## PAPERS COMMUNICATED

## 12. Projective Parameters in Projective and Conformal Geometries.

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## § 1. Projective parameters in projective geometry.

In an $n$-dimensional space $A_{n}$ with the affine connection $\Gamma_{j k}^{i}$, a system of curves called paths is defined by the differential equations of the form

$$
\begin{equation*}
\frac{d^{2} x^{i}}{d s^{2}}+\Gamma_{j k}^{i} \frac{d x^{j}}{d s} \frac{d x^{k}}{d s}=0 \quad(i, j, k, \ldots=1,2, \ldots, n) \tag{1.1}
\end{equation*}
$$

as autoparallel curves, where $s$ is called affine parameter on each path. Conversely, if we are given the differential equations of the form (1.1) in an $n$-dimensional space $X_{n}$, we can define a symmetric affine connection in this space taking $\Gamma_{j k}^{i}$ as the components of the connection. The study of the properties of these differential equations constitutes the affine geometry of paths ${ }^{1}$. But, an affine connection is not defined uniquely by the system of paths (1.1). H. Weyl ${ }^{2}$ and L. P. Eisenhart ${ }^{3}$ have independently shown that any two affine connections whose components $\bar{\Gamma}_{j k}^{i}$ and $\Gamma_{j k}^{i}$ are related by the equations of the form

$$
\begin{equation*}
\bar{\Gamma}_{j k}^{i}=\Gamma_{j k}^{i}+\delta_{j}^{i} \psi_{k}+\delta_{k}^{i} \psi_{j}, \tag{1.2}
\end{equation*}
$$

where $\psi_{j}$ are components of an arbitrary covariant vector not necessarily gradient, give the same paths. In this sense, the change over from $\bar{\Gamma}_{j k}^{i}$ to $\Gamma_{j k}^{i}$ is called the projective change of affine connections, and the study of those properties which are invariant under such changes of affine connections is called the projective geometry of paths ${ }^{4}$.

To study the projective geometry of paths, T.Y. Thomas ${ }^{\text {( }}$ ) has introduced the functions

$$
\begin{equation*}
\Pi_{j k}^{i}=\Gamma_{j k}^{i}-\frac{1}{n+1}\left(\delta_{j}^{i} \Gamma_{a k k}^{a}+\delta_{k}^{i} \Gamma_{a j j}^{a}\right), \tag{1.3}
\end{equation*}
$$

which are invariant under projective change of affine connections (1.2).

[^0]Although $\Pi_{j k}^{i}$ are invariant under the projective change of affine connections, their law of transformation under the change of coordinates is not identical with that of the components of the affine connection, that is the case when and only when the jacobian of the transformation is constant. The study of the invariant properties of $\Pi_{j k}^{i}$ under such restricted transformations constitutes the equi-projective geometry of paths ${ }^{1}$.

To avoid this inconvenience, T. Y. Thomas ${ }^{2)}$ has introduced an extra dimension $x^{0}$ and defined an affine connection ${ }^{*} \Pi_{\mu \nu}^{\lambda}(\lambda, \mu, \nu, \ldots=$ $0,1,2, \ldots, n$ ) in an associated space of ( $n+1$ ) dimensions by means of the relations

$$
\begin{equation*}
{ }^{*} \Pi_{0 \nu}^{\lambda}={ }^{*} \Pi_{\nu 0}^{\lambda}=-\frac{1}{n+1} \delta_{\nu}^{\lambda}, \quad{ }^{*} \Pi_{j k}^{i}=\Pi_{j k}^{i}, \quad{ }^{*} \Pi_{j k}^{0}=\frac{n+1}{n-1} \Pi_{j k}, \tag{1.4}
\end{equation*}
$$

where

$$
\Pi_{j k}=\Pi_{\cdot j k i}^{i} \quad \text { and } \quad \Pi_{\cdot j k h}^{i}=\frac{\partial \Pi_{j k}^{i}}{\partial x^{h}}-\frac{\partial \Pi_{j h}^{i}}{\partial x^{k}}+\Pi_{j k h}^{a} \Pi_{a h}^{i}-\Pi_{j h}^{a} \Pi_{a k k}^{i}
$$

and formulated the projective geometry of paths as the invariant theory of the affine connection of this $(n+1)$-dimensional associated space under the special change of coordinates

$$
\begin{equation*}
x^{0^{\prime}}=x^{0}+\log \left|\frac{\partial x^{\prime}}{\partial x}\right|, \quad x^{i^{\prime}}=x^{i^{\prime}}\left(x^{1}, x^{2}, \ldots, x^{n}\right) . \tag{1.5}
\end{equation*}
$$

