

## A CONFORMAL TRANSFORMATION OF CERTAIN CONTACT RIEMANNIAN MANIFOLDS

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1. For any contact manifold  $M$  with a contact form  $\eta$ , we can find an associated Riemannian metric  $g$ , a (1.1)-tensor  $\phi$  and a unit vector field  $\xi$  such that  $\phi, \xi, \eta$  and  $g$  are the tensors of a contact metric structure. They satisfy the following relations:

- (1. 1)  $\phi\xi=0, \quad \eta(\xi)=1, \quad \phi^2X=-X+\eta(X)\cdot\xi,$
- (1. 2)  $\eta(X)=g(\xi, X), \quad g(\phi X, \phi Y)=g(X, Y)-\eta(X)\eta(Y),$
- (1. 3)  $d\eta(X, Y)=2g(X, \phi Y)=2\omega(X, Y)$

for any vector fields  $X$  and  $Y$  on  $M$ . A contact structure is said to be regular if the distribution defined by  $\xi$  is regular. A contact metric structure is a  $K$ -contact metric structure if  $\xi$  is a Killing vector field, and furthermore it is a normal contact metric one if the following relation is satisfied

$$(\nabla_Z\omega)(X, Y) = \eta(X)g(Z, Y) - \eta(Y)g(Z, X)$$

for any vector fields  $X, Y$  and  $Z$  on  $M$ , where  $\nabla$  denotes the Riemannian connection by  $g$ . For the details see [4], [6] and [7].

In this note we prove the following

**THEOREM.** *In a compact, connected, regular and normal contact Riemannian  $m(> 3)$ -dimensional manifold  $M$ , if  $M$  admits a non-isometric conformal transformation, then  $M$  is isometric with a unit sphere.*

In this direction, M. Okumura [5] proved the following

(A) Let  $M$  be a complete, normal contact Riemannian  $m(> 3)$ -dimensional connected manifold. If it admits a non-isometric infinitesimal conformal transformation, then  $M$  is isometric with a unit sphere.

Denote by  $C(M)$  or  $I(M)$  the groups of conformal transformations or isometries of  $M$ , and by  $C_0(M)$  or  $I_0(M)$  their identity components. To prove our Theorem, it is enough to verify the following

PROPOSITION. *In a compact, connected, regular K-contact Riemannian manifold  $M$ , suppose that  $C_0(M)=I_0(M)$ . Then we have  $C(M)=I(M)$ .*

In fact, assume that  $M$  is not isometric with a unit sphere, then by (A)  $M$  does not admit any non-isometric infinitesimal conformal transformation, i.e.  $C_0(M)=I_0(M)$ . By this proposition we have  $C(M)=I(M)$ , this means that  $M$  does not admit any non-isometric conformal transformation.

**2. Proof of the Proposition.** In a  $K$ -contact Riemannian manifold, the Riemannian curvature tensor  $R$  satisfies the identity (see [2]):

$$(2. 1) \quad g(R(X, \xi)Y, \xi) = g(X, Y) - \eta(X) \cdot \eta(Y)$$

for any vector fields  $X$  and  $Y$  on  $M$ , where

$$-R(X, \xi)Y = \nabla_X \nabla_\xi Y - \nabla_\xi \nabla_X Y - \nabla_{[X, \xi]} Y.$$

Let  $\varphi$  be a conformal transformation, then we have  $\varphi^*g = \sigma g$  for some scalar function  $\sigma$ . As  $\xi$  is a Killing vector field, it generates a 1-parameter group of isometries  $\phi_t$  of  $M$ . Then, denoting by  $\varphi$  also the differential of  $\varphi$ ,  $\varphi\xi$  and  $\varphi^{-1}\xi$  generate  $\varphi \cdot \phi_t \cdot \varphi^{-1}$  and  $\varphi^{-1} \cdot \phi_t \cdot \varphi$  respectively (see p.7, [3]). By the fact that  $\varphi \cdot \phi_t \cdot \varphi^{-1}$  and  $\varphi^{-1} \cdot \phi_t \cdot \varphi$  are conformal transformations and by the assumption that  $C_0(M)=I_0(M)$ ,  $\varphi\xi$  and  $\varphi^{-1}\xi$  are Killing vector fields. If one operates the Lie derivation  $L(\xi)$  to  $\sigma g = \varphi^*g$ , one gets

$$\begin{aligned} (L(\xi)\sigma)g &= L(\xi)(\varphi^*g) \\ &= \lim_{t \rightarrow 0} \left( \frac{1}{t} \right) (\varphi^* \varphi^{-1*} \phi_t^* \varphi^* g - \varphi^* g) \\ &= \varphi^*(L(\varphi\xi)g) = 0, \end{aligned}$$

since  $(\varphi \cdot \phi_t \cdot \varphi^{-1})^* = \varphi^{-1*} \cdot \phi_t^* \cdot \varphi^*$ . This shows that  $L(\xi)\sigma = 0$ . As for the Lie derivation  $L(\varphi^{-1}\xi)$ , we have  $L(\varphi^{-1}\xi)\sigma = 0$ .

