

On a causal analysis of economic time series

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Abstract. This paper describes a testing methodology for causal relations between time series. The concept of the local causality and the instantaneous local causality is introduced. The mathematical structure of the local causality is shown. The data of GNP and Money Supply are analyzed by the proposed test.

Key words: Local and weak stationarity. KM₂O-Langevin equation. Test(S), Local causality, Instantaneous local causality, Real GNP, Money Supply, Local Causal Test, Instantaneous Local Causal Test.

1. Introduction

A weakly stationary process, whose time parameter space is a finite interval of \mathbf{T} , is called a local and weakly stationary process. The letter \mathbf{T} denotes $\{0, \pm 1, \pm 2, \dots\}$. In the present paper, we propose a concept of causality, which we call local causality, in local and weakly stationary processes. Local causality is defined from the predictional point of view. We propose a method, which we call the Local Causal Test, how to test local causal relations in local and weakly stationary processes. As an application, time series of Money Supply and Real Gross National Product (RGNP), which are known as the most important time series in economics, are analyzed to find local causal relations.

The well-known Granger's causality (Granger [7]) was defined for stochastic processes whose time parameter space is \mathbf{T} . Up to this day, many works on causal analysis in Granger's sense (eg., [7], Sims [33], Sargent [31], Ram [30], Komura [10]) are known. Among them a test which is called the Granger and Sargent Test is often used. Including these works, almost all studies in time series analysis use simplified models such as autoregressive (AR) or autoregressive moving average (ARMA) models in the model fitting for given data. As economists emphasize, the methods above, assuming "weak stationarity" of given data, have a contradiction from the viewpoint of the theory of stochastic processes (e.g., Sawa [32]).

On the other hand, we do not take the position that given data have “weak stationarity”. Okabe and Nakano [26] constructed Test(S) which states a criterion that multi-dimensional data are a realization of a local and weakly stationary process. We apply this Test(S) to given data, including some transformed data. If the data pass Test(S), viz. that they are accepted to be a realization of a local and weakly stationary time series, we proceed to further analysis. In like manner, Okabe [19] defined causality in local and weakly stationary processes from the viewpoint of the prediction and proposed a method how to test it. Okabe and Inoue [25] developed this analysis further. As we mentioned at the beginning of this section, we shall propose a concept of causality from the predictational point of view, and develop its analysis such as the Local Causal Test in this paper. We compare the Local Causal Test with the Granger-Sargent Test when both tests are applied to time series of Money Supply and RGNP.

The outline of this paper is as follows: Through this paper the theory of KM_2O -Langevin equations, which are associated with local and weakly stationary processes, plays a crucial role. Therefore we overview in §2 briefly the theory of KM_2O -Langevin equations. As an application of this theory, it was proposed to apply Test(S) to the question of whether given data are a realization of a local and weakly stationary process or not (see [26]). In §3 we summarize the deduced process of Test(S). We applied Test(S) to quarterly data of Money Supply and RGNP in three periods. [30] and [10] analyzed the causal relation in Granger’s sense between these data in the period from 1955-I to 1971-II. They assumed that the first order differences of log-transformed data are a realization of an AR model. However the result of Table 3.1 shows that they are not a realization of a local and weakly stationary process. In the periods from 1965 to 1987 and from 1965 to 1990, we accept from Table 3.2 and Table 3.3 that the second order differences of the original data are a realization of a local and weakly stationary process.

§4 introduces Granger’s causality for stochastic processes whose time parameter space is \mathbf{T} and summarizes briefly the Granger-Sargent Test which is a representative test for Granger’s causality. As above mentioned, the Granger-Sargent Test also assumes that given data are a realization of an AR model. This test is applied to quarterly data of Money Supply and RGNP in the periods from 1965 to 1987 and from 1965 to 1990. The results shown in Table 4.1 and Table 4.2 report that RGNP causes, in Granger’s sense, Money Supply in both periods. However converse relations are not

accepted. These results are compared with the results of the Local Causal Test which is developed in §6.

We define in §5 the local causality and the instantaneous local causality between local and weakly stationary processes, and characterize them. On the basis of the theory of KM_2O -Langevin equations, we investigate in Theorem 5.2 a mathematical structure of the causal relation between local and weakly stationary processes. Theorem 5.1 gives a theory which judges causal relations between local and weakly stationary processes. Moreover, a theory which judges instantaneous causal relations between local and weakly stationary processes is given by Theorem 5.5.

In §6 we apply the theory developed in §5 to data analysis. As an application of Theorem 5.1, we propose the Local Causal Test which tests the local causality between given time series, which are accepted by Test(S) as a realization of a local and weakly stationary process. In the same way, the Instantaneous Local Causal Test is proposed as an application of Theorem 5.5. Both tests are applied to quarterly data of Money Supply and RGNP in the periods from 1965 to 1987 and from 1965 to 1990. Table 5.1 and Table 5.2 report that RGNP locally causes Money Supply in both periods and Money Supply locally causes RGNP in the period from 1965 to 1987. Now, it is an established theory that Money Supply and RGNP are mutually related. On the other hand, we can not accept that Money Supply locally causes RGNP in the period from 1965 to 1990. However, this phenomenon is explicable from the point of view of economics. Since the Granger-Sargent Test does not accept in both periods that Money Supply causes RGNP in Granger's sense, we can assert the efficiency of the Local Causal Test.

2. KM_2O -Langevin equations

The theory of KM_2O -Langevin equations was introduced by Okabe [17]. Following the notation and terminology of [17] and Okabe-Nakano [26], we overview it in this section. Let $d, N \in \mathbf{N}$. Let $\mathbf{X} = (X(n); |n| \leq N)$ be any d -dimensional stochastic process on a probability space $(\Omega, \mathcal{B}, \mathcal{P})$.

Definition 2.1 \mathbf{X} is called a local and weakly stationary process with covariance function R if it holds that for any $n, m \in \mathbf{T}, |n| \leq N, |m| \leq N$,

$$E(X) = E[X(n)] = \mu \quad (2.1)$$

$$E[(X(n) - \mu)^t(X(m) - \mu)] = R(n - m). \quad (2.2)$$

Without loss of generality, we assume that $\mu = \mathbf{0}$.

For any $n \in \{1, \dots, N\}$, we define a block Toeplitz matrix $S_n \in M(nd; \mathbf{R})$ by

$$S_n = \begin{pmatrix} R(0) & R(1) & \cdots & R(n-1) \\ {}^tR(1) & R(0) & \cdots & R(n-2) \\ \vdots & \vdots & \ddots & \vdots \\ {}^tR(n-2) & {}^tR(n-3) & \cdots & R(1) \\ {}^tR(n-1) & {}^tR(n-2) & \cdots & R(0) \end{pmatrix} \quad (2.3)$$

In this paper, we assume

$$R(0) \in GL(d; \mathbf{R}) \quad (A-1)$$

and

$$S_n \in GL(nd; \mathbf{R}). \quad (A-2)$$

We set

$$X(n) = \begin{pmatrix} X_1(n) \\ X_2(n) \\ \vdots \\ X_d(n) \end{pmatrix} \quad (|n| \leq N). \quad (2.4)$$

For $n_1 < n_2$, $n_1, n_2 \in \{-N, \dots, N\}$, we define $\mathbf{M}_{n_1}^{n_2}(\mathbf{X})$, which is a closed linear subspace of $L^2(\Omega, \mathcal{B}, P)$ by

$$\begin{aligned} \mathbf{M}_{n_1}^{n_2}(\mathbf{X}) = \text{the closed linear hull of} \\ \{X_j(m); 1 \leq j \leq d, n_1 \leq m \leq n_2\}. \end{aligned} \quad (2.5)$$

Especially, we define that

$$\mathbf{M}_0^{-1}(\mathbf{X}) = \mathbf{M}_1^0(\mathbf{X}) = \mathbf{0}. \quad (2.6)$$

For $n \in \{0, \dots, N\}$, $P_{\mathbf{M}_0^{n-1}(\mathbf{X})}$ is a projection operator on $\mathbf{M}_0^{n-1}(\mathbf{X})$, and $P_{\mathbf{M}_{-n+1}^0(\mathbf{X})}$ projection operator on $\mathbf{M}_{-n+1}^0(\mathbf{X})$. Now, the random forces of \mathbf{X} , which we call, $\nu_+ = (\nu_+(n); 0 \leq n \leq N)$, $\nu_- = (\nu_-(-n); 0 \leq n \leq N)$ are introduced:

$$\nu_+(n) = X(n) - P_{\mathbf{M}_0^{n-1}(\mathbf{X})}X(n) \quad (2.7)$$

$$\nu_-(-n) = X(-n) - P_{\mathbf{M}_{-n+1}^0(\mathbf{X})}X(-n). \quad (2.8)$$

It holds that

$$\nu_+(0) = \nu_-(0) = X(0). \quad (2.9)$$

$P_{\mathbf{M}_0^{n-1}(\mathbf{X})}X(n)$ and $P_{\mathbf{M}_{-n+1}^0(\mathbf{X})}X(-n)$ are called fluctuation parts of \mathbf{X} .

For any $n \in \{1, \dots, N\}$, $k \in \{0, \dots, n-1\}$, there exist $\gamma_+(n, k)$, $\gamma_-(n, k) \in M(d; \mathbf{R})$ such that

$$P_{\mathbf{M}_0^{n-1}(\mathbf{X})}X(n) = - \sum_{k=0}^{n-1} \gamma_+(n, k)X(k) \quad (2.10)$$

$$P_{\mathbf{M}_{-n+1}^0(\mathbf{X})}X(-n) = - \sum_{k=0}^{n-1} \gamma_-(n, k)X(-k). \quad (2.11)$$

It holds that

$$\mathbf{M}_0^n(\mathbf{X}) = \mathbf{M}_0^n(\nu_+) \quad (2.12)$$

$$\mathbf{M}_{-n}^0(\mathbf{X}) = \mathbf{M}_{-n}^0(\nu_-). \quad (2.13)$$

The following Theorem 2.1 is known as an expression formula of \mathbf{X} .

