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## WEIGHTED COMPOSITION OPERATORS ON NON-LOCALLY CONVEX WEIGHTED SPACES

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ABSTRACT. Let  $(A, \tau)$  be a topological vector space, Xand Y Hausdorff completely regular spaces and V and U Nachbin families on X and Y respectively. For a pair of maps  $\varphi: Y \to X$  and  $\psi: Y \to \mathcal{L}(A)$ ,  $\mathcal{L}(A)$  being the vector space of continuous operators from A into itself, we study the conditions under which the corresponding weighted composition operator  $\psi C_{\varphi}$ , assigning to each  $f \in CV(X, A)$  the function  $y \mapsto \psi_y(f \circ \varphi(y))$ , maps a subspace E of CV(X, A) continuously into another given subspace F of CU(Y, A). We also examine when  $\psi C_{\varphi}$  is bounded, (locally) equicontinuous or (locally) precompact from E into F.

1. Introduction. The weighted composition operators  $uC_{\varphi}$ :  $f \mapsto uf \circ \varphi$  on the Banach algebra C(K) of scalar-valued continuous functions on a compact space K were studied by Kamowitz in [8]; where  $u \in C(K)$  and  $\varphi : K \to K$  is a continuous self map on K. Since then, numerous papers were published in connection with the subject in the scalar case and in the vector-valued one [6, 7, 10, 12, 15, 21, 22], etc. In the scalar case, Singh and Summers [21] studied the composition operators  $C_{\varphi}$  on the Nachbin weighted spaces CV(X)and  $CV_0(X)$ , X being a Hausdorff completely regular space and V a Nachbin family on X. The so-called extended composition operators between weighted spaces were the subject of [14].

Jeang and Wong [7] dealt with the weighted composition operators  $uC_{\varphi}: f \mapsto uf \circ \varphi$  from  $C_0(X)$  into  $C_0(Y)$ , where X and Y are Hausdorff locally compact spaces,  $u \in C(Y)$  and  $\varphi$  a map from Y into X. For special function spaces, namely the Banach spaces of analytic functions on the unit disk, the multiplication operators were the subject of [4].

In the vector-valued setting, Jamison and Rajagopalan [6] considered the weighted composition operators  $\psi C_{\varphi}$  on the Banach space C(K, A),

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where K is a compact space, A a Banach space,  $\varphi$  a self map on X and  $\psi$  an  $\mathcal{L}(A)$ -valued function on K.

Such operator-valued weighted composition operators from the space  $C_p(X, A)$  of all A-valued continuous functions f such that f(X) is precompact were studied in [22] for an arbitrary completely regular space X and any locally convex space A.

For weighted spaces CV(X, A) with A non-locally convex, the weighted composition operators were studied mainly in [10, 12, 13] and [19].

In this paper, we deal with weighted composition operators  $\psi C_{\varphi}$  from a given subspace E of CV(X, A) into another subspace F of some CU(Y, A), A being an arbitrary Hausdorff topological vector space, Ya Hausdorff completely regular space and U a Nachbin family on Y. In Section 2 we produce some preliminaries and notations, while in Section 3, we characterize those weighted composition operators which map E continuously into CU(Y, A), into  $CU_0(Y, A)$  or into an arbitrary  $F \subset CU(Y, A)$ . Section 4 is devoted to the conditions under which  $\psi C_{\varphi}$ is bounded, (locally) equicontinuous or (locally) precompact.

Note that, in most of the works on weighted spaces, essentiality as defined by Prolla in [17] plays an important role. Here, we release this condition and then cover many more situations.

2. Preliminaries. Throughout this paper, A will be a Hausdorff topological vector space over the field  $\mathbf{K}$  (=  $\mathbf{R}$  or  $\mathbf{C}$ ) and  $\mathcal{N}$  (or  $\mathcal{N}_A$  if any confusion might occur) the collection of all closed, shrinkable and circled 0-neighborhoods in A. This constitutes a fundamental system of 0-neighborhoods [11]. Recall that a subset G of A is shrinkable if  $rcl(G) \subset int(G)$  for every  $0 \le r < 1$ , where cl(G) denotes the closure of G in A and int(G) its interior. For every  $G \in \mathcal{N}$ ,  $P_G$  will be the gauge of G. This is

$$P_G(a) = \inf\{\alpha > 0 : a \in \alpha G\}, \quad a \in A.$$

It is clear that  $P_G(\lambda a) = |\lambda| P_G(a)$  for every  $a \in A$  and  $\lambda \in \mathbf{K}$ . Moreover, if  $H \in \mathcal{N}$  enjoys  $H + H \subset G$ , then

$$P_G(a+b) \le P_H(a) + P_H(b), \quad a, b \in A.$$

A linear map  $T: A \to A$  is continuous if, and only if, for every  $G \in \mathcal{N}$ , there is  $H \in \mathcal{N}$  such that

$$P_G(T(a)) \leq P_H(a)$$
, for all  $a \in A$ .

The algebra of all continuous operators from a topological vector space C into A is denoted by  $\mathcal{L}(C, A)$ . If C = A, we just write  $\mathcal{L}(A)$ . If  $\mathcal{B}$  is a collection of subsets of C, we will denote by  $\mathcal{L}_{\mathcal{B}}(C, A)$  the set of those  $T \in \mathcal{L}(C, A)$  which are bounded on the members of  $\mathcal{B}$ .  $\mathcal{L}_{\mathcal{B}}(C, A)$  will be equipped with the topology  $\tau_{\mathcal{B}}$  of uniform convergence on the members of  $\mathcal{B}$ . A fundamental system of 0-neighborhoods for  $\tau_{\mathcal{B}}$  is given by all the intersections of finitely many sets of the form

$$N(B,G) := \{ T \in \mathcal{L}_{\mathcal{B}}(C,A) : T(B) \subset G \}, \quad G \in \mathcal{N}, \quad B \in \mathcal{B}.$$

If  $\mathcal{B}$  consists of the finite (respectively bounded, precompact) sets, we will denote  $\mathcal{L}_{\mathcal{B}}(C, A)$  by  $\mathcal{L}_{\sigma}(C, A)$  (respectively  $\mathcal{L}_{\beta}(C, A)$ ,  $\mathcal{L}_{c}(C, A)$ ) and  $\tau_{\mathcal{B}}$  by  $\tau_{\sigma}$  (respectively  $\tau_{\beta}$ ,  $\tau_{c}$ ). When C = A, we drop it from the notations and write  $\mathcal{L}_{\mathcal{B}}(A)$ .