This idea of introducing an extra coordinate $x^{0}$ is adopted later by O. Veblen ${ }^{3}$. O. Veblen has defined the projective geometry as the invariant theory of $\Pi_{\mu \nu}^{\lambda}$, symmetric and satisfying the following conditions

$$
\begin{equation*}
\Pi_{0 \nu}^{\lambda}=\Pi_{\nu 0}^{\lambda}=\delta_{\nu}^{\lambda}, \quad \frac{\partial}{\partial x^{0}} \Pi_{\mu \nu}^{\lambda}=0, \tag{1.6}
\end{equation*}
$$

under special transformations of coordinates

$$
\begin{equation*}
x^{0^{\prime}}=x^{0}+\log \rho\left(x^{1}, x^{2}, \ldots, x^{n}\right), \quad x^{i^{\prime}}=x^{i^{\prime}}\left(x^{1}, x^{2}, \ldots, x^{n}\right) . \tag{1.7}
\end{equation*}
$$

Let $\Pi_{\mu \nu}^{\lambda}$ be the components of an affine connection in an $(n+1)$ dimensional space $A_{n+1}$. If there exists a coordinate system in which the components of connection $\Pi_{\mu \nu}^{\lambda}$ satisfy the conditions (1.6), then the $A_{n+1}$ referred to this coordinate system may be taken to represent a projective space $P_{n}$. From this point of view, J. H. C. Whitehead ${ }^{4)}$ has studied the representation of projective spaces, and derived many interesting results on generalized projective geometry.

Let $\Pi_{j k}^{i}$ be the components of an symmetric affine connection of an $n$-dimensional space $A_{n}$, then introducing a symmetric tensor $\Pi_{j k}^{0}$,

[^1]we can construct a symmetric affine connection $\Pi_{\mu \nu}^{\lambda}$ of an $(n+1)$ dimensional space $A_{n+1}$ by means of $I_{j k}^{i}, ~ I I_{j k}^{0}$ and $I_{0 \nu}^{\lambda}=I I_{\nu 0}^{\lambda}=\delta_{\nu}^{\lambda}$.

The equations of paths in $A_{n+1}$ are given by

$$
\begin{equation*}
\frac{d^{2} x^{\lambda}}{d t^{2}}+\Pi_{\mu \nu}^{\lambda} \frac{d x^{\mu}}{d t} \frac{d x^{\nu}}{d t}=0, \tag{1.8}
\end{equation*}
$$

where $t$ is an affine parameter for the paths of $A_{n+1}$. Putting $\lambda=0$ and $\lambda=i$ in (1.8), we obtain

$$
\left\{\begin{array}{l}
\frac{d^{2} x^{0}}{d t^{2}}+\Pi_{j k}^{0} \frac{d x^{j}}{d t} \frac{d x^{k}}{d t}+\left(\frac{d x^{0}}{d t}\right)^{2}=0 \quad \text { and }  \tag{1.9}\\
\frac{d^{2} x^{i}}{d t^{2}}+\Pi_{j k}^{i} \frac{d x^{j}}{d t} \frac{d x^{k}}{d t}+2\left(\frac{d x^{0}}{d t}\right) \frac{d x^{i}}{d t}=0
\end{array}\right.
$$

respectively. If we introduce a new parameter $s$ by means of the relation $2\left(\frac{d x^{0}}{d t}\right)=\frac{d^{2} t}{d s^{2}} /\left(\frac{d t}{d s}\right)^{2}$ or $x^{0}=\frac{1}{2} \log \frac{d t}{d s}$, the equations (1.9) take respectively the form

$$
\begin{equation*}
\{t, s\}=-2 \Pi_{j k}^{0} \frac{d x^{j}}{d s} \frac{d x^{k}}{d s} \quad \text { and } \quad \frac{d^{2} x^{i}}{d s^{2}}+I_{j k}^{i} \frac{d x^{j}}{d s} \frac{d x^{k}}{d s}=0 \tag{1.10}
\end{equation*}
$$

