**Tôhoku Math. Journ.** 27 (1975), 515-559.

## ON SOME TYPES OF ISOPARAMETRIC HYPERSURFACES IN SPHERES I

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(Received August 6, 1974)

1. Introduction. We shall exhibit two series of non-homogeneous isoparametric hypersurfaces in spheres in this paper, and then give a classification of some types of isoparametric hypersurfaces in a forthcoming paper.

We begin with a few definitions and notations to explain our results more precisely. Let  $\overline{M}$  be a Riemannian manifold with metric (,). The induced inner product on cotangent vectors is also denoted by (,). A differentiable function f defined on an open set U in  $\overline{M}$  is called *isoparametric* if  $df \wedge d(df, df) = 0$  and  $df \wedge d(\Delta f) = 0$ , where  $\Delta$  denotes the Laplacian on  $\overline{M}$ . A hypersurface M (a submanifold of codim 1) in  $\overline{M}$  is called *isoparametric* if, for each point p of M, there exist an open neighborhood U of p in  $\overline{M}$  and an isoparametric function f defined on Usuch that

$$U \cap M = \{q \in U \mid f(q) = f(p)\}$$
.

Let  $\mathscr{I} = \{M_t \mid t \in I\}$  be a family of hypersurfaces in  $\overline{M}$  parametrized by an open interval I.  $\mathscr{I}$  is called a family of isoparametric hypersurfaces if there exist an open set U in  $\overline{M}$  and an isoparametric function f on Usuch that  $M_t = f^{-1}(t)$  for each  $t \in I$ . Two families  $\mathscr{I} = \{M_t \mid t \in I\}$  and  $\mathscr{I}' = \{M'_{t'} \mid t' \in I'\}$  of isoparametric hypersurfaces in  $\overline{M}$  are identified if there exists a diffeomorphism  $\varphi$  of I onto I' such that  $M_t = M'_{\varphi(t)}$  for each  $t \in I$ . Also, if we have an imbedding  $\varphi$  of I into I' such that  $M_t \subset M'_{\varphi(t)}$  for each  $t \in I$ , then we write  $\mathscr{I} \subset \mathscr{I'}$ .

Now, let  $\overline{M} = S^{N-1}$  be the unit sphere in an N-dimensional Euclidean space  $\mathbb{R}^N$  centered at the origin, and M a locally closed hypersurface in  $\overline{M}$ . M is said to be homogeneous if a suitable subgroup of O(N) acts transitively on M where O(N) denotes the real orthogonal group of  $\mathbb{R}^N$ . It is known that M is isoparametric if and only if M has locally constant principal curvatures (Cartan [2]). Thus, every homogeneous hypersurface in  $S^{N-1}$  is isoparametric. Two hypersurfaces M and M' in  $S^{N-1}$  are said to be equivalent if a suitable orthogonal transformation of  $\mathbb{R}^N$  transforms M onto M'. Similarly, two families of isoparametric hypersurfaces in  $S^{N-1}$  are equivalent if a suitable orthogonal transformation of  $\mathbb{R}^N$  transforms one to the other.

The following results are due to Münzner [5]. For every connected isoparametric hypersurface M in  $S^{N-1}$ , there exists a unique maximal (relative to the above order  $\subset$ ) family  $\mathscr{I}_{M} = \{M_{t} \mid t \in I\}$  of isoparametric hypersurfaces in  $S^{N-1}$  such that each  $M_{t}$  is closed in  $S^{N-1}$  and for some t M is an open submanifold of  $M_{t}$ . If M and M' are equivalent, then  $\mathscr{I}_{M}$  and  $\mathscr{I}_{M}$ , are equivalent in our sense. Further the classification problem of such maximal families is reduced to an algebraic one in the following way. Let F be a homogeneous polynomial function of degree g on  $\mathbb{R}^{N}$ . For g > 2, let  $m_{1}$  and  $m_{2}$  be positive such that  $m_{1} + m_{2} + m_{1} +$  $m_{2} + \cdots = N - 2$ , and let  $m_{1} = N - 2 > 0$  for g = 1. Assume F satisfies

(M) 
$$\begin{cases} (dF, dF) = g^2 r^{2g-2} \\ \Delta F = c r^{g-2} \end{cases}$$

where  $c = (1/2)(m_2 - m_1)g^2$  for  $g \ge 2$  and c = 0 for g = 1 and where r is the radius function and  $\Delta$  is the Laplacian on  $\mathbb{R}^N$ . Then the restriction f of F to  $S^{N-1}$  is isoparametric on  $S^{N-1}$ , and  $\mathscr{I}_F = \{M_t = f^{-1}(t) \mid t \in (-1, 1)\}$ is a maximal family of isoparametric hypersurfaces in  $S^{N-1}$  such that each  $M_t$  is connected and closed. Conversely, any maximal family of isoparametric hypersurfaces in  $S^{N-1}$  is given in the above way. Such two families  $\mathscr{I}_F$  and  $\mathscr{I}_F$ , are equivalent if and only if there exists an element  $\sigma$  in O(N) such that

$$F(\sigma^{\scriptscriptstyle -1} x) = \pm F'(X) \qquad x \in I\!\!R^N$$
 .

In this case, F and F' are said to be *equivalent*. Münzner also has shown that the above (M) has a solution only if g = 1, 2, 3, 4 or 6 and that  $m_1 = m_2$  if g is 3.

Geometrically, the above integers g,  $m_1$  and  $m_2$  are related to each isoparametric hypersurface  $M_i$  as follows. Consider the unit normal vector field  $X_i = \operatorname{grad}(f)/(df, df)^{1/2}$  for each  $M_i$ . Let

$$k_1(t) > \cdots > k_{g(t)}(t)$$

be the distinct principal curvatures of  $M_i$  relative to  $X_i$ , and  $m_j(t)$  the multiplicity of  $k_j(t)$  for each j. Then g(t) and  $m_j(t)$  are constant, and we have

$$egin{aligned} g &= g(t) \;, \ m_1 &= m_1(t) = m_3(t) = \; \cdots \;, \ m_2 &= m_2(t) = \; m_4(t) = \; \cdots \;, \ k_j(t) &= \; \cot \left( rac{1}{g} \left\{ (j - 1) \pi \, + \, \cos^{-1}(t) 
ight\} 
ight) \end{aligned}$$

for  $j = 1, 2, \dots, g$ .

We come to the problem of classifying equivalent classes of polynomials F satisfying the above condition (M). In the case where g = 1 or g = 2 it is easy. Cartan solved it in the case g = 3 ([3]) and proposed a problem: Is every closed isoparametric hypersurface in  $S^{N-1}$  homogeneous? Recently, Takagi [6] classified the case where g = 4 and  $m_1$  or  $m_2 = 1$ , and his result still shows that the obtained ones are homogeneous.

In the present paper I, we shall investigate a homogeneous polynomial function F satisfying the differential equations (M) of Münzner in the case g = 4. To such an F, we associate  $m_1 + 1$  quadratic forms  $\{p_{\alpha}\}$  and  $m_1 + 1$  cubic forms  $\{q_{\alpha}\}$  in  $m_1 + 2m_2$  variables, and give a complete characterization of F in terms of  $\{p_{\alpha}\}$  and  $\{q_{\alpha}\}$  in Theorem 1. Using this, two series of non-homogeneous isoparametric hypersurfaces in spheres will be constructed in Theorem 2.

The polynomial functions F defining them are given explicitly as follows. We denote by F the real quaternion algebra H or the real Cayley algebra K, and by  $u \rightarrow \overline{u}$  the canonical involution of F. For the *n*-column vector space  $F^n$  over F, the canonical inner product is denoted by (,). For each positive integer r, the space  $F^{2(r+1)}$  can be identified with  $\mathbb{R}^N$  where N = 8(r+1) or 16(r+1). For a point  $x = u \times v \in F^{r+1} \times$  $F^{r+1} = F^{2(r+1)}$ , we set

$$u=egin{pmatrix}u_{\scriptscriptstyle 0}\u_{\scriptscriptstyle 1}\end{pmatrix}$$
 ,  $v=egin{pmatrix}v_{\scriptscriptstyle 0}\v_{\scriptscriptstyle 1}\end{pmatrix}$ 

where  $u_0, v_0 \in F, u_1, v_1 \in F^r$ . Then we put

$$F_{0}(u \times v) = 4\{||\ {}^{t}u \overline{v} \, ||^{2} - (u, v)^{2}\} + \{||\ u_{1} \, ||^{2} - ||\ v_{1} \, ||^{2} + 2(u_{0}, v_{0})\}^{2}$$

where || || denotes the length of a vector, and

$$F=r^{\scriptscriptstyle 4}-2F_{\scriptscriptstyle 0}$$
 .

Then  $M_t = \{x \in S^{N-1} | F(x) = t\}$  for each t in (-1, 1) is isoparametric and its multiplicities  $m_1$  and  $m_2$  are given by

$$m_1 = 3$$
 and  $m_2 = 4r$ 

or

$$m_{\scriptscriptstyle 1}=7$$
 and  $m_{\scriptscriptstyle 2}=8r$ 

respectively according to F = H or K.

The homogeneous isoparametric hypersurfaces in spheres have been classified by Hsiang-Lawson [4]. In Part II, we shall give an explicit form of F for each of them, and classify the polynomials F satisfying

the condition (M) in the case where g = 4 and  $m_1$  or  $m_2 = 2$ . It will be shown that every closed isoparametric hypersurface in this case is homogeneous.

We thank Prof. T. Takahashi and Prof. R. Takagi for many helpful discussions.

2. Preliminaries. First we introduce a few notations for operations on polynomial functions and give some of their elementary properties. These notations and properties will be used consistently throughout our papers I and II.

Let  $\mathbb{R}^n$  be an *n*-dimensional Euclidean space with inner product (,) and *r* the radius function of  $\mathbb{R}^n$ . The induced inner product on the dual space is also denoted by (,). For any polynomial functions *f* and *g* on  $\mathbb{R}^n$ , we denote by  $\langle f, g \rangle$  the polynomial function on  $\mathbb{R}^n$  defined by

$$(2.1) \qquad \langle f, g \rangle(x) = ((df)_x, (dg)_x) \qquad x \in \mathbb{R}^n.$$

The mapping  $(f, g) \rightarrow \langle f, g \rangle$  is bilinear and symmetric, and also satisfies

(2.2) 
$$\langle f, g_1g_2 \rangle = \langle f, g_1 \rangle g_2 + \langle f, g_2 \rangle g_1$$
.

Let  $\{x_1, \dots, x_n\}$  be an orthonormal coordinate system for  $\mathbb{R}^n$ . Then  $\langle f, g \rangle$  is equivalently defined by

(2.3) 
$$\langle f, g \rangle = \sum_{i=1}^{n} \frac{\partial f}{\partial x_i} \frac{\partial g}{\partial x_i}.$$

Especially, for a homogeneous polynomial f of degree k on  $\mathbb{R}^n$ , and for any positive integer l we have

$$(2.4) \qquad \langle r^{2l}, f \rangle = 2k l f r^{2(l-1)}$$

We denote by  $\varDelta$  the Laplacian on  $\mathbb{R}^n$ , that is,

(2.5) 
$$\Delta = \sum_{i=1}^{n} \frac{\partial^2}{(\partial x_i)^2} \,.$$

Then, for any positive integer k, we have

$$(2.6) \qquad \qquad \Delta r^{2k} = 2k(n+2k-2)r^{2(k-1)}$$

Let V be a linear subspace of  $\mathbb{R}^n$ . We introduce the restriction forms of  $\langle , \rangle$  and  $\varDelta$  as follows. Let W be the orthogonal complement of V so that we have  $\mathbb{R}^n = V \bigoplus W$  (orthogonal decomposition). Choose orthonormal coordinate systems  $\{v_i\}$  and  $\{w_j\}$  for V and W respectively. Then any polynomial functions f and g on  $\mathbb{R}^n$  can be expressed as polynomials in variables  $\{v_i\}$  and  $\{w_j\}$ . We put

(2.7) 
$$\langle f, g \rangle_{v} = \sum_{i} \frac{\partial f}{\partial v_{i}} \frac{\partial g}{\partial v_{i}}$$

and

They are determined independently on the choices of coordinate systems, and sometimes they will be also denoted by  $\langle f, g \rangle_{\{v_i\}}$  and  $\mathcal{A}_{\{v_i\}}f$ . From the definitions it follows that, for an arbitrary orthogonal decomposition  $\mathbf{R}^n = \mathbf{V} \bigoplus \mathbf{W}$ , we have

(2.9) 
$$\langle f, g \rangle = \langle f, g \rangle_{v} + \langle f, g \rangle_{w}$$

and

$$(2.10) \qquad \qquad \Delta f = \Delta_v f + \Delta_w f \,.$$

Let f be a polynomial function on  $\mathbb{R}^n$ , and V a linear subspace of  $\mathbb{R}^n$ . f is said to be homogeneous of degree k on V if f is homogeneous of degree k with respect to the variables  $\{v_i\}$  in the expression of f as a polynomial in  $\{v_i\}$  and  $\{w_j\}$ .

Let V be a linear subspace of  $\mathbb{R}^n$ . Every polynomial function f on V can be considered also as a polynomial function on  $\mathbb{R}^n$  canonically through the orthogonal decomposition  $\mathbb{R}^n = V \bigoplus W$ . By this identification, it follows that for polynomial functions f and g on V we have

$$(2.11) \qquad \qquad \langle f, g \rangle_v = \langle f, g \rangle$$

and

Finally, for a quadratic form f on  $\mathbb{R}^n$ , we define a symmetric linear mapping  $\eta(f)$  of  $\mathbb{R}^n$  by

(2.13) 
$$(\eta(f)(x), x') = f(x, x')$$
  $x, x' \in \mathbb{R}^n$ 

where f is considered in the usual way as a symmetric bilinear form on  $\mathbb{R}^n$ . The correspondence  $f \to \eta(f)$  is one to one from the set of quadratic forms on  $\mathbb{R}^n$  onto the set of symmetric linear mappings of  $\mathbb{R}^n$ .

For quadratic forms f and g on  $\mathbb{R}^n$ , we have

(2.14) 
$$\eta(\langle f, g \rangle) = 2(\eta(f)\eta(g) + \eta(g)\eta(f)),$$

and especially

(2.15) 
$$\eta(\langle f, f \rangle) = 4(\eta(f))^2$$
.

Furthermore, we have

(2.16) 
$$\Delta f = 2 \operatorname{Tr} (\eta(f))$$

They can be verified easily.

Now, let  $S^{N-1}$  be the unit sphere in  $\mathbb{R}^N$  centered at the origin. We need the following preliminary lemmas.

LEMMA 1. Let F be a homogeneous polynomial function of degree g on  $\mathbb{R}^{N}$  satisfying

$$\langle F,\,F
angle=g^{_2}r^{_{^{2g-2}}}$$
 .

Then the restriction f of F to  $S^{N-1}$  is singular at a point x of  $S^{N-1}$  if and only if

$$(dF)_x = \pm (dr^g)_x$$
.

PROOF. By definition, f is singular at x if and only if  $(df)_x = 0$ . Note that a tangent vector X in  $T_x(\mathbb{R}^n)$  is contained in  $T_x(S^{N-1})$  if and only if

$$(dr^g)_x(X)=0.$$

Thus,  $(df)_x = 0$  if and only if

$$(dF)_x = c(dr^g)_x$$

for some constant c. Since  $(dF, dF) = \langle F, F \rangle = (dr^{g}, dr^{g})$  from our assumption, we see that  $(df)_{x} = 0$  if and only if

$$(dF)_x = \pm (dr^g)_x$$
. q.e.d.

LEMMA 2. Let F be as in Lemma 1. Then the restriction f of F to  $S^{N-1}$  ranges from -1 to 1 unless it is constant, and f is singular at a point x of  $S^{N-1}$  if and only if  $F(x) = \pm 1$ .

**PROOF.** Let x be a point of  $S^{N-1}$  and choose an orthonormal coordinate system  $\{u_1, \dots, u_{N-1}, z\}$  such that z(x) = 1 and  $u_i(x) = 0$  for  $i = 1, 2, \dots, N-1$ . We expand F as a polynomial in z as

 $F = a_0 z^g + a_1 z^{g-1} + \cdots + a_g$ 

where  $a_h$  is a homogeneous polynomial of degree h in  $u_1, \dots, u_{N-1}$ . We have

$$(dF)_x = \left(rac{\partial F}{\partial z}
ight)(x)(dz)_x + \sum_{i=1}^{N-1} \left(rac{\partial F}{\partial u_i}
ight)(x)(du_i)_x = ga_0(dz)_x + \sum_{i=1}^{N-1} \left(rac{\partial F}{\partial u_i}
ight)(x)(du_i)_x$$

and

$$(dr^g)_x = g(r^{g-2} r dr)_x = g(dz)_x$$

First suppose that f is singular at x. Then, by Lemma 1 we have  $(dF)_x = \pm (dr^g)_x$ , and hence  $a_0 = \pm 1$ . This shows  $F(x) = a_0 = \pm 1$ .

Conversely, suppose  $F(x) = \pm 1$ , i.e.,  $a_0 = \pm 1$ . We have

Since  $\langle F, F \rangle = g^2 r^{2g-2}$ ,  $\langle F, F \rangle(x) = g^2$ , and hence we have  $(\partial F/\partial u_i)(x) = 0$ for  $i = 1, 2, \dots, N-1$ . Thus, we have  $(dF)_x = \pm (dr^g)_x$ , and hence f is singular at x by Lemma 1.

We have proved the latter assertion in Lemma 2. The former assertion follows from the latter since  $S^{N-1}$  is compact. q.e.d.

LEMMA 3. Let F be as in Lemma 1, and put

$$F = \sum a_{i_1 \cdots i_N} x_1^{i_1} \cdots x_N^{i_N}$$

where  $\{x_1, \dots, x_N\}$  is an orthonormal coordinate system for  $\mathbb{R}^N$ . Assume that the degree g is even and F satisfies

$$F \mid_{x_{k+1} = \dots = x_N = 0} = \left(\sum_{i=1}^k x_i^2\right)^{g/2}$$

Then we have

 $a_{i_1\cdots i_N}=0$ 

whenever  $i_1 + \cdots + i_k = g - 1$ .

**PROOF.** Put  $F = \sum F_h$  where  $F_h$  is the homogeneous part of degree h in the variables  $x_1, \dots, x_k$ :

$$F_h = \sum_{i_1+\cdots+i_k=h} a_{i_1\cdots i_N} x_1^{i_1} \cdots x_N^{i_N}$$
.

