

Transformations of pseudo-Riemannian manifolds

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An m -dimensional pseudo-Riemannian manifold (M, g) is by definition a differentiable manifold M with a definite or indefinite Riemannian metric tensor g of signature (r, s) . If the signature of g is $(m, 0)$, then we say that (M, g) is a Riemannian manifold. The purpose of this note is to generalize the results on transformations of Riemannian manifolds to those of pseudo-Riemannian manifolds.

In section 1 we give the basic relations of connections or various tensors satisfied by projective or conformal transformations. In section 2 we consider affine transformations and, for example, we get

COROLLARY 2.5. *If (M, g) is a compact irreducible pseudo-Riemannian manifold of signature (r, s) satisfying $r \neq s$, then any affine transformation of M is an isometry.*

In sections 3, 4, 5 and 6 we study projective and conformal transformations leaving some tensors invariant, in a similar way as in K. Yano and T. Nagano's paper [10]. However, some statements of theorems in [10] seem to be incomplete, and so we give here complete statements and prove them in pseudo-Riemannian manifolds. For example we have

PROPOSITION 5.1. *Let (M, g) and $(N, 'g)$ be pseudo-Riemannian manifolds of dimension $m \geq 4$. If there is a conformal transformation φ of M to N which leaves the covariant derivatives of the Weyl conformal curvature tensors invariant and if the set of points where φ is non-affine is dense in M , then M and N are conformally flat.*

As a consequence of this proposition we have

PROPOSITION 5.3. *Let M ($m \geq 4$) be an irreducible locally symmetric pseudo-Riemannian manifold of signature (r, s) , $r \neq s$. Then we have either*

- (i) M is of constant curvature, or
- (ii) M does not admit any non-homothetic conformal transformation.

In the last section we give examples which support our statements of Proposition 3.1 and Proposition 5.1.

§1. Preliminaries.

(i) Let M and N be differentiable manifolds with linear connections ∇ and ∇' . If φ is a transformation (diffeomorphism) of M to N , then φ induces a map of geometric objects $\nabla'K$ on N to those on M denoted by ${}^{\varphi}K$. Especially for ∇' on N we have an induced connection ${}^{\varphi}\nabla$ defined by

$$(1.1) \quad {}^{\varphi}\nabla_X Y = \varphi^{-1} \cdot \nabla_{\varphi X}(\varphi Y)$$

for any vector fields X and Y on M , where φ itself denotes the differential of φ . From now on by V, X, Y and Z we denote vector fields on M . Since the difference of the connections ${}^{\varphi}\nabla$ and ∇ makes a tensor field of type $(1, 2)$ we denote it by W , and we define W_X by

$$(1.2) \quad {}^{\varphi}\nabla_X Y - \nabla_X Y = W(Y, X) = W_X(Y).$$

If K is a tensor field of type $(1, 1)$, for example, then we have

$$({}^{\varphi}\nabla_X K - \nabla_X K)Y = W_X(KY) - K \cdot W_X(Y).$$

In the last equation if we replace K by ${}^{\varphi}K$, and notice the relation ${}^{\varphi}\nabla_X {}^{\varphi}K = {}^{\varphi}(\nabla_{\varphi X} {}^{\varphi}K)$, then we get

LEMMA 1.1. *Let φ be a transformation of (M, ∇) to (N, ∇') and let $\nabla'K$ be a tensor field of type $(1, 1)$, for example, on N . Then we have*

$$(1.3) \quad ({}^{\varphi}(\nabla_{\varphi X} {}^{\varphi}K) - \nabla_X {}^{\varphi}K)Y = W_X({}^{\varphi}KY) - {}^{\varphi}K \cdot W_X(Y).$$