A Nachbin family on a Hausdorff completely regular space X is any collection V of non-negative upper semi-continuous functions on X such that, for every  $x \in X$ , some  $v \in V$  exists so that v(x) > 0 and, for every  $v_1, v_2 \in V$  and  $\lambda > 0$ , there is some  $v \in V$  such that  $\lambda v_i \leq v$ , i = 1, 2. With such a family V is associated the so-called weighted space

$$CV(X, A) := \{ f : X \longrightarrow A \text{ continuous}; (vf)(X) \text{ is bounded in } A,$$
for all  $v \in V \}.$ 

This space is linearly topologized, see [1] and [9], by considering as a fundamental system of neighborhoods of zero all the sets of the form

$$B_{G,v} := \{ f \in CV(X,A); (vf)(X) \subset G \},\$$

G running over  $\mathcal{N}$  and v over V. The gauge of such a set is denoted by  $P_{G,v}$ . This is

$$P_{G,v}(f) := \sup\{v(x)P_G(f(x)), x \in X\}, \quad f \in CV(X, A).$$

A remarkable subspace of CV(X, A) is

$$CV_0(X,A) := \{ f \in CV(X,A); v(P_G \circ f) \text{ vanishes at infinity,}$$
for all  $v \in V, G \in \mathcal{N} \}.$ 

If we set for a non-negative function u on X and  $\varepsilon > 0$ ,

$$N(u,\varepsilon) := \{ x \in X : u(x) \ge \varepsilon \} \text{ and } N_u := \{ x \in X : u(x) > 0 \},\$$

then a continuous function f belongs to  $CV_0(X, A)$  if, and only if, for every  $v \in V$ ,  $G \in \mathcal{N}$  and  $\varepsilon > 0$ , the set  $N(vP_G \circ f, \varepsilon)$  is compact. Finally, following [1], X is called a  $V_{\mathbf{R}}$ -space if a real-valued function on X is continuous whenever its restriction to each  $N(v, \varepsilon)$  is,  $v \in V$ and  $\varepsilon > 0$ , see [1–3] for more details.

Henceforth, X and Y will be Hausdorff completely regular spaces and V and U Nachbin families on X and Y respectively. A linear map T from CV(X, A) into CU(Y, A) is continuous if, and only if, for all  $u \in U, G \in \mathcal{N}$ , there exists  $v \in V, H \in \mathcal{N}$ :

$$P_{G,u}(T(f)) \leq P_{H,v}(f), \quad f \in CV(X, A).$$

The set of all A-valued functions on Y will be denoted by  $\mathcal{F}(Y, A)$  while C(Y, A) will be that of all the continuous ones. With arbitrary maps  $\psi: Y \to \mathcal{L}(A)$  and  $\varphi: Y \to X$  is associated the linear map  $\psi C_{\varphi}$  defined from CV(X, A) into  $\mathcal{F}(Y, A)$  by  $\psi C_{\varphi}(f)(y) = \psi_y(f(\varphi(y)))$ . This map will be called the weighted composition operator associated with  $\psi$  and  $\varphi$ . From now on, E will be a linear subspace of CV(X, A) and  $\cos(E)$  its cozero set. This is:

$$\cos(E) := \{ x \in X; f(x) \neq 0 \text{ for some } f \in E \}.$$

We will also consider the sets:

$$Y_{E,\varphi} := \{ y \in Y : \varphi(y) \in \operatorname{coz}(E) \} = \varphi^{-1}(\operatorname{coz}(E)),$$
  
$$Y_{E,\varphi,\psi} := \operatorname{coz}(\psi C_{\varphi}(E)).$$

The set  $Y_{E,\varphi}$ , respectively  $Y_{E,\varphi,\psi}$ , is an open subset of Y whenever  $C_{\varphi}(E) \subset C(Y,A)$ , respectively  $\psi C_{\varphi}(E) \subset C(Y,A)$ , where  $C_{\varphi}$  is the composition operator  $f \mapsto f \circ \varphi$ . Finally, E will be said to satisfy the property (M) if, for every  $a \in A, G \in \mathcal{N}$  and  $f \in E$ , the function  $P_G \circ f \otimes a : x \mapsto P_G(f(x))a$  belongs to E. It is easily seen that, whenever E satisfies (M), the following equality holds:

$$Y_{E,\varphi,\psi} = Y_{E,\varphi} \cap \operatorname{coz}(\psi).$$

The spaces CV(X, A) itself and  $CV_0(X, A)$  as well as many other subspaces of CV(X, A) satisfy (M).

3. Continuous weighted composition operators. In this section we study the continuity of  $\psi C_{\varphi}$  from E into a subspace F of CU(Y, A). Since  $\psi C_{\varphi}(f)$  must then be continuous on Y for every  $f \in E$ , we first provide instances in which this is realized. For this purpose, let  $\gamma$  be a property a net from Y may or may not satisfy. Any net satisfying  $\gamma$  will be called a  $\gamma$ -net. A function from Y into an arbitrary topological space is  $\gamma$ -continuous if, for every  $y \in Y$  and every  $\gamma$ -net  $(y_i)_i$  converging to y, the net  $(f(y_i))_i$  converges to f(y). We will say that Y is a  $\gamma_{\mathbf{R}}$ -space, if every  $\gamma$ -continuous function from Y into **R** or into any completely regular space is continuous. At this point, it is worthwhile to recall that the classical  $k_{\mathbf{B}}$ -spaces as well as the sequential, the pseudo-compact and the  $V_{\mathbf{R}}$ -spaces enter in this category, see [15] for more details. For such a property  $\gamma$ , denote by  $\mathcal{L}_{\gamma}(A)$  the algebra consisting of all continuous operators on A which are bounded on the converging  $\gamma$ -nets of A, endowed with the topology of uniform convergence on such nets. In the sequel, we will assume, in addition, that every constant net is a  $\gamma$ -net and that  $\gamma$  is defined also in A and is conserved by A-valued continuous functions.

**Proposition 1.** Let  $f : X \to A$  be a map such that  $C_{\varphi}(f) \in C(Y, A)$ . Under each of the following conditions  $\psi C_{\varphi}(f)$  belongs to C(Y, A):

1. Y is a  $\gamma_{\mathbf{R}}$ -space for some  $\gamma$  and  $\psi$  maps Y continuously into  $\mathcal{L}_{\gamma}(A)$ .

2.  $\psi$  maps Y continuously into  $\mathcal{L}_{\sigma}(A)$  and every  $y \in Y$  possesses some neighborhood whose image by  $\psi$  is equicontinuous on A.

*Proof.* Let  $y_0 \in Y$  and  $G \in \mathcal{N}$  be given. Choose  $H \in \mathcal{N}$  so that  $H + H \subset G$ .

1. Since  $\psi_{y_0}$  is continuous, there exists  $K \in \mathcal{N}$  with  $K \subset H$  and  $\psi_{y_0}(K) \subset H$ . In order to show that  $\psi C_{\varphi}(f)$  is continuous, it suffices to show that it is  $\gamma$ -continuous. Let then  $(y_i)_{i \in I}$  be a  $\gamma$ -net converging to  $y_0$ . Since  $f \circ \varphi$  is continuous, the net  $(f \circ \varphi(y_i))_i$  is a  $\gamma$ -net and the set

$$N(C,K) := \{T \in \mathcal{L}_{\gamma}(A) : T(C) \subset K\}$$

is a 0-neighborhood in  $\mathcal{L}_{\gamma}(A)$ , where  $C := \{f \circ \varphi(y_i), i \in I\}$ . Then there is a neighborhood  $\Omega$  of  $y_0$  such that, for every  $y \in \Omega$ ,  $(\psi_y - \psi_{y_0}) \in N(C, K)$ . Therefore

$$(\psi_y - \psi_{y_0})(f \circ \varphi(y_i)) \in K, \quad i \in I, \quad y \in \Omega.$$

But  $y_i$  tends to  $y_0$ . Then there exists  $i_1 \in I$  so that  $y_i \in \Omega$  whenever  $i \geq i_1$ . As  $f \circ \varphi$  is continuous, there is some  $i_2 \in I$  with

$$f \circ \varphi(y_i) - f \circ \varphi(y_0) \in K$$
, for all  $i \ge i_2$ .

