# SOLUTION OF A PROBLEM ABOUT SYMMETRIC FUNCTIONS 

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> ABSTRACT. Let $a>b>c$ be positive integers with $(a, b, c)=1$. Then the field $\mathbf{Q}\left(X^{a}+Y^{a}, X^{b}+Y^{b}, X^{c}+Y^{c}\right)$ is the field of all symmetric rational functions in $X, Y$ over $\mathbf{Q}$. This solves a conjecture made by Mead and Stein.

Let $X, Y$ be independent indeterminates and, for a positive integer $m$, let

$$
N_{m}=N_{m}(X, Y)=X^{m}+Y^{m}
$$

be the Newton symmetric power of order $m$. In the recent paper [2], the authors calculate the degree $\left[S: \mathbf{Q}\left(N_{a}, N_{b}\right)\right.$ ], where $S$ is the field of all symmetric rational functions in $X, Y$ with rational coefficients. They also raise a few conjectures on the fields $\mathbf{Q}\left(N_{a}, N_{b}, N_{c}\right)$. The purpose of the present paper is to prove their main Conjecture 1, which we state as the following.

Theorem 1. If $a>b>c$ are distinct positive integers with $(a, b, c)=1$, then the functions $N_{a}, N_{b}, N_{c}$ generate $S$ over $\mathbf{Q}$.

In [2] the authors also state a conjecture (see Conjecture 4 of Section 3) about the minimal degree $d$ of a polynomial relation satisfied by $N_{a}, N_{b}, N_{c}$ where, by degree of a monomial $N_{a}^{i} N_{b}^{j} N_{c}^{k}$, they mean $a i+b j+c k$. At the end of the paper we shall show how our Theorem 1 implies a strong form of their conjecture, namely,

Theorem 2. Assumptions being as in Theorem 1, we have $d=a b c / 2$ if $a b c$ is even and $d=(a-1) b c / 2$ otherwise.

Proof of Theorem 1. To start with, we show that it is sufficient to prove the analogous statement with $\mathbf{Q}$ replaced by its algebraic closure

[^0]$\overline{\mathbf{Q}}$. In fact, note first that, as we shall show below, we have
\[

$$
\begin{equation*}
\left[S: \mathbf{Q}\left(N_{a}, N_{b}\right)\right]=\left[\overline{\mathbf{Q}} S: \overline{\mathbf{Q}}\left(N_{a}, N_{b}\right)\right] \tag{1}
\end{equation*}
$$

\]

Then, assuming $\overline{\mathbf{Q}} S=\overline{\mathbf{Q}}\left(N_{a}, N_{b}, N_{c}\right)$ and recalling the easy fact that $S / \mathbf{Q}\left(N_{a}, N_{b}\right)$ is finite, we find

$$
\begin{aligned}
{\left[S: \mathbf{Q}\left(N_{a}, N_{b}\right)\right] } & =\left[S: \mathbf{Q}\left(N_{a}, N_{b}, N_{c}\right)\right]\left[\mathbf{Q}\left(N_{a}, N_{b}, N_{c}\right): \mathbf{Q}\left(N_{a}, N_{b}\right)\right] \\
& \geq\left[S: \mathbf{Q}\left(N_{a}, N_{b}, N_{c}\right)\right]\left[\overline{\mathbf{Q}} S: \overline{\mathbf{Q}}\left(N_{a}, N_{b}\right)\right] \\
& =\left[S: \mathbf{Q}\left(N_{a}, N_{b}, N_{c}\right)\right]\left[S: \mathbf{Q}\left(N_{a}, N_{b}\right)\right]
\end{aligned}
$$

the last equality following from (1). Therefore, $\left[S: \mathbf{Q}\left(N_{a}, N_{b}, N_{c}\right)\right]=1$, which is the desired conclusion.