The assumption says  $F_g = (\sum_{i=1}^k x_i^2)^{g/2}$ . We shall show  $F_{g-1} = 0$ . Put

$$G=F_{g-2}+\cdots+F_{0}$$
 ,

so that we have

$$F=F_g+F_{g-1}+G.$$

Now, we have

$$\frac{\partial F}{\partial x_i} = g x_i \left(\sum_{i=1}^k x_i^2\right)^{(g/2)-1} + \frac{\partial F_{g-1}}{\partial x_i} + \frac{\partial G}{\partial x_i}$$

for  $i = 1, \dots, k$ , and

$$\frac{\partial F}{\partial x_j} = \frac{\partial F_{g-1}}{\partial x_j} + \frac{\partial G}{\partial x_j}$$

for  $j = k + 1, \dots, N$ , and hence

$$\begin{split} \langle F, F \rangle &= \sum_{i=1}^{k} \left( \frac{\partial F}{\partial x_{i}} \right)^{2} + \sum_{j=k+1}^{N} \left( \frac{\partial F}{\partial x_{j}} \right)^{2} \\ &= \sum_{i=1}^{k} \left\{ g^{2} x_{i}^{2} \left( \sum_{i=1}^{k} x_{i}^{2} \right)^{g-2} + \left( \frac{\partial F_{g-1}}{\partial x_{i}} \right)^{2} + \left( \frac{\partial G}{\partial x_{i}} \right)^{2} \\ &+ 2g x_{i} \left( \sum_{i=1}^{k} x_{i}^{2} \right)^{(g/2)-1} \left( \frac{\partial F_{g-1}}{\partial x_{i}} + \frac{\partial G}{\partial x_{i}} \right) + 2 \frac{\partial F_{g-1}}{\partial x_{i}} \frac{\partial G}{\partial x_{i}} \right\} \\ &+ \sum_{j=k+1}^{N} \left\{ \left( \frac{\partial F_{g-1}}{\partial x_{j}} \right)^{2} + \left( \frac{\partial G}{\partial x_{j}} \right)^{2} + 2 \frac{\partial F_{g-1}}{\partial x_{j}} \frac{\partial G}{\partial x_{j}} \right\} . \end{split}$$

On the other hand, we have

$$\langle F, \, F 
angle = g^2 r^{2g-2} = g^2 \Big( \sum_{i=1}^k x_i^2 + \sum_{j=k+1}^N x_j^2 \Big)^{g-1}$$
 .

Comparing the homogeneous terms of degree 2g - 2 in the variables  $x_1, \dots, x_k$  in the above two equations, we get

$$\sum_{j=k+1}^{N} \left( \frac{\partial F_{g-1}}{\partial x_j} \right)^2 = 0$$

and hence

$$rac{\partial F_{g-1}}{\partial x_i}=0 \qquad \qquad ext{for } j=k+1,\,\cdots,\,N\,.$$

Since  $F_{g-1}$  is linear in  $x_{k+1}, \dots, x_N$ , we have  $F_{g-1} = 0$ . This proves Lemma 3. q.e.d.

3. Reductions. From now on we shall concern with isoparametric hypersurfaces in  $S^{N-1}$  with 4 distinct principal curvatures. So we investigate a homogeneous polynomial function F of degree 4 on  $\mathbb{R}^N$  satisfying  $\langle F, F \rangle = 16r^6$  and  $\Delta F = 8(m_2 - m_1)r^2$ . These two equations will be replaced by equivalent ones step by step, and in the latter part of this section two families  $\{p_{\alpha}\}$  and  $\{q_{\alpha}\}$  of polynomials will be associated to F on a suitable coordinate system. Our first purpose is to give a complete characterization of such an F in terms of  $\{p_{\alpha}\}$  and  $\{q_{\alpha}\}$  (Theorem 1 in § 4).

Let  $m_1$  and  $m_2$  be two positive integers such that  $N = 2(m_1 + m_2 + 1)$ , and F a homogeneous polynomial function of degree 4 on  $\mathbb{R}^{N}$ . Consider

the following two conditions on F;

(3.1) 
$$\langle F, F 
angle = 16r^{\mathfrak{s}}$$
 ,

(3.2) 
$$\Delta F = 8(m_2 - m_1)r^2.$$

As a first step of reductions, we choose a unit vector e in  $\mathbb{R}^N$  such that the restriction f of F to  $S^{N-1}$  takes its maximum at the point e. Let X be the orthogonal complement of the 1-dimensional subspace Re so that we have

$$(3.3) R^N = X \oplus Re$$

Let z be the coordinate function on Re defined by z(e) = 1 and  $\{x_1, \dots, x_{N-1}\}$  an orthonormal coordinate system for X.

**LEMMA 4.** Assume that F satisfies (3.1) and (3.2). Then, F can be written in the form

$$(3.4) F = z^4 + Az^2 + Bz + C$$

where A, B and C are homogeneous polynomial functions on X of degree 2, 3 and 4 respectively, and A, B and C satisfy the following equations  $(1-1)\sim(1-8)$  listed below. Conversely, assume that a homogeneous polynomial function F of the above form (3.4) is given with A, B and C satisfying  $(1-1)\sim(1-8)$ . Then F satisfies (3.1) and (3.2).

(1-1) 
$$\langle A, A \rangle + 16A = 48 \left( \sum_{i=1}^{N-1} x_i^2 \right)$$

 $(1-2) \qquad \langle A, B \rangle + 4B = 0$ 

(1-3) 
$$\langle B, B \rangle + 2 \langle A, C \rangle + 4A^2 = 48 \left( \sum_{i=1}^{N-1} x_i^2 \right)^2$$

$$(1-4) \qquad \langle B, C \rangle + 2AB = 0$$

(1-5) 
$$\langle C, C \rangle + B^2 = 16 \left(\sum_{i=1}^{N-1} x_i^2\right)^3$$

**PROOF.** Assume that F satisfies (3.1) and (3.2). We first remark that the restriction f of F to  $S^{N-1}$  is not a constant. In fact, suppose that f is a constant c on  $S^{N-1}$ . Then we have  $F = cr^4$ . Since  $\langle F, F \rangle = 16r^6$ , we have  $c = \pm 1$ . On the other hand,

$$arDelta F = c arDelta r^{*} = c(8+4N)r^{2} = 8(m_{2}-m_{1})r^{2}$$
 .

Hence,  $\pm (8 + 4N) = 8(m_2 - m_1)$ . It follows that  $m_1 = -1$  or  $m_2 = -1$ . This is a contradiction.

By Lemma 2, we have F(e) = 1. By the choice of coordinates, we have

$$F \mid_{z_1 = \cdots = z_{N-1} = 0} = (z^2)^2$$
 .

Applying Lemma 3, we see that F has the form

$$F = z^4 + Az^2 + Bz + C$$

where A, B and C are homogeneous polynomials in  $x_1, \dots, x_{N-1}$  of degree 2, 3 and 4 respectively. We write (3.1) and (3.2) in terms of A, B and C. We have

$$egin{aligned} \langle F,\,F
angle &= \left(rac{\partial F}{\partial z}
ight)^2 + \langle F,\,F
angle_x \ &= 16z^6 + 4A^2z^2 + B^2 + 16Az^4 + 8Bz^3 + 4ABz + \langle F,\,F
angle_x \ &= 16z^6 + (16A + \langle A,\,A
angle)z^4 + (8B + 2\langle A,\,B
angle)z^3 \ &+ (4A^2 + \langle B,\,B
angle + 2\langle A,\,C
angle)z^2 + (4AB + 2\langle B,\,C
angle)z \ &+ B^2 + \langle C,\,C
angle \ , \end{aligned}$$

and

$$egin{aligned} 16r^6 &= 16(z^2 + \sum x_i^2)^3 \ &= 16z^6 + \ 48(\sum x_i^2)z^4 + \ 48(\sum x_i^2)^2z^2 + \ 16(\sum x_i^2)^3 \ . \end{aligned}$$

Comparing the coefficients of  $z^h$  for each h, we see that (3.1) is equivalent to  $(1-1)\sim(1\sim5)$  as a whole.

Next, we have

$$egin{aligned} arDelta F &= arDelta_{\langle z 
angle} F + arDelta_x F \ &= 12 z^2 + 2 A + (arDelta_x A) z^2 + (arDelta_x B) z + arDelta_x C$$
 ,

and

 $8(m_2 - m_1)r^2 = 8(m_2 - m_1)(z^2 + \sum x_i^2)$ .

Hence, (3.2) is equivalent to  $(1-6)\sim(1-8)$ . Thus, we have the first assertion of Lemma 4.

The converse follows clearly from the above argument. q.e.d.

LEMMA 5. Let A be a quadratic form on X satisfying (1-1) and (1-6). Then, X has a unique orthogonal decomposition

$$(3.5) X = Y \oplus W$$

with dim  $W = m_1 + 1$  such that A has the form

$$(3.6) A = 2\left(\sum_{j=1}^n y_j^2\right) - 6\left(\sum_{\alpha=0}^{m_1} w_\alpha^2\right)$$

where  $\{y_j\}$  and  $\{w_{\alpha}\}$  are orthonormal coordinate systems for Y and W respectively, and  $n = m_1 + 2m_2$ . Conversely, if A is of the above form with respect to an orthogonal decomposition  $X = Y \bigoplus W$  with dim  $W = m_1 + 1$ , then A satisfies (1-1) and (1-6).

**PROOF.** We denote by  $\tilde{A}$  the symmetric mapping  $\eta(A)$  of X associated to A. Then (1-1) and (1-6) are equivalent to

$$(1-1)' \qquad \qquad (\tilde{A})^2 + 4\tilde{A} - 12\,\mathbf{1}_X = 0$$

and

(1-6)' 
$$\operatorname{Tr}(\tilde{A}) = 4(m_2 - m_1) - 6$$

respectively, where  $1_x$  denotes the identity mapping of X. Assume (1-1) and (1-6). (1-1)' shows that an eigenvalue of  $\tilde{A}$  is 2 or -6. Decompose X into the eigenspaces:

$$X = Y \oplus W$$

where Y and W are the eigenspaces for the eigenvalues 2 and -6 respectively. This is an orthogonal decomposition since  $\tilde{A}$  is symmetric. From (1-6)' it follows that dim  $Y = m_1 + 2m_2$  and dim  $W = m_1 + 1$ . This shows our first assertion. The converse is easily seen. q.e.d.

LEMMA 6. Assume (1-1) and (1-6) for A. Then, B satisfies (1-2) if and only if B is homogeneous of degree 2 on Y and of degree 1 on W.

**PROOF.** Write

$$B=\sum_{h=0}^{3}B_{h}$$

where  $B_k$  is the homogeneous part of degree h on W and hence of degree 3 - h on Y. Consider (1-2). Since  $A = 2(\sum y_j^2) - 6(\sum w_{\alpha}^2)$  by Lemma 5, we have

$$egin{aligned} &\langle A, B 
angle + 4B \ &= \langle A, B 
angle_{Y} + \langle A, B 
angle_{W} + 4B \ &= 2 \langle \sum y_{j}^{2}, B 
angle_{Y} - 6 \langle \sum w_{a}^{2}, B 
angle_{W} + 4B \ &= 2(2B_{2} + 4B_{1} + 6B_{0}) - 6(6B_{3} + 4B_{2} + 2B_{1}) \ &+ 4(B_{3} + B_{2} + B_{1} + B_{0}) \ &= -32B_{3} - 16B_{2} + 16B_{0} \ . \end{aligned}$$

Thus (1-2) is equivalent to  $B_3 = 0$ ,  $B_2 = 0$  and  $B_0 = 0$ . This shows Lemma 6. q.e.d.

Hereafter we assume (1-1), (1-6) together with (1-2). The orthogonal decomposition  $X = Y \bigoplus W$  in Lemma 5 gives us the second reduction. Let  $\{y_j\}$  and  $\{w_\alpha\}$  be orthonormal coordinate systems for Y and W respectively where j runs from 1 to  $n = m_1 + 2m_2$  and  $\alpha$  runs from 0 to  $m_1$ . In view of Lemma 6, we can define  $m_1 + 1$  quadratic forms  $p_0, \dots, p_{m_1}$  on Y by

$$B = 8 \sum_{\alpha=0}^{m_1} p_{\alpha} w_{\alpha} .$$

For C, we put

$$(3.8) C = \sum_{h=0}^{4} C_h$$

where  $C_h$  is the homogeneous part of degree h on W and hence of degree 4 - h on Y, and we define  $m_1 + 1$  cubic forms  $q_0, \dots, q_{m_1}$  on Y by

(3.9) 
$$C_1 = 8 \sum_{\alpha=0}^{m_1} q_{\alpha} w_{\alpha}$$
.

LEMMA 7. The equation (1-3) holds if and only if we have (i)  $C_4 = (\sum w_{\alpha}^2)^2$ , (ii)  $C_3 = 0$ , (iii)  $C_2 = 2 \sum_{\alpha,\beta} \langle p_{\alpha}, p_{\beta} \rangle w_{\alpha} w_{\beta} - 6(\sum y_j^2) (\sum w_{\alpha}^2)$ , (iv)  $C_0 = (\sum y_j^2)^2 - 2 \sum p_{\alpha}^2$ . PROOF. Recall (1-3):

$$\langle B,\,B
angle+2\langle A,\,C
angle+4A^{2}=48(\sum x_{\imath}^{2})^{2}$$
 .

We have

$$egin{aligned} & 4A^2 &= 4\{2(\sum y_j^2) - 6(\sum w_lpha^2)\}^2 \ &= 4\cdot 36(\sum w_lpha^2)^2 - 96(\sum y_j^2)(\sum w_lpha^2) + 16(\sum y_j^2)^2 \,, \ &\leq B, \ B 
angle &= \langle B, \ B 
angle_Y + \langle B, \ B 
angle_W \ &= 64\sum_{lpha,eta} \langle p_lpha, \ p_eta 
angle_W \langle w_eta + 64\sum p_lpha^2 \ &\geq 2\langle A, \ C 
angle &= 2\langle A, \ C 
angle_Y + 2\langle A, \ C 
angle_W \ &= 4\langle \sum y_j^2, \ \sum C_h 
angle - 12\langle \sum w_lpha^2, \ \sum C_h 
angle \ &= 8(C_3 + 2C_2 + 3C_1 + 4C_0) \ &= -24(4C_4 + 3C_3 + 2C_2 + C_1) \ &= -96C_4 - 64C_3 - 32C_2 + 32C_0 \end{aligned}$$

and

$$48(\sum x_i^2)^2 = 48(\sum w_{\alpha}^2)^2 + 96(\sum y_j^2)(\sum w_{\alpha}^2) + 48(\sum y_j^2)^2$$
 .

Summarizing their homogeneous terms, (1-3) is equivalent to

$$egin{aligned} 4\cdot 36(\sum w_lpha^2)^2 &- 96C_4 &= 48(\sum w_lpha^2)^2 \ , \ &- 64C_3 &= 0 \ , \ &- 96(\sum y_j^2)(\sum w_lpha^2) + 64\sum \langle p_lpha, \ p_eta 
angle w_lpha w_eta &- 32C_2 &= 96(\sum y_j^2)(\sum w_lpha^2) \ , \ &16(\sum y_j^2)^2 + 64\sum p_lpha^2 + 32C_0 &= 48(\sum y_j^2)^2 \ . \end{aligned}$$

Now Lemma 7 follows.

REMARK 1. By Lemmas 4, 5, 6 and 7, it follows that the polynomial function F can be constructed uniquely from  $\{p_{\alpha}\}$  and  $\{q_{\alpha}\}$ .

Our  $\{p_{\alpha}\}$  and  $\{q_{\alpha}\}$  associated to F depend on the choice of e in  $S^{N-1}$ such that F(e) = 1 and on the choice of an orthonormal coordinate system  $\{w_{\alpha}\}$  for W. Let F' be another homogeneous polynomial function of degree 4 on  $\mathbb{R}^{N}$  satisfying (3.1) and (3.2). Choose e' in  $S^{N-1}$  and  $\{w'_{\alpha}\}$  for W' in the same way, so that we have  $\{p'_{\alpha}\}$  and  $\{q'_{\alpha}\}$  on Y' associated to F'. We say that F and F' are O(N)-equivalent if there exists an element  $\sigma$ in O(N) such that

$$F'(x) = F(\sigma^{-1}x)$$
 for  $x \in \mathbb{R}^N$ .

Let V and V' be two finite-dimensional vector spaces over R. For a linear isomorphism  $\tau$  of V onto V', and for a polynomial function f on V, we denote by  $\tau f$  the polynomial function on V' obtained by

$$(\tau f)(v')=f(\tau^{-1}v').$$

With these notations, we state the following two remarks for a later use.

REMARK 2. Suppose that F and F' are O(N)-equivalent by an element  $\sigma$  in O(N) such that  $\sigma(e) = e'$ . Then  $\sigma$  induces orthonormal transformations  $\sigma_W \colon W \to W'$  and  $\sigma_Y \colon Y \to Y'$ . By a suitable choice of  $\{w'_{\alpha}\}$  for W', we have

$$\sigma_{_{Y}}p_{_{lpha}}=p_{_{lpha}}'$$
,  $\sigma_{_{Y}}q_{_{lpha}}=q_{_{a}}'$ 

for  $\alpha = 0, 1, \dots, m_1$ . Conversely, suppose that there exists an orthonormal tansformation  $\tau$  of Y onto Y' such that

$$au p_{lpha} = p'_{lpha}$$
 ,  $au q_{lpha} = q'_{lpha}$ 

for  $\alpha = 0, 1, \dots, m_1$ . Then F and F' are O(N)-equivalent by an element  $\sigma$  in O(N) such that  $\sigma(e) = e'$ .

q.e.d.

REMARK 3. Consider the case where the isoparametric hypersurface in  $S^{N-1}$  defined by F = c for some constant c is homogeneous by a subgroup of O(N). Then it follows that the singular submanifold

$$M_1 = \{x \in S^{N-1}; F(x) = 1\}$$

is also homogeneous by the *e*-component of the same group. Therefore F and F' are O(N)-equivalent if and only if there exist an orthogonal matrix  $(\tau_{\alpha\beta})$  of degree  $m_1 + 1$  and an orthonormal transformation  $\sigma$  of Y onto Y' such that

$$p'_{eta} = \sum_{lpha} au_{eta lpha}(\sigma p_{lpha}) , 
onumber \ q'_{eta} = \sum_{oldsymbol lpha} au_{eta lpha}(\sigma q_{lpha})$$

for  $\beta = 0, 1, \dots, m_1$ .

Remarks 2 and 3 are immediate consequences of the preceding lemmas.

4. A characterization by  $\{p_{\alpha}\}$  and  $\{q_{\alpha}\}$ . We continue the argument of the preceding section under the assumptions (1-1), (1-2), (1-3) and (1-6). The equations (1-4), (1-5), (1-7) and (1-8) will be reformulated first in terms of B,  $C_0$  and  $C_1$ , and then in terms of  $\{p_{\alpha}\}$  and  $\{q_{\alpha}\}$ , using Lemmas 5, 6 and 7.

