

CONSTANT-SIGN SOLUTIONS OF
A SYSTEM OF INTEGRAL EQUATIONS
WITH INTEGRABLE SINGULARITIES

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ABSTRACT. We consider the following systems of Fredholm integral equations

$$u_i(t) = \int_0^1 g_i(t, s) f_i(s, u_1(s), u_2(s), \dots, u_n(s)) ds,$$
$$t \in [0, 1], \quad 1 \leq i \leq n$$

$$u_i(t) = \int_0^\infty g_i(t, s) f_i(s, u_1(s), u_2(s), \dots, u_n(s)) ds,$$
$$t \in [0, \infty), \quad 1 \leq i \leq n$$

and the system of Volterra integral equations

$$u_i(t) = \int_0^t g_i(t, s) f_i(s, u_1(s), u_2(s), \dots, u_n(s)) ds,$$
$$t \in [0, T], \quad 1 \leq i \leq n,$$

where the nonlinearities f_i , $1 \leq i \leq n$ may be singular in the independent variable and may also be singular at $u_j = 0$, $j \in \{1, 2, \dots, n\}$. Our aim is to establish criteria such that the above systems have at least one *constant-sign* solution (u_1, u_2, \dots, u_n) , i.e., for each $1 \leq i \leq n$, $\theta_i u_i \geq 0$ where $\theta_i \in \{1, -1\}$ is fixed.

1. Introduction. In this paper we consider three systems of singular integral equations. Specifically we are interested in the following

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systems of Fredholm integral equations

$$(F) \quad u_i(t) = \int_0^1 g_i(t, s) f_i(s, u_1(s), u_2(s), \dots, u_n(s)) ds, \\ t \in [0, 1], \quad 1 \leq i \leq n$$

$$(F)_\infty \quad u_i(t) = \int_0^\infty g_i(t, s) f_i(s, u_1(s), u_2(s), \dots, u_n(s)) ds, \\ t \in [0, \infty), \quad 1 \leq i \leq n$$

and the system of Volterra integral equations

$$(V) \quad u_i(t) = \int_0^t g_i(t, s) f_i(s, u_1(s), u_2(s), \dots, u_n(s)) ds, \\ t \in [0, T], \quad 1 \leq i \leq n$$

where $T > 0$ is fixed. The nonlinearities f_i , $1 \leq i \leq n$ in the above systems may be singular in the independent variable and may also be singular at $u_j = 0$, $j \in \{1, 2, \dots, n\}$.

By using Schauder and Schauder-Tychonoff fixed point theorems, we shall develop existence criteria for a *constant-sign solution* of the above systems. A solution $u = (u_1, u_2, \dots, u_n)$ is said to be of *constant sign* if, for each $1 \leq i \leq n$, $\theta_i u_i(t) \geq 0$ for t in the respective domain; here $\theta_i \in \{1, -1\}$ is fixed. Note that *positive* solution is a special case of *constant-sign* solution when $\theta_i = 1$ for all $1 \leq i \leq n$.

There are only a handful of papers in the literature, see [1–10 and the references therein] that tackle particular cases of (F), $(F)_\infty$ and (V), namely, when $n = 1$, $\theta_1 = 1$, and the nonlinearity has the form $f(t, y) = y^{-a}$, $a > 0$. Thus, f is singular only in the dependent variable y . For instance, in [8, 10], the following problem that arises in communications, as well as in boundary layer theory in fluid dynamics, is discussed

$$y(t) = \int_0^1 g(t, s) \frac{1}{y(s)} ds, \quad t \in [0, 1].$$

Karlin and Nirenberg [6] have also studied a more general problem

$$y(t) = \int_0^1 g(t, s) \frac{1}{[y(s)]^a} ds, \quad t \in [0, 1]$$

where $a > 0$ is fixed and g is a nonnegative continuous function on $[0, 1] \times [0, 1]$.

Our present work uses a new approach to establish new results. In particular, the restrictive conditions in [6], namely, (i) $f(t, y)$ is bounded as $y \rightarrow \infty$, (ii) g is continuous and bounded, and (iii) $g(t, t) > 0$ for all $t > 0$ are not needed in our theorems. Moreover, we have generalized the problems to (i) *systems*, (ii) *general* form of nonlinearities f_i , $1 \leq i \leq n$ that can be singular in both independent and dependent variables, (iii) existence of *constant-sign* solutions, which include *positive* solutions as a special case. The paper is outlined as follows. In Section 2 we shall state the necessary fixed point theorems. The existence results for systems (F) , (V) and $(F)_\infty$ are presented in Section 3.

2. Preliminaries.

Theorem 2.1 (Schauder fixed point theorem). *Let D be a closed, convex subset of a normed linear space E . Then every compact and continuous map $S : D \rightarrow D$ has at least one fixed point.*

Theorem 2.2 (Schauder-Tychonoff fixed point theorem). *Let D be a closed, convex subset of a Fréchet space E . Assume that $S : D \rightarrow D$ is continuous, and $S(D)$ is relatively compact in E . Then S has at least one fixed point in D .*

We also require compactness criteria in the various spaces that we work in.

Theorem 2.3 (Arzela-Ascoli theorem). *Let $M \subseteq C[0, T]$. If M is uniformly bounded and equicontinuous, then M is relatively compact in $C[0, T]$.*

Let $BC[0, \infty)$ be the space of bounded continuous functions on $[0, \infty)$, and let

$$(2.1) \quad C_l[0, \infty) = \left\{ y \mid y \in BC[0, \infty) \text{ and } \lim_{t \rightarrow \infty} y(t) \text{ exists} \right\}.$$

Theorem 2.4 [4, p. 62]. *Let $M \subseteq C_1[0, \infty)$. Then M is compact in $C_1[0, \infty)$ if (a) M is bounded in $C_1[0, \infty)$; (b) the functions in M are equicontinuous on any compact interval of $[0, \infty)$; (c) the functions in M are equiconvergent, i.e., given $\varepsilon > 0$, there exists $T(\varepsilon) > 0$ such that $|f(t) - f(\infty)| < \varepsilon$ for any $t \geq T(\varepsilon)$ and $f \in M$.*

3. Main results. In this section we shall present existence results for the systems of integral equations (F) , $(F)_\infty$ and (V) . Throughout we shall denote $u = (u_1, u_2, \dots, u_n)$, and for $1 \leq j \leq n$,

$$(3.1) \quad [0, \infty)_j = \begin{cases} [0, \infty) & \text{if } \theta_j = 1, \\ (-\infty, 0] & \text{if } \theta_j = -1. \end{cases}$$

System (F). Our first three results are for the system of Fredholm integral equations (F) , where the nonlinearities f_i , $1 \leq i \leq n$ may be singular at $u_j = 0$, $j \in \{1, 2, \dots, n\}$ and may also be singular in the independent variable at some set $\Omega \subset [0, 1]$ with measure zero. Let the Banach space $B = \{u \mid u \in (C[0, 1])^n\}$ be equipped with the norm $\|u\| = \max_{1 \leq i \leq n} \sup_{t \in [0, 1]} |u_i(t)|$.

Theorem 3.1. *Let $\theta_i \in \{1, -1\}$, $1 \leq i \leq n$ be fixed and integers p, q be such that $1 \leq p \leq q \leq \infty$ and $1/p + 1/q = 1$. For each $1 \leq i \leq n$, suppose the following conditions are satisfied:*

$$(3.2) \quad \begin{cases} g_i^t(s) \equiv g_i(t, s) \geq 0 \text{ for all } t \in [0, 1], \text{ a.e. } s \in [0, 1] \text{ and} \\ g_i^t(s) > 0 \text{ for a.e. } t \in [0, 1], \text{ a.e. } s \in [0, 1]; \end{cases}$$

$$(3.3) \quad \begin{cases} g_i^t(s) \in L^p[0, 1] \text{ for all } t \in [0, 1] \text{ and} \\ \text{the map } t \rightarrow g_i^t \text{ is continuous from } [0, 1] \text{ to } L^p[0, 1]; \end{cases}$$

$$(3.4) \quad \begin{cases} f_i : [0, 1] \times (\mathbf{R} \setminus \{0\})^n \rightarrow \mathbf{R} \\ \text{with } t \rightarrow f_i(t, u) \text{ measurable for all } u \in (\mathbf{R} \setminus \{0\})^n \\ \text{and } u \rightarrow f_i(t, u) \text{ continuous for a.e. } t \in (0, 1); \end{cases}$$

