# On the normal forms for Pfaffian systems 

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#### Abstract

We discuss local normal forms of Pfaffian systems and obtain a necessary and sufficient condition, in terms of relative polarizations, for the local generators of a Pfaffian system to convert to the contact system on the jet manifold $J^{r}\left(\mathbb{R}^{h}, \mathbb{R}^{q}\right)$, or to the Pfaffian system associated to a system of partial differential equations. This result generalizes the Darboux theorem on a Pfaffian equation of constant class.


Key words: Pfaffian system, contact system, relative polarization, local normal form.

## 1. Introduction

On the jet manifold $J^{r}\left(\mathbb{R}^{h}, \mathbb{R}^{q}\right)=\left(x_{\alpha_{1}}, z^{i}, z_{\alpha_{1}}^{i}, \ldots, z_{\alpha_{1} \cdots \alpha_{r}}^{i}\right)$ there is a canonical Pfaffian system, called the contact system, which is the Pfaffian system generated by the 1-forms

$$
\left\{\begin{array}{l}
\omega^{i}=d z^{i}-\sum_{\alpha_{1}=1}^{h} z_{\alpha_{1}}^{i} d x_{\alpha_{1}},  \tag{1}\\
\omega_{\alpha_{1}}^{i}=d z_{\alpha_{1}}^{i}-\sum_{\alpha_{2}=1}^{h} z_{\alpha_{1} \alpha_{2}}^{i} d x_{\alpha_{2}}, \\
\vdots \\
\vdots \\
\omega_{\alpha_{1} \cdots \alpha_{r-1}}^{i}=d z_{\alpha_{1} \cdots \alpha_{r-1}}^{i}-\sum_{\alpha_{r}=1}^{h} z_{\alpha_{1} \cdots \alpha_{r}}^{i} d x_{\alpha_{r}} . \\
\quad\left(1 \leq i \leq q, 1 \leq \alpha_{1}, \ldots, \alpha_{r-1} \leq h\right)
\end{array}\right.
$$

The contact system restricted to a submanifold of $J^{r}\left(\mathbb{R}^{h}, \mathbb{R}^{q}\right)$ is called the Pfaffian system associated to a system of partial differential equations.

The study of local normal forms of Pfaffian systems seems to have been initiated by Darboux [1], who showed that a Pfaffian equation $\omega=0$ of constant class $2 h+1$ (that is, $\omega \wedge(d \omega)^{h} \neq 0$ and $\left.\omega \wedge(d \omega)^{h+1}=0\right)$ can be

[^0]transformed locally into the contact form
$$
\omega=d z-\sum_{i=1}^{h} y_{i} d x_{i}
$$
on the jet manifold $J^{1}\left(\mathbb{R}^{h}, \mathbb{R}\right)$ (called the Darboux theorem on a Pfaffian equation of constant class). Many works have been done concerning local normal forms of Pfaffian systems in various cases. Engel [4], von Weber [13], Bryant [2], Goze-Haraguchi [6], and Kumpera-Rubin [7] gave a necessary and sufficient condition for the local generators of a Pfaffian system to be transformed into the contact system on $J^{2}(\mathbb{R}, \mathbb{R})$ (called the Engel normal form), the contact system on $J^{r}(\mathbb{R}, \mathbb{R})$ (called the Cartanvon Weber model), the contact system on $J^{1}\left(\mathbb{R}^{h}, \mathbb{R}^{q}\right), q \geq 3$ (called the Bryant normal form), the contact system on $J^{1}\left(\mathbb{R}^{h}, \mathbb{R}^{q}\right)$, and the contact system on $J^{r}\left(\mathbb{R}, \mathbb{R}^{q}\right)$ (called the extended von Weber model) respectively. Yamaguchi [14] gave a general criterion for a Pfaffian system to be transformed into the contact system on $J^{r}\left(\mathbb{R}^{h}, \mathbb{R}^{q}\right)$ using the theory of exterior differential systems.

The aim of this paper is to give a necessary and sufficient condition for a Pfaffian system to be transformed into the contact system on $J^{r}\left(\mathbb{R}^{h}, \mathbb{R}^{q}\right)$ or into the Pfaffian system associated to a system of partial differential equations. To prove this result, we use the properties of relative polarization (see in Lemma 3.1 and Lemma 3.2).

In Section 2, we prepare some basic definitions from the theory of Pfaffian systems, and recall Pfaffian systems on jet manifolds (the contact system and the Pfaffian system associated to a system of partial differential equations).

In Section 3, we define the relative polarization of a Pfaffian system according to Libermann [9], and discuss the Pfaffian systems with relative polarizations. We note that there is not always the relative polarization of a Pfaffian system (see in Proposition 3.3). Given a Pfaffian system with relative polarization, we can choose local coordinates to simplify the local generators of a Pfaffian system. We also evaluate the class and the Engel invariant, which are the invaiants of a Pfaffian system, using the existence of relative polarization.

In Section 4, we prove that under the existence of relative polarization and the condition on the type and the class of a Pfaffian system, the local
generators of a Pfaffian system can be transformed into the contact system (1) above, or into the contact system restricted to a submanifold of $J^{r}\left(\mathbb{R}^{h}, \mathbb{R}^{q}\right)$ (see in Theorem 4.1).

## 2. Pfaffian systems

Let $M$ be a $C^{\infty}$-manifold of dimension $n$ and $T^{*} M$ its cotangent bundle. Let $C^{\infty}(M)$ denote the ring of $C^{\infty}$-functions on $M$ and $\Gamma\left(T^{*} M\right)$ the $C^{\infty}(M)$-module of global $C^{\infty}$-sections of $T^{*} M$.

A Pfaffian system $S$ on $M$ is a $C^{\infty}(M)$-submodule of $\Gamma\left(T^{*} M\right)$. The system $S$ is said to have rank $q$ at $x \in M$ if the values of elements of $S$ (at $x$ ) form a $q$-dimensional subspace of $T_{x}^{*} M$. If the rank of $S$ is constant on $M, S$ is a space of $C^{\infty}$-sections of a subbundle of $T^{*} M$. We usually consider locally, and assume that $S$ is of constant rank and spanned by 1 -forms $\omega^{1}, \ldots, \omega^{q}$.

Let $\Omega^{k}(M)$ be the space of $k$-forms on $M, \Omega^{*}(M)=\oplus_{k=0}^{n} \Omega^{k}(M)$ the exterior algebra of differential forms on $M$, and $\mathscr{S}$ the ideal generated by $S$.

Definition 1 The Engel invariant of a Pfaffian system $S$ is the nonnegative integer $s_{0}$ defined as

$$
s_{0}=\min \left\{s \in \mathbb{Z}(\geq 0) \mid(d \omega)^{s+1} \equiv 0 \bmod \mathscr{S}, \omega \in S\right\}
$$

Let $S$ be a Pfaffian system on $M$ of $\operatorname{rank} q$ and $\left\{\omega^{1}, \ldots, \omega^{q}\right\}$ a local basis of $S$. We define $\operatorname{Char}_{x} S$ by

$$
\operatorname{Char}_{x} S=\left\{X \in T_{x} M \mid \omega^{i}(X)=0, \iota_{X} d \omega^{i} \equiv 0 \bmod \mathscr{S}, 1 \leq i \leq q\right\},
$$

where $\iota_{X}$ is the interior product with respect to the vector $X$. We denote the annihilator of $\operatorname{Char}_{x} S$ by $C(S)_{x}$. Note that the dimension of $C(S)_{x}$ is not necessarily constant even if the rank of $S$ is constant on $M$. However, we always consider the case where $C(S)_{x}$ is of constant dimension on $M$ throughout this paper. Then $C(S):=\cup_{x \in M} C(S)_{x}$ (called the Cartan system of $S$ ) is a space of $C^{\infty}$-sections of a subbundle of $T^{*} M$.
Definition 2 The class of $S$ is the rank of $C(S)$.
The following theorem shows that the class of a Pfaffian system is the minimum number of variables necessary for describing local generators of the system.

Theorem 2.1 (Cartan [3]) Let $S$ be a Pfaffian system of constant rank. The Cartan system $C(S)$ is the smallest completely integrable Pfaffian system with the property such that if $\left(x_{1}, \ldots, x_{p}\right)$ is a local system of the first integrals of $C(S)$, then there exist local generators of $S$, which depend only on $\left(x_{1}, \ldots, x_{p}\right)$ and their differentials.

The first derived system of $S$ is defined as

$$
S_{1}=\{\eta \in S \mid d \eta \equiv 0 \bmod \mathscr{S}\}
$$

Definition 3 We say that a Pfaffian system $S$ is totally regular if there is a decreasing sequence

$$
S=S_{0} \supset S_{1} \supset \cdots \supset S_{r-1} \supset S_{r}=S_{r+1}=\cdots
$$

of Pfaffian systems of constant rank, where $S_{k}, 1 \leq k \leq r$, is the first derived system of $S_{k-1}$ (called the $k$ th derived system of $S$ ).

Obviously, there exists the smallest non-negative integer $r$ such that $S_{r+p}=S_{r+p+1}$ for all $p \geq 0$. The integer $r$ satisfying the condition is called the length of $S$.
Definition 4 Let $S$ be a totally regular Pfaffian system of length $r$

$$
C(S) \supset S=S_{0} \supset S_{1} \supset \cdots \supset S_{r-1} \supset S_{r}=S_{r+1}=\cdots
$$

The type of $S$ is the $(r+2)$-tuple of non-negative integers $\left(p_{0}, \ldots, p_{r+1}\right)$ defined by

$$
\left\{\begin{array}{l}
p_{0}=\operatorname{rank} S_{r} \\
p_{k}=\operatorname{rank} S_{r-k} / S_{r-k+1}, 1 \leq k \leq r \\
p_{r+1}=\operatorname{rank} C(S) / S
\end{array}\right.
$$

The rank of each derived system $S_{r-k}, 1 \leq k \leq r$, and the class of $S$ easily seen to be

$$
\operatorname{rank} S_{r-k}=\sum_{i=0}^{k} p_{i}, \quad \text { class } S=\sum_{i=0}^{r+1} p_{i}
$$

Let $J^{r}\left(\mathbb{R}^{h}, \mathbb{R}^{q}\right)$ be the manifold of $r$-jets of maps from $\mathbb{R}^{h}$ to $\mathbb{R}^{q}$ and

$$
\mathbf{x}:=\left(x_{\alpha_{1}}, z^{i}, z_{\alpha_{1}}^{i}, \ldots, z_{\alpha_{1} \cdots \alpha_{r}}^{i}\right)_{1 \leq i \leq q, 1 \leq \alpha_{1}, \ldots, \alpha_{r} \leq h}
$$

the canonical coordinate system of $J^{r}\left(\mathbb{R}^{h}, \mathbb{R}^{q}\right)$, where $\left(x_{\alpha}\right) \in \mathbb{R}^{h},\left(z^{i}\right) \in \mathbb{R}^{q}$,
and $z_{\alpha_{1} \alpha_{2}}^{i}, \ldots, z_{\alpha_{1} \ldots \alpha_{r}}^{i}$ are symmetric with respect to the subscript $\alpha_{1}, \ldots, \alpha_{r}$. On $J^{r}\left(\mathbb{R}^{h}, \mathbb{R}^{q}\right)$, there is a canonical Pfaffian system, called the contact system, which is given as follows.

Definition 5 The contact system on $J^{r}\left(\mathbb{R}^{h}, \mathbb{R}^{q}\right)$ is the Pfaffian system generated by the 1 -forms $\omega^{i}, \omega_{\alpha_{1}}^{i}, \ldots, \omega_{\alpha_{1} \ldots \alpha_{r-1}}^{i}$, where

$$
\left\{\begin{array}{l}
\omega^{i}:=d z^{i}-\sum_{\alpha_{1}=1}^{h} z_{\alpha_{1}}^{i} d x_{\alpha_{1}},  \tag{2}\\
\omega_{\alpha_{1}}^{i}:=d z_{\alpha_{1}}^{i}-\sum_{\alpha_{2}=1}^{h} z_{\alpha_{1} \alpha_{2}}^{i} d x_{\alpha_{2}}, \\
\vdots \\
\vdots \\
\omega_{\alpha_{1} \cdots \alpha_{r-1}}^{i}:=d z_{\alpha_{1} \cdots \alpha_{r-1}}^{i}-\sum_{\alpha_{r}=1}^{h} z_{\alpha_{1} \cdots \alpha_{r}}^{i} d x_{\alpha_{r}} . \\
\quad\left(1 \leq i \leq q, 1 \leq \alpha_{1}, \ldots, \alpha_{r-1} \leq h\right)
\end{array}\right.
$$

We denote this contact system on $J^{r}\left(\mathbb{R}^{h}, \mathbb{R}^{q}\right)$ by $\Omega^{r}\left(\mathbb{R}^{h}, \mathbb{R}^{q}\right)$. We note that the 1-forms $\omega_{\alpha_{1} \ldots \alpha_{k}}^{i}, 2 \leq k \leq r-1$, are symmetric with respect to the subscript $\alpha_{1}, \ldots, \alpha_{k}$. Namely, $\left(\alpha_{1}, \ldots, \alpha_{k}\right)$ is the same index as $\left(\beta_{1}, \ldots, \beta_{k}\right)$ as a set, then $\omega_{\alpha_{1} \ldots \alpha_{k}}^{i}$ and $\omega_{\beta_{1} \ldots \beta_{k}}^{i}$ are coincident.