(ii) Suppose that the linear connections ∇ and ∇' are symmetric. A transformation φ of M to N is projective if and only if we have a 1-form p on M such that

$$(1.4) \quad W_X(Y) = W(Y, X) = p(Y)X + p(X)Y.$$

We say that φ is non-affine at x of M if $p_x \neq 0$. The Riemannian curvature tensors R and ${}^{\varphi}R$, the Ricci curvature tensors R_1 and ${}^{\varphi}R_1$ are, as is well known (for example, see [1]), related by

$$(1.5) \quad {}^{\varphi}R(X, Y)Z = R(X, Y)Z + (\nabla_Y p)(Z)X - (\nabla_X p)(Z)Y + p(Z)p(X)Y - p(Z)p(Y)X + ((\nabla_Y p)(X) - (\nabla_X p)(Y))Z,$$

$$(1.6) \quad {}^{\varphi}R_1(X, Y) = R_1(X, Y) + (m-1)(p(X)p(Y) - (\nabla_Y p)(X)) + (\nabla_X p)(Y) - (\nabla_Y p)(X).$$

Now we define a tensor P_1 of type $(0, 2)$ by

$$(1.7) \quad (m^2 - 1)P_1(X, Y) = -mR_1(X, Y) - R_1(Y, X).$$

Then the Weyl projective curvature tensor P defined by

$$(1.8) \quad P(Z, X, Y) = R(X, Y)Z + P_1(Z, X)Y - P_1(Z, Y)X \\ + (P_1(X, Y) - P_1(Y, X))Z$$

is invariant under any projective transformation, i.e. ${}^{\circ}P = P$. For $m \geq 3$ we define a tensor Q of type $(0, 3)$ by defining $(m-2)Q(Z, X, Y)$ to be the trace of the map $V \rightarrow (\nabla_V P)(Z, X, Y)$. If the Ricci tensor is symmetric, then (1.8) is written as

$$(1.8)' \quad P(Z, X, Y) = R(X, Y)Z - (m-1)^{-1}(R_1(X, Z)Y - R_1(Y, Z)X).$$

LEMMA 1.2. For a projective transformation φ of a differentiable manifold (M, ∇) ($m \geq 3$) with symmetric connection and symmetric Ricci tensor to another such (N, ∇') we have

$$(1.9) \quad {}^{\circ}Q(Z, X, Y) - Q(Z, X, Y) = \rho(P(Z, X, Y)).$$

PROOF. If we apply (1.3) to the projective curvature tensor P , then, using ${}^{\circ}P = P$, we get

$$(m-2)({}^{\circ}Q(Z, X, Y) - Q(Z, X, Y)) = \text{trace}[V \rightarrow W_V P(Z, X, Y) - P(W_V Z, X, Y) \\ - P(Z, W_V X, Y) - P(Z, X, W_V Y)].$$

By applying (1.4), the right hand side is written as

$$\text{trace}[V \rightarrow \rho(P(Z, X, Y))V - 2\rho(V)P(Z, X, Y) - \rho(Z)P(V, X, Y) \\ - \rho(X)P(Z, V, Y) - \rho(Y)P(Z, X, V)].$$

By (1.8)' we see that $\text{trace}[V \rightarrow P(Z, X, V)] = 0$. Similarly we get $\text{trace}[V \rightarrow P(V, X, Y)] = 0$ and $\text{trace}[V \rightarrow P(Z, V, Y)] = 0$. Then (1.9) follows from

$$\text{trace}[V \rightarrow \rho(P(Z, X, Y))V - 2\rho(V)P(Z, X, Y)] = (m-2)\rho(P(Z, X, Y)).$$

(iii) Let φ be a conformal transformation of a pseudo-Riemannian manifold (M, g) to (N, g') such that ${}^{\circ}g = e^{2\alpha}g$ for a function α on M . With respect to the Riemannian connections ∇ and ∇' on M and N we have

$$(1.10) \quad W_X Y = (X\alpha)Y + (Y\alpha)X - g(X, Y)\text{grad } \alpha,$$

where $\text{grad } \alpha$ is a vector field associated with $d\alpha$ defined by the metric tensor g . We say that φ is non-homothetic at x of M if $(d\alpha)_x \neq 0$. The relation between the Riemannian curvature tensors is

$$(1.11) \quad {}^{\circ}R(X, Y)Z = R(X, Y)Z + F(Z, Y)X - F(Z, X)Y \\ + g(Z, Y)F(X) - g(Z, X)F(Y),$$

where

$$(1.12) \quad F(Z, Y) = (\nabla_Z d\alpha)(Y) - (Z\alpha)(Y\alpha) + 2^{-1}g(\text{grad } \alpha, \text{grad } \alpha)g(Z, Y)$$