$$(3.5) \quad \begin{cases} \text{for any } r_i > 0, \text{ there exists } \psi_{r_i, i} : [0, 1] \rightarrow \mathbf{R}, \\ \psi_{r_i, i}(t) > 0 \text{ for a.e. } t \in [0, 1], \\ \psi_{r_i, i} \in L^q[0, 1] \text{ such that for all } |u_j| \in (0, r_j], 1 \leq j \leq n, \\ \theta_i f_i(t, u) \geq \psi_{r_i, i}(t) \text{ for a.e. } t \in [0, 1]; \end{cases}$$

$$(3.6) \quad \left\{ \begin{array}{l} \text{for any } r_i > 0 \text{ with } \int_0^1 g_i(t, s)\psi_{r_i, i}(s) ds \leq r_i \\ \text{for } t \in [0, 1], \text{ there exists } h_{r_i, i} : [0, 1] \rightarrow R, \\ h_{r_i, i}(t) \geq 0 \text{ for a.e. } t \in [0, 1], \\ h_{r_i, i} \in L^q[0, 1] \text{ such that} \\ \text{for all } |u_j| \in \left[\int_0^1 g_j(t, s)\psi_{r_j, j}(s) ds, r_j \right], 1 \leq j \leq n, \\ \theta_i f_i(t, u) \leq h_{r_i, i}(t) \text{ for a.e. } t \in [0, 1]; \end{array} \right.$$

$$(3.7) \quad \left\{ \begin{array}{l} \text{there exists } M_i > 0 \text{ such that for } t \in [0, 1], \\ M_i \geq \int_0^1 g_i(t, s)h_{M_i, i}(s) ds \geq \int_0^1 g_i(t, s)\psi_{M_i, i}(s) ds. \end{array} \right.$$

Then, (F) has a constant-sign solution $u \in (C[0, 1])^n$ with $\theta_i u_i(t) > 0$, almost every $t \in [0, 1]$, $1 \leq i \leq n$.

Proof. To begin, we define a closed convex subset of $B = (C[0, 1])^n$ as

$$D = \left\{ u \in B \mid \int_0^1 g_i(t, s)h_{M_i, i}(s) ds \geq \theta_i u_i(t) \geq \int_0^1 g_i(t, s)\psi_{M_i, i}(s) ds \right. \\ \left. \text{for } t \in [0, 1], 1 \leq i \leq n \right\}.$$

Let the operator $S : D \rightarrow B$ be defined by

$$(3.8) \quad Su(t) = (S_1 u(t), S_2 u(t), \dots, S_n u(t)), \quad t \in [0, 1]$$

where

$$(3.9) \quad S_i u(t) = \int_0^1 g_i(t, s)f_i(s, u(s)) ds, \quad t \in [0, 1], \quad 1 \leq i \leq n.$$

Clearly, a fixed point of the operator S is a solution of the system (F). Indeed, a fixed point of S obtained in D will be a *constant-sign solution* of the system (F).

First we shall show that S maps D into D . Let $u \in D$. By (3.7) it is clear that

$$(3.10) \quad M_i \geq \int_0^1 g_i(t, s) h_{M_i, i}(s) ds \geq \theta_i u_i(t) \geq \int_0^1 g_i(t, s) \psi_{M_i, i}(s) ds > 0, \\ t \in [0, 1], \quad 1 \leq i \leq n.$$

Hence, it follows from (3.5) that

$$\theta_i f_i(t, u) \geq \psi_{M_i, i}(t), \quad \text{a.e. } t \in [0, 1], \quad 1 \leq i \leq n$$

and subsequently

$$(3.11) \quad \theta_i S_i u(t) = \int_0^1 g_i(t, s) \theta_i f_i(s, u(s)) ds \geq \int_0^1 g_i(t, s) \psi_{M_i, i}(s) ds, \\ t \in [0, 1], \quad 1 \leq i \leq n.$$

Also, from (3.6) and (3.10) we have

$$\theta_i f_i(t, u) \leq h_{M_i, i}(t), \quad \text{a.e. } t \in [0, 1], \quad 1 \leq i \leq n$$

and so

$$(3.12) \quad \theta_i S_i u(t) \leq \int_0^1 g_i(t, s) h_{M_i, i}(s) ds, \quad t \in [0, 1], \quad 1 \leq i \leq n.$$

Having obtained (3.11) and (3.12), we have shown that $S : D \rightarrow D$.

Next, we shall prove that $S : D \rightarrow D$ is continuous. Let $\{u^m\}$ be a sequence in D and $u^m \rightarrow u$ in B . Then, we find for $t \in [0, 1]$ and $1 \leq i \leq n$,

$$|S_i u^m(t) - S_i u(t)| \leq \int_0^1 g_i(t, s) |f_i(s, u^m(s)) - f_i(s, u(s))| ds \\ \leq \left(\int_0^1 [g_i(t, s)]^p ds \right)^{1/p} \\ \times \left(\int_0^1 |f_i(s, u^m(s)) - f_i(s, u(s))|^q ds \right)^{1/q}.$$

Since

$$\int_0^1 |f_i(s, u^m(s)) - f_i(s, u(s))|^q ds \leq 2^q \int_0^1 [h_{M_i, i}(s)]^q ds < \infty,$$

$$1 \leq i \leq n,$$

together with (3.3) and (3.4), the Lebesgue dominated convergence theorem gives for each $1 \leq i \leq n$,

$$\begin{aligned} & \sup_{t \in [0,1]} |S_i u^m(t) - S_i u(t)| \\ & \leq \left(\sup_{t \in [0,1]} \int_0^1 [g_i(t, s)]^p ds \right)^{1/p} \\ & \quad \times \left(\int_0^1 |f_i(s, u^m(s)) - f_i(s, u(s))|^q ds \right)^{1/q} \longrightarrow 0 \end{aligned}$$

as $m \rightarrow \infty$, or $\|S u^m - S u\| \rightarrow 0$ as $m \rightarrow \infty$. Hence, S is continuous.

Finally, we shall check that $S : D \rightarrow D$ is compact. Let $u \in D$. Then, by (3.12) and (3.7) we have

$$\sup_{t \in [0,1]} |S_i u(t)| \leq \sup_{t \in [0,1]} \int_0^1 g_i(t, s) h_{M_i, i}(s) ds \leq M_i, \quad 1 \leq i \leq n$$

or $\|S u\| \leq \max_{1 \leq i \leq n} M_i$. Further, using (3.12) and (3.3) we get for $t, t' \in [0, 1]$ and $1 \leq i \leq n$,

$$\begin{aligned} |S_i u(t) - S_i u(t')| & \leq \int_0^1 |g_i(t, s) - g_i(t', s)| h_{M_i, i}(s) ds \\ & \leq \left(\int_0^1 |g_i^t(s) - g_i^{t'}(s)|^p ds \right)^{1/p} \\ & \quad \times \left(\int_0^1 [h_{M_i, i}(s)]^q ds \right)^{1/q} \longrightarrow 0 \end{aligned}$$

as $t \rightarrow t'$. Now Theorem 2.3 guarantees that S is compact.

Hence, we conclude from Theorem 2.1 that S has a fixed point in D . The proof is complete. \square

Remark 3.1. In Theorem 3.1, the condition (3.6) can be replaced by the following:

$$(3.6') \quad \left\{ \begin{array}{l} \text{for any } r_i > 0 \text{ with } \int_0^1 g_i(t, s) \psi_{r_i, i}(s) ds \leq r_i \text{ for } t \in [0, 1], \text{ let} \\ h_{r_i, i}(t) = \sup \left\{ f_i(t, u) : |u_j| \in \left[\int_0^1 g_j(t, s) \psi_{r_j, j}(s) ds, r_j \right], 1 \leq j \leq n \right\} \\ \text{and assume } h_{r_i, i} \in L^q[0, 1]. \end{array} \right.$$

Remark 3.2. If f_i , $1 \leq i \leq n$ are nonsingular, i.e., $f_i : [0, 1] \times \mathbf{R}^n \rightarrow \mathbf{R}$, then we can have a modified Theorem 3.1 with (3.5)–(3.7) replaced by the following conditions:

$$\left\{ \begin{array}{l} \text{for any } r_i > 0, \text{ there exists } h_{r_i, i} : [0, 1] \rightarrow \mathbf{R}, \\ h_{r_i, i}(t) \geq 0 \text{ for a.e. } t \in [0, 1], \\ h_{r_i, i} \in L^q[0, 1] \text{ such that for all } |u_j| \in [0, r_j], 1 \leq j \leq n, \\ 0 \leq \theta_i f_i(t, u) \leq h_{r_i, i}(t) \text{ for a.e. } t \in [0, 1]; \end{array} \right.$$

there exists $M_i > 0$ such that for $t \in [0, 1]$, $M_i \geq \int_0^1 g_i(t, s) h_{M_i, i}(s) ds \geq 0$.

