### A CLASS FUNCTION ON THE TORELLI GROUP

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#### Abstract

The Magnus representation of the Torelli group has been defined in virtue of Fox derivation. The Torelli group is a significant subgroup of the mapping class group of a surface. In this paper, we show some properties of the characteristic polynomials of matrices obtained from the Magnus representation of the Torelli group, which is a class function on the Torelli group.

#### 1. Introduction

Let  $\Sigma_{g,1}$  be an oriented surface obtained from a closed surface  $\Sigma_g$  of genus g by removing an open disk. We denote by  $\mathcal{M}_{g,1}$  the mapping class group of  $\Sigma_{g,1}$  relative to the boundary, that is the group of path components of the group of orientation preserving diffeomorphisms of  $\Sigma_{g,1}$  which restrict to the identity on the boundary. Let  $\mathcal{I}_{g,1}$  be the Torelli group of  $\Sigma_{g,1}$ , namely the normal subgroup of  $\mathcal{M}_{g,1}$  consisting of all the elements which act on the first homology group of  $\Sigma_{g,1}$  trivially.

We call the following mapping  $r_1$  the Magnus representation of the Torelli group:

$$r_1: \mathcal{I}_{g,1} \to \mathrm{GL}(2g; \mathbf{Z}[H])$$

where  $H = H_1(\Sigma_{g,1}; \mathbf{Z})$ . We will consider the characteristic polynomials of matrices obtained from the Magnus representation of the Torelli group. That is, we will investigate

$$R(\varphi) = \det(\lambda I_{2g} - r_1(\varphi))$$

for  $\varphi \in \mathscr{I}_{g,1}$ , where  $I_{2g}$  is the unit matrix and  $\lambda$  is an indeterminate. Then R is a class function on  $\mathscr{I}_{g,1}$ .

We will prove some properties of this class function R. For example, we will show that the restriction of R to  $\mathcal{K}_{g,1}$  is non-trivial, where  $\mathcal{K}_{g,1}$  is the normal subgroup of  $\mathcal{I}_{g,1}$  generated by all the Dehn twists along bounding simple closed curves.

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## 2. Definition of the Magnus representation of the Torelli group

In this section, we recall the definition of the Magnus representation of the Torelli group.

Let  $F_n$  be a free group of rank n with free basis  $z_1, \ldots, z_n$ . The following simple derivation on the integral group ring  $\mathbf{Z}[F_n]$  is the main ingredient of Fox derivation.

DEFINITION 2.1 (Fox derivation). The Fox derivation is defined by the following equations:

$$\frac{\partial}{\partial z_{j}}(z_{\mu_{1}}^{\varepsilon_{1}}\cdots z_{\mu_{r}}^{\varepsilon_{r}}) = \sum_{i=1}^{r} \varepsilon_{i}\delta_{\mu_{i},j}z_{\mu_{1}}^{\varepsilon_{1}}\cdots z_{\mu_{i-1}}^{\varepsilon_{i-1}}z_{\mu_{i}}^{(1/2)(\varepsilon_{i}-1)}, \quad \varepsilon_{i} = \pm 1$$

$$\frac{\partial}{\partial z_{j}}\left(\sum a_{w}w\right) = \sum a_{w}\frac{\partial w}{\partial z_{j}}, \quad w \in F_{n}, \ a_{w} \in \mathbf{Z}.$$

We fix a system of generators  $\alpha_1, \ldots, \alpha_g, \beta_1, \ldots, \beta_g$  of the free group  $\Gamma_0 = \pi_1(\Sigma_{g,1})$  as shown in Figure 1. Let us simply write  $\gamma_1, \ldots, \gamma_{2g}$  for them. Moreover, we obtain a system of symplectic basis  $x_i, y_i$  of H by abelianizing  $\alpha_i, \beta_i$  respectively.

# DEFINITION 2.2. We call the mapping

$$\begin{split} r: \mathcal{M}_{g,1} &\to \mathrm{GL}(2g; \boldsymbol{Z}[\Gamma_0]) \\ \varphi &\mapsto \left( \overline{\frac{\partial \varphi(\gamma_j)}{\partial \gamma_i}} \right)_{i,j} \end{split}$$

the Magnus representation for the mapping class group. Here  $\partial/\partial \gamma_i$  is Fox derivation and  $\bar{z}: \mathbf{Z}[\Gamma_0] \ni \sum a\gamma \mapsto \sum a\gamma^{-1} \in \mathbf{Z}[\Gamma_0]$ .

