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ABSTRACT. The notion of S-stability of foliations on branched simple polyhedrons is introduced by R. Benedetti and C. Petronio in the study of characteristic foliations of contact structures on 3-manifolds. We additionally assume that the 1-form β defining a foliation on a branched simple polyhedron *P* satisfies $d\beta > 0$, which means that the foliation is possibly a characteristic foliation of a contact form whose Reeb flow is transverse to *P*. In this paper, we show that if there exists a 1-form β on *P* with $d\beta > 0$ then we can find a 1-form with the same property and additionally being S-stable. We then prove that the number of simple tangency points of an S-stable foliation on a positive or negative flow-spine is at least 2 and give a recipe for constructing a characteristic foliation of a 1-form β with $d\beta > 0$ on the abalone.

1. Introduction

A flow-spine P is a branched simple spine embedded in an oriented, closed, smooth 3-manifold M such that there exists a non-singular flow in M that is transverse to P and "constant" in the complement $M \setminus P$. This notion was introduced by I. Ishii in [8]. In that paper, he proved that any non-singular flow in M has a flow-spine. Therefore, regarding a Reeb flow on a contact 3-manifold as a flow of its flow-spine, we may use it for studying contact structures on 3-manifolds. This setting is analogous to the setting of the correspondence between contact 3-manifolds and open book decompositions in [11, 4]. One of the advantages of this setting is that the contact structure in the complement of a flow-spine is always tight since the Reeb flow is "constant". Thus the study of contact structures via flow-spines divides into two parts, one is the study of contact structures in small neighborhoods of flow-spines and the other is to see what happens when tight 3-balls are glued to the neighborhoods.

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Fig. 1. The index of simple tangency points.

A characteristic foliation on a branched polyhedron embedded in a contact 3-manifold had been studied by Benedetti and Petronio in [1], following the work of Giroux on characteristic foliations on surfaces [3]. Setting the branched polyhedron in a general position, we may assume that the foliation is non-singular on the singular set S(P) of P. We further assume that the indices of simple tangency points of the foliation to S(P) are always +1 and away from vertices of S(P). See Figure 1 for the definition of the index of a simple tangency point. A foliation that satisfies the above conditions is called an S-stable foliation. In [1], they proved several statements. For instance, it is proved that if a characteristic foliation on a branched polyhedron P in a contact 3-manifold M is S-stable then the contact structure with this foliation is unique in a small neighborhood of P up to contactomorphism. It is also proved that if that contact structure is tight in a neighborhood of P then it extends to a tight contact structure on M and the extended contact structure on M is unique up to contactomorphism. Remark that the Reeb flows of these contact structures may not be transverse to P. In this paper, we always assume that a contact structure is positive, that is, its contact form α satisfies $\alpha \wedge d\alpha > 0.$

Suppose that there exists a contact form α on M whose Reeb flow is transverse to a flow-spine P. We choose the orientations of the regions of P so that their intersections with the Reeb flow are positive. In this setting, the form $\beta = \alpha|_P$ on P satisfies $d\beta > 0$. To advance the study in this setting, we need to study a 1-form β on P with $d\beta > 0$ and whose characteristic foliation on P is S-stable. Note that there are many branched simple polyhedrons that admit a 1-form β with $d\beta > 0$, see Remark 1.

The aim of this paper is to understand if there is a 1-form β on P with $d\beta > 0$ and whose kernel gives an S-stable foliation on P and if there exists a constraint for positions of leaves of S-stable foliations on P. The following theorem answers the first question.

THEOREM 1. Let P be a branched simple polyhedron. If there exists a 1-form β on P with $d\beta > 0$ then there exists a 1-form β' on P such that $d\beta' > 0$ and the foliation defined by $\beta' = 0$ on P is S-stable.

Note that it is proved in [1] that any characteristic foliation on a branched simple polyhedron *P* in a contact 3-manifold *M* can be made to be S-stable by C^0 -perturbation of *P* in *M*. In our claim, there is no direct relation between β and β' .

Our construction of an S-stable foliation is very efficient in the sense that the number of simple tangency points is very small (at most twice the number of triple lines). On the other hand, it is difficult to find an S-stable foliation defined by a 1-form β with $d\beta > 0$ and without simple tangency points. Actually, in Theorem 2 below, we show that such a foliation does not exist if a branched simple polyhedron is a flow-spine and satisfies a certain condition. A region of a branched simple polyhedron is called a *preferred region* if the orientations of all edges and circles on its boundary are opposite to the one induced from the orientation of the region defined by the branching of *P*. Note that the number of simple tangency points is always even, see Lemma 4.

THEOREM 2. If a flow-spine P has a preferred region then any foliation on P defined by a 1-form β with $d\beta > 0$ has at least two simple tangency points.

A point on a simple polyhedron that has a neighborhood shown in Figure 2 (iii) is called a *vertex*. A branched simple polyhedron has two kinds of vertices: the vertex shown on the middle in Figure 3 is called a *vertex of* ℓ -type and the one on the right is called of *r*-type. A flow-spine P is said to be *positive* if it has at least one vertex and all vertices are of ℓ -type. In [9] it is shown that the map sending a positive flow-spine P to the contact structure whose Reeb flow is a flow of P gives a surjection from the set of positive flow-spines to the set of contact 3-manifolds up to contactomorphism. It is also proved that we cannot expect the same result without restricting the source to the set of positive flow-spines. Thus, the positivity is important when we study contact 3-manifolds using flow-spines. We say that a flow-spine is *negative* if it has at least one vertex and all vertices are of *r*-type.

