

Examples of 4-dimensional symplectic-Haantjes manifolds

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Abstract. Symplectic-Haantjes manifolds are constructed for several Hamiltonian systems following P. Tempesta and G. Tondo [14], which yield the complete integrability of systems.

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§1. Introduction

Recently, certain ways of characterizing integrable systems with $(1, 1)$ -tensors have been investigated (cf. [2], [4], [5], [11], [12], [13], [16], etc.). On the other hand, according to [10], [14] and [15] established new method of using $(1, 1)$ -tensor field for the integrable system. P. Tempesta and G. Tondo [14] introduce a concept of symplectic-Haantjes manifolds or $\omega\mathcal{H}$ manifolds and Lenard-Haantjes chain to treat completely integrable Hamiltonian system by means of the Haantjes tensor [3]. For a $(1, 2)$ -tensor field L , the Haantjes tensor \mathcal{H}_L is given by Definition 2.1 below. If \mathcal{H}_L vanishes, the tensor is called a *Haantjes operator*. In [14], [15], Tempesta and Tondo showed that the existence of an $\omega\mathcal{H}$ manifold is a necessary and sufficient condition for a non-degenerate Hamiltonian system to be completely integrable. They showed an algorithm for solving the inverse problem, that is, for a given set of involutive functions, a Haantjes structure of the involutive functions is constructed by using Lenard-Haantjes chains.

We consider the system with respect to the hydrodynamic type on the orbit space with Hsiang-Lawson metric in the case of the Berger sphere (as in Section 3), via S^1 -equivariant CMC- H (constant mean curvature H) immersion and

the corresponding Lagrangian formalism [7], [8], [9]. In Section 4, we construct of symplectic-Haantjes manifold for a Hamiltonian system of Section 3.

In Section 5, we construct $\omega\mathcal{H}$ manifolds of Hamiltonian systems of geodesic flow of two-dimensional Minkowski space. [13] showed complete integrability of the geodesic flow of the Minkowski metric using a $(1, 1)$ tensor, however we construct the complete integrability of two-dimensional case by obtaining different $(1, 1)$ tensors from [13] in this paper. In this Section, we revise [6] and add some results.

In Sections 3 and 4, we construct a geometrical example of 4-dimensional symplectic Haantjes manifold.

§2. Haantjes operator, symplectic-Haantjes manifold, Lenard-Haantjes chain

In this Section, we recall basic concepts of Haantjes operators, symplectic-Haantjes manifolds and Lenard-Haantjes chains (see for details, e.g., [14]).

Let M be a differentiable manifold and $L : TM \rightarrow TM$ be a $(1, 1)$ tensor field, i.e., a field of linear operators on the tangent space at each point of M .

Definition 2.1. *The Nijenhuis torsion of L is the skew-symmetric $(1, 2)$ tensor field defined by*

$$\mathcal{N}_L(X, Y) = L^2[X, Y] + [LX, LY] - L([X, LY] + [LX, Y])$$

and the Haantjes tensor associated with L is the $(1, 2)$ tensor field defined by

$$\mathcal{H}_L(X, Y) = L^2\mathcal{N}_L(X, Y) + \mathcal{N}_L(LX, LY) - L(\mathcal{N}_L(X, LY) + \mathcal{N}_L(LX, Y))$$

where $X, Y \in TM$ and $[\cdot, \cdot]$ denotes the commutator of two vector fields.

In local coordinates $x = (x_1, \dots, x_n)$, the Nijenhuis torsion and the Haantjes tensor can be written in the form

$$(\mathcal{N}_L)^i_{jk} = \sum_{\alpha=1}^n \left(\frac{\partial L_k^i}{\partial x^\alpha} L_j^\alpha - \frac{\partial L_j^i}{\partial x^\alpha} L_k^\alpha + \left(\frac{\partial L_j^\alpha}{\partial x^k} - \frac{\partial L_k^\alpha}{\partial x^j} \right) L_\alpha^i \right)$$

and

(2.1)

$$(\mathcal{H}_L)^i_{jk} = \sum_{\alpha, \beta=1}^n \left\{ L_\alpha^i (L_\beta^\alpha (\mathcal{N}_L)^{\beta}_{jk}) - (\mathcal{N}_L)^{\alpha}_{\beta k} L_j^\beta + ((\mathcal{N}_L)^i_{\alpha\beta} L_j^\alpha - L_\alpha^i (\mathcal{N}_L)^{\alpha}_{j\beta}) L_k^\beta \right\},$$

respectively.

Tempesta and Tondo [14] remarks that the skew-symmetry of the Nijenhuis torsion implies that of the Haantjes tensor.

Definition 2.2. A $(1,1)$ -tensor is called *Haantjes operator* when its Haantjes tensor vanishes.

Now they introduce a concept of symplectic-Haantjes manifold ($\omega\mathcal{H}$ manifold) in [14]. They can formulate the theory of Hamiltonian integrable systems naturally by means of symplectic-Haantjes manifolds.

Definition 2.3. An $\omega\mathcal{H}$ manifold $(M, \omega, K_0, K_1, \dots, K_{n-1})$ is a $2n$ -dimension symplectic manifold M , endowed with n endomorphisms of TM

$$K_\alpha : TM \mapsto TM, \quad \alpha = 0, \dots, n-1,$$

which satisfy the following conditions :

- $K_0 = I$.
- Their Haantjes tensor vanishes identically, i.e.

$$\mathcal{H}_{K_\alpha}(X, Y) = 0, \quad \forall X, Y \in TM, \quad \alpha = 0, \dots, n-1.$$

- The endomorphisms are compatible with ω (or equivalently, with the corresponding symplectic operator $\Omega := \omega^\flat$) :

$$K_\alpha^T \Omega = \Omega K_\alpha, \quad \alpha = 0, \dots, n-1,$$

that is, the operators ΩK_α are skew symmetric.