First we list the equations:

(2-1) 
$$\langle B, C_2 \rangle_{Y} = 8B(\sum w_{\alpha}^2)$$

 $(2-2) \qquad \langle B, C_1 \rangle_{\rm F} = 0$ 

(2-3) 
$$\langle B, C_2 \rangle_W + \langle B, C_0 \rangle_Y + 4B(\sum y_j^2) = 0$$

 $(2-4) \qquad \langle B, C_1 \rangle_W = 0$ 

(2-5) 
$$\langle C_2, C_2 \rangle_Y + 16C_2(\sum w_{\alpha}^2) = 48(\sum y_j^2)(\sum w_{\alpha}^2)^2$$

$$(2-6) \qquad \langle C_2, C_1 \rangle_Y + 4C_1(\sum w_\alpha^2) = 0$$

$$(2-7) \qquad \langle C_2, C_2 \rangle_W + \langle C_1, C_1 \rangle_Y + 2 \langle C_2, C_0 \rangle_Y + B^2 = 48(\sum y_j^2)^2 (\sum w_\alpha^2)$$

(2-8) 
$$\langle C_2, C_1 \rangle_W + \langle C_1, C_0 \rangle_Y = 0$$

(2-9) 
$$\langle C_1, C_1 \rangle_W + \langle C_0, C_0 \rangle_Y = 16(\sum y_j^2)^{\varepsilon}$$

 $(2-10) \qquad \qquad \Delta_{Y}B=0$ 

(2-11) 
$$\Delta_{Y}C_{2} = (8m_{2} - 12m_{1})(\sum w_{\alpha}^{2})$$

(2-13) 
$$\Delta_W C_2 + \Delta_Y C_0 = (8m_2 - 8m_1 - 4)(\sum y_j^2) .$$

LEMMA 8. The following implications hold:

- (i)  $(1-4) \Leftrightarrow (2-1), (2-2), (2-3) \text{ and } (2-4),$
- (ii)  $(1-5) \Leftrightarrow (2-5), (2-6), (2-7), (2-8) \text{ and } (2-9),$
- (iii)  $(1-7) \Leftrightarrow (2-10),$
- (iv)  $(1-8) \Leftrightarrow (2-11), (2-12) \text{ and } (2-13).$

PROOF. In each of (1-4), (1-5), (1-7) and (1-8), we replace A by  $2(\sum y_j^2) - 6(\sum w_{\alpha}^2)$ , C by  $C_4 + C_2 + C_1 + C_0$ , and then  $C_4$  by  $(\sum w_{\alpha}^2)^2$ . Decomposing the results into the homogeneous part with respect to the variables  $w_{\alpha}$ 's, we can conclude Lemma 8. We give here the proof of (i). The rest can be shown in a similar way.

Recall (1-4): 
$$\langle B, C \rangle + 2AB = 0$$
.

We have

$$egin{aligned} \langle B,\,C
angle &= \langle B,\,C
angle_{Y} + \langle B,\,C
angle_{W} \ &= \langle B,\,C_{4}
angle_{Y} + \langle B,\,C_{2}
angle_{Y} + \langle B,\,C_{1}
angle_{Y} + \langle B,\,C_{0}
angle_{Y} \ &+ \langle B,\,C_{4}
angle_{W} + \langle B,\,C_{2}
angle_{W} + \langle B,\,C_{1}
angle_{W} + \langle B,\,C_{0}
angle_{W} \ . \end{aligned}$$

Note  $\langle B, C_4 \rangle_Y = 0$ ,  $\langle B, C_0 \rangle_W = 0$ , and  $\langle B, C_4 \rangle_W = \langle B, (\sum w_{\alpha}^2)^2 \rangle_W = 4B(\sum w_{\alpha}^2)$ . Thus, we have

$$egin{aligned} &\langle B,\,C
angle+2AB\ &=\langle B,\,C_2
angle_r-8B(\sum w^2_lpha)\ &+\langle B,\,C_1
angle_r\ &+\langle B,\,C_0
angle_r+\langle B,\,C_2
angle_w+4B(\sum y^2_j)\ &+\langle B,\,C_1
angle_w\ , \end{aligned}$$

from which we can see easily  $(1-4) \Leftrightarrow (2-1) \sim (2-4)$ . q.e.d.

Now we reformulate the above equations  $(2-1)\sim(2-13)$  in terms of  $\{p_{\alpha}\}$  and  $\{q_{\alpha}\}$  as follows:

(3-1) 
$$\begin{cases} \langle \langle p_{\alpha}, p_{\alpha} \rangle, p_{\alpha} \rangle = 16p_{\alpha}, \quad \Delta p_{\alpha} = 0, \\ \Delta (\langle p_{\alpha}, p_{\alpha} \rangle) = 16m_{2} \quad \text{for each } \alpha; \end{cases}$$

$$(3-2) 2\langle\langle p_{\alpha}, p_{\beta}\rangle, p_{\beta}\rangle + \langle\langle p_{\beta}, p_{\beta}\rangle, p_{\alpha}\rangle = 16p_{\alpha}$$

for distinct  $\alpha, \beta$ ;

$$(3-3) \qquad \langle \langle p_{\alpha}, p_{\beta} \rangle, p_{\gamma} \rangle + \langle \langle p_{\beta}, p_{\gamma} \rangle, p_{\alpha} \rangle + \langle \langle p_{\gamma}, p_{\alpha} \rangle, p_{\beta} \rangle = 0$$

for mutually distinct  $\alpha$ ,  $\beta$ ,  $\gamma$ ;

$$(3-4) \langle p_{\alpha}, q_{\alpha} \rangle = 0 for each \alpha;$$

$$(3-5) \qquad \langle p_{\alpha}, q_{\beta} \rangle + \langle p_{\beta}, q_{\alpha} \rangle = 0 \qquad \text{for distinct } \alpha, \beta;$$

$$(3-6) \qquad \langle \langle p_{\alpha}, p_{\beta} \rangle, q_{\gamma} \rangle + \langle \langle p_{\beta}, p_{\gamma} \rangle, q_{\alpha} \rangle + \langle \langle p_{\gamma}, p_{\alpha} \rangle, q_{\alpha} \rangle = 0$$
  
for mutually distinct  $\alpha, \beta, \gamma$ ;

(3-7) 
$$\sum_{\alpha=0}^{m_1} p_{\alpha} q_{\alpha} = 0;$$

(3-8) 
$$16\left(\sum_{\alpha=0}^{m_1}q_{\alpha}^2\right) = 16G(\sum y_j^2) - \langle G, G \rangle;$$

$$\begin{array}{ll} (3-9) \qquad 8\langle q_{\alpha},\,q_{\alpha}\rangle = 8(\langle p_{\alpha},\,p_{\alpha}\rangle(\sum y_{j}^{2}) - p_{\alpha}^{2}) + \langle\langle p_{\alpha},\,p_{\alpha}\rangle,\,G\rangle\\ & -24G - 2\sum\limits_{\gamma=0}^{m_{1}} \langle p_{\alpha},\,p_{\gamma}\rangle^{2} \qquad \qquad \text{for each $\alpha$ ;} \end{array}$$

$$\begin{array}{ll} (3\text{-}10) & 8\langle q_{\alpha},\,q_{\beta}\rangle = 8(\langle p_{\alpha},\,p_{\beta}\rangle(\sum\,y_{j}^{z})\,-\,p_{\alpha}p_{\beta}) + \langle\langle p_{\alpha},\,p_{\beta}\rangle,\,G\rangle \\ & -2\sum\limits_{\gamma=0}^{m_{1}}\langle p_{\alpha},\,p_{\gamma}\rangle\langle p_{\beta},\,p_{\gamma}\rangle & \text{for distinct }\alpha,\,\beta\ ; \end{array}$$

where  $G = \sum_{\alpha=0}^{m_1} p_{\alpha}^2$  and the indices  $\alpha, \beta, \gamma$  run from 0 to  $m_1$ .

LEMMA 9. The following implications hold: (i) (2-1), (2-10), (2-11)  $\Rightarrow$  (3-1), (3-2), (3-3) (3-1), (3-2), (3-3)  $\Rightarrow$  (2-1), (2-10), (ii) (2-2)  $\Leftrightarrow$  (3-4), (3-5), (iii) (2-6)  $\Rightarrow$  (3-6), (iv) (2-4)  $\Leftrightarrow$  (3-7), ((a) (2-2) (3-2))

$$(v) \quad (2-9) \Leftrightarrow (3-8),$$

(vi) 
$$(2-7) \Leftrightarrow (3-9), (3-10).$$

We give here the proofs of (i) and (iii). The rest can be proved similarly.

PROOF OF (i). Recall (2-10):  $\Delta_r B = 0$ . This is equivalent to  $\Delta p_{\alpha} = 0$ . Consider (2-11):

$$\varDelta_{Y}C_{2} = (8m_{2} - 12m_{1})(\sum w_{\alpha}^{2})$$
.

Using  $C_2 = 2 \sum \langle p_{\alpha}, p_{\beta} \rangle w_{\alpha} w_{\beta} - 6(\sum y_j^2)(\sum w_{\alpha}^2)$ , we get

$$arDelta_{
m Y} C_{
m 2} = 2\sum arDelta_{
m Y} (\langle p_lpha, \, p_eta 
angle) w_lpha w_eta - 12 (m_{
m 1} + 2m_{
m 2}) (\sum w_lpha^2)$$
 .

Thus, (2-11) can be written as

$$2 \sum arDelta_{
m r}(\langle p_{lpha}, \, p_{eta} 
angle) w_{lpha} w_{eta} = \{12(m_1 + 2m_2) + 8m_2 - 12m_1\} (\sum w_{lpha}^2) \ = 32m_2(\sum w_{lpha}^2) \; .$$

And hence we see that (2-11) is equivalent to

(2-11-1) 
$$ilde{\Delta}(\langle p_{lpha}, p_{lpha} 
angle) = 16m_2$$
 for each  $lpha$  ,

and

$$(2 - 11 - 2)$$

$$\varDelta(\langle p_{lpha}, p_{eta} 
angle) = 0$$
 for distinct  $lpha, eta$ .

Now consider (2-1):  $\langle B, C_2 \rangle_Y = 8B(\sum w_{\alpha}^2)$ . We have

$$egin{aligned} &\langle B,\,C_{z}
angle_{_{Y}}-8B(\sum w_{lpha}^{z})\ &=2\langle B,\,\sum \langle p_{lpha},\,p_{eta}
angle_{_{lpha}}w_{lpha}w_{eta}
angle_{_{Y}}-6\langle B,\,(\sum y_{j}^{z})(\sum w_{lpha}^{z})
angle_{_{Y}}-8B(\sum w_{lpha}^{z})\ &=16\langle\sum p_{lpha}w_{lpha},\,\sum \langle p_{lpha},\,p_{eta}
angle_{_{lpha}}w_{lpha}w_{eta}
angle_{_{Y}}-32B(\sum w_{lpha}^{z})\ &=16\{\sum \langle \langle p_{lpha},\,p_{eta}
angle,\,p_{\gamma}
angle_{_{lpha}}w_{lpha}w_{eta}w_{\gamma}-16\sum p_{lpha}w_{lpha}w_{eta}^{z}\}\ . \end{aligned}$$

Now we have the implication (2-1), (2-10), (2-11)  $\Rightarrow$  (3-1), (3-2), (3-3). From the above argument, we also have the implication (3-1), (3-2), (3-3)  $\Rightarrow$  (2-1), (2-10).

PROOF OF (iii). Recall (2-6): 
$$\langle C_2, C_1 \rangle_Y + 4C_1(\sum w_\alpha^2) = 0$$
. By Lemma  
7,  $C_2 = 2 \sum \langle p_\alpha, p_\beta \rangle w_\alpha w_\beta - 6(\sum y_j^2)(\sum w_\alpha^2)$ . We have  
 $\langle C_2, C_1 \rangle_Y + 4C_1(\sum w_\alpha^2)$   
 $= 16 \langle \sum \langle p_\alpha, p_\beta \rangle w_\alpha w_\beta, \sum q_T w_T \rangle_Y$   
 $- 6(\sum w_\alpha^2) \langle (\sum y_j^2), C_1 \rangle_Y + 4C_1(\sum w_\alpha^2)$   
 $= 16 \sum \langle \langle p_\alpha, p_\beta \rangle, q_T \rangle w_\alpha w_\beta w_T - 32C_1(\sum w_\alpha^2)$   
 $= 16 \{ \sum \langle \langle p_\alpha, p_\beta \rangle, q_T \rangle w_\alpha w_\beta w_T - 16 \sum q_\alpha w_\alpha w_\beta^2 \}$ .

Thus, we see that (2-6) is equivalent to the following three conditions as a whole:

 $(2-6-1) \qquad \qquad \langle \langle p_{\alpha}, p_{\alpha} \rangle, q_{\alpha} \rangle = 16q_{\alpha} \qquad \qquad \text{for each } \alpha ;$ 

$$(2-6-2) 2\langle\langle p_{\alpha}, p_{\beta}\rangle, q_{\alpha}\rangle + \langle\langle p_{\alpha}, p_{\alpha}\rangle, q_{\beta}\rangle = 16q$$

for distinct  $\alpha$ ,  $\beta$ ;

$$\begin{array}{ll} (2\text{-}6\text{-}3) & \quad \langle \langle p_{\alpha}, \, p_{\beta} \rangle, \, q_{\gamma} \rangle + \langle \langle p_{\beta}, \, p_{\gamma} \rangle, \, q_{\alpha} \rangle + \langle \langle p_{\gamma}, \, p_{\alpha} \rangle, \, q_{\beta} \rangle = 0 \\ & \quad \text{for distinct } \alpha, \, \beta, \, \gamma \, . \end{array}$$

Thus we have  $(2-6) \Rightarrow (3-6) = (2-6-3)$ .

Lemma 9 shows the first assertion of the following Theorem 1.

THEOREM 1. Let  $m_1$  and  $m_2$  be positive integers such that  $N = 2(m_1 + m_2 + 1)$ , and put  $n = m_1 + 2m_2$ .

Assume that a homogeneous polynomial function F of degree 4 on  $\mathbb{R}^{N}$  satisfies  $\langle F, F \rangle = 16r^{6}$  and  $\Delta F = 8(m_{2} - m_{1})r^{2}$ . Then two families  $\{p_{\alpha}\}$  and  $\{q_{\alpha}\}$  of polynomials associated to F in §3 satisfy the equations  $(3-1)\sim(3-10)$ .

Conversely, assume that there are given  $m_1 + 1$  quadratic forms  $p_0, \dots, p_{m_1}$  and  $m_1 + 1$  cubic forms  $q_0, \dots, q_{m_1}$  both on  $\mathbb{R}^n$  such that they

satisfy the equations (3-1)~(3-10). Then the polynomial function F on  $\mathbb{R}^{N}$  constructed from  $\{p_{\alpha}\}$  and  $\{q_{\alpha}\}$  as in § 3 satisfies  $\langle F, F \rangle = 16r^{6}$  and  $\Delta F = 8(m_{2} - m_{1})r^{2}$ .

To prove "the converse" in Theorem 1, it suffices, in view of Lemma 9, to show that (2-3), (2-5), (2-6), (2-8), (2-11), (2-12) and (2-13) follow from  $(3-1)\sim(3-10)$ . We first show (2-3), (2-8) and (2-13) below, and then reformulate the rest in terms of  $\{p_{\alpha}\}$  and  $\{q_{\alpha}\}$ . They will be proved in § 5.

LEMMA 10. 
$$(2-3)$$
,  $(2-8)$  and  $(2-13)$  follow from  $(3-1)\sim(3-10)$ .

PROOF. Recall (2-3):  $\langle B, C_2 \rangle_W + \langle B, C_0 \rangle_Y + 4B(\sum y_j^2) = 0$ . We have  $\langle B, C_2 \rangle_W = \langle B, 2 \sum \langle p_{\alpha}, p_{\beta} \rangle w_{\alpha} w_{\beta} \rangle_W - \langle B, 6(\sum y_j^2)(\sum w_{\alpha}^2) \rangle_W$  $= 32 \sum p_{\alpha} \langle p_{\alpha}, p_{\beta} \rangle w_{\beta} - 96(\sum p_{\alpha} w_{\alpha})(\sum y_j^2)$ 

and

$$egin{aligned} &\langle B,\,C_0
angle_{Y}=\langle B,\,(\sum\,y_j^2)^2
angle_{Y}-\langle B,\,2G
angle_{Y}\ &=8B(\sum\,y_j^2)-16\sum\,\langle p_{lpha},\,G
angle_{Y}w_{lpha}\,. \end{aligned}$$

Thus, we have

$$egin{aligned} &\langle B,\ C_2
angle_W+\langle B,\ C_0
angle_Y+4B(\sum y_j^2)\ &=32\sum \langle p_lpha,\ p_eta
angle p_eta w_lpha -16\sum \langle p_lpha,\ G
angle w_lpha\ &=16\{\sum \limits_{lpha} w_lpha(2\sum \limits_{eta}\langle p_lpha,\ p_eta
angle p_eta -\langle p_lpha,\ G
angle)\}\ . \end{aligned}$$

Since  $G = \sum p_{\beta}^2$ , we have  $\langle p_{\alpha}, G \rangle = 2 \sum_{\beta} \langle p_{\alpha}, p_{\beta} \rangle p_{\beta}$ , and hence we have (2-3).

Next recall (2-8):  $\langle C_2, C_1 \rangle_W + \langle C_1, C_0 \rangle_Y = 0$ . We have

$$egin{aligned} &\langle C_2,\ C_1 
angle_{W} = \langle 2 \sum \langle p_lpha,\ p_eta 
angle w_lpha w_eta, 8 \sum q_lpha w_lpha 
angle_{W} \ &- \langle 6 \ (\sum y_j^2) (\sum w_lpha), 8 \sum q_lpha w_lpha 
angle_{W} \ &= 32 \sum \langle p_lpha,\ p_eta 
angle q_lpha w_eta - 96 (\sum y_j^2) (\sum q_lpha w_lpha) \ , \end{aligned}$$

and

$$egin{aligned} &\langle C_{1},\,C_{0}
angle_{Y}=\langle C_{1},\,(\sum y_{j}^{2})^{2}
angle_{Y}-2\langle C_{1},\,G
angle_{Y}\ &=12C_{1}(\sum y_{j}^{2})-2\langle C_{1},\,G
angle_{Y}\ &=96\,(\sum y_{j}^{2})\sum q_{lpha}w_{lpha}-16\sum\langle q_{lpha},\,G
angle w_{lpha}\,. \end{aligned}$$

Hence we have

$$egin{aligned} &\langle C_2,\,C_1
angle_W+\langle C_1,\,C_0
angle_Y\ &=16\{2\sum\langle p_lpha,\,p_eta
angle q_eta w_lpha-\sum\langle q_lpha,\,G
angle w_lpha\}\,. \end{aligned}$$

Now we see that (2-8) is equivalent to

$$2\sum_{eta} \langle p_{lpha}, \, p_{eta} 
angle q_{eta} = \langle q_{lpha}, \, G 
angle \qquad \qquad ext{for each } lpha \; .$$

By definition,  $\langle q_{\alpha}, G \rangle = \langle q_{\alpha}, \sum p_{\beta}^2 \rangle = 2 \sum_{\beta} \langle q_{\alpha}, p_{\beta} \rangle p_{\beta}$ . Using (3-4) and (3-5), we have

$$\langle q_{lpha},\,G
angle=-2\sum\limits_{eta}ig\langle p_{lpha},\,q_{eta}ig
angle p_{eta}$$
 .