Theorem 2.2 *There exists the unique system*

$$\{\gamma_+(n, k), \gamma_-(n, k) \in M(d; \mathbf{R}); 0 \leq k < n \leq N\}$$

such that

$$X(n) = - \sum_{k=0}^{n-1} \gamma_+(n, k)X(k) + \nu_+(n) \quad (2.14)$$

$$X(-n) = - \sum_{k=0}^{n-1} \gamma_-(n, k)X(-k) + \nu_-(-n). \quad (2.15)$$

Here, $\delta_+(n)$, $\delta_-(n)$ ($1 \leq n \leq N$) which are known as partial correlation functions, are defined as

$$\delta_+(n) = \gamma_+(n, 0), \quad \delta_-(n) = \gamma_-(n, 0). \quad (2.16)$$

The equations (2.14) and (2.15) are called KM₂O-Langevin equations associated with \mathbf{X} . There exist interactions between fluctuation parts and dissipation parts. These interactions are called the Fluctuation-Dissipation Theorem (FDT). For $n \in \{0, \dots, N\}$, we set

$$E(\nu_+(n)^t \nu_+(n)) = V_+(n) \text{ and } E(\nu_-(-n)^t \nu_-(-n)) = V_-(n). \quad (2.17)$$

FDT is described as follows:

Theorem 2.3 (FDT). For $1 \leq k < n \leq N$,

- (i) $\gamma_+(n, k) = \gamma_+(n-1, k-1) + \delta_+(n)\gamma_-(n-1, n-1-k)$
- (ii) $\gamma_-(n, k) = \gamma_-(n-1, k-1) + \delta_-(n)\gamma_+(n-1, n-1-k)$
- (iii) $\delta_+(n) = -(R(n) + \sum_{m=0}^{n-2} \gamma_+(n-1, m)R(m+1))V_-(n-1)^{-1}$
- (iv) $\delta_-(n) = -({}^tR(n) + \sum_{m=0}^{n-2} \gamma_-(n-1, m){}^tR(m+1))V_+(n-1)^{-1}$.

For $1 \leq n \leq N$,

- (v) $V_+(n) = (I - \delta_+(n)\delta_-(n))V_+(n-1)$
- (vi) $V_-(n) = (I - \delta_-(n)\delta_+(n))V_-(n-1)$.

For the special case $n = 0$, we get

- (vii) $V_+(0) = V_-(0) = R(0)$
- (viii) $\delta_+(1) = -R(1)R(0)^{-1}$
- (ix) $\delta_-(1) = -{}^tR(1)R(0)^{-1}$.

When $d = 1$, $R(n) = {}^tR(-n)$. Therefore, we can see that

$$\begin{cases} \delta_+(\cdot) = \delta_-(\cdot) \\ \gamma_+(\cdot, \cdot) = \gamma_-(\cdot, \cdot) \\ V_+(\cdot) = V_-(\cdot). \end{cases} \quad (2.18)$$

The system

$$\{\gamma_+(n, k), \gamma_-(n, k), V_+(l), V_-(l); 0 \leq k < n \leq N, 0 \leq l \leq N\}$$

is called a KM₂O-Langevin data associated with covariance function R .

3. Test(S)

Test(S) was proposed by Okabe-Nakano [26] to test whether a given time series is a realization of a local and weakly stationary process or not. Following [26], we summarize the deduced processes of Test(S).

Any $d, N \in \mathbf{N}$ be fixed. We are given any $N+1$ vectors $\mathcal{Z}(n) \in \mathbf{R}^d$ ($0 \leq n \leq N$). $\mathcal{Z} = (\mathcal{Z}(n); 0 \leq n \leq N)$ is called data. The sample mean vector

$\mu^{\mathcal{Z}}$ of \mathcal{Z} and the sample covariance matrix function $R^{\mathcal{Z}} = (R_{jk}^{\mathcal{Z}})_{1 \leq j, k \leq d}$ of \mathcal{Z} are defined as follows:

$$\mu^{\mathcal{Z}} \equiv \frac{1}{N+1} \sum_{m=0}^N \mathcal{Z}(m) \tag{3.1}$$

$$R_{jk}^{\mathcal{Z}}(n) \equiv \frac{1}{N+1} \sum_{m=0}^{N-n} (\mathcal{Z}_j(n+m) - \mu_j^{\mathcal{Z}})(\mathcal{Z}_k(m) - \mu_k^{\mathcal{Z}}) \tag{3.2}$$

$$R_{jk}^{\mathcal{Z}}(-n) \equiv R_{kj}^{\mathcal{Z}}(n), \tag{3.3}$$

where

$$\mu^{\mathcal{Z}} = \begin{pmatrix} \mu_1^{\mathcal{Z}} \\ \vdots \\ \mu_d^{\mathcal{Z}} \end{pmatrix}, \quad \mathcal{Z}(n) = \begin{pmatrix} \mathcal{Z}_1(n) \\ \vdots \\ \mathcal{Z}_d(n) \end{pmatrix} \quad (0 \leq n \leq N). \tag{3.4}$$

The standardized data $\mathcal{X} = (\mathcal{X}(n); 0 \leq n \leq N)$ of \mathcal{Z} is defined as follows:

$$\mathcal{X}(n) = \begin{pmatrix} \sqrt{R_{11}^{\mathcal{Z}}(0)^{-1}} & & \mathbf{0} \\ & \ddots & \\ \mathbf{0} & & \sqrt{R_{dd}^{\mathcal{Z}}(0)^{-1}} \end{pmatrix} (\mathcal{Z}(n) - \mu^{\mathcal{Z}}). \tag{3.5}$$

Let $R^{\mathcal{X}} = (R_{jk}^{\mathcal{X}})_{1 \leq j, k \leq d}$ be the sample covariance matrix function of \mathcal{X} defined similarly to (3.1), (3.2) and (3.3). We can define the sample block Toeplitz matrix $S_n^{\mathcal{X}}$ ($1 \leq n \leq N$) similarly to (2.3). Here, it is assumed that

$$S_n^{\mathcal{X}} \in GL(nd; \mathbf{R}) \quad (1 \leq n \leq N). \tag{3.6}$$

Replacing R by $R^{\mathcal{X}}$ in the algorithm from (i) to (ix) in §2, we get the sample KM₂O-Langevin data

$$\{\gamma_+(n, k), \gamma_-(n, k), V_+(l), V_-(l); 0 \leq k < n \leq N, 0 \leq l \leq N\}.$$

Then $\nu_+ = (\nu_+(n); 0 \leq n \leq N)$ which is called the sample random force of data \mathcal{X} is introduced by

$$\begin{cases} \nu_+(0) = \mathcal{X}(0) \\ \nu_+(n) = \mathcal{X}(n) + \sum_{k=0}^{n-1} \gamma_+(n, k) \mathcal{X}(k) \end{cases} \quad (1 \leq n \leq N). \tag{3.7}$$

We choose lower triangular matrices $W_+(n) \in GL(d; \mathbf{R})$ such that

$$V_+(n) = W_+(n)^t W_+(n) \quad (0 \leq n \leq N). \quad (3.8)$$

We define the d -dimensional data $\xi_+ = (\xi_+(n); 0 \leq n \leq N)$ by

$$\xi_+(n) = W_+(n)^{-1} \nu_+(n) \quad (0 \leq n \leq N). \quad (3.9)$$

Set

$$\xi_+(n) = \begin{pmatrix} \xi_{+1}(n) \\ \vdots \\ \xi_{+d}(n) \end{pmatrix} \quad (0 \leq n \leq N). \quad (3.10)$$

Rearranging (3.10), we can construct the one-dimensional data $\xi = (\xi(n); 0 \leq n \leq d(N+1) - 1)$ as follows: For $n = 0, \dots, d(N+1) - 1$,

$$\xi(n) = \xi_{+p}(m), \quad n = dm + p - 1 \quad (1 \leq p \leq d, 0 \leq m \leq N). \quad (3.11)$$

Then, the Construction Theorem of Okabe [17] suggests that (S.1) and (S.2) below are equivalent to each other.

(S.1) \mathcal{X} is a realization of a local and weakly stationary time series with $R^{\mathcal{X}}$ as its covariance function.

(S.2) ξ realizes an one-dimensional standardized white noise.

To test (S.2), we introduce

$$\mu^\xi, (v^\xi - 1)^\sim \text{ and } R^\xi(n, m) \quad (1 \leq n \leq L_N, 0 \leq m \leq L_N - n)$$

by

$$\mu^\xi = \frac{1}{d(N+1)} \sum_{k=0}^{d(N+1)-1} \xi(k) \quad (3.12)$$

$$\begin{aligned} (v^\xi - 1)^\sim &= \frac{1}{d(N+1)} \left(\sum_{k=0}^{d(N+1)-1} \xi(k)^2 \right) \\ &\quad \times \left(\sum_{k=0}^{d(N+1)-1} (\xi(k)^2 - 1)^2 \right)^{-1/2} \end{aligned} \quad (3.13)$$

$$R^\xi(n, m) = \frac{1}{d(N+1)} \sum_{k=m}^{d(N+1)-1-n} \xi(k) \xi(n+k). \quad (3.14)$$

Here L_N is an effective length of R^ξ , in this case, is taken to be $L_N = [2\sqrt{d(N+1)}] - 1$.

We institute the following criterion (M), (V), and (O) for checking whether ξ satisfies (S.2) or not.

- (M) $\sqrt{d(N+1)}|\mu^\xi| < 1.96$
- (V) $|(v^\xi - 1)^\sim| < 2.2414$
- (O) for any n, m ($1 \leq n \leq L_N, 0 \leq m \leq L_N - n$)

$$d(N+1)\left(\sum_{j=1}^2 (L_{n,m}^{(j)})^{1/2}\right)^{-1} |R^\xi(n, m)| < 1.96.$$

Here $L_{n,m}^{(j)}$ ($1 \leq j \leq 2$) are defined as follows: Dividing $d(N+1)$ and m by $2n$ and n respectively, we get the following expression form.

$$d(N+1) = q(2n) + r \quad (0 \leq r \leq 2n - 1) \tag{3.15}$$

$$m = sn + t \quad (0 \leq t \leq n - 1). \tag{3.16}$$

If $r \in \{0, \dots, n\}$, then

$$\begin{cases} L_{n,m}^{(1)} = \begin{cases} n(q + (s/2)) - m & (s \text{ is even}) \\ n(q - (s+1)/2) & (s \text{ is odd}) \end{cases} \\ L_{n,m}^{(2)} = \begin{cases} n(q - 1 - (s/2)) + r & (s \text{ is even}) \\ n(q - 1 + (s+1)/2) + r - m & (s \text{ is odd}) \end{cases} \end{cases} \tag{3.17}$$

and if $r \in \{n+1, \dots, 2n-1\}$,

$$\begin{cases} L_{n,m}^{(1)} = \begin{cases} n(q - 1 + (s/2)) + r - m & (s \text{ is even}) \\ n(q - 1 - (s+1)/2) + r & (s \text{ is odd}) \end{cases} \\ L_{n,m}^{(2)} = \begin{cases} n(q - (s/2)) & (s \text{ is even}) \\ n(q + (s+1)/2) - m & (s \text{ is odd}). \end{cases} \end{cases} \tag{3.18}$$

Now, it is known that the estimator $R(n)$ has a poor performance when n comes close to N . A rule of experience concerning data analysis tells us that an effective number of the sample covariance matrix function R^χ is considered to be at most $[3\sqrt{N+1}/d]$. Therefore, we set

$$M = [3\sqrt{N+1}/d] - 1. \tag{3.19}$$

Making use of the reliable $\{R(n); 0 \leq n \leq M\}$ and the reliable subsystem

$\{\gamma_+(n, k), \gamma_-(n, k), V_+(l), V_-(l); 0 \leq k < n \leq M, 0 \leq l \leq M\}$, we restate the new criterion alternative to (M), (V) and (O).

