

RIEMANNIAN METRICS ON PRINCIPAL CIRCLE BUNDLES OVER LOCALLY SYMMETRIC KÄHLERIAN MANIFOLDS

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0. Introduction.

In Riemannian Geometry, one of the most interesting problems is to find all Einsteinian manifolds. A. Besse has suggested the research for Einsteinian manifolds satisfying the condition (see [3], p. 165)

$$(*) \quad R_{i p q r} R_j^{p q r} = \text{constant } g_{ij},$$

where $g=(g_{ij})$ is the Riemannian metric and $R=(R^i_{jkl})$ is the curvature tensor. Its typical examples are a locally symmetric spaces and a harmonic Riemannian manifold (cf. [13]). But the author [17] has recently shown that $Sp(2)/SU(2)$ of Berger (cf. [2]) is an Einsteinian manifold satisfying (*).

On the other hand, J. E. D'Atri and H. K. Nickerson has initiated a study of the Riemannian manifold whose local geodesic symmetries are volume-preserving (up to sign). In this paper, we call such a manifold a (locally) volume symmetric space. It has been studied by J. E. D'Atri and H. K. Nickerson ([5], [6]), K. Sekigawa ([15]) and Y. Watanabe ([16]). This class of manifolds obviously includes harmonic Riemannian manifolds and locally symmetric spaces. Then we are interested in Einsteinian manifolds (especially Einsteinian manifolds satisfying (*)), which are volume symmetric.

In this paper, we consider the Riemannian metric $\tilde{g}(t)$ given on a principal circle bundle P over a Kählerian manifold M (cf. §2). We show that if M is locally symmetric, then $(P, \tilde{g}(t))$ is locally homogeneous and volume symmetric. Especially we also remark that an Einsteinian metric is given on P in the case that M is Einsteinian.

In §2, we define the Riemannian metric on a principal circle bundle over an n -dimensional Riemannian manifold and give the fundamental formulas. In §3, we calculate the covariant derivative of the Riemannian curvature tensor by using the structure equations obtained in §2. In §4, we define a tensor field T of type $(1,2)$ on P and state its properties for later use. In §5, M is assumed to be a locally symmetric Kählerian manifold. Then by using the equations obtained in sections 3 and 4, we show the main results. In the last section, an

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example is stated in detail, because in the opinion of the author the method in this paper should have other applications.

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1. A principal circle bundle.

Let \tilde{M} and M be two Riemannian manifolds of dimensions m and n respectively, where $m-n>0$. A Riemannian submersions, which shall call simply submersion, is a differentiable map $\pi: \tilde{M} \rightarrow M$, which is onto, and for which at each point $x \in M$ the differential map π_* acts as an orthogonal projection of $T_{\tilde{x}}\tilde{M}$ onto $T_x M$, where $x = \pi(\tilde{x})$. Then for each point $x \in M$ its inverse image $\pi^{-1}(x)$ is a submanifold of \tilde{M} of dimension $m-n$, which is called the fibre over x .

A vector field on \tilde{M} is called vertical if it is always tangent to fibres and horizontal if always orthogonal to fibres; we use corresponding terminology for individual tangent vectors. We denote the Riemannian connections by $\tilde{\nabla}$ on \tilde{M} , ∇ on M and $\bar{\nabla}$ on the fibres, defined by the Riemannian metrics \tilde{g} on \tilde{M} , g on M and \bar{g} on the fibres respectively. For a submersion $\pi: \tilde{M} \rightarrow M$, let \mathcal{H} and \mathcal{V} denote the projections of the tangent space of \tilde{M} onto the subspaces of horizontal and vertical vectors, respectively. We define a vector field \tilde{X} on \tilde{M} to be basic provided \tilde{X} is horizontal and π -related to a vector field X on M . Every vector field X on M has a unique horizontal lift \tilde{X} to \tilde{M} , and \tilde{X} is basic. Thus $\tilde{X} \leftrightarrow X$ is a one-to-one correspondence between basic vector fields on \tilde{M} and arbitrary vector fields on M . This correspondence preserves brackets, inner products and covariant derivatives to the following (see [12]).

LEMMA 2.1. *If X and Y are basic vector fields on M , then*

- (1) $\langle \tilde{X}, \tilde{Y} \rangle = \langle X, Y \rangle \circ \pi$,
- (2) $[\tilde{X}, \tilde{Y}]$ is the basic vector field corresponding to $[X, Y]$,
- (3) $\tilde{\nabla}_{\tilde{X}} \tilde{Y}$ is the basic vector field corresponding to $\nabla_X Y$,

where $\langle \tilde{X}, \tilde{Y} \rangle$ (resp. $\langle X, Y \rangle$) is the inner product $\tilde{g}(\tilde{X}, \tilde{Y})$ (resp. $g(X, Y)$) of vectors \tilde{X} and \tilde{Y} of \tilde{M} (resp. X and Y of M).

