# SUBGRADIENT ESTIMATE AND LIOUVILLE-TYPE THEOREM FOR THE CR HEAT EQUATION ON HEISENBERG GROUPS* 

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#### Abstract

In this paper, we first get a subgradient estimate of the CR heat equation on a closed pseudohermitian $(2 n+1)$-manifold. Secondly, by deriving the CR version of sub-Laplacian comparison theorem on an $(2 n+1)$-dimensional Heisenberg group $H^{n}$, we are able to establish a subgradient estimate and then the Liouville-type theorem for the CR heat equation on $H^{n}$.


Key words. Subgradient estimate, Liouville-type Theorem, Heat Kernel, Pseudohermitian manifold, Heisenberg Group, CR-pluriharmonic, CR-Paneitz operator, Sub-Laplacian, Li-Yau Harnack inequality.

AMS subject classifications. Primary 32V05, 32V20; Secondary 53C56

1. Introduction. In the paper of $[\mathrm{Y}]$, S.-T. Yau derived a gradient estimate for positive harmonic functions on a complete noncompact Riemannian manifold. As a consequence, Liouville-type theorems can be proved for manifolds of nonnegative Ricci curvature. Moreover, in the paper of [LY], P. Li and S.-T. Yau established the parabolic Li-Yau gradient estimate and Li-Yau Harnack inequality for the positive solution of the heat equation on a complete Riemannian manifold.

However for a pseudohermitian $(2 n+1)$-manifold $(M, J, \theta)$, the corresponding estimates are not clear due to a lack of sub-Laplacian comparison theorem and CR Bochner formula. In this paper, we consider the CR heat equation (1.6) with respect to the sub-Laplacian on $(M, J, \theta)$. By using the arguments of [LY] and CR Bochner formula (2.1), we are able to derive the CR version of parabolic Li-Yau gradient estimate and the so-called reversed Li-Yau Harnack inequality for the positive solution of CR heat equation. Then by combining the standard parabolic Li-Yau gradient estimate, we derive a subgradient estimate of the CR heat equation on closed pseudohermitian $(2 n+1)$-manifolds. Moreover, by deriving the CR version of sub-Laplacian comparison theorem on $(2 n+1)$-dimensional Heisenberg groups $H^{n}$, we are able to establish the subgradient estimate and the Liouville-type theorem for the CR heat equation on $H^{n}$.

The main key step is to derive the CR version of Bochner formula. This formula (2.1) involving a third order operator $P$ which characterizes CR-pluriharmonic functions ([L1]), is hard to control. However after integrating by parts (see 1.5), we are able to relate this extra term to the CR Paneitz operator $P_{0}$.

We first give a brief introduction to pseudohermitian geometry (see [L1] for more details). Let $(M, \xi)$ be a $(2 n+1)$-dimensional, orientable, contact manifold with contact structure $\xi, \operatorname{dim}_{R} \xi=2 n$. A CR structure compatible with $\xi$ is an endomorphism $J: \xi \rightarrow \xi$ such that $J^{2}=-1$. We also assume that $J$ satisfies the following integrability condition: If $X$ and $Y$ are in $\xi$, then so is $[J X, Y]+[X, J Y]$

[^0]and $J([J X, Y]+[X, J Y])=[J X, J Y]-[X, Y]$. A CR structure $J$ can extend to $\mathbb{C} \otimes \xi$ and decomposes $\mathbb{C} \otimes \xi$ into the direct sum of $T_{1,0}$ and $T_{0,1}$ which are eigenspaces of $J$ with respect to $i$ and $-i$, respectively. A manifold $M$ with a CR structure is called a CR manifold. A pseudohermitian structure compatible with $\xi$ is a $C R$ structure $J$ compatible with $\xi$ together with a choice of contact form $\theta$. Such a choice determines a unique real vector field $T$ transverse to $\xi$, which is called the the characteristic vector field of $\theta$, such that $\theta(T)=1$ and $\mathcal{L}_{T} \theta=0$ or $d \theta(T, \cdot)=0$. Let $\left\{T, Z_{\alpha}, Z_{\bar{\alpha}}\right\}$ be a frame of $T M \otimes \mathbb{C}$, where $Z_{\alpha}$ is any local frame of $T_{1,0}, Z_{\bar{\alpha}}=\overline{Z_{\alpha}} \in T_{0,1}$ and $T$ is the characteristic vector field. Then $\left\{\theta, \theta^{\alpha}, \theta^{\bar{\alpha}}\right\}$, which is the coframe dual to $\left\{T, Z_{\alpha}, Z_{\bar{\alpha}}\right\}$, satisfies
\[

$$
\begin{equation*}
d \theta=i h_{\alpha \bar{\beta}} \theta^{\alpha} \wedge \theta^{\bar{\beta}} \tag{1.1}
\end{equation*}
$$

\]

for some hermitian matrix of functions $\left(h_{\alpha \bar{\beta}}\right)$. Actually we can always choose $Z_{\alpha}$ such that $h_{\alpha \bar{\beta}}=\delta_{\alpha \beta}$; hence, throughout this paper, we assume $h_{\alpha \bar{\beta}}=\delta_{\alpha \beta}$.

The Levi form $\langle,\rangle_{L_{\theta}}$ is the Hermitian form on $T_{1,0}$ defined by

$$
\langle Z, W\rangle_{L_{\theta}}=-i\langle d \theta, Z \wedge \bar{W}\rangle
$$

We can extend $\langle,\rangle_{L_{\theta}}$ to $T_{0,1}$ by defining $\langle\bar{Z}, \bar{W}\rangle_{L_{\theta}}=\overline{\langle Z, W\rangle}_{L_{\theta}}$ for all $Z, W \in T_{1,0}$. The Levi form induces naturally a Hermitian form on the dual bundle of $T_{1,0}$, denoted by $\langle,\rangle_{L_{\theta}^{*}}$, and hence on all the induced tensor bundles. Integrating the Hermitian form (when acting on sections) over $M$ with respect to the volume form $d \mu=\theta \wedge d \theta$, we get an inner product on the space of sections of each tensor bundle. We denote the inner product by the notation $\langle$,$\rangle . For example$

$$
\langle\varphi, \psi\rangle=\int_{M} \varphi \bar{\psi} d \mu
$$

for functions $\varphi$ and $\psi$.
The pseudohermitian connection of $(J, \theta)$ is the connection $\nabla$ on $T M \otimes \mathbb{C}$ (and extended to tensors) given in terms of a local frame $Z_{\alpha} \in T_{1,0}$ by

$$
\nabla Z_{\alpha}=\theta_{\alpha}^{\beta} \otimes Z_{\beta}, \quad \nabla Z_{\bar{\alpha}}=\theta_{\bar{\alpha}}^{\bar{\beta}} \otimes Z_{\bar{\beta}}, \quad \nabla T=0
$$

where $\theta_{\alpha}{ }^{\beta}$ are the 1-forms uniquely determined by the following equations:

$$
\begin{align*}
d \theta^{\beta} & =\theta^{\alpha} \wedge \theta_{\alpha}{ }^{\beta}+\theta \wedge \tau^{\beta} \\
0 & =\tau_{\alpha} \wedge \theta^{\alpha}  \tag{1.2}\\
0 & =\theta_{\alpha}{ }^{\beta}+\theta_{\bar{\beta}^{\bar{\alpha}}}
\end{align*}
$$

We can write (by Cartan lemma) $\tau_{\alpha}=A_{\alpha \gamma} \theta^{\gamma}$ with $A_{\alpha \gamma}=A_{\gamma \alpha}$. The curvature of the Webster-Stanton connection, expressed in terms of the coframe $\left\{\theta=\theta^{0}, \theta^{\alpha}, \theta^{\bar{\alpha}}\right\}$, is

$$
\begin{aligned}
\Pi_{\beta}^{\alpha} & =\overline{\Pi_{\bar{\beta}} \bar{\alpha}^{\alpha}}=d \theta_{\beta}{ }^{\alpha}-\theta_{\beta}^{\gamma} \wedge \theta_{\gamma}{ }^{\alpha} \\
\Pi_{0}^{\alpha} & =\Pi_{\alpha}{ }^{0}=\Pi_{0}{ }^{\bar{\beta}}=\Pi_{\bar{\beta}}{ }^{0}=\Pi_{0}{ }^{0}=0 .
\end{aligned}
$$

Webster showed that $\Pi_{\beta}{ }^{\alpha}$ can be written

$$
\Pi_{\beta}{ }^{\alpha}=R_{\beta}{ }^{\alpha}{ }_{\rho \bar{\sigma}} \theta^{\rho} \wedge \theta^{\bar{\sigma}}+W_{\beta}{ }^{\alpha}{ }_{\rho} \theta^{\rho} \wedge \theta-W^{\alpha}{ }_{\beta \bar{\rho}} \theta^{\bar{\rho}} \wedge \theta+i \theta_{\beta} \wedge \tau^{\alpha}-i \tau_{\beta} \wedge \theta^{\alpha}
$$

where the coefficients satisfy

$$
R_{\beta \bar{\alpha} \rho \bar{\sigma}}=\overline{R_{\alpha \bar{\beta} \sigma \bar{\rho}}}=R_{\bar{\alpha} \beta \bar{\sigma} \rho}=R_{\rho \bar{\alpha} \beta \bar{\sigma}}, \quad W_{\beta \bar{\alpha} \gamma}=W_{\gamma \bar{\alpha} \beta}
$$

We will denote components of covariant derivatives with indices preceded by comma; thus write $A_{\alpha \beta, \gamma}$. The indices $\{0, \alpha, \bar{\alpha}\}$ indicate derivatives with respect to $\left\{T, Z_{\alpha}, Z_{\bar{\alpha}}\right\}$. For derivatives of a scalar function, we will often omit the comma, for instance, $f_{\alpha}=Z_{\alpha} f, f_{\alpha \bar{\beta}}=Z_{\bar{\beta}} Z_{\alpha} f-\theta_{\alpha}{ }^{\gamma}\left(Z_{\bar{\beta}}\right) Z_{\gamma} f, f_{0}=T f$ for a (smooth) function.

For a real function $f$, the subgradient $\nabla_{b}$ is defined by $\nabla_{b} f \in \xi$ and $\left\langle Z, \nabla_{b} f\right\rangle_{L_{\theta}}=$ $d f(Z)$ for all vector fields $Z$ tangent to contact plane. Locally $\nabla_{b} f=\sum_{\alpha} f_{\bar{\alpha}} Z_{\alpha}+f_{\alpha} Z_{\bar{\alpha}}$. We can use the connection to define the subhessian as the complex linear map

$$
\left(\nabla^{H}\right)^{2} f: T_{1,0} \oplus T_{0,1} \rightarrow T_{1,0} \oplus T_{0,1}
$$

by

$$
\left(\nabla^{H}\right)^{2} f(Z)=\nabla_{Z} \nabla_{b} f
$$

Also

$$
\Delta_{b} f=\operatorname{Tr}\left(\left(\nabla^{H}\right)^{2} f\right)=\sum_{\alpha}\left(f_{\alpha \bar{\alpha}}+f_{\bar{\alpha} \alpha}\right)
$$

The Webster-Ricci tensor and the torsion tensor on $T_{1,0}$ are defined by

$$
\operatorname{Ric}(X, Y)=R_{\alpha \bar{\beta}} X^{\alpha} Y^{\bar{\beta}}
$$

and

$$
\operatorname{Tor}(X, Y)=i \sum_{\alpha, \beta}\left(A_{\bar{\alpha} \bar{\beta}} X^{\bar{\alpha}} Y^{\bar{\beta}}-A_{\alpha \beta} X^{\alpha} Y^{\beta}\right)
$$

where $X=X^{\alpha} Z_{\alpha}, \quad Y=Y^{\beta} Z_{\beta}, \quad R_{\alpha \bar{\beta}}=R_{\gamma}{ }^{\gamma}{ }_{\alpha \bar{\beta}}$. The Webster scalar curvature is $R=R_{\alpha}{ }^{\alpha}=h^{\alpha \bar{\beta}} R_{\alpha \bar{\beta}}$.

Next we recall some definitions.
Definition 1.1. (i) A piecewise smooth curve $\gamma:[0,1] \rightarrow M$ is said to be horizontal if $\gamma^{\prime}(t) \in \xi$ whenever $\gamma^{\prime}(t)$ exists. The length of $\gamma$ is then defined by

$$
l(\gamma)=\int_{0}^{1}\left\langle\gamma^{\prime}(t), \gamma^{\prime}(t)\right\rangle^{\frac{1}{2}} d t
$$

The Carnot-Carathéodory distance between two points $p, q \in M$ is

$$
d_{c}(p, q)=\inf \left\{l(\gamma) \mid \gamma \in C_{p, q}\right\}
$$

where $C_{p, q}$ is the set of all horizontal curves joining $p$ and $q$.
(ii) By Chow connectivity theorem [Cho], there always exists a horizontal curve joining $p$ and $q$, so the distance is finite. We say $M$ is complete if it is complete as a metric space.

Definition 1.2. A smooth real-valued function $u$ in $M$ is said to be $C R$ pluriharmonic function if for any point $p \in M$, there is an open neighborhood $U$ of $p$ in $M$ and a smooth real-valued function $v$ on $U$ such that $\bar{\partial}_{b}(u+i v)=0$.

Definition 1.3. ([L1]) Let $\left(M^{2 n+1}, J, \theta\right)$ be a complete pseudohermitian manifold. Define

$$
P \varphi=\sum_{\alpha=1}^{n}\left(\varphi_{\bar{\alpha}}{ }^{\bar{\alpha}}{ }_{\beta}+i n A_{\beta \alpha} \varphi^{\alpha}\right) \theta^{\beta}=\left(P_{\beta} \varphi\right) \theta^{\beta}, \quad \beta=1,2, \cdots, n
$$

which is an operator that characterizes CR-pluriharmonic functions. Here

$$
\begin{equation*}
P_{\beta} \varphi=\sum_{\alpha=1}^{n}\left(\varphi_{\bar{\alpha}}{ }^{\bar{\alpha}}{ }_{\beta}+i n A_{\beta \alpha} \varphi^{\alpha}\right) \tag{1.3}
\end{equation*}
$$

and $\bar{P} \varphi=\left(\bar{P}_{\beta} \varphi\right) \theta^{\bar{\beta}}$, the conjugate of $P$. Moreover we define

$$
\begin{equation*}
P_{0} \varphi=4\left(\delta_{b}(P \varphi)+\bar{\delta}_{b}(\bar{P} \varphi)\right) \tag{1.4}
\end{equation*}
$$

which is the so-called CR Paneitz operator $P_{0}$. Here $\delta_{b}$ is the divergence operator that takes $(1,0)$-forms to functions by $\delta_{b}\left(\sigma_{\alpha} \theta^{\alpha}\right)=\sigma_{\alpha}{ }^{\alpha}$ and $\bar{\delta}_{b}\left(\sigma_{\bar{\alpha}} \theta^{\bar{\alpha}}\right)=\sigma_{\bar{\alpha}},{ }^{\bar{\alpha}}$. If we define $\partial_{b} \varphi=\varphi_{\alpha} \theta^{\alpha}$ and $\bar{\partial}_{b} \varphi=\varphi_{\bar{\alpha}} \theta^{\bar{\alpha}}$, then the formal adjoint of $\partial_{b}$ on functions (with respect to the Levi form and the volume form $d \mu$ ) is $\partial_{b}^{*}=-\delta_{b}$.

We observe that if $(M, J, \theta)$ is a closed pseudohermitian $(2 n+1)$-manifold, then

$$
\begin{equation*}
-\int_{M}\left\langle P \varphi+\bar{P} \varphi, d_{b} \varphi\right\rangle d \mu=\frac{1}{4} \int_{M} P_{0} \varphi \cdot \varphi d \mu \tag{1.5}
\end{equation*}
$$

In particular if $(M, J, \theta)$ has zero torsion, we have

$$
P_{0} \varphi=\mathcal{L}_{n} \mathcal{L}_{\bar{n}}=\left[\Delta_{b}^{2} \varphi+n^{2} T^{2} \varphi\right]
$$

Here

$$
\mathcal{L}_{n} \varphi=-\Delta_{b} \varphi+i n T \varphi=-2 \varphi_{\bar{\alpha}}{ }^{\bar{\alpha}}
$$

For the details about these operators, the reader can make reference to [GL], $[\mathrm{H}]$ and [L1].

Remark 1.1. ([H], [GL]) (i) Let $(M, J, \theta)$ be a closed pseudohermitian $(2 n+1)$ manifold with $n \geq 2$. Then a smooth real-valued function $f$ satisfies $P_{0} f=0$ on $M$ if and only if $P_{\beta} f=0$ on $M$. It holds also for a closed pseudohermitian 3-manifold of zero torsion.
(ii) Let $P_{\beta} f=0$. If $M$ is the boundary of a connected strictly pseudoconvex domain $\Omega \subset C^{n+1}$, then $f$ is the boundary value of a pluriharmonic function $u$ in $\Omega$. That is, $\partial \bar{\partial} u=0$ in $\Omega$. Moreover, if $\Omega$ is simply connected, there exists a holomorphic function $w$ in $\Omega$ such that $\operatorname{Re}(w)=u$ and $\left.u\right|_{M}=f$.

