

154. On Some Generalised Solution of a Nonlinear First Order Hyperbolic Partial Differential Equation

By Takaaki NISHIDA

(Comm. by Kinjirô KUNUGI, M.J.A., Oct. 12, 1967)

We consider the following Cauchy problem in $t \geq 0$, $-\infty < x < +\infty$.

$$(1) \quad \frac{\partial u}{\partial t} + \frac{\partial f(u)}{\partial x} = h(u)$$

$$(2) \quad u(0, x) = u_0(x),$$

where $f(u) \in C^2$, $h(u) \in C^1$ and $u_0(x) \in L^\infty$.

First we assume that $f_{uu}(u) \geq \delta > 0$ for $\forall u$.

Oleinik [1] proved the uniqueness and existence theorem of the generalised solution for Cauchy problem $u_t + f(t, x, u)_x = g(t, x, u)$ with (2) under the condition $f_{uu} \geq \text{const.} > 0$ and $|g_u(t, x, u)| \leq \text{const.}$ Here we consider the case that $|g_u(t, x, u)| \leq \text{const.}$ is not satisfied and see that the uniqueness and existence theorem is valid for some case under the following definition of the generalised solution.

We call $u(t, x)$ the generalised solution of (1)(2), which satisfies the following:

i) $u(t, x)$ is a measurable and locally bounded function.

ii) for arbitrary continuously differentiable function $\varphi(t, x)$ with compact support

$$(3) \quad \int \int \left[u \frac{\partial \varphi}{\partial t} + f(u) \frac{\partial \varphi}{\partial x} + h(u) \varphi \right] dt dx + \int_{-\infty}^{+\infty} \varphi(0, x) u_0(x) dx = 0.$$

iii)

$$(4) \quad \frac{u(t, x_1) - u(t, x_2)}{x_1 - x_2} < K(t, x_1, x_2),$$

where $K(t, x_1, x_2)$ is continuous in $t > 0$, $-\infty < x_1, x_2 < +\infty$.

§1. Uniqueness Theorem. We have the following uniqueness theorem.

Theorem. *The generalised solution $u(t, x)$ of (1)(2) is unique under the following estimate.*

$$(5) \quad \begin{aligned} -\beta(t) \leq u(t, x) \leq \alpha(t, x) & \quad \text{for } t \geq 0, x \geq 0, \\ -\alpha(t, -x) \leq u(t, x) \leq \beta(t) & \quad \text{for } t \geq 0, x \leq 0, \end{aligned}$$

where $\beta(t)$, $\alpha(t, x)$ are nonnegative and continuous in $\{t \geq 0\}$, $\{t \geq 0, x \geq 0\}$ respectively.

This can be proved by a slight modification of the argument in [1] th. 1. Following it, let us assume that there exist two generalised solutions $u_1(t, x)$, $u_2(t, x)$ satisfying (5). It is sufficient to see that for any $F(t, x) \in C^1$ such that there exist $T > \alpha > 0$, $X > 0$ (may depend

on F) and $F \equiv 0$ for $t \geq T$, $0 \leq t \leq \alpha$ or $|x| \geq X$, the following is true

$$(6) \quad \iint_{t > 0} F(t, x)(u_1(t, x) - u_2(t, x)) dt dx = 0.$$

For the proof of (6) we consider the dual linear differential equation

$$(7) \quad \frac{\partial v}{\partial t} + \phi(t, x) \frac{\partial v}{\partial x} + \psi(t, x)v = F(t, x),$$

where $\phi(t, x) = \frac{f(u_1) - f(u_2)}{u_1 - u_2}$, $\psi(t, x) = \frac{h(u_1) - h(u_2)}{u_1 - u_2}$. In order to have

a continuously differentiable solution $v(t, x)$ we take the following averaged equation instead of (7).

$$(8) \quad \frac{\partial v}{\partial t} + \phi_h(t, x) \frac{\partial v}{\partial x} + \psi_{h\rho}(t, x)v = F(t, x),$$

where $\phi_h, \psi_{h\rho}$ are averaged functions of ϕ, ψ and $\psi_{h\rho} = 0$ for $0 \leq t \leq \rho$, therefore $h \rightarrow 0, \rho \rightarrow 0$ include $\phi_h \rightarrow \phi, \psi_{h\rho} \rightarrow \psi$.

