

Local existence and analyticity of hyperfunction solutions of partial differential equations of first order in two independent variables

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§ 1. Introduction.

Let P be a differential operator of first order in two independent variables x and y ,

$$P = a(x, y) \frac{\partial}{\partial x} + b(x, y) \frac{\partial}{\partial y} + c(x, y).$$

Here we assume that the coefficients a , b and c are (complex-valued) real analytic functions defined in an open set Ω in \mathbf{R}^2 , and that

$$|a(x, y)| + |b(x, y)| \neq 0.$$

In this paper we shall study conditions for the local existence and analyticity of hyperfunction solutions of the equation $Pu = f$. The basic facts about the theory of hyperfunctions may be found in [2], [4]. We denote by \mathcal{A} , \mathcal{B} , and \mathcal{O} the sheaves of real analytic functions, hyperfunctions, and holomorphic functions, respectively.

Let p be the principal part of P . We define the k -th commutator c_p^k of p by induction:

$$c_p^0 = \bar{p} = \text{the operator with complex conjugate coefficients,}$$

$$c_p^k = [p, c_p^{k-1}] = pc_p^{k-1} - c_p^{k-1}p.$$

Let $k_p(x, y)$ denote the first value of k for which c_p^k is not proportional to p at the point (x, y) . If c_p^k is proportional to p for all values of k , we define $k_p(x, y)$ to be ∞ . Note that P is elliptic at (x, y) , if and only if $k_p(x, y) = 0$. It is easily seen that $k_p(x, y)$ does not depend on the choice of local coordinates, and that it is invariant under multiplication of P by a non-vanishing function.

Our main results are the following two theorems which state the relation between the parity of $k_p(x, y)$ and the analyticity and existence of hyperfunction solutions of $Pu = f$.

THEOREM A. (Analyticity of solutions). *The following two conditions on P are equivalent:*

(a) *For every open subset ω of Ω , if $u \in \mathcal{B}(\omega)$ and $Pu \in \mathcal{A}(\omega)$, then $u \in \mathcal{A}(\omega)$.*

(A) *At every point (x, y) of Ω , $k_p(x, y)$ is even.*

THEOREM B. (Local existence of solutions). *The following two conditions on P are equivalent:*

(b) *For every point (x, y) of Ω , there exists a neighborhood ω of (x, y) such that $P\mathcal{B}(\omega) = \mathcal{B}(\omega)$.*

(B) *At every point (x, y) of Ω , $k_p(x, y)$ is either even or ∞ .*

Recently M. Sato [1], [5] has proved the analyticity of hyperfunction solutions of elliptic differential equations. As to the problem of existence, P. Schapira [6] has given an example of equation without solutions in the space of hyperfunctions. Later Schapira [7], [8] has shown that for differential equations of first order in any number of independent variables, the condition (P') of Nirenberg and Treves [3] is a necessary and sufficient condition for the local existence of hyperfunction solutions. Schapira uses the technique of *a priori* inequalities, whereas our proof is based on the behavior of characteristic curves in the complex domain.

§ 2. Characteristic curves in the complex domain.

We extend the functions a , b , and c to complex values of the independent variables x and y . From now on x and y will denote complex variables.

We shall study the behavior of the characteristic curves in the complex domain. They are solutions of the system of equations

$$(2.1) \quad \frac{dx}{ds} = a(x, y), \quad \frac{dy}{ds} = b(x, y),$$

where s is a complex variable. Let (x_0, y_0) be a point of Ω and let $x = x(s, t)$, $y = y(s, t)$ be a solution of (2.1) containing a parameter t such that $x(0, 0) = x_0$, $y(0, 0) = y_0$ and the Jacobian $\partial(x, y)/\partial(s, t)$ evaluated at $(0, 0)$ is different from zero. If the domain of definition V of $x(s, t)$ and $y(s, t)$ is a sufficiently small open neighborhood of $(0, 0)$ in \mathbb{C}^2 , then the mapping $(s, t) \rightarrow (x(s, t), y(s, t))$ is a one-to-one transformation from V onto a complex open neighborhood U of (x_0, y_0) and has a holomorphic inverse.