Moreover, the conclusion of the modified Theorem 3.1 becomes: system (F) has a constant-sign solution $u \in (C[0, 1])^n$ with $\theta_i u_i(t) \geq 0$, $t \in [0, 1]$, $1 \leq i \leq n$.

Theorem 3.2. Let $\theta_i \in \{1, -1\}$, $1 \leq i \leq n$ be fixed and integers p, q be such that $1 \leq p \leq q \leq \infty$ and $1/p + 1/q = 1$. For each $1 \leq i \leq n$, suppose (3.2)–(3.5) hold and the following conditions are satisfied:

$$(3.13) \quad \left\{ \begin{array}{l} \theta_i f_i(t, u) \leq \phi_i(t) [\rho_i(u) + \tau_i(u)] \text{ for } (t, u) \in [0, 1] \times \prod_{j=1}^n [0, \infty)_j, \\ \text{where } \phi_i : [0, 1] \rightarrow \mathbf{R}, \phi_i(t) > 0 \text{ for a.e. } t \in [0, 1], \\ \rho_i, \tau_i : \prod_{j=1}^n (0, \infty)_j \rightarrow (0, \infty) \text{ are continuous,} \\ \text{if } |u_j| \leq |v_j| \text{ for some } j \in \{1, 2, \dots, n\}, \\ \text{then } \rho_i(u_1, \dots, u_j, \dots, u_n) \geq \rho_i(u_1, \dots, v_j, \dots, u_n) \text{ and} \\ \tau_i(u_1, \dots, u_j, \dots, u_n) \leq \tau_i(u_1, \dots, v_j, \dots, u_n); \end{array} \right.$$

$$(3.14) \quad \begin{cases} \phi_i \in L^q[0, 1], \text{ and for any } r_j > 0, 1 \leq j \leq n, \\ \phi_i(t) \rho_i \left(\theta_1 \int_0^1 g_1(t, s) \psi_{r_1, 1}(s) ds, \right. \\ \left. \theta_2 \int_0^1 g_2(t, s) \psi_{r_2, 2}(s) ds, \dots, \theta_n \int_0^1 g_n(t, s) \psi_{r_n, n}(s) ds \right) \\ \in L^q[0, 1]; \end{cases}$$

(3.15)

$$\begin{cases} \text{there exists } M_i > 0 \text{ such that for } t \in [0, 1], \\ M_i \geq \int_0^1 g_i(t, s) \phi_i(s) \left[\tau_i(\theta_1 M_1, \theta_2 M_2, \dots, \theta_n M_n) \right. \\ \left. + \rho_i \left(\theta_1 \int_0^1 g_1(s, x) \psi_{M_1, 1}(x) dx, \theta_2 \int_0^1 g_2(s, x) \psi_{M_2, 2}(x) dx, \dots, \right. \right. \\ \left. \left. \theta_n \int_0^1 g_n(s, x) \psi_{M_n, n}(x) ds \right) \right] dx \\ \geq \int_0^1 g_i(t, s) \psi_{M_i, i}(s) ds. \end{cases}$$

Then, (F) has a constant-sign solution $u \in (C[0, 1])^n$ with $\theta_i u_i(t) > 0$, almost every $t \in [0, 1]$, $1 \leq i \leq n$.

Proof. We shall show that (3.6) and (3.7) are satisfied; then the conclusion is immediate from Theorem 3.1. In view of (3.13), we obtain for almost every $t \in [0, 1]$, $|u_j| \in [\int_0^1 g_j(t, s) \psi_{r_j, j}(s) ds, r_j]$, $1 \leq j \leq n$ and $1 \leq i \leq n$,

$$(3.16) \quad \theta_i f_i(t, u) \leq$$

$$\begin{aligned} \phi_i(t) \left[\rho_i \left(\theta_1 \int_0^1 g_1(t, s) \psi_{r_1, 1}(s) ds, \theta_2 \int_0^1 g_2(t, s) \psi_{r_2, 2}(s) ds, \dots, \right. \right. \\ \left. \left. \theta_n \int_0^1 g_n(t, s) \psi_{r_n, n}(s) ds \right) + \tau_i(\theta_1 r_1, \theta_2 r_2, \dots, \theta_n r_n) \right] \equiv h_{r_i, i}(t). \end{aligned}$$

Observe that we have picked $h_{r_i, i}(t)$ to be the right-hand side of (3.16). Now, (3.6) is fulfilled since (3.14) ensures that $h_{r_i, i} \in L^q[0, 1]$. Further, (3.15) implies (3.7). \square

As an application of Theorem 3.2, we consider a special case of system (F), viz.,

$$(3.17) \quad u_i(t) = \int_0^1 g_i(t, s) \theta_i \phi_i(s) [\rho_i(u(s)) + \tau_i(u(s))] ds, \\ t \in [0, 1], \quad 1 \leq i \leq n,$$

where $\theta_i \in \{1, -1\}$, $1 \leq i \leq n$ are fixed.

Theorem 3.3. *Let $\theta_i \in \{1, -1\}$, $1 \leq i \leq n$ be fixed and integers p, q be such that $1 \leq p \leq q \leq \infty$ and $1/p + 1/q = 1$. For each $1 \leq i \leq n$, suppose (3.2) and (3.3) hold and the following conditions are satisfied:*

$$(3.18) \quad \left\{ \begin{array}{l} \phi_i : [0, 1] \rightarrow \mathbf{R}, \phi_i(t) > 0 \text{ for a.e. } t \in [0, 1], \\ \rho_i, \tau_i : \prod_{j=1}^n (0, \infty)_j \rightarrow (0, \infty) \text{ are continuous,} \\ \text{if } |u_j| \leq |v_j| \text{ for some } j \in \{1, 2, \dots, n\}, \\ \text{then } \rho_i(u_1, \dots, u_j, \dots, u_n) \geq \rho_i(u_1, \dots, v_j, \dots, u_n) \text{ and} \\ \tau_i(u_1, \dots, u_j, \dots, u_n) \leq \tau_i(u_1, \dots, v_j, \dots, u_n); \end{array} \right.$$

$$(3.19) \quad \left\{ \begin{array}{l} \phi_i \in L^q[0, 1], \text{ and for any } r_j > 0, 1 \leq j \leq n, \\ \phi_i(t) \rho_i \left(\theta_1 \rho_1(\theta_1 r_1, \theta_2 r_2, \dots, \theta_n r_n) \int_0^1 g_1(t, s) \phi_1(s) ds, \right. \\ \left. \theta_2 \rho_2(\theta_1 r_1, \theta_2 r_2, \dots, \theta_n r_n) \int_0^1 g_2(t, s) \phi_2(s) ds, \dots, \right. \\ \left. \theta_n \rho_n(\theta_1 r_1, \theta_2 r_2, \dots, \theta_n r_n) \int_0^1 g_n(t, s) \phi_n(s) ds \right) \in L^q[0, 1]; \end{array} \right.$$

$$(3.20) \quad \left\{ \begin{array}{l} \text{there exists } M_i > 0 \text{ such that for } t \in [0, 1], \\ M_i \geq \int_0^1 g_i(t, s) \phi_i(s) \left[\tau_i(\theta_1 M_1, \theta_2 M_2, \dots, \theta_n M_n) \right. \\ \left. + \rho_i \left(\theta_1 \rho_1(\theta_1 M_1, \theta_2 M_2, \dots, \theta_n M_n) \int_0^1 g_1(s, x) \phi_1(x) dx, \right. \right. \\ \left. \left. \theta_2 \rho_2(\theta_1 M_1, \theta_2 M_2, \dots, \theta_n M_n) \int_0^1 g_2(s, x) \phi_2(x) dx, \dots, \right. \right. \\ \left. \left. \theta_n \rho_n(\theta_1 M_1, \theta_2 M_2, \dots, \theta_n M_n) \int_0^1 g_n(s, x) \phi_n(x) dx \right) \right] ds \\ \left. \geq \rho_i(\theta_1 M_1, \theta_2 M_2, \dots, \theta_n M_n) \int_0^1 g_i(t, s) \phi_i(s) ds. \right. \end{array} \right.$$

Then (3.17) has a constant-sign solution $u \in (C[0, 1])^n$ with $\theta_i u_i(t) > 0$, almost every $t \in [0, 1]$, $1 \leq i \leq n$.

