

ON POSITIVE SCALAR CURVATURE AND MODULI OF CURVES

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Abstract

In this article we first show that any finite cover of the moduli space of closed Riemann surfaces of genus g with $g \geq 2$ does not admit any Riemannian metric ds^2 of nonnegative scalar curvature such that $\|\cdot\|_{ds^2} \succ \|\cdot\|_T$ where $\|\cdot\|_T$ is the Teichmüller metric.

Our second result is the proof that any cover M of the moduli space \mathbb{M}_g of a closed Riemann surface S_g does not admit any complete Riemannian metric of uniformly positive scalar curvature in the quasi-isometry class of the Teichmüller metric, which implies a conjecture of Farb–Weinberger in [9].

1. Introduction

Many aspects of positive scalar curvatures on Riemannian manifolds have been well understood since the fundamental works of Schoen–Yau [31, 32] and Gromov–Lawson [14, 15]. Important generalizations have been developed by Roe [29], Yu [43] and many others. The main object of this paper is to study obstructions to the existence of positive scalar curvature metric on the moduli spaces of Riemann surfaces.

Let S_g be a closed Riemann surface of genus g with $g \geq 2$, $\text{Mod}(S_g)$ be the mapping class group and $\text{Teich}(S_g)$ be the Teichmüller space of S_g . Topologically $\text{Teich}(S_g)$ is a manifold of real dimension $6g-6$, which carries various $\text{Mod}(S_g)$ -invariant metrics which descend to metrics on the moduli space \mathbb{M}_g of S_g with respective properties. For examples, the famous Weil–Petersson metric and Teichmüller metric. The Teichmüller metric $\|\cdot\|_T$ is not Riemannian but a complete Finsler metric. It was shown in [24] that $\|\cdot\|_T$ is not nonpositively curved in the metric sense by showing that there exists two different geodesic rays starting at the same point such that they have bounded Hausdorff distance. Furthermore, Masur and Wolf in [26] showed that $(\text{Teich}(S_g), \|\cdot\|_T)$ is not Gromov-hyperbolic. The Weil–Petersson metric ds_{WP}^2 is Kähler [1], incomplete [7, 35], geodesically convex [37] and has negative sectional curvature

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[34, 36]. Since $g \geq 2$, the works in [38, 42] tell that $\text{Teich}(S_g)$ is not Gromov-hyperbolic. Let $\text{Teich}(S_{g,n})$ be the Teichmüller space of surfaces of genus g with n punctures. Brock and Farb in [4] showed that the space $(\text{Teich}(S_{g,n}), ds_{WP}^2)$ is Gromov-hyperbolic if and only if $3g + n \leq 5$.

There are also some other important metrics on \mathbb{M}_g . For examples, the asymptotic Poincaré metric, the induced Bergman metric, the Kähler–Einstein metric, the McMullen metric, the Ricci metric, and the perturbed Ricci metric are all complete and Kähler metrics. The Kobayashi metric and the Caratheodory metric are complete Finsler metrics. In [21, 22, 27], the authors showed that all these metrics are bi-Lipschitz (or equivalent) to the Teichmüller metric. And the Weil–Petersson metric plays important roles in their proofs.

The perturbed Ricci metric [21, 22] has pinched negative Ricci curvature. In particular, it also has negative scalar curvature. The McMullen metric [27] has negative scalar curvature at certain points since the metric, restricted on a certain thick part of the moduli space, is the Weil–Petersson metric. However, Farb and Weinberger in [13] showed that any finite cover M of the moduli space \mathbb{M}_g ($g \geq 2$) admits a complete finite-volume Riemannian metric of (uniformly) positive scalar curvature, which is analogous to Block–Weinberger’s result in [5] on certain locally symmetric arithmetic manifolds.

The motivation of this paper is a result of Gromov–Lawson in [15] which says that *given a complete Riemannian manifold (X, ds_1^2) of non-positive sectional curvature, then X cannot admit any Riemannian metric ds_2^2 on X with $\|\cdot\|_{ds_2^2} \succ \|\cdot\|_{ds_1^2}$ such that (X, ds_2^2) has positive scalar curvature.* (One can also see Theorem 1.1 in [29]) where $\|\cdot\|_{ds_2^2} \succ \|\cdot\|_{ds_1^2}$ means that there exists a constant $k > 0$ such that for all tangent vector v we have $\|v\|_{ds_2^2} \geq k \cdot \|v\|_{ds_1^2}$. One immediate application is that the torus \mathbb{T}^n ($n \geq 2$) cannot carry a complete Riemannian metric of positive scalar curvature. For low dimensions $n \leq 7$, this was first settled in a series of papers by R. Schoen and S. T. Yau in [31] and [32].

Our first result in this paper is the following theorem.

Theorem 1.1. *Let S_g be a closed Riemann surface of genus g with $g \geq 2$ and M be a finite cover of the moduli space \mathbb{M}_g of S_g . Then for any Riemannian metric ds^2 on M with $\|\cdot\|_{ds^2} \succ \|\cdot\|_T$ where $\|\cdot\|_T$ is the Teichmüller metric,*

$$\inf_{p \in (M, ds^2)} \text{Sca}(p) < 0.$$

E. Leuzinger in [20] showed that *any finite cover of the moduli space \mathbb{M}_g of S_g does not admit any Riemannian metric of uniformly positive scalar curvature such that the metric is bi-Lipschitz to the Teichmüller metric.* Theorem 1.1 generalizes his result and the method in this article

is completely different from the one of E. Leuzinger in [20]. Leuzinger first provided a good partition for a finite manifold cover of the moduli space and then apply an argument of Chang [6] to prove his theorem. Our method is to use some recent developments in [2, 21, 22, 27] on the geometry of Teichmüller space as bridges to prove Theorem 1.1. The second author in [41] applied the negativity of the Ricci curvature of the perturbed Ricci metric [21, 22] to show that *any finite cover of the moduli space \mathbb{M}_g does not admit any complete finite-volume Kähler metric of nonnegative scalar curvature*. Moreover, he also showed that *the total scalar curvature of any Kähler metric, which is bi-Lipschitz to the Teichmüller metric, is negative provided the scalar curvature is bounded from below*. However, the method in [41] highly depends on the canonical complex structure on \mathbb{M}_g . For example, the identity map between \mathcal{M}_g endowed with different Kähler metrics is biholomorphic. Then certain Bochner formula can be applied. In the setting of Riemannian metrics, the identity map cannot even be harmonic.

Theorem 1.1 applies to the metric $ds^2 = ds_*^2 + ds_a^2$ where ds_*^2 is either the McMullen metric, Bergman metric, Ricci metric or perturbed Ricci metric and ds_a^2 is only Riemannian and not necessarily Hermitian. We remark here that there is no finite-volume condition for Theorem 1.1. As stated above the Teichmüller metric is not nonpositively curved. So the argument in [15] cannot lead to Theorem 1.1.

Remark 1.2. (1). Following entirely the same arguments in this article, one can deduce that Theorem 1.1 is still true for the Teichmüller space of noncompact surface $S_{g,n}$ of genus g with n punctures if $3g+n \geq 5$. Note that Theorem 4.1 and 4.3 require that the dimension of the space is greater than or equal to 3.

(2). For the cases $(g, n) = (1, 1)$ or $(0, 4)$, it is not hard to see that Theorem 1.1 still holds without the assumptions on the Teichmüller metric, since for these two cases the scalar curvature is the same as the sectional curvature up to a constant. More precisely, Theorem 1.1 directly follows from the fact that the mapping class group contains free subgroups of rank ≥ 2 .

(3). The existence theorem of Farb–Weinberger in [13], which one can also see Theorem 4.5 in [9], tells that Theorem 1.1 does not hold anymore without the assumptions on the Teichmüller metric if $3g+n \geq 6$. It is *interesting* to know whether Theorem 1.1 is still true without the assumption on the Teichmüller metric when $3g+n=5$.

