# OSCILLATION PROPERTIES OF THIRD ORDER DIFFERENTIAL EQUATIONS 

GARY D. JONES


#### Abstract

Oscillation properties of elements of possible bases for the solution space of a third order linear differential equation are considered.


1. Introduction. We will consider the differential equation

$$
\begin{equation*}
y^{\prime \prime \prime}+p(x) y^{\prime}+q(x) y=0 \tag{1}
\end{equation*}
$$

and its adjoint

$$
\begin{equation*}
y^{\prime \prime \prime}+p(x) y^{\prime}+\left(p^{\prime}(x)-q(x)\right) y=0 \tag{2}
\end{equation*}
$$

where we will assume that the coefficients are continuous on $[0,+\infty)$. In particular, we will consider equations which are of Class I or Class II as defined by Hanan [1].

We will consider a solution of (1) oscillatory if it changes sign for arbitrarily large $x$.

It has been shown by Utz [3], that the solution space of equation (1) can have at the same time a basis consisting of $i$ oscillatory solutions and $3-i$ nonoscillatory solutions, for $i=0,1,2,3$.

We will describe the types of bases possible for the solution spaces of equations (1) of Class I and Class II, with respect to the number of oscillatory solutions possible in a given basis. In doing so, we will generalize a theorem of Utz [3].
2. An equation (1) is said to be Class I if any solution for which $y(a)=y^{\prime}(a)=0, y^{\prime \prime}(a)>0$ is positive on $[0, a)$. It is said to be Class II if any solution for which $y(a)=y^{\prime}(a)=0, y^{\prime \prime}(a)>0$ is positive on $(a,+\infty)$. It was shown by Hanan [1] that (1) is Class I if and only if (2) is Class II.

In [1], Hanan considers a solution $y(x)$ of (1) to be oscillatory if it has an infinity of zeros in [ $0,+\infty$ ), but it follows from the definitions that if (1) is Class I or Class II, then this definition of oscillation implies $y(x)$ must change signs for arbitrarily large $x$.

We will use a method similar to that used by Lazer [2, p. 437] to prove the following lemma.

Received by the editors September 10, 1971 and, in revised form, January 31, 1972.

AMS (MOS) subject classifications (1970). Primary 34A30; Secondary 34C10.

Lemma. If (1) is Class I, and if (1) has an oscillatory solution, then there exists a nontrivial nonoscillatory solution such that $y(x)>0$ for $x \in[0,+\infty)$.

Proof. Let $u(x), v(x), w(x)$ be a basis for the solution space of (1). Let

$$
y_{n}(x) \equiv C_{n, 1} u(x)+C_{n, 2} v(x)+C_{n, 3} w(x)
$$

where $y_{n}(n)=y_{n}{ }^{\prime}(n)=0, \quad y_{n}{ }^{\prime \prime}(n)>0, \quad$ and where $C_{n, 1}^{2}+C_{n, 2}^{2}+$ $C_{n, 3}^{2}=1$. Suppose further, without loss of generality, that $\lim C_{n, i}=$ $C_{i}$ for $i=1,2,3$. Let

$$
y(x)=C_{1} u(x)+C_{2} v(x)+C_{3} w(x)
$$

Since $\left\{y_{n}(x)\right\}$ converges to $y(x)$ uniformly on any finite subinterval of $(0,+\infty)$, we have $y(x) \geqq 0$. Now $y(x) \neq 0$ since $C_{1}{ }^{2}+C_{2}{ }^{2}+C_{3}{ }^{2}$ $=1$. Further, by [1] if there is an $x_{1}$ such that $y\left(x_{1}\right)=0$, then $y$ is oscillatory. Thus, $y(x)>0$ for all $x$.

Using Lemma 1.1 of [2], we observe that Utz in Theorem 2 [3] is considering a special equation of Class I. Thus the following theorem will generalize the result of Utz.

Theorem 1. If (1) is Class I, and if some solution oscillates, then the solution space of (1) has a basis with three oscillatory solutions, and a basis with exactly two oscillatory solutions.

