

Algebra & Number Theory

Volume 12

2018

No. 8

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We obtain several formulas for the Euclidean distance degree (ED degree) of an arbitrary nonsingular variety in projective space: in terms of Chern and Segre classes, Milnor classes, Chern–Schwartz–MacPherson classes, and an extremely simple formula equating the Euclidean distance degree of X with the Euler characteristic of an open subset of X .

1. Introduction

The *Euclidean distance degree* (ED degree) of a variety X is the number of critical nonsingular points of the distance function from a general point u outside of X . This definition, tailored to real algebraic varieties, may be adapted to complex projective varieties X , by considering the critical points of the (complex-valued) function $\sum_i (x_i - u_i)^2$ on the smooth part of the affine cone over X . This is the context in which we will work in this paper. The ED degree is studied thoroughly in [Draisma et al. 2016], which provides a wealth of examples, results, and applications. In particular, [Draisma et al. 2016, Theorem 5.4] states that the ED degree of a complex projective variety $X \subseteq \mathbb{P}^{n-1}$ equals the sum of its “polar degrees”, provided that the variety satisfies a technical condition related to its intersection with the *isotropic quadric*, i.e., the quadric Q with equation $x_1^2 + \cdots + x_n^2 = 0$. As a consequence, a formula is obtained [Draisma et al. 2016, Theorem 5.8] computing the Euclidean distance degree of a *nonsingular* variety X , assuming that X intersects Q transversally, i.e., under the assumption that $Q \cap X$ is a nonsingular hypersurface of X . This number is a certain combination of the degrees of the components of the *Chern class* of X (see (3-1)); we call this number the “generic Euclidean distance degree” of X , $\text{gEDdeg}(X)$, since it equals the Euclidean distance degree of a general translate of X .

There are several directions in which this formula could be generalized. For example, the hypothesis of nonsingularity on X could be relaxed; it is then understood that the role of the Chern class of X is taken by the so-called *Chern–Mather* class of X , one of several generalizations of the notion of Chern class to possibly singular X . The resulting formula (see, e.g., [Aluffi 2018, Proposition 2.9]) gives the generic ED degree of an arbitrarily singular variety X . In a different direction, one could maintain the nonsingularity hypothesis, but attempt to dispose of any requirement regarding the relative position of Q and X , and aim at computing the “actual” ED degree of X .

MSC2010: primary 14C17; secondary 14N10, 57R20.

Keywords: algebraic optimization, intersection theory, characteristic classes, Chern–Schwartz–MacPherson classes.

The main result of this note is of this second type. It consists of formulas for the Euclidean distance degree of an *arbitrary nonsingular subvariety* of projective space; different versions are presented, in terms of different types of information that may be available on X . The simplest form of the result is the following:

Theorem 8.1. *Let X be a smooth subvariety of \mathbb{P}^{n-1} , and assume $X \not\subseteq Q$. Then*

$$\text{EDdeg}(X) = (-1)^{\dim X} \chi(X \setminus (Q \cup H)), \quad (1-1)$$

where H is a general hyperplane.

Here, χ is the ordinary topological Euler characteristic. This statement will be proven in [Section 8](#); in each of [Sections 5–7](#) we obtain an equivalent formulation of the same result. These serve as stepping stones in the proof of (1-1), and seem of independent interest. [Theorems 5.1](#) and [6.1](#) will express $\text{EDdeg}(X)$ as a “correction” $\gamma(X)$ of the generic Euclidean distance degree due to the singularities of $Q \cap X$. For example, it will be a consequence of [Theorem 6.1](#) that when $Q \cap X$ has *isolated* singularities, then this correction equals the sum of the Milnor numbers of the singularities. (If X is a smooth hypersurface of degree $\neq 2$, the singularities of $Q \cap X$ are necessarily isolated; see [Section 9.3](#).) [Theorem 5.1](#) expresses $\gamma(X)$ in terms of the Segre class of the singularity subscheme of $Q \cap X$; this version of the result is especially amenable to effective implementation, using available algorithms for the computation of Segre classes [[Harris 2017](#)]. [Theorem 7.1](#) relates the Euclidean distance degree to *Chern–Schwartz–MacPherson* classes, an important notion in the theory of characteristic classes for singular or noncompact varieties. In fact, $\text{EDdeg}(X)$ admits a particularly simple expression, given in (7-3), in terms of the Chern–Schwartz–MacPherson class of the nonsingular, but noncompact, variety $X \setminus Q$. [Theorem 8.1](#), reproduced above, follows from this expression.

The progression of results in [Sections 5–8](#) is preceded by a general formula, [Theorem 4.3](#), giving the correction term $\gamma(X)$ for essentially arbitrary varieties X . Coupled with [[Aluffi 2018](#), Proposition 2.9], this yields a general formula for $\text{EDdeg}(X)$. This master formula is our main tool for the applications to nonsingular varieties obtained in the sections that follow; in principle it could be used in more general situations, but at this stage we do not know how to extract a simple statement such as formula (1-1) from [Theorem 4.3](#) without posing some nonsingularity hypothesis on X .

Refining the techniques used in this paper may yield more general results, but this is likely to be challenging. Ultimately, the reason why we can obtain simple statements such as (1-1) is that Segre classes of singularity subschemes of hypersurfaces *of a nonsingular variety X* are well understood. In general, singularities of X will themselves contribute to the singularity subscheme of $Q \cap X$, even if the intersection of Q and X is (in some suitable sense) “transversal”. In fact, for several of our formulas to hold it is only necessary that X be nonsingular along $Q \cap X$ (see [Remarks 5.2](#) and [6.2](#)).

The raw form of our result is a standard application of Fulton–MacPherson intersection theory, modulo one technical difficulty, which we will attempt to explain here. Techniques developed in [[Draisma et al. 2016](#)] express the ED degree as the degree of a projection map from a certain correspondence in

$\mathbb{P}^{n-1} \times \mathbb{P}^{n-1}$. Applying Fulton–MacPherson’s intersection theory, one obtains a formula for the ED degree involving the Segre class of an associated subscheme Z_u^Δ in the conormal space of X (Theorem 4.3); this formula holds for arbitrary $X \not\subseteq Q$. In the nonsingular case, the formula may be recast in terms of the Segre class *in* X of a scheme supported on the singular locus of $Q \cap X$. A somewhat surprising complication arises here, since this scheme does *not* coincide with the singularity subscheme of $Q \cap X$. However, we can prove (Lemma 5.4) that the ideal sheaves of the two subschemes have the same *integral closure*, and deduce from this that their Segre classes coincide. This is key to our explicit formulas.

This technical difficulty is likely one of the main obstacles in extending the results of this paper to the case of more general subvarieties of projective space, by analogous techniques. We may venture the guess that a different approach, aiming at “understanding” (1-1) more directly, without reference to the theory of characteristic classes of singular varieties, may be more amenable to generalization. Finding such an approach would appear to be a natural project.

Preliminaries on the Euclidean distance degree are given in Section 2. In Section 3 we point out that (1-1), in its equivalent formulation (8-2), agrees with $\text{gEDdeg}(X)$ when X is nonsingular and meets the isotropic quadric transversally. We find that this observation clarifies why a formula such as (1-1) may be expected to hold without transversality hypotheses. It is perhaps natural to conjecture that an analogue replacing ordinary Euler characteristics in (1-1) with the degree χ_{Ma} of the Chern–Mather class may hold for arbitrary varieties. Under the transversality hypothesis, an analogue of (8-2) does hold for possibly singular varieties, as we show in Proposition 3.1. The main body of the paper consists of Sections 4–8. Examples of applications of the results obtained here are given in Section 9.

2. Preliminaries on the Euclidean distance degree

As recalled in the introduction, the Euclidean distance degree of a variety in \mathbb{R}^n is the number of critical nonsingular points of the (squared) distance function from a general point outside of the variety. We consider the complex projective version of this notion: for a subvariety $X \subseteq \mathbb{P}^{n-1} := \mathbb{P}(\mathbb{C}^n)$, we let $\text{EDdeg}(X)$ be the number of critical points of the (complex) function

$$(x_1 - u_1)^2 + \cdots + (x_n - u_n)^2 \tag{2-1}$$

which occur at nonsingular points of the cone over X , where (u_1, \dots, u_n) is a general point.

Remark 2.1. If X is a subset of the isotropic quadric Q (with equation $x_1^2 + \cdots + x_n^2 = 0$), then the quadratic term in (2-1) vanishes, and (2-1) has *no* critical points. Therefore, $\text{EDdeg}(X) = 0$ in this case, and we can adopt the blanket convention that $X \not\subseteq Q$. With suitable positions, our results will hold without this assumption (see, e.g., Remark 5.8).

The definition of $\text{EDdeg}(X)$ may be interpreted in terms of a *projective ED correspondence*, and this will be needed for our results. Our reference here is [Draisma et al. 2016, §5] (but we use slightly different notation). Consider the projective space \mathbb{P}^{n-1} and its dual $\check{\mathbb{P}}^{n-1}$, parametrizing hyperplanes in \mathbb{P}^{n-1} . It is well-known that the projective cotangent space $\mathbb{T}^*\mathbb{P}^n := \mathbb{P}(T^*\mathbb{P}^{n-1})$ of \mathbb{P}^{n-1} may be realized as the

incidence correspondence $I \subseteq \mathbb{P}^{n-1} \times \check{\mathbb{P}}^{n-1}$ consisting of pairs (p, H) with $p \in H$. Every subvariety $X \subsetneq \mathbb{P}^{n-1}$ has a (projective) conormal space $\mathbb{T}_X^* \mathbb{P}^{n-1}$, defined as the closure of the projective conormal variety to X ; this may be realized as

$$\mathbb{T}_X^* \mathbb{P}^{n-1} := \overline{\{(p, H) \mid p \in X^{ns} \text{ and } T_p X \subseteq H\}} \subseteq I = \mathbb{T}^* \mathbb{P}^{n-1}.$$

Consider the subvariety $Z \subseteq \mathbb{P}^{n-1} \times \check{\mathbb{P}}^{n-1} \times \mathbb{C}^n$ obtained as the image of

$$\{(x, y, u) \in (\mathbb{C}^n \setminus \{0\})^2 \times \mathbb{C}^n \mid u = x + y\};$$

that is,

$$Z = \{([x], [y], u) \in \mathbb{P}^{n-1} \times \check{\mathbb{P}}^{n-1} \times \mathbb{C}^n \mid \dim \langle x, y, u \rangle \leq 2\} \tag{2-2}$$

consists of points $([x], [y], u)$ such that $[x], [y], [u]$ are collinear. The (projective joint) ED correspondence \mathcal{PE} (denoted $\mathcal{PE}_{X,Y}$ in [Draisma et al. 2016]) is the component of $(\mathbb{T}_X^* \mathbb{P}^{n-1} \times \mathbb{C}^n) \cap Z$ dominating $\mathbb{T}_X^* \mathbb{P}^{n-1}$. Thus, the fiber of \mathcal{PE} over $([x], [y]) \in \mathbb{T}_X^* \mathbb{P}^{n-1}$ consists, for $[x] \neq [y]$, of the vectors $u \in \mathbb{C}^n$ in the span of x and y ; this confirms that \mathcal{PE} is irreducible and has dimension n . (Since $X \not\subseteq Q$ by our blanket assumption, there exist points $([x], [y]) \in \mathbb{T}_X^* \mathbb{P}^{n-1}$ with $[x] \neq [y]$.) The projection $\mathcal{PE} \rightarrow \mathbb{C}^n$ is in fact dominant, and we have the following result.