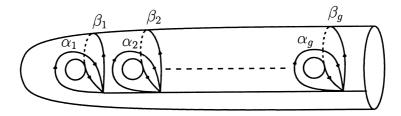


Figure 1. Generators of  $\Gamma_0$ 

This mapping r is a crossed homomorphism. The product formula below follows from the chain rule of Fox derivation.

Proposition 2.3 ([M1]). For any two elements  $\varphi, \psi \in \mathcal{M}_{g,1}$ , we have  $r(\varphi\psi) = r(\varphi) \cdot {}^{\varphi}r(\psi)$ 

where  ${}^{\varphi}r(\psi)$  denotes the matrix obtained from  $r(\psi)$  by applying the automorphism  $\varphi: \mathbf{Z}[\Gamma_0] \to \mathbf{Z}[\Gamma_0]$  on each entry.

We denote by  $r^{\alpha}$  the composition of the mapping r by abelianizing  $\alpha : \mathbf{Z}[\Gamma_0] \to \mathbf{Z}[H]$  the coefficients. If we consider elements of the Torelli group, we write  $r_1$  for  $r^{\alpha}$ . That is to say, we get a genuine representation  $r_1$  by restricting this mapping  $r^{\alpha}$  to the Torelli group:

$$r_1: \mathscr{I}_{g,1} \to \mathrm{GL}(2g; \mathbf{Z}[H]).$$

# 3. Characteristic polynomials

In this section, we investigate characteristic polynomials of the Magnus matrices. Here the Magnus matrix means the image of  $r_1$  for a mapping class. We define

$$R(\varphi) = \det(\lambda I_{2g} - r_1(\varphi))$$

for  $\varphi \in \mathscr{I}_{g,1}$ . In particular, for any elements  $\varphi_1, \varphi_2 \in \mathscr{I}_{g,1}$  we have

$$R(\varphi_2\varphi_1\varphi_2^{-1}) = R(\varphi_1)$$

so that R is constant in the conjugacy classes of  $\mathcal{I}_{g,1}$ , that is, R is a class function on  $\mathcal{I}_{g,1}$ .

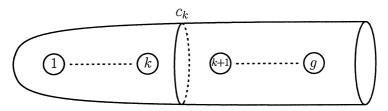


FIGURE 2. Bounding simple closed curve  $c_k$ 

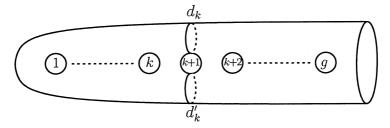


FIGURE 3. Bounding pair  $d_k, d'_k$ 

The curve  $c_k$  shown in Figure 2 is a bounding simple closed curve, where bounding means 0-homologous. Let  $\varphi_k$  denote the BSCC map which is the Dehn twist along a bounding simple closed curve  $c_k$ . We denote by  $\psi_k$  the product of the right Dehn twist along a simple closed curve  $d_k$  and the left Dehn twist along a simple closed curve  $d'_k$  which is disjoint and homologous to  $d_k$  as shown in Figure 3. We call  $\psi_k$  to be the BP map. It is known that the Torelli group  $\mathscr{I}_{g,1}$  is normally generated in  $\mathscr{M}_{g,1}$  by  $\psi_1$  (see [J] for details).

First, we compute the Magnus matrices of BSCC map  $\varphi_k$  and BP map  $\psi_k$ directly. Since

$$\varphi_k(\alpha_j) = \begin{cases} [\beta_k, \alpha_k] \cdots [\beta_1, \alpha_1] \alpha_j [\alpha_1, \beta_1] \cdots [\alpha_k, \beta_k] & 1 \leq j \leq k \\ \alpha_j & k < j \end{cases}$$

and

$$\varphi_k(\beta_j) = \begin{cases} [\beta_k, \alpha_k] \cdots [\beta_1, \alpha_1] \beta_j [\alpha_1, \beta_1] \cdots [\alpha_k, \beta_k] & 1 \leq j \leq k \\ \beta_j & k < j \end{cases},$$
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$$\frac{\partial(\varphi_k(\alpha_j))}{\partial \alpha_i} = \begin{cases} [\beta_k, \alpha_k] \cdots [\beta_{i+1}, \alpha_{i+1}]\beta_i \\ - [\beta_k, \alpha_k] \cdots [\beta_1, \alpha_i] \\ + \delta_{i,j} [\beta_k, \alpha_k] \cdots [\beta_1, \alpha_1] \\ + [\beta_k, \alpha_k] \cdots [\beta_1, \alpha_1] \alpha_j [\alpha_1, \beta_1] \cdots [\alpha_{i-1}, \beta_{i-1}] \\ - [\beta_k, \alpha_k] \cdots [\beta_1, \alpha_1] \alpha_j [\alpha_1, \beta_1] \cdots [\alpha_{i-1}, \beta_{i-1}] \alpha_i \beta_i \overline{\alpha}_i \\ 1 \leq j \leq k, i \leq k \\ 0 \qquad 1 \leq j \leq k, k < i \leq g \\ \delta_{i,j} \qquad k < j \end{cases}$$