where $\{t, s\}$ denotes the Schwarzian derivative of $t$ with respect to $s$.
Thus, the projective connection of O. Veblen and J. H. C. Whitehead defines a system of paths in $A_{n}$ and a projective parameter $t$ on each path. The projective parameter $t$ introduced first by J.H.C. Whitehead plays an important part in the study of projective geometry of paths.
L. Berwald ${ }^{1)}$ developed, on the other hand, the projective geometry of paths resting on two notions: the notion of the class of affine connections belonging to a system of paths and the notion of a projective parameter of a system of paths. He defines the paths by (1.1) and projective parameter by

$$
\begin{equation*}
\{t, s\}=-2 \Gamma_{j k}^{0} \frac{d x^{j}}{d s} \frac{d x^{k}}{d s} \tag{1.11}
\end{equation*}
$$

The projective parameter $t$ being defined by a Schwarzian derivative,
(a) it is determined, up to an arbitrary linear fractional transformation, on each path of the system at the same time, he requires moreover that
(b) it is not altered by transformations of coordinates,
(c) it remains the same for all affine connections of the class belonging to the system of paths.
From the condition (b) and (1.11), we know that $\Gamma_{j k}^{0}$ are the components of a tensor, and from the condition (c), we conclude that, the

[^2]law of transformation of $\Gamma_{j k}^{0}$ under the projective change of affine connections (1.2) is
\[

$$
\begin{equation*}
\bar{I}_{j k}^{0}=\Gamma_{j k}^{0}+\frac{1}{2}\left(\frac{\partial \psi_{j}}{\partial x^{k}}+\frac{\partial \psi_{k}}{\partial x^{j}}\right)-\psi_{i} \Gamma_{j k}^{i}-\psi_{j} \psi_{k} . \tag{1.12}
\end{equation*}
$$

\]

The term $\frac{1}{2}\left(\frac{\partial \psi_{j}}{\partial x^{k}}+\frac{\partial \psi_{k}}{\partial x^{j}}\right)$ appears owing to the fact that $\Gamma_{j k}^{0}$ in (1.11) are the coefficients of a quadratic form and consequently only the symmetric part of $\Gamma_{j k}^{0}$ is in question.

The present author ${ }^{1)}$ has shown that all these projective geometries of paths may be naturally interpretated from the standpoint of $E$. Cartan ${ }^{2)}$. If we define Cartan's projective connection by the formulae

$$
\begin{equation*}
d A_{0}=d x^{i} A_{i}, \quad d A_{j}=\Gamma_{j k}^{0} d x^{l} A_{0}+\Gamma_{j k}^{i} d x^{k} A_{i} \tag{1.13}
\end{equation*}
$$

and paths as the curves whose developments in tangent projective space are straight lines, then the equation of paths may be written as

$$
\begin{equation*}
\frac{d^{2}}{d t^{2}} \rho A_{0}=0 \tag{1.14}
\end{equation*}
$$

and the differential equations of the paths coincide with (1.1) and $t$ is precisely the projective parameter defined by (1.11). The theory of T. Y. Thomas is obtained if we adopt the so-called repère naturel in the space with normal projective connection.
J. Haantjes ${ }^{3}$ studied the projective geometry of paths using the homogeneous coordinates of D. van Dantzig ${ }^{4}$. The differential equations of the paths are

$$
\begin{equation*}
\frac{d^{2} x^{\lambda}}{d r^{2}}+\Pi_{\mu \nu}^{\lambda} \frac{d x^{\mu}}{d r} \frac{d x^{\nu}}{d r}=\alpha x^{\lambda}+\beta \frac{d x^{\lambda}}{d r} \tag{1.15}
\end{equation*}
$$

where $x^{\lambda}$ are homogeneous coordinates, $\Pi_{\mu \nu}^{\lambda}$ components of the symmetric projective connection which are homogeneous functions of degree -1 and satisfy $\Pi_{\mu \nu}^{\lambda} x^{\mu}=0$, and $r$ an arbitrary parameter on the paths. J. Haantjes also introduced special homogeneous coordinates $u^{0}$ and $u^{1}$ on each paths and showed that their ratio coincides with the projective parameter $t$ appeared in old theories.