Consider (3-7):  $\sum p_{\beta}q_{\beta} = 0$ . We have

$$0 = \langle p_{lpha}, \sum p_{eta} q_{eta} 
angle = \sum_{eta} \langle p_{lpha}, \, p_{eta} 
angle q_{eta} + \sum_{eta} \langle p_{lpha}, \, q_{eta} 
angle p_{eta}$$
 .

This proves the required equation.

Finally recall (2-13):  $\Delta_w C_2 + \Delta_y C_0 = \{8(m_2 - m_1) - 4\}(\sum y_j^2)$ . We have

$$egin{aligned} & arDelta_w C_2 = arDelta_w \{2 \sum \langle p_lpha, \ p_eta 
angle w_lpha w_eta - 6(\sum y_j^2)(\sum w_lpha)\} \ &= 4 \sum \langle p_lpha, \ p_lpha 
angle - 12(m_1+1)(\sum y_j^2) \end{aligned}$$

and

$$egin{aligned} & arphi_{\rm Y} C_{\rm 0} &= arphi_{\rm Y} \{ (\sum y_j^2)^2 - 2G \} \ &= (8+4n) (\sum y_j^2) - 2 \sum arphi_{\rm x} p_{lpha}^2 \ &= (8+4n) (\sum y_j^2) - 2 \sum \{ 2p_{lpha} arphi p_{lpha} + 2 \langle p_{lpha}, \, p_{lpha} 
angle \} \,. \end{aligned}$$

Since  $\Delta p_{\alpha} = 0$  by (3-1), we have

$$\Delta_W C_2 + \Delta_Y C_0 = \{(8 + 4n) - 12(m_1 + 1)\}(\sum y_j^2)$$
.

Now

and hence we have (2-13).

LEMMA 11. (2-5) and (2-12) can be written as:

respectively.

PROOF. Recall (2-5):  $\langle C_2, C_2 \rangle_F + 16C_2(\sum w_{\alpha}^2) = 48(\sum w_{\alpha}^2)^2(\sum y_j^2)$ , and  $C_2 = 2 \sum \langle p_{\alpha}, p_{\beta} \rangle w_{\alpha} w_{\beta} - 6(\sum y_j^2)(\sum w_{\alpha}^2)$ . We have

q.e.d.

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$$egin{aligned} &\langle C_2,\,C_2
angle_Y = 4\sum\limits_{lpha,eta,\gamma,\delta}\langle\langle p_lpha,\,p_eta
angle,\,\langle p_\gamma,\,p_\delta
angle
angle w_lpha w_eta w_et$$

and

$$16C_2(\sum w_{lpha}^2) = 32\sum_{lpha,eta, au} \langle p_{lpha}, p_{eta} 
angle w_{lpha} w_{eta} w_{eta}^2 - 96(\sum y_{eta}^2)(\sum w_{lpha}^2)^2$$
 .

They show that (2-5) is equivalent to (2-5)'.

Recall (2-12):  $\Delta_r C_1 = 0$ . Since  $C_1 = \sum 8q_{\alpha}w_{\alpha}$ , clearly (2-12) is equivalent to (2-12)'. q.e.d.

Note that (2-6) and (2-11) have been reformulated in the proof of Lemma 9.

5. The third decomposition of  $\mathbb{R}^{N}$ . In this section, first the family  $\{p_{\alpha}\}$  of quadratic forms on Y will be characterized in matricial forms. Then we shall give a further decomposition of the space Y. The proof of Theorem 1 will be completed.

For each quadratic form  $p_{\alpha}$  on Y, we define the symmetric linear mapping  $P_{\alpha}$  of Y as in §2 by

$$(5.1) P_{\alpha} = \eta(p_{\alpha}) .$$

We have

LEMMA 12. The conditions (3-1), (3-2) and (3-3) on  $\{p_{\alpha}\}$  are equivalent to the following conditions (i), (ii) and (iii) respectively:

(i) For each  $\alpha$ , we have

$$(4-1)_{\alpha} \qquad \qquad P_{\alpha}^{3}=P_{\alpha} , \quad \mathrm{Tr} \ P_{\alpha}=0 , \quad \mathrm{rank} \ P_{\alpha}=2m_{2} ;$$

(ii) For each distinct  $\alpha$ ,  $\beta$ , we have

$$(4-2)_{\alpha,\beta} \qquad \qquad P_{\alpha}=P_{\beta}^{2}P_{\alpha}+P_{\alpha}P_{\beta}^{2}+P_{\beta}P_{\alpha}P_{\beta};$$

(iii) For each mutually distinct  $\alpha$ ,  $\beta$ ,  $\gamma$  we have

$$(4-2)_{lpha,\,eta,\,\gamma} \hspace{1cm} \mathfrak{S}(P_{lpha}P_{eta}P_{\gamma}) = 0 \;,$$

where  $\mathfrak{S}$  denotes the sum of terms obtained by interchanging the indices over all permutations.

Note dim  $Y = n = m_1 + 2m_2$ . Lemma 12 follows by direct verifications, using (2.14), (2.15) and (2.16).

LEMMA 13. (2-5) follows from (3-1), (3-2) and (3-3).

**PROOF.** Recall, by Lemma 11,  $(2-5) \Leftrightarrow (2-5)'$ :

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$$\sum\limits_{lpha,eta, au,ar{s}} ig\langle\langle p_{lpha},\ p_{eta}
angle,\ \langle p_{ au},\ p_{eta}
angle
angle w_{lpha}w_{eta}w_{$$

The monomials of  $w_{\alpha}$ 's appearing in (2-5)' are classified in the following types;

 $w_{\alpha}^{4}, w_{\alpha}^{3}w_{\beta}, w_{\alpha}^{2}w_{\beta}^{2}, w_{\alpha}^{2}w_{\beta}w_{\gamma}, w_{\alpha}w_{\beta}w_{\gamma}w_{\delta}$ 

where  $\alpha$ ,  $\beta$ ,  $\gamma$  and  $\delta$  are all distinct. Now (2-5)' decomposes into the following five equations;

$$(2-5-1)$$
  $\langle\langle p_{lpha},\,p_{lpha}
angle,\,\langle p_{lpha},\,p_{lpha}
angle
angle=16\langle p_{lpha},\,p_{lpha}
angle$  ,

$$(2\text{-}5\text{-}2) \qquad \qquad \langle \langle p_{\alpha}, \, p_{\alpha} \rangle, \, \langle p_{\alpha}, \, p_{\beta} \rangle \rangle = 8 \langle p_{\alpha}, \, p_{\beta} \rangle \,,$$

$$\begin{array}{ll} (2-5-3) & \quad & \langle \langle p_{\alpha}, \, p_{\alpha} \rangle, \, \langle p_{\beta}, \, p_{\beta} \rangle \rangle + 2 \langle \langle p_{\alpha}, \, p_{\beta} \rangle, \, \langle p_{\alpha}, \, p_{\beta} \rangle \rangle \\ & \quad = 8 (\langle p_{\alpha}, \, p_{\alpha} \rangle + \langle p_{\beta}, \, p_{\beta} \rangle) \; , \end{array}$$

$$(2\text{-}5\text{-}4) \quad \langle \langle p_{\alpha}, \, p_{\alpha} \rangle, \, \langle p_{\beta}, \, p_{\gamma} \rangle \rangle + 2 \langle \langle p_{\alpha}, \, p_{\beta} \rangle, \, \langle p_{\alpha}, \, p_{\gamma} \rangle \rangle = 8 \langle p_{\beta}, \, p_{\gamma} \rangle \text{ ,}$$

$$egin{aligned} (2-5-5) & \langle\langle p_{lpha},\,p_{eta}
angle,\,\langle p_{ au},\,p_{ar{s}}
angle
angle+\,\langle\langle p_{lpha},\,p_{ au}
angle,\,\langle p_{eta},\,p_{ar{s}}
angle
angle\ +\,\langle\langle p_{lpha},\,p_{ar{s}}
angle,\,\langle p_{eta},\,p_{ au}
angle
angle=0 \ , \end{aligned}$$

where  $\alpha$ ,  $\beta$ ,  $\gamma$ ,  $\delta$  are all distinct.

We give here a proof of (2-5-4). In the following verification,  $P_{\alpha}, P_{\beta}, \cdots$  are denoted simply by  $\alpha, \beta, \cdots$ , and the notation  $\langle , \rangle$  is also used for mappings, i.e.,  $\langle \alpha, \beta \rangle = 2(\alpha\beta + \beta\alpha)$ .

To prove (2-5-4), it suffices to show

$$\langle\langle lpha, lpha 
angle, \langle eta, \gamma 
angle 
angle + 2 \langle\langle lpha, eta 
angle, \langle lpha, \gamma 
angle 
angle = 8 \langle eta, \gamma 
angle \; .$$

The left hand side

$$= 8\{\langle \alpha^{2}, (\beta\gamma + \gamma\beta) \rangle + \langle (\alpha\beta + \beta\alpha), (\alpha\gamma + \gamma\alpha) \rangle\} \\= 16\{\alpha^{2}\beta\gamma + \alpha^{2}\gamma\beta + \beta\gamma\alpha^{2} + \gamma\beta\alpha^{2} \\+ \alpha\beta\alpha\gamma + \alpha\beta\gamma\alpha + \beta\alpha\alpha\gamma + \beta\alpha\gamma\alpha \\+ \alpha\gamma\alpha\beta + \alpha\gamma\beta\alpha + \gamma\alpha\alpha\beta + \gamma\alpha\beta\alpha\}.$$

The right hand side

$$= 16(\beta\gamma + \gamma\beta)$$
.

From  $(4-2)_{\gamma,\alpha}$ :  $\gamma = \alpha^2 \gamma + \gamma \alpha^2 + \alpha \gamma \alpha$ , we have

$$\gamma eta = lpha^2 \gamma eta + \gamma lpha^2 eta + lpha \gamma lpha eta$$
 .

From  $(4-2)_{\beta,\alpha}$ :  $\beta = \alpha^2 \beta + \beta \alpha^2 + \alpha \beta \alpha$ , we have  $\beta \gamma = \alpha^2 \beta \gamma + \beta \alpha^2 \gamma + \alpha \beta \alpha \gamma$ . Substituting them, we see that it suffices to show

$$eta\gammalpha^{_2}+\gammaetalpha^{_2}+lphaeta\gammalpha+etalpha\gammalpha+lpha\gammaetalpha+\gammalphaetalpha=0$$
 .

Now the left hand side of this equation coincides with  $\mathfrak{S}(\alpha\beta\gamma)\alpha$ , which is 0 by  $(4-3)_{\alpha,\beta,\gamma}$ .

The rest of equations can be proved in a similar way. q.e.d.

From now on in this section we assume (3-1) and (3-2). We choose an arbitrary index  $\alpha$ , say  $\alpha = 0$ .

By virtue of  $(4-1)_{\alpha}$ , each  $P_{\alpha}$  has the eigenvalues 1, -1 and 0. We decompose the space Y into the eigenspaces of  $P_0$ ;

$$(5.2) Y = U \oplus V \oplus Z$$

where U, V and Z are the eigenspaces of  $P_0$  for the eigenvalues 1, -1 and 0 respectively. Note that the decomposition (5.2) is orthogonal since  $P_0$  is symmetric and that, by  $(4-1)_0$ , we have

(5.3) 
$$\begin{cases} \dim U = \dim V = m_2 , \\ \dim Z = m_1 . \end{cases}$$

Now, with respect to orthonormal bases of U, V and W,  $P_0$  is represented by the matrix;

$$P_{\circ} \sim \begin{pmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

where 1 denotes the identity matrix of degree  $m_2$ . Similarly, we have

LEMMA 14. For each  $\alpha > 0$ ,  $P_{\alpha}$  is represented by the following matrix;

$$P_{lpha}\sim egin{pmatrix} 0&a_{lpha}&b_{lpha}\ a'_{lpha}&0&c_{lpha}\ b'_{lpha}&c'_{lpha}&0 \end{pmatrix}$$

where  $a_{\alpha}$  is  $m_2 \times m_2$ ,  $b_{\alpha}$  and  $c_{\alpha}$  are  $m_2 \times m_1$  and ' indicates the transpose. Further they satisfy

(5.4)  $\begin{cases} a_{\alpha}a'_{\alpha}+2b_{\alpha}b'_{\alpha}=1, \\ b'_{\alpha}b_{\alpha}=c'_{\alpha}c_{\alpha}; \end{cases} a'_{\alpha}a_{\alpha}+2c_{\alpha}c'_{\alpha}=1,$ 

(5.5) 
$$\begin{cases} b_{\alpha}c'_{\alpha}a'_{\alpha} + a_{\alpha}c_{\alpha}b'_{\alpha} = 0, \qquad c_{\alpha}b'_{\alpha}a_{\alpha} + a'_{\alpha}b_{\alpha}c_{\alpha} = 0, \\ c'_{\alpha}a'_{\alpha}b_{\alpha} + b'_{\alpha}a_{\alpha}c_{\alpha} = 0. \end{cases}$$

Conversely, assume that a matrix of the above form is given and satisfies (5.4), (5.5). Then it satisfies  $(4-1)_{\alpha}$ ,  $(4-2)_{\alpha,0}$  and  $(4-2)_{0,\alpha}$ .

**PROOF.** Consider  $(4-2)_{\alpha,0}$ :

 $P_{lpha} = P_0^2 P_{lpha} + P_{lpha} P_0^2 + P_0 P_{lpha} P_0$  .

This gives the required form for  $P_{\alpha}$ . Similarly,  $(4-2)_{0,\alpha}$ :

 $P_0 = P_\alpha^2 P_0 + P_\alpha^2 P_0 + P_\alpha P_0 P_\alpha$ 

gives (5.4). If we assume  $(4-2)_{\alpha,0}$ ,  $(4-2)_{0,\alpha}$ , then  $(4-1)_{\alpha}$  is equivalent to (5.5). Note that the condition: rank  $P_{\alpha} = 2m_2$  follows from (5.4) and (5.5). q.e.d.

COROLLARY 1. (2-11-2) holds, i.e., we have

$$\Delta \langle p_{\alpha}, p_{\beta} \rangle = 0$$

for each distinct  $\alpha$ ,  $\beta$ .

PROOF. Without loss of generality, we may assume  $\beta = 0$ . We have

$${\it \Delta}\langle p_{\scriptscriptstyle 0},\,p_{\scriptscriptstyle lpha}
angle=4\,{
m Tr}\left(P_{\scriptscriptstyle 0}P_{\scriptscriptstyle lpha}+P_{\scriptscriptstyle lpha}P_{\scriptscriptstyle 0}
ight)$$
 .

It can be easily verified that  $\operatorname{Tr}(P_0P_\alpha) = 0$  and  $\operatorname{Tr}(P_\alpha P_0) = 0$  for  $\alpha > 0$  using Lemma 14. q.e.d.

Let  $\{u_i\}, \{v_i\}$  and  $\{z_k\}$  be orthonormal coordinate systems for U, Vand Z respectively. We consider the homogeneous degree with respect to the variables  $z_1, \dots, z_{m_1}$  for polynomial functions on Y. Let

(5.6) 
$$p_{\alpha} = \sum_{h} p_{\alpha,h}$$
,  $q_{\alpha} = \sum_{h} q_{\alpha,h}$ 

be the decompositions into homogeneous parts with respect to  $z_1, \dots, z_{m_1}$ , where h indicates the total degree on  $\{z_k\}$ .

COROLLARY 2. For each  $\alpha > 0$ , we have (i)  $p_{\alpha,2} = 0$ , (ii)  $\langle p_0, p_{\alpha,0} \rangle = 0$ .

One can verify them using matricial forms given in Lemma 14.

LEMMA 15. We have, from (3-8) and (3-4), (i)  $q_{\alpha,3} = 0$  for each  $\alpha$ ,

(ii)  $q_0$  is homogeneous of degree 1 on U, V and W.

**PROOF.** (i) Recall (3-8):

$$16\left(\sum_{lpha} q_{lpha}^2
ight) = 16(\sum y_j^2)G - \langle G, G 
angle$$

where  $G = \sum_{\alpha} p_{\alpha}^2$  and  $\sum y_j^2 = \sum u_i^2 + \sum v_i^2 + \sum z_k^2$ . In the equation (3-8),

consider the homogeneous parts of degree 6 with respect to  $z_1, \dots, z_{m_1}$ . Since  $p_{\alpha,2} = 0$ , the total degree of G with respect to  $z_k$ 's is less than 4. Similarly, the total degree of  $\langle G, G \rangle$  with respect to  $z_k$ 's is less than 6, since  $\langle G, G \rangle = 4 \sum \langle p_{\alpha}, p_{\beta} \rangle p_{\alpha} p_{\beta}$ . Thus, we have  $\sum q_{\alpha,3}^2 = 0$ , and hence  $q_{\alpha,3} = 0$  for each  $\alpha$ .

(ii) For  $\alpha = 0$ , (3-4) gives

$$\langle p_{\scriptscriptstyle 0}, q_{\scriptscriptstyle 0} 
angle = 0$$
 .

Now we have  $p_0 = \sum u_i^2 - \sum v_i^2$ , and hence

$$\langle p_{\scriptscriptstyle 0},\,q_{\scriptscriptstyle 0}
angle = 2\sum u_i rac{\partial q_{\scriptscriptstyle 0}}{\partial u_i} - 2\sum v_i rac{\partial q_{\scriptscriptstyle 0}}{\partial v_i} \;.$$

If S is homogeneous of degree k and l with respect to  $\{u_i\}$  and  $\{v_i\}$  respectively, then we have

$$\langle p_{\scriptscriptstyle 0}, S \rangle = 2(k-l)S$$
 .

Thus,  $\langle p_0, q_0 \rangle = 0$  implies that each non zero term of  $q_0$  consists of monomials with the same degree on  $\{u_i\}$  and  $\{v_i\}$ . Since  $q_0$  is cubic and  $q_{0,3} = 0$  by (i), we have (ii). q.e.d.

COROLLARY. (2-12) and (2-6-1) follow from  $(3-1)\sim(3-10)$ .

**PROOF.** Recall  $(2-12) \Leftrightarrow (2-12)'$ :  $\Delta q_{\alpha} = 0$  for each  $\alpha$ . Without loss of generality, we may assume  $\alpha = 0$ . Then  $\Delta q_0 = 0$  follows from (ii) of Lemma 15.

Next, recall (2-6-1):  $\langle\langle p_{\alpha}, p_{\alpha}\rangle, q_{\alpha}\rangle = 16q_{\alpha}$  for each  $\alpha$ . Again we may assume  $\alpha = 0$  without loss of generality. Since  $p_0 = \sum u_i^2 - \sum v_i^2$ , we have

$$\langle p_{\scriptscriptstyle 0},\,p_{\scriptscriptstyle 0}
angle = 4(\sum u_{\scriptscriptstyle 1}^{\scriptscriptstyle 2}+\sum v_{\scriptscriptstyle 1}^{\scriptscriptstyle 2})$$
 .