$$\frac{\partial(\varphi_k(\beta_j))}{\partial \alpha_i} = \begin{cases} [\beta_k, \alpha_k] \cdots [\beta_{i+1}, \alpha_{i+1}]\beta_i \\ - [\beta_k, \alpha_k] \cdots [\beta_1, \alpha_1]\beta_j [\alpha_1, \beta_1] \cdots [\alpha_{i-1}, \beta_{i-1}] \\ - [\beta_k, \alpha_k] \cdots [\beta_1, \alpha_1]\beta_j [\alpha_1, \beta_1] \cdots [\alpha_{i-1}, \beta_{i-1}] \alpha_i \beta_i \overline{\alpha}_i \\ 1 \leq j \leq k, i \leq k \end{cases}$$

$$0 \qquad 1 \leq j \leq k, k < i \leq g \\ 0 \qquad k < j \end{cases}$$

$$\frac{\partial(\varphi_k(\alpha_j))}{\partial \beta_i} = \begin{cases} [\beta_k, \alpha_k] \cdots [\beta_{i+1}, \alpha_{i+1}] \\ - [\beta_k, \alpha_k] \cdots [\beta_{i+1}, \alpha_{i+1}] \\ - [\beta_k, \alpha_k] \cdots [\beta_1, \alpha_1]\alpha_j [\alpha_1, \beta_1] \cdots [\alpha_{i-1}, \beta_{i-1}]\alpha_i \\ - [\beta_k, \alpha_k] \cdots [\beta_1, \alpha_1]\alpha_j [\alpha_1, \beta_1] \cdots [\alpha_i, \beta_i] \\ 1 \leq j \leq k, i \leq k \end{cases}$$

$$0 \qquad 1 \leq j \leq k, k < i \leq g \\ 0 \qquad k < j \end{cases}$$

$$\frac{\partial(\varphi_k(\beta_j))}{\partial \beta_i} = \begin{cases} [\beta_k, \alpha_k] \cdots [\beta_{i+1}, \alpha_{i+1}] \\ -[\beta_k, \alpha_k] \cdots [\beta_{i+1}, \alpha_{i+1}] \beta_i \alpha_i \overline{\beta}_i \\ + \delta_{i,j} [\beta_k, \alpha_k] \cdots [\beta_1, \alpha_1] \\ + [\beta_k, \alpha_k] \cdots [\beta_1, \alpha_1] \beta_j [\alpha_1, \beta_1] \cdots [\alpha_{i-1}, \beta_{i-1}] \alpha_i \\ -[\beta_k, \alpha_k] \cdots [\beta_1, \alpha_1] \beta_j [\alpha_1, \beta_1] \cdots [\alpha_i, \beta_i] \end{cases}$$

$$1 \le j \le k, \ i \le k$$

$$0 \qquad 1 \le j \le k, \ k < i \le g$$

$$\delta_{i,j} \qquad k < j$$

Then the Magnus matrix of genus k BSCC map  $\varphi_k$  is

$$r_1(\varphi_k) = I_{2q} + a_k b_k$$

where

$$a_k = {}^t(\overline{y}_1 - 1 \cdots \overline{y}_k - 1 \underbrace{0 \cdots 0}_{g-k \text{ times}} 1 - \overline{x}_1 \cdots 1 - \overline{x}_k \underbrace{0 \cdots 0}_{g-k \text{ times}})$$

$$b_k = (1 - \overline{x}_1 \cdots 1 - \overline{x}_k \underbrace{0 \cdots 0}_{g-k \text{ times}} 1 - \overline{y}_1 \cdots 1 - \overline{y}_k \underbrace{0 \cdots 0}_{g-k \text{ times}}).$$