In this paper, we consider the positive solution $u(x, t)$ of the CR heat equation with respect to the sub-Laplacian

$$
\begin{equation*}
\frac{\partial}{\partial t} u(x, t)=\Delta_{b} u(x, t) \tag{1.6}
\end{equation*}
$$

on $M \times[0, T)$.

Proposition 1.1. Let $(M, J, \theta)$ be a closed pseudohermitian $(2 n+1)$-manifold. If $u(x, t)$ is the positive smooth solution of (1.6) on $M \times[0, \infty)$. Suppose that

$$
[2 \operatorname{Ric}-(n+2) \operatorname{Tor}](Z, Z) \geq-l_{0}|Z|^{2}
$$

for all $Z \in T_{1,0}$ and $l_{0}$ is a nonnegative constant. Then the function

$$
\begin{equation*}
G=t\left[\left|\nabla_{b} \varphi\right|^{2}+\left(1+\frac{2}{n}\right) \varphi_{t}\right] \tag{1.7}
\end{equation*}
$$

satisfies the inequality

$$
\begin{aligned}
\left(\Delta_{b}-\frac{\partial}{\partial t}\right) G \geq & -\frac{2 n}{n+2}\left\langle\nabla_{b} \varphi, \nabla_{b} G\right\rangle \\
& +\frac{2 n}{(n+1)(n+2)^{2} t} G\left(G-\frac{(n+1)(n+2)^{2}}{2 n}\right) \\
& -l_{0} t\left|\nabla_{b} \varphi\right|^{2}-\frac{8}{n} t u^{-2}\left\langle P u+\bar{P} u, d_{b} u\right\rangle_{L_{\theta}^{*}}
\end{aligned}
$$

Let $u(x, t)$ be a positive solution of (1.6) on $M \times[0, \infty)$. In section 2 , it is proved that if $P_{\beta} u=0$ at $t=0$, then $P_{\beta} u=0$ for all $t$ on a closed pseudohermitian $(2 n+1)$ manifold of zero torsion. Then the extra term of CR Bochner formula (2.1) becomes

$$
\begin{equation*}
\left\langle P u+\bar{P} u, d_{b} u\right\rangle=0 \tag{1.8}
\end{equation*}
$$

on $M \times[0, \infty)$.
Now by using the arguments of [LY], (2.1) and (1.8), we are able to derive the CR version of parabolic Li-Yau gradient estimate for the positive solution $u(x, t)$ of (1.6) on $M \times[0, \infty)$.

Corollary 1.2. Let $(M, J, \theta)$ be a closed pseudohermitian $(2 n+1)$-manifold of zero torsion and nonnegative pseudohermitian Ricci tensors. If $u(x, t)$ is the positive solution of (1.6) on $M \times[0, \infty)$ such that

$$
P_{\beta} u=0
$$

at $t=0$. Then $u$ satisfies the estimate

$$
\begin{equation*}
\frac{\left|\nabla_{b} u\right|^{2}}{u^{2}}+\frac{n+2}{n} \frac{u_{t}}{u} \leq \frac{(n+1)(n+2)^{2}}{2 n} \frac{1}{t} \tag{1.9a}
\end{equation*}
$$

on $M \times[0, \infty)$.
By combining the result of [CY] and Corollary 1.2, we get the following subgradient estimate of the logarithm of a positive solution to (1.6).

ThEOREM 1.3. Let $(M, J, \theta)$ be a closed pseudohermitian $(2 n+1)$-manifold of zero torsion and nonnegative pseudohermitian Ricci tensor. If $u(x, t)$ is the positive solution of (1.6) on $M \times[0, \infty)$ such that

$$
P_{\beta} u=0, \quad \beta=1,2, \cdots, n
$$

at $t=0$. Then there exist constants $C_{1}, C_{2}$ such that $u$ satisfies the subgradient estimate

$$
\begin{equation*}
t\left|\nabla_{b} \log u\right|^{2} \leq C_{1}+C_{2} t \tag{1.10}
\end{equation*}
$$

on $M \times[0, \infty)$.
Note that the arguments of [LY] can be extended easily to complete noncompact pseudohermitian $(2 n+1)$-manifold if one can have the CR version of Laplacian comparison theorem. Indeed, this is the case for a $(2 n+1)$-dimensional Heisenberg group $H^{n}$ (see section 5 for details). Then we have

THEOREM 1.4. If $u(x, t)$ be a positive smooth solution of (1.6)

$$
\left(\Delta_{b}-\frac{\partial}{\partial t}\right) u(x, t)=0
$$

on $H^{n} \times[0, T)$ with

$$
P_{\beta} u=0
$$

at $t=0$, then $u$ satisfies the subgradient estimate

$$
t\left|\nabla_{b} \log u\right|^{2} \leq \frac{(n+2)\left(n^{2}+5 n+2\right)}{4(n+1)}+\epsilon
$$

on $H^{n} \times[0, T)$ for any $\epsilon>0$.
REmark 1.2. For the CR Yamabe flow on a closed pseudohermitian 3-manifold of zero torsion and nonnegative Tanaka-Webster curvature, we have the similar result on CR version of Li-Yau-Hamilton inequality ([CCW]).

As a consequence, we have the following Liouville-type theorems for CR heat equation on $H^{n} \times[0, \infty)$.

Corollary 1.5. Let $\left(H^{n}, J, \theta\right)$ be the standard $(2 n+1)$-dimensional Heisenberg group. If $u(x, t)$ is a positive solution of (1.6) on $H^{n} \times[0, \infty)$ with a positive smooth $C R$-pluriharmonic function as an initial. Then $u$ is a constant.

REMARK 1.3. It is true that there are no nontrivial positive harmonic functions on $H^{n}$. See [KS] for details.

Now for any $L^{2}$-function $u(x, t)$, we may write

$$
u(x, t)=u_{\mathrm{ker}}(x, t)+u^{\perp}(x, t)
$$

with $P_{0}\left(u_{\text {ker }}(x, t)\right)=0$. From Lemma 2.2, we may split the CR heat equation (1.6) into the following heat equations respectively :

$$
\begin{equation*}
\frac{\partial}{\partial t} u^{\perp}=\Delta_{b} u^{\perp} \tag{1.11}
\end{equation*}
$$

and

$$
\begin{equation*}
\frac{\partial}{\partial t} u_{\mathrm{ker}}=\Delta_{b} u_{\mathrm{ker}} \tag{1.12}
\end{equation*}
$$

on Heisenberg group $\left(H^{n}, J, \theta\right)$. Observe that $H(x, y, t) \in C^{\infty}\left(H^{n} \times H^{n} \times \mathbf{R}^{+}\right)$and for any fixed $y, t, H(x, y, t) \in L^{2}\left(H^{n}\right)$. Then for any $L^{2}$-function $u(x, 0)=f(x)$, we have

$$
f(x)=f_{\mathrm{ker}}(x)+f^{\perp}(x)
$$

and

$$
H(x, y, t)=H_{\mathrm{ker}}(x, y, t)+H^{\perp}(x, y, t)
$$

with $P_{0}\left(f_{\text {ker }}(x)\right)=0$ and $P_{0}\left(H_{\text {ker }}(x, y, t)\right)=0$. Hence

$$
u^{\perp}(y, t)=\int H^{\perp}(x, y, t) f^{\perp}(x) d x
$$

and

$$
u_{\mathrm{ker}}(y, t)=\int H_{\mathrm{ker}}(x, y, t) f_{\mathrm{ker}}(x) d x
$$

As a consequence from Theorem 1.4 and Corollary 4.4, we have the following subgradient estimate of the heat kernel.

Corollary 1.6. Let $H(x, y, t)$ be the heat kernel of (1.6) on $H^{n} \times[0, T)$ with $H(x, y, t)=H_{\mathrm{ker}}(x, y, t)+H^{\perp}(x, y, t)$. Then for some constant $\delta$ and $0<\epsilon<1$,

$$
\left|\nabla_{b} H_{\mathrm{ker}}(x, y, t)\right| \leq C(\epsilon)^{\frac{\delta}{2}} t^{-\frac{(2 n+3)}{2}} \exp \left(-\frac{d_{c}^{2}(x, y)}{2(4+\epsilon) t}\right)
$$

with $C(\epsilon) \rightarrow \infty$ as $\epsilon \rightarrow 0$.
For simplicity, we first prove Theorems of this paper on a pseudohermitian ( $2 n+$ 1 )-manifold ( $M, J, \theta$ ) with $n=1$ as in section 3,4 . The higher dimensional cases will be given in section 5,6 .

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2. CR Bochner formula and preserving property. In this section, we will drive the CR version of Bochner formula and the preserving property for (1.6) on a pseudohermitian ( $M^{2 n+1}, J, \theta$ ).

We first derive the following CR version of Bochner formula on a complete pseudohermitian ( $M^{2 n+1}, J, \theta$ ).

Lemma 2.1. Let $\left(M^{2 n+1}, J, \theta\right)$ be a complete pseudohermitian manifold. For a real smooth function $u$ on $(M, J, \theta)$,

$$
\begin{align*}
\frac{1}{2} \Delta_{b}\left|\nabla_{b} u\right|^{2}= & \left|\left(\nabla^{H}\right)^{2} u\right|^{2}+\left(1+\frac{2}{n}\right)<\nabla_{b} u, \nabla_{b} \Delta_{b} u>_{L_{\theta}} \\
& +[2 \text { Ric }-(n+2) \text { Tor }]\left(\left(\nabla_{b} u\right)_{\mathbf{C}},\left(\nabla_{b} u\right)_{\mathbf{C}}\right)  \tag{2.1}\\
& -\frac{4}{n}<P u+\bar{P} u, d_{b} u>_{L_{\theta}^{*}} .
\end{align*}
$$

Here $\left(\nabla_{b} u\right)_{\mathbf{C}}=u_{\bar{\alpha}} Z_{\alpha}$ is the corresponding complex (1,0)-vector field of $\nabla_{b} u$ and $d_{b} u=u_{\alpha} \theta^{\alpha}+u_{\bar{\alpha}} \theta^{\bar{\alpha}}$.

Remark 2.1. In [Chi] and [CC], the CR Bochner formulae (2.1) was derived for $n=1$.

Proof. First from [Gr], we have for a real function $u$

$$
\begin{align*}
\frac{1}{2} \Delta_{b}\left|\nabla_{b} u\right|^{2}= & \left|\left(\nabla^{H}\right)^{2} u\right|^{2}+<\nabla_{b} u, \nabla_{b} \Delta_{b} u>_{L_{\theta}} \\
& +(2 \text { Ric }-n \text { Tor })\left(\left(\nabla_{b} u\right)_{\mathbf{C}},\left(\nabla_{b} u\right)_{\mathbf{C}}\right)  \tag{2.2}\\
& -2 i \sum_{\alpha=1}^{n}\left(u_{\alpha} u \bar{\alpha} 0-u_{\bar{\alpha}} u_{\alpha 0}\right)
\end{align*}
$$

We use the matrix $h_{\alpha \bar{\beta}}$ to raise and lower indices. In the following we always compute at one point. Then one may assume $h_{\alpha \bar{\beta}}=\delta_{\alpha \bar{\beta}}$ to lower the index. For instance,

$$
P_{\beta} \varphi=\sum_{\alpha=1}^{n}\left(\varphi_{\bar{\alpha} \alpha \beta}+i n A_{\beta \alpha} \varphi_{\bar{\alpha}}\right)
$$

and

$$
u_{0 \bar{\alpha}}-u_{\bar{\alpha} 0}=\sum_{\gamma=1}^{n} A_{\bar{\gamma}} \bar{\alpha}_{\gamma}
$$

and

$$
i u_{0}=u_{\gamma \bar{\beta}}-u_{\bar{\beta} \gamma}
$$

Compute

$$
\begin{aligned}
& i u_{\alpha} u_{\bar{\alpha} 0} \\
& =i u_{\alpha} u_{0 \bar{\alpha}}-i \sum_{\gamma=1}^{n} A \bar{\gamma} \bar{\alpha} u_{\alpha} u_{\gamma} \\
& =\frac{1}{n} u_{\alpha} \sum_{\beta=1}^{n}\left(u_{\beta \bar{\beta} \bar{\alpha}}-u_{\bar{\beta} \beta \bar{\alpha}}\right)-i \sum_{\gamma=1}^{n} A \bar{\gamma} \bar{\alpha} u_{\gamma} u_{\alpha} \\
& =\frac{1}{n} u_{\alpha} \bar{P}_{\alpha} u+i \sum_{\gamma=1}^{n} A \bar{\gamma} \bar{\alpha} u_{\alpha} u_{\gamma}-\frac{1}{n} \sum_{\beta=1}^{n}\left(u_{\alpha} u_{\bar{\beta} \beta \bar{\alpha}}\right) \\
& -i \sum_{\gamma=1}^{n} A \bar{\gamma} \bar{\alpha}_{\gamma} u_{\alpha} \\
& =\frac{1}{n} u_{\alpha} \bar{P}_{\alpha} u-\frac{1}{n} \sum_{\beta=1}^{n}\left(u_{\alpha} u_{\bar{\beta} \beta \bar{\alpha}}\right)
\end{aligned}
$$

and

$$
-i u_{\bar{\alpha}} u_{\alpha 0}=\operatorname{conj}\left(i u_{\alpha} u_{\bar{\alpha} 0}\right)
$$

Then

$$
\begin{aligned}
-2 i \sum_{\alpha=1}^{n}\left(u_{\alpha} u_{\bar{\alpha} 0}-u_{\bar{\alpha}} u_{\alpha 0}\right)= & -\frac{2}{n}<P u+\bar{P} u, d_{b} u>_{L_{\theta}^{*}} \\
& +\frac{2}{n} \sum_{\alpha, \beta=1}^{n}\left(u_{\alpha} u_{\bar{\beta} \beta \bar{\alpha}}+u_{\bar{\alpha}} u_{\beta \bar{\beta} \alpha}\right) .
\end{aligned}
$$

But

$$
\begin{aligned}
& <\nabla_{b} u, \nabla_{b} \Delta_{b} u>_{L_{\theta}} \\
& =\sum_{\alpha, \beta=1}^{n}\left[u_{\alpha}\left(u_{\bar{\beta} \beta}+u_{\beta \bar{\beta}}\right)_{\bar{\alpha}}+u_{\bar{\alpha}}\left(u_{\bar{\beta} \beta}+u_{\beta \bar{\beta}}\right)_{\alpha}\right] \\
& =\sum_{\alpha, \beta=1}^{n}\left(u_{\alpha} u_{\bar{\beta} \beta \bar{\alpha}}+u_{\bar{\alpha}} u_{\beta \bar{\beta} \alpha}\right)+\sum_{\alpha, \beta=1}^{n}\left(u_{\alpha} u_{\beta \bar{\beta} \bar{\alpha}}+u_{\bar{\alpha}} u_{\bar{\beta} \beta \alpha}\right) \\
& =\sum_{\alpha, \beta=1}^{n}\left(u_{\alpha} u_{\bar{\beta} \beta \bar{\alpha}}+u_{\bar{\alpha}} u_{\beta \bar{\beta} \alpha}\right)+<P u+\bar{P} u, d_{b} u>_{L_{\theta}^{*}} \\
& +i n \sum_{\gamma, \alpha=1}^{n}\left(A_{\bar{\gamma}} \bar{\alpha}_{\alpha} u_{\gamma}-A_{\gamma \alpha} u_{\bar{\alpha}} u_{\bar{\gamma}}\right) \\
& =\sum_{\alpha, \beta=1}^{n}\left(u_{\alpha} u_{\bar{\beta} \beta \bar{\alpha}}+u_{\bar{\alpha}} u_{\beta \bar{\beta} \alpha}\right)+<P u+\bar{P} u, d_{b} u>_{L_{\theta}^{*}} \\
& +n T o r\left(\left(\nabla_{b} u\right)_{\mathbf{C}},\left(\nabla_{b} u\right)_{\mathbf{C}}\right) .
\end{aligned}
$$

It follows that

$$
\begin{align*}
-2 i \sum_{\alpha=1}^{n}\left(u_{\alpha} u_{\bar{\alpha} 0}-u_{\bar{\alpha}} u_{\alpha 0}\right)= & -\frac{4}{n}<P u+\bar{P} u, d_{b} u>_{L_{\theta}^{*}} \\
& -2 \operatorname{Tor}\left(\left(\nabla_{b} u\right)_{\mathbf{C}},\left(\nabla_{b} u\right)_{\mathbf{C}}\right)  \tag{2.3}\\
& +\frac{2}{n}<\nabla_{b} u, \nabla_{b} \Delta_{b} u>_{L_{\theta}} .
\end{align*}
$$

Finally from (2.2) and (2.3), we have

$$
\begin{aligned}
\frac{1}{2} \Delta_{b}\left|\nabla_{b} u\right|^{2}= & \left|\left(\nabla^{H}\right)^{2} u\right|^{2}+\left(1+\frac{2}{n}\right)<\nabla_{b} u, \nabla_{b} \Delta_{b} u>_{L_{\theta}} \\
& +[2 \text { Ric }-(n+2) \text { Tor }]\left(\left(\nabla_{b} u\right)_{\mathbf{C}},\left(\nabla_{b} u\right)_{\mathbf{C}}\right) \\
& -\frac{4}{n}<P u+\bar{P} u, d_{b} u>_{L_{\theta}^{*}} .
\end{aligned}
$$

Lemma 2.2. Let $(M, J, \theta)$ be a closed pseudohermitian $(2 n+1)$-manifold of zero torsion. If $u(x, t)$ is a solution of

$$
\left(\Delta_{b}-\frac{\partial}{\partial t}\right) u(x, t)=0
$$

on $M \times[0, \infty)$ with $P_{\beta} u(x, 0)=0$. Then $P_{\beta} u(x, t)=0$ for all $t \in(0, \infty)$.
Proof. Let $(M, J, \theta)$ be a closed pseudohermitian $(2 n+1)$-manifold of zero torsion. From Remark 1.1, we have $P_{0} u=0$ if and only if $P_{\beta} u=0$ and

$$
P_{0} u=\left(\left(\Delta_{b}\right)^{2} u+n T^{2} u\right)
$$

It follows that $\Delta_{b} P_{0} u=P_{0} \Delta_{b} u$. Apply $P_{0}$ to the heat equation, we obtain

$$
\left(\Delta_{b}-\frac{\partial}{\partial t}\right) P_{0} u(x, t)=0
$$

on $M \times[0, \infty)$ with $P_{0} u(x, 0)=0$. Hence the Lemma follows from the maximum principle and Remark 1.1. $\square$

Lemma 2.3. Let $\left(H^{n}, J, \theta\right)$ be the standard $(2 n+1)$-dimensional Heisenberg group. If $u(x, t)$ is a solution of

$$
\left(\Delta_{b}-\frac{\partial}{\partial t}\right) u(x, t)=0
$$

on $M \times[0, \infty)$ with $P_{\beta} u(x, 0)=0, \beta=1, \ldots, n$. Then $P_{\beta} u(x, t)=0$ for all $t \in[0, \infty)$.
REMARK 2.2. Since $\left(H^{n}, J, \theta\right)$ is complete noncompact, $P_{\beta} u$ is not necessarily vanishing even if $P_{0} u=0$. So we need to have a different proof from Lemma 2.2.

