## NOTE ON FUNCTIONAL FORMS QUADRATIC IN A FUNCTION AND ITS FIRST p DERIVATIVES\*

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It has been shown that a normal functional form quadratic in a function and its derivative is reducible to an invariantive form quadratic in a function and a constant, and that the continuity of the coefficients of the first form implies the continuity of those of the second.  $\dagger$  The result is here generalized to a form quadratic in a function and p derivatives.

Let  $y_0^{\alpha}$  denote a continuous function of the real variable  $\alpha$  defined on the range  $a \leq \alpha \leq b$ . Let  $y_1^{\alpha}$ ,  $y_2^{\alpha}$ ,  $\cdots$ ,  $y_p^{\alpha}$  denote the corresponding derivatives defined and continuous on the same interval. The normal quadratic form is

(A) 
$$Q = \sum_{i,j=0}^{p} A_{\alpha\beta}^{ij} y_i^{\alpha} y_j^{\beta} + A_{\alpha}^{ij} y_i^{\alpha} y_j^{\alpha},$$

where  $A_{\alpha}{}^{i}{}_{\beta}{}^{i}$  and  $A_{\alpha}{}^{i}{}^{j}$  are functions integrable in the Riemann sense, and where a Greek index repeated as a subscript and as a superscript is understood to denote integration with respect to that variable over the fundamental interval (a,b). The form Q is such that no generality is lost by assuming that  $A_{\alpha}{}^{i}{}_{\beta}{}^{i} = A_{\beta}{}^{i}{}_{\alpha}{}^{i}$  and  $A_{\alpha}{}^{i}{}^{j} = A_{\alpha}{}^{i}{}^{i}$ . This assumption is made.

The convention of denoting integration by repeated Greek indices will be used in all that follows. In addition, when a Latin index (except p) occurs in a single term once as a superscript and once as a subscript, we shall understand summation with respect to that index over an integer range (0, p-1). Thus

$$(A') \qquad Q = A_{\alpha\beta}^{ij} y_i^{\alpha} y_j^{\beta} + A_{\alpha\beta}^{pj} y_p^{\alpha} y_j^{\beta} + A_{\alpha\beta}^{ip} y_i^{\alpha} y_p^{\beta} + A_{\alpha\beta}^{pp} y_p^{\alpha} y_p^{\beta}$$
$$+ A_{\alpha}^{ij} y_i^{\alpha} y_j^{\alpha} + A_{\alpha}^{pj} y_p^{\alpha} y_j^{\alpha} + A_{\alpha}^{ip} y_p^{\alpha} y_p^{\alpha} + A_{\alpha}^{pp} (y_p^{\alpha})^2.$$

<sup>\*</sup> Presented to the Society, December 30, 1930.

<sup>†</sup> A. D. Michal and L. S. Kennison, Quadratic functional forms on a composite range, Proceedings of the National Academy of Sciences, vol. 16 (1930), pp. 617-619.

We now state and prove the following theorems:

THEOREM 1. The form Q may be written as a form quadratic in the single function  $w^{\alpha} = y_{p}^{\alpha}$  and the p constants  $y^{i} = y_{i}^{\alpha}$ ,  $(i = 0, 1, \dots, p-1)$ .

The reduction is readily accomplished by use of a remainder form of Taylor's theorem:

(1) 
$$y_{i}^{\alpha} = y_{i}^{a} + (\alpha - a)y_{i+1}^{a} + \dots + \frac{(\alpha - a)^{p-i-1}}{(p - i - 1)!}y_{p-1}^{a} + \int_{a}^{\alpha} \frac{(\alpha - \sigma)^{p-i-1}}{(p - i - 1)!}y_{p}^{\sigma}d\sigma.$$

However, it is convenient to condense this by defining the functions

$$\begin{split} E_{i}^{\alpha} &= \frac{(\alpha - \sigma)^{p-i-1}}{(p-i-1)!}, & \text{if } \alpha > \sigma, \\ &= \frac{1}{2} \frac{(\alpha - \sigma)^{p-i-1}}{(p-i-1)!}, & \text{if } \alpha = \sigma, \\ &= 0, & \text{if } \alpha < \sigma; \\ E_{i}^{\alpha} &= \frac{(\alpha - a)^{k-i}}{(k-i)!}, & \text{if } k \ge i, \\ &= 0, & \text{if } k < i. \end{split}$$