Proof. By the lemma, there is a nonoscillatory solution $w(x)$ of (1). By [1] any solution of (1) that vanishes at least once is oscillatory. Let $w(x), u(x), v(x)$ be solutions of (1) which form a basis, where $w(x)$ is nonoscillatory and $u(x)$ is oscillatory.

Let $a \in(0, \infty)$ such that $u(a) v(a) \neq 0$. Choose constants $k_{1}$ and $k_{2}$ such that $v(a)+k_{1} w(a)=0$ and $v(a)+k_{2} u(a)=0$. Then, $y_{1}(x) \equiv v(x)+k_{1} w(x)$ is oscillatory, $y_{2}(x) \equiv v(x)+k_{2} u(x)$ is oscillatory, and $u(x)$ is oscillatory. Further

$$
\begin{aligned}
v(x)+k_{2} u(x)-k_{2} u(x) & \equiv v(x) \\
v(x)+k_{1} w(x)-v(x) & \equiv k_{1} w(x)
\end{aligned}
$$

Since $k_{1} \neq 0, y_{1}(x), y_{2}(x)$, and $u(x)$ forms a basis for the solution space of (1).

Also, $u(x), y_{2}(x)$, and $w(x)$ is a basis for the solution space of (1).
We will now consider an equation of Class II.
Theorem 2. If (1) is Class II, and if some solution oscillates, then the solution space of (1) has a basis consisting of exactly $i$ oscillatory solutions, for $i=0,1,2$.

Proof. Since (1) has an oscillatory solution, (2) has an oscillatory solution by [1]. Also, since (1) is Class II, (2) is Class I. Let $u_{1}(x)$, $u_{2}(x), u_{3}(x)$ be a basis for the solution space of (2) such that $u_{1}(x)$ is nonoscillatory, and such that $u_{2}(x)$ and $u_{3}(x)$ are oscillatory. Then $u_{1}(x), u_{2}(x)$, and

$$
u_{3}(x)+\lambda u_{1}(x) \equiv w_{3}(x)
$$

is a basis where $\lambda$ is chosen such that

$$
u_{3}(a)+\lambda u_{1}(a)=u_{2}(a)=0
$$

for some $a \in[0,+\infty)$. Note that $u_{1}(x)$ is nonoscillatory, but $u_{2}(x)$ and $w_{3}(x)$ are oscillatory. Now

$$
\begin{aligned}
& U_{1}(x) \equiv u_{1}(x) u_{2}^{\prime}(x)-u_{2}(x) u_{1}^{\prime}(x) \\
& U_{2}(x) \equiv u_{1}(x) w_{3}^{\prime}(x)-w_{3}(x) u_{1}^{\prime}(x) \\
& U_{3}(x) \equiv u_{2}(x) w_{3}^{\prime}(x)-u_{2}^{\prime}(x) w_{3}(x)
\end{aligned}
$$

is a basis for the solution space of $(1)$. It is clear that $U_{1}(x)$, and $U_{2}(x)$ are oscillatory solutions. Now $U_{3}(a)=U_{3}{ }^{\prime}(a)=0$ implies $U_{3}(x)$ is nonoscillatory since it is a nontrivial solution of (1) which is Class II.

Let $u_{1}(x), u_{2}(x), u_{3}(x)$ be a basis for the solution space of (2) such that each is oscillatory. Let $a \in[0,+\infty)$ be such that $u_{1}(a)=0$. Not both $u_{2}(a)$ and $u_{3}(a)=0$. Suppose $u_{3}(a) \neq 0$. Choose a constant $\lambda$ such that $u_{2}(a)+\lambda u_{3}(a)=0$. Let

$$
v_{2}(x) \equiv u_{2}(x)+\lambda u_{3}(x)
$$

Now $u_{1}(x), v_{2}(x)$, and $u_{3}(x)$ is a basis for (2) where each oscillates. Since $u_{1}(a)=v_{2}(a)=0$ and they are linearly independent, their zeros separate on $(a,+\infty)$ [1]. Suppose $b$ is the first zero of $u_{1}(x)$ to the right of $a$, and $c$ is the first zero of $v_{2}(x)$ to the right of $a$. Suppose further that $b<c$. Since