It is shown in the author's These that if we choose a suitable factor $\rho$ and parameter $t$ on each path, the equations of paths (1.15) may be written as

$$
\begin{equation*}
\frac{d^{2} \rho x^{\lambda}}{d t^{2}}+\Pi_{\mu \nu}^{\lambda}(\rho x) \frac{d \rho x^{\mu}}{d t} \frac{d \rho x^{\nu}}{d t}=0 \tag{1.16}
\end{equation*}
$$

[^3]It is interesting to remark that, in all these theories, the equations of paths in their most simple forms (1.8), (1.14) and (1.16) have the same form that the second derivatives of the coordinates vanish, and that the parameter $t$ which admits this simplification is the projective parameter.
§2. Projective parameters in conformal geometry.
In this section, we shall show that the method of L. Berwald explained in $\S 1$ may be applied also to the conformal geometry.
(i) Conformal geometry.

Let us consider an $n$-dimensional Riemann space $V_{n}$ with the fundamental quadratic form $d s^{2}=g_{j k} d x^{j} d x^{k}$. By a conformal transformation $\bar{g}_{j k}=\rho^{2} g_{j k}$ of the fundamental tensor, the line-element $d s$ of each curve and the Christoffel symbols $\left\{\begin{array}{l}i \\ j k\end{array}\right\}$ are transformed into $d \bar{s}$ and $\overline{\left\{i{ }_{j k}\right\}}$ respectively by the formulae of the form

$$
\begin{gather*}
d \bar{s}=\rho d s,  \tag{2.1}\\
\overline{\left\{{ }_{j k}^{i}\right\}}=\left\{\begin{array}{l}
i \\
\left.j_{j k}\right\}
\end{array}+\delta_{j}^{i} \rho_{k}+\delta_{k}^{i} \rho_{j}-g^{i a} \rho_{a} g_{j k}, \quad\left(\rho_{j}=\frac{\partial}{\partial x^{j}} \log \rho\right)\right. \tag{2.2}
\end{gather*}
$$

consequently the tangent vector $\frac{d x^{i}}{d s}$ and the curvature vector $\frac{\delta}{\delta s} \frac{d x^{i}}{d s}$ $=\frac{\delta^{2} x^{i}}{\delta s^{2}}$ of any curve are transformed into $\frac{d x^{i}}{d \bar{s}}$ and $\frac{\delta^{2} x^{i}}{\delta \bar{s}^{2}}$ respectively by

$$
\begin{equation*}
\frac{d x^{i}}{d \bar{s}}=\frac{d x^{i}}{d s} / \frac{d \bar{s}}{d s} \tag{2.3}
\end{equation*}
$$

$$
\begin{equation*}
\frac{\delta^{2} x^{i}}{\delta \bar{s}^{2}}=\frac{\delta^{2} x^{i}}{\delta s^{2}} /\left(\frac{d \bar{s}}{d s}\right)^{2}+\frac{d x^{i}}{d s} \frac{d^{2} \bar{s}}{d s^{2}} /\left(\frac{d \bar{s}}{d s}\right)^{3}-g^{i a} \rho_{a} /\left(\frac{d \bar{s}}{d s}\right)^{2} \tag{2.4}
\end{equation*}
$$

where $\delta / \delta s$ denotes the covariant differentiation along the curve with respect to the Christoffel symbols $\left\{\begin{array}{l}i \\ j_{k}\end{array}\right\}$ and $\delta / \delta \bar{s}$ with respect to $\{\bar{i}\}$.

Now we define a projective parameter $t$ on each curve $x^{i}(s)$ by means of the Schwarzian differential equation of the form

$$
\begin{equation*}
\{t, s\}=\frac{1}{2} g_{j k} \frac{\delta^{2} x^{j}}{\delta s^{2}} \frac{\delta^{2} x^{k}}{\delta s^{2}}-I I_{j k}^{0} \frac{d x^{j}}{d s} \frac{d x^{k}}{d s} . \tag{2.5}
\end{equation*}
$$