To prove (1) we could appeal to the theory of regular extensions (see for instance [5]); however, it is perhaps easier to proceed directly. Let $\gamma$ be a primitive element for $S$ over $\mathbf{Q}\left(N_{a}, N_{b}\right)$ and let $f \in$ $\overline{\mathbf{Q}}\left(N_{a}, N_{b}\right)[X]$ be its minimal equation over $\overline{\mathbf{Q}}\left(N_{a}, N_{b}\right)$. We may write $f=\alpha_{1} f_{1}+\cdots+\alpha_{h} f_{h}$, where $f_{1} \cdots f_{h} \in \mathbf{Q}\left(N_{a}, N_{b}\right)[X]$ are nonzero and $\alpha_{1}, \ldots, \alpha_{h} \in \overline{\mathbf{Q}}$ are linearly independent over $\mathbf{Q}$. Substituting $\gamma$ in place of $X$ we obtain a relation $0=\alpha_{1} f_{1}(\gamma)+\cdots+\alpha_{h} f_{h}(\gamma)$. Now $f_{i}(\gamma) \in S$ and $S=\mathbf{Q}\left(N_{1}, N_{2}\right)$ is purely transcendental over Q. Hence we must have $f_{i}(\gamma)=0$ for $i=1, \ldots, h$. Finally, $\left[S: \mathbf{Q}\left(N_{a}, N_{b}\right)\right] \leq \operatorname{deg}_{X} f_{i} \leq \operatorname{deg}_{X} f=\left[\overline{\mathbf{Q}} S: \overline{\mathbf{Q}}\left(N_{a}, N_{b}\right)\right]$. Since the opposite inequality is trivial, this concludes the argument.

We are left with the task of proving

$$
\begin{equation*}
\overline{\mathbf{Q}} S=\overline{\mathbf{Q}}\left(N_{a}, N_{b}, N_{c}\right) \tag{2}
\end{equation*}
$$

Let $\mathcal{V}$ be the affine variety, over $\overline{\mathbf{Q}}$, determined by the generic point $\left(N_{a}, N_{b}, N_{c}\right)$. Then the inclusion $\overline{\mathbf{Q}}\left(N_{a}, N_{b}, N_{c}\right) \subset \overline{\mathbf{Q}} S \subset \overline{\mathbf{Q}}(X, Y)$ corresponds to a dominant rational $\operatorname{map} \varphi: \mathbf{A}^{2} \rightarrow \mathcal{V}$. To prove (2) we have just to verify that $\operatorname{deg} \varphi=2$. Assuming the contrary, for a point $(x, y)$ in a nonempty Zariski open subset of $\mathbf{A}^{2}(\overline{\mathbf{Q}})$, there exists a point $\left(x^{\prime}, y^{\prime}\right) \in \mathbf{A}^{2}(\overline{\mathbf{Q}})$, with $\{x, y\} \neq\left\{x^{\prime}, y^{\prime}\right\}$ and

$$
N_{m}(x, y)=N_{m}\left(x^{\prime}, y^{\prime}\right), \quad m=a, b, c
$$

Put, for $x \neq 0, z=y / x, u=x^{\prime} / x, v=y^{\prime} / x$. Then we have

$$
\begin{equation*}
N_{m}(1, z)=N_{m}(u, v), \quad m=a, b, c \tag{3}
\end{equation*}
$$

Moreover, since $\{x, y\} \neq\left\{x^{\prime}, y^{\prime}\right\}$, we have that $\{1, z\} \neq\{u, v\}$. Also, as $(x, y)$ runs through a nonempty Zariski open set in $\mathbf{A}^{2}(\overline{\mathbf{Q}})$, we have that $z$ varies in a nonempty Zariski open set in $\mathbf{A}^{1}(\overline{\mathbf{Q}})$.
Eliminating $v$ from the first two of the equations (3), we get

$$
\left(1+z^{a}-u^{a}\right)^{b}=\left(1+z^{b}-u^{b}\right)^{a}
$$

Since $a>b$, this is a nontrivial algebraic equation for $u$ over $\overline{\mathbf{Q}}(z)$. Clearly, similar equations are verified if we replace $b$ with $c$ and/or $u$ with $v$. Since they hold for almost all $z \in \overline{\mathbf{Q}}$, we may assume that the equations

$$
\begin{equation*}
N_{m}(1, Z)=N_{m}(U, V), \quad m=a, b, c \tag{4}
\end{equation*}
$$

have a solution $U, V$ in a finite extension $L$ of $\overline{\mathbf{Q}}(Z)$ with $\{U, V\} \neq$ $\{1, Z\}$. This amounts to a recurrence sequence of order four in a function field, having four distinct integral zeros (corresponding to $m=0, a, b, c)$. In general, such a sequence cannot have more than six zeros (see [1, Theorem 2]) and we have to improve on this in the present special case.