and $F(X)$ is defined by $g(F(X), Y) = F(X, Y)$. We have also the relations between the Ricci curvature tensors, and scalar curvatures S and ${}^{\varphi}S$. The Weyl conformal curvature tensor C defined for $m \geq 3$ by

$$(1.13) \quad C(Z, X, Y) = R(X, Y)Z - (m-2)^{-1}(R_1(Z, X)Y - R_1(Z, Y)X) \\ + g(Z, X)R^1(Y) - g(Z, Y)R^1(X) \\ + (m-1)^{-1}(m-2)^{-1}S(g(Z, X)Y - g(Z, Y)X)$$

is invariant under any conformal transformation, where $R^1(X)$ is defined by $g(R^1(X), Y) = R_1(X, Y)$. If $m = 3$, then we have $C = 0$. For $m \geq 4$, we define $(m-3)E(Z, X, Y)$ to be the trace of the map $V \rightarrow (\nabla_V C)(Z, X, Y)$. Then E is a tensor field of type $(0, 3)$. Similarly to Lemma 1.2, we have

LEMMA 1.3. For a conformal transformation φ of a pseudo-Riemannian manifold $(M, g)(m \geq 4)$ to another $(N, 'g)$ we have

$$(1.14) \quad {}^{\varphi}E(Z, X, Y) - E(Z, X, Y) = d\alpha(C(Z, X, Y)).$$

PROOF. If we apply (1.3) to the conformal curvature tensor C , then, using ${}^{\varphi}C = C$, we get

$$(m-3)({}^{\varphi}E(Z, X, Y) - E(Z, X, Y)) = \text{trace} [V \longrightarrow W_V C(Z, X, Y) \\ - C(W_V Z, X, Y) - C(Z, W_V X, Y) - C(Z, X, W_V Y)].$$

By (1.10) the right hand side is written as

$$\text{trace} [V \longrightarrow d\alpha(C(Z, X, Y))V - 2(V\alpha)(C(Z, X, Y)) \\ - g(V, C(Z, X, Y)) \text{grad } \alpha - (Z\alpha)C(V, X, Y) \\ - (X\alpha)C(Z, V, Y) - (Y\alpha)C(Z, X, V) \\ + g(V, Z)C(\text{grad } \alpha, X, Y) + g(V, X)C(Z, \text{grad } \alpha, Y) \\ + g(V, Y)C(Z, X, \text{grad } \alpha)].$$

First we have

$$\text{trace} [V \longrightarrow d\alpha(C(Z, X, Y))V - 2(V\alpha)C(Z, X, Y)] = (m-2)d\alpha(C(Z, X, Y)), \\ \text{trace} [V \longrightarrow -g(V, C(Z, X, Y)) \text{grad } \alpha] = -g(\text{grad } \alpha, C(Z, X, Y)) \\ = -d\alpha(C(Z, X, Y)).$$

Next by (1.13) we get $\text{trace} [V \rightarrow C(V, X, Y)] = 0$, $\text{trace} [V \rightarrow C(Z, V, Y)] = 0$ and $\text{trace} [V \rightarrow C(Z, X, V)] = 0$. If we write $C(Z, X, Y) = C(X, Y)Z$, then it is known that C satisfies the same algebraic equations as those satisfied by the Riemannian curvature tensor R , and so we have

$$\begin{aligned}
\text{trace } [V \longrightarrow g(V, Z)C(\text{grad } \alpha, X, Y)] &= g(Z, C(\text{grad } \alpha, X, Y)) \\
&= -g(\text{grad } \alpha, C(Z, X, Y)) \\
&= -d\alpha(C(Z, X, Y)), \\
\text{trace } [V \longrightarrow g(V, X)C(Z, \text{grad } \alpha, Y) + g(V, Y)C(Z, X, \text{grad } \alpha)] \\
&= g(X, C(Z, \text{grad } \alpha, Y)) + g(Y, C(Z, X, \text{grad } \alpha)) \\
&= -g(Z, C(X, \text{grad } \alpha, Y)) + C(Y, X, \text{grad } \alpha) \\
&= g(Z, C(\text{grad } \alpha, Y, X)) \\
&= g(\text{grad } \alpha, C(Z, X, Y)) \\
&= d\alpha(C(Z, X, Y)).
\end{aligned}$$

Therefore, adding these results together we have (1.14).