Now, for  $i \in I$  larger than both  $i_1$  and  $i_2$ , we have

$$\psi_{y_i}(f \circ \varphi(y_i)) - \psi_{y_0}(f \circ \varphi(y_0)) = (\psi_{y_i} - \psi_{y_0})(f \circ \varphi(y_i)) + \psi_{y_0}(f \circ \varphi(y_i) - f \circ \varphi(y_0)) \in K + K \subset G.$$

whence the  $\gamma$ -continuity of  $\psi C_{\varphi}(f)$  at  $y_0$  and then everywhere.

2. Let  $\Omega_1$  be a neighborhood of  $y_0$  so that  $\psi(\Omega_1)$  is equicontinuous on A. Then there exists  $K \in \mathcal{N}$  contained in H and satisfying  $\psi_y(K) \subset H$  for all  $y \in \Omega_1$ . Since  $f \circ \varphi$  and  $\psi$  are continuous at  $y_0$ , there exists another neighborhood  $\Omega_2$  of  $y_0$  such that:

$$(f \circ \varphi(y) - f \circ \varphi(y_0)) \in K \quad \text{and} \quad (\psi_y - \psi_{y_0})(f \circ \varphi(y_0)) \in K, \quad y \in \Omega_2.$$

For every  $y \in \Omega := \Omega_1 \cap \Omega_2$ , one has

$$\begin{split} \psi_y \left( f \circ \varphi(y) \right) - \psi_{y_0} \left( f \circ \varphi(y_0) \right) &= \psi_y \left( f \circ \varphi(y) - f \circ \varphi(y_0) \right) \\ &+ \left( \psi_y - \psi_{y_0} \right) \left( f \circ \varphi(y_0) \right) \\ &\in \psi_y(K) + K \\ &\subset H + H \subset G. \end{split}$$

Whence the continuity of  $\psi C_{\varphi}(f)$ .

According to Proposition 1,  $\psi C_{\varphi}(f)$  belongs to C(Y, A) whenever  $C_{\varphi}(f)$  and  $\psi: Y \to \mathcal{L}_{\beta}(A)$  are continuous and Y is a  $k_{\mathbf{R}}-$ , a  $b_{\mathbf{R}}-$ , a pseudo-compact, or a sequential space.

The fact that  $C_{\varphi}(E) \subset C(Y, A)$ , respectively  $\psi C_{\varphi}(E) \subset C(Y, A)$ , forces  $\varphi$ , respectively  $\psi$ , to be continuous on  $Y_{E,\varphi}$ , as we will see next.

**Proposition 2.** 1. If E is a  $C_b(X)$ -module and  $C_{\varphi}(E) \subset C(Y, A)$ , then  $\varphi$  is continuous on  $Y_{E,\varphi}$ .

2. If E satisfies (M) and  $C_{\varphi}(E) \cup (\psi C_{\varphi})(E) \subset C(Y,A)$ , then  $\psi$  is  $\sigma$ -continuous on  $Y_{E,\varphi}$ .

*Proof.* Let  $y_0 \in Y_{E,\varphi}$ . Then there are  $f_0 \in E$  and  $K \in \mathcal{N}$  such that  $P_K(f_0(\varphi(y_0))) = 1$ .

1. Let  $\Omega$  be a neighborhood of  $\varphi(y_0)$  and choose  $g \in C_b(X)$  so that  $g(\varphi(y_0)) = 1, 0 \leq g \leq 1$  and  $\operatorname{supp} g \subset \Omega$ . Since E is a  $C_b(X)$ -module,  $gf_0$  belongs to E. Then  $[g(P_K \circ f_0)] \circ \varphi$  is continuous on Y. Hence

$$\Lambda := \left\{ y \in Y : \frac{1}{2} < g(\varphi(y)) P_K(f_0(\varphi(y))) < \frac{3}{2} \right\}$$

is open and contains  $y_0$ . Since  $\operatorname{supp} g \subset \Omega$ ,  $\varphi(y) \in \Omega$  for all  $y \in \Lambda$ . Hence  $\varphi(\Lambda) \subset \Omega$ , whereby  $\varphi$  is continuous at  $y_0$  and then on the whole  $Y_{E,\varphi}$ .

2. Let  $G \in \mathcal{N}$  and  $a \in A$ . We have to find a neighborhood  $\Omega$ of  $y_0$  so that  $\psi_y(a) - \psi_{y_0}(a) \in G$  for all  $y \in \Omega$ . Consider  $H \in \mathcal{N}$ with  $H + H + H \subset G$ . The continuity of  $y \mapsto P_K(f_0(\varphi(y)))$  yields a neighborhood  $\Omega_1$  of  $y_0$  such that

$$\left|\frac{1}{P_K(f_0(\varphi(y)))} - 1\right| < \frac{1}{2}, \quad y \in \Omega_1$$

By our assumption,  $P_K \circ f_0 \otimes a$  belongs to E and  $y \mapsto \psi_y(P_K(f_0(\varphi(y)))a)$ is continuous at  $y_0$ . Hence some neighborhood  $\Omega \subset \Omega_1$  exists so that

$$\psi_{y}(P_{K}(f_{0}(\varphi(y)))a) - \psi_{y_{0}}(P_{K}(f_{0}(\varphi(y_{0})))a) \in \frac{1}{P_{H}(\psi_{y_{0}}(a)) + 1} H,$$
  
$$\forall y \in \Omega.$$

Hence

$$\begin{split} \psi_y(a) - \psi_{y_0}(a) &= \frac{1}{P_K(f_0(\varphi(y)))} \\ &\times \left[\psi_y(P_K(f_0(\varphi(y))a)) - \psi_{y_0}(P_K(f_0(\varphi(y_0))a))\right] \\ &+ \left[\frac{1}{P_K(f(\varphi(y)))} - 1\right]\psi_{y_0}(a) \\ &\in 2H + H \subset H + H + H \subset G \end{split}$$

Hence  $\psi$  is continuous at  $y_0$  and then on  $Y_{E,\varphi}$ .

The continuity of  $\psi C_{\varphi}$  from E into CU(Y, A) does not imply that of  $\varphi$  on  $Y_{E,\varphi}$  in general. Such a situation occurs for example if  $\psi: Y \to \mathcal{L}(A)$  is a constant function with a non one-to-one value Tand  $E := \{f \in CV(X, A) : f(X) \subset \ker T\}$ . Then E is a  $C_b(X)$ -module and  $\cos(E) = \cos(CV(X))$ . Moreover,  $\psi C_{\varphi} = 0$  is continuous. But  $\varphi$  need not be, since it is arbitrary. Notice that E does not enjoy the property (M).

Now, we are going to characterize the continuous operators  $\psi C_{\varphi}$  from a subspace E of CV(X, A) into CU(Y, A).