Proof. Taking $\psi_{r_i, i}(t) = \phi_i(t)\rho_i(\theta_1 r_1, \theta_2 r_2, \dots, \theta_n r_n)$, the conclusion follows immediately from Theorem 3.2. \square

Example 3.1. Consider (3.17) where, for each $1 \leq i \leq n$,

$$(3.21) \quad \begin{aligned} \theta_i &= 1, & \rho_i(u) &= |u_i|^{-\alpha_i}, & \tau_i(u) &= A_i |u_i|^{\beta_i} + B_i, \\ & & 0 < \alpha_i < 1, & 0 \leq \beta_i < 1, & A_i, B_i &\geq 0, \end{aligned}$$

$$(3.22) \quad g_i \text{ fulfills (3.2) and (3.3),} \quad \phi_i \text{ satisfies (3.18) and (3.19).}$$

Then, (3.20) reduces to

$$(3.23) \quad \begin{aligned} M_i &\geq \int_0^1 g_i(t, s)\phi_i(s) \left[A_i M_i^{\beta_i} + B_i + M_i^{\alpha_i^2} \left(\int_0^1 g_i(s, x)\phi_i(x) dx \right)^{-\alpha_i} \right] ds \\ &\geq M_i^{-\alpha_i} \int_0^1 g_i(t, s)\phi_i(s) ds, \quad 1 \leq i \leq n, \end{aligned}$$

which is satisfied for large M_i . Thus, by Theorem 3.3 the system (3.17) with (3.21) and (3.22) has a constant-sign solution $u \in (C[0, 1])^n$ with $\theta_i u_i(t) > 0$, almost everywhere $t \in [0, 1]$, $1 \leq i \leq n$.

System (V). Next, we shall investigate the system of Volterra integral equations (V), where the nonlinearities f_i , $1 \leq i \leq n$, may be singular at $u_j = 0$, $j \in \{1, 2, \dots, n\}$, and may also be singular in the independent variable at some set $\Omega \subset [0, T]$ with measure zero. Let the Banach space $B = \{u \mid u \in (C[0, T])^n\}$ be equipped with the norm $\|u\| = \max_{1 \leq i \leq n} \sup_{t \in [0, T]} |u_i(t)|$.

Theorem 3.4. Let $\theta_i \in \{1, -1\}$, $1 \leq i \leq n$ be fixed, and let integers p, q be such that $1 \leq p \leq q \leq \infty$ and $1/p + 1/q = 1$. For each $1 \leq i \leq n$, suppose the following conditions are satisfied:

$$(3.24) \quad \begin{cases} \text{for all } t \in [0, T], g_i^t(s) \equiv g_i(t, s) \geq 0 \text{ for a.e. } s \in [0, t] \text{ and} \\ \text{for a.e. } t \in [0, T], g_i^t(s) > 0 \text{ for a.e. } s \in [0, t]; \end{cases}$$

(3.25)

$$g_i^t(s) \in L^p[0, t] \quad \text{for all } t \in [0, T] \quad \text{and} \quad \sup_{t \in [0, T]} \int_0^t [g_i^t(s)]^p ds < \infty;$$

for any $t, t' \in [0, T]$,

(3.26)

$$\int_0^{\min\{t, t'\}} |g_i^t(s) - g_i^{t'}(s)|^p ds \longrightarrow 0 \quad \text{as } t \rightarrow t';$$

(3.27)

$$\begin{cases} f_i : [0, T] \times (\mathbf{R} \setminus \{0\})^n \rightarrow \mathbf{R} \text{ with} \\ t \rightarrow f_i(t, u) \text{ measurable for all } u \in (\mathbf{R} \setminus \{0\})^n \\ \text{and } u \rightarrow f_i(t, u) \text{ continuous for a.e. } t \in (0, T); \end{cases}$$

(3.28)

$$\begin{cases} \text{for any } r_i > 0, \text{ there exists } \psi_{r_i, i} : [0, T] \rightarrow \mathbf{R}, \psi_{r_i, i}(t) > 0 \\ \text{for a.e. } t \in [0, T], \psi_{r_i, i} \in L^q[0, T] \text{ s.t. } \forall |u_j| \in (0, r_j], 1 \leq j \leq n, \\ \theta_i f_i(t, u) \geq \psi_{r_i, i}(t) \text{ for a.e. } t \in [0, T]; \end{cases}$$

(3.29)

$$\begin{cases} \text{for any } r_i > 0 \text{ with } \int_0^t g_i(t, s) \psi_{r_i, i}(s) ds \leq r_i \text{ for } t \in [0, T], \\ \exists h_{r_i, i} : [0, T] \rightarrow \mathbf{R}, h_{r_i, i}(t) \geq 0 \text{ for a.e. } t \in [0, T], h_{r_i, i} \in L^q[0, T] \\ \text{s.t. for a.e. } t \in [0, T] \text{ and all } |u_j| \in \left[\int_0^t g_j(t, s) \psi_{r_j, j}(s) ds, r_j \right], \\ 1 \leq j \leq n, \theta_i f_i(t, u) \leq h_{r_i, i}(t); \end{cases}$$

(3.30)

$$\begin{cases} \text{there exists } M_i > 0 \text{ such that for } t \in [0, T], \\ M_i \geq \int_0^t g_i(t, s) h_{M_i, i}(s) ds \geq \int_0^t g_i(t, s) \psi_{M_i, i}(s) ds. \end{cases}$$

Then, (V) has a constant-sign solution $u \in (C[0, T])^n$ with $\theta_i u_i(t) > 0$, almost every $t \in [0, T]$, $1 \leq i \leq n$.

Proof. Define a closed convex subset of $B = (C[0, T])^n$ as

$$D = \left\{ u \in B \mid \int_0^t g_i(t, s) h_{M_i, i}(s) ds \geq \theta_i u_i(t) \geq \int_0^t g_i(t, s) \psi_{M_i, i}(s) ds \right. \\ \left. \text{for } t \in [0, T], 1 \leq i \leq n \right\}.$$

Let the operator $S : D \rightarrow B$ be defined by

$$(3.31) \quad Su(t) = (S_1u(t), S_2u(t), \dots, S_nu(t)), \quad t \in [0, T],$$

where

$$(3.32) \quad S_iu(t) = \int_0^t g_i(t, s) f_i(s, u(s)) ds, \quad t \in [0, T], \quad 1 \leq i \leq n.$$

Clearly, a fixed point of S obtained in D will be a constant-sign solution of the system (V).

Following a similar argument as in the proof of Theorem 3.1, we can show that S maps D into D .

Next, we shall prove that $S : D \rightarrow D$ is continuous. Let $\{u^m\}$ be a sequence in D and $u^m \rightarrow u$ in B . Then, we have for $t \in [0, T]$ and $1 \leq i \leq n$,

$$\begin{aligned} & |S_iu^m(t) - S_iu(t)| \\ & \leq \int_0^t g_i(t, s) |f_i(s, u^m(s)) - f_i(s, u(s))| ds \\ & \leq \left(\int_0^t [g_i(t, s)]^p ds \right)^{1/p} \left(\int_0^T |f_i(s, u^m(s)) - f_i(s, u(s))|^q ds \right)^{1/q}. \end{aligned}$$

Noting that

$$\int_0^T |f_i(s, u^m(s)) - f_i(s, u(s))|^q ds \leq 2^q \int_0^T [h_{M_i, i}(s)]^q ds < \infty, \quad 1 \leq i \leq n$$

and also (3.25) and (3.27), the Lebesgue dominated convergence theorem yields for each $1 \leq i \leq n$,

$$\begin{aligned} & \sup_{t \in [0, T]} |S_iu^m(t) - S_iu(t)| \\ & \leq \left(\sup_{t \in [0, T]} \int_0^t [g_i(t, s)]^p ds \right)^{1/p} \left(\int_0^T |f_i(s, u^m(s)) - f_i(s, u(s))|^q ds \right)^{1/q} \\ & \qquad \qquad \qquad \longrightarrow 0 \end{aligned}$$

as $m \rightarrow \infty$, or $\|Su^m - Su\| \rightarrow 0$ as $m \rightarrow \infty$. Hence, S is continuous.

