

SOME THEOREMS ON TENSOR DIFFERENTIAL INVARIANTS

BY JACK LEVINE

1. *Introduction.* In the theory of algebraic invariants there is a theorem which states that if an absolute invariant be written as the quotient of two relatively prime polynomials, then the numerator and denominator are relative invariants.* If we consider absolute scalar differential invariants of a metric (or affine) space, then it is possible to prove a similar theorem regarding them. In the course of the proof we give a new proof of the fact that in a relation of the form (2) the ϕ must be a power of the Jacobian of the coordinate transformation. (In the algebraic theory the u_j^i are of course constants.) This proof involves the use of the differential equations satisfied by the scalar.† In this proof it is not necessary to restrict B and ϕ to be polynomials in their arguments as is done in the usual proof of the corresponding theorem in the invariant theory. It is sufficient to assume that ϕ possesses first derivatives with respect to the u_j^i and that $B(\bar{g})$ is an analytic function of ϵ in the neighborhood of $\epsilon=0$. We also extend the theorem to the case of tensor differential invariants of the form (5).

2. *Scalar Differential Invariants.* We consider the differential invariants of a metric space V_n with a quadratic form $g_{ij}dx^i dx^j$. Let

$$A \left(g_{ij}; \frac{\partial g_{ij}}{\partial x^k}; \cdots; \frac{\partial^p g_{ij}}{\partial x^k \cdots \partial x^l} \right)$$

be an absolute scalar invariant of V_n which we take to be rational in its arguments. We can then write A in terms of the g_{ij} and their extensions $g_{ij,k \cdots l}$, and we have

$$A(g_{ij}; 0; g_{ij,kl}; \cdots) = \frac{B(g_{ij}; 0; g_{ij,kl}; \cdots)}{C(g_{ij}; 0; g_{ij,kl}; \cdots)},$$

* See, for example, H. W. Turnbull, *The Theory of Determinants, Matrices, and Invariants*, p. 277.

† T. Y. Thomas and A. D. Michal, *Differential invariants of relative quadratic differential forms*, *Annals of Mathematics*, vol. 28 (1927), p. 679.

where B and C are polynomials in the g_{ij} and their extensions. We may assume that B and C have no common factor. Now

$$(1) \quad \frac{B(g_{ij}; \dots)}{C(g_{ij}; \dots)} = \frac{B(\bar{g}_{ij}; \dots)}{C(\bar{g}_{ij}; \dots)},$$

under an arbitrary coordinate transformation $x \rightarrow \bar{x}$, the barred g 's being the g 's in the (\bar{x}) coordinate system. It is easily shown we must have*

$$(2) \quad B(\bar{g}_{ij}; \dots) = \phi(u_b^a) B(g_{ij}; \dots),$$

$$(3) \quad C(\bar{g}_{ij}; \dots) = \phi(u_b^a) C(g_{ij}; \dots),$$

where $u_b^a = \partial x^a / \partial \bar{x}^b$ and ϕ is a polynomial in the u 's. We now prove ϕ is a power of $|\partial x / \partial \bar{x}|$, thus showing B and C are relative scalars.

Write (2) in the form

$$B(\bar{g})\phi^{-1} = B(g),$$

and consider the infinitesimal transformation

$$x^i = \bar{x}^i + \epsilon \xi^i(\bar{x}).$$

We have

$$\left(\frac{d\phi^{-1}}{d\epsilon} \right)_{\epsilon=0} = - \left(\frac{\partial \phi}{\partial u_j^i} \right)_{\epsilon=0} \left(\frac{du_j^i}{d\epsilon} \right)_{\epsilon=0} = - \left(\frac{\partial \phi}{\partial u_j^i} \right)_{\epsilon=0} \frac{\partial \xi^i(x)}{\partial x^j}.$$

As ϕ is a polynomial, so also is $\partial \phi / \partial u_j^i$, and on evaluating this last expression at $\epsilon = 0$, we obtain a set of constants k_i^j , so that

$$\left(\frac{d\phi^{-1}}{d\epsilon} \right)_{\epsilon=0} = - k_i^j \frac{\partial \xi^i}{\partial x^j}.$$

Proceeding then as in the paper by Thomas and Michal, page 679, we obtain the differential equations satisfied by B in the form

$$(4) \quad X_s^t(\rho)B = k_s^t B.$$

Now for any function G we have †

$$(X_s^t, X_m^l)G = \delta_m^t X_s^l G - \delta_s^l X_m^t G,$$

* H. W. Turnbull, loc. cit.