- The endomorphisms are commuting each other, i.e. they form a commutative ring \mathcal{K} :

$$K_\alpha K_\beta = K_\beta K_\alpha, \quad \alpha = 0, \dots, n-1,$$

and also generate a module over the ring of smooth functions on M :

$$\mathcal{H}_{(\sum_{\alpha=0}^{n-1} a_\alpha(x) K_\alpha)}(X, Y) = 0, \quad \forall X, Y \in TM,$$

where $a_\alpha(x)$ are arbitrary smooth functions on M .

The $(n+1)$ -ple $(\omega, K_0, K_1, \dots, K_{n-1})$ will be called the $\omega\mathcal{H}$ structure associated with the $\omega\mathcal{H}$ manifold and \mathcal{K} the Haantjes module (ring).

By using the Haantjes operators, we can generalize the notion of integrability, which is called a Lenard-Haantjes chain.

Definition 2.4. Let $(M, \omega, K_0, K_1, \dots, K_{n-1})$ be a $2n$ -dimensional $\omega\mathcal{H}$ manifold and $\{\mathcal{H}_j\}_{1 \leq j \leq n}$ be n independent functions which satisfy the following relations :

$$d\mathcal{H}_j = K_{j-1}^T d\mathcal{H}, \quad j = 1, \dots, n, \quad \mathcal{H} := \mathcal{H}_1.$$

The functions $\{\mathcal{H}_j\}_{1 \leq j \leq n}$ are called a Lenard-Haantjes chain generated by the function \mathcal{H} .

Let us consider Hamiltonian systems with two degrees of freedom. In [14], Tempesta and Tondo proposed a general procedure to compute a Haantjes operator adapted to the Lenard-Haantjes chain formed by two integrals of motion in involution. Let (M, ω) be a four dimensional symplectic manifold. They searched for a Haantjes operator K whose minimal polynomial should be of degree two, namely, the maximum degree allowed by their assumptions:

$$m_K(x) = x^2 - c_1x - c_2,$$

where c_1 and c_2 are functions on M .

We construct the Haantjes operator K according to the conditions in [14].

$$(2.2) \quad K^T \Omega = \Omega K,$$

$$(2.3) \quad K^T d\mathcal{H} = d\mathcal{H}_2,$$

$$(2.4) \quad (K^T)^2 d\mathcal{H} = (c_1 K^T + c_2 I) d\mathcal{H},$$

$$(2.5) \quad \mathcal{H}_K(X, Y) = 0, \quad \forall X, Y \in TM,$$

where $\Omega = \omega^\flat$ and I denotes the identity operator.

§3. Berger sphere, Hsiang-Lawson metric, Lagrangian

Let $S^3 \subset \mathbb{C} \times \mathbb{C}$ be the unit 3-sphere. The following metric g_β ($\beta > -1$) on S^3 is called to be the Berger metric :

$$(g_\beta)_z(v, w) = \langle v, w \rangle + \beta \langle v, iz \rangle \langle w, iz \rangle,$$

where $v = (v_1, v_2), w = (w_1, w_2) \in T_z S^3$ and $\langle v, w \rangle = \operatorname{Re}(v\bar{w})$.

Then $S_\beta^3 := (S^3, g_\beta)$ is called to be the Berger sphere ($\beta > -1$). X denotes the orbit space via g_β -isometric S^1 -action $r_t : S^3 \rightarrow S^3$ as follows :

$$r_t(z) = (z_1, e^{it} z_2), \quad z = (z_1, z_2) \in S^3.$$

As the parameterization of X we use the following map :

$$(\theta, \phi) \rightarrow (e^{i\phi} \cos \theta, \sin \theta), \quad 0 \leq \phi \leq 2\pi, \quad 0 \leq \theta \leq \frac{\pi}{2}.$$

Let $X^\circ := X \setminus (\partial X \cup \{pole\})$. For a curve $\gamma : J \subset \mathbb{R} \rightarrow X^\circ$, we consider S^1 -equivariant map $\mu : N \rightarrow S_\beta^3$ such that $\gamma \circ \pi = \sigma \circ \mu$, where $N = \gamma^{-1}(S_\beta^3) := \{(z, y) \in J \times S_\beta^3 \mid \gamma(z) = \sigma(y)\}$ is the induced bundle, not an inverse map, $\pi : N \rightarrow J$ and $\sigma : S_\beta^3 \rightarrow X^\circ$ are Riemannian submersions. This commutative diagram is called the pull-back construction [1], [7]. Throughout the paper, we assume that μ is an S^1 -equivariant CMC- H (constant mean curvature H) immersion. Then the orbital metric h_β on X° is given by

$$(3.1) \quad h_\beta : ds^2 = d\theta^2 + \frac{(1 + \beta) \cos^2 \theta}{1 + \beta \sin^2 \theta} d\phi^2.$$

The volume function V of orbits and the Hsiang-Lawson metric $\hat{h}_\beta = V^2 h_\beta$ on X° are given as follows:

$$(3.2) \quad V = 2\pi \sin \theta \sqrt{1 + \beta \sin^2 \theta}, \quad \hat{h}_\beta = (\hat{h}_\beta)_1 d\theta^2 + (\hat{h}_\beta)_2 d\phi^2$$

where $(\hat{h}_\beta)_1 = 4\pi^2 \sin^2 \theta (1 + \beta \sin^2 \theta)$, $(\hat{h}_\beta)_2 = 4\pi^2 (1 + \beta) \sin^2 \theta \cos^2 \theta$.