Similarly, since

$$\begin{split} \psi_k(\alpha_j) \\ &= \begin{cases} [\alpha_1, \beta_1] \cdots [\alpha_k, \beta_k] \alpha_{k+1} \beta_{k+1} \overline{\alpha}_{k+1} \alpha_j \alpha_{k+1} \overline{\beta}_{k+1} \overline{\alpha}_{k+1} [\beta_k, \alpha_k] \cdots [\beta_1, \alpha_1] & 1 \leq j \leq k \\ [\alpha_1, \beta_1] \cdots [\alpha_k, \beta_k] \alpha_{k+1} & j = k+1 \\ \alpha_j & k+1 < j \end{cases} \end{split}$$

and

$$\psi_{k}(\beta_{j}) = \begin{cases}
[\alpha_{1}, \beta_{1}] \cdots [\alpha_{k}, \beta_{k}] \alpha_{k+1} \beta_{k+1} \overline{\alpha}_{k+1} \overline{\beta}_{j} \alpha_{k+1} \overline{\beta}_{k+1} \overline{\alpha}_{k+1} [\beta_{k}, \alpha_{k}] \cdots [\beta_{1}, \alpha_{1}] & 1 \leq j \leq k \\
\beta_{j} & k < j
\end{cases},$$

the Magnus matrix of genus k BP map  $\psi_k$  is

$$r_1(\psi_k) = \begin{pmatrix} B_1 & B_2 \\ B_3 & B_4 \end{pmatrix}$$

where

$$B_{1} = \begin{pmatrix} \overline{y}_{k+1} + X_{1}Y_{1} & \cdots & X_{k}Y_{1} & Y_{1} & 0 & \cdots & 0 \\ \vdots & \ddots & \vdots & \vdots & \vdots & \ddots & \vdots \\ X_{1}Y_{k} & \cdots & \overline{y}_{k+1} + X_{k}Y_{k} & Y_{k} & 0 & \cdots & 0 \\ 0 & \cdots & 0 & 0 & 1 & \cdots & 0 \\ \vdots & & \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & \cdots & 0 & 0 & 0 & \cdots & 1 \end{pmatrix}$$

$$B_{2} = \begin{pmatrix} Y_{1}Y_{1} & \cdots & Y_{k}Y_{k+1} & 1 & 0 & \cdots & 0 \\ \vdots & \ddots & \vdots & \vdots & \ddots & \vdots \\ Y_{1}Y_{k} & \cdots & Y_{k}Y_{1} & 0 & \cdots & 0 \\ \vdots & \ddots & \vdots & \vdots & \ddots & \vdots \\ Y_{1}Y_{k} & \cdots & Y_{k}Y_{k+1} & 0 & \cdots & 0 \\ 0 & \cdots & 0 & 0 & \cdots & 0 \end{pmatrix}$$

$$\vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & \cdots & 0 & 0 & \cdots & 0 \end{pmatrix}$$

$$A_{3} = \begin{pmatrix} -X_{1}X_{1} & \cdots & -X_{k}X_{1} & -X_{1} & 0 & \cdots & 0 \\ \vdots & \ddots & \vdots & \vdots & \vdots & \ddots & \vdots \\ -X_{1}X_{k} & \cdots & -X_{k}X_{k} & -X_{k} & 0 & \cdots & 0 \\ \vdots & \ddots & \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & \cdots & 0 & 0 & 0 & \cdots & 0 \end{pmatrix}$$

$$\vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & \cdots & 0 & 0 & 0 & \cdots & 0 \end{pmatrix}$$

$$\vdots & \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ -X_{k}Y_{1} & \cdots & \overline{y}_{k+1} - X_{k}Y_{k} & 0 & 0 & \cdots & 0 \\ \vdots & \ddots & \vdots & \vdots & \vdots & \ddots & \vdots \\ -X_{k}Y_{1} & \cdots & \overline{y}_{k+1} - X_{k}Y_{k} & 0 & 0 & \cdots & 0 \\ \vdots & \ddots & \vdots & \vdots & \vdots & \ddots & \vdots \\ -X_{k}Y_{1} & \cdots & \overline{y}_{k+1} - X_{k}Y_{k} & 0 & 0 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & \cdots & 0 & 0 & 1 & \cdots & 0 \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & \cdots & 0 & 0 & 1 & \cdots & 0 \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & \cdots & 0 & 0 & 1 & \cdots & 0 \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ \vdots & \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ \vdots & \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ \vdots & \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ \vdots & \vdots & \vdots & \vdots & \ddots &$$

Here  $X_i = 1 - \bar{x}_i = 1 - x_i^{-1}$ ,  $Y_i = 1 - \bar{y}_i = 1 - y_i^{-1}$ .

Then straightforward calculations show the following results about the characteristic polynomials of them.

Lemma 3.1. Let  $\varphi_k, \psi_k$  be as above. Then we have 1.  $\det(\lambda I_{2g} - r_1(\varphi_k)) = (\lambda - 1)^{2g}$  2.  $\det(\lambda I_{2g} - r_1(\psi_k)) = (\lambda - 1)^{2g-2k} (\lambda - y_{k+1}^{-1})^{2k}$ .