THEOREM 1. *The condition (A) holds in Ω , if and only if,*

(α) *Every point of Ω has a neighborhood in which every characteristic curve has at most one real point.*

The condition (B) holds in Ω , if and only if,

(β) *Every point of Ω has a neighborhood in which every characteristic curve either has at most one real point or else is a real curve.*

PROOF. Let (x_0, y_0) be a point of Ω . It is possible to introduce new *real* local coordinates in a neighborhood of (x_0, y_0) , so that the operator takes the form

$$p = a'(x, y) \left(-\frac{\partial}{\partial x} + ib'(x, y) \frac{\partial}{\partial y} \right),$$

where $a'(x, y)$ is a non-vanishing complex-valued analytic function, and $b'(x, y)$ is a *real*-valued analytic function [3]. Since the conditions (A), (B), (α) and (β) are local and invariant under a *real* change of variables and multiplication of p by a non-vanishing function, we may suppose that p has the form

$$(2.2) \quad p = -\frac{\partial}{\partial x} + ib(x, y) \frac{\partial}{\partial y},$$

where $b(x, y)$ is a *real*-valued analytic function.

For the operator p of the form (2.2), c_p^k becomes

$$c_p^k = \left(-2i \frac{\partial^k b}{\partial x^k} + \sum_{j=0}^{k-1} d_{jk} \frac{\partial^j b}{\partial x^j} \right) \frac{\partial}{\partial y}, \quad k \geq 1,$$

so that

$$(2.3) \quad k_p(x, y) = \min \left\{ k; \frac{\partial^k b(x, y)}{\partial x^k} \neq 0 \right\}.$$

Hence, at a real point (x, y) on an integral curve $y = \varphi(x)$ of the characteristic equation $dy/dx = ib(x, y)$, we have

$$(2.4) \quad k_p(x, y) = \min \{ k; \operatorname{Im} \varphi^{(k+1)}(x) \neq 0 \}$$

and

$$(2.5) \quad \operatorname{Im} \varphi^{(k+1)}(x) = \frac{\partial^k b(x, y)}{\partial x^k} \quad \text{when } k = k_p(x, y).$$

(A) \Rightarrow (α). It follows from (2.3) that, if the condition (A) holds, the sign of the function $b(x, y)$ does not vary with x and y . Neither does the sign of $(\partial/\partial x)^k b(x, y)$. Suppose that, on a characteristic curve $y = \varphi(x)$, there were more than one real points. When x moves along the real axis, it follows from (2.4) that every zero of $\operatorname{Im} \varphi(x)$ is of odd order $k_p + 1$. Hence the sign of $\operatorname{Im} \varphi^{(k_p+1)}(x)$ changes at successive zeros of $\operatorname{Im} \varphi(x)$ on the real axis. In view of (2.5), this is a contradiction.

(B) \Rightarrow (β). Suppose that the condition (B) holds in Ω . Let (x_0, y_0) be a point of Ω which we may assume to be $(0, 0)$ without loss of generality. Since $b(x, y)$ is an analytic function, it follows from (2.3) that, for fixed y , the sign of $b(x, y)$ does not vary with x . Hence, if we choose a neighborhood ω of $(0, 0)$ of sufficiently small width in the direction of the y -axis, the sign of $b(x, y)$ does not vary with x and y in each of the two regions $\omega^+ = \omega \cap \{y > 0\}$ and $\omega^- = \omega \cap \{y < 0\}$.

When $b(x, y)$ does not change sign in the whole of ω , by the same argument as in the proof of (A) \Rightarrow (α), we prove that if a characteristic curve is not a real curve, then it has at most one real point.

When $b(x, y)$ changes sign, $b(x, 0)$ vanishes identically and there is a constant $C > 0$ such that $|b(x, y)| \leq C|y|$. Hence for every characteristic curve $y = \varphi(x)$ except $y = 0$ we have

$$|\arg \varphi(x_2) - \arg \varphi(x_1)| \leq \left| \int_{x_1}^{x_2} \frac{\varphi'(x) dx}{\varphi(x)} \right| \leq C|x_2 - x_1|.$$

Let the diameter of ω be smaller than π/C . Suppose that there were a characteristic curve which is not a real curve and has more than one real points. Then the sign of $\text{Im } \varphi^{(k_p+1)}(x)$ changes at successive zeros x_1 and x_2 of $\text{Im } \varphi(x)$ on the real axis and so does the sign of $(\partial/\partial x)^{k_p} b(x, y)$ in view of (2.5). Hence $\varphi(x_1)$ and $\varphi(x_2)$ must be of opposite signs. It follows therefore that $|x_2 - x_1| \geq \pi/C$. Contradiction.