We take as the boundary condition for $v(t, x)$ the following:

$$(9) \quad \begin{aligned} v(T, x) &= 0 & \text{for } -\infty < x < +\infty, \\ v(t, \pm\infty) &= 0 & \text{for } 0 \leq t \leq T, \end{aligned}$$

where it is sufficient for the latter to take $v(t, \pm(X+CT)) = 0$ for each $F(t, x)$, where $C = \max_{0 \leq t \leq T} \beta(t)$.

Now we have

$$\begin{aligned} -C &\leq \phi_h(t, x) \leq A(x) & \text{for } x \geq 0, \quad 0 \leq t \leq T, \\ -A(-x) &\leq \phi_h(t, x) \leq C & \text{for } x < 0, \quad 0 \leq t \leq T, \\ |\psi_{h\rho}(t, x)| &\leq \text{const.} & \text{for } (t, x) \in D, \end{aligned}$$

where $D = \{(t, x) \mid 0 \leq t \leq T, |x| \leq X\}$ and $A(x) \in C^1$ in $[0, +\infty)$.

Taking account of the explicit formula

$$(10) \quad v(t_1, x_1) = \int_{t_0}^{t_1} F(s, x(s, t_1, x_1)) \left[\exp \int_{t_1}^s -\psi_{h\rho}(\tau, x(t_1, x_1)) d\tau \right] ds,$$

where $x(t, t_1, x_1)$ is the characteristics passing through the point (t_1, x_1) i.e., the solution of $dx/dt = \phi_h(t, x)$ and $|x(t_0, t_1, x_1)| \geq X+CT$ or $t_0 = T$, and also the fact that $F(t, x) = 0$ for $(t, x) \notin D \cap \{t \geq \alpha\}$, quite analogously to [1], we have the following:

$$v(t_1, x_1) \in C^1(0 \leq t_1 \leq T, -\infty < x_1 < +\infty),$$

$$|v(t_1, x_1)| \leq \text{const. (indep. of } h, \text{ dep. on } D \text{ and } \sup_D \{|u_1|, |u_2|\}),$$

$$\left| \frac{\partial v}{\partial x_1} \right| \leq \text{const. (indep. of } h) \text{ for } (t_1, x_1) \in D \cap \{t \geq \alpha\}, \rho: \text{fixed,}$$

$$\text{Variation } v(t_1, x_1) < \text{const. (indep. of } h \text{ and } t) \text{ for } \rho: \text{fixed.}$$

Thus using the definition (3) of the generalised solution, and tending h, ρ to zero appropriately, then we have

$$(11) \quad \int\int_{t \geq 0} (u_1 - u_2) F dt dx = \int\int (u_1 - u_2) \left(\frac{\partial v}{\partial t} + \phi_h \frac{\partial v}{\partial x} + \psi_{h_0} v \right) dt dx \\ = \int\int (u_1 - u_2) \left[(\phi_h - \phi) \frac{\partial v}{\partial x} + (\psi_{h_0} - \psi) v \right] dt dx = 0.$$

§ 2. **Existence Theorem.** Hereafter we assume that

$$(12) \quad \begin{aligned} &h(u) \leq \text{const.} (u^2 + 1) \quad \text{for } u \geq 0, \\ &h(u) \geq -\text{const.} (u^2 + 1) \quad \text{for } u < 0 \text{ and there exist} \\ &u_0 = \text{const. such that } h(u_0) = 0. \end{aligned}$$

For the initial value $u_0(x)$ we assume

$$(13) \quad u_0(x) - u_0$$

is some bounded measurable function with compact support.

Theorem. *The generalised solution of Cauchy problem (1) (2), which satisfies the estimate (5), exists for $0 \leq t < +\infty$, $-\infty < x < +\infty$ under the assumptions (12) (13).*

The proof is analogous to that of [2]. For the simplicity of the argument we discuss the case that $f_u(0) = 0$, $h(0) = 0$ and $u_0(x)$ is a L^∞ -function with compact support.