Example $1 \Omega^{r}\left(\mathbb{R}^{h}, \mathbb{R}^{q}\right)$ is a totally regular Pfaffian system of length $r$. The derived system of $\Omega^{r}\left(\mathbb{R}^{h}, \mathbb{R}^{q}\right)$ is computed as follows:

$$
\begin{aligned}
\Omega^{r}\left(\mathbb{R}^{h}, \mathbb{R}^{q}\right)_{1} & =\operatorname{span}\left\{\omega^{i}, \ldots, \omega_{\alpha_{1} \cdots \alpha_{r-2}}^{i}\right\}=\pi_{r-1}^{r *} \Omega^{r-1}\left(\mathbb{R}^{h}, \mathbb{R}^{q}\right), \\
\Omega^{r}\left(\mathbb{R}^{h}, \mathbb{R}^{q}\right)_{2} & =\operatorname{span}\left\{\omega^{i}, \ldots, \omega_{\alpha_{1} \cdots \alpha_{r-3}}^{i}\right\}=\pi_{r-2}^{r *} \Omega^{r-2}\left(\mathbb{R}^{h}, \mathbb{R}^{q}\right), \\
& \vdots \\
\Omega^{r}\left(\mathbb{R}^{h}, \mathbb{R}^{q}\right)_{r-1} & =\operatorname{span}\left\{\omega^{i}\right\}=\pi_{1}^{r *} \Omega^{1}\left(\mathbb{R}^{h}, \mathbb{R}^{q}\right), \\
\Omega^{r}\left(\mathbb{R}^{h}, \mathbb{R}^{q}\right)_{r} & =\{0\},
\end{aligned}
$$

where $\pi_{k}^{r}: J^{r}\left(\mathbb{R}^{h}, \mathbb{R}^{q}\right) \rightarrow J^{k}\left(\mathbb{R}^{h}, \mathbb{R}^{q}\right)$ is the natural projection. The rank, the class, and the Engel invariant of each derived system are

$$
\operatorname{rank} \Omega^{r}\left(\mathbb{R}^{h}, \mathbb{R}^{q}\right)_{r-j}=q\binom{h+j-1}{j-1}
$$

$$
\begin{aligned}
& \operatorname{class} \Omega^{r}\left(\mathbb{R}^{h}, \mathbb{R}^{q}\right)_{r-j}=h+q\binom{h+j}{j} \\
& s_{r-j}=h, \quad(1 \leq j \leq r-1)
\end{aligned}
$$

where $\binom{a}{b}$ stands for the binomial coefficients. The type of $\Omega^{r}\left(\mathbb{R}^{h}, \mathbb{R}^{q}\right)$ is

$$
\left(p_{0}, p_{1}, \ldots, p_{r}, p_{r+1}\right)=\left(0, q, \ldots, q\binom{h+r-2}{h+r-1}, q\binom{h+r-1}{h+r}\right)
$$

We define the Pfaffian system associated to a system of partial differential equations (PDEs for short). By a system of rth order PDEs in $\mathbb{R}^{h}$ and $\mathbb{R}^{q}$ of codimension $\sigma$, we mean a submanifold $\mathscr{L}_{\left\{F_{j}\right\}}$ of $J^{r}\left(\mathbb{R}^{h}, \mathbb{R}^{q}\right)$ defined locally by

$$
\mathscr{L}_{\left\{F_{j}\right\}}=\left\{\mathbf{x} \in J^{r}\left(\mathbb{R}^{h}, \mathbb{R}^{q}\right) \mid F_{j}(\mathbf{x})=0,1 \leq j \leq \sigma\right\}
$$

where we require the following regularity condition

$$
\operatorname{rank} \frac{\partial\left(F_{1}, \ldots, F_{\sigma}\right)}{\partial\left(z_{1 \cdots 1}^{1}, \ldots, z_{\alpha_{1} \cdots \alpha_{r}}^{i}, \ldots, z_{h \cdots h}^{q}\right)}=\sigma
$$

Let $\Sigma$ be an open subset of $\mathbb{R}^{l}, l=\operatorname{dim} J^{r}\left(\mathbb{R}^{h}, \mathbb{R}^{q}\right)-\sigma$, and $\imath: \Sigma \rightarrow \mathscr{L}_{\left\{F_{j}\right\}}$ a $C^{\infty}$-map of maximal rank.

Definition 6 The Pfaffian system on $\Sigma$ associated to $\mathscr{L}_{\left\{F_{j}\right\}}$ is the pull back $\imath^{*} \Omega^{r}\left(\mathbb{R}^{h}, \mathbb{R}^{q}\right)$ of $\Omega^{r}\left(\mathbb{R}^{h}, \mathbb{R}^{q}\right)$ to $\Sigma$. We denote this system by $\Omega\left(\Sigma_{\sigma}^{(r, h, q)}\right):=\imath^{*} \Omega^{r}\left(\mathbb{R}^{h}, \mathbb{R}^{q}\right)$.

Example 2 (Libermann [10]) Consider the Cauchy-Riemann equation

$$
\mathscr{L}_{\left\{F_{j}\right\}}=\left\{\mathbf{x} \in J^{1}\left(\mathbb{R}^{2}, \mathbb{R}^{2}\right) \mid z_{1}^{1}-z_{2}^{2}=0, z_{2}^{1}+z_{1}^{2}=0\right\}
$$

Take $\Sigma=\mathbb{R}^{6}=\left\{\left(x_{1}, x_{2}, z^{1}, z^{2}, z_{1}^{1}, z_{2}^{1}\right)\right\}$. We have the map $\imath: \Sigma \rightarrow J^{1}\left(\mathbb{R}^{2}, \mathbb{R}^{2}\right)$ defined by

$$
\imath\left(x_{1}, x_{2}, z^{1}, z^{2}, z_{1}^{1}, z_{2}^{1}\right)=\left(x_{1}, x_{2}, z^{1}, z^{2}, z_{1}^{1}, z_{2}^{1},-z_{2}^{1}, z_{1}^{1}\right)
$$

Therefore

$$
\Omega\left(\Sigma_{2}^{(1,2,2)}\right)=\left\{\begin{array}{l}
\imath^{*} \omega^{1}=d z^{1}-z_{1}^{1} d x_{1}-z_{2}^{1} d x_{2} \\
\imath^{*} \omega^{2}=d z^{2}+z_{2}^{1} d x_{1}-z_{1}^{1} d x_{2}
\end{array}\right.
$$

Example 3 (Gardner [5]) Consider the Monge-Ampère equation

$$
\mathscr{L}_{F}=\left\{\mathbf{x} \in J^{2}\left(\mathbb{R}^{2}, \mathbb{R}\right) \mid\left(z_{11}^{1}-f_{1}\right)\left(z_{22}^{1}-f_{3}\right)-\left(z_{12}^{1}-f_{2}\right)^{2}=0\right\}
$$

where $f_{i}$ is a function of variables $\left(x_{1}, x_{2}, z^{1}, z_{1}^{1}, z_{2}^{1}\right)$ of $J^{2}\left(\mathbb{R}^{2}, \mathbb{R}\right) \rightarrow J^{1}\left(\mathbb{R}^{2}, \mathbb{R}\right)$. Take $\Sigma=\left\{\left(x_{1}, x_{2}, z^{1}, z_{1}^{1}, z_{2}^{1}, u, v\right) \in \mathbb{R}^{7} \mid(u, v) \neq(0,0)\right\}$. We have the map $\imath: \Sigma \rightarrow J^{2}\left(\mathbb{R}^{2}, \mathbb{R}\right)$ defined by

$$
\imath\left(x_{1}, x_{2}, z^{1}, z_{1}^{1}, z_{2}^{1}, u, v\right)=\left(x_{1}, x_{2}, z^{1}, z_{1}^{1}, z_{2}^{1}, f_{1}+v u^{2}, f_{2}+v u, f_{3}+v\right)
$$

Therefore

$$
\Omega\left(\Sigma_{1}^{(2,2,1)}\right)=\left\{\begin{array}{l}
\imath^{*} \omega^{1}=d z^{1}-z_{1}^{1} d x_{1}-z_{2}^{1} d x_{2} \\
\imath^{*} \omega_{1}^{1}=d z_{1}^{1}-\left(f_{1}+v u^{2}\right) d x_{1}-\left(f_{2}+v u\right) d x_{2} \\
\imath^{*} \omega_{2}^{1}=d z_{2}^{1}-\left(f_{2}+v u\right) d x_{1}-\left(f_{3}+v\right) d x_{2}
\end{array}\right.
$$

## 3. Pfaffian systems with relative polarizations

In this section we discuss totally regular Pfaffian systems with relative polarizations. A relative polarization, which was introduced by Libermann [9], is a useful notion in our discussion (called pivot by Lutz [11] and it is the anologue of polarization introduced by Molino [12]). There does not always exist such a relative polarization for every totally regular Pfaffian system. Given a totally regular Pfaffian system with relative polarization, we can choose local coordinates to simplify the local genelators of a Pfaffian system. Also, we evaluate the Engel invariant and the class, which is the minimum number of variables necessary in order to describe the local generators of a Pfaffian system. Here we start with the definition of relative polarizations for totally regular Pfaffian systems.

Definition 7 Let $S$ be a totally regular Pfaffian system on $M$ of length $r$. We say that $S$ has a relative polarization $H$ if there exists a Pfaffian system $H$ of constant rank, satisfying the following conditions:
(i) $S \cap H=0_{M}$ (zero section),
(ii) $H$ and $S_{i} \oplus H, 0 \leq i \leq r$, are completely integrable, where $S_{i}$ is the $i$ th derived system of $S$,
(iii) $H$ is minimal, that is, if a subbundle $\bar{H} \subset H$ satisfies the conditions (i) and (ii), then $\bar{H}=H$.

Example 4 Consider the contact system $\Omega^{r}\left(\mathbb{R}^{h}, \mathbb{R}^{q}\right)$ on the jet manifold $J^{r}\left(\mathbb{R}^{h}, \mathbb{R}^{q}\right)$. The exterior derivatives of (2) can be written as

$$
\left\{\begin{array}{l}
d \omega^{i} \equiv \sum_{\alpha_{1}=1}^{h} d x_{\alpha_{1}} \wedge \omega_{\alpha_{1}}^{i} \bmod \mathscr{S}_{r-1}, \\
\vdots \\
d \omega_{\alpha_{1} \cdots \alpha_{l}}^{i} \equiv \sum_{\alpha_{l+1}=1}^{h} d x_{\alpha_{l+1}} \wedge \omega_{\alpha_{1} \cdots \alpha_{l+1}}^{i} \bmod \mathscr{S}_{r-l-1} \\
\vdots \\
\vdots \\
d \omega_{\alpha_{1} \cdots \alpha_{r-1}}^{i} \equiv \sum_{\alpha_{r}=1}^{h} d x_{\alpha_{r}} \wedge d z_{\alpha_{1} \cdots \alpha_{r-1} \alpha_{r}}^{i} \bmod \mathscr{S} \\
\quad\left(1 \leq i \leq q, 1 \leq l \leq r-2,1 \leq \alpha_{1}, \ldots, \alpha_{r} \leq h\right)
\end{array}\right.
$$

It can be verified that $\Omega^{r}\left(\mathbb{R}^{h}, \mathbb{R}^{q}\right)$ has a relative polarization

$$
H=\operatorname{span}\left\{d x_{1}, \ldots, d x_{h}\right\}
$$

We note that $H$ is the pull back of $T^{*} \mathbb{R}^{h}$ by the source projection $J^{r}\left(\mathbb{R}^{h}, \mathbb{R}^{q}\right) \rightarrow \mathbb{R}^{h}$.

Example 5 (Libermann [10]) Consider the Pfaffian system $S$ on $\mathbb{R}^{7}$ of rank 5 defined by 1 -forms $\omega^{1}, \ldots, \omega^{5}$, satisfying

$$
\begin{align*}
d \omega^{1} & =\omega^{4} \wedge \omega^{6}+\omega^{3} \wedge \omega^{7}  \tag{3}\\
d \omega^{2} & =\omega^{4} \wedge \omega^{7}+\omega^{3} \wedge \omega^{6}  \tag{4}\\
d \omega^{3} & =\omega^{5} \wedge \omega^{6}  \tag{5}\\
d \omega^{4} & =\omega^{5} \wedge \omega^{7}  \tag{6}\\
d \omega^{5} & =\omega^{6} \wedge \omega^{7} \tag{7}
\end{align*}
$$

where $\omega^{1} \wedge \cdots \wedge \omega^{7} \neq 0$. Then $S$ is a totally regular Pfaffian system of length 3 and the derived systems are

$$
S_{1}=\operatorname{span}\left\{\omega^{1}, \ldots, \omega^{4}\right\}, \quad S_{2}=\operatorname{span}\left\{\omega^{1}, \omega^{2}\right\}, \quad S_{3}=\{0\}
$$

The system $S$ has a relative polarization $H=\operatorname{span}\left\{\omega^{6}, \omega^{7}\right\}$ of rank 2 .
Indeed, differentiating $(3) \sim(7)$ we have

$$
\begin{align*}
& 0=\omega^{4} \wedge d \omega^{6}+\omega^{3} \wedge d \omega^{7}  \tag{8}\\
& 0=\omega^{4} \wedge d \omega^{7}+\omega^{3} \wedge d \omega^{6}  \tag{9}\\
& 0=\omega^{5} \wedge d \omega^{6} \tag{10}
\end{align*}
$$

$$
\begin{align*}
& 0=\omega^{5} \wedge d \omega^{7}  \tag{11}\\
& 0=d \omega^{6} \wedge \omega^{7}-\omega^{6} \wedge d \omega^{7} . \tag{12}
\end{align*}
$$

From (10) and (11) there exist two 1 -forms $\theta^{6}, \theta^{7} \in \Omega^{1}\left(\mathbb{R}^{7}\right)$ such that

$$
\begin{equation*}
d \omega^{6}=\omega^{5} \wedge \theta^{6}, \quad d \omega^{7}=\omega^{5} \wedge \theta^{7} . \tag{13}
\end{equation*}
$$

Put the 1-forms $\theta^{i}(i=6,7)$ as $\theta^{i}:=\sum_{j=1}^{7} f_{j}^{i} \omega^{j}, f_{j}^{i} \in \Omega^{0}\left(\mathbb{R}^{7}\right)$. Substituting (13) into (8), (9), and (12), we can see that $\theta^{6}=f_{5}^{6} \omega^{5}, \theta^{7}=f_{5}^{7} \omega^{5}$. Therefore

$$
d \omega^{6}=d \omega^{7}=0 .
$$

Thus the system $H$ is completely integrable. Since $S_{i} \oplus H, 0 \leq i \leq 2$, are also completely integrable by (8) $\sim(12)$, it is easy to see that $H$ satisfies the conditions (i) $\sim(\mathrm{iii})$.