For future reference, we note that neither $U$ nor $V$ can be constant. In fact, assume for instance $V=\alpha \in \overline{\mathbf{Q}}$. If $\alpha=1$ we would have $U^{m}=Z^{m}$ for $m=a, b, c$, whence $U=Z$ against our assumption. If, on the other hand, $\alpha \neq 1$, the equations $\left(1-\alpha^{a}+Z^{a}\right)^{b}=\left(1-\alpha^{b}+Z^{b}\right)^{a}$ and $\left(1-\alpha^{a}+Z^{a}\right)^{c}=\left(1-\alpha^{b}+Z^{c}\right)^{a}$ lead to a contradiction.

We extend to $L$ the natural derivation of $\overline{\mathbf{Q}}(Z)$, denoting it with a prime. Differentiating (4), we obtain equations

$$
Z^{m-1}-U^{m-1} U^{\prime}-V^{m-1} V^{\prime}=0, \quad m=a, b, c
$$

In particular,

$$
\operatorname{det}\left(\begin{array}{ccc}
Z^{a} & U^{a} & V^{a} \\
Z^{b} & U^{b} & V^{b} \\
Z^{c} & U^{c} & V^{c}
\end{array}\right)=U V Z \cdot \operatorname{det}\left(\begin{array}{ccc}
Z^{a-1} & U^{a-1} & V^{a-1} \\
Z^{b-1} & U^{b-1} & V^{b-1} \\
Z^{c-1} & U^{c-1} & V^{c-1}
\end{array}\right)=0
$$

Adding the second column and subtracting the first one to the third and last column does not affect the value of the determinant. Therefore, taking (4) into account, we obtain

$$
\operatorname{det}\left(\begin{array}{lll}
Z^{a} & U^{a} & 1 \\
Z^{b} & U^{b} & 1 \\
Z^{c} & U^{c} & 1
\end{array}\right)=0
$$

and clearly the same equation holds with $V$ in place of $U$. Expanding the determinants and dividing by $Z^{c} U^{c}$, respectively $Z^{c} V^{c}$, we obtain, after a few calculations, the equalities

$$
\begin{equation*}
\frac{U^{a-c}-1}{U^{b-c}-1}=\frac{V^{a-c}-1}{V^{b-c}-1}=\frac{Z^{a-c}-1}{Z^{b-c}-1} \tag{5}
\end{equation*}
$$

We now put $a-c=A d, b-c=B d$, where $d=(a-c, b-c)$ and

$$
R(T)=\frac{T^{A}-1}{T^{B}-1}=\frac{1+T+\cdots+T^{A-1}}{1+T+\cdots+T^{B-1}}
$$

Since $A>B$ and $A, B$ are coprime, we have $\operatorname{deg} R=A-1$. Note that (5) may be rewritten as

$$
\begin{equation*}
R\left(U^{d}\right)=R\left(V^{d}\right)=R\left(Z^{d}\right) \tag{6}
\end{equation*}
$$

In order to exploit (6), we introduce a new indeterminate $\lambda$ and study the equation

$$
\begin{equation*}
R(T)=\lambda \tag{7}
\end{equation*}
$$

trying to determine its Galois group $\Gamma$ over $\overline{\mathbf{Q}}(\lambda)$. (The final result already occurred in connection with an example in the recent paper [1], where no details were given. We supply here complete detail.)

We first calculate the ramification of the cover of the $\lambda$-sphere given by (7).

The points of the $T$-sphere above $\lambda=\infty$ are given by $T=\infty$ and $\left(T^{B}-1\right) /(T-1)=0$. Since this equation has no multiple roots, ramification may occur only for $T=\infty$, the corresponding ramification index being $A-B$.

The other branch points are given by the values $\lambda=R(t)$, where $R^{\prime}(t)=0$. This equation amounts to

$$
\begin{equation*}
A t^{A-1}\left(t^{B}-1\right)-B t^{B-1}\left(t^{A}-1\right)=0, \quad t \neq 1 \tag{8}
\end{equation*}
$$

where we may exclude the solution $t=1$ because $R^{\prime}(1)=(A / 2 B)(A-$ $B) \neq 0$.