If a flow-spine is either positive or negative then it always has a preferred region. Hence the following corollary holds.

COROLLARY 1. Let P be a positive or negative flow-spine of a closed, oriented, smooth 3-manifold M. If the Reeb flow of a contact form α on M is a flow of P then the characteristic foliation of ker α on P has at least two simple tangency points.

Remark that if P is a positive flow-spine then there exists a contact form α on M whose Reeb flow is a flow of P and such a contact structure is unique up to contactomorphism, which is proved in [9, Theorem 1.1]. On the other hand, if P is a negative flow-spine, we do not know if there exists such a contact form or not.

As we mentioned, our second aim is to understand if there is a constraint for S-stable characteristic foliations in our setting, and the above corollary gives some insight into this question. Furthermore, in Section 6.2, we will give an example of an S-stable foliation given by a 1-form β with $d\beta > 0$ on the abalone explicitly, in which we can see that there exists a constraint for the positions of leaves of S-stable characteristic foliations, see Remark 3. We will also give a branched standard spine that admits an S-stable foliation defined by $\beta = 0$ with $d\beta > 0$ and without simple tangency points, see Section 6.3. We do not know if there exists a flow-spine that admits an S-stable foliation defined by a 1-form β with $d\beta > 0$ and without simple tangency points.

This paper is organized as follows. In Section 2, we recall some terminologies of polyhedrons that we use in this paper. Section 3 and Section 4 are devoted to the proofs of Theorems 1 and 2, respectively. In Section 5, we shortly introduce the DS-diagram of a flow-spine and give the proof of Corollary 1. In Section 6, after giving a Poincaré-Hopf lemma for flow-spines, we give an example of an S-stable foliation given by a 1-form β with $d\beta > 0$ on the abalone explicitly. We also give an example of a branched standard spine that admits an S-stable foliation given by a 1-form β with $d\beta > 0$ and without simple tangency points.

2. Preliminaries

In this section, we recall terminologies of polyhedrons used in this paper.

2.1. Simple polyhedron. A polyhedron P is said to be *simple* if every point on P has a neighborhood represented by one of the models shown in Figure 2. Each connected component of the set of points with the model (i) is called a *region*, that with the model (ii) is called a *triple line* and that with the model (iii) is called a *triple line* and that with the model (iii) is called a *true vertex*, which we call a *vertex* for short. Let S(P) denote the union of triple lines and vertices of P, which is called the *singular set* of P. A triple line is either an open arc, called an *edge*, or a circle. A simple poly-



Fig. 2. The local models of a simple polyhedron.



Fig. 3. The orientation of a triple line induced from the branching.

hedron P is said to be *standard*¹ if every connected component of $P \setminus S(P)$ is homeomorphic to an open disk and every triple line is an open arc.

Let *P* be a simple polyhedron embedded in an oriented 3-manifold *M* and assume that each region of *P* is orientable. An assignment of orientations to the regions of *P* such that for any triple line the three orientations induced from those of the adjacent regions do not coincide is called a *branching*. A simple polyhedron equipped with a branching is called a *branched polyhedron*. If a branched polyhedron is standard then it is called a *branched standard polyhedron*. For a branched polyhedron *P*, we define the orientation of each triple line of S(P) by the orientation induced from the two adjacent regions, see Figure 3.

A region of a branched simple polyhedron is called a *preferred region* if the orientations of all edges on its boundary are opposite to the one induced from the orientation of the region defined by the branching of *P*.

2.2. Spine and flow-spine. Let M be a closed, connected, oriented 3-manifold and P be a simple polyhedron embedded in M. The polyhedron P is called a *spine* of M if $M \setminus \text{Int } B$ collapses to P, where B is a 3-ball in $M \setminus P$. If a spine is standard (resp. branched) then it is called a *standard* (resp. *branched*) *spine*.

The singular set S(P) of a branched simple polyhedron P can be regarded as the image of an immersion of a finite number of circles. The immersion has only normal crossings as shown in Figure 3. A flow-spine is defined from a non-singular flow in a closed, connected, oriented, smooth 3-manifold and a disk D intersecting all orbits of the flow transversely by floating the boundary of D smoothly until it arrives in the disk D itself. See [8] for the precise definition (cf. [9]). By the construction, the flow is positively transverse to the flow-spine. We can easily see that a branched simple polyhedron P is a flow-spine if and only if S(P) is the image of an immersion of one circle.

¹ It is also called a *special* polyhedron.

2.3. Admissibility condition. Let *P* be a branched simple polyhedron. To have a 1-form β on *P* with $d\beta > 0$, *P* needs to satisfy the following admissibility condition. Let R_1, \ldots, R_n be the regions of *P*. Regions and triple lines of *P* are oriented by the branching. Let $\overline{R_i}$ be the metric completion of R_i with the path metric inherited from a Riemannian metric on R_i . Let $\kappa_i : \overline{R_i} \to P$ be the natural extension of the inclusion $R_i \to P$.