**Theorem 3.** Assume that  $E \subset CV(X, A)$  is a  $C_b(X)$ -module satisfying (M) and that  $\psi C_{\varphi}(E) \subset C(Y, A)$ . Then  $\psi C_{\varphi}$  is continuous from E into CU(Y, A) if, and only if, the following condition holds. For all  $G \in \mathcal{N}$ ,  $u \in U$ , there exists  $H \in \mathcal{N}$ ,  $v \in V$ :

(1) 
$$u(y)P_G(\psi_y(a)) \le v(\varphi(y))P_H(a), \text{ for all } a \in A, y \in Y_{E,\varphi}.$$

*Proof.* Necessity. Since  $\psi C_{\varphi} : E \to CU(Y, A)$  is continuous, for every  $G \in \mathcal{N}$  and  $u \in U$ , there exist  $H \in \mathcal{N}$  and  $v \in V$  such that

$$P_{G,u}(\psi C_{\varphi}(f)) \le P_{H,v}(f), \quad f \in E.$$

Then for every  $y \in Y$ , one has

$$u(y)P_G(\psi_y(f(\varphi(y))) \le \sup\{v(x)P_H(f(x)), x \in X\}.$$

Let  $y_0$  be given in  $Y_{E,\varphi}$ . There is some  $f \in E$  such that  $f(\varphi(y_0)) \neq 0$ . Then we may (and do) take f and H so that  $P_H(f(\varphi(y_0))) = 1$ . Consider then the open neighborhood

$$U_n := \left\{ x \in X : v(x) < v(\varphi(y_0)) + \frac{1}{n} \text{ and } P_H(f(x)) < 1 + \frac{1}{n} \right\}$$

of  $\varphi(y_0)$  and take a continuous functions  $g_n \in C_b(X)$  such that  $g_n(\varphi(y_0)) = 1, \ 0 \leq g_n \leq 1$  and  $\operatorname{supp} g_n \subset U_n$ . Since E is a  $C_b(X)$ -module and satisfies (M), the function  $g_n P_H \circ f \otimes a$  belongs to E for arbitrary  $a \in A$ . Hence we have

$$u(y_0)P_G(\psi_{y_0}(a)) \le \left(v(\varphi(y_0)) + \frac{1}{n}\right)\left(1 + \frac{1}{n}\right)P_H(a).$$

As n tends to infinity, we get

$$u(y_0)P_G(\psi_{y_0}(a)) \le v(\varphi(y_0))P_H(a),$$

which is the required inequality.

Sufficiency. Let  $f \in E$ ,  $G \in \mathcal{N}$  and  $u \in U$  be given. By (1), there exist  $v \in V$  and  $H \in \mathcal{N}$  so that

(2) 
$$u(y)P_G(\psi_y(f(\varphi(y)))) \le v(\varphi(y))P_H(f(\varphi(y))), \text{ for all } y \in Y.$$

Therefore,

$$P_{G,u}(\psi C_{\varphi}(f)) := \sup\{u(y)P_G(\psi_y(f(\varphi(y)))), y \in Y\}$$
  
$$\leq \sup\{v(\varphi(y))P_H(f(\varphi(y))), y \in Y\}$$
  
$$\leq P_{H,v}(f) < +\infty.$$

This shows that  $\psi C_{\varphi}(f) \in CU(Y, A)$  and, since f is arbitrary in E, that  $\psi C_{\varphi}$  is continuous.  $\Box$ 

It follows from Theorem 3 that, for any  $C_b(X)$ -module  $E \subset CV(X, A)$ satisfying (M), if  $\operatorname{coz}(E) = \operatorname{coz}(CV(X, A))$  and  $\psi C_{\varphi}(CV(X, A)) \subset C(Y, A)$ , then  $\psi C_{\varphi}$  maps CV(X, A) continuously into CU(Y, A) if, and only if, the same holds for E.

Whenever  $\psi C_{\varphi}(f)$  is continuous for some f, (1) implies that  $\psi C_{\varphi}(f)$ belongs to CU(Y, A). However, (1) does not imply the continuity of  $\psi C_{\varphi}(f)$  although  $f, \psi$  and  $\varphi$  are all continuous. Such an example is obtained by taking  $X = Y = \hat{\mathbf{N}}$  the one point compactification of  $\mathbf{N}, V = U$  the collection of all non-negative functions vanishing on Xexcept on a finite set,  $\varphi$  the identity map and A = C[0, 1] with the norm of  $L^1[0, 1]$ . Let  $(g_n)_n$  be a null sequence in A such that  $(g_n f_n)_n$ does not converge to 0 for some other null sequence  $(f_n)_n$ . Define  $\psi$  by  $\psi(n) = L_{g_n} : f \mapsto fg_n$  for  $n \in \mathbf{N}$  and  $\psi(\infty) = 0$ . Then  $\psi$  is continuous from X into  $\mathcal{L}_{\sigma}(A)$  such that (1) is fulfilled, for  $||\psi_y(h)|| \leq ||\psi_y||_{\infty}||h||$ ,  $h \in A$ . Nevertheless, for  $f \in CV(X, A)$  defined by  $f(n) = f_n$  for  $n \in \mathbf{N}$ and  $f(\infty) = 0, \ \psi C_{\varphi}(f)$  is not continuous at  $\infty$ , since  $f_ng_n$  does not converge to 0.

Next, we will examine when  $\psi C_{\varphi}$  is a continuous weighted composition operator ranging in a smaller subspace F of CU(Y, A). We first look at the case  $F = CU_0(Y, A)$ . To this aim, let us set

 $Cst(E) := \{ K \subset X : \forall a \in A, \exists f \in E \text{ with } f = a \text{ identically on } K \}.$ 

It is easily seen that every  $v \in V$  is bounded on every  $K \in Cst(E)$ .

**Theorem 4.** Let  $E \subset CV(X, A)$  be a  $C_b(X)$ -module satisfying (M)such that  $\psi C_{\varphi}(E) \subset C(Y, A)$ . Assume that, for every  $v \in V$ ,  $G \in \mathcal{N}$ ,  $f \in E$  and  $\varepsilon > 0$ ,  $N(vP_G \circ f, \varepsilon) \in Cst(E)$  and  $f(N(vP_G \circ f, \varepsilon))$  is precompact in A. Then  $\psi C_{\varphi}$  is continuous from E into  $CU_0(Y, A)$  if, and only if, (1) in Theorem 3 holds and

$$\varphi^{-1}(K) \cap \{ y \in Y : u(y) P_G(\psi_y(a)) \ge \varepsilon \}$$

is relatively compact, for all  $K \in Cst(E)$ ,  $G \in \mathcal{N}$ ,  $u \in U$ ,  $a \neq 0$  and  $\varepsilon > 0$ .

*Proof.* Necessity. (1) follows from Theorem 3. Now, assume that  $K \in \operatorname{Cst}(E)$  and let  $u \in U$ ,  $G \in \mathcal{N}$ ,  $a \in A \setminus \{0\}$  and  $\varepsilon > 0$  are given. Choose  $f \in E$  such that f = a identically on K. As  $\psi C_{\varphi}(f)$  belongs to  $CU_0(Y, A)$ , the set

$$S := \{ y \in Y : u(y) P_G(\psi_y(f(\varphi(y)))) \ge \varepsilon \}$$

is compact and contains

$$\varphi^{-1}(K) \cap \{ y \in Y : u(y) P_G(\psi_y(a)) \ge \varepsilon \}.$$

Hence the latter is relatively compact.