By $A(M)$, $H(M)$ and $I(M)$ we denote the group of affine ($W=0$), homothetic ($d\alpha=0$) and isometric ($\alpha=0$) transformations of M , respectively.

If a transformation φ of (M, g) to $(N, 'g)$ satisfies ${}^{\varphi}g = -e^{2\alpha}g$ we say that φ is an anti-conformal transformation, an anti-homothety, or an anti-isometry.

§ 2. Affine transformations.

In the previous paper [6] generalizing [2] we obtained the following

PROPOSITION 2.1. *Let (M, g) and $(N, 'g)$ be irreducible pseudo-Riemannian manifolds and assume that the signature (r, s) of g satisfies $r \neq s$. If there is an affine transformation φ of M to N , then the signature of $'g$ is (r, s) or (s, r) and φ is a homothety or an anti-homothety, respectively.*

REMARK 2.2. Any 2-dimensional orientable pseudo-Riemannian manifold (M, g) of signature $(1, 1)$ is reducible. In fact for any point x of M each 1-dimensional subspace of the tangent space M_x at x defined by null vectors is invariant by the restricted homogeneous holonomy group.

REMARK 2.3. Since the distinction between g and $-g$ in a pseudo-Riemannian manifold M is not essential, in many cases we may assume that the signature (r, s) of g satisfies $r \geq s$.

PROPOSITION 2.4. *Any homothety (or anti-homothety) of a compact pseudo-Riemannian manifold (M, g) is an isometry (or anti-isometry).*

PROOF. We assume that M is orientable. Then we have the volume element $(\epsilon \det g)^{1/2} dx^1 \wedge \dots \wedge dx^m$ defined by the determinant of g in each coordinate neighborhood (the order (x^1, \dots, x^m) being compatible with the orientation and ϵ being the sign of $\det g$). Then the proof for a homothety is the same as in the Riemannian case (cf. [5]). An anti-homothety can exist only when the signature of g is (r, r) . And for an anti-homothety φ of (M, g) , we consider

a homothety φ of (M, g) to $(M, -g)$.

By Propositions 2.1. and 2.4 we get

COROLLARY 2.5. *If (M, g) is a compact irreducible pseudo-Riemannian manifold of signature (r, s) satisfying $r \neq s$, then any affine transformation of M is an isometry.*

Similarly to [2], we have

COROLLARY 2.6. *Let M be an irreducible pseudo-Riemannian manifold of signature (r, s) satisfying $r \neq s$. Then we have:*

- (i) *Any compact subgroup of $A(M)$ is a subgroup of $I(M)$.*
- (ii) *The commutator subgroup $[A(M), A(M)]$ is a subgroup of $I(M)$.*

REMARK 2.7. Let M and N be pseudo-Riemannian manifolds. If an affine transformation of M to N is isometric at some point of M , then it is an isometry (see [9], p. 57).

§ 3. ∇P -preserving projective transformations.

PROPOSITION 3.1. *Let $M(m \geq 3)$ and N be differentiable manifolds with symmetric connections ∇ and ∇' , and symmetric Ricci tensors R_1 and R_1' . If there is a projective transformation φ of M to N which leaves the covariant derivatives of the Weyl projective curvature tensors invariant and if the set of points where φ is non-affine is dense in M , then M and N are projectively flat.*

PROOF. By $\varphi(\nabla'P) = \nabla P$, we have $\varphi Q = Q$. Next by Lemma 1.2 we have $p(P(Z, X, Y)) = 0$. If we apply (1.3) to P , using $\varphi(\nabla'P) = \nabla P$ and $\varphi P = P$, we get

$$0 = W_\nu(P(Z, X, Y)) - P(W_\nu Z, X, Y) - P(Z, W_\nu X, Y) - P(Z, X, W_\nu Y).$$

By (1.4), using $p(P(Z, X, Y)) = 0$, we get

$$(3.1) \quad \begin{aligned} 0 = & 2p(V)P(Z, X, Y) + p(Z)P(V, X, Y) \\ & + p(X)P(Z, V, Y) + p(Y)P(Z, X, V). \end{aligned}$$

Take a point x of M such that $p_x \neq 0$. Then we have a basis (e_1, \dots, e_m) of M_x and the dual basis (w^1, \dots, w^m) such that $w^1 = p_x$.

