BOUNDS FOR MATRIX MOMENTS

GENE H. GOLUB*

1. Introduction. Let A be a real symmetric positive definite $n \times n$ matrix with

$$Au_i = \lambda_i u_i, \quad (i = 1, 2, \cdots, n)$$

 $u_i^T u_j = \delta_{ij}$, and $0 < \lambda_1 \leq \lambda_2 \leq \cdots \leq \lambda_n$. Let r_0 be an arbitrary vector and consider the Krylov sequence

$$r_{i+1} = Ar_i$$
, for $i = 0, 1, \dots, k-1$,

so that

$$r_i = A^i r_0 \quad (i = 0, 1, \cdots, k).$$

Let

$$\mu_{p,q} = r_p^T r_q = (A^p r_0)^T A^q r_0$$
$$= r_0^T A^{p+q} r_0$$
$$\equiv \mu_{p+q}.$$

Thus if $r_0 = \sum_{i=1}^n \alpha_i u_i$,

$$\boldsymbol{\mu}_m = \sum_{i=1}^m \alpha_i^2 \lambda_i^m \equiv \int \lambda^m \, d\boldsymbol{\alpha}(\lambda) \quad (m = 0, 1, \cdots, 2k)$$

where $\alpha(\lambda) = 0$ for $\lambda \leq \lambda_1$,

$$= \alpha_1^2 + \cdots + \alpha_t^2 \quad \lambda_t < \lambda \leq \lambda_{t+1},$$
$$= \alpha_1^2 + \cdots + \alpha_n^2 \quad \lambda_n < \lambda.$$

Thus, $\{\mu_m\}_{m=1}^{2k}$ are a set of moments associated with the distribution function $\alpha(\lambda)$.

In certain applications (cf. [1]) we are interested in determining bounds for μ_s where s is a positive integer greater than 2k or a negative integer. We shall construct algorithms for computing bounds on μ_s where we have an upper bound on the largest eigenvalue and a positive lower bound on the smallest eigenvalue, e.g.,

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G. GOLUB

$$0 < a \leq \lambda_i \leq b$$
 $i = 1, \dots, n$.

Note that when the eigenvalues are known precisely linear programming may be used for determining upper and lower bounds on μ_s (cf. [1]).

2. Construction of bounds. Suppose we are given $\{\mu_i\}_{i=0}^{2k}$, and a function $\varphi(\lambda)$, $(a \leq \lambda \leq b)$ and we wish to determine (L, U) so that

$$L \leq \int_{a}^{b} \varphi(\lambda) \, d\alpha(\lambda) \leq U.$$

We can determine a Gauss-Radau quadrature rule so that

$$\boldsymbol{\mu}_{r} = \sum_{i=0}^{k} A_{i} t_{i}^{r} \quad \text{for } r = 0, 1, \cdots, 2k$$

where $\{A_i\}_{i=0}^k$ and $\{t_i\}_{i=1}^k$ are unknown and t_0 is specified. Then

$$\int_{a}^{b} \varphi(\lambda) \, d\alpha(\lambda) = \sum_{i=0}^{k} A_{i} \varphi(t_{i}) + R[\varphi]$$

where

$$R[\varphi] = \frac{\varphi^{(2k+1)}(\eta)}{(2k+1)!} \int_a^b (\lambda - t_0) \left[\prod_{i=1}^k (\lambda - t_i) \right]^2 d\alpha(\lambda), a < \eta < b.$$

Thus if $\varphi(\lambda) = \lambda^s$,

$$R[\lambda^{s}] = \left(\begin{array}{c}s\\2k+1\end{array}\right) \eta^{s-(2k+1)} \times \\ \int_{a}^{b} (\lambda - t_{0}) \left[\prod_{i=1}^{k} (\lambda - t_{i})\right]^{2} d\alpha(\lambda), a < \eta < b.$$

Hence, if s > 2k and $t_0 = a$, then $R[\lambda^s] \ge 0$ and hence the Gauss-Radau rule yields an upper bound and if $t_0 = b$, a lower bound. However if s < 0 and $t_0 = a$, then $R[\lambda^s] \le 0$ and hence the Gauss-Radau rule yields an upper bound and if $t_0 = b$, a lower bound. It can be shown that these bounds are attainable (cf. [2]).

Unfortunately, using the moments for computing the quadrature rules is a very ill-conditioned numerical problem [3]. We can avoid this difficulty by working with orthogonal polynomials which are defined by the distribution function $\alpha(\lambda)$.

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3. The Lanczos algorithm. Associated with the distribution function $\alpha(\lambda)$, there is a set of orthogonal polynomials $\{p_i(\lambda)\}$ such that

$$\int_{a}^{b} p_{m}(\lambda) p_{\ell}(\lambda) \ d\alpha(\lambda) = 0 \text{ when } m \neq \ell.$$

It is well known that these polynomials satisfy the relationship

(3.1)
$$p_{j+1}(\lambda) = (\xi_{j+1} - \lambda)p_j(\lambda) - \eta_j^2 p_{j-1}(\lambda)$$

with $p_{-1}(\lambda) = 0$, $p_0(\lambda) = 1$. The zeros of $p_k(\lambda)$ are the nodes of the Gauss quadrature rule associated with $\alpha(\lambda)$ and $\{\mu_j\}_{j=0}^{2k-1}$; e.g., $p_k(t_i) = 0$ $(i = 1, 2, \dots, k)$, $\int_a^b \lambda^r d\alpha(\lambda) = \sum_{i=1}^k A_i t_i^r$ $(i = 0, 1, \dots, 2k-1)$. The coefficients of (3.1) can be calculated directly from the moments but this is also a numerically unstable process.

