

LCM-stableness in ring extensions

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Introduction

In his paper [4], R. Gilmer introduced the concept of LCM-stableness, relating to GCD-properties of a commutative group ring. The main purpose of this paper is to point out that, in some cases, the necessary and sufficient conditions for a ring extension to be LCM-stable can be given in terms of polynomial grade, originally due to M. Hochster and developed by D. G. Northcott. For this purpose, we shall introduce two further notions, R_2 -stableness and G_2 -stableness, and investigate the relationship between LCM-stableness and them. In these discussions it is important to know when ' $\text{Gr}(I) \geq 2$ ' implies ' $\text{gr}(I) \geq 2$ '. We shall give in the last section an example of a finitely generated ideal I in an integral domain, with $\text{gr}(I) = 1$ and $\text{Gr}(I) \geq 2$.

In §2, we shall show that flatness, INC and LCM-stableness are all equivalent notions for a simple extension which satisfies some conditions (cf. Th. 2.7). In §3, we shall examine a relation between R_2 -stableness and G_2 -stableness, and study universality of LCM-stableness; namely, in Th. 3.5 we shall prove that $A \subset B$ is G_2 -stable if and only if $A[X] \subset B[X]$ is G_2 -stable, and also if and only if $A[X] \subset B[X]$ is R_2 -stable. As a corollary to this theorem, we can see that, in case A is locally a GCD-domain, $A \subset B$ is LCM-stable if and only if so is $A[X] \subset B[X]$.

In §4, we shall examine LCM-stableness of a simple extension $A \subset A[\alpha]$. Let I be the kernel of the canonical homomorphism of $A[X]$ onto $A[\alpha]$. We shall first show in Th. 4.3 that if $I = (f(X))$ ($f(X) \in A[X]$), then $A[Y] \subset A[\alpha][Y]$ is R_2 -stable if and only if $\text{Gr}(c(f)) \geq 3$. Moreover, we shall show in Th. 4.5 that, under some conditions, $A \subset A[\alpha]$ is R_2 -stable if and only if $\text{Gr}(c(f)) \geq 3$. In particular, we can show that if A is locally a GCD-domain, then $A \subset A[\alpha]$ is LCM-stable if and only if $\text{Gr}(c(I)) \geq 3$ (cf. Cor. 4.6).

In §5 and §6, we shall deal with the case of doubly generated extension $A \subset A[\alpha, \beta]$. In §5, we shall study a special case (cf. Th. 5.5). In §6, we shall consider the case where $K(\alpha), K(\beta)$ are linearly disjoint over the quotient field K of A . Firstly we shall treat the case when $A \subset A[\alpha]$ is (faithfully) flat (cf. Prop. 6.1, Th. 6.4), and secondly we shall examine the kernel $K_{\alpha, \beta}$ of the canonical homomorphism of $A[X, Y]$ onto $A[\alpha, \beta]$ by means of polynomial grade (cf. Prop. 6.6, Cor. 6.7, Prop. 6.8). Moreover, in case A is locally a GCD-domain, we shall give a characterization of LCM-stableness of $A \subset A[\alpha, \beta]$ (cf. Th. 6.10).

Finally, in §7, we shall give an example such that R_2 -stablens does not necessarily imply G_2 -stablens.

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Notation and terminology

Throughout this paper, rings will be all integral domains unless otherwise specified and X will be an indeterminate. Moreover, A will be an integral domain with the quotient field K and Ω will be the algebraic closure of K . We let $\text{Spec}(A)$ and $\text{Max}(A)$ stand for the set of all prime ideals of A and that of all maximal ideals of A respectively. An *overring* of A is a subring of K containing A . Let I be an ideal of A . We denote by $\text{Gr}(I)$ and $\text{gr}(I)$ the polynomial grade of I and the classical grade of I respectively. Let J be an ideal of $A[X]$. We denote by $c(J)$ the ideal of A generated by all coefficients of all polynomials in J and we call it the *content* of J .

§1. Basic properties of LCM-stablens

Let A and B be integral domains. We say that $A \subset B$ is *LCM-stable* if $(aA \cap bA)B = aB \cap bB$ for all $a, b \in A$ (cf. [4]). It follows easily from the definition that $A \subset B$ is LCM-stable if and only if $(a :_A b)B = a :_B b$ for all $a, b \in A - \{0\}$. In this section, we examine basic properties of LCM-stablens. The following proposition is a well-known result on flatness.

PROPOSITION 1.1. *If $A \subset B$ is flat, then $A \subset B$ is LCM-stable. In particular, $A \subset A_S$ is LCM-stable for each multiplicatively closed set S in A .*

As for transitivity, the following proposition is important. However it can be proved easily, and so the proof is omitted.

PROPOSITION 1.2. *Let $A_1 \subset A_2 \subset A_3$ be integral domains. Then we have the following statements.*

- (1) *If both $A_1 \subset A_2$ and $A_2 \subset A_3$ are LCM-stable, then so is $A_1 \subset A_3$.*
- (2) *Assume that $IA_3 \cap A_2 = I$ for any ideal I of A_2 . If $A_1 \subset A_3$ is LCM-stable, then so is $A_1 \subset A_2$.*

REMARK 1.3. LCM-stablens of both $A_1 \subset A_2$ and $A_1 \subset A_3$ does not necessarily imply that of $A_2 \subset A_3$. Moreover, LCM-stablens of both $A_1 \subset A_3$ and $A_2 \subset A_3$ does not necessarily imply that of $A_1 \subset A_2$. For example, the former case is $\mathbf{Z} \subset \mathbf{Z}[\sqrt{5}] \subset \mathbf{Z}[(1 + \sqrt{5})/2]$ and the latter case is $\mathbf{Z}[\sqrt{5}] \subset$

$\mathbb{Z}[(1+\sqrt{5})/2] \subset \mathbb{Q}[\sqrt{5}]$, where \mathbb{Z} is the ring of integers and \mathbb{Q} is the rational number field.

PROPOSITION 1.4 (cf. [12], Lemma 2). *Let $A \subset T \subset B$ be integral domains with $T \subset K$. If $A \subset B$ is LCM-stable, then so is $T \subset B$.*

PROOF. Let $x, y \in T - \{0\}$. Put $x = a/c$ and $y = b/c$, where $a, b, c \in A - \{0\}$. Then we have $x :_B y = a :_B b = (a :_A b)B \subset (a :_T b)B = (x :_T y)B$. Thus, $x :_B y = (x :_T y)B$. This shows that $T \subset B$ is LCM-stable.

COROLLARY 1.5. *Let $A \subset B$ be LCM-stable. Then the following statements hold.*

- (1) *For each multiplicatively closed set S in A with $A_S \subset B$, $A_S \subset B$ is LCM-stable.*
- (2) *Suppose that S and T are multiplicatively closed sets of A and B respectively and that $S \subset T$. Then $A_S \subset B_T$ is LCM-stable.*

As for A -algebras, we give some characterizations of LCM-stableness.

PROPOSITION 1.6. *For $A \subset B \subset C$, the following statements are equivalent.*

- (1) *$B \subset C$ is LCM-stable.*
- (2) *For each $P \in \text{Spec}(A)$, $B_P \subset C_P$ is LCM-stable.*
- (3) *For each $M \in \text{Max}(A)$, $B_M \subset C_M$ is LCM-stable.*
- (4) *For each $Q \in \text{Max}(C)$ with $Q \cap B = P$, $B_P \subset C_Q$ is LCM-stable.*

PROOF. We first prove (3) \Rightarrow (1). Let $a, b \in B$ and $M \in \text{Max}(A)$. We have obviously $(a :_B b)C \subset a :_C b$. Since $B_M \subset C_M$ is LCM-stable, $(a :_B b)C_M = (a :_B b)C_M = a :_{C_M} b = (a :_C b)C_M$. Therefore, $(a :_B b)C = a :_C b$. That is, $B \subset C$ is LCM-stable.

(4) \Rightarrow (1) can be proved similarly. Moreover, the assertions (1) \Rightarrow (2) \Rightarrow (3) and (1) \Rightarrow (4) follow immediately from Cor. 1.5.

PROPOSITION 1.7 (cf. [3], Lemma 6.5). *Let B be an overring of A . Then the following statements are equivalent.*

- (1) *$A \subset B$ is LCM-stable.*
- (2) *$(y :_A x)B = B$ for each $x/y \in B$.*
- (3) *$A \subset B$ is flat.*

PROOF. The equivalence of (2) and (3) follows from Lemma 1 and Th. 1 in [12]. The implication (3) \Rightarrow (1) is obvious (cf. Prop. 1.1).

(1) \Rightarrow (2). Let $x/y \in B$, where $x, y \in A$ and $y \neq 0$. Then since $A \subset B$ is LCM-stable, we have $(y :_A x)B = y :_B x = B$.

F. Richman and D. E. Dobbs gave some characterizations of a Prüfer domain

in terms of flatness (cf. [12], Th. 4 and [2], Prop. 3.1). By virtue of Prop. 1.7, we have a new characterization of a Prüfer domain.

COROLLARY 1.8. *The following statements are equivalent.*

- (1) *A is a Prüfer domain.*
- (2) *For any integral domain B containing A, $A \subset B$ is LCM-stable.*
- (3) *For each $u \in K$, $A \subset A[u]$ is LCM-stable.*

Next, we give a sufficient condition for $A \subset B$ to be LCM-stable.

PROPOSITION 1.9. *Let $A \subset B$ be integral domains. If $A \subset A[x, y]$ is LCM-stable for any $x, y \in B$, then $A \subset B$ is LCM-stable.*

PROOF. Let $a, b \in A$ and assume that $ax = by \in aB \cap bB$, where $x, y \in B$. Then since $A \subset A[x, y]$ is LCM-stable, we have $ax = by \in aA[x, y] \cap bA[x, y] = (aA \cap bA)A[x, y] \subset (aA \cap bA)B$. Therefore, $aB \cap bB = (aA \cap bA)B$. Thus, $A \subset B$ is LCM-stable.

REMARK 1.10. In the above proposition, we can not replace two elements x and y by a single element x . In fact, let $A = \mathcal{Q}[s, t]_{(s,t)}$, where s, t are indeterminates over \mathcal{Q} . We can take $x, y \in \Omega$ with the properties that $x^2 + sx + s^2 = 0$, $y^2 + ty + t^2 = 0$ and $tx = sy$. Then since A is integrally closed and $A[x, y]$ is integral over A , $A[z]$ is a free A -module for each $z \in A[x, y]$. In particular, $A \subset A[z]$ is LCM-stable for each $z \in A[x, y]$. On the other hand, since $(s, t) \neq A$, $A \subset A[x, y]$ is not LCM-stable (cf. Prop. 5.3).