On the other hand, as  $\varphi$  is a conformal transformation, the Riemannian curvature teneor  ${}^pR$  of  $\varphi^*g$  is given by the relation:

$$\begin{aligned} (2. 2) \quad {}^pR^i{}_{jkl} &= R^i{}_{jkl} + \delta_k^i (\nabla_j \alpha_l - \alpha_j \alpha_l) - \delta_l^i (\nabla_j \alpha_k - \alpha_j \alpha_k) \\ &\quad + (\nabla_k \alpha^l - \alpha_k \alpha^l) g_{jl} - (\nabla_l \alpha^k - \alpha_l \alpha^k) g_{jk} \\ &\quad + \alpha_r \alpha^r (\delta_k^i g_{jl} - \delta_l^i g_{jk}) \end{aligned}$$

in a local coordinate neighborhood, where  $\alpha = (1/2) \log \sigma$  and  $\alpha_k = \partial_k \alpha$ . As  $M$  is compact, there exists a point  $x$  of  $M$  where  $\sigma$  takes the maximum. Then at  $x$  we have  $d\alpha = 0$  namely  $\alpha_k = 0$ . Let  $y$  be the point  $\varphi x$ , then by (2.1) we have

$$(2.3) \quad \begin{aligned} g_y(R(\varphi\xi, \xi)\varphi\xi, \xi) &= g_y(\varphi\xi, \varphi\xi) - [\eta_y(\varphi\xi)]^2 \\ &= \sigma_x - [\eta_y(\varphi\xi)]^2. \end{aligned}$$

Transvecting (2.2) with  $\xi^k(\varphi^{-1}\xi)^i\xi^j$ , we have

$$g_x({}^pR(\xi, \varphi^{-1}\xi)\xi, \varphi^{-1}\xi) = g_x(R(\xi, \varphi^{-1}\xi)\xi, \varphi^{-1}\xi),$$

where we have utilized  $\alpha_k|_x=0$ ,  $\xi^k\nabla_j\alpha_k|_x = -(\nabla_j\xi^k)\alpha_k|_x=0$  since  $\xi^k\alpha_k=0$ , and similar relation  $(\varphi^{-1}\xi)^k\nabla_j\alpha_k|_x=0$ . Thus we have

$$(2.4) \quad \begin{aligned} g_y(R(\varphi\xi, \xi)\varphi\xi, \xi) &= g_y(\varphi[\varphi^{-1}\cdot R(\varphi\xi, \xi)\varphi\xi], \varphi\varphi^{-1}\xi) \\ &= \sigma_x g_x({}^pR(\xi, \varphi^{-1}\xi)\xi, \varphi^{-1}\xi) \\ &= \sigma_x g_x(R(\xi, \varphi^{-1}\xi)\xi, \varphi^{-1}\xi) \\ &= \sigma_x g_x(\varphi^{-1}\xi, \varphi^{-1}\xi) - \sigma_x [\eta_x(\varphi^{-1}\xi)]^2 \\ &= 1 - \sigma_x [\eta_x(\varphi^{-1}\xi)]^2. \end{aligned}$$

However we have

$$\eta_y(\varphi\xi) = g_y(\xi, \varphi\xi) = (\varphi^*g)_x(\varphi^{-1}\xi, \xi) = \sigma_x \eta_x(\varphi^{-1}\xi).$$

Therefore by (2.3) and (2.4), we get

$$(2.5) \quad (\sigma_x - 1)(1 - \sigma_x [\eta_x(\varphi^{-1}\xi)]^2) = 0.$$

Hence  $\sigma_x=1$  or  $1 = \sigma_x [\eta_x(\varphi^{-1}\xi)]^2$  holds good. Suppose that  $[\eta_x(\varphi^{-1}\xi)]^2 = \sigma_x^{-1}$  holds, then as  $g_x(\varphi^{-1}\xi, \varphi^{-1}\xi) = \sigma_x^{-1}$ , by (1.2)<sub>2</sub> we see that  $\varphi_y^{-1}\xi_y$  is proportional to  $\xi_x$ . Let  $l(x)$  be the leaf of  $\xi$  which passes through  $x$ , then  $\varphi l(x)$  is the leaf  $l(y)$  which passes through  $y$ . While each leaf of  $\xi$  is of the same length in a regular contact manifold ([1], [9]). But the relation  $L(\xi)\sigma=0$  implies that  $\sigma$  is constant on  $l(x)$ , and hence  $\sigma=1$  holds on  $l(x)$ . Thus (2.5) shows that  $\sigma=1$  on  $l(x)$ , and as  $\sigma_x$  is the maximum,  $\sigma=1$  must hold on  $M$ . This completes the proof.

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