Proof. We first do it for $n=1$. We need the following commutation relation ([L1])

$$
\begin{align*}
C_{I, 01}-C_{I, 10} & =C_{I, \overline{1}} A_{11}-k C_{I} A_{11, \overline{1}} \\
C_{I, 0 \overline{1}}-C_{I, \overline{10}} & =C_{I, 1} A_{\overline{11}}+k C_{I} A_{\overline{11}, 1}  \tag{2.4}\\
C_{I, 1 \overline{1}}-C_{I, \overline{1} 1} & =i C_{I, 0}+k W C_{I}
\end{align*}
$$

Here $C_{I}$ denotes a coefficient of a tensor with multi-index $I$ consisting of only 1 and $\overline{1}$, and $k$ is the number of 1 minus the number of $\overline{1}$ in $I$.

For

$$
\begin{aligned}
\frac{\partial}{\partial t} u_{\overline{1} 11} & =\left(\Delta_{b} u\right)_{\bar{T}_{11}} \\
& =\left(u_{\overline{\overline{1} 1}}+u_{1 \overline{1}}\right)_{\overline{1} 11} \\
& =\left(u_{\overline{1} 1 \overline{1} 11}+u_{1 \overline{1111}}\right)
\end{aligned}
$$

it follows from (2.4) that

$$
u_{\overline{\mathrm{T}}_{1111}}=u_{\overline{1} 11 \overline{1} 1}-i u_{\overline{1} 101}=u_{\overline{1} 11 \overline{1} 1}-i u_{\overline{1} 110}
$$

and

$$
\begin{aligned}
u_{1 \overline{11} 11} & =u_{\overline{\mathrm{T}}_{1 \overline{1} 11}}+i u_{o \overline{1}_{11}} \\
& =\left(u_{\mathrm{T}_{111} 1}-i u_{\overline{1} 101}\right)+i u_{0 \overline{\mathrm{~T}} 11} \\
& =\left(u_{\overline{\mathrm{T}}_{111 \overline{1}}}-i u_{\overline{\mathrm{T}}_{110}}\right)-i u_{\overline{1} 101}+i u_{0 \overline{1} 11} \\
& =u_{\overline{\mathrm{T}}_{111 \overline{1}}}-i u_{\overline{\mathrm{T}}_{110}} .
\end{aligned}
$$

Thus for $\mathcal{L}_{2}=-\Delta_{b}+2 i T$

$$
\begin{equation*}
\frac{\partial}{\partial t} u_{\overline{1} 11}=\Delta_{b} u_{\overline{1} 11}-2 i u_{\overline{1}_{110}}=-\mathcal{L}_{2} u_{\overline{1} 11} \tag{2.5}
\end{equation*}
$$

This plus (2.5) imply

$$
\frac{\partial}{\partial t}\left(P_{1} u\right)=-\mathcal{L}_{2}\left(P_{1} u\right)
$$

Similarly for $n \geq 2$, we have

$$
\frac{\partial}{\partial t}\left(P_{\beta} u\right)=\frac{\partial}{\partial t}\left(\sum_{\alpha=1}^{n} u_{\bar{\alpha} \alpha \beta}\right)=\sum_{\alpha=1}^{n}\left(\Delta_{b} u\right)_{\bar{\alpha} \alpha \beta}=\sum_{\gamma, \alpha=1}^{n}\left(u_{\gamma \bar{\gamma}}+u_{\bar{\gamma} \gamma}\right)_{\bar{\alpha} \alpha \beta} .
$$

Now by commutation relations

$$
\begin{align*}
u_{\gamma \overline{\gamma \alpha} \alpha \beta} & =u_{\bar{\gamma} \gamma \bar{\alpha} \alpha \beta}+i u_{0 \bar{\alpha} \alpha \beta} \\
& =u_{\bar{\gamma} \gamma \bar{\alpha} \beta \alpha}+i u_{\bar{\alpha} \alpha \beta 0} \\
& =u_{\bar{\gamma} \gamma \beta \bar{\alpha} \alpha}-i u_{\bar{\gamma} \gamma 0 \alpha}+i u_{\bar{\alpha} \alpha \beta 0}  \tag{2.6}\\
& =u_{\bar{\gamma} \gamma \beta \bar{\alpha} \alpha}-i u_{\bar{\gamma} \gamma \alpha 0}+i u_{\bar{\alpha} \alpha \beta 0}
\end{align*}
$$

and

$$
\begin{align*}
u_{\bar{\gamma} \gamma \bar{\alpha} \alpha \beta} & =u_{\bar{\gamma} \gamma \bar{\alpha} \beta \alpha} \\
& =u_{\bar{\gamma} \gamma \beta \bar{\alpha} \alpha}-i u_{\bar{\gamma} \gamma 0 \alpha}  \tag{2.7}\\
& =u_{\bar{\gamma} \gamma \beta \alpha \bar{\alpha}}-i u_{\bar{\gamma} \gamma \beta 0}-i u_{\bar{\gamma} \gamma \alpha 0} .
\end{align*}
$$

It follows from (2.6) and (2.7) that

$$
\begin{aligned}
\frac{\partial}{\partial t}\left(P_{\beta} u\right) & =\sum_{\gamma, \alpha=1}^{n}\left(u_{\gamma \overline{\gamma \alpha \alpha} \alpha \beta}+u_{\bar{\gamma} \gamma \bar{\alpha} \alpha \beta}\right) \\
& =\Delta_{b}\left(P_{\beta} u\right)-2 i \sum_{\gamma, \alpha=1}^{n} u_{\bar{\gamma} \gamma \alpha 0}+i \sum_{\gamma, \alpha=1}^{n} u_{\bar{\alpha} \alpha \beta 0}-i \sum_{\gamma, \alpha=1}^{n} u_{\bar{\gamma} \gamma \beta 0} \\
& =\Delta_{b}\left(P_{\beta} u\right)-2 i \sum_{\gamma, \alpha=1}^{n} u_{\bar{\gamma} \gamma \alpha 0} \\
& =\Delta_{b}\left(P_{\beta} u\right)-2 i T\left(\sum_{\alpha=1}^{n} P_{\alpha} u\right) .
\end{aligned}
$$

Hence

$$
\frac{\partial}{\partial t}\left(\sum_{\beta=1}^{n} P_{\beta} u\right)=\Delta_{b}\left(\sum_{\beta=1}^{n} P_{\beta} u\right)-i 2 n T\left(\sum_{\beta=1}^{n} P_{\beta} u\right)
$$

That is

$$
\frac{\partial}{\partial t}\left(\sum_{\beta=1}^{n} P_{\beta} u\right)=-\mathcal{L}_{2 n}\left(\sum_{\beta=1}^{n} P_{\beta} u\right)
$$

Here $\mathcal{L}_{2 n}=-\Delta_{b}+i 2 n T$. Since $2 n$ is not an odd integer, $-\mathcal{L}_{2 n}$ is a subelliptic operator again. Then by the uniqueness of solution to subelliptic parabolic equation, $P_{\beta} u(x, t)=0$ for all $t \in[0, \infty)$ if $P_{\beta} u(x, 0)=0, \quad \beta=1, \ldots, n . \square$
3. Subgradient estimate of the $\mathbf{C R}$ heat equation. In this section, we first establish the subgradient estimate of Theorem 1.3 for $n=1$. For $n \geq 2$, we refer it to section 6 .

Let $(M, J, \theta)$ be a closed pseudohermitian 3-manifold. By using the arguments of [LY], we are able to derive the CR version of parabolic Li-Yau gradient estimate for the positive solution $u(x, t)$ of (1.6) on $M \times[0, \infty)$.

Let $\varphi=\log u$. Then $\varphi$ satisfies

$$
\left(\Delta_{b}-\frac{\partial}{\partial t}\right) \varphi=-\left|\nabla_{b} \varphi\right|^{2}
$$

On the other hand, from Cao-Yau's ([CY]) paper, one has the standard parabolic Li-Yau gradient estimate.

Proposition 3.1. ([CY, Theorem 2.1]) Let $(M, J, \theta)$ be a closed pseudohermitian $(2 n+1)$-manifold and $u(x, t)$ be a positive smooth solution of (1.6) on $M \times[0, \infty)$. Then there exist constants $C^{\prime}, C^{\prime \prime}$ and $\delta_{0}>1$ such that for any $\delta \geq \delta_{0}$, u satisfies the estimate

$$
\begin{equation*}
\frac{\left|\nabla_{b} u\right|^{2}}{u^{2}}-\delta \frac{u_{t}}{u} \leq \frac{C^{\prime}}{t}+C^{\prime \prime} \tag{3.1}
\end{equation*}
$$

on $M \times[0, \infty)$.

Now we derive the CR version of parabolic Li-Yau gradient estimate for the positive solution of the CR heat equation. First, we need the following Lemma.

LEMMA 3.2. Let $(M, J, \theta)$ be a closed pseudohermitian $(2 n+1)$-manifold. Let $\varphi=\ln f$, for $f>0$. Then

$$
\begin{align*}
& \left\langle P \varphi+\bar{P} \varphi, d_{b} \varphi\right\rangle_{L_{\theta}^{*}}  \tag{3.2}\\
& \left.=f^{-2}\left\langle P f+\bar{P} f, d_{b} f\right\rangle_{L_{\theta}^{*}}-\left.\frac{1}{2}\left\langle\nabla_{b} \varphi, \nabla_{b}\right| \nabla_{b} \varphi\right|^{2}\right\rangle-\frac{1}{2} f^{-1} \Delta_{b} f\left|\nabla_{b} \varphi\right|^{2} .
\end{align*}
$$

Proof. In the following, we use the Einstein convention notation. Let $Q(x)=$ $\left|\nabla_{b} \varphi\right|^{2}(x)$. We compute

$$
\begin{aligned}
\nabla_{b} Q & =Q_{\bar{\alpha}} Z_{\alpha}+Q_{\alpha} Z_{\bar{\alpha}}=2 \nabla_{b}\left(\varphi_{\alpha} \varphi_{\bar{\alpha}}\right) \\
& =2 f^{-4}\left(f^{2} f_{\alpha} f_{\bar{\alpha} \bar{\beta}}+f^{2} f_{\bar{\alpha}} f_{\alpha \bar{\beta}}-2 f_{\alpha} f_{\bar{\alpha}} f_{\bar{\beta}}\right) Z_{\beta}+\text { complex conjugate. }
\end{aligned}
$$

It follows that

$$
\begin{aligned}
& P_{\beta} \varphi \\
= & \varphi_{\bar{\alpha} \alpha \beta}+i n A_{\beta \alpha} \varphi_{\bar{\alpha}} \\
= & f^{-4}\left(f^{3} f_{\bar{\alpha} \alpha \beta}-f^{2} f_{\alpha} f_{\bar{\alpha} \beta}-f^{2} f_{\bar{\alpha}} f_{\alpha \beta}-f^{2} f_{\beta} f_{\bar{\alpha} \alpha}+2 f f_{\alpha} f_{\beta} f_{\bar{\alpha}}\right)+i n A_{\beta \alpha} f^{-1} f_{\bar{\alpha}} \\
= & f^{-1}\left(P_{\beta} f-\frac{1}{2} f Q_{\beta}-f^{-1} f_{\beta} f_{\bar{\alpha} \alpha}\right) \\
= & f^{-1}\left(P_{\beta} f-\frac{1}{2} f Q_{\beta}-\varphi_{\beta} f_{\bar{\alpha} \alpha}\right)
\end{aligned}
$$

thus

$$
\begin{aligned}
\left\langle P \varphi+\bar{P} \varphi, d_{b} \varphi\right\rangle_{L_{\theta}^{*}} & =\left\langle\left(P_{\beta} \varphi\right) \theta^{\beta}+\left(\bar{P}_{\beta} \varphi\right) \theta^{\bar{\beta}}, \varphi_{\beta} \theta^{\beta}+\varphi_{\bar{\beta}} \theta^{\bar{\beta}}\right\rangle_{L_{\theta}^{*}} \\
& =\left(P_{\beta} \varphi\right) \varphi_{\bar{\beta}}+\left(\bar{P}_{\beta} \varphi\right) \varphi_{\beta} \\
& =f^{-1}\left(P_{\beta} f-\frac{1}{2} f Q_{\beta}-\varphi_{\beta} f_{\bar{\alpha} \alpha}\right) \varphi_{\bar{\beta}}+\text { complex conjugate } \\
& \left.=f^{-2}\left\langle P f+\bar{P} f, d_{b} f\right\rangle_{L_{\theta}^{*}}-\left.\frac{1}{2}\left\langle\nabla_{b} \varphi, \nabla_{b}\right| \nabla_{b} \varphi\right|^{2}\right\rangle-\frac{1}{2} f^{-1} \Delta_{b} f\left|\nabla_{b} \varphi\right|^{2} .
\end{aligned}
$$

This implies the Lemma.
Lemma 3.3. Let $(M, J, \theta)$ be a closed pseudohermitian 3-manifold. If $u(x, t)$ is the positive smooth solution $u(x, t)$ of (1.6) on $M \times[0, \infty)$. Suppose that

$$
(2 \text { Ric }-3 \text { Tor })(Z, Z) \geq-k_{0}|Z|^{2}
$$

for all $Z \in T_{1,0}$ and $k_{0}$ is a nonnegative constant. Then the function

$$
\begin{equation*}
F=t\left(\left|\nabla_{b} \varphi\right|^{2}+3 \varphi_{t}\right) \tag{3.3}
\end{equation*}
$$

satisfies the inequality

$$
\begin{aligned}
\left(\Delta_{b}-\frac{\partial}{\partial t}\right) F \geq & -\frac{2}{3}\left\langle\nabla_{b} \varphi, \nabla_{b} F\right\rangle+\frac{1}{9 t} F(F-9)+ \\
& -k_{0} t\left|\nabla_{b} \varphi\right|^{2}-8 t u^{-2}\left\langle P u+\bar{P} u, d_{b} u\right\rangle_{L_{\theta}^{*}}
\end{aligned}
$$

Proof. First differentiating (3.3) w.r.t. the $t$-variable, we have

$$
\begin{align*}
F_{t} & =\frac{1}{t} F+t\left(\left|\nabla_{b} \varphi\right|^{2}+3 \varphi_{t}\right)_{t} \\
& =\frac{1}{t} F+t\left(4\left|\nabla_{b} \varphi\right|^{2}+3 \Delta_{b} \varphi\right)_{t}  \tag{3.4}\\
& =\frac{1}{t} F+t\left[8\left\langle\nabla_{b} \varphi, \nabla_{b} \varphi_{t}\right\rangle+3 \Delta_{b} \varphi_{t}\right] .
\end{align*}
$$

