The Structure of Space-Time Transformations

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Abstract. Let T be a one-to-one mapping of n-dimensional space-time M onto itself. If T maps light cones onto light cones and $\dim M \ge 3$, it is shown that T is, up to a scale factor, an inhomogeneous Lorentz transformation. Thus constancy of light velocity alone implies the Lorentz group (up to dilatations). The same holds if T and T^{-1} preserve $(x-y)^2>0$. This generalizes Zeeman's Theorem. It is then shown that if T maps lightlike lines onto (arbitrary) straight lines and if $\dim M \ge 3$, then T is linear. The last result can be applied to transformations connecting different reference frames in a relativistic or non-relativistic theory.

1. Introduction

Let M denote n-dimensional space-time (Minkowski space). It is an affine space of n-tuples $x = (x_0, ..., x_{n-1})$, where $x_0 = ct$. We denote by x^2 the quadratic form¹

$$x^2 \equiv x_0^2 - \sum_{i=1}^{n-1} x_i^2 \,. \tag{1.1}$$

Zeeman [1] has shown for dim $M \ge 3$ that a mapping T of M onto M is an orthochronous Lorentz transformation² times a dilatation plus a translation if T and T^{-1} preserve the relation

$$\{(y-x)^2 > 0 \text{ and } x_0 < y_0\}$$
 (1.2)

or the relation

$$\{(y-x)^2 = 0 \text{ and } x_0 < y_0\}.$$
 (1.3)

Since the direction of time plays no particular role in quantum field theory and since moreover time reversal is an important symmetry one should drop time order preservation, which, in fact, is quite a strong continuity condition³. Thus, instead of Eqs. (1.2) or (1.3) we take as

¹ As usual we call two points x and y timelike if $(y-x)^2 > 0$, spacelike if $(y-x)^2 < 0$, and lightlike if $(y-x)^2 = 0$. The light cone in x consists of all y with $(y-x)^2 = 0$.

² I.e., linear maps of M which preserve the form (1.1) and preserve time orientation.

³ It follows immediately from the preservation of Eq. (1.2) that T is continuous. Indeed, preservation of (1.2) means that T is continuous with respect to the associated order topology which, however, coincides for finite-dimensional spaces with Euclidean topology as already noted in [5].

preserved relations only

$$(x - y)^2 > 0 (1.4)$$

or

$$(x - y)^2 = 0. (1.5)$$

The latter just expresses constancy of light velocity. In Section 2 we will prove

Theorem 1. Let dim $M \ge 3$ and T be a 1-1 map of M onto M. Then T and T^{-1} preserve the relation $(x-y)^2 > 0$ if and only if they preserve the relation $(x-y)^2 = 0$. The group of all such maps is generated by

- (i) the full Lorentz group (including time reversal),
- (ii) translations of M,
- (iii) dilations (multiplication by a scalar).

Preservation of $(x - y)^2 = 0$ by T and T^{-1} simply means that light cones are mapped onto light cones. Thus constancy of light velocity c alone implies the Poincaré group⁴ (up to dilatations)!

The main statement of Theorem 1 is that T is affine ("linear"), and one wonders whether linearity also holds in the nonrelativistic case. Of course, c is no longer constant in all reference frames. If light cones are mapped onto light cones then lightlike lines 5 are mapped onto lightlike lines since any such line is the intersection of two light cones.

In the relativistic as well as nonrelativistic case the worldlines of light rays (photons) should be mapped onto straight lines. It suffices to consider light sources at rest⁶ to be able to apply the next result.

Theorem 2. Let dim $M \ge 3$, and let T be a 1-1 map of M onto M which maps lightlike lines onto (arbitrary) straight lines. Then T is linear.

Remarks. (i) Theorem 1 can be derived from Theorem 2 in a straightforward way. Our proofs of both theorems are, however, more or less independent (Sections 2 and 3). For $\dim M = 2$ the theorems do not hold.

- (ii) For linearity, the rotational symmetry of the light cone ("isotropy of light velocity") is not crucial. It suffices that its boundary is sufficiently smooth, i.e., sufficiently smooth directional dependence of light velocity.
- (iii) Our results severely limit the form of any physical theory which retains straight lines for light rays and which has no distinguished reference frames. For then the laws of Physics have to be form-invariant under transformations connecting different reference frames.