The solution of the characteristic equation of (1)

$$(14) \quad \frac{dx}{dt} = f_u(u), \quad \frac{du}{dt} = h(u)$$

with the initial values $x(0, \xi) = \xi$, $u(0, \xi) = u_0(\xi)$, $\xi \in (a, b)$ satisfies the following

$$(15) \quad \int_{u_0(\xi)}^{u(t, \xi)} \frac{f_u(u)}{h(u)} du = x(t, \xi) - \xi, \text{ or} \\ u(t, \xi) = u_0(\xi) \quad \text{for } h(u_0(\xi)) = 0.$$

Because of the continuous differentiability of $h(u)$ and the formula (15) with $f_{uu} \geq \delta > 0$ we have

$$(16) \quad \begin{aligned} &0 \leq u(t, \xi) \leq u_0(\xi) e^{x-\xi} \quad \text{for } u_0(\xi) \geq 0, \\ &0 \geq u(t, \xi) \geq u_0(\xi) e^{-(x-\xi)} \quad \text{for } u_0(\xi) < 0. \end{aligned}$$

Differentiation (14) with respect to ξ gives

$$\frac{\partial u(t, \xi)}{\partial \xi} = \frac{\partial u(0, \xi)}{\partial \xi} \exp \int_0^t h_u(u(\tau, \xi)) d\tau \\ \frac{\partial x(t, \xi)}{\partial \xi} = \frac{\partial x(0, \xi)}{\partial \xi} + \frac{\partial u(0, \xi)}{\partial \xi} \int_0^t f_{uu}(u(\tau, \xi)) \exp \int_0^\tau h_u(u(\eta, \xi)) d\eta d\tau$$

and so under the condition $\partial x(0, \xi) / \partial \xi \geq 0$, $\partial u(0, \xi) / \partial \xi \geq 0$ we have

$$(17.1) \quad \frac{\partial u}{\partial x} = \frac{\partial u}{\partial \xi} / \frac{\partial x}{\partial \xi} \leq \frac{\exp \int_0^t h_u(u(\tau, \xi)) d\tau}{\int_0^t f_{uu}(u(\tau, \xi)) \exp \int_0^\tau h_u(u(\eta, \xi)) d\eta d\tau} \\ \leq \frac{\text{const. exp } |x|}{\delta t}.$$

In the case that the initial is $x(0, \varepsilon) = \text{const}$,

$$u(0, \varepsilon) = u_- + \varepsilon(u_+ - u_-) \quad \text{for } 0 \leq \varepsilon \leq 1, \quad u_- < u_+$$

the same is true:

$$(17.2) \quad \frac{\partial u}{\partial x} = \frac{\partial u}{\partial \varepsilon} \Big/ \frac{\partial x}{\partial \varepsilon} \leq \frac{\text{const. exp } |x|}{\delta t}.$$

Now we approximate the initial condition $u_0(x)$ with piecewise constant functions $u^h(0, x) (h > 0)$:

$$(18) \quad u^h(0, x) = \frac{1}{h} \int_{kh}^{(k+1)h} u_0(\xi) d\xi \quad \text{for } kh < x < (k+1)h,$$

where $u^h(0, x) \equiv 0$ for $|x| \geq \exists N > 0$,

then we construct the generalised solution for the Cauchy problem (1)(18) by means of the solution of the characteristics equation (14) with the initial values

$$(19) \quad x(0, \xi) = \xi, \quad u(0, \xi) = u^h(0, \xi),$$

where

$$\xi \in (kh, (k+1)h), \quad k = 0, \pm 1, \pm 2, \dots,$$

and if $u^h(0, kh-0) < u^h(0, kh+0)$, then we supplement the initial values

$$(20) \quad x(0, \varepsilon) = kh, \quad u(0, \varepsilon) = u^h(0, kh-0) + \varepsilon(u^h(0, kh+0) - u^h(0, kh-0)),$$

for $0 \leq \varepsilon \leq 1$ and necessary k .