If we put $V = e_1, Z = e_l, X = e_j, Y = e_k$ in (3.1), then we get $P(e_l, e_j, e_k) = 0$ for $j, k, l \neq 1$.

If we put $V = Z = e_1, X = e_j, Y = e_k$ in (3.1), then we have $P(e_1, e_j, e_k) = 0$ for $j, k \neq 1$.

If we put $V = X = e_1, Z = e_l, Y = e_k$ in (3.1), then we get $P(e_l, e_1, e_k) = 0$ for $k, l \neq 1$.

Finally if we put $V = Z = X = e_1, Y = e_k$ in (3.1), then we have $P(e_1, e_1, e_k) = 0$ for $k \neq 1$.

Therefore we have $P=0$ at x . Since the set of points x such that $p_x \neq 0$ is dense in M , we have $P=0$ on M .

REMARK 3.2. In section 7, we give an example showing necessity of the assumption that "the set of points where φ is non-affine is dense in M " in the above Proposition.

A pseudo-Riemannian manifold M is said to be of constant curvature at x , if the Riemannian curvature tensor satisfies

$$R(X, Y)Z = k_x(g(Z, Y)X - g(Z, X)Y)$$

at x for some real number k_x . If k_x is constant on M , M is said to be of constant curvature. It is known that any projectively flat pseudo-Riemannian manifold is of constant curvature. Thus we get

PROPOSITION 3.3. *Let (M, g) and $(N, 'g)$ be pseudo-Riemannian manifolds ($m \geq 3$). If there is a projective transformation φ of M to N which leaves the covariant derivatives of the Weyl projective curvature tensors invariant and if the set of points where φ is non-affine is dense in M , then M and N are of constant curvature.*

COROLLARY 3.4. *Suppose that a pseudo-Riemannian manifold $M(m \geq 3)$ is not of constant curvature on any open set in M . Then any projective transformation of M to another N which leaves the covariant derivatives of the Weyl projective curvature tensors invariant is affine.*

PROPOSITION 3.5. *Let $(M, g)(m \geq 3)$ be a locally symmetric pseudo-Riemannian manifold. Then either*

- (i) M is of constant curvature, or
- (ii) M does not admit any non-affine projective transformation.

PROOF. Since M is locally symmetric we have $\nabla R=0$ and hence $\nabla P=0$. Suppose that M is not of constant curvature. Then P does not vanish at some point of M . Since P is a parallel tensor field, it does not vanish anywhere. Thus any projective transformation of M is necessarily affine.

REMARK 3.6. When the metric is positive definite, Proposition 3.3 and Corollary 3.4 for non-affine infinitesimal projective transformation were stated by K. Yano and T. Nagano in [10] without the condition that the set of points where φ is non-affine is dense in M .

Proposition 3.5 is a generalization of a result due to T. Sumitomo [5] on Riemannian manifolds.

§ 4. Ricci-curvature-tensor-preserving projective transformations.

First we remark that a projective transformation leaves the Ricci curvature tensor invariant if and only if it leaves the Riemannian curvature tensor invariant. In fact, each condition is equivalent to $(\nabla_x p)(Y) = p(X)p(Y)$ in

(1.5) and (1.6).

PROPOSITION 4.1. *Let M and N be irreducible pseudo-Riemannian manifolds and assume that the signature (r, s) of g satisfies $r \neq s$. Then any projective transformation of M to N which leaves the Ricci curvature tensors invariant is a homothety, or anti-homothety.*

Especially, further, if both Ricci curvature tensors of M and N vanish, then any projective transformation is a homothety, or anti-homothety.

PROOF. Since the restricted holonomy group of M is irreducible, it has no invariant covector. By S. Ishihara's result ([1], p. 209) any Ricci-curvature-tensor-preserving projective transformation is affine. So if we apply Proposition 2.1, then the proof is completed.