We now show that $R^{\prime}(T)$ has no multiple roots except possibly $T=0$. In fact, dividing the left side of (8) by $t^{B-1}$ and differentiating, one gets

$$
A(A-B) t^{A-B-1}\left(t^{B}-1\right)
$$

However, this polynomial has no common roots with the left side of (8), except possibly $t=0,1$.

If $B>1, t=0$ is a solution of (8). We have $R(0)=1$, and the corresponding ramification index is just $B$. As to the remaining solutions, we show that, for any value of $B$, they give rise to distinct values for $R(t)$, except possibly for the value $R(t)=1$. In fact, suppose that $t_{1}, t_{2}$ are two distinct nonzero solutions of (8), with $R\left(t_{1}\right)=R\left(t_{2}\right)$. Equation (8) can be written as

$$
\frac{A}{B} t^{A-B}=R(t)
$$

Therefore, we get $t_{1}^{A-B}=t_{2}^{A-B}$, i.e., $t_{1}^{A} t_{2}^{B}=t_{2}^{A} t_{1}^{B}$. On the other hand, $R\left(t_{1}\right)=R\left(t_{2}\right)$ leads to

$$
t_{1}^{A} t_{2}^{B}-t_{2}^{B}-t_{1}^{A}+1=t_{2}^{A} t_{1}^{B}-t_{1}^{B}-t_{2}^{A}+1
$$

From the last two equations, we get $\left(t_{1}^{A-B}-1\right) t_{1}^{B}=\left(t_{2}^{A-B}-1\right) t_{2}^{B}$. If $t_{1}^{A-B}=1$, we get $t_{1}^{A}=t_{1}^{B}$ and $R\left(t_{1}\right)=1$. Otherwise we get $t_{1}^{B}=t_{2}^{B}$ which, combined with $t_{1}^{A-B}=t_{2}^{A-B}$, gives $t_{1}=t_{2}$.
In conclusion, the ramification indices above any of the branch points except $\lambda=1, \infty$ are given by the sequence $2,1,1, \ldots, 1$, while the ramification sequence above $\lambda=\infty$ is given by $A-B, 1,1, \ldots, 1$.

Also, if $B=1$, we have $R(t)-1=t\left(1+\cdots+t^{A-2}\right)$, so there is no ramification above $\lambda=1$.
Now recall that the Galois group $\Gamma$ of (7), as a permutation group on $A-1$ elements, can be generated by permutations whose cycle decompositions have the same type as the ramification sequences. One may pick precisely one permutation corresponding to each branch point, and in such a way their product is the identity. In particular, one may disregard any single such permutation and still generate $\Gamma$. (Such facts are implicit in the so-called Riemann existence theorem; see, e.g., [4, pp. 32-37, especially Remark 4.33].)

If $B=1$, we disregard the permutation associated to $\infty$ and deduce that $\Gamma$ is generated by transpositions. If $B \neq 1$, we instead disregard the permutation corresponding to 1 , concluding that $\Gamma \subset \mathcal{S}_{A-1}$ is generated by transpositions and a cycle of length $A-B<A-1$. Also, $\Gamma$ is transitive, since $R(T)-\lambda$ is irreducible.

We have now the following presumably known lemma, whose proof we give for completeness. In view of what we have just proved, it implies that $\Gamma=\mathcal{S}_{A-1}$.

Lemma. If a transitive subgroup $\Gamma$ of $\mathcal{S}_{n}$ is generated by transpositions and a cycle of length $<n$, then $\Gamma=\mathcal{S}_{n}$.

Proof of lemma. Because $\Gamma$ is transitive, we may suppose after renumbering that the cycle is $\sigma=(1,2, \ldots, k)$, for a $k<n$ and that one of the transpositions is $\tau=(1, k+1)$. Now observe the formulas $\tau \sigma^{j} \tau \sigma^{-j} \tau=(1, j+1)$, for $j=0, \ldots, k-1$. Since we have $\sigma=(1, k)(1, k-1) \cdots(1,2)$, we thus see that $\Gamma$ is generated by transpositions. Now the results follows, e.g., from [3, Lemma 1, p. 139]. -

Coming back to the proof of Theorem 1, we remark that no two among $U, V, Z$ can have a constant ratio. In fact, suppose for instance that $U=\mu V, \mu \in \overline{\mathbf{Q}}$. Using (4), we derive

$$
\left(\mu^{m}+1\right) V^{m}-1=Z^{m}, \quad m=a, b, c
$$

whence $\left(\left(\mu^{a}+1\right) V^{a}-1\right)^{b}=\left(\left(\mu^{b}+1\right) V^{b}-1\right)^{a}$. Since $V$ is nonconstant, this implies $\mu^{a}+1=0$, which contradicts the previous equation for $m=a$. The other cases are dealt with similarly.