The equation (1) then becomes simply

$$y_i^{\alpha} = E_k^{\alpha} y^k + E_{\sigma}^{\alpha} w^{\sigma}.$$

If the latter result now be placed in the expression (A') for Q, we have

(B) 
$$Q = B_{kl} y^k y^l + 2B_{k\sigma} y^k w^{\sigma} + B_{\sigma\tau} w^{\sigma} w_{\tau} + B_{\sigma} (w^{\sigma})^2,$$

where

$$B_{kl} = A_{\alpha\beta}^{ij} E_{k}^{\alpha} E_{l}^{\beta} + A_{\alpha}^{ij} E_{k}^{\alpha} E_{l}^{\alpha},$$

$$B_{k\sigma} = A_{\alpha\beta}^{ij} E_{k}^{\alpha} E_{\sigma}^{\beta} + A_{\alpha}^{ij} E_{k}^{\alpha} E_{\sigma}^{\alpha} + A_{\alpha\sigma}^{ip} E_{k}^{\alpha} + A_{\sigma}^{ip} E_{k}^{(\sigma)},$$

$$B_{\sigma\tau} = A_{\alpha\beta}^{ij} E_{\sigma}^{\alpha} E_{\sigma}^{\beta} + A_{\alpha}^{ij} E_{\sigma}^{\alpha} E_{\sigma}^{\alpha} + 2A_{\alpha\sigma}^{ip} E_{k}^{\alpha} + A_{\tau}^{pj} E_{\sigma}^{(\tau)} + A_{\sigma}^{ip} E_{\tau}^{(\sigma)},$$

$$+ A_{\sigma\tau}^{pp},$$

$$B_{\sigma} = A_{\sigma}^{pp},$$

where the indices in parentheses indicating suspension of the integration until the coefficient B has been associated with the function w. Thus we demonstrate the theorem by giving an explicit expression for the new coefficients B in terms of the coefficients A.

THEOREM 2. If the coefficients A are continuous, the coefficients B as given by (3) are also continuous.

This may be seen at once from the expressions (3). The coefficients B are the sums of certain of the coefficients A and a finite number of definite integrals of the products of the coefficients A by the functions E. Since the functions E are all continuous, except  $_{p-1}E^{\alpha}_{\sigma}$ , any discontinuities of B must arise in terms containing  $_{p-1}E^{\alpha}_{\sigma}$ . Consider then these terms. Terms of the type  $A_{\alpha}{}^{i_{p-1}}{}_{i}E^{\alpha}_{kp-1}E^{\alpha}_{\sigma}$  in which  $_{p-1}E^{\alpha}_{\sigma}$  appears with one of its variables in integrated form must be continuous, for they are simply integrals in which the non-integrated variable of  $_{p-1}E^{\alpha}_{\sigma}$  is one of the limits. For example,

$$A_{\alpha}^{ip-1}E_{k}^{\alpha} \qquad E_{\sigma}^{\alpha} = \int_{\sigma}^{b} (A_{\alpha}^{ip-1}E_{k}^{(\alpha)}) d\alpha.$$

There is a possible exception in the term

$$A_{\alpha}^{p-1}E^{\alpha}_{\sigma}E^{\alpha}_{\sigma}$$
,

but we see that

$$A_{\alpha}^{p-1} \stackrel{p-1}{\underset{p-1}{E_{\sigma}}} \stackrel{E_{\sigma}^{\alpha}}{\underset{p-1}{E_{\tau}}} = \int_{u(\sigma,\sigma)}^{b} (A_{\alpha}^{p-1})^{p-1} d\alpha,$$

where  $\mu$  is equal to the greater of  $\sigma$  and  $\tau$ . Being a continuous function of a continuous function, the term is continuous. The only terms in which  $_{p-1}E_{\sigma}^{\alpha}$  appears unintegrated are the terms  $A_{\sigma}^{p-1p}$   $_{p-1}E_{\gamma}^{(\sigma)}$  and  $A_{\sigma}^{p-1}$   $_{p-1}E_{\sigma}^{(\gamma)}$ . However, their sum is equal to  $A_{\mu}^{p-1p}$  where  $\mu$  is defined as above. Thus all the coefficients B are continuous, if the coefficients A are.

It has been shown elsewhere\* that the form (B) of Q is invariantive; that is, a necessary and sufficient condition that Q vanish for all continuous functions  $w^a$  for which  $w^a = w^b = 0$  and for all constants  $y^k$  is that the coefficients B be zero. Thus we may state

THEOREM 3. A necessary and sufficient condition that a form quadratic in a function and its first p derivatives vanish for all functions  $y_0^{\alpha}$  whose pth derivative is continuous and vanishes at the end points is that the coefficients A satisfy the equations obtained by equating to zero the right members of the equations (3).

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<sup>\*</sup> See A. D. Michal, American Journal of Mathematics, 1928; A. D. Michal and T. S. Peterson, forthcoming issue of the Annals of Mathematics; A. D. Michal, Proceedings of National Academy, 1930; A. D. Michal, forthcoming issue of American Journal of Mathematics; A. D. Michal and L. S. Kennison, loc. cit.