Sufficiency. Let  $f \in E$ ,  $G \in \mathcal{N}$ ,  $u \in U$  and  $\varepsilon > 0$  be arbitrary and consider again the set S defined as above. Let  $H \in \mathcal{N}$  satisfy  $H + H \subset G$ . By (1), there are  $I \in \mathcal{N}$  and  $v \in V$  with

$$u(y)P_H(\psi_y(a)) \le v(\varphi(y))P_I(a), \quad a \in A, \quad y \in Y_{E,\varphi}.$$

But  $K := N(vP_I \circ f, (\varepsilon/2))$  belongs to Cst (E) and satisfies  $\varphi(S) \subset K$ . In order to show that  $\psi C_{\varphi}(f)$  belongs to  $CU_0(Y, A)$ , it suffices to show that S is contained in some union of finitely many sets of the form

$$C_i := \left\{ y \in Y : u(y) P_H(\psi_y(a_i)) \ge \frac{\varepsilon}{2} \right\}$$

for some  $a_i \in A \setminus \{0\}$ . But  $f(\varphi(S))$  is contained in f(K) which is precompact, then it is itself precompact in A. Thus there are  $y_1, \ldots, y_n \in S$  such that

$$f(\varphi(S)) \subset \bigcup_{i=1}^{n} \left( f(\varphi(y_i)) + \frac{\varepsilon}{2m} I \right),$$

with  $m = \sup\{v(x), x \in K\}$ . Then, for  $y \in S$ , there is some  $i \in \{1, \ldots, n\}$  so that

$$v(\varphi(y))P_I(f(\varphi(y)) - f(\varphi(y_i))) \le \frac{\varepsilon}{2}.$$

By (1), We get

$$u(y)P_H(\psi_y(f(\varphi(y)) - \psi_y(f(\varphi(y_i)))) \le \frac{\varepsilon}{2}.$$

Therefore,

$$\begin{split} \varepsilon &\leq u(y) P_G\left(\psi_y(f(\varphi(y)))\right) \\ &\leq u(y) P_H[\psi_y(f(\varphi(y)) - \psi_y(f(\varphi(y_i))] + u(y) P_H\left(\psi_y(f(\varphi(y_i)))\right) \\ &\leq \frac{\varepsilon}{2} + u(y) P_H\left(\psi_y(f(\varphi(y_i)))\right), \end{split}$$

whereby

$$\frac{\varepsilon}{2} \le u(y) P_H\left(\psi_y(f(\varphi(y_i)))\right),$$

and consequently

$$S \subset \bigcup_{i=1}^{n} \left\{ y \in Y : u(y) P_{H}(\psi_{y}(a_{i})) \geq \frac{\varepsilon}{2} \right\}, \quad \text{with } a_{i} := f(\varphi(y_{i})).$$

To prove the continuity of  $\psi C_{\varphi}$ , just proceed as at the end of the proof of Theorem 3.

In case  $E \subset CV_0(X, A)$ , we get the following

**Theorem 5.** Let  $E \subset CV_0(X, A)$  be a  $C_b(X)$ -module satisfying (M) such that  $\psi C_{\varphi}(E) \subset C(Y, A)$ . Then  $\psi C_{\varphi}$  is continuous from E into  $CU_0(Y, A)$  if, and only if, (1) holds and

$$\varphi^{-1}(K) \cap \{ y \in Y : u(y) P_G(\psi_y(a)) \ge \varepsilon \}$$

is relatively compact, for every compact  $K \subset coz(E), G \in \mathcal{N}, u \in U$ ,  $a \neq 0 \text{ and } \varepsilon > 0$ .

*Proof.* A similar proof as that of Theorem 4 works provided that, for every  $v \in V$ ,  $G \in \mathcal{N}$ ,  $f \in E$  and  $\varepsilon > 0$ ,  $f(N(vP_G \circ f, \varepsilon))$  is precompact in A and  $N(vP_G \circ f, \varepsilon) \in Cst(E)$ . But,  $N(vP_G \circ f, \varepsilon)$  is compact, so its image by f is precompact. The second condition is a consequence of

**Lemma 6.** Let  $E \subset CV(X, A)$  be a  $C_b(X)$ -module satisfying (M). If  $K \subset coz(E)$  is a compact set and  $C \subset X$  a closed set such that  $K \cap C = \emptyset$ , then for every  $a \in A$ , there exists  $f \in E$  such that f = a on K and f = 0 on C.

*Proof.* For every  $x \in K$ , consider  $G_x \in \mathcal{N}$  and  $f_x \in E$  so that  $P_{G_x}(f_x(x)) = 1$ . Choose then  $g_x \in C_b(X)$  with  $g_x(x) = 1$ ,  $0 \leq g_x \leq 1$  and  $g_x = 0$  identically on C. Set  $j_x := g_x P_{G_x} \circ f_x$  and  $h_x := |j_x|^2 \Gamma(j_x^2)$ , where, for a function g,

$$\Gamma(g)(t) := \begin{cases} |g(t)| & |g(t)| \le 1\\ 1/|g(t)| & \text{otherwise.} \end{cases}$$

Then  $h_x(x) = 1, 0 \le h_x \le 1$  and  $h_x = 0$  on C. By a compactness argument, there exist  $x_1, x_2, \ldots, x_m$  in X such that

$$K \subset \bigcup_{i=1}^{m} \{t \in X : h_{x_i}(t) > 1/2\}.$$

Now, the function

$$h := \sum_{n=1}^{m} h_{x_n}$$

satisfies h(t) > 1/2 for every  $t \in K$ . Hence, for  $a \in A$ , the function  $f := 2h\Gamma(2h) \otimes a$  belongs to E, for E is a  $C_b(X)$ -module and satisfies (M), and enjoys the required conditions.  $\Box$ 

According to Theorem 5, for any  $C_b(X)$ -module  $E \subset CV_0(X, A)$ satisfying (M), if  $\cos(E) = \cos(CV_0(X, A))$  and  $\psi C_{\varphi}(CV_0(X, A)) \subset C(Y, A)$ , then  $\psi C_{\varphi}$  maps continuously  $CV_0(X, A)$  into  $CU_0(Y, A)$  if, and only if, the same holds for E.

Remark 7. 1. A subspace E of CV(X, A) satisfying the hypotheses of Theorem 4 need not be contained in  $CV_0(X, A)$ . For instance, take  $X = \mathbf{R}$ , A a topological vector space in which every bounded set is precompact (e.g., a semi-Montel space or a locally convex space with its weak topology) and  $E = C_b(X, A)$ . For every integer  $n \ge 2$ , define a continuous function  $w_n$  on X by

$$w_n(x) = \begin{cases} n(x - n + (1/n)) & n - (1/n) \le x \le n \\ n(n + (1/n) - x) & n \le x \le n + (1/n) \\ 0 & \text{otherwise.} \end{cases}$$

Put then

$$w(x) = \sum_{n=2}^{+\infty} w_n(x)$$
 and  $v(x) := \max(e^{-|x|}, w(x)).$ 

Then  $V = \{\lambda v, \lambda > 0\}$  is a Nachbin family on X such that  $E \subset CV(X, A)$  satisfies all the hypotheses of Theorem 4. However, the non-zero constant functions belong to E but not to  $CV_0(X, A)$ .

2. In Theorem 5 the second condition does not hold for compact sets not contained in  $\cos(E)$ . For such an example, take  $X = [0, +\infty[, Y = ]0, +\infty[, \varphi(y) = (1/y), y \in Y, U = V = Z, A = \mathbb{C}, \psi$  the constant function with value 1 and  $E = \{f \in CV_0(X) : f(0) = 0\}$ , where Z is the Nachbin family on X consisting of all the positive constant functions. Then  $\psi C_{\varphi}$  is even an isometry from E into  $CU_0(Y)$ . However, for the compact  $K = [0, 1], \varphi^{-1}(K) \cap \{y \in Y : \psi_y(1) \geq 1\}$ , being  $[1, +\infty[$ , is not relatively compact.

3. In Theorem 4 and Theorem 5, the second condition implies that  $\psi C_{\varphi}(f)$  belongs to  $CU_0(Y, A)$  whenever (1) holds. In general, we will say that F is  $E\varphi$ -solid if a function  $g \in C(Y, A)$  belongs to F whenever for all  $G \in \mathcal{N}, u \in U$ , there exists  $H \in \mathcal{N}, v \in V, f \in E$ :

(3)  $(uP_G \circ g)(y) \le (vP_H \circ f)(\varphi(y)), \text{ for all } y \in Y_{E,\varphi}.$ 

If X = Y,  $\varphi = \text{Id}_X$  and  $A = \mathbf{K}$ , we get the classical notion of being solid.

