TRANSFORMATION GROUPS AND BIFURCATION AT MULTIPLE EIGENVALUES¹

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Communicated by Hans F. Weinberger, January 12, 1973

1. Topological degree arguments show that bifurcation must take place at eigenvalues of odd multiplicity, while examples show bifurcation may not take place at eigenvalues of even multiplicity. The general problem of bifurcation at multiple eigenvalues is one which does not readily submit to a complete solution, so the approach must proceed by special cases. One important class for which a more detailed analysis is possible is that of problems invariant under a transformation group. The purpose of this note is to present some results in this direction. We would also like to call the reader's attention to the recent interesting work of D. Ruelle.

2. Consider a nonlinear problem

(1)
$$(L_0 + \lambda L_1)u + N(u) = 0$$

where L_0 , L_1 and N are continuous operators from a Banach space X to $Y(X \subset Y)$. We assume that N is Fréchet differentiable, that N'(0) = 0, and that $L_0 + \lambda L_1$ is a Fredholm operator for all λ . (This means that the dimension of the null space of $L_0 + \lambda L_1$ is equal to the codimension of its range in Y, and that its range is closed in Y.) Let G be the group generated by S^1 (the unit circle with the usual addition) together with an inversion operator $i(i^2 = e)$, where e is the identity operator). Let T_g be a representation of G on Y. We label elements of S^1 by γ , δ , where $0 \le \gamma$, $\delta < 2\pi$. Then $T_\delta T_\gamma = T_{\delta + \gamma}$. We assume that $L_0 + \lambda L_1$ and N commute with T_g for all g in G.

Let \mathcal{N}_{λ} be the null space of $(L_0 + \lambda L_1)$ and let $\{\lambda_j\}$ be the real numbers λ for which \mathcal{N}_{λ} is nontrivial. \mathcal{N}_{λ_j} is invariant under G, and we assume \mathcal{N}_{λ_j} is finite dimensional. If \mathcal{N}_{λ_j} is irreducible, it is either one or two dimensional. Since bifurcation at simple eigenvalues is well understood (see [5] or [3]), let us consider the case dim $\mathcal{N}_{\lambda_j} = 2$. The eigenvalues of T_i are ± 1 , so in \mathcal{N}_{λ_j} there is one vector φ_j such that $T_i\varphi_j = \varphi_j$. Restricting (1) to the subspaces X' and Y' of all vectors u such that $u = T_i u$, the corresponding null space $\mathcal{N}_{\lambda_j}^+$ is one dimensional. (Since N commutes with T_i , $T_i N(u) = N(T_i u) = N(u)$ if u is in X^+ .) We can now apply the usual bifurcation arguments to obtain a bifurcating curve of solutions

AMS (MOS) subject classifications (1970). Primary 35J60, 20C35. Key words and phrases. Transformation groups, bifurcation theory. ¹Partially supported by NSF GP-27973.

 (λ, u) with u in X^+ . But then, applying the operators T_{δ} , we get a one parameter sheet of solutions $(\lambda, T_{\delta}u)$, $0 \le \delta < 2\pi$, bifurcating from $(\lambda, 0)$.

THEOREM 1. Let \mathcal{N}_{λ_j} be irreducible. If dim $\mathcal{N}_{\lambda_j} = 1$ there bifurcate two branches of solutions of (1) from $(\lambda_j, 0)$, all invariant under S^1 . If dim $\mathcal{N}_{\lambda_j} = 2$ we get a one parameter sheet of solutions. Moreover, the solutions obtained above constitute the full set of solutions bifurcating from $(\lambda_j, 0)$.

The proof of the final statement proceeds along the following lines. Let (μ_n, u_n) be a sequence of solutions of (1) tending to $(\lambda_j, 0)$. For large $n, u_n = a_n \varphi_1 + b_n \varphi_2 + O(1)$ where $\mathcal{N}_{\lambda_j} = [\varphi_1, \varphi_2]$. By applying an appropriate rotation T_{δ_n} we can put $b_n = 0$. (This is a special property of the group S^1 .) The problem is then reduced to an argument depending on the uniqueness of solutions obtained by an implicit function theorem argument. The details will be presented in a future paper.

The isotropy subgroup of a set \mathcal{N} is the subgroup of transformations which leave \mathcal{N} invariant. The subgroups of S^1 are the cyclic subgroups \mathscr{C}_n generated by $T_{2\pi/n}$ for some integer n. We continue to assume that \mathcal{N}_i is irreducible under G.

THEOREM 2. Let the isotropy subgroup of \mathcal{N}_{λ_j} be $\mathscr{C}_{n_j} \cup i$. A sheet emanating from $(\lambda_j, 0)$ then consists of solutions invariant under $\mathscr{C}_{n_j} \cup i$ and this sheet must either tend to infinity or go to $(\lambda_k, 0)$, where $\mathscr{C}_{n_i} \subset \mathscr{C}_{n_k}$.

PROOF. If (1) is restricted to the subspace X_j of vectors invariant under \mathscr{C}_{n_j} then we see only those eigenvalues λ_k for which φ_k belongs to X_j , thus $\mathscr{C}_{n_j} \subset \mathscr{C}_{n_k}$. We now restrict the subspace further to elements invariant under *i*. In that case λ_j is simple, and topological degree arguments [2] show that the solutions bifurcating from $(\lambda_j, 0)$ must tend to infinity or another simple eigenvalue, in this case an eigenvalue λ_k with $\mathscr{C}_{n_j} \subset \mathscr{C}_{n_k}$. We also see that dim $\mathscr{N}_{\lambda_k} \cap X_j = 2$.

3. Examples. The equation

(2)
$$\Delta u + \lambda u + f(u) = 0$$

on a circular disk with u=0 on the boundary provides a simple illustration of the above ideas. We define T_{δ} by $(T_{\delta}u)(r,\theta)=u(r,\theta+\delta)$, and $T_{i}u(r,\theta)=u(r,-\theta)$. The null spaces \mathscr{N}_{λ} are all irreducible [4, p. 484]. From each simple eigenvalue there bifurcate two branches of axisymmetric solutions, while from each double eigenvalue there bifurcates a one parameter sheet of solutions. The same results hold if f=f(r,u).

As a second example, consider the Navier-Stokes equations

$$\Delta u_i = \partial p/\partial x_i + u_i \partial u_i/\partial x_i, \qquad \partial u_i/\partial x_i = 0$$

on a cylindrical domain $r_1 < r < r_2$ (summation convention). The

boundary conditions are periodic in the z direction, and $u_r = u_z = 0$, $u_{\theta}(r_1) = A$, $u_{\theta}(r_2) = B$ on the lateral surfaces. The appropriate group representation is $T_{\delta} \vec{u}(x) = O \vec{u}(O^{-1}x)$ where O is a rotation about the z axis through the angle δ . For T_i we take $T_i \vec{u}(x) = -\vec{u}(-x)$. An equation of the form (1) is obtained by linearizing about the special axisymmetric laminar solution (Couette flow, see [1]).

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