As stated above Farb and Weinberger in [13] proved the existence of complete Riemannian metrics of uniformly positive scalar curvature on the moduli space. Actually they also showed that these metrics are not quasi-isometric to the Teichmüller metric. Motivated by Chang’s result in [6] on certain locally symmetric spaces, they conjecture in

[9] (see Conjecture 4.6 in [9]) that *any finite cover M of the moduli space \mathbb{M}_g of S_g does not admit a finite volume Riemannian metric of (uniformly bounded) positive scalar curvature in the quasi-isometry class of the Teichmüller metric.* Instead of using Theorem 5.2 of Gromov–Lawson in the proof of Theorem 1.1, we apply a theorem of Yu in [43] to give a short proof of the following result, which, in particular, gives a proof of this conjecture of Farb–Weinberger.

Theorem 1.3. *Let S_g be a closed surface of genus g with $g \geq 2$. Then any cover M of the moduli space \mathbb{M}_g of S_g does not admit a complete Riemannian metric of uniformly positive scalar curvature in the quasi-isometry class of the Teichmüller metric.*

There are no conditions on finite cover and finite volume in Theorem 1.3, compared to the Farb–Weinberger conjecture. We remark here that Farb and Weinberger have a different approach to their conjecture by using methods from Chang’s thesis [6] together with a theorem of Farb–Masur in [11] on the asymptotic cone of the moduli space, which is different from the method in this article. We thank Prof. Farb for sharing their information.

1.1. Plan of the paper. In Section 2, we give some necessary preliminaries and notations for surface theory. In Section 3, we review some recent developments on the geometry of Teichmüller space which will be served as bridges to prove Theorem 1.1. In Section 4, we will show that any complete Riemannian metric on the moduli space of surfaces with nonnegative scalar curvature can be deformed an equivalent Riemannian metric of positive scalar curvature. Theorem 1.1 will be proved in Section 5. In Section 6, we will discuss Theorem 1.3 in details. A related open problem will be discussed in Section 7.

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2. Notations and preliminaries

2.1. Surfaces. Let S_g be a closed Riemann surface of genus g with $g \geq 2$, and M_{-1} denote the space of Riemannian metrics on S_g with constant curvature -1 , and $X = (S_g, \sigma|dz|^2)$ be an element in M_{-1} . The group Diff_0 of diffeomorphisms of S_g isotopic to the identity, acts

on M_{-1} by pull-backs. The Teichmüller space $\text{Teich}(S_g)$ of S_g is defined by the quotient space

$$\text{Teich}(S_g) = M_{-1} / \text{Diff}_0.$$

Let Diff_+ be the group of orientation-preserving diffeomorphisms of S_g . The mapping class group $\text{Mod}(S_g)$ is defined as

$$\text{Mod}(S_g) = \text{Diff}_+ / \text{Diff}_0.$$

The moduli space \mathbb{M}_g of S_g is defined by the quotient space

$$\mathbb{M}_g = \text{Teich}(S_g) / \text{Mod}(S_g).$$

The Teichmüller space has a natural complex structure, and its holomorphic cotangent space $T_X^* \text{Teich}(S_g)$ is identified with the *quadratic differentials*

$$\text{QD}(X) = \{\phi(z)dz^2\},$$

while its holomorphic tangent space is identified with the *harmonic Beltrami differentials*

$$\text{HBD}(X) = \left\{ \frac{\overline{\phi(z)} d\bar{z}}{\sigma(z) dz} \right\}.$$

2.2. Mapping class group. The mapping class group $\text{Mod}(S_g)$ is a finitely generated discrete group which acts properly on the Teichmüller space. One special set of generators of $\text{Mod}(S_g)$ is the Dehn-twists along simple closed curves, which play an important role in studying $\text{Mod}(S_g)$. Let α be a nontrivial simple closed curve on S_g and τ_α be the Dehn-twist along α . The following lemma will be applied later.

Lemma 2.1. *Let α, β be two simple closed curves on M such that the geometric intersection points $i(\alpha, \beta) \geq 2$. Then, for any $n, m \in \mathbb{Z}^+$, the group $\langle \tau_\alpha^n, \tau_\beta^m \rangle$ is a free group of rank 2.*

Proof. One can check chapter 3 in [12] for details. q.e.d.

2.3. The Teichmüller metric and Weil–Peterson metric. Recall that the *Teichmüller metric* $\|\cdot\|_T$ on $\text{Teich}(S_g)$ is defined as

$$\left\| \frac{\overline{\phi(z)}}{\sigma(z)} \right\|_T := \sup_{\psi dz^2 \in \text{QD}(X), \int_X |\psi|=1} \text{Re} \int_X \frac{\overline{\phi(z)}}{\sigma(z)} \cdot \psi(z) \frac{dz \wedge d\bar{z}}{-2i},$$

where $\frac{dz \wedge d\bar{z}}{-2i}$ is the area form of the hyperbolic surface X .

The induced path metric of the above metric, denoted by dist_T , on $\text{Teich}(S_g)$ can also be characterized as follows; let $p_1, p_2 \in \text{Teich}(S_g)$, then

$$\text{dist}_T(p_1, p_2) = \frac{1}{2} \log K,$$

where $K \geq 1$ is the least number such that there is a K -quasiconformal mapping between the hyperbolic surfaces p_1 and p_2 . The Teichmüller

metric is not Riemannian but Finsler. The following fundamental theorem on the Teichmüller metric will be used later.

Theorem 2.2 (Teichmüller).

- (1). The Teichmüller space $(\text{Teich}(S_g), \|\cdot\|_T)$ is complete.
- (2). The Teichmüller space $(\text{Teich}(S_g), \|\cdot\|_T)$ is uniquely geodesic, i.e., for any two points $p_1, p_2 \in \text{Teich}(S_g)$ there exists a unique geodesic $c : [0, 1] \rightarrow (\text{Teich}(S_g), \|\cdot\|_T)$ such that $c(0) = p_1$ and $c(1) = p_2$.

A direct corollary is

Proposition 2.3. Any geodesic ball of finite radius in $(\text{Teich}(S_g), \|\cdot\|_T)$ is contractible.

Proof. Let $p \in (\text{Teich}(S_g), \|\cdot\|_T)$ and $r > 0$. Consider the geodesic ball

$$B(p; r) := \{q; \text{dist}_T(p, q) \leq r\} \subset (\text{Teich}(S_g), \|\cdot\|_T).$$

For any $z \in B(p; r)$, by Theorem 2.2 we know that there exists a unique geodesic $c_z : [0, \text{dist}_T(p, z)] \rightarrow B(p; r)$ such that $c_z(0) = p$ and $c_z(\text{dist}_T(p, z)) = z$. Here we use the arc-length parameter for c . Then we consider the following map

$$\begin{aligned} H : B(p; r) \times [0, 1] &\rightarrow B(p; r), \\ (z, t) &\mapsto c_z(t \cdot \text{dist}_T(p, z)). \end{aligned}$$

Theorem 2.2 tells us that H is well-defined and continuous.

It is clear that

$$H(z, 0) = p \quad \text{and} \quad H(z, 1) = z \quad \forall z \in B(p; r).$$

That is, the geodesic ball $B(p; r)$ is contractible. q.e.d.

For more details on Teichmüller geometry, one can refer to the book [18] and the recent survey [25] for more details.

The Weil–Petersson metric ds_{WP}^2 is the Hermitian metric on T_g arising from the Petersson scalar product

$$\langle \varphi, \psi \rangle_{ds_{WP}^2} = \int_X \frac{\varphi(z) \cdot \overline{\psi(z)} dz \wedge d\bar{z}}{\sigma(z) \cdot -2\mathbf{i}},$$

via duality. The Weil–Petersson metric is Kähler ([1]), incomplete ([7, 35]) and has negative sectional curvature ([34, 36]). One can refer to Wolpert’s recent book [39] for the progress on the study of the Weil–Petersson metric.

Both the Teichmüller metric and the Weil–Petersson metric are $\text{Mod}(S_g)$ -invariant.