Examples of such solid spaces are given in the following

*Examples.* 1. Clearly, CU(Y, A) is  $E\varphi$ -solid for every subspace E of CV(X, A).

2. If, for every  $v \in V$ ,  $u \in U$  and every compact subset K of  $N_v \cap \operatorname{coz}(E)$ ,  $\varphi^{-1}(K) \cap N_u$  is relatively compact, then  $CU_0(Y, A)$  is  $E\varphi$ -solid for every subspace E of  $CV_0(X, A)$ .

3. If  $C_lV(X, A) = \{f \in CV(X, A); \text{ for all } v \in V, G \in \mathcal{N}, \text{ there exists } v' \in V : vP_G(f) \leq v'\}$  and if  $V \circ \varphi \leq U$ , then  $C_lU(Y, A)$  is  $E\varphi$ -solid for every  $E \subset C_lV(X, A)$ . Indeed, assume that  $g \in C(Y, A)$  satisfies (3). Then

$$u(y)P_G(g(y)) \le (vP_H \circ f)(\varphi(y))$$
  
$$\le v'(\varphi(y)), \quad \text{(for } P_H \circ f \in C_l V(X))$$
  
$$\le u'(y), \quad \text{(since } V \circ \varphi \le U),$$

hence  $P_G \circ g \in C_l U(Y)$  and then  $g \in C_l U(Y, A)$ .

4. If  $C_A V(X, A) = \{f \in CV(X, A); \text{ for all } v \in V, f(N_v) \text{ is bounded}$ in  $A\}$  and, for every  $u \in U$ , there is some  $v \in V$  such that  $(v \circ \varphi)/u$  is bounded on  $N_u$ , then  $C_A U(Y, A)$  is  $E\varphi$ -solid for every  $E \subset C_A V(X, A)$ .

If we combine 2 with 3, respectively 2 with 4, we get sufficient conditions for

$$C_l U_0(Y, A) := C U_0(Y, A) \cap C_l U(Y, A),$$

respectively

$$C_A U_0(Y, A) := C_A U(Y, A) \cap C U_0(Y, A)),$$

to be  $E\varphi$ -solid for every subspace E of  $C_lV_0(X, A)$ , respectively  $C_AV_0(X, A)$ . We refer to [5] and [16] for details on the spaces  $C_AV(X, A)$  and  $C_lV(X, A)$ .

It is easy to show

**Proposition 8.** Let  $E \subset CV(X, A)$  be a  $C_b(X)$ -module satisfying (M) such that  $\psi C_{\varphi}(E) \subset C(Y, A)$ . If F is  $E\varphi$ -solid, then  $\psi C_{\varphi}$  is continuous from E into F if, and only if, (1) holds.

4. Bounded weighted composition operators. A linear map  $\theta$  is said to be bounded, precompact or compact, if it maps some 0-neighborhood into a bounded, precompact or compact set respectively. It will be called locally bounded (respectively locally precompact, locally compact) if it maps every bounded set into a bounded (respectively precompact, compact) one. Whenever  $\theta$  ranges in a space of continuous functions on Y, it will be said to be locally equicontinuous, respectively equicontinuous, on  $Y_0 \subset Y$ , if the image by  $\theta$  of every bounded set, respectively of some 0-neighborhood, is equicontinuous at any point  $y \in Y_0$ .

In this section we deal with bounded, (locally) equicontinuous and (locally) precompact weighted composition operators. For this purpose, we need the following lemma generalizing Lemma 10 of [15] to the non-locally convex setting.

**Lemma 9.** Let L be a subset of CV(X, A) such that  $C_b^+(X)L \subset L$ and L satisfies (M). Then, for every  $G \in \mathcal{N}$ ,  $v \in V$  and  $x \in coz(L)$ , the equality

$$\frac{1}{v(x)} = \sup\{P_G(f(x)), f \in B_{G,v} \cap L\}$$

holds, with  $1/0 = +\infty$ .

*Proof.* The same as that of Lemma 10 of [15] with gauges of members of  $\mathcal{N}$  instead of continuous semi-norms.  $\Box$ 

Henceforth, when there is no risk of confusion, we will use the same notation  $B_{G,v}$  to mean  $B_{G,v} \cap E$ .

**Theorem 10.** Assume that  $E \subset CV(X, A)$  is a  $C_b(X)$ -module satisfying (M) and that  $\psi C_{\varphi}(E) \subset C(Y, A)$ . Then  $\psi C_{\varphi}$  is bounded from E into CU(Y, A) if, and only if, the following condition holds. There exists  $H \in \mathcal{N}, v \in V$ : for all  $G \in \mathcal{N}, u \in U$ , there exists  $\lambda > 0$ :

(4)  $u(y)P_G(\psi_y(a)) \le \lambda v(\varphi(y))P_H(a), \text{ for all } a \in A, y \in Y_{E,\varphi}.$ 

Moreover, if  $\psi C_{\varphi}$  is bounded, then so is also  $\psi_y$  for every  $y \in Y_{E,\varphi}$ .

*Proof.* Necessity. Since  $\psi C_{\varphi} : E \to CU(Y, A)$  is bounded, there exist  $H \in \mathcal{N}$  and  $v \in V$  such that, for every  $G \in \mathcal{N}$  and  $u \in U$ , there is some  $\lambda > 0$  enjoying

$$P_{G,u}(\psi C_{\varphi}(f)) \leq \lambda, \quad f \in B_{H,v}.$$

In particular,

$$u(y)P_G(\psi_y(P_H \circ f \otimes a)(\varphi(y))) \leq \lambda, \quad y \in Y, \ f \in B_{G,v}, \ a \in H$$

or

$$u(y)P_H(f(\varphi(y)))P_G(\psi_y(a)) \le \lambda, \quad y \in Y, \quad f \in B_{G,v}, \quad a \in H.$$

By Lemma 9 and a classical argument, we get

(5) 
$$u(y)P_G(\psi_y(a)) \le \lambda v(\varphi(y))P_H(a), \quad y \in Y_{E,\varphi}, \quad a \in A.$$

Sufficiency. Assume that, for every  $G \in \mathcal{N}$  and  $u \in U$ , (4) holds. Then, for  $f \in E$  and  $y \in Y$ , we have

$$u(y)P_G(\psi_y(f(\varphi(y)))) \le \lambda v(\varphi(y))P_H(f(\varphi(y))), \quad y \in Y.$$

In particular, for  $f \in B_{H,v}$ , we get

$$u(y)P_G(\psi_y(f(\varphi(y)))) \le \lambda, \quad y \in Y_{E,\varphi},$$

giving  $P_{G,u}(\psi C_{\varphi}(f)) \leq \lambda, f \in B_{H,v}$ .