Let P be a principal circle bundle over an n -dimensional manifold with projection π , g a Riemannian metric on M and η a connection form on P defining a connection in the bundle P . Functions on M such as components of tensor fields on M are considered sometimes as functions on P in a natural way without any change of notations. We shall also agree on that indices i, j, k and l run from 1 to n and α, β, γ and δ run from 0 to n . Since the structure group S^1 of P is abelian, the structure equation is given by

$$(2.1) \quad d\eta = \Omega,$$

where Ω is the curvature form of η . Then $\tilde{g} = \pi^*g + t^2\eta \otimes \eta$ for any $t > 0$, is a

Riemannian metric on P with respect to which π becomes a Riemannian submersion ([7], [12]). Explicitly if $\tilde{x} \in P$, $\tilde{X}, \tilde{Y} \in T_{\tilde{x}}P$, then

$$(2.2) \quad \tilde{g}(\tilde{X}, \tilde{Y}) = g(\pi_*\tilde{X}, \pi_*\tilde{Y}) + t^2\eta(\tilde{X})\eta(\tilde{Y}).$$

The action of S^1 on P allows us to take a unit fundamental vector field ξ such that

$$(2.3) \quad \tilde{g}(\tilde{X}, \xi) = t\eta(\tilde{X}),$$

for any vector field \tilde{X} on P . If \tilde{X} is basic, then $[\tilde{X}, \xi]$ is vertical. Thus since $[\tilde{X}, \xi]$ is horizontal (cf. [11]), we have the following

LEMMA 2.2 (cf. [7]). *If \tilde{X} is a basic vector field on M , then*

$$(2.4) \quad [\tilde{X}, \xi] = 0.$$

3. Structure equations of the fibring

To calculate the Riemannian curvature tensor \tilde{R} of \tilde{g} at any fixed point $\tilde{x} \in P$, we shall take a special orthonormal frame field on a neighborhood of $x = \pi(\tilde{x})$ such that $\nabla_{X_i}X_j = 0$ at x for any i and j . The basic vector fields \tilde{X}_i corresponding to X_i are orthonormal vector fields such that $\tilde{\nabla}_{\tilde{X}_i}\tilde{X}_j$ is vertical on the fibre passing through \tilde{x} for any i and j . Therefore we have a local orthonormal frame field $\{\xi, \tilde{X}_1, \dots, \tilde{X}_n\}$ around \tilde{x} . Using the standard formula

$$\begin{aligned} 2\langle \tilde{\nabla}_{\tilde{X}}\tilde{Y}, \tilde{Z} \rangle &= \tilde{X}\langle \tilde{Y}, \tilde{Z} \rangle + \tilde{Y}\langle \tilde{Z}, \tilde{Y} \rangle - \tilde{Z}\langle \tilde{X}, \tilde{Y} \rangle - \langle \tilde{X}, [\tilde{Y}, \tilde{Z}] \rangle \\ &\quad + \langle \tilde{Y}, [\tilde{Z}, \tilde{X}] \rangle + \langle \tilde{Z}, [\tilde{X}, \tilde{Y}] \rangle, \end{aligned}$$

for any vector fields \tilde{X}, \tilde{Y} and \tilde{Z} and the definition (2.2), we can prove the following lemma (cf. [14]).

LEMMA 3.1. *The components of the connection $\tilde{\nabla}$ with respect to the orthonormal frame field taken above are given by*

- (1) $\tilde{\nabla}_{\xi}\xi = 0$,
- (2) $\tilde{\nabla}_{\xi}\tilde{X}_i = \nabla_{\tilde{X}_i}\xi = t\Sigma\Omega_{ij}\tilde{X}_j$,
- (3) $\mathcal{C}\mathcal{V}(\tilde{\nabla}_{\tilde{X}_i}\tilde{X}_j) = (1/2)\mathcal{C}\mathcal{V}[\tilde{X}_i, \tilde{X}_j] = -t\Omega_{ij}\xi$,
- (4) $\mathcal{A}(\tilde{\nabla}_{\tilde{X}_i}\tilde{X}_j) = \Sigma S_{ijk}\tilde{X}_k$,
- (5) $(\tilde{\nabla}_{\xi}\Omega)(\tilde{X}_i, \tilde{X}_j) = 0$,

in a neighborhood of \tilde{x} , where $\Omega_{ij} = \Omega(\tilde{X}_i, \tilde{X}_j)$ and $S_{ijk} = \langle \nabla_{X_i}X_j, X_k \rangle \circ \pi$.

Let \tilde{R} (resp. R) be the curvature tensor of P (resp. M). Then by repeated use of Lemma 3.1, we can obtain the following

LEMMA 3.2. (cf. [10]). *The components of the curvature tensor R with respect to the orthonormal frame $\{\xi, \tilde{X}_1, \dots, \tilde{X}_n\}$ are given by*

- (1) $\tilde{R}_{i_0j_0} = t^2 \Sigma \Omega_{jl} \Omega_{li},$
- (2) $\tilde{R}_{i_0jk} = \tilde{\nabla}_i \Omega_{jk},$
- (3) $\tilde{R}_{ijkl} = R_{ijkl} - t^2 (\Omega_{il} \Omega_{jk} - \Omega_{ik} \Omega_{jl} - 2\Omega_{ij} \Omega_{kl}),$

where $\tilde{R}_{i_0j_0} = \langle \tilde{R}(\tilde{X}_i, \xi) \tilde{X}_j, \xi \rangle$, $\tilde{R}_{i_0jk} = \langle \tilde{R}(\tilde{X}_i, \xi) \tilde{X}_j, \tilde{X}_k \rangle$, $\tilde{R}_{ijkl} = \langle \tilde{R}(\tilde{X}_i, \tilde{X}_j) \tilde{X}_k, \tilde{X}_l \rangle$, $R_{ijkl} = \langle R(X_i, X_j) X_k, X_l \rangle$ and $\tilde{\nabla}_i \Omega_{jk} = (\tilde{\nabla}_{\tilde{X}_i} \Omega)(\tilde{X}_j, \tilde{X}_k)$.