By (ii) of Lemma 15,  $q_0 = q_{0,1}$ . Now we have

$$\langle\langle p_{\scriptscriptstyle 0},\,p_{\scriptscriptstyle 0}
angle,\,q_{\scriptscriptstyle 0}
angle=\langle\langle p_{\scriptscriptstyle 0},\,p_{\scriptscriptstyle 0}
angle,\,q_{\scriptscriptstyle 0,1}
angle=16q_{\scriptscriptstyle 0,1}=16q_{\scriptscriptstyle 0}$$
 .

This proves our corollary.

LEMMA 16. (2-6-2) follows from  $(3-1) \sim (3-10)$ .

**PROOF.** Recall (2-6-2):  $2\langle\langle p_{\alpha}, p_{\beta}\rangle, q_{\alpha}\rangle + \langle\langle p_{\alpha}, p_{\alpha}\rangle, q_{\beta}\rangle = 16q_{\beta}$  for each distinct  $\alpha, \beta$ . Interchanging the indices, it suffices to show

$$2\langle\langle p_{0},\ p_{lpha}
angle,\ q_{0}
angle+\langle\langle p_{0},\ p_{0}
angle,\ q_{lpha}
angle=16q_{lpha}$$

for  $\alpha > 0$ . From  $\langle p_0, p_0 \rangle = 4(\sum u_i^2 + \sum v_i^2)$ , we have

$$\langle\langle p_{\scriptscriptstyle 0},\,p_{\scriptscriptstyle 0}
angle,\,q_{\scriptscriptstyle lpha,\,h}
angle=8(3-h)q_{\scriptscriptstyle lpha,\,h}$$

q.e.d.

for any h. Since  $q_{\alpha,3} = 0$  by (i) of Lemma 15, it suffices now to show

$$\langle\langle p_{\scriptscriptstyle 0},\,p_{\scriptscriptstyle lpha}
angle,\,q_{\scriptscriptstyle 0}
angle=4q_{\scriptscriptstyle lpha,\,2}-4q_{\scriptscriptstyle lpha,\,0}$$
 .

By Corollary 2 of Lemma 14, it suffices to show

(\*) 
$$\langle \langle p_0, p_{\alpha,1} \rangle, q_0 \rangle = 4q_{\alpha,2} - 4q_{\alpha,0}$$

Now we consider the total degree on the variables  $u_1, \dots, u_{m_2}$ . Let

$$egin{array}{l} p_{lpha,1} = s_1 + s_0 \;, \ q_{lpha,0} = f_3 + f_2 + f_1 + f_0 \;, \ q_{lpha,1} = g_2 + g_1 + g_0 \;, \ q_{lpha,2} = h_1 + h_0 \end{array}$$

be the decompositions into homogeneous parts, where each suffix indicates the total degree on  $u_1, \dots, u_{m_2}$ . Recall (3-5). We have

$$\langle p_{\scriptscriptstyle 0},\, q_{\scriptscriptstyle lpha}
angle + \langle p_{\scriptscriptstyle lpha},\, q_{\scriptscriptstyle 0}
angle = 0$$
 ,

and hence

$$egin{aligned} &\langle p_{\scriptscriptstyle 0},\,q_{\scriptscriptstyle lpha,0}
angle+\langle p_{\scriptscriptstyle 0},\,q_{\scriptscriptstyle lpha,1}
angle+\langle p_{\scriptscriptstyle 0},\,q_{\scriptscriptstyle lpha,2}
angle\ &+\langle p_{\scriptscriptstyle lpha,0},\,q_{\scriptscriptstyle 0,1}
angle+\langle p_{\scriptscriptstyle lpha,1},\,q_{\scriptscriptstyle 0,1}
angle=0\;. \end{aligned}$$

Equivalently, we have

$$egin{aligned} & \{\langle p_0, \, q_{lpha,2} 
angle + \langle p_{lpha,1}, \, q_0 
angle_{|u_i,v_i|}\} \ & + \{\langle p_0, \, q_{lpha,1} 
angle + \langle p_{lpha,0}, \, q_{0,1} 
angle\} \ & + \{\langle p_0, \, q_{lpha,0} 
angle + \langle p_{lpha,1}, \, q_0 
angle_Z\} = 0 \;. \end{aligned}$$

Observing the degree with respect to  $z_1, \dots, z_{m_1}$  of each term in the above equation, we obtain:

(1) 
$$\langle p_0, q_{\alpha,2} \rangle + \langle p_{\alpha,1}, q_0 \rangle_{\{u_i, v_i\}} = 0$$
,

(2) 
$$\langle p_{\mathfrak{q}}, q_{\mathfrak{a},\mathfrak{l}} 
angle + \langle p_{\mathfrak{a},\mathfrak{q}}, q_{\mathfrak{q}} 
angle = 0$$
 ,

$$(3) \qquad \langle p_0, q_{\alpha,0} \rangle + \langle p_{\alpha,1}, q_0 \rangle_Z = 0.$$

From  $p_0 = \sum u_i^2 - \sum v_i^2$ , we obtain:

(4) 
$$\langle p_{\mathfrak{q},\mathfrak{q}_{\mathfrak{a},\mathfrak{z}}
angle = 2h_{\mathfrak{l}}-2h_{\mathfrak{q}}$$
 ,

(5) 
$$\langle p_{\scriptscriptstyle 0},\,q_{\scriptscriptstyle \alpha,1}
angle = 4g_{\scriptscriptstyle 2} - 4g_{\scriptscriptstyle 0}$$
 ,

(6) 
$$\langle p_0, q_{\alpha,0} \rangle = 2(3f_3 + f_2 - f_1 - 3f_0)$$

On the other hand, we have

$$egin{array}{lll} \langle p_{lpha,1},\,q_0
angle_{\{u_i,v_i\}} = \langle s_0,\,q_0
angle_{\{u_i,v_i\}} + \langle s_1,\,q_0
angle_{\{u_i,v_i\}} \ &= \langle s_0,\,q_0
angle_V + \langle s_1,\,q_0
angle_U \,. \end{array}$$

Substituting this and (4) into (1), we get

(7) 
$$\begin{cases} 2h_1 + \langle s_0, q_0 \rangle_V = 0 , \\ 2h_0 - \langle s_1, q_0 \rangle_U = 0 . \end{cases}$$

Similarly, substituting  $\langle p_{\alpha,1}, q_0 \rangle_Z = \langle s_1, q_0 \rangle_Z + \langle s_0, q_0 \rangle_Z$  and (6) into (3), we get

(8) 
$$\begin{cases} f_3 = f_0 = 0 , \\ 2f_2 + \langle s_1, q_0 \rangle_Z = 0 , \\ 2f_1 - \langle s_0, q_0 \rangle_Z = 0 . \end{cases}$$

Since  $\langle p_0, p_{\alpha,1} \rangle = \langle p_0, s_0 \rangle + \langle p_0, s_1 \rangle = -2s_0 + 2s_1$ , (7) and (8) give the required equation (\*).

Note that we have completed the proof of Theorem 1.

6. A further characterization. In this section we give a further characterization of  $\{p_{\alpha}\}$  and  $\{q_{\alpha}\}$  under an additional condition (A) for a later use. Let  $\{p_{\alpha}\}$  be  $m_1 + 1$  quadratic forms on Y satisfying (3-1) and (3-2). With the notations in § 5, we state

LEMMA 17. The following three conditions are mutually equivalent: (i)  $\langle p_{\alpha}, p_{\beta} \rangle = 0$  for distinct  $\alpha, \beta$ ; (ii)  $\langle p_{\alpha}, p_{\alpha} \rangle = \langle p_{\beta}, p_{\beta} \rangle$  for distinct  $\alpha, \beta$ ; (iii)  $p_{\alpha,1} = 0$  for each  $\alpha$ .

**PROOF.** As one can see easily, to prove Lemma 17, it suffices to show that, for each  $\alpha > 0$ , the following three conditions are mutually equivalent:

Using Lemma 14, we give matricial representations for  $\langle p_0, p_\alpha \rangle$ ,  $\langle p_\alpha, p_\alpha \rangle$ and  $p_{\alpha,1}$ . In the following, the indices for submatrices are omitted. We have

$$egin{aligned} &\langle p_{0}, \ p_{lpha} 
angle \sim 2 egin{pmatrix} 0 & 0 & b \ 0 & 0 & -c \ b' & -c' & 0 \end{pmatrix}, \ &\langle p_{lpha}, \ p_{lpha} 
angle \sim 4 egin{pmatrix} aa' + bb' & bc' & ac \ cb' & a'a + cc' & a'b \ c'a' & b'a & b'b + c'c \end{pmatrix} \end{aligned}$$

$$p_{lpha,1} \sim egin{pmatrix} 0 & 0 & b \ 0 & 0 & c \ b' & c' & 0 \end{pmatrix}.$$

Thus, (i)'  $\Leftrightarrow$  (iii)' and (iii)'  $\Rightarrow$  (ii)' are clear. Suppose (ii)'. Then aa' + bb' = 1. Since aa' + 2bb' = 1 by Lemma 14, we see bb' = 0, and hence b = 0. Similarly we have c = 0. This proves (ii)'  $\Rightarrow$  (iii)'. q.e.d.

From now on we denote by (A) one of the three conditions in Lemma 17. Now assume that  $\{p_{\alpha}\}$  satisfy the condition (A) together with (3-1) and (3-2). We remark here that the image and the kernel of  $P_{\alpha}$  are independent on  $\alpha$  and that the condition (3-3) follows automatically. We put, for each  $\alpha$ ,

$$(6.1) R_{\alpha} = P_{\alpha}|_{U \oplus V} .$$

We see that  $R_{\alpha}$  is a symmetric mapping of  $U \bigoplus V$  into itself and for  $\alpha = 0$ ,  $R_0|_U = 1_U$ ,  $R_0|_V = -1_V$ . Furthermore it is easily seen that the family  $\{R_{\alpha}\}$  satisfies the following two conditions:

$$(5-1) R_{\alpha}^2 = 1_{U \oplus V} , Tr R_{\alpha} = 0 for each \alpha ;$$

$$(5-2) R_{\alpha}R_{\beta} + R_{\beta}R_{\alpha} = 0 for distinct \alpha, \beta.$$

Conversely, we have

LEMMA 18. Let  $\{R_{\alpha}\}$  be  $m_1 + 1$  symmetric mappings of  $U \oplus V$  into itself satisfying (5-1) and (5-2). Then we can associate  $m_1 + 1$  quadratic forms  $\{p_{\alpha}\}$  on Y satisfying (3-1), (3-2) and the condition (A) with the relation (6.1) for each  $\alpha$ .

**PROOF.** For each  $R_{\alpha}$ , we define  $P_{\alpha}$  by

$$P_{lpha} = egin{cases} R_{lpha} & ext{on} \ U \bigoplus V \ 0 & ext{on} \ Z \ . \end{cases}$$

Then  $P_{\alpha}$  is a symmetric mapping of  $Y = U \bigoplus V \bigoplus Z$ . Now (5-1) implies  $(4-1)_{\alpha}$  for each  $\alpha$ . From the construction of  $P_{\alpha}$ , it follows that  $(4-2)_{\alpha,\beta}$  is a consequence of (5-2). Let  $p_{\alpha}$  be the quadratic form on Y corresponding to  $P_{\alpha}$ .  $\{p_{\alpha}\}$  satisfy the required conditions. q.e.d.

LEMMA 19. Assume that  $\{p_{\alpha}\}$  satisfy (3-1), (3-2) and the condition (A). Let  $\{q_{\alpha}\}$  be  $m_1 + 1$  cubic forms on Y. Then (3-3) and (3-6) follow immediately. The conditions (3-8), (3-9) and (3-10) can be written equivalently as

$$(5-8) \qquad \qquad \sum q_{\alpha}^2 = G(\sum z_k^2) ,$$

(5-9) 
$$\langle q_{\alpha}, q_{\alpha} \rangle = G - p_{\alpha}^2 + 4(\sum u_i^2 + \sum v_i^2)(\sum z_k^2)$$
 for each  $\alpha$ ,

for distinct  $\alpha$ ,  $\beta$ 

$$(5-10) \qquad \langle q_{\alpha}, q_{\beta} \rangle = -p_{\alpha}p_{\beta}$$

respectively.

**PROOF.** By Lemma 17, we see that (3-3) and (3-6) follow immediately from (A). For  $G = \sum p_{\alpha}^2$ , consider  $\langle G, G \rangle$ . We have

$$egin{aligned} &\langle G,\ G
angle &=\sum\limits_{lpha,eta} \langle p_{lpha}^2,\ p_{eta}^2
angle &=4\sum\limits_{lpha,eta} p_{lpha} p_{eta} \langle p_{lpha},\ p_{eta}
angle \ &=4\sum\limits_{lpha} p_{lpha}^2 \langle p_{lpha},\ p_{lpha}
angle &=4igg(\sum\limits_{lpha}\ p_{lpha}^2igg) \langle p_{0},\ p_{0}
angle \ &=16G(\sum\ u_{\imath}^2+\sum\ v_{\imath}^2)\ . \end{aligned}$$

This gives  $(3-8) \Leftrightarrow (5-8)$ . Since each  $p_{\beta}$  is a quadratic form on  $U \bigoplus V$ , we have

$$egin{aligned} &\langle\langle p_lpha,\ p_lpha
angle,\ p_eta
angle &=\langle\langle p_0,\ p_0
angle,\ p_eta
angle \ &=\langle\langle p_0,\ p_0
angle,\ p_eta
angle_{U\oplus V}=16p_eta\ . \end{aligned}$$

Thus, we have

$$egin{array}{lll} \langle\langle p_lpha,\ p_lpha
angle,\ G
angle = \sum_eta \langle\langle p_lpha,\ p_lpha
angle,\ p_eta
angle 
angle \ = \sum_eta 2p_eta \langle\langle p_0,\ p_0
angle,\ p_eta
angle = 32G \ . \end{array}$$

This and Lemma 17 give  $(3-9) \Leftrightarrow (5-9)$ . Lemma 17 gives also  $(3-10) \Leftrightarrow (5-10)$ .

By Lemmas 18 and 19, it follows that for a given  $\{R_{\alpha}\}$  satisfying (5-1) and (5-2), the required conditions for  $\{q_{\alpha}\}$  in Theorem 1 are now (3-4), (3-5), (3-7), (5-8), (5-9) and (5-10).

For a later use, we give the following lemma.

LEMMA 20. Let  $\{p_{\alpha}\}$  be  $m_1 + 1$  quadratic forms on Y satisfying (3-1), (3-2) and (A). Then  $p_0, \dots, p_{m_1}$  are algebraically independent over R.

**PROOF.** First we prove that  $p_0, \dots, p_{m_1}$  are linearly independent over **R**. Suppose  $\sum a_{\alpha}p_{\alpha} = 0$ ,  $a_{\alpha} \in \mathbf{R}$ . We have for any  $\beta$ ,

$$\left\langle p_{ extsf{ heta}},\,\sum\limits_{lpha}a_{lpha}p_{lpha}
ight
angle =a_{eta}\!\left\langle p_{eta},\,p_{eta}
ight
angle$$
 ,

and hence  $a_{\beta} = 0$ . Next suppose

$$\sum a_{i_0\cdots i_m} p_{0}^{i_0}\cdots p_{m_1}^{i_{m_1}} = 0$$
.

Since each  $p_{\alpha}$  is a quadratic form, we have

$$\sum_{i_0+\cdots+i_{m_1}=l}a_{i_0\cdots i_{m_1}}p_0^{i_0}\cdots p_{m_1}^{i_{m_1}}=0$$

for each l. We shall show  $a_{i_0\cdots i_{m_1}}=0$  for all  $i_0, \cdots, i_{m_1}$ . This will be shown by the induction on  $l=i_0+\cdots+i_{m_1}$ . The case l=1 has been proved. For each  $\beta$ , we have

$$egin{aligned} &\langle p_{m{eta}}, \sum a_{i_0 \cdots i_{m_1}} p_0^{i_0} \cdots p_{m_1}^{i_{m_1}} 
angle \ &= \sum i_{m{eta}} a_{i_0 \cdots i_{m_1}} p_0^{i_0} \cdots p_{m{eta}}^{i_{m{eta}^{-1}}} \cdots p_{m_1}^{i_{m_1}} \langle p_0, \ p_0 
angle \ . \end{aligned}$$

Using this, one can complete easily the proof.

7. Representations of a Clifford algebra. In this section we prove certain lemmas concerning representations of a Clifford algebra for a later use.

Let F be an associative division algebra over R, i.e., F = R, C or the real quaternion algebra H. We denote by  $M_m(F)$  the algebra of all  $m \times m$  matrices with coefficients in F, and by  $1_m$  the unit matrix in  $M_m(F)$ .  $M_m(F)$  is called the total matrix algebra over F of degree m.

For each non-negative integer  $\kappa$ , we denote by  $C_{\kappa}$  the Clifford algebra over R associated to the negative definite quadratic form -(,) on  $R^{\epsilon}$ , where (,) is the usual inner product on  $R^{\epsilon}$ . Let  $\{e_1, \dots, e_{\kappa}\}$  be an orthonormal base for  $R^{\epsilon}$  with respect to (,). Then  $C_{\kappa}$  is the associative algebra over R with the unit 1 generated by  $e_1, \dots, e_{\kappa}$  with the relations:

$$\left\{egin{array}{ll} e_k^2 &= -1 & ext{for each } k \;, \ e_k e_l \,+\, e_l e_k = 0 & ext{for each distinct } k, l \;, \end{array}
ight.$$

and  $\{1, e_{k_1} \cdots e_{k_r}; k_1 < \cdots < k_r, 1 \leq r \leq \kappa\}$  forms a basis of the underlying vector space of  $C_{\kappa}$ , and hence dim  $C_{\kappa} = 2^{\kappa}$ . We denote by  $x \to x^*$  the canonical involution of  $C_{\kappa}$ , that is, the anti-automorphism of  $C_{\kappa}$  satisfying  $e_k = -e_k$  for each k. A homomorphism

$$\rho: C_{\kappa} \to M_m(\mathbf{R}) \text{ with } \rho(1) = 1_m$$

is called a representation of  $C_{\epsilon}$  of degree *m*. Two representations  $\rho$ ,  $\tilde{\rho}$  of  $C_{\epsilon}$  of degree *m* are said to be *equivalent* if there exists  $A \in GL(m, R)$  such that  $\tilde{\rho}(x) = A\rho(x)A^{-1}$  for each  $x \in C_{\epsilon}$ . The set of equivalence classes of representations of  $C_{\epsilon}$  of degree *m* will be denoted by  $\mathscr{R}_m(C_{\epsilon})$ .

We consider a representation  $\rho$  of  $C_{\kappa}$  of degree m satisfying

(7.1) 
$$\rho(x^*) = \rho(x)'$$
 for each  $x \in C_s$ ,

where ' indicates the transpose of a matrix. Two representations  $\rho$ ,  $\tilde{\rho}$  of  $C_{\epsilon}$  satisfying (7.1) are said to be orthogonally equivalent if there exists

q.e.d.