We remark that the characteristic polynomial R is a class function not on  $\mathcal{M}_{g,1}$  but on  $\mathcal{I}_{g,1}$ . More precisely,

Proposition 3.2. For any  $\varphi \in \mathcal{I}_{q,1}$  and  $f \in \mathcal{M}_{q,1}$ ,

$$R(f\varphi f^{-1}) = f(R(\varphi))$$

where we also denote by f the mapping  $\mathbf{Z}[\lambda, x_1^{\pm 1}, \dots, x_g^{\pm 1}, y_1^{\pm 1}, \dots, y_g^{\pm 1}] \to \mathbf{Z}[\lambda, f(x_1)^{\pm 1}, \dots, f(x_g)^{\pm 1}, f(y_1)^{\pm 1}, \dots, f(y_g)^{\pm 1}].$ 

*Proof.* First, we note that  ${}^f r(f^{-1}) = r(f)^{-1}$ , because we have

$$I_{2g} = r(ff^{-1}) = r(f) \cdot {}^{f}r(f^{-1}).$$

Then we get

$$R(f\varphi f^{-1}) = \det(I_{2g} - r_1(f\varphi f^{-1}))$$

$$= \det(I_{2g} - r^{\mathfrak{a}}(f) \cdot {}^{f}r_1(\varphi) \cdot {}^{f\varphi}r^{\mathfrak{a}}(f^{-1}))$$

$$= \det(I_{2g} - r^{\mathfrak{a}}(f) \cdot {}^{f}r_1(\varphi) \cdot r^{\mathfrak{a}}(f)^{-1})$$

$$= \det(I_{2g} - {}^{f}r_1(\varphi))$$

$$= f(\det(I_{2g} - r_1(\varphi)))$$

$$= f(R(\varphi))$$

Any BSCC map  $\varphi$  can be written as  $\varphi = f\varphi_k f^{-1}$ , where  $f \in \mathcal{M}_{g,1}$  and  $\varphi_k$  is the Dehn twist along a simple closed curve  $c_k$  as before. According to Lemma 3.1, we deduce the following corollary.

Corollary 3.3. For any BSCC map  $\varphi$ , we have

$$R(\varphi) = (\lambda - 1)^{2g}.$$

For any BSCC map  $\varphi$ , the characteristic polynomial of  $r_1(\varphi)$  is trivial. However, the characteristic polynomial of a product of two BSCC maps is not always trivial. For example, we can show that

$$R(\varphi_1\nu_1\varphi_1\nu_1^{-1}) = (\lambda - 1)^{2g} + \lambda(\lambda - 1)^{2g-2}(y_1 - 2 + \overline{y}_1)(y_2 - 2 + \overline{y}_2).$$

Here  $v_1$  is the Dehn twist along  $n_1$  as shown in Figure 4. This means that the restriction of R to  $\mathcal{K}_{g,1}$  is non-trivial, where  $\mathcal{K}_{g,1}$  is the normal subgroup of  $\mathcal{I}_{g,1}$  generated by all the BSCC maps.

PROPOSITION 3.4. For any  $\psi \in \mathcal{I}_{g,1}$ , R has a common factor  $(\lambda - 1)^2$ .

*Proof.* From our previous paper [S2], there exsists a non-singular matrix P such that for any element  $\psi \in \mathcal{I}_{q,1}$ 

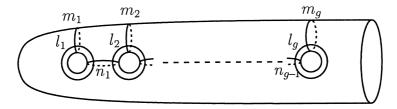


FIGURE 4. Lickorish generators

$$P^{-1}r_1(\psi)P = egin{pmatrix} 1 & * & * & * \ \hline 0 & & & & \ dots & 
ho_B(\psi) & * \ \hline 0 & 0 & \cdots & 0 & 1 \end{pmatrix}.$$

Here  $\rho_B$  is a (2g-2)-dimensional irreducible representation of  $\mathcal{I}_{g,1}$  (see [S2] for details). This means that the assertion holds.

Moreover, from our previous paper [S2], we have

$$\rho_B(\tau_\zeta) = I_{2g-2},$$

where  $\tau_{\zeta}$  be the Dehn twist along a simple closed curve on  $\Sigma_{g,1}$  which is parallel to the boundary. This equality says that R factors through  $\mathscr{I}_{g,*}$ . Here  $\mathscr{I}_{g,*}$  is the Torelli group of  $\Sigma_g$  relative to the base point  $* \in \Sigma_g$ .