Let us consider a totally regular Pfaffian system $S$ of length $r$ with relative polarization of rank $h$. We have the following lemmas on $S$. The main theorem in Section 4 can be obtained by using these properties. Let $M$ be a $C^{\infty}$-manifold of dimension $n$, where $n$ is sufficiently big. In the next lemma, due to Libermann [10], we use

$$
\begin{aligned}
x & :=\left(x_{1}, \ldots, x_{h}\right), \quad y^{(k)}:=\left(y_{1}^{(k)}, \ldots, y_{p_{k}}^{(k)}\right), \\
u & :=\left(u_{1}, \ldots, u_{n-\left(h+p_{1}+\cdots+p_{r}\right)}\right)
\end{aligned}
$$

to denote local coordinates of $M$, where $\left(p_{0}, \ldots, p_{r+1}\right)$ is the type of $S$ and $k=1, \ldots, r$.

Lemma 3.1 (Libermann) Let $S$ be a totally regular Pfaffian system on $M$ of length $r$ with $S_{r}=\{0\}$. If $S$ has a relative polarization $H$ of rank $h$, then there exist local coordinates $\left(x, y^{(1)}, \ldots, y^{(r)}, u\right)$ around each point in $M$ such that $S$ is generated by 1-forms

$$
\left\{\begin{array}{l}
\omega_{(1)}^{i_{1}}=d y_{i_{1}}^{(1)}-\sum_{\alpha=1}^{h} A_{\alpha}^{i_{1}}(1) d x_{\alpha},  \tag{14}\\
\vdots \\
\vdots \\
\omega_{(r)}^{i_{r}}=d y_{i_{r}}^{(r)}-\sum_{\alpha=1}^{h} A_{\alpha}^{i_{r}}(r) d x_{\alpha} . \\
\quad\left(1 \leq i_{1} \leq p_{1}, \ldots, 1 \leq i_{r} \leq p_{r}\right)
\end{array}\right.
$$

Each derived system $S_{r-k}, 1 \leq k \leq r-1$, is generated by the 1-forms $\omega_{(1)}^{i_{1}}, \ldots, \omega_{(k)}^{i_{k}}$, and each $A_{\alpha}^{i_{k}}(k)$ is a function

$$
A_{\alpha}^{i_{k}}(k)=A_{\alpha}^{i_{k}}(k)\left(x, y^{(1)}, \ldots, y^{(k)}, y^{(k+1)}\right)
$$

Proof. By the integrability of $H$ and $S_{r-1} \oplus H$, let $\left(x_{1}, \ldots, x_{h}\right)$ be a family of the first integrals generating $H$ and $\left(y_{1}^{(1)}, \ldots, y_{p_{1}+h}^{(1)}\right)$ a family of the first integrals generating $S_{r-1} \oplus H$. Then we can choose, by changing numbering if needed, the local basis $\left\{\omega_{(1)}^{1}, \ldots, \omega_{(1)}^{p_{1}}\right\}$ of $S_{r-1}$ such that $\omega_{(1)}^{1}=$ $\pi_{1}\left(d y_{1}^{(1)}\right), \ldots, \omega_{(1)}^{p_{1}}=\pi_{1}\left(d y_{p_{1}}^{(1)}\right)$, where $\pi_{1}: S_{r-1} \oplus H \rightarrow S_{r-1}$ is the natural projection. Therefore we have

$$
d y_{i_{1}}^{(1)}=\omega_{(1)}^{i_{1}}+\sum_{\alpha=1}^{h} A_{\alpha}^{i_{1}}(1) d x_{\alpha}, \quad 1 \leq i_{1} \leq p_{1}
$$

where $A_{\alpha}^{i_{1}}(1) \in \Omega^{0}(M)$. Thus the $(r-1)$ st derived system $S_{r-1}$ is locally generated by the 1 -forms

$$
\omega_{(1)}^{i_{1}}=d y_{i_{1}}^{(1)}-\sum_{\alpha=1}^{h} A_{\alpha}^{i_{1}}(1) d x_{\alpha}, \quad 1 \leq i_{1} \leq p_{1}
$$

To consider the $(r-2)$ nd derived system $S_{r-2}$, we take any Pfaffian system $T_{r-1}$ satisfying $S_{r-2}=S_{r-1} \oplus T_{r-1}$. By the integrability of $S_{r-2} \oplus H$, let $\left(y_{1}^{(2)}, \ldots, y_{p_{1}+p_{2}+h}^{(2)}\right)$ be a family of the first integrals generating $S_{r-2} \oplus H$. Then we can choose, by changing numbering if needed, the local basis $\left\{\eta_{(2)}^{1}, \ldots, \eta_{(2)}^{p_{2}}\right\}$ of $T_{r-1}$ such that $\eta_{(2)}^{1}=\pi_{2}\left(d y_{1}^{(2)}\right), \ldots, \eta_{(2)}^{p_{2}}=\pi_{2}\left(d y_{p_{2}}^{(2)}\right)$, where $\pi_{2}: S_{r-2} \oplus H \rightarrow T_{r-1}$ is the natural projection. Therefore we have

$$
d y_{i_{2}}^{(2)}=\eta_{(2)}^{i_{2}}+\sum_{i_{1}=1}^{p_{1}} f_{i_{1}}^{i_{2}} \omega_{(1)}^{i_{1}}+\sum_{\alpha=1}^{h} A_{\alpha}^{i_{2}}(2) d x_{\alpha}, \quad 1 \leq i_{2} \leq p_{2}
$$

where $f_{i_{1}}^{i_{2}}, A_{\alpha}^{i_{2}}(2) \in \Omega^{0}(M)$. Putting $\omega_{(2)}^{i_{2}}:=\eta_{(2)}^{i_{2}}+\sum_{i_{1}=1}^{p_{1}} f_{i_{1}}^{i_{2}} \omega_{(1)}^{i_{1}}$, we can see that $S_{r-2}$ is locally generated by the 1 -forms

$$
\left\{\begin{array}{l}
\omega_{(1)}^{i_{1}}=d y_{i_{1}}^{(1)}-\sum_{\alpha=1}^{h} A_{\alpha}^{i_{1}}(1) d x_{\alpha} \\
\omega_{(2)}^{i_{2}}=d y_{i_{2}}^{(2)}-\sum_{\alpha=1}^{h} A_{\alpha}^{i_{2}}(2) d x_{\alpha} . \quad\left(1 \leq i_{1} \leq p_{1}, 1 \leq i_{2} \leq p_{2}\right)
\end{array}\right.
$$

After $r-2$ times application of this manipulation, we obtain the local normal form (14) of $S$. By the definition of the derived system of $S_{r-k}$, we have

$$
d \omega_{(k)}^{i_{k}} \wedge \omega_{(1)}^{1} \wedge \cdots \wedge \omega_{(1)}^{p_{1}} \wedge \cdots \wedge \omega_{(k+1)}^{1} \wedge \cdots \wedge \omega_{(k+1)}^{p_{k+1}}=0, \quad 1 \leq i_{k} \leq p_{k}
$$

From (14), this implies

$$
\sum_{\alpha=1}^{h}\left(d x_{\alpha} \wedge d A_{\alpha}^{i_{k}}(k)\right) \wedge d y_{1}^{(1)} \wedge \cdots \wedge d y_{p_{1}}^{(1)} \wedge \cdots \wedge d y_{1}^{(k+1)} \wedge \cdots \wedge d y_{p_{k+1}}^{(k+1)}=0
$$

Therefore $A_{\alpha}^{i_{k}}(k)$ is a function of the coordinates $x, y^{(1)}, \ldots, y^{(k+1)}$ as desired.

Lemma 3.2 Let $S$ be a totally regular Pfaffian system on $M$ of length r. If $S$ has a relative polarization $H$ of rank $h$, then the set of exterior derivatives of elements of $S_{r-k}, 1 \leq k \leq r$, satisfies the inclusion

$$
\begin{equation*}
d S_{r-k} \bmod \mathscr{S}_{r-k} \subset \mathscr{H} \cap \mathscr{S}_{r-k-1} \tag{15}
\end{equation*}
$$

where $S_{-1}$ stands for the Cartan system $C(S)$ of $S$.
Proof. We first consider the case of $1 \leq k \leq r-1$. Let $\left(p_{0}, \ldots, p_{r+1}\right)$ denote the type of $S$. Let $\left\{\omega_{(k)}^{1}, \ldots, \omega_{(k)}^{p_{k}}\right\}$ be a local basis of any complementary subspace of $S_{r-k+1}$ in $S_{r-k}$ and $\left\{\omega_{(k+1)}^{1}, \ldots, \omega_{(k+1)}^{p_{k+1}}\right\}$ a local basis of any complementary subspace of $S_{r-k}$ in $S_{r-k-1}$. According to the previous lemma, the exterior derivative of $\omega_{(k)}^{i_{k}}, 1 \leq i_{k} \leq p_{k}$, can be written in the form

$$
\begin{aligned}
d \omega_{(k)}^{i_{k}} & =\sum_{\alpha=1}^{h} d x_{\alpha} \wedge d A_{\alpha}^{i_{k}}(k) \\
& \equiv \sum_{\alpha=1}^{h} \sum_{j_{k+1}=1}^{p_{k+1}} \frac{\partial A_{\alpha}^{i_{k}}(k)}{\partial y_{j_{k+1}}^{(k+1)}} d x_{\alpha} \wedge \omega_{(k+1)}^{j_{k+1}}+\sum_{\alpha, \beta=1}^{h}\left(\frac{\partial A_{\alpha}^{i_{k}}(k)}{\partial x_{\beta}}\right. \\
& +\sum_{j_{1}=1}^{p_{1}} \frac{\partial A_{\alpha}^{i_{k}}(k)}{\partial y_{j_{1}}^{(1)}} A_{\beta}^{j_{1}}(1)+\cdots+\sum_{j_{k}=1}^{p_{k}} \frac{\partial A_{\alpha}^{i_{k}}(k)}{\partial y_{j_{k}}^{(k)}} A_{\beta}^{j_{k}}(k) \\
& \left.+\sum_{j_{k+1}=1}^{p_{k+1}} \frac{\partial A_{\alpha}^{i_{k}}(k)}{\partial y_{j_{k+1}}^{(k+1)}} A_{\beta}^{j_{k+1}}(k+1)\right) d x_{\alpha} \wedge d x_{\beta} \bmod \mathscr{S}_{r-k}
\end{aligned}
$$

Since $d \omega_{(k)}^{i_{k}}$ vanishes mod $\mathscr{S}_{r-k-1}$, the terms of $d x_{\alpha} \wedge d x_{\beta}, 1 \leq \alpha, \beta \leq h$, do
vanish. Hence we have

$$
\begin{equation*}
d \omega_{(k)}^{i_{k}} \equiv \sum_{\alpha=1}^{h} \sum_{i_{k+1}=1}^{p_{k+1}} \frac{\partial A_{\alpha}^{i_{k}}(k)}{\partial y_{i_{k+1}}^{(k+1)}} d x_{\alpha} \wedge \omega_{(k+1)}^{i_{k+1}} \quad \bmod \mathscr{S}_{r-k} \tag{16}
\end{equation*}
$$

Since the 1-forms $d x_{1}, \ldots, d x_{h}$ and $\omega_{(k+1)}^{1}, \ldots, \omega_{(k+1)}^{p_{k+1}}$ are the local basis of $H$ and of $S_{r-k-1} / S_{r-k}$ respectively, we obtain (15) as claimed. Consider the case of $k=r$. Let $\left\{d u_{1}, \ldots, d u_{p_{r+1}-h}\right\}$ be a local basis of any complementary subspace of $S_{0} \oplus H$ in $S_{-1}$. The exterior derivative of $\omega_{(r)}^{i_{r}}, 1 \leq i_{r} \leq p_{r}$, can be written in the form

$$
\begin{aligned}
d \omega_{(r)}^{i_{r}} \equiv & \sum_{\alpha=1}^{h} \sum_{l=1}^{p_{r+1}-h} \frac{\partial A_{\alpha}^{i_{r}}(r)}{\partial u_{l}} d x_{\alpha} \wedge d u_{l} \\
& +\sum_{\alpha, \beta=1}^{h}\left(\frac{\partial A_{\alpha}^{i_{r}}(r)}{\partial x_{\beta}}+\sum_{j_{1}=1}^{p_{1}} \frac{\partial A_{\alpha}^{i_{r}}(r)}{\partial y_{j_{1}}^{(1)}} A_{\beta}^{i_{1}}(1)+\cdots\right. \\
& \left.+\sum_{j_{r}=1}^{p_{r}} \frac{\partial A_{\alpha}^{i_{r}}(r)}{\partial y_{j_{r}}^{(r)}} A_{\beta}^{j_{r}}(r)\right) d x_{\alpha} \wedge d x_{\beta} \quad \bmod \mathscr{S}_{0}
\end{aligned}
$$

We obtain the desired inclusion (15) in the same way of the case of $1 \leq i \leq$ $r-1$.