LEMMA 3.3. *The curvature tensor \tilde{R} is expressed in the terms of R_{ijkl} and Ω_{ij} as follows:*

- (1) $\tilde{R}(\xi, \tilde{X}_i) \xi = t^2 \Sigma \Omega_{jk} \Omega_{ki} \tilde{X}_j,$
- (2) $\tilde{R}(\xi, \tilde{X}_i) \tilde{X}_j = -t^2 \Sigma (\Omega_{ik} \Omega_{kj} \xi - t \tilde{\nabla}_i \Omega_{jk} \tilde{X}_k),$
- (3) $\tilde{R}(\tilde{X}_i, \tilde{X}_j) \xi = t \Sigma \tilde{\nabla}_k \Omega_{ij} \tilde{X}_k,$
- (4) $\tilde{R}(\tilde{X}_i, \tilde{X}_j) \tilde{X}_k = t \tilde{\nabla}_k \Omega_{ij} \xi + \Sigma [R_{ijkl} - t^2 (\Omega_{il} \Omega_{jk} - \Omega_{ik} \Omega_{jl} - 2\Omega_{ij} \Omega_{kl})] X_l.$

We shall calculate the covariant derivative $\tilde{\nabla} \tilde{R}$ of the curvature tensor \tilde{R} by using Lemmas 3.1, 3.2 and 3.3.

LEMMA 3.4.

- (1) $(\tilde{\nabla}_\xi \tilde{R})(\xi, \tilde{X}_i) \xi = 0,$
- (2) $(\tilde{\nabla}_{\tilde{X}_i} \tilde{R})(\xi, \tilde{X}_j) \xi = t^2 \Sigma [\Omega_{kl} \Omega_{lj} (S_{ikl} + S_{iak})$
 $+ S_{ilk} (\Omega_{kj} \Omega_{al} + \Omega_{ak} \Omega_{lj}) + \Omega_{lj} \tilde{\nabla}_i \Omega_{al} + \Omega_{al} \tilde{\nabla}_i \Omega_{lj}] \tilde{X}_a,$
- (3) $(\tilde{\nabla}_\xi \tilde{R})(\xi, \tilde{X}_i) \tilde{X}_j = -t \Sigma [\xi (\nabla_i \Omega_{jk}) - t \Omega_{lk} \tilde{\nabla}_i \Omega_{jl} + \Omega_{il} \tilde{\nabla}_l \Omega_{jk} + \Omega_{jl} \tilde{\nabla}_i \Omega_{lk}] \tilde{X}_k,$
- (4) $(\tilde{\nabla}_{\tilde{X}_k} \tilde{R})(\xi, \tilde{X}_i) \tilde{X}_j = -\Sigma [t^2 \{(\tilde{\nabla}_k \Omega_{jl}) \Omega_{li} + \Omega_{jl} (\tilde{\nabla}_k \Omega_{li})\} \xi$
 $- t \Omega_{kl} R(\tilde{X}_l, \tilde{X}_i) \tilde{X}_j - S_{kil} \tilde{R}(\xi, \tilde{X}_l) \tilde{X}_j - S_{kjl} \tilde{R}(\xi, \tilde{X}_l) \tilde{X}_i],$
- (5) $(\tilde{\nabla}_{\tilde{X}_k} \tilde{R})(\tilde{X}_i, \tilde{X}_j) \xi = \Sigma [t \tilde{X}_k (\tilde{\nabla}_l \Omega_{ij}) \tilde{X}_l + t S_{kla} \tilde{\nabla}_l \Omega_{ij} \tilde{X}_a - t \Omega_{kl} \tilde{R}(\tilde{X}_i, \tilde{X}_j) \tilde{X}_l$
 $- S_{kil} \tilde{R}(\tilde{X}_l, \tilde{X}_j) \xi - t S_{kjl} \tilde{\nabla}_a \Omega_{il} \tilde{X}_a + t^3 \Omega_{al} (\Omega_{ki} \Omega_{lj} - \Omega_{kj} \Omega_{li}) \tilde{X}_a + t \tilde{\nabla}_k \Omega_{ij} \xi],$
- (6) $(\tilde{\nabla}_{\tilde{X}_h} \tilde{R})(\tilde{X}_i, \tilde{X}_j) \tilde{X}_k = \Sigma [\{(\nabla_{X_h} R)(X_i, X_j) X_k, X_l\} - t^2 (\Omega_{jk} \tilde{\nabla}_h \Omega_{il}$
 $+ \Omega_{il} \tilde{\nabla}_h \Omega_{jk} - \Omega_{jl} \tilde{\nabla}_h \Omega_{ik} - \Omega_{ik} \tilde{\nabla}_h \Omega_{jl} - 2\Omega_{ki} \tilde{\nabla}_h \Omega_{ij} - 2\Omega_{ij} \tilde{\nabla}_h \Omega_{kl})\} X_l$
 $- t \Omega_{hl} \tilde{R}_{ijkl} \xi + S_{hla} \tilde{R}_{ijkl} \tilde{X}_a - S_{hil} \tilde{R}(\tilde{X}_l, \tilde{X}_j) \tilde{X}_k - S_{hjl} \tilde{R}(X_i, \tilde{X}_l) \tilde{X}_k$
 $- S_{ikh} \tilde{R}(\tilde{X}_l, \tilde{X}_j) \tilde{X}_l + t^2 (-t \Omega_{kl} \Omega_{lj} \xi + \tilde{\nabla}_i \Omega_{hl} \tilde{X}_l) \Omega_{hi} + t^2 \Omega_{hk} (\tilde{\nabla}_i \Omega_{ij}) \tilde{X}_l$
 $+ t^2 (t \Omega_{kl} \Omega_{li} \xi + \tilde{\nabla}_i \Omega_{kl} \tilde{X}_l) \Omega_{hj}].$