Lemma 2.2. *The Euclidean distance degree $\text{EDdeg}(X)$ equals the degree of the projection $\mathcal{PE} \rightarrow \mathbb{C}^n$.*

Proof. This is implied by the argument in the proof of [Draisma et al. 2016, Theorem 5.4]. □

Lemma 2.2 suggests that one should be able to express $\text{EDdeg}(X)$ in terms of an intersection with the fiber Z_u of Z over a general point $u \in \mathbb{C}^n$. We may view Z_u as a subvariety of $\mathbb{P}^{n-1} \times \check{\mathbb{P}}^{n-1}$:

$$Z_u = \{([x], [y]) \in \mathbb{P}^{n-1} \times \check{\mathbb{P}}^{n-1} \mid \dim \langle x, y, u \rangle \leq 2\},$$

where u is now fixed (and general). It is easy to verify that Z_u is an n -dimensional irreducible variety, and that

$$[Z_u] = h^{n-2} + h^{n-3}\check{h} + \dots + \check{h}^{n-2} \tag{2-3}$$

in the Chow group $A_*(\mathbb{P}^{n-1} \times \check{\mathbb{P}}^{n-1})$. Here, h , resp. \check{h} , denote the pull-back of the hyperplane class from \mathbb{P}^{n-1} , resp. $\check{\mathbb{P}}^{n-1}$. (For example, one may verify (2-3) by intersecting Z_u with suitably chosen $\mathbb{P}^i \times \check{\mathbb{P}}^j$ within $\mathbb{P}^{n-1} \times \check{\mathbb{P}}^{n-1}$.) This implies the following statement; see [Draisma et al. 2016, Theorem 5.4].

Lemma 2.3. *For all $u \in \mathbb{C}^{n-1}$ and all subvarieties $X \subseteq \mathbb{P}^{n-1}$,*

$$Z_u \cdot \mathbb{T}_X^* \mathbb{P}^{n-1} = \sum_{i=0}^{n-2} \delta_i(X),$$

where the numbers $\delta_i(X)$ are the polar degrees of X .

Indeed, the polar degrees are (by definition) the coefficients of the monomials $h^{n-1-i}\check{h}^{i+1}$ in the class $[\mathbb{T}_X^* \mathbb{P}^{n-1}]$.

In view of [Lemma 2.3](#), we define

$$\text{gEDdeg}(X) := \sum_{i=0}^{n-2} \delta_i(X),$$

the “generic Euclidean distance degree” of X . By [Lemma 2.2](#), $\text{EDdeg}(X)$ is the contribution of the projective ED correspondence to the intersection number $\text{gEDdeg}(X) = Z_u \cdot \mathbb{T}_X^* \mathbb{P}^{n-1}$ calculated in [Lemma 2.3](#). It is a consequence of [[Draisma et al. 2016](#), Theorem 5.4] that if X is in sufficiently general position, then this contribution in fact equals the whole intersection number, i.e., $\text{EDdeg}(X) = \text{gEDdeg}(X)$. Our goal is to determine a precise “correction term” evaluating the discrepancy between $\text{EDdeg}(X)$ and $\text{gEDdeg}(X)$ without any *a priori* hypothesis on X . In [Section 4](#) we will formalize this goal and deduce a general formula for $\text{EDdeg}(X)$ for an arbitrary variety X . In [Sections 4–8](#) we will use this result to obtain more explicit formulas for $\text{EDdeg}(X)$ under the assumption that X is nonsingular.

3. The generic Euclidean distance degree, revisited

This section is not used in the sections that follow, but should help motivating formula (1-1), which will be proven in [Section 8](#). We also propose a possible conjectural generalization of this formula to arbitrary projective varieties.

We have defined the “generic” Euclidean distance degree of a subvariety $X \subseteq \mathbb{P}^{n-1}$ as the sum of its polar degrees. In [[Draisma et al. 2016](#), Theorem 5.8] it is shown that if X is nonsingular, then

$$\text{gEDdeg}(X) = \sum_{j=0}^{\dim X} (-1)^{\dim X+j} c(X)_j (2^{j+1} - 1); \tag{3-1}$$

this number may be interpreted as the Euclidean distance degree of a general translation of X , which will meet Q transversally by Bertini’s theorem. Here $c(X)_j$ is the degree of the component of dimension j of the Chern class $c(TX) \cap [X]$ of X . Formula (3-1) holds for arbitrarily singular varieties X if one replaces $c(X)$ with the *Chern–Mather* class $c_{\text{Ma}}(X)$ of X [[Aluffi 2018](#), Proposition 2.9].

Assume first that X is nonsingular. As a preliminary observation, the reader is invited to perform the following calculus exercise:

For $0 \leq j \leq N$, the coefficient of t^N in the expansion of

$$\frac{t^{N-j}}{(1+t)(1+2t)}$$

is $(-1)^j (2^{j+1} - 1)$.

With this understood, we have the following computation:

$$\text{gEDdeg}(X) = (-1)^{\dim X} \sum_{j=0}^{\dim X} c(X)_j (-1)^j (2^{j+1} - 1)$$

$$\begin{aligned}
 &= (-1)^{\dim X} \sum_{j=0}^{\dim X} c(X)_j \int \frac{h^{\dim X-j}}{(1+h)(1+2h)} \cdot h^{\operatorname{codim} X} \cap [\mathbb{P}^{n-1}] \\
 &= (-1)^{\dim X} \int \frac{1}{(1+h)(1+2h)} \cdot c(TX) \cap [X] \\
 &= (-1)^{\dim X} \int \left(1 - \frac{h}{1+h} - \frac{2h}{1+2h} + \frac{h \cdot 2h}{(1+h)(1+2h)} \right) \cdot c(TX) \cap [X].
 \end{aligned}$$

Assuming further that X is transversal to Q and that H is a general hyperplane, the last expression may be rewritten as

$$\begin{aligned}
 (-1)^{\dim X} \left(\int c(TX) \cap [X] - \int c(T(X \cap H)) \cap [X \cap H] \right. \\
 \left. - \int c(T(X \cap Q)) \cap [X \cap Q] + \int c(T(X \cap Q \cap H)) \cap [X \cap Q \cap H] \right)
 \end{aligned}$$

(by transversality, all of the loci appearing in this expression are nonsingular). The degree of the zero-dimensional component of the Chern class of a compact complex nonsingular variety is its topological Euler characteristic, so this computation shows

$$\operatorname{EDdeg}(X) = (-1)^{\dim X} (\chi(X) - \chi(X \cap H) - \chi(X \cap Q) + \chi(X \cap Q \cap H)), \tag{3-2}$$

if X is nonsingular and meets Q transversally (and where H is a general hyperplane).

Theorem 8.1 will amount to the assertion that (3-2) holds as soon as X is nonsingular, without any hypothesis on the intersection of Q and X . By the good inclusion-exclusion properties of the Euler characteristic, (3-2) is equivalent to (1-1).

While the computation deriving (3-2) from [Draisma et al. 2016, Theorem 5.8] is trivial under the transversality hypothesis, we do not know of any simple way to obtain this formula in the general case. The next several Sections (4–8) will lead to a proof of (3-2) for arbitrary nonsingular varieties.

The above computation can be extended to singular projective subvarieties. Just as the topological Euler characteristic of a nonsingular variety is the degree of its top Chern class, we can define an “Euler–Mather characteristic” of a possibly singular variety V by setting

$$\chi_{\operatorname{Ma}}(V) := \int c_{\operatorname{Ma}}(V),$$

the degree of the Chern–Mather class of V . This number is a linear combination of Euler characteristics of strata of V , with coefficients determined by the *local Euler obstruction* Eu , a well-studied numerical invariant of singularities.

Proposition 3.1. *For any subvariety $X \subseteq \mathbb{P}^{n-1}$ intersecting Q transversally,*

$$\operatorname{EDdeg}(X) = (-1)^{\dim X} (\chi_{\operatorname{Ma}}(X) - \chi_{\operatorname{Ma}}(X \cap Q) - \chi_{\operatorname{Ma}}(X \cap H) + \chi_{\operatorname{Ma}}(X \cap Q \cap H)), \tag{3-3}$$

where H is a general hyperplane.

Proof. Argue precisely as in the discussion leading to (3-2), using [Aluffi 2018, Proposition 2.9] in place of [Draisma et al. 2016, Theorem 5.8]. The only additional ingredient needed for the computation is the fact that if W is a nonsingular hypersurface intersecting a variety V transversally, then

$$c_{\text{Ma}}(W \cap V) = \frac{W}{1+W} \cap c_{\text{Ma}}(V).$$

For a much stronger result, and a discussion of the precise meaning of “transversality”, we address the reader to [Schürmann 2017], particularly Theorem 1.2. \square

Of course (3-3) specializes to (3-2) when X is nonsingular, under the transversality hypothesis; but it does not do so in general, because $Q \cap X$ may be singular even if X is nonsingular, and $\chi_{\text{Ma}}(Q \cap X)$ does not necessarily agree with $\chi(Q \cap X)$ in that case. Therefore, the transversality hypothesis in Proposition 3.1 is necessary. The signed Euler–Mather characteristic of the complement,

$$(-1)^{\dim X} \chi_{\text{Ma}}(X \setminus (Q \cup H)) = (-1)^{\dim X} \int c_*(\text{Eu}_{X \setminus (Q \cup H)})$$

(where c_* denotes MacPherson’s natural transformation) may be the most natural candidate as an expression for $\text{EDdeg}(X)$ for arbitrary subvarieties $X \subseteq \mathbb{P}^{n-1}$, without smoothness or transversality hypotheses.

4. Intersection formula

In Section 2 we defined the projective ED correspondence \mathcal{PE} to be one component of the intersection $(\mathbb{T}_X^* \mathbb{P}^{n-1} \times \mathbb{C}^n) \cap Z$, where Z is the variety of linearly dependent triples defined in (2-2). We next determine the union of the *other* irreducible components. We denote by Δ the diagonal in $\mathbb{P}^{n-1} \times \check{\mathbb{P}}^{n-1}$. In this section, $X \subseteq \mathbb{P}^{n-1}$ is a subvariety (not necessarily smooth), and $X \not\subseteq Q$ (see Remark 2.1).

Lemma 4.1. *There exists a subscheme $Z^\Delta \subset \mathbb{T}_X^* \mathbb{P}^{n-1} \times \mathbb{C}^n$ such that*

$$(\mathbb{T}_X^* \mathbb{P}^{n-1} \times \mathbb{C}^n) \cap Z = \mathcal{PE} \cup Z^\Delta,$$

where the support of Z^Δ equals the support of $(\Delta \cap \mathbb{T}_X^* \mathbb{P}^{n-1}) \times \mathbb{C}^n$.

Proof. Consider the projection $(\mathbb{T}_X^* \mathbb{P}^{n-1} \times \mathbb{C}^n) \cap Z \rightarrow \mathbb{P}^{n-1} \times \check{\mathbb{P}}^{n-1}$. We have already observed in Section 2 that the fiber over $([x], [y]) \in \mathbb{T}_X^* \mathbb{P}^{n-1}$, $([x], [y]) \notin \Delta$, consists of the span $\langle x, y \rangle$ in \mathbb{C}^n ; it follows that \mathcal{PE} is the only component of the intersection dominating $\mathbb{T}_X^* \mathbb{P}^{n-1}$. (Again note that since $X \not\subseteq Q$, there are points $([x], [y]) \in \mathbb{T}_X^*$, $([x], [y]) \notin \Delta$.)

We claim that if $([x], [x]) \in \mathbb{T}_X^* \mathbb{P}^{n-1}$, then the fiber of $(\mathbb{T}_X^* \mathbb{P}^{n-1} \times \mathbb{C}^n) \cap Z$ over $([x], [x])$ consists of the whole space \mathbb{C}^{n-1} ; the statement follows immediately from this assertion.