(β) \Rightarrow (B). Suppose that the condition (B) does not hold in Ω . Then there is a point (x_0, y_0) in Ω such that $k_p(x_0, y_0)$ is odd. We may suppose $(x_0, y_0) = (0, 0)$. We denote by $\varphi(x, t)$ the solution of the equation $dy/dx = ib(x, y)$ such that $\varphi(0, t) = it$. We have then

$$\varphi(x, 0) = id x^{k_0+1} + \dots,$$

where $d = (\partial/\partial x)^{k_0} b(0, 0)/(k_0+1)!$, $k_0 = k_p(0, 0)$. Hence

$$(2.6) \quad \varphi(x, t) = (i + o(1))t + (id + o(1))x^{k_0+1},$$

so that for sufficiently small real x and real t we have

$$|\text{Im } \varphi(x, t) - t - dx^{k_0+1}| \leq (|t| + |d|x^{k_0+1})/2.$$

When $dt < 0$ it follows that $\text{Im } \varphi(x, t)$ lies between $(t + 3dx^{k_0+1})/2$ and $(3t + dx^{k_0+1})/2$. Thus if t is sufficiently small, the characteristic curve $y = \varphi(x, t)$ has more than one real points and is not a real curve.

(α) \Rightarrow (A). Suppose that the condition (A) does not hold in Ω . Then there is a point (x_0, y_0) in Ω such that $k_p(x_0, y_0)$ is either odd or ∞ . If $k_p(x_0, y_0)$ is odd, (β) is not valid. If $k_p(x_0, y_0) = \infty$, the characteristic curve passing through (x_0, y_0) is a real curve. In either case, in any neighborhood of (x_0, y_0) , we can find a characteristic curve having more than one real points.

§ 3. Some lemmas.

First note that the statements of Theorems A and B are local and invariant under a real change of variables and multiplication of P by a non-vanishing function.

The Cauchy-Kovalevsky theorem implies that the equation $ph+c=0$ has an analytic solution in sufficiently small open sets. If we set $u=ve^h$, the equation $Pu=f$ is transformed into $pv=e^{-h}f$. Hence we need only prove the Theorems A and B for homogeneous operators p .

As to Theorem A, since we can locally solve $pv=e^{-h}f$ with v analytic, it is enough to prove the equivalence of the condition (A) to the following.

(a₀) For every open subset ω of Ω , if $u \in \mathcal{B}(\omega)$ and $pu=0$, then $u \in \mathcal{A}(\omega)$.

Let ω be an open set in \mathbf{R}^2 and let U be a complex neighborhood of ω , that is, an open set in \mathbf{C}^2 which contains ω as a relatively closed subset. We use the following notation:

$$\begin{aligned} U_1 &= \{(x, y) \in U; \operatorname{Im} x \neq 0\}, & U_2 &= \{(x, y) \in U; \operatorname{Im} y \neq 0\}, \\ U_1^\pm &= \{(x, y) \in U; \operatorname{Im} x \gtrless 0\}, & U_2^\pm &= \{(x, y) \in U; \operatorname{Im} y \gtrless 0\}, \\ U^\sigma &= \{(x, y) \in U; (\operatorname{Im} x, \operatorname{Im} y) \text{ is in the } \sigma\text{th quadrant of } \mathbf{R}^2\}. \end{aligned}$$

If we choose a Stein neighborhood U such that $U \cap \mathbf{R}^2 = \omega$, then $\mathcal{B}(\omega)$ may be identified with $\mathcal{O}(U_1 \cap U_2)/(\mathcal{O}(U_1) + \mathcal{O}(U_2))$. Hence a hyperfunction $u \in \mathcal{B}(\omega)$ is represented by a holomorphic function defined in $U_1 \cap U_2$ which we call a defining function of u . We denote by u^σ the restriction to U^σ of a defining function. If each u^σ can be analytically continued across ω , that is, if there is a complex open set W containing ω such that each u^σ has a holomorphic extension to $W \cap U^\sigma$, then the hyperfunction u is a real analytic function. Conversely, if u is a real analytic function and all u^σ except one vanish identically, then u^σ can be analytically continued across ω .