It is well-known that for an overring B of A , if $A \subset B$ is flat and B is integral over A , then $A = B$ (see [12]). This fact suggests to us the following propositions on LCM-stableness.

PROPOSITION 1.11. *Let A be a quasi-local domain with the unique maximal ideal M and B be an integral domain containing A . Assume that $MB \neq B$. If $A \subset B$ is LCM-stable, then we have $B \cap K = A$.*

PROOF. Let $x = a/b \in B \cap K$, where $a, b \in A - \{0\}$. Since $A \subset B$ is LCM-stable, we have $a = bx \in (aA \cap bA)B$. Therefore, there exist $x_i \in aA \cap bA$ and $\beta_i \in B$ such that $a = bx = \sum_{i=1}^r x_i \beta_i$. We can put $x_i = ay_i = bz_i$ for $1 \leq i \leq r$, where $y_i, z_i \in A$. Then we have $1 = \sum_{i=1}^r y_i \beta_i$. Since $MB \neq B$, there exists i such that $y_i \notin M$. Therefore, $a \in bA$. Thus, $x \in A$. That is, we have $B \cap K = A$.

From Prop. 1.11 and Prop. 1.6, the following corollaries follow easily.

COROLLARY 1.12. *Let $A \subset B$ be integral domains. Assume that for each $P \in \text{Spec}(A)$ there exists $Q \in \text{Spec}(B)$ such that $Q \cap A = P$. If $A \subset B$ is LCM-stable, then we have $B \cap K = A$.*

COROLLARY 1.13. *Let B be an overring of A with $B \neq A$. Assume that $A \subset B$ is LCM-stable. Then there exists $M \in \text{Max}(A)$ such that $MB = B$. In particular, B is not integral over A .*

Finally, we give a property of LCM-stableness in terms of prime ideals. For $P \in \text{Spec}(A)$, we denote by $\text{ht}(P)$ the height of P .

PROPOSITION 1.14 (cf. [3], Prop. 6.4). *Assume that $A \subset B$ is LCM-stable. Let $P \in \text{Spec}(B)$ with $\text{ht}(P) \leq 1$. Then we have $\text{ht}(P \cap A) \leq 1$.*

PROOF. By Cor. 1.5, $A_{P \cap A} \subset B_P$ is LCM-stable. Therefore, we may assume that A and B are quasi-local domains with the maximal ideals P and M , respectively, and that $M \cap A = P \neq 0$ and $\text{ht}(M) \leq 1$. Let $a \in P - \{0\}$. Since $\text{ht}(M) = 1$ and B is a quasi-local domain, we have $M = \text{rad}(aB)$. On the other hand, since $A \subset B$ is LCM-stable and $PB \neq B$, $aB \cap A = aA$ by Prop. 1.11. Therefore, $P = M \cap A = \text{rad}(aB) \cap A = \text{rad}(aB \cap A) = \text{rad}(aA)$. This implies that $\text{ht}(P) = 1$.

§2. LCM-stableness of $A \subset A[\alpha]$ with $\alpha^m \in K$

Let $\alpha \in \Omega$ with $\alpha^m \in K$ for some $m > 0$. In this section, we shall give some characterizations for $A \subset A[\alpha]$ to be LCM-stable.

PROPOSITION 2.1. *Let A be a quasi-local domain and $\alpha \in \Omega$. Assume that $\alpha^m = u \in K - A$ and that $A \subset A[\alpha]$ is LCM-stable. Then we have $\alpha^{-1} \in A[\alpha]$. Therefore, α^{-1} is integral over A and also so is u^{-1} .*

PROOF. Put $u = a/b$, where $a, b \in A - \{0\}$. Since $A \subset A[\alpha]$ is LCM-stable, we have $a = b\alpha^m \in (aA \cap bA)A[\alpha]$. Therefore, there exist $r > 0$ and $x_i, y_i, z_i \in A$ such that $a = b\alpha^m = \sum_{i=0}^r x_i \alpha^i$ and $x_i = ay_i = bz_i$ for $0 \leq i \leq r$. Now since $u \notin A$, y_i is a non-unit for every i . Thus, $1 - y_i$ is a unit in A for each i . Therefore, we have $\alpha^{-1} = (1 - y_0)^{-1} \sum_{i=1}^r y_i \alpha^{i-1} \in A[\alpha]$. This completes the proof.

Let $A \subset B$ be integral domains. We say that $A \subset B$ is INC if two different prime ideals of B with the same contraction in A can not be comparable (see [7], [16]).

COROLLARY 2.2. *Let $\alpha \in \Omega$ with $\alpha^m \in K$ for some $m > 0$. If $A \subset A[\alpha]$ is LCM-stable, then $A \subset A[\alpha]$ is INC.*

PROOF. By virtue of §1 and [16], we may assume that A is a quasi-local domain. Then $A \subset A[\alpha]$ is INC by Prop. 2.1 and Cor. 3.2 in [16].

REMARK 2.3. The converse of Cor. 2.2 is false as is seen in $\mathbb{Z}[\sqrt{5}] \subset$

$\mathbf{Z}[(1 + \sqrt{5})/2]$.

Let $\alpha \in \Omega$. Hereafter, by K_α we shall denote the kernel of the canonical homomorphism of $A[X]$ onto $A[\alpha]$. From now on, we examine some conditions for the converse of Cor. 2.2 to be true.

COROLLARY 2.4. *Let $\alpha \in \Omega$ with $\alpha^m \in K$ for some $m > 0$. Assume that K_α is invertible. Then $A \subset A[\alpha]$ is LCM-stable if and only if $A \subset A[\alpha]$ is INC; and when that is so, $A \subset A[\alpha]$ is flat.*

PROOF. The assertions follow immediately from Prop. 1.1, Cor. 2.2, Cor. 3.2 in [16] and Cor. 2.20 in [10].

Here, we need two lemmas relating to a linear base. It is well-known that A is integrally closed if and only if K_u has a linear base for each $u \in K$ (cf. (11.13) in [8] and [11]). The following lemma is a generalization of Th. 1 in [11] which can be proved in the same manner.

LEMMA 2.5. *Let $\alpha \in \Omega$ with $\alpha^m = u \in K - \{0\}$ for some $m > 0$ and put $u = a/b$ where $a, b \in A - \{0\}$. Put $B_u = \{dx - e \mid d, e \in A \text{ and } be = ad\}$ and $B_\alpha = \{dX^m - e \mid d, e \in A \text{ and } be = ad\}$. Then the following statements are equivalent.*

- (1) $K_u = B_u A[X]$; that is, K_u has a linear base.
- (2) If $bX^m - a$ is irreducible over K , then $K_\alpha = B_\alpha A[X]$.
- (3) $(a, b)^n \cap (b^{n+1} :_A a) \subset b^n A$ for each $n > 0$.

Generally, it is easily shown that for $u \in K$ if A is integrally closed in $A[u]$, then K_u has a linear base (cf. (11.13) in [8]). On the other hand, the converse is false as is seen in $A \subset A[u]$, where $A = \mathbf{Z} + \mathbf{Z}2\sqrt{-1}$ and $u = 1/2\sqrt{-1}$. Therefore, the following lemma is a slight generalization of the $u - u^{-1}$ Lemma which are essentially proved in Th. 67 in [7].

LEMMA 2.6. *Let A be a quasi-local domain with the unique maximal ideal M and take $u \in K$. Assume that K_u has a linear base. If $K_u \not\subset MA[X]$, then either $u \in A$ or $u^{-1} \in A$.*

THEOREM 2.7. *Let $\alpha \in \Omega - \{0\}$ with $\alpha^m = u \in K$ for some $m > 0$. Put $u = a/b$, where $a, b \in A - \{0\}$. Assume that K_u has a linear base and that $bX^m - a$ is irreducible over K . Then the following statements are equivalent.*

- (1) $A \subset A[\alpha]$ is LCM-stable.
- (2) $A \subset A[\alpha]$ is INC.
- (3) $A \subset A[\alpha]$ is flat.
- (4) (a, b) is invertible.

PROOF. Since incomparability, LCM-stableness, flatness and the property

that K_u has a linear base, where $u \in K$, are local properties (see [16] and §1), we may assume that A is a quasi-local domain with the unique maximal ideal M . Then we have only to show the implications (2) \Rightarrow (4) and (4) \Rightarrow (3), since the others are obvious (cf. Cor. 2.2).

(2) \Rightarrow (4). Assume that $A \subset A[\alpha]$ is INC. Then we have $c(K_\alpha) = A$ by Cor. 3.2 in [16]. On the other hand, it follows easily from Lemma 2.5 that $c(K_u) = c(K_u)$. Therefore, $K_u A[X] \not\subset MA[X]$. Thus, by Lemma 2.6, we have either $u \in A$ or $u^{-1} \in A$. That is, (a, b) is principal.

(4) \Rightarrow (3). Assume that (a, b) is invertible. Since A is a quasi-local domain, we have easily either $u \in A$ or $u^{-1} \in A$. Suppose that $u \in A$. Then we have $K_\alpha = (X^m - u)A[X]$ by the assumption. Therefore, $A \subset A[\alpha]$ is obviously flat. We now proceed to the case $u^{-1} \in A$. Similarly, we have $K_\alpha = (u^{-1}X^m - 1)A[X]$. Therefore, $A \subset A[\alpha]$ is flat by Cor. 2.20 in [10].

COROLLARY 2.8 (cf. Cor. 4.4). *Let $aX^m - b$ be a prime element of $A[X]$, where $m > 0$ and $a, b \in A - \{0\}$. Then the following statements are equivalent.*

- (1) $A \subset A[X]/(aX^m - b)$ is LCM-stable.
- (2) $A \subset A[X]/(aX^m - b)$ is flat.
- (3) $(a, b) = A$.