Trivially, $([x], [x], u) \in \mathbb{T}_X^* \mathbb{P}^{n-1} \times \mathbb{C}^n$ for all u , so we simply need to verify that $([x], [x], u) \in Z$ for all $u \in \mathbb{C}^n$. But this is clear, since there are points $([x'], [y'], u)$ with $u \in \langle x', y' \rangle$ and $([x'], [y'])$ arbitrarily close to $([x], [x])$. \square

The fact that Z contains $\Delta \times \mathbb{C}^n$ (used in the proof) may also be verified by observing that equations for Z in $\mathbb{P}^{n-1} \times \check{\mathbb{P}}^{n-1} \times \mathbb{C}^n$ are given by the 3×3 minors of the matrix

$$\begin{pmatrix} x_1 & x_2 & \dots & x_n \\ y_1 & y_2 & \dots & y_n \\ u_1 & u_2 & \dots & u_n \end{pmatrix} \quad (4-1)$$

associated with a point $([x], [y], u) \in \mathbb{P}^{n-1} \times \check{\mathbb{P}}^{n-1} \times \mathbb{C}^n$; the diagonal $\Delta \times \mathbb{C}^n$ obviously satisfies these equations.

Now we fix a general $u \in \mathbb{C}^n$. By [Lemma 2.2](#), the fiber $\mathcal{P}\mathcal{E}_u$ consists of $\text{EDdeg}(X)$ simple points, which will be disjoint from the diagonal for general u . On the other hand, for all u , the fiber Z_u (when viewed as a subvariety of $\mathbb{P}^{n-1} \times \check{\mathbb{P}}^{n-1}$) contains Δ . We deduce the following consequence of [Lemma 4.1](#).

Corollary 4.2. *For a general $u \in \mathbb{C}^n$,*

$$Z_u \cap \mathbb{T}_X^* \mathbb{P}^{n-1} = \{\text{EDdeg}(X) \text{ simple points}\} \sqcup Z_u^\Delta$$

(as subschemes of $\mathbb{T}_X^* \mathbb{P}^{n-1}$), where the support of Z_u^Δ agrees with the support of $\Delta \cap \mathbb{T}_X^* \mathbb{P}^{n-1}$.

Taking into account [Lemma 2.3](#) we obtain that

$$\text{EDdeg}(X) = \text{gEDdeg}(X) - \gamma(X), \quad (4-2)$$

where $\gamma(X)$ is the contribution of Z_u^Δ to the intersection product $Z_u \cdot \mathbb{T}_X^* \mathbb{P}^{n-1}$. This ‘‘correction term’’ $\gamma(X)$ does not depend on the chosen (general) u , and vanishes if $\Delta \cap \mathbb{T}_X^* \mathbb{P}^{n-1} = \emptyset$, since in this case $Z_u^\Delta = \emptyset$ by [Corollary 4.2](#). This special case recovers the statement of [[Draisma et al. 2016](#), Theorem 5.4], and indeed (4-2) is essentially implicit in [[loc. cit.](#)]. We are interested in computable expressions for the correction term $\gamma(X)$.

We will first obtain the following master formula, through a direct application of Fulton–MacPherson intersection theory. The diagonal Δ is isomorphic to \mathbb{P}^{n-1} , and we denote by H its hyperplane class, as well as its restrictions. (Thus, H agrees with the restriction of both h and \check{h} .)

Theorem 4.3. *With notation as above,*

$$\gamma(X) = \int (1 + H)^{n-1} \cap_s (Z_u^\Delta, \mathbb{T}_X^* \mathbb{P}^{n-1}) \quad (4-3)$$

for u general in \mathbb{C}^n .

Here, \int denotes degree, and $s(-, -)$ is the *Segre class*, in the sense of [[Fulton 1984](#), Chapter 4]. Segre classes are effectively computable by available implementations of algorithms (see, e.g., [[Harris 2017](#)]). However, the need to obtain explicit equations for the scheme Z_u^Δ , and conditions guaranteeing that a given u is general enough, limit the direct applicability of [Theorem 4.3](#). Our task in the next several sections of this paper will be to obtain from (4-3) concrete computational tools, at the price of requiring X to be of a more specific type—we will assume in the following sections that $X \not\subseteq Q$ is *nonsingular*, but otherwise arbitrary.

The proof of [Theorem 4.3](#) requires some additional information on Z_u , which we gather next. As noted in [Section 2](#), Z_u is an irreducible n -dimensional subvariety of $\mathbb{P}^{n-1} \times \check{\mathbb{P}}^{n-1}$. Equations for Z_u in $\mathbb{P}^{n-1} \times \check{\mathbb{P}}^{n-1}$ are given by the 3×3 minors of the matrix (4-1), where now $u = (u_1, \dots, u_n)$ is fixed. The diagonal Δ is a divisor in Z_u .

Lemma 4.4. *The subvariety Z_u of $\mathbb{P}^{n-1} \times \check{\mathbb{P}}^{n-1}$ is smooth at all points $([x], [y]) \neq ([u], [u])$.*

Proof. Given $(x, y, u) \in \mathbb{P}^{n-1} \times \check{\mathbb{P}}^{n-1} \times \mathbb{C}^n$ we can change coordinates so that $u = (1, 0, \dots, 0)$. If either $[x]$ or $[y]$ is not $[u]$, we may without loss of generality assume that $x_n \neq 0$, and hence $x_n = 1$. The ideal of Z_u at this point $([x], [y])$ is generated by the 3×3 minors of

$$\begin{pmatrix} x_1 & x_2 & \dots & x_{n-1} & 1 \\ y_1 & y_2 & \dots & y_{n-1} & y_n \\ 1 & 0 & \dots & 0 & 0 \end{pmatrix}$$

and among these we find the $n - 2$ minors

$$y_i - x_i y_n, \quad i = 2, \dots, n - 1.$$

Near $([x], [y])$, these generate the ideal of an irreducible smooth complete intersection of dimension $n = \dim Z_u$, which must then coincide with Z_u in a neighborhood of $([x], [y])$, giving the statement. \square

Denote complements of $\{([u], [u])\}$ by $^\circ$. Thus $Z_u^\circ = Z_u \setminus \{([u], [u])\}$, $\Delta^\circ = \Delta \setminus \{([u], [u])\}$, etc. By [Lemma 4.4](#), Z_u° is a local complete intersection in $(\mathbb{P}^{n-1} \times \check{\mathbb{P}}^{n-1})^\circ$, and we let N be its normal bundle.

Lemma 4.5. *With notation as above, $c(N)|_{\Delta^\circ} = (1 + H)^{n-1}$.*

Proof. Consider the rational map

$$\pi : \mathbb{P}^{n-1} \times \check{\mathbb{P}}^{n-1} \rightarrow \mathbb{P}^{n-2} \times \mathbb{P}^{n-2}$$

defined by the linear projection from $[u]$ on each factor. Let $U \subseteq \mathbb{P}^{n-1} \times \check{\mathbb{P}}^{n-1}$ be the complement of the union of $\{[u]\} \times \mathbb{P}^{n-1}$ and $\check{\mathbb{P}}^{n-1} \times \{[u]\}$; thus, $\pi|_U : U \rightarrow \mathbb{P}^{n-2} \times \mathbb{P}^{n-2}$ is a regular map, and U contains Δ° . A simple coordinate computation shows that $Z_u \cap U = \pi|_U^{-1}(\Delta')$, where Δ' is the diagonal in $\mathbb{P}^{n-2} \times \mathbb{P}^{n-2}$. It follows that

$$N|_{Z_u \cap U} = \pi|_U^*(N_{\Delta'}|_{\mathbb{P}^{n-2} \times \mathbb{P}^{n-2}}) \cong \pi|_U^*(T\Delta').$$

Since $\Delta' \cong \mathbb{P}^{n-2}$, $c(T\Delta') = (1 + H')^{n-1}$, where H' is the hyperplane class. The statement follows by observing that the pull-back of H' to Δ° agrees with the pull-back of H . This is the case, since the restriction $\pi|_{\Delta^\circ} : \Delta^\circ \cong \mathbb{P}^{n-1} \setminus \{u\} \rightarrow \Delta' \cong \mathbb{P}^{n-2}$ is a linear projection. \square

With these preliminaries out of the way, we can prove [Theorem 4.3](#).

Proof of Theorem 4.3. Since $[u]$ is general, it may be assumed not to be a point of X . This ensures that $([u], [u]) \notin \mathbb{T}_X^* \mathbb{P}^{n-1}$; in particular

$$Z_u^\circ \cap \mathbb{T}_X^* \mathbb{P}^{n-1} = Z_u \cap \mathbb{T}_X^* \mathbb{P}^{n-1}.$$

It follows that, as a class in $A_*(Z_u \cap \mathbb{T}_X^* \mathbb{P}^{n-1})$, the (Fulton–MacPherson) intersection product of $\mathbb{T}_X^* \mathbb{P}^{n-1}$ by Z_u on $\mathbb{P}^{n-1} \times \check{\mathbb{P}}^{n-1}$ equals the intersection product of $\mathbb{T}_X^* \mathbb{P}^{n-1}$ by Z_u° on $(\mathbb{P}^{n-1} \times \check{\mathbb{P}}^{n-1})^\circ$.

Therefore, we can view $\gamma(X)$ as the contribution of Z_u^Δ to $Z_u^\circ \cdot \mathbb{T}_X^* \mathbb{P}^{n-1}$. Consider the fiber diagram

$$\begin{array}{ccc} Z_u \cap \mathbb{T}_X^* \mathbb{P}^{n-1} & \longrightarrow & \mathbb{T}_X^* \mathbb{P}^{n-1} \\ g \downarrow & & \downarrow \\ Z_u^\circ & \longrightarrow & (\mathbb{P}^{n-1} \times \check{\mathbb{P}}^{n-1})^\circ \end{array}$$

By [Fulton 1984, §6.1] (especially Proposition 6.1(a), Example 6.1.1), this contribution equals

$$\int c(g|_{Z_u^\Delta}^* N) \cap s(Z_u^\Delta, \mathbb{T}_X^* \mathbb{P}^{n-1}),$$

where $N = N_{Z_u^\circ}(\mathbb{P}^{n-1} \times \check{\mathbb{P}}^{n-1})^\circ$ as above. Since Z_u^Δ is supported on a subscheme of Δ° , $c(g|_{Z_u^\Delta}^* N)$ equals (the restriction of) $(1 + H)^{n-1}$ by Lemma 4.5. The stated formula follows. \square

Summarizing, we have proven that

$$\text{EDdeg}(X) = \text{gEDdeg}(X) - \int (1 + H)^{n-1} \cap s(Z_u^\Delta, \mathbb{T}_X^* \mathbb{P}^{n-1}) \tag{4-4}$$

for all subvarieties $X \not\subseteq Q$ of \mathbb{P}^{n-1} . (If $X \subseteq Q$, then $\text{EDdeg}(X) = 0$; see Remark 2.1.) The quantity $\text{gEDdeg}(X)$ is invariant under projective translations, and may be computed in terms of the Chern–Mather class of X . The other term records subtle information concerning the intersection of X and Q , by means of the Segre class $s(Z_u^\Delta, \mathbb{T}_X^* \mathbb{P}^{n-1})$. We will focus on obtaining alternative expressions for this class.

5. Euclidean distance degree and Segre classes

Now we assume that $X \subseteq \mathbb{P}^{n-1}$ is a *smooth* closed subvariety. As recalled in Section 3, in this case $\text{gEDdeg}(X)$ is given by a certain combination of the Chern classes of X :

$$\text{gEDdeg}(X) = (-1)^{\dim X} \sum_{j=0}^{\dim X} (-1)^j c(X)_j (2^{j+1} - 1).$$

An application of Theorem 4.3, obtained in this section, will yield an explicit formula for the correction term $\gamma(X)$ (and hence for $\text{EDdeg}(X)$). This result has two advantages over Theorem 4.3: first, the formula will not depend on the choice of a general u ; second, its ingredients will allow us to draw a connection with established results in the theory of characteristic classes for singular varieties, leading to the results presented in Sections 6–8.