Let $\|\cdot\|_1$ and $\|\cdot\|_2$ be any two Finsler (including Riemannian) metrics on $\text{Teich}(S_g)$. If there exists a constant $k > 0$ such that for any $p \in \text{Teich}(S_g)$ and $v \in T_p \text{Teich}(S_g)$ we have

$$\|v\|_1 \geq k \cdot \|v\|_2,$$

where $\|v\|_*$ is the norm of the tangent vector v with respect to the metric $\|\cdot\|_*$. We write it as

$$\|\cdot\|_1 \succ \|\cdot\|_2.$$

We call the two metrics $\|\cdot\|_1$ and $\|\cdot\|_2$ are *bi-Lipschitz* (or *equivalent*) if

$$\|\cdot\|_1 \succ \|\cdot\|_2 \quad \text{and} \quad \|\cdot\|_2 \succ \|\cdot\|_1,$$

which is denoted by

$$\|\cdot\|_1 \asymp \|\cdot\|_2.$$

It is not hard to see that the Cauchy–Schwarz inequality and the Gauss–Bonnet formula give that

$$\|\cdot\|_T \succ \|\cdot\|_{ds_{WP}^2}.$$

However, since the Weil–Petersson metric is incomplete and the Teichmüller metric is complete, we have

$$\|\cdot\|_{ds_{WP}^2} \not\asymp \|\cdot\|_T.$$

3. Universal properties of Riemannian metrics equivalent to $\|\cdot\|_T$

It is shown in [21, 22, 27] that the asymptotic Poincaré metric, the induced Bergman metric, Kähler–Einstein metric, the McMullen metric, the Ricci metric, and the perturbed Ricci metric are all Kähler and equivalent to the Teichmüller metric. For any metric ds^2 in the convex hull of all these metrics we have $\|\cdot\|_{ds^2} \asymp \|\cdot\|_T$. We are going to apply one of these metrics as bridges to prove Theorem 1.1. Actually any one of these six metrics works.

3.1. Kähler metrics on \mathbb{M}_g . In this subsection we briefly review some properties of the following two Kähler metrics \mathbb{M}_g : the Ricci metric and the perturbed Ricci metric. They will be applied to prove Theorem 1.1.

3.1.1. The Ricci metric and the perturbed Ricci metric. In [34, 36] it is shown that the Weil–Petersson metric has negative sectional curvature. The negative Ricci curvature tensor defines a new metric ds_τ^2 on \mathbb{M}_g , which is called the *Ricci metric*. Trapani in [33] proved ds_τ^2 is a complete Kähler metric. In [21] Liu–Sun–Yau perturbed the Ricci metric with the Weil–Petersson metric to give new metrics on \mathbb{M}_g which are called the *perturbed Ricci metrics*, denoted by ds_{LSY}^2 . More precisely, let ω_τ be the Kähler form of the Ricci metric, for any constant $C > 0$, the Kähler form of the perturbed Ricci metric is

$$\omega_{LSY} = \omega_\tau + C \cdot \omega_{WP}.$$

Motivated by the results of McMullen in [27], K. Liu, X. Sun and S. T. Yau in [21] showed that

Theorem 3.1 (Liu–Sun–Yau). *On the moduli space \mathbb{M}_g , both $(\mathbb{M}_g, ds_\tau^2)$ and $(\mathbb{M}_g, ds_{LSY}^2)$ satisfy*

(1). *They have bounded sectional curvatures and finite volumes.*

(2). $\|\cdot\|_{ds_\tau^2} \asymp \|\cdot\|_{ds_{LSY}^2} \asymp \|\cdot\|_T$.

(3). *There exists a constant $\epsilon_0 > 0$ such that the injectivity radii of the universal covers satisfy that*

$$\text{inj}(\text{Teich}(S_g), ds_\tau^2) \geq \epsilon_0 > 0,$$

and

$$\text{inj}(\text{Teich}(S_g), ds_{LSY}^2) \geq \epsilon_0 > 0.$$

3.2. Asymptotic dimension. Gromov in [16] introduced the notion of *asymptotic dimension* as a large-scale analog of the covering dimension. More precisely, a metric space X has asymptotic dimension $\text{asydim}(X) \leq n$ if for every $R > 0$ there is a cover of X by uniformly bounded sets such that every metric R -ball intersects at most $n + 1$ of sets in the cover. One can refer to Theorem 19 in [3] for some other equivalent definitions of the asymptotic dimension. By using Minsky’s product theorem in [28] for the thin part of the Teichmüller space $(\text{Teich}(S_g), \|\cdot\|_T)$, recently M. Bestvina, K. Bromberg and K. Fujiwara in [2] proved the following result which is crucial for this paper.

Theorem 3.2 (Bestvina-Bromberg-Fujiwara). *Let S_g be a closed surface of genus g with $g \geq 1$. Then the Teichmüller space, endowed with the Teichmüller metric, satisfies*

$$\text{asydim}((\text{Teich}(S_g), \|\cdot\|_T)) < \infty.$$

From the definition of the asymptotic dimension it is not hard to see that the asymptotic dimension is a quasi-isometric invariance. For more details, one can see the remark on page 21 of [16] or Proposition 22 in [3].

Theorem 3.3. *Let ds^2 be a Riemannian metric on $\text{Teich}(S_g)$ with $\|\cdot\|_{ds^2} \asymp \|\cdot\|_T$. Then,*

$$(3.1) \quad \text{asydim}((\text{Teich}(S_g), ds^2)) < \infty.$$

In particular, for the perturbed Ricci metric d_{LSY}^2 we have

$$(3.2) \quad \text{asydim}((\text{Teich}(S_g), d_{LSY}^2)) < \infty.$$

Proof. Since the asymptotic dimension is a quasi-isometry invariant of $\text{Teich}(S_g)$, it is clear that inequality (3.1) follows from Theorem 3.2, and inequality (3.2) follows from Part (2) of Theorem 3.1 and inequality (3.1). q.e.d.

4. Deformation to positive scalar curvature

As stated in the introduction Farb and Weinberger in [13] showed that the set of complete Riemannian metrics of positive scalar curvatures on the moduli space \mathbb{M}_g is not empty. In this section, we will show that any complete Riemannian metric of nonnegative scalar curvature on a manifold which finitely covers \mathbb{M}_g can be deformed to a new complete Riemannian metric of positive scalar curvature which is equivalent to the base metric. This will be applied to prove Theorem 1.1.

In [19] Kazdan showed that any Riemannian metric of zero scalar curvature on a manifold, whose dimension is greater than or equal to 3, can be deformed to a new metric of positive scalar curvature which is equivalent to the base metric provided that the based metric is not Ricci flat. Actually his method also works when the scalar curvature is nonnegative. This argument will be used in this section to prove Theorem 4.1. One can see [19] for more details.

Let M be a finite cover of the moduli space \mathbb{M}_g and ds^2 be a complete Riemannian metric on M . Since M may be an orbifold, the Riemannian metric ds^2 on M means a Riemannian metric on the Teichmüller space $\text{Teich}(S_g)$ on which the orbifold fundamental group $\widetilde{\pi}_1(M)$ acts on $(\text{Teich}(S_g), ds^2)$ by isometries. It is known that the mapping class group $\text{Mod}(S_g)$ contains torsion-free subgroups of finite indices (see [12]). We can pass to a finite cover \overline{M} of M such that \overline{M} is a manifold. It is clear that the fundamental group $\pi_1(\overline{M})$ is a torsion-free subgroup of $\text{Mod}(S_g)$ of finite index.

In this section, we prove the following result.

Theorem 4.1. *Let S_g be a closed surface of genus g with $g \geq 2$ and M be a finite cover of the moduli space \mathbb{M}_g of S_g such that M is a manifold. Then for any complete Riemannian metric ds^2 of nonnegative scalar curvature on M , there exists a new metric ds_1^2 on M such that*

- (1). *The scalar curvature $\text{Sca}_{(M, ds_1^2)} > 0$ on (M, ds_1^2) .*
- (2). $\|\cdot\|_{ds_1^2} \asymp \|\cdot\|_{ds^2}$.

Before we go to prove the theorem above. First let us provide the following fact in the moduli space.