§3. Universality

In this section, we shall examine the universality of LCM-stableness. For this purpose, we prepare two notions, R_2 -stableness and G_2 -stableness, related to LCM-stableness. Let $A \subset B$ be integral domains. We say that $A \subset B$ is G_2 -stable if $\text{Gr}(IB) \geq 2$ for each non-zero finitely generated ideal I of A with $\text{Gr}(I) \geq 2$. Moreover, we say that $A \subset B$ is R_2 -stable if $a :_B b = a$ for any $a, b \in A - \{0\}$ with $a :_A b = a$. Obviously, if $A \subset B$ is LCM-stable, then $A \subset B$ is R_2 -stable and if A is a GCD-domain, then the converse holds. Let I be an ideal of A . If $\text{Gr}(I) \leq 2$, then we have $A :_K I = A$. But the converse is false as is seen in Remark 2.4 in [6]. On the other hand, in case I is finitely generated, $\text{Gr}(I) \geq 2$ if and only if $A :_K I = A$ by virtue of Th. 7 of Chap. 5 in [9]. Therefore, by Ex. 1 and Ex. 2 (p. 102) in [7], if $A \subset B$ is G_2 -stable, then $A \subset B$ is R_2 -stable and moreover, if A is a Noetherian domain, then the converse is true. However, neither G_2 -stableness nor R_2 -stableness does necessarily imply LCM-stableness as is seen in $\mathbb{Z}[\sqrt{5}] \subset \mathbb{Z}[(1 + \sqrt{5})/2]$. So we first study a regular sequence of length 2 in a polynomial ring. We denote by $Z(R)$ the set of all zero-divisors of a ring R .

LEMMA 3.1. *Let R be a commutative ring with identity and Q be the total quotient ring of R . Let $f(X) = a_0 + a_1X + \dots + a_kX^k \in R[X]$. Assume that $c(f)$ contains a non-zero-divisor. Then the following statements are equivalent.*

- (1) $a :_{R[X]} f(X) = a$ for each $a \in R - Z(R)$.

- (2) $a:_{R[X]} f(X) = a$ for each $a \in c(f) - Z(R)$.
 (3) $a:_R c(f) = a$ for each $a \in c(f) - Z(R)$.
 (4) $a:_R c(f) = a$ for some $a \in c(f) - Z(R)$.
 (5) $R:_{\mathcal{Q}} c(f) = R$.

PROOF. The equivalences (3) \Leftrightarrow (4) \Leftrightarrow (5) are easy and (2) \Leftrightarrow (3) follows from Th. 7 of Chap. 5 in [9]. Moreover, (1) \Rightarrow (2) is obvious.

(2) \Rightarrow (1). Let $a \in R - Z(R)$. By the assumption, there exists $b \in c(f) - Z(R)$. Since $ab \in c(f) - Z(R)$, we have $ab:_{R[X]} f(X) = ab$. Thus, $a:_{R[X]} f(X) = a$.

THEOREM 3.2. *Let R be a commutative ring with identity and \mathcal{Q} be the total quotient ring of R . Let $f(X), g(X) \in R[X]$. Assume that $c(f)$ contains a non-zero-divisor. Then $f(X):_{R[X]} g(X) = f(X)$ if and only if (i) $f(X):_{\mathcal{Q}[X]} g(X) = f(X)$ and (ii) $R:_{\mathcal{Q}} (c(f) + c(g)) = R$.*

PROOF. Suppose first that $f(X):_{R[X]} g(X) = f(X)$. Since $R[X] \subset \mathcal{Q}[X]$ is flat, we have obviously $f(X):_{\mathcal{Q}[X]} g(X) = f(X)$. Let $a/b \in R:_{\mathcal{Q}} (c(f) + c(g))$, where $a \in R$ and $b \in R - Z(R)$. Then there exist $\phi(X), \psi(X) \in R[X]$ such that $af(X) = b\phi(X)$, $ag(X) = b\psi(X)$. Since $b \notin Z(R)$, we have $f(X)\psi(X) = g(X)\phi(X)$. Therefore, $\phi(X) \in f(X):_{R[X]} g(X) = f(X)$. That is, we can take $c(X) \in R[X]$ so that $\phi(X) = c(X)f(X)$. Since $f(X) \notin Z(R[X])$, we have $a = bc(X) \in bR[X] \cap R = bR$. Thus, $a/b \in R$. This implies that $R:_{\mathcal{Q}} (c(f) + c(g)) = R$.

Conversely, let $h(X) \in f(X):_{R[X]} g(X)$ and take $\phi(X) \in R[X]$ so that $h(X)g(X) = f(X)\phi(X)$. Since $h(X) \in f(X)\mathcal{Q}[X]$ by (i), there exist $a \in R - Z(R)$ and $\psi(X) \in R[X]$ such that $ah(X) = f(X)\psi(X)$. Then since $f(X) \notin Z(R[X])$, we have $a\phi(X) = g(X)\psi(X)$. Put $F(X) = X^n f(X) + g(X)$, where $n > \deg g$. Then $c(F) = c(f) + c(g)$ and by (ii) $R:_{\mathcal{Q}} c(F) = R$. Since $F(X)\psi(X) = a(X^n h(X) + \phi(X))$, we have $\psi(X) \in aR[X]$ by Lemma 3.1. Therefore, $h(X) \in f(X)R[X]$ by noting $a \notin Z(R)$. That is, $f(X):_{R[X]} g(X) = f(X)$.

COROLLARY 3.3. *With the notation of Th. 3.2, let $a \in R - Z(R)$. Then $a:_{R[X]} f(X) = a$ if and only if $R:_{\mathcal{Q}} (a, c(f)) = R$. Moreover, assume that $R:_{\mathcal{Q}} c(f) = R$. Then for each $b \in R - \{0\}$, $a:_{R[X]} bf(X) = a$ if and only if $a:_R b = a$.*

PROPOSITION 3.4. *Let I be a non-zero proper ideal of $A[X]$. If $\text{Gr}(I) \geq 2$, then $\text{gr}(I) \geq 2$.*

PROOF. Suppose that $I \cap A = 0$. Then we have $IK[X] \neq K[X]$. Therefore, $\text{Gr}(IK[X]) \leq 1$. On the other hand, $\text{Gr}(I) \leq \text{Gr}(IK[X]) \leq 1$ by Ex. 10 of Chap. 5 in [9], a contradiction. Thus, $I \cap A \neq 0$. Take $a \in I \cap A - \{0\}$. Since $\text{Gr}(I/(a)) \geq 1$ by Th. 15 of Chap. 5 in [9], we have obviously $\text{gr}(I/(a)) \geq 1$. Thus, $\text{gr}(I) \geq 2$.

With these preparations, we study universality.

THEOREM 3.5. *For $A \subset B$, the following statements are equivalent.*

- (1) $A \subset B$ is G_2 -stable.
- (2) $A[X] \subset B[X]$ is G_2 -stable.
- (3) $A[X] \subset B[X]$ is R_2 -stable.

PROOF. (1) \Rightarrow (3). Let $f(X), g(X) \in A[X] - \{0\}$ and assume that $f(X) :_{A[X]} g(X) = f(X)$. Then by Th. 3.2, we have (i) $f(X) :_{K[X]} g(X) = f(X)$ and (ii) $A :_K (c(f) + c(g)) = A$. Let L be the quotient field of B . By (i), we have immediately $f(X) :_{L[X]} g(X) = f(X)$. Since $\text{Gr}(c(f) + c(g)) \geq 2$ by (ii) and $A \subset B$ is G_2 -stable, $\text{Gr}((c(f) + c(g))B) \geq 2$. Therefore, $B :_L (c(f) + c(g)) = B$. Thus, $f(X) :_{B[X]} g(X) = f(X)$ by Th. 3.2. That is, $A[X] \subset B[X]$ is R_2 -stable.

(3) \Rightarrow (2). Let I be a finitely generated ideal of $A[X]$ with $\text{Gr}(I) \geq 2$. We may assume that $I \neq A[X]$. Then by Prop. 3.4 we have $\text{gr}(I) \geq 2$. Since $A[X] \subset B[X]$ is R_2 -stable, $\text{gr}(IB) \geq 2$. Therefore, $\text{Gr}(IB) \geq 2$. That is, $A[X] \subset B[X]$ is G_2 -stable.

The implication (2) \Rightarrow (1) follows easily from the definition.

If $A[X] \subset B[X]$ is R_2 -stable, then obviously so is $A \subset B$. The converse is false as is seen in §7. As for the converse, we consider the following condition. We say that A satisfies the condition (*) if A_P is a valuation ring for any $P \in \text{Spec}(A)$ with $\text{gr}(P) = 1$. By Th. 2.2 in [14], if A is a GCD-domain, then A satisfies (*). Moreover, if A satisfies (*), A is integrally closed by Cor. 2.16 in [1].

THEOREM 3.6. *Assume that A satisfies the condition (*). Then for $A \subset B$, $A \subset B$ is G_2 -stable if and only if $A \subset B$ is R_2 -stable.*

PROOF. Suppose that $A \subset B$ is R_2 -stable. Let I be a finitely generated ideal of A with $\text{Gr}(I) \geq 2$. We may assume that $IB \neq B$. Then there exists $Q \in \text{Spec}(B)$ such that $\text{Gr}(IB) = \text{Gr}(Q)$ by Th. 16 of Chap. 5 in [9]. Put $Q \cap A = P$. Then we have $I \subset P$. Assume that $\text{gr}(P) = 1$. By the assumption, A_P is a valuation ring. Therefore, IA_P is a proper principal ideal of A_P . On the other hand, since $A :_K I = A$, $A_P :_K IA_P = A_P$. This is a contradiction. Thus, $\text{gr}(P) \geq 2$. Since $A \subset B$ is R_2 -stable, $\text{gr}(PB) \geq 2$. Therefore, $\text{Gr}(IB) = \text{Gr}(Q) \geq \text{Gr}(PB) \geq 2$. That is, $A \subset B$ is G_2 -stable.

COROLLARY 3.7. *Let A be a GCD-domain. Then the following statements are equivalent.*

- (1) $A \subset B$ is LCM-stable.
- (2) $A \subset B$ is R_2 -stable.
- (3) $A \subset B$ is G_2 -stable.
- (4) $A[X] \subset B[X]$ is LCM-stable.

- (5) $A[X] \subset B[X]$ is R_2 -stable.
- (6) $A[X] \subset B[X]$ is G_2 -stable.

COROLLARY 3.8. *Let A be locally a GCD-domain. Then $A \subset B$ is LCM-stable if and only if $A[X] \subset B[X]$ is LCM-stable.*

Hereafter, we shall fix $A \subset B$ and let L be the quotient field of B . Assume that A is integrally closed. With this assumption, we examine LCM-stableness of $A[X] \subset B[X]$.