Finally, we shall show that $S : D \rightarrow D$ is compact. Let $u \in D$. Then, by (3.29) and (3.30) we have

$$\sup_{t \in [0, T]} |S_i u(t)| \leq \sup_{t \in [0, T]} \int_0^t g_i(t, s) h_{M_i, i}(s) ds \leq M_i, \quad 1 \leq i \leq n$$

or $\|Su\| \leq \max_{1 \leq i \leq n} M_i$. Further, in view of (3.25), (3.26) and (3.29), we get for $t, t' \in [0, T]$, with $t' < t$ and $1 \leq i \leq n$,

$$\begin{aligned} & |S_i u(t) - S_i u(t')| \\ & \leq \int_0^{t'} |g_i(t, s) - g_i(t', s)| f_i(s, u(s)) ds + \int_{t'}^t g_i(t, s) f_i(s, u(s)) ds \\ & \leq \int_0^{t'} |g_i(t, s) - g_i(t', s)| h_{M_i, i}(s) ds + \int_{t'}^t g_i(t, s) h_{M_i, i}(s) ds \\ & \leq \left(\int_0^{t'} |g_i^t(s) - g_i^{t'}(s)|^p ds \right)^{1/p} \left(\int_0^T [h_{M_i, i}(s)]^q ds \right)^{1/q} \\ & \quad + \left(\sup_{t \in [0, T]} \int_0^t [g_i^t(s)]^p ds \right)^{1/p} \left(\int_{t'}^t [h_{M_i, i}(s)]^q ds \right)^{1/q} \rightarrow 0 \end{aligned}$$

as $t \rightarrow t'$. A similar argument also holds for $t' > t$. Now Theorem 2.3 guarantees that S is compact.

It now follows from Theorem 2.1 that S has a fixed point in D . The proof is complete. \square

Remark 3.3. In Theorem 3.4, the condition (3.29) can be replaced by the following:

$$(3.29)' \left\{ \begin{array}{l} \text{for any } r_i > 0 \text{ with } \int_0^t g_i(t, s) \psi_{r_i, i}(s) ds \leq r_i \text{ for } t \in [0, T], \text{ let} \\ h_{r_i, i}(t) = \sup \left\{ f_i(t, u) : |u_j| \in \left[\int_0^t g_j(t, s) \psi_{r_j, j}(s) ds, r_j \right], 1 \leq j \leq n \right\} \\ \text{and assume } h_{r_i, i} \in L^q[0, T]. \end{array} \right.$$

Remark 3.4. In Theorem 3.4, the condition (3.26) can be replaced by the following: for any $t, t' \in [0, T]$,

$$(3.26)' \quad \int_0^{\min\{t, t'\}} |g_i^t(s) - g_i^{t'}(s)|^p ds + \int_{\min\{t, t'\}}^{\max\{t, t'\}} |g_i^{\max\{t, t'\}}(s)|^p ds \longrightarrow 0$$

as $t \rightarrow t'$.

Note that (3.26)' implies $\sup_{t \in [0, T]} \int_0^t [g_i^t(s)]^p ds < \infty$ in (3.25).

Remark 3.5. If $f_i, 1 \leq i \leq n$ are nonsingular, i.e., $f_i : [0, T] \times \mathbf{R}^n \rightarrow \mathbf{R}$, then we can have a modified Theorem 3.4 with (3.28)–(3.30) replaced by the following conditions:

$$\begin{cases} \text{for any } r_i > 0, \text{ there exists } h_{r_i, i} : [0, T] \rightarrow \mathbf{R}, h_{r_i, i}(t) \geq 0, \\ \text{for a.e. } t \in [0, T], h_{r_i, i} \in L^q[0, T] \text{ s.t. } \forall |u_j| \in [0, r_j], 1 \leq j \leq n, \\ 0 \leq \theta_i f_i(t, u) \leq h_{r_i, i}(t) \text{ for a.e. } t \in [0, T]; \end{cases}$$

there exists $M_i > 0$ such that for $t \in [0, T]$, $M_i \geq \int_0^t g_i(t, s) h_{M_i, i}(s) ds \geq 0$.

Moreover, the conclusion of the modified Theorem 3.4 becomes: system (V) has a constant-sign solution $u \in (C[0, T])^n$ with $\theta_i u_i(t) \geq 0, t \in [0, T], 1 \leq i \leq n$.

Theorem 3.5. Let $\theta_i \in \{1, -1\}, 1 \leq i \leq n$ be fixed, and let integers p, q be such that $1 \leq p \leq q \leq \infty$ and $1/p + 1/q = 1$. For each $1 \leq i \leq n$, suppose (3.24)–(3.28) hold and the following conditions are satisfied:

$$(3.33) \quad \begin{cases} \theta_i f_i(t, u) \leq \phi_i(t) [\rho_i(u) + \tau_i(u)] \text{ for } (t, u) \in [0, T] \times \prod_{j=1}^n [0, \infty)_j, \\ \text{where } \phi^i : [0, T] \rightarrow \mathbf{R}, \phi_i(t) > 0 \text{ for a.e. } t \in [0, T], \\ \rho_i, \tau_i : \prod_{j=1}^n (0, \infty)_j \rightarrow (0, \infty) \text{ are continuous, if } |u_j| \leq |v_j| \\ \text{for some } j \in \{1, 2, \dots, n\}, \\ \text{then } \rho_i(u_1, \dots, u_j, \dots, u_n) \geq \rho_i(u_1, \dots, v_j, \dots, u_n) \text{ and} \\ \tau_i(u_1, \dots, u_j, \dots, u_n) \leq \tau_i(u_1, \dots, v_j, \dots, u_n); \end{cases}$$

(3.34)

$$\begin{cases} \phi_i \in L^q[0, T], \text{ and for any } r_j > 0, 1 \leq j \leq n, \\ \phi_i(t) \rho_i \left(\theta_1 \int_0^t g_1(t, s) \psi_{r_1,1}(s) ds, \theta_2 \int_0^t g_2(t, s) \psi_{r_2,2}(s) ds, \dots, \right. \\ \left. \theta_n \int_0^t g_n(t, s) \psi_{r_n,n}(s) ds \right) \in L^q[0, T]; \end{cases}$$

(3.35)

$$\begin{cases} \text{there exists } M_i > 0 \text{ such that for } t \in [0, T], \\ M_i \geq \int_0^t g_i(t, s) \phi_i(s) \left[\tau_i(\theta_1 M_1, \theta_2 M_2, \dots, \theta_n M_n) \right. \\ \left. + \rho_i \left(\theta_1 \int_0^s g_1(s, x) \psi_{M_1,1}(x) dx, \theta_2 \int_0^s g_2(s, x) \psi_{M_2,2}(x) dx, \dots, \right. \right. \\ \left. \left. \theta_n \int_0^s g_n(s, x) \psi_{M_n,n}(x) dx \right) \right] ds \geq \int_0^t g_i(t, s) \psi_{M_i,i}(s) ds. \end{cases}$$

Then, (V) has a constant-sign solution $u \in (C[0, T])^n$ with $\theta_i u_i(t) > 0$, almost every $t \in [0, T]$, $1 \leq i \leq n$.

Proof. For each $1 \leq i \leq n$, let

$$h_{r_i,i}(t) = \phi_i(t) \left[\tau_i(\theta_1 r_1, \theta_2 r_2, \dots, \theta_n r_n) + \rho_i \left(\theta_1 \int_0^t g_1(t, s) \psi_{r_1,1}(s) ds, \right. \right. \\ \left. \left. \theta_2 \int_0^t g_2(t, s) \psi_{r_2,2}(s) ds, \dots, \theta_n \int_0^t g_n(t, s) \psi_{r_n,n}(s) ds \right) \right].$$

Then, using a similar argument as in the proof of Theorem 3.2, we can show that (3.29) and (3.30) are satisfied, and so the conclusion is immediate from Theorem 3.4. \square

As an application of Theorem 3.5, we consider a special case of system (V), viz.,

$$(3.36) \quad u_i(t) = \int_0^t g_i(t, s) \theta_i \phi_i(s) [\rho_i(u(s)) + \tau_i(u(s))] ds, \\ t \in [0, T], 1 \leq i \leq n$$

where $\theta_i \in \{1, -1\}$, $1 \leq i \leq n$ are fixed.

The following result is immediate from Theorem 3.5. The proof is similar to that of Theorem 3.3.