The main result of this section is the following. Recall that we are denoting by Q the isotropic quadric, i.e., the hypersurface of \mathbb{P}^{n-1} with equation $\sum_{i=1}^n x_i^2 = 0$. By our blanket assumption that X should not be contained in Q , we have that $Q \cap X$ is a (possibly singular) hypersurface of X . We let $J(Q \cap X)$ denote its *singularity subscheme*, defined locally by the partial derivatives of its equation in X (or equivalently

by the appropriate Fitting ideal of the sheaf of differentials of $Q \cap X$). Also, recall that h denotes the hyperplane class in \mathbb{P}^{n-1} .

Theorem 5.1. *Let X be a smooth subvariety of \mathbb{P}^{n-1} , and assume $X \not\subseteq Q$. Then*

$$\text{EDdeg}(X) = \text{gEDdeg}(X) - \int \frac{(1+2h) \cdot c(T^*X \otimes \mathbb{O}(2h))}{1+h} \cap s(J(Q \cap X), X). \quad (5-1)$$

The key ingredient in (5-1) is the Segre class $s(J(Q \cap X), X)$. This may be effectively computed by using the algorithm for Segre classes described in [Harris 2017].

Remark 5.2. It will be clear from the argument that it is only necessary to require X to be nonsingular in a neighborhood of $Q \cap X$. (Of course X must only have isolated singularities in this case.) Formula (5-1) holds as stated in this more general case; $\text{gEDdeg}(X)$ may be computed using the same formula as in the smooth case (that is, (3-1)), but using the degrees of the component of the Chern–Mather class of X [Aluffi 2018, Proposition 2.9]. The hypothesis $X \not\subseteq Q$ is also not essential; see Remark 5.8.

The proof of Theorem 5.1 will rely on a more careful study of the schemes $\Delta \cap \mathbb{T}_X^* \mathbb{P}^{n-1}$ and Z_u^Δ encountered in Section 4. In Corollary 4.2 we have shown that these two schemes have the same support; here we will prove the much stronger statement that they have the same Segre class in $\mathbb{T}_X^* \mathbb{P}^{n-1}$. Since $\Delta \cap \mathbb{T}_X^* \mathbb{P}^{n-1}$ is closely related with $J(Q \cap X)$ (Lemma 5.3), this will allow us to recast Theorem 4.3 in terms of the Segre class appearing in (5-1), by means of a result of W. Fulton.

Recall that $\Delta \subseteq Z_u$ (in fact, Δ is a divisor in Z_u); it follows that

$$\Delta \cap \mathbb{T}_X^* \mathbb{P}^{n-1} \subseteq Z_u^\Delta.$$

These two schemes have the same support (Corollary 4.2); but they are in general different. It is straightforward to identify $\Delta \cap \mathbb{T}_X^* \mathbb{P}^{n-1}$ with a subscheme of X .

Lemma 5.3. *Let $\delta : \mathbb{P}^{n-1} \rightarrow \mathbb{P}^{n-1} \times \mathbb{P}^{n-1}$ be the diagonal embedding, and let X be a smooth subvariety of \mathbb{P}^{n-1} . Then $J(Q \cap X) = \delta^{-1}(\mathbb{T}_X^* \mathbb{P}^{n-1})$, i.e., δ maps $J(Q \cap X)$ isomorphically to $\Delta \cap \mathbb{T}_X^* \mathbb{P}^{n-1}$.*

Proof. Since $\mathbb{T}_X^* \mathbb{P}^{n-1} \subseteq \mathbb{P}(T^* \mathbb{P}^{n-1})$, we have

$$\Delta \cap \mathbb{T}_X^* \mathbb{P}^{n-1} = \Delta \cap \mathbb{P}(T^* \mathbb{P}^{n-1}) \cap \mathbb{T}_X^* \mathbb{P}^{n-1} = \mathbb{T}_Q^* \mathbb{P}^{n-1} \cap \mathbb{T}_X^* \mathbb{P}^{n-1}. \quad (5-2)$$

The diagonal δ restricts to an isomorphism $q : Q \xrightarrow{\sim} \mathbb{T}_Q^* \mathbb{P}^{n-1}$. By (5-2), we have that $\delta^{-1}(\mathbb{T}_X^* \mathbb{P}^{n-1})$ agrees with $q^{-1}(\mathbb{T}_X^* \mathbb{P}^{n-1})$, viewed as a subscheme of \mathbb{P}^{n-1} .

Now $q^{-1}(\mathbb{T}_X^* \mathbb{P}^{n-1})$ consists of points $[x]$ such that $[x] \in Q \cap X$ and $T_{[x]}Q \supseteq T_{[x]}X$, and these conditions define $J(Q \cap X)$ scheme-theoretically. The statement follows. \square

Determining Z_u^Δ requires more work. We may assume without loss of generality that $u = (1, 0, \dots, 0)$, so that equations for Z_u^Δ are given by the 3×3 minors of

$$\begin{pmatrix} x_1 & x_2 & \dots & x_{n-1} & x_n \\ y_1 & y_2 & \dots & y_{n-1} & y_n \\ 1 & 0 & \dots & 0 & 0 \end{pmatrix}$$

(defining Z_u) as well as the requirement that $([x], [y]) \in \mathbb{T}_X^* \mathbb{P}^{n-1}$. It is in fact useful to keep in mind that, for $([x], [y]) \in \mathbb{T}_X^* \mathbb{P}^{n-1}$, $\Delta \cap \mathbb{T}_X^* \mathbb{P}^{n-1}$ is defined by the 2×2 minors of

$$\begin{pmatrix} x_1 & x_2 & \dots & x_{n-1} & x_n \\ y_1 & y_2 & \dots & y_{n-1} & y_n \end{pmatrix}$$

while Z_u^Δ is defined (near the diagonal) by the 2×2 minors of

$$\begin{pmatrix} x_2 & \dots & x_{n-1} & x_n \\ y_2 & \dots & y_{n-1} & y_n \end{pmatrix}.$$

Let $\mathcal{F}_{\Delta \cap \mathbb{T}_X^* \mathbb{P}^{n-1}} \supseteq \mathcal{F}_{Z_u^\Delta}$ be the corresponding ideal sheaves on $\mathbb{T}_X^* \mathbb{P}^{n-1}$.

Lemma 5.4. *The ideal $\mathcal{F}_{\Delta \cap \mathbb{T}_X^* \mathbb{P}^{n-1}}$ is integral over $\mathcal{F}_{Z_u^\Delta}$. Therefore,*

$$s(Z_u^\Delta, \mathbb{T}_X^* \mathbb{P}^{n-1}) = s(\Delta \cap \mathbb{T}_X^* \mathbb{P}^{n-1}, \mathbb{T}_X^* \mathbb{P}^{n-1}). \tag{5-3}$$

Proof. The second assertion follows from the first; see the proof of [Aluffi 1995, Lemma 1.2]. The first assertion may be verified on local analytic charts, so we obtain an analytic description of $\mathbb{T}_X^* \mathbb{P}^{n-1}$ at a point $([x], [x])$ of the diagonal. Again without loss of generality we may let $[x] = (1 : 0 : \dots : 0 : i) \in Q \cap X$, and assume that the embedding $\iota : X \rightarrow \mathbb{P}^{n-1}$ has the following analytic description near this point:

$$\iota : (\underline{s}) = (s_2, \dots, s_d) \mapsto (1 : s_2 : \dots : s_d : \varphi_{d+1}(\underline{s}) : \dots : \varphi_n(\underline{s})).$$

Here \underline{s} are analytic coordinates for X , centered at 0, and $\varphi_j(0) = 0$ for $j = d + 1, \dots, n - 1$, $\varphi_n(0) = i$. The tangent space to X at (\underline{s}) is cut out by the $n - d$ hyperplanes

$$\varphi_{j2}x_2 + \dots + \varphi_{jd}x_d - x_j = \Phi_j x_1, \quad j = d + 1, \dots, n, \tag{5-4}$$

where $\varphi_{jk} = \partial\varphi_j/\partial s_k$ and

$$\Phi_j = \varphi_{j2}s_2 + \dots + \varphi_{jd}s_d - \varphi_j.$$

The hyperplanes (5-4) span the fiber of $\mathbb{T}_X^* \mathbb{P}^{n-1}$ over the point $\iota(\underline{s})$. Therefore, $\Delta \cap \mathbb{T}_X^* \mathbb{P}^{n-1}$ is cut out by the 2×2 minors of the matrix

$$\begin{pmatrix} 1 & s_2 & \dots & s_d & \varphi_{d+1} & \dots & \varphi_n \\ \sum_j \lambda_j \Phi_j & -\sum_j \lambda_j \varphi_{j2} & \dots & -\sum_j \lambda_j \varphi_{jd} & \lambda_{d+1} & \dots & \lambda_n \end{pmatrix} \tag{5-5}$$

where $\lambda_{d+1}, \dots, \lambda_n$ are homogeneous coordinates in the fibers of $\mathbb{T}_X^* \mathbb{P}^{n-1}$, while Z_u^Δ is cut out by the 2×2 minors of

$$\begin{pmatrix} s_2 & \dots & s_d & \varphi_{d+1} & \dots & \varphi_n \\ -\sum_j \lambda_j \varphi_{j2} & \dots & -\sum_j \lambda_j \varphi_{jd} & \lambda_{d+1} & \dots & \lambda_n \end{pmatrix}. \tag{5-6}$$

The last several minors in both matrices may be used to eliminate the homogeneous coordinates λ_j , giving $\lambda_j \propto \varphi_j$; in other words, we find that, near $([x], [x])$ both $\Delta \cap \mathbb{T}_X^* \mathbb{P}^{n-1}$ and Z_u^Δ lie in the local analytic section $\sigma : X \rightarrow \mathbb{T}_X^* \mathbb{P}^{n-1}$ defined by

$$\sigma(\underline{s}) : (\lambda_{d+1} : \dots : \lambda_n) = (\varphi_{d+1}(\underline{s}) : \dots : \varphi_n(\underline{s})).$$

Setting $\lambda_j = \varphi_j$ we obtain from (5-6) generators

$$s_k + \sum_j \varphi_j \varphi_{jk}, \quad k = 2, \dots, d \tag{5-7}$$

for the ideal of Z_u^Δ in $\sigma(X)$; the same generators, together with

$$1 - \sum_{j=d+1}^n \varphi_j \Phi_j \tag{5-8}$$

give the ideal of $\Delta \cap \mathbb{T}_X^* \mathbb{P}^{n-1}$ in $\sigma(X)$. It suffices then to verify that (5-8) is integral over the ideal generated by (5-7).

For this, note that the hypersurface $\iota^{-1}(Q \cap X)$ has the equation

$$G(\underline{s}) = 1 + s_2^2 + \dots + s_d^2 + \varphi_{d+1}^2 + \dots + \varphi_n^2.$$

Since $\partial G / \partial s_k = 2(s_k + \sum_j \varphi_j \varphi_{jk})$, the ideal generated by (5-7) is nothing but

$$\left(\frac{\partial G}{\partial s_2}, \dots, \frac{\partial G}{\partial s_d} \right). \tag{5-9}$$

On the other hand, (5-8) may be written as

$$\begin{aligned} 1 - \sum_{j=d+1}^n \varphi_j \Phi_j &= 1 - \sum_{j=d+1}^n \varphi_j (\varphi_{j2}s_2 + \dots + \varphi_{jd}s_d - \varphi_j) \\ &= 1 - s_2 \left(\sum_j \varphi_j \varphi_{j2} \right) - \dots - s_d \left(\sum_j \varphi_j \varphi_{jd} \right) + \varphi_{d+1}^2 + \dots + \varphi_n^2 \\ &\sim 1 + s_2^2 + \dots + s_d^2 + \varphi_{d+1}^2 + \dots + \varphi_n^2 = G(\underline{s}) \end{aligned}$$

modulo (5-7). Since G is integral over (5-9) by [Huneke and Swanson 2006, Corollary 7.2.6], this shows that (5-8) is integral over (5-7), as needed. □

Remark 5.5. The argument also shows that the ideal of $\Delta \cap \mathbb{T}_X^* \mathbb{P}^{n-1}$ in $\sigma(X)$ equals $(G, \partial G / \partial s_2, \dots, \partial G / \partial s_d)$, that is, the (local analytic) ideal of $J(Q \cap X)$. This confirms the isomorphism $J(Q \cap X) \cong \Delta \cap \mathbb{T}_X^* \mathbb{P}^{n-1}$ obtained in Lemma 5.3.