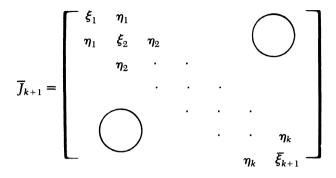
The coefficients $\{\xi_j\}_{j=1}^k$, $\{\eta_j^2\}_{j=1}^{k-1}$ can be computed directly using the Lanczos algorithm [4]. We generate a sequence of vectors $\{z_j\}_{j=0}^{k+1}$ such that

$$\mathbf{z}_i^T \mathbf{z}_j = \begin{cases} 0 & \text{for } i \neq j \\ 1 & \text{for } i = j. \end{cases}$$

Let $z_0 = r_0 \times (||r_0||)^{-1}$ $(||r_0|| = (r_0^T r_0)^{1/2})$. Then for $j = 0, 1, \dots, k$,

$$\begin{split} \xi_{j+1} &= z_j^T A z_j, \\ w_{j+1} &= A z_j - \xi_{j+1} z_j - \eta_j^2 z_{j-1}, \quad (\eta_0 = 0), \\ \eta_{j+1} &= \| w_{j+1} \| \\ z_{j+1} &= \eta_{j+1} \times w_{j+1}. \end{split}$$

For numerical stability, one must reorthogonalize z_{j+1} with respect to all the previous z_j 's (cf. [5]). It is well known (cf. [6]) that the eigenvalues of the symmetric tridiagonal matrix $J_k = \{\eta_{j-1}, \xi_j, \eta_j\}$ are the roots of the polynomial $p_k(\lambda)$ and that the square of the first component of the orthonormalized eigenvectors is the associated weight of the quadrature rule when $\mu_0 = 1$. The eigenvalues of J_k and the first component of the eigenvectors can be efficiently and accurately computed by the QR method of Francis ([7]). Let



We wish to compute the element $\overline{\xi}_{k+1}$ so that $p_{k+1}(t_0) = 0$, and thus the eigenvalues and eigenvectors of \overline{J}_{k+1} yield the Gauss-Radau rule. Now

$$0 = p_{k+1}(t_0) = (t_0 - \bar{\xi}_{k+1})p_k(t_0) - \eta_k^2 p_{k-1}(t_0),$$

and hence,

$$\bar{\xi}_{k+1} = t_0 - \eta_k^2 p_{k-1}(t_0) / p_k(t_0).$$

The quantity $\rho_{k-1} \equiv p_k(t_0)/p_{k-1}(t_0)$ can be easily computed. Defining $\rho_j = p_{j+1}(t_0)/p_j(t_0)$ $(j = 0, 1, \dots, k-1)$, then $\rho_j = (t_0 - \xi_{j+1}) - \eta_j^2/\rho_{j-1}$ with $\rho_1 = (t_0 - \xi_1)$.

It is not necessary to compute the eigenvalues and eigenvectors of J_{k+1} to compute upper and lower bounds on μ_s . Let

$$\bar{J}_{k+1} = QTQ^T, QQ^T = I_{k+1},$$

where T is the diagonal matrix of eigenvalues of \bar{J}_{k+1} and Q is the matrix of eigenvectors. The vector $w_0 = Q^T e_1$, $(e_1^T = (1, 0, \dots, 0))$ consists of the first element of each eigenvector of \bar{J}_{k+1} . Hence

$$\sum_{i=0}^{k} A_{i}t_{i}^{s} = e_{1}^{T}\bar{J}_{k+1}^{s}e_{1}$$

If s = 2p (say), then $\sum_{i=0}^{k} A_i t_i^s = (e_1^T \overline{J}_{k+1}^p)(\overline{J}_{k+1}^p e_1)$. And if s is negative it is only necessary to repeatedly solve the tridiagonal system of equations $\overline{J}_{k+1}^p f = e_1$.

4. A numerical example. Let A be the tridiagonal matrix $A = \{-1, 2, -1\}$ so that $a = 2 - 2\cos(\pi/(n + 1))$, $b = 2 + 2\cos(\pi/(n + 1))$. The vector r_0 is a random vector with $||r_0|| = 1.07188$. We wish to construct upper and lower bounds for s = -2 when n = 25. The exact

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solution is $\mu_{-2} = 1.0$. Using the Lanczos algorithm we have the following bounds.

k	lower bound	upper bound
1	.36834	18.99795
2	.43465	9.62961
3	.46049	4.51138
4	.47367	2.76067
5	.49212	2.11169
23	.999820503726357	1.00000054223912
24	.999999999914178	1.0000000000003

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STANFORD UNIVERSITY, STANFORD, CALIFORNIA 94503