§ 5. ∇C -preserving conformal transformations.

An analogous proposition to Proposition 3.3 is as follows.

PROPOSITION 5.1. *Let (M, g) and $(N, 'g)$ be pseudo-Riemannian manifolds ($m \geq 4$). If there is a conformal transformation φ of M to N which leaves the covariant derivatives of the Weyl conformal curvature tensors invariant and if the set of points where φ is non-homothetic is dense in M , then we have $C=0$ and, M and N are conformally flat.*

PROOF. By ${}^{\varphi}C=C$ and ${}^{\varphi}(\nabla' C)=\nabla C$, we have ${}^{\varphi}E=E$. Then by Lemma 1.3 we get $d\alpha(C(Z, X, Y))=0$, and this also implies $C(\text{grad } \alpha, X, Y)=0$. If we apply (1.3) to C , then we get

$$0 = W_{\nu}(C(Z, X, Y)) - C(W_{\nu}Z, X, Y) - C(Z, W_{\nu}X, Y) - C(Z, X, W_{\nu}Y).$$

Using (1.10) and above relations, we get

$$(5.1) \quad 0 = 2(V\alpha)C(Z, X, Y) + g(V, C(Z, X, Y)) \text{grad } \alpha \\ + (Z\alpha)C(V, X, Y) + (X\alpha)C(Z, V, Y) + (Y\alpha)C(Z, X, V).$$

Taking the inner product with U we get

$$(5.2) \quad 0 = 2(V\alpha)g(U, C(Z, X, Y)) + (U\alpha)g(V, C(Z, X, Y)) \\ + (Z\alpha)g(U, C(V, X, Y)) + (X\alpha)g(U, C(Z, V, Y)) \\ + (Y\alpha)g(U, C(Z, X, V)).$$

If $d\alpha \neq 0$ at x of M , then we can take a basis (e_1, \dots, e_m) of M_x and the dual basis (w^1, \dots, w^m) at x such that $w^1 = d\alpha$. In the following calculation we read $(V\alpha) = d\alpha(V)$, etc.

If we put $V = e_1, X = e_j, Y = e_k, Z = e_l, U = e_i$ in (5.2), then we have $g(e_i, C(e_l, e_j, e_k)) = 0$ for $i, j, k, l \neq 1$.

If we put $V = U = e_1, X = e_j, Y = e_k, Z = e_l$ in (5.2), we get $g(e_1, C(e_l, e_j, e_k))$

$= 0$ for $j, k, l \neq 1$.

If we put $V = U = X = e_1, Y = e_k, Z = e_l$ in (5.2), then we have $g(e_1, C(e_l, e_1, e_k)) = 0$ for $k, l \neq 1$.

Thus we have $g(U, C(Z, X, Y)) = 0$ at x for any U, Z, X , and Y , and we get $C = 0$ at x . Since the set of points x such that $(d\alpha)_x \neq 0$ is dense in M , we have $C = 0$ on M .

COROLLARY 5.2. *Suppose that a pseudo-Riemannian manifold $M(m \geq 4)$ is conformally non-flat on any open set in M . Then any conformal transformation of M to another N which preserves the covariant derivatives of the Weyl conformal curvature tensors is a homothety.*

PROPOSITION 5.3. *Let $M(m \geq 4)$ be an irreducible locally symmetric pseudo-Riemannian manifold of signature $(r, s), r \neq s$. Then we have either*

- (i) M is of constant curvature, or
- (ii) M does not admit any non-homothetic conformal transformation.

PROOF. By local symmetry of M we have $\nabla R = 0$ and $\nabla C = 0$. If C is not trivial at some point, then it is not trivial anywhere. So we have (ii). Otherwise we have $C = 0$ on M , and so if we show the next Lemma, we get (i).

LEMMA 5.4. *If an irreducible pseudo-Riemannian manifold (M, g) has signature (r, s) satisfying $r \neq s$ and has parallel Ricci curvature tensor, then it is an Einstein space.*

In fact, if we define a $(1, 1)$ -tensor A by $R_1(X, Y) = g(X, AY)$, then by the same argument as in [6] we have $A = aI$, where a is constant since g and R_1 are parallel. Therefore M is an Einstein space.

