# MANIFOLDS WITH ANTINORMAL ( $f, g, u, v, \lambda)$-STRUCTURE 

By Kentaro Yano and U-Hang Ki<br>To Professor Shigeru Ishihara on his fiftieth birthday

## 0 . Introduction.

It is now well known that submanifolds of codimension 2 of an almost Hermitian manifold and hypersurfaces of an almost contact metric manifold admit an ( $f, g, u, v, \lambda$ )-structure, that is, a set of a tensor field $f$ of type ( 1,1 ), a Riemannian metric $g$, two 1 -forms $u$ and $v$ and a function $\lambda$ satisfying

$$
\begin{align*}
& f^{2} X=-X+u(X) U+v(X) V \\
& g(f X, f Y)=g(X, Y)-u(X) u(Y)-v(X) v(Y),  \tag{0.1}\\
& u(f X)=\lambda v(X), \quad v(f X)=-\lambda u(X), \\
& u(U)=1-\lambda^{2}, \quad u(V)=0, \quad v(U)=0, \quad v(V)=1-\lambda^{2}
\end{align*}
$$

for arbitrary vector fields $X$ and $Y, U$ and $V$ being vector fields defined by $u(X)=g(U, X)$ and $v(X)=g(V, X)$ respectively. If the tensor defined by

$$
\begin{equation*}
S(X, Y)=N(X, Y)+(d u)(X, Y) U+(d v)(X, Y) V \tag{0.2}
\end{equation*}
$$

$N(X, Y)$ being the Nijenhuis tensor formed with $f$, vanishes, the ( $f, g, u, v, \lambda$ )structure is said to be normal.

In the sequel we assume that the dimension of the manifold denoted by $M$ is greater than 2.

Okumura and one of the present authors [8] proved
Theorem 0.1. Let $M$ be a complete differentiable manifold with normal ( $f, g, u, v, \lambda$ )-structure satisfying

$$
d u=2 \omega, \quad d v=2 \phi \omega,
$$

$\omega$ being a 2-form defined by $\omega(X, Y)=g(f X, Y)$ and $\phi$ a function on $M$. If $\lambda\left(1-\lambda^{2}\right)$ is almost everywhere non-zero, then $M$ is isometric to an even-dimensional sphere.

Received December 24, 1971.

The present authors [6] proved
Theorem 0.2. Let $M$ be a complete differentiable manifold with normal ( $f, g, u, v, \lambda$ )-structure satisfying

$$
\mathcal{L}_{U} g=-2 c \lambda g \quad \text { or } \quad d v=2 c \omega,
$$

$\mathcal{L}_{U}$ denoting the Lie derivation with respect to the vector field $U$ and $c$ a non-zero constant. If $\lambda\left(1-\lambda^{2}\right)$ is almost everywhere non-zero, then $M$ is isometric to an evendimensional sphere.

Okumura and one of the present authors [9] proved
Theorem 0.3. Let a complete differentiable submanifold $M$ of codimension 2 of an even-dimensional Euclidean space $E$ be such that the connection induced in the normal bundle of $M$ is trivial. If the ( $f, g, u, v, \lambda$ )-structure induced on $M$ is normal, $\lambda\left(1-\lambda^{2}\right)$ being almost everywhere non-zero, then $M$ is a sphere, a plane, or a product of a sphere and a plane.

A typical example of an even-dimensional differentiable manifold with a normal ( $f, g, u, v, \lambda$ )-structure is an even-dimensional sphere $S^{2 n}$.
$S^{n} \times S^{n}$ is also a typical example of an even-dimensional differentiable manifold which admits an $(f, g, u, v, \lambda)$-structure, but the structure is not normal. Blair, Ludden and one of the present authors [1,2] proved

Theorem 0.4. If $M$ is a complete orientable hypersurface of $S^{2 n+1}$ of constant scalar curvature satisfying $f K+K f=0, K$ being the Weingarten tensor and $\lambda \neq$ constant, $\lambda\left(1-\lambda^{2}\right)$ being almost everywhere non-zero, then $M$ is a natural sphere $S^{2 n}$ or $S^{n} \times S^{n}$.

The ( $f, g, u, v, \lambda$ )-structure induced on an orientable hypersurface of $S^{2 n+1}(1)$ with induced metric tensor $g_{j i}$ and the second fundamental tensor $k_{j i}$ satisfies

$$
\begin{equation*}
\nabla_{j} f_{i}{ }^{h}=-g_{j i} u^{h}+\delta_{j}^{h} u_{i}-k_{j i} v^{h}+k_{j}{ }^{h} v_{i}, \tag{0.3}
\end{equation*}
$$

$$
\nabla_{j} u_{i}=f_{j i}-\lambda k_{j i},
$$

$$
\begin{gather*}
\nabla_{j} v_{i}=-k_{j t} f_{\imath}^{t}+\lambda g_{j i},  \tag{0.5}\\
\nabla_{j} \lambda=k_{j i} u^{2}-v_{j}, \tag{0.6}
\end{gather*}
$$

where $f_{i}{ }^{h}, u_{i}, v_{i}$ and $\lambda$ are components of $f, u, v$ and $\lambda$ respectively, $\nabla_{J}$ being the operator of covariant differentiation with respect to $g_{j i}$. Here and in the sequel, the indices $h, i, j, k, \cdots$ run over the range $\{1,2, \cdots, 2 n\}$.

One of the present authors [4] proved
Theorem 0.5. Suppose that a complete orientable $2 n$-dimensional differentiable manifold $M^{2 n}$ is immersed in $S^{2 n+1}(1)$ as a hypersurface. If $(f, g, u, v, \lambda)$-structure induced on this hypersurface is such that $\lambda \neq$ const. and $\lambda\left(1-\lambda^{2}\right)$ is almost every-
where non-zero and if it satisfies $\nabla_{i} \lambda=c v_{i}, c$ being a non-zero constant, then $c$ must be -1 or -2 and when $c=-1, M^{2 n}$ is isometric to $S^{2 n}(1)$ and when $c=-2, M^{2 n}$ is isometric to $S^{n}(1 / \sqrt{2}) \times S^{n}(1 / \sqrt{2})$.

Theorem 0.6. If $M^{2 n}$ is a complete orientable hypersurface of $S^{2 n+1}(1)$ satisfying $f_{t}{ }^{h} k_{i}{ }^{t}+k_{t}{ }^{h} f_{2}{ }^{t}=0$ and $K(\gamma)=$ const., where $f_{i}{ }^{h}$ is the tensor field of type $(1,1)$ defining the $(f, g, u, v, \lambda)$-structure induced on $M^{2 n}, \lambda\left(1-\lambda^{2}\right)$ being almost everywhere non-zero, $k_{j i}$ the second fundamental tensor of the hypersurface and $K(\gamma)$ the sectional curvature of $M^{2 n}$ with respect to the section $\gamma$ spanned by $u^{h}$ and $v^{h}$, then $M^{2 n}$ is isometric to a natural sphere $S^{2 n}(1)$ or to $S^{n}(1 / \sqrt{2}) \times S^{n}(1 / \sqrt{2})$.