⁴ I.e., the inhomogeneous Lorentz group, generated by (i) and (ii).

⁵ A (straight) line is called timelike, spacelike, or lightlike if any two points on it are timelike, spacelike, or lightlike, respectively.

 $^{^6}$ For these the light velocity is also c in the nonrelativistic case. But in another reference frame the light velocity becomes direction dependent.

Notation. C_a denotes the light cone in a, $C_a = \{x \in M; (x-a)^2 = 0\}$. The interior 7 C_a of a light cone consists of all points timelike to a, $\hat{C}_a = \{x; (x-a)^2 > 0\}$. \hat{C}_a^+ denotes the positive cone $\hat{C}_a^+ = \{x; (x-a)^2 > 0, x_0 > a_0\}$, and C_a^- the negative cone. The image under a map will be denoted by a dash, e.g., $x' \equiv T(x)$.

2. Constancy of Light Velocity Implies the Poincaré Group

The results of this section are based on the following observation.

Lemma 2.1. Let W be a lightlike line in M, $W = \{x = \lambda w + a; -\infty < \lambda < \infty\}$ say, where $w^2 = 0$, and consider the hyperplane H_W $\equiv \{x; w \cdot (x-a) = 0\}$, which contains W. Then H_W is tangent to every light cone with vertex in W, and the union of all these cones is $M \setminus (H_W \setminus W)^8$.

Proof. Let $C_{\tau} \equiv \{x; (x - \tau w - a)^2 = 0\}$, the cone with vertex in $\tau w + a$. Let $y \notin H_W$. Then $y \in C_{\tau}$ with $\tau = (y - a)^2/2w \cdot (y - a)$. Now let $y \in H_W \cap \bigcup C_{\tau}$. Then

$$0 = (y - \tau_0 w - a)^2 = (y - a)^2 - 2\tau_0 w \cdot (y - a) = (y - a)^2$$
 (2.1)

implies $y \in \bigcap_{\tau} C_{\tau} = W$. Q.E.D.

The next corollary reduces Theorem 1 to the result of Zeeman [1]. Further below, however, we will give a direct derivation based on Lemma 2.1.

Corollary 2.2. Let dim M > 2, and let T be a 1-1-mapping of M onto itself. Then the following statements are equivalent.

- (i) T maps light cones onto light cones, i.e., T and T^{-1} preserve $(x-y)^2=0$.
- (ii) T maps the interior of light cones onto the interior of light cones, i.e., T and T^{-1} preserve $(x-y)^2 > 0$.
- (iii) T and T^{-1} preserve the relation $\{(x-y)^2 > 0, x_0 < y_0\}$ or carry it over in $\{(x'-y')^2 > 0, x'_0 > y'_0\}$, i.e., T fulfills (ii) and preserves or reverses time order.
 - (iv) T fulfills (i) and preserves or reverses time order.

Proof. If T fulfills (i), it maps a lightlike line W onto a lightlike line W' and hence, by Lemma 2.1, $M \setminus (H_W \setminus W)$ onto $M \setminus (H_{W'} \setminus W')$. Hence H_W is mapped onto $H_{W'}$. If C_a is a given light cone and \hat{C}_a its interior, then $\bigcup \{H_W; W \subset C_a\} = M \setminus \hat{C}_a$ since $w \neq 0$, $w^2 = 0$ and $w \cdot (x - a) = 0$

⁷ This is an abuse of language. C_a is the boundary of \hat{C}_a .

⁸ I.e., every point in this set can be reached by a lightlike line from some point of W. Note that, for dim M=2, the hyperplane coincides with W and hence $M \setminus (H_W \setminus W) = M$.

immediately implies $(x-a)^2 \le 0$; conversely, for given x with $(x-a)^2 = 0$ there is always a lightlike $w \ne 0$ with $w \cdot (x-a) = 0$ if dim $M \ge 3$. Hence $M \setminus \hat{C}_a$ is mapped onto $M \setminus \hat{C}_{a'}$ and thus \hat{C}_a onto $\hat{C}_{a'}$. Hence (i) \Rightarrow (ii).