Proof. Using the standard formula

$$\begin{aligned} (\tilde{\nabla}_{\tilde{X}}\tilde{R})(\tilde{Y}, \tilde{Z})\tilde{W} &= \tilde{\nabla}_{\tilde{X}}(\tilde{R}(\tilde{Y}, \tilde{Z})\tilde{W}) - \tilde{R}(\tilde{\nabla}_{\tilde{X}}\tilde{Y}, \tilde{Z})\tilde{W} \\ &\quad - \tilde{R}(\tilde{Y}, \tilde{\nabla}_{\tilde{X}}\tilde{Z})\tilde{W} - \tilde{R}(\tilde{Y}, \tilde{Z})(\tilde{\nabla}_{\tilde{X}}\tilde{W}), \end{aligned}$$

for any vector fields \tilde{X} , \tilde{Y} and \tilde{Z} , we shall prove this lemma. By using the above formula for $X=\xi$, $Y=\xi$, $Z=X_i$ and $W=\xi$, we have, from (1) and (2) of Lemma 3.1 and (1) of Lemma 3.2,

$$\begin{aligned} (\tilde{\nabla}_{\xi}\tilde{R})(\xi, \tilde{X}_i)\xi &= \tilde{\nabla}_{\xi}(\tilde{R}(\xi, \tilde{X}_i)\xi) - \tilde{R}(\tilde{\nabla}_{\xi}\xi, \tilde{X}_i)\xi - \tilde{R}(\xi, \tilde{\nabla}_{\xi}\tilde{X}_i)\xi - \tilde{R}(\xi, \tilde{X}_i)(\tilde{\nabla}_{\xi}\xi) \\ &= \Sigma[t^2\tilde{\nabla}_{\xi}(\Omega_{jl}\Omega_{il}\tilde{X}_j) - t\Omega_{il}\tilde{R}(\xi, \tilde{X}_i)\xi] \\ &= \Sigma[t^2(\Omega_{jl}\Omega_{il})\tilde{\nabla}_{\xi}\tilde{X}_j - t^2\Omega_{il}\Omega_{jk}\Omega_{kl}\tilde{X}_j] = 0. \end{aligned}$$

Thus we obtain the formula (1). Similarly, we can obtain the formulas (2), (3), (4), (5) and (6) by Lemmas 3.1 and 3.3.

4. The tensor field T of type (1, 2) on P .

We shall give a tensor field T of type (1, 2), which plays an important role in our assertion, and study its properties. Let us define T by

$$(4.1) \quad T(\tilde{X}, \tilde{Y}) = t[\Omega(\tilde{X}, \tilde{Y})\xi + t(\eta(\tilde{X})\phi\tilde{Y} - \eta(\tilde{Y})\phi\tilde{X})],$$

for any vector fields \tilde{X} , \tilde{Y} on P , where ϕ is defined by $\tilde{g}(\phi\tilde{X}, \tilde{Y}) = \Omega(\tilde{X}, \tilde{Y})$, then T is a tensor field of type (1, 2) on P such that $T(\tilde{X}, \tilde{Y}) = -T(\tilde{Y}, \tilde{X})$. With respect to the orthonormal frame field taken in section 3, we have

$$(4.2) \quad T(\xi, \tilde{X}_i) = t\Sigma\Omega_{il}\tilde{X}_l,$$

and

$$(4.3) \quad T(\tilde{X}_i, \tilde{X}_j) = t\Omega_{ij}\xi.$$

Hence we obtain

LEMMA 4.1.

$$(1) \quad (\tilde{\nabla}_{\xi}T)(\tilde{X}_i, \tilde{X}_j) = (\tilde{\nabla}_{\xi}T)(\xi, \tilde{X}_i) = 0,$$

$$(2) \quad (\tilde{\nabla}_{\tilde{X}_i}T)(\xi, \tilde{X}_j) = t\Sigma(\tilde{\nabla}_i\Omega_{jk})\tilde{X}_k,$$

$$(3) \quad (\tilde{\nabla}_{\tilde{X}_i}T)(\tilde{X}_j, \tilde{X}_k) = t(\tilde{\nabla}_i\Omega_{jk}) + \Sigma t^2(\Omega_{jk}\Omega_{il} + \Omega_{ij}\Omega_{kl} - \Omega_{ik}\Omega_{jl})\tilde{X}_l.$$