Lemma 4.2. *Let S_g be a closed surface of genus g with $g \geq 2$ and M be a finite cover of the moduli space \mathbb{M}_g of S_g . Then, for any complete Riemannian metric ds^2 on M , there exists a point $p_0 \in M$ such that the Ricci tensor at p_0 satisfies*

$$\text{Ric}_{(M, ds^2)}(p_0) \neq 0.$$

Proof. The following argument is standard. One may see [17] for more applications of this argument.

We argue by contradiction. Suppose not. That is, there exists a complete Riemannian metric ds^2 on M such that for all $p \in M$ the

Ricci tensor

$$\text{Ric}_{(M, ds^2)}(p) = 0.$$

As described above, if necessary we pass to a finite cover \overline{M} such that \overline{M} is a manifold. We lift the metric ds^2 onto \overline{M} , still denoted by ds^2 . Then,

$$(4.1) \quad \text{Ric}_{(\overline{M}, ds^2)}(p) = 0.$$

Let α, β be two nontrivial simple closed curves on S_g with the geometric intersection $i(\alpha, \beta) \geq 2$, and τ_α, τ_β be the Dehn-twists along α and β respectively. Since the fundamental group $\pi_1(\overline{M})$ is a subgroup of $\text{Mod}(S_g)$ of finite index, there exists $n_0, m_0 \in \mathbb{Z}^+$ such that $\tau_\alpha^{n_0}, \tau_\beta^{m_0} \in \pi_1(\overline{M})$. From Lemma 2.1 we know that the group

$$(4.2) \quad \langle \tau_\alpha^{n_0}, \tau_\beta^{m_0} \rangle \cong \mathbb{F}_2,$$

where \mathbb{F}_2 is a free group of rank 2. For sure $\langle \tau_\alpha^{n_0}, \tau_\beta^{m_0} \rangle$ acts on the universal cover $(\text{Teich}(S_g), ds^2)$ of (\overline{M}, ds^2) by isometries.

We endow $\langle \tau_\alpha^{n_0}, \tau_\beta^{m_0} \rangle$ with the word metric $dist_{word}$ w.r.t the generator set $\{\tau_\alpha^{n_0}, \tau_\alpha^{-n_0}, \tau_\beta^{m_0}, \tau_\beta^{-m_0}\}$. Let e be the unit in $\langle \tau_\alpha^{n_0}, \tau_\beta^{m_0} \rangle$. For any $r > 0$ we set

$$B(e, r) := \{\phi \in \langle \tau_\alpha^{n_0}, \tau_\beta^{m_0} \rangle : dist_{word}(\phi, e) \leq r\}.$$

Let $q_0 \in (\text{Teich}(S_g), ds^2)$ and $dist_{ds^2}$ be the induced path metric of $(\text{Teich}(S_g), ds^2)$ on $\text{Teich}(S_g)$. We define

$$C := \max \{dist_{ds^2}(\tau_\alpha^{n_0} \circ q_0, q_0), dist_{ds^2}(\tau_\beta^{m_0} \circ q_0, q_0)\} > 0.$$

The triangle inequality leads to

$$(4.3) \quad dist_{ds^2}(\phi \circ q_0, q_0) \leq r \cdot C, \quad \forall \phi \in B(e, r).$$

Since $\langle \tau_\alpha^{n_0}, \tau_\beta^{m_0} \rangle$ acts freely on the universal cover $(\text{Teich}(S_g), ds^2)$ of (\overline{M}, ds^2) , there exists a number $\epsilon_0 > 0$ such that

$$dist_{ds^2}(\gamma \circ q_0, q_0) > 2\epsilon_0, \quad \forall e \neq \gamma \in \langle \tau_\alpha^{n_0}, \tau_\beta^{m_0} \rangle,$$

which implies

$$(4.4) \quad \gamma_1 \circ B(q_0; \epsilon_0) \cap \gamma_2 \circ B(q_0; \epsilon_0) = \emptyset, \quad \forall \gamma_1 \neq \gamma_2 \in \langle \tau_\alpha^{n_0}, \tau_\beta^{m_0} \rangle,$$

where $B(q_0; \epsilon_0) := \{p \in (\text{Teich}(S_g), ds^2); dist_{ds^2}(p, q_0) \leq \epsilon_0\}$.

From inequality (4.3) and the triangle inequality we know that, for all $r > 0$,

$$(4.5) \quad \bigcup_{\gamma \in B(e, r)} \gamma \circ B(q_0; \epsilon_0) \subset B(q_0; r \cdot C + \epsilon_0).$$

Equation (4.4) tells that the geodesic balls $\{\gamma \circ B(q_0; \epsilon_0)\}_{\gamma \in B(e,r)}$ are pairwise disjoint. Thus, by taking the volume, equations (4.4) and (4.5) lead to

$$(4.6) \quad \sum_{\gamma \in B(e,r)} \text{Vol}(\gamma \circ B(q_0, \epsilon_0)) = \text{Vol}\left(\bigcup_{\gamma \in B(e,r)} \gamma \circ B(q_0; \epsilon_0)\right) \leq \text{Vol}(B(q_0; r \cdot C + \epsilon_0)).$$

Since the group $\langle \tau_\alpha^{n_0}, \tau_\beta^{m_0} \rangle$ acts on $(\text{Teich}(S_g), ds^2)$ by isometries, $\text{Vol}(\gamma \circ B(q_0, \epsilon_0)) = \text{Vol}(B(q_0; \epsilon_0))$ for all $\gamma \in \langle \tau_\alpha^{n_0}, \tau_\beta^{m_0} \rangle$. From inequality (4.6) we have

$$(4.7) \quad \#B(e, r) \cdot \text{Vol}(B(q_0, \epsilon_0)) \leq \text{Vol}(B(q_0, r \cdot C + \epsilon_0)).$$

Rewrite it as

$$(4.8) \quad \#B(e, r) \leq \frac{\text{Vol}(B(q_0; r \cdot C + \epsilon_0))}{\text{Vol}(B(q_0; \epsilon_0))}.$$

Since $(\text{Teich}(S_g), ds^2)$ is complete, from equation (4.1) and the Gromov–Bishop volume comparison inequality (see [17]), we have, for all $r > 0$,

$$(4.9) \quad \#B(e, r) \leq \frac{\text{Vol}(B(q_0; r \cdot C + \epsilon_0))}{\text{Vol}(B(q_0; \epsilon_0))}$$

$$(4.10) \quad \leq \frac{(r \cdot C + \epsilon_0)^{6g-6}}{\epsilon_0^{6g-6}}.$$

Which, in particular, implies that the group $\langle \tau_\alpha^{n_0}, \tau_\beta^{m_0} \rangle \subset \text{Mod}(S_g)$ has polynomial growth, which contradicts equation (4.2) since the free group \mathbb{F}_2 has exponential growth. q.e.d.

Let M be a finite cover of \mathbb{M}_g which is a manifold and ds^2 be a complete Riemannian metric on M which has nonnegative scalar curvature. Since the metric is smooth, for any $p_0 \in M$ there exists a constant $r_1 > 0$ such that the geodesic ball $B(p_0; r_1)$ centered at p_0 of radius r_1 has smooth boundary $\partial B(p_0; r_1)$ and smooth outer normal derivative $\frac{\partial}{\partial \nu}$ on $\partial B(p_0, r_1)$. It suffices to choose r_1 to be less than the injectivity radius of M at p_0 .

We let Sca_{ds^2} be the scalar curvature of (M, ds^2) and Δ_{ds^2} be the Laplace operator of (M, ds^2) . Consider the operator

$$(4.11) \quad \mathcal{L}_{ds^2}(u) := -\frac{2(m-1)}{m/2-1} \Delta_{ds^2} u + \text{Sca}_{ds^2} \cdot u,$$

where $u \in C^\infty((M, ds^2), \mathbb{R})$ and $m = 6g - 6$ is the real dimension of M .

For $0 < r < \text{inj}(p_0)$ where $\text{inj}(p_0)$ is the injectivity radius of (M, ds^2) at p_0 . Let $\mu_1(B(p_0; r))$ be the lowest eigenvalue of \mathcal{L} with Neumann

boundary conditions $\frac{\partial u}{\partial \nu} = 0$ on $\partial B(p_0; r)$. It is well-known that

$$(4.12) \quad \mu_1(B(p_0; r)) = \inf_{v \in C^\infty((M, ds^2), \mathbb{R})} \frac{\int_{B(p_0; r)} (|\nabla v|_{ds^2}^2 + \text{Sca}_{ds^2} \cdot v^2) \, d\text{Vol}}{\int_{B(p_0; r)} v^2 \, d\text{Vol}}.$$

The following result is Theorem A in [19] which is crucial in this section.