Theorem 0.7. Assume that a complete $2 n$-dimensional differentiable manifold $M^{2 n}$ admits an ( $f, g, u, v, \lambda$ )-structure such that $\lambda\left(1-\lambda^{2}\right)$ is almost everywhere nonzero, and

$$
\nabla_{j} u_{i}-\nabla_{i} u_{j}=2 f_{j i}, \quad \nabla_{i} \lambda=-v_{i}
$$

or

$$
\nabla_{j} u_{i}-\nabla_{i} u_{j}=2 f_{j i}, \quad \nabla_{i} \lambda=-2 v_{i} .
$$

At a point at which $\lambda \neq 0$, we define a tensor field $k_{j i}$ of type $(0,2)$ by

$$
\nabla_{j} u_{i}+\nabla_{i} u_{j}=-2 \lambda k_{j i}
$$

and assume that $u_{i}$ satisfies

$$
\nabla_{k} \nabla_{j} u_{i}=-g_{k j} u_{i}+g_{k i} u_{j}-k_{k j} v_{i}+k_{k i} v_{j}+2 v_{k} k_{j i} .
$$

Then $M^{2 n}$ is isometric to $S^{2 n}(1)$ if $\nabla_{i} \lambda=-v_{i}$ and isometric to $S^{n}(1 / \sqrt{2}) \times S^{n}(1 / \sqrt{2})$ if $\nabla_{i} \lambda=-2 v_{i}$.

We note here that Theorems $0.3 \sim 0.6$ state properties of $(f, g, u, v, \lambda)$-structures induced on submanifolds of codimension 2 of a Euclidean space $E^{2 n+2}$ or on hypersurfaces of a sphere $S^{2 n+1}(1)$, while Theorems $0.1,0.2$ and 0.7 state intrinsic properties of $(f, g, u, v, \lambda)$-structures of manifolds themselves.

In the present paper we first of all show that for an $(f, g, u, v, \lambda)$-structure induced on a hypersurface of $S^{2 n+1}(1)$ the conditions

$$
\begin{equation*}
f_{t}{ }^{h} k_{i}{ }^{t}+k_{t}{ }^{h} f_{\imath}{ }^{t}=0 \tag{0.7}
\end{equation*}
$$

and

$$
\begin{equation*}
S_{j i}{ }^{h}=2 v_{j}\left(\nabla_{i} v^{h}-\lambda \delta_{i}^{h}\right)-2 v_{i}\left(\nabla_{j} v^{h}-\lambda \delta_{j}^{h}\right) \tag{0.8}
\end{equation*}
$$

are equivalent.
Since the commutativity of $f$ and $K$ and the condition $S=0$ are equivalent for a hypersurface of $S^{2 n+1}(1)$ and an ( $\left.f, g, u, v, \lambda\right)$-structure satisfying $S=0$ is said to be normal, we say that an ( $f, g, u, v, \lambda$ )-structure satisfying ( 0.7 ) or ( 0.8 ) is antinormal. (See [2], [3], [4], [5]).

We study in the present paper properties of ( $f, g, u, v, \lambda$ )-structures which are antinormal in this sense.

1. A necessary and sufficient condition to be $\boldsymbol{f} \boldsymbol{K}+\boldsymbol{K} \boldsymbol{f}=0$.

We prove in this section
Theorem 1.1. In an orientable hypersurface $M$ with an ( $f, g, u, v, \lambda$ )-structure of $S^{2 n+1}(1)$ (or of a Sasakian manifold) such that $\lambda\left(1-\lambda^{2}\right)$ is almost everywhere non-zero, the conditions (0.7) and (0.8) are equivalent.

Proof. We know that the ( $f, g, u, v, \lambda$ )-structure induced on an orientable hypersurface of $S^{2 n+1}(1)$ or of a Sasakian manifold satisfies $(0.3) \sim(0.6)$.

We substitute these into

$$
\begin{align*}
S_{j i}{ }^{h}= & f_{j}^{t} \nabla_{t} f_{i}^{h}-f_{\imath} \nabla_{t} f_{j}^{h}-\left(\nabla_{j} f_{\imath}^{t}-\nabla_{\imath} f_{j}^{l}\right) f_{t}^{h} \\
& +\left(\nabla_{j} u_{i}-\nabla_{i} u_{j}\right) u^{h}+\left(\nabla_{j} v_{i}-\nabla_{i} v_{j}\right) v^{h} \tag{1.1}
\end{align*}
$$

and find

$$
S_{j i h}=-v_{j}\left(k_{i t} f_{h}{ }^{t}+k_{h t} f_{\imath}{ }^{t}\right)+v_{i}\left(k_{j t} f_{h}{ }^{t}+k_{h t} f_{j}{ }^{t}\right)
$$

or, using (0.5),

$$
\begin{equation*}
S_{j i h}=v_{j}\left(\nabla_{i} v_{h}+\nabla_{h} v_{i}-2 \lambda g_{i h}\right)-v_{i}\left(\nabla_{j} v_{h}+\nabla_{h} v_{j}-2 \lambda g_{j h}\right), \tag{1.2}
\end{equation*}
$$

where $S_{j i n}=S_{j i}{ }^{t} g_{t h}$.
Suppose now that (0.7) is satisfied. Then we have

$$
\begin{equation*}
k_{j t} f_{v}^{t}-k_{i l} f_{j}^{t}=0 \tag{1.3}
\end{equation*}
$$

and consequently, we have, from (0.5),

$$
\nabla_{j} v_{i}-\nabla_{i} v_{j}=0
$$

Thus (1.2) gives (0.8).
Conversely suppose that $(0.8)$ is satisfied. Then substituting ( 0.3 ) $\sim(0.6)$ into (0.8), we find

$$
\begin{equation*}
v_{j}\left(k_{i t} f_{h}^{t}-k_{h t} f_{i}^{t}\right)-v_{i}\left(k_{j t} f_{h}^{t}-k_{h t} f_{j}^{t}\right)=0 . \tag{1.4}
\end{equation*}
$$