Proof. Using the standard formula

$$(4.4) \quad (\tilde{\nabla}_{\tilde{X}}T)(\tilde{Y}, \tilde{Z}) = \tilde{\nabla}_{\tilde{X}}(T(\tilde{Y}, \tilde{Z})) - T(\tilde{\nabla}_{\tilde{X}}\tilde{Y}, \tilde{Z}) - T(\tilde{Y}, \tilde{\nabla}_{\tilde{X}}\tilde{Z}),$$

for any vector fields \tilde{X} , \tilde{Y} and \tilde{Z} , we shall prove this lemma. Using the above

formula for $\tilde{X}=\tilde{X}_i$, $\tilde{Y}=\tilde{X}$, and $\tilde{Z}=\tilde{X}_k$, we verify the third assertion as follows: By (2) and (3) of Lemma 3.1 and the definition (4.1) of T , we have

$$\begin{aligned} (\tilde{\nabla}_{\tilde{X}_i} T)(\tilde{X}_i, \tilde{X}_k) &= \tilde{\nabla}_{\tilde{X}_i}(T(\tilde{X}_j, \tilde{X}_k)) - T(\tilde{\nabla}_{\tilde{X}_i}\tilde{X}_j, \tilde{X}_k) - T(\tilde{X}_j, \tilde{\nabla}_{\tilde{X}_i}\tilde{X}_k) \\ &= \tilde{\nabla}_{\tilde{X}_i}[t\Omega(\tilde{X}_j, \tilde{X}_k)\xi + t^2(\gamma(\tilde{X}_j)\phi\tilde{X}_k - \gamma(\tilde{X}_k)\phi\tilde{X}_j)] \\ &\quad - [t\Omega(\tilde{\nabla}_{\tilde{X}_i}\tilde{X}_j, \tilde{X}_k)\xi + t^2(\gamma(\tilde{\nabla}_{\tilde{X}_i}\tilde{X}_j)\phi\tilde{X}_k - \gamma(\tilde{X}_k)\phi\tilde{X}_j)] \\ &\quad - [t\Omega(\tilde{X}_j, \tilde{\nabla}_{\tilde{X}_i}\tilde{X}_k)\xi + t^2(\gamma(\tilde{X}_j)\phi(\tilde{\nabla}_{\tilde{X}_i}\tilde{X}_k) - \gamma(\tilde{\nabla}_{\tilde{X}_i}\tilde{X}_j)\phi\tilde{X}_k)] \\ &= t(\tilde{\nabla}_i\Omega_{jk})\xi + t^2\Sigma(\Omega_{jk}\Omega_{il} + \Omega_{ij}\Omega_{kl} - \Omega_{ik}\Omega_{jl})\tilde{X}_l. \end{aligned}$$

The assertions (1) and (2) follow similarly from (4.1), (4.2), (4.3) and Lemma 3.1. Here if we put

$$(4.5) \quad (T_{\tilde{X}} \cdot T)(\tilde{Y}, \tilde{Z}) = T(\tilde{X}, T(\tilde{Y}, \tilde{Z})) - T(T(\tilde{X}, \tilde{Y}), \tilde{Z}) - T(\tilde{Y}, T(\tilde{X}, \tilde{Z})),$$

for any vector fields \tilde{X} , \tilde{Y} and \tilde{Z} , the $T_{\tilde{X}} \cdot T$ is a tensor field of type (1, 2) on P and satisfies the following

LEMMA 4.2.

- (1) $(T_{\tilde{X}_i} \cdot T)(\tilde{X}_i, \tilde{X}_j) = -t^2\Sigma(\Omega_{jk}\Omega_{il} + \Omega_{ij}\Omega_{kl} - \Omega_{ik}\Omega_{jl})\tilde{X}_l$,
- (2) $(T_{\tilde{X}_i} \cdot T)(\xi, \tilde{X}_j) = (T_{\xi} \cdot T)(\tilde{X}_i, \tilde{X}_j) = 0$.

Proof. By (4.1), (4.2), (4.3) and Lemma 3.1, we have

$$\begin{aligned} T(\tilde{X}_i, T(\tilde{X}_j, \tilde{X}_k)) &- T(T(\tilde{X}_i, \tilde{X}_j), \tilde{X}_k) - T(\tilde{X}_j, T(\tilde{X}_i, \tilde{X}_k)) \\ &= t[\Omega_{jk}T(\tilde{X}_i, \xi) - \Omega_{ij}T(\xi, \tilde{X}_k) - \Omega_{ik}T(\tilde{X}_j, \xi)] \\ &= -t^2\Sigma(\Omega_{jk}\Omega_{il} + \Omega_{ij}\Omega_{kl} - \Omega_{ik}\Omega_{jl})\tilde{X}_l. \end{aligned}$$

Similarly we can verify the assertion (2).

