\lambda}(x)=f(\lambda x)$, we have

$$
\begin{equation*}
f_{\lambda}(x)=\int_{0}^{\infty} \varrho(a, \lambda \mu) \frac{d \mu}{\mu} \varphi\left(\mu^{-1} x\right) . \tag{A1}
\end{equation*}
$$

The right hand side of this equation has an analytic continuation in $\lambda$ in the open set $\mathbb{C} \backslash \mathbb{R}^{-}$, and the $\operatorname{map}(\lambda, \varphi) \rightarrow f_{\lambda}$ is a continuous map of $\left(\mathbb{C} \backslash \mathbb{R}^{-}\right) \times \mathscr{S}\left(\mathbb{R}^{N}\right)$ into $\mathscr{S}\left(\mathbb{R}^{N}\right)$, holomorphic in $\lambda$. Thus $f$ is radially continuous and analytic in the angle $\left\{\lambda:|\lambda|>0, \theta_{1} \leqq \arg \lambda \leqq \theta_{2}\right\}$ whenever $-\pi<\theta_{1}<\theta_{2}<\pi$.

This shows that radially analytic functions are dense in $\mathscr{S}\left(\mathbb{R}^{N}\right)$. Note that if $\varphi$ has its support in a closed set $F \subset \mathbb{R}^{N}$ then for all $\lambda \in \mathbb{C} \backslash \mathbb{R}^{-}, f_{\lambda}$ as defined by (A1) has its support in the closed cone generated by $F$.

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[^0]:    * Permanent address: Département de Physique Théorique,Université de Genève, $\mathrm{CH}-1211$ Genève 4, Switzerland