For each $i \in \{0, \dots, N - M\}$, we consider the shifted data \mathcal{X}_i with $\mathcal{X}(i)$ as its initial point $\mathcal{X}_i(0)$:

$$\mathcal{X}_i = (\mathcal{X}(i + n); 0 \leq n \leq M). \quad (3.20)$$

Similarly to (3.7), the sample random force $\nu_{+i} = (\nu_{+i}(n); 0 \leq n \leq M)$ of data \mathcal{X}_i is defined by

$$\begin{cases} \nu_{+i}(0) = \mathcal{X}(i) \\ \nu_{+i}(n) = \mathcal{X}(i + n) + \sum_{k=0}^{n-1} \gamma_+(n, k) \mathcal{X}(i + k) \quad (1 \leq n \leq M). \end{cases} \quad (3.21)$$

In (3.10) replacing $\xi(n)$ by $\xi_i(n)$, $\xi_{+j}(n)$ ($1 \leq j \leq d$) by $\xi_{+ij}(n)$ ($1 \leq j \leq d$) and N by M respectively, the one-dimensional data $\xi_i = (\xi_i(n); 0 \leq n \leq d(M + 1) - 1)$ is constructed similarly to (3.11). Moreover, we replace $\xi(n)$ by $\xi_i(n)$ and N by M from (3.12) to (3.18). Then, we get the criterion $(M)_i$, $(V)_i$ and $(O)_i$ which checks that ξ_i is a realization of a normalized white noise. Concerning the main problem of testing the local and weak stationarity of the original data \mathcal{Z} , [26] proposed:

Test(S) : *the rate of $i \in \{0, \dots, N - M\}$ for which $(M)_i$ (resp. $(V)_i$ and $(O)_i$) holds is over 80 percent (resp. 70 percent and 80 percent).*

We say that data \mathcal{Z} is a realization of a local and weakly stationary process if Test(S) is accepted. Also we say simply that \mathcal{Z} has the local and weak stationarity.

The efficiency of Test(S) was certified in [26].

Money Supply and Gross National Product (GNP) are known as representative economic indices. Money Supply is the stock of money consisting of coin, currency, and bank demand deposits. There are several ways to define Money Supply. The bank of Japan has used for some time M_1 as Money Supply, but now mainly uses $M_2 + CD$. Gross National Product is the the total value of the goods and services produced in a nation during a specific period. There are two kinds. One is called Real Gross National Product (RGNP) and another is called Nominal Gross National Product (NGNP).

Ram [30] and Komura [10] discussed the Granger's causal relations between quarterly time series, which are Money Supply (M_1) and RGNP of Japan from 1955-I to 1971-II. They assumed that given data have weak

stationarity in a wide sense.

Now, we apply Test(S) to these data. Let data $\mathcal{Z}_1 = ({}^t(\mathcal{Z}_{11}(n), \mathcal{Z}_{12}(n)); 0 \leq n \leq 65)$ be M_1 and RGNP above. Transforming \mathcal{Z}_∞ , we introduce seven two-dimensional data $\mathcal{Z}_1^{(j)} = (\mathcal{Z}_1^{(j)}(n); 0 \leq n \leq N_j^{(1)})$ ($0 \leq j \leq 6$, $N_0^{(1)} = N_3^{(1)} = N_4^{(1)} = 65$, $N_1^{(1)} = N_5^{(1)} = N_6^{(1)} = 64$, $N_2^{(1)} = 63$) by

$$\mathcal{Z}_1^{(j)}(n) = {}^t(\mathcal{Z}_{11}^{(j)}(n), \mathcal{Z}_{12}^{(j)}(n)) \tag{3.22}$$

$$= \begin{cases} {}^t(\mathcal{Z}_{11}(n), \mathcal{Z}_{12}(n)) & (j = 0) \\ {}^t(\mathcal{Z}_{11}(n+1) - \mathcal{Z}_{11}(n), \mathcal{Z}_{12}(n+1) - \mathcal{Z}_{12}(n)) & (j = 1) \\ {}^t(\mathcal{Z}_{11}^{(1)}(n+1) - \mathcal{Z}_{11}^{(1)}(n), \mathcal{Z}_{12}^{(1)}(n+1) - \mathcal{Z}_{12}^{(1)}(n)) & (j = 2) \\ {}^t(\log \mathcal{Z}_{11}(n), \log \mathcal{Z}_{12}(n)) & (j = 3) \\ {}^t(\arctan \mathcal{Z}_{11}(n), \arctan \mathcal{Z}_{12}(n)) & (j = 4) \\ {}^t(\mathcal{Z}_{11}^{(3)}(n+1) - \mathcal{Z}_{11}^{(3)}(n), \mathcal{Z}_{12}^{(3)}(n+1) - \mathcal{Z}_{12}^{(3)}(n)) & (j = 5) \\ {}^t(\arctan \mathcal{Z}_{11}^{(1)}(n), \arctan \mathcal{Z}_{12}^{(1)}(n)) & (j = 6). \end{cases}$$

Table 3.1 shows the results of Test(S) for these data.

Table 3.1 Test(S) for ${}^t(M_1, \text{RGNP})$ from 1955-I to 1971-II.

j	(M)	(V)	(O)	(S)
0	1.000	0.163	0.981	NS
1	0.962	0.203	1.000	NS
2	1.000	0.188	1.000	NS
3	0.981	0.381	1.000	NS
4	1.000	0.527	1.000	NS
5	0.962	0.500	0.925	NS
6	0.981	0.444	1.000	NS

Here, (M), (V) and (O) denote the rate of i such that $(M)_i$, $(V)_i$ and $(O)_i$ hold respectively. “S” and “NS” indicate for stationarity and non-stationarity respectively. We could not get “stationary data” as far as we tried.

Let $\mathcal{Z}_2 = ({}^t(\mathcal{Z}_{21}(n), \mathcal{Z}_{22}(n)); 0 \leq n \leq 91)$ and $\mathcal{Z}_3 = ({}^t(\mathcal{Z}_{31}(n), \mathcal{Z}_{32}(n)); 0 \leq n \leq 103)$ be quarterly time series of M_2+CD and RGNP from 1965 to 1987 and from 1965 to 1990 respectively. Let $j \in \{0, 1, 2, 5\}$. Table 3.2 and Table 3.3 report the results of Test(S) for transformed data $\mathcal{Z}_2^{(j)} =$

$(\mathcal{Z}_2^{(j)}(n); 0 \leq n \leq N_j^{(2)})$ ($N_0^{(2)} = 91, N_1^{(2)} = N_5^{(2)} = 90, N_2^{(2)} = 89$) and $\mathcal{Z}_3^{(j)} = (\mathcal{Z}_3^{(j)}(n); 0 \leq n \leq N_j^{(3)})$ ($N_0^{(3)} = 103, N_1^{(3)} = N_5^{(3)} = 102, N_2^{(3)} = 101$) respectively. Here the number j of $\mathcal{Z}_2^{(j)}$ and $\mathcal{Z}_3^{(j)}$ corresponds to transformations of (3.22). We can find that the second order differences in the original data in both periods have local and weak stationarity. We apply these results in §4 and §6.

Table 3.2 Test(S) for $t(M_2+CD, RGNP)$ from 1965 to 1987.

j	(M)	(V)	(O)	(S)
0	1.000	0.000	1.000	NS
1	0.961	0.628	0.974	NS
2	0.974	0.701	0.974	S
5	1.000	0.628	0.871	NS

Table 3.3 Test(S) for $t(M_2 + CD, RGNP)$ from 1965 to 1990.

j	(M)	(V)	(O)	(S)
0	1.000	0.088	1.000	NS
1	0.955	0.674	0.898	NS
2	0.977	0.704	0.943	S
5	0.988	0.528	0.865	NS

4. Granger's causality and the Granger-Sargent Test

It has long been recognized that high correlation among a set of variables does not in any necessary sense establish that they are causally related (Pierce and Haugh [29]). Wold [34] emphasized the importance of causal analysis in science, explaining the examples of economic time series. Under the circumstances, Granger [7] introduced the definitions of causal relation in stochastic processes whose time parameter spaces are \mathbf{T} in view of the predictability as follows:

Let $\mathbf{X} = (X(n); n \in \mathbf{T})$, and $\mathbf{Y} = (Y(n); n \in \mathbf{T})$ be d_1 and d_2 -dimensional stochastic processes. For each $n \in \mathbf{T}$, I_n is an information set, including at least $\{X(n), Y(n)\}$. Let $\tilde{I}(n) = \{I(m), m < n\}$, $\bar{I}(n) = \{I(m), m \leq n\}$. $\tilde{X}(n), \bar{X}(n), \tilde{Y}(n), \bar{Y}(n)$ are defined similarly. $\tilde{I}(n) - \tilde{Y}(n)$ is

equal to the set of elements of $\tilde{I}(n)$ without the elements of $\tilde{Y}(n)$. Denote by $\sigma^2(X(n)|\tilde{I}(n))$, $\sigma^2(X(n)|\tilde{I}(n) - \tilde{Y}(n))$ the mean square prediction error of $X(n)$ given information set $\tilde{I}(n)$, $\tilde{I}(n) - \tilde{Y}(n)$ respectively. Granger's definitions of causality are:

Definition 4.1 (Granger's causality) If $\sigma^2(X(n)|\tilde{I}(n)) < \sigma^2(X(n)|\tilde{I}(n) - \tilde{Y}(n))$, it is said that $Y(n)$ causes $X(n)$ in the sense of Granger, denoted by $Y(n) \xrightarrow{\text{GC}} X(n)$. Otherwise, we say that $Y(n)$ does not cause $X(n)$ in the sense of Granger, denoted by $Y(n) \not\xrightarrow{\text{GC}} X(n)$.

Definition 4.2 (Granger's instantaneous causality) If $\sigma^2(X(n)|\tilde{I}(n), \tilde{Y}(n)) < \sigma^2(X(n)|\tilde{I}(n))$, it is said that $Y(n)$ causes $X(n)$ instantaneously in the sense of Granger.

In the stationary case, $\sigma^2(X(n)|\tilde{I}(n))$, $\sigma^2(X(n)|\tilde{I}(n) - \tilde{Y}(n))$, and $\sigma^2(X(n)|\tilde{I}(n), \tilde{Y}(n))$ are independent of n . Then, we denote simply $Y(n) \xrightarrow{\text{GC}} X(n)$ by $\mathbf{Y} \xrightarrow{\text{GC}} \mathbf{X}$.