$t$ being defined on each curve up to an arbitrary linear fractional transformation, we assume moreover that it is not altered by transformations of coordinates and that it remains same for all metrics related by a conformal transformation $\bar{g}_{j k}=\rho^{2} g_{j k}$. From the first assumption, we can conclude that the functions $\Pi_{j k}^{0}$ are components of a symmetric tensor. From the second assumption, we find, by a straightforward calculation with the aid of (2.1), (2.3), (2.4) and

$$
\{t, \bar{s}\}=(\{t, s\}-\{\bar{s}, s\}) /\left(\frac{d \bar{s}}{d s}\right)^{2}
$$

that the law of transformation of $I_{j k}^{0}$ under a conformal transformation $\bar{g}_{j k}=\rho^{2} g_{j k}$ is

$$
\begin{equation*}
\bar{I}_{j k}^{0}=\Pi_{j k}^{0}+\frac{\partial \rho_{j}}{\partial x^{k}}-\rho_{i}\left\{{ }_{j j k}^{i}\right\}-\rho_{j} \rho_{k}+\frac{1}{2} g^{a b} \rho_{a} \rho_{b} g_{j k} \tag{2.6}
\end{equation*}
$$

Thus the conformal geometry is fixed by giving $g_{j k}$ and consequently $\left\{{ }_{j k}^{i}\right\}$ and $\Pi_{j k}^{0}$ whose laws of transformations under the conformal transformation $\bar{g}_{j k}=\rho^{2} g_{j k}$ are (2.2) and (2.6) respectively.
(ii) Conformal circles.

Geodesic circles ${ }^{1)}$ in Riemann geometry are defined by the equations

$$
\begin{equation*}
\frac{\delta^{3} x^{i}}{\delta s^{3}}+g_{j k} \frac{\delta^{2} x^{j}}{\delta s^{2}} \frac{\delta^{2} x^{k}}{\delta s^{2}} \frac{d x^{i}}{d s}=0 . \tag{2.7}
\end{equation*}
$$

The left-hand side of this equation is not invariant under a conformal transformation $\bar{g}_{j k}=\rho^{2} g_{j k}$. Under this transformation it is transformed by

$$
\begin{align*}
\frac{\delta^{3} x^{i}}{\delta \bar{s}^{3}} & +\bar{g}_{j k} \frac{\delta^{2} x^{j}}{\delta \bar{s}^{2}} \frac{\delta^{2} x^{k}}{\delta \bar{s}^{2}} \frac{d x^{i}}{d \bar{s}}  \tag{2.8}\\
& =\frac{1}{\rho^{3}}\left(\frac{\delta^{3} x^{i}}{\delta s^{3}}+g_{j k} \frac{\delta^{2} x^{j}}{\delta s^{2}} \frac{\delta^{2} x^{k}}{\delta s^{2}} \frac{d x^{i}}{d s}+\rho_{j k} \frac{d x^{j}}{d s} \frac{d x^{k}}{d s} \frac{d x^{i}}{d s}-\rho_{\cdot k}^{i} \frac{d x^{k}}{d s}\right)
\end{align*}
$$

where

$$
\begin{equation*}
\rho_{j k}=\frac{\partial \rho_{j}}{\partial x^{k}}-\rho_{i}\left\{{ }_{j k}^{i}\right\}-\rho_{j} \rho_{k}+\frac{1}{2} g^{a b} \rho_{a} \rho_{b} g_{j k}, \quad \text { and } \quad \rho_{\cdot k}^{i}=g^{i a} \rho_{a k} \tag{2.9}
\end{equation*}
$$

hence, from (2.6) and (2.8) we have

$$
\begin{aligned}
\frac{\delta^{3} x^{i}}{\partial \bar{s}^{3}} & +\bar{g}_{j k} \frac{\delta^{2} x^{j}}{\delta \bar{s}^{2}} \frac{\delta^{2} x^{k}}{\delta \bar{s}^{2}} \frac{d x^{i}}{d \bar{s}}-\bar{\Pi}_{j k}^{0} \frac{d x^{j}}{d \bar{s}} \frac{d x^{k}}{d \bar{s}} \frac{d x^{i}}{d \bar{s}}+\bar{\Pi}_{\infty k}^{i} \frac{d x^{k}}{d \bar{s}} \\
& =\frac{1}{\rho^{3}}\left[\frac{\delta^{3} x^{i}}{\delta s^{3}}+g_{j k} \frac{\delta^{2} x^{j}}{\delta s^{2}} \frac{\delta^{2} x^{k}}{\delta s^{2}} \frac{d x^{i}}{d s}-\Pi_{j k}^{0} \frac{d x^{j}}{d s} \frac{d x^{k}}{d s} \frac{d x^{i}}{d s}+\Pi_{\infty k}^{i} \frac{d x^{k}}{d s}\right],
\end{aligned}
$$