Proposition 3.1 Let $S$ be a totally regular Pfaffian system of length $r$ with $S_{r}=\{0\}$. If $S$ has a relative polarization of rank $h$, then the Engel invariant $s_{r-k}$ of each derived system $S_{r-k}, 1 \leq k \leq r-1$, satisfies the inequality

$$
s_{r-k} \leq h
$$

Proof. Let $\left\{\omega_{(1)}^{i_{1}}, \ldots, \omega_{(k)}^{i_{k}} \mid 1 \leq i_{1} \leq p_{1}, \ldots, 1 \leq i_{k} \leq p_{k}\right\}$ be a local basis of $S_{r-k}$ and $\left\{\omega_{(k+1)}^{1}, \ldots, \omega_{(k+1)}^{p_{k+1}}\right\}$ a local basis of any complementary subspace of $S_{r-k}$ in $S_{r-k-1}$. Then, by the definition of the derived system of $S_{r-k}$, we have

$$
\left\{\begin{array}{l}
d \omega_{(1)}^{i_{1}} \equiv 0 \bmod \mathscr{S}_{r-k}, \\
\vdots \\
d \omega_{(k-1)}^{i_{k-1}} \equiv 0 \bmod \mathscr{S}_{r-k}, \\
d \omega_{(k)}^{i_{k}} \neq 0 \bmod \mathscr{S}_{r-k} . \quad\left(1 \leq i_{1} \leq p_{1}, \ldots, 1 \leq i_{k} \leq p_{k}\right)
\end{array}\right.
$$

Let $\left\{d x_{1}, \ldots, d x_{h}, \omega_{(1)}^{i_{1}}, \ldots, \omega_{(k+1)}^{i_{k+1}}\right\}$ be a local basis of $S_{r-k-1} \oplus H$. Then by (16) and linear independence of $\left\{d x_{1}, \ldots, d x_{h}, \omega_{(1)}^{i_{1}}, \ldots, \omega_{(k+1)}^{i_{k+1}}\right\}$ we can see that

$$
\begin{aligned}
\left(d \omega_{(k)}^{i_{k}}\right)^{h} & \equiv \pm h!\sum_{j_{1}, \ldots, j_{h}=1}^{p_{k+1}} \frac{\partial A_{1}^{i_{k}}(k)}{\partial y_{j_{1}}^{(k+1)}} \cdots \frac{\partial A_{h}^{i_{k}}(k)}{\partial y_{j_{h}}^{(k+1)}} \mathbf{d} \mathbf{x} \wedge \omega_{(k+1)}^{j_{1}} \wedge \cdots \wedge \omega_{(k+1)}^{j_{h}} \\
& \not \equiv 0 \quad \bmod \mathscr{S}_{r-k}
\end{aligned}
$$

where $\mathbf{d x}$ stands for a $h$-form $\mathbf{d} \mathbf{x}=d x_{1} \wedge \cdots \wedge d x_{h}$. Therefore

$$
\begin{aligned}
\left(d \omega_{(k)}^{i_{k}}\right)^{h+1} & =\left(d \omega_{(k)}^{i_{k}}\right)^{h} \wedge d \omega_{(k)}^{i_{k}} \\
& =\left(d \omega_{(k)}^{i_{k}}\right)^{h} \wedge \sum_{\alpha=1}^{h}\left(d x_{\alpha} \wedge d A_{\alpha}^{i_{k}}(k)\right) \\
& \equiv 0 \quad \bmod \mathscr{S}_{r-k}
\end{aligned}
$$

This proves Proposition 3.1.
The following proposition means that the existence of relative polarizations allows us to evaluate the number of variables necessary in order to describe the local generators of each derived system $S_{r-k}$.

Proposition 3.2 Let $S$ be a totally regular Pfaffian system on $M$ of length $r$ with $S_{r}=\{0\}$. If $S$ has a relative polarization $H$ of rank $h$, then the class of each derived system $S_{r-k}, 1 \leq k \leq r-1$, satisfies the inequality

$$
\operatorname{class} S_{r-k} \leq \operatorname{rank} S_{r-k-1}+h
$$

Proof. From Lemma 3.1, we know that there exist local coordinates $\left(x, y^{(1)}, \ldots, y^{(r)}, u\right)$ in $M$ such that $S$ is generated by the 1 -forms

$$
\left\{\begin{array}{l}
\omega_{(1)}^{i_{1}}=d y_{i_{1}}^{(1)}-\sum_{\alpha=1}^{h} A_{\alpha}^{i_{1}}(1) d x_{\alpha}, \\
\vdots \\
\omega_{(r)}^{i_{r}}=d y_{i_{r}}^{(r)}-\sum_{\alpha=1}^{h} A_{\alpha}^{i_{r}}(r) d x_{\alpha}, \quad\left(1 \leq i_{1} \leq p_{1}, \ldots, 1 \leq i_{r} \leq p_{r}\right)
\end{array}\right.
$$

and the $(r-k)$ th derived system $S_{r-k}$ is generated by the 1-forms
$\omega_{(1)}^{i_{1}}, \ldots, \omega_{(k)}^{i_{k}}$. By the definition of $S_{r-k}$ and Lemma 3.2 the exterior derivatives $d \omega_{(1)}^{i_{1}}, \ldots, d \omega_{(k-1)}^{i_{k-1}}$, and $d \omega_{(k)}^{i_{k}}$, of $S_{r-k}$ satisfy

$$
\left\{\begin{array}{l}
d \omega_{(1)}^{i_{1}} \equiv 0 \bmod \mathscr{S}_{r-k}, \\
\vdots \\
\vdots \\
d \omega_{(k-1)}^{i_{k-1}} \equiv 0 \bmod \mathscr{S}_{r-k}, \quad\left(1 \leq i_{1} \leq p_{1}, \ldots, 1 \leq i_{k-1} \leq p_{k-1}\right)
\end{array}\right.
$$

and

$$
\begin{aligned}
d \omega_{(k)}^{i_{k}} & \equiv \sum_{\alpha=1}^{h} \sum_{i_{k+1}=1}^{p_{k+1}} \frac{\partial A_{\alpha}^{i_{k}}(k)}{\partial y_{i_{k+1}}^{k+1)}} d x_{\alpha} \wedge \omega_{(k+1)}^{i_{k+1}} \\
& \not \equiv 0 \quad \bmod \mathscr{S}_{r-k}, \quad 1 \leq i_{k} \leq p_{k}
\end{aligned}
$$

Hence the condition $\iota_{X} d \omega_{(k)}^{i_{k}} \equiv 0 \bmod \mathscr{S}_{r-k}$ implies

$$
\sum_{\alpha=1}^{h} \sum_{i_{k+1}=1}^{p_{k+1}} \frac{\partial A_{\alpha}^{i_{k}}(k)}{\partial y_{i_{k+1}}^{(k+1)}}\left(d x_{\alpha}(X) \omega_{(k+1)}^{i_{k+1}}-\omega_{(k+1)}^{i_{k+1}}(X) d x_{\alpha}\right)=0
$$

The linear independence of $\left\{d x_{1}, \ldots, d x_{h}, \omega_{(k+1)}^{1}, \ldots, \omega_{(k+1)}^{p_{k+1}}\right\}$ allows us to represent the formula above as

$$
\left(\begin{array}{c|c}
{ }^{t} A^{1} &  \tag{17}\\
\vdots & 0 \\
{ }^{t} A^{p_{k}} & \\
\hline & A^{1} \\
0 & \vdots \\
& A^{p_{k}}
\end{array}\right)\left(\begin{array}{c}
d x_{1}(X) \\
\vdots \\
d x_{h}(X) \\
\hline \omega_{(k+1)}^{1}(X) \\
\vdots \\
\omega_{(k+1)}^{p_{k+1}(X)}
\end{array}\right)=0
$$

where $A^{i}, 1 \leq i \leq p_{k}$, is a $h \times p_{k+1}$ matrix

$$
A^{i}:=\left(\frac{\partial A_{\alpha}^{i}(k)}{\partial y_{j}^{(k+1)}}\right)_{\substack{1 \leq \alpha \leq h \\ 1 \leq j \leq p_{k+1}}}
$$

and ${ }^{t} A^{i}$ is the transposed matrix of $A^{i}$. The rank of the coefficient matrix is clearly less than or equal to $h+p_{k+1}$. The class of $S_{r-k}$ is equal to the number of independent equations on the vectors $X \in T M, \omega_{(1)}^{i_{1}}(X)=\cdots=$

$$
\begin{gathered}
\omega_{(k)}^{i_{k}}(X)=0\left(1 \leq i_{1} \leq p_{1}, \ldots, 1 \leq i_{k} \leq p_{k}\right), \text { and }(17) . \text { So we have } \\
\operatorname{class} S_{r-k} \leq\left(p_{1}+\cdots+p_{k}\right)+\left(h+p_{k+1}\right)
\end{gathered}
$$

which is the desired inequality.
We end this section by giving an example of totally regular Pfaffian system which does not have relative polarization. The following proposition gives a necessary condition for the existence of relative polarizations. We define the reduced derived system $\widetilde{S_{r-k}}$ of $S_{r-k}$ by

$$
\widetilde{S_{r-k}}=\left\{\omega \in S_{r-k-1} \mid d \omega \equiv 0 \bmod \mathscr{S}_{r-k-1}+\left(\mathscr{S}_{r-k-2} \cap \mathscr{S}^{2}\right)\right\} .
$$

Proposition 3.3 (cf. Libermann [9]) Let $S$ be a totally regular Pfaffian system on $M$ of length $r$. If the system $S$ has a relative polarization $H$, then it satisfies the condition

$$
S_{r-k}=\widetilde{S_{r-k}}, \quad 0 \leq k \leq r-2
$$

Proof. Since $S_{r-k} \subset \widetilde{S_{r-k}}$ holds, it is sufficient to show that $S_{r-k} \supset$ $\widetilde{S_{r-k}}$. We take an element $\widetilde{\omega}$ of $\widetilde{S_{r-k}}$. Then $\widetilde{\omega} \in S_{r-k-1}$ and $d \widetilde{\omega} \bmod$ $\mathscr{S}_{r-k-1} \in \mathscr{S}_{r-k-2} \cap \mathscr{S}^{2}$. Let $\left\{\alpha^{1}, \ldots, \alpha^{h}\right\}$ be a local basis of $H$ and $\left\{\omega_{(k+2)}^{1}, \ldots, \omega_{(k+2)}^{p_{k+2}}\right\}$ a local basis of any complementary subspace of $S_{r-k-1}$ in $S_{r-k-2}$. By Lemma $3.2 d \widetilde{\omega}$ can be written

$$
d \widetilde{\omega} \bmod \mathscr{S}_{r-k-1} \equiv \sum_{i=1}^{h} \sum_{j=1}^{p_{k+2}} f_{j}^{i} \alpha^{i} \wedge \omega_{(k+2)}^{j}
$$

where $f_{j}^{i} \in \Omega^{0}(M)$. The condition (i) of the relative polarization gives $\alpha^{i} \wedge \omega_{(k+2)}^{j} \notin \mathscr{S}^{2}$, and hence

$$
\alpha^{i} \wedge \omega_{(k+2)}^{j} \notin \mathscr{S}_{r-k-2} \cap \mathscr{S}^{2} .
$$

Therefore we have

$$
d \widetilde{\omega} \equiv 0 \quad \bmod \mathscr{S}_{r-k-1}
$$

This proves Proposition 3.3.

Example 6 (Kumpera-Ruiz [8]) Consider the Pfaffian system $S$ on $\mathbb{R}^{5}=$ $\left(t, x_{1}, x_{2}, x_{3}, x_{4}\right)$ of rank 3 , defined by 1-forms

$$
\left\{\begin{array}{l}
\omega^{1}=d x_{1}-x_{2} d t  \tag{18}\\
\omega^{2}=d x_{2}-x_{3} d t \\
\omega^{3}=d t-x_{4} d x_{3}
\end{array}\right.
$$

The system $S$ does not have a relative polarization.
Indeed, put 1-forms $\omega^{4}, \omega^{5}$ as $\omega^{4}:=d x_{3}$ and $\omega^{5}:=d x_{4}$. Differentiating (18) we have

$$
\left\{\begin{array}{l}
d \omega^{1}=-\omega^{2} \wedge \omega^{3}-x_{4} \omega^{2} \wedge \omega^{4} \\
d \omega^{2}=-\omega^{4} \wedge \omega^{3} \\
d \omega^{3}=-\omega^{5} \wedge \omega^{4}
\end{array}\right.
$$

The system $S$ is a totally regular Pfaffian system of length 3 and the derived systems are

$$
S_{1}=\operatorname{span}\left\{\omega^{1}, \omega^{2}\right\}, \quad S_{2}=\operatorname{span}\left\{\omega^{1}\right\}, \quad S_{3}=\{0\}
$$

Note that the ideals $\mathscr{S}^{2}, \mathscr{S}_{1}$, and $\mathscr{S}_{2}$ are

$$
\begin{aligned}
\mathscr{S}^{2} & =\left\{\sum_{i=1}^{3} \sum_{j=1}^{3} \alpha_{j}^{i} \wedge \omega^{i} \wedge \omega^{j} \mid \alpha_{j}^{i} \in \Omega^{*}\left(\mathbb{R}^{5}\right)\right\} \\
\mathscr{S}_{1} & =\left\{\alpha^{1} \wedge \omega^{1}+\alpha^{2} \wedge \omega^{2} \mid \alpha^{i} \in \Omega^{*}\left(\mathbb{R}^{5}\right)\right\} \\
\mathscr{S}_{2} & =\left\{\alpha \wedge \omega^{1} \mid \alpha \in \Omega^{*}\left(\mathbb{R}^{5}\right)\right\}
\end{aligned}
$$

We have also $\mathscr{S}_{1} \cap \mathscr{S}^{2}=\left\{\sum_{i=1}^{2} \sum_{j=1}^{3} \alpha_{j}^{i} \wedge \omega^{i} \wedge \omega^{j} \mid \alpha_{j}^{i} \in \Omega^{*}\left(\mathbb{R}^{5}\right)\right\}$. Hence

$$
\left\{\begin{array}{l}
\omega^{2} \wedge \omega^{3} \in \mathscr{S}_{1} \cap \mathscr{S}^{2} \\
\omega^{2} \wedge \omega^{4} \notin \mathscr{S}_{2}, \omega^{2} \wedge \omega^{4} \notin \mathscr{S}_{1} \cap \mathscr{S}^{2}
\end{array}\right.
$$

Therefore

$$
d \omega^{1} \equiv\left\{\begin{array}{l}
0 \bmod \mathscr{S}_{2}+\left(\mathscr{S}_{1} \cap \mathscr{S}^{2}\right), \quad \text { if } x_{4}=0 \\
x_{4} \omega^{4} \wedge \omega^{2} \bmod \mathscr{S}_{2}+\left(\mathscr{S}_{1} \cap \mathscr{S}^{2}\right), \quad \text { if } x_{4} \neq 0
\end{array}\right.
$$

and hence $\widetilde{S_{3}}$ is

$$
\widetilde{S_{3}}=\left\{\begin{array}{l}
\operatorname{span}\left\{\omega^{1}\right\}, \quad \text { if } x_{4}=0 \\
\{0\}, \quad \text { if } x_{4} \neq 0
\end{array}\right.
$$

Thus we have $S_{3} \neq \widetilde{S_{3}}$ and $S$ does not have a relative polarization by Proposition 3.3.