To show (ii) \Rightarrow (iii) 9 , we first assume that there is an $a \in M$ and $b \in \hat{C}_a^+$ such that $b' \in \hat{C}_{a'}^+$. Then $\hat{C}_b^- \supset \hat{C}_a^-$ and $\hat{C}_{b'}^- \supset \hat{C}_{a'}^-$. Now let $y \in \hat{C}_a^+$. If $y \notin \hat{C}_b$, then $y' \notin \hat{C}_{b'} \supset \hat{C}_{a'}^-$ and thus $y' \in C_{a'}^+$. If $y \in \hat{C}_b$, there is a $z \in \hat{C}_a^+ \setminus \hat{C}_b$ such that $y \notin C_z$. Then $\hat{C}_z \supset \hat{C}_z^- \supset \hat{C}_a^-$ and $z' \in C_{a'}^+$ implies $y' \notin C_{z'} \supset \hat{C}_{a'}^-$. Thus $y' \in \hat{C}_{a'}^+$. Hence \hat{C}_a^+ is mapped into $\hat{C}_{a'}^+$. Hence there is a $c \in \hat{C}_a^-$ with $c' \in \hat{C}_{a'}^-$ and the same argument gives $T(\hat{C}_a^-) \subset \hat{C}_{a'}^-$. Hence \hat{C}_a^+ is mapped onto $\hat{C}_{a'}^+$, and \hat{C}_a^- onto $\hat{C}_{a'}^-$. Since two light cones always intersect, one gets the same for all \hat{C}_x^\pm . If there is no a and b with the above property, then $T(\hat{C}_a^+) = \hat{C}_{a'}^-$ for all a, since otherwise there would be an $a \in M$ and $b \in \hat{C}_a^-$ with $b' \in \hat{C}_{a'}^-$, and by the same argument $T(\hat{C}_a^-) \subset C_{a'}^-$, contradicting $T(\hat{C}_a^-) = \hat{C}_{a'}^-$.

(iii) \Rightarrow (iv) is very simple and follows directly from Lemma 1 of [1] since, if τ denotes time reversal, either T and T^{-1} or τT and $(\tau T)^{-1}$ preserve $\{(x-y)^2, x_0 < y_0\}$. (iv) \Rightarrow (i) is trivial. Q.E.D.

We will now give a fairly simple proof of Theorem 1 without using Zeeman's result. We first note some simple properties of the tangential hyperplane H_W .

Lemma 2.3. H_W contains only spacelike and lightlike lines, and the latter are all parallel to W.

Proof. We use the notation of the proof of Lemma 2.1. Let $W_1 \subset H_W$, $W_1 = \{x = \lambda w_1 + b; -\infty < \lambda < \infty\}$. After a parallel displacement, we can assume b = a. If W_1 is lightlike, $w \cdot (\lambda w_1 + a - a) = 0$ implies by Eq. (2.1), with $\lambda = \lambda w_1 + a$, that $W_1 \subset \bigcap C_\tau = W$. If W_1 were timelike, then $w \cdot w_1 = 0$,

but $w_1^2 > 0$ and $w^2 = 0$; this is impossible (alternatively, H_W does not contain points of \hat{C}_r). Q.E.D.

Lemma 2.4. Every spacelike line W is the intersection of suitable hyperplanes H_{W_i} , $i = 1, ..., n - 1 = \dim M - 1$.

Proof. We can assume $W = \{x = \lambda w; -\infty < \lambda < \infty\}$, $w^2 < 0$. Then there are n-1 linearly independent lightlike vectors w_i with $w \cdot w_i = 0$. Hence, with $W_i \equiv \{\lambda w_i\}$, one has that $\bigcap_i H_{W_i}$ is a straight line which contains W. Q.E.D.

By the implication (ii) \Rightarrow (i) of Corollary 2.2, which can very easily also be shown directly, it suffices to show that, if T maps light cones onto light cones, then T is linear and hence, up to a translation and dilatation, a Lorentz transformation. Then T and T^{-1} automatically preserve $(x-y)^2 > 0$.