Transvecting $v^{3}$ to (1.4), we find

$$
\left(1-\lambda^{2}\right)\left(k_{i t} f_{h}^{t}-k_{h t} f_{2}^{l}\right)=v_{i} \alpha_{h},
$$

where

$$
\alpha_{h}=\left(k_{j t} f_{h}{ }^{t}-k_{h t} f_{j}\right) v^{j},
$$

from which

$$
v_{i} \alpha_{h}+v_{h} \alpha_{i}=0
$$

and consequently $\alpha_{i}=0$. Thus we have

$$
\left(1-\lambda^{2}\right)\left(k_{i t} f_{h}^{t}-k_{h t} f_{\imath}{ }^{l}\right)=0,
$$

from which

$$
k_{i t} f_{n}{ }^{t}-k_{h t} f_{i}^{t}=0,
$$

and we have (0.7). Thus the theorem is proved.
Combining Theorems 0.6 and 1.1, we have
Theorem 1.2. If $M^{2 n}$ is a complete orientable hypersurface of $S^{2 n+1}(1)$ with antinormal $(f, g, u, v, \lambda)$-structure and with $K(\gamma)=$ const. $\lambda\left(1-\lambda^{2}\right)$ being almost everywhere non-zero, where $K(\gamma)$ is the sectional curvature with respect to the section $r$ spanned by $u^{h}$ and $v^{h}$, then $M^{2 n}$ is isometric to the unit sphere $S^{2 n}(1)$ or to $S^{n}(1 / \sqrt{2}) \times S^{n}(1 / \sqrt{2})$.

## 2. Lemmas.

The present authors [6] proved following general formulas which an ( $f, g, u, v, \lambda$ )structure satisfies, that is,

$$
\begin{align*}
& S_{j i h}-\left(f_{j} f_{t i h}-f_{i}^{l} f_{t j h}\right) \\
= & -\left(f_{j}^{t} \nabla_{n} f_{t i}-f_{i}^{t} \nabla_{h} f_{t j}\right)+u_{j}\left(\nabla_{i} u_{h}\right)-u_{i}\left(\nabla_{j} u_{h}\right)+v_{j}\left(\nabla_{i} v_{h}\right)-v_{i}\left(\nabla_{j} v_{h}\right) \tag{2.1}
\end{align*}
$$

and

$$
\begin{align*}
& \left\{S_{j i h}-\left(f_{j}^{t} f_{t i h}-f_{i}^{t} f_{t j h}\right)\right\} u^{j} \\
= & \left(\nabla_{i} u_{h}+\nabla_{h} u_{i}\right)-u_{i}\left(\nabla_{t} u_{h}+\nabla_{h} u_{t}\right) u^{t}+\lambda f_{\imath}^{t}\left(\nabla_{t} v_{h}+\nabla_{h} v_{t}\right)  \tag{2.2}\\
& -\lambda^{2}\left(\nabla_{i} u_{h}-\nabla_{h} u_{i}\right)-\left(\lambda f_{i}^{t}+v_{i} u^{t}\right)\left(\nabla_{t} v_{h}-\nabla_{h} v_{t}\right),
\end{align*}
$$

where

$$
\begin{equation*}
f_{j i h}=\nabla_{J} f_{i n}+\nabla_{\imath} f_{h j}+\nabla_{h} f_{j i .} . \tag{2.3}
\end{equation*}
$$

We now prove a series of lemmas.
Lemma 2.1. Assume that a differentiable manifold admits an ( $f, g, u, v, \lambda$ )structure such that $\lambda\left(1-\lambda^{2}\right)$ is almost everywhere non-zero,

$$
\begin{equation*}
\nabla_{j} u_{i}-\nabla_{i} u_{j}=2 f_{j i} \tag{2.4}
\end{equation*}
$$

and

$$
\begin{equation*}
S_{j i}^{h}=2 v_{j}\left(\nabla_{i} v^{h}-\lambda \delta_{i}^{h}\right)-2 v_{i}\left(\nabla_{j} v^{h}-\lambda \delta_{j}^{h}\right) \tag{2.5}
\end{equation*}
$$

At a point at which $\lambda \neq 0$, we define a tensor field $k_{j i}$ of type $(0,2)$ by

$$
\begin{equation*}
\nabla_{j} u_{i}+\nabla_{i} u_{j}=-2 \lambda k_{j i} . \tag{2.6}
\end{equation*}
$$

Then we have

$$
\begin{gather*}
\nabla_{j} u_{i}=f_{j i}-\lambda k_{j i},  \tag{2.7}\\
\nabla_{j} v_{i}=-k_{j t} f_{i}^{t}+\lambda g_{j i} \tag{2.8}
\end{gather*}
$$

and

$$
\begin{equation*}
\nabla_{j} \lambda=k_{j i} u^{i}-v_{j} . \tag{2.9}
\end{equation*}
$$

Proof. Equation (2.7) follows from (2.4) and (2.6). Transvecting $u^{2}$ to (2.7) and using $u_{i} u^{i}=1-\lambda^{2}$, we find

$$
-\lambda \nabla_{j} \lambda=\lambda v_{j}-\lambda k_{j i} u^{2}
$$

from which (2.9) follows.
Differentiating (2.4) covariantly, we find

$$
\nabla_{k} \nabla_{j} u_{i}-\nabla_{k} \nabla_{i} u_{\jmath}=2 \nabla_{k} f_{j i}
$$

from which

$$
\begin{equation*}
f_{k j i}=\nabla_{k} f_{j i}+\nabla_{\jmath} f_{i k}+\nabla_{\imath} f_{k j}=0 \tag{2.10}
\end{equation*}
$$

Thus substituting (2.5), (2.7) and (2.10) into (2.2), we obtain

$$
\begin{aligned}
& -2 v_{i}\left(\nabla_{j} v_{h}-\lambda g_{j h}\right) u^{j} \\
= & -2 \lambda k_{i h}+2 \lambda u_{i} k_{t h} u^{t}+\lambda f_{2}^{t}\left(\nabla_{t} v_{h}+\nabla_{h} v_{t}\right) \\
& -2 \lambda^{2} f_{i h}-\lambda f_{\imath}^{t}\left(\nabla_{t} v_{h}-\nabla_{h} v_{t}\right)-v_{i}\left(\nabla_{t} v_{h}-\nabla_{h} v_{t}\right) u^{t},
\end{aligned}
$$

from which

$$
\begin{aligned}
& -2 \lambda k_{i h}+2 \lambda u_{i} k_{t h} u^{t}+2 \lambda f_{\imath}^{t} \nabla_{h} v_{t}-2 \lambda^{2} f_{i h} \\
& +v_{i}\left(u^{t} \nabla_{t} v_{h}\right)-v_{i}\left(\nabla_{h} u_{t}\right) v^{t}-2 \lambda v_{i} u_{h}=0
\end{aligned}
$$