Remark 5.6. The smoothness of X is needed in our argument, since it gives us direct access to the conormal space $\mathbb{T}_X^* \mathbb{P}^{n-1}$. However, it is reasonable to expect that (5-3) holds without this assumption, and it would be interesting to establish this equality for more general varieties.

By Theorem 4.3 and Lemma 5.4,

$$\gamma(X) = \int (1 + H)^{n-1} \cap_s (\Delta \cap \mathbb{T}_X^* \mathbb{P}^{n-1}, \mathbb{T}_X^* \mathbb{P}^{n-1}) \tag{5-10}$$

if X is nonsingular and not contained in Q . We are now ready to prove Theorem 5.1.

Proof of Theorem 5.1. Our main tools are [Lemma 5.3](#) and a result of W. Fulton. For a closed embedding $V \subseteq M$ of a scheme in a nonsingular variety M , Fulton [[1984](#), Example 4.2.6] proves that the class

$$c_F(V) := c(TM|_V) \cap s(V, M) \quad (5-11)$$

is independent of M ; We call $c_F(V)$ the ‘‘Chern–Fulton class’’ of V .

By [Lemma 5.3](#), the diagonal embedding $\delta : \mathbb{P}^{n-1} \rightarrow \mathbb{P}^{n-1} \times \check{\mathbb{P}}^{n-1}$ restricts to an isomorphism $\delta|_{J(Q \cap X)} : J(Q \cap X) \xrightarrow{\sim} \Delta \cap \mathbb{T}_X^* \mathbb{P}^{n-1}$. Let $\pi' : \Delta \cap \mathbb{T}_X^* \mathbb{P}^{n-1} \rightarrow J(Q \cap X)$ be the natural projection, that is, the inverse of $\delta|_{J(Q \cap X)}$. Then

$$c_F(\Delta \cap \mathbb{T}_X^* \mathbb{P}^{n-1}) = \pi'^* c_F(J(Q \cap X)) \quad (5-12)$$

by Fulton’s result. We proceed to determine this class. The Euler sequence for the projective bundle $\mathbb{T}_X^* \mathbb{P}^{n-1} = \mathbb{P}(T_X^* \mathbb{P}^{n-1}) \xrightarrow{\pi} X$,

$$0 \rightarrow \mathbb{O} \rightarrow \pi^* T_X^* \mathbb{P}^{n-1} \otimes \mathbb{O}(1) \rightarrow T(\mathbb{T}_X^* \mathbb{P}^{n-1}) \rightarrow \pi^* TX \rightarrow 0,$$

yields

$$c(T(\mathbb{T}_X^* \mathbb{P}^{n-1})) = c(\pi^* T_X^* \mathbb{P}^{n-1} \otimes \mathbb{O}(1)) \cdot \pi^* c(TX).$$

Pulling back and tensoring by $\mathbb{O}(1)$, the cotangent sequence defining the conormal bundle gives the exact sequence

$$0 \rightarrow \pi^* T_X^* \mathbb{P}^{n-1} \otimes \mathbb{O}(1) \rightarrow \pi^* T^* \mathbb{P}^{n-1} \otimes \mathbb{O}(1) \rightarrow \pi^* T^* X \otimes \mathbb{O}(1) \rightarrow 0,$$

implying

$$c(T(\mathbb{T}_X^* \mathbb{P}^{n-1})) = \frac{c(\pi^* T^* \mathbb{P}^{n-1} \otimes \mathbb{O}(1)) \cdot \pi^* c(TX)}{c(\pi^* T^* X \otimes \mathbb{O}(1))}.$$

The cotangent bundle $T^* \mathbb{P}^{n-1}$ may be identified with the incidence correspondence in the product $\mathbb{P}^{n-1} \times \check{\mathbb{P}}^{n-1}$, and $\mathbb{O}(1) = \mathbb{O}(h + \check{h})$ under this identification (see, e.g., [[Aluffi 2018](#), §2.2]). Also, $c(T^* \mathbb{P}^{n-1}) = (1 - h)^n$. It follows that

$$c(T(\mathbb{T}_X^* \mathbb{P}^{n-1})) = \frac{(1 + \check{h})^n \cdot \pi^* c(TX)}{(1 + h + \check{h}) \cdot c(\pi^* T^* X \otimes \mathbb{O}(h + \check{h}))}.$$

Now we restrict to the diagonal. As in [Section 4](#), we denote by H the hyperplane class in $\Delta \cong \mathbb{P}^{n-1}$ (and its restrictions); note that $H = h \cdot \Delta = \check{h} \cdot \Delta$. Therefore

$$c(T(\mathbb{T}_X^* \mathbb{P}^{n-1})|_{\Delta \cap \mathbb{T}_X^* \mathbb{P}^{n-1}}) = \frac{(1 + H)^n \cdot \pi'^* c(TX)}{(1 + 2H) \cdot c(\pi'^* T^* X \otimes \mathbb{O}(2H))},$$

where π' denotes the projection $\Delta \cap \mathbb{T}_X^* \mathbb{P}^{n-1} \rightarrow J(Q \cap X)$ as above (and we are omitting other evident restrictions). Since $H = \pi'^* h$, the Chern–Fulton class of $\Delta \cap \mathbb{T}_X^* \mathbb{P}^{n-1}$ must be

$$c_F(\Delta \cap \mathbb{T}_X^* \mathbb{P}^{n-1}) = \pi'^* \left(\frac{(1 + h)^n \cdot c(TX)}{(1 + 2h) \cdot c(T^* X \otimes \mathbb{O}(2h))} \right) \cap s(\Delta \cap \mathbb{T}_X^* \mathbb{P}^{n-1}, \mathbb{T}_X^* \mathbb{P}^{n-1}).$$

Using (5-12), this shows that

$$\begin{aligned} s(\Delta \cap \mathbb{T}_X^* \mathbb{P}^{n-1}, \mathbb{T}_X^* \mathbb{P}^{n-1}) &= \pi'^* \left(\frac{(1+2h) \cdot c(T^*X \otimes \mathbb{C}(2h))}{(1+h)^n \cdot c(TX)} \cap_{c_F(J(Q \cap X))} \right) \\ &= \pi'^* \left(\frac{(1+2h) \cdot c(T^*X \otimes \mathbb{C}(2h))}{(1+h)^n} \cap_{s(J(Q \cap X), X)} \right). \end{aligned}$$

Since $\pi'^* = (\delta|_{Q \cap X})_*$ preserves degrees, and $H = \pi'^*(h)$, (5-10) gives

$$\gamma(X) = \int \frac{(1+2h) \cdot c(T^*X \otimes \mathbb{C}(2h))}{1+h} \cap_{s(J(Q \cap X), X)} \tag{5-13}$$

and this concludes the proof. □

Remark 5.7. The very definition of the Euclidean distance degree relies on the square-distance function, $\sum_i (x_i - u_i)^2$, which is not a projective invariant. Therefore, $\text{EDdeg}(X)$ *does* depend on the choice of coordinates in the ambient projective space \mathbb{P}^{n-1} . Formula (4-2),

$$\text{EDdeg}(X) = \text{gEDdeg}(X) - \gamma(X),$$

expresses the Euclidean distance degree of a variety in terms of a quantity that *is* projectively invariant, i.e., $\text{gEDdeg}(X)$, and a correction term $\gamma(X)$ which is not. In fact, the coordinate choice determines the isotropic quadric Q ; that is, $\sum_i x_i^2 = 0$ is a specific nonsingular quadric in \mathbb{P}^{n-1} . [Theorem 5.1](#) prompts us to define a transparent “projective invariant version” $\text{EDdeg}(Q, X)$ of the Euclidean distance degree, for smooth X : $\text{EDdeg}(Q, X)$ could be defined by the right-hand side of (5-1), where now Q is an *arbitrary* nonsingular quadric in \mathbb{P}^{n-1} . (If X is not necessarily smooth, (4-3) could likewise be used to define such a notion.) The number $\text{EDdeg}(Q, X)$ is determined by the pair $X \cap Q \subseteq X$ and does not depend on the choice of coordinates. What [Theorem 5.1](#) shows is that if homogeneous coordinates x_1, \dots, x_n are chosen so that the equation of Q is $\sum_{i=1}^n x_i^2$, then $\text{EDdeg}(Q, X)$ equals the Euclidean distance degree of the variety X (in those coordinates). This fact is occasionally useful in computations; see [Section 9.5](#).

Remark 5.8. As pointed out in [Remark 2.1](#), $\text{EDdeg}(X) = 0$ if $X \subseteq Q$. [Theorem 5.1](#) is compatible with this fact, in the following sense. If $Q \cap X = X$, it is natural to set $J(Q \cap X) = X$, and hence $s(J(Q \cap X), X) = s(X, X) = [X]$. The reader can verify (using (3-1)) that

$$\int \frac{(1+2h) \cdot c(T^*X \otimes \mathbb{C}(2h))}{1+h} \cap [X] = \text{gEDdeg}(X).$$

Therefore (5-1) reduces to $\text{EDdeg}(X) = 0$ in this case, as expected.

6. Euclidean distance degree and Milnor classes

While the formula in [Theorem 5.1](#) is essentially straightforward to implement, given the algorithm for the computation of Segre classes in [\[Harris 2017\]](#), it is fair to say that its “geometric meaning” is not too transparent. In this section and the following two we use results from the theory of characteristic classes

of singular varieties to provide versions of the formula in terms of notions with a more direct geometric interpretation.

Our first aim is the following result. The *Milnor class* of a variety V is the signed difference

$$\mathcal{M}(V) := (-1)^{\dim V - 1} (c_{\text{SM}}(V) - c_F(V))$$

between its Chern–Fulton class $c_F(V)$ (which we already encountered in [Section 5](#)) and its *CSM* (“*Chern–Schwartz–MacPherson*”) class.

We denote by $\mathcal{M}(V)_j$ the component of $\mathcal{M}(V)$ of dimension j . The Milnor class owes its name to the fact that if V is a hypersurface with at worst isolated singularities in a compact nonsingular variety, then the degree of its Milnor class is the sum of the Milnor numbers of its singularities [[Parusiński and Pragacz 2001](#), Example 0.1].

The CSM class of a variety V is a “homology” class which agrees with the total Chern class of the tangent bundle of V when V is nonsingular, and satisfies a functorial requirement formalized by Deligne and Grothendieck. See [[MacPherson 1974](#)] for a definition inspired by this functorial requirement, and [[Schwartz 1965a](#); [1965b](#)] for an earlier equivalent definition motivated by the problem of extending theorems of Poincaré–Hopf type. An efficient summary of MacPherson’s definition (upgraded to the Chow group) may be found in [[Fulton 1984](#), Example 19.1.7]. With notation as in this reference (or as in [[MacPherson 1974](#)]), our $c_{\text{SM}}(V)$ is $c_*(\mathbb{1}_V)$.

As an easy consequence of functoriality, the degree of $c_{\text{SM}}(V)$ equals $\chi(V)$, the topological Euler characteristic of V . In fact the degrees of all the terms in $c_{\text{SM}}(V)$ may be interpreted in terms of Euler characteristics [[Aluffi 2013](#), Theorem 1.1], and this will be key for the version of the result we will present in [Section 8](#).