⁹ For dim M=2 this is most easily seen by a diagram of which the following is an abstraction.

Proof of Theorem 1. As remarked before, it follows from Lemma 2.1 that H_W is mapped onto H_W for each lightlike line W. Hence, by Lemma 2.4, spacelike lines are mapped onto spacelike lines 10 . Therefore, since each plane contains 3 spacelike directions, planes are mapped onto planes. Since every straight line is the intersection of two planes, it follows that every straight line is mapped onto a straight line. Hence, by the main theorem of projective geometry, the map T is affine, T(x) = Ax + a, where A is a linear operator (matrix).

Since $x^2 = 0$ implies $(Ax)^2 = 0$, A leaves the light cone C_0 invariant and hence, from linearity $(Ax)^2 = \kappa x^2$ for all $x \in M$. For dim M > 2, the exterior of C_0 is connected while the interior is not. Since T is affine and hence continuous, it can not map the interior onto the exterior. Hence $\kappa > 0$. Thus $A = \kappa^{1/2} \Lambda$ where Λ satisfies $(\Lambda x)^2 = x^2$ and is thus a general Lorentz transformation. Q.E.D.

Remark. Let \overline{M} denote the space obtained by adjoining to M the hyperplane at infinity, and let T be a 1-1-map of \overline{M} onto \overline{M} such that both T and T^{-1} map lightlike lines onto lightlike lines. Then it follows in a similar way as before that *all* straight lines are mapped onto straight lines. Hence T is a projective transformation. Since it leaves the (extended) light cone invariant, T is an element of the *conformal group*.

3. Linearity for the General Case

The proof of Theorem 2 is based on the next lemma.

Lemma 3.1. Let dim $M \ge 3$ and let T be a 1-1-mapping of M onto M which maps lightlike lines onto straight lines. Then planes which contain two different lightlike directions are mapped onto planes.

For dim $M \ge 4$ a proof of this lemma will be given at the end of this section. The remaining case will be treated elsewhere [4]. Lemma 3.1 allows a reduction of Theorem 2 to the main theorem of projective geometry.

Proof of Theorem 2. Every line in M is the intersection of two planes containing two different lightlike directions. Its image is the intersection of the two image planes, which is a straight line. Hence T maps straight lines onto straight lines. Q.E.D.

 $^{^{10}}$ At this point one could invoke a result of [2]: If a 1-1 map T maps all straight lines in a given cone and all their translates onto straight lines, then T is linear. Here one can take a cone of spacelike lines.

It remains to show Lemma 3.1. We first prove

Lemma 3.2. Under the assumptions of Lemma 3.1, let w_1 , w_2 , and w_3 be 3 linearly independent lightlike vectors, and let S_3 be the 3-dimensional subspace of M spanned by them and a point P. Then the image of S_3 is again contained in a 3-dimensional subspace of M.

Proof. Let W_1 and W_3 be the lines through P parallel to w_1 and w_3 . Let $P_1 \in W_1$, $P_1 \neq P$, and let W_2 be the line through P_1 parallel to w_2 . These lines and their points will be called to be of class 0. If lines and points of class m-1 have been defined, we will call of class m those additional lines and points obtained by drawing a lightlike line through two different points of class m-1.

Now, W_1' , W_2' , and W_3' lie in a 3-dimensional subspace, U say, since four points always do. If the images of all points of class m-1 lie in U, so do their lightlike connecting lines and hence the images of all points of class m. We will show that every point in S_3 is of class $m \le 6$. This then will prove the lemma.

We denote by $W_i(Q)$ the parallel to W_i through a point Q and put $H_i \equiv H_{W_i} \cap S_3$ where H_{W_i} is the tangent hyperplane of Lemma 2.1 containing W_i . Note that H_i is a plane and that a lightlike line in S_3 which is not parallel to W_i meets it in a single point.

We first show that the points in the $W_2 - W_3(P_1)$ -plane are of class $m \le 4$. Since W_3 meets H_2 in a single point, there are points $P_2 \in W_2$ and

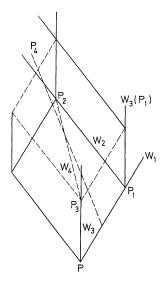


Fig. 1. Proof of Lemma 3.2

 $P_3 \in W_3$, $P_2 \neq P_1$ and $P_3 \neq P$, which can be connected by a lightlike line, W_4 say. W_4 is of class 1. Since W_4 is not parallel to W_1 , it meets H_1 in a single point.