# 4. The relation between $R(\psi)$ and $R(\psi^{-1})$

The relation between  $R(\psi)$  and  $R(\psi^{-1})$  is given by the following formula.

Proposition 4.1. For  $\psi \in \mathscr{I}_{g,1}$ , we have

$$R(\psi) = \overline{R(\psi^{-1})},$$

where  $\overline{\cdot}: x_i \mapsto x_i^{-1}, \ y_i \mapsto y_i^{-1}.$ 

To prove Proposition 4.1, we recall that the Magnus representation of the Torelli group is symplectic.

PROPOSITION 4.2 (Morita [M1]). There exists a matrix  $J \in GL(2g; \mathbf{Z}[H])$  such that for any  $\psi \in \mathcal{I}_{g,1}$  we have the equality

$$\overline{{}^t r_1(\psi)} J r_1(\psi) = J.$$

Here J is defined as follows:

$$J = \begin{pmatrix} J_1 & J_2 \\ J_3 & J_4 \end{pmatrix}$$

where

here 
$$J_{1} = \begin{pmatrix} 1 - x_{1} & 1 - x_{2} & 1 - x_{3} \\ (1 - x_{2})(1 - \bar{x}_{1}) & 1 - x_{2} & 1 - x_{3} \\ \vdots & \vdots & \ddots & \vdots \\ (1 - x_{g})(1 - \bar{x}_{1}) & (1 - x_{g})(1 - \bar{x}_{2}) & 1 - x_{3} \\ \vdots & \vdots & \ddots & \vdots \\ (1 - x_{g})(1 - \bar{y}_{1}) & (1 - x_{g})(1 - \bar{y}_{2}) & \cdots & 1 - x_{g} \end{pmatrix}$$

$$J_{2} = \begin{pmatrix} x_{1}\bar{y}_{1} & x_{2}\bar{y}_{2} & & & \\ (1 - x_{2})(1 - \bar{y}_{1}) & (1 - x_{3})(1 - \bar{y}_{2}) & x_{3}\bar{y}_{3} & & \vdots \\ (1 - x_{g})(1 - \bar{y}_{1}) & (1 - x_{g})(1 - \bar{y}_{2}) & \cdots & x_{g}\bar{y}_{g} \end{pmatrix}$$

$$J_{3} = \begin{pmatrix} 1 - \bar{x}_{1} - y_{1} & & & & \\ (1 - y_{2})(1 - \bar{x}_{1}) & 1 - \bar{x}_{2} - y_{2} & & & \\ (1 - y_{3})(1 - \bar{x}_{1}) & (1 - y_{3})(1 - \bar{x}_{2}) & 1 - \bar{x}_{3} - y_{3} & & \\ \vdots & & & \ddots & \\ (1 - y_{g})(1 - \bar{x}_{1}) & (1 - y_{g})(1 - \bar{x}_{2}) & \cdots & 1 - \bar{x}_{g} - y_{g} \end{pmatrix}$$

$$J_{4} = \begin{pmatrix} 1 - \bar{y}_{1} & & & & \\ (1 - y_{2})(1 - \bar{y}_{1}) & (1 - y_{3})(1 - \bar{y}_{2}) & 1 - \bar{y}_{3} & & \\ \vdots & & & \ddots & \\ (1 - y_{g})(1 - \bar{y}_{1}) & (1 - y_{g})(1 - \bar{y}_{2}) & \cdots & 1 - \bar{y}_{g} \end{pmatrix}.$$

Proof of Proposition 4.1. By Proposition 4.2, we get

$$\overline{{}^{t}r_{1}(\psi)} = Jr_{1}(\psi)^{-1}J^{-1} = Jr_{1}(\psi^{-1})J^{-1}.$$

Hence we conclude

$$R(\psi) = \det(\lambda I - r_1(\psi))$$

$$= \det(\lambda I - Jr_1(\psi)J^{-1})$$

$$= \det(\lambda I - \frac{1}{r_1(\psi^{-1})})$$

$$= \overline{\det(\lambda I - r_1(\psi^{-1}))}$$

$$= \overline{R(\psi^{-1})}.$$

Corollary 3.3 states that the determinant of the Magnus matrix for any BSCC map is one. Because the group  $\mathcal{K}_{g,1}$  is generated by BSCC maps, det  $r_1(\varphi) = 1$  for any  $\varphi \in \mathcal{K}_{g,1}$ . Then we deduce the following.