Theorem 4.3 (Kazdan). *Assume that $\mu_1(B(p_0; r)) > 0$. Then there is a solution $u > 0$ on (M, ds^2) of $\mathcal{L}u > 0$; in fact, there exist two constants $C_1, C_2 > 0$ such that*

$$0 < C_1 \leq u(p) \leq C_2, \quad \forall p \in (M, ds^2).$$

Assume that $u > 0$ on (M, ds^2) . We define the conformal metric

$$(4.13) \quad ds_u^2 := u^{\frac{2}{3g-4}} \cdot ds^2.$$

Direct computation shows that the scalar curvature $\text{Sca}_{ds_u^2}$ of ds_u^2 is given by the formula

$$(4.14) \quad \mathcal{L}_{ds^2} u = -\frac{2(6g-7)}{3g-4} \Delta_{ds^2} u + \text{Sca}_{ds^2} \cdot u$$

$$(4.15) \quad = \text{Sca}_{ds_u^2} \cdot u^{\frac{3g-2}{3g-4}}.$$

Thus,

$$(4.16) \quad \text{Sca}_{ds_u^2} = \mathcal{L}_{ds^2} u \cdot u^{-\frac{3g-2}{3g-4}}.$$

Proof of Theorem 4.1. We follow the argument as in [19].

First from Lemma 4.2 we know that there exists a point $p_0 \in M$ such that the Ricci tensor

$$(4.17) \quad \text{Ric}_{(M, ds^2)}(p_0) \neq 0.$$

We let r_1 be a constant with $0 < r_1 < \text{inj}(p_0)$. Pick a function $\eta \in C_0^\infty(B(p_0, r_1); \mathbb{R}^{\geq 0})$ with $\eta(p_0) > 0$ and consider a family of metrics

$$ds_t^2 := ds^2 - t \cdot \eta \cdot \text{Ric}_{(M, ds^2)},$$

with scalar curvature $\text{Sca}_{(M, ds_t^2)}$ and the corresponding operator $\mathcal{L}_{ds_t^2}$ defined in equation (4.11) with lowest Neumann eigenvalue $\mu_1(B(p_0, r_1), t)$. The first variation formula (see [19]) gives that

$$(4.18) \quad \frac{d}{dt} \mu_1(B(p_0, r_1), t)|_{t=0} = \frac{\eta \langle \text{Ric}, \text{Ric} \rangle}{\text{Vol}(B(p_0, r_1))},$$

where $\langle \cdot \rangle$ is the standard inner product for tensors in the ds^2 metric.

Since $\eta(p_0) > 0$, equations (4.17) and (4.18) give that

$$(4.19) \quad \frac{d}{dt} \mu_1(B(p_0, r_1), t)|_{t=0} > 0.$$

Since $\text{Sca}_{(M, ds^2)} \geq 0$, equation (4.12) gives that

$$\mu_1(B(p_0, r_1), 0) = \mu_1(B(p_0, r_1)) \geq 0.$$

Thus, from inequality (4.19) we know that for small enough $t_0 > 0$,

$$(4.20) \quad \mu_1(B(p_0, r_1), t_0) > 0.$$

It is clear that

$$(4.21) \quad \|\cdot\|_{ds_{t_0}^2} \asymp \|\cdot\|_{ds^2}.$$

Because of inequality (4.20) we apply Theorem 4.3 to $(M, ds_{t_0}^2)$. Thus, there is a smooth function u on $(M, ds_{t_0}^2)$ such that

$$(4.22) \quad \mathcal{L}_{ds_{t_0}^2} u(p) > 0 \quad \text{and} \quad u(p) > 0, \quad \forall p \in (M, ds_{t_0}^2).$$

And there exist two constants $C_1, C_2 > 0$ such that

$$(4.23) \quad 0 < C_1 \leq u(p) \leq C_2, \quad \forall p \in (M, ds_{t_0}^2).$$

Then we define the new metric as

$$(4.24) \quad ds_1^2 := u^{\frac{2}{3g-4}} \cdot ds_{t_0}^2.$$

It is clear that Part (1) follows from equations (4.16) and (4.22). And Part (2) follows from equations (4.21), (4.24) and inequality (4.23).
 q.e.d.

5. Proof of Theorem 1.1

Before we prove Theorem 1.1, let us make some preparation and fix the notations.

Let $(M_1, ds_1^2), (M_2, ds_2^2)$ be two Finsler manifolds of the same dimensions, and $f : (M_1, ds_1^2) \rightarrow (M_2, ds_2^2)$ be a smooth map. For $C > 0$, we call that f is a C -contraction if for any $p \in M_1$,

$$(5.1) \quad \|f_*(v)\|_{ds_2^2} \leq C \cdot \|v\|_{ds_1^2}, \quad \forall v \in T_p M_1.$$

Recall that the degree $\text{deg}(f)$ of f is defined as

$$(5.2) \quad \text{deg}(f) = \sum_{q \in f^{-1}(p)} \text{sign}(\det f_*(q)),$$

where p is a regular value of f .

Definition 5.1. We call an n -dimensional Riemannian manifold X is *hyperspherical* if for every $\epsilon > 0$, there exists an ϵ -contraction map $f_\epsilon : X \rightarrow \mathbb{S}^n$ of nonzero degree onto the standard unit n -sphere such that f_ϵ is a constant outside a compact subset in X .

The following result was proved by Gromov and Lawson in [15].

Theorem 5.2 (Gromov–Lawson). *A complete aspherical Riemannian manifold X cannot have positive scalar curvature if the universal cover \tilde{X} of X is hyperspherical.*

Proof. See the proof of Theorem 6.12 in [15]. q.e.d.

The classical Cartan–Hardamard theorem implies that any complete simply connected Riemannian manifold of nonpositive sectional curvature is hyperspherical. A direct corollary of Theorem 5.2 is

Theorem 5.3 (Gromov–Lawson). *Let (X, ds_1^2) be a complete Riemannian manifold of nonpositive sectional curvature. Then for any Riemannian metric ds_2^2 on X with $\|\cdot\|_{ds_2^2} \succ \|\cdot\|_{ds_1^2}$, the scalar curvature of (X, ds_2^2) cannot be positive everywhere on X .*

Proof. One may see [15] or [29] for the details. q.e.d.

Now let us state the theorem (Theorem 1.1) we will prove in this section.

Theorem 5.4. *Let S_g be a closed surface of genus g with $g \geq 2$ and M be a finite cover of the moduli space \mathbb{M}_g of S_g . Then for any Riemannian metric ds^2 on M with $\|\cdot\|_{ds^2} \succ \|\cdot\|_T$, we have*

$$\inf_{p \in (M, ds^2)} \text{Sca}(p) < 0.$$

Recall that in the proof of Theorem 5.3 in [15], the nonpositivity of the sectional curvature is crucial because in this case the inverse of the exponential map is a contraction. In the setting of Theorem 5.4, although the inverse of the exponential map is well-defined by Theorem 2.2, it is far from a contraction. In fact, Masur in [24] showed that there exists two different geodesics in $(\text{Teich}(S_g), \|\cdot\|_T)$ starting from the same point such that they have bounded Hausdorff distance. In particular, $(\text{Teich}(S_g), \|\cdot\|_T)$ is not nonpositively curved in the sense of metric spaces. Hence, the argument in [15] cannot be directly applied to show Theorem 5.4. Furthermore, the following question is *unknown* as far as we know.

Question 1. Is $(\text{Teich}(S_g), \|\cdot\|_T)$ hyperspherical?

We are going to steer clear of Question 1 to prove Theorem 5.4. It is very *interesting* to know the answer to Question 1. We will discuss it from different viewpoints in the last section.