Now for later use, we define a tensor field $T_{\tilde{X}} \cdot \tilde{R}$ of type (1, 3) on P by

$$(4.6) \quad \begin{aligned} (T_{\tilde{W}} \cdot \tilde{R})(\tilde{X}, \tilde{Y})\tilde{Z} &= T(\tilde{W}, \tilde{R}(\tilde{X}, \tilde{Y})\tilde{Z}) - \tilde{R}(T(\tilde{W}, \tilde{X}), \tilde{Y})\tilde{Z} \\ &\quad - \tilde{R}(\tilde{X}, T(\tilde{W}, \tilde{Y}))\tilde{Z} - \tilde{R}(\tilde{X}, \tilde{Y})(T(\tilde{W}, \tilde{Z})), \end{aligned}$$

for any vector fields \tilde{X} , \tilde{Y} , \tilde{Z} and \tilde{W} . Then we have the following

LEMMA 4.3.

- (1) $(T_{\xi} \cdot \tilde{R})(\xi, \tilde{X}_i) = 0$,
- (2) $(T_{\tilde{X}_i} \cdot \tilde{R})(\xi, \tilde{X}_j)\xi = -t^2\Sigma\Omega_{ik}(\tilde{\nabla}_j\Omega_{kl})\tilde{X}_l$,
- (3) $(T_{\xi} \cdot \tilde{R})(\xi, \tilde{X}_i)\tilde{X}_j = t^2\Sigma[-\Omega_{kl}(\tilde{\nabla}_i\Omega_{jk}) + \Omega_{ik}(\tilde{\nabla}_k\Omega_{jl}) + \Omega_{jk}(\tilde{\nabla}_i\Omega_{kl})]\tilde{X}_l$,

$$\begin{aligned}
(4) \quad (T_{\tilde{X}_k} \cdot \tilde{R})(\xi, \tilde{X}_i) \tilde{X}_j &= \Sigma [t^3 \Omega_{jl} \Omega_{li} \Omega_{ka} \tilde{X}_a - t^2 \Omega_{kl} (\tilde{\nabla}_i \Omega_{jl}) \xi \\
&\quad + t \Omega_{kl} \tilde{R}(\tilde{X}_l, \tilde{X}_i) \tilde{X}_j - t^3 \Omega_{kj} \Omega_{al} \Omega_{li} \tilde{X}_a], \\
(5) \quad (T_{\tilde{X}_k} \cdot \tilde{R})(\tilde{X}_i, \tilde{X}_j) \xi &= \Sigma [t \Omega_{kl} (\tilde{\nabla}_l \Omega_{ij}) \xi - t^3 (\Omega_{ki} \Omega_{al} \Omega_{lj}) \tilde{X}_a \\
&\quad + t^2 \Omega_{kj} \Omega_{al} \Omega_{li} \tilde{X}_a + t \Omega_{kl} \tilde{R}(\tilde{X}_i, \tilde{X}_j) \tilde{X}_l], \\
(6) \quad (T_{\tilde{X}_k} \cdot \tilde{R})(\tilde{X}_i, \tilde{X}_j) \tilde{X}_k &= \Sigma [-t \Omega_{hl} \tilde{\nabla}_k \Omega_{ij} \tilde{X}_l + t \Omega_{kl} \tilde{R}_{ij} \xi + t^3 \Omega_{hi} \Omega_{kl} \Omega_{lj} \xi \\
&\quad + t^2 \Omega_{hi} (\tilde{\nabla}_j \Omega_{kl}) \tilde{X}_l - t^3 \Omega_{hj} \Omega_{kl} \Omega_{li} \xi - t^2 \Omega_{hk} (\tilde{\nabla}_l \Omega_{ij}) \tilde{X}_l].
\end{aligned}$$

Proof. By Lemmas 3.1 and 3.2, (2.4), (4.1), (4.2), (4.3) and (4.6) imply that

$$\begin{aligned}
(T_{\xi} \cdot \tilde{R})(\xi, \tilde{X}_i) \xi &= T(\xi, \tilde{R}(\xi, \tilde{X}_i) \xi) - \tilde{R}(T(\xi, \xi), \tilde{X}_i) \xi - \tilde{R}(\xi, T(\xi, \tilde{X}_i) \xi) - \tilde{R}(\xi, \tilde{X}_i) T(\xi, \xi) \\
&= \Sigma [t^2 \Omega_{jl} \Omega_{li} T(\xi, \tilde{X}_j) - t \Omega_{il} \tilde{R}(\xi, \tilde{X}_l) \xi] = 0.
\end{aligned}$$

Similarly we can obtain the equations (2), (3), (4), (5) and (6).

5. Main results.

Let M be a locally symmetric Kählerian manifold with a Kählerian metric g and the fundamental 2-form Θ . Let P be a principal circle bundle over M , \tilde{g} a Riemannian metric on P given by (2.2) and η a connection form on P such that $d\eta = \pi^* \Theta$. Let τ be a local cross-section of P defined on a neighborhood U of x such that $\tau(x) = \tilde{x}$ and the differential map of τ maps the tangent space of M at x onto the horizontal space of P at \tilde{x} , and J_{ij} the component of the almost complex structure J with respect to the orthonormal frame field $\{X_1, \dots, X_n\}$ taken in section 3. Noting that $\mathcal{A}\tau_* X_j = X_j$ on U for each j , we obtain

$$\begin{aligned}
(5.1) \quad \Omega(\tilde{X}_j, \tilde{X}_k)_{\tau(y)} &= \Omega(\tau_* X_j, \tau_* X_k)_{\tau(y)} = (\tau^* \Omega)(\tilde{X}_j, \tilde{X}_k) \\
&= -\langle JX_j, X_k \rangle_y = -J_{jk},
\end{aligned}$$

for any y of U . Hence we see that

$$(5.2) \quad \tilde{\nabla}_i \Omega_{jk} = \tilde{\nabla}_i \tilde{\nabla}_j \Omega_{kn} = 0.$$