COROLLARY 4.3. Let  $\varphi$  be an element of  $\mathcal{K}_{g,1}$ . Suppose that the characteristic polynomial is written as

$$R(\varphi) = \lambda^{2g} + p_1 \lambda^{2g-1} + p_2 \lambda^{2g-2} + \dots + p_{2g-1} \lambda + 1,$$

where  $p_k \in \mathbf{Z}[H]$ , then  $p_k = \overline{p_{2g-k}}$ . In particular, we have  $p_g = \overline{p_g}$ .

Moreover, in the case of genus 2, for any  $\varphi \in \mathcal{K}_{2,1}$  the variables  $p_k$  can be reduced to just one. That is, we have

$$R(\varphi) = (\lambda - 1)^{2}(\lambda^{2} + p\lambda + 1)$$

by Proposition 3.4. The above equation and Corollary 4.3 yield the following statement.

Corollary 4.4. For any  $\varphi \in \mathcal{K}_{2,1}$  we have

$$R(\varphi) = R(\varphi^{-1}).$$

For higher genera, this statement does not hold. For example, an explicit calculation shows that

$$R(\varphi_1\lambda_2\nu_1\varphi_1\nu_1^{-1}\lambda_2^{-1}\nu_2\lambda_2\nu_1\varphi_1'\nu_1^{-1}\lambda_2^{-1}\nu_2^{-1}) \neq R((\varphi_1\lambda_2\nu_1\varphi_1\nu_1^{-1}\lambda_2^{-1}\nu_2\lambda_2\nu_1\varphi_1'\nu_1^{-1}\lambda_2^{-1}\nu_2^{-1})^{-1}).$$

Here  $\varphi'_1, \lambda_2, \nu_2$  are the Dehn twists along  $c'_1, l_2, \nu_2$  as shown in Figure 5 and Figure 4. However, for a product of two BSCC maps, we arrive at the following.

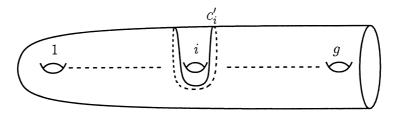


FIGURE 5. bounding simple closed curve  $c'_i$ 

Theorem 4.5. Let  $\varphi_1, \varphi_2$  be BSCC maps. Then we have

$$R(\varphi_1\varphi_2) = R((\varphi_1\varphi_2)^{-1}).$$

We provide the following to prove Theorem 4.5.

Lemma 4.6. Let  $u_1, u_2$  be n-dimensional column vectors and  $v_1, v_2$  n-dimensional row vectors. Then we get

$$\det(tI_n + u_1v_1 + u_2v_2 - u_1v_1u_2v_2)$$

$$= \det(tI_n - u_1v_1 - u_2v_2 - u_1v_1u_2v_2) + 2(\operatorname{tr} u_1v_1 + \operatorname{tr} u_2v_2)t^{n-1}.$$

If we write  $M_1, M_2$  for  $-u_1v_1 - u_2v_2 + u_1v_1u_2v_2$ ,  $u_1v_1 + u_2v_2 + u_1v_1u_2v_2$  respectively, then the above equality can be stated as

$$\det(tI_n - M_1) = \det(tI_n - M_2) + 2(\operatorname{tr} u_1v_1 + \operatorname{tr} u_1v_1)t^{n-1}.$$

Thus we will prove the above equation.

*Proof.* The characteristic polynomial of matrix  $M_l = (m_{i,j}^l)$  is given as

$$\det(tI_n - M_l) = t^n + c_1^l t^{n-1} + c_2^l t^{n-2} + \dots + c_{n-1}^l t + c_n^l \quad (l = 1, 2)$$

where

$$c_{k}^{l} = (-1)^{k} \sum_{1 \leq i_{1} < i_{2} < \dots < i_{k} \leq n} \begin{vmatrix} m_{i_{1}, i_{1}}^{l} & m_{i_{1}, i_{2}}^{l} & \dots & m_{i_{1}, i_{k}}^{l} \\ m_{i_{2}, i_{1}}^{l} & m_{i_{2}, i_{2}}^{l} & \dots & m_{i_{2}, i_{k}}^{l} \\ \vdots & \vdots & \ddots & \vdots \\ m_{i_{k}, i_{1}}^{l} & m_{i_{k}, i_{2}}^{l} & \dots & m_{i_{k}, i_{k}}^{l} \end{vmatrix}.$$

$$(4.1)$$

Since the rank of  $M_l$  is less than 3, then

$$c_3^l = c_4^l = \dots = c_n^l = 0.$$

This means that the difference between the characteristic polynomial of  $M_1$  and that of  $M_2$  appears only in terms of  $t^{n-1}$  and  $t^{n-2}$ . First, the coefficient of  $t^{n-1}$  is the difference between tr  $M_1$  and tr  $M_2$ :

$$(c_1^1 - c_1^2)t^{n-1} = (-\operatorname{tr} M_1 + \operatorname{tr} M_2)t^{n-1} = 2(\operatorname{tr} u_1v_1 + \operatorname{tr} u_2v_2)t^{n-1}.$$