or

$$
\begin{align*}
& -2 \lambda k_{i h}+2 \lambda u_{i} k_{t h} u^{t}+2 \lambda f_{\imath}^{t} \nabla_{h} v_{t}-2 \lambda^{2} f_{i h} \\
& +v_{i}\left(u^{t} \nabla_{t} v_{h}\right)+\lambda v_{i} k_{t h} v^{t}-\lambda v_{i} u_{h}=0 \tag{2.11}
\end{align*}
$$

by virtue of (2.7).
Transvecting (2.11) with $v^{i}$, we find

$$
\begin{aligned}
& -2 \lambda k_{t h} v^{t}+2 \lambda^{2} u^{t} \nabla_{h} v_{t}-2 \lambda^{3} u_{h} \\
& +\left(1-\lambda^{2}\right)\left(u^{t} \nabla_{t} v_{h}\right)+\lambda\left(1-\lambda^{2}\right) k_{t h} v^{t}-\lambda\left(1-\lambda^{2}\right) u_{h}=0,
\end{aligned}
$$

from which, using $u^{t} \nabla_{h} v_{t}=-v^{t}\left(\nabla_{h} u_{t}\right)=-v^{t}\left(f_{h t}-\lambda k_{h t}\right)=\lambda u_{h}+\lambda k_{t h} v^{t}$

$$
\begin{equation*}
u^{t} \nabla_{t} v_{h}=\lambda\left(u_{h}+k_{t h} v^{l}\right) . \tag{2.12}
\end{equation*}
$$

Substituting (2.12) into (2.11), we find

$$
-2 \lambda k_{i h}+2 \lambda u_{i} k_{t h} u^{t}+2 \lambda f_{\imath}{ }^{t} \nabla_{h} v_{t}-2 \lambda^{2} f_{i h}+2 \lambda v_{i} k_{t h} v^{t}=0,
$$

or

$$
f_{\imath}^{t} \nabla_{h} v_{t}=k_{i h}+\lambda f_{i h}-u_{i} k_{t h} u^{t}-v_{i} k_{t h} v^{t},
$$

from which, transvecting with $f_{k}{ }^{i}$,

$$
\begin{aligned}
& \left(-\delta_{k}^{t}+u_{k} u^{t}+v_{k} v^{t}\right) \nabla_{h} v_{t} \\
= & k_{h t} f_{k}^{t}+\lambda\left(-g_{k h}+u_{k} u_{h}+v_{k} v_{h}\right)-\lambda v_{k} k_{t h} u^{t}+\lambda u_{k} k_{t h} v^{t},
\end{aligned}
$$

or, using (2.7) and (2.9),

$$
\begin{aligned}
& -\nabla_{h} v_{k}-u_{k}\left(f_{h t}-\lambda k_{h t}\right) v^{t}-\lambda v_{k}\left(k_{h t} u^{t}-v_{h}\right) \\
= & k_{h t} f_{k}^{t}-\lambda g_{k h}+\lambda u_{k} u_{h}+\lambda v_{k} v_{h}-\lambda v_{k} k_{t h} u^{t}+\lambda u_{k} k_{t h} v^{t},
\end{aligned}
$$

from which,

$$
\nabla_{h} v_{k}=-k_{h t} f_{k}{ }^{t}+\lambda g_{h k}
$$

which proves (2.8).
Substituting (2.8) into (2.12), we find

$$
u^{t}\left(-k_{t s} f_{n}^{s}+\lambda g_{t h}\right)=\lambda\left(u_{h}+k_{t h} v^{t}\right),
$$

or

$$
\begin{equation*}
k_{t s} u^{t} f_{h}^{s}+\lambda k_{t h} v^{t}=0, \tag{2.13}
\end{equation*}
$$

from which, transvecting $v^{h}$,

$$
\begin{equation*}
k_{j i} u^{j} u^{2}+k_{j i} v^{j} v^{2}=0 . \tag{2.14}
\end{equation*}
$$

Lemma 2.2. Under the same assumptions as those in Lemma 2.1, we have

$$
\begin{equation*}
k_{j t} f_{\imath}^{t}-k_{i t} f_{j}^{t}=0 \tag{2.15}
\end{equation*}
$$

and

$$
\begin{equation*}
\nabla_{k} f_{j i}=-g_{k j} u_{i}+g_{k i} u_{j}-k_{k j} v_{i}+k_{k i} v_{j} . \tag{2.16}
\end{equation*}
$$

Proof. Substituting (2.5) and (2.10) into (2.1), we find

$$
\begin{align*}
& f_{j}^{t} \nabla_{h} f_{t i}-f_{\imath} \nabla_{h} f_{t j}  \tag{2.17}\\
= & u_{j}\left(\nabla_{i} u_{h}\right)-u_{i}\left(\nabla_{j} u_{h}\right)-v_{j}\left(\nabla_{i} v_{h}-2 \lambda g_{i n}\right)+v_{i}\left(\nabla_{j} v_{h}-2 \lambda g_{j h}\right) .
\end{align*}
$$

We compute the first member of (2.17) as follows.

$$
\begin{aligned}
& f_{j}^{t} \nabla_{h} f_{t i}-f_{\imath}{ }^{t} \nabla_{h} f_{t j} \\
= & \nabla_{h}\left(f_{j} f_{t i}\right)+2 f_{\imath}{ }^{t} \nabla_{h} f_{j t} \\
= & \nabla_{h}\left(-g_{j i}+u_{j} u_{i}+v_{j} v_{i}\right)+2 f_{\imath} \nabla_{h} f_{j t} \\
= & \left(\nabla_{h} u_{j}\right) u_{i}+u_{j}\left(\nabla_{h} u_{i}\right)+\left(\nabla_{h} v_{j}\right) v_{i}+v_{j}\left(\nabla_{h} v_{i}\right)+2 f_{\imath} \nabla_{\nabla_{h}} f_{j t} .
\end{aligned}
$$

Thus (2.17) becomes

$$
\begin{aligned}
2 f_{\imath} \nabla_{h} f_{j t}= & u_{j}\left(\nabla_{i} u_{h}-\nabla_{h} u_{i}\right)-u_{i}\left(\nabla_{j} u_{h}+\nabla_{h} u_{j}\right) \\
& -v_{j}\left(\nabla_{i} v_{h}+\nabla_{h} v_{i}-2 \lambda g_{i h}\right)+v_{i}\left(\nabla_{j} v_{h}-\nabla_{h} v_{j}-2 \lambda g_{j h}\right) .
\end{aligned}
$$