LEMMA 3.9. *Let $f(X), g(X) \in A[X] - \{0\}$. If $f(X):_{K[X]} g(X) = f(X)$, then we have $f(X):_{A[X]} g(X) = (A:_{K} (c(f) + c(g)))f(X)A[X]$.*

PROOF. Let $x \in A:_{K} (c(f) + c(g))$. Then $xf(X), xg(X) \in A[X]$. Therefore, we have $xf(X) \in f(X):_{A[X]} g(X)$. Thus, $(A:_{K} (c(f) + c(g)))f(X)A[X] \subset f(X):_{A[X]} g(X)$.

Conversely, let $h(X) \in f(X):_{A[X]} g(X)$. Then there exists $\phi(X) \in A[X]$ such that $h(X)g(X) = f(X)\phi(X)$. Since $f(X):_{K[X]} g(X) = f(X)$, there exist $a \in A - \{0\}$ and $\psi(X) \in A[X]$ such that $ah(X) = f(X)\psi(X)$. Then we have $a\phi(X) = g(X)\psi(X)$. Put $F(X) = f(X)X^n + g(X)$, where $n > \deg g$. Then $c(F) = c(f) + c(g)$ and $a(h(X)X + \phi(X)) = F(X)\psi(X)$. Therefore, $h(X)X^n + \psi(X) \in F(X)K[X] \cap A[X]$. On the other hand, since A is integrally closed, we have $F(X)K[X] \cap A[X] = (A:_{K} c(F))F(X)A[X]$ by Th. B in [15]. Thus, there exist $x_i \in A:_{K} c(F)$ and $g_i(X) \in A[X]$ such that $h(X)X^n + \phi(X) = \sum_{i=1}^r x_i F(X)g_i(X)$. Therefore, we have $\psi(X) = a \sum_{i=1}^r x_i g_i(X)$. Thus, $h(X) = \sum_{i=1}^r x_i f(X)g_i(X) \in (A:_{K} c(F))f(X)A[X]$. That is, $f(X):_{A[X]} g(X) \subset (A:_{K} (c(f) + c(g)))f(X)A[X]$. This completes the proof.

PROPOSITION 3.10. *Assume that $A[X] \subset B[X]$ is LCM-stable. Then for each non-zero finitely generated ideal I of A , $B:_{L} I = (A:_{K} I)B$.*

PROOF. Suppose that $I = (a, a_0, a_1, \dots, a_n)$ is a non-zero finitely generated ideal of A (in case I is principal, we set $n=0$ and $a_0=a$), and put $f(X) = \sum_{i=0}^n a_i X^i$. By Lemma 3.9, we have $f(X):_{A[X]} a = (A:_{K} I)f(X)A[X]$. On the other hand, generally $(A:_{K} I)f(X)B[X] \subset (B:_{L} I)f(X)B[X] \subset f(X):_{B[X]} a$. Since $A[X] \subset B[X]$ is LCM-stable, $(A:_{K} I)f(X)B[X] = (B:_{L} I)f(X)B[X]$. Therefore, $(A:_{K} I)B = B:_{L} I$.

THEOREM 3.11. *Assume that B is integrally closed and that L is algebraic over K . Then the following statements are equivalent.*

- (1) $A[X] \subset B[X]$ is LCM-stable.
- (2) $B:_{L} I = (A:_{K} I)B$ for any non-zero finitely generated ideal I of A .
- (3) $a:_{B} I = (a:_{A} I)B$ for any $a \in A - \{0\}$ and non-zero finitely generated ideal I of A .

PROOF. (1) \Rightarrow (2). This follows from Prop. 3.10.

(2) \Rightarrow (1). Let $f(X), g(X) \in A[X] - \{0\}$. Since $K[X]$ is a PID, there exist $d(X) \in K[X]$ and $f_1(X), g_1(X) \in A[X]$ such that $f(X) = d(X)f_1(X)$, $g(X) = d(X)g_1(X)$ and $f_1(X):_{K[X]} g_1(X) = f_1(X)$. Then $f(X):_{A[X]} g(X) = f_1(X):_{A[X]} g_1(X)$. Therefore, we may assume that $f(X):_{K[X]} g(X) = f(X)$. Then we have obviously $f(X):_{L[X]} g(X) = f(X)$. Thus, since B is integrally closed, by Lemma 3.9 and the assumption we have

$$\begin{aligned} f(X):_{B[X]} g(X) &= (B:_L(c(f) + c(g))f(X)B[X] \\ &= (A:_K(c(f) + c(g))f(X)B[X] \\ &= (f(X):_{A[X]} g(X))f(X)B[X]. \end{aligned}$$

Therefore, $A[X] \subset B[X]$ is LCM-stable.

(2) \Leftrightarrow (3). Since L is algebraic over K , $L = B \otimes_A K$ and the assertion follows easily.

§4. Simple extensions

In this section, we shall give a necessary and sufficient condition for a simple extension over A , which is locally a GCD-domain, to be LCM-stable and discuss a difference between LCM-stableness and flatness. Let I be a finitely generated proper ideal of A . It is well-known that if $\text{gr}(I) \geq 2$, then $\text{Gr}(I) \geq 2$, or equivalently $A:_K I = A$, and if A is a Noetherian domain, then the converse is true. Moreover, the converse holds for a polynomial ring as is seen in Prop. 3.4. More generally we can show that this is true for a wider class of domains, containing Noetherian domains and Krull domains. We say that I has a primary decomposition if $I = \bigcap_{i=1}^r Q_i$ for some primary ideals Q_1, Q_2, \dots, Q_r .

LEMMA 4.1. *Assume that each proper principal ideal of A has a primary decomposition. Let I be a finitely generated proper ideal of A . If $\text{Gr}(I) \geq 2$, then we have $\text{gr}(I) \geq 2$.*

PROOF. Suppose that $\text{Gr}(I) \geq 2$. In particular, $I \neq 0$. Let $a \in A - \{0\}$. Then we have $a:_A I = a$. Let $aA = \bigcap_{i=1}^r Q_i$ be an irredundant primary decomposition of aA . We put $P_i = \text{rad}(Q_i)$. Then $Z(A/aA) = \bigcup_{i=1}^r P_i$. Assume that $I \subset Z(A/aA)$. There exists i such that $I \subset P_i$. Since I is finitely generated, $I^n \subset Q_i$ for some $n > 0$. Take $b \in \bigcap_{j \neq i} Q_j - Q_i$. Then $b \notin aA$ and $bI^n \subset aA$. Since $a:_A I = a$, we have $a:_A I^n = a$. This is a contradiction. Therefore, $I \not\subset Z(A/aA)$, by which we have easily $\text{gr}(I) \geq 2$.

The following Lemma follows immediately from Ex. 10 of Chap. 5, Th. 5 of Chap. 6 in [9] and Th. 3.5 in [13].

LEMMA 4.2. Let I be an ideal of $A[X]$ generated by an $A[X]$ -sequence of length n ($n \geq 0$) and let $a(X) \in A[X]$ with $a(X) \notin I$. Let Q be a minimal prime ideal of $I :_{A[X]} a(X)$. Put $Q \cap A = P$. Then $\text{Gr}(Q) = \text{Gr}(QA[X]_Q) = n$ and if $\text{Gr}(P) \geq n$, then $Q = PA[X]$.

Throughout the following Th. 4.3, Cor. 4.4 and Th. 4.5, let $f(X)$ be a prime element of $A[X]$ with $\deg f \geq 1$ and let $B = A[X]/(f(X))$.

THEOREM 4.3. $A[Y] \subset B[Y]$ is R_2 -stable if and only if $\text{Gr}(c(f)) \geq 3$, where Y is an indeterminate. In particular, if $\text{Gr}(c(f)) \geq 3$, then $A \subset B$ is R_2 -stable.

PROOF. Suppose that $A[Y] \subset B[Y]$ is R_2 -stable. We may assume that $c(f) \neq A$. Let $a \in c(f) - \{0\}$. Since $f(X)$ is a prime element of $A[X]$, $a :_{A[Y]} f(Y) = a$. Also, since $A[Y] \subset B[Y]$ is R_2 -stable, $a :_{B[Y]} f(Y) = a$. Therefore, $\{f(X), a, f(Y)\}$ is an $A[X, Y]$ -sequence in $c(f)A[X, Y]$. Thus, $\text{Gr}(c(f)) \geq 3$.

Conversely, suppose that $\text{Gr}(c(f)) \geq 3$. Let $a(Y), b(Y) \in A[Y] - \{0\}$ and assume that $a(Y) :_{A[Y]} b(Y) = a(Y)$. Since $f(X)$ is a prime element of $A[X]$, we have either $f(X) :_{A[X, Y]} a(Y) = f(X)$ or $f(X) :_{A[X, Y]} b(Y) = f(X)$. Say $f(X) :_{A[X, Y]} a(Y) = f(X)$. If $(f(X), a(Y), b(Y)) = A[X, Y]$, then $(a(Y), b(Y))B[Y] = B[Y]$ and therefore, we have $a(Y) :_{B[Y]} b(Y) = a(Y)$. So suppose that $(f(X), a(Y), b(Y)) \neq A[X, Y]$. Assume that $\{f(X), a(Y), b(Y)\}$ is not an $A[X, Y]$ -sequence. Then there exists $h(X, Y) \in A[X, Y]$ such that $b(Y)h(X, Y) \in (f(X), a(Y))$ and $h(X, Y) \notin (f(X), a(Y))$. Let Q be a minimal prime ideal of $(f(X), a(Y)) :_{A[X, Y]} h(X, Y)$ and put $Q \cap A[Y] = P$. Then $Q \supset (f(X), a(Y), b(Y))$ and therefore, $P \supset (a(Y), b(Y))$. Thus, $\text{Gr}(P) \geq 2$. By Lemma 4.2, we have $\text{Gr}(Q) = 2$ and $Q = PA[X, Y]$. Then since $f(X) \in Q$, $c(f) \subset P \cap A$. Therefore, $\text{Gr}(Q) = \text{Gr}(P) \geq \text{Gr}(c(f)) \geq 3$. This is a contradiction. Thus, $\{f(X), a(Y), b(Y)\}$ is an $A[X, Y]$ -sequence. That is, $a(Y) :_{B[Y]} b(Y) = a(Y)$. This implies that $A[Y] \subset B[Y]$ is R_2 -stable.

COROLLARY 4.4. Let A be a GCD-domain. Then $A \subset B$ is LCM-stable if and only if $\text{Gr}(c(f)) \geq 3$.

THEOREM 4.5. Assume that each principal proper ideal of A has a primary decomposition. Then the following statements are equivalent.