Before we prove Theorem 5.4, we first provide two important properties for the Teichmüller space $(\text{Teich}(S_g), ds^2)$ where $\|\cdot\|_{ds^2} \asymp \|\cdot\|_T$, which will be applied later.

Definition 5.5. Let X be a metric space. We call X is *uniformly contractible* if there is a function $f : (0, \infty) \rightarrow (0, \infty)$ so that for each $x \in X$ and $r > 0$, the ball $B(x; r)$ of radius r centered at x is contractible in the concentric ball $B(x; f(r))$ of radius $f(r)$.

Proposition 5.6. *Let ds^2 be a Riemannian metric on $\text{Teich}(S_g)$ such that $\|\cdot\|_{ds^2} \asymp \|\cdot\|_T$. Then $(\text{Teich}(S_g), ds^2)$ is uniformly contractible.*

In particular, the Teichmüller space endowed with the perturbed Ricci metric $(\text{Teich}(S_g), d_{LSY}^2)$ is uniformly contractible.

Proof. From Theorem 3.1 we know that $\|\cdot\|_{ds_{LSY}^2} \asymp \|\cdot\|_T$. It suffices to show that $(\text{Teich}(S_g), ds^2)$ is uniformly contractible provided that $\|\cdot\|_{ds^2} \asymp \|\cdot\|_T$.

Since $\|\cdot\|_{ds^2} \asymp \|\cdot\|_T$, there exist two constants $k_1, k_2 > 0$ such that

$$k_1 \cdot \|\cdot\|_T \leq \|\cdot\|_{ds^2} \leq k_2 \cdot \|\cdot\|_T.$$

In particular, we have, for each $p \in \text{Teich}(S_g)$ and $r > 0$

$$(5.3) \quad B_{ds^2}(p; r) \subset B_{\|\cdot\|_T}(p; \frac{r}{k_1}) \subset B_{ds^2}(p; \frac{k_2}{k_1} \cdot r),$$

where $B_{ds^2}(p; r) := \{q \in \text{Teich}(S_g); \text{dist}_{ds^2}(p, q) \leq r\}$ and $B_{\|\cdot\|_T}(p; r) := \{q \in \text{Teich}(S_g); \text{dist}_T(p, q) \leq r\}$.

Proposition 2.3 tells that the Teichmüller ball $B_{\|\cdot\|_T}(p; r)$ is contractible for all $r > 0$ and $p \in \text{Teich}(S_g)$. Thus, equation (5.3) tells that $B_{ds^2}(p; r)$ is contractible in $B_{ds^2}(p; \frac{k_2}{k_1} \cdot r)$. Therefore, the conclusion follows by choosing

$$f(r) = \frac{k_2}{k_1} \cdot r. \qquad \text{q.e.d.}$$

Definition 5.7. Let X be a metric space. We call that X has *bounded geometry in the sense of coarse geometry* if for every $\epsilon > 0$ and every $r > 0$, there exists an integer $n(r, \epsilon) > 0$ such that for each $x \in X$ every ball $B(x; r)$ contains at most $n(r, \epsilon)$ ϵ -disjoint points. Where ϵ -disjoint means that any two different points are at at least ϵ distance from each other.

Proposition 5.8. $(\text{Teich}(S_g), d_{LSY}^2)$ have bounded geometry in the sense of coarse geometry.

Proof. Let $\epsilon_0 > 0$ be the constant which is the lower bound for the injectivity radius of $(\text{Teich}(S_g), ds_{LSY}^2)$ in Theorem 3.1. For every $r > 0$ and every $\epsilon > 0$. Let $p \in \text{Teich}(S_g)$ and $B(p; r) := \{q \in \text{Teich}(S_g); \text{dist}_{ds_{LSY}^2}(p, q) \leq r\}$ be the geodesic ball of radius r centered at p . Assume $K = \{x_i\}_{i=1}^k$ be an arbitrary ϵ - disjoint points in $B_{ds_{LSY}^2}(p; r)$. That is

$$(5.4) \quad \text{dist}_{ds_{LSY}^2}(x_i, x_j) \geq \epsilon, \quad \forall 1 \leq i \neq j \leq k.$$

Let $\epsilon_1 = \min\{\frac{\epsilon}{4}, \epsilon_0\}$. First the triangle inequality tells that

$$(5.5) \quad \bigcup_{i=1}^k B(x_i; \epsilon_1) \subset B(p, r + \epsilon_1) \subset B(p, r + \epsilon_0).$$

By our assumptions that $\epsilon_1 \leq \frac{\epsilon}{4}$, inequality (5.4) gives that

$$(5.6) \quad B(x_i; \epsilon_1) \cap B(x_j; \epsilon_1) = \emptyset, \quad \forall 1 \leq i \neq j \leq k.$$

From equations (5.5) and (5.6) we have

$$(5.7) \quad \sum_{i=1}^k \text{Vol}(B(x_i; \epsilon_1)) \leq \text{Vol}(B(p, r + \epsilon_0)).$$

From Theorem 3.1 there exists a lower bound for the sectional curvatures of $(\text{Teich}(S_g), ds_{LSY}^2)$, by using the Gromov–Bishop volume comparison inequality, in particular, we have that there exists a constant $C(r, \epsilon_0, g) > 0$ depending on r, ϵ_0 and the genus g such that the volume

$$(5.8) \quad \text{Vol}(B(p, r + \epsilon_0)) \leq C(r, \epsilon_0, g).$$

On the other hand, from Theorem 3.1 we know that the sectional curvatures of $(\text{Teich}(S_g), ds_{LSY}^2)$ have an upper bound. Since

$$\epsilon_1 \leq \epsilon_0 = \text{inj}(\text{Teich}(S_g), ds_{LSY}^2).$$

Elementary Riemannian geometry tells that there exists a constant $D(\epsilon_1, g) > 0$ depending on ϵ_1 and the genus g such that the volume

$$(5.9) \quad \text{Vol}(B(x_i, \epsilon_1)) \geq D(\epsilon_1, g) > 0, \quad \forall 1 \leq i \leq k.$$

Inequalities (5.7), (5.8) and (5.9) give that

$$(5.10) \quad k \leq \frac{C(r, \epsilon_0, g)}{D(\epsilon_1, g)}.$$

Then the conclusion follows by choosing

$$n(r, \epsilon) = \frac{C(r, \epsilon_0, g)}{D(\epsilon_1, g)}. \quad \text{q.e.d.}$$

The following result of A. N. Dranishnikov in [8] will be applied to prove Theorem 5.4.

Theorem 5.9 (Dranishnikov). *Let X be a complete uniformly contractible Riemannian manifold with bounded geometry whose asymptotic dimension is finite, then the product $X \times \mathbb{R}^n$, endowed with the product metric, is hyperspherical for some positive number $n \in \mathbb{Z}$.*

We remark here that the statement of the theorem above is different from Theorem 5 (or Theorem B) in [8] where there is no condition on the bounded geometry. But if one checks the proof of Theorem 5 in [8], Theorem 5 follows from Theorem 4 and Lemma 4 in [8] where Theorem 4 requires that the space X has bounded geometry. We are grateful to Prof. Dranishnikov for the clarification.

Now we are ready to prove Theorem 1.1.

Proof of Theorem 1.1. Let M be a finite cover of the moduli space \mathbb{M}_g of S_g and ds^2 be a Riemannian metric on M such that $\|\cdot\|_{ds^2} \succ \|\cdot\|_T$. That is, there exists a constant $k_1 > 0$ such that

$$(5.11) \quad \|\cdot\|_{ds^2} \geq k_1 \cdot \|\cdot\|_T.$$

We argue by contradiction. Assume that

$$(5.12) \quad \inf_{p \in (M, ds^2)} \text{Sca}(p) \geq 0.$$

If necessary, we pass to a finite cover of M , still denoted by M , such that M is a manifold. From inequality (5.11) we know that (M, ds^2) is complete since the Teichmüller metric is complete. Thus, from Theorem 4.1 we know that there exists a new metric ds_1^2 on M such that

$$(5.13) \quad \text{Sca}(p) > 0, \quad \forall p \in (M, ds_1^2),$$

and

$$(5.14) \quad \|\cdot\|_{ds_1^2} \asymp \|\cdot\|_{ds^2}.$$

Let ds_{LSY}^2 be the perturbed Ricci metric on M . In fact, either the McMullen metric or the Ricci metric also works here. From Proposition 5.6, Proposition 5.8 and Theorem 3.3 we know that the universal cover $(\text{Teich}(S_g), ds_{LSY}^2)$ of (M, ds_{LSY}^2) is uniformly contractible, has bounded geometry and

$$\text{asydim}((\text{Teich}(S_g), ds_{LSY}^2)) < \infty.$$

Hence, one may apply Theorem 5.9 to get a positive integer n such that $(\text{Teich}(S_g), ds_{LSY}^2) \times \mathbb{R}^n$, endowed with the product metric, is hyperspherical.