where

$$
\bar{I}_{\infty<k}^{i}=\bar{g}^{i j} \bar{\Pi}_{j k k}^{0} \quad \text { and } \quad I_{\infty}^{i}=g^{2 j} I_{j k}^{0},
$$

which shows that the curve defined by

$$
\begin{equation*}
\frac{\delta^{3} x^{i}}{\delta s^{3}}+g_{j k} \frac{\delta^{2} x^{j}}{\delta s^{2}} \frac{\delta^{2} x^{k}}{\delta s^{2}} \frac{d x^{i}}{d s}-\Pi_{j k}^{0} \frac{d x^{j}}{d s} \frac{d x^{k}}{d s} \frac{d x^{i}}{d s}+\Pi_{\infty k}^{i} \frac{d x^{k}}{d s}=0 \tag{2.10}
\end{equation*}
$$

has conformal property. This is the conformal circle found by the author in the conformally connected space ${ }^{2)}$.
(iii) Conformal curvature tensor.

It is well known that the Riemann-Christoffel curvature tensor

$$
R_{\cdot j k h}^{i}=\frac{\partial\left\{\begin{array}{l}
i \\
i k
\end{array}\right\}}{\partial x^{h}}-\frac{\partial\left\{\begin{array}{c}
i \\
i n
\end{array}\right\}}{\partial x^{k}}+\left\{\begin{array}{c}
a \\
a
\end{array}\right\}\left\{\begin{array}{c}
i \\
a h
\end{array}\right\}-\left\{\begin{array}{l}
a \\
j h
\end{array}\right\}\left\{\begin{array}{c}
i \\
a k
\end{array}\right\}
$$

is transformed into $\bar{R}^{i}{ }_{j k h}$ under a conformal transformation $\bar{g}_{j k}=\rho^{2} g_{j k}$ of the fundamental metric tensor $g_{j k}$ by the formulae

[^4]\[

$$
\begin{equation*}
\bar{R}_{j k h}^{i}=R_{\cdot j k h}^{i}-\rho_{j k} \delta_{h}^{i}+\rho_{j h} \delta_{k}^{j}-g_{j k} \rho_{\cdot h}^{i}+g_{j h} \rho_{\cdot k}^{i} . \tag{2.11}
\end{equation*}
$$

\]

Substituting the relation

$$
\rho_{j k}=\bar{I}_{j k}^{0}-\Pi_{j k}^{0}
$$

obtained from (2.6) in the equation (2.11), we have

$$
\begin{aligned}
& \bar{R}_{\cdot j k h}^{i}+\bar{\Pi}_{j k k}^{0} \delta_{h}^{i}-\bar{\Pi}_{j h}^{0} \delta_{k}^{i}+\bar{g}_{j k} \bar{\Pi}_{\infty h}^{i}-\bar{g}_{j h} \bar{\Pi}_{\infty k}^{i} \\
& \quad=R_{\cdot j k h}^{i}+\Pi_{j k}^{0} \delta_{h}^{i}-I \Pi_{j h}^{0} \delta_{k}^{i}+g_{j k} I_{\infty}^{i}-g_{j h} I_{\infty}^{i}
\end{aligned}
$$

which shows that the curvature tensor defined by

$$
\begin{equation*}
C_{\cdot}^{i}{ }_{j k h}=R_{\cdot j k h}^{i}+I I_{j k}^{0} \partial_{h}^{i}-\Pi_{j h}^{0} \partial_{k}^{i}+g_{j k} \Pi_{\infty h}^{i}-g_{j h} \Pi_{\infty k}^{i} \tag{2.12}
\end{equation*}
$$

is a conformal invariant.
(iv) Determination of $\Pi_{j k}^{0}$ in terms of $g_{j k}$.