DEFINITION 1. A branched simple polyhedron P is said to be *admissible* if there exists an assignment of real numbers x_1, \ldots, x_m to the triple lines e_1, \ldots, e_m , respectively, of P such that for any $i \in \{1, \ldots, n\}$

$$\sum_{\tilde{\varepsilon}_j \subset \partial \bar{\mathcal{R}}_i} \varepsilon_{ij} x_j > 0, \tag{1}$$

where \tilde{e}_j is an open arc or a circle on $\partial \bar{R}_i$ such that $\kappa_i|_{\tilde{e}_j} : \tilde{e}_j \to e_j$ is a homeomorphism, and $\varepsilon_{ij} = 1$ if the orientation of e_j coincides with that of $\kappa_i(\tilde{e}_j)$ induced from the orientation of R_i and $\varepsilon_{ij} = -1$ otherwise.

We set

$$C(P) = \left\{ (x_1, \dots, x_m) \in \mathbb{R}^m \, \middle| \, \sum_{\bar{e}_j \subset \partial \bar{R}_i} \varepsilon_{ij} x_j > 0, \, i = 1, \dots, n \right\}.$$

By the definition, P is admissible if and only if C(P) is non-empty.

3. Proof of Theorem 1

Theorem 1 will follow from the following proposition.

PROPOSITION 1. Let P be a branched simple polyhedron. Then, there exists a 1-form β on P with $d\beta > 0$ such that the foliation on P defined by $\beta = 0$ is S-stable if and only if P is admissible.

REMARK 1. It is known that many flow-spines satisfy the admissibility condition, see [9, Section 4.1]. For instance, a branched standard spine of a rational homology 3-sphere is admissible. Such branched simple polyhedrons always satisfy the condition in Theorem 1.

Let *P* be a branched simple polyhedron, *Q* be a small compact neighborhood of S(P) in *P*, R'_1, \ldots, R'_n be connected components of *P*\Int *Q* and e_1, \ldots, e_m be triple lines of *P*. The orientation of R'_i is defined from the branching of *P* and that of e_i is defined as explained in Section 2.1.

LEMMA 1. Suppose that P is admissible. Then there exists a 1-form β_0 on Q such that

- (1) the foliation on Q defined by $\beta_0 = 0$ is S-stable,
- (2) $\int_{\partial R'_i} \beta_0 > 0$ for $i = 1, \ldots, n$, and
- (3) $d\beta_0' > 0$ on Q.

PROOF. Let v_1, \ldots, v_{n_v} be the vertices of P and N_{v_j} be a small compact neighborhood of v_j in P. For each $j = 1, \ldots, n_v$, we define a projection pr_{v_j} from N_{v_i} to \mathbb{R}^2 such that

- (i) the orientation of each region defined by the branching coincides with that of \mathbb{R}^2 ,
- (ii) the image is included in a small open disk centered at the point $\left(\cos\frac{2\pi j}{n_c},\sin\frac{2\pi j}{n_c}\right)$, and
- (iii) the orientations of the images of the triple lines in N_{v_j} are counterclockwise.

See Figure 4. The arrowed edges in the figure are the images of triple lines of P, which are oriented according to the branching of P as shown in Figure 3.

Let (r, θ) be the polar coordinates of \mathbb{R}^2 , set a 1-form on \mathbb{R}^2 as $r^2 d\theta$ and define the 1-form β_0 on N_{v_j} by $\operatorname{pr}_{v_j}^*(r^2 d\theta)$. Note that $d\beta_0 > 0$ on N_{v_i} since $d(r^2 d\theta) = 2r dr \wedge d\theta > 0$.

Next, we define the 1-form β_0 on a neighborhood of each triple line of P. Let e_1, \ldots, e_m be the triple lines of P and N_{e_i} , $j = 1, \ldots, m$, be a small



Fig. 4. The images of $N_{v_1}, \ldots, N_{v_{n_v}}$ on \mathbb{R}^2 .



Fig. 5. The images of N'_{e_i} on \mathbb{R}^2 in the case $E_j > 0$ and $E_j < 0$.

compact neighborhood of e_j in P and set $N'_{e_j} = N_{e_j} \setminus \operatorname{Int}(N_{v(e_j)} \cup N_{v'(e_j)})$, where $v(e_j)$ and $v'(e_j)$ are the two vertices at the endpoints of e_j . Since P is assumed to be admissible, we can choose an *m*-tuple of real numbers (E_1, \ldots, E_m) in C(P).

Suppose that e_j is an edge. If $E_j > 0$, we choose a projection pr_{e_j} from N'_{e_j} to \mathbb{R}^2 as shown on the left in Figure 5 and define the 1-form β_0 on N'_{e_j} by $\operatorname{pr}^*_{e_j}(r^2 \ d\theta)$ as before. Set $e'_j = e_j \cap N'_{e_j}$. Let a_j and a'_j be the endpoints of $\operatorname{pr}_{e_j}(e'_j)$ and let ℓ_{e_j} and ℓ'_{e_j} be the line segments on \mathbb{R}^2 connecting the origin and a_j and the origin and a'_j , respectively. Since these segments are in the kernel of $r^2 \ d\theta$, the integrations of $r^2\theta$ along ℓ_{e_j} and ℓ'_{e_j} are 0. By Stokes' theorem, the absolute value of the integration of β_0 along e'_j coincides with the area of the region bounded by $\operatorname{pr}_{e_j}(e'_j)$, ℓ_{e_j} and ℓ'_{e_j} . We may choose pr_{e_j} so that the area becomes the given real number $E_j > 0$, which means that the integration of β_0 along e'_j coincides with E_j . Note that the foliation defined by $\beta_0 = 0$ has no simple tangency point on N'_{e_j} .