## 4. The main theorem

Fixing integers $h, m, p_{1}, r \in \mathbb{N}$ with $m \geq p_{1}\binom{h+r-1}{r}$, we take a manifold $M$ of dimension $n=h+p_{1}\binom{h+r}{r}+m$, and consider local coordinates of $M, x, z, z(1), z(k), 1 \leq k \leq r$, in the following way:

$$
\left\{\begin{array}{l}
x:=\left(x_{1}, \ldots, x_{h}\right), \\
z:=\left(z^{1}, \ldots, z^{p_{1}}\right), \\
z(k):=\left(\ldots, z_{\alpha_{1} \cdots \alpha_{k}}^{i}, \ldots\right)_{1 \leq i \leq p_{1}, 1 \leq \alpha_{1}, \ldots, \alpha_{k} \leq h},
\end{array}\right.
$$

where $z_{\alpha_{1} \cdots \alpha_{k}}^{i}, 2 \leq k \leq r$, is symmetric with respect to the subscript $\alpha_{1}, \ldots, \alpha_{k}$. Let $\widetilde{z(r)}$ denote the coordinates $z(r)$ with some $\sigma$ coordinate functions deleted for $\sigma \geqq 0$. We note that the number of elements of the coordinates $z(k)$ and $\widetilde{z(r)}$ are $p_{1}\binom{h+k-1}{k}$ and $p_{1}\binom{h+r-1}{r}-\sigma$.

In Theorem 4.1 below, we prove the following. Under the existence of relative polarizations and the condition on the type and the class of a Pfaffian system, there exist local coordinates $(x, z, z(1), \ldots, z(r-1), \widetilde{z(r)}$, $u_{1}, \ldots, u_{m-p_{1}\binom{h+r-1}{r}+\sigma}$ ) in $M$ such that the Pfaffian system can be transformed locally into the normal form

$$
\left\{\begin{array}{l}
\omega^{i}=d z^{i}-\sum_{\alpha_{1}=1}^{h} z_{\alpha_{1}}^{i} d x_{\alpha_{1}},  \tag{19}\\
\omega_{\alpha_{1}}^{i}=d z_{\alpha_{1}}^{i}-\sum_{\alpha_{2}=1}^{h} z_{\alpha_{1} \alpha_{2}}^{i} d x_{\alpha_{2}}, \\
\vdots \\
\vdots \\
\omega_{\alpha_{1} \cdots \alpha_{r-2}}^{i}=d z_{\alpha_{1} \cdots \alpha_{r-2}}^{i}-\sum_{\alpha_{r-1}=1}^{h} z_{\alpha_{1} \cdots \alpha_{r-1}}^{i} d x_{\alpha_{r-1}}, \\
\omega_{\alpha_{1} \cdots \alpha_{r-1}}^{i}=d z_{\alpha_{1} \cdots \alpha_{r-1}}^{i}-\sum_{\alpha_{r}=1}^{h} F_{\alpha_{1} \cdots \alpha_{r}}^{i}\left(x, \ldots, u_{1}, \ldots\right) d x_{\alpha_{r}}, \\
\quad\left(1 \leq i \leq p_{1}, 1 \leq \alpha_{1}, \ldots, \alpha_{r-1} \leq h\right)
\end{array}\right.
$$

where $F_{\alpha_{1} \ldots \alpha_{r}}^{i}$ is a function on $M$, symmetric with respect to the subscript $\alpha_{1}, \ldots, \alpha_{r}$, and satisfies the condition

$$
\operatorname{rank} \frac{\partial\left(\ldots, F_{\alpha_{1} \cdots \alpha_{r}}^{i}, \ldots\right)}{\partial(\widetilde{z(r))}}=p_{1}\binom{h+r-1}{r}-\sigma
$$

The Pfaffian system (19) is just the Pfaffian system $\Omega\left(\Sigma_{\sigma}^{\left(r, h, p_{1}\right)}\right)$ associated to a system of $r$ th order PDEs in $\mathbb{R}^{h}$ and $\mathbb{R}^{p_{1}}$ of codimension $\sigma$. When $\sigma=0$, it is just the contact system $\Omega^{r}\left(\mathbb{R}^{h}, \mathbb{R}^{p_{1}}\right)$ on $J^{r}\left(\mathbb{R}^{h}, \mathbb{R}^{p_{1}}\right)$.

Theorem 4.1 For $h, m, n, p_{1}, r, \sigma$ as above, let $S$ be a Pfaffian system on $M$. There exist local coordinates $\left(x, z, z(1), \ldots, z(r-1), z(r), u_{1}, \ldots\right.$, $u_{m-p_{1}\binom{h+r-1}{r}+\sigma}$ ) in $M$ such that $S$ can be transformed locally into the normal form (19) if and only if $S$ satisfies the following conditions:
(i) $S$ is a totally regular Pfaffian system of length $r$ with $S_{r}=\{0\}$, that is, there is a decreasing sequence of derived systems

$$
S=S_{0} \supset S_{1} \supset \cdots \supset S_{r-1} \supset S_{r}=\{0\}
$$

(ii) $S$ has a relative polarization of rank $h$,
(iii) the type $\left(p_{0}, \ldots, p_{r+1}\right)$ of $S$ satisfies

$$
p_{i}=\left\{\begin{array}{l}
0, \quad \text { if } i=0, \\
p_{1}\binom{h+i-2}{i-1}, \quad \text { if } 1 \leq i \leq r,
\end{array}\right.
$$

(iv) for each derived system $S_{r-j}, 1 \leq j \leq r-1$, and $S$,

$$
\text { class } S_{r-j}=\left\{\begin{array}{l}
h+p_{1}\binom{h+j}{j}, \quad \text { if } 1 \leq j \leq r-1, \\
h+p_{1}\binom{h+r}{r}-\sigma, \quad \text { if } j=r
\end{array}\right.
$$

Proof. Assume that $S$ admits locally the normal form (19). Then by Example 1 and Example 4, it is easy to see that $S$ satisfies the conditions (i) $\sim(i v)$. Now, assuming $S$ is a Pfaffian system satisfying the conditions (i) $\sim($ (iv), we prove that $S$ can be transformed locally into the normal form (19). From Lemma 3.1 we know that there exist local coordinates $\left(x, y^{(1)}, \ldots, y^{(r)}, u\right)$ in $M$ such that $S$ is generated by the 1 -forms

$$
\left\{\begin{array}{l}
\omega_{(1)}^{i_{1}}=d y_{i_{1}}^{(1)}-\sum_{\alpha=1}^{h} A_{\alpha}^{i_{1}}(1) d x_{\alpha}, \\
\vdots \\
\vdots \\
\omega_{(r)}^{i_{r}}=d y_{i_{r}}^{(r)}-\sum_{\alpha=1}^{h} A_{\alpha}^{i_{r}}(r) d x_{\alpha}, \quad\left(1 \leq i_{1} \leq p_{1}, \ldots, 1 \leq i_{r} \leq p_{r}\right)
\end{array}\right.
$$

where $x:=\left(x_{1}, \ldots, x_{h}\right), y^{(k)}:=\left(y_{1}^{(k)}, \ldots, y_{p_{k}}^{(k)}\right), 1 \leq k \leq r, u:=\left(u_{1}, \ldots, u_{m}\right)$, $h+\sum_{k=1}^{r} p_{k}+m=n$, and $A_{\alpha}^{i_{k}}(k)$ is a function $A_{\alpha}^{i_{k}}(k)=A_{\alpha}^{i_{k}}\left(x, y^{(1)}, \ldots, y^{(k+1)}\right)$.

Let us consider the $(r-1)$ st derived system $S_{r-1}$. According to Lemma 3.2 the exterior derivatives $d \omega_{(1)}^{i_{1}}, 1 \leq i_{1} \leq p_{1}$, of elements of $S_{r-1}$ can be written in the form

$$
d \omega_{(1)}^{i_{1}} \equiv \sum_{\alpha=1}^{h} \sum_{i_{2}=1}^{p_{2}} \frac{\partial A_{\alpha}^{i_{1}}(1)}{\partial y_{i_{2}}^{(2)}} d x_{\alpha} \wedge \omega_{(2)}^{i_{2}} \quad \bmod \mathscr{S}_{r-1}
$$

Thus the condition $\iota_{X} d \omega_{(1)}^{i_{1}} \equiv 0 \bmod \mathscr{S}_{r-1}$ is equivalent to

$$
\sum_{\alpha=1}^{h} \sum_{i_{2}=1}^{p_{2}} \frac{\partial A_{\alpha}^{i_{1}}(1)}{\partial y_{i_{2}}^{(2)}}\left(d x_{\alpha}(X) \omega_{(2)}^{i_{2}}-\omega_{(2)}^{i_{2}}(X) d x_{\alpha}\right)=0
$$

By the linear independence of $\left\{\omega_{(2)}^{i_{2}}, d x_{\alpha}\right\}$ we have

$$
\begin{cases}\sum_{\alpha=1}^{h} \frac{\partial A_{\alpha}^{i_{1}}(1)}{\partial y_{i_{2}}^{(2)}} d x_{\alpha}(X)=0, & 1 \leq i_{1} \leq p_{1}, 1 \leq i_{2} \leq p_{2} \\ \sum_{i_{2}=1}^{p_{2}} \frac{\partial A_{\alpha}^{i_{1}}(1)}{\partial y_{i_{2}}^{(2)}} \omega_{(2)}^{i_{2}}(X)=0, & 1 \leq i_{1} \leq p_{1}, 1 \leq \alpha \leq h\end{cases}
$$

So the class of $S_{r-1}$ is equal to the number of independent equations on the vectors $X \in T M, \omega_{(1)}^{i_{1}}(X)=0,1 \leq i_{1} \leq p_{1}$, and

$$
\left(\begin{array}{c|c}
{ }^{t} A^{1} & \\
\vdots & 0 \\
{ }^{t} A^{p_{1}} & \\
\hline & A^{1} \\
0 & \vdots \\
& A^{p_{1}}
\end{array}\right)\left(\begin{array}{c}
d x_{1}(X) \\
\vdots \\
d x_{h}(X) \\
\hline \omega_{(2)}^{1}(X) \\
\vdots \\
\omega_{(2)}^{p_{2}}(X)
\end{array}\right)=0
$$

where $A^{i_{1}}, 1 \leq i_{1} \leq p_{1}$, is a $h \times p_{2}$ matrix

$$
A^{i_{1}}:=\left(\frac{\partial A_{\alpha_{1}}^{i_{1}}(1)}{\partial y_{i_{2}}^{(2)}}\right)_{\substack{1 \leq \alpha_{1} \leq h \\ 1 \leq i_{2} \leq p_{2}}}
$$

and ${ }^{t} A^{i_{1}}$ is the transposed matrix of $A^{i_{1}}$. By the assumption that class $S_{r-1}=h+p_{1}+p_{1} h$ and $p_{2}=p_{1} h$, we can see that the rank of the coefficient matrix is equal to $h+p_{1} h$. The upper left part of the coefficient matrix is a $p_{1} p_{2} \times h$ matrix, so the rank of the upper left part is less than or equal to $h$. Hence the $p_{1} h$-square matrix ${ }^{t}\left(A^{1} \cdots A^{p_{1}}\right)$ should be nonsingular. Therefore we have

$$
\begin{aligned}
d A_{1}^{1}(1) \wedge \cdots \wedge d A_{h}^{p_{1}}(1) & = \pm \operatorname{det}^{t}\left(A^{1} \cdots A^{p_{1}}\right) d y_{1}^{(2)} \wedge \cdots \wedge d y_{p_{2}}^{(2)} \\
& \neq 0
\end{aligned}
$$