In particular, it follows that $U^{d}, V^{d}, Z^{d}$ are distinct.
Denote by $\Omega$ the splitting field of $R(T)=\lambda$ over $\overline{\mathbf{Q}}(\lambda)$, where $\lambda=R\left(U^{d}\right)$. By (6), $U^{d}, V^{d}, Z^{d} \in \Omega$ and the Galois group $\operatorname{Gal}(\Omega / \overline{\mathbf{Q}}(\lambda))$ is $\Gamma \cong \mathcal{S}_{A-1}$.

To deal with $U, V, Z$ rather than their $d$ th powers, a little more work is needed. Observe that, since the ramification of $\overline{\mathbf{Q}}\left(U^{d}\right)$ over $\overline{\mathbf{Q}}(\lambda)$ above $\infty$ has indices given by $(A-B, 1,1, \ldots, 1)$, the extension $\Omega / \overline{\mathbf{Q}}(\lambda)$ is ramified above $\infty$ with indices all equal to $A-B$. Therefore, $\Omega / \overline{\mathbf{Q}}\left(U^{d}\right)$
is unramified above $\infty$. On the other hand, $\overline{\mathbf{Q}}(U) / \overline{\mathbf{Q}}\left(U^{d}\right)$ is totally ramified above $\infty$, whence $U$ has degree $d$ over $\Omega$.
Since $\Gamma$ is the full symmetric group, by (6) we may choose $\sigma \in \Gamma$ such that $\sigma\left(U^{d}\right)=U^{d}, \sigma\left(V^{d}\right)=Z^{d}, \sigma\left(Z^{d}\right)=V^{d}$.
Let $\xi$ be an arbitrary $d$ th root of 1 . Since $U$ has degree $d$ over $\Omega$, we can lift $\sigma$ to an algebraic closure of $\overline{\mathbf{Q}}(\lambda)$ so that $\sigma(U)=\xi U$. Moreover, we must have $\sigma(V)=\alpha Z, \sigma(Z)=\beta V$, where $\alpha, \beta$ are suitable $d$ th roots of unity. Applying $\sigma$ to the equations (4), which we rewrite as

$$
\begin{equation*}
U^{m}+V^{m}-Z^{m}=1, \quad m=a, b, c, \tag{9}
\end{equation*}
$$

we get

$$
\begin{equation*}
\xi^{m} U^{m}+\alpha^{m} Z^{m}-\beta^{m} V^{m}=1, \quad m=a, b, c . \tag{10}
\end{equation*}
$$

Suppose first that, for all choices of $\xi$ the equations (9) and (10) are identical for $m=a, b, c$, i.e., $\xi^{m}=1, \alpha^{m}=\beta^{m}=-1$. Then $\xi=1$, which implies $d=1$. But in this case we have $\sigma(Z)=V, \sigma(V)=Z$, so $\alpha=\beta=1$, a contradiction.
Therefore, we may assume that, for some choice of $\xi$ and of $m \in$ $\{a, b, c\}$ the equations (9) and (10) are not identical. Using (9) and (10) to eliminate one among $U^{m}, V^{m}, Z^{m}$, we obtain an equation of type

$$
c_{1} W_{1}^{m}+c_{2} W_{2}^{m}=c_{3},
$$

where $c_{1}, c_{2}, c_{3}$ are constants, not all zero, and where $\left\{W_{1}, W_{2}, W_{3}\right\}=$ $\{U, V, Z\}$. Say that $c_{1} \neq 0$ and choose a $\sigma \in \Gamma$ with $\sigma\left(W_{1}^{d}\right)=W_{3}^{d}$ and $\sigma\left(W_{2}^{d}\right)=W_{2}^{d}$. As before, we may show that $W_{2}$ has degree $d$ over $\Omega$, so we may lift $\sigma$ to have $\sigma\left(W_{2}\right)=W_{2}$. Applying $\sigma$ to the last displayed equation, we get that the ratio $W_{1} / W_{3}$ is constant, a contradiction which concludes the proof of Theorem 1.