We pick this integer $n \in \mathbb{Z}^+$ and consider the product space

$$(\text{Teich}(S_g), ds_1^2) \times \mathbb{R}^n,$$

where $(\text{Teich}(S_g), ds_1^2)$ is the universal cover of (M, ds_1^2) .

It is clear that $(\text{Teich}(S_g), ds_1^2) \times \mathbb{R}^n$ is a complete $(6g - 6 + n)$ -dimensional Riemannian manifold, and the scalar curvature of $(\text{Teich}(S_g), ds_1^2) \times \mathbb{R}^n$ satisfies that

$$(5.15) \quad \text{Sca}((p, v)) = \text{Sca}(p) > 0,$$

where (p, v) is arbitrary in $(\text{Teich}(S_g), ds_1^2) \times \mathbb{R}^n$.

Claim. *The complete product manifold $(\text{Teich}(S_g), ds_1^2) \times \mathbb{R}^n$ is hyperspherical.*

Proof of the Claim: First since $\|\cdot\|_{ds_1^2} \asymp \|\cdot\|_{ds^2}$ (see equation (5.14)), the identity map

$$(5.16) \quad i_1 : (\text{Teich}(S_g), ds_1^2) \times \mathbb{R}^n \rightarrow (\text{Teich}(S_g), ds^2) \times \mathbb{R}^n$$

is a c_1 -contraction diffeomorphism for some constant $c_1 \geq 1$.

Since we assume that $\|\cdot\|_{ds^2} \succ \|\cdot\|_T$ (by assumption), the identity map

$$(5.17) \quad i_2 : (\text{Teich}(S_g), ds^2) \times \mathbb{R}^n \rightarrow (\text{Teich}(S_g), \|\cdot\|_T) \times \mathbb{R}^n$$

is a c_2 -contraction diffeomorphism for some constant $c_2 \geq 1$.

From Theorem 3.1 we know that $\|\cdot\|_T \asymp \|\cdot\|_{ds^2_{LSY}}$. Thus, the identity map

$$(5.18) \quad i_3 : (\text{Teich}(S_g), \|\cdot\|_T) \times \mathbb{R}^n \rightarrow (\text{Teich}(S_g), ds^2_{LSY}) \times \mathbb{R}^n$$

is a c_3 -contraction diffeomorphism for some constant $c_3 \geq 1$.

By the choice of $n \in \mathbb{Z}^+$ we know that for every $\epsilon > 0$ there exists an ϵ -contraction map

$$(5.19) \quad f_\epsilon : (\text{Teich}(S_g), ds^2_{LSY}) \times \mathbb{R}^n \rightarrow \mathbb{S}^{6g-6+n},$$

such that f_ϵ is of nonzero degree onto the unit $(6g - 6 + n)$ -sphere and f_ϵ is a constant outside a compact subset in $(\text{Teich}(S_g), ds^2_{LSY}) \times \mathbb{R}^n$.

Consider the following composition map

$$(5.20) \quad \begin{aligned} F_\epsilon : (\text{Teich}(S_g), ds^2_1) \times \mathbb{R}^n &\rightarrow \mathbb{S}^{6g-6+n} \\ (p, v) &\mapsto f_\epsilon \circ i_3 \circ i_2 \circ i_1(p, v), \end{aligned}$$

where (p, v) is arbitrary in $(\text{Teich}(S_g), ds^2_1) \times \mathbb{R}^n$.

Since i_1, i_2 and i_3 are diffeomorphisms and f_ϵ has nonzero degree, F_ϵ also has nonzero degree by the definition.

Since i_1, i_2 and i_3 are diffeomorphisms and f_ϵ is a constant outside a compact subset of $(\text{Teich}(S_g), ds^2_{LSY}) \times \mathbb{R}^n$, a standard argument in set-point topology gives that F_ϵ is also a constant outside a compact subset of $(\text{Teich}(S_g), ds^2_{LSY}) \times \mathbb{R}^n$.

It is clear that F_ϵ is onto because i_1, i_2, i_3 and f_ϵ are onto.

It remains to show that F_ϵ is a contraction. For every point $(p, v) \in (\text{Teich}(S_g), ds^2_1) \times \mathbb{R}^n$ and any tangent vector $W \in T_{(p,v)}((\text{Teich}(S_g), ds^2_1) \times \mathbb{R}^n) = \mathbb{R}^{6g-6+n}$,

$$\begin{aligned} \|(F_\epsilon)_*(W)\| &= \|(f_\epsilon \circ i_3 \circ i_2 \circ i_1)_*(W)\| \\ &\leq \epsilon \cdot \|(i_3 \circ i_2 \circ i_1)_*(W)\| \\ &\leq \epsilon \cdot c_3 \cdot \|(i_2 \circ i_1)_*(W)\| \\ &\leq \epsilon \cdot c_3 \cdot c_2 \cdot \|(i_1)_*(W)\| \\ &\leq \epsilon \cdot c_3 \cdot c_2 \cdot c_1 \cdot \|W\|, \end{aligned}$$

where $\|\cdot\|$ is the standard Euclidean norm in \mathbb{R}^{6g-6+n} .

Since $\epsilon > 0$ is arbitrary and $c_1, c_2, c_3 > 0$, the claim follows. q.e.d.

From the claim above and Theorem 5.2 of Gromov–Lawson we know that the product manifold $(\text{Teich}(S_g), ds^2_1) \times \mathbb{R}^n$ cannot have positive scalar curvature which contradicts inequality (5.15). q.e.d.

Remark 5.10. The following more general statement follows from exactly the same argument as the proof of Theorem 1.1.

Theorem 5.11. *Let S_g be a closed surface of genus g with $g \geq 2$ and M be any (maybe infinite) cover of the moduli space \mathbb{M}_g of S_g such that the orbifold fundamental group of M contains a free subgroup of rank*

≥ 2 . Then for any Riemannian metric ds^2 on M with $\|\cdot\|_{ds^2} \succ \|\cdot\|_T$ we have

$$\inf_{p \in (M, ds^2)} \text{Sca}(p) < 0.$$

6. Proof of Theorem 1.3

We start with the following definition.

Definition 6.1. Let M be a cover, which may be an infinite cover, of the moduli space \mathbb{M}_g and ds^2 be a Riemannian metric on M . We call that ds^2 is *quasi-isometric* to the Teichmüller metric $\|\cdot\|_T$ if there exist two positive constants $L \geq 1$ and $K \geq 0$ such that on the universal cover $(\text{Teich}(S_g), ds^2)$ ($(\text{Teich}(S_g), \|\cdot\|_T)$) of (M, ds^2) ($(M, \|\cdot\|_T)$) respectively, the identity map satisfies

$$L^{-1} \text{dist}_T(p, q) - K \leq \text{dist}_{ds^2}(p, q) \leq L \text{dist}_T(p, q) + K, \quad \forall p, q \in \text{Teich}(S_g).$$

If $K = 0$, ds^2 is equivalent to $\|\cdot\|_T$.

In the quasi-isometry setting, the identity map, defined in equation (5.17) in the proof of Theorem 1.1, may not be a contraction. Therefore, the proof of Theorem 1.1 cannot directly lead to Theorem 1.3. Instead of applying Theorem 5.2 in the proof of Theorem 1.1, we apply the following theorem of Yu in [43] to prove Theorem 1.3. One can see Corollary 7.3 in [43].