Under the assumption that given data are a realization of an AR model, some tests (e.g., [7], Sargent [31], Sims [33], etc.) are proposed to test Granger's causal relations among them. Now, one of such tests which is called the Granger-Sargent Test is well known and applied to economic time series (e.g., [30], [10]).

The Granger-Sargent Test is as follows: Let $\mathbf{Z} = \begin{pmatrix} X(n) \\ Y(n) \end{pmatrix}; n \in \mathbf{T}$ be a bivariate AR(m)-model with mean $\mathbf{0}$ such that

$$X(n) = \sum_{i=1}^m a_i X(n-i) + \sum_{i=1}^m b_i Y(n-i) + u_1(n) \tag{4.1}$$

$$Y(n) = \sum_{i=1}^m c_i Y(n-i) + \sum_{i=1}^m d_i X(n-i) + u_2(n) \tag{4.2}$$

where $m \in \mathbf{N}$. It is assumed that $I_n = \{X(n), Y(n)\}$, $n \in \mathbf{T}$. To judge $\mathbf{Y} \xrightarrow{\text{GC}} \mathbf{X}$ or not, we test the null hypothesis

$$H_0 : b_1 = \dots = b_m = 0$$

against an alternative hypothesis

$$H_1 : \text{exists } j \in \{1, \dots, m\} \text{ such that } b_j \neq 0.$$

The testing procedure is as follows: Given data $\mathcal{Z} = \left(\begin{pmatrix} \mathcal{X}(n) \\ \mathcal{Y}(n) \end{pmatrix}; 0 \leq n \leq N \right)$, we estimate the coefficients $\{a_i, b_j; 1 \leq i, j \leq m\}$ by least square estimation. Then, the coefficient of determination of (4.1) is defined by

$$R^2 = \frac{\sum_{n=m}^N (\sum_{i=1}^m a_i \mathcal{X}(n-i) + \sum_{i=1}^m b_i \mathcal{Y}(n-i))^2}{\sum_{n=m}^N \mathcal{X}(n)^2}. \quad (4.3)$$

Secondly, it is assumed that $\mathcal{X} = (\mathcal{X}(n); 0 \leq n \leq N)$ is a realization of the following one-dimensional AR(m)-model

$$X(n) = \sum_{i=1}^m e_i X(n-i) + u_3(n). \quad (4.4)$$

Using data \mathcal{X} , the coefficients $\{e_i; 1 \leq i \leq m\}$ are estimated by least square estimation. The coefficient of determination of (4.4) is given by

$$R_1^2 = \frac{\sum_{n=m}^N (\sum_{i=1}^m e_i \mathcal{X}(n-i))^2}{\sum_{n=m}^N \mathcal{X}(n)^2}. \quad (4.5)$$

Now, the test statistic F_1 is defined by

$$F_1 = \frac{(R^2 - R_1^2)/m}{(1 - R^2)/(N - 3m + 1)}. \quad (4.6)$$

At the α significant level,

If $F_1 > F(m, N - 3m + 1)_\alpha$ then reject H_0

If $F_1 \leq F(m, N - 3m + 1)_\alpha$ then accept H_0

where $F(m, N - 3m + 1)_\alpha$ is the critical value at the α level of F distribution with m and $N - 3m + 1$ degrees of freedom.

To test $\mathbf{X} \xrightarrow{\text{GC}} \mathbf{Y}$ or not, exchanging of X for Y , we can define F_2 similarly to F_1 .

Remark 4.1 Coefficients of (4.1), (4.2) and (4.4) are conveniently estimated by the sample covariance matrix function of \mathcal{Z} (e.g., Akaike and Nakagawa [1], [10]), alternative to least square estimation.

We apply the Granger-Sargent Test to the quarterly data of ${}^t(\text{M}_2 + \text{CD}, \text{RGNP})$ in two periods from 1965 to 1987 and from 1965 to 1990. In §3, the second order differences in the original data were accepted to be stationary. It is here assumed that the order m of the AR model is at most $\sqrt{(N + 1)}/2$.

Table 4.1 The Granger-Sargent Test for $t(M_2 + CD, RGNP)$ from 1965 to 1987.

m	$N - 3m + 1$	F_1	F_2
1	87	0.0820	0.029
2	84	4.010*	-0.0232
3	81	3.580*	0.204
4	78	2.803*	0.293
5	75	2.157*	0.343
6	72	2.279*	0.381
7	69	3.653*	0.333
8	66	3.271*	0.469
9	63	2.917*	0.747

Table 4.2 The Granger-Sargent Test for $t(M_2 + CD, RGNP)$ from 1965 to 1990.

m	$N - 3m + 1$	F_1	F_2
1	99	2.870*	0.475
2	96	2.318	0.634
3	93	1.937	0.295
4	90	2.545*	0.688
5	87	1.782	1.520
6	84	1.608	1.209
7	81	1.213	1.091
8	78	0.948	0.996
9	75	0.956	0.969
10	72	0.826	0.898

Table 4.1 and Table 4.2 report the results of the Granger-Sargent Test for the second order differences in the original data in two periods. Since we choose the second order differences in the data, $N = 89$ in the Table 4.1 and $N = 101$ in the Table 4.2 respectively. Here we choose that $\alpha = 0.10$. The symbol “*” indicates the cases in which the F_1 value or F_2 value exceeds the critical value at the 0.10 level. In both periods, there are some cases where F_1 exceeds the critical point at the 10 percent level. On the other hand, there are no cases where the F_2 exceeds the critical point at the 10

percent level. Therefore we accept in both periods that

$$M_2 + CD \not\stackrel{GC}{\Rightarrow} \text{RGNP}, \text{RGNP} \stackrel{GC}{\Rightarrow} M_2 + CD. \quad (4.7)$$

In §6, these results are compared with the results by the Local Causal Test.

5. A local causality and its characterization

We develop, in this section, a causal analysis of local and weakly stationary processes. Granger's causal analysis introduced in §4 assumes that given data are a realization of a bivariate AR model. We do not assume that given data are a realization of a specified process. After accepting by Test(S) that the data are a realization of a local and weak stationary process, we proceed to further analysis. In like manner, Okabe [19] defined a causality in local and weakly stationary processes from the viewpoint of the prediction and proposed a method how to test it. Okabe and Inoue [25] developed this analysis further. The definition of causality by [25] is as follows: Let $\mathbf{X} = (X(n); n \in \mathbf{T})$, $\mathbf{Y} = (Y(n); n \in \mathbf{T})$ be d_1 and d_2 -dimensional stochastic processes respectively. It is said that \mathbf{Y} causes \mathbf{X} in the sense of Okabe-Inoue if for each $n \in \mathbf{T}$ there exists a measurable mapping F_n from the infinite-dimensional space $(\mathbf{R}^{d_2})^{\mathbf{N}^*}$ to the finite dimensional space \mathbf{R}^{d_1} such that $X(n) = F_n(Y(n), Y(n-1), Y(n-2), \dots)$.

Under the assumption that $\mathbf{Z} = \left(\begin{pmatrix} X(n) \\ Y(n) \end{pmatrix}; n \in \mathbf{T} \right)$ is a $(d_1 + d_2)$ -dimensional weakly stationary process, the necessary and sufficient condition in which \mathbf{Y} causes \mathbf{X} in the sense of Okabe-Inoue was investigated and applied to data analysis in [25]. Moreover, Okabe-Ootsuka [27] and [28] investigated the non-linear prediction problem.

Now, let us introduce the definition of local causality in local and weakly stationary processes and investigate its characterization. Let $\mathbf{X} = (X(n); |n| \leq N)$ and $\mathbf{Y} = (Y(n); |n| \leq N)$ be d_1 and d_2 -dimensional local and weakly stationary processes respectively. Moreover, we assume that $\mathbf{Z} = (Z(n); |n| \leq N)$,

$$Z(n) = \begin{pmatrix} X(n) \\ Y(n) \end{pmatrix} \quad (5.1)$$

is a $(d_1 + d_2)$ -dimensional local and weakly stationary process.

We set

$$X(n) = \begin{pmatrix} X_1(n) \\ \vdots \\ X_{d_1}(n) \end{pmatrix}, \quad Y(n) = \begin{pmatrix} Y_1(n) \\ \vdots \\ Y_{d_2}(n) \end{pmatrix}. \quad (5.2)$$

For each $n \in \{0, \dots, N\}$, $I(n)$ is an information set at time n , including at least $X_i(n), Y_j(n)$ ($1 \leq i \leq d_1, 1 \leq j \leq d_2$). The available set at time n is defined by

$$I_0^n = \{I_m; 0 \leq m \leq n\}. \quad (5.3)$$

Let J be an information set and $\hat{X}_J(n)$ be the linear prediction $X(n)$ by J . Then, the prediction error of $X(n)$ by J and its variance are defined :

$$\epsilon(X(n)|J) = X(n) - \hat{X}_J(n) \quad (5.4)$$

$$\sigma^2(X(n)|J) = \|\epsilon(X(n)|J)\|^2. \quad (5.5)$$

$I_0^n - X_0^n$ denotes all the elements of I_0^n eliminated $X_i(m)$ ($0 \leq m \leq n, 1 \leq i \leq d_1$). Similarly, $I_0^n - Y_0^n$ is defined. Here we set $I_0^{-1} = I_0^{-1} - X_0^{-1} = I_0^{-1} - Y_0^{-1} = \phi$. Local causality between \mathbf{X} and \mathbf{Y} is defined as follows:

Definition 5.1 (local causality) If there exists $n \in \{0, \dots, N\}$ such that

$$\sigma(X(n)|I_0^{n-1}) < \sigma(X(n)|I_0^{n-1} - Y_0^{n-1}), \quad (5.6)$$

we say that \mathbf{Y} causes \mathbf{X} locally, denoted by $\mathbf{Y} \xrightarrow{\text{LC}} \mathbf{X}$. Otherwise, we say that \mathbf{Y} does not cause \mathbf{X} locally, denoted by $\mathbf{Y} \not\xrightarrow{\text{LC}} \mathbf{X}$.

Definition 5.2 (instantaneous local causality) If there exists $n \in \{0, \dots, N\}$ such that

$$\sigma(X(n)|I_0^{n-1}, Y(n)) < \sigma(X(n)|I_0^{n-1}), \quad (5.7)$$

we say that *instantaneous local causality of \mathbf{Y} to \mathbf{X} occurs*, denoted by $\mathbf{Y} \xrightarrow{\text{ILC}} \mathbf{X}$. Otherwise, we say that *instantaneous local causality of \mathbf{Y} to \mathbf{X} does not occur*, denoted by $\mathbf{Y} \not\xrightarrow{\text{ILC}} \mathbf{X}$.