Now, assume that  $\psi C_{\varphi}(B_{G,v})$  is bounded in A, and let  $y_0 \in Y_{E,\varphi}$ and  $f_0 \in B_{G,v}$  be such that  $f_0(\varphi(y_0)) \neq 0$ . Let  $H \in \mathcal{N}$  enjoy  $P_H(f_0(\varphi(y_0))) = 1$  and  $\alpha > P_{H,v}(f_0)$ . Then  $(1/\alpha)P_H \circ f_0 \otimes a$  belongs to  $B_{G,v}$  for all  $a \in G$ . Given  $I \in \mathcal{N}$  and let  $u \in U$  be such that  $u(y_0) \neq 0$ . There exists  $\lambda > 0$  so that:

$$\left[u\psi C_{\varphi}\left(\frac{1}{\alpha}P_{H}\circ f_{0}\otimes a\right)\right](Y)\subset\frac{\lambda}{\alpha}I,\quad a\in G.$$

In particular,  $u(y_0)\psi_{y_0}(a) \in \lambda I$ . Since  $a \in G$  and  $I \in \mathcal{N}$  are arbitrary,  $\psi_{y_0}(G)$  is bounded in A.

A similar proof yields

**Theorem 11.** Assume that  $E \subset CV_0(X, A)$  is a  $C_b(X)$ -module satisfying (M) and that  $\psi C_{\varphi}(E) \subset C(Y, A)$ . Then  $\psi C_{\varphi}$  is bounded from E into  $CU_0(Y, A)$  if, and only if, (4) holds and

$$\varphi^{-1}(K) \cap \{ y \in Y : u(y) P_G(\psi_y(a)) \ge \varepsilon \}$$

is relatively compact for every compact  $K \subset coz(E)$ ,  $u \in U$ ,  $G \in \mathcal{N}$ ,  $a \neq 0$  and  $\varepsilon > 0$ .

We now examine the equicontinuity of  $\psi C_{\varphi}$ .

**Theorem 12.** Assume that  $E \subset CV(X, A)$  is a  $C_b(X)$ -module satisfying (M) and that  $\psi C_{\varphi}(E) \subset C(Y, A)$ . Then  $\psi C_{\varphi}$  is locally equicontinuous on  $Y_{E,\varphi,\psi}$  if, and only if, the following conditions hold:

1.  $\varphi$  is locally constant on  $Y_{E,\varphi,\psi}$ .

2.  $\psi$  is continuous from Y into  $\mathcal{L}_{\beta}(A)$ .

*Proof.* Necessity. 1. Assume that  $\varphi$  is constant on no neighborhood of some  $y_0 \in Y_{E,\varphi,\psi}$  and choose  $f_0 \in E$  with  $\psi_{y_0}(f_0(\varphi(y_0))) \neq 0$ . If  $\mathcal{V}$  is the collection of all neighborhoods of  $y_0$ , then every  $\Omega \in \mathcal{V}$ contains some  $y_\Omega$  with  $\varphi(y_0) \neq \varphi(y_\Omega)$ . Consider  $f_\Omega \in C_b(X)$  such that  $0 \leq f_\Omega \leq 1$ ,  $f_\Omega(\varphi(y_\Omega)) = 0$  and  $f_\Omega(\varphi(y_0)) = 1$ . The set

 $\{g_{\Omega} := f_{\Omega}f_0, \Omega \in \mathcal{V}\}\$  is bounded in E and then its image by  $\psi C_{\varphi}$  is equicontinuous at  $y_0$ . Therefore, for every  $G \in \mathcal{N}$ , there exists  $\Omega_0 \in \mathcal{V}$  such that

$$\psi_y(g_\Omega(\varphi(y))) - \psi_{y_0}(g_\Omega(\varphi(y_0))) \in G$$
, for all  $y \in \Omega_0$ ,  $\Omega \in \mathcal{V}$ .

Hence, for every  $\Omega \subset \Omega_0$  and  $y = y_{\Omega}$ , we get  $\psi_{y_0}(f_0(\varphi(y_0))) \in G$ . Since G is arbitrary,  $\psi_{y_0}(g_{\Omega}(\varphi(y_0))) = 0$  which is a contradiction.

2. Let  $y_0 \in Y_{E,\varphi,\psi}$ , B a bounded set in A and  $H \in \mathcal{N}$  be given. By 1 there exists a neighborhood  $\Omega_0$  of  $y_0$  on which  $\varphi$  is constant with value, say,  $x_0$ . Choose  $f_0 \in E$  so that  $\psi_{y_0}(f_0(x_0)) \neq 0$  and  $H \in \mathcal{N}$  with  $P_H(\psi_{y_0}(f_0(\varphi(y_0)))) = 1$ . Since the set

$$K := \{ P_H \circ f_0 \otimes b, b \in B \}$$

is bounded in E,  $\psi C_{\varphi}(K)$  is equicontinuous at  $y_0$ . Hence there is some  $y_0$ -neighborhood  $\Omega$  contained in  $\Omega_0$  such that

$$[\psi_{y}(P_{H}(f_{0}(\varphi(y)))b) - \psi_{y_{0}}(P_{H}(f_{0}(\varphi(y_{0})))b)] \in G, \quad y \in \Omega, \quad b \in B.$$

This yields  $\psi_y - \psi_{y_0} \in N(B,G)$  for every  $y \in \Omega$ , showing that  $\psi$  is  $\beta$ -continuous at  $y_0$ . Since  $y_0$  is arbitrary in  $Y_{E,\varphi,\psi}, \psi$  is  $\beta$ -continuous on  $Y_{E,\varphi,\psi}$ .

Sufficiency. Given a bounded set  $\mathbf{B} \subset E$ ,  $y_0 \in Y_{E,\varphi,\psi}$  and  $G \in \mathcal{N}$ . By our assumption, there is some neighborhood  $\Omega_0$  of  $y_0$  so that  $\varphi$ is constant on  $\Omega_0$ . Choose  $v \in V$  with  $v(\varphi(y_0)) \neq 0$ . Since the set  $B := \{v(x)f(x), f \in \mathbf{B}, x \in X\}$  is bounded in A and  $\psi$  is  $\beta$ -continuous at  $y_0$ , there is some other neighborhood  $\Omega$  of  $y_0$  such that  $\Omega \subset \Omega_0$  and

$$\psi_y - \psi_{y_0} \in N(B, v(\varphi(y_0))G), \quad y \in \Omega.$$

This is

$$\psi_y(v(x)f(x)) - \psi_{y_0}(v(x)f(x)) \in v(\varphi(y_0))G, \quad y \in \Omega, \quad x \in X,$$

yielding

$$\psi C_{\varphi}(f)(y) - \psi C_{\varphi}(f)(y_0) \in G, \quad y \in \Omega$$

whereby  $\psi C_{\varphi}(\mathbf{B})$  is equicontinuous at  $y_0$  and then on  $Y_{E,\varphi,\psi}$ .

A trivial consequence of Theorem 12 is

**Corollary 13.** Assume that E is a  $C_b(X)$ -module satisfying (M). If  $\varphi$  is not constant on any open set (in particular, if X has no isolated point and  $\varphi$  is one to one), then  $\psi C_{\varphi}$  is locally equicontinuous from E into C(Y, A) if, and only if, it is identically zero.

In case of multiplication operators, we get the following corollary improving Proposition 11 of [15].

**Corollary 14.** Let E be a  $C_b(X)$ -module satisfying (M) and  $\psi$ :  $X \to \mathcal{L}(A)$  a map. If  $M_{\psi} : E \to C(X, A)$  is locally equicontinuous, then  $\cos(M_{\psi}(E))$  is a discrete space.