By using the CR version of Bochner formula (2.1) and Lemma 3.2, one obtains

$$
\begin{align*}
\Delta_{b} F= & t\left(\Delta_{b}\left|\nabla_{b} \varphi\right|^{2}+3 \Delta_{b} \varphi_{t}\right) \\
= & t\left[2\left|\left(\nabla^{H}\right)^{2} \varphi\right|^{2}+6\left\langle\nabla_{b} \varphi, \nabla_{b} \Delta_{b} \varphi\right\rangle\right. \\
& +2(2 \text { Ric }-3 T o r)\left(\left(\nabla_{b} \varphi\right)_{\mathbf{C}},\left(\nabla_{b} \varphi\right) \mathbf{C}\right) \\
& \left.-8\left\langle P \varphi+\bar{P} \varphi, d_{b} \varphi\right\rangle_{L_{\theta}^{*}}+3 \Delta_{b} \varphi_{t}\right] \\
\geq & t\left[4\left|\varphi_{11}\right|^{2}+\left(\Delta_{b} \varphi\right)^{2}+6\left\langle\nabla_{b} \varphi, \nabla_{b} \Delta_{b} \varphi\right\rangle-k_{0}\left|\nabla_{b} \varphi\right|^{2}\right.  \tag{3.5}\\
& \left.-8\left\langle P \varphi+\bar{P} \varphi, d_{b} \varphi\right\rangle_{L_{\theta}^{*}}+3 \Delta_{b} \varphi_{t}\right] \\
= & t\left[4\left|\varphi_{11}\right|^{2}+\left(\Delta_{b} \varphi\right)^{2}+6\left\langle\nabla_{b} \varphi, \nabla_{b} \Delta_{b} \varphi\right\rangle-k_{0}\left|\nabla_{b} \varphi\right|^{2}\right. \\
& -8 u^{-2}\left\langle P u+\bar{P} u, d_{b} u\right\rangle_{L_{\theta}^{*}}+4 \varphi_{t}\left|\nabla_{b} \varphi\right|^{2} \\
& \left.\left.+\left.4\left\langle\nabla_{b} \varphi, \nabla_{b}\right| \nabla_{b} \varphi\right|^{2}\right\rangle+3 \Delta_{b} \varphi_{t}\right] .
\end{align*}
$$

Here we have used the inequalities

$$
\begin{gather*}
\left|\left(\nabla^{H}\right)^{2} \varphi\right|^{2}=2\left|\varphi_{11}\right|^{2}+\frac{1}{2}\left(\Delta_{b} \varphi\right)^{2}+\frac{1}{2} \varphi_{0}^{2} \geq 2\left|\varphi_{11}\right|^{2}+\frac{1}{2}\left(\Delta_{b} \varphi\right)^{2}  \tag{3.6}\\
(2 \text { Ric }-3 \text { Tor })\left(\left(\nabla_{b} \varphi\right)_{\mathbb{C}},\left(\nabla_{b} \varphi\right)_{\mathbb{C}}\right) \geq-k_{0}\left|\left(\nabla_{b} \varphi\right)_{\mathbb{C}}\right|^{2}=-\frac{k_{0}}{2}\left|\nabla_{b} \varphi\right|^{2},
\end{gather*}
$$

and

$$
\varphi_{t}=\frac{u_{t}}{u}=\frac{\Delta_{b} u}{u} .
$$

Applying the formula

$$
\begin{equation*}
\Delta_{b} \varphi=\varphi_{t}-\left|\nabla_{b} \varphi\right|^{2}=\frac{1}{3 t} F-\frac{4}{3}\left|\nabla_{b} \varphi\right|^{2} \tag{3.7}
\end{equation*}
$$

and combining (3.4), (3.5), we conclude

$$
\begin{aligned}
\left(\Delta_{b}-\frac{\partial}{\partial t}\right) F \geq & -\frac{1}{t} F+t\left[4\left|\varphi_{11}\right|^{2}+\left(\Delta_{b} \varphi\right)^{2}+6\left\langle\nabla_{b} \varphi, \nabla_{b} \Delta_{b} \varphi\right\rangle\right. \\
& \left.+\left.4\left\langle\nabla_{b} \varphi, \nabla_{b}\right| \nabla_{b} \varphi\right|^{2}\right\rangle-8\left\langle\nabla_{b} \varphi, \nabla_{b} \varphi_{t}\right\rangle \\
& \left.-k_{0}\left|\nabla_{b} \varphi\right|^{2}+4 \varphi_{t}\left|\nabla_{b} \varphi\right|^{2}-8 u^{-2}\left\langle P u+\bar{P} u, d_{b} u\right\rangle_{L_{\theta}^{*}}\right] \\
= & -\frac{1}{t} F+t\left[-\frac{2}{3 t}\left\langle\nabla_{b} \varphi, \nabla_{b} F\right\rangle-\left.\frac{4}{3}\left\langle\nabla_{b} \varphi, \nabla_{b}\right| \nabla_{b} \varphi\right|^{2}\right\rangle+4\left|\varphi_{11}\right|^{2} \\
& \left.+\left(\Delta_{b} \varphi\right)^{2}-k_{0}\left|\nabla_{b} \varphi\right|^{2}+4 \varphi_{t}\left|\nabla_{b} \varphi\right|^{2}-8 u^{-2}\left\langle P u+\bar{P} u, d_{b} u\right\rangle_{L_{\theta}^{*}}\right] .
\end{aligned}
$$

Now it is easy to see that

$$
\left.\left.\left\langle\nabla_{b} \varphi, \nabla_{b}\right| \nabla_{b} \varphi\right|^{2}\right\rangle=4 \operatorname{Re}\left(\varphi_{11} \varphi_{\overline{1}} \varphi_{\overline{1}}\right)+\Delta_{b} \varphi\left|\nabla_{b} \varphi\right|^{2} .
$$

Thus

$$
\begin{aligned}
\left.-\left.\frac{4}{3}\left\langle\nabla_{b} \varphi, \nabla_{b}\right| \nabla_{b} \varphi\right|^{2}\right\rangle & =-\frac{16}{3} \operatorname{Re}\left(\varphi_{11} \varphi_{\overline{1}} \varphi_{\overline{1}}\right)-\frac{4}{3} \Delta_{b} \varphi\left|\nabla_{b} \varphi\right|^{2} \\
& \geq-4\left|\varphi_{11}\right|^{2}-\frac{16}{9}\left|\varphi_{\overline{1}}\right|^{4}-\frac{4}{3} \Delta_{b} \varphi\left|\nabla_{b} \varphi\right|^{2} \\
& =-4\left|\varphi_{11}\right|^{2}-\frac{4}{9}\left|\nabla_{b} \varphi\right|^{4}-\frac{4}{3} \Delta_{b} \varphi\left|\nabla_{b} \varphi\right|^{2} .
\end{aligned}
$$

Here we have used the basic inequality $2 \operatorname{Re}(z w) \leq \epsilon|z|^{2}+\epsilon^{-1}|w|^{2}$ for all $\epsilon>0$. All these imply

$$
\begin{aligned}
\left(\Delta_{b}-\frac{\partial}{\partial t}\right) F \geq & -\frac{1}{t} F-\frac{2}{3}\left\langle\nabla_{b} \varphi, \nabla_{b} F\right\rangle+t\left[\left(\Delta_{b} \varphi\right)^{2}+\frac{8}{3} \Delta_{b} \varphi\left|\nabla_{b} \varphi\right|^{2}\right. \\
& \left.+\frac{32}{9}\left|\nabla_{b} \varphi\right|^{4}-k_{0}\left|\nabla_{b} \varphi\right|^{2}-8 u^{-2}\left\langle P u+\bar{P} u, d_{b} u\right\rangle_{L_{\theta}^{*}}\right] \\
\geq & -\frac{2}{3}\left\langle\nabla_{b} \varphi, \nabla_{b} F\right\rangle+\frac{1}{9 t} F(F-9) \\
& -k_{0} t\left|\nabla_{b} \varphi\right|^{2}-8 u^{-2}\left\langle P u+\bar{P} u, d_{b} u\right\rangle_{L_{\theta}^{*}}
\end{aligned}
$$

This completes the proof of Lemma 3.3.
THEOREM 3.4. Let $(M, J, \theta)$ be a closed pseudohermitian 3-manifold of zero torsion and nonnegative Tanaka-Webster scalar curvature. If $u(x, t)$ is the positive solution of (1.6) on $M \times[0, \infty)$ such that

$$
P_{1} u=0
$$

at $t=0$. Then $u$ satisfies the estimate

$$
\begin{equation*}
\frac{\left|\nabla_{b} u\right|^{2}}{u^{2}}+3 \frac{u_{t}}{u} \leq \frac{9}{t} \tag{3.8}
\end{equation*}
$$

on $M \times[0, \infty)$.
Proof. Applying Lemma 3.3 to $\varphi$ by setting $A_{11}=0, k_{0}=0$ and

$$
\left\langle P u+\bar{P} u, d_{b} u\right\rangle=0 .
$$

Then we have

$$
\begin{equation*}
\left(\Delta_{b}-\frac{\partial}{\partial t}\right) F \geq-\frac{2}{3}\left\langle\nabla_{b} \varphi, \nabla_{b} F\right\rangle+\frac{1}{9 t} F(F-9) \tag{3.9}
\end{equation*}
$$

The theorem claims that $F$ is at most 9 . If not, at the maximum point $\left(x_{0}, t_{0}\right)$ of $F$ on $M \times[0, T]$ for some $T>0$,

$$
F\left(x_{0}, t_{0}\right)>9
$$

Clearly, $t_{0}>0$, because $F(x, 0)=0$. By the fact that $\left(x_{0}, t_{0}\right)$ is a maximum point of $F$ on $M \times[0, T]$, we have

$$
\begin{aligned}
& \Delta_{b} F\left(x_{0}, t_{0}\right) \leq 0 \\
& \nabla_{b} F\left(x_{0}, t_{0}\right)=0
\end{aligned}
$$

and

$$
F_{t}\left(x_{0}, t_{0}\right) \geq 0
$$

Combining with (3.9), this implies

$$
0 \geq \frac{1}{9 t_{0}} F\left(x_{0}, t_{0}\right)\left(F\left(x_{0}, t_{0}\right)-9\right),
$$

which is a contradiction. Hence $F \leq 9$ and the theorem follows.
Then by combining Proposition 3.1 and Theorem 3.4, the subgradient estimate Theorem 1.3 follows easily for $n=1$.
4. Subgradient estimates in the Heisenberg group $H^{1}$. In this section, we first establish Liouville-type theorems for the CR heat equation on a 3-dimensional Heisenberg group $H^{1}$. Secondly, we derive the subgradient estimate for CR Heat Kernel on $H^{1}$.

From [PP], we recall the following result.
Proposition 4.1. If $u(x, t)$ be a positive smooth solution of (1.6) on $H^{n} \times[0, T)$, then $u$ satisfies the estimate

$$
\frac{\left|\nabla_{b} u\right|^{2}}{u^{2}}-\frac{u_{t}}{u} \leq \frac{n}{t}
$$

on $H^{n} \times[0, T)$.

THEOREM 4.2. If $u(x, t)$ be a positive smooth solution of (1.6)

$$
\left(\Delta_{b}-\frac{\partial}{\partial t}\right) u(x, t)=0
$$

on $H^{1} \times[0, T)$ with

$$
P_{1} u=0
$$

at $t=0$, then $u$ satisfies the subgradient estimate

$$
\frac{\left|\nabla_{b} u\right|^{2}}{u^{2}}+3 \frac{u_{t}}{u} \leq \frac{9+\epsilon}{t}
$$

on $H^{1} \times[0, T)$ for any $\epsilon>0$.
Proof. Let $B_{2 R}$ be a ball of radius $2 R$ center at $O \in H^{1}$. Let $\varphi=\log u$ and $F=t\left(\left|\nabla_{b} \varphi\right|^{2}+3 \varphi_{t}\right)$, then

$$
\sup _{B_{R}}\left(\frac{\left|\nabla_{b} u\right|^{2}}{u^{2}}+3 \frac{u_{t}}{u}\right)=\sup _{B_{R}} \frac{F}{t}
$$

Let $\psi \in C_{0}^{\infty}(R)$ be a cut-off function ([DT]) such that $0 \leq \psi \leq 1, \psi(t) \equiv 1$ for $t \in[0,1], \psi(t) \equiv 0$ for $t \geq 2$. We also require

$$
\begin{equation*}
\psi^{\prime} \leq 0, \quad \psi^{\prime \prime} \geq-C_{1}, \quad \text { and } \quad \frac{\left|\psi^{\prime}\right|^{2}}{\psi} \leq C_{2} \tag{4.1}
\end{equation*}
$$

where $C_{1}$ and $C_{2}$ are positive constants. Denote by $d_{c}(x)$ be the Carnot-Carathéodory distance from $O$ to $x$ in $H^{1}$. Then we define $\eta(x)=\psi\left(\frac{d_{c}(x)}{R}\right)$. It is clear that $\operatorname{supp} \eta \subset B_{2 R}$ and $\left.\eta\right|_{B_{R}} \equiv 1$.

We want to apply the maximum principle to $\eta F$. The function $\eta$ may not be smooth at the cut locus of $O \in H^{1}$. However, when applying the maximum principle, we can assume $\eta$ is differentiable as in $[\mathrm{LY}]$.

If $\eta F$ attains its maximum at $\left(x_{0}, t_{0}\right) \in B_{2 R} \times\left[0, T^{\prime}\right]$ with $0<T^{\prime}<T$, clearly we may assume $(\eta F)\left(x_{0}, t_{0}\right)>0$ (otherwise $F \leq 0$, and the theorem is true). So $x_{0} \in B_{2 R}, t_{0}>0$, and by the maximum principle, at $\left(x_{0}, t_{0}\right)$

$$
\begin{gather*}
\nabla_{b}(\eta F)=F \nabla_{b} \eta+\eta \nabla_{b} F=0  \tag{4.2}\\
\Delta_{b}(\eta F) \leq 0 \tag{4.3}
\end{gather*}
$$

and

$$
\begin{equation*}
\frac{\partial}{\partial t}(\eta F)=\eta F_{t} \geq 0 \tag{4.4}
\end{equation*}
$$

In the sequel, all computations will be at the point $\left(x_{0}, t_{0}\right)$. By (4.2), $\nabla_{b} F=$ $-F \nabla_{b} \eta / \eta$, and by (4.3)

$$
\begin{align*}
0 & \geq \Delta_{b}(\eta F)=F \Delta_{b} \eta+\eta \Delta_{b} F+2\left\langle\nabla_{b} \eta, \nabla_{b} F\right\rangle  \tag{4.5}\\
& =F \Delta_{b} \eta+\eta \Delta_{b} F-2 F \frac{\left|\nabla_{b} \eta\right|^{2}}{\eta}
\end{align*}
$$

By (4.1), we have

$$
\begin{equation*}
\frac{\left|\nabla_{b} \eta\right|^{2}}{\eta}=\frac{\left|\psi^{\prime}\right|^{2}\left|\nabla_{b} d_{c}\right|^{2}}{R^{2} \psi}=\frac{\left|\psi^{\prime}\right|^{2}}{R^{2} \psi} \leq \frac{C_{2}}{R^{2}} \tag{4.6}
\end{equation*}
$$

and

$$
\Delta_{b} \eta=\frac{\psi^{\prime \prime}\left|\nabla_{b} d_{c}\right|^{2}}{R^{2}}+\frac{\psi^{\prime} \Delta_{b} d_{c}}{R}=\frac{\psi^{\prime \prime}}{R^{2}}+\frac{\psi^{\prime}}{R} \Delta_{b} d_{c} \geq-\frac{C_{1}}{R^{2}}-\frac{\sqrt{C_{2}}}{R} \Delta_{b} d_{c}
$$

Since in $H^{1}$, we have the sub-Laplacian comparison $(*)$ (see the proof in next section)

$$
\begin{equation*}
\Delta_{b} d_{c} \leq \frac{C}{d_{c}} \tag{*}
\end{equation*}
$$

for some constant $C$. Then

$$
\Delta_{b} \eta \geq-\frac{C_{3}}{R^{2}}
$$

Substituting this into (4.5) and applying Lemma 2.3 and Lemma 3.3 with $A_{11}=0$, $k_{0}=0$, all these imply

$$
\begin{aligned}
0 & \geq \Delta_{b}(\eta F) \geq-\frac{C_{3}}{R^{2}} F-2 F \frac{\left|\nabla_{b} \eta\right|^{2}}{\eta}+\eta \Delta_{b} F \\
& \geq-\frac{C_{3}}{R^{2}} F-2 F \frac{\left|\nabla_{b} \eta\right|^{2}}{\eta}+\eta\left[F_{t}+2\left\langle\nabla_{b} \varphi, \nabla_{b} F\right\rangle+\frac{1}{9 t} F(F-9)\right]
\end{aligned}
$$