Here, we discuss only the case when $I_n = \{X_i(n), Y_j(n); 1 \leq i \leq d_1, 1 \leq j \leq d_2\}$ ($0 \leq n \leq N$). Hence, it follows that $I_0^{n-1} - Y_0^{n-1} = \{X_i(m); 1 \leq i \leq d_1, 0 \leq m \leq n-1\}$ ($0 \leq n \leq N$).

Let $n \in \{0, \dots, N\}$. We get the following KM₂O-Langevin equations:

$$X(n) = P_{\mathbf{M}_0^{n-1}(\mathbf{X})}X(n) + \nu_{+X}(n) \quad (5.8)$$

$$Z(n) = P_{\mathbf{M}_0^{n-1}(\mathbf{Z})}Z(n) + \nu_{+Z}(n). \quad (5.9)$$

Here

$$\nu_{+Z}(n) = \begin{pmatrix} \nu_{+Z,X}(n) \\ \nu_{+Z,Y}(n) \end{pmatrix} \quad (5.10)$$

is defined by

$$\nu_{+Z,X}(n) = X(n) - P_{\mathbf{M}_0^{n-1}(\mathbf{Z})}X(n) \quad (5.11)$$

$$\nu_{+Z,Y}(n) = Y(n) - P_{\mathbf{M}_0^{n-1}(\mathbf{Z})}Y(n). \quad (5.12)$$

The following Lemma 5.1 is clear.

Lemma 5.1

$$\epsilon(X(n)|I_0^{n-1} - Y_0^{n-1}) = \nu_{+X}(n) \quad (5.13)$$

$$\epsilon(X(n)|I_0^{n-1}) = \nu_{+Z,X}(n). \quad (5.14)$$

Now, we have

Lemma 5.2 $\mathbf{Y} \stackrel{\text{LC}}{\not\Rightarrow} \mathbf{X}$ if and only if

$$\nu_{+X}(n) = \nu_{+Z,X}(n) \quad (0 \leq n \leq N). \quad (5.15)$$

Proof. We assume that $\mathbf{Y} \stackrel{\text{LC}}{\not\Rightarrow} \mathbf{X}$. Then,

$$\begin{aligned} & \|\nu_{+X}(n) - \nu_{+Z,X}(n)\|^2 \\ &= \langle \nu_{+X}(n) - \nu_{+Z,X}(n), \nu_{+X}(n) - \nu_{+Z,X}(n) \rangle \\ &= \langle \nu_{+X}(n), \nu_{+X}(n) \rangle + \langle \nu_{+Z,X}(n), \nu_{+Z,X}(n) \rangle \\ & \quad - 2\langle \nu_{+Z,X}(n), \nu_{+X}(n) \rangle. \end{aligned} \quad (5.16)$$

From (5.13) and (5.14),

$$\|\nu_{+X}(n)\|^2 = \|\nu_{+Z,X}(n)\|^2. \quad (5.17)$$

Since $\nu_{+X}(n) - \nu_{+Z,X}(n) \in \mathbf{M}_0^{n-1}(\mathbf{Z})$,

$$\langle \nu_{+Z,X}(n), \nu_{+X}(n) - \nu_{+Z,X}(n) \rangle = 0. \quad (5.18)$$

Hence

$$\begin{aligned} \|\nu_{+X}(n) - \nu_{+Z,X}(n)\|^2 &= 2\|\nu_{+Z,X}(n)\|^2 \\ &\quad - 2\langle \nu_{+Z,X}(n), \nu_{+X}(n) - \nu_{+Z,X}(n) + \nu_{+Z,X}(n) \rangle \\ &= 2\|\nu_{+Z,X}(n)\|^2 - 2\|\nu_{+Z,X}(n)\|^2 \\ &= 0. \end{aligned} \quad (5.19)$$

Therefore, we get $\nu_{+X}(n) = \nu_{+Z,X}(n)$. It is clear to prove the sufficient condition. \square

Let us consider how to characterize (5.15). For $n \in \{0, \dots, N\}$, we set

$$V_{+X}(n) = E\nu_{+X}(n)^t \nu_{+X}(n) \quad (5.20)$$

$$V_{+Z,X}(n) = E\nu_{+Z,X}(n)^t \nu_{+Z,X}(n) \quad (5.21)$$

$$V_{+Z}(n) = E\nu_{+Z}(n)^t \nu_{+Z}(n). \quad (5.22)$$

$V_{+X}(n)$, $V_{+Z,X}(n)$ and $V_{+Z}(n)$ are covariance matrices of $\nu_{+X}(n)$, $\nu_{+Z,X}(n)$ and $\nu_{+Z}(n)$ respectively. Furthermore, let $W_{+X}(n)$, $W_{+Z,X}(n)$ and $W_{+Z}(n)$ be lower triangular matrices such that

$$V_{+X}(n) = W_{+X}(n)^t W_{+X}(n) \quad (5.23)$$

$$V_{+Z,X}(n) = W_{+Z,X}(n)^t W_{+Z,X}(n) \quad (5.24)$$

$$V_{+Z}(n) = W_{+Z}(n)^t W_{+Z}(n). \quad (5.25)$$

Then we get the following Theorem 5.1.

Theorem 5.1 *The necessary and sufficient condition of $\mathbf{Y} \stackrel{\text{LC}}{\not\Rightarrow} \mathbf{X}$ is that either of the following (L-1), (L-2) or (L-3) holds. Here, $(I)_d$ denotes the d -dimensional identity matrix.*

- (L-1) $W_{+Z,X}(n)^{-1} \nu_{+X}(n)$, $0 \leq n \leq N$ is a d_1 -dimensional white noise with mean $\mathbf{0}$ and covariance matrix $(I)_{d_1}$.
- (L-2) $W_{+X}(n)^{-1} \nu_{+Z,X}(n)$, $0 \leq n \leq N$ is a d_1 -dimensional white noise with mean $\mathbf{0}$ and covariance matrix $(I)_{d_1}$.

(L-3) $W_{+Z}(n)^{-1} \begin{pmatrix} \nu_{+X}(n) \\ \nu_{+Z,Y}(n) \end{pmatrix}$, $0 \leq n \leq N$ is a $(d_1 + d_2)$ -dimensional white noise with mean $\mathbf{0}$ and covariance matrix $(I)_{(d_1+d_2)}$.

Proof. We prove that (L-3) is equivalent to $\mathbf{Y} \stackrel{\text{LC}}{\not\Rightarrow} \mathbf{X}$. We assume that (L-3) holds. Then, we obtain

$$\begin{aligned} W_{+Z}(n)^{-1} E \begin{pmatrix} \nu_{+X}(n) \\ \nu_{+Z,Y}(n) \end{pmatrix}^t \begin{pmatrix} \nu_{+X}(n) \\ \nu_{+Z,Y}(n) \end{pmatrix}^t W_{+Z}(n)^{-1} \\ = (I)_{(d_1+d_2)}. \end{aligned} \quad (5.26)$$

Therefore

$$\begin{aligned} E \begin{pmatrix} \nu_{+X}(n)^t \nu_{+X}(n) & \nu_{+X}(n)^t \nu_{+Z,Y}(n) \\ \nu_{+Z,Y}(n)^t \nu_{+X}(n) & \nu_{+Z,Y}(n)^t \nu_{+Z,Y}(n) \end{pmatrix} \\ = E \begin{pmatrix} \nu_{+Z,X}(n)^t \nu_{+Z,X}(n) & \nu_{+Z,X}(n)^t \nu_{+Z,Y}(n) \\ \nu_{+Z,Y}(n)^t \nu_{+Z,X}(n) & \nu_{+Z,Y}(n)^t \nu_{+Z,Y}(n) \end{pmatrix}. \end{aligned} \quad (5.27)$$

From the special case of (5.27),

$$E \nu_{+X}(n)^t \nu_{+X}(n) = E \nu_{+Z,X}(n)^t \nu_{+Z,X}(n). \quad (5.28)$$

Setting

$$\nu_{+X}(n) = \begin{pmatrix} \nu_{+X,1}(n) \\ \vdots \\ \nu_{+X,d_1}(n) \end{pmatrix}, \quad \nu_{+Z,X}(n) = \begin{pmatrix} \nu_{+Z,X,1}(n) \\ \vdots \\ \nu_{+Z,X,d_1}(n) \end{pmatrix}, \quad (5.29)$$

we have $E \nu_{+X,i}(n)^2 = E \nu_{+Z,X,i}(n)^2$ ($1 \leq i \leq d_1$). As shown in Lemma 5.2, we get $\nu_{+X,i}(n) = \nu_{+Z,X,i}(n)$ ($1 \leq i \leq d_1$). The proof of the converse is clear. \square

Sims [33] introduced a distributed lag model as a model of Granger's causal relation between AR models. Here we get the following Theorem 5.2 which shows the structure of $\mathbf{Y} \stackrel{\text{LC}}{\not\Rightarrow} \mathbf{X}$.

Theorem 5.2 *The necessary and sufficient condition of $\mathbf{Y} \stackrel{\text{LC}}{\not\Rightarrow} \mathbf{X}$ is as follows: there exist the unique matrices $\{A(n, k) \in M(d_2 \times d_1; \mathbf{R}), 0 \leq k \leq n \leq N\}$, and appropriate matrices $\{B(n, k) \in M(d_2 \times d_2; \mathbf{R}), 0 \leq k \leq n \leq N\}$,*

$N\}$, such that for any $n \in \{0, \dots, N\}$, $Y(n)$ is expressed as

$$Y(n) = \sum_{k=0}^n A(n, k)X(k) + \sum_{k=0}^n B(n, k)\nu^*(k). \quad (5.30)$$

Here,

$$B(n, n) \in GL(d_2; \mathbf{R}) \quad (5.31)$$

(5.32) $(\nu^*(n); 0 \leq n \leq N)$ is orthogonal to $\mathbf{M}_0^N(\mathbf{X})$, and is a d_2 -dimensional white noise with mean $\mathbf{0}$ and covariance matrix $(I)_{d_2}$

(5.33) $\nu^*(n)$ is orthogonal to $\mathbf{M}_0^{n-1}(\mathbf{Y})$, for $n = 1, \dots, n - 1$.