Since the curvature tensor $C^{i}{ }_{j k h}$ is a conformal one, the condition

$$
\begin{equation*}
C_{. j k i}^{i}=0 \tag{2.13}
\end{equation*}
$$

is also a conformal one. From (2.12) and (2.13), we have

$$
\begin{equation*}
0=R_{j k}+(n-2) \Pi_{j k}^{0}+g_{j k} g^{a b} \Pi_{a b}^{0} \tag{2.14}
\end{equation*}
$$

from which

$$
\begin{equation*}
g^{a b} \Pi_{a b}^{0}=-\frac{R}{2(n-1)} \tag{2.15}
\end{equation*}
$$

where

$$
R_{j k}=R_{\cdot j k i}^{i} \quad \text { and } \quad R=g^{a b} R_{a b}
$$

Substituting (2.15) in (2.14) we find

$$
\begin{equation*}
I_{j k}^{0}=-\frac{R_{j k}}{n-2}+\frac{R g_{j k}}{2(n-1)(n-2)} \tag{2.16}
\end{equation*}
$$

Thus, the functions $I I_{j k}^{0}$ are completely determined in terms of $g_{j k}$ by imposing purely conformal condition (2.13). If we substitute (2.16) in (2.5), we have

$$
\begin{equation*}
\{t, s\}=\frac{1}{2} g_{j k} \frac{\delta^{2} x^{j}}{\delta s^{2}} \frac{\delta^{2} x^{k}}{\delta s^{2}}+\frac{1}{n-2} R_{j k} \frac{d x^{j}}{d s} \frac{d x^{k}}{d s}-\frac{R}{2(n-1)(n-2)} . \tag{2.17}
\end{equation*}
$$

The projective parameter defined by this equation may be called the preferred projective parameter on each curve in Riemann space.

Substituting (2.16) in (2.12), we have

$$
\begin{align*}
C_{\cdot j k h}^{i} & =R_{\cdot j k h}^{i}-\frac{1}{n-2}\left(R_{j k} \delta_{h}^{i}-R_{j h} \delta_{k}^{i}+g_{j k} R_{\cdot h}^{i}-g_{j h} R_{\cdot{ }^{i} k}^{i}\right)  \tag{2.18}\\
& +\frac{R}{(n-1)(n-2)}\left(g_{j k} \delta_{h}^{i}-g_{j h} \partial_{k}^{i}\right)
\end{align*}
$$

which is the Weyl conformal curvature tensor.
(v) The theory of T. Y. Thomas ${ }^{1)}$.

[^5]Under a conformal transformation $\bar{g}_{j k}=\rho^{2} g_{j k}$ of the fundamental tensor, the tensor density of weight $-\frac{2}{n}$ defined by

$$
\begin{equation*}
G_{j k}=g_{j k} / g^{\frac{1}{n}} \tag{2.19}
\end{equation*}
$$

is invariant where $g$ denotes the determinant formed with $g_{j k}$. Then, on each curve in $V_{n}$, a parameter $\sigma$ is defined by

$$
\begin{equation*}
d \sigma^{2}=G_{j k} d x^{j} d x^{k}, \tag{2.20}
\end{equation*}
$$

this parameter $\sigma$ is a conformal one but is not a scalar and its law of transformation under the transformations of coordinates $x^{i^{\prime}}=$ $x^{i^{\prime}}\left(x^{1}, x^{2}, \ldots, x^{n}\right)$ is

$$
\begin{equation*}
d \sigma^{\prime}=\Delta^{-\frac{1}{n}} d \sigma \tag{2.21}
\end{equation*}
$$

where $\Delta$ is the jacobian of the transformation: $\Delta=\left|\frac{\partial x^{i}}{\partial x^{i^{\prime}}}\right|$.
Denoting by $\delta / \delta \sigma$ the formal covariant differentiation along the curve with the use of Christoffel symbols formed with $G_{j k}$ :

$$
{ }^{*} I I_{j k}^{i}=\frac{1}{2} G^{i a}\left(\frac{\partial G_{a j}}{\partial x^{k}}+\frac{\partial G_{a k}}{\partial x^{j}}-\frac{\partial G_{j k}}{\partial x^{a}}\right),
$$

we define the projective parameter $t$ by

$$
\begin{equation*}
\{t, \sigma\}=\frac{1}{2} G_{j k} \frac{\delta^{2} x^{j}}{\delta \sigma^{2}} \frac{\delta^{2} x^{k}}{\delta \sigma^{2}}-{ }^{*} \Pi_{j k}^{0} \frac{d x^{j}}{d \sigma} \frac{d x^{k}}{d \sigma}, \tag{2.22}
\end{equation*}
$$

and require that $t$ is a conformally invariant scalar under the transformation of coordinates. From this assumption we obtain the law of transformation of the functions ${ }^{*} I I_{j k}^{0}$ :