Since $\eta F_{t}=(\eta F)_{t} \geq 0,2 \eta\left\langle\nabla_{b} \varphi, \nabla_{b} F\right\rangle=\frac{2}{3} F\left\langle\nabla_{b} \varphi, \nabla_{b} \eta\right\rangle$, the above inequality can be reduced as

$$
0 \geq-\frac{C_{3}}{R^{2}} F-2 F \frac{\left|\nabla_{b} \eta\right|^{2}}{\eta}+\frac{2}{3} F\left\langle\nabla_{b} \varphi, \nabla_{b} \eta\right\rangle+\frac{1}{9 t} \eta F(F-9)
$$

and multiplying by $\eta$, we get

$$
\begin{aligned}
0 & \geq-\frac{C_{3}}{R^{2}} \eta F-2 F\left|\nabla_{b} \eta\right|^{2}+\frac{2}{3} F \eta\left\langle\nabla_{b} \varphi, \nabla_{b} \eta\right\rangle+\frac{1}{9 t} \eta^{2} F(F-9) \\
& =(\eta F)\left(-\frac{C_{3}}{R^{2}}-2 \frac{\left|\nabla_{b} \eta\right|^{2}}{\eta}-\frac{\eta}{t}\right)+\frac{2}{3} \eta F\left\langle\nabla_{b} \varphi, \nabla_{b} \eta\right\rangle+\frac{1}{9 t}(\eta F)^{2} \\
& \geq(\eta F)\left(-\frac{C_{3}}{R^{2}}-2 \frac{\left|\nabla_{b} \eta\right|^{2}}{\eta}-\frac{\eta}{t}\right)-2 \eta F\left|\nabla_{b} \varphi\right|\left|\nabla_{b} \eta\right|+\frac{1}{9 t}(\eta F)^{2}
\end{aligned}
$$

Using $0 \leq \eta \leq 1$, and (4.6), we get

$$
\begin{aligned}
0 & \geq(\eta F)\left(-\frac{C_{3}}{R^{2}}-2 \frac{C_{2}}{R^{2}}-\frac{1}{t}\right)-2 \eta^{3 / 2} F \frac{\sqrt{C_{2}}}{R}\left|\nabla_{b} \varphi\right|+\frac{1}{9 t}(\eta F)^{2} \\
& =(\eta F)\left(-\frac{1}{t}-\frac{C_{4}}{R^{2}}\right)-2 \eta^{3 / 2} F \frac{\sqrt{C_{2}}}{R}\left|\nabla_{b} \varphi\right|+\frac{1}{9 t}(\eta F)^{2}
\end{aligned}
$$

where $C_{4}=C_{3}+2 C_{2}$. Multiplying by $t$ to the above inequality, this leads to

$$
\begin{aligned}
0 & \geq(\eta F)\left(\frac{1}{9} \eta F-1-\frac{C_{4}}{R^{2}} t\right)-2 t \eta^{3 / 2} F \frac{\sqrt{C_{2}}}{R}\left|\nabla_{b} \varphi\right| \\
& =(\eta F)\left(\frac{1}{9} \eta F-1-\frac{C_{4}}{R^{2}} t-\frac{2 \sqrt{C_{2}}}{R} \eta^{1 / 2}\left|\nabla_{b} \varphi\right| t\right)
\end{aligned}
$$

Therefore, we get

$$
\eta F \leq 9+\frac{9 C_{4}}{R^{2}} t+\frac{18 \sqrt{C_{2}}}{R} \eta^{1 / 2}\left|\nabla_{b} \varphi\right| t
$$

(i) If $\varphi_{t}\left(x_{0}, t_{0}\right)<0$, then, by the Proposition $4.1,\left|\nabla_{b} \varphi\right|^{2} \leq\left|\nabla_{b} \varphi\right|^{2}-\varphi_{t} \leq 1 / t$ and using $0 \leq \eta \leq 1$, we have

$$
\eta F \leq 9+\frac{C_{4}}{R^{2}} t+\frac{18 \sqrt{C_{2}}}{R} t^{1 / 2}
$$

Recall that all the computations are at $\left(x_{0}, t_{0}\right)$ and $\left(x_{0}, t_{0}\right)$ is the maximum point, $t_{0} \leq T^{\prime}$, so we have

$$
(\eta F)\left(x, T^{\prime}\right) \leq(\eta F)\left(x_{0}, t_{0}\right) \leq 9+\frac{C_{4}}{R^{2}} T^{\prime}+\frac{18 \sqrt{C_{2}}}{R} \sqrt{T^{\prime}}
$$

But $\eta \equiv 1$ on $B_{R}$, hence

$$
\begin{equation*}
\sup _{x \in B_{R}}\left(\left|\nabla_{b} \varphi\right|^{2}+3 \varphi_{t}\right)\left(x, T^{\prime}\right) \leq \frac{C_{4}}{R^{2}}+\frac{18 \sqrt{C_{2}}}{R} \frac{1}{\sqrt{T^{\prime}}}+\frac{9}{T^{\prime}} . \tag{4.7}
\end{equation*}
$$

Now for any fixed time $t \in(0, \infty)$, by letting $R \rightarrow \infty$, one obtains

$$
\frac{\left|\nabla_{b} u\right|^{2}}{u^{2}}+3 \frac{u_{t}}{u} \leq \frac{9}{t}
$$

on $H^{1} \times[0, T)$.
(ii) If $\varphi_{t}\left(x_{0}, t_{0}\right) \geq 0$, then $t^{1 / 2}\left|\nabla_{b} \varphi\right| \leq F^{1 / 2}$. The above inequality leads to

$$
\eta F-\frac{18 \sqrt{C_{2}}}{R} t^{1 / 2}(\eta F)^{1 / 2}-\left(9+\frac{C_{4}}{R^{2}} t\right) \leq 0
$$

Hence

$$
\eta F \leq 9+\frac{C_{4}}{R^{2}} t+\frac{18 \sqrt{C_{2}}}{R} t^{1 / 2}(\eta F)^{1 / 2}
$$

If $(\eta F) \leq 1$, then

$$
\eta F \leq 9+\frac{C_{4}}{R^{2}} t+\frac{18 \sqrt{C_{2}}}{R} t^{1 / 2}
$$

Otherwise,

$$
\eta F \leq 9+\frac{C_{4}}{R^{2}} t+\frac{18 \sqrt{C_{2}}}{R} t^{1 / 2}(\eta F)
$$

For fix $t$, we can choose $R$ such that $\frac{18 \sqrt{C_{2}}}{R} t^{1 / 2} \leq \frac{1}{2}$, thus

$$
\eta F \leq 18+\frac{C_{4}}{R^{2}} t
$$

and similar argument as before

$$
\begin{equation*}
\sup _{x \in B_{R}}\left(\left|\nabla_{b} \varphi\right|^{2}+3 \varphi_{t}\right)\left(x, T^{\prime}\right) \leq \frac{C_{4}}{R^{2}}+\frac{18}{T^{\prime}} \tag{4.8}
\end{equation*}
$$

Now for any fixed time $t \in(0, \infty)$, by letting $R \rightarrow \infty$ such that $\frac{18 \sqrt{C_{2}}}{R} t^{1 / 2} \rightarrow 0$, one obtains

$$
\frac{\left|\nabla_{b} u\right|^{2}}{u^{2}}+3 \frac{u_{t}}{u} \leq \frac{9+\epsilon}{t}
$$

on $H^{1} \times[0, T)$ for any $\epsilon>0$.
Then, by combining Theorem 4.2 and Proposition 4.1, Theorem 1.4 follows for $n=1$ easily.

Now we will apply the subgradient estimates in Theorem 4.2 and Proposition 4.1 to obtain the following Harnack inequality for positive solutions of the CR heat equation (1.6) on $H^{1} \times[0, T)$.

THEOREM 4.3. If $u(x, t)$ be a positive smooth solution of (1.6)

$$
\left(\Delta_{b}-\frac{\partial}{\partial t}\right) u(x, t)=0
$$

on $H^{1} \times[0, T)$ with

$$
P_{1} u=0
$$

at $t=0$, then for all points $x_{1}, x_{2}$ in $H^{1}$ and times $0<t_{1}<t_{2}<T$, we have the inequality

$$
\frac{t_{1}}{t_{2}} \exp \left(-\frac{d_{c}^{2}\left(x_{1}, x_{2}\right)}{4\left(t_{2}-t_{1}\right)}\right) \leq \frac{u\left(x_{2}, t_{2}\right)}{u\left(x_{1}, t_{1}\right)} \leq\left(\frac{t_{2}}{t_{1}}\right)^{(3+\epsilon)} \exp \left(\frac{3 d_{c}^{2}\left(x_{1}, x_{2}\right)}{4\left(t_{2}-t_{1}\right)}\right)
$$

for any $\epsilon>0$.
Proof. Let $\gamma$ be a horizontal curve with $\gamma\left(t_{1}\right)=x_{1}$ and $\gamma\left(t_{2}\right)=x_{2}$. We define $\eta:\left[t_{1}, t_{2}\right] \rightarrow M \times\left[t_{1}, t_{2}\right]$ by

$$
\eta(t)=(\gamma(t), t)
$$

Clearly $\eta\left(t_{1}\right)=\left(x_{1}, t_{1}\right)$ and $\eta\left(t_{2}\right)=\left(x_{2}, t_{2}\right)$. Let $\varphi=\log u(x, t)$, integrate $\frac{d}{d t} \varphi$ along $\eta$, we get

$$
\begin{aligned}
\varphi\left(x_{2}, t_{2}\right)-\varphi\left(x_{1}, t_{1}\right) & =\int_{t_{1}}^{t_{2}} \frac{d}{d t} \varphi d t \\
& =\int_{t_{1}}^{t_{2}}\left\{\left\langle\dot{\gamma}, \nabla_{b} \varphi\right\rangle+\varphi_{t}\right\} d t
\end{aligned}
$$

Applying Theorem 4.2 to $\varphi_{t}$, this yields

$$
\begin{aligned}
\varphi\left(x_{2}, t_{2}\right)-\varphi\left(x_{1}, t_{1}\right) & \leq \int_{t_{1}}^{t_{2}}\left\{|\dot{\gamma}|\left|\nabla_{b} \varphi\right|+\varphi_{t}\right\} d t \\
& \leq \int_{t_{1}}^{t_{2}}\left\{\frac{3}{4}|\dot{\gamma}|+\frac{3+\epsilon}{t}\right\} d t \\
& =\int_{t_{1}}^{t_{2}} \frac{3}{4}|\dot{\gamma}| d t+(3+\epsilon) \log \left(\frac{t_{2}}{t_{1}}\right)
\end{aligned}
$$

Then the right-hand side inequality in theorem 4.3 follows by taking exponentials of the above inequality. Similarly, we can also get the left-hand side inequality.

As a consequence of Theorem 4.3 and [CY], we have
Corollary 4.4. Let $H(x, y, t)$ be a $L^{2}$-heat kernel of (1.6) on $H^{1} \times[0, T)$. Then for some constant $\delta$ and $0<\epsilon<1$, we have the inequality

$$
H(x, y, t) \leq \frac{C(\epsilon)^{\delta}}{V\left(B_{x}(\sqrt{t})\right)} \exp \left(-\frac{d_{c}^{2}(x, y)}{(4+\epsilon) t}\right) \leq \frac{C(\epsilon)^{\delta}}{t^{2}} \exp \left(-\frac{d_{c}^{2}(x, y)}{(4+\epsilon) t}\right)
$$

with $C(\epsilon) \rightarrow \infty$ as $\epsilon \rightarrow 0$.
Remark 4.1. Here we use the volume $V\left(B_{x}(R)\right) \leq C R^{(2 n+2)}$ in an $(2 n+1)$ dimensional Heisenberg group $H^{n}$ ([DT]). One should compare this result with [BGG].

Then Corollary 1.6 follows easily from Theorem 1.4 and Corollary 4.4.
5. Sub-Laplacian of Carnot-Caratheodory distance on Heisenberg groups $H^{n}$. In this section, we prove the sub-Laplacian comparison $(*)$ as in previous section. We consider the following two vector fields defined on $\mathbf{R}^{3}$ with coordinates $(x, t)=\left(x_{1}, x_{2}, t\right):$

$$
X_{1}=\frac{\partial}{\partial x_{1}}+2 a x_{2} \frac{\partial}{\partial t} \quad \text { and } \quad X_{2}=\frac{\partial}{\partial x_{2}}-2 a x_{1} \frac{\partial}{\partial t}
$$

with $a>0$. It is easy to check that

$$
\left[X_{1}, X_{2}\right]=-4 a \frac{\partial}{\partial t}
$$

Now we consider the following operator

$$
\Delta_{H}=-\frac{1}{2}\left(X_{1}^{2}+X_{2}^{2}\right)
$$

The vector fields $X_{1}, X_{2}$ and $T=\frac{\partial}{\partial t}$ and the operator $\Delta_{H}$ are left-invariant with respect to the "Heisenberg translation": for $(x, t)=\left(x_{1}, x_{2}, t\right)$ and $(y, s)=\left(y_{1}, y_{2}, s\right) \in$ $\mathbf{R}^{3}$,

$$
(x, t) \circ(y, s)=\left(x_{1}+y_{1}, x_{2}+y_{2}, t+s+2 a\left[x_{2} y_{1}-x_{1} y_{2}\right]\right)
$$

Actually, the above multiplicative law defines a group structure on $\mathbf{R}^{3}$ which we call the 1-dimensional Heisenberg group with $(x, t)^{-1}=(-x,-t)$.

REMARK 5.1. By comparing the previous notations, we first put some conventions as followings: for $a=\frac{1}{2}$

$$
Z_{1}=\frac{1}{2}\left(X_{1}-i X_{2}\right) \text { and } Z_{\overline{1}}=\frac{1}{2}\left(X_{1}+i X_{2}\right)
$$

and

$$
J\left(X_{1}\right)=X_{2} \quad \text { and } J\left(X_{2}\right)=-X_{1}
$$

and

$$
\Delta_{b}=-\Delta_{H}
$$

The symbol of $\Delta_{H}$ is

$$
H(x, \xi, \theta)=\frac{1}{2}\left(\xi_{1}+2 a x_{2} \theta\right)^{2}+\frac{1}{2}\left(\xi_{2}-2 a x_{1} \theta\right)^{2}=\frac{1}{2}\left(\zeta_{1}^{2}+\zeta_{2}^{2}\right)
$$

where $\zeta_{1}=\xi_{1}+2 a x_{2} \theta$ and $\zeta_{2}=\xi_{2}-2 a x_{1} \theta$.
In this notation, Hamilton-Jacobi equations for the bicharacteristic curve $\left(x_{1}(s), x_{2}(s), t(s), \xi_{1}(s), \xi_{2}(s), \theta(s)\right)$ take the form:

$$
\begin{align*}
\dot{x}_{1}(s) & =\frac{\partial H}{\partial \xi_{1}}=\xi_{1}+2 a x_{2} \theta=\zeta_{1}(s),  \tag{5.1}\\
\dot{x}_{2}(s) & =\frac{\partial H}{\partial \xi_{2}}=\xi_{2}-2 a x_{1} \theta=\zeta_{2}(s), \\
\dot{t}(s) & =\frac{\partial H}{\partial \theta}=\left(\xi_{1}+2 a x_{2} \theta\right)\left(2 a x_{2}\right)-\left(\xi_{2}-2 a x_{1} \theta\right)\left(2 a x_{1}\right)=2 a\left(\zeta_{1} x_{1}-\zeta_{2} x_{2}\right), \\
\dot{\xi}_{1}(s) & =-\frac{\partial H}{\partial x_{1}}=(2 a \theta)\left(\xi_{2}-2 a x_{1} \theta\right)=(2 a \theta) \zeta_{2}, \\
\dot{\xi}_{2}(s) & =-\frac{\partial H}{\partial x_{2}}=-(2 a \theta)\left(\xi_{1}+2 a x_{2} \theta\right)=-(2 a \theta) \zeta_{1}, \\
\dot{\theta}(s) & =-\frac{\partial H}{\partial t}=0,
\end{align*}
$$

where the dot denotes $\frac{d}{d s}$. We let $s$ run along the ray from 0 to a point $\tau \in \mathbf{C}$. Because of group invariance we need to consider paths relative to the origin and a point $(x, t)=\left(x_{1}, x_{2}, t\right)$ only, and assume boundary conditions

$$
\begin{equation*}
x_{1}(0)=0, \quad x_{2}(0)=0, \quad x_{1}(\tau)=x_{1}, \quad x_{2}(\tau)=x_{2}, \quad t(\tau)=t \tag{5.2}
\end{equation*}
$$

Then it is easy to see that the Hamiltonian,

$$
\frac{1}{2} \dot{x}_{1}^{2}(s)+\frac{1}{2} \dot{x}_{2}^{2}(s)=H(x, \xi, \theta)=H_{0} \equiv \frac{1}{2}\left(\zeta_{1}(0) \zeta_{1}(0)+\zeta_{2}(0) \zeta_{2}(0)\right)
$$

is constant along a given bicharacteristic. The projection of the bicharacteristic curve onto the base is a subRiemannian geodesic connecting the point $(x, t)$ to the origin.