Hence, except for a single point, every point on W_4 can be connected by a lightlike line with a point¹¹ on W_1 , and vice versa. These lines meet the $W_2 - W_3(P_1)$ -plane, each in a single point, with the exception of W_2 and W_3 . From these points of class $m \le 2$ we can choose two, P_4 and P_5 say, such that $\overrightarrow{P_4P_5}$ is not parallel to W_3 . Then $W_3(P_4)$ and $W_3(P_5)$ do not coincide, both meet W_2 , and hence are of class $m \le 3$. The parallels to W_2 through them are of class $m \le 4$ and cover the $W_2 - W_3(P_1)$ -plane.

It follows that the points of the $W_3 - W_3(P_2)$ -plane are of class $m \le 5$. Finally, an arbitrary $Q \in S_3 \setminus W_3(P_2)$ lies on $W_1(Q)$ which meets the $W_2 - W_3(P_1)$ - and $W_3 - W_3(P_2)$ -plane in distinct points; hence Q is of class $m \le 2^{12}$. Q.E.D.

Proof of Lemma 3.1. Let E be a plane which contains two non-parallel lightlike lines W_1 and W_2 . Let $W_i = \{x = \tau w_i + a_i, -\infty < \tau < \infty\}$, and complete $\{w_1, w_2\}$ to a basis $\{w_1, ..., w_n\}$ of lightlike vectors for M. Let $a \in W_1 \cap W_2$. For given $(\mu) = (\mu_3, ..., \mu_n)$, with not all μ_i vanishing, we consider the 3-dimensional subspace $S(\mu)$ through a spanned by w_1, w_2 , and $w(\mu) = \sum \mu_i w_i$. Since $S(\mu)$ always contains a third linearly independent lightlike direction, we have, by Lemma 3.2, $T|S(\mu)| \subset U(\mu)$ where $U(\mu)$ is a 3-dimensional subspace of M. Since $\bigcup S(\mu) = M$ and since T

is onto, there are (μ) and $(\hat{\mu})$ such that $U(\mu) \neq \hat{U}(\hat{\mu})$ if $\dim M > 3$. From $E = S(\mu) \cap S(\hat{\mu})$ we have $T(E) \subset U(\mu) \cap U(\hat{\mu})$, and hence E' is contained in a plane. Any parallel to W_1 in E is therefore mapped onto a parallel to W_1' since they do not meet. Therefore there is, through each point of W_2' , a parallel to W_1' all of which lie in E'. Since they form a plane, this proves Lemma 3.1.

Note added in proof: In a forthcoming paper [4], the authors will, by purely algebraic methods, prove the following result which is much stronger than Theorem 2 and which also covers the case of dim M=3.

Theorem [4]: Let L be a set of directions in \mathbb{R}^n , $n \ge 2$, and let \mathscr{T}_L be the set of all 1-1 mappings T of \mathbb{R}^n into itself which map every straight line parallel to L onto a straight line. Then every $T \in \mathscr{T}_L$ is linear if and only if

- (i) L does not lie on a degenerate cone of second order (and, for n = 2, contains at least 3 directions);
- (ii) the subfield of \mathbb{R} generated by all ratios of the form λ_i/λ_j , where $\Sigma \lambda_i h_i \in L$ for some fixed basis $\{h_1, \ldots, h_n\}$ in \mathbb{R}^n , coincides with \mathbb{R} .

¹¹ This point is unique since there are no triangles with lightlike lines. One can avoid the use of Lemma 2.1 by a very simple direct calculation.

¹² By a slightly different construction one can show that every point in S_3 is of class $m \le 3$.

The second condition requires in particular that L contains uncountably many directions. It is interesting that condition (i) is sufficient for linearity if T is continuous at some point [4]. Hence in this case 1/2n(n+1)-1 suitably chosen directions will ensure linearity for $n \ge 3$ while for n = 2 one needs 3.

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