From now on p will denote both the operator on \mathcal{B} and on \mathcal{O} . If we choose U such that $p\mathcal{O}(U_i) = \mathcal{O}(U_i)$, the conditions (a₀) and (b) can be transformed into conditions expressed in terms of defining functions of hyperfunctions.

LEMMA 1. Let U be a Stein neighborhood of $\omega \subset \Omega$ such that $p\mathcal{O}(U_i) = \mathcal{O}(U_i)$, $i=1, 2$.

The following two conditions are equivalent:

(a₀)_ω If $u \in \mathcal{B}(\omega)$ and $pu=0$, then $u \in \mathcal{A}(\omega)$.

(ā₀)_ω For each σ , if $u^\sigma \in \mathcal{O}(U^\sigma)$ and $pu^\sigma=0$, then u^σ can be analytically continued across ω .

The following two conditions are equivalent:

(b)_ω $p\mathcal{B}(\omega) = \mathcal{B}(\omega)$.

(b̄)_ω For each σ , $p\mathcal{O}(U^\sigma) = \mathcal{O}(U^\sigma)$.

PROOF. (ā₀)_ω \Rightarrow (a₀)_ω. Let $u \in \mathcal{B}(\omega)$ be represented by $u^\sigma \in \mathcal{O}(U^\sigma)$. Then $pu=0$ means $pu^\sigma = e_1 + e_2$, $e_i \in \mathcal{O}(U_i)$. By hypothesis on U , there exist $u_i \in \mathcal{O}(U_i)$ such that $pu_i = e_i$. Then u is represented also by $u'^\sigma = u^\sigma - u_1 - u_2$ for which we have $pu'^\sigma = 0$. It follows from (ā₀)_ω that u'^σ can be analytically continued

across ω . Hence $u \in \mathcal{A}(\omega)$.

$(b)_\omega \Rightarrow (\tilde{b})_\omega$. Given $f^\sigma \in \mathcal{O}(U^\sigma)$, it follows from $(b)_\omega$ that we can find $u^\sigma \in \mathcal{O}(U^\sigma)$ such that $pu^\sigma - f^\sigma \in \mathcal{O}(U_1) + \mathcal{O}(U_2)$. Thus there exist $e_i \in \mathcal{O}(U_i)$ such that $pu^\sigma - f^\sigma = e_1 + e_2$. By hypothesis on U , there exist $u_i \in \mathcal{O}(U_i)$ such that $pu_i = e_i$. If we set $u'^\sigma = u^\sigma - u_1 - u_2$, then $u'^\sigma \in \mathcal{O}(U^\sigma)$ and $pu'^\sigma = f^\sigma$.

The implications $(a_0)_\omega \Rightarrow (\tilde{a}_0)_\omega$ and $(\tilde{b})_\omega \Rightarrow (b)_\omega$ are obvious.

In the construction of a Stein neighborhood U satisfying the hypothesis of Lemma 1 and also in the proof of Theorem B we need the following lemma.

LEMMA 2. *Let G be an open set in the space of two complex variables (x, t) . If every section $G(t)$ of G by $t = \text{const}$ is simply-connected, then $(\partial/\partial x)\mathcal{O}(G) = \mathcal{O}(G)$.*

PROOF. We denote by π the projection $(x, t) \rightarrow t$. Since every $G(t)$ is simply-connected, there exists an open covering $\{N_i\}$ of $\pi(G)$ such that $(\partial/\partial x)\mathcal{O}(G_i) = \mathcal{O}(G_i)$, where $G_i = G \cap \pi^{-1}(N_i)$. For any $g \in \mathcal{O}(G)$, we can then find a solution $v_i \in \mathcal{O}(G_i)$ of $(\partial/\partial x)v_i = g$. Since $(\partial/\partial x)(v_i - v_j) = 0$ in $G_i \cap G_j$ and all the sections $G(t)$ are connected, $v_i(x, t) - v_j(x, t)$ is a function of t alone which we denote by $w_{ij}(t)$, $t \in N_i \cap N_j$. Since the first Cousin problem has a solution in any open set in the complex plane, we can find $w_i(t) \in \mathcal{O}(N_i)$ so that $w_{ij} = w_i - w_j$ in $N_i \cap N_j$. If we set $v(x, t) = v_i(x, t) - w_i(t)$ in G_i , then $v \in \mathcal{O}(G)$ and $(\partial/\partial x)v = g$. QED.