Proof. We assume $\mathbf{Y} \stackrel{\text{LC}}{\not\Rightarrow} \mathbf{X}$. For $n \in \{0, \dots, N\}$, let $W_{+Z}(n)$ be a lower triangular matrix defined by (5.25). We set

$$\begin{aligned} \nu^*(n) &= W_{+Z}(n)^{-1}\nu_{+Z}(n) \\ &= W_{+Z}(n)^{-1} \begin{pmatrix} \nu_{+Z,X}(n) \\ \nu_{+Z,Y}(n) \end{pmatrix} = \begin{pmatrix} \nu_1^*(n) \\ \nu_2^*(n) \end{pmatrix}. \end{aligned} \quad (5.34)$$

Let $d = d_1 + d_2$. Then, $\nu^*(n)$, $0 \leq n \leq N$ is a d -dimensional white noise with mean $\mathbf{0}$ and covariance matrix $(I)_d$. We define KM₂O-Langevin equations of \mathbf{X} and \mathbf{Z} as follows:

$$X(n) = - \sum_{k=0}^{n-1} \gamma_{+X}(n, k)X(k) + \nu_{+X}(n) \quad (5.35)$$

$$\begin{aligned} \begin{pmatrix} X(n) \\ Y(n) \end{pmatrix} &= - \sum_{k=0}^{n-1} \gamma_{+Z}(n, k) \begin{pmatrix} X(k) \\ Y(k) \end{pmatrix} \\ &\quad + \begin{pmatrix} \nu_{+Z,X}(n) \\ \nu_{+Z,Y}(n) \end{pmatrix}. \end{aligned} \quad (5.36)$$

Multiplying $W_{+Z}(n)^{-1}$ from the left-hand side of (5.36), we get

$$\begin{aligned} W_{+Z}(n)^{-1} \begin{pmatrix} X(n) \\ Y(n) \end{pmatrix} &= - \sum_{k=0}^{n-1} W_{+Z}(n)^{-1} \\ &\quad \times \gamma_{+Z}(n, k) \begin{pmatrix} X(k) \\ Y(k) \end{pmatrix} + \begin{pmatrix} \nu_1^*(n) \\ \nu_2^*(n) \end{pmatrix}. \end{aligned} \quad (5.37)$$

We set a lower triangular matrix $W_{+Z}(n)$ by

$$W_{+Z}(n) = \begin{pmatrix} B_{11}(n) & \mathbf{0} \\ B_{21}(n) & B_{22}(n) \end{pmatrix}, \quad (5.38)$$

where $B_{ij}(n) \in M(d_i \times d_j; \mathbf{R})$ ($i, j = 1, 2$), $B_{12}(n) = \mathbf{0}$, and $B_{ii}(n) \in GL(d_i; \mathbf{R})$ ($i = 1, 2$). $W_{+Z}(n)^{-1}$ is also a lower triangular matrix defined by

$$W_{+Z}(n)^{-1} = \begin{pmatrix} C_{11}(n) & \mathbf{0} \\ C_{21}(n) & C_{22}(n) \end{pmatrix}, \quad (5.39)$$

where $C_{ij}(n) \in M(d_i \times d_j; \mathbf{R})$ ($i, j = 1, 2$), $C_{12}(n) = \mathbf{0}$, and $C_{ii}(n) \in GL(d_i; \mathbf{R})$ ($i = 1, 2$). Moreover, we set

$$W_{+Z}(n)^{-1}\gamma_{+Z}(n, k) = \begin{pmatrix} \Gamma_{11}(n, k) & \Gamma_{12}(n, k) \\ \Gamma_{21}(n, k) & \Gamma_{22}(n, k) \end{pmatrix}. \quad (5.40)$$

Then, (5.37) leads to

$$\begin{aligned} & C_{21}(n)X(n) + C_{22}(n)Y(n) \\ &= -\sum_{k=0}^{n-1} \Gamma_{21}(n, k)X(k) - \sum_{k=0}^{n-1} \Gamma_{22}(n, k)Y(k) + \nu_2^*(n). \end{aligned} \quad (5.41)$$

Since $C_{22}(n) \in GL(d_2; \mathbf{R})$,

$$\begin{aligned} Y(n) &= -C_{22}(n)^{-1}C_{21}(n)X(n) \\ &- \sum_{k=0}^{n-1} C_{22}(n)^{-1}\Gamma_{21}(n, k)X(k) - \sum_{k=0}^{n-1} C_{22}(n)^{-1}\Gamma_{22}(n, k)Y(k) \\ &+ C_{22}(n)^{-1}\nu_2^*(n). \end{aligned} \quad (5.42)$$

Any component of $\nu_2^*(n)$ is a linear combination of components of $\nu_{+Z}(n)$. Therefore,

$$EX(k)^t \nu_2^*(n) = \mathbf{0} \quad (0 \leq k \leq n-1). \quad (5.43)$$

Moreover, any component of $\nu_{+Z, X}(n)$ is expressed as a linear combination of components of $\nu_1^*(n)$. This shows

$$E\nu_{+Z, X}(n)^t \nu_2^*(n) = \mathbf{0}. \quad (5.44)$$

From the definition of $\mathbf{M}_0^{n-1}(\mathbf{Z})$, $E\{P_{\mathbf{M}_0^{n-1}(\mathbf{Z})}X(n)\}^t \nu_2^*(n) = \mathbf{0}$.

The KM₂O-Langevin equation shows

$$X(n) = P_{\mathbf{M}_0^{n-1}(\mathbf{Z})}X(n) + \nu_{+Z,X}(n). \quad (5.45)$$

Hence, we get

$$EX(n)^t \nu_2^*(n) = \mathbf{0}. \quad (5.46)$$

Similarly to (5.45),

$$X(n+1) = P_{\mathbf{M}_0^n(\mathbf{X})}X(n+1) + \nu_{+X}(n+1). \quad (5.47)$$

We have $\nu_{+X}(n+1) = \nu_{+Z,X}(n+1)$ from the assumption. Hence $E\nu_{+X}(n+1)^t \nu_2^*(n) = \mathbf{0}$. Therefore we have

$$EX(n+1)^t \nu_2^*(n) = \mathbf{0}. \quad (5.48)$$

Inductively, we get

$$EX(k)^t \nu_2^*(n) = \mathbf{0} \quad (0 \leq k \leq N). \quad (5.49)$$

Substituting $Y(k)$, $0 \leq k \leq n-1$ in (5.41) inductively, we have the expression of (5.30).

Let us show that $\{A(n, k), 0 \leq k \leq n \leq N\}$ is unique. If $Y(n)$ has another expression form such as

$$Y(n) = \sum_{k=0}^n \tilde{A}(n, k)X(k) + \sum_{k=0}^n \tilde{B}(n, k)\eta^*(k), \quad (5.50)$$

we multiply ${}^tX(m)$ ($0 \leq m \leq n$) to (5.30) and (5.50) from the right-hand side. Taking their expectations, we get

$$\sum_{k=0}^n A(n, k)R(k-m) = \sum_{k=0}^n \tilde{A}(n, k)R(k-m). \quad (5.51)$$

The Toeplitz condition of §2 suggests

$$A(n, k) = \tilde{A}(n, k) \quad (0 \leq k \leq n). \quad (5.52)$$

Let us prove the converse. We set

$$\gamma_{+Z}(n, k) = \begin{pmatrix} \gamma_{11}(n, k) & \gamma_{12}(n, k) \\ \gamma_{21}(n, k) & \gamma_{22}(n, k) \end{pmatrix} \quad (0 \leq k < n \leq N), \quad (5.53)$$

where $\gamma_{ij}(n, k) \in M(d_i \times d_j; \mathbf{R})$ ($i, j = 1, 2$). From (5.36), we have

$$\begin{aligned} X(n) &= - \sum_{k=0}^{n-1} \gamma_{11}(n, k)X(k) \\ &\quad - \sum_{k=0}^{n-1} \gamma_{12}(n, k)Y(k) + \nu_{+Z,X}(n). \end{aligned} \quad (5.54)$$

We substitute $Y(k)$, $0 \leq k \leq n-1$ of (5.30) in (5.54). Then there exist appropriate matrices $C(n, k) \in M(d_1; \mathbf{R})$ and $D(n, k) \in M(d_1; \mathbf{R})$ such that $X(n)$ is expressed as

$$\begin{aligned} X(n) &= - \sum_{k=0}^{n-1} C(n, k)X(k) \\ &\quad - \sum_{k=0}^{n-1} D(n, k)\nu^*(k) + \nu_{+Z,X}(n). \end{aligned} \quad (5.55)$$

Since $B(k, k) \in GL(d_2; \mathbf{R})$, any components of $\nu^*(k)$ belong to $\mathbf{M}_0^k(\mathbf{Z})$. Hence

$$E\nu_{+Z,X}(n)^t \nu^*(k) = \mathbf{0} \quad (0 \leq k \leq n-1). \quad (5.56)$$

The assumption leads to

$$EX(l)^t \nu^*(k) = 0 \quad (0 \leq l \leq N). \quad (5.57)$$

Multiplying ${}^t \nu^*(k)$ ($0 \leq k \leq n-1$) to the right-hand side of (5.55) and taking its expectation, we get

$$D(n, k) = \mathbf{0} \quad (0 \leq k \leq n-1). \quad (5.58)$$

Hence, we have

$$\nu_{+Z,X}(n) = \nu_{+X}(n). \quad (5.59)$$

This shows $\mathbf{Y} \stackrel{\text{LC}}{\not\Rightarrow} \mathbf{X}$. □

Remark 5.7 In (5.30) and (5.51), the following holds.

$$B(n, k)\nu^*(k) = \tilde{B}(n, k)\eta^*(k), \quad 0 \leq k \leq n \leq N \quad (5.60)$$

$$B(n, k)^t B(n, k) = \tilde{B}(n, k)^t \tilde{B}(n, k), \quad 0 \leq k \leq n \leq N. \quad (5.61)$$

We can show (5.60) as follows: Since $\sum_{k=0}^n B(n, k)\nu^*(k) = \sum_{k=0}^n \tilde{B}(n, k)\eta^*(k)$,

$$\begin{aligned} \sum_{k=0}^{n-1} B(n, k)\nu^*(k) - \sum_{k=0}^{n-1} \tilde{B}(n, k)\eta^*(k) \\ = B(n, n)\nu^*(n) - \tilde{B}(n, n)\eta^*(n). \end{aligned} \tag{5.62}$$

Components of the left-hand side of the above equation belong to $\mathbf{M}_0^{n-1}(\mathbf{Z})$. On the other hand, $B(n, n)\nu^*(n) - \tilde{B}(n, n)\eta^*(n)$ is orthogonal to $\mathbf{M}_0^{n-1}(\mathbf{Z})$. Hence we get (5.60). It is easy to get (5.61) from (5.60).

Similarly to (5.35), we get that

$$Y(n) = - \sum_{k=0}^{n-1} \gamma_{+Y}(n, k)Y(k) + \nu_{+Y}(n). \tag{5.63}$$

Example 5.1 Let $d_1 = d_2 = 1$ and $Y(n) = aX(n) + w(n)$ ($a \neq 0$). Here $w(n)$, $0 \leq n \leq N$ is a white noise with variance σ^2 , and independent of $X(k)$, $0 \leq k \leq N$. Let the covariance function of \mathbf{X} be $\{R(n); |n| \leq N\}$ such that $R(1) \neq 0$. From Theorem 5.2, $\mathbf{Y} \stackrel{\text{LC}}{\not\Rightarrow} \mathbf{X}$. We get that $\nu_{+Z, Y}(1) = Y(1) - aR(1)X(0)/R(0)$ and $\nu_{+Y}(1) = Y(1) - a^2R(1)Y(0)/(a^2R(0) + \sigma^2)$. Therefore, we have $\nu_{+Z, Y}(1) \neq \nu_{+Y}(1)$. This leads to $\mathbf{X} \stackrel{\text{LC}}{\Rightarrow} \mathbf{Y}$.