$\tau(\gamma) = \nabla_{\gamma'} \gamma'$ and $\hat{\tau}(\gamma) = \hat{\nabla}_{\gamma'} \gamma'$ stand for the tension fields of $\gamma = \gamma(s)$ with respect to the metric h_β and \hat{h}_β , respectively, where s is the arc-length parameter with respect to the orbital metric h_β .

On the orbit space (X°, h_β) , the velocity vector field of a curve $\gamma(s) = (\theta(s), \phi(s))$ is given by the following component functions :

$$(3.3) \quad \theta'(s) = \cos \lambda(s), \quad \phi'(s) = \frac{\sqrt{1 + \beta \sin^2 \theta(s)} \sin \lambda(s)}{\sqrt{1 + \beta \cos^2 \theta(s)}},$$

where $\lambda(s)$ stands for an auxiliary function with variable s , then (3.3) can be obtained by using $\sin^2 \lambda(s) + \cos^2 \lambda(s) = 1$ and (3.1). Then, using the conformal transformation of the metric, we have the following formula :

$$(3.4) \quad h_\beta(\tau(\gamma), \eta) - \eta(\log V) = h_\beta(\hat{\tau}(\gamma), \eta) = 2H,$$

where η denotes the unit normal vector field to γ :

$$\eta(s) = -\sin \lambda(s) \frac{\partial}{\partial \theta} + \frac{\sqrt{1 + \beta \sin^2 \theta(s)} \cos \lambda(s)}{\sqrt{1 + \beta \cos^2 \theta(s)}} \frac{\partial}{\partial \phi}.$$

In the following, we consider the motion of a particle as time parameter s on the orbit space X° with the Hsiang-Lawson metric \hat{h}_β . In general, this motion has the Lagrangian

$$\mathcal{L} = \frac{1}{2} \left\{ (\hat{h}_\beta)_1 (\theta')^2 + (\hat{h}_\beta)_2 (\phi')^2 \right\} - G(\theta, \phi),$$

where $G = G(\theta, \phi)$ called as a potential function is a smooth function on the configuration space and θ', ϕ' stand for the derivatives of $\theta = \theta(s)$, $\phi = \phi(s)$ by s , respectively.

Then we can regard the Lagrangian \mathcal{L} as a smooth function on the tangent bundle TX° of X° .

Via the canonical momenta p_1, p_2 conjugate to θ, ϕ :

$$(3.5) \quad p_1 = \frac{\partial \mathcal{L}}{\partial \theta'} = (\hat{h}_\beta)_1 \theta' = (\hat{h}_\beta)_1 \cos \lambda,$$

$$(3.6) \quad p_2 = \frac{\partial \mathcal{L}}{\partial \phi'} = (\hat{h}_\beta)_2 \phi' = (\hat{h}_\beta)_2 \frac{\sqrt{1 + \beta \sin^2 \theta}}{\sqrt{1 + \beta \cos \theta}} \sin \lambda,$$

we have the Hamiltonian

$$\mathcal{H} = \theta' p_1 + \phi' p_2 - \mathcal{L} = \frac{1}{2} \left(\hat{h}_\beta^1 p_1^2 + \hat{h}_\beta^2 p_2^2 \right) + G(\theta, \phi),$$

where \hat{h}_β^1 and \hat{h}_β^2 are the inverse of $(\hat{h}_\beta)_1$ and $(\hat{h}_\beta)_2$, respectively.

On the orbit space (X°, \hat{h}_β) , we consider the system of hydrodynamic type as follows. Assume that smooth functions ν^1 and ν^2 on X° do not depend on ϕ . Moreover, let either $\nu^1 = \nu^1(\theta)$ or $\nu^2 = \nu^2(\theta)$ be nonzero-valued as a function of θ only. Then we can consider the functions \mathcal{H} and \mathcal{H}_2 on the phase space :

$$\begin{aligned} \mathcal{H} &= \frac{1}{2} \left(\hat{h}_\beta^1 p_1^2 + \hat{h}_\beta^2 p_2^2 \right) + G(\theta, \phi), \\ \mathcal{H}_2 &= \frac{1}{2} \left(\nu^1 \hat{h}_\beta^1 p_1^2 + \nu^2 \hat{h}_\beta^2 p_2^2 \right), \end{aligned}$$

where we assume that \mathcal{H} and \mathcal{H}_2 are in involution.