Substituting (2.7) and (2.8) into this, we find

$$
\begin{aligned}
2 f_{\imath} \nabla_{h} f_{j t}= & 2 u_{j} f_{i h}+2 \lambda u_{i} k_{j h}-v_{j}\left(-k_{i t} f_{h}^{t}-k_{h l} f_{\imath}\right) \\
& +v_{i}\left(-k_{j t} f_{h}^{t}+k_{h t} f_{j}^{t}-2 \lambda g_{j h}\right),
\end{aligned}
$$

from which, transvecting $f_{k}{ }^{i}$, we obtain

$$
\begin{align*}
& 2\left(-\delta_{k}^{t}+u_{k} u^{t}+v_{k} v^{t}\right) \nabla_{h} f_{j t} \\
= & 2 u_{j}\left(-g_{k h}+u_{k} u_{h}+v_{k} v_{h}\right)+2 \lambda^{2} v_{k} k_{j h}  \tag{2.18}\\
& +v_{j}\left\{k_{t s} f_{k}^{t} f_{h}^{s}+k_{h t}\left(-\delta_{k}^{t}+u_{k} u^{t}+v_{k} v^{t}\right)\right\}-\lambda u_{k}\left(k_{h t} f_{j}^{t}-k_{j t} f_{h}^{t}-2 \lambda g_{j h}\right) .
\end{align*}
$$

We compute the first member of (2.18) as follows:

$$
\begin{aligned}
& 2\left(-\delta_{k}^{t}+u_{k} u^{t}+v_{k} v^{t}\right) \nabla_{h} f_{j t} \\
= & -2 \nabla_{h} f_{j k}+2 u_{k}\left(\nabla_{h}\left(f_{j t} u^{t}\right)-f_{j}^{t}\left(\nabla_{h} u_{t}\right)\right\}+2 v_{k}\left\{\nabla_{h}\left(f_{j t} v^{t}\right)-f_{j}^{t}\left(\nabla_{h} v_{t}\right)\right\} \\
= & -2 \nabla_{h} f_{j k}+2 u_{k}\left\{\left(\nabla_{h} \lambda\right) v_{j}+\lambda\left(\nabla_{h} v_{j}\right)-f_{j}^{t}\left(\nabla_{h} u_{t}\right)\right\}-2 v_{k}\left\{\left(\nabla_{h} \lambda\right) u_{j}+\lambda\left(\nabla_{h} u_{j}\right)+f_{j}^{t}\left(\nabla_{h} v_{t}\right)\right\},
\end{aligned}
$$

or, using (2.7), (2.8) and (2.9),

$$
\begin{aligned}
& 2\left(-\delta_{k}^{t}+u_{k} u^{t}+v_{k} v^{t}\right) \nabla_{h} f_{j t} \\
= & -2 \nabla_{h} f_{j k}+2 u_{k}\left\{\left(k_{h t} u^{t}-v_{h}\right) v_{j}+\lambda\left(-k_{h t} f_{j}^{t}+\lambda g_{h j}\right)\right. \\
& \left.-\left(g_{j h}-u_{j} u_{h}-v_{j} v_{h}-\lambda k_{h t} f_{j}^{t}\right)\right\} \\
& -2 v_{k}\left(k_{h t} u^{t}-v_{h}\right) u_{j}+\lambda\left(f_{h j}-\lambda k_{h j}\right) \\
& \left.+\left(k_{h j}-k_{h t} u^{t} u_{j}-k_{h t} v^{t} v_{j}+\lambda f_{j h}\right)\right\}
\end{aligned}
$$

$$
\begin{aligned}
= & -2 \nabla_{h} f_{j k}+2 u_{k} v_{j} k_{h t} u^{t}-2\left(1-\lambda^{2}\right) u_{k} g_{j h}+2 u_{k} u_{j} u_{h} \\
& +2 v_{k} u_{j} v_{h}-2\left(1-\lambda^{2}\right) v_{k} k_{h j}+2 v_{k} v_{j} k_{h t} v^{t} .
\end{aligned}
$$

Thus (2.18) becomes

$$
\begin{aligned}
& -2 \nabla_{h} f_{j k}+2 u_{k} v_{j} k_{h t} u^{t}-2\left(1-\lambda^{2}\right) u_{k} g_{j h}+2 u_{k} u_{j} u_{h} \\
& +2 v_{k} u_{j} v_{h}-2\left(1-\lambda^{2}\right) v_{k} k_{h j}+2 v_{k} v_{j} k_{h t} v^{t} \\
= & 2 u_{j}\left(-g_{k h}+u_{k} u_{h}+v_{k} v_{h}\right)+2 \lambda^{2} v_{k} k_{j h} \\
& +v_{j}\left\{k_{t s} f_{k} f_{f_{h}}{ }^{s}+k_{h t}\left(-\partial_{k}^{t}+u_{k} u^{t}+v_{k} v^{t}\right)\right\} \\
& -\lambda u_{k}\left(k_{h t} f_{j}^{t}-k_{j t} f_{h}^{t}-2 \lambda g_{j h}\right),
\end{aligned}
$$

or

$$
\begin{align*}
2 \nabla_{h} f_{j k}= & 2 u_{j} g_{k h}-2 u_{k} g_{j h}-2 v_{k} k_{h j}+v_{j} k_{h k} \\
& +u_{k} v_{j} k_{h t} u^{t}+v_{k} v_{j} k_{h t} v^{t}  \tag{2.19}\\
& -v_{j} k_{t s} f_{k}^{t} f_{h}^{s}+\lambda u_{k}\left(k_{h t} f_{j}^{t}-k_{j t} f_{h}^{t}\right) .
\end{align*}
$$

Taking the skew-symmetric part of (2.19) with respect to $h$ and $k$ and using $\nabla_{h} f_{j k}-\nabla_{k} f_{j h}=-\nabla_{j} f_{k h}$, we find

$$
\begin{align*}
-2 V_{J} f_{k h}= & -2\left(u_{k} g_{j h}-u_{h} g_{j k}\right)-2\left(v_{k} k_{h j}-v_{h} k_{k j}\right)+v_{j}\left(u_{k} k_{h t} u^{t}-u_{h} k_{k t} u^{t}\right.  \tag{2.20}\\
& \left.+v_{k} k_{h t} v^{t}-v_{h} k_{k t} v^{t}\right)+\lambda u_{k}\left(k_{h t} f_{j}^{t}-k_{j t} f_{h}^{t}\right)-\lambda u_{h}\left(k_{k t} f_{j}^{t}-k_{j t} f_{k}^{t}\right) .
\end{align*}
$$

Now, transvecting $u^{3}$ to (2.19) and taking account of (2.13), we find

$$
\begin{equation*}
u^{t} \nabla_{j} f_{t h}=\left(1-\lambda^{2}\right) g_{j h}-u_{j} u_{h}-v_{h} k_{j t} u^{t} . \tag{2.21}
\end{equation*}
$$