- (1) $A \subset B$ is R_2 -stable.
- (2) $A[X] \subset B[X]$ is R_2 -stable.
- (3) $\text{Gr}(c(f)) \geq 3$.

PROOF. We have only to prove (1) \Rightarrow (3). Suppose that $A \subset B$ is R_2 -stable. We may assume that $c(f) \neq A$. By Lemma 3.1, $\text{Gr}(c(f)) \geq 2$. Therefore, by Lemma 4.1, there exist $a, b \in c(f)$ such that $\{a, b\}$ is an A -sequence. Since $A \subset B$ is R_2 -stable, we have $a :_B b = a$. Thus, $\{f(X), a, b\}$ is an $A[X]$ -sequence in $c(f)A[X]$. Therefore, $\text{Gr}(c(f)) \geq 3$.

LEMMA 4.6. *Let I be a finitely generated ideal of A . Then we have $\text{Gr}(I) = \inf \{ \text{Gr}(IA_M); M \in \text{Max}(A) \}$.*

PROOF. Let $A(Y)$ be a localization of $A[Y]$ by a multiplicatively closed set consisting of all polynomials $f(Y)$ of $A[Y]$ with $\text{c}(f) = A$, where Y is a finite set of variables. By Cor. 1 of Prop. 2 in [5], we have $\text{Gr}(I) = \text{Gr}(IA(Y))$. Therefore, $\inf \{ IA_M \} = \inf \{ IA_M(Y) \} = \inf \{ IA(Y)_{MA(Y)} \}$, $M \in \text{Max}(A)$. Since there exists a bijection between $\text{Max}(A)$ and $\text{Max}(A(Y))$, we may assume that $\text{Gr}(I) = n$ and $\{ a_1, a_2, \dots, a_n \}$ is an A -sequence in I . Then $\text{Gr}(I/(a_1, a_2, \dots, a_n)) = \text{Gr}(I) - n = 0$ and $\inf \{ \text{Gr}(IA_M/(a_1, a_2, \dots, a_n)) \} = \inf \{ \text{Gr}(IA_M) \} - n$, $M \in \text{Max}(A)$. Therefore, we may assume that $\text{Gr}(I) = 0$. Then since I is finitely generated, there exists $x \in A - \{0\}$ such that $xI = 0$ by Th. 8 of Chap. 5 in [9]. Take $M \in \text{Max}(A)$ so that $x/1 \neq 0$ in A_M . Then we have $\text{Gr}(IA_M) = 0$ by Th. 8 of Chap. 5 in [9]. This completes the proof.

THEOREM 4.7. *Let A be locally a GCD-domain and $\alpha \in \Omega - \{0\}$. Let I be the kernel of the canonical homomorphism of $A[X]$ onto $A[\alpha]$. Then $A \subset A[\alpha]$ is LCM-stable if and only if $\text{Gr}(\text{c}(I)) \geq 3$.*

PROOF. Suppose that $\text{Gr}(\text{c}(I)) \geq 3$. Let $M \in \text{Max}(A)$. Since A_M is a GCD-domain, there exists $f_M(X) \in A_M[X]$ such that $IA_M[X] = f_M(X)A_M[X]$. Therefore, we have $\text{c}(IA_M[X]) = \text{c}(f_M)$. Thus, $\text{Gr}(\text{c}(f_M)) \geq 3$. By Cor. 4.4, $A_M \subset A_M[\alpha]$ is LCM-stable. Therefore, $A \subset A[\alpha]$ is LCM-stable by Prop. 1.6.

Conversely, suppose that $A \subset A[\alpha]$ is LCM-stable. Let $M \in \text{Max}(A)$. Take $f_M(X) \in A_M[X]$ so that $IA_M[X] = f_M(X)A_M[X]$. Since $A_M \subset A_M[\alpha]$ is LCM-stable by Cor. 1.5, we have $\text{Gr}(\text{c}(IA_M[X])) = \text{Gr}(\text{c}(f_M)) \geq 3$ by Cor. 4.4. That is, $\text{Gr}(\text{c}(I)_{A_M}) \geq 3$ for each $M \in \text{Max}(A)$. Therefore, $\text{Gr}(\text{c}(I)) \geq 3$ by Lemma 4.6.

Finally, we give an example of $A \subset B$ which is not flat but LCM-stable.

Example 4.8. Let $A = k[s, t, u]$ where k is a field and s, t and u are indeterminates. Let $B = A[X]/(sX^2 + tX + u)$. Then $A \subset B$ is LCM-stable but is not flat.

§5. LCM-stableness of $A \subset A[\alpha, \beta]$

Let $\alpha, \beta \in \Omega - \{0\}$. Even if both $A \subset A[\alpha]$ and $A \subset A[\beta]$ are LCM-stable, $A \subset A[\alpha, \beta]$ is not necessarily LCM-stable as is seen in Remark 1.10. So we shall examine LCM-stableness of $A \subset A[\alpha, \beta]$ under the condition $\alpha/\beta \in K$ in §5 and under the condition that $K(\alpha), K(\beta)$ are linearly disjoint over K in §6. The following lemma follows easily from Prop. 1.2, Cor. 1.5 and Prop. 1.6.

LEMMA 5.1. Let $A \subset B$ be integral domains and $a_1, a_2, \dots, a_n \in A$. Assume that $(a_1, a_2, \dots, a_n)B = B$. Then $A \subset B$ is LCM-stable if and only if $A \subset B_{a_i}$ is LCM-stable for every i with $1 \leq i \leq n$.

Throughout this section, we assume that A is integrally closed and that $\alpha = b\beta$ for some $a, b \in A - \{0\}$ with $a :_A b = a$.

LEMMA 5.2. If $A \subset A[\alpha, \beta]$ is LCM-stable, then there exists $\gamma \in A[\alpha, \beta]$ such that $\alpha = b\gamma$, $\beta = a\gamma$ and $A[\alpha, \beta] = A[\gamma]$.

PROPOSITION 5.3. Assume that both α and β are integral over A . Then $A \subset A[\alpha, \beta]$ is LCM-stable if and only if $(a, b) = A$.

PROOF. Suppose that $(a, b) = A$. Since $\alpha = b\beta$, we have $A_a[\alpha, \beta] = A_a[\beta]$ and $A_b[\alpha, \beta] = A_b[\alpha]$. Since both $A \subset A_a[\beta]$ and $A \subset A_b[\alpha]$ are LCM-stable, so is $A \subset A[\alpha, \beta]$ by Lemma 5.1.

Conversely, suppose that $A \subset A[\alpha, \beta]$ is LCM-stable. By Lemma 5.2, we can take $\gamma \in A[\alpha, \beta]$ so that $\alpha = b\gamma$, $\beta = a\gamma$ and $A[\alpha, \beta] = A[\gamma]$. Put $\gamma = f(\alpha, \beta) \in A[\alpha, \beta]$. Since both α and β are integral over A , so is γ . Therefore, $A[\gamma]$ is a free A -module. Since $\gamma = f(\alpha, \beta) = f(b\gamma, a\gamma)$, we have $1 \in (a, b)$. Thus, $(a, b) = A$.

In order to generalize Prop. 5.3, we need a lemma.

LEMMA 5.4. Let $f_\alpha(X) = \sum_{i=0}^k s_i X^i$ and $f_\beta(X) = \sum_{i=0}^k t_i X^i$ be irreducible polynomials of α and β over K with coefficients in A , respectively. Then we have $t_i \in a^{k-i} :_A s_k$ and $s_i \in b^{k-i} :_A t_k$ for $0 \leq i \leq k-1$.

PROOF. Put $g(X) = \sum_{i=0}^k t_i b^{k-i} a^i X^i$. Then since $g(\alpha) = b^k f_\beta(\beta) = 0$, $f_\alpha(X)$ divides $g(X)$ in $K[X]$. Since $\deg f_\alpha = \deg g$, there exist $c, d \in A - \{0\}$ such that $cf_\alpha(X) = dg(X)$. Then we have $cs_i = dt_i b^{k-i} a^i$ for $0 \leq i \leq k$. Therefore, $s_k t_i b^{k-i} = t_k s_i a^{k-i}$ for $0 \leq i \leq k-1$. Since $a :_A b = a$, $a^{k-i} :_A b^{k-i} = a^{k-i}$ for $0 \leq i \leq k-1$. Thus, for $1 \leq i \leq k-1$, there exists $x_i \in A$ such that $s_k t_i = a^{k-i} x_i$ and $t_k s_i = b^{k-i} x_i$. This completes the proof.

THEOREM 5.5. Let α be integral over A . Then $A \subset A[\alpha, \beta]$ is LCM-stable if and only if $A \subset A[\beta]$ is LCM-stable and $(a, b) = A$.

PROOF. Since $A_a[\alpha, \beta] = A_a[\beta]$ and $A_b[\alpha, \beta] = A_b[\alpha]$, it suffices to prove the 'only if' part by Lemma 5.1. Suppose that $A \subset A[\alpha, \beta]$ is LCM-stable. We first show that $(a, b) = A$. Let $1, \alpha, \dots, \alpha^{k-1}$ be a free basis of $A[\alpha]$ over A . Since $a^{k-1} \alpha^{k-1} = b^{k-1} \beta^{k-1}$, $a^{k-1} :_A b^{k-1} = a^{k-1}$ and $A \subset A[\alpha, \beta]$ is LCM-stable, there exist $f_i(\beta) \in A[\beta]$ ($0 \leq i \leq k-1$) such that $\beta^{k-1} = a^{k-1} \sum_{i=0}^{k-1} f_i(\beta) \alpha^i$. Thus, we have

$$(\#) \quad \beta^{k-1} = \sum_{i=0}^{k-1} a^{k-i-1} b^i \beta^i f_i(\beta).$$

Let $f_\beta(X) = \sum_{i=0}^{k-1} t_i X^i \in A[X]$ be an irreducible polynomial of β over K . Since A is integrally closed, the kernel of the canonical homomorphism of $A[X]$ onto $A[\beta]$ equals $(A :_K \mathfrak{c}(f_\beta))f_\beta(X)A[X]$ by Th. B in [15]. By (#), there exist $x_i \in A :_K \mathfrak{c}(f_\beta)$ and $g_i(X) \in A[X]$ such that

$$\begin{aligned} X^{k-1} - \sum_{i=0}^{k-1} a^{k-i-1} b^i f_i(X) X^i \\ = \sum_{i=1}^r x_i f_\beta(X) g_i(X). \end{aligned}$$

Therefore, $1 \in (a, b) + \sum_{i=1}^r \mathfrak{c}(x_i f_\beta)$. Put $x_i t_k = t_{ik}$ for $1 \leq i \leq r$. Then $t_{ik} \in A$. Since α is integral over A , $1 \in (a, b) + \sum_{i=1}^r t_{ik} A$ by Lemma 5.4. For each i with $1 \leq i \leq r$, $A_{t_{ik}}[\beta]$ is integral over $A_{t_{ik}}$ and $A_{t_{ik}} \subset A_{t_{ik}}[\alpha, \beta]$ is LCM-stable. Therefore, we have $(a, b)A_{t_{ik}} = A_{t_{ik}}$ by Prop. 5.3. Thus, $t_{ik} \in \text{rad}(a, b)$ for each i . That is, $(a, b) = A$.