The Poisson bracket of \mathcal{H} and \mathcal{H}_2 is calculated as follows :

$$\begin{aligned} \{\mathcal{H}_2, \mathcal{H}\} &= \left\{ \frac{1}{2} \left(\left(\frac{\partial}{\partial \theta} \hat{h}_\beta^1 \right) p_1^2 + \left(\frac{\partial}{\partial \theta} \hat{h}_\beta^2 \right) p_2^2 \right) + \frac{\partial G}{\partial \theta} \right\} \nu^1 \hat{h}_\beta^1 p_1 \\ &\quad + \frac{\partial G}{\partial \phi} \nu^2 \hat{h}_\beta^2 p_2 - \frac{1}{2} \hat{h}_\beta^1 p_1 \left\{ \frac{\partial}{\partial \theta} (\nu^1 \hat{h}_\beta^1) p_1^2 + \frac{\partial}{\partial \theta} (\nu^2 \hat{h}_\beta^2) p_2^2 \right\}, \end{aligned}$$

since \hat{h}_β^1 and \hat{h}_β^2 depend only on the variable θ . Hereafter, we consider the case $\nu^1 = 0$. Then we have

$$\{\mathcal{H}_2, \mathcal{H}\} = \frac{\partial G}{\partial \phi} \nu^2 \hat{h}_\beta^2 p_2 - \frac{1}{2} \hat{h}_\beta^1 \frac{\partial}{\partial \theta} (\nu^2 \hat{h}_\beta^2) p_1 p_2^2.$$

Thus $\{\mathcal{H}_2, \mathcal{H}\} = 0$ implies that

$$\frac{\partial G}{\partial \phi} \nu^2 \hat{h}_\beta^2 = 0, \quad \hat{h}_\beta^1 \frac{\partial}{\partial \theta} (\nu^2 \hat{h}_\beta^2) = 0,$$

from which, we obtain that $\nu^2 = k(\hat{h}_\beta)_2$ (k is nonzero constant). Then the potential function G depends only on the variable θ .

§4. Construction of symplectic-Haantjes manifold for a Hamiltonian system

Assume that $\nu^1 = 0$, $\nu^2 = k(\hat{h}_\beta)_2$ (k is nonzero constant) and the potential function G depends only on θ . Then we can consider the functions

$$\begin{aligned}\mathcal{H} &= \frac{1}{2} \left(\hat{h}_\beta^1 p_1^2 + \hat{h}_\beta^2 p_2^2 \right) + G(\theta), \\ \mathcal{H}_2 &= \frac{1}{2} k p_2^2,\end{aligned}$$

where we assume that λ is a suitable function of θ as in (3.5) and (3.6), \mathcal{H} and \mathcal{H}_2 are in involution, k is nonzero constant. Using above functions, we construct a Haantjes operator.

We put a 4-dimensional square matrix

$$\begin{aligned}K &= (K_j^i) \\ &= \begin{pmatrix} a(\theta) & b(\theta) & 0 & b(\theta) \\ c(\theta, p_1, p_2) & a(\theta) & -b(\theta) & 0 \\ 0 & c(\theta, p_1, p_2) & a(\theta) & c(\theta, p_1, p_2) \\ -c(\theta, p_1, p_2) & 0 & b(\theta) & a(\theta) \end{pmatrix} = \begin{pmatrix} a & b & 0 & b \\ c & a & -b & 0 \\ 0 & c & a & c \\ -c & 0 & b & a \end{pmatrix},\end{aligned}$$

where $a = k(\hat{h}_\beta)_2$, $b = b(\theta)$, $c = -k\hat{h}_\beta^1(\hat{h}_\beta)_2^2 p_1 p_2^{-1}$.

This function matrix K satisfies conditions (2.2), (2.3), and the potential function G is given such that the following formula is satisfied:

$$\frac{\partial G}{\partial \theta} = -\frac{1}{2} \left(\frac{\partial \hat{h}_\beta^1}{\partial \theta} p_1^2 + \frac{\partial \hat{h}_\beta^2}{\partial \theta} p_2^2 \right) + \frac{1}{k} b(\hat{h}_\beta^2)^2 p_2,$$

where, from (3.5) and (3.6), G can be regarded as a function of θ , under the assumption that λ is a suitable function of θ . Then, minimal polynomial of K is

$$(4.1) \quad m_K(x) = x^2 - 2ax + a^2.$$

From (4.1), we put $c_1 = 2a$ and $c_2 = -a^2$, the condition (2.4) is satisfied.

We set $x_1 = \theta$, $x_2 = \phi$, $x_3 = p_1$, $x_4 = p_2$ and $K \left(\frac{\partial}{\partial x_j} \right) = \sum_{i=1}^4 K_j^i \frac{\partial}{\partial x_i}$ ($j =$

1, 2, 3, 4). For example, we have, using the definition of the Nijenhuis torsion:

$$\begin{aligned}
(\mathcal{N}_K)_{12}^1 &= \sum_{\alpha=1}^4 \frac{\partial b}{\partial x_\alpha} K_1^\alpha - \sum_{\alpha=1}^4 \frac{\partial a}{\partial x_\alpha} K_2^\alpha \\
&\quad + a \left(\frac{\partial a}{\partial x_2} - \frac{\partial b}{\partial x_1} \right) + b \left(\frac{\partial c}{\partial x_2} - \frac{\partial a}{\partial x_1} \right) - b \frac{\partial c}{\partial x_2} \\
&= b'a - a'b - ab' - ba' \\
&= -2a'b, \\
(\mathcal{N}_K)_{14}^2 &= - \sum_{\alpha=1}^4 \frac{\partial c}{\partial x_\alpha} K_4^\alpha + c \left(\frac{\partial a}{\partial x_4} - \frac{\partial b}{\partial x_1} \right) + a \frac{\partial c}{\partial x_4} - b \left(- \frac{\partial c}{\partial x_1} \right) \\
&= - \frac{\partial c}{\partial \theta} b - \frac{\partial c}{\partial p_1} c - \frac{\partial c}{\partial p_2} a - b'c + a \frac{\partial c}{\partial p_2} + b \frac{\partial c}{\partial \theta} \\
&= -b'c - c \frac{\partial c}{\partial p_1},
\end{aligned}$$

where $a' := \frac{\partial a}{\partial \theta}$, $b' := \frac{\partial b}{\partial \theta}$.