On the other hand, transvecting $u^{k}$ to (2.20) and taking account of (2.13), we find

$$
\begin{align*}
-2 u^{t} \nabla_{J} f_{t h}= & -2\left(1-\lambda^{2}\right) g_{j h}+2 u_{j} u_{h}+2 v_{h} k_{j t} u^{t} \\
& \left.+v_{j}\left(1-\lambda^{2}\right) k_{h t} u^{t}-u_{h} k_{t s} u^{t} u^{s}-v_{h} k_{t s} u^{t} v^{s}\right\}  \tag{2.22}\\
& +\lambda\left(1-\lambda^{2}\right)\left(k_{h t} f_{j}^{t}-k_{j t} f_{h}^{t}\right) .
\end{align*}
$$

Adding twice of (2.21) and (2.22), we find

$$
\begin{equation*}
\left.v_{j}\left(1-\lambda^{2}\right) k_{h t} u^{t}-u_{h} k_{t s} u^{t} u^{s}-v_{h} k_{t s} u^{t} v^{s}\right\}+\lambda\left(1-\lambda^{2}\right)\left(k_{h t} f_{j}^{t}-k_{j t} f_{h}^{t}\right)=0, \tag{2.23}
\end{equation*}
$$

from which, taking the symmetric part,

$$
\begin{aligned}
& v_{j}\left\{\left(1-\lambda^{2}\right) k_{h t} u^{t}-u_{h} k_{t s} u^{t} u^{s}-v_{h} k_{t s} u^{t} v^{s}\right\} \\
& \quad+v_{h}\left\{\left(1-\lambda^{2}\right) k_{j t} u^{t}-u_{j} k_{t s} u^{t} u^{s}-v_{j} k_{t s} u^{t} v^{s}\right\}=0,
\end{aligned}
$$

Transvecting this with $v^{j}$, we find

$$
\begin{equation*}
\left(1-\lambda^{2}\right) k_{h t} u^{t}=k_{t s} u^{t} u^{s} u_{h}+k_{t s} u^{t} v^{s} v_{h} . \tag{2.24}
\end{equation*}
$$

Substituting (2.24) into (2.23), we find

$$
\begin{equation*}
k_{j t} f_{n}^{t}-k_{h t} f_{j}^{t}=0, \tag{2.25}
\end{equation*}
$$

which proves (2.15).
From (2.13), we have

$$
\left(1-\lambda^{2}\right) k_{t s} u^{t} f_{h}^{s}+\lambda\left(1-\lambda^{2}\right) k_{t h} v^{t}=0 .
$$

Substituting (2.24) into this equation, we find

$$
\lambda k_{t s} u^{t} u^{s} v_{h}-\lambda k_{t s} u^{t} v^{s} u_{h}+\lambda\left(1-\lambda^{2}\right) k_{t h} v^{t}=0
$$

from which,

$$
\begin{equation*}
\left(1-\lambda^{2}\right) k_{j t} v^{t}=k_{t s} u^{t} v^{s} u_{j}-k_{t s} u^{t} u^{s} v_{j} \tag{2.26}
\end{equation*}
$$

Substituting (2.24), (2.25) and (2.26) into (2.20) $\times\left(1-\lambda^{2}\right)$, we find

$$
2\left(1-\lambda^{2}\right) \nabla_{j} f_{k h}=2\left(1-\lambda^{2}\right)\left(u_{k} g_{j h}-u_{h} g_{j k}\right)+2\left(1-\lambda^{2}\right)\left(v_{k} k_{h j}-v_{h} k_{k j}\right)
$$

which proves (2.16).
Lemma 2.3. Under the same assumptions as those in Lemma 2.1, we have, at a point at which $1-\lambda^{2} \neq 0$,

$$
\begin{align*}
k_{t}{ }^{\prime} & =0  \tag{2.27}\\
k_{j t} u^{t} & =\beta v_{j}  \tag{2.28}\\
k_{j t} v^{t} & =\beta u_{j} \tag{2.29}
\end{align*}
$$

where

$$
\beta=\frac{1}{1-\lambda^{2}} k_{t s} u^{t} v^{s} .
$$

Proof. Differentiating (2.9) covariantly and using (2.7) and (2.8), we find

$$
\nabla_{k} \nabla_{j} \lambda=\left(\nabla_{k} k_{j i}\right) u^{i}+k_{\jmath}\left(f_{k t}-\lambda k_{k t}\right)+k_{k t} f_{j}^{t}-\lambda g_{k \jmath}
$$

from which,

$$
\begin{equation*}
\left(\nabla_{k} k_{j i}-\nabla_{j} k_{k i}\right) u^{i}=0 \tag{2.31}
\end{equation*}
$$

From (2.24) and (2.26), we have

$$
\begin{equation*}
k_{j t} u^{t}=\alpha u_{j}+\beta v_{j} \tag{2.32}
\end{equation*}
$$

and

$$
\begin{equation*}
k_{j t} v^{t}=\beta u_{j}-\alpha v_{j} \tag{2.33}
\end{equation*}
$$

respectively, where

$$
\alpha=\frac{1}{1-\lambda^{2}} k_{t s} u^{t} u^{s} .
$$

Differentiating (2.32) covariantly and using (2.7) and (2.8), we find

$$
\begin{aligned}
& \left(\nabla_{k} k_{j t}\right) u^{t}+k_{j}^{t}\left(f_{k t}-\lambda k_{k t}\right) \\
= & \left(\nabla_{k} \alpha\right) u_{j}+\alpha\left(f_{k j}-\lambda k_{k j}\right)+\left(\nabla_{k} \beta\right) v_{j}+\beta\left(-k_{k t} f_{j}^{t}+\lambda g_{k j}\right),
\end{aligned}
$$

from which, taking the skew-symmetric part and using (2.31),

$$
\begin{equation*}
\left(\nabla_{k} \alpha\right) u_{j}-\left(\nabla_{j} \alpha\right) u_{k}+\left(\nabla_{k} \beta\right) v_{j}-\left(\nabla_{j} \beta\right) v_{k}+2 \alpha f_{k_{j}}=0 . \tag{2.34}
\end{equation*}
$$

Transvecting $u^{j}$ to (2.34), we see that $\nabla_{k} \alpha$ is written in the form

$$
\nabla_{k} \alpha=a u_{k}+b v_{k},
$$

and transvecting $v^{j}$ to (2.34), we see that $\nabla_{k} \beta$ is written in the form

$$
\nabla_{k} \beta=c u_{k}+d v_{k} .
$$

Substituting these into (2.34), we have

$$
(b-c)\left(v_{k} u_{j}-u_{k} v_{j}\right)+2 \alpha f_{k j}=0,
$$

from which, we have $\alpha=0$. This proves (2.28) and (2.29).
Transvecting $f_{k}{ }^{h}$ to (2.25), we find

$$
k_{j t}\left(-\delta_{k}^{t}+u_{k} u^{t}+v_{k} v^{t}\right)-k_{t s} f_{j}^{t} f_{k}^{s}=0,
$$

or using (2.28) and (2.29),

$$
-k_{j k}+\beta\left(u_{j} v_{k}+u_{k} v_{j}\right)-k_{t s} f_{j}^{t} f_{k}^{s}=0
$$

from which, transvecting $g^{j k}$,

$$
-k_{t}^{t}-k_{t s}\left(g^{t_{s}^{s}}-u^{t} u^{s}-v^{t} v^{s}\right)=0,
$$

that is, $k_{t}{ }^{t}=0$ and (2.27) is proved.
Finally, from (2.9) and (2.28), we have

$$
\nabla_{j} \lambda=k_{j t} u^{t}-v_{j}=(\beta-1) v_{j}
$$

which proves (2.30).