We now prove that $A \subset A[\beta]$ is LCM-stable. Since $A_a[\alpha, \beta] = A_a[\beta]$, $A \subset A_a[\beta]$ is LCM-stable by Cor. 1.5. Moreover, since $A_b[\beta] \subset A_b[\alpha, \beta] = A_b[\alpha]$ and since α is integral over A , $A \subset A_b[\beta]$ is obviously LCM-stable. Thus, $A \subset A[\beta]$ is LCM-stable by Lemma 5.1.

REMARK 5.6. Let k be a field and s, t, u and b be indeterminates.

(1) Let $\alpha, \beta \in \Omega$. Even if both $A \subset A[\alpha]$ and $A \subset A[\alpha, \beta]$ are LCM-stable, $A \subset A[\beta]$ is not necessarily so. In fact, let $A = k[s, t, u, b]$ and take $\gamma \in \Omega$ which satisfies $sy^2 + t\gamma + u = 0$. Put $a = 1 - sb, \alpha = a\gamma$ and $\beta = b\gamma$. Then we have $A[\gamma] = A[\alpha, \beta]$. Both $A \subset A[\alpha]$ and $A \subset A[\alpha, \beta]$ are LCM-stable. But $A \subset A[\beta]$ is not LCM-stable.

(2) Let $\alpha, \beta \in \Omega$. LCM-stableness of $A \subset A[\alpha, \beta]$ does not necessarily imply $(a, b) = A$. In fact, let $A = k[s, t, u]$ and take $\gamma \in \Omega$ which satisfies $s^2 u^2 \gamma^2 + st u \gamma + (1 - su) = 0$. Put $\alpha = u\gamma$ and $\beta = s\gamma$. Then we have $A[\alpha, \beta] = A[\gamma]$. Moreover, $A \subset A[\alpha], A \subset A[\beta]$ and $A \subset A[\alpha, \beta]$ are all LCM-stable. But, obviously $(u, s) \neq A$.

§ 6. LCM-stableness of $A \subset A[\alpha, \beta]$ (continued)

Throughout this section, let $\alpha, \beta \in \Omega - \{0\}$ and assume that $K(\alpha), K(\beta)$ are linearly disjoint over K .

PROPOSITION 6.1. If $A \subset A[\alpha]$ is flat and if $A \subset A[\beta]$ is LCM-stable, then $A \subset A[\alpha, \beta]$ is LCM-stable. Moreover, if $A \subset A[\alpha]$ is faithfully flat, then $A \subset A[\alpha, \beta]$ is LCM-stable if and only if so is $A \subset A[\beta]$.

PROOF. Since $A \subset A[\alpha]$ is flat and $K(\alpha), K(\beta)$ are linearly disjoint over K , we have $A[\alpha, \beta] = A[\alpha] \otimes_A A[\beta]$. Therefore, $A \subset A[\alpha, \beta]$ is LCM-stable by Prop. 1.2, (1).

Suppose that $A \subset A[\alpha]$ is faithfully flat and $A \subset A[\alpha, \beta]$ is LCM-stable. Then $A[\beta] \subset A[\alpha, \beta]$ is faithfully flat and therefore, $A \subset A[\beta]$ is LCM-stable by Prop. 1.2, (2).

COROLLARY 6.2. *Assume that A is integrally closed and α is integral over A . Then $A \subset A[\alpha, \beta]$ is LCM-stable if and only if so is $A \subset A[\beta]$.*

LEMMA 6.3. *Assume that $(\sum_{i=0}^k a_i X^i)$ is the kernel of the canonical homomorphism of $A[X]$ onto $A[\alpha]$. Then $A \subset A[\alpha]$ is faithfully flat if and only if $(a_1, a_2, \dots, a_k) = A$.*

PROOF. Let $M \in \text{Max}(A)$. Put $f(X) = \sum_{i=0}^k a_i X^i$ and $\bar{A} = A/M$. We denote by $\bar{f}(X)$ the reduction of $f(X)$ modulo M . Then we have $A[\alpha]/MA[\alpha] = \bar{A}[X]/(\bar{f}(X))$. Therefore, this lemma follows immediately from Cor. 2.20 in [10].

THEOREM 6.4. *In addition to the assumption of Lemma 6.3, we assume that $A \subset A[\alpha]$ is flat. Then $A \subset A[\alpha, \beta]$ is LCM-stable if and only if $A \subset A_{a_i}[\beta]$ is LCM-stable for every i , $1 \leq i \leq k$.*

PROOF. Since $A \subset A[\alpha]$ is flat, $(a_0, a_1, \dots, a_k) = A$ by Cor. 2.20 in [10]. Therefore, we have $(a_1, a_2, \dots, a_k)A[\alpha] = A[\alpha]$. By Lemma 5.1, $A \subset A[\alpha, \beta]$ is LCM-stable if and only if $A \subset A_{a_i}[\alpha, \beta]$ is LCM-stable for every i . Fix i with $1 \leq i \leq k$. By Prop. 1.2 and Cor. 1.5, $A \subset A_{a_i}[\alpha, \beta]$ is LCM-stable if and only if $A_{a_i} \subset A_{a_i}[\alpha, \beta]$ is LCM-stable. Moreover, since $A_{a_i} \subset A_{a_i}[\alpha]$ is faithfully flat by Lemma 6.3, $A_{a_i} \subset A_{a_i}[\alpha, \beta]$ is LCM-stable if and only if $A_{a_i} \subset A_{a_i}[\beta]$ is LCM-stable by Prop. 6.1. Also, $A_{a_i} \subset A_{a_i}[\beta]$ is LCM-stable if and only if $A \subset A_{a_i}[\beta]$ is LCM-stable. Thus, this theorem holds.

REMARK 6.5. In Th. 6.4, $A \subset A[\beta]$ is not necessarily LCM-stable and therefore, the converse of the first half of Prop. 6.1 is false. In fact, let $A = k[s, t]$ where k is a field and s, t are indeterminates. Take $\alpha, \beta \in \Omega$ so that $s\alpha^2 + t\alpha + 1 = 0$ and $s\beta + t = 0$, respectively. Then $A \subset A[\alpha]$ is flat, but $A \subset A[\beta]$ is not LCM-stable by Cor. 2.8. Since $K(\beta) = K$, $K(\alpha)$, $K(\beta)$ are obviously linearly disjoint over K . On the other hand, $A \subset A[\alpha, \beta]$ is LCM-stable by Th. 6.4.

In what follows, let Y be an indeterminate and we denote by K_α (resp. K_β) the kernel of the canonical homomorphism of $A[X]$ (resp. $A[Y]$) onto $A[\alpha]$ (resp. $A[\beta]$). Moreover, we denote by $K_{\alpha, \beta}$ the kernel of the canonical homomorphism of $A[X, Y]$ onto $A[\alpha, \beta]$. We now examine $K_{\alpha, \beta}$. In the following Prop. 6.6 and Cor. 6.7, we assume that $K_\alpha = (f_\alpha(X))$ and $K_\beta = (f_\beta(Y))$, where $f_\alpha(X), f_\beta(Y) \in A[X]$.

PROPOSITION 6.6. $K_{\alpha, \beta} = (f_\alpha(X), f_\beta(Y))$ if and only if $\text{Gr}(c(f_\alpha) + c(f_\beta)) \geq 3$.

PROOF. Suppose that $K_{\alpha,\beta}=(f_\alpha(X), f_\beta(Y))$. We may assume that $c(f_\alpha)+c(f_\beta)\neq A$. Let $a\in c(f_\alpha)-\{0\}$. Then $\{a, f_\alpha(X)\}$ is an $A[X]$ -sequence since $f_\alpha(X)$ is a prime element of $A[X]$. Let $f(X, Y)\in (a, f_\alpha(X)):_{A[X,Y]}f_\beta(Y)$. Then we can take $g(X, Y), h(X, Y)\in A[X, Y]$ so that $f(X, Y)f_\beta(Y)=ag(X, Y)+f_\alpha(X)h(X, Y)$. We have $g(X, Y)\in K_{\alpha,\beta}$. By the assumption, there exist $\phi_\alpha(X, Y), \phi_\beta(X, Y)\in A[X, Y]$ such that $g(X, Y)=f_\alpha(X)\phi_\alpha(X, Y)+f_\beta(Y)\phi_\beta(X, Y)$. Therefore, $f_\alpha(X)\cdot(h(X, Y)+a\phi_\alpha(X, Y))=f_\beta(Y)(f(X, Y)-a\phi_\beta(X, Y))$. Since $f_\alpha(X):_{A[X,Y]}f_\beta(Y)=f_\alpha(X)$, $f(X, Y)-a\phi_\beta(X, Y)\in f_\alpha(X)A[X, Y]$, and therefore $f(X, Y)\in (a, f_\alpha(X))$. Thus, $(a, f_\alpha(X)):_{A[X,Y]}f_\beta(Y)=(a, f_\alpha(X))$. That is, $\{a, f_\alpha(X), f_\beta(Y)\}$ is an $A[X, Y]$ -sequence in $c(f_\alpha)+c(f_\beta)$, which shows that $\text{Gr}(c(f_\alpha)+c(f_\beta))\geq 3$.