If V is a hypersurface, then $c_F(V)$ equals the class of the *virtual* tangent bundle of V ; it may be interpreted as the limit of the Chern class of a smoothing of V in the same linear equivalence class. The terms in $c_F(V)$ may therefore also be interpreted in terms of Euler characteristics (of smoothings of V). Roughly, the Milnor class measures the changes in the Euler characteristics of general hyperplane sections of V as we smooth it within its linear equivalence class.

Theorem 6.1. *Let X be a smooth subvariety of \mathbb{P}^{n-1} , and assume $X \not\subseteq Q$. Then*

$$\text{EDdeg}(X) = \text{gEDdeg}(X) - \sum_{j \geq 0} (-1)^j \deg \mathcal{M}(Q \cap X)_j. \quad (6-1)$$

Milnor classes are also accessible computationally; see [[Aluffi 2003](#), Example 4.7].

Remark 6.2. It suffices to require X to be nonsingular in a neighborhood of $Q \cap X$; see [Remark 5.2](#).

Proof. We begin by recalling an expression relating the Milnor class of a hypersurface V of a nonsingular variety M to the Segre class of its singularity subscheme $J(V)$. Letting $\mathcal{L} = \mathcal{O}(V)$,

$$\mathcal{M}(V) = (-1)^{\dim M} \frac{c(TM)}{c(\mathcal{L})} \cap (s(J(V), M)^\vee \otimes_M \mathcal{L}). \quad (6-2)$$

This is [Aluffi 1999a, Theorem I.4]. The notation used in this statement are as follows (see [Aluffi 1999a, §1.4] or [Aluffi 1994, §2]): if $A = \sum_{i \geq 0} a^i$ is a rational equivalence class in $V \subseteq M$, where a^i has codimension i in M , and \mathcal{L} is a line bundle on V , then

$$A^\vee = \sum_{i \geq 0} (-1)^i a^i, \quad A \otimes_M \mathcal{L} = \sum_{i \geq 0} \frac{a^i}{c(\mathcal{L})^i}$$

(note that the codimension is computed in the ambient variety M , even if the class may be defined in the Chow group of the subscheme V).

This notation satisfies several properties, for example a basic compatibility with respect to Chern classes of tensors of vector bundles. One convenient property is given in [Aluffi 2017, Lemma 3.1]: with notation as above, the term of codimension c in M in

$$c(\mathcal{L})^{c-1} \cap (A \otimes_M \mathcal{L})$$

is independent of \mathcal{L} . In particular,

$$\int c(\mathcal{L})^{\dim M-1} \cap (A \otimes_M \mathcal{L})$$

is independent of \mathcal{L} , and this implies (using [Aluffi 1994, Proposition 2])

$$\int c(\mathcal{L})^{\dim M-1} \cap A = \int A \otimes_M \mathcal{L}^\vee.$$

Apply this fact to $\gamma(X)$ (from (5-13)), viewed as

$$\gamma(X) = \int (1+2h)^{\dim X-1} \cap \left(\frac{c(T^*X \otimes \mathbb{O}(2h))}{(1+h)(1+2h)^{\dim X-2}} \cap s(J(Q \cap X, X)) \right),$$

with $M = X$, $\mathcal{L} = \mathbb{O}(2h)$. We obtain

$$\begin{aligned} \gamma(X) &= \int \left(\frac{c(T^*X \otimes \mathbb{O}(2h))}{(1+h)(1+2h)^{\dim X-2}} \cap s(J(Q \cap X, X)) \right) \otimes_M \mathbb{O}(-2h) \\ &\stackrel{!}{=} \int \frac{c(T^*X)}{(1-h)(1-2h)} \cap (s(J(Q \cap X, X)) \otimes_M \mathbb{O}(-2h)), \end{aligned}$$

where the equality $\stackrel{!}{=}$ follows by applying [Aluffi 1994, Proposition 1]. Since the degree of a class in X is the degree of its component of dimension 0, i.e., codimension $\dim X$, this gives

$$\begin{aligned} \gamma(X) &= (-1)^{\dim X} \int \left(\frac{1}{1-h} \cdot \frac{c(T^*X)}{1-2h} \cap (s(J(Q \cap X, X)) \otimes_M \mathbb{O}(-2h)) \right)^\vee \\ &= (-1)^{\dim X} \int \frac{1}{1+h} \cdot \frac{c(TX)}{1+2h} \cap (s(J(Q \cap X, X))^\vee \otimes_M \mathbb{O}(2h)). \end{aligned}$$

Finally, by (6-2) (with $M = X$, $V = Q \cap X$, $\mathcal{L} = \mathbb{O}(V) = \mathbb{O}(2h)$), we get

$$\gamma(X) = \int \frac{1}{1+h} \cap \mathcal{M}(Q \cap X),$$

and this implies (6-1). □

Corollary 6.3. *If $Q \cap X$ only has isolated singularities x_i , then*

$$\text{EDdeg}(X) = \text{gEDdeg}(X) - \sum_i \mu(x_i),$$

where $\mu(-)$ denotes the Milnor number.

We will see that this is in fact the case for most smooth hypersurfaces (Section 9.3).

7. Euclidean distance degree and Chern–Schwartz–MacPherson classes

Our next aim is to express the Euclidean distance degree of a nonsingular projective variety directly, rather than in terms of a correction from a “generic” situation. CSM classes provide a convenient means to do so. The formula presented in Section 8 may look more appealing, but the alternative (7-1) presented here, besides being a necessary intermediate result, is in a sense algorithmically more direct.

Theorem 7.1. *Let X be a smooth subvariety of \mathbb{P}^{n-1} . Then*

$$\text{EDdeg}(X) = (-1)^{\dim X} \sum_{j \geq 0} (-1)^j (c(X)_j - c_{\text{SM}}(Q \cap X)_j). \tag{7-1}$$

Here, $c_{\text{SM}}(Q \cap X)_j$ denotes the degree of the j -dimensional component of $Q \cap X$. Again, (7-1) is straightforward to implement given available algorithms for characteristic classes (for example [Aluffi 2003; Jost 2015; Harris 2017]).

Remark 7.2. If $X \subseteq Q$, then $c_{\text{SM}}(Q \cap X) = c_{\text{SM}}(X) = c(X)$ by the basic normalization property of CSM classes, as X is nonsingular. In this case (7-1) gives $\text{EDdeg}(X) = 0$, as it should (see Remark 2.1). Therefore, we will assume $X \not\subseteq Q$ in the proof.

Remark 7.3. In the proof we will use the fact that $c(X) = c_{\text{F}}(X)$ if X is nonsingular. This prevents a straightforward generalization of the argument to the case in which X is only required to be nonsingular in a neighborhood of $Q \cap X$.

Proof. According to Theorem 6.1,

$$\text{EDdeg}(X) = \text{gEDdeg}(X) - (-1)^{\dim X} \sum_{j \geq 0} (-1)^j (c_{\text{SM}}(Q \cap X)_j - c_{\text{F}}(Q \cap X)_j).$$

By (3-1), therefore, $\text{EDdeg}(X)$ equals

$$(-1)^{\dim X} \sum_{j \geq 0} (-1)^j ((2^{j+1} - 1)c(X)_j + c_{\text{F}}(Q \cap X)_j - c_{\text{SM}}(Q \cap X)_j). \tag{7-2}$$

By definition,

$$c_{\text{F}}(Q \cap X) = c(TX) \cap s(Q \cap X, X) = \frac{c(TX) \cdot 2h}{1+2h} \cap [X]$$

(after push-forward to X) since $Q \cap X$ is a hypersurface in X and $\mathbb{O}(Q) = \mathbb{O}(2h)$ as Q is a quadric. Therefore

$$\sum_{j \geq 0} (-1)^j c_F(Q \cap X)_j = \int \frac{1}{1+h} \frac{2h}{1+2h} c(TX) \cap [X] = \sum_{j \geq 0} c(X)_j \int \frac{h^{\dim X - j}}{1+h} \frac{2h}{1+2h} \cap [\mathbb{P}^{\dim X}].$$

The coefficient of $c(X)_j$ in this expression equals the coefficient of h^j in the expansion of

$$\frac{2h}{(1+h)(1+2h)} = \sum_{j \geq 0} (-1)^{j+1} (2^{j+1} - 2) h^j.$$

Therefore (7-2) gives

$$\text{EDdeg}(X) = (-1)^{\dim X} \sum_{j \geq 0} (-1)^j ((2^{j+1} - 1) - (2^{j+1} - 2)) c(X)_j - c_{\text{SM}}(Q \cap X)_j$$

and (7-1) follows. □

CSM classes may be associated with locally closed sets: if V is a locally closed set of a variety M , then $c_{\text{SM}}(V) = c_*(\mathbb{1}_V)$ is a well-defined class in A_*M . (If $V = \bar{V} \setminus W$, with W closed, then $c_{\text{SM}}(V) = c_{\text{SM}}(\bar{V}) - c_{\text{SM}}(W)$.) This notation allows us to express (7-1) in (even) more concise terms: if X is a smooth subvariety of \mathbb{P}^{n-1} , and $X \not\subseteq Q$, then

$$\text{EDdeg}(X) = (-1)^{\dim X} \sum_{j \geq 0} (-1)^j c_{\text{SM}}(X \setminus Q)_j. \tag{7-3}$$

Indeed, $c(X) = c_{\text{SM}}(X)$ since X is nonsingular.

If $Q \cap X$ is (supported on) a simple normal crossing divisor, (7-3) admits a particularly simple expression, given in the corollary that follows. An illustration of this case will be presented in Section 9.6.

Corollary 7.4. *Let $X \subseteq \mathbb{P}^{n-1}$ be a smooth subvariety, and assume the support of $Q \cap X$ is a divisor D with normal crossings and nonsingular components D_i , $i = 1, \dots, r$. Then*

$$\text{EDdeg}(X) = \int \frac{c(T^*X(\log D))}{1-H} \cap [X] = \int \frac{1}{1-H} \cdot \frac{c(T^*X)}{\prod_i (1-D_i)} \cap [X].$$

Proof. If D is a simple normal crossing divisor in X , then

$$c_{\text{SM}}(X \setminus D) = c(TX(-\log D)) \cap [X] \tag{7-4}$$

(see [Aluffi 1999b], or [Goresky and Pardon 2002, Proposition 15.3]). Using this fact in (7-3), the stated formulas follow from simple manipulations and the well-known expression for $c(T^*X(\log D))$ when D is a simple normal crossing divisor. □

Liao has shown that (7-4) holds as soon as D is a free divisor that is locally quasihomogeneous [Liao 2012] or more generally with Jacobian of linear type [Liao 2018]. Therefore, $\text{EDdeg}(X) = \int c(T^*X(\log D))/(1-H) \cap [X]$ as in Corollary 7.4 as soon as the support of $Q \cap X$ satisfies these less restrictive conditions.

8. Euclidean distance degree and Euler characteristics

Finally, we present a version of the main result which makes no use (in its formulation) of characteristic classes for singular varieties. This is the version given in the introduction.

Theorem 8.1. *Let X be a smooth subvariety of \mathbb{P}^{n-1} . Then*

$$\text{EDdeg}(X) = (-1)^{\dim X} \chi(X \setminus (Q \cup H)), \quad (8-1)$$

where H is a general hyperplane.

By the inclusion-exclusion property of the topological Euler characteristic, (8-1) is equivalent to

$$\text{EDdeg}(X) = (-1)^{\dim X} (\chi(X) - \chi(X \cap Q) - \chi(X \cap H) + \chi(X \cap Q \cap H)) \quad (8-2)$$

which has the advantage of only involving closed subsets of \mathbb{P}^{n-1} . Any of the aforementioned implementations of algorithms for characteristic classes of singular varieties includes explicit functions to compute Euler characteristics of projective schemes from defining homogenous ideals, so (8-2) is also essentially trivial to implement. However, despite its conceptual simplicity, this expression is computationally expensive.