Second, we compute the term of  $t^{n-2}$ . We set

$$u_1 = {}^{t}(c_1 \cdots c_n), \quad u_2 = {}^{t}(d_1 \cdots d_n), \quad v_1 = (e_1 \cdots e_n), \quad v_2 = (f_1 \cdots f_n).$$

The (i, j)-components of  $M_1$  and  $M_2$  are

$$m_{i,j}^1 = -c_i e_j - d_i f_j + A c_i f_j, \quad m_{i,j}^2 = c_i e_j + d_i f_j + A c_i f_j$$

where  $A = \sum_{k=1}^{n} e_k d_k$ . Because of the equation (4.1), we get the following.

$$\begin{split} c_{2}^{1} - c_{2}^{2} &= \sum_{1 \leq i < j \leq n} \left| \begin{matrix} m_{i,i}^{1} & m_{i,j}^{1} \\ m_{j,i}^{1} & m_{j,j}^{1} \end{matrix} \right| - \sum_{1 \leq i < j \leq n} \left| \begin{matrix} m_{i,i}^{2} & m_{i,j}^{2} \\ m_{j,i}^{2} & m_{j,j}^{2} \end{matrix} \right| \\ &= \sum_{1 \leq i < j \leq n} \left( m_{i,i}^{1} m_{j,j}^{1} - m_{i,j}^{1} m_{j,i}^{1} - m_{i,i}^{2} m_{j,j}^{2} + m_{i,j}^{2} m_{j,i}^{2} \right) \\ &= \sum_{1 \leq i < j \leq n} \left\{ \left( -c_{i} e_{i} - d_{i} f_{i} + A c_{i} f_{i} \right) \left( -c_{j} e_{j} - d_{j} f_{j} + A c_{j} f_{j} \right) \right. \\ &- \left. \left( -c_{i} e_{j} - d_{i} f_{j} + A c_{i} f_{j} \right) \left( -c_{j} e_{i} - d_{j} f_{i} + A c_{j} f_{i} \right) \right. \\ &- \left. \left( c_{i} e_{i} + d_{i} f_{i} + A c_{i} f_{i} \right) \left( c_{j} e_{i} + d_{j} f_{j} + A c_{j} f_{i} \right) \right\} \\ &= 0 \end{split}$$

This means that the coefficient of  $t^{n-2}$  is zero and completes the proof.

*Proof of Theorem* 4.5. The Magnus matrix of  $\varphi_i$  which is any BSCC map can be written as

$$r_1(\varphi_i) = I_{2q} + u_i v_i \quad i = 1, 2$$

where  $u_i$  is a *n*-dimensional column vector and  $v_i$  is a *n*-dimensional row vector. Corollary 3.3 states that tr  $u_i v_i = v_i u_i$  equals zero. This deduces  $r_1(\varphi_i^{-1}) = I_{2g} - u_i v_i$ . Therefore we have

$$\begin{split} R(\varphi_2^{-1}\varphi_1^{-1}) &= R(\varphi_1^{-1}\varphi_2^{-1}) \\ &= \det(\lambda I_{2g} - (I_{2g} - u_1v_1)(I_{2g} - u_2v_2)) \\ &= \det((\lambda - 1)I_{2g} + u_1v_1 + u_2v_2 - u_1v_1u_2v_2) \\ &= \det((\lambda - 1)I_{2g} - u_1v_1 - u_2v_2 - u_1v_1u_2v_2) \quad \text{Because of Lemma 4.6} \\ &= \det(\lambda I_{2g} - (I_{2g} + u_1v_1)(I_{2g} + u_2v_2)) \\ &= R(\varphi_1\varphi_2) \end{split}$$

This completes the proof.

In general, we can not decide how many BSCC maps are producted for a given element of  $\mathcal{K}_{g,1}$ . However, Corollary 3.3 and Theorem 4.5 help to determine the number. More precisely, we have the following criterion.

COROLLARY 4.7. First, for an element  $\varphi$  of  $\mathcal{K}_{g,1}$ , if the characteristic polynomial is not trivial, then the element  $\varphi$  can not be written as just one BSCC map. Second, if the characteristic polynomial of  $r_1(\varphi)$  and that of  $r_1(\varphi)^{-1}$  are not the same, then the element  $\varphi$  can neither be written as one BSCC map nor a product of two BSCC maps.

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