Conversely, suppose that $\text{Gr}(c(f_\alpha)+c(f_\beta))\geq 3$. Let $a\in (c(f_\alpha)+c(f_\beta))-\{0\}$. Assume that $(f_\alpha(X), f_\beta(Y)):_{A[X,Y]}a\neq (f_\alpha(X), f_\beta(Y))$. Then we can take $h(X, Y)\in A[X, Y]$ so that $ah(X, Y)\in (f_\alpha(X), f_\beta(Y))$ and $h(X, Y)\notin (f_\alpha(X), f_\beta(Y))$. Let Q be a minimal prime ideal of $(f_\alpha(X), f_\beta(Y)):_{A[X,Y]}h(X, Y)$. Then $a, f_\alpha(X), f_\beta(Y)\in Q$. Put $Q\cap A[X]=P$. Since $\{f_\alpha(X), f_\beta(Y)\}$ is an $A[X, Y]$ -sequence and $a, f_\alpha(X)\in P$, we have $\text{Gr}(Q)=\text{Gr}(QA[X, Y]_Q)=2$ and $Q=PA[X, Y]$ by Lemma 4.2. Since $f_\beta(Y)\in Q, c(f_\beta)\subset Q\cap A$. On the other hand, $\{a, f_\beta(Y)\}$ is an $A[X]$ -sequence. Thus, $\text{Gr}(Q\cap A)=\text{Gr}(P\cap A)\geq 2$. Since $\text{Gr}(PA[X]_P)=\text{Gr}(QA[X, Y]_Q)=2, P=(P\cap A)A[X]$ by Th. 3.5 in [13]. That is, $Q=(Q\cap A)A[X, Y]$. Thus, $c(f_\alpha)+c(f_\beta)\subset Q\cap A$. By the assumption, we have $\text{Gr}(Q)=\text{Gr}(Q\cap A)\geq \text{Gr}(c(f_\alpha)+c(f_\beta))\geq 3$. This is a contradiction. Therefore, $(f_\alpha(X), f_\beta(Y)):_{A[X,Y]}a=(f_\alpha(X), f_\beta(Y))$. Let S be the multiplicatively closed set of A generated by the leading coefficients of $f_\alpha(X)$ and $f_\beta(Y)$. Since $K(\alpha), K(\beta)$ are linearly disjoint over K , we have $K_{\alpha,\beta}A_S[X, Y]=(f_\alpha(X), f_\beta(Y))A_S[X, Y]$. Therefore, $K_{\alpha,\beta}=(f_\alpha(X), f_\beta(Y))$ by the relation obtained above.

COROLLARY 6.7. *If $A\subset A[\alpha]$ is G_2 -stable, then we have $K_{\alpha,\beta}=(f_\alpha(X), f_\beta(Y))$.*

PROOF. Let $a\in c(f_\alpha)-\{0\}$. Since $f_\beta(Y):_{A[Y]}a=f_\beta(Y)$ and since $A[Y]\subset A[\alpha][Y]$ is R_2 -stable by Th. 3.5, we have $f_\beta(Y):_{A[\alpha,Y]}a=f_\beta(Y)$. Therefore, $(f_\alpha(X), f_\beta(Y)):_{A[X,Y]}a=(f_\alpha(X), f_\beta(Y))$. Thus, $\text{Gr}(c(f_\alpha)+c(f_\beta))\geq 3$, and $K_{\alpha,\beta}=(f_\alpha(X), f_\beta(Y))$ by Prop. 6.6.

COROLLARY 6.8. *Let A be locally a GCD-domain. If $A\subset A[\alpha]$ is LCM-stable, then $K_{\alpha,\beta}=(K_\alpha, K_\beta)A[X, Y]$.*

PROOF. Let $M\in \text{Max}(A)$. Since A_M is a GCD-domain, both $K_\alpha A_M[X]$ and $K_\beta A_M[Y]$ are principal and $A_M\subset A_M[\alpha]$ is G_2 -stable by Cor. 1.5 and Cor. 3.7. Therefore, we have $K_{\alpha,\beta}A_M[X, Y]=(K_\alpha, K_\beta)A_M[X, Y]$ by Cor. 6.7. Thus, $K_{\alpha,\beta}=(K_\alpha, K_\beta)A[X, Y]$.

Let $a_1, a_2, \dots, a_n\in A$. Hereafter, we say that $\{a_1, a_2, \dots, a_n\}$ is an A -sequence even if $(a_1, a_2, \dots, a_n)=A$.

PROPOSITION 6.9. *Let A be locally a GCD-domain. If both $A \subset A[\alpha]$ and $A \subset A[\alpha, \beta]$ are LCM-stable, then we have $\text{Gr}(c(f_\alpha) + c(f_\beta)) \geq 4$.*

PROOF. By virtue of Lemma 4.6, we may assume that A is a local domain. Then A is a GCD-domain by the assumption. Therefore, both K_α and K_β are principal. Put $K_\alpha = (f_\alpha(X))$ and $K_\beta = (f_\beta(Y))$, where $f_\alpha(X), f_\beta(X) \in A[X]$. Moreover, $A \subset A[\alpha]$ is G_2 -stable by Cor. 3.7. Let Z be an indeterminate. We can take a positive integer n so that $c(f_\alpha(Z) + f_\beta(Z)Z^n) = c(f_\alpha) + c(f_\beta)$. Put $F(Z) = f_\alpha(Z) + f_\beta(Z)Z^n$. Since $f_\alpha(Z)$ is a prime element of $A[Z]$, we have $A :_K c(F) = A$. Let $a \in c(f_\alpha) - \{0\}$. Then $a :_{A[Z]} F(Z) = a$ by Lemma 3.1. Since $A[Z] \subset A[\alpha, \beta][Z]$ is R_2 -stable by Th. 3.5, $a :_{A[\alpha, \beta, Z]} F(Z) = a$. Therefore, we have $(f_\alpha(X), f_\beta(Y), a) :_{A[X, Y, Z]} F(Z) = (f_\alpha(X), f_\beta(Y), a)$ by Cor. 6.7. On the other hand, it is easily shown by Cor. 6.7 that $\{f_\alpha(X), f_\beta(Y), a\}$ is an $A[X, Y]$ -sequence. Thus, $\{f_\alpha(X), f_\beta(Y), a, F(Z)\}$ is an $A[X, Y, Z]$ -sequence in $(c(f_\alpha) + c(f_\beta))A[X, Y, Z]$. Thus, $\text{Gr}(c(f_\alpha) + c(f_\beta)) \geq 4$. This implies that $\text{Gr}(c(K_\alpha) + c(K_\beta)) \geq 4$.

THEOREM 6.10. *Let A be locally a GCD-domain. Assume that both $A \subset A[\alpha]$ and $A \subset A[\beta]$ are LCM-stable. Then $A \subset A[\alpha, \beta]$ is LCM-stable if and only if $\text{Gr}(c(K_\alpha) + c(K_\beta)) \geq 4$.*

PROOF. By virtue of Prop. 6.9, it is sufficient to prove the ‘if’ part. By Prop. 1.6 and Ex. 10 of Chap. 5 in [9], we may assume that A is a local domain. Then A is a GCD-domain. Therefore, it is sufficient to show that $A \subset A[\alpha, \beta]$ is R_2 -stable. Moreover, we can put $K_\alpha = (f_\alpha(X))$ and $K_\beta = (f_\beta(Y))$, where $f_\alpha(X), f_\beta(X) \in A[X]$. Suppose that $\text{Gr}(c(f_\alpha) + c(f_\beta)) \geq 4$. Let $a, b \in A - \{0\}$ and assume that $a :_A b = a$. Since $A \subset A[\alpha]$ is G_2 -stable by Cor. 3.7, it is easily shown by Cor. 6.7 that $\{f_\alpha(X), f_\beta(Y), a\}$ is an $A[X, Y]$ -sequence. Assume that $\{f_\alpha(X), f_\beta(Y), a, b\}$ is not an $A[X, Y]$ -sequence. Then there exists $h(X) \in A[X, Y]$ such that $bh(X, Y) \in (f_\alpha(X), f_\beta(Y), a)$ and $h(X, Y) \notin (f_\alpha(X), f_\beta(Y), a)$. Let Q be a minimal prime ideal of $(f_\alpha(X), f_\beta(Y), a) :_{A[X, Y]} h(X, Y)$. Then we have $f_\alpha(X), f_\beta(Y), a, b \in Q$. Put $Q \cap A[X] = P$ and $Q \cap A = P_0$. Since $A \subset A[\alpha]$ is LCM-stable, $\{f_\alpha(X), a, b\}$ is an $A[X]$ -sequence in P . Thus, $\text{Gr}(P) \geq 3$. Therefore, $\text{Gr}(Q) = \text{Gr}(QA[X, Y]_Q) = 3$ and $Q = PA[X, Y]$ by Lemma 4.2. Hence, $\text{Gr}(PA[X]_P) = \text{Gr}(QA[X, Y]_Q) = 3$ and $c(f_\beta) \subset P_0$. Since $A \subset A[\beta]$ is LCM-stable, $\text{Gr}(P_0) \geq \text{Gr}(c(f_\beta)) \geq 3$ by Th. 4.7. Therefore, $P = P_0A[X]$ by Th. 3.5 in [13]. Thus, $Q = P_0A[X, Y]$. Then we have $c(f_\alpha), c(f_\beta) \subset P_0$. By the assumption, $\text{Gr}(Q) = \text{Gr}(P_0) \geq \text{Gr}(c(f_\alpha) + c(f_\beta)) \geq 4$. This is a contradiction. That is, $(f_\alpha(X), f_\beta(Y), a) :_{A[X, Y]} b = (f_\alpha(X), f_\beta(Y), a)$. By Cor. 6.7, we have $a :_{A[\alpha, \beta]} b = a$. Thus, $A \subset A[\alpha, \beta]$ is R_2 -stable. This completes the proof.

REMARK 6.11. In Th. 6.10, the condition that $A \subset A[\beta]$ is LCM-stable can not be omitted. In fact, let $A = Q[s, t, u, v]$, where s, t, u, v are indeterminates

and take $\alpha, \beta \in \Omega$ so that $s\alpha^2 + t\alpha + u = 0$ and $v\beta^2 + t\beta + t = 0$ respectively. Then $A \subset A[\alpha]$ is LCM-stable, but $A \subset A[\beta]$ is not LCM-stable. By prop. 6.6, we see that the kernel of the canonical homomorphism of $A[X, Y]$ onto $A[\alpha, \beta]$ is equal to $(sX^2 + tX + u, vY^2 + tY + t)$, and therefore it is easily shown that $A \subset A[\alpha, \beta]$ is not LCM-stable.

§7. Examples

In §4 we have seen that, if $\text{Gr}(I) \geq 2$, then $\text{gr}(I) \geq 2$ under some conditions on the ideal I . It seems plausible to the author that ‘ $\text{Gr}(I) \geq 2$ ’ does not necessarily imply ‘ $\text{gr}(I) \geq 2$ ’; however such an example can be found nowhere in the literature. So, in this section we give an example and by making use of it, we show that R_2 -stableness does not necessarily imply G_2 -stableness.