Theorem 6.2 (Yu). *A uniformly contractible Riemannian manifold with finite asymptotic dimension cannot have uniform positive scalar curvature.*

Now we are ready to prove Theorem 1.3.

Proof of Theorem 1.3. Let M be a cover of the moduli space \mathbb{M}_g of S_g and ds^2 be a Riemannian metric on M such that ds^2 is quasi-isometric to $\|\cdot\|_T$. That is, there exist two constants $L \geq 1$ and $K > 0$ such that

$$(6.1) \quad L^{-1} \text{dist}_T(p, q) - K \leq \text{dist}_{ds^2}(p, q) \leq L \text{dist}_T(p, q) + K, \quad \forall p, q \in \text{Teich}(S_g).$$

Since the asymptotic dimension is a quasi-isometric invariance, Theorem 3.2 gives that

$$(6.2) \quad \text{asydim}((\text{Teich}(S_g), ds^2)) < \infty.$$

From Theorem 6.2 of Yu, it remains to show that $(\text{Teich}(S_g), ds^2)$ is uniformly contractible. We follow a similar argument in the proof of Proposition 5.6 to finish the proof.

For each $p \in \text{Teich}(S_g)$ and every $r > 0$, inequality (6.1) and the triangle inequality lead to

$$(6.3) \quad \begin{aligned} B_{ds^2}(p; r) &\subset B_{\|\cdot\|_T}(p; L \cdot r + K) \subset B_{\|\cdot\|_T}(p; L \cdot (r + K)) \\ &\subset B_{ds^2}(p; L^2 \cdot (r + K) + K), \end{aligned}$$

where $B_{ds^2}(p; r) := \{q \in \text{Teich}(S_g); \text{dist}_{ds^2}(p, q) \leq r\}$ and $B_{\|\cdot\|_T}(p; r) := \{q \in \text{Teich}(S_g); \text{dist}_T(p, q) \leq r\}$.

Proposition 2.3 tells that the Teichmüller ball $B_{\|\cdot\|_T}(p; L \cdot (r + K))$ is contractible for all $r > 0$ and $p \in \text{Teich}(S_g)$. Thus, equation (6.3) tells that $B_{ds^2}(p; r)$ is contractible in $B_{ds^2}(p; L^2 \cdot (r + K) + K)$. Thus, the conclusion follows by choosing

$$f(r) = L^2 \cdot (r + K) + K. \tag{q.e.d.}$$

Remark 6.3. Theorem 1.3 also holds in the following sense of quasi-isometry, where we call that ds^2 is *quasi-isometric* to the Teichmüller metric $\|\cdot\|_T$ if there exist two positive constants $L \geq 1, K \geq 0$ and a map

$$f : (\text{Teich}(S_g), \|\cdot\|_T) \rightarrow (\text{Teich}(S_g), ds^2),$$

such that for all $p, q \in \text{Teich}(S_g)$,

$$L^{-1} \text{dist}_T(p, q) - K \leq \text{dist}_{ds^2}(f(p), f(q)) \leq L \text{dist}_T(p, q) + K.$$

If we assume that $(\text{Teich}(S_g), ds^2)$ is quasi-isometric to $(\text{Teich}(S_g), \|\cdot\|_T)$, then the space $(\text{Teich}(S_g), ds^2)$ is also quasi-isometric to $(\text{Teich}(S_g), ds^2_M)$ or $(\text{Teich}(S_g), ds^2_{LSY})$, where these two metrics are uniformly contractible. Indeed, Theorem 7.1 in [43] and Theorem 3.3 give that the coarse Baum–Connes conjecture holds for $(\text{Teich}(S_g), ds^2_M)$ or $(\text{Teich}(S_g), d^2_{LSY})$. Then one can see Corollary 3.9 in [30] and use the same argument in the proof of Theorem 1.3 to get the conclusion.

7. An open question

Let N be an n -dimensional complete simply-connected Riemannian manifold of nonpositive sectional curvature. For any $p \in N$, let T_pN be the tangent space of N at p , it is well-known that the inverse of the exponential map at p

$$\exp_p^{-1} : N \rightarrow T_pN = \mathbb{R}^n$$

is a 1-contraction diffeomorphism. And this property plays an important role in the proof of Theorem 5.3 of Gromov–Lawson. The following question arises in this project.

Question 2. Is there any proper differential map

$$F : (\text{Teich}(S_g), \|\cdot\|_T) \rightarrow \mathbb{R}^{6g-6},$$

such that F is a 1-contraction of degree one? Moreover, could F be a diffeomorphism?

The constant 1 for the contraction property in this question is not essential, since one can take a rescaling on the target space \mathbb{R}^{6g-6} . An affirmative answer to Question 2 will give another proof of Theorem 1.1 by following exact the same argument in [15]. See Theorem 5.2.

We end this section by recalling several well-known parameterizations of the Teichmüller space, which may be helpful for this question.

(1). Recall that the Teichmüller parametrization at a point $X \in \text{Teich}(S_g)$ is given by

$$\begin{aligned} F_X : (\text{Teich}(S_g), \|\cdot\|_T) &\rightarrow \mathbb{R}^{6g-6} = \mathbb{S}^{6g-7} \times \mathbb{R}^{\geq 0}, \\ Y &\mapsto (V[X, Y], \text{dist}_T(X, Y)), \end{aligned}$$

where $V[X, Y]$ is the direction of the Teichmüller geodesic from X to Y .

It is well-known that F_X is a proper differential map of degree one. However, F_X is not a contraction since there exists two geodesics starting at X which have bounded Hausdorff distance, which was proved by Masur in [24].

(2). Let $X \in \text{Teich}(S_g)$ be a hyperbolic surface and $\text{QD}(X)$ be the holomorphic quadratic differential on X which can be identified with \mathbb{R}^{6g-6} . Let β_X be the Bers embedding of $(\text{Teich}(S_g), \|\cdot\|_T)$ into $\text{QD}(X)$ with respect to the base point X .

It is well-known that β_X is a contraction (For example, one can see Theorem 4.3 in [10]). However, β_X is not proper since the image of the Bers embedding is a bounded subset in \mathbb{R}^{6g-6} .

(3). Fix a hyperbolic surface $X \in \text{Teich}(S_g)$. Then for any $Y \in \text{Teich}(S_g)$ there exists a unique harmonic map from X to Y which is isotopic to the identity map. The Hopf differential $F_X(Y)$ of this harmonic map is a holomorphic quadratic differential on X . In particular, this gives a differential map from $\text{Teich}(S_g)$ to $\text{QD}(X)$. Wolf in [40] showed that this map

$$F_X : (\text{Teich}(S_g), \|\cdot\|_T) \rightarrow \text{QD}(X) = \mathbb{R}^{6g-6}$$

is a diffeomorphism. In particular, this map is proper of degree one. However, Markovic in [23] showed that F_X is not a contraction (One can see Theorem 2.2 in [23]).

(4). Since $\|\cdot\|_T \succ \|\cdot\|_{ds_{WP}^2}$, the identity map

$$i : (\text{Teich}(S_g), \|\cdot\|_T) \rightarrow (\text{Teich}(S_g), ds_{WP}^2)$$

is a contraction diffeomorphism. Fix a hyperbolic surface $X \in \text{Teich}(S_g)$. Since the sectional curvature of the Weil–Petersson metric is negative [34, 36] and the Weil–Petersson metric is geodesically convex [37], the inverse of the exponential map at X

$$\exp_X^{-1} : \text{Teich}(S_g) \rightarrow T_X(\text{Teich}(S_g)) = \mathbb{R}^{6g-6}$$

is a 1-contraction. Consider the composition map

$$\begin{aligned} F_X : (\text{Teich}(S_g), \|\cdot\|_T) &\rightarrow T_X(\text{Teich}(S_g)) = \mathbb{R}^{6g-6}, \\ Y &\mapsto \exp_X^{-1} \circ i(Y). \end{aligned}$$

It is not hard to see that F_X is a contraction and differential map of degree one. However, since the Weil–Petersson metric is incomplete [7, 35], F_X is not proper.

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