Remark 8.2. As in Section 7, we have to insist that X be smooth; only requiring it to be nonsingular in a neighborhood of $Q \cap X$ is not enough for the result to hold.

Proof. The statement is a consequence of Theorem 7.1 and of a result from [Aluffi 2013]. Collect the degrees of the components of the CSM class of a locally closed set $V \subseteq \mathbb{P}^N$ into a polynomial

$$\Gamma_V(t) = \sum_{j \geq 0} c_{\text{SM}}(V)_j t^j;$$

and collect the signed Euler characteristics of generic linear sections of V into another polynomial

$$\chi_V(t) = \sum_{j \geq 0} (-1)^j \chi(V \cap H_1 \cap \cdots \cap H_j) t^j,$$

where the H_i 's are general hyperplanes. Then according to [Aluffi 2013, Theorem 1.1] we have

$$\Gamma_V(t) = \mathcal{F}(\chi_V),$$

where \mathcal{F} is an explicit involution. It follows from the specific expression of \mathcal{F} that

$$\Gamma_V(-1) = \chi_V(0) + \chi_V'(0)$$

(see the paragraph preceding the statement of [Aluffi 2013, Theorem 1.1]). Therefore

$$\sum_{j \geq 0} (-1)^j c_{\text{SM}}(V)_j = \chi(V) - \chi(V \cap H) \quad (8-3)$$

for every locally closed set V in projective space.

The statement of the theorem, in the form given in (8-2), follows by applying (8-3) to (7-1). \square

9. Examples

9.1. Computations. The ingredients needed to implement the main theorems of this text on computer algebra systems such as [Sage] or [Macaulay2] are all available. One can compute Segre classes and Chern–Mather classes via [Harris 2017] and Chern–Schwartz–MacPherson classes via (for example) any of [Aluffi 2003; Marco-Buzunáriz 2012; Jost 2013; 2015; Helmer 2016; Harris 2017]. One issue in concrete examples is that computer algebra systems prefer to work with \mathbb{Q} -coefficients, and it is often difficult to write the defining equations of a variety which is tangent to the isotropic quadric without extending the field of coefficients. This difficulty can sometimes be circumvented by a suitable choice of coordinates; see Remark 5.7. Also see Section 9.5 below for a discussion of a template situation.

In many cases, the “standard” algorithm of [Draisma et al. 2016, Example 2.11] appears to be at least as fast as the alternatives obtained by implementing the results presented here. In some examples these alternatives are faster, particularly if they take advantage of the refinements which will be presented below. As an illustration, we can apply Proposition 9.2 (Section 9.4) to compute the ED degrees of plane curves in terms of a generator of their homogeneous ideal. A (non-optimal) implementation of this method in Macaulay2 can be coded as follows:

```
PP2 = QQ[x,y,z]; C = ideal( F )
S = QQ[s,t,i,Degrees=>{{1,0},{1,0},{0,1}}]/(i^2+1)
J = sub(C,{x=>s^2-t^2,y=>2*s*t,z=>i*(s^2+t^2)})
p = (first degrees radical J)#0 -- ignore degree of i
d = degree C
d*(d-2) + p
```

where $F = F(x, y, z)$ is the defining homogeneous polynomial for the curve.

For example, trial runs of computations of the ED degrees of Fermat curves $x^d + y^d + z^d = 0$ for all degrees $d = 3, \dots, 40$ took an average of 4.5 seconds using this method (in a more efficient implementation), and 260 seconds by using the standard algorithm. However, direct implementations of the general formulas presented in this paper do not fare as well.

The interested reader can find the actual code used here, as well as implementations of the more general formulas at <http://github.com/coreysharris/EDD-M2>. At this stage, the value of the formulas obtained in Theorems 5.1–8.1 appears to rest more on their theoretical applications (in examples such as the ones discussed below in Section 9.6) than in the speed of their computer algebra implementations.

If the variety is known to be transversal to the isotropic quadric, then its Euclidean distance degree equals the *generic* Euclidean distance degree. This may be computed by using the algorithm for Chern–Mather classes in [Harris 2017], often faster than the standard algorithm. For example, let S be a general hyperplane section of the second Veronese embedding of \mathbb{P}^3 in \mathbb{P}^9 . Then S is transversal to the isotropic quadric, and the implementation of the algorithm in [Harris 2017] computes its Euclidean distance degree (i.e., 36) in about 2 seconds. The standard algorithm appears to take impractically long on this example;

one can improve its performance by first projecting S to a general \mathbb{P}^3 (this does not affect the Euclidean distance degree, by [Draisma et al. 2016, Corollary 6.1]), and the computation then takes about a minute.

9.2. Quadrics and spheres. Let $X \subseteq \mathbb{P}^{n-1}$ be a nonsingular quadric hypersurface. We say that X is a *sphere* if it is given by the equation

$$x_1^2 + \cdots + x_{n-1}^2 = cx_n^2$$

with $c > 0$ a real number. It is clear from the definition in terms of critical points of the distance function that $\text{EDdeg}(X) = 2$ if X is a sphere in \mathbb{P}^{n-1} , $n \geq 2$.

We use this example to illustrate some of the formulas obtained in this paper.

First, since X is a degree 2 hypersurface in \mathbb{P}^{n-1} ,

$$c(TX) = \frac{c(T\mathbb{P}^{n-1}|_X)}{1+2h} = \frac{(1+h)^n}{1+2h}$$

(where h denotes the hyperplane class and its pull-backs, as in previous sections). Applying (3-1), one easily sees that

$$\text{gEDdeg}(X) = 2n - 2,$$

while

$$c(T^*X \otimes \mathcal{O}(2h)) = \frac{(1-h+2h)^n}{(1+2h)(1-2h+2h)} = \frac{(1+h)^n}{1+2h}.$$

For a sphere $X \subseteq \mathbb{P}^{n-1}$, the intersection $Q \cap X$ consists of a double quadric in \mathbb{P}^{n-2} , supported on the transversal intersection $X \cap H$ of X with a hyperplane. It follows that $J(Q \cap X) = X \cap H$, and therefore

$$s(J(Q \cap X), X) = \frac{h \cdot [X]}{1+h}.$$

According to Theorem 5.1, the correction term in this case is given by

$$\begin{aligned} \int \frac{(1+2h) \cdot c(T^*X \otimes \mathcal{O}(2h))}{1+h} \cdot s(J(Q \cap X), X) &= \int \frac{(1+2h)(1+h)^n}{(1+h)(1+2h)} \cdot \frac{h \cdot 2h}{1+h} \cap [\mathbb{P}^{n-1}] \\ &= \int 2(1+h)^{n-2} \cdot h^2 \cap [\mathbb{P}^{n-1}] \\ &= 2(n-2). \end{aligned}$$

By (5-1), $\text{EDdeg}(X) = (2n - 2) - 2(n - 2) = 2$, as it should.

From the point of view of Theorem 8.1, we should deal with the topological Euler characteristics of X , $X \cap Q$, $X \cap H$, $X \cap Q \cap H$, where H is a general hyperplane (see (8-2)). If X is a sphere, then $X \cap Q$ is (supported on) a nonsingular quadric in \mathbb{P}^{n-2} ; so is $X \cap H$, and $X \cap Q \cap H$ is a nonsingular quadric in \mathbb{P}^{n-3} . The Euler characteristic of a nonsingular quadric in \mathbb{P}^N is $N + 1$ if N is odd, N if N is even; therefore

$$\chi(X) - \chi(X \cap Q) - \chi(X \cap H) + \chi(X \cap Q \cap H) = \begin{cases} (n - 1) - 2(n - 1) + (n - 3) = -2 & n \text{ odd,} \\ n - 2(n - 2) + (n - 2) = 2 & n \text{ even.} \end{cases}$$

and by [Theorem 8.1](#),

$$\text{EDdeg}(X) = (-1)^{\dim X} \chi(X \setminus (Q \cup H)) = 2$$

for all n , as expected.

9.3. Hypersurfaces. The case of smooth hypersurfaces of degree ≥ 3 is more constrained than it may look at first.

Claim 9.1. If two smooth hypersurfaces of degree d_1, d_2 in projective space are tangent along a positive dimensional algebraic set, then $d_1 = d_2$.

(This is [\[Aluffi 2000, Claim 3.2\]](#).) It follows that if $X \subset \mathbb{P}^{n-1}$ is a smooth hypersurface of degree $d \neq 2$, then the intersection $Q \cap X$ necessarily has isolated singularities. We are then within the scope of [Corollary 6.3](#), and we can conclude

$$\text{EDdeg}(X) = \text{gEDdeg}(X) - \sum_i \mu(x_i),$$

where the sum is over all singularities x_i of $Q \cap X$, and $\mu(-)$ denotes the Milnor number.

9.4. Curves. Let $C \subseteq \mathbb{P}^{n-1}$ be a nonsingular curve. Then

$$\text{EDdeg}(C) = d + \#(Q \cap C) - \chi(C). \tag{9-1}$$

(This follows immediately from [Theorem 8.1](#).)

For example, the twisted cubic parametrized by

$$(s : t) \mapsto (s^3 : \sqrt{3}s^2t : \sqrt{3}st^2 : t^3)$$

has EDdeg equal to 3: indeed, it meets the isotropic quadric at the images of the solutions of $s^6 + 3s^4t^2 + 3s^2t^4 + t^6 = (s^2 + t^2)^3 = 0$, that is, at two points. More generally, the Euclidean distance degree of the rational normal curve of degree $n - 1$ in \mathbb{P}^{n-1} parametrized by

$$(s : t) \mapsto \left(\sqrt{\binom{n-1}{j}} s^{n-1-j} t^j \right)_{j=0, \dots, n-1}$$

is $(n - 1) + 2 - 2 = n - 1$.

For *plane curves*, [\(9-1\)](#) admits a particularly explicit formulation.

Proposition 9.2. *Let C be a nonsingular plane curve, defined by an irreducible homogeneous polynomial $F(x, y, z)$. Then*

$$\text{EDdeg}(C) = d(d - 2) + R,$$

where R is the number of distinct factors of the polynomial

$$F(s^2 - t^2, 2st, i(s^2 + t^2)) \in \mathbb{C}[t]$$

and $d = \deg F$.

Proof. This follows immediately from (9-1), after observing that $d - \chi(C) = d - (2 - (d - 1)(d - 2)) = d(d - 2)$ and that the isotropic conic $x^2 + y^2 + z^2 = 0$ is parametrized by $(s : t) \mapsto (s^2 - t^2, 2st, i(s^2 + t^2))$. □

For instance, consider the conic $x^2 + 2y^2 + 2iyz = 0$. Since

$$(s^2 - t^2)^2 + 2(2st)^2 + 2i(2st)(i(s^2 + t^2)) = (s - t)^4,$$

we have $R = 1$, therefore its Euclidean distance degree is $2 \cdot 0 + 1 = 1$.

For another example, the Fermat quintic $C: x^5 + y^5 + z^5 = 0$ has $R = 8$ (as Macaulay2 can verify), therefore $\text{EDdeg}(C) = 5 \cdot 3 + 8 = 23$ (see [Draisma et al. 2016, Example 2.5]). More generally, the Euclidean distance degree of the Fermat curve $x^d + y^d + z^d = 0$ is $d(d - 2) + R$, where R is the number of distinct factors of the polynomial

$$(s^2 - t^2)^d + (2st)^d + (i(s^2 + t^2))^d.$$

An explicit expression for the Euclidean distance degree of Fermat hypersurfaces in any dimension may be found in [Lee 2017, Theorem 4].

