175. Index Theorem for a Maximally Overdetermined System of Linear Differential Equations

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In this note we state the index theorem for a maximally overdetermined system of linear partial differential equations. The theorem comprises as a special case the already known index theorem for an ordinary differential equation (Kashiwara [2], Komatsu [4] and Malgrange [5]).

1. Local characteristic. Let (S, x) be a germ of an irreducible analytic space. We define the local characteristic $c_x(S)$ by the induction on the dimension of S as follows.

We embed (S, x) into an enclidean space $(\mathbb{C}^N, 0)$ and choose a Whitney stratification $S = \bigcup S_{\alpha}$ of S. The open stratum of S is denoted by S_0 . Let d_{α} be the dimension of S_{α} and x_{α} be a point in S_{α} . We define $c_x(S)$ inductively by the following formula

$$c_x(S) = \sum_{S_\alpha \neq S_0} c_x(\bar{S}_\alpha) \chi(U_\alpha \cap S_0 \cap Z_\alpha)$$

where U_{α} denotes a sufficiently small open ball with center x_{α} , Z_{α} denotes a $(d_{\alpha}+1)$ -codimensional linear variety in a generic position in C^{N} sufficiently close to x_{α}, χ denotes the Euler characteristic and the sum extends over all the strata S_{α} other than S_{0} .

Proposition. The definition of a local characteristic $c_x(S)$ is independent of the choice of the embedding $(S, x) \subset (\mathbb{C}^N, 0)$ and the stratification.

We will give the expamples of local characteristics.

Example 1. If (S, x) is non singular, then $c_x(S) = 1$.

Example 2. If (S, x) is a hypersurface in C^{n+1} with the isolated singularity at x, then $c_x(S) = 1 + (-1)^{n-1}\mu$ where μ is the Milnor number of the generic hyperplane section of S through the point x. In particular, for $S = \{x \in C^{n+1}; x_0^{p_0} + \cdots + x_n^{p_n} = 0\}$, we have $c_0(S) = 1$ $+ (-1)^{n-1}(p_1-1)\cdots(p_n-1)$ with $p_0 = \max_i p_i$

Example 3. If (S, x) is a curve, then $c_x(S)$ coincides with the multiplicity of S at x.

Example 4. If $S = \{(x, y, z) \in C^3; x^n + y^p z^q = 0\}$ (g. c. d. (p, q, n) = 1and $p, q, n \ge 1$), then $c_0(S) = \min(n, p) + \min(n, q) - n$.

2. Index theorem. Let X be a complex manifold, \mathcal{O} be the sheaf of holomorphic functions on X, \mathcal{D} be the sheaf of differential operators

of finite order on X and \mathcal{M} be a system of differential equations, that is, a coherent left \mathcal{D} -Module (as for the notations we refer the reader to Sato-Kawai-Kashiwara [1], Kashiwara [2], [3]).

Let $\mathcal{M} = \bigcup \mathcal{M}_k$ be a good filtration of \mathcal{M} , namely, a filtration by such coherent \mathcal{O} -Modules \mathcal{M}_k that one has $\mathcal{D}_l \mathcal{M}_k \subset \mathcal{M}_{k+l}$ for any l, kand $\mathcal{D}_l \mathcal{M}_k = \mathcal{M}_{l+k}$ for $k \gg 0$ with \mathcal{D}_l denoting the sheaf of differential operators of order $\leq l$. $SS(\mathcal{M})$ is the support of the coherent sheaf $\widetilde{gr\mathcal{M}}$ on T^*X associated with $gr\mathcal{M} = \bigoplus (\mathcal{M}_k / \mathcal{M}_{k-1})$. For an irreducible analytic subset Λ in T^*X , the multiplicity of \mathcal{M} at Λ is by the definition the multiplicity of $\widetilde{gr\mathcal{M}}$ at Λ . These notions are independent of the choice of the good filtration.

We assume that \mathcal{M} is maximally overdetermined. This means the dimension of $\widehat{SS}(\mathcal{M})$ equals to that of X.

By definition the index $\chi_x(\mathcal{M})$ of \mathcal{M} at a point x of X is given by $\chi_x(\mathcal{M}) = \sum (-1)^i \dim_{\mathcal{C}} \mathcal{E}_{xt_{\mathcal{O}}^i}(\mathcal{M}, \mathcal{O})_x.$

 $\hat{S}\hat{S}(\mathcal{M})$ is expressed as union

$$\widehat{SS}(\mathcal{M}) = \bigcup \overline{T^*_{\mathbf{r}_j}X}$$

in a neighborhood of x where Y'_j is a non singular locus of an analytic subset Y_j of X irreducible at x. This expression is unique.

Theorem. $\chi_x(\mathcal{M}) = \sum_j (-1)^{d_j} c_x(Y_j) m_j$ where d_j is the codimension of Y_j and m_j is the multiplicity of \mathcal{M} at $T^*_{Y_i}X$.

This theorem is derived from the structure theorem for a maximally overdetermined system of pseudo-differential equations and the study of the sheaf $\mathcal{E}_{xt_{\mathcal{O}}^{j}}(\mathcal{M}, \mathcal{O})$ (see [3]).

References

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