If $E_j < 0$, we choose a projection pr_{e_j} from N'_{e_j} to \mathbb{R} as shown on the right in Figure 5 and define the 1-form β_0 on N'_{e_j} by $\operatorname{pr}_{e_j}^*(r^2 d\theta)$ as before. By the same observation as in the case $E_j > 0$, we may choose pr_{e_j} so that the integration of β_0 along e'_j coincides with E_i . For each edge e_j with $E_j < 0$, the foliation defined by $\beta_0 = 0$ has exactly two simple tangency points and their indices are +1.

If $E_j = 0$, we choose the projection pr_{e_j} as shown in Figure 6. In the figure, pr_{e_j} is chosen in such a way that the area of the region $D_{e_j}^+$ bounded by $\operatorname{pr}_{e_j}(e'_j)$, ℓ'_{e_j} and ℓ'_{e_j} is equal to the area of the region $D_{e_j}^-$ bounded by $\operatorname{pr}_{e_j}(e'_j)$. Then we have

$$E_j = \int_{\mathrm{pr}_{e_j}(e_j')} r^2 \ d\theta = \int_{D_{e_j}^+} 2r \ dr \wedge d\theta - \int_{D_{e_j}^-} 2r \ dr \wedge d\theta = 0.$$

Two simple tangency points of index +1 appear in this case.



Fig. 6. The image of N'_{e_i} on \mathbb{R}^2 in the case $E_j = 0$.

If e_j is a circle and $E_j \neq 0$ then we embed N_{e_j} into \mathbb{R}^2 along a circle centered at the origin and define β_0 by $\operatorname{pr}_{e_j}^*(r^2 d\theta)$ as before. We choose the embedding such that the orientation of the triple line in the image is counter-clockwise if $E_j > 0$ and clockwise if $E_j < 0$. Choosing the radius of the circle suitably, we have $\int_{e_j} \operatorname{pr}_{e_j}^*(r^2 d\theta) = E_j$. It has no simple tangency point.

If e_j is a circle and $E_j = 0$ then we embed N_{e_j} into \mathbb{R}^2 along an "8"-shaped immersed curve so that the origin is in the middle of the region whose boundary is oriented counter-clockwise. Using the same trick as in Figure 6, we may have an embedding of N_{e_j} such that $\int_{e_j} \operatorname{pr}_{e_j}^*(r^2 d\theta) = 0$. Note that the foliation defined by $r^2 d\theta = 0$ has two simple tangency points of index +1.

Finally, we check if the 1-form β_0 obtained above satisfies the required conditions. It satisfies the condition (1) by the construction. The condition (2) is satisfied by choosing Q to be sufficiently narrow so that $\int_{\partial R'_i} \beta_0$ is sufficiently close to $\sum_{j=1}^m \varepsilon_{ij} E_j$, where ε_{ij} is the coefficient in inequality (1). Since $(E_1, \ldots, E_m) \in C(P)$, the sum $\sum_{j=1}^m \varepsilon_{ij} E_j$ is positive. Hence $\int_{\partial R'_i} \beta_0$ is also positive. The condition (3) is obviously satisfied since $d(r^2 d\theta) > 0$. This completes the proof.

Now we extend the 1-form β_0 on Q to P by applying the following lemma used in the paper of Thurston and Winkelnkemper [11]. For a compact surface Σ with boundary $\partial \Sigma$, let Nbd $(\partial \Sigma; \Sigma)$ denote a small compact neighborhood of $\partial \Sigma$ in Σ .

LEMMA 2 (Thurston-Winkelnkemper). Let Σ be a compact, oriented surface with boundary and β_0 be a 1-form on Nbd $(\partial \Sigma; \Sigma)$ such that $\int_{\partial \Sigma} \beta_0 > 0$ and $d\beta_0 > 0$. Then there exists a 1-form β on Σ such that

- $\beta = \beta_0$ on Nbd $(\partial \Sigma; \Sigma)$, and
- $d\beta > 0$ on Σ .

PROOF (Proof of Proposition 1). Suppose that a branched simple polyhedron P is admissible. The conditions (2) and (3) for β_0 in Lemma 1 allow us to use Lemma 2 for each region R_i of P. Then the 1-form β obtained by this lemma satisfies the required conditions in the assertion.

Conversely, if there exists a 1-form β that satisfies the required conditions then the *m*-tuple $(\int_{e_1} \beta, \dots, \int_{e_m} \beta)$ is an element in C(P) by Stokes' theorem. Therefore *P* is admissible. This completes the proof.

PROOF (Proof of Theorem 1). As mentioned in the end of the above proof, if there exists a 1-form β on P with $d\beta > 0$ then P is admissible. Thus Theorem 1 follows from Proposition 1.

REMARK 2. The number of simple tangency points of the foliation defined by β constructed in the above proof is at most 2m, where m is the number of triple lines of P.

4. Proof of Theorem 2

In this section, we prove Theorem 2.

LEMMA 3. Let P be a branched simple polyhedron. If P has a preferred region then

$$\{(x_1,\ldots,x_m)\in C(P) \mid x_i>0, i=1,\ldots,m\}$$

is empty.

PROOF. Let \overline{R} be the metric completion of a preferred region R and $\kappa : \overline{R} \to P$ be the natural extension of the inclusion $R \to P$. Let $\{l_1, \ldots, l_s\}$ be the set of edges and circles on the boundary $\partial \overline{R}$ of \overline{R} such that $\kappa(l_k)$ is a triple line of P.