From (5.1), we know that $\theta(s)=\theta(0)=\theta$ and we may take it to be the free parameter. Equations (5.1) imply that

$$
\begin{aligned}
& \dot{\zeta}_{1}=\dot{\xi}_{1}+2 a \theta \dot{x}_{2}=2 a \theta \zeta_{2}+2 a \theta \zeta_{2}=4 a \theta \zeta_{2}, \\
& \dot{\zeta}_{2}=\dot{\xi}_{2}-2 a \theta \dot{x}_{1}=-2 a \theta \zeta_{1}-2 a \theta \zeta_{1}=-4 a \theta \zeta_{1} .
\end{aligned}
$$

Hence,

$$
\begin{aligned}
& \zeta_{1}(s)=\cos (4 a \theta s) \zeta_{1}(0)+\sin (4 a \theta s) \zeta_{2}(0) \\
& \zeta_{2}(s)=-\sin (4 a \theta s) \zeta_{1}(0)+\cos (4 a \theta s) \zeta_{2}(0)
\end{aligned}
$$

Therefore, we may solve for $x(s)$ as a function of $x, \tau$ and $\theta$, and then solve for $t(s)$ as a function of $x, t, \tau$ and $\theta$. Here are the calculations.

$$
\begin{aligned}
x_{1}(s) & =\int_{0}^{s} \zeta_{1}(\rho) d \rho=-\frac{1}{4 a \theta}\left\{\zeta_{2}(s)-\zeta_{2}(0)\right\} \\
& =-\frac{1}{4 a \theta}\left\{-\sin (4 a \theta s) \zeta_{1}(0)+[\cos (4 a \theta s)-1] \zeta_{2}(0)\right\} \\
& =\frac{\sin (2 a \theta s)}{2 a \theta}\left\{\cos (2 a \theta s) \zeta_{1}(0)+\sin (2 a \theta s)\right\}
\end{aligned}
$$

and

$$
\begin{aligned}
x_{2}(s) & =\frac{1}{4 a \theta}\left\{\zeta_{1}(s)-\zeta_{1}(0)\right\} \\
& =\frac{1}{4 a \theta}\left\{[\cos (4 a \theta s)-1] \zeta_{1}(0)+\sin (4 a \theta s) \zeta_{2}(0)\right\} \\
& =\frac{\sin (2 a \theta s)}{2 a \theta}\left\{-\cos (2 a \theta s) \zeta_{1}(0)+\sin (2 a \theta s)\right\}
\end{aligned}
$$

Therefore,

$$
\left[\begin{array}{l}
\zeta_{1}(0) \\
\zeta_{2}(0)
\end{array}\right]=\frac{2 a \theta}{\sin (2 a \theta \tau)}\left[\begin{array}{cc}
\cos (2 a \theta \tau) & -\sin (2 a \theta \tau) \\
\sin (2 a \theta \tau) & \cos (2 a \theta \tau)
\end{array}\right]\left[\begin{array}{c}
x_{1} \\
x_{2}
\end{array}\right]
$$

It follows that

$$
H_{0}=\frac{1}{2}\left(\zeta_{1}(0) \zeta_{1}(0)+\zeta_{2}(0) \zeta_{2}(0)\right)=\frac{(2 a \theta)^{2}}{2 \sin ^{2}(2 a \theta \tau)}\left(x_{1}^{2}+x_{2}^{2}\right)=\frac{(2 a \theta)^{2}}{2 \sin ^{2}(2 a \theta \tau)}\|x\|^{2}
$$

When $\theta=0$, we have $\zeta(s)=\zeta(0), x(s)=\zeta(0) s$ and $t(s)=t(0)$. Substituting these calculations into (5.1), we have

$$
\begin{aligned}
t-t(s) & =2 a \int_{s}^{\tau}\left[\zeta_{1}(\rho) x_{2}(\rho)-\zeta_{2}(\rho) x_{1}(\rho)\right] d \rho \\
& =\frac{1}{2 \theta} \int_{s}^{\tau}[1-\cos (4 a \theta \rho)] d \rho \cdot\left[\zeta_{1}^{2}(0)+\zeta_{2}^{2}(0)\right] \\
& =(\tau-s) \frac{2 a^{2} \theta}{\sin ^{2}(2 a \theta \tau)}\|x\|^{2}-\frac{a}{2} \cdot \frac{\sin (4 a \theta \tau)-\sin (4 a \theta s)}{\sin ^{2}(2 a \theta \tau)}\|x\|^{2}
\end{aligned}
$$

THEOREM 5.1. The solution of equations (5.1) with boundary conditions (5.2) is

$$
\begin{align*}
x_{1}(s) & =\frac{\sin (2 a \theta s)}{\sin (2 a \theta \tau)}\left\{\cos [2 a \theta(s-\tau)] x_{1}+\sin [2 a \theta(s-\tau)] x_{2}\right\} \\
& =\frac{\sin (2 a \theta s)}{\sin (2 a \theta \tau)}\left\{-\sin [2 a \theta(s-\tau)] x_{1}+\cos [2 a \theta(s-\tau)] x_{2}\right\},  \tag{5.3}\\
& =\left[\frac{a}{2} \frac{\sin (4 a \theta \tau)-\sin (4 a \theta s)}{\sin ^{2}(2 a \theta \tau)}-(\tau-s) \frac{2 a^{2} \theta}{\sin ^{2}(2 a \theta \tau)}\right]\left(x_{1}^{2}+x_{2}^{2}\right)-t .
\end{align*}
$$

The value of the Hamiltonian $H$ on this path is

$$
H_{0}=\frac{2 a^{2} \theta^{2}}{\sin ^{2}(2 a \theta \tau)}\left(x_{1}^{2}+x_{2}^{2}\right)
$$

Next (5.3) yields

$$
t-t(0)=a \mu(2 a \theta \tau)\|x\|^{2}
$$

where we set

$$
\mu(z)=\frac{z}{\sin ^{2} z}-\cot z
$$

The action integral associated to the Hamiltonian curve is

$$
S(x, t, \tau ; \theta)=\int_{0}^{\tau}\left\{\sum_{j=1}^{2} \xi_{j}(s) \dot{x}_{j}(s)+\theta \dot{t}(s)-H(x(s), \xi(s), \theta)\right\} d s
$$

$H$ is homogeneous of degree 2 with respect to $\left(\xi_{1}, \xi_{2}, \theta\right)$, so

$$
\begin{equation*}
S=\int_{0}^{\tau}\left\{\sum_{j=1}^{2} \xi_{j} \frac{\partial H}{\partial \xi_{j}}+\theta \frac{\partial H}{\partial \theta}-H\right\} d s=\int_{0}^{\tau}(2 H-H) d s=\tau H_{0} \tag{5.4}
\end{equation*}
$$

From formulas (5.3), we have the following theorem:

Theorem 5.2. The action integral $S(x, t, \tau, \theta)$ is given by

$$
\begin{aligned}
S(x, t, \tau, \theta) & =\frac{\tau(2 a \theta)^{2}}{2 \sin ^{2}(2 a \theta \tau)}\|x\|^{2} \\
& =[t-t(0)] \theta+a \theta \cot (2 a \theta \tau)\left(x_{1}^{2}+x_{2}^{2}\right), \quad \theta \in\left[0, \frac{\pi}{a}\right)
\end{aligned}
$$

It is convenient to fix $\tau, \tau=1$. Then the Hamiltonian paths are determined entirely by the parameter $\theta$. We may take the end points to be $(\mathbf{0}, 0)$ and $(x, t)$. Then $\theta$ must satisfy

$$
t=a \mu(2 a \theta)\left(x_{1}^{2}+x_{2}^{2}\right)=a \mu(2 a \theta)\|x\|^{2}
$$

It can be shown that $\mu$ is a monotone increasing diffeomorphism of the interval $(-\pi, \pi)$ onto R. On each interval $(m \pi,(m+1) \pi), m=1,2, \ldots, \mu$ has a unique critical point $z_{m}$. On this interval $\mu$ decreases strictly from $+\infty$ to $\mu\left(z_{m}\right)$ and then increases strictly from $\mu\left(z_{m}\right)$ to $+\infty$. Now the complete picture of the geodesics is given in the following two theorems.

Theorem 5.3. There are finitely many geodesics that join the origin to $(x, t)$ if and only if $x \neq \mathbf{0}$. These geodesics are parametrized by the solutions $\theta$ of

$$
\begin{equation*}
a \mu(2 a \theta)\|x\|^{2}=|t| \tag{5.5}
\end{equation*}
$$

and their lengths increase strictly with $\theta$. There is exactly one such geodesic if and only if

$$
|t|<a \mu\left(z_{1}\right)\|x\|^{2}
$$

and the number of geodesics increases without bound as $\frac{|t|}{a\|x\|^{2}} \rightarrow \infty$.
The square of the length of the geodesic associated to a solution $\theta$ of (5.5) is

$$
\begin{align*}
2 S(x,|t|, 1, \theta) & =\frac{(2 a \theta)^{2}}{\sin ^{2}(2 a \theta \theta)}\left(x_{1}^{2}+x_{2}^{2}\right) \\
& =\frac{(2 a \theta)^{2}}{\sin ^{2}(2 a \theta)} \frac{\left(x_{1}^{2}+x_{2}^{2}\right)}{\left(x_{1}^{2}+x_{2}^{2}\right)+|t| / a}\left[\frac{|t|}{a}+\left(x_{1}^{2}+x_{2}^{2}\right)\right] \\
& =\frac{(2 a \theta)^{2}}{\sin ^{2}(2 a \theta)} \frac{1}{1+\mu(2 a \theta)}\left[\frac{|t|}{a}+\left(x_{1}^{2}+x_{2}^{2}\right)\right]  \tag{5.6}\\
& =\nu(2 a \theta)\left(\frac{|t|}{a}+\|x\|^{2}\right),
\end{align*}
$$

where $\nu(0)=2$ and otherwise

$$
\nu(z)=\frac{z^{2}}{\sin ^{2} z} \frac{1}{1+\mu(z)}=\frac{z^{2}}{z+\sin ^{2} z-\sin z \cos z}
$$

Consequently, if $2 a \theta \in(m \pi,(m+1) \pi)$ the length $d_{\theta}$ of the geodesic satisfies

$$
\frac{m^{2} \pi^{2}}{(m+1) \pi+2}\left(\frac{|t|}{a}+\|x\|^{2}\right)<\left(d_{\theta}\right)^{2}<\frac{(m+1)^{2} \pi^{2}}{m \pi}\left(\frac{|t|}{a}+\|x\|^{2}\right)
$$

When $x=\mathbf{0}$, we need to find the Hamiltonian paths connecting the origin to $(0, t)$, i.e., $x_{1}(1)=0, x_{2}(1)=0, t(1)=t$. This implies that $\zeta_{1}(1)=\zeta_{1}(0)$ and $\zeta_{2}(1)=\zeta_{2}(0)$. It follows that

$$
\begin{aligned}
& \zeta_{1}(1)=\cos (4 a \theta) \zeta_{1}(0)+\sin (4 a \theta) \zeta_{2}(0)=\zeta_{1}(0) \\
& \zeta_{2}(1)=-\sin (4 a \theta) \zeta_{1}(0)+\cos (4 a \theta) \zeta_{2}(0)=\zeta_{2}(0)
\end{aligned}
$$

This implies that

$$
\sin (4 a \theta)=0, \quad \text { and } \quad \cos (4 a \theta)=1
$$

i.e.,

$$
2 a \theta=m \pi, \quad \text { with } \quad m=1,2,3, \ldots
$$

In this case,

$$
t=\frac{1}{2 \theta}\left(\zeta_{1}^{2}(0)+\zeta_{2}^{2}(0)\right)
$$

therefore, $\theta \neq 0$ and $m \neq 0$ in (5.4). We also know that

$$
d_{m}^{2}=\frac{m \pi|t|}{a}
$$

Summarizing, we have the following theorem.
Theorem 5.4. The geodesics that join the origin to a point ( $0,0, t$ ) have lengths $d_{1}, d_{2}, d_{3}, \ldots$, where

$$
d_{m}^{2}=\frac{m \pi|t|}{a}
$$

Since $x_{1}(1)=x_{2}(1)=0$, we may use $\left(\zeta_{1}(0), \zeta_{2}(0)\right)$ to obtain the geodesics as follows:

$$
\begin{aligned}
x_{1}^{(m)}(s) & =-\frac{1}{2 m \pi}\left\{-\sin (2 m \pi s) \zeta_{1}(0)+[\cos (2 m \pi s)-1] \zeta_{2}(0)\right\} \\
& =\left(\frac{t}{4 a m \pi}\right)^{\frac{1}{2}}\left\{\sin (2 m \pi s) \frac{\zeta_{1}(0)}{\|\zeta(0)\|}+[1-\cos (2 m \pi s)] \frac{\zeta_{2}(0)}{\|\zeta(0)\|}\right\}
\end{aligned}
$$

where $\|\zeta(0)\|=\sqrt{\zeta_{1}^{2}(0)+\zeta_{2}^{2}(0)}$. Similarly, we have

$$
\begin{aligned}
x_{2}^{(m)}(s) & =\frac{1}{2 m \pi}\left\{[\cos (2 m \pi s)-1] \zeta_{1}(0)+\sin (2 m \pi s) \zeta_{2}(0)\right\} \\
& =\left(\frac{t}{4 a m \pi}\right)^{\frac{1}{2}}\left\{[\cos (2 m \pi s)-1] \frac{\zeta_{1}(0)}{\|\zeta(0)\|}+\sin (2 m \pi s) \frac{\zeta_{2}(0)}{\|\zeta(0)\|}\right\},
\end{aligned}
$$

and

$$
t^{(m)}(s)=[2 m \pi s-\sin (2 m \pi s)] \frac{t}{2 m \pi}
$$

This shows that for each fixed $m, m=1,2, \ldots$, the geodesics $\left(x_{1}^{(m)}(s), x_{2}^{(m)}(s), t^{(m)}(s)\right)$ can be parametrized by a unit vector $\zeta(0) /\|\zeta(0)\|$ on the unit circle. These curves lie in a cylinder around the $t$-axis whose radius is $\mathcal{O}(1 / \sqrt{m})$.

A special case of (5.6) is the square of the Carnot-Caratheodory distance $\left[d_{c}(x, t)\right]^{2}$ :

$$
\left[d_{c}(x, t)\right]^{2}=2 S\left(x,|t|, 1 ; \theta_{c}\right)=\left[\frac{2 a \theta_{c}}{\sin \left(2 a \theta_{c}\right)}\right]^{2}\|x\|^{2}=\nu\left(2 a \theta_{c}\right)\left(\frac{|t|}{a}+\|x\|^{2}\right)
$$

where $\theta_{c}$ is the unique solution of $a \mu(2 a \theta)\|x\|^{2}=|t|$ in the interval $[0, \pi / 2 a)$. Introduce a new parameter $\phi=2 a \theta_{c}$. Then the Carnot-Caratheodory distance between the origin and point $\left(x_{1}, x_{2}, t\right)$ can be expressed as

$$
d_{c}(x, t)=\frac{\phi}{\sin \phi}\|x\| \quad \text { with } \quad a \mu(\phi)\|x\|^{2}=|t| \quad \text { and } \quad \phi \in[0, \pi)
$$

We will compute $\Delta_{H} d_{c}(x, t)$. In polar coordinates,

$$
-\Delta_{H}=\frac{1}{2}\left(\frac{\partial^{2}}{\partial r^{2}}+\frac{1}{r} \frac{\partial^{2}}{\partial r \partial \theta}+\frac{1}{r^{2}} \frac{\partial^{2}}{\partial \theta^{2}}\right)+2 a \frac{\partial^{2}}{\partial t \partial \theta}+2 a^{2} r^{2} \frac{\partial^{2}}{\partial t^{2}}
$$

Since $d_{c}(x, t)$ depends only on $r=\|x\|=\sqrt{x_{1}^{2}+x_{2}^{2}}$, we have

$$
-\Delta_{H} d_{c}(x, t)=\left(\frac{1}{2} \frac{\partial^{2}}{\partial r^{2}}+2 a^{2} r^{2} \frac{\partial^{2}}{\partial t^{2}}\right) d_{c}(r, t)
$$

Introduce a new variable $u=|t| / a r^{2}$, then

$$
d_{c}(r, t):=f_{c}(r, u)=\frac{\phi}{\sin \phi} r \quad \text { where } u \text { satisfies } \quad u=\mu(\phi)=\frac{\phi-\sin \phi \cos \phi}{\sin ^{2} \phi}
$$

Hence

$$
-\Delta_{H} d_{c}(r, t)=\left(\frac{1}{2} \frac{\partial^{2}}{\partial r^{2}}+\frac{2}{r^{2}} \frac{\partial^{2}}{\partial u^{2}}\right) f_{c}(r, u)=\frac{2}{r} \frac{\partial^{2}}{\partial u^{2}}\left(\frac{\phi}{\sin \phi}\right)
$$

where $u$ is given by $u=\mu(\phi)$. Let $g(\phi)=\frac{\phi}{\sin \phi}$. Then

$$
\frac{d g}{d u}=\frac{d g}{d \phi} \cdot \frac{d \phi}{d u} \quad \text { and } \quad \frac{d^{2} g}{d u^{2}}=\frac{d^{2} g}{d \phi^{2}} \cdot\left(\frac{d \phi}{d u}\right)^{2}+\frac{d g}{d \phi} \cdot \frac{d^{2} \phi}{d u^{2}}
$$

We next compute $\frac{d g}{d \phi}, \frac{d^{2} g}{d \phi^{2}}, \frac{d \phi}{d u}$ and $\frac{d^{2} \phi}{d u^{2}}$.

$$
\frac{d g}{d \phi}=\frac{\sin \phi-\phi \cos \phi}{\sin ^{2} \phi} \quad \text { and } \quad \frac{d^{2} g}{d \phi^{2}}=\frac{\phi\left(1+\cos ^{2} \phi\right)-2 \sin \phi \cos \phi}{\sin ^{3} \phi}
$$