Theorem 3.6. *Let $\theta_i \in \{1, -1\}$, $1 \leq i \leq n$ be fixed, and let integers p, q be such that $1 \leq p \leq q \leq \infty$ and $1/p + 1/q = 1$. For each $1 \leq i \leq n$, suppose (3.24)–(3.26) hold and the following conditions are satisfied:*

$$(3.37) \quad \begin{cases} \phi_i : [0, T] \rightarrow \mathbf{R}, \phi_i(t) > 0 \text{ for a.e. } t \in [0, T], \\ \rho_i, \tau_i : \prod_{j=1}^n (0, \infty)_j \rightarrow (0, \infty) \text{ are continuous,} \\ \text{if } |u_j| \leq |v_j| \text{ for some } j \in \{1, 2, \dots, n\}, \\ \text{then } \rho_i(u_1, \dots, u_j, \dots, u_n) \geq \rho_i(u_1, \dots, v_j, \dots, u_n) \text{ and} \\ \tau_i(u_1, \dots, u_j, \dots, u_n) \leq \tau_i(u_1, \dots, v_j, \dots, u_n); \end{cases}$$

$$(3.38) \quad \begin{cases} \phi_i \in L^q[0, T], \text{ and for any } r_j > 0, 1 \leq j \leq n, \\ \phi_i(t) \rho_i(\theta_1 r_1, \theta_2 r_2, \dots, \theta_n r_n) \int_0^t g_1(t, s) \phi_1(s) ds, \\ \theta_2 \rho_2(\theta_1 r_1, \theta_2 r_2, \dots, \theta_n r_n) \int_0^t g_2(t, s) \phi_2(s) ds, \dots, \\ \theta_n \rho_n(\theta_1 r_1, \theta_2 r_2, \dots, \theta_n r_n) \int_0^t g_n(t, s) \phi_n(s) ds \in L^q[0, T]; \end{cases}$$

$$(3.39) \quad \begin{cases} \text{there exists } M_i > 0 \text{ such that for } t \in [0, T], \\ M_i \geq \int_0^t g_i(t, s) \phi_i(s) \left[\tau_i(\theta_1 M_1, \theta_2 M_2, \dots, \theta_n M_n) \right. \\ \left. + \rho_i \left(\theta_1 \rho_1(\theta_1 M_1, \theta_2 M_2, \dots, \theta_n M_n) \int_0^s g_1(s, x) \phi_1(x) dx, \right. \right. \\ \left. \theta_2 \rho_2(\theta_1 M_1, \theta_2 M_2, \dots, \theta_n M_n) \int_0^s g_2(s, x) \phi_2(x) dx, \dots, \right. \\ \left. \left. \theta_n \rho_n(\theta_1 M_1, \theta_2 M_2, \dots, \theta_n M_n) \int_0^s g_n(s, x) \phi_n(x) dx \right) \right] ds \\ \left. \geq \rho_i(\theta_1 M_1, \theta_2 M_2, \dots, \theta_n M_n) \int_0^t g_i(t, s) \phi_i(s) ds. \right. \end{cases}$$

Then, (3.36) has a constant-sign solution $u \in (C[0, T])^n$ with $\theta_i u_i(t) > 0$, almost every $t \in [0, 1]$, $1 \leq i \leq n$.

System $(F)_\infty$. We shall now study the system of Fredholm integral equations $(F)_\infty$, where the nonlinearities f_i , $1 \leq i \leq n$ may be singular at $u_j = 0$, $j \in \{1, 2, \dots, n\}$ and may also be singular in the independent variable at some set $\Omega \subset [0, \infty)$ with measure zero. Let the Banach space $B = \{u \mid u \in (BC[0, \infty))^n\}$ be equipped with the norm $\|u\| = \max_{1 \leq i \leq n} \sup_{t \in [0, \infty)} |u_i(t)|$. Note that $BC[0, \infty)$ is the space of bounded continuous functions on $[0, \infty)$. Let $C_l[0, \infty)$ be defined as in (2.1). We are interested to obtain a solution of $(F)_\infty$ in $(C_l[0, \infty))^n$.

Theorem 3.7. *Let $\theta_i \in \{1, -1\}$, $1 \leq i \leq n$ be fixed, and let integers p, q be such that $1 \leq p \leq q \leq \infty$ and $1/p + 1/q = 1$. For each $1 \leq i \leq n$, suppose the following conditions are satisfied:*

$$(3.40) \quad \begin{cases} g_i^t(s) \equiv g_i(t, s) \geq 0 \text{ for all } t \in [0, \infty), \text{ a.e. } s \in [0, \infty) \text{ and} \\ g_i^t(s) > 0 \text{ for a.e. } t \in [0, \infty), \text{ a.e. } s \in [0, \infty); \end{cases}$$

$$(3.41) \quad \begin{cases} g_i^t(s) \in L^p[0, \infty) \text{ for all } t \in [0, \infty) \text{ and} \\ \text{the map } t \rightarrow g_i^t \text{ is continuous from } [0, \infty) \text{ to } L^p[0, \infty); \end{cases}$$

$$(3.42) \quad \begin{cases} \text{there exists } \tilde{g}_i \in L^p[0, 1) \text{ s.t. } g_i^t \rightarrow \tilde{g}_i \text{ in } L^p[0, \infty) \text{ as } t \rightarrow \infty, \\ \text{i.e., } \lim_{t \rightarrow \infty} \|g_i^t - \tilde{g}_i\|_p = 0; \end{cases}$$

$$(3.43) \quad \begin{cases} f_i : [0, \infty) \times (\mathbf{R} \setminus \{0\})^n \rightarrow \mathbf{R} \text{ with } t \rightarrow f_i(t, u) \text{ measurable} \\ \forall u \in (\mathbf{R} \setminus \{0\})^n \text{ and } u \rightarrow f_i(t, u) \text{ continuous for a.e. } t \in (0, \infty); \end{cases}$$

$$(3.44) \quad \begin{cases} \text{for any } r_i > 0, \text{ there exists } \psi_{r_i, i} : [0, \infty) \rightarrow \mathbf{R}, \\ \psi_{r_i, i}(t) > 0 \text{ for a.e. } t \in [0, \infty), \psi_{r_i, i} \in L^q[0, \infty) \\ \text{such that for all } |u_j| \in (0, r_j], 1 \leq j \leq n, \\ \theta_i f_i(t, u) \geq \psi_{r_i, i}(t) \text{ for a.e. } t \in [0, \infty); \end{cases}$$

(3.45)

$$\left\{ \begin{array}{l} \text{for any } r_i > 0 \text{ with } \int_0^\infty g_i(t, s)\psi_{r_i, i}(s) ds \leq r_i \text{ for } t \in [0, \infty), \\ \exists h_{r_i, i} : [0, \infty) \rightarrow \mathbf{R}, h_{r_i, i}(t) \geq 0 \text{ for a.e. } t \in [0, \infty), \\ h_{r_i, i} \in L^q[0, \infty) \text{ s.t. } \forall |u_j| \in \left[\int_0^\infty g_j(t, s)\psi_{r_j, j}(s) ds, r_j \right], 1 \leq j \leq n, \\ \theta_i f_i(t, u) \leq h_{r_i, i}(t) \text{ for a.e. } t \in [0, \infty); \end{array} \right.$$

$$(3.46) \quad \left\{ \begin{array}{l} \text{there exists } M_i > 0 \text{ such that for } t \in [0, \infty), \\ M_i \geq \int_0^\infty g_i(t, s)h_{M_i, i}(s) ds \geq \int_0^\infty g_i(t, s)\psi_{M_i, i}(s) ds. \end{array} \right.$$

Then, $(F)_\infty$ has a constant-sign solution $u \in (C_1[0, \infty))^n$ with $\theta_i u_i(t) > 0$, almost every $t \in [0, \infty)$, $1 \leq i \leq n$.

Proof. To begin, we define

$$D = \left\{ u \in (C_1[0, \infty))^n \mid \int_0^\infty g_i(t, s)h_{M_i, i}(s) ds \geq \theta_i u_i(t) \geq \int_0^\infty g_i(t, s)\psi_{M_i, i}(s) ds \text{ for } t \in [0, \infty), 1 \leq i \leq n \right\}.$$

Clearly, D is a closed subset of $(C_1[0, \infty))^n$ as $(C_1[0, \infty))^n$ is a closed subspace of $(BC[0, \infty))^n$. Let the operator $S : D \rightarrow (BC[0, \infty))^n$ be defined by

$$(3.47) \quad Su(t) = (S_1u(t), S_2u(t), \dots, S_nu(t)), \quad t \in [0, \infty)$$

where

$$(3.48) \quad S_iu(t) = \int_0^\infty g_i(t, s)f_i(s, u(s)) ds, \quad t \in [0, \infty), \quad 1 \leq i \leq n.$$

It is clear that a fixed point of the operator S is a solution of system $(F)_\infty$. Indeed, a fixed point of S obtained in D will be a *constant-sign solution* of system $(F)_\infty$.