Assume that there exists a point (E_1, \ldots, E_m) in C(P) with $E_i > 0$ for $i = 1, \ldots, m$. For $k = 1, \ldots, s$, let L_k be the real number E_{j_k} assigned to the triple line e_{j_k} of P with $\kappa(l_k) = e_{j_k}$. Since the orientation of l_k is opposite to the orientation induced from that of R, the sum of the assigned real numbers along $\partial \overline{R}$ becomes $-L_1 - \cdots - L_s < 0$. This contradicts the assumption that $(E_1, \ldots, E_m) \in C(P)$.

Let \mathscr{F} be an S-stable foliation on a branched simple polyhedron P defined by a 1-form β on P. Since \mathscr{F} is S-stable, it is transverse to S(P) in a small neighborhood of a vertex of P.

86



LEMMA 4. Let P be a branched simple polyhedron and \mathcal{F} be an S-stable foliation on P defined by a 1-form β . Then the number of simple tangency points of \mathcal{F} is even.

PROOF. The assertion follows from the fact that S(P) consists of the image of an immersion of a finite number of circles and \mathscr{F} is co-oriented.

Since \mathscr{F} is transverse to S(P) in small neighborhoods of vertices, there are four kinds of projections as shown in Figure 7. In the figure, type 1 is the case where both of the oriented edges of S(P) intersect the leaves of \mathscr{F} in the same direction and type 2 is the case where they intersect the leaves in opposite directions. The arrows with symbol β represent the direction along which the integration of β becomes positive. The sign of type is + if the direction of the arrow coincides with the orientation of the edge passing from the left-bottom to the right-top and the sign is – otherwise. Each sign + or – written near the endpoints of the edges of S(P) represents the sign of the value obtained by inserting a vector tangent to the edge whose direction is consistent with the orientation of the edge into the 1-form β . In each figure, only the painted region can be a part of a preferred region in both of ℓ -type and r-type vertex cases. We call the small neighborhoods of vertices in Figure 7 with labels 1_+ , 1_- , 2_+ and 2_- the *H*-pieces of type 1_+ , 1_- , 2_+ and 2_- , respectively.

LEMMA 5. Let P be a flow-spine of a closed, oriented, smooth 3-manifold and \mathcal{F} be an S-stable foliation on P defined by a 1-form. If there exists a vertex of P whose H-piece is of type 2 then \mathcal{F} has a simple tangency point.

Recall that S(P) consists of the image of an immersion of a finite number of circles. In the following proofs, a *circuit* means the image of an immersion of one of these circles. If a circuit passes all triple lines then it is called an *Euler circuit*. A branched simple spine is a flow-spine if and only if it has an Euler circuit.

PROOF. Assume that there exists a vertex of P whose H-piece is of type 2 and \mathscr{F} has no tangency point. The latter condition implies that if two edges

of S(P) are connected in a circuit then the integrations of β along these edges are either both positive or both negative. Since there is an H-piece of type 2, S(P) has at least two circuits. This contradicts the assumption that P is a flow-spine.

PROOF (Proof of Theorem 2). Assume that there exists an S-stable foliation \mathscr{F} defined by a 1-form β with $d\beta > 0$ and without simple tangency points. If *P* has no vertex then it does not admit such a 1-form β . Suppose *P* has at least one vertex. By Lemma 5, the H-pieces of all the vertices are of type 1. Furthermore, all vertices must have the same sign, otherwise there exists an edge of *P* which connects two vertices with opposite signs. If all vertices are of type 1_+ then $\int_{e_j} \beta > 0$ for all edges e_1, \ldots, e_m . Since *P* has a preferred region, this is impossible by Lemma 3. If all vertices are of type 1_- then $\int_{e_j} \beta < 0$ for all edges e_1, \ldots, e_m . Now we take the sum of the integrations of β along the boundaries of all the regions of *P*. In this calculation, $\int_{e_j} \beta < 0$ for all $j = 1, \ldots, m$, the sum of the integrations is negative. This contradicts the assumption that $d\beta > 0$ on *P*.

5. DS-diagram and Proof of Corollary 1

To explain the proof of Corollary 1, we first shortly introduce the DSdiagram of a flow-spine, see [10, 9] for details (cf. [6]). Let P be a flowspine of a closed, oriented, smooth 3-manifold M. The complement $M \setminus P$ is an open ball. The singular set S(P) of P induces a trivalent graph on the boundary of the closed ball B^3 obtained as the geometric completion of $M \setminus P$, which is called the *DS*-diagram of *P*. The flow of *P* induces a flow on B^3 , and the set of points on the boundary ∂B^3 at which the flow is tangent to ∂B^3 constitutes a simple closed curve. This curve is called the *E-cycle*. The E-cycle separates ∂B^3 into two open disks S^+ and S^- , where the flow is positively transverse to S^+ and negatively transverse to S^- . Here the orientation of ∂B^3 is induced from that of B^3 , and those of S^+ and S^- are induced by the inclusions $S^+, S^- \subset \partial B$. The E-cycle is oriented as the boundary of S^+ . Observing the geometric completion of B^3 in M, we may see that each region of P corresponds to a region on S^+ bounded by the DS-diagram and each triple line of P corresponds to an edge or circle in S^+ . The same is true for S^- . Each triple line of P also corresponds to an edge or circle in the E-cycle. The orientation of S^+ (resp. S^-) is consistent with (resp. opposite to) the orientations of the regions of P. We assign orientations to the edges and circles of the DS-diagram so that they coincide with the orientations of the triple lines of P.