## 3. Theorems on ( $f, g, u, v, \lambda)$-structures.

In this section we first prove
Theorem 3.1. Suppose that a complete differentiable manifold $M$ admits an ( $f, g, u, v, \lambda$ )-structure such that $\lambda\left(1-\lambda^{2}\right)$ is almost everywhere non-zero,

$$
\begin{equation*}
\nabla_{j} u_{i}-\nabla_{i} u_{j}=2 f_{j i} \tag{3.1}
\end{equation*}
$$

and

$$
\begin{equation*}
S_{j i}^{h}=2 v_{j}\left(\nabla_{i} v^{h}-\lambda \delta_{i}^{h}\right)-2 v_{i}\left(\nabla_{j} v^{h}-\lambda \delta_{j}^{h}\right) \tag{3.2}
\end{equation*}
$$

At a point at which $\lambda \neq 0$, we define a tensor field $k_{j i}$ of type $(0,2)$ by

$$
\begin{equation*}
\nabla_{j} u_{i}+\nabla_{i} u_{j}=-2 \lambda k_{j i} . \tag{3.3}
\end{equation*}
$$

If $u^{h}$ and $k_{j i}$ satisfy

$$
\begin{equation*}
u^{j} \nabla_{j} u_{i}=0 \tag{3.4}
\end{equation*}
$$

and

$$
\begin{equation*}
\nabla_{k} k_{j i}-\nabla_{j} k_{k \imath}=0 \tag{3.5}
\end{equation*}
$$

then the manifold is isometric to $S^{n}(1 / \sqrt{2}) \times S^{n}(1 / \sqrt{2})$.
Proof. Since the assumptions of Lemma 2.1 are satisfied, the conclusions of Lemmas 2.1, 2.2 and 2.3 are all valid.

From (2.7), (2.28) and (3.4), we have

$$
0=u^{j} \nabla_{j} u_{i}=-\lambda v_{i}-\lambda \beta v_{i}=-\lambda(1+\beta) v_{i}
$$

from which $\beta=-1$. Thus, (2.28), (2.29) and (2.30) become respectively

$$
\begin{gather*}
k_{j t} u^{t}=-v_{j},  \tag{3.6}\\
k_{j t} v^{t}=-u_{j},  \tag{3.7}\\
\nabla_{j} \lambda=-2 v_{j} . \tag{3.8}
\end{gather*}
$$

Differentiating (3.7) covariantly and substituting (2.7) and (2.8), we find

$$
\left(\nabla_{k} k_{j}^{t}\right) v_{t}+k_{\jmath}^{t}\left(-k_{k s} f_{t}^{s}+\lambda g_{k t}\right)=\lambda k_{k j}-f_{k j}
$$

from which, taking the skew-symmetric part and using (3.5),

$$
k_{\jmath}{ }^{t} k_{k}{ }^{s} f_{t s}=f_{k j}
$$

or, using (2.15),

$$
\begin{equation*}
k_{\jmath}{ }^{t} k_{t}{ }^{s} f_{k s}=f_{k_{j}} . \tag{3.9}
\end{equation*}
$$

Transvecting (3.9) with $f_{2}{ }^{k}$, we find

$$
k_{j}{ }^{t} k_{t}{ }^{s}\left(-g_{i s}+u_{i} u_{s}+v_{i} v_{s}\right)=-g_{j i}+u_{j} u_{i}+v_{j} v_{i},
$$

or, using (3.6) and (3.7),
(3.10)

$$
k_{j}{ }^{t} k_{t i}=g_{j i} .
$$

Differentiating (3.10) covariantly, we have

$$
\begin{equation*}
\left(\nabla_{k} k_{j}{ }^{t}\right) k_{t i}+k_{j}^{t}\left(\nabla_{k} k_{t i}\right)=0 . \tag{3.11}
\end{equation*}
$$

Since $\nabla_{k} k_{j i}$ is symmetric in all indices, (3.11) can be written as

$$
\begin{equation*}
k_{j}{ }^{t}\left(\nabla_{i} k_{t k}\right)+k_{i}{ }^{t}\left(\nabla_{j} k_{t k}\right)=0, \tag{3.12}
\end{equation*}
$$

which shows that $k_{j}{ }^{t}\left(\nabla_{k} k_{t i}\right)$ is skew-symmetric in $j$ and $k$.
Now, from (3.11), we have, taking the skew-symmetric part with respect to $k$ and $j$,

$$
k_{j}{ }^{t}\left(\nabla_{k} k_{t i}\right)-k_{k}{ }^{t}\left(\nabla_{j} k_{t i}\right)=0,
$$

or

$$
\begin{equation*}
k_{j}{ }^{t}\left(\nabla_{k} k_{t i}\right)=0, \tag{3.13}
\end{equation*}
$$

from which, using (3.10),

$$
\begin{equation*}
\nabla_{k} k_{t i}=0 . \tag{3.14}
\end{equation*}
$$

On the other hand, differentiating (2.7) covariantly and using (2.15), (3.8) and (3.14), we obtain

$$
\begin{equation*}
\nabla_{k} \nabla_{j} u_{i}=-g_{k j} u_{i}+g_{k i} u_{j}-k_{k j} v_{i}+k_{k i} v_{j}+2 v_{k} k_{j i} . \tag{3.15}
\end{equation*}
$$

Thus the theorem follows from Theorem 0.7.
Theorem 3.2. Assume that a complete differentiable manifold $M$ admits an ( $f, g, u, v, \lambda$ )-structure such that $\lambda\left(1-\lambda^{2}\right)$ is almost everywhere non-zero, and (3.1), (3.2) hold. At a point at which $\lambda \neq 0$, we define $k_{j i}$ by (3.3).