Let $\mathbf{d x}, \mathbf{d y}^{(\mathbf{k})}, 1 \leq k \leq r$, and $\mathbf{d u}$ denote differential forms

$$
\begin{aligned}
& \mathbf{d} \mathbf{x}:=d x_{1} \wedge \cdots \wedge d x_{h}, \quad \mathbf{d} \mathbf{y}^{(\mathbf{k})}:=d y_{1}^{(k)} \wedge \cdots \wedge d y_{p_{k}}^{(k)}, \\
& \mathbf{d u}:=d u_{1} \wedge \cdots \wedge d u_{m}
\end{aligned}
$$

respectively. Since we have

$$
\begin{aligned}
\mathbf{d} \mathbf{x} & \wedge \mathbf{d} \mathbf{y}^{(\mathbf{1})} \wedge d A_{1}^{1}(1) \wedge \cdots \wedge d A_{h}^{p_{1}}(1) \wedge \mathbf{d} \mathbf{y}^{(\mathbf{3})} \wedge \cdots \wedge \mathbf{d} \mathbf{y}^{(\mathbf{r})} \wedge \mathbf{d u} \\
& = \pm \operatorname{det}^{t}\left(A^{1} \cdots A^{p_{1}}\right) \mathbf{d} \mathbf{x} \wedge \mathbf{d} \mathbf{y}^{(\mathbf{1})} \wedge \mathbf{d} \mathbf{y}^{(\mathbf{2})} \wedge \mathbf{d} \mathbf{y}^{(\mathbf{3})} \wedge \cdots \wedge \mathbf{d} \mathbf{y}^{(\mathbf{r})} \wedge \mathbf{d u} \\
& \neq 0
\end{aligned}
$$

the functions $x, y^{(1)}, A_{\alpha_{1}}^{i_{1}}(1)\left(1 \leq i_{1} \leq p_{1}, 1 \leq \alpha_{1} \leq h\right), y^{(3)}, \ldots, y^{(r)}$, and $u$ form local coordinates in $M$. Put the 1-forms $\omega_{(1)}^{i_{1}}$ and the functions $y_{i_{1}}^{(1)}$, $A_{\alpha_{1}}^{i_{1}}(1)$ as $\omega^{i_{1}}:=\omega_{(1)}^{i_{1}}, z^{i_{1}}:=y_{i_{1}}^{(1)}$, and $z_{\alpha_{1}}^{i_{1}}:=A_{\alpha_{1}}^{i_{1}}(1)$. Then we can choose local coordinates $\left(x, z, z(1), y^{(3)}, \ldots, y^{(r)}, u\right)$ in $M$ such that $S_{r-1}$ is locally generated by the 1 -forms

$$
\begin{equation*}
\omega^{i_{1}}=d z^{i_{1}}-\sum_{\alpha_{1}=1}^{h} z_{\alpha_{1}}^{i_{1}} d x_{\alpha_{1}}, \quad 1 \leq i_{1} \leq p_{1} \tag{20}
\end{equation*}
$$

Let us consider the $(r-2)$ nd derived system $S_{r-2}=S_{r-1} \oplus \operatorname{span}\left\{\omega_{(2)}^{i_{2}}\right\}$ in the new coordinates $\left(x, z, z(1), y^{(3)}, \ldots, y^{(r)}, u\right)$ of $M$. Since $A_{\alpha}^{i_{1}}$ is a function of the variables $x, y^{(1)}, y^{(2)}$ on the coordinates $\left(x, y^{(1)}, y^{(2)}, y^{(3)}, \ldots, y^{(r)}, u\right)$ and ${ }^{t}\left(A^{1} \cdots A^{p_{1}}\right)$ is nonsingular, we can see that $y_{i_{2}}^{(2)}=y_{i_{2}}^{(2)}(x, z, z(1))$ on the new coordinates $\left(x, z, z(1), y^{(3)}, \ldots, y^{(r)}, u\right)$ of $M$. Hence the local basis $\left\{\omega_{(2)}^{i_{2}}\right\}$, of any complementary subspace of $S_{r-1}$ in $S_{r-2}$ can be written in
the form

$$
\omega_{(2)}^{i_{2}}=d y_{i_{2}}^{(2)}-\sum_{\alpha=1}^{h} A_{\alpha}^{i_{2}}(2)\left(x, z, z(1), y^{(3)}\right) d x_{\alpha}, \quad 1 \leq i_{2} \leq p_{2}
$$

Note that $d y_{i_{2}}^{(2)}$ is generated by $d x_{\alpha_{1}}, \omega^{i}$, and $d z_{\alpha_{1}}^{i}$, hence $\omega_{(2)}^{i_{2}}$ are expressed as

$$
\left(\begin{array}{c}
\omega_{(2)}^{1} \\
\vdots \\
\omega_{(2)}^{p_{2}}
\end{array}\right)=X_{1}\left(\begin{array}{c}
\omega^{1} \\
\vdots \\
\omega^{p_{1}}
\end{array}\right)+X_{2}\left(\begin{array}{c}
d z_{1}^{1} \\
\vdots \\
d z_{h}^{p_{1}}
\end{array}\right)-R\left(\begin{array}{c}
d x_{1} \\
\vdots \\
d x_{h}
\end{array}\right)
$$

where $X_{1}$ and $X_{2}$ are a $p_{2} \times p_{1}$ matrix and a $p_{2} \times p_{1} h$ matrix

$$
X_{1}:=\left(\frac{\partial y_{i_{2}}^{(2)}}{\partial z^{i}}\right)_{\substack{1 \leq i_{2} \leq p_{2} \\ 1 \leq i \leq p_{1}}}, \quad X_{2}:=\left(\frac{\partial y_{i_{2}}^{(2)}}{\partial z_{\alpha_{1}}^{i}}\right)_{\substack{1 \leq i_{2} \leq p_{2} \\ 1 \leq i \leq p_{1}, 1 \leq \alpha_{1} \leq h}}
$$

respectively, and $R$ is a $p_{2} \times h$ matrix. Since $X_{2}$ is the inverse matrix of ${ }^{t}\left(A^{1} \cdots A^{p_{1}}\right)$, we can replace ${ }^{t}\left(\omega_{(2)}^{1}, \ldots, \omega_{(2)}^{p_{2}}\right)$ by

$$
X_{2}^{-1}\left\{\left(\begin{array}{c}
\omega_{(2)}^{1} \\
\vdots \\
\omega_{(2)}^{p_{2}}
\end{array}\right)-X_{1}\left(\begin{array}{c}
\omega^{1} \\
\vdots \\
\omega^{p_{1}}
\end{array}\right)\right\}
$$

Then we have

$$
\left(\begin{array}{c}
\omega_{(2)}^{1}  \tag{21}\\
\vdots \\
\omega_{(2)}^{p_{2}}
\end{array}\right)=\left(\begin{array}{c}
d z_{1}^{1} \\
\vdots \\
d z_{h}^{p_{1}}
\end{array}\right)-\left(\begin{array}{ccc}
x_{1}^{1} & \cdots & x_{h}^{1} \\
\vdots & & \vdots \\
x_{1}^{p_{2}} & \cdots & x_{h}^{p_{2}}
\end{array}\right)\left(\begin{array}{c}
d x_{1} \\
\vdots \\
d x_{h}
\end{array}\right)
$$

where $\left(x_{\alpha_{2}}^{i_{2}}\right):=X_{2}^{-1} R$. We put

$$
\left\{\begin{array}{l}
i_{2}:=(i-1) h+\alpha_{1} \\
\omega_{\alpha_{1}}^{i}:=\omega_{(2)}^{i_{2}} \\
A_{\alpha_{1} \alpha_{2}}^{i}:=x_{\alpha_{2}}^{i_{2}} . \quad\left(1 \leq i \leq p_{1}, 1 \leq \alpha_{1}, \alpha_{2} \leq h\right)
\end{array}\right.
$$

Then the formula (21) can be written in the form

$$
\left(\begin{array}{c}
\omega_{1}^{1}  \tag{22}\\
\vdots \\
\omega_{h}^{1} \\
\hline \vdots \\
\hline \omega_{1}^{p_{1}} \\
\vdots \\
\omega_{h}^{p_{1}}
\end{array}\right)=\left(\begin{array}{c}
d z_{1}^{1} \\
\vdots \\
d z_{h}^{1} \\
\vdots \\
\frac{d z_{1}^{p_{1}}}{\vdots} \\
d z_{h}^{p_{1}}
\end{array}\right)-\left(\begin{array}{ccc}
A_{11}^{1} & \cdots & A_{1 h}^{1} \\
\vdots & & \vdots \\
A_{h 1}^{1} & \cdots & A_{h h}^{1} \\
\vdots & & \vdots \\
\hline A_{11}^{p_{1}} & \cdots & A_{1 h}^{p_{1}} \\
\vdots & & \vdots \\
A_{h 1}^{p_{1}} & \cdots & A_{h h}^{p_{1}}
\end{array}\right)\left(\begin{array}{c}
d x_{1} \\
\vdots \\
d x_{h}
\end{array}\right)
$$

By Lemma 3.2 and (22) the exterior derivative $d \omega^{i}$ can be written

$$
\begin{aligned}
d \omega^{i} & \equiv \sum_{\alpha_{1}=1}^{h} f_{\alpha_{1}}^{i} d x_{\alpha_{1}} \wedge \omega_{\alpha_{1}}^{i} \\
& \equiv \sum_{\alpha_{1}=1}^{h} f_{\alpha_{1}}^{i} d x_{\alpha_{1}} \wedge\left(d z_{\alpha_{1}}^{i}-\sum_{\alpha_{2}=1}^{h} A_{\alpha_{1} \alpha_{2}}^{i} d x_{\alpha_{2}}\right) \quad \bmod \mathscr{S}_{r-1}
\end{aligned}
$$

where $f_{\alpha_{1}}^{i} \in \Omega^{0}(M)$. Comparing the coefficients between the formulae above and the exterior derivatives of (20), we have

$$
\begin{equation*}
A_{\alpha_{1} \alpha_{2}}^{i}-A_{\alpha_{2} \alpha_{1}}^{i}=0 . \quad\left(1 \leq i \leq p_{1}, 1 \leq \alpha_{1}, \alpha_{2} \leq h\right) \tag{23}
\end{equation*}
$$

Therefore $S_{r-2}$ is locally generated by the 1 -forms

$$
\begin{cases}\omega^{i}=d z^{i}-\sum_{\alpha_{1}=1}^{h} z_{\alpha_{1}}^{i} d x_{\alpha_{1}}, &  \tag{24}\\ \omega_{\alpha_{1}}^{i}=d z_{\alpha_{1}}^{i}-\sum_{\alpha_{2}=1}^{h} A_{\alpha_{1} \alpha_{2}}^{i} d x_{\alpha_{2}} & \text { with } A_{\alpha_{1} \alpha_{2}}^{i}=A_{\alpha_{2} \alpha_{1}}^{i}, \\ & \left(1 \leq i \leq p_{1}, 1 \leq \alpha_{1} \leq h\right)\end{cases}
$$

where $A_{\alpha_{1} \alpha_{2}}^{i}$ is a function $A_{\alpha_{1} \alpha_{2}}^{i}=A_{\alpha_{1} \alpha_{2}}^{i}\left(x, z, z(1), y^{(3)}\right)$.
Let us show that the functions $x, z, z(1), A_{\alpha_{1} \alpha_{2}}^{i}\left(1 \leq i \leq p_{1}\right.$, $\left.1 \leq \alpha_{1}, \alpha_{2} \leq h\right), y^{(4)}, \ldots, y^{(r)}$, and $u$ form local coordinates of $M$. From (24) and the linear independence of $\left\{d x_{\alpha}, \omega_{(3)}^{i_{3}}\right\}$ the condition $\iota_{X} d \omega_{\alpha_{1}}^{i} \equiv 0 \bmod$ $\mathscr{S}_{r-2}$ is equivalent to

$$
\begin{cases}\sum_{\alpha_{2}=1}^{h} \frac{\partial A_{\alpha_{1} \alpha_{2}}^{i}}{\partial y_{i_{3}}^{(3)}} d x_{\alpha_{2}}(X)=0, & 1 \leq i_{3} \leq p_{3} \\ \sum_{i_{3}=1}^{p_{3}} \frac{\partial A_{\alpha_{1} \alpha_{2}}^{i}}{\partial y_{i_{3}}^{(3)}} \omega_{(3)}^{i_{3}}(X)=0, & 1 \leq \alpha_{2} \leq h\end{cases}
$$

Hence the class of $S_{r-2}$ is equal to the number of independent equations on the vectors $X \in T M, \omega^{i}(X)=\omega_{\alpha_{1}}^{i}(X)=0\left(1 \leq i \leq p_{1}, 1 \leq \alpha_{1} \leq h\right)$, and

$$
\left(\begin{array}{c|c}
{ }^{t} A_{1}^{1} & \\
\vdots & 0 \\
{ }^{t} A_{h}^{p_{1}} & \\
\hline & A_{1}^{1} \\
0 & \vdots \\
& A_{h}^{p_{1}}
\end{array}\right)\left(\begin{array}{c}
d x_{1}(X) \\
\vdots \\
d x_{h}(X) \\
\hline \omega_{(3)}^{1}(X) \\
\vdots \\
\omega_{(3)}^{p_{3}}(X)
\end{array}\right)=0
$$

where $A_{\alpha_{1}}^{i}$ is a $h \times p_{3}$ matrix

$$
A_{\alpha_{1}}^{i}:=\left(\frac{\partial A_{\alpha_{1} \alpha_{2}}^{i}}{\partial y_{i_{3}}^{(3)}}\right)_{\substack{1 \leq \alpha_{2} \leq h \\ 1 \leq i_{3} \leq p_{3}}}
$$

By the assumption that class $S_{r-2}=p_{1}\binom{h+1}{1}+h+p_{1}\binom{h+1}{2}$ and $p_{3}=p_{1}\binom{h+1}{2}$, we can see that the rank of the coefficient matrix is equal to $h+p_{1}\binom{h+1}{2}$. The upper left part of the coefficient matrix is a $p_{1} h p_{3} \times h$ matrix, so the rank of the upper left part is less than or equal to $h$. Hence we should be

$$
\operatorname{rank}^{t}\left(A_{1}^{1} \cdots A_{h}^{p_{1}}\right)=p_{1}\binom{h+1}{2}
$$