We keep the notation used in the proof of Theorem 1. The change of variables $(x, y) \rightarrow (x, x+y)$ transforms the differential operator into

$$p = \frac{\partial}{\partial x} + (1 + ib(x, y-x)) \frac{\partial}{\partial y}$$

and the equation of characteristic curves into $y = \phi(x, t) \equiv x + \varphi(x, t)$. If the domain of definition V of $\phi(x, t)$ is a sufficiently small open neighborhood of $(0, 0)$ in \mathbb{C}^2 , then the mapping $(x, t) \rightarrow (x, \phi(x, t))$ is a one-to-one transformation from V onto a complex open neighborhood U of $(0, 0)$ and has a holomorphic inverse. Set $V = X \times T$, where X and T are rectangles about 0 in the complex plane. Then U is a Stein manifold.

Under the complex change of variables $(x, y) \rightarrow (x, t)$, we have the following table of corresponding quantities:

$$\begin{array}{ll} pu(x, y) = f(x, y); & (\partial/\partial x)v(x, t) = g(x, t), \\ U, U_i, U_i^\pm, U^\sigma; & V, V_i, V_i^\pm, V^\sigma, \\ \text{characteristic curve } C_i: y = \phi(x, t); & V(t) = X, \\ C_t \cap U_i^\pm, C_t \cap U^\sigma; & V_i^\pm(t), V^\sigma(t). \end{array}$$

We denote by x' and x'' the real and imaginary part of x , respectively.

Since $(\partial/\partial x'') \operatorname{Im} \phi(x' + ix'', t) = 1$ when $(x, t) = (0, 0)$, we can solve the equation $\operatorname{Im} \phi(x' + ix'', t) = 0$ for x'' and write $x'' = \xi(x', t)$, if V is taken sufficiently small. Thus we have $V_1^\pm(t) = \{x \in X; x'' \geq 0\}$, $V_2^\pm(t) = \{x \in X; x'' \geq \xi(x', t)\}$ and $V^\sigma(t) = \{x \in X; x'' \geq 0 \text{ and } x'' \geq \xi(x', t)\}$, so $V_1^\pm(t)$ and $V_2^\pm(t)$ are simply-connected. In view of Lemma 2, U satisfies the hypothesis of Lemma 1.

§ 4. Proof of Theorem A.

First note that real points on the characteristic curve $y = \phi(x, t)$ correspond to zeros of $\xi(x', t)$ and that the characteristic curve is a real curve, if and only if $\xi(x', t)$ vanishes identically. When $k_0 = k_p(0, 0)$ is finite, we obtain from (2.6)

$$\phi(x, t) = (i + o(1))t + x + (id + o(1))x^{k_0+1}.$$

Hence, if t is real, $\xi(x', 0) = -dx'^{k_0+1} + \dots$ and $\xi(0, t) = -t + \dots$, so that we have

$$(4.1) \quad \xi(x', t) = -(1 + o(1))t - (d + o(1))x'^{k_0+1}.$$

When $k_0 = \infty$, $\xi(x', 0)$ vanishes identically.

(A) \Rightarrow (A₀). Suppose that the condition (A) holds in a neighborhood of $(0, 0)$. Since $k_0 + 1$ is odd, it follows from (4.1) with $t = 0$ that $V^\sigma(0) \neq \emptyset$ for every σ . Furthermore, in view of (α), for every $t \in T$, $\xi(x', t)$ has at most one zero. Hence $V^\sigma(t)$ is connected or empty.