First we shall show that S maps D into D . Let $u \in D$. Using a similar argument as in the proof of Theorem 3.1, we obtain

$$\psi_{M_i,i}(t) \leq \theta_i f_i(t, u) \leq h_{M_i,i}(t), \quad \text{a.e. } t \in [0, \infty), \quad 1 \leq i \leq n,$$

and so

$$(3.49) \quad \int_0^\infty g_i(t, s) \psi_{M_i,i}(s) ds \leq \theta_i S_i u(t) \leq \int_0^\infty g_i(t, s) h_{M_i,i}(s) ds, \\ t \in [0, \infty), \quad 1 \leq i \leq n.$$

It also follows from (3.49) and (3.46) that

(3.50)

$$|S_i u(t)| \leq \int_0^\infty g_i(t, s) h_{M_i,i}(s) ds \leq M_i, \quad t \in [0, \infty), \quad 1 \leq i \leq n,$$

i.e., $S_i u$, $1 \leq i \leq n$ are bounded. Moreover, $S_i u \in C[0, \infty)$, $1 \leq i \leq n$ since if $t, t' \in [0, \infty)$, then (3.41) and (3.45) provide

(3.51)

$$|S_i u(t) - S_i u(t')| \\ \leq \int_0^\infty |g_i(t, s) - g_i(t', s)| h_{M_i,i}(s) ds \\ \leq \left(\int_0^\infty |g_i^t(s) - g_i^{t'}(s)|^p ds \right)^{1/p} \left(\int_0^\infty [h_{M_i,i}(s)]^q ds \right)^{1/q} \longrightarrow 0$$

as $t \rightarrow t'$. It remains to show that $\lim_{t \rightarrow \infty} S_i u(t)$, $1 \leq i \leq n$ exist. Applying (3.42), we get for $1 \leq i \leq n$,

$$\int_0^\infty |[g_i^t(s) - \tilde{g}_i(s)] f_i(s, u(s))| ds \\ \leq \int_0^\infty |g_i^t(s) - \tilde{g}_i(s)| h_{M_i,i}(s) ds \\ \leq \left(\int_0^\infty |g_i^t(s) - \tilde{g}_i(s)|^p ds \right)^{1/p} \left(\int_0^\infty [h_{M_i,i}(s)]^q ds \right)^{1/q} \longrightarrow 0$$

as $t \rightarrow \infty$. Hence, it follows that

$$\begin{aligned}
 (3.52) \quad \lim_{t \rightarrow \infty} S_i u(t) &= \lim_{t \rightarrow \infty} \int_0^\infty g_i^t(s) f_i(s, u(s)) ds \\
 &= \int_0^\infty \tilde{g}_i(s) f_i(s, u(s)) ds, \quad 1 \leq i \leq n.
 \end{aligned}$$

This completes the proof of $S : D \rightarrow D$. \square

Next, using a similar argument as in the proof of Theorem 3.1, we see that $S : D \rightarrow D$ is continuous.

Finally, we shall show that $S : D \rightarrow D$ is compact. Let $u \in D$. Then, clearly, from (3.50)

$$\begin{aligned}
 (3.53) \quad \sup_{t \in [0, \infty)} |S_i u(t)| &\leq \sup_{t \in [0, \infty)} \int_0^\infty g_i(t, s) h_{M_i, i}(s) ds \leq M_i, \\
 &1 \leq i \leq n,
 \end{aligned}$$

or $\|Su\| \leq \max_{1 \leq i \leq n} M_i$. Further, we have (3.51) as $t \rightarrow t'$. Also, for each $1 \leq i \leq n$, from (3.52) it follows that, given $\varepsilon_i > 0$, there exists $T_i > 0$ such that $|S_i u(t) - S_i u(\infty)| < \varepsilon_i$ for any $t \geq T_i$. Now, Theorem 2.4 guarantees that S is compact.

Hence, it follows from Theorem 2.1 that S has a fixed point in D . This completes the proof. \square

Remark 3.6. In Theorem 3.7, the condition (3.45) can be replaced by the following:

$$(3.45)' \quad \left\{ \begin{array}{l} \text{for any } r_i > 0 \text{ with } \int_0^\infty g_i(t, s) \psi_{r_i, i}(s) ds \leq r_i \text{ for } t \in [0, \infty), \text{ let} \\ h_{r_i, i}(t) = \sup\{f_i(t, u) : |u_j| \in \left[\int_0^\infty g_j(t, s) \psi_{r_j, j}(s) ds, r_j \right], \\ 1 \leq j \leq n\} \text{ and assume } h_{r_i, i} \in L^q[0, \infty). \end{array} \right.$$

Remark 3.7. If $f_i, 1 \leq i \leq n$ are nonsingular, i.e., $f_i : [0, \infty) \times \mathbf{R}^n \rightarrow \mathbf{R}$, then we can have a variant of Theorem 3.7 with (3.44)–(3.46)

replaced by the following conditions:

$$\begin{cases} \text{for any } r_i > 0, \text{ there exists } h_{r_i,i} : [0, \infty) \rightarrow \mathbf{R}, \\ h_{r_i,i}(t) \geq 0 \text{ for a.e. } t \in [0, \infty), \\ h_{r_i,i} \in L^q[0, \infty) \text{ such that for all } |u_j| \in [0, r_j], 1 \leq j \leq n, \\ 0 \leq \theta_i f_i(t, u) \leq h_{r_i,i}(t) \text{ for a.e. } t \in [0, \infty); \end{cases}$$

there exists $M_i > 0$ such that for $t \in [0, \infty)$, $M_i \geq \int_0^\infty g_i(t, s) h_{M_i,i}(s) ds \geq 0$.

Moreover, the conclusion of the modified Theorem 3.7 becomes: system $(F)_\infty$ has a constant-sign solution $u \in (C_1[0, \infty))^n$ with $\theta_i u_i(t) \geq 0$, $t \in [0, \infty)$, $1 \leq i \leq n$.

Using a similar argument as in the proof of Theorem 3.2, we obtain the following result.

Theorem 3.8. *Let $\theta_i \in \{1, -1\}$, $1 \leq i \leq n$ be fixed and integers p, q be such that $1 \leq p \leq q \leq \infty$ and $1/p + 1/q = 1$. For each $1 \leq i \leq n$, suppose (3.40)–(3.44) hold and the following conditions are satisfied:*

$$(3.54) \quad \begin{cases} \theta_i f_i(t, u) \leq \phi_i(t) [\rho_i(u) + \tau_i(u)] \\ \text{for } (t, u) \in [0, \infty) \times \prod_{j=1}^n [0, \infty)_j, \text{ where} \\ \phi_i : [0, \infty) \rightarrow \mathbf{R}, \phi_i(t) > 0 \text{ for a.e. } t \in [0, \infty), \\ \rho_i, \tau_i : \prod_{j=1}^n (0, \infty)_j \rightarrow (0, \infty) \text{ are continuous,} \\ \text{if } |u_j| \leq |v_j| \text{ for some } j \in \{1, 2, \dots, n\}, \\ \text{then } \rho_i(u_1, \dots, u_j, \dots, u_n) \geq \rho_i(u_1, \dots, v_j, \dots, u_n) \text{ and} \\ \tau_i(u_1, \dots, u_j, \dots, u_n) \leq \tau_i(u_1, \dots, v_j, \dots, u_n); \end{cases}$$

(3.55)

$$\begin{cases} \phi_i \in L^q[0, \infty), \text{ and for any } r_j > 0, 1 \leq j \leq n, \\ \phi_i(t) \rho_i \left(\theta_1 \int_0^\infty g_1(t, s) \psi_{r_1,1}(s) ds, \theta_2 \int_0^\infty g_2(t, s) \psi_{r_2,2}(s) ds, \dots, \right. \\ \left. \theta_n \int_0^\infty g_n(t, s) \psi_{r_n,n}(s) ds \right) \in L^q[0, \infty); \end{cases}$$

(3.56)

$$\left\{ \begin{array}{l} \text{there exists } M_i > 0 \text{ such that for } t \in [0, \infty), \\ M_i \geq \int_0^\infty g_i(t, s) \phi_i(s) \left[\tau_i(\theta_1 M_1, \theta_2 M_2, \dots, \theta_n M_n) \right. \\ \left. + \rho_i \left(\theta_1 \int_0^\infty g_1(s, x) \psi_{M_1, 1}(x) dx, \theta_2 \int_0^\infty g_2(s, x) \psi_{M_2, 2}(x) dx, \dots, \right. \right. \\ \left. \left. \theta_n \int_0^\infty g_n(s, x) \psi_{M_n, n}(x) ds \right) \right] dx \\ \geq \int_0^\infty g_i(t, s) \psi_{M_i, i}(s) ds. \end{array} \right.$$

Then, $(F)_\infty$ has a constant-sign solution $u \in (C_1[0, \infty))^n$ with $\theta_i u_i(t) > 0$, almost every $t \in [0, \infty)$, $1 \leq i \leq n$.