Then we get the following equations which calculate the components of a Nijenhuis torsion $\mathcal{N}_K = \mathcal{N}$:

$$\begin{aligned}
\mathcal{N}_{12}^1 &= -2a'b, \quad \mathcal{N}_{14}^1 = -2a'b, \quad \mathcal{N}_{12}^2 = -b'c - c \frac{\partial c}{\partial p_1}, \quad \mathcal{N}_{13}^2 = a'b - b \frac{\partial c}{\partial p_2}, \\
\mathcal{N}_{14}^2 &= -b'c - c \frac{\partial c}{\partial p_1}, \quad \mathcal{N}_{23}^2 = -bb' - b \frac{\partial c}{\partial p_1}, \quad \mathcal{N}_{24}^2 = -a'b - b \frac{\partial c}{\partial p_2}, \\
\mathcal{N}_{34}^2 &= bb' + b \frac{\partial c}{\partial p_1}, \quad \mathcal{N}_{12}^3 = -a'c - c \frac{\partial c}{\partial p_2}, \quad \mathcal{N}_{14}^3 = -a'c - c \frac{\partial c}{\partial p_2}, \\
\mathcal{N}_{23}^3 &= a'b - b \frac{\partial c}{\partial p_2}, \quad \mathcal{N}_{34}^3 = -a'b + b \frac{\partial c}{\partial p_2}, \quad \mathcal{N}_{12}^4 = b'c + c \frac{\partial c}{\partial p_1}, \\
\mathcal{N}_{13}^4 &= -a'b + b \frac{\partial c}{\partial p_2}, \quad \mathcal{N}_{14}^4 = b'c + c \frac{\partial c}{\partial p_1}, \quad \mathcal{N}_{23}^4 = b'b + b \frac{\partial c}{\partial p_1}, \\
\mathcal{N}_{24}^4 &= a'b + b \frac{\partial c}{\partial p_2}, \quad \mathcal{N}_{34}^4 = -bb' - b \frac{\partial c}{\partial p_1},
\end{aligned}$$

where $\mathcal{N}_{jk}^i = 0$ (otherwise, except skew-symmetric ones with the above formulas). From (2.1), we have

$$\begin{aligned}
(4.2) \quad (\mathcal{H}_K)_{jk}^i &= \sum_{\alpha, \beta=1}^n \left\{ K_\alpha^i K_\beta^\alpha (\mathcal{N}_K)_{jk}^\beta + K_j^\alpha K_k^\beta (\mathcal{N}_K)_{\alpha\beta}^i \right. \\
&\quad \left. + K_\alpha^i K_j^\beta (\mathcal{N}_K)_{k\beta}^\alpha + K_\alpha^i K_k^\beta (\mathcal{N}_K)_{\beta j}^\alpha \right\}.
\end{aligned}$$

For example, we have, from the components of K and Nijenhuis torsion :

$$\begin{aligned}
& \sum_{\alpha, \beta=1}^4 K_\alpha^1 K_\beta^\alpha (\mathcal{N}_K)_{12}^\beta \\
&= \sum_{\alpha=1}^4 K_\alpha^1 (K_1^\alpha (\mathcal{N}_K)_{12}^1 + K_2^\alpha (\mathcal{N}_K)_{12}^2 + K_3^\alpha (\mathcal{N}_K)_{12}^3 + K_4^\alpha (\mathcal{N}_K)_{12}^4) \\
&= K_1^1 (K_1^1 (\mathcal{N}_K)_{12}^1 + K_2^1 (\mathcal{N}_K)_{12}^2 + K_4^1 (\mathcal{N}_K)_{12}^4) \\
&\quad + K_2^1 (K_1^2 (\mathcal{N}_K)_{12}^1 + K_2^2 (\mathcal{N}_K)_{12}^2 + K_3^2 (\mathcal{N}_K)_{12}^3) \\
&\quad + K_4^1 (K_1^4 (\mathcal{N}_K)_{12}^1 + K_3^4 (\mathcal{N}_K)_{12}^3 + K_4^4 (\mathcal{N}_K)_{12}^4) \\
&= a^2(-2a'b) + ab \left(-b'c - c \frac{\partial c}{\partial p_1} \right) + ab \left(b'c + c \frac{\partial c}{\partial p_1} \right) \\
&\quad + bc(-2a'b) + ba \left(-b'c - c \frac{\partial c}{\partial p_1} \right) + b(-b) \left(-a'c - c \frac{\partial c}{\partial p_2} \right) \\
&\quad + b(-c)(-2a'b) + b^2 \left(-a'c - c \frac{\partial c}{\partial p_2} \right) + ba \left(b'c + c \frac{\partial c}{\partial p_1} \right) \\
&= -2a^2 a'b.
\end{aligned}$$

Similarly, we have

$$\sum_{\alpha, \beta=1}^4 K_1^\alpha K_2^\beta (\mathcal{N}_K)_{\alpha\beta}^1 = -2a^2 a'b.$$