Now we define a linear connection D on P ,

$$(5.3) \quad D_{\tilde{X}} \tilde{Y} = \tilde{\nabla}_{\tilde{X}} \tilde{Y} + T(\tilde{X}, \tilde{Y}),$$

for any vector fields \tilde{X} , \tilde{Y} and \tilde{Z} . Then by (2.3) and (4.1), we have

$$(5.4) \quad (D_{\tilde{X}} \tilde{g})(\tilde{Y}, \tilde{Z}) = 0.$$

This means that D is a metric connection. Since M is locally symmetric Kählerian manifold, after a long calculation Lemmas 3.4, 4.1, 4.2, 4.3, 5.2 and 5.3 imply that for any vector field \tilde{X} ,

$$D_{\tilde{x}}\tilde{R}=0 \quad \text{and} \quad D_{\tilde{x}}T=0.$$

By a result of W. Ambrose and I.M. Singer (see [1], p. 656), we find that P is locally homogeneous. Thus we have

PROPOSITION 5.1. *Let M be a locally symmetric Kählerian manifold and P a principal circle bundle over M with a Riemannian metric given by (2.2) and a connection form η such that $d\eta=\pi^*\Theta$, where Θ is the fundamental 2-form of M . Then P is locally homogeneous.*

Furthermore we find from the definition of T and (5.5) that

$$(5.6) \quad (\tilde{\nabla}_{\tilde{x}}\tilde{R})(\tilde{Y}, \tilde{X})\tilde{X} = -T(\tilde{X}, \tilde{R}(\tilde{Y}, \tilde{X})\tilde{X}) + \tilde{R}(T(\tilde{X}, \tilde{Y}), \tilde{X})\tilde{X}$$

and

$$(5.7) \quad (\tilde{\nabla}_{\tilde{x}}T)(\tilde{X}, \tilde{Y})=0,$$

for any vector fields \tilde{X} and \tilde{Y} . Thus by a result J. E. D'Atri and H. K. Nickerson (see [6], p. 252), we have

THEOREM 5.2. *Let M be a locally symmetric Kählerian manifold and P a principal circle bundle over M with a Riemannian metric given by (2.2) and a connection form η such that $d\eta=\pi^*\Theta$. Then P is a locally homogeneous and volume symmetric space.*

Now let $\tilde{\text{Ric}}$ and Ric be the Ricci tensor of \tilde{g} and g respectively. Then by Lemma 3.2, we have the following

LEMMA 5.3 (cf. [10]).

- (1) $\tilde{\text{Ric}}(\tilde{X}_i, \tilde{X}_j) = \text{Ric}(X_i, X_j) - 2t^2\delta_{ij}$,
- (2) $\tilde{\text{Ric}}(\tilde{X}_i, \xi) = 0$,
- (3) $\tilde{\text{Ric}}(\xi, \xi) = nt^2$.

By this lemma, S. Kobayashi [10] showed that if M is Einsteinian, $\text{Ric}(X_i, X_j) = (S/n)\delta_{ij}$, then putting $t^2 = S/n(n+2)$, we have an Einsteinian metric on P . Then he proved the following

PROPOSITION 5.4. *If M is a complete Einstein-Kählerian manifold with positive scalar curvature, then we can construct a principal circle bundle P over M and specially an Einsteinian metric with positive scalar curvature.*

Combining Theorem 5.2 and Proposition 5.4, we have the following

THEOREM 5.5. *If M is a complete locally symmetric Einstein-Kählerian manifold with positive scalar curvature. Then we can construct a principal circle bundle P over M , which is locally homogeneous and volume symmetric (especially even Einsteinian).*

Now assume that the Einsteinian metric obtained in Proposition 5.4 satisfies the condition (*). Then we first note that

$$\Sigma \check{R}_{\alpha\beta\gamma} \check{R}_{\alpha\beta\gamma} = 2\Sigma \check{R}_{\alpha i o j} \check{R}_{\alpha i o j} = 2S^2/n(n+2)^2,$$

taking (1) of Lemma 3.2. Hence we have

$$\begin{aligned} \Sigma \check{R}_{\alpha\beta\gamma\delta} \check{R}_{\alpha\beta\gamma\delta} &= \Sigma \check{R}_{\alpha\beta\gamma\delta} \check{R}_{\alpha\beta\gamma\delta} + \Sigma \check{R}_{i\beta\gamma\delta} \check{R}_{i\beta\gamma\delta} \\ &= (n+1)\Sigma \check{R}_{\alpha\beta\gamma\delta} \check{R}_{\alpha\beta\gamma\delta} = 2\check{S}^2/n(n+1). \end{aligned}$$

This concludes that P is of constant curvature. Thus we have

PROPOSITION 5.6. *A Riemannian metric on P obtained in Proposition 5.4 is an Einsteinian manifold satisfying (*) if and only if it is of constant curvature.*

6. An example.

Consider the complex quadric of complex dimension 2, $Q^2(C) = CP^1 \times CP^1$. Then $Q^2(C)$ admits the natural product Einstein-Kählerian metric, which is locally symmetric. Therefore by Theorem 5.5, we can construct a principal circle bundle over $Q^2(C)$, which is homogeneous and volume symmetric (especially Einsteinian).