Theorem 5.3 *The necessary and sufficient condition of $\mathbf{Y} \stackrel{\text{LC}}{\not\Rightarrow} \mathbf{X}$ and $\mathbf{X} \stackrel{\text{LC}}{\not\Rightarrow} \mathbf{Y}$ is*

$$E\nu_{+X}(n)^t \nu_{+Y}(m) = \mathbf{0} \quad n \neq m, \quad n, m \in \{0, \dots, N\}. \tag{5.64}$$

Proof. If $\mathbf{Y} \stackrel{\text{LC}}{\not\Rightarrow} \mathbf{X}$ and $\mathbf{X} \stackrel{\text{LC}}{\not\Rightarrow} \mathbf{Y}$, $\nu_{+X}(n) = \nu_{+Z, X}(n)$, $\nu_{+Y}(n) = \nu_{+Z, Y}(n)$, for each $n \in \{0, \dots, N\}$. Hence, (5.64) holds.

We show the converse. For each $m \in \{0, \dots, N\}$, $Y(m)$ is a linear combination of $\nu_{+Y}(0), \dots, \nu_{+Y}(m)$. Therefore we have

$$E\nu_{+X}(n)^t Y(m) = \mathbf{0} \quad (0 \leq m \leq n - 1). \tag{5.65}$$

It is clear that $E\nu_{+Z, X}(n)^t Y(m) = \mathbf{0}$ ($0 \leq m \leq n - 1$). On the other hand, $\nu_{+X}(n) - \nu_{+Z, X}(n)$ is a linear combination of $X(0), \dots, X(n - 1), Y(0),$

$\dots, Y(n-1)$. Hence, we get $\|\nu_{+X}(n) - \nu_{+Z,X}(n)\|^2 = 0$. This shows that $\nu_{+X}(n) - \nu_{+Z,X}(n) = \mathbf{0}$. Similarly, we have $\nu_{+Y}(n) - \nu_{+Z,Y}(n) = \mathbf{0}$. \square

It is easy to get the following Corollary 5.1.

Corollary 5.1 *If $EX(0)^tY(0) = \mathbf{0}$, the necessary and sufficient condition of $\mathbf{Y} \stackrel{\text{LC}}{\not\Rightarrow} \mathbf{X}$ and $\mathbf{X} \stackrel{\text{LC}}{\not\Rightarrow} \mathbf{Y}$ is*

$$EX(n)^tY(m) = \mathbf{0} \quad n, m \in \{0, \dots, N\}. \quad (5.66)$$

Corollary 5.1 shows that the conception of causality is more universal than the conception of correlation.

Let us now consider the instantaneous local causality.

Theorem 5.4 *The necessary and sufficient condition that instantaneous local causality of \mathbf{X} to \mathbf{Y} does not occur is*

$$C_{21}(n) = \mathbf{0} \quad (0 \leq n \leq N). \quad (5.67)$$

where $C_{21}(n)$ is defined by (5.39).

Proof. (5.36) and (5.41) show that the necessary and sufficient condition of $\mathbf{X} \stackrel{\text{ILC}}{\not\Rightarrow} \mathbf{Y}$ is

$$\|\nu_{+Z,Y}(n)\|^2 = \|C_{22}(n)^{-1}\nu_2^*(n)\|^2 \quad (0 \leq n \leq N). \quad (5.68)$$

From (5.37), we get

$$\begin{aligned} \begin{pmatrix} \nu_1^*(n) \\ \nu_2^*(n) \end{pmatrix} &= \begin{pmatrix} C_{11}(n) & \mathbf{0} \\ C_{21}(n) & C_{22}(n) \end{pmatrix} \begin{pmatrix} \nu_{+Z,X}(n) \\ \nu_{+Z,Y}(n) \end{pmatrix} \\ &= \begin{pmatrix} C_{11}(n)\nu_{+Z,X}(n) \\ C_{21}(n)\nu_{+Z,X}(n) + C_{22}(n)\nu_{+Z,Y}(n) \end{pmatrix}. \end{aligned} \quad (5.69)$$

Hence

$$\begin{aligned} &\|C_{22}(n)^{-1}\nu_2^*(n)\|^2 \\ &= \|C_{22}(n)^{-1}C_{21}(n)\nu_{+Z,X}(n) + \nu_{+Z,Y}(n)\|^2 \\ &= \|C_{22}(n)^{-1}C_{21}(n)\nu_{+Z,X}(n)\|^2 + \|\nu_{+Z,Y}(n)\|^2 \\ &\quad + 2E^t(C_{22}(n)^{-1}C_{21}(n)\nu_{+Z,X}(n))\nu_{+Z,Y}(n). \end{aligned} \quad (5.70)$$

Since $C_{11}(n) \in GL(d_1; \mathbf{R})$, we obtain from (5.69)

$$E\nu_{+Z,X}(n)^t(C_{21}(n)\nu_{+Z,X}(n) + C_{22}(n)\nu_{+Z,Y}(n)) = \mathbf{0}. \quad (5.71)$$

We shall indicate by trA the trace of a matrix A . Now, we have from (5.71)

$$\begin{aligned} & E^t(C_{22}(n)^{-1}C_{21}(n)\nu_{+Z,X}(n))\nu_{+Z,Y}(n) \\ &= trE\nu_{+Z,Y}(n)^t(C_{22}(n)^{-1}C_{21}(n)\nu_{+Z,X}(n)) \\ &= trEC_{22}(n)^{-1}(C_{22}(n)\nu_{+Z,Y}(n) + C_{21}(n)\nu_{+Z,X}(n) \\ &\quad - C_{21}(n)\nu_{+Z,X}(n)) \times {}^t(C_{22}(n)^{-1}C_{21}(n)\nu_{+Z,X}(n)) \\ &= -trE(C_{22}(n)^{-1}C_{21}(n)\nu_{+Z,X}(n)){}^t(C_{22}(n)^{-1}C_{21}(n)\nu_{+Z,X}(n)) \\ &= -E^t(C_{22}(n)^{-1}C_{21}(n)\nu_{+Z,X}(n))(C_{22}(n)^{-1}C_{21}(n)\nu_{+Z,X}(n)) \\ &= -\|C_{22}(n)^{-1}C_{21}(n)\nu_{+Z,X}(n)\|^2. \end{aligned} \quad (5.72)$$

Hence, we get

$$\begin{aligned} \|C_{22}(n)^{-1}\nu_2^*(n)\|^2 &= \|\nu_{+Z,Y}(n)\|^2 \\ &\quad - \|C_{22}(n)^{-1}C_{21}(n)\nu_{+Z,X}(n)\|^2. \end{aligned} \quad (5.73)$$

This shows that the necessary and sufficient condition of $\mathbf{X} \stackrel{\text{ILC}}{\not\Rightarrow} \mathbf{Y}$ is

$$\|C_{22}(n)^{-1}C_{21}(n)\nu_{+Z,X}(n)\|^2 = 0. \quad (5.74)$$

Therefore, we have

$$C_{22}(n)^{-1}C_{21}(n)\nu_{+Z,X}(n) = \mathbf{0}. \quad (5.75)$$

This leads to

$$C_{22}(n)^{-1}C_{21}(n)V_{+Z,X}(n) = \mathbf{0}. \quad (5.76)$$

Since $C_{22}(n) \in GL(d_2; \mathbf{R})$, and $V_{+Z,X}(n) \in GL(d_1; \mathbf{R})$, we have $C_{21}(n) = \mathbf{0}$. \square

For $n \in \{0, \dots, N\}$ and $i, j \in \{1, \dots, d\}$, let $V_{+Z,ij}(n)$ be the (i, j) component of covariance matrix $V_{+Z}(n)$. Then we obtain:

Corollary 5.2 *The necessary and sufficient condition that instantaneous local causality of \mathbf{X} to \mathbf{Y} does not occur is*

$$\begin{aligned} V_{+Z,ij}(n) &= 0 \\ (d_1 + 1 \leq i \leq d_1 + d_2, 1 \leq j \leq d_1, 0 \leq n \leq N). \end{aligned} \quad (5.77)$$

Proof. The necessary and sufficient condition that (5.67) holds is

$$B_{21}(n) = \mathbf{0} \quad (0 \leq n \leq N). \quad (5.78)$$

It is clear that (5.78) is equivalent to (5.77). \square

It is easy to get the following Corollary 5.3.

Corollary 5.3 *The necessary and sufficient condition that instantaneous local causality of \mathbf{X} to \mathbf{Y} does not occur is*

$$E\nu_{+Z,Y}(n)^t \nu_{+Z,X}(n) = \mathbf{0} \quad (0 \leq n \leq N). \quad (5.79)$$

Corollary 5.3 shows that $\mathbf{Y} \not\stackrel{\text{ILC}}{\rightleftharpoons} \mathbf{X}$ and $\mathbf{X} \not\stackrel{\text{ILC}}{\rightleftharpoons} \mathbf{Y}$ are equivalent to each other.

Now we characterize $\mathbf{X} \not\stackrel{\text{ILC}}{\rightleftharpoons} \mathbf{Y}$.

Theorem 5.5 *The necessary and sufficient condition that instantaneous local causality of \mathbf{X} to \mathbf{Y} does not occur is that*

$$\begin{pmatrix} C_{11}(n) & \mathbf{0} \\ \mathbf{0} & C_{22}(n) \end{pmatrix} \nu_{+Z}(n), \quad 0 \leq n \leq N \quad (5.80)$$

is a white noise with mean $\mathbf{0}$ and covariance matrix $(I)_d$.

Proof. The necessity is clear from Corollary 5.2. We show the sufficiency. We set

$$C(n) = \begin{pmatrix} C_{11}(n) & \mathbf{0} \\ \mathbf{0} & C_{22}(n) \end{pmatrix}. \quad (5.81)$$

Since

$$V_{+Z}(n) = C(n)^{-1} \times {}^t C(n)^{-1}, \quad (5.82)$$

we obtain (5.77). \square

6. Data analysis of local causality

We introduce the Local Causal Test for the analysis of local causality and the Instantaneous Local Causal Test for the analysis of instantaneous local causality. These tests are applied to the data of ${}^t(M_2 + \text{CD}, \text{RGNP})$.