† Thomas and Michal, loc. cit., p. 663.

and, in particular, for B we would have

$$(X_s^t, X_m^l)B = \delta_m^t X_s^l B - \delta_s^l X_m^t B = B(\delta_m^l k_s^t - \delta_s^t k_m^l).$$

But also

$$(X_s^t, X_m^l)B = X_s^t(k_m^l B) - X_m^l(k_s^t B) = B(k_m^l k_s^t - k_s^t k_m^l) = 0,$$

so that

$$\delta_m^t k_s^l - \delta_s^t k_m^l = 0,$$

from which follows $k_m^l = k \delta_m^l$, where k is a constant. Substituting in (4) we find that B is a relative scalar of weight k and* $\phi = |\partial x / \partial \bar{x}|^k$. Similar results hold for C also. As stated in §1 we can prove a generalization of this result which we state as follows.

THEOREM 1. *Given a function*

$$B\left(g_{ij}; \frac{\partial g_{ij}}{\partial x^k}; \cdots; \frac{\partial^p g_{ij}}{\partial x^k \cdots \partial x^l}\right),$$

with the law of transformation

$$B\left(\bar{g}_{ij}; \cdots; \frac{\partial^p \bar{g}_{ij}}{\partial \bar{x}^k \cdots \partial \bar{x}^l}\right) = \phi(u_b^a) B\left(g_{ij}; \cdots; \frac{\partial^p g_{ij}}{\partial x^k \cdots \partial x^l}\right),$$

where ϕ possesses first derivatives in the u 's and $B(\bar{g})$ is analytic in the neighborhood of $\epsilon = 0$. Then ϕ is a power of the Jacobian and B is a relative scalar differential invariant.

3. *Tensor Differential Invariants.* Consider the absolute tensor differential invariant with components of the form

$$(5) \quad T_{i \cdots j}^{a \cdots b} = \frac{U_{i \cdots j}^{a \cdots b}(g_{kl}; g_{kl, mq}; \cdots)}{D(g_{kl}; \cdots)},$$

where the U 's and D are polynomials (with no common factor) in their arguments. Corresponding to (1) in the scalar case we have

$$(6) \quad \frac{U_{i \cdots j}^{a \cdots b}(g) u_k^i \cdots u_l^j}{U_{k \cdots l}^{m \cdots p}(g, u) u_m^a \cdots u_p^b} = \frac{D(g)}{D'(g, u)} = \frac{Q(g, u)}{P(g, u)},$$

* Thomas and Michal, loc. cit.

(P, Q having no common factor), where the primed U 's and D represent the result of replacing the barred g 's by their values in terms of the g 's and u 's in the expressions $U_{i \dots j}(\bar{g})$ and $D(\bar{g})$. From (6) we see that Q is a factor of D and of $U_{i \dots j}^{a \dots b} u_k^i \dots u_l^j$, and hence must be a function $Q'(g)$, so that

$$(7) \quad U_{i \dots j}^{a \dots b}(g) u_k^i \dots u_l^j = Q'(g) V_{k \dots l}^{a \dots b}(g, u),$$

$$(8) \quad D(g) = Q'(g) R(g).$$

In (7) put $u_j^i = \delta_j^i$; then

$$(9) \quad U_{k \dots l}^{a \dots b}(g) = Q'(g) V_{k \dots l}^{a \dots b}(g, \delta).$$

Hence $Q'(g) = \text{const.}$, since D and the U 's have no common factor. Since $D(g)$ and $D'(g, u)$ are of the same degree in the g 's, it then follows from (6) that $P(g, u) = P'(u)$, so that

$$D(\bar{g}) = \phi(u_j^i) D(g).$$

Hence as proved in the previous section for B , we have shown that D is a relative scalar of weight k , and therefore $U_{i \dots j}^{a \dots b}$ are the components of a relative tensor of weight k . We can also prove the following theorem.

THEOREM 2. *If the set of quantities*

$$T_{a \dots b}^{i \dots j} \left(g_{kl}; \dots; \frac{\partial^p g_{kl}}{\partial x^m \dots \partial x^r} \right)$$

have the transformation law

$$T_{v \dots w}^{s \dots t}(\bar{g}_{kl}; \dots) u_s^i \dots u_t^j = \phi(u_e^d) T_{a \dots b}^{i \dots j}(g_{kl}; \dots) u_v^a \dots u_w^b,$$

then ϕ is a power of $|\partial x / \partial \bar{x}|$ and the T 's are components of a relative tensor invariant, it being assumed that ϕ possesses first derivatives in the u 's, and $T(\bar{g})$ are analytic in the neighborhood of $\epsilon = 0$.

The proof is similar to that used for B of the previous section. Similar results to those obtained for metric scalar and tensor differential invariants hold for affine invariants.