As an application of Theorem 3.8, we consider a special case of system $(F)_\infty$, viz.,

$$(3.57) \quad \begin{aligned} u_i(t) &= \int_0^\infty g_i(t, s) \theta_i \phi_i(s) [\rho_i(u(s)) + \tau_i(u(s))] ds, \\ t &\in [0, \infty), \quad 1 \leq i \leq n, \end{aligned}$$

where $\theta_i \in \{1, -1\}$, $1 \leq i \leq n$ are fixed. A similar argument as in the proof of Theorem 3.3 yields the following result.

Theorem 3.9. *Let $\theta_i \in \{1, -1\}$, $1 \leq i \leq n$ be fixed and integers p, q be such that $1 \leq p \leq q \leq \infty$ and $1/p + 1/q = 1$. For each $1 \leq i \leq n$, suppose (3.40)–(3.42) hold and the following conditions are satisfied:*

$$(3.58) \quad \left\{ \begin{array}{l} \phi_i : [0, \infty) \rightarrow \mathbf{R}, \phi_i(t) > 0 \text{ for a.e. } t \in [0, \infty), \\ \rho_i, \tau_i : \prod_{j=1}^n (0, \infty)_j \rightarrow (0, \infty) \text{ are continuous,} \\ \text{if } |u_j| \leq |v_j| \text{ for some } j \in \{1, 2, \dots, n\}, \\ \text{then } \rho_i(u_1, \dots, u_j, \dots, u_n) \geq \rho_i(u_1, \dots, v_j, \dots, u_n) \text{ and} \\ \tau_i(u_1, \dots, u_j, \dots, u_n) \leq \tau_i(u_1, \dots, v_j, \dots, u_n); \end{array} \right.$$

(3.59)

$$\left\{ \begin{array}{l} \phi_i \in L^q[0, \infty), \text{ and for any } r_j > 0, 1 \leq j \leq n, \\ \phi_i(t) \rho_i \left(\theta_1 \rho_1(\theta_1 r_1, \theta_2 r_2, \dots, \theta_n r_n) \int_0^\infty g_1(t, s) \phi_1(s) ds, \right. \\ \left. \theta_2 \rho_2(\theta_1 r_1, \theta_2 r_2, \dots, \theta_n r_n) \int_0^\infty g_2(t, s) \phi_2(s) ds, \dots, \right. \\ \left. \theta_n \rho_n(\theta_1 r_1, \theta_2 r_2, \dots, \theta_n r_n) \int_0^\infty g_n(t, s) \phi_n(s) ds \right) \in L^q[0, \infty); \end{array} \right.$$

$$(3.60) \left\{ \begin{array}{l} \text{there exists } M_i > 0 \text{ such that for } t \in [0, \infty), \\ M_i \geq \int_0^\infty g_i(t, s) \phi_i(s) \left[\tau_i(\theta_1 M_1, \theta_2 M_2, \dots, \theta_n M_n) \right. \\ \left. + \rho_i(\theta_1 \rho_1(\theta_1 M_1, \theta_2 M_2, \dots, \theta_n M_n) \int_0^\infty g_1(s, x) \phi_1(x) dx, \right. \\ \left. \theta_2 \rho_2(\theta_1 M_1, \theta_2 M_2, \dots, \theta_n M_n) \int_0^\infty g_2(s, x) \phi_2(x) dx, \dots, \right. \\ \left. \theta_n \rho_n(\theta_1 M_1, \theta_2 M_2, \dots, \theta_n M_n) \int_0^\infty g_n(s, x) \phi_n(x) dx \right] ds \\ \left. \geq \rho_i(\theta_1 M_1, \theta_2 M_2, \dots, \theta_n M_n) \int_0^\infty g_i(t, s) \phi_i(s) ds. \right. \end{array} \right.$$

Then, (3.57) has a constant-sign solution $u \in (C_l[0, \infty))^n$ with $\theta_i u_i(t) > 0$, almost every $t \in [0, \infty)$, $1 \leq i \leq n$.

In Theorems 3.7–3.9, we require solutions of $(F)_\infty$ to lie in $(C_l[0, \infty))^n$. We shall now seek solutions of $(F)_\infty$ in $(C[0, \infty))^n$. Since $C[0, \infty)$ is a Fréchet space, we shall apply the Schauder-Tychonoff fixed point theorem (Theorem 2.2) instead of the Schauder fixed point theorem (Theorem 2.1).

Theorem 3.10. *Let $\theta_i \in \{1, -1\}$, $1 \leq i \leq n$ be fixed, and let integers p, q be such that $1 \leq p \leq q \leq \infty$ and $1/p + 1/q = 1$. For each $1 \leq i \leq n$, suppose (3.40), (3.41) and (3.43)–(3.46) are satisfied. Then, $(F)_\infty$ has a constant-sign solution $u \in (BC[0, \infty))^n$ with $\theta_i u_i(t) > 0$, almost every $t \in [0, 1)$, $1 \leq i \leq n$.*

Proof. To begin, we define

$$D = \left\{ u \in (C[0, \infty))^n \mid u \in (BC[0, \infty))^n \text{ and} \right. \\ \left. \int_0^\infty g_i(t, s) h_{M_i, i}(s) ds \geq \theta_i u_i(t) \geq \int_0^\infty g_i(t, s) \psi_{M_i, i}(s) ds \right. \\ \left. \text{for } t \in [0, \infty), 1 \leq i \leq n \right\}.$$

Clearly, D is a closed (Note (3.46)) convex subset of the Fréchet space $(C[0, \infty))^n$. Let the operator $S : D \rightarrow (C[0, \infty))^n$ be defined by (3.47) and (3.48). As seen from (3.49)–(3.51), we have $S : D \rightarrow D$.

Next, $S : D \rightarrow D$ is compact since we have (3.53) for $u \in D$ which gives $\|Su\| \leq \max_{1 \leq i \leq n} M_i$, and we already have (3.51) as $t \rightarrow t'$.

Finally, we shall show that $S : D \rightarrow D$ is continuous. Let $\{u^m\}$ be a sequence in D and $u^m \rightarrow u$ in $(C[0, \infty))^n$, i.e., $u_i^m \rightarrow u_i$ in $C[0, \infty)$, $1 \leq i \leq n$. Then, for each $1 \leq i \leq n$, $u_i^m \rightarrow u_i$ in $C[0, k]$ for each $k \in \mathbf{Z}^+$, and u_i^m converges pointwise to u_i on $[0, \infty)$. Fix $k \in \mathbf{Z}^+$. Using a similar argument as in the proof of Theorem 3.1, we see that for each $1 \leq i \leq n$, $S_i u^m(t) \rightarrow S_i u(t)$ for each $t \in [0, \infty)$, and $S_i u^m \rightarrow S_i u$ in $C[0, k]$. Since this is true for each $k \in \mathbf{Z}^+$, it follows that $S_i u^m \rightarrow S_i u$ in $C[0, \infty)$. Hence, $S : D \rightarrow D$ is continuous.

We now conclude from Theorem 2.2 that S has a fixed point in D .
□

Remark 3.8. Remarks 3.6 and 3.7 (with $(C_i[0, \infty))^n$ replaced by $(BC[0, \infty))^n$) also hold for Theorem 3.10.

A similar argument as in Theorems 3.8 and 3.9 give the following results.

Theorem 3.11. *Let $\theta_i \in \{1, -1\}$, $1 \leq i \leq n$ be fixed, and let integers p, q be such that $1 \leq p \leq q \leq \infty$ and $1/p + 1/q = 1$. For each $1 \leq i \leq n$, suppose (3.40), (3.41), (3.43), (3.44) and (3.54)–(3.56) hold. Then, $(F)_\infty$ has a constant-sign solution $u \in (BC[0, \infty))^n$ with $\theta_i u_i(t) > 0$, almost every $t \in [0, \infty)$, $1 \leq i \leq n$.*

Theorem 3.12. *Let $\theta_i \in \{1, -1\}$, $1 \leq i \leq n$ be fixed, and let integers p, q be such that $1 \leq p \leq q \leq \infty$ and $1/p + 1/q = 1$. For each $1 \leq i \leq n$, suppose (3.40), (3.41) and (3.58)–(3.60) hold. Then, (3.57) has a constant-sign solution $u \in (BC[0, \infty))^n$ with $\theta_i u_i(t) > 0$, almost every $t \in [0, \infty)$, $1 \leq i \leq n$.*

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