Let I be a non-zero proper ideal of A . We first construct a ring B so that $\text{gr}(IB) = 1$. For the ideal I , we consider a set of indeterminates $\{X_{\lambda\mu}\}_{\lambda, \mu \in I}$. Let $R = A[\{X_{\lambda\mu}\}_{\lambda, \mu \in I}]$ and $J = (X_{\lambda\mu}X_{\alpha\beta} \mid \lambda, \mu, \alpha, \beta \in I)R$. Put $I_{\lambda\mu} = (\lambda, \mu)$ for any $\lambda, \mu \in I$. We denote by B a subdomain $A + \sum I_{\lambda\mu}X_{\lambda\mu} + J$ ($\lambda, \mu \in I$) of R . Let $f \in B$. Then there exist uniquely $f_0 \in A, f_{\lambda\mu} \in I_{\lambda\mu}$ ($\lambda, \mu \in I$) and $f_1 \in J$ such that $f = f_0 + \sum f_{\lambda\mu}X_{\lambda\mu} + f_1$ ($\lambda, \mu \in I$), where $f_{\lambda\mu} = 0$ for almost all $\lambda, \mu \in I$. We say that $f = f_0 + \sum f_{\lambda\mu}X_{\lambda\mu} + f_1$ ($\lambda, \mu \in I$) is the decomposition of f .

LEMMA 7.1. *Let $f \in B$ and $f_0 + \sum f_{\lambda\mu}X_{\lambda\mu} + f_1$ ($\lambda, \mu \in I$) be the decomposition of f . Then we have*

- (1) for $\lambda, \mu \in I, X_{\lambda\mu}f \in B$ if and only if $f_0 \in I_{\lambda\mu}$,
- (2) if $X_{\lambda\mu}f \in B$, then $X_{\lambda\mu}f \in fB$.

COROLLARY 7.2. $\text{gr}(IB) = 1$.

PROOF. Let $f, g \in IB$ and let $f_0 + \sum f_{\lambda\mu}X_{\lambda\mu} + f_1, g_0 + \sum g_{\lambda\mu}X_{\lambda\mu} + g_1$ be the decompositions of f, g respectively. Since $f, g \in IB$, we have $f_0, g_0 \in I$. Therefore, $X_{f_0g_0}f \in f :_B g$ and $X_{f_0g_0}f \in fB$ by Lemma 7.1. Thus, $f :_B g \neq f$. This implies that $\text{gr}(IB) = 1$.

Next, we consider the following condition (**) to make $\text{Gr}(IB) \geq 2$.

$$(**) \quad (\alpha, \beta) :_A I = (\alpha, \beta) \quad \text{for any } \alpha, \beta \in I.$$

For example, let $A = k[s, t, u]$ where k is a field and s, t, u are all indeterminates. Put $I = (s, t, u)$. Then I satisfies the condition (**).

PROPOSITION 7.3. *Assume that I satisfies the condition (**). Then we have $\lambda :_B I = \lambda$ for each $\lambda \in I$. In particular, if I is finitely generated, then $\text{Gr}(IB) \geq 2$.*

PROOF. Let $\lambda \in I$. We assume that $\lambda \neq 0$. Let $f \in \lambda :_B I$ and let $f_0 +$

$\sum f_{\alpha\beta}X_{\alpha\beta} + f_1$ be the decomposition of f . Then for each $\mu \in I$, there exists $g_\mu \in B$ such that $\mu f = \lambda g_\mu$. Let $g_0^\mu + \sum g_{\alpha\beta}^\mu X_{\alpha\beta} + g_1^\mu$ be the decomposition of g_μ for each $\mu \in I$. Then the following (i), (ii) and (iii) hold for each $\mu \in I$: (i) $\mu f_0 = \lambda g_0^\mu$, (ii) $\mu f_{\alpha\beta} = \lambda g_{\alpha\beta}^\mu$ for any $\alpha, \beta \in I$, (iii) $\mu f_1 = \lambda g_1^\mu$. By (i) and the condition (**), $f_0 \in \lambda :_A I = \lambda$. Therefore, we can take $h_0 \in A$ so that $f_0 = \lambda h_0$. Next, by (iii) and the condition (**), $f_1 \in \lambda :_R I = (\lambda :_A I)R = \lambda R$. Therefore, we can take $h_1 \in R$ so that $f_1 = \lambda h_1$. Then since $f_1 \in J$, we have $h_1 \in J$. Moreover, by (ii) and the condition (**), $f_{\alpha\beta} \in \lambda :_A I = \lambda$ for any $\alpha, \beta \in I$. Therefore, we can take $h_{\alpha\beta} \in A$ so that $f_{\alpha\beta} = \lambda h_{\alpha\beta}$ for any $\alpha, \beta \in I$. Put $h = h_0 + \sum h_{\alpha\beta}X_{\alpha\beta} + h_1$ ($\alpha, \beta \in I$). Then we have $h \in R$ and $f = \lambda h$. Since $\mu h = g_\mu$, $\mu h_{\alpha\beta} = g_{\alpha\beta}^\mu \in I_{\alpha\beta}$ for any $\mu, \alpha, \beta \in I$. Thus, we have $h_{\alpha\beta} \in (\alpha, \beta) :_A I = (\alpha, \beta)$ by the condition (**). That is, $h \in B$. Therefore, $f \in \lambda B$. This implies that $\lambda :_B I = \lambda$.

LEMMA 7.4. Let $A[\{X_\lambda\}_{\lambda \in A}]$ be a polynomial ring in variables $\{X_\lambda\}_{\lambda \in A}$ over A . Let $f \in A[\{X_\lambda\}_{\lambda \in A}]$ with $f(0) = 1$. Then we have $a :_{A[\{X_\lambda\}_{\lambda \in A}]} f = a$ for each $a \in A$.

Here, let $A = k[s, t, u]_{(s,t,u)}$, where k is a field and s, t, u are all indeterminates. Put $M = (s, t, u)A$ and let $R = A[\{X_{\alpha\beta}\}_{\alpha, \beta \in M}]$, where $\{X_{\alpha\beta}\}_{\alpha, \beta \in M}$ is a set of variables. Moreover, put $M_{\alpha\beta} = (\alpha, \beta)$ for any $\alpha, \beta \in M$ and put $J = (X_{\alpha\beta}X_{\lambda\mu} | \alpha, \beta, \lambda, \mu \in M)R$. Let $B = A + \sum M_{\alpha\beta}X_{\alpha\beta} + J$ ($\alpha, \beta \in M$) and $T = A + \sum MX_{\alpha\beta} + J$ ($\alpha, \beta \in M, \alpha \neq 0$ or $\beta \neq 0$). Then we have $A \subset B \subset T \subset R$.

PROPOSITION 7.5. With the above notation, we have $\text{Gr}(MT) = 1$. In particular, $B \subset T$ is not G_2 -stable.

PROOF. Let $a, \alpha, \beta \in M - \{0\}$. Then we have $aX_{\alpha\beta} \in T$. Since $m(aX_{\alpha\beta}) = a(mX_{\alpha\beta})$ for each $m \in M$, $aX_{\alpha\beta} \in a :_T M$. On the other hand, since $X_{\alpha\beta} \notin T$, $aX_{\alpha\beta} \notin aT$. Therefore, $a :_T M \neq a$. Thus, $\text{Gr}(MT) = 1$. Furthermore, we have $\text{Gr}(MB) \geq 2$ by Prop. 7.3. That is, $B \subset T$ is not G_2 -stable.

PROPOSITION 7.6. With the notation of Prop. 7.5, $B \subset T$ is R_2 -stable.

PROOF. Let $f, g \in B$ and assume that $f :_B g = f$. Let $f_0 + \sum f_{\alpha\beta}X_{\alpha\beta} + f_1, g_0 + \sum g_{\alpha\beta}X_{\alpha\beta} + g_1$ ($\alpha, \beta \in M$) be the decompositions of f, g respectively. By the proof of Cor. 7.2, it is easy to see that either $f_0 \notin M$ or $g_0 \notin M$. Say $f_0 \notin M$. Since A is a local domain, we may assume that $f_0 = 1$. Let $h \in f :_T g$ and take $\phi \in T$ so that $hg = f\phi$. Put $h = h_0 + \sum h_{\alpha\beta}X_{\alpha\beta} + h_1$ ($\alpha, \beta \in M, \alpha \neq 0$ or $\beta \neq 0$) and $\phi = \phi_0 + \sum \phi_{\alpha\beta}X_{\alpha\beta} + \phi_1$ ($\alpha, \beta \in M, \alpha \neq 0$ or $\beta \neq 0$), where $h_0, \phi_0 \in A, h_{\alpha\beta}, \phi_{\alpha\beta} \in M$ for any $\alpha, \beta \in M$ and $h_1, \phi_1 \in J$. If $h_{\alpha\beta} = \phi_{\alpha\beta} = 0$ for any $\alpha, \beta \in M$, then $h, \phi \in B$. Therefore, $h \in f :_B g = f$. That is, $h \in fB \subset fT$. Now, suppose that there exist $\alpha, \beta \in M$ such that $h_{\alpha\beta} \neq 0$ and $\phi_{\alpha\beta} \neq 0$. Then we can take $a \in \cap M_{\alpha\beta} - \{0\}$, the interesection ranging over all $\alpha, \beta \in M$ with $h_{\alpha\beta} \neq 0$ and $\phi_{\alpha\beta} \neq 0$. Then we have

$ah, a\phi \in B$. Since $f:{}_B g = f$ and $g(ah) = f(a\phi)$, there exists $\psi \in B$ such that $ah = f\psi$ and $a\phi = g\psi$. Moreover, there exists $\xi \in R$ such that $h = f\xi$ and $\psi = a\xi$ by Lemma 7.4. Put $\xi = \xi_0 + \sum \xi_{\alpha\beta} X_{\alpha\beta} + \xi_1$ ($\alpha, \beta \in M$), where $\xi_0, \xi_{\alpha\beta} \in A$ for any $\alpha, \beta \in M$ and $\xi_1 \in J$. Then we have $h_{\alpha\beta} = \xi_{\alpha\beta} + \xi_0 f$ for any $\alpha, \beta \in M$. (In particular, $\xi_{00} = 0$). Therefore, $\xi_{\alpha\beta} \in M$ for any $\alpha, \beta \in M$. Thus, $\xi \in T$. That is, $h = f\xi \in fT$. This implies that $f:{}_T g = f$. Thus, $B \subset T$ is R_2 -stable.

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