Proof of Theorem 2. Let $F\left(N_{a}, N_{b}, N_{c}\right)=0$ be a generating polynomial relation (see [2]) and let $\mathcal{V}$ be the hypersurface defined by $F(X, Y, Z)=0$. It is part of the preceding proof (and also follows from Theorem 1) that the rational map $\varphi:(x, y) \mapsto\left(N_{a}(x, y), N_{b}(x, y)\right.$, $N_{c}(x, y)$ ), from the affine plane to $\mathcal{V}$, is dominant of degree 2. Define $\mathcal{W} \in \mathbf{A}^{3}$ by the equation $F\left(T^{a}, U^{b}, V^{c}\right)=0$; it is easily seen
that $F\left(T^{a}, U^{b}, V^{c}\right)$ is homogeneous, so $\mathcal{W}$ is a cone, whose degree $d$ is the number we are seeking. We have an obvious rational map $\psi:(t, u, v) \mapsto\left(t^{a}, u^{b}, v^{c}\right)$ from $\mathcal{W}$ to $\mathcal{V}$. Plainly, $\operatorname{deg} \psi=a b c$.

We consider a generic plane $\pi \in \mathbf{A}^{3}$ defined by an equation $\alpha T+\beta U+$ $\gamma V=0$. Then $\pi$ will intersect $\mathcal{W}$ in $d$ lines through the origin; in fact, $\mathcal{W}$ may be considered as a projective curve of degree $d$ and, via this identification, $\pi$ corresponds to a generic projective line. For any choice of a triple $\Theta=(\mu, \nu, \zeta)$ of roots of unity of order $a, b, c$, respectively, let $\pi_{\Theta}$ be the plane with equation $\alpha \mu T+\mathcal{B} \nu U+\gamma \zeta V=0$. For generic $\alpha, \beta, \gamma$ no two such planes intersect in a line contained in $\mathcal{W}$. Hence the union of these planes will intersect $\mathcal{W}$ in $a b c d$ lines and it will be defined by the equation $\prod_{\Theta}(\alpha \mu T+\beta \nu U+\gamma \zeta V)=0$. We may plainly write the product on the left side as $G\left(T^{a}, U^{b}, V^{c}\right)$ for a suitable polynomial $G$. Consider the intersection of $\mathcal{V}$ with the hypersurface $G(X, Y, Z)=0$. This intersection will decompose as a finite union of distinct irreducible curves. (Since $\pi$ is a generic plane, we may assume that the intersection multiplicity is 1 along each curve.) Let $h$ be the number of such curves. The inverse image of each curve under $\psi$ will be a union of $a b c$ lines lying in the intersection of $\mathcal{W}$ with the union of planes $\pi_{\Theta}$. Therefore, we get $d=h$ and we are left to compute $h$.

To this end, we use the map $\varphi$. The curves in question will correspond under our two-to-one map to the components of the curve $G\left(X^{a}+\right.$ $\left.Y^{a}, X^{b}+Y^{b}, X^{c}+Y^{c}\right)=0$ (which is a union of lines in $\mathbf{A}^{2}$ ), except that we have to disregard a possible component (with its multiplicity) given by $X+Y=0$. In fact, (i) this line collapses to a point under the map $\varphi$ in case $a, b, c$ are all odd, and (ii) no other line can collapse, since the g.c.d. of $N_{a}, N_{b}, N_{c}$ divides $X+Y$ in all cases. So, suppose first that $a b c$ is even. Then, since $G\left(N_{a}, N_{b}, N_{c}\right)$ has degree $a b c$ and, since $\varphi$ has degree 2 , we obtain $d=a b c / 2$. If $a, b, c$ are all odd, we have a component $X+Y=0$. To compute its multiplicity, we first observe that $(X+Y)^{i+j+k}$ divides exactly a term $N_{a}^{i} N_{b}^{j} N_{c}^{k}$. Further, observe that $G(X, Y, Z)$ is the sum of the term $\alpha^{a b c} X^{b c}$ and of a linear combination of monomials $X^{i} Y^{j} Z^{k}$ for which $i+j+k>b c$, whence the required multiplicity is just $b c$. Therefore, we obtain $a b c-b c$ as the number of suitable lines, and the conclusion again follows.

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