Let ${ }^{t}\left(\widetilde{A_{1}^{1} \cdots A_{h}^{p_{1}}}\right)$ be any matrix consisting of $p_{3}$ independent rows of $p_{1} h^{2} \times p_{3}$ matrix ${ }^{t}\left(A_{1}^{1} \cdots A_{h}^{p_{1}}\right)$. Since $p_{3}=p_{1}\binom{h+1}{2}$, we can see that the $p_{1}\binom{h+1}{2}$-square matrix ${ }^{t}\left(A_{1}^{1} \cdots A_{h}^{p_{1}}\right)$ is nonsingular. Hence, for all the functions $A_{\alpha_{1} \alpha_{2}}^{i}$ with $A_{\alpha_{1} \alpha_{2}}^{i}=A_{\alpha_{2} \alpha_{1}}^{i}\left(1 \leq i \leq p_{1}, 1 \leq \alpha_{1}, \alpha_{2} \leq h\right)$, we have

$$
\begin{aligned}
d A_{11}^{1} \wedge \cdots \wedge d A_{h h}^{p_{1}} & = \pm \operatorname{det}^{t}\left(\widetilde{A_{1}^{1} \cdots A_{h}^{p_{1}}}\right) \operatorname{dy}^{(\mathbf{3})} \\
& \neq 0 .
\end{aligned}
$$

Let $\mathbf{d z}$ and $\mathbf{d z}(\mathbf{1})$ denote differential forms

$$
\mathrm{dz}:=d z^{1} \wedge \cdots \wedge d z^{p_{1}} \text { and } \mathbf{d z}(\mathbf{1}):=d z_{1}^{1} \wedge \cdots \wedge d z_{\alpha_{1}}^{i} \wedge \cdots \wedge d z_{h}^{p_{1}}
$$

Since we have

$$
\begin{aligned}
\mathbf{d} \mathbf{x} & \wedge \mathbf{d z} \wedge \mathbf{d z}(\mathbf{1}) \wedge d A_{11}^{1}(1) \wedge \cdots \wedge d A_{h h}^{p_{1}}(1) \wedge \mathbf{d} \mathbf{y}^{(\mathbf{4})} \wedge \cdots \wedge \mathbf{d} \mathbf{y}^{(\mathbf{r})} \wedge \mathbf{d u} \\
& = \pm \operatorname{det}^{t}\left(A_{1}^{1 \times \cdots A_{h}^{p_{1}}}\right) \mathbf{d x} \wedge \mathbf{d z} \wedge \mathbf{d z}(\mathbf{1}) \wedge \mathbf{d} \mathbf{y}^{(\mathbf{3})} \wedge \cdots \wedge \mathbf{d} \mathbf{y}^{(\mathbf{r})} \wedge \mathbf{d u} \\
& \neq 0
\end{aligned}
$$

the functions $x, z, z(1), A_{\alpha_{1} \alpha_{2}}^{i}\left(1 \leq i \leq p_{1}, 1 \leq \alpha_{1}, \alpha_{2} \leq h\right), y^{(4)}, \ldots, y^{(r)}$, and $u$ form local coordinates of $M$. Put the functions $A_{\alpha_{1} \alpha_{2}}^{i}$ as $z_{\alpha_{1} \alpha_{2}}^{i}:=$ $A_{\alpha_{1} \alpha_{2}}^{i}$. Then we can choose local coordinates $\left(x, z, z(1), z(2), y^{(4)}, \ldots, y^{(r)}, u\right)$ in $M$ such that $S_{r-2}$ is locally generated by the 1-forms

$$
\begin{cases}\omega^{i}=d z^{i}-\sum_{\alpha_{1}=1}^{h} z_{\alpha_{1}}^{i} d x_{\alpha_{1}}, \\ \omega_{\alpha_{1}}^{i}=d z_{\alpha_{1}}^{i}-\sum_{\alpha_{2}=1}^{h} z_{\alpha_{1} \alpha_{2}}^{i} d x_{\alpha_{2}} \quad & \text { with } z_{\alpha_{1} \alpha_{2}}^{i}=z_{\alpha_{2} \alpha_{1}}^{i} \\ & \left(1 \leq i \leq p_{1}, 1 \leq \alpha_{1} \leq h\right)\end{cases}
$$

After $r-3$ reiteration of the same manipulation, we can get local coordinates $(x, z, z(1), \ldots, z(r-1), u)$ in $M$ such that the first derived system $S_{1}$ is locally generated by the 1 -forms

$$
\left\{\begin{array}{c}
\omega^{i}=d z^{i}-\sum_{\alpha_{1}=1}^{h} z_{\alpha_{1}}^{i} d x_{\alpha_{1}}  \tag{25}\\
\vdots \\
\vdots \\
\omega_{\alpha_{1} \cdots \alpha_{r-2}}^{i}=d z_{\alpha_{1} \cdots \alpha_{r-2}}^{i}-\sum_{\alpha_{r-1}=1}^{h} z_{\alpha_{1} \cdots \alpha_{r-1}}^{i} d x_{\alpha_{r-1}} \\
\\
\quad\left(1 \leq i \leq p_{1}, 1 \leq \alpha_{1}, \ldots, \alpha_{r-1} \leq h\right)
\end{array}\right.
$$

where the coordinates $z_{\alpha_{1} \alpha_{2}}^{i}, \ldots, z_{\alpha_{1} \cdots \alpha_{r-1}}^{i}$ are symmetric with respect to the subscript $\alpha_{1}, \ldots, \alpha_{r-1}$.

Let us consider the system $S=S_{1} \oplus \operatorname{span}\left\{\omega_{(r)}^{i_{r}}\right\}$ in the new coordinates $(x, z, z(1), \ldots, z(r-1), u)$ of $M$. Since $A_{\alpha_{1} \cdots \alpha_{r-1}}^{i}$ is a function of the variables $x, y^{(1)}, \ldots, y^{(r-1)}, y^{(r)}$ on the coordinates $\left(x, y^{(1)}, \ldots, y^{(r-1)}, y^{(r)}, u\right)$ and the matrix ${ }^{t}\left(\cdots A_{\alpha_{1} \cdots \alpha_{r-2}}^{i} \cdots\right)$ is nonsingular, we can see that $y_{i_{r}}^{(r)}=$ $y_{i_{r}}^{(r)}(x, z, z(1), \ldots, z(r-1))$ on the coordinates $(x, z, z(1), \ldots, z(r-1), u)$
of $M$. Hence the local basis $\left\{\omega_{(r)}^{i_{r}}\right\}$, of any complementary subspace of $S_{1}$ in $S$ can be written in the form

$$
\omega_{(r)}^{i_{r}}=d y_{i_{r}}^{(r)}-\sum_{\alpha=1}^{h} A_{\alpha}^{i_{r}}(r) d x_{\alpha}, \quad 1 \leq i_{r} \leq p_{r}
$$

where $A_{\alpha}^{i_{r}}(r)=A_{\alpha}^{i_{r}}(x, z, z(1), \ldots, z(r-1), u)$. Note that $d y_{i_{r}}^{(r)}$ is generated by $d x_{\alpha_{1}}, \omega^{i}, \omega_{\alpha_{1} \cdots \alpha_{k}}^{i}, 1 \leq k \leq r-2$, and $z_{\alpha_{1} \cdots \alpha_{r-1}}^{i}$, hence the 1 -forms $\omega_{(r)}^{i_{r}}$ are expressed as

$$
\begin{aligned}
\left(\begin{array}{c}
\omega_{(r)}^{1} \\
\vdots \\
\omega_{(r)}^{p_{r}}
\end{array}\right)= & X_{1}\left(\begin{array}{c}
\omega^{1} \\
\vdots \\
\omega^{p_{1}}
\end{array}\right)+\cdots+X_{r-1}\left(\begin{array}{c}
\omega_{1 \cdots 1}^{1} \\
\vdots \\
\omega_{h \cdots h}^{p_{1}}
\end{array}\right) \\
& +X_{r}\left(\begin{array}{c}
d z_{1 \cdots 1}^{1} \\
\vdots \\
d z_{h \cdots h}^{p_{1}}
\end{array}\right)-R\left(\begin{array}{c}
d x_{1} \\
\vdots \\
d x_{h}
\end{array}\right)
\end{aligned}
$$

where $X_{1}$ and $X_{k}(2 \leq k \leq r)$, are a $p_{r} \times p_{1}$ matrix and a $p_{r} \times p_{k}$ matrix

$$
X_{1}:=\left(\frac{\partial y_{i_{r}}^{(r)}}{\partial z^{i}}\right)_{\substack{1 \leq i_{r} \leq p_{r} \\ 1 \leq i \leq p_{1}}}, \quad X_{k}:=\left(\frac{\partial y_{i_{r}}^{(r)}}{\partial z_{\alpha_{1} \cdots \alpha_{k-1}}^{i}}\right)_{\substack{1 \leq i_{r} \leq p_{r} \\ 1 \leq i \leq p_{1}, 1 \leq \alpha_{1}, \ldots, \alpha_{k-1} \leq h}}
$$

and $R$ is a $p_{r} \times h$ matrix. Since $X_{r}$ is nonsingular, we can replace ${ }^{t}\left(\omega_{(r)}^{1} \cdots \omega_{(r)}^{p_{r}}\right)$ by

$$
X_{r}^{-1}\left\{\left(\begin{array}{c}
\omega_{(r)}^{1} \\
\vdots \\
\omega_{(r)}^{p_{r}}
\end{array}\right)-X_{1}\left(\begin{array}{c}
\omega^{1} \\
\vdots \\
\omega^{p_{1}}
\end{array}\right)-\cdots-X_{r-1}\left(\begin{array}{c}
\omega_{1 \cdots 1}^{1} \\
\vdots \\
\omega_{h \cdots h}^{p_{1}}
\end{array}\right)\right\}
$$

Then we have

$$
\left(\begin{array}{c}
\omega_{(r)}^{1}  \tag{26}\\
\vdots \\
\omega_{(r)}^{p_{r}}
\end{array}\right)=\left(\begin{array}{c}
d z_{1 \cdots 1}^{1} \\
\vdots \\
d z_{h \cdots h}^{p_{1}}
\end{array}\right)-\left(\begin{array}{ccc}
x_{1}^{1} & \cdots & x_{h}^{1} \\
\vdots & & \vdots \\
x_{1}^{p_{r}} & \cdots & x_{h}^{p_{r}}
\end{array}\right)\left(\begin{array}{c}
d x_{1} \\
\vdots \\
d x_{h}
\end{array}\right)
$$

where $\left(x_{\alpha_{r}}^{i_{r}}\right):=X_{r}^{-1} R$. We put

$$
\left\{\begin{array}{l}
i_{r}:=(i-1)\binom{h+r-2}{r-1}+\sum_{k_{1}=1}^{\alpha_{1}-1}\binom{h+r-1-k_{1}}{r-1}+\cdots \\
\\
\quad+\sum_{k_{r-3}=1}^{\alpha_{r}-3-1}\left({ }_{2}^{h+2-k_{r-3}}\right)+\sum_{k_{r-2}=1}^{\alpha_{r-2}-2}\left(h-k_{r-2}\right)+\alpha_{r-1}, \\
\omega_{\alpha_{1} \ldots \alpha_{r-1}}^{i}:=\omega_{r}, \quad\left(1 \leq i \leq p_{1}, 1 \leq \alpha_{1}, \ldots, \alpha_{r} \leq h\right) \\
A_{\alpha_{1} \cdots \alpha_{r}}^{i}:=x_{\alpha_{\alpha_{r}}}^{i_{r}} . \quad
\end{array}\right.
$$

Then the formula (26) can be written in the form

$$
\begin{equation*}
\omega_{\alpha_{1} \cdots \alpha_{r-1}}^{i}=d z_{\alpha_{1} \cdots \alpha_{r-1}}^{i}-\sum_{\alpha_{r}=1}^{h} A_{\alpha_{1} \cdots \alpha_{r}}^{i}(x, \ldots, z(r-1), u) d x_{\alpha_{r}} . \tag{27}
\end{equation*}
$$

Let us show that the functions $A_{\alpha_{1} \ldots \alpha_{r}}^{i}$ are symmetric with respect to the subscript $\alpha_{1}, \ldots, \alpha_{r}$. By Lemma 3.2 and (27) the exterior derivative $d \omega_{\alpha_{1} \cdots \alpha_{r-2}}^{i}$ can be written

$$
\begin{aligned}
d \omega_{\alpha_{1} \cdots \alpha_{r-2}}^{i} & \equiv \sum_{\alpha_{r-1}=1}^{h} f_{\alpha_{1} \cdots \alpha_{r-1}}^{i} d x_{\alpha_{r-1}} \wedge \omega_{\alpha_{1} \cdots \alpha_{r-1}}^{i} \\
\equiv & \sum_{\alpha_{r-1}=1}^{h} f_{\alpha_{1} \cdots \alpha_{r-1}}^{i} d x_{\alpha_{r-1}} \\
& \wedge\left(d z_{\alpha_{1} \cdots \alpha_{r-1}}^{i}-\sum_{\alpha_{r}=1}^{h} A_{\alpha_{1} \cdots \alpha_{r}}^{i} d x_{\alpha_{r}}\right) \quad \bmod \mathscr{S}
\end{aligned}
$$

where $f_{\alpha_{1} \cdots \alpha_{r-1}}^{i} \in \Omega^{0}(M)$. Comparing the coefficients between the formulae above and the exterior derivatives of (25), we can see that

$$
A_{\alpha_{1} \cdots \alpha_{r-1} \alpha_{r}}^{i}-A_{\alpha_{1} \cdots \alpha_{r} \alpha_{r-1}}^{i}=0 . \quad\left(1 \leq i \leq p_{1}, 1 \leq \alpha_{1}, \ldots, \alpha_{r} \leq h\right)
$$