 $\sigma \in O(m)$  such that  $\tilde{\rho}(x) = \sigma \rho(x) \sigma^{-1}$  for each  $x \in C_{\kappa}$ . The set of orthogonal equivalence classes of representations of  $C_{\kappa}$  of degree *m* satisfying (7.1) will be denoted by  $\mathscr{R}_m(C_{\kappa}, *)$ .

LEMMA 21. The natural map:

$$\mathscr{R}_m(C_\kappa, *) \to \mathscr{R}_m(C_\kappa)$$

is a bijection.

**PROOF.\*** The bracket operation [x, y] = xy - yx on  $C_{\epsilon}$  defines a Lie algebra over  $\mathbf{R}$ , which is denoted by g. Since  $C_{\epsilon}$  is a semi-simple algebra over  $\mathbf{R}$ , it is the direct sum of a finite number of total matrix algebras. It follows that g has a natural structure of reductive algebraic Lie algebra over  $\mathbf{R}$ . Now the canonical involution  $x \to x^*$  of  $C_{\epsilon}$  is a positive involution in the sense that the symmetric bilinear form  $\operatorname{Tr}(L_{xy^*})$  on  $C_{\epsilon}$  is positive definite,  $L_x$  being the left regular representation of  $C_{\epsilon}: L_x y = xy$ . In fact, for  $x_0 = e_{i_1} \cdots e_{i_r}, y_0 = e_{j_1} \cdots e_{j_s}(i_1 < \cdots < i_r, j_1 < \cdots < j_s)$ , we have

$$x_{\scriptscriptstyle 0}y_{\scriptscriptstyle 0}^{\,m st} = egin{cases} 1 & r = s,\,\{i_{\scriptscriptstyle 1},\,\cdots,\,i_{\scriptscriptstyle r}\} = \{j_{\scriptscriptstyle 1},\,\cdots,\,j_{\scriptscriptstyle s}\}\ \pm e_{k_{\scriptscriptstyle 1}}\cdots e_{k_{\scriptscriptstyle t}},\,t > 0 & ext{otherwise} \ , \end{cases}$$

where

$$\{k_1, \dots, k_t\} = \{i_1, \dots, i_r\} \cup \{j_1, \dots, j_s\} - \{i_1, \dots, i_r\} \cap \{j_1, \dots, j_s\}$$
.

Thus we have

$${
m Tr}\;(L_{x_0y_0^\star}) = egin{cases} \dim C_{\kappa} = 2^{\kappa} > 0 & r = s,\,\{i_1,\,\cdots,\,i_r\} = \{j_1,\,\cdots,\,j_s\} \ 0 & ext{otherwise} \;, \end{cases}$$

and hence  $\operatorname{Tr}(L_{xy^*})$  is positive definite on  $C_x$ . Thus, by a theorem of Weil [8], the map  $\theta$  of g defined by  $x \to -x^*$  is a Cartan involution of g.

We shall show first the surjectivity. Let  $\rho$  be a representation of  $C_{\epsilon}$  of degree *m*. Then the representation

 $\rho: \mathfrak{g} \to \mathfrak{gl}(m, R)$ 

is completely reducible. Hence there exists a Cartan involution  $\theta_0$  of gl(m, R) such that

$$\theta_0(\rho(x)) = \rho(\theta(x))$$
 for each  $x \in g$ .

 $\theta_0$  can be expressed as

$$\theta_0(X) = -P^{-1}X'P$$
 for  $X \in \mathfrak{gl}(m, R)$ 

<sup>\*</sup> The proof of surjectivity is due to I. Satake.

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by a positive definite symmetric matrix  $P \in M_m(R)$ . Thus we have

$$\rho(x^*) = P^{-1}\rho(x)'P \qquad \text{for } x \in C_{\kappa}.$$

Put  $A = P^{1/2}$  and

$$ilde{
ho}(x) = A 
ho(x) A^{-1}$$
 for  $x \in C_{\kappa}$ .

Then we have for each  $x \in C_{\kappa}$ 

$$egin{aligned} \widetilde{
ho}(x^*) &= A
ho(x^*)A^{_{-1}} = AP^{_{-1}}
ho(x)'PA^{_{-1}} \ &= A'^{_{-1}}
ho(x)'A' = \widetilde{
ho}(x)' \;, \end{aligned}$$

and hence  $\tilde{\rho}$  satisfies (7.1). This proves the surjectivity of the map.

To prove the injectivity, let  $\rho$  and  $\tilde{\rho}$  be mutually equivalent representations of  $C_{\kappa}$  satisfying (7.1). Let  $A \in GL(m, \mathbb{R})$  such that

(7.2) 
$$\tilde{\rho}(x) = A \rho(x) A^{-1} \qquad \text{for } x \in C_{\kappa} .$$

Then we have  $\tilde{\rho}(x^*) = A\rho(x^*)A^{-1}$  for each  $x \in C_x$ . From the condition (7.1) we have  $\tilde{\rho}(x)' = A\rho(x)'A^{-1}$  and hence

(7.3) 
$$\widetilde{\rho}(x) = A'^{-1}\rho(x)A' \qquad \text{for } x \in C_{\kappa}$$

(7.2) and (7.3) imply that the symmetric matrix A'A commutes with each  $\rho(x)$ . Now write A as the product:  $A = \sigma P$  of  $\sigma \in O(m)$  and a positive definite symmetric matrix P. Then  $A'A = P^2$  commutes with each  $\rho(e_k)$ . From the condition (7.1),  $\tau_t = \exp t\rho(e_k)$  is in O(m) for each  $t \in \mathbf{R}$ , and hence  $\tau_t P \tau_t^{-1}$  is also a positive definite symmetric matrix. It follows from  $\tau_t P^2 \tau_t^{-1} = (\tau_t P \tau_t^{-1})^2 = P^2$  that each  $\tau_t$  commutes with P and hence each  $\rho(e_k)$  commutes with P. Since  $C_k$  is generated by  $e_1, \dots, e_k$ , we have

$$\widetilde{
ho}(x) = \sigma 
ho(x) \sigma^{-1}$$
 for  $x \in C_{\star}$  .

Thus  $\rho$  and  $\tilde{\rho}$  are orthogonally equivalent.

The subspace of  $C_{\kappa}$  spanned by  $e_1, \dots, e_{\kappa}$  is identified with  $\mathbf{R}^{\kappa}$  in a natural way, and any orthogonal transformation  $\sigma$  of  $\mathbf{R}^{\kappa}(\sigma \in O(\kappa))$  is extended uniquely to an automorphism  $\sigma$  of  $C_{\kappa}$ . For a representation  $\rho$  of  $C_{\kappa}$  of degree m, we define another representation  $\sigma\rho$  by

$$(\sigma \rho)(x) = \rho(\sigma^{-1}x)$$
 for  $x \in C_{\kappa}$ .

If  $\rho$  satisfies (7.1), then  $\sigma\rho$  also satisfies (7.1), since the automorphism  $\sigma$  of  $C_{\kappa}$  commutes with the canonical involution  $x \to x^*$ . The correspondence  $(\sigma, \rho) \to \sigma\rho$  gives an action of  $O(\kappa)$  on  $\mathscr{R}_m(C_{\kappa})$  and on  $\mathscr{R}_m(C_{\kappa}, *)$ . Let  $O(\kappa) \setminus \mathscr{R}_m(C_{\kappa})$  and  $O(\kappa) \setminus \mathscr{R}_m(C_{\kappa}, *)$  denote the spaces of  $O(\kappa)$ -orbits respectively. Since the natural map  $\mathscr{R}_m(C_{\kappa}, *) \to \mathscr{R}_m(C_{\kappa})$  is  $O(\kappa)$ -equivariant, Lemma 21 gives us the natural bijection

$$O(\kappa) \setminus \mathscr{R}_m(C_\kappa, *) \to O(\kappa) \setminus \mathscr{R}_m(C_\kappa)$$
.

We cite Atiyah-Bott-Shapiro [1]: We have an isomorphism

(7.4)  $C_{\kappa+8}\cong C_\kappa\otimes M_{16}(R)$  ,

and the Clifford algebras  $C_{\kappa}$ 's for  $\kappa \leq 8$  are given by the following table;

κ	$C_{\kappa}$	$d(\kappa)$
1	С	2
2	H	4
3	$H \oplus H$	4
4	$M_{2}(H)$	8
5	$M_4(C)$	8
6	$M_{ m s}(oldsymbol{R})$	8
7	$M_{ m s}({m R}) \oplus M_{ m s}({m R})$	8
8	$M_{\scriptscriptstyle 16}({old R})$	16

where  $d(\kappa)$  denotes the degree of irreducible representations of  $C_{\kappa}$ . We have

$$(7.5) d(\kappa + 8) = 16d(\kappa)$$

in virtue of the isomorphism (7.4).

LEMMA 22. For  $\kappa \geq 1$ ,  $O(\kappa) \setminus \mathscr{R}_{\kappa+1}(C_{\kappa}, *)$  is not empty if and only if  $\kappa = 1, 3$  or 7. For  $\kappa = 1, 3$  or 7,  $O(\kappa) \setminus \mathscr{R}_{\kappa+1}(C_{\kappa}, *)$  consists of exactly one element, represented by an irreducible representation of  $C_{\kappa}$ .

**PROOF.** By Lemma 21, it suffices to show the above for the set  $O(\kappa) \setminus \mathscr{R}_{\kappa+1}(C_{\kappa})$ . From (7.5) we have

$$d(\kappa + 8) - (\kappa + 8) = 16d(\kappa) - \kappa - 8$$
  
=  $(15d(\kappa) - 8) + (d(\kappa) - \kappa) > d(\kappa) - \kappa$ .

It follows that if  $\mathscr{R}_{\kappa+1}(C_{\kappa})$  is not empty, then  $\kappa \leq 8$  and  $\mathscr{R}_{\kappa+1}(C_{\kappa})$  consists of equivalent classes of irreducible representations. From the table cited above we get the first assertion of Lemma 22.

In case  $\kappa = 1$ ,  $C_1 = C$  and  $\mathscr{R}_2(C_1)$  consists of just one class. In case  $\kappa = 3$ ,  $C_3 = H \bigoplus H$  and  $\mathscr{R}_4(C_3)$  consists of two classes. Putting  $z = e_1e_2e_3$  in  $C_3$ , we define  $f_+$ ,  $f_- \in C_3$  by

$$f_+ = \frac{1}{2}(1 + z), \ f_- = \frac{1}{2}(1 - z)$$
.

Then they are primitive idempotents of  $C_3$  defining the decomposition  $C_3 = H \bigoplus H$ . Since  $-1_3 \in O(3)$  transforms  $f_+$  into  $f_-$ ,  $O(3) \setminus \mathscr{R}_4(C_3)$  consists exactly one element. In case  $\kappa = 7$ , we see similarly that  $O(7) \setminus \mathscr{R}_8(C_7)$  consists exactly one element, making use of the element  $z = e_1e_2 \cdots e_7 \in C_7$ . q.e.d.

For  $\kappa = 1, 3, 7$ , we have  $C_{\kappa-1} \cong R$ , H,  $M_{8}(R)$  respectively. Hence we have

LEMMA 23. For  $\kappa = 1, 3, 7$ , the set  $\mathscr{R}_m(C_{\kappa-1}, *)$  is not empty if and only if m is a multiple of 1, 4, 8 respectively. In these cases,  $\mathscr{R}_m(C_{\kappa-1}, *)$  consists of exactly one class.

Now, let  $\kappa$ , m be positive integers. Consider a family  $\{a_k\}_{1 \le k \le \kappa}$  of  $\kappa$  matrices in  $M_m(\mathbf{R})$  satisfying the following condition:

(7.6) 
$$\begin{cases} a'_k a_k = 1_m & \text{for each } k \\ a'_k a_l + a'_l a_k = 0 & \text{for distinct } k, l \end{cases}$$

Two such families  $\{a_k\}$ ,  $\{\tilde{a}_k\}$  are said to be *equivalent* and denoted by  $\{a_k\} \sim \{\tilde{a}_k\}$  if there exist  $\sigma, \tau \in O(m)$  such that

$$\widetilde{a}_k = \sigma a_k \tau^{-1}$$
 for each  $k$ .

They are classified in terms of representations of Clifford algebras as follows.

LEMMA 24. The set of equivalence classes of families  $\{a_k\}$  of  $\kappa$  matrices in  $M_m(\mathbf{R})$  satisfying the condition (7.6) is in a bijective correspondence with the set  $\mathscr{R}_m(C_{\kappa-1}, *)$ .

**PROOF.** Let  $\rho$  be a representation of  $C_{\kappa-1}$  of degree *m* satisfying (7.1). We define  $\kappa$  matrices  $a_1, \dots, a_{\kappa}$  by

$$egin{cases} a_k = 
ho(e_k) & 1 \leq k \leq \kappa-1 \;, \ a_\kappa = 1_m \;. \end{cases}$$

Since we have

$$egin{array}{lll} \{a_k'=-a_k,\,a_k^2=-1_m & ext{for each }k,\,1\leq k\leq\kappa-1 \ a_ka_l+a_la_k=0 & ext{for distinct }k,\,l,\,1\leq k,\,l\leq\kappa-1 \ , \end{array}$$

the family  $\{a_k\}$  satisfies the condition (7.6). The correspondence  $\rho \to \{a_k\}$  induces a map of  $\mathscr{R}_m(C_{\kappa-1}, *)$  into the set of equivalence classes of families  $\{a_k\}$  satisfying (7.6). One can see easily that it is bijective. q.e.d.

Next, consider a family  $\{A_k\}_{1 \le k \le \kappa}$  of  $\kappa$  matrices in  $M_m(\mathbf{R})$  satisfying the following condition:

(7.7) 
$$\begin{cases} A'_k = -A_k, \ A^2_k = -1_m & \text{for each } k , \\ A_k A_l + A_l A_k = 0 & \text{for distinct } k, l . \end{cases}$$

Note that the condition (7.7) implies the condition (7.6). Two such families  $\{A_k\}, \{\tilde{A}_k\}$  are said to be *equivalent* and denoted by  $\{A_k\} \approx \{\tilde{A}_k\}$  if there exist  $\sigma \in O(m)$  and  $\tau = (\tau_{kl}) \in O(\kappa)$  such that

$$\widetilde{A}_k = \sum_{l=1}^{\kappa} \tau_{kl} (\sigma A_l \sigma^{-1})$$
 for each  $k$ .

They are also classified in terms of representations of Clifford algebras as follows.

LEMMA 25. The set of equivalence classes of families  $\{A_k\}$  of  $\kappa$  matrices in  $M_m(\mathbf{R})$  satisfying the condition (7.7) is in a bijective correspondence with the set  $O(\kappa) \setminus \mathscr{R}_m(C_{\kappa}, *)$ .

**PROOF.** For each representation  $\rho$  of  $C_{\kappa}$  of degree *m* satisfying (7.1), we define  $\kappa$  matrices  $A_{1}, \dots, A_{\kappa}$  by

$$A_k = \rho(e_k)$$
 for each  $k$ .

Then the family  $\{A_k\}$  satisfies the condition (7.7). The correspondence  $\rho \rightarrow \{A_k\}$  induces a bijection required in our lemma. q.e.d.

From Lemmas  $22 \sim 25$ , we have

LEMMA 26. There exists a family  $\{A_k\}$  of  $\kappa$  matrices in  $M_{\kappa+1}(\mathbf{R})$ satisfying the condition (7.7) if and only if  $\kappa = 1, 3, 7$ . For  $\kappa = 1, 3, 7$ , there exists a family  $\{a_k\}$  of  $\kappa$  matrices in  $M_m(\mathbf{R})$  satisfying the condition (7.6) if and only if m is a multiple of 1, 4, 8 respectively. In these cases, both of equivalence classes of  $\{A_k\}$  and  $\{a_k\}$  are unique.

8. Examples of non-homogeneous isoparametric hypersurfaces. Now we come back to families of quadratic forms  $\{p_{\alpha}\}$  and cubic forms  $\{q_{\alpha}\}$  on  $Y = \mathbb{R}^{n}$ . In this section we shall classify polynomials  $\{p_{\alpha}\}, \{q_{\alpha}\}$  under certain conditions and construct two series of non-homogeneous isoparametric hypersurfaces.

As in §5, let

$$Y = U \oplus V \oplus Z$$

be the eigenspace decomposition of the symmetric mapping  $P_0$  corresponding to  $p_0$ , where U, V and Z are the eigenspaces for the eigenvalues 1, -1 and 0 respectively. Recall dim  $U = \dim V = m_2$  and dim  $Z = m_1$ . We choose orthonormal coordinate systems  $\{u_i\}, \{v_i\}$  and  $\{z_k\}$  for U, V and Z respectively. Each symmetric mapping  $P_k$  corresponding to  $p_k$  for  $k \ge 1$  will be represented by a matrix with respect to these coordinates

as in Lemma 14.

LEMMA 27. Assume that  $P_0$  is represented in the above way. Then the family  $\{p_{\alpha}\}$  satisfies (3-1), (3-2) and the condition (A) if and only if (1) each  $P_k(1 \leq k \leq m_1)$  is represented by a matrix of the form

$$\begin{pmatrix} 0 & a_k & 0 \\ a'_k & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

with  $a_k \in M_{m_2}(\mathbf{R})$  and (2) the family  $\{a_k\}$  satisfies the condition (7.6) for  $\kappa = m_1$  and  $m = m_2$ .

**PROOF.** First suppose  $\{p_{\alpha}\}$  satisfies (3-1), (3-2) and (A). Then the family  $\{R_{\alpha}\}$  of symmetric mappings of  $U \bigoplus V$  associated to  $\{p_{\alpha}\}$  in §6 satisfies (5-1) and (5-2). The condition (5-2) for  $\alpha = 0$  and  $\beta = k$  implies that  $R_k$  is represented by a matrix of the form

$$\begin{pmatrix} 0 & a_k \\ a'_k & 0 \end{pmatrix}$$

with  $a_k \in M_{m_2}(\mathbf{R})$ . Now (5-1) gives

(i)  $a_k a'_k = a'_k a_k = \mathbf{1}_{m_2}$  for each k,

and also (5-2) gives

(ii)  $\begin{cases} a_k a'_l + a_l a'_k = 0 \\ a'_k a_l + a'_l a_k = 0 \end{cases}$  for distinct k, l

where  $1 \leq k, l \leq m_1$ . (i) and (ii) together are equivalent to the condition (7.6), thereby obtaining (1) and (2) of Lemma 27.

The converse follows from the above argument and Lemma 18.

q.e.d.

Now let  $\{p_{\alpha}\}$  be a family of quadratic forms on Y satisfying (3-1), (3-2) and (A), and let  $\{q_{\alpha}\}$  be a family of cubic forms on Y. We assume the following additional condition:

(B) For each  $\alpha$ ,  $q_{\alpha}$  is expressed as

$$q_{\scriptscriptstyle lpha} = \sum_{\scriptscriptstyle eta} \lambda_{\scriptscriptstyle lpha \scriptscriptstyle eta} p_{\scriptscriptstyle eta}$$

where  $\lambda_{\alpha\beta}$ 's are linear forms on Z.