REMARK 5.5. Proposition 5.1 (as well as Corollary 5.2) for a Riemannian manifold was first stated by K. Yano and T. Nagano [10] for a non-homothetic infinitesimal conformal transformation without specifying that the set of points where φ is non-homothetic is dense in M . We give an example in the last section which shows that this condition is necessary.

REMARK 5.6. Proposition 5.3 is a generalization of T. Sumitomo's result [5] on Riemannian manifolds.

§ 6. Ricci-curvature-tensor-preserving conformal transformations.

As in the case of a projective transformation, a conformal transformation leaves the Ricci curvature tensor invariant if and only if it leaves the Riemannian curvature tensor invariant.

Now we prove

PROPOSITION 6.1. *Let $(M, g)(m \geq 3)$ be a pseudo-Riemannian manifold such that the Riemannian connection is complete. Then any Ricci-curvature-tensor-preserving conformal transformation of (M, g) to another $(N, 'g)$ is a homothety.*

PROOF. By $\varphi R_1 = R_1$, we have $\varphi R = R$ and $F = 0$:

$$(6.1) \quad \nabla d\alpha - d\alpha \otimes d\alpha + 2^{-1}g(\text{grad } \alpha, \text{grad } \alpha)g = 0.$$

If $\text{grad } \alpha$ is a null vector field everywhere, then we have $\nabla d\alpha = d\alpha \otimes d\alpha$. Since ∇ is complete, we have $d\alpha = 0$ by S. Ishihara's Lemma ([1], p. 210). If $\text{grad } \alpha$ is not a null vector at some point x of M , then we apply the argument of S. Ishihara's Lemma ([1], p. 216). Transvecting (6.1) with $\text{grad } \alpha$, we have

$$(6.2) \quad 2\nabla_{\text{grad } \alpha} \text{grad } \alpha = g(\text{grad } \alpha, \text{grad } \alpha) \text{grad } \alpha.$$

This implies that each trajectory of $\text{grad } \alpha$ is a geodesic. So we take a trajectory $x(t)$ of $\text{grad } \alpha$ passing through x . Since $\text{grad } \alpha$ is not null at x , we can assume that the parameter t is the arc-length parameter. Consider a function λ defined by

$$\lambda^2 = \varepsilon g(\text{grad } \alpha, \text{grad } \alpha) = |\text{grad } \alpha|^2$$

on $x(t)$ such that $\lambda > 0$ at x , ε being the sign of $g(\text{grad } \alpha, \text{grad } \alpha)$. Let $X = (\text{grad } \alpha)/\lambda$ in the domain where $\lambda > 0$. Then we have

$$\begin{aligned} 2\lambda d\lambda/dt &= \varepsilon \nabla_X (g(\text{grad } \alpha, \text{grad } \alpha)) \\ &= \varepsilon 2(1/\lambda)g(\text{grad } \alpha, \nabla_{\text{grad } \alpha} \text{grad } \alpha) \\ &= \varepsilon(1/\lambda)(g(\text{grad } \alpha, \text{grad } \alpha))^2 \quad \text{by (6.2)}. \end{aligned}$$

Thus we have $2d\lambda/dt = \varepsilon\lambda^2$ and $\lambda = -2\varepsilon/(t-c)$ for some constant c . Now notice that the arc-length parameter t for a non-light-like geodesic is also an affine parameter (in our case we have $\nabla_{\text{grad } \alpha} ((\text{grad } \alpha)/\lambda) = 0$). By completeness of the Riemannian connection, λ^2 must be defined for $t = c$. But this is impossible, namely, we have $\lambda = 0$ everywhere, and α must be constant on M .

§ 7. Examples.