Now we give an explicit construction of this example. We take G/H as follows:

$$G = \left\{ \left\{ \begin{array}{cc} SU(2) & \mathbf{0} \\ \mathbf{0} & SU(2) \end{array} \right\} \right\}, \quad H = \left\{ \left\{ \begin{array}{cc} e^{-iu} & \mathbf{0} \\ e^{iu} & \mathbf{0} \\ \mathbf{0} & e^{-iv} \\ \mathbf{0} & e^{-iv} \end{array} \right\}, u, v \in \mathbf{R} \right\}.$$

Then G is a compact connected Lie group with the Lie algebra \mathfrak{g} and H a closed subgroup with the Lie algebra \mathfrak{h} . His locally the direct product of two closed normal subgroups H_1 and H_2 :

$$H_1 = \left\{ \left\{ \begin{array}{ccc} e^{-iu} & & \mathbf{0} \\ & e^{iu} & \\ \mathbf{0} & & e^{-iu} \\ & & & e^{iu} \end{array} \right\}, u \in \mathbf{R} \right\}, \quad H_2 = \left\{ \left\{ \begin{array}{ccc} e^{-iv} & & \mathbf{0} \\ & e^{iv} & \\ \mathbf{0} & & e^{iv} \\ & & & e^{-iv} \end{array} \right\}, v \in \mathbf{R} \right\}.$$

This means that $\mathfrak{h} = \mathfrak{h}_1 \oplus \mathfrak{h}_2$ (direct sum of ideals), where \mathfrak{h}_1 and \mathfrak{h}_2 are the Lie algebras of H_1 and H_2 , respectively. Then $P = G/H_2$ is a principal circle bundle over G/H with projection π and structure group H_1 where $\pi : P \rightarrow G/H$ is defined by $\pi(gH_2) = gH$ for $g \in G$ (see [9]). The $ad(G)$ -invariant positive definite sym-

metric bilinear form $B: \mathfrak{g} \times \mathfrak{g} \rightarrow R$ is taken to be $-(1/2)$ the killing form on $\mathfrak{g} = su(2) + su(2)$. An orthonormal basis for \mathfrak{g} with respect to this form is given by

$$e_1 = \begin{bmatrix} 0 & 1 & 0 & 0 \\ -1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}, \quad e_2 = \begin{bmatrix} 0 & i & 0 & 0 \\ i & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}, \quad e_3 = \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & -1 & 0 \end{bmatrix},$$

$$e_4 = \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & i \\ 0 & 0 & i & 0 \end{bmatrix}, \quad e_5 = 1/\sqrt{2} \begin{bmatrix} -i & \mathbf{0} \\ i & \\ \mathbf{0} & -i \\ \mathbf{0} & i \end{bmatrix}, \quad e_6 = 1/\sqrt{2} \begin{bmatrix} -i & \mathbf{0} \\ i & \\ \mathbf{0} & i \\ \mathbf{0} & -i \end{bmatrix}.$$

Now note that $\{e_5, e_6\}$ is a basis for the Lie algebra \mathfrak{h} of H , and e_6 a basis for the Lie algebra \mathfrak{h}_2 . We set \mathfrak{m} = the orthogonal complement of \mathfrak{h}_2 in \mathfrak{g} spanned by $\{e_1, e_2, e_3, e_4, e_5\}$ and \mathfrak{m}' = the orthogonal complement of \mathfrak{h} in \mathfrak{g} spanned by $\{e_1, e_2, e_3, e_4\}$. Let \langle, \rangle be the metric induced by restricting B to \mathfrak{m}' , $\langle, \rangle_{o'} = B|_{\mathfrak{m}'}$ and $J_{o'} = -ad_{\mathfrak{m}'}(e_6)$, where $\langle, \rangle_{o'}$ (resp. $J_{o'}$) is the restriction of \langle, \rangle (resp. J) to the tangent space $T_{o'}(G/H)$ of G/H at $o' = H$, identifying \mathfrak{m}' with $T_{o'}(G/H)$. Then (J, \langle, \rangle) is the natural (product) Kählerian structure on G/H . Furthermore let $\widetilde{\langle, \rangle}$ be the metric induced by restricting B to \mathfrak{m} , $\widetilde{\langle, \rangle}_o = B|_{\mathfrak{m}}$, where $\widetilde{\langle, \rangle}_o$ is the restriction of $\widetilde{\langle, \rangle}$ to tangent space $T_o(G/H_2)$ of G/H_2 at $o = \{H_2\} \in G/H_2$, identifying \mathfrak{m} with $T_o(G/H_2)$. Setting $\eta_o(X) = \langle X, e_6 \rangle_o$ for $X \in \mathfrak{m}$, one can see that η is a connection form on G/H_2 and $d\eta = \pi^* \Theta$ where Θ is the fundamental 2-form of the Kählerian structure (J, \langle, \rangle) .

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