9.5. Surfaces. According to Theorem 8.1, if $S \subseteq \mathbb{P}^{n-1}$ is a smooth degree- d surface, and C is the support of the intersection $Q \cap S$ (which may very well be singular), then

$$\text{EDdeg}(S) = \chi(S) - \chi(S \cap H) - \chi(C) + \text{deg}(C),$$

where H is a general hyperplane. If $n - 1 = 3$, then $\chi(S) = d(d^2 - 4d + 6)$ and $\chi(S \cap H) = 3d - d^2$; for $d \neq 2$, C is necessarily reduced (Claim 9.1), so $\text{deg}(C) = 2d$. In this case ($S \subseteq \mathbb{P}^3$ a smooth surface of degree $d \neq 2$, or more generally such that $S \cap Q$ is reduced),

$$\text{EDdeg}(S) = d(d^2 - 4d + 6) - (3d - d^2) - \chi(C) + 2d = d(d^2 - 3d + 5) - \chi(C). \tag{9-2}$$

If C is nonsingular, then $\chi(C) = -2d(d - 2)$, and $\text{EDdeg}(S) = \text{gEDdeg}(S) = d(d^2 - d + 1)$.

If S is a plane in \mathbb{P}^3 , tangent to the isotropic quadric Q , then $C = Q \cap S$ is a pair of lines, and (9-2) gives $\text{EDdeg}(S) = 0$. But note that the coefficients of the equation of this plane are necessarily not all real, so the enumerative interpretation of $\text{EDdeg}(S)$ as the number of critical points of a “distance” function should be taken *cum grano salis*.

Next let S be a Veronese surface in \mathbb{P}^5 , described parametrically by

$$(s : t : u) \mapsto (a_1s^2 : a_2st : a_3su : a_4t^2 : a_5tu : a_6u^2)$$

with $a_1 \dots a_6 \neq 0$. According to Theorem 8.1,

$$\text{EDdeg}(S) = 3 - 2 - \chi(C) + 2 \text{deg } C = 2 \text{deg } C - \chi(C) + 1,$$

where C is the support of the curve with equation

$$a_1^2x^4 + a_2^2x^2y^2 + a_3^2x^2z^2 + a_4y^4 + a_5y^2z^2 + a_6z^4 = 0 \tag{9-3}$$

in the plane. (The degree of the image of C in \mathbb{P}^5 is $2 \deg C$.)

For example, if C is a smooth quartic (the “generic” case), then $\chi(C) = -4$ and $\text{EDdeg}(S) = \text{gEDdeg}(S) = 13$. If the rank of the matrix

$$\begin{pmatrix} 2a_1^2 & a_2^2 & a_3^2 \\ a_2^2 & 2a_4^2 & a_5^2 \\ a_3^2 & a_5^2 & 2a_6^2 \end{pmatrix} \tag{9-4}$$

is 1, then (9-3) is a double (smooth) conic, so that $\chi(C) = \deg(C) = 2$ and $\text{EDdeg}(S) = 3$. For example, this is the case for

$$(s : t : u) \mapsto (s^2 : \sqrt{2} st : \sqrt{2} su : t^2 : \sqrt{2} tu : u^2). \tag{9-5}$$

If the rank of (9-4) is 2, then (9-3) factors as a product

$$(a'x^2 + b'y^2 + c'z^2)(a''x^2 + b''y^2 + c''z^2) = 0$$

and the factors are different and correspond to nonsingular conics. If these conics meet transversally, then $\text{EDdeg}(S) = 9$; if they are “bitangent”, then $\text{EDdeg}(S) = 7$ (use [Corollary 6.3](#), or again [Theorem 8.1](#)). Explicit examples of these two types are

$$(s : t : u) \mapsto (s^2 : \sqrt{3} st : 2 su : \sqrt{2} t^2 : \sqrt{5} tu : \sqrt{3} u^2)$$

and

$$(s : t : u) \mapsto (s^2 : \sqrt{3} st : \sqrt{2} su : \sqrt{2} t^2 : \sqrt{3} tu : u^2).$$

More general Veronese embeddings are considered in [Section 9.6](#).

Note that we could equivalently hold the surface $S = X$ fixed, choosing for example the standard Veronese embedding, parametrized by $(s : t : u) \mapsto (s^2 : st : su : t^2 : tu : u^2)$ with ideal

$$(x_1x_4 - x_2^2, x_1x_5 - x_2x_3, x_1x_6 - x_3^2, x_2x_5 - x_3x_4, x_2x_6 - x_3x_5, x_4x_6 - x_5^2)$$

in $\mathbb{P}^5_{(x_1, \dots, x_6)}$, and consider a more general nonsingular quadric

$$Q : q_1x_1^2 + q_2x_2^2 + \dots + q_6x_6^2 = 0,$$

$q_1 \dots q_6 \neq 0$, in place of the isotropic quadric. This corresponds to a change of coordinates $x_i \mapsto \sqrt{q_i}x_i$; i.e., $q_i = a_i^2$ with notation as above. The right-hand side $\text{EDdeg}(Q, X)$ of (5-1) (or equivalently (6-1), (7-1), (8-1)) is independent of the coordinate choice; see [Remark 5.7](#). For example, choosing

$$x_1^2 + 2x_2^2 + 2x_3^2 + x_4^2 + 2x_5^2 + x_6^2 = 0$$

for Q , along with the standard Veronese embedding, is equivalent to choosing the standard isotropic quadric along with the embedding (9-5) (hence $\text{EDdeg}(Q, X) = 3$ in this case).

This observation may be useful in effective computations, since computer algebra systems prefer to work with \mathbb{Q} coefficients.

9.6. Segre and Segre–Veronese varieties. Let X be the image of the usual Segre embedding

$$\mathbb{P}(\mathbb{C}^{m_1}) \times \cdots \times \mathbb{P}(\mathbb{C}^{m_p}) \rightarrow \mathbb{P}(\mathbb{C}^{m_1} \otimes \cdots \otimes \mathbb{C}^{m_p}),$$

that is, $\mathbb{P}^{m_1-1} \times \cdots \times \mathbb{P}^{m_p-1} \rightarrow \mathbb{P}^{m_1 \cdots m_p-1}$. This embedding maps a point

$$((s_1^1 : \cdots : s_{m_1}^1), \dots, (s_1^p : \cdots : s_{m_p}^p))$$

to the point in $\mathbb{P}^{m_1 \cdots m_p-1}$ whose homogeneous coordinates (\underline{x}) are all the monomials of multidegree $(1, \dots, 1)$ in the variables $\underline{s}^1, \dots, \underline{s}^p$. The equation $\sum_i x_i^2 = 0$ of the isotropic quadric pulls back to

$$\left(\sum_i (s_i^1)^2 \right) \cdots \left(\sum_i (s_i^p)^2 \right) = 0.$$

Let Q_i be the isotropic quadric in the i -th factor. Then this shows that

$$Q \cap X = (Q_1 \times \mathbb{P}^{m_2-1} \times \cdots \times \mathbb{P}^{m_p-1}) \cup \cdots \cup (\mathbb{P}^{m_1-1} \times \cdots \times \mathbb{P}^{m_{p-1}-1} \times Q_p).$$

It follows that $Q \cap X$ is a divisor with normal crossings and nonsingular components. Denoting by h_i the hyperplane class in the i -th factor, the class of the i -th component is $2h_i$. By [Corollary 7.4](#),

$$\text{EDdeg}(X) = \int \frac{1}{1 - h_1 - \cdots - h_p} \cdot \frac{(1 - h_1)^{m_1} \cdots (1 - h_p)^{m_p}}{(1 - 2h_1) \cdots (1 - 2h_p)} \cap [X]. \tag{9-6}$$

The conclusion is that $\text{EDdeg}(\mathbb{P}^{m_1-1} \times \cdots \times \mathbb{P}^{m_p-1})$ equals the coefficient of $h_1^{m_1-1} \cdots h_p^{m_p-1}$ in the expansion of

$$\frac{1}{1 - h_1 - \cdots - h_p} \cdot \prod_{i=1}^p \frac{(1 - h_i)^{m_i}}{1 - 2h_i}.$$

Friedland and Ottaviani [[2014](#), Theorem 4] (see [[Draisma et al. 2016](#), Theorem 8.1]) obtain a different expression for the same quantity: they prove that it must equal the coefficient of $z_1^{m_1-1} \cdots z_p^{m_p-1}$ in the expression

$$\prod_{i=1}^p \frac{\hat{z}_i^{m_i} - z_i^{m_i}}{\hat{z}_i - z_i}, \tag{9-7}$$

where $\hat{z}_i = (z_1 + \cdots + z_p) - z_i$. These coefficients must be equal, since they both compute the Euclidean distance degrees of Segre varieties. We note that, for example,

$$\text{EDdeg}(\mathbb{P}^2 \times \mathbb{P}^8 \times \mathbb{P}^{11} \times \mathbb{P}^{13} \times \mathbb{P}^{24}) = 1430462027777307645494624$$

according to *both* formulas.

The same technique may be used to deal with *Segre–Veronese varieties*, obtained by composing a Segre embedding with a product of Veronese embeddings:

$$\mathbb{P}(\mathbb{C}^{m_1}) \times \cdots \times \mathbb{P}(\mathbb{C}^{m_p}) \rightarrow \mathbb{P}(\text{Sym}^{\omega_1} \mathbb{C}^{m_1}) \times \cdots \times \mathbb{P}(\text{Sym}^{\omega_p} \mathbb{C}^{m_p}) \rightarrow \mathbb{P}(\text{Sym}^{\omega_1} \mathbb{C}^{m_1} \otimes \cdots \otimes \text{Sym}^{\omega_p} \mathbb{C}^{m_p}).$$

Using general coordinates for the Veronese embeddings, each Q_i (with notation as above) restricts to a smooth hypersurface of degree $2\omega_i$, and the resulting hypersurfaces of the product meet with normal crossings. The hyperplane class restricts to $\omega_1 h_1 + \cdots + \omega_p h_p$, therefore (again by [Corollary 7.4](#)) the EDdegree of this variety equals the coefficient of $h_1^{m_1-1} \cdots h_p^{m_p-1}$ in the expansion of

$$\frac{1}{1 - \omega_1 h_1 - \cdots - \omega_p h_p} \cdot \prod_{i=1}^p \frac{(1 - h_i)^{m_i}}{1 - 2\omega_i h_i}. \quad (9-8)$$

Friedland and Ottaviani also consider Segre–Veronese varieties, but they choose suitably invariant coordinates in each factor; this is a different problem. (For $p = 1$, $m_1 = \omega_1 = 2$, this choice of coordinates is given by [\(9-5\)](#).) They prove [[Friedland and Ottaviani 2014](#), [Draisma et al. 2016](#), Theorem 8.6] that with these special coordinates the EDdegree is given again by the coefficient of $z_1^{m_1-1} \cdots z_p^{m_p-1}$ in [\(9-7\)](#), but where now $\hat{z}_i = (\omega_1 z_1 + \cdots + \omega_p z_p) - z_i$. From our point of view, the choice of coordinates affects the restrictions of the isotropic quadrics Q_i to the factors. With the invariant coordinates used by Friedland and Ottaviani, each Q_i restricts to a multiple *quadric*, and this affects the denominator of [\(9-8\)](#): the resulting EDdegree equals the coefficient of $h_1^{m_1-1} \cdots h_p^{m_p-1}$ in the expansion of

$$\frac{1}{1 - \omega_1 h_1 - \cdots - \omega_p h_p} \cdot \prod_{i=1}^p \frac{(1 - h_i)^{m_i}}{1 - 2h_i}. \quad (9-9)$$

Therefore, this coefficient must agree with the one obtained with the Friedland–Ottaviani formula. (It does not seem combinatorially trivial that this should be the case in general; it is easy to verify that both formulas yield $((\omega_1 - 1)^{m_1} - 1)/(\omega_1 - 2)$ for $p = 1$.)

Acknowledgments

This work was supported in part by NSA grant H98230-16-1-0016. The authors thank Giorgio Ottaviani for suggesting the example presented in [Section 9.6](#).

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Communicated by Ravi Vakil

Received 2017-11-03 Revised 2018-05-03 Accepted 2018-06-19

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ANT peer review and production are managed by EditFLOW® from MSP.

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