Next $u=\mu(\phi)$ implies

$$
1=\mu^{\prime}(\phi) \frac{d \phi}{d u}, \quad \frac{d \phi}{d u}=\frac{1}{\mu^{\prime}(\phi)} \quad \text { and } \quad \frac{d^{2} \phi}{d u^{2}}=-\frac{\mu^{\prime \prime}(\phi)}{\left(\mu^{\prime 3}\right)}
$$

We now compute $\mu^{\prime}(\phi)$ and $\mu^{\prime \prime}(\phi)$ from $\mu(\phi)=\phi \csc ^{2} \phi-\cot \phi$.

$$
\mu^{\prime 2} \phi-2 \phi \csc ^{2} \phi \cot \phi+\csc ^{2} \phi=2 \csc ^{2} \phi(1-\phi \cot \phi)
$$

and

$$
\begin{aligned}
& \mu^{\prime \prime 2} \phi \cot \phi(1-\phi \cot \phi)+2 \csc ^{2} \phi\left(\phi \csc ^{2} \phi-\cot \phi\right) \\
& =2 \csc ^{2} \phi\left[\phi\left(3 \cot ^{2} \phi+1\right)-3 \cot \phi\right]
\end{aligned}
$$

We finally compute $-\Delta_{h} f_{c}(r, u)=\frac{2}{r} \frac{d^{2}}{d u^{2}} g(\phi)$.

$$
\begin{aligned}
-\Delta_{H} f_{c}(r, u) & =\frac{2}{r}\left[\frac{d^{2} g}{d \phi^{2}} \cdot\left(\frac{d \phi}{d u}\right)^{2}+\frac{d g}{d \phi} \cdot \frac{d^{2} \phi}{d u^{2}}\right] \\
& =\frac{2}{r}\left[\frac{d^{2} g}{d \phi^{2}} \cdot \frac{1}{\left(\mu^{\prime 2}\right)}-\frac{d g}{d \phi} \frac{\mu^{\prime \prime}(\phi)}{\left(\mu^{\prime 3}\right)}\right] \\
& =\frac{2}{r\left(\mu^{\prime 2}\right)}\left[\frac{d^{2} g}{d \phi^{2}}-\frac{d g}{d \phi} \cdot \frac{\mu^{\prime \prime}(\phi)}{\mu^{\prime}(\phi)}\right]
\end{aligned}
$$

We shall compute the term in [...] in term of $\phi$ first.

$$
\begin{aligned}
& \frac{d^{2} g}{d \phi^{2}}-\frac{d g}{d \phi} \cdot \frac{\mu^{\prime \prime}(\phi)}{\mu^{\prime}(\phi)} \\
= & \frac{\phi\left(1+\cos ^{2} \phi\right)-2 \sin \phi \cos \phi}{\sin ^{3} \phi}-\frac{\sin \phi-\phi \cos \phi}{\sin ^{2} \phi} \cdot \frac{2 \csc ^{2} \phi\left[\phi\left(3 \cot ^{2} \phi+1\right)-3 \cot \phi\right]}{2 \csc ^{2} \phi(1-\phi \cot \phi)} \\
= & \frac{\phi\left(1+\cos ^{2} \phi\right)-2 \sin \phi \cos \phi}{\sin ^{3} \phi}-\frac{\phi\left(3 \cot ^{2} \phi+1\right)-3 \cot \phi}{\sin \phi} \\
= & \frac{\phi\left(1+\cos ^{2} \phi\right)-2 \sin \phi \cos \phi-\phi\left(3 \cos ^{2} \phi+\sin ^{2} \phi\right)+3 \cos \phi \sin \phi}{\sin ^{3} \phi} \\
= & \frac{\sin \phi \cos \phi-\phi \cos ^{2} \phi}{\sin ^{3} \phi} .
\end{aligned}
$$

Hence we have

$$
\begin{aligned}
-\Delta_{H} f_{c}(r, u) & =\frac{2}{r\left(\mu^{\prime 2}\right.}\left[\frac{d^{2} g}{d \phi^{2}}-\frac{d g}{d \phi} \cdot \frac{\mu^{\prime \prime}(\phi)}{\mu^{\prime}(\phi)}\right] \\
& =\frac{\sin \phi \cos \phi-\phi \cos ^{2} \phi}{\sin ^{3} \phi} \cdot \frac{1}{2 r \csc ^{4} \phi(1-\phi \cot \phi)^{2}} \\
& =\frac{(1-\phi \cot \phi) \sin \phi \cos \phi}{2 r \csc \phi(1-\phi \cot \phi)^{2}} \\
& =\frac{\sin ^{2} \phi \cos \phi}{2 r(1-\phi \cot \phi)}
\end{aligned}
$$

Since $d_{c}=\frac{\phi}{\sin \phi} r$,

$$
\begin{equation*}
-\Delta_{H} d_{c}=\frac{1}{2 d_{c}} \cdot \frac{\phi \sin ^{2} \phi \cos \phi}{\sin \phi-\phi \cos \phi} \tag{5.7}
\end{equation*}
$$

We next study the function $F(\phi)=\frac{\phi \sin ^{2} \phi \cos \phi}{2(\sin \phi-\phi \cos \phi)}$ where $\phi$ is given by

$$
a r^{2} \mu(\phi)=t \quad \text { with } \quad \mu(\phi)=\frac{\phi-\sin \phi \cos \phi}{\sin ^{2} \phi}
$$

The function $F(\phi)$ is smooth on the interval $[0, \pi]$, decreasing from $\left[0, \phi_{m}\right]$ and increasing from $\left[\phi_{m}, \pi\right] . \phi_{m}$ is the unique critical point of $F(\phi)$ inside the interval $(0, \pi)$. $F(0)=3, F(\pi / 2)=F(\pi)=0$.

As $r \rightarrow 0$ with $t>0$ fixed, $\phi \rightarrow \pi^{-}$and the equation $a r^{2} \mu(\phi)=t$ implies

$$
\frac{a r^{2}}{t} \frac{\phi-\sin \phi \cos \phi}{\sin ^{2} \phi}=1
$$

This shows that

$$
\phi \rightarrow \pi \quad \text { and } \quad \sin \phi \sim\left(\frac{a \pi}{t}\right)^{1 / 2} r \quad \text { as } \quad r \rightarrow 0
$$

This implies (5.7) makes sense when $r=0$. This corresponds to $\phi=\pi$.
All these imply

$$
\Delta_{b} d_{c}=-\Delta_{H} d_{c} \leq \frac{3}{d_{c}}
$$

and then the Sub-Laplacian comparison $(*)$ follows.
We now turn to the study of the $(2 n+1)$-dimensional Heisenberg group $H^{n}$. The manifold is $\mathbf{R}^{2 n} \times \mathbf{R}$ and the group law is given by

$$
(\mathbf{x}, t) \circ(\mathbf{y}, s)=\left(\mathbf{x}+\mathbf{y}, t+s+2 \sum_{j=1}^{n} a_{j}\left[x_{2 j} y_{2 j-1}-x_{2 j-1} y_{2 j}\right]\right)
$$

for $a_{1}, a_{2}, \cdots, a_{n}$ are positive constants and numbered so that

$$
0<a_{1} \leq a_{2} \leq \cdots \leq a_{n}
$$

The vector fields

$$
\begin{aligned}
X_{2 j-1} & =\frac{\partial}{\partial x_{2 j-1}}+2 a_{j} x_{2 j} \frac{\partial}{\partial t} \\
X_{2 j} & =\frac{\partial}{\partial x_{2 j}}-2 a_{j} x_{2 j-1} \frac{\partial}{\partial t} \\
T & =\frac{\partial}{\partial t}
\end{aligned}
$$

are left-invariant and generate the Lie algebra. The associated Heisenberg subLaplacian is

$$
\Delta_{H}=-\frac{1}{2} \sum_{j=1}^{2 n} X_{j}^{2}
$$

The symbol of $\Delta_{H}$ is

$$
H(\mathbf{x}, \xi, \theta)=\frac{1}{2} \sum_{j=1}^{n}\left[\left(\xi_{2 j-1}+2 a_{j} x_{2 j} \theta\right)^{2}+\left(\xi_{2 j}-2 a_{j} x_{2 j-1} \theta\right)^{2}=\frac{1}{2}\left(\zeta_{1}^{2}+\zeta_{2}^{2}\right)\right.
$$

We can find the bicharacteristic curve connecting the point $(\mathbf{x}, t)$ to the origin by solving the associated Hamilton's equations which take essentially the same form as (5.1). We will just list the formulae that we need and refer to [BGG] for details. The value of the Hamiltonian $H$ on the bicharacteristic curve is the constant:

$$
H_{0}=\sum_{j=1}^{n} \frac{2 a_{j}^{2} \theta^{2}}{\sin ^{2}\left(2 a_{j} \tau \theta\right)} r_{j}^{2}
$$

with $r_{j}^{2}=x_{2 j-1}^{2}+x_{2 j}^{2}$. The analogue of (5.5) is follows:

$$
t=\sum_{j=1}^{n} a_{j} \mu\left(2 a_{j} \tau \theta\right) r_{j}^{2}
$$

The action integral $S(\mathbf{x}, t, \tau ; \theta)$ takes a similar form:

$$
S(\mathbf{x}, t, \tau ; \theta)=\sum_{j=1}^{n} \frac{4 \tau a_{j}^{2} \theta^{2}}{\sin ^{2}\left(2 a_{j} \tau \theta\right)} r_{j}^{2}=t \theta+\sum_{j=1}^{n} a_{j} \theta \cot \left(2 a_{j} \tau \theta\right) r_{j}^{2}
$$

When we study the classical action and Carnot-Caratheodory distance, we set $\tau=1$. In the case of $\mathbf{x} \neq 0$, there are finitely many geodesics from the origin to $(\mathbf{x}, t)$. The geodesics are indexed by the solutions of

$$
\begin{equation*}
|t|=\sum_{j=1}^{n} a_{j} \mu\left(2 a_{j} \theta\right) r_{j}^{2} \tag{5.8}
\end{equation*}
$$

and their lengths increase with $\theta$. The Carnot-Caratheodory distance from the origin to $(\mathbf{x}, t)$ is

$$
d^{2}(\mathbf{x}, t)=2 S\left(\mathbf{x},|t|, 1 ; \theta_{c}\right)
$$

where $\theta_{c}$ is the unique solution of (5.8) in the interval $\left[0, \pi / 2 a_{n}\right)$.
In the isotropic case $a_{1}=a_{2}=\cdots=a_{n}$, the results of the previous computations for $n=1$ carry over with no change.
6. Subgradient estimate on higher dimensional pseudohermitian manifolds. Let $(M, J, \theta)$ be a closed pseudohermitian $(2 n+1)$-manifold for $n \geq 2$. In this section, we derive the CR version of parabolic Li-Yau gradient estimate for the positive solution $u(x, t)$ of $(1.6)$ on $M \times[0, \infty)$ for $n \geq 2$.

First, we derive the following inequalities which we need in the proof of Proposition 1.1.

Lemma 6.1. Let $(M, J, \theta)$ be a closed pseudohermitian $(2 n+1)$-manifold. Let $f$ be a smooth real-valued function on M. Then

$$
\left|\left(\nabla^{H}\right)^{2} f\right|^{2} \geq 2 \sum_{\alpha, \beta=1}^{n}\left|f_{\alpha \beta}\right|^{2}+2 \sum_{\substack{\alpha, \beta=1 \\ \alpha \neq \beta}}^{n}\left|f_{\alpha \bar{\beta}}\right|^{2}+\frac{1}{2} \sum_{\alpha=1}^{n}\left|f_{\alpha \bar{\alpha}}+f_{\bar{\alpha} \alpha}\right|^{2}
$$

Proof. Since

$$
\begin{aligned}
\left|\left(\nabla^{H}\right)^{2} f\right|^{2} & =2 \sum_{\alpha, \beta=1}^{n}\left(f_{\alpha \beta} f_{\bar{\alpha} \bar{\beta}}+f_{\alpha \bar{\beta}} f_{\bar{\alpha} \beta}\right) \\
& =2 \sum_{\alpha, \beta=1}^{n}\left(\left|f_{\alpha \beta}\right|^{2}+\left|f_{\alpha \bar{\beta}}\right|^{2}\right) \\
& =2\left(\sum_{\alpha, \beta=1}^{n}\left|f_{\alpha \beta}\right|^{2}+\sum_{\substack{\alpha, \beta=1 \\
\alpha \neq \beta}}^{n}\left|f_{\alpha \bar{\beta}}\right|^{2}+\sum_{\alpha=1}^{n}\left|f_{\alpha \bar{\alpha}}\right|^{2}\right)
\end{aligned}
$$

and

$$
\begin{aligned}
\sum_{\alpha=1}^{n}\left|f_{\alpha \bar{\alpha}}\right|^{2} & =\frac{1}{4} \sum_{\alpha=1}^{n}\left(\left|f_{\alpha \bar{\alpha}}+f_{\bar{\alpha} \alpha}\right|^{2}+f_{0}^{2}\right) \\
& =\frac{1}{4} \sum_{\alpha=1}^{n}\left|f_{\alpha \bar{\alpha}}+f_{\bar{\alpha} \alpha}\right|^{2}+\frac{n}{4} f_{0}^{2}
\end{aligned}
$$

It follows that

$$
\begin{aligned}
\left|\left(\nabla^{H}\right)^{2} f\right|^{2} & =2\left(\sum_{\alpha, \beta=1}^{n}\left|f_{\alpha \beta}\right|^{2}+\sum_{\alpha, \beta=1}^{n}\left|f_{\alpha \bar{\beta}}\right|^{2}\right)+\frac{1}{2} \sum_{\alpha=1}^{n}\left|f_{\alpha \bar{\alpha}}+f_{\bar{\alpha} \alpha}\right|^{2}+\frac{n}{2} f_{0}^{2} \\
& \geq 2\left(\sum_{\alpha, \beta=1}^{n}\left|f_{\alpha \beta}\right|^{2}+\sum_{\substack{\alpha, \beta=1 \\
\alpha \neq \beta}}^{n}\left|f_{\alpha \bar{\beta}}\right|^{2}\right)+\frac{1}{2} \sum_{\alpha=1}^{n}\left|f_{\alpha \bar{\alpha}}+f_{\bar{\alpha} \alpha}\right|^{2} .
\end{aligned}
$$

Lemma 6.2. Let $(M, J, \theta)$ be a closed pseudohermitian $(2 n+1)$-manifold for $n \geq 2$. Let $f$ be a smooth real-valued function on $M$. Then

$$
\begin{aligned}
\left.\left.\left\langle\nabla_{b} f, \nabla_{b}\right| \nabla_{b} f\right|^{2}\right\rangle \leq & (n+2) \sum_{\alpha, \beta=1}^{n}\left|f_{\alpha \beta}\right|^{2}+(n+2) \sum_{\substack{\alpha, \beta=1 \\
\alpha \neq \beta}}^{n}\left|f_{\alpha \bar{\beta}}\right|^{2} \\
& +\left(\Delta_{b} f+\left|\nabla_{b} f\right|^{2}\right)\left|\nabla_{b} f\right|^{2}+\frac{(n+2)(n-1)}{4(n+1)} \sum_{\alpha=1}^{n}\left|f_{\alpha \bar{\alpha}}+f_{\bar{\alpha} \alpha}\right|^{2} .
\end{aligned}
$$

Proof. We first derive

$$
\begin{aligned}
& \left.\left.\left\langle\nabla_{b} f, \nabla_{b}\right| \nabla_{b} f\right|^{2}\right\rangle \\
= & 4 \sum_{\alpha, \beta=1}^{n} \operatorname{Re}\left(f_{\alpha \beta} f_{\bar{\alpha}} f_{\bar{\beta}}+f_{\alpha \bar{\beta}} f_{\bar{\alpha}} f_{\beta}\right) \\
= & 4 \operatorname{Re}\left(\sum_{\alpha, \beta=1}^{n} f_{\alpha \beta} f_{\bar{\alpha}} f_{\bar{\beta}}+\sum_{\substack{\alpha, \beta=1 \\
\alpha \neq \beta}}^{n} f_{\alpha \bar{\beta}} f_{\bar{\alpha}} f_{\beta}\right)+2 \sum_{\alpha=1}^{n}\left(f_{\alpha \bar{\alpha}}+f_{\bar{\alpha} \alpha}\right)\left|f_{\alpha}\right|^{2} \\
\leq & (n+2)\left(\sum_{\alpha, \beta=1}^{n}\left|f_{\alpha \beta}\right|^{2}+\sum_{\substack{\alpha, \beta=1 \\
\alpha \neq \beta}}^{n}\left|f_{\alpha \bar{\beta}}\right|^{2}\right)+\frac{4}{n+2} \sum_{\alpha, \beta=1}^{n}\left|f_{\alpha}\right|^{2}\left|f_{\beta}\right|^{2} \\
& +\frac{4}{n+2} \sum_{\substack{\alpha, \beta=1 \\
\alpha \neq \beta}}^{n}\left|f_{\alpha}\right|^{2}\left|f_{\beta}\right|^{2}+2 \sum_{\alpha=1}^{n}\left(f_{\alpha \bar{\alpha}}+f_{\bar{\alpha} \alpha}\right)\left|f_{\alpha}\right|^{2} \\
= & (n+2)\left(\sum_{\alpha, \beta=1}^{n}\left|f_{\alpha \beta}\right|^{2}+\sum_{\substack{\alpha, \beta=1 \\
\alpha \neq \beta}}^{n}\left|f_{\alpha \bar{\beta}}\right|^{2}\right)+\frac{1}{n+2}\left|\nabla_{b} f\right|^{4} \\
& +\frac{4}{n+2} \sum_{\substack{\alpha, \beta=1 \\
\alpha \neq \beta}}^{n}\left|f_{\alpha}\right|^{2}\left|f_{\beta}\right|^{2}+2 \sum_{\alpha=1}^{n}\left(f_{\alpha \bar{\alpha}}+f_{\bar{\alpha} \alpha}\right)\left|f_{\alpha}\right|^{2} .
\end{aligned}
$$