Let $\mathcal{X} = (\mathcal{X}(n); 0 \leq n \leq N)$ be d_1 -dimensional data, and $\mathcal{Y} = (\mathcal{Y}(n);$

$0 \leq n \leq N$) d_2 -dimensional data. Set $d = d_1 + d_2$. We construct the d -dimensional data $\mathcal{Z} = \left(\begin{pmatrix} \mathcal{X}^{(n)} \\ \mathcal{Y}^{(n)} \end{pmatrix}; 0 \leq n \leq N \right)$. Following §3, we construct the sample KM₂O-Langevin equations and other related quantities. These quantities are represented by replacing \mathbf{X} with \mathcal{X} , \mathbf{Y} with \mathcal{Y} , and \mathbf{Z} with \mathcal{Z} respectively in the variables defined in §5. At first we apply Test(S) to data \mathcal{Z} . If Test(S) for \mathcal{Z} is accepted, we proceed to test whether $\mathbf{Y} \xrightarrow{\text{LC}} \mathbf{X}$ or not.

Let M be defined by (3.19). For each $i \in \{0, \dots, N - M\}$, we introduce the shifted data \mathcal{Z}_i , \mathcal{X}_i and \mathcal{Y}_i similarly to (3.20). Then we get the sample KM₂O-Langevin fluctuation force $\begin{pmatrix} \nu_{+i, \mathcal{Z}, \mathcal{X}}^{(n)} \\ \nu_{+i, \mathcal{Z}, \mathcal{Y}}^{(n)} \end{pmatrix}$ ($0 \leq n \leq M$) of \mathcal{Z}_i , the sample KM₂O-Langevin fluctuation force $\nu_{+i, \mathcal{X}}^{(n)}$ ($0 \leq n \leq M$) of \mathcal{X}_i , the sample KM₂O-Langevin fluctuation force $\nu_{+i, \mathcal{Y}}^{(n)}$ ($0 \leq n \leq M$) of \mathcal{Y}_i respectively. In Test(S) for \mathcal{Z} , by replacing the component $\nu_{+i, \mathcal{Z}, \mathcal{X}}^{(n)}$ of $\begin{pmatrix} \nu_{+i, \mathcal{Z}, \mathcal{X}}^{(n)} \\ \nu_{+i, \mathcal{Z}, \mathcal{Y}}^{(n)} \end{pmatrix}$ by $\nu_{+i, \mathcal{X}}^{(n)}$ for all $n \in \{0, \dots, M\}$, we get

$$W_{+\mathcal{Z}}(n)^{-1} \begin{pmatrix} \nu_{+i, \mathcal{X}}^{(n)} \\ \nu_{+i, \mathcal{Z}, \mathcal{Y}}^{(n)} \end{pmatrix}, \quad 0 \leq n \leq M. \tag{6.1}_i$$

Test(S) for the one-dimensional data constructed from (6.1)_{*i*} is called the LC₁ Test. If the LC₁ Test is accepted (resp. not accepted), we can find from (L-3) of Theorem 5.1 that $\mathbf{Y} \not\xrightarrow{\text{LC}} \mathbf{X}$ (or $\mathbf{Y} \xrightarrow{\text{LC}} \mathbf{X}$). Similarly, Test(S) for the one-dimensional data constructed from

$$W_{+\mathcal{Z}}(n)^{-1} \begin{pmatrix} \nu_{+i, \mathcal{Z}, \mathcal{X}}^{(n)} \\ \nu_{+i, \mathcal{Y}}^{(n)} \end{pmatrix}, \quad 0 \leq n \leq M \tag{6.2}_i$$

is called the LC₂ Test. If the LC₂ Test is accepted (or not accepted), $\mathbf{X} \not\xrightarrow{\text{LC}} \mathbf{Y}$ (or $\mathbf{X} \xrightarrow{\text{LC}} \mathbf{Y}$). The Local Causal Test (LC Test) is the general term for the LC₁ Test and the LC₂ Test.

Similarly to §4, we apply these tests to the second order differences in the quarterly data of ${}^t(M_2 + \text{CD}, \text{RGNP})$ in two periods from 1965 to 1987 and from 1965 to 1990.

“S” (or “NS”) indicates that the LC Test is accepted (or not accepted). Table 6.1 and Table 6.2 report that RGNP locally causes Money Supply in both periods and Money Supply locally causes RGNP in the period from 1965 to 1987. Now, it is an established theory that Money Supply and

Table 6.1 The LC Test for $t(M_2+CD, RGNP)$ from 1965 to 1987.

j	LC Test	(M)	(V)	(O)	(S)
2	LC ₁	0.974	0.649	0.948	NS
2	LC ₂	0.987	0.675	0.987	NS

Table 6.2 The LC Test for $t(M_2+CD, RGNP)$ from 1965 to 1990.

j	LC Test	(M)	(V)	(O)	(S)
2	LC ₁	0.977	0.693	0.931	NS
2	LC ₂	0.954	0.736	0.886	S

RGNP are mutually related. On the other hand, we can not accept that Money Supply locally causes RGNP in the period from 1965 to 1990. We can explain these phenomena as follows: During the three years from 1987 to 1989, Japan went through a so-called bubble economy. The anomalous increase in the Money Supply is an example of this phenomenon. However this increase was nominal and failed substantially to boost RGNP.

Figure 6.1 and Figure 6.2 illustrate the local causal relations between Money Supply and RGNP.

Let us now compare the LC Test with the Granger-Sargent Test. (4.7) shows that the Granger-Sargent Test could not accept $M_2 + CD \xrightarrow{GC} RGNP$ in the period from 1965 to 1987. On the other hand, the LC Test accepts that $M_2 + CD \xrightarrow{LC} RGNP$ in the same period. As can be seen from the data analysis above, we can assert the efficiency of the LC Test.

Secondly, we consider how to test $\mathbf{X} \xrightarrow{ILC} \mathbf{Y}$. We set

$$W_{+z}(n)^{-1} = \begin{pmatrix} C_{11}(n) & \mathbf{0} \\ C_{12}(n) & C_{22}(n) \end{pmatrix}, \quad 0 \leq n \leq M. \tag{6.3}$$

Let $i \in \{0, \dots, N - M\}$. Similarly to the LC Test, Test(S) for the one-

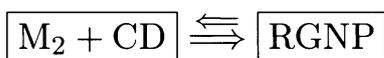


Figure 6.1 Local causality from 1965 to 1987.

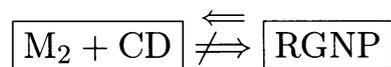


Figure 6.2 Local causality from 1965 to 1990.

Table 6.3 The ILC Test for $t(M_2 + CD, RGNP)$.

period	j	Test	(M)	(V)	(O)	(S)
1965–1987	2	ILC	0.974	0.662	0.961	NS
1965–1990	2	ILC	0.954	0.704	0.909	S

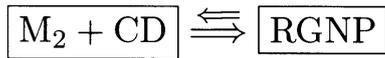


Figure 6.3 Instantaneous local causality from 1965 to 1987.



Figure 6.4 Instantaneous local causality from 1965 to 1990.

dimensional data constructed from

$$\begin{pmatrix} C_{11}(n) & \mathbf{0} \\ \mathbf{0} & C_{22}(n) \end{pmatrix} \begin{pmatrix} \nu_{+i,z,x}(n) \\ \nu_{+i,z,y}(n) \end{pmatrix}, \quad 0 \leq n \leq M \quad (6.4)$$

is called the Instantaneous Local Causal Test (ILC Test). If the ILC Test is accepted (or not accepted), we can find from Theorem 5.5 that $\mathbf{X} \stackrel{\text{ILC}}{\not\Rightarrow} \mathbf{Y}$ (or $\mathbf{X} \stackrel{\text{ILC}}{\Rightarrow} \mathbf{Y}$). Applications of the ILC Test to the second differences of quarterly data of $t(M_2 + CD, RGNP)$ are shown in Table 6.3, Figure 6.3 and Figure 6.4.

Similarly to Table 6.1 and Table 6.2, “S” (or “NS”) indicates that the test is accepted (or not accepted). These results are illustrated in Figure 6.3 and Figure 6.4.

Appendix

Table A Quarterly data of Japan Money Supply $M_2 + CD$ from 1965 to 1990,
(unit: one billion yen,
source: Databank, Toyokeizai Company, 1976, 1991).

Year	I	II	III	IV
1965	21678	22398	23376	25394
1966	25687	26354	27501	29522
1967	29731	30528	31660	34097
1968	34169	35482	36301	39153
1969	39435	41346	42817	46399
1970	46612	48810	50285	54237
1971	55002	58845	61908	67398
1972	68224	72260	75533	84040
1973	85346	90134	92831	98188
1974	98235	102159	102908	109494
1975	109374	113823	116458	125330
1976	126234	132192	134881	142248
1977	142350	147143	148910	158033
1978	157331	165076	167461	178720
1979	177587	184497	187794	195012
1980	194734	200250	199238	208985
1981	208097	217791	219200	232041
1982	230485	238028	240229	250466
1983	247926	255752	257236	268692
1984	267172	274751	279321	289714
1985	291609	299756	298904	314938
1986	313893	323076	323060	343887
1987	341860	355366	358173	380867
1988	380995	394455	398179	419732
1989	419615	433606	438292	470020
1990	472477	488055	495901	504972

Table B Quarterly data of RGNP from 1965 to 1990,
(unit: one billion yen, source: Databank, Toyokeizai Company, 1991).

Year	I	II	III	IV
1965	98209.69	99735.81	101896.29	103098.64
1966	106076.01	110631.11	113185.28	115268.23
1967	118371.29	121498.60	125714.28	128152.62
1968	131073.26	135839.40	138949.09	147732.80
1969	148577.10	152773.07	156197.76	162995.67
1970	167713.04	169192.18	174021.33	173813.68
1971	174559.62	177414.66	180425.90	182278.55
1972	187336.36	191269.92	195155.95	200124.06
1973	206472.57	208376.62	208501.38	210108.22
1974	204711.41	206395.56	208692.68	207357.88
1975	207093.75	212430.81	214653.93	217128.78
1976	218960.03	220760.27	223468.66	224092.79
1977	229443.96	231294.76	232687.24	236124.81
1978	239969.33	241920.21	245332.34	248396.84
1979	252587.19	256803.72	259272.22	261244.60
1980	264987.60	264164.02	266706.46	269937.72
1981	273731.49	273943.75	276643.88	277837.72
1982	280889.91	284347.12	285907.10	288785.51
1983	289804.67	290870.27	295221.30	296067.13
1984	301134.08	305081.63	306776.56	309458.94
1985	314832.56	320582.12	322546.73	327069.65
1986	324254.63	329177.45	330809.87	335300.05
1987	337484.68	339459.30	345743.11	353281.28
1988	359179.54	361860.14	368643.16	373095.36
1989	376977.24	376976.68	386060.58	391148.04
1990	397447.82	402877.40	407432.80	409539.20

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