Note that the 1 -forms $\omega_{\alpha_{1} \cdots \alpha_{r-1}}^{i}$ are symmetric with respect to the subscript $\alpha_{1}, \ldots, \alpha_{r-1}$, hence the functions $A_{\alpha_{1} \cdots \alpha_{r}}^{i}$ are also symmetric. Therefore the system $S$ is locally generated by the 1 -forms (25) and

$$
\begin{aligned}
& \omega_{\alpha_{1} \cdots \alpha_{r-1}}^{i}=d z_{\alpha_{1} \cdots \alpha_{r-1}}^{i}-\sum_{\alpha_{r}=1}^{h} A_{\alpha_{1} \cdots \alpha_{r}}^{i} d x_{\alpha_{r}}, \\
&\left(1 \leq i \leq p_{1}, 1 \leq \alpha_{1}, \ldots, \alpha_{r} \leq h\right)
\end{aligned}
$$

where $A_{\alpha_{1} \cdots \alpha_{r}}^{i}$ is a function on $M$ and symmetric with respect to the sub-
script $\alpha_{1}, \ldots, \alpha_{r}$.
By the computation of $\iota_{X} d \omega_{\alpha_{1} \cdots \alpha_{r-1}}^{i} \equiv 0 \bmod \mathscr{S}$, it is easy to see that the class of $S$ is equal to the number of independent equations on the vectors $X \in T M, \omega^{i}(X)=\cdots=\omega_{\alpha_{1} \cdots \alpha_{r-1}}^{i}(X)=0\left(1 \leq i \leq p_{1}, 1 \leq \alpha_{1}, \ldots, \alpha_{r-1} \leq h\right)$, and

$$
\left(\begin{array}{c|c}
{ }^{t} A_{1 \cdots 1}^{1} & \\
\vdots & 0 \\
{ }^{t} A_{h \cdots h}^{p_{1}} & \\
\hline & A_{1 \cdots 1}^{1} \\
* & \vdots \\
& A_{h \cdots h}^{p_{1}}
\end{array}\right)\left(\begin{array}{c}
d x_{1}(X) \\
\vdots \\
d x_{h}(X) \\
\hline d u_{1}(X) \\
\vdots \\
d u_{m}(X)
\end{array}\right)=0
$$

where $A_{\alpha_{1} \cdots \alpha_{r-1}}^{i}$ is an $h \times m$ matrix

$$
A_{\alpha_{1} \cdots \alpha_{r-1}}^{i}:=\left(\frac{\partial A_{\alpha_{1} \cdots \alpha_{r-1} \alpha_{r}}^{i}}{\partial u_{k}}\right)_{\substack{1 \leq \alpha_{r} \leq h \\ 1 \leq k \leq m}}
$$

By the assumption that class $S=p_{1}\binom{h+r-1}{r-1}+h+p_{1}\binom{h+r-1}{r}-\sigma$ and $\operatorname{rank} S=p_{1}\binom{h+r-1}{r-1}$, we can see that the rank of the coefficient matrix is equal to $h+p_{1}\binom{h+r-1}{r}-\sigma$. The upper left part of the coefficient matrix is a $p_{1}\binom{h+r-1}{r} m \times h$ matrix, so we have

$$
\begin{equation*}
\operatorname{rank}^{t}\left(A_{1 \cdots 1}^{1} \cdots A_{\alpha_{1} \cdots \alpha_{r}}^{i} \cdots A_{h \cdots h}^{p_{1}}\right)=p_{1}\binom{h+r-1}{r}-\sigma . \tag{28}
\end{equation*}
$$

Let $\mathbf{A}$ be any matrix consisting of the $p_{1}\binom{h+r-1}{r}-\sigma$ independent rows of the $p_{1}\binom{h+r-1}{r} h \times m$ matrix ${ }^{t}\left(A_{1 \cdots 1}^{1} \cdots A_{\alpha_{1} \cdots \alpha_{r}}^{i} \cdots A_{h \cdots h}^{p_{1}}\right)$. Let $d A_{1 \cdots 1}^{1} \wedge \cdots \wedge d A_{h \cdots h}^{p_{1}}$ be $p_{1}\binom{h+r-1}{r}-\sigma$ independent differential forms excluding $\sigma$ 1-forms from $d A_{1 \cdots 1}^{1} \wedge \cdots \wedge d A_{\alpha_{1} \cdots \alpha_{r}}^{i} \wedge \cdots \wedge d A_{h \cdots h}^{p_{1}}$. Then we can see that the $\left\{p_{1}\binom{h+r-1}{r}-\sigma\right\}$-square matrix $\mathbf{A}$ is nonsingular. Hence, for all the functions $A_{\alpha_{1} \cdots \alpha_{r}}^{i}\left(1 \leq i \leq p_{1}, 1 \leq \alpha_{1}, \ldots, \alpha_{r} \leq h\right)$, we have

$$
\begin{aligned}
d A_{1 \ldots 1}^{1} \widetilde{\wedge \cdots \wedge} d A_{h \cdots h}^{p_{1}} & = \pm \operatorname{det} \mathbf{A} d u_{m-p_{1}\binom{h+r-1}{r}+\sigma+1} \wedge \cdots \wedge d u_{m} \\
& \neq 0 .
\end{aligned}
$$

Let $\widetilde{\mathbf{d u}}$ and $\mathbf{d u}$ denote differential forms

$$
\left\{\begin{array}{l}
\widetilde{\mathbf{d u}}:=d u_{m-p_{1}\binom{h+r-1}{r}+\sigma+1} \wedge \cdots \wedge d u_{m} \\
\mathbf{d u}:=d u_{1} \wedge \cdots \wedge d u_{m-p_{1}\binom{h+r-1}{r}+\sigma}
\end{array}\right.
$$

Let $\widetilde{A(r)}$ be $p_{1}\binom{h+r-1}{r}-\sigma$ independent functions excluding $\sigma$ functions from $\left(\ldots, A_{\alpha_{1} \cdots \alpha_{r}}^{i}, \ldots\right)$. Since we have

$$
\begin{aligned}
\mathbf{d} \mathbf{x} & \wedge \mathbf{d z} \wedge \mathbf{d z}(\mathbf{1}) \wedge \cdots \wedge \mathbf{d z}(\mathbf{r}-\mathbf{1}) \wedge d A_{1 \cdots 1}^{1} \widetilde{\wedge \cdots \wedge} d A_{h \cdots h}^{p_{1}} \wedge \mathbf{d u} \\
& = \pm \operatorname{det} \mathbf{A} \mathbf{d x} \wedge \mathbf{d z} \wedge \mathbf{d z}(\mathbf{1}) \wedge \cdots \mathbf{d z}(\mathbf{r}-\mathbf{1}) \wedge \widetilde{\mathbf{d u}} \wedge \mathbf{d u} \\
& \neq 0
\end{aligned}
$$

the functions $x, z, \ldots, z(r-1), \widetilde{A(r)}, u_{1}, \ldots, u_{m-p_{1}\binom{h+r-1}{r}+\sigma}$ form local coordinates in $M$. Therefore we can get local coordinates $(x, z, z(1), \ldots, z(r-1)$, $\left.\widetilde{A(r)}, u_{1}, \ldots, u_{m-p_{1}\binom{h+r-1}{r}+\sigma}\right)$ in $M$ such that $S$ is locally generated by the 1-forms (25) and

$$
\begin{array}{r}
\omega_{\alpha_{1} \cdots \alpha_{r-1}}^{i}=d z_{\alpha_{1} \cdots \alpha_{r-1}}^{i}-\sum_{\alpha_{r}=1}^{h} A_{\alpha_{1} \cdots \alpha_{r}}^{i}\left(x, \ldots, u_{m-p_{1}\binom{h+r-1}{r}+\sigma}\right) d x_{\alpha_{r}} \\
\left(1 \leq i \leq p_{1}, 1 \leq \alpha_{1}, \ldots, \alpha_{r-1} \leq h\right)
\end{array}
$$

By (28), the function $A_{\alpha_{1} \cdots \alpha_{r}}^{i}$ satisfies

$$
\operatorname{rank} \frac{\partial\left(\ldots, A_{\alpha_{1} \cdots \alpha_{r}}^{i}, \ldots\right)}{\partial(\widetilde{A(r)})}=p_{1}\binom{h+r-1}{r}-\sigma
$$

This completes the proof of Theorem 4.1.
Corollary 4.2 Let $S$ be a Pfaffian system on $M$. Then there exist local coordinates $\left(x, z, z(1), \ldots, z(k-1), \widetilde{z(k)}, y_{1}^{(k+1)}, \ldots, y_{p_{1}\binom{h+k-2}{k-1}+\sigma}^{(k+1)}, y^{(k+2)}, \ldots\right.$, $\left.y^{(r)}, u\right)$ in $M$ such that the $(r-k)$ th derived system $S_{r-k}$ can be transformed locally into the Pfaffian sysytem $\Omega\left(\Sigma_{\sigma}^{\left(k, h, p_{1}\right)}\right)$ associated to a system of $k$ th order PDEs in $\mathbb{R}^{h}$ and $\mathbb{R}^{p_{1}}$ of codimension $\sigma$, if and only if $S$ satisfies the following conditions:
(i) $S$ is a totally regular Pfaffian system of length $r$ with $S_{r}=\{0\}$,
(ii) $S$ has a relative polarization of rank $h$,
(iii) the type $\left(p_{0}, \ldots, p_{r+1}\right)$ of $S$ satisfies

$$
p_{i}=\left\{\begin{array}{l}
0, \quad \text { if } i=0 \\
p_{1}\binom{h+i-2}{i-1}, \quad \text { if } 1 \leq i \leq k+1
\end{array}\right.
$$

(iv) for each derived system $S_{r-j}, 1 \leq j \leq k$,

$$
\operatorname{class} S_{r-j}=\left\{\begin{array}{l}
h+p_{1}\binom{h+j}{j}, \quad \text { if } 1 \leq j \leq k-1, \\
h+p_{1}\binom{h+k}{k}-\sigma, \quad \text { if } j=k
\end{array}\right.
$$

Proof. Assume that the $(r-k)$ th derived system $S_{r-k}$ of $S$ admits $\Omega\left(\Sigma_{\sigma}^{\left(k, h, p_{1}\right)}\right)$. Then by Example 1 and Example 4, it is easy to see that $S$ satisfies the conditions (i) $\sim(i v)$. Now, assuming $S$ is a Pfaffian system satisfying the conditions (i) $\sim(i v)$, we prove that $S_{r-k}$ can be transformed locally into the normal form $\Omega\left(\Sigma_{\sigma}^{\left(k, h, p_{1}\right)}\right)$. From Lemma 3.1 we know that there exist local coordinates $\left(x, y^{(1)}, \ldots, y^{(r)}, u\right)$ in $M$ such that $S$ is generated by the 1 -forms (14). Applying Theorem 4.1 to the $(r-k+1)$ st derived system $S_{r-k+1}$, there exist local coordinates $(x, z, z(1), \ldots, z(k-1)$, $\left.y^{(k+1)}, \ldots, y^{(r)}, u\right)$ in $M$ such that $S_{r-k+1}$ is generated by the 1 -forms

$$
\left\{\begin{array}{l}
\omega^{i}=d z^{i}-\sum_{\alpha_{1}=1}^{h} z_{\alpha_{1}}^{i} d x_{\alpha_{1}}, \\
\vdots \\
\vdots \\
\omega_{\alpha_{1} \cdots \alpha_{k-2}}^{i}=d z_{\alpha_{1} \cdots \alpha_{k-2}}^{i}-\sum_{\alpha_{k-1}=1}^{h} z_{\alpha_{1} \cdots \alpha_{k-1}}^{i} d x_{\alpha_{k-1}} \\
\\
\\
\quad\left(1 \leq i \leq p_{1}, 1 \leq \alpha_{1}, \ldots, \alpha_{k-2} \leq h\right)
\end{array}\right.
$$

where the coordinates $z_{\alpha_{1} \alpha_{2}}^{i}, \ldots, z_{\alpha_{1} \cdots \alpha_{k-1}}^{i}$ are symmetric with respect to the subscript $\alpha_{1}, \ldots, \alpha_{k-1}$. Let us consider the system $S_{r-k}=S_{r-k+1} \oplus$ $\operatorname{span}\left\{\omega_{(k)}^{i_{k}}\right\}$ in the new coordinates $\left(x, z, z(1), \ldots, z(k-1), y^{(k+1)}, \ldots, y^{(r)}, u\right)$ of $M$. The proof is completely analogous to that of the construction of $S=$ $S_{1} \oplus \operatorname{span}\left\{\omega_{(r)}^{i_{r}}\right\}$ on Theorem 4.1 (pp. 838-842).
Example 7 We consider Example 5 in Section 3 again. Applying Corollary 4.2 to $S_{2}=\operatorname{span}\left\{\omega^{1}, \omega^{2}\right\}$, we have coordinates $\left(x_{1}, x_{2}, z^{1}, z^{2}, \widetilde{z^{3}}, \widetilde{z^{4}}, y_{1}^{(3)}\right)$ in $\mathbb{R}^{7}$ such that $S_{2}$ can be transformed into the Pfaffian system $\Omega\left(\Sigma_{2}^{(1,2,2)}\right)$, which is a Pfaffian system associated to a system of first order PDEs in $\mathbb{R}^{2}$
and $\mathbb{R}^{2}$ of codimension 2 :

$$
S_{2}=\left\{\begin{array}{c}
\omega^{1}=d z^{1}-F_{1}^{1}\left(x_{1}, x_{2}, z^{1}, z^{2}, \widetilde{z^{3}}, \widetilde{z^{4}}\right) d x_{1} \\
\\
\quad-F_{2}^{1}\left(x_{1}, x_{2}, z^{1}, z^{2}, \widetilde{z^{3}}, \widetilde{z^{4}}\right) d x_{2} \\
\omega^{2}= \\
\\
\quad \\
-F_{2}^{2}-F_{1}^{2}\left(x_{1}, x_{2}, x_{2}, z^{1}, z^{2}, \widetilde{z^{2}}, \widetilde{z^{3}}, \widetilde{z^{4}}\right) d x_{2}
\end{array}\right.
$$

with

$$
\begin{equation*}
\operatorname{rank} \frac{\partial\left(F_{1}^{1}, F_{2}^{1}, F_{1}^{2}, F_{2}^{2}\right)}{\partial\left(\widetilde{z^{3}}, \widetilde{z^{4}}\right)}=2 \tag{29}
\end{equation*}
$$

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