If the sectional curvature $K(\gamma)$ with respect to the section $\gamma$ spanned by $u^{h}$ and $v^{h}$ is constant and

$$
\begin{equation*}
\nabla_{k} k_{j i}-\nabla_{j} k_{k i}=0, \tag{3.16}
\end{equation*}
$$

then the manifold is isometric to a sphere $S^{2 n}(1)$ or to $S^{n}(1 / \sqrt{2}) \times S^{n}(1 / \sqrt{2})$.
Proof. In this case also, the conclusions of Lemmas 2.1,2.2 and 2.3 are all valid.

Differentiating (2.7) covariantly and using (2.9), (2.15) and (2.28), we find

$$
\begin{equation*}
\nabla_{k} \nabla_{j} u_{i}=-g_{k j} u_{i}+g_{k i} u_{j}-k_{k j} v_{i}+k_{k i} v_{j}+(1-\beta) v_{k} k_{j i}-\lambda \nabla_{k} k_{j i}, \tag{3.17}
\end{equation*}
$$

from which, using the Ricci identity,

$$
-K_{k j i}{ }^{h} u_{h}=g_{k i} u_{j}-g_{j i} u_{k}+k_{k i} v_{j}-k_{j i} v_{k}+(1-\beta)\left(v_{k} k_{j i}-v_{j} k_{k i}\right),
$$

$K_{k j i}{ }^{h}$ being the curvature tensor and consequently

$$
\begin{equation*}
K(\gamma)=-\frac{K_{k j i i} v^{k} u^{j} v^{i} u^{h}}{\left(1-\lambda^{2}\right)^{2}}=1-\beta^{2} . \tag{3.18}
\end{equation*}
$$

Since we have assumed that $K(\gamma)$ is constant, $\beta$ must be also constant. From (2.29), we have

$$
k_{j}{ }^{t} v_{t}=\beta u_{j} .
$$

Differentiating this covariantly and using (2.7) and (2.8), we find

$$
\left(\nabla_{k} k_{j}{ }^{t}\right) v_{t}+k_{j}^{t}\left(-k_{k s} f_{t}^{s}+\lambda g_{k t}\right)=\beta\left(f_{k j}-\lambda k_{k j}\right),
$$

from which, taking the skew-symmetric part and using (3.16),

$$
k_{j} k_{k s} f_{t}^{s}=-\beta f_{k j}
$$

or, using (2.16),

$$
\begin{equation*}
k_{j}{ }^{t} k_{t}{ }^{s} f_{k s}=-\beta f_{k j} . \tag{3.19}
\end{equation*}
$$

Transvecting $u^{j}$ to (3.19) and using (2.28) and (2.29), we find

$$
\lambda \beta^{2} v_{k}=-\lambda \beta v_{k},
$$

from which, using $\beta=$ const.

$$
\begin{equation*}
\beta=0 \quad \text { or } \quad \beta=-1 \tag{3.20}
\end{equation*}
$$

Transvecting $f_{i}^{k}$ to (3.19), we find

$$
k_{j}{ }^{t} k_{t}^{s}\left(-g_{i s}+u_{i} u_{s}+v_{i} v_{s}\right)=-\beta\left(-g_{j i}+u_{j} u_{i}+v_{j} v_{i}\right),
$$

or, using (2.28) and (2.29)

$$
-k_{j}{ }^{t} k_{t i}+\beta^{2}\left(u_{j} u_{i}+v_{j} v_{i}\right)=\beta\left(g_{j i}-u_{j} u_{i}-v_{j} v_{i}\right),
$$

that is,

$$
\begin{equation*}
k_{j}{ }^{t} k_{t i}=-\beta g_{j i}+\beta(\beta+1)\left(u_{j} u_{i}+v_{j} v_{i}\right) . \tag{3.21}
\end{equation*}
$$

Thus, if $\beta=0$, then $k_{j i}=0$ and in this case we have, from (2.30),

$$
\begin{equation*}
\nabla_{j} \lambda=-v_{i} \tag{3.22}
\end{equation*}
$$

and (3.17) becomes

$$
\begin{equation*}
\nabla_{k} \nabla_{j} u_{i}=-g_{k j} u_{i}+g_{k i} u_{j} . \tag{3.23}
\end{equation*}
$$

If $\beta=-1$, then

$$
\begin{equation*}
k_{j}{ }^{t} k_{l i}=g_{j i}, \tag{3.24}
\end{equation*}
$$

and in this case we have, from (2.30)

$$
\begin{equation*}
\nabla_{j} \lambda=-2 v_{j} . \tag{3.25}
\end{equation*}
$$

In the proof of Theorem 3.1, we found that (3.16) and (3.24) imply $\nabla_{k} k_{j i}=0$. Thus (3.17) gives

$$
\begin{equation*}
\nabla_{k} \nabla_{j} u_{i}=-g_{k j} u_{i}+g_{k i} u_{j}-k_{k j} v_{i}+k_{k i} v_{j}+2 v_{k} k_{j i} . \tag{3.26}
\end{equation*}
$$

Equations (3.22), (3.23), (3.25), (3.26) and Theorem 0.7 prove the theorem.

## Bibliography

[1] Blair, D. E., G.D. Ludden, and K. Yano, Induced structures on submanifolds. Kōdai Math. Sem. Rep. 22 (1970), 188-198.
[2] Blair, D.E., G.D. Ludden, and K. Yano, Hypersurfaces of an odd-dimensional sphere. J. Diff. Geom. 5 (1971), 479-486.
[3] Blair, D.E., G.D. Ludden, and K. Yano, On the intrinsic geometry of $S^{n} \times S^{n}$. Math. Ann. 194 (1971), 68-77.
[4] Yano, K., Differential geometry of $S^{n} \times S^{n}$. To appear in J. Diff. Geom.
[5] Yano, K., and S. Ishihara, Note on hypersurfaces of an odd-dimensional sphere. Kōdai Math. Sem. Rep. 24 (1972), 422-429.
[6] Yano, K., and U-Hang Ki, On quasi-normal ( $f, g, u, v, \lambda$ )-structures. Kōdai Math. Sem. Rep. 24 (1972), 106-120.
[7] Yano, K., and U-Hang Ki, Submanifolds of codimension 2 in an even-dimensional Euclidean space. Kōdai Math. Sem. Rep. 24 (1972), 315-330.
[8] Yano, K., and M. Okumura, On ( $f, g, u, v, \lambda$ )-structures. Kōdai Math. Sem. Rep. 22 (1970), 401-423.
[9] Yano, K., and M. Okumura, On normal ( $f, g, u, v, \lambda$ )-structures on submanifolds of codimension 2 in an even-dimensional Euclidean space. Kōdai Math. Sem. Rep. 23 (1971), 172-197.

Tokyo Institute of Technology, and Kyungpook University.