Here we used the identity $\sum_{\alpha, \beta=1}^{n}\left|f_{\alpha}\right|^{2}\left|f_{\beta}\right|^{2}=\left(\sum_{\alpha=1}^{n}\left|f_{\alpha}\right|^{2}\right)^{2}=\frac{1}{4}\left|\nabla_{b} f\right|^{4}$.
Now we compute the last term in the above inequality.

$$
\begin{aligned}
& \sum_{\alpha=1}^{n}\left(f_{\alpha \bar{\alpha}}+f_{\bar{\alpha} \alpha}\right)\left|f_{\alpha}\right|^{2} \\
= & {\left[\sum_{\alpha=1}^{n}\left(f_{\alpha \bar{\alpha}}+f_{\bar{\alpha} \alpha}\right)\right]\left(\sum_{\beta=1}^{n}\left|f_{\beta}\right|^{2}\right) } \\
& -\sum_{\alpha=1}^{n}\left(f_{\alpha \bar{\alpha}}+f_{\bar{\alpha} \alpha}\right)\left(\sum_{\substack{\beta=1 \\
\beta \neq \alpha}}^{n}\left|f_{\beta}\right|^{2}\right) \\
\leq & \frac{1}{2} \Delta_{b} f\left|\nabla_{b} f\right|^{2}+\sum_{\alpha=1}^{n}\left|f_{\alpha \bar{\alpha}}+f_{\bar{\alpha} \alpha}\right|\left(\sum_{\substack{\beta=1 \\
\beta \neq \alpha}}^{n}\left|f_{\beta}\right|^{2}\right) \\
\leq & \frac{1}{2} \Delta_{b} f\left|\nabla_{b} f\right|^{2}+\frac{(n-1)(n+2)}{8(n+1)} \sum_{\alpha=1}^{n}\left|f_{\alpha \bar{\alpha}}+f_{\bar{\alpha} \alpha}\right|^{2} \\
& +\frac{2(n+1)}{(n-1)(n+2)} \sum_{\substack{\alpha=1}}^{n}\left(\sum_{\substack{\beta=1 \\
\beta \neq \alpha}}^{n}\left|f_{\beta}\right|^{2}\right)^{2} .
\end{aligned}
$$

Substituting the above inequality into (6.1), one obtains

$$
\begin{aligned}
& \left.\left.\left\langle\nabla_{b} f, \nabla_{b}\right| \nabla_{b} f\right|^{2}\right\rangle \\
\leq & (n+2)\left(\sum_{\alpha, \beta=1}^{n}\left|f_{\alpha \beta}\right|^{2}+\sum_{\substack{\alpha, \beta=1 \\
\alpha \neq \beta}}^{n}\left|f_{\alpha \bar{\beta}}\right|^{2}\right)+\Delta_{b} f\left|\nabla_{b} f\right|^{2} \\
& +\frac{(n-1)(n+2)}{4(n+1)} \sum_{\alpha=1}^{n}\left|f_{\alpha \bar{\alpha}}+f_{\bar{\alpha} \alpha}\right|^{2}+\frac{1}{n+2}\left|\nabla_{b} f\right|^{4} \\
& +\frac{4(n+1)}{(n+2)(n-1)} \sum_{\alpha=1}^{n}\left(\sum_{\substack{\beta=1 \\
\beta \neq \alpha}}^{n}\left|f_{\beta}\right|^{2}\right)^{2}+\frac{4}{n+2} \sum_{\substack{\alpha, \beta=1 \\
\alpha \neq \beta}}^{n}\left|f_{\alpha}\right|^{2}\left|f_{\beta}\right|^{2} \\
\leq & (n+2)\left(\sum_{\alpha, \beta=1}^{n}\left|f_{\alpha \beta}\right|^{2}+\sum_{\substack{\alpha, \beta=1 \\
\alpha \neq \beta}}^{n}\left|f_{\alpha \bar{\beta}}\right|^{2}\right)+\Delta_{b} f\left|\nabla_{b} f\right|^{2} \\
& +\frac{(n+2)(n-1)}{4(n+1)} \sum_{\alpha=1}^{n}\left|f_{\alpha \bar{\alpha}}+f_{\bar{\alpha} \alpha}\right|^{2}+\frac{1}{n+2}\left|\nabla_{b} f\right|^{4} \\
& +\frac{4(n+1)}{(n+2)(n-1)}\left(\sum_{\alpha=1}^{n}\left(\sum_{\substack{\beta=1 \\
\beta \neq \alpha}}^{n}\left|f_{\beta}\right|^{2}\right)^{2}+\sum_{\substack{\alpha, \beta=1 \\
\alpha \neq \beta}}^{n}\left|f_{\alpha}\right|^{2}\left|f_{\beta}\right|^{2}\right) \\
= & (n+2)\left(\sum_{\alpha, \beta=1}^{n}\left|f_{\alpha \beta}\right|^{2}+\sum_{\substack{\alpha, \beta=1 \\
\alpha \neq \beta}}^{n}\left|f_{\alpha \bar{\beta}}\right|^{2}\right)+\Delta_{b} f\left|\nabla_{b} f\right|^{2} \\
& +\frac{(n+2)(n-1)}{4(n+1)} \sum_{\alpha=1}^{n}\left|f_{\alpha \bar{\alpha}}+f_{\bar{\alpha} \alpha}\right|^{2}+\left|\nabla_{b} f\right|^{4} .
\end{aligned}
$$

Here we have used the identity

$$
\sum_{\alpha=1}^{n}\left(\sum_{\substack{\beta=1 \\ \beta \neq \alpha}}^{n}\left|f_{\beta}\right|^{2}\right)^{2}+\sum_{\substack{\alpha, \beta=1 \\ \alpha \neq \beta}}^{n}\left|f_{\alpha}\right|^{2}\left|f_{\beta}\right|^{2}=(n-1)\left(\sum_{\alpha=1}^{n}\left|f_{\alpha}\right|^{2}\right)^{2}=\frac{n-1}{4}\left|\nabla_{b} f\right|^{4}
$$

This completes the proof of the Lemma. $\square$
Now we can derive the following Proposition 1.1 which is exact form of Lemma 3.3 for $n \geq 2$.

Proof of Proposition 1.1. First differentiating (1.7) w.r.t. the $t$-variable, we have

$$
\begin{align*}
G_{t} & =\frac{1}{t} G+t\left[\left|\nabla_{b} \varphi\right|^{2}+\left(1+\frac{2}{n}\right) \varphi_{t}\right]_{t} \\
& =\frac{1}{t} G+t\left[2\left(1+\frac{1}{n}\right)\left|\nabla_{b} \varphi\right|^{2}+\left(1+\frac{2}{n}\right) \Delta_{b} \varphi\right]_{t}  \tag{6.2}\\
& =\frac{1}{t} G+t\left[4\left(1+\frac{1}{n}\right)\left\langle\nabla_{b} \varphi, \nabla_{b} \varphi_{t}\right\rangle+\left(1+\frac{2}{n}\right) \Delta_{b} \varphi_{t}\right]
\end{align*}
$$

By using the CR version of Bochner formula (2.1) and Lemma 3.2, one obtains

$$
\begin{align*}
\Delta_{b} G= & t\left(\Delta_{b}\left|\nabla_{b} \varphi\right|^{2}+\left(1+\frac{2}{n}\right) \Delta_{b} \varphi_{t}\right) \\
= & t\left[2\left|\left(\nabla^{H}\right)^{2} \varphi\right|^{2}+2\left(1+\frac{2}{n}\right)\left\langle\nabla_{b} \varphi, \nabla_{b} \Delta_{b} \varphi\right\rangle\right. \\
& +2[2 \operatorname{Ric}-(n+2) \text { Tor }]\left(\left(\nabla_{b} \varphi\right)_{\mathbf{C}},\left(\nabla_{b} \varphi\right)_{\mathbf{C}}\right) \\
& \left.-\frac{8}{n}\left\langle P \varphi+\bar{P} \varphi, d_{b} \varphi\right\rangle_{L_{\theta}^{*}}+\left(1+\frac{2}{n}\right) \Delta_{b} \varphi_{t}\right] \\
\geq & t\left[2\left|\left(\nabla^{H}\right)^{2} \varphi\right|^{2}+2\left(1+\frac{2}{n}\right)\left\langle\nabla_{b} \varphi, \nabla_{b} \Delta_{b} \varphi\right\rangle-l_{0}\left|\nabla_{b} \varphi\right|^{2}\right.  \tag{6.3}\\
& \left.-\frac{8}{n}\left\langle P \varphi+\bar{P} \varphi, d_{b} \varphi\right\rangle_{L_{\theta}^{*}}+\left(1+\frac{2}{n}\right) \Delta_{b} \varphi_{t}\right] \\
= & t\left[2\left|\left(\nabla^{H}\right)^{2} \varphi\right|^{2}+2\left(1+\frac{2}{n}\right)\left\langle\nabla_{b} \varphi, \nabla_{b} \Delta_{b} \varphi\right\rangle-l_{0}\left|\nabla_{b} \varphi\right|^{2}\right. \\
& -\frac{8}{n} u^{-2}\left\langle P u+\bar{P} u, d_{b} u\right\rangle_{L_{\theta}^{*}}+\frac{4}{n} \varphi_{t}\left|\nabla_{b} \varphi\right|^{2} \\
& \left.\left.+\left.\frac{4}{n}\left\langle\nabla_{b} \varphi, \nabla_{b}\right| \nabla_{b} \varphi\right|^{2}\right\rangle+\left(1+\frac{2}{n}\right) \Delta_{b} \varphi_{t}\right] .
\end{align*}
$$

Here we have used the inequalities

$$
[2 \operatorname{Ric}-(n+2) \operatorname{Tor}]\left(\left(\nabla_{b} \varphi\right)_{C},\left(\nabla_{b} \varphi\right)_{C}\right) \geq-l_{0}\left|\left(\nabla_{b} \varphi\right)_{C}\right|^{2}=-\frac{l_{0}}{2}\left|\nabla_{b} \varphi\right|^{2}
$$

and

$$
\varphi_{t}=\frac{u_{t}}{u}=\frac{\Delta_{b} u}{u}
$$

Applying the formula

$$
\begin{equation*}
\Delta_{b} \varphi=\varphi_{t}-\left|\nabla_{b} \varphi\right|^{2}=\frac{n}{(n+2) t} G-\frac{2(n+1)}{n+2}\left|\nabla_{b} \varphi\right|^{2} \tag{6.4}
\end{equation*}
$$

and combining (6.2), (6.3), we conclude

$$
\begin{aligned}
& \left(\Delta_{b}-\frac{\partial}{\partial t}\right) G \\
\geq & -\frac{1}{t} G+t\left[2\left|\left(\nabla^{H}\right)^{2} \varphi\right|^{2}+2\left(1+\frac{2}{n}\right)\left\langle\nabla_{b} \varphi, \nabla_{b} \Delta_{b} \varphi\right\rangle+\left.\frac{4}{n}\left\langle\nabla_{b} \varphi, \nabla_{b}\right| \nabla_{b} \varphi\right|^{2}\right\rangle \\
& \left.-4\left(1+\frac{1}{n}\right)\left\langle\nabla_{b} \varphi, \nabla_{b} \varphi_{t}\right\rangle-l_{0}\left|\nabla_{b} \varphi\right|^{2}+\frac{4}{n} \varphi_{t}\left|\nabla_{b} \varphi\right|^{2}-\frac{8}{n} u^{-2}\left\langle P u+\bar{P} u, d_{b} u\right\rangle_{L_{\theta}^{*}}\right] \\
= & -\frac{1}{t} G-\frac{2 n}{(n+2)}\left\langle\nabla_{b} \varphi, \nabla_{b} G\right\rangle+t\left[2\left|\left(\nabla^{H}\right)^{2} \varphi\right|^{2}-\left.\frac{4}{n+2}\left\langle\nabla_{b} \varphi, \nabla_{b}\right| \nabla_{b} \varphi\right|^{2}\right\rangle \\
& \left.-l_{0}\left|\nabla_{b} \varphi\right|^{2}+\frac{4}{n} \varphi_{t}\left|\nabla_{b} \varphi\right|^{2}-\frac{8}{n} u^{-2}\left\langle P u+\bar{P} u, d_{b} u\right\rangle_{L_{\theta}^{*}}\right] .
\end{aligned}
$$

Now, by Lemma 6.1, Lemma 6.2, Cauchy-Schwarz inequality and applying the formula (6.4), we final have

$$
\begin{aligned}
& \left(\Delta_{b}-\frac{\partial}{\partial t}\right) G \\
\geq & -\frac{2 n}{(n+2)}\left\langle\nabla_{b} \varphi, \nabla_{b} G\right\rangle+t\left[\frac{2}{n+1} \sum_{\alpha=1}^{n}\left|\varphi_{\alpha \bar{\alpha}}+\varphi_{\bar{\alpha} \alpha}\right|^{2}+\frac{8}{n(n+2)} \varphi_{t}\left|\nabla_{b} \varphi\right|^{2}\right. \\
& \left.-l_{0}\left|\nabla_{b} \varphi\right|^{2}-\frac{8}{n} u^{-2}\left\langle P u+\bar{P} u, d_{b} u\right\rangle_{L_{\theta}^{*}}\right]-\frac{1}{t} G \\
\geq & -\frac{2 n}{(n+2)}\left\langle\nabla_{b} \varphi, \nabla_{b} G\right\rangle+t\left[\frac{2}{n(n+1)}\left(\Delta_{b} \varphi\right)^{2}+\frac{8}{n(n+2)} \varphi_{t}\left|\nabla_{b} \varphi\right|^{2}\right. \\
& \left.-l_{0}\left|\nabla_{b} \varphi\right|^{2}-\frac{8}{n} u^{-2}\left\langle P u+\bar{P} u, d_{b} u\right\rangle_{L_{\theta}^{*}}\right]-\frac{1}{t} G \\
= & -\frac{2 n}{(n+2)}\left\langle\nabla_{b} \varphi, \nabla_{b} G\right\rangle+t\left[\frac{2 n}{(n+1)(n+2)^{2} t^{2}} G^{2}+\frac{8}{n(n+2)^{2}}\left|\nabla_{b} \varphi\right|^{4}\right. \\
& \left.-l_{0}\left|\nabla_{b} \varphi\right|^{2}-\frac{8}{n} u^{-2}\left\langle P u+\bar{P} u, d_{b} u\right\rangle_{L_{\theta}^{*}}\right]-\frac{1}{t} G .
\end{aligned}
$$

This completes the proof of Proposition 1.1.
Following the same proof as in Theorem 3.4. We have the following result.
ThEOREM 6.3. Let $(M, J, \theta)$ be a closed pseudohermitian $(2 n+1)$-manifold of zero torsion and nonnegative pseudohermitian Ricci tensors for $n \geq 2$. If $u(x, t)$ is the positive solution of (1.6) on $M \times[0, \infty)$ such that

$$
P_{\beta} u=0
$$

at $t=0$. Then $u$ satisfies the estimate

$$
\frac{\left|\nabla_{b} u\right|^{2}}{u^{2}}+\frac{n+2}{n} \frac{u_{t}}{u} \leq \frac{(n+1)(n+2)^{2}}{2 n} \frac{1}{t}
$$

on $M \times[0, \infty)$.

Following the same proof as in Theorem 4.2. We have the following result.
THEOREM 6.4. If $u(x, t)$ be a positive smooth solution of (1.6)

$$
\left(\Delta_{b}-\frac{\partial}{\partial t}\right) u(x, t)=0
$$

on $H^{n} \times[0, T)$ with

$$
P_{\beta} u=0
$$

at $t=0$, then $u$ satisfies the subgradient estimate

$$
\frac{\left|\nabla_{b} u\right|^{2}}{u^{2}}+\frac{n+2}{n} \frac{u_{t}}{u} \leq\left[\frac{(n+1)(n+2)^{2}}{2 n}+\epsilon\right] \frac{1}{t}
$$

on $H^{n} \times[0, T)$ for any $\epsilon>0$.
Then by combining Theorem 6.4 and Proposition 4.1, Theorem 1.4 follows easily for all $n$.

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