We call a region on S^+ not adjacent to the E-cycle an *internal region*. If a DS-diagram has a circle component then the DS-diagram consists of three parallel circles one of which is the E-cycle, one is in S^+ and the last one is in S^- . The 3-manifold of the flow-spine given by this DS-diagram is $S^1 \times S^2$. See [2, Remark 1.2] (cf. [9, Example 3]).

LEMMA 6. The DS-diagram of a flow-spine has an internal region on S^+ homeomorphic to a disk.

PROOF. Let n_v be the number of vertices of P. Observing the geometric completion of $M \setminus P$, we can verify that the DS-diagram has n_v vertices on S^+ and $2n_v$ vertices on the E-cycle. If the DS-diagram has a circle component then the assertion follows. We assume that it has no circle component. Let G be the subgraph of the DS-diagram consisting of edges lying in S^+ and vertices adjacent to these edges. Note that the edges on the E-cycle are not contained in G. We denote by \overline{G} the union of G and the regions on S^+ bounded by G. Let $e(\overline{G})$ and $f(\overline{G})$ be the numbers of edges and regions of \overline{G} , respectively. Since G has n_v univalent vertices and n_v trivalent vertices, we have $n_v + 3n_v = 2e(\overline{G})$. On the other hand, the Euler characteristic $\chi(\overline{G})$ of \overline{G} is given as

$$\chi(\overline{G}) = 2n_v - e(\overline{G}) + f(\overline{G}).$$

These equalities imply that $f(\overline{G}) = \chi(\overline{G})$. Since $\chi(\overline{G}) > 0$, we have $f(\overline{G}) > 0$. Hence there exists an internal region homeomorphic to a disk.

PROOF (Proof of Corollary 1). By Lemma 6, the DS-diagram of a flowspine has an internal region homeomorphic to a disk. It is proved in [9, Lemma 4.6] that if a flow-spine is positive then an internal region is always a preferred region, and the proof written there works for negative flow-spines also. Thus, the assertion follows from Theorem 2.

6. Examples

In this section, we give an S-stable characteristic foliation given by a 1-form β with $d\beta > 0$ on the abalone explicitly. We also give an example of a branched standard spine that has an S-stable foliation without simple tangency points.

6.1. Poincaré-Hopf. We introduce a lemma that is useful for determining singularities of foliations on flow-spines. Let P be a flow-spine of a closed, oriented, smooth 3-manifold M and \mathcal{F} be a foliation on P with only elliptic and hyperbolic singularities. Assume that \mathcal{F} is tangent to S(P) at a finite



Fig. 8. Simple tangency points and corresponding singularities on ∂B^3 .

number of points in the interior of triple lines and the singularities of \mathscr{F} do not lie on S(P). Let *e* be the number of elliptic singularities, *h* be the number of hyperbolic singularities and t_+ and t_- be the numbers of simple tangency points of \mathscr{F} with index +1 and -1, respectively.

LEMMA 7. Suppose that the foliation \mathcal{F} is in the above setting. Then the following equality holds:

$$e-h=1+\frac{t_{+}-t_{-}}{2}.$$

Note that if \mathcal{F} is S-stable then $t_{-} = 0$.

PROOF. According to the definition of DS-diagram, the regions and triple lines of *P* can be described on the boundary of the closed 3-ball B^3 obtained as the geometric completion of the complement $M \setminus P$. Thus, we may describe \mathscr{F} on the boundary ∂B^3 of B^3 , which has 2e elliptic singularities and 2hhyperbolic singularities. Each simple tangency point of index +1 becomes as shown on the top-middle in Figure 8 and it can be regarded as a hyperbolic singularity as shown on the right. Each simple tangency point of index -1becomes as shown on the bottom in the figure and it can be regarded as an elliptic singularity. By the Poincaré-Hopf formula on the sphere ∂B^3 , we have $(2e + t_-) - (2h + t_+) = 2$. Thus the assertion follows.

6.2. Foliation on the abalone. The branched polyhedron A obtained from the neighborhood of the singular set shown in Figure 9 by attaching two disks D_1 and D_2 is called the *abalone*. This is a flow-spine of S^3 . We can easily see



Fig. 9. The abalone A.

that $(E_1, E_2) \in C(A)$ if and only if

$$\begin{cases} -E_1 > 0\\ 2E_1 + E_2 > 0. \end{cases}$$

This system of inequalities has a solution, for example $(-1, 13) \in \mathbb{R}^2$. Hence A is admissible.

We give an S-stable foliation on A defined by a 1-form β with $d\beta > 0$ explicitly. Set $(E_1, E_2) = (-1, 13) \in C(A)$. According to the construction in the proof of Theorem 1, one can construct an S-stable foliation on Nbd(S(A); A) defined by a 1-form β_0 with $d\beta_0 > 0$ as the left figures in Figure 10. Let R_1 and R_2 be the regions of A containing D_1 and D_2 , respectively. We describe four leaves on R_2 as shown on the right in Figure 10. We denote these leaves by ℓ_1, \ldots, ℓ_4 . For each ℓ_i , we can find a 1-form β_{ℓ_i} on Nbd $(\ell_i; R_2)$ so that $\beta_{\ell_i} = \beta_0$ on Nbd $(\ell_i; R_2) \cap$ Nbd $(\partial R_2; R_2)$ and ℓ_i is a leaf of the foliation defined by $\beta_{\ell_i} = 0$.