$$
\begin{align*}
& * \Pi_{j^{\prime} k^{\prime}}^{0}=\frac{\partial x^{j}}{\partial x^{j^{\prime}}} \frac{\partial x^{k}}{\partial x^{k^{\prime}}} * \Pi_{j k}^{0}+\left(\frac{\partial \psi_{j^{\prime}}}{\partial x^{k^{\prime}}}-\psi_{i^{\prime}}{ }^{*} \Pi_{j^{\prime} k^{\prime}}^{i^{\prime}}\right)+\psi_{j^{\prime}} \psi_{k^{\prime}}  \tag{2.23}\\
& -\frac{1}{2} G^{a^{\prime} b^{\prime}} \psi_{a^{\prime}} \psi_{b^{\prime}} G_{j^{\prime} k k^{\prime}}
\end{align*}
$$

where

$$
\psi_{j^{\prime}}=\frac{\partial}{\partial x^{j^{\prime}}} \log d^{-\frac{1}{n}}
$$

${ }^{*} I I_{j k}^{0}$ being invariant under a conformal transformation $\bar{g}_{j k}=\rho^{2} g_{j k}$.
The transformation law of the functions ${ }^{*} \Pi_{j k}^{0}$ being thus obtained, we can show by a straightforward calculation that the curves defined by the differential equations

$$
\begin{equation*}
\frac{\delta^{3} x^{i}}{\delta \sigma^{3}}+G_{j k} \frac{\delta^{2} x^{j}}{\partial \sigma^{2}} \frac{\delta^{2} x^{k}}{\delta \sigma^{2}} \frac{d x^{i}}{d \sigma}-{ }^{*} I_{j k}^{0} \frac{d x^{j}}{d \sigma} \frac{d x^{k}}{d \sigma} \frac{d x^{i}}{d \sigma}+{ }^{*} I_{\infty<\infty}^{i} \frac{d x^{k}}{d \sigma}=0 \tag{2.24}
\end{equation*}
$$

is a conformal one, where

$$
{ }^{*} \Pi_{\infty<k}^{i}=G^{i j *} \Pi_{j k}^{0},
$$

and the left-hand side of these equations are the components of a vector density and the quantities defined by
(2.25)

$$
{ }^{*} C \cdot{ }_{j k h}={ }^{*} \Pi_{\cdot}^{i}{ }_{j k h}+{ }^{*} \Pi_{j k}^{0} \delta_{h}^{i}-{ }^{*} \Pi_{j h}^{0} \delta_{k}^{i}+G_{j k}{ }^{*} \Pi_{\infty h}^{i}-G_{j h}{ }^{*} \Pi_{\infty}^{i}
$$

are components of a tensor, where

$$
{ }^{*} I_{\cdot j k h}^{i}=\frac{\partial^{*} \Pi_{j k}^{i}}{\partial x^{h}}-\frac{\partial^{*} \Pi_{j h}^{i}}{\partial x^{k}}+{ }^{*} \Pi_{j k}^{a}{ }^{*} I_{a h}^{i}-{ }^{*} I I_{j h}^{a} * \Pi_{a l c}^{i}
$$

The conformal invariance of (2.24) and (2.25) being evident, we have thus defined a conformal curve and a conformal tensor. If we impose the conformal condition

$$
\begin{equation*}
{ }^{*} C_{\cdot j k i}^{i}=0 \tag{2.26}
\end{equation*}
$$

on ${ }^{*} C^{i}{ }_{j k h}$, the functions ${ }^{*} \Pi_{j k}^{0}$ may be determined completely in terms of $G_{j k}$, thus

$$
\begin{equation*}
{ }^{*} I I_{j k}^{0}=-\frac{{ }^{1} I_{j k}}{n-2}+\frac{{ }^{*} I I G_{j k}}{2(n-1)(n-2)} \tag{2.27}
\end{equation*}
$$

where

$$
{ }^{*} \Pi_{j k}={ }^{*} \Pi_{\cdot j k i}^{i} \quad \text { and } \quad{ }^{*} \Pi=G^{a b *} \Pi_{a b} .
$$

It is shown by a straightforward calculation that, if we substitute (2.27) in (2.24) and (2.25), we obtain precisely (2.10) and (2.18) and we know that (2.24) defines the conformal circle and (2.25) defines the Weyl's conformal curvature tensor.


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