Also, we have

$$\begin{aligned}
& \sum_{\alpha, \beta=1}^4 K_\alpha^1 K_1^\beta (\mathcal{N}_K)_{2\beta}^\alpha = K_1^1 K_1^1 (\mathcal{N}_K)_{21}^1 + K_2^1 (K_1^1 (\mathcal{N}_K)_{21}^2 + K_1^4 (\mathcal{N}_K)_{24}^2) \\
&\quad + K_4^1 (K_1^1 (\mathcal{N}_K)_{21}^4 + K_1^4 (\mathcal{N}_K)_{24}^4) \\
&= 2a^2 a'b + ba \left(b'c + c \frac{\partial c}{\partial p_1} \right) + b(-c) \left(-a'b - b \frac{\partial c}{\partial p_2} \right) \\
&\quad + ba \left(-b'c - c \frac{\partial c}{\partial p_1} \right) + b(-c) \left(a'b + b \frac{\partial c}{\partial p_2} \right) \\
&= 2a^2 a'b.
\end{aligned}$$

Similarly, we have

$$\sum_{\alpha, \beta=1}^4 K_\alpha^1 K_2^\beta (\mathcal{N}_K)_{\beta 1}^\alpha = 2a^2 a'b.$$

Then we have

$$\begin{aligned}
(\mathcal{H}_K)_1^1 &= \sum_{\alpha, \beta=1}^n \left\{ K_\alpha^1 K_\beta^\alpha (\mathcal{N}_K)_{12}^\beta + K_1^\alpha K_2^\beta (\mathcal{N}_K)_{\alpha\beta}^1 \right. \\
&\quad \left. + K_\alpha^1 K_1^\beta (\mathcal{N}_K)_{2\beta}^\alpha + K_\alpha^1 K_2^\beta (\mathcal{N}_K)_{\beta 1}^\alpha \right\} \\
&= 0.
\end{aligned}$$

Secondly, we calculate $(\mathcal{H}_K)_{34}^2$.

$$\begin{aligned}
&\sum_{\alpha, \beta=1}^4 K_\alpha^2 K_\beta^\alpha (\mathcal{N}_K)_{34}^\beta \\
&= K_1^2 (K_2^1 (\mathcal{N}_K)_{34}^2 + K_4^1 (\mathcal{N}_K)_{34}^4) + K_2^2 (K_2^2 (\mathcal{N}_K)_{34}^2 + K_3^2 (\mathcal{N}_K)_{34}^3) \\
&\quad + K_3^2 (K_2^3 (\mathcal{N}_K)_{34}^2 + K_3^3 (\mathcal{N}_K)_{34}^3 + K_4^3 (\mathcal{N}_K)_{34}^4) \\
&= cb \left(bb' + b \frac{\partial c}{\partial p_1} \right) + cb \left(-bb' - b \frac{\partial c}{\partial p_1} \right) + a^2 \left(bb' + b \frac{\partial c}{\partial p_1} \right) \\
&\quad + a(-b) \left(-a'b + b \frac{\partial c}{\partial p_2} \right) - bc \left(bb' + b \frac{\partial c}{\partial p_1} \right) - ba \left(-a'b + b \frac{\partial c}{\partial p_2} \right) \\
&\quad - bc \left(-bb' - b \frac{\partial c}{\partial p_1} \right) \\
&= a^2 bb' + 2aa'b^2 + a^2 b \frac{\partial c}{\partial p_1} - 2ab^2 \frac{\partial c}{\partial p_2}.
\end{aligned}$$

Similarly, we have

$$\sum_{\alpha, \beta=1}^4 K_3^\alpha K_4^\beta (\mathcal{N}_K)_{\alpha\beta}^2 = a^2 bb' + a^2 b \frac{\partial c}{\partial p_1} + 2ab^2 \frac{\partial c}{\partial p_2}.$$

Also we have

$$\begin{aligned}
&\sum_{\alpha, \beta=1}^4 K_\alpha^2 K_3^\beta (\mathcal{N}_K)_{4\beta}^\alpha = K_2^2 (K_3^2 (\mathcal{N}_K)_{42}^2 + K_3^3 (\mathcal{N}_K)_{43}^2) + K_3^2 K_3^3 (\mathcal{N}_K)_{43}^3 \\
&= a(-b) \left(a'b + b \frac{\partial c}{\partial p_2} \right) + a^2 \left(-bb' - b \frac{\partial c}{\partial p_1} \right) \\
&\quad - ba \left(a'b - b \frac{\partial c}{\partial p_2} \right) \\
&= -2aa'b^2 - a^2 bb' - a^2 b \frac{\partial c}{\partial p_1}.
\end{aligned}$$

Similarly, we have

$$\sum_{\alpha, \beta=1}^4 K_\alpha^2 K_4^\beta (\mathcal{N}_K)_{\beta 3}^\alpha = -a^2 b b' - a^2 b \frac{\partial c}{\partial p_1}.$$

Consequently, we have

$$\begin{aligned} (\mathcal{H}_K)_{34}^2 &= \sum_{\alpha, \beta=1}^n \left\{ K_\alpha^2 K_\beta^\alpha (\mathcal{N}_K)_{34}^\beta + K_3^\alpha K_4^\beta (\mathcal{N}_K)_{\alpha\beta}^2 \right. \\ &\quad \left. + K_\alpha^2 K_3^\beta (\mathcal{N}_K)_{4\beta}^\alpha + K_\alpha^2 K_4^\beta (\mathcal{N}_K)_{\beta 3}^\alpha \right\} \\ &= 0. \end{aligned}$$

Similarly, we can prove that all components of Haantjes tensor vanish.

Thus the function matrix K satisfies the condition (2.5). Hence, we get a Haantjes operator K . Thus, we construct a symplectic Haantjes manifold $(T^*X^\circ, \omega, I, K)$.