We decompose ∂R_2 into 15 arcs by the endpoints of the leaves ℓ_1, \ldots, ℓ_4 , the tangent points of these leaves with ∂R_2 and the vertices on ∂R_2 . We label these arcs as a_1, \ldots, a_{15} as shown on the right in Figure 10. For the arcs a_1, \ldots, a_{15} , we assign real numbers A_1, \ldots, A_{15} so that

$$A_1 + A_2 + A_3 = E_2,$$
 $A_4 + A_5 + A_6 = E_1,$ $A_7 + A_8 + A_9 = -E_2,$
 $A_{10} + A_{11} + A_{12} = E_1,$ $A_{13} + A_{14} + A_{15} = E_2$

and

$$\begin{aligned} A_{15} + A_1 + A_8 &> 0, & A_2 + A_5 > 0, & A_3 > 0, & A_4 > 0, & A_6 + A_7 > 0, \\ A_9 + A_{10} &> 0, & A_{11} + A_{14} > 0, & A_{12} > 0, & A_{13} > 0, \end{aligned}$$



Fig. 10. An S-stable foliation on Nbd(S(A); A) (left) and the leaves ℓ_1, \ldots, ℓ_4 on R_2 (right).

and $(A_4, A_5, A_6) = (A_{10}, A_{11}, A_{12})$. The five equalities mean that the assignment of real numbers to a_1, \ldots, a_{15} is a refinement of the assignment of those to e_1 and e_2 . The nine inequalities mean that, for each region bounded by $\partial R_2 \cup \bigcup_{i=1}^4 \ell_i$, the sum of the real numbers along its boundary is positive, which is necessary for applying Lemma 2. Note that we set the real number assigned to ℓ_i to be 0 since ℓ_i will be a leaf of the foliation obtained by a 1-form. The last equality is needed since, for each i = 4, 5, 6, the two edges a_i and a_{i+6} correspond to the same arc on the edge e_1 divided by the two simple tangency points. This system of equalities and inequalities has a solution, for example as

$$(A_1, \ldots, A_{15}) = (6, 6, 1, 2, -5, 2, -1, -11, -1, 2, -5, 2, 1, 6, 6).$$

Let β' be a 1-form defined on a small neighborhood N of $S(P) \cup (\bigcup_{i=1}^{4} \ell_i)$ in P so that

- $d\beta' > 0$ on N,
- the characteristic foliation on N has leaves shown on the right in Figure 10,
- $\int_{a_j} \beta' = A_j$ for j = 1, ..., 15.

Such a 1-form can be easily constructed as in the proof of Theorem 1 (cf. [9, the proof of Lemma 6.3]). We may extend β' to the whole *P* by applying Lemma 2.

REMARK 3. The arcs ℓ_1, \ldots, ℓ_4 are Legendrian if we consider a contact form α on Nbd(A; M) whose characteristic foliation coincides with the foliation defined by $\beta' = 0$. When we describe a characteristic foliation of a flow-spine with a transverse Reeb flow, we need to choose the positions of these leaves so that the integration of β' along the boundary of each region separated by these leaves is positive. This gives a strong restriction for positions of leaves, which is different from the case of characteristic foliations on surfaces.

Consider a foliation on A shown in Figure 11, which coincides with the one defined by β' on N. It has two elliptic singularities with positive divergence and no hyperbolic singularities (cf. Lemma 7). It is not difficult to find a 1-form β on P with $d\beta > 0$ that defines the foliation in the figure. For example, let R be the region on R_2 bounded by the leaves ℓ_3 and ℓ_4 and the edges a_{11} and a_{14} and regard R as a rectangle with coordinates (x, y) so that the foliation is parallel to the x-axis. On Nbd $(\partial R; R)$, β is given in the form $\varphi(x, y)dy$, where $\varphi(x, y)$ is a smooth function on Nbd $(\partial R; R)$ with $\frac{\partial \varphi}{\partial x}(x, y) > 0$. Remark that $\int_{a_{11}} \varphi(x, y)dy = A_{11}$, $\int_{a_{14}} \varphi(x, y)dy = A_{14}$ and $A_{11} + A_{14} > 0$. We observe the graph of the function $\varphi(x, y)$ on Nbd $(\partial R; R)$, and extend it to the whole R so that $\frac{\partial \varphi}{\partial x}(x, y) > 0$. The 1-form $\varphi(x, y)dy$ defines the foliation on R and satisfies $d(\varphi(x, y)dy) > 0$.

The region R' bounded by the leaf ℓ_4 and the edges a_{12} and a_{13} has one elliptic singularity with positive divergence. For any region T bounded by an arc on $a_{12} \cup a_{13}$ and two leaves connecting the elliptic singularity and the endpoints of the arc, the 1-form β that we are going to make should satisfy $\int_T d\beta > 0$. Therefore, the assignment to the edges a_{12} and a_{13} must satisfy the inequalities $A_{12} > 0$ and $A_{13} > 0$. Under this setting, the 1-form on R' with required property can be found by the same way as before.

Applying the same construction for other regions bounded by the E-cycles and the leaves ℓ_1, \ldots, ℓ_4 , we can obtain a 1-form β on A that defines the foliation in Figure 11 and satisfies $d\beta > 0$. The DS-diagram with this S-stable foliation is described in Figure 12.

The foliation in Figure 11 has two simple tangency points on e_1 . Since R_1 is a preferred region, due to Theorem 2, we can conclude that there is no S-stable foliation defined by a 1-form β with $d\beta > 0$ and with less simple tangency points.