EXAMPLE 7.1. *There exist projectively non-flat differentiable manifolds (M, ∇) and (N, ∇') with symmetric connections and symmetric Ricci tensors, such that they admit a non-affine projective transformation which maps ∇P into $\nabla' P$.*

Let M be a sphere with the natural metric g^* . The Riemannian connection ∇^* is symmetric and the Ricci tensor R^* is also symmetric. Since g^* is of constant curvature, (M, ∇^*) is projectively flat. Take a small open set U^* in M and define a non-constant positive C^∞ -function f^* on M such that f^* takes value 1 outside U^* . Let ∇' be the Riemannian connection defined by f^*g^* . Then we have $\nabla' = \nabla^*$ outside U^* and there is a point x in U^* where ∇' is not projectively flat (because, as is known, any projectively flat Riemannian manifold is of constant curvature, but f^*g^* is not of constant curvature

in U^*). Notice that $'R_1$ is symmetric. Take an open set U outside U^* and take a non-trivial C^∞ -function f on M which vanishes outside U . Then we have a 1-form p defined by $p = df$ on M vanishing outside U . Now define a connection ∇ by

$$\nabla_x Y = ' \nabla_x Y + p(X)Y + p(Y)X.$$

Then ∇ is symmetric and the Ricci curvature tensor R_1 is also symmetric by (1.6), since $'R_1$ is symmetric and p is a derived form. By the way the identity transformation $\varphi : (M, \nabla) \rightarrow (N = M, ' \nabla)$ is projective on M and affine on U^* . Therefore on U^* we have ${}^o(\nabla P) = \nabla P$. Outside U^* we have $'P = P = 0$ and hence ${}^o(\nabla P) = \nabla P$. Since f and p are not trivial, φ is not affine at some point. Moreover, we have $'P = P \neq 0$ at x .

EXAMPLE 7.2. *There exists a Riemannian manifold which is not conformally flat and which admits a non-homothetic (infinitesimal) conformal transformation which leaves the covariant derivative of the Weyl conformal curvature tensor invariant.*

A simple example is constructed on an odd dimensional sphere $M = S^{2n+1}$. Since M admits a Sasakian structure, namely, a normal contact metric structure, we denote the structure tensors by (ϕ, ξ, η, g) where ξ is a unit Killing vector field with respect to the metric g induced from that in E^{2n+2} (cf. [4]). Let x be an arbitrary point of M and take two small neighborhoods U and V such that the closure of U is contained in V . Since ξ generates a 1-parameter group of isometries $\exp t\xi$, we have a great circle $(\exp t\xi \cdot x; 0 \leq t < 2\pi)$ and its tubular neighborhoods $*U = (\exp t\xi \cdot U; 0 \leq t < 2\pi)$ and $*V = (\exp t\xi \cdot V; 0 \leq t < 2\pi)$. We define a non-negative C^∞ -function f on M such that

- (i) f is invariant by $\exp t\xi$,
- (ii) $f = 1$ on $*U$,
- (iii) $f = 0$ outside $*V$.

Now we define a new metric $*g$ on M for a constant $\alpha > 1$ by

$$(7.1) \quad *g = g + (\alpha - 1)f(g + \alpha\eta \otimes \eta).$$

Then $*g$ on $*U$ is $\alpha g + (\alpha^2 - \alpha)\eta \otimes \eta$, and this is an associated Riemannian metric with respect to another Sasakian structure on $*U$. But $*g$ on $*U$ is not of constant curvature (cf. [8]). On the other hand, if the associated Riemannian metric of a Sasakian structure is conformally flat, then it is of constant curvature ([3], [7]). Therefore $*g$ is not conformally flat on $*U$. Since ξ leaves η invariant too, by (7.1) ξ is a Killing vector field also with respect to $*g$. Next we take a small open set W outside $*V$ and define a positive C^∞ -function h such that

- (iv) there is a point y in W where $h(y) \neq 1$, and
- (v) for any z outside W we have $h(z) = 1$.

Then the metric G defined by $G = h^*g$ is the one required. Namely, we have

- (vi) G is not conformally flat (on $*U$).
- (vii) M admits an infinitesimal conformal transformation ξ which is a Killing vector field with respect to G outside W and which is non-homothetic on some open set in W , since $L_\xi G = (L_\xi h)(1/h)G$.
- (viii) The covariant derivative ∇C of the Weyl conformal curvature tensor may be non-vanishing only in $*V$. Since ξ is a Killing vector field on $*V$ we have $L_\xi \nabla C = \nabla L_\xi C = 0$ on $*V$ and hence on M .

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