§5. Other examples

In this Section, we construct $\omega\mathcal{H}$ manifolds in three cases. Let us consider the Hamiltonian system of the geodesic flow of 2-dimensional Minkowski space (cf. [13])

$$(5.1) \quad \mathcal{H} = \frac{1}{2}(-p_1^2 + p_2^2)$$

with an independent integral of motion

$$(5.2) \quad \mathcal{H}_2 = p_1.$$

Thus, \mathcal{H} has Haantjes operator K in the following way.

We consider $\mathcal{G} = \mathcal{G}(q, p)$ which is functionally independent of \mathcal{H} . We assume the Poisson bracket $\{\mathcal{H}, \mathcal{G}\}$ vanishes, that is

$$\{\mathcal{H}, \mathcal{G}\} = \sum_{i=1}^2 \left(\frac{\partial \mathcal{H}}{\partial p_i} \frac{\partial \mathcal{G}}{\partial q_i} - \frac{\partial \mathcal{H}}{\partial q_i} \frac{\partial \mathcal{G}}{\partial p_i} \right) = -p_1 \frac{\partial \mathcal{G}}{\partial q_1} + p_2 \frac{\partial \mathcal{G}}{\partial q_2} = 0.$$

Then we get the following condition:

$$(5.3) \quad p_1 \frac{\partial \mathcal{G}}{\partial q_1} = p_2 \frac{\partial \mathcal{G}}{\partial q_2}.$$

The function \mathcal{H}_2 in (5.2) as \mathcal{G} satisfies the condition (5.3). Under the condition (2.2), we put a 4-dimensional square matrix

$$K = \begin{pmatrix} a_{11} & a_{12} & 0 & b_{12} \\ a_{21} & a_{22} & -b_{12} & 0 \\ 0 & c_{12} & a_{11} & a_{21} \\ -c_{12} & 0 & a_{12} & a_{22} \end{pmatrix}.$$

Then from the condition (2.3), we get the following relationship

$$\begin{aligned} a_{21} &= \frac{a_{11}p_1 + 1}{p_2}, \\ a_{22} &= \frac{a_{12}p_1}{p_2}, \\ b_{12} &= 0. \end{aligned}$$

Further, we put $c_1 = (a_{12}p_1 + a_{11}p_2)p_2^{-1}$ and $c_2 = a_{12}p_2^{-1}$, the condition (2.4) is satisfied. We set $x_1 = p_1$, $x_2 = p_2$, $x_3 = q_1$, $x_4 = q_2$. For example, we have, using the definition of the Nijenhuis torsion :

$$\begin{aligned} (\mathcal{N}_K)_{jk}^1 &= \sum_{\alpha=1}^4 \left(\frac{\partial K_j^\alpha}{\partial x_k} - \frac{\partial K_k^\alpha}{\partial x_j} \right) K_\alpha^1 = \left(\frac{\partial K_j^2}{\partial x_k} - \frac{\partial K_k^2}{\partial x_j} \right) K_2^1, \\ (\mathcal{N}_K)_{12}^1 &= \left(\frac{\partial K_1^2}{\partial x_2} - \frac{\partial K_2^2}{\partial x_1} \right) K_2^1 \\ &= \left\{ \frac{\partial}{\partial p_2} \left(\frac{a_{11}p_1 + 1}{p_2} \right) - \frac{\partial}{\partial p_1} \left(\frac{a_{12}p_1}{p_2} \right) \right\} a_{12} \\ &= a_{12} \left(-\frac{a_{11}p_1 + 1}{p_2^2} - \frac{a_{12}}{p_2} \right) \\ &= -\frac{a_{12}(a_{11}p_1 + a_{12}p_2 + 1)}{p_2^2}, \\ (\mathcal{N}_K)_{23}^1 &= \left(\frac{\partial K_2^2}{\partial x_3} - \frac{\partial K_3^2}{\partial x_2} \right) K_2^1 = \left\{ \frac{\partial}{\partial q_1} \left(\frac{a_{12}p_1}{p_2} \right) - 0 \right\} a_{12} = 0. \end{aligned}$$

Then we get the following equations which calculate the components of the

Nijenhuis torsion $\mathcal{N}_K = \mathcal{N}$:

$$\begin{aligned}\mathcal{N}_{12}^1 &= -\frac{a_{12}(a_{11}p_1 + a_{12}p_2 + 1)}{p_2^2}, & \mathcal{N}_{12}^2 &= -\frac{a_{12}p_1(a_{11}p_1 + a_{12}p_2 + 1)}{p_2^3}, \\ \mathcal{N}_{12}^3 &= -\frac{c_{12}(a_{11}p_1 + a_{12}p_2 + 1)}{p_2^2}, & \mathcal{N}_{14}^3 &= -\frac{(a_{11}p_1 + 1)(a_{11}p_1 + a_{12}p_2 + 1)}{p_2^3}, \\ \mathcal{N}_{24}^3 &= \frac{a_{11}(a_{11}p_1 + a_{12}p_2 + 1)}{p_2^2}, & \mathcal{N}_{14}^4 &= -\frac{a_{12}p_1(a_{11}p_1 + a_{12}p_2 + 1)}{p_2^3}, \\ \mathcal{N}_{24}^4 &= \frac{a_{12}(a_{11}p_1 + a_{12}p_2 + 1)}{p_2^2},\end{aligned}$$

where $\mathcal{N}_{jk}^i = 0$ (otherwise, except skew-symmetric ones with the above formulas). From (4.2), for example, we have, from the components of K and Nijenhuis torsion :