An S-stable foliation of the flow-spine of the Poincaré homology 3-sphere whose DS-diagram is the dodecahedron is observed by the first author in [5] by the same manner. It is shown that the flow-spine admits an S-stable



Fig. 11. An S-stable foliation on A with $d\beta > 0$ and with minimal number of simple tangency points.



Fig. 12. The DS-diagram with the S-stable foliation in Figure 11.



Fig. 13. A branched standard spine that admits an S-stable foliation defined by a 1-form β with $d\beta > 0$ and without simple tangency points.

foliation defined by a 1-form β with $d\beta > 0$ and having two simple tangency points.

6.3. An example without simple tangency point. Let *P* be the branched simple polyhedron obtained from the branched polyhedron with boundary described in Figure 13 by attaching four disks along the four connected components of the boundary of *P*. It has three vertices, six edges and four disk regions. The orientations of the edges e_1, \ldots, e_6 in the figure are those induced from the adjacent regions by the rule in Figure 3. The Euler characteristic of *P* is 3-6+4=1, and hence the Euler characteristic of the boundary of a thickening of *P* is 2. We may easily verify that the boundary of a thickening of *P* is connected and hence it is S^2 . This means that *P* is a branched standard spine of a closed, oriented 3-manifold. We can check that the DS-diagram of this spine, with forgetting the branching, is the diagram (1-10) in [7] and conclude that the 3-manifold is S^3 .

The region containing the disk D_0 in the figure is a preferred region. The defining inequalities of C(P) are $E_6 > 0$, $-E_2 - E_3 > 0$, $E_1 + E_2 - E_6 > 0$ and $E_2 + 2E_3 + E_4 + E_5 + E_6 > 0$. This system of inequalities has a solution, for example as $(6, 1, -2, -1, -1, 6) \in \mathbb{R}^6$. Hence P is admissible. To have an S-stable foliation without simple tangency points, the signs of the real numbers assigned to the edges on each of three circuits $e_1 \cup e_2$, $e_3 \cup e_4 \cup e_5$ and e_6 must be the same and the assignment $(6, 1, -2, -1, -1, 6) \in \mathbb{R}^6$ satisfies this condition. Referring to these signs, we choose the projection pr_{v_i} for each of vertices v_1 , v_2 and v_3 so that their H-pieces become as shown in Figure 14. Under this setting, we can obtain an S-stable foliation defined by a 1-form β with $d\beta > 0$ and without simple tangency points.



Fig. 14. The H-pieces of v_1 , v_2 and v_3 .



Fig. 15. An S-stable foliation on P with $d\beta > 0$ and without simple tangency points.

We here give an S-stable foliation on P defined by a 1-form β with $d\beta > 0$ and without simple tangency points on P explicitly. Set

 $(E_1, E_2, E_3, E_4, E_5, E_6) = (6, 1, -2, -1, -1, 6) \in C(P).$

Let R_1 , R_2 , R_3 , R_4 be the regions of *P* bounded by the sequences of edges $\{e_6\}$, $\{-e_2, -e_3\}$, $\{e_1, e_2, -e_5, -e_6, e_5\}$ and $\{e_1, e_4, e_5, e_3, -e_1, e_3, e_4, e_6, -e_4, e_2\}$, respectively, see Figure 15. Draw four leaves ℓ_1 , ℓ_2 , ℓ_3 and ℓ_4 as shown in the



Fig. 16. The DS-diagram with the S-stable foliation in Figure 15.

figure. The edge e_1 on the boundary of R_3 divides into two oriented arcs by an endpoint of ℓ_1 , named a_1 and a_2 as in the figure. Similarly, we name a_3 , a_4 , a_5 , a_6 , a_7 and a_8 as in the figure. For these arcs a_1, \ldots, a_8 , we assign real numbers A_1, \ldots, A_8 as

$$(A_1, A_2, A_3, A_4, A_5, A_6, A_7, A_8) = (1.6, 4.4, 0.8, 5.2, 1.5, 4.5, 3.2, 2.8),$$

so that they satisfy $A_1 + A_2 = A_5 + A_6 = E_1$, $A_3 + A_4 = A_7 + A_8 = E_6$ and

$$\begin{split} E_5 + A_1 &> 0, \qquad A_2 + E_2 - A_4 > 0, \qquad -E_5 - A_3 > 0, \\ E_1 + E_4 + E_5 + E_3 - A_5 &> 0, \qquad -A_6 + A_8 - E_4 + E_2 > 0, \qquad E_3 + E_4 + A_7 > 0. \end{split}$$

Thus, this assignment satisfies the required conditions for obtaining a 1-form β with $d\beta > 0$ on *P*. We may draw a foliation in the regions R_1, \ldots, R_4

described in Figure 15 so that R_1 has only one elliptic singularity in the middle and the other regions have no singularity, and there exists a 1-form β with $d\beta > 0$ on P which gives this foliation as in the case of abalone. There are two "tangency points" on the boundary of R_3 described in Figure 15, one is at the intersection of the edges e_5 and e_1 and the other is of the edges e_5 and e_6 , and the boundary of R_4 also has two "tangency points". The "tangency point" at the intersection of e_5 and e_1 appears in a neighborhood of the vertex v_1 shown on the left in Figure 14, where the leaves of the foliation given by $\beta = 0$ is horizontal. The other three "tangency points" appear by the same reason. Therefore, these leaves are transverse to the singular set of P and the foliation given in Figure 15 has no simple tangency points. The DS-diagram with this S-stable foliation is described in Figure 16.

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