First note that the above expression of  $q_{\alpha}$  is unique by virtue of Lemma 20. We put

(8.1) 
$$\lambda_{\alpha\beta} = \sum_{k=1}^{m_1} a_{\alpha\beta k} z_k$$

for each  $\alpha$ ,  $\beta$ , and define  $m_1$  matrices  $A_1, \dots, A_{m_1}$  in  $M_{m_1+1}(\mathbf{R})$  by

$$(8.2) A_k = (a_{\alpha\beta k})_{0 \leq \alpha, \beta \leq m_1}$$

for each k,  $1 \leq k \leq m_1$ .

LEMMA 28. As in the above, suppose that  $\{p_{\alpha}\}$  and  $\{q_{\alpha}\}$  satisfy (3-1) and (3-2) together with (A) and (B). Then,  $\{p_{\alpha}\}$  and  $\{q_{\alpha}\}$  satisfy the conditions (3-4), (3-5), (3-7), (5-8), (5-9) and (5-10) if and only if the family  $\{A_k\}$  of  $m_1$  matrices in  $M_{m_1+1}(\mathbf{R})$  satisfies the condition (7.7) and the following condition:

(8.3) 
$$\frac{1}{2}\sum_{k}\left(a_{\alpha\gamma k}a_{\beta\delta k}+a_{\alpha\delta k}a_{\beta\gamma k}\right)=\delta_{\alpha\beta}\delta_{\gamma\delta}$$

for each  $\alpha$ ,  $\beta$ ,  $\gamma$ ,  $\delta$  with  $\{\alpha, \beta\} \cap \{\gamma, \delta\} = \emptyset$ .

**PROOF.** Note that the above condition (8.3) is equivalent to the following two conditions:

(8.3.1) 
$$\sum_{k} a_{\alpha\beta k} a_{\alpha\gamma k} = \delta_{\beta\gamma} \text{ for each } \alpha, \beta, \gamma \text{ with } \beta \neq \alpha, \gamma \neq \alpha ;$$

(8.3.2) 
$$\sum_{k} (a_{\alpha\gamma k} a_{\beta\delta k} + a_{\alpha\delta k} a_{\beta\gamma k}) = 0$$
 for mutually distinct  $\alpha, \beta, \gamma, \delta$ .

Similarly, the condition (7.7) decomposes into

(7.7.1) 
$$A_k + A'_k = 0$$
 for each k;

(7.7.2) 
$$\begin{cases} A'_k A_k = \mathbf{1}_{m_1+1} & \text{for each } k , \\ A'_k A_l + A'_l A_k = 0 & \text{for distinct } k, l \end{cases}$$

First we show the following implications:  $(3-7) \Leftrightarrow (7.7.1); (7.7.1) \Rightarrow (3-4)$  and (3-5); and then  $(5-8) \Leftrightarrow (7.7.2)$ .

Recall (3-7):  $\sum p_{\alpha}q_{\alpha} = 0$ . We have

$$\sum\limits_lpha p_lpha q_lpha = \sum\limits_{lpha, eta} \lambda_{lpha eta} p_lpha p_eta = rac{1}{2} \sum\limits_k \Big\{ \sum\limits_{lpha, eta} (a_{lpha eta k} + a_{eta lpha k}) p_lpha p_eta \Big\} z_k \; .$$

By Lemma 20, we see (3-7)  $\Leftrightarrow$  (7.7.1). Since each  $\lambda_{\beta\gamma}$  is a linear form on Z, we have  $\langle p_{\alpha}, \lambda_{\beta\gamma} \rangle = 0$ . Thus, we have

$$\langle p_{lpha},\,q_{eta}
angle = \sum_{\gamma}\lambda_{eta\gamma}\langle p_{lpha},\,p_{\gamma}
angle = \lambda_{etalpha}\langle p_{0},\,p_{0}
angle$$
 ,

using Lemma 17. Therefore we can write

$$\langle p_{lpha},\,q_{eta}
angle+\langle p_{eta},\,q_{lpha}
angle=(\lambda_{lphaeta}+\,\lambda_{lphaeta})\!\langle p_{\scriptscriptstyle 0}\!,\,p_{\scriptscriptstyle 0}
angle\,.$$

This shows  $(7.7.1) \Rightarrow (3-4)$  and (3-5). Recall (5-8):  $\sum q_{\alpha}^2 = G(\sum z_k^2)$ . We have

$$\sum_{lpha} q_{lpha}^2 = \sum_{lpha} \left( \sum_{eta} \lambda_{lphaeta} p_{eta} 
ight)^2 = \sum_{lpha,eta,\gamma} \lambda_{lphaeta} \lambda_{lpha\gamma} p_{eta} p_{\gamma} \ = rac{1}{2} \sum_{lpha,eta,\gamma,k,l} (a_{lphaeta} a_{lpha\gamma l} + a_{lphaeta l} a_{lpha\gamma k}) p_{eta} p_{\gamma} z_k z_l \;,$$

and

$$G\!\left(\sum\limits_k {oldsymbol z}_k^2
ight) = \left(\sum\limits_k {oldsymbol z}_k^2
ight)\!\left(\sum\limits_lpha {oldsymbol p}_lpha^2
ight).$$

Now (5-8) is equivalent to

$$egin{array}{ll} & \displaystyle \sum_{lpha,eta, au} a_{lphaeta k} a_{lpha au k} p_eta p_{ au} & = \sum_eta p_eta^2 & ext{for each } k \;, \ & \displaystyle \sum_{lpha,eta, au} (a_{lphaeta k} a_{lpha au l} + a_{lphaeta l} a_{lpha au k}) p_eta p_{ au} & = 0 & ext{for distinct } k, l \;, \ & \displaystyle \ext{for distinct } k, l \;, \end{array}$$

.

which is, by Lemma 20, equivalent to

$$\begin{cases} \sum_{\alpha} a_{\alpha\beta k} a_{\alpha\gamma k} = \delta_{\beta\gamma} & \text{for each } \beta, \gamma, k , \\ \sum_{\alpha} (a_{\alpha\beta k} a_{\alpha\gamma l} + a_{\alpha\beta l} a_{\alpha\gamma k}) = 0 & \text{for each } \beta, \gamma \text{ and distinct } k, l . \end{cases}$$

This is nothing but (7.7.2), thereby obtaining the implications described first.

Henceforth we assume the condition (7.7). Consider the condition (5-9). We have

$$egin{aligned} &\langle q_lpha,\,q_lpha
angle &= \left\langle \sum_eta \lambda_{lphaeta} p_eta,\,\sum_ au \lambda_{lpha au} p_ au
ight
angle 
ight
angle \ &= \sum_{eta, au} \left\langle \lambda_{lphaeta},\,\lambda_{lpha au} 
ight
angle p_eta p_ au + \sum_{eta, au} \lambda_{lphaeta} \lambda_{lpha au} \left\langle p_{eta},\,p_ au
ight
angle 
ight
angle \ &= \sum_{eta, au,k} a_{lphaeta k} a_{lpha au k} p_eta p_ au + 4 (\sum u_i^2 + \sum v_i^2) \sum_{eta,k,l} a_{lphaeta k} a_{lphaeta l} z_k z_l \ , \end{aligned}$$

and

$$egin{array}{ll} G &= p_{lpha}^{2} + 4(\sum u_{i}^{2} + \sum v_{i}^{2})(\sum z_{k}^{2}) \ &= \sum \limits_{lpha 
eq eta} p_{eta}^{2} + 4(\sum u_{i}^{2} + \sum v_{i}^{2})(\sum z_{k}^{2}) \;. \end{array}$$

Again by Lemma 20, we see that (5.9) is equivalent to the following three conditions:

(i) 
$$\sum_{k} a_{\alpha\beta k} a_{\alpha\gamma k} = \delta_{\beta\gamma} \text{ for each } \alpha, \beta, \gamma \text{ with } \beta \neq \alpha, \gamma \neq \alpha ;$$

(ii) 
$$\sum_{k} a_{\alpha\alpha k} a_{\alpha\alpha k} = 0$$
 for each  $\alpha$ ;

(iii) 
$$\sum_{\beta} a_{\alpha\beta k} a_{\alpha\beta l} = \delta_{kl}$$
 for each  $\alpha, k, l$ .

Since (ii) and (iii) follow from (7.7), we have  $(5-9) \Leftrightarrow (i) = (8.3.1)$ . By a similar computation, we can see  $(5-10) \Rightarrow (8.3.2)$  and  $(8.3) \Rightarrow (5-10)$ .

Now we recall some properties of inner products on division algebras over R. Let F be a (not necessarily associative) division algebra over R, i.e., F = R, C, H or the real Cayley algebra K. Let  $c_0 = 1, c_1, \dots, c_{d-1}$ be the standard units of F with  $d = \dim F$ .  $u \to \overline{u}$  denotes the canonical involution of F. We put  $\Im F = \{u \in F | \overline{u} = -u\}$ . Then  $\Im F$  is a (d-1)dimensional subspace of F spanned by  $c_1, \dots, c_{d-1}$ . The subspace R1 = $\{u \in F | \overline{u} = u\}$  will be identified with R in a natural way. On F,

$$(u, v) = \frac{1}{2}(u\overline{v} + v\overline{u})$$

defines an inner product with the following properties:

$$egin{aligned} &(ar{u},\,ar{v})=(u,\,v)\ ,\ &(uv,\,w)=(v,\,ar{u}w)=(u,\,war{v})\ ,\ &ar{u}(vw)+v(ar{u}w)=(wu)ar{v}+(wv)ar{u}=2(u,\,v)w\ . \end{aligned}$$

 $\{c_0, c_1, \dots, c_{d-1}\}$  forms an orthonormal basis of F with respect to the above inner product. The dual base  $\{u_0, u_1, \dots, u_{d-1}\}$  of  $\{c_0, c_1, \dots, c_{d-1}\}$  forms an orthonormal coordinate system for F, which we call standard. (,) is extended to the *m*-column vector space  $F^m$  by

$$(u, v) = \frac{1}{2}(u'\overline{v} + v'\overline{u})$$

for  $u, v \in F^m$ , where ' denotes the transpose. The standard orthonormal coordinate system for  $F^m$  consists of  $\{u_i^{(\lambda)} | 0 \leq i \leq d-1, 1 \leq \lambda \leq m\}$  where  $\{u_i^{(\lambda)} | 0 \leq i \leq d-1\}$  denotes the standard orthonormal coordinates for the  $\lambda$ -th component  $u^{(\lambda)}$  of  $u \in F^m$ . We write also ||u|| for the norm  $(u, u)^{1/2}$  of a vector u.

THEOREM 2. Let  $m_1$  and  $m_2$  be positive integers such that  $N = 2(m_1 + m_2 + 1)$ , and set  $n = m_1 + 2m_2$ .

(i) There exist  $m_1 + 1$  quadratic forms  $\{p_{\alpha}\}$  and  $m_1 + 1$  cubic forms  $\{q_{\alpha}\}$  on  $Y = \mathbb{R}^n$  satisfying the equations (3-1) ~ (3-10) together with the conditions (A) and (B) if and only if the pair  $(m_1, m_2)$  is one of the following three types: (1, r), (3, 4r), (7, 8r) for some positive integer r. In these cases, the polynomial F associated to such  $\{p_{\alpha}, q_{\alpha}\}$  is unique up to (ON)-equivalence.

(ii) The polynomial F on  $\mathbb{R}^N$  associated to such  $\{p_{\alpha}, q_{\alpha}\}$  is given explicitly as follows:

(a)  $(m_1, m_2) = (1, r)$ ; We define a polynomial  $F_0$  on  $\mathbb{R}^{2(r+2)} = \mathbb{C}^{r+2}$  by

$$F_0(\hat{arsigma}) = \left\| \sum_{i=1}^{r+2} \xi_i^2 \right\|^2 \quad for \quad \xi = egin{pmatrix} \xi_1 \ dots \ dots \ \xi_{r+2} \end{pmatrix} \in C^{r+2} ext{ ,}$$

and set  $F = r^4 - 2F_0$ .

(b)  $(m_1, m_2) = (3, 4r)$  or (7, 8r); **F** denotes **H** or **K** according to  $m_1 = 3$  or 7. We define a polynomial  $F_0$  on  $\mathbb{R}^N = \mathbb{F}^{2(r+1)} = \mathbb{F}^{r+1} \times \mathbb{F}^{r+1}$  by

$$F_{0}(u \times v) = 4\{||u'\bar{v}||^{2} - (u, v)^{2}\} + \{||u_{1}||^{2} - ||v_{1}||^{2} + 2(u_{0}, v_{0})\}^{2}$$

for

$$u=egin{pmatrix} u_{_0}\ u_{_1} \end{pmatrix}$$
 ,  $v=egin{pmatrix} v_{_0}\ v_{_1} \end{pmatrix}$  ,  $u_{_0}$ ,  $v_{_0}$   $\in$   $oldsymbol{F}$  ,  $u_{_1}$ ,  $v_{_1}$   $\in$   $oldsymbol{F}^r$  ,

and set  $F = r^4 - 2F_0$ .

In each case, F satisfies the differential equations (M) of Münzner.

REMARK. Takagi-Takahashi [7] gave the multiplicities of principal curvatures for homogeneous isoparametric hypersurfaces in spheres. Our pairs  $(m_1, m_2)$  of multiplicities in the case (b) do not appear in their table except  $(m_1, m_2) = (3, 4)$ . Hence our isoparametric hypersurfaces given in the above case (b) are not homogeneous, possibly except the case where  $(m_1, m_2) = (3, 4)$ . However, in Part II it will be shown that our isoparametric hypersurfaces for  $(m_1, m_2) = (3, 4)$  are also non-homogeneous.

PROOF OF (i). The "only if" part follows immediately from Lemmas 26, 27, 28. Conversely, assume that  $(m_1, m_2)$  is (1, r), (3, 4r) or (7, 8r). Let F = C, H or K respectively, so that dim  $F = m_1 + 1$ . In the following, indices  $k, l, \cdots$  and  $\alpha, \beta, \cdots$  run through  $1, 2, \cdots, m_1$  and  $0, 1, \cdots, m_1$  respectively. For  $u, v \in F$  we have

$$(\mathbf{c}_k u, v) = (u, \overline{c}_k v) = -(c_k v, u)$$
 for each  $k$   
 $c_k(c_k u) = -\overline{c}_k(c_k u) = -(c_k, c_k)u = -u$  for each  $k$   
 $c_k(c_l u) + c_l(c_k u) = -\overline{c}_k(c_l u) - \overline{c}_l(c_k u) = -2(c_k, c_l)u = 0$ 

for distinct k, l.

We define  $A_1, \dots, A_{m_1} \in M_{m_1+1}(\mathbf{R})$  by

 $A_k = (a_{lphaeta k})_{0 \leq lpha, eta \leq m_1}$  with  $a_{lphaeta k} = (c_k c_eta, c_lpha)$ 

for each k. Then  $\{A_k\}$  satisfy (7.7) as is easily seen from the above properties. Consider (8.3). For each  $\alpha$ ,  $\beta$ ,  $\gamma$ ,  $\delta$  with  $\{\alpha, \beta\} \cap \{\gamma, \delta\} = \emptyset$ , we have

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$$\begin{split} \sum_{k} \left( a_{\alpha\gamma k} a_{\beta\delta k} + a_{\alpha\delta k} a_{\beta\gamma k} \right) \\ &= \sum_{k} \left( c_{k} c_{\gamma}, \, c_{\alpha} \right) (c_{k} c_{\delta}, \, c_{\beta}) + \sum_{k} \left( c_{k} c_{\delta}, \, c_{\alpha} \right) (c_{k} c_{\gamma}, \, c_{\beta}) \\ &= \sum_{\epsilon} \left( c_{\epsilon} c_{\gamma}, \, c_{\alpha} \right) (c_{\epsilon} c_{\delta}, \, c_{\beta}) + \sum_{\epsilon} \left( c_{\epsilon} c_{\delta}, \, c_{\alpha} \right) (c_{\epsilon} c_{\gamma}, \, c_{\beta}) \\ &= \sum_{\epsilon} \left( c_{\epsilon}, \, c_{\alpha} \overline{c}_{\gamma} \right) (c_{\epsilon}, \, c_{\beta} \overline{c}_{\delta}) + \sum_{\epsilon} \left( c_{\epsilon}, \, c_{\alpha} \overline{c}_{\delta} \right) (c_{\epsilon}, \, c_{\beta} \overline{c}_{\gamma}) \\ &= \left( c_{\alpha} \overline{c}_{\gamma}, \, c_{\beta} \overline{c}_{\delta} \right) + \left( c_{\alpha} \overline{c}_{\delta}, \, c_{\beta} \overline{c}_{\gamma} \right) \\ &= \left( \overline{c}_{\beta} (c_{\alpha} \overline{c}_{\gamma}), \, \overline{c}_{\delta} \right) + \left( \overline{c}_{\delta}, \, \overline{c}_{\alpha} (c_{\beta} \overline{c}_{\gamma}) \right) \\ &= 2 (c_{\beta}, \, c_{\alpha}) (\overline{c}_{\gamma}, \, \overline{c}_{\delta}) = 2 (c_{\alpha}, \, c_{\beta}) (c_{\gamma}, \, c_{\delta}) \\ &= 2 \delta_{\alpha\beta} \delta_{\gamma\delta} \, , \end{split}$$

and hence we have (8.3) for  $\{A_k\}$ .

Next, we define  $m_1$  matrices  $\{a_k\}$  in  $M_{m_2}(\mathbf{R})$  as follows: for  $m_1 = 1$ 

$$a_k=1_r$$
,

and for  $m_1 = 3$  or 7

$$a_k = egin{pmatrix} A_k & 0 \ \ddots & 0 \ 0 & A_k \end{pmatrix}$$

where  $A_k$  appears r-times in the diagonal. One sees easily that  $\{a_k\}$  satisfy (7.6).

Now by Lemma 27 we can associate to the matrices  $\{a_k\}$   $m_1 + 1$  quadratic forms  $\{p_{\alpha}\}$  on Y, satisfying (3-1), (3-2) and (A). From the matrices  $\{A_k\}$ , using (8.1) we can define  $m_1 + 1$  cubic forms on Y, satisfying (B). Our polynomials  $\{p_{\alpha}\}, \{q_{\alpha}\}$  satisfy, in virtue of Lemma 28, (3-4), (3-5), (3-7), (5-8), (5-9), (5-10), and hence the equations  $(3-1) \sim (3-10)$  by Lemma 19, which proves the "if" part of (i).