$$\begin{aligned}& \sum_{\alpha, \beta=1}^4 K_\alpha^3 K_\beta^\alpha (\mathcal{N}_K)_{12}^\beta \\ &= K_2^3 K_2^2 (\mathcal{N}_K)_{12}^2 + K_1^1 (K_2^3 (\mathcal{N}_K)_{12}^2 + K_1^1 (\mathcal{N}_K)_{12}^3) + K_1^2 K_2^1 (\mathcal{N}_K)_{12}^3, \\ & \sum_{\alpha, \beta=1}^4 K_1^\alpha K_2^\beta (\mathcal{N}_K)_{\alpha\beta}^3 \\ &= K_1^1 K_2^2 (\mathcal{N}_K)_{12}^3 - K_1^2 K_2^1 (\mathcal{N}_K)_{12}^3 + K_2^3 (K_2^1 (\mathcal{N}_K)_{14}^3 + K_2^2 (\mathcal{N}_K)_{24}^3), \\ & \sum_{\alpha, \beta=1}^4 K_\alpha^3 K_1^\beta (\mathcal{N}_K)_{2\beta}^\alpha \\ &= -K_2^3 (K_1^1 (\mathcal{N}_K)_{12}^2 + K_2^3 (\mathcal{N}_K)_{24}^2) - K_1^1 (K_1^1 (\mathcal{N}_K)_{12}^3 + K_2^3 (\mathcal{N}_K)_{24}^3) \\ &\quad - K_1^2 (K_1^1 (\mathcal{N}_K)_{12}^4 + K_2^3 (\mathcal{N}_K)_{24}^4), \\ & \sum_{\alpha, \beta=1}^4 K_\alpha^3 K_2^\beta (\mathcal{N}_K)_{\beta 1}^\alpha = -K_2^3 K_2^2 (\mathcal{N}_K)_{12}^2 - K_1^1 K_2^2 (\mathcal{N}_K)_{12}^3.\end{aligned}$$

From above equations, we get

$$\begin{aligned}(\mathcal{H}_K)_{12}^3 &= K_2^3 (K_2^1 (\mathcal{N}_K)_{14}^3 + K_2^2 (\mathcal{N}_K)_{24}^3) - K_2^3 K_2^3 (\mathcal{N}_K)_{24}^2 - K_1^1 K_2^3 (\mathcal{N}_K)_{24}^3 \\ &\quad - K_1^2 (K_1^1 (\mathcal{N}_K)_{12}^4 + K_2^3 (\mathcal{N}_K)_{24}^4) \\ &= -\frac{c_{12}(a_{11}p_1 + a_{12}p_2 + 1)(a_{11}^2 p_2 + a_{11}a_{12}p_1 + 2a_{12})}{p_2^3}.\end{aligned}$$

If $(\mathcal{H}_K)_{12}^3 = 0$, we can choose $a_{11} = 0$, $a_{12} = 0$ as one of the solutions.

Consequently, we have

$$(\mathcal{H}_K)_{12}^3 = 0,$$

where $a_{11} = 0$, $a_{12} = 0$ and $\mathcal{N} \neq 0$. Similarly, we can prove that all components of Haantjes tensor vanish. Thus we get the Haantjes operator K :

$$K = \begin{pmatrix} 0 & 0 & 0 & 0 \\ p_2^{-1} & 0 & 0 & 0 \\ 0 & c_{12} & 0 & p_2^{-1} \\ -c_{12} & 0 & 0 & 0 \end{pmatrix},$$

where $\mathcal{N} \neq 0$ and $c_{12} \neq 0$. Hence we construct a $\omega\mathcal{H}$ manifold $(T^*\mathbb{R}^2, \omega, I, K)$.

Now, we put the function

$$(5.4) \quad \mathcal{H}_3 = k_1 p_1 + k_2 p_2.$$

This function (5.4) satisfies the condition (5.3). Then, by the same calculation as above, we construct the Haantjes operator K' :

$$K' = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 5p_2^{-1} & k_2 p_2^{-1} & 0 & 0 \\ 0 & c_{12} & 0 & 5p_2^{-1} \\ -c_{12} & 0 & 0 & k_2 p_2^{-1} \end{pmatrix},$$

where $(\mathcal{N}_{K'})_{12}^2 = (\mathcal{N}_{K'})_{14}^4 = -5k_2 p_2^{-3}$, $(\mathcal{N}_{K'})_{12}^3 = -5c_{12} p_2^{-2}$, $(\mathcal{N}_{K'})_{14}^3 = -25p_2^{-3}$ and otherwise except skew-symmetric ones with the above formulas. Hence, we get a different $\omega\mathcal{H}$ manifold $(T^*\mathbb{R}^2, \omega, I, K')$ from the one above.

Moreover, we consider

$$(5.5) \quad \mathcal{H}_4 = k p_1 p_2.$$

Similar to the above, this function (5.5) satisfies the condition (5.3). Then, if we put

$$K'' = \begin{pmatrix} 0 & -5 & 0 & 0 \\ 5 & 0 & 0 & 0 \\ 0 & c_{12} & 0 & 5 \\ -c_{12} & 0 & -5 & 0 \end{pmatrix},$$

K'' is a Haantjes operator. In fact, (5.1), (5.5) and K'' satisfy the conditions (2.2), (2.3), (2.4) and (2.5). Therefore, we construct an $\omega\mathcal{H}$ manifold $(T^*\mathbb{R}^2, \omega, I, K'')$.

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