The method to construct the generalised solutions $u^h(t, x)$ for the Cauchy problem (1)(18) is analogous to that of [2], thus using the formulae (16), (17) for $u^h(t, x)$ we have the following

$$\begin{aligned} -C &\leq u^h(t, x) \leq \alpha(x) \quad \text{for } x \geq 0, \\ -\alpha(-x) &\leq u^h(t, x) \leq C \quad \text{for } x < 0, \\ \frac{u^h(t, x_1) - u^h(t, x_2)}{x_1 - x_2} &< K(t, x_1, x_2), \end{aligned}$$

where $K(t, x_1, x_2)$ is continuous in $t > 0, -\infty < x_1, x_2 < +\infty$. On these bases by the analogous argument in [2] we see that for $\forall K$: compact subdomain in $\{t \geq 0, -\infty < x < +\infty\}$ $u^h(t, x)$ is uniformly bounded and compact in $L^1(K)$, i.e.,

$$\sup_K |u^h(t, x)| \leq \text{const. (indep. of } h),$$

$$\text{Variation } \{u^h(t, x)\}_{-\forall x \leq x \leq x} \leq \frac{\text{const.}}{t} \quad (\text{indep. of } h),$$

$$\int_{-x}^x |u^h(t_1, x) - u^h(t_2, x)| dx \leq \text{const. } |t_1 - t_2|$$

$$\text{for } t_1, t_2 \geq \forall \alpha > 0$$

(indep. of h , dep. on X and α).

By the way $u^h(t, x)$ satisfies the following for any continuously differentiable function $\varphi(t, x)$ with compact support:

$$(21) \quad \iint_{t \geq 0} \left[u^h \frac{\partial \varphi}{\partial t} + f(u^h) \frac{\partial \varphi}{\partial x} + h(u^h) \varphi \right] dt dx + \int_{-\infty}^{+\infty} u^h(0, x) \varphi(0, x) dx = 0,$$

and considering that there exist a subsequence $u^{h_j}(t, x)$ of $u^h(t, x)$ such

that $u^{h,j}(t, x) \rightarrow u(t, x) \in L^\infty(\text{loc})$ in $L^1(\text{loc})$, passing to the limit in (21) along $h, j \rightarrow 0$, then we have the following for the limit function $u(t, x)$

$$\iint_{t \geq 0} \left[u \frac{\partial \varphi}{\partial t} + f(u) \frac{\partial \varphi}{\partial x} + h(u) \varphi \right] dt dx + \int_{-\infty}^{+\infty} \varphi(0, x) u_0(x) dx = 0,$$

that is, $u(t, x)$ is the desired generalised solution for (1)(2), and also the uniqueness of the generalised solution concludes that all sequence $u^h(t, x)$ converge to $u(t, x)$ in $L^1(\text{loc})$.

Remark. 1. For the equation $u_t + (u^2/2)_x = g(x)u^2$, where $g(x)$ is any continuously differentiable function, we have an analogous result to the above, if we take the above definition of the generalised solution. (cf. [2]).

2. If we take the assumption $u_0(x) \in L^\infty$ instead of

$$u_0(x) - u_0 \in L^\infty \cap S'$$

(or $u_0(x) \in L^\infty$ and the set $\{x \mid h(u_0(x)) \neq 0\}$ is equivalent almost everywhere to some compact set), we can not generally expect that the generalised solution of (1)(2) exists in $t \geq 0$ and is locally bounded in $t \geq 0$, $-\infty < x < +\infty$ under the assumption (12).

3. If we take $h(u) = u^{2+\alpha}$ ($\alpha > 0$, const.), then even for the case $u_0(x) \in L^\infty \cap S'$ we can not generally expect that the generalised solution of (1)(2) exists and is locally bounded in $t \geq 0$, $-\infty < x < +\infty$, but the same existence theorem as the above is true under the additional condition that if u is infinite, then

$$\int_{u_0}^u \frac{f_u(v)}{h(v)} dv \text{ is infinite for finite values } u_0.$$

(by virtue of (15)).

The writer wishes to express his sincere gratitude to Professor M. Tada and Professor M. Yamaguti for valuable encouraging suggestions and their interest in this note.

References

- [1] O. A. Oleinik: Discontinuous solutions of nonlinear differential equations. Amer. Math. Soc. Trans. Ser. II, **26**, 95-172.
- [2] T. Nishida: A remark on a nonlinear hyperbolic equation of first order. Mem. Fac. Eng. Kyoto Univ., **24**, 213-223 (1967).