*Proof.* Take in Theorem 12 Y = X and  $\varphi = \text{Id}_X$ . Then  $M_{\psi}$  is nothing but  $\psi C_{\varphi}$  and then Id<sub>X</sub> is locally constant on  $Y_{E,\varphi,\psi}$ . This means that  $\cos(M_{\psi}(E)) = Y_{E,\varphi,\psi}$  is discrete.  $\Box$ 

**Theorem 15.** Assume that  $E \subset CV(X, A)$  is a  $C_b(X)$ -module satisfying (M) and that  $\psi C_{\varphi}(E) \subset C(Y, A)$ . Then  $\psi C_{\varphi}$  is equicontinuous on  $Y_{E,\varphi,\psi}$  if, and only if, the following two conditions hold:

1.  $\varphi$  is locally constant on  $Y_{E,\varphi,\psi}$ .

2. There exists  $G \in \mathcal{N}$  such that, for every  $y_0 \in Y_{E,\varphi,\psi}$  and  $H \in \mathcal{N}$ , there is some neighborhood  $\Omega$  of  $y_0$  so that  $\psi_y - \psi_{y_0} \in N(G, H)$  for every  $y \in \Omega$ .

Under conditions 1 and 2 every point  $y_0 \in Y_{E,\varphi,\psi}$  admits a neighborhood whose image by  $\psi$  is equicontinuous on A.

*Proof.* Assume that there exist  $v \in V$  and  $G \in \mathcal{N}$  so that  $\psi C_{\varphi}(B_{G,v})$  is equicontinuous on  $Y_{E,\varphi,\psi}$ . By Theorem 12, there exists a neighborhood  $\Omega_0$  of  $y_0$  on which  $\varphi$  is constant with value, say,  $x_0$ .

Necessity. 1. follows from Theorem 12 since an equicontinuous map is already locally equicontinuous.

2. Let  $y_0 \in Y_{E,\varphi,\psi}$  and  $H \in \mathcal{N}$  be given. By property (M), we may choose  $f_0 \in B_{G,v}$  so that  $P_G(f_0(x_0)) \neq 0$ . Since the set

$$K := \{ P_G \circ f_0 \otimes a, \ a \in G \}$$

is contained in  $B_{G,v}$ ,  $\psi C_{\varphi}(K)$  is equicontinuous on Y. Hence there is some  $y_0$ -neighborhood  $\Omega$  contained in  $\Omega_0$  such that

$$\begin{bmatrix} \psi_y(P_G(f_0(\varphi(y)))a) - \psi_{y_0}(P_G(f_0(\varphi(y_0)))a) \end{bmatrix} \in P_G(f_0(x_0))H, \\ y \in \Omega, \quad a \in G. \end{bmatrix}$$

This leads to  $\psi_y - \psi_{y_0} \in N(G, H)$  for every  $y \in \Omega$ .

For the remainder, let  $y_0 \in Y_{E,\varphi,\psi}$  and  $H \in \mathcal{N}$ . Choose again  $f_0 \in B_{G,v}$  so that  $\alpha := P_G(f(x_0)) \neq 0$ . Since  $\psi C_{\varphi}(B_{G,v})$  is equicontinuous at  $y_0$ , for every  $I \in \mathcal{N}$  satisfying  $I + I \subset H$ , there exists a neighborhood  $\Omega \subset \Omega_0$  of  $y_0$  such that

$$\psi C_{\varphi}(f)(y) - \psi C_{\varphi}(f)(y_0) \in \alpha I, \quad y \in \Omega, \quad f \in B_{G,v}.$$

This is

$$\psi_y(f(x_0)) - \psi_{y_0}((f(x_0)) \in \alpha I, \quad y \in \Omega, \quad f \in B_{G,v}.$$

For an arbitrary  $a \in G$ ,  $P_G \circ f_0 \otimes a$  still belongs to  $B_{G,v}$ . Hence

$$P_G(f_0(x_0))[\psi_y(a) - \psi_{y_0}(a)] \in \alpha I, \quad y \in \Omega,$$

or  $\psi_y(a) - \psi_{y_0}(a) \in I$ ,  $y \in \Omega$ . Now, the continuity of  $\psi_{y_0}$  yields a 0-neighborhood  $J \in \mathcal{N}$  such that  $\psi_{y_0}(J) \subset I$ . Finally, for  $a \in R := J \cap G$ ,

$$\psi_y(a) = [\psi_y(a) - \psi_{y_0}(a)] + \psi_{y_0}(a) \in I + I \subset H, \quad y \in \Omega$$

showing that  $\{\psi_y, y \in \Omega\}$  is equicontinuous at 0 and then everywhere on A.

In [1], Bierstedt showed that the precompact sets are equicontinuous in CV(X) whenever X is a  $V_{\mathbf{R}}$ -space. Bierstedt's result was extended in [18] to the space

$$CV_p(X, A) := \{ f \in CV(X, A) : (vf)(X) \text{ is precompact in } A, \forall v \in V \},$$

where A is a locally convex space. Later, this result was extended in [15] to CV(X, A), again with A locally convex. Actually, this result holds for CV(X, A) for arbitrary topological vector space A. Indeed, let  $\delta_x$  denote the evaluation  $f \mapsto f(x)$  at the point x and  $\Delta$  the evaluation map  $x \mapsto \delta_x$  defined from X into  $\mathcal{L}(CV(X, A), A)$ . Then we have

**Proposition 16.** 1. The evaluation map  $\Delta$  is continuous from X into  $\mathcal{L}_c(CV(X, A), A)$  if, and only if, every precompact subset of CV(X, A) is equicontinuous.

2. If X is a  $V_{\mathbf{R}}$ -space, then every precompact subset of CV(X, E) is equicontinuous.

Proof. 1. is straightforward. Next, in view of 1 and our assumption on X, it suffices to show that  $\Delta$  is continuous on each  $N_{v,1} := \{x \in X : v(x) \geq 1\}$ . Let then  $v \in V$  and  $x \in N_{v,1}$  be given. If  $\Lambda$  is a neighborhood of  $\delta_x$  in  $\mathcal{L}_c(CV(X, A), A)$ , then there exist  $G \in \mathcal{N}$  and a precompact set  $C \subset CV(X, E)$  such that  $\delta_x + N(C, G) \subset \Lambda$ . But there exist  $h_i \in C$ ,  $i \in \{1, 2, \ldots n\}$ , so that  $C \subset \bigcup_{i=1}^n (h_i + H)$ , where  $H + H + H \subset G$ . Consider a neighborhood  $\Omega$  of x with  $h_i(t) - h_i(x) \in H$ for every  $i = 1, 2 \ldots n$  and  $t \in \Omega$ . Now, if  $t \in \Omega \cap N_{v,1}$  and  $h \in C$ , then  $h = h_i + f$  for some  $i \in \{1, 2, \ldots, n\}$  and some  $f \in B_{H,v}$ . Hence

$$\begin{split} \delta_t(h) - \delta_x(h) &= h(t) - h(x) \\ &= h_i(t) - h_i(x) + \frac{1}{v(t)} \left( v(t)f(t) \right) - \frac{1}{v(x)} \left( v(x)f(x) \right) \\ &\in H + \frac{1}{v(t)} H + \frac{1}{v(x)} H \subset G. \end{split}$$

Since h is arbitrary in C,  $\Delta(t) - \Delta(x) \in N(C,G)$  and thus  $\Delta$  is continuous on  $N_{v,1}$  and 2 is proved.

According to Corollary 13 and Proposition 16, for a  $C_b(X)$ -module *E* satisfying (M), if *Y* is a  $U_{\mathbf{R}}$ -space and  $\varphi$  is constant on no open set, then  $\psi C_{\varphi}$  is locally precompact from *E* into CU(Y, A) if, and only if, it is identically zero.

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