Let $u^\sigma \in \mathcal{O}(U^\sigma)$ be a solution of $pu^\sigma = 0$. We shall show that u^σ can be analytically continued to a neighborhood of $(0, 0)$. Under the change of variables $(x, y) \rightarrow (x, t)$, there corresponds to u^σ a solution $v^\sigma \in \mathcal{O}(V^\sigma)$ of $(\partial/\partial x)v^\sigma = 0$. Since all the sections $V^\sigma(t)$ are connected, $v^\sigma(x, t)$ is a function of t alone, so it can be analytically continued to $\tilde{V}^\sigma = \{(x, t) \in V; V^\sigma(t) \neq \emptyset\}$. Since $V^\sigma(0) \neq \emptyset$, \tilde{V}^σ is an open neighborhood of $(0, 0)$. Thus u^σ can be continued to a neighborhood \tilde{U}^σ of $(0, 0)$.

(A₀) \Rightarrow (A). If k_0 is either odd or ∞ , then $V^\sigma(0) = \emptyset$ for some σ . This means that $t \neq 0$ when $(x, t) \in V^\sigma$. If we set $v^\sigma(x, t) = t^{-1}$, then $v^\sigma \in \mathcal{O}(V^\sigma)$ and $(\partial/\partial x)v^\sigma = 0$ while v^σ can not be continued analytically to a neighborhood of $(0, 0)$.

§ 5. Proof of Theorem B.

(B) \Rightarrow (b). Suppose that the condition (B) holds in a neighborhood of $(0, 0)$. It follows from (β) that either $\xi(x', t)$ has at most one zero or else vanishes identically. Hence for every σ and every t , $V^\sigma(t)$ is simply-connected or

empty. We have by Lemma 2 $(\partial/\partial x)\mathcal{O}(V^\sigma) = \mathcal{O}(V^\sigma)$, so that $p\mathcal{O}(U^\sigma) = \mathcal{O}(U^\sigma)$.

(b) \Rightarrow (B). Let $k_0 = k_p(0, 0)$ be odd. It follows from (4.1) that for sufficiently small real t and x'

$$|\xi(x', t) + t + dx'^{k_0+1}| \leq (|t| + |d|x'^{k_0+1})/2.$$

To fix ideas, suppose that $d > 0$. Then we have

$$\xi(x', t) \leq (-t - dx'^{k_0+1})/2$$

when $t \geq 0$. If we set $S(t) = \{x \in X; (-t - dx'^{k_0+1})/2 < x'' < 0\}$ for $t \geq 0$, then $S(t) \subset V^\sigma(t)$, $\sigma = 2$.

Set $f(x, y) = 1/xy$ and $g(x, t) = 1/x\phi(x, t)$. $f(x, y)$ is a defining function of $(2\pi i)^2\partial(x, y)$. We now claim that the equation $(\partial/\partial x)v = g$ has no solution $v \in \mathcal{O}(V^2)$. Suppose on the contrary that there were a solution $v \in \mathcal{O}(V^2)$ of $(\partial/\partial x)v = g$. Choose two points x_1 and x_2 in $S(0)$ so that $x'_1 < 0$ and $x'_2 > 0$. For $t > 0$ let $\Gamma(t)$ be a path from x_1 to x_2 lying in $S(t)$. Then we have

$$\int_{\Gamma(t)} g(x, t)dx = v(x_2, t) - v(x_1, t).$$

As $t \downarrow 0$ the right hand side tends to $v(x_2, 0) - v(x_1, 0)$.

On the other hand, $\phi(x, t)$ does not vanish when $x'' > (-t - dx'^{k_0+1})/2$. Let $\Gamma_1(t)$ be a circle with center at $x = 0$ which is oriented counter-clockwise and contained in the region $\{x \in X; x'' > (-t - dx'^{k_0+1})/2\}$. Let Γ_2 be a path from x_1 to x_2 lying in the region $\{x \in X; x'' > -dx'^{k_0+1}/2\}$. Then we have

$$\int_{\Gamma(t)} g(x, t)dx = \int_{\Gamma_1(t)} g(x, t)dx + \int_{\Gamma_2} g(x, t)dx.$$

The first integral on the right hand side is equal to $2\pi i/\phi(0, t) = 2\pi/t$. As $t \downarrow 0$ the second integral tends to the integral of $g(x, 0)$ along Γ_2 . Hence the left hand side tends to ∞ . This gives a contradiction.

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