It remains to prove the uniqueness. Let  $\{p_{\alpha}, q_{\alpha}\}$  and  $\{\tilde{p}_{\alpha}, \tilde{q}_{\alpha}\}$  be two families of polynomials on Y satisfying the conditions in (i), and let Fand  $\tilde{F}$  be the associated polynomials on  $\mathbb{R}^{N}$  respectively. Let

$$(1) Y = U \oplus V \oplus Z,$$

$$(2) Y = \widetilde{U} \oplus \widetilde{V} \oplus \widetilde{Z}$$

be the eigenspace decompositions of symmetric mappings  $P_0$ ,  $\tilde{P}_0$  corresponding to  $p_0$ ,  $\tilde{p}_0$  respectively. We take orthonormal coordinate systems  $\{u_i\}, \{v_i\}, \{z_k\}$  for U, V, W respectively. Linear mappings of Y will be represented by matrices with respect to these coordinates.

Choosing  $\sigma_{_1} \in O(n)$  such that  $\sigma_{_1}U = \widetilde{U}, \, \sigma_{_1}V = \widetilde{V}$  and  $\sigma_{_1}Z = \widetilde{Z}$ , we put

$$p^{\scriptscriptstyle (1)}_lpha=\sigma^{\scriptscriptstyle -1}_{\scriptscriptstyle 1}\widetilde{p}_lpha$$
 ,  $q^{\scriptscriptstyle (1)}_lpha=\sigma^{\scriptscriptstyle -1}_{\scriptscriptstyle 1}\widetilde{q}_lpha$  .

Then the polynomials  $\{p_{\alpha}^{(1)}, q_{\alpha}^{(1)}\}$  also satisfy the conditions in (i) and the eigenspace decomposition of  $P_0^{(1)}$  corresponding to  $p_0^{(1)}$  is the same as (1). The condition (B) for  $\{p_{\alpha}, q_{\alpha}\}$  and  $\{p_{\alpha}^{(1)}, q_{\alpha}^{(1)}\}$  gives  $\{A_k\}$  and  $\{A_k^{(1)}\}$  in  $M_{m_1+1}(\mathbf{R})$  respectively, which satisfy (7.7) by Lemma 28. It follows from Lemma 26 that  $\{A_k\} \approx \{A_k^{(1)}\}$ , that is, there exist  $\varphi = (\varphi_{kl}) \in O(m_1)$  and  $\tau = (\tau_{\alpha\beta}) \in O(m_1 + 1)$  such that

$$A_k^{(1)} = \sum_l \varphi_{kl}(\tau A_l \tau^{-1})$$
 for each  $k$ .

We put

$$p_{\scriptscriptstyle lpha}^{\scriptscriptstyle (2)} = \sum_{\scriptscriptstyle eta} au_{\scriptscriptstyle lphaeta} p_{\scriptscriptstyle eta}$$
 .

Then the quadratic forms  $\{p_{\alpha}^{(2)}\}$  also satisfy (3-1), (3-2), (A). Let

$$Y = U^{\scriptscriptstyle (2)} \oplus V^{\scriptscriptstyle (2)} \oplus Z$$

be the eigenspace decomposition of  $P_0^{(2)}$  corresponding to  $p_0^{(2)}$ . Choosing  $\sigma_2 \in O(n)$  such that  $\sigma_2 U^{(2)} = U$ ,  $\sigma_2 V^{(2)} = V$ ,  $\sigma_2 | Z = \text{identity}$ , we put

$$p_{\alpha}^{\scriptscriptstyle (3)} = \sigma_2 p_{\alpha}^{\scriptscriptstyle (2)}.$$

Then  $\{p_{\alpha}^{(3)}\}$  also satisfy (3-1), (3-2), (A), and the eigenspace decomposition of  $P_0^{(3)}$  corresponding to  $p_0^{(3)}$  is the same as (1). It follows from Lemma 27 that  $\{p_{\alpha}^{(1)}\}$  and  $\{p_{\alpha}^{(3)}\}$  define  $\{a_k^{(1)}\}$  and  $\{a_k^{(3)}\}$  in  $M_{m_2}(\mathbf{R})$  respectively, satisfying (7.6). By Lemma 26, we have  $\{a_k^{(1)}\} \sim \{a_k^{(3)}\}$ , that is, we can find  $\sigma_s$ ,  $\sigma_4 \in O(m_2)$  such that

$$\sigma_{\scriptscriptstyle 3} a_{\scriptscriptstyle k}^{\scriptscriptstyle (3)} \sigma_{\scriptscriptstyle 4}^{\scriptscriptstyle -1} = a_{\scriptscriptstyle k}^{\scriptscriptstyle (1)} \quad ext{for each} \quad k \; .$$

Putting together  $\sigma_3$ ,  $\sigma_4$  and  $\varphi^{-1}$ , we get an element  $\sigma_3 \times \sigma_4 \times \varphi^{-1} \in O(m_2) \times O(m_2) \times O(m_1) \subset O(n)$ . Put  $\sigma = \sigma_1(\sigma_3 \times \sigma_4 \times \varphi^{-1})\sigma_2 \in O(n)$ . Then we have

$$\widetilde{p}_lpha = \sum_eta au_{lphaeta}(\sigma p_eta), \ \widetilde{q}_lpha = \sum_eta au_{lphaeta}(\sigma q_eta) \ \ ext{for each} \ \ lpha \ ,$$

which gives the required uniqueness. In fact,

$$\sum\limits_{\scriptscriptstyle eta} au_{\scriptscriptstyle lphaeta}(\sigma p_{\scriptscriptstyle eta}) = \sigma p_{\scriptscriptstyle lpha}^{\scriptscriptstyle (2)} = \sigma_{\scriptscriptstyle 1}(\sigma_{\scriptscriptstyle 3} imes \sigma_{\scriptscriptstyle 4} imes arphi^{\scriptscriptstyle -1}) p_{\scriptscriptstyle lpha}^{\scriptscriptstyle (3)} = \sigma_{\scriptscriptstyle 1} p_{\scriptscriptstyle lpha}^{\scriptscriptstyle (1)} = \widetilde{p}_{\scriptscriptstyle lpha} \; .$$

Denoting by  $a_{\alpha\beta k}, a_{\alpha\beta k}^{(1)}$  the  $(\alpha, \beta)$ -elements of  $A_k, A_k^{(1)}$  respectively, we have

$$\begin{split} \sigma_1^{-1} & \left( \sum_{\beta} \tau_{\alpha\beta} (\sigma q_{\beta}) \right) = (\sigma_3 \times \sigma_4 \times \varphi^{-1}) \sigma_2 \Big( \sum_{\beta, \gamma, l} \tau_{\alpha\beta} a_{\beta\gamma l} z_l p_{\gamma} \Big) \\ &= \sum_{\beta, \gamma, l} \tau_{\alpha\beta} a_{\beta\gamma l} (\varphi^{-1} z_l) (\sigma_3 \times \sigma_4 \times \varphi^{-1}) \sigma_2 \Big( \sum_{\delta} \tau_{\delta\gamma} p_{\delta}^{(2)} \Big) \\ &= \sum_{\beta, \gamma, \delta, l, k} \tau_{\alpha\beta} a_{\beta\gamma l} \varphi_{kl} \tau_{\delta\gamma} z_k p_{\delta}^{(1)} = \sum_{\delta, k} a_{\alpha\delta k}^{(1)} z_k p_{\delta}^{(1)} = q_{\alpha}^{(1)} , \end{split}$$

and hence

$$\sum_{\scriptscriptstyle{\theta}} \tau_{\scriptscriptstyle{lpha}\scriptscriptstyle{eta}} \left( \sigma q_{\scriptscriptstyle{eta}} 
ight) = \widetilde{q}_{\scriptscriptstyle{lpha}}$$
 .

It follows that F and  $\tilde{F}$  are O(N)-equivalent.

PROOF OF (ii). (b) 
$$m_1 = 3$$
 or 7. Let  $F = H$  or  $K$  respectively. Let  $U = F^r, V = F^r, \hat{Z} = F, W = F, Z = \Im F \subset \hat{Z}$ ,

and let

$$oldsymbol{R}^{\scriptscriptstyle N} = U igoplus V igoplus \widehat{Z} igoplus W$$
 , $Y = U igodow V igodow Z$ 

be the orthogonal direct sums. Elements of U, V, Z, W will be denoted by u, v, z, w respectively. The standard orthonormal coordinate systems for  $U, V, \hat{Z}, W$  are denoted by  $\{u_i^{(1)}\}, \{v_i^{(1)}\}, \{z_{\alpha}\}, \{w_{\alpha}\}$  respectively, and they as a whole form an orthonormal coordinate system for  $\mathbb{R}^N$ . As a base point e in  $\mathbb{R}^N$ , we take the unit  $c_0$  in  $\hat{Z}$  so that we have  $z = z_0$  in the notation of §3. We compute polynomials  $\{p_{\alpha}\}, \{q_{\alpha}\}$  on Y corresponding to matrices  $\{a_k\}, \{A_k\}$  given in the proof of (i), with respect to the above orthonormal coordinate system. We have

$$\begin{split} p_{0} &= \sum_{\substack{0 \leq i \leq m_{1} \\ 1 \leq \lambda \leq \tau}} \{ (u_{i}^{(\lambda)})^{2} - (v_{i}^{(\lambda)})^{2} \} = || u ||^{2} - || v ||^{2} ,\\ p_{k} &= 2 \sum_{\substack{0 \leq i, j \leq m_{1} \\ 1 \leq \lambda \leq \tau}} (c_{k}c_{j}, c_{i}) u_{i}^{(\lambda)} v_{j}^{(\lambda)} = 2 \sum_{1 \leq \lambda \leq \tau} (c_{k}v^{(\lambda)}, u^{(\lambda)}) = 2(c_{k}, u'\bar{v}) \\ q_{\alpha} &= \sum_{\beta, k} (c_{k}c_{\beta}, c_{\alpha}) z_{k} p_{\beta} \\ &= \sum_{k} \left\{ (c_{k}c_{0}, c_{\alpha}) p_{0} + \sum_{l} (c_{k}c_{l}, c_{\alpha}) p_{l} \right\} z_{k} \\ &= \sum_{k} \left\{ (c_{k}c_{0}, c_{\alpha}) (|| u ||^{2} - || v ||^{2}) + 2 \sum_{l} (c_{k}c_{l}, c_{\alpha}) (c_{l}, u'\bar{v}) \right\} z_{k} \\ &= (c_{0}, \bar{z}c_{\alpha}) (|| u ||^{2} - || v ||^{2}) + 2 \sum_{l} (c_{l}, \bar{z}c_{\alpha}) (c_{l}, u'\bar{v}) , \end{split}$$

where we have

$$egin{aligned} &(c_{\scriptscriptstyle 0},\,ar{z}c_{\scriptscriptstyle lpha})\,=\,(z,\,c_{\scriptscriptstyle lpha})\;,\ &\sum_l\,(c_{\scriptscriptstyle l},\,ar{z}c_{\scriptscriptstyle lpha})(c_{\scriptscriptstyle l},\,u'ar{v})\,=\,(ar{z}c_{\scriptscriptstyle lpha},\,u'ar{v})\,-\,(c_{\scriptscriptstyle 0},\,ar{z}c_{\scriptscriptstyle lpha})(c_{\scriptscriptstyle 0},\,u'ar{v})\ &=\,(ar{z}c_{\scriptscriptstyle lpha},\,u'ar{v})\,-\,(z,\,c_{\scriptscriptstyle lpha})(u,\,v)\;. \end{aligned}$$

Hence we have

$$q_{\alpha} = (z, c_{\alpha})(||u||^2 - ||v||^2 - 2(u, v)) + 2(\overline{z}c_{\alpha}, u'\overline{v})$$

In particular,  $q_0 = 2(\bar{z}, u'\bar{v})$ . Now we have

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$$\begin{split} \sum_{\alpha} p_{\alpha} w_{\alpha} &= (||u||^{2} - ||v||^{2}) w_{0} + 2 \sum_{k} (c_{k}, u'\bar{v}) w_{k} \\ &= (||u||^{2} - ||v||^{2}) w_{0} + 2(w, u'\bar{v}) - 2(c_{0}, u'\bar{v}) w_{0} \\ &= (||u||^{2} - ||v||^{2} - 2(u, v)) w_{0} + 2(w, u'\bar{v}) , \\ \sum_{\alpha} q_{\alpha} w_{\alpha} &= (z, w)(||u||^{2} - ||v||^{2} - 2(u, v)) + 2(\bar{z}w, u'\bar{v}) , \\ \sum_{\alpha} p_{\alpha}^{2} &= (||u||^{2} - ||v||^{2})^{2} + 4 \sum_{k} (c_{k}, u'\bar{v})^{2} \\ &= (||u||^{2} - ||v||^{2})^{2} + 4 ||u'\bar{v}||^{2} - 4(u, v)^{2} . \end{split}$$

Furthermore we have

$$\langle p_{lpha}, \, p_{eta} 
angle = 4(||\,u\,||^2 + ||\,v\,||^2) \delta_{lpha,eta}$$
 for each  $lpha, \, eta$  .

Recall Lemmas 4, 5, 6, 7. The polynomial F on  $\mathbb{R}^N$  associated to  $\{p_{\alpha}\}, \{q_{\alpha}\}$  is given by

$$\begin{split} F &= z_0^4 + z_0^2 \{2(||u||^2 + ||v||^2 + ||z||^2) - 6 ||w||^2 \} \\ &+ 8z_0 \{||u||^2 - ||v||^2 - 2(u, v))w_0 + 2(w, u'\bar{v}) \} \\ &+ (||u||^2 + ||v||^2 + ||z||^2)^2 - 2\{(||u||^2 - ||v||^2)^2 + 4 ||u'\bar{v}||^2 - 4(u, v)^2 \} \\ &+ 8\{(z, w)(||u||^2 - ||v||^2 - 2(u, v)) + 2(\bar{z}w, u'\bar{v}) \} \\ &+ 8\{(||u||^2 + ||v||^2)||w||^2 - 6(||u||^2 + ||v||^2 + ||z||^2)||w||^2 + ||w||^4 \\ &= z_0^4 + 2z_0^2(||u||^2 + ||v||^2 + ||z||^2) + (||u||^2 + ||v||^2 + ||z||^2)^2 \\ &- 6z_0^2||w||^2 - 6(||u||^2 + ||v||^2 + ||z||^2)||w||^2 \\ &+ 8z_0w_0(||u||^2 - ||v||^2 - 2(u, v)) + 8(z, w)(||u||^2 - ||v||^2 - 2(u, v)) \\ &+ 16z_0(w, u'\bar{v}) + 16(\bar{z}w, u'\bar{v}) \\ &- 2(||u||^2 - ||v||^2)^2 - 8||u'\bar{v}||^2 + 8(u, v)^2 \\ &+ 8(||u||^2 + ||v||^2)||w||^2 + ||w||^4 \,. \end{split}$$

Putting  $\zeta = z_0c_0 + z \in \hat{Z}$   $(z \in Z)$ , we have

$$\begin{split} F &= (||u||^2 + ||v||^2 + ||\zeta||^2)^2 - 6(||u||^2 + ||v||^2 + ||\zeta||^2) ||w||^2 \\ &+ 8(\zeta, w)(||u||^2 - ||v||^2 - 2(u, v)) + 16(\bar{\zeta}w, u'\bar{v}) \\ &- 2(||u||^2 - ||v||^2)^2 - 8||u'\bar{v}||^2 + 8(u, v)^2 \\ &+ 8(||u||^2 + ||v||^2) ||w||^2 + ||w||^4 \\ &= (||u||^2 + ||v||^2 + ||\zeta||^2 + ||w||^2)^2 - 8||\zeta||^2 ||w||^2 \\ &+ 8(\zeta, w)(||u||^2 - ||v||^2 - 2(u, v)) + 16(\bar{\zeta}w, u'\bar{v}) \\ &- 2(||u||^2 - ||v||^2)^2 - 8||u'\bar{v}||^2 + 8(u, v)^2 \,. \end{split}$$

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$$\begin{split} ||u'\overline{v} - \overline{\zeta}w||^2 &= ||u'\overline{v}||^2 - 2(\overline{\zeta}w, u'\overline{v}) + ||\zeta||^2 ||w||^2 \\ (||u||^2 - ||v||^2 - 2(\zeta, w))^2 &= (||u||^2 - ||v||^2)^2 - 4(\zeta, w)(||u||^2 - ||v||^2) + 4(\zeta, w)^2 \\ ((u, v) - (\zeta, w))^2 &= (u, v)^2 - 2(\zeta, w)(u, v) + (\zeta, w)^2 , \end{split}$$

we get

$$F = r^4 - 2F_0$$

where

 $F_{\scriptscriptstyle 0} = 4\{||\, u'\bar{v} - \bar{\zeta}w\,||^2 - ((u,\,v) - (\zeta,\,w))^2\} + (||\,u\,||^2 - ||\,v\,||^2 - 2(\zeta,\,w))^2 \,.$ We put  $u_{\scriptscriptstyle 0} = \bar{\zeta}, \, v_{\scriptscriptstyle 0} = -\bar{w}$ , and

$$u_1 = egin{pmatrix} u_0 \ u \end{pmatrix}$$
,  $v_1 = egin{pmatrix} v_0 \ v \end{pmatrix} \in F^{r+1}$ .

Then we have

$$F_0 = 4\{||u_1'\overline{v}_1||^2 - (u_1, v_1)^2\} + (||u||^2 - ||v||^2 + 2(u_0, v_0))^2$$

which shows the case (b) of (ii).

(a)  $m_1 = 1$ . Let

$$U = R^r$$
,  $V = R^r$ ,  $\hat{Z} = C$ ,  $W = C$ ,  $Z = \Im C \subset \hat{Z}$ 

and let

$$R^{2(r+2)} = U \oplus V \oplus \widehat{Z} \oplus W$$
,  
 $Y = U \oplus V \oplus Z$ 

be the orthogonal direct sums. In the same way as (b), we get

$$F = r^4 - 2F_0$$

where

$$F_{0} = 4((u, v) - z_{0}w_{1} + z_{1}w_{0})^{2} + (||u||^{2} - ||v||^{2} - 2(\zeta, w))^{2}$$
.

We put

$$\begin{split} \xi_{2} &= u_{0}^{(2)} + \sqrt{-1} \, v_{0}^{(2)} \quad \text{for} \quad \lambda = 1, \, \cdots, \, r \; , \\ \xi_{r+1} &= \frac{1}{\sqrt{2}} \{ (z_{1} - w_{1}) + \sqrt{-1} \, (z_{0} + w_{0}) \} \; , \\ \xi_{r+2} &= \frac{1}{\sqrt{2}} \{ (-z_{0} + w_{0}) + \sqrt{-1} (z_{1} + w_{1}) \} \; . \end{split}$$

Then we have

$$\sum_{i=1}^{r+2} \xi_i^2 = (||u||^2 - ||v||^2 - 2(\zeta, w)) + 2\sqrt{-1}((u, v) - z_0w_1 + z_1w_0).$$

Thus we have

$$F_{_{0}}=\left\|\sum_{_{i=1}}^{r+1}\xi_{_{i}}^{^{2}}
ight\|^{^{2}}$$
 ,

which shows (a) of (ii).

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