$$
u_{1}(b) v_{2}(c)-u_{1}(c) v_{2}(b) \neq 0
$$

we can solve

$$
\begin{aligned}
& 0=c_{1} u_{1}(b)+c_{2} v_{2}(b)+c_{3} u_{3}(b) \\
& 0=c_{1} u_{1}(c)+c_{2} v_{2}(c)+c_{3} u_{3}(c)
\end{aligned}
$$

where $c_{3} \neq 0$. Let

$$
v_{3}(x) \equiv c_{1} u_{1}(x)+c_{2} v_{2}(x)+c_{3} u_{3}(x)
$$

Since $c_{3} \neq 0, u_{1}(x), v_{2}(x), v_{3}(x)$ is a basis for (2) where each is oscillatory. Now

$$
\begin{aligned}
& W_{1}(x) \equiv u_{1}(x) v_{2}^{\prime}(x)-v_{2}(x) u_{1}^{\prime}(x) \\
& W_{2}(x) \equiv u_{1}(x) v_{3}^{\prime}(x)-v_{3}(x) u_{1}^{\prime}(x) \\
& W_{3}(x) \equiv v_{2}(x) v_{3}^{\prime}(x)-v_{3}(x) v_{2}^{\prime}(x)
\end{aligned}
$$

is a basis for (1). Note that $W_{1}(a)=W_{1}{ }^{\prime}(a)=W_{2}(b)=W_{2}{ }^{\prime}(b)=$ $W_{3}(c)=W_{3}{ }^{\prime}(c)=0$, and since (1) is Class II each is nonoscillatory.

The fact that (1) also has a basis with exactly one oscillatory solution follows immediately.

Let $u_{1}(x), u_{2}(x)$, and $u_{3}(x)$ be a basis for (2) such that $u_{1}(a)=u_{2}(a)=$ 0 for some $a \in[0,+\infty)$ and such that $u_{3}(x)>0$ for all $x$. Then

$$
\begin{aligned}
& U_{1}(x) \equiv u_{1}(x) u_{3}^{\prime}(x)-u_{3}(x) u_{1}^{\prime}(x) \\
& U_{2}(x) \equiv u_{2}(x) u_{3}^{\prime}(x)-u_{3}(x) u_{2}^{\prime}(x) \\
& U_{3}(x) \equiv u_{1}(x) u_{2}^{\prime}(x)-u_{2}(x) u_{1}^{\prime}(x)
\end{aligned}
$$

As before, $U_{1}(x), U_{2}(x)$, and $U_{3}(x)$ form a basis for (1), $U_{1}(x)$ and $U_{2}(x)$ are oscillatory, but $U_{3}(x)$ is nonoscillatory.

Theorem 3. If (1) is Class II, and if the solution space of (1) has a basis consisting of three oscillatory solutions, then the solution space of (2) has a basis with one oscillatory and two nonoscillatory solutions.

Proof. Let $U_{1}(x), U_{2}(x)$, and $U_{3}(x)$ be as in the last paragraph. Since $U_{1}(x) U_{2}^{\prime}(x)-U_{2}(x) U_{1}^{\prime}(x)=k u_{3}(x) \neq 0$, since $k \neq 0$ and $u_{3}(x)>0$, the zeros of $U_{1}(x)$ and $U_{2}(x)$ separate. If (1) has a basis with three oscillatory solutions, then some oscillatory solution $z(x)$ must be of the form

$$
z(x) \equiv U_{3}(x)+c_{1} U_{1}(x)+c_{2} U_{2}(x)
$$

Let $x_{1}<x_{2}<\cdots$ be the consecutive zeros of $z(x)$. Define

$$
y_{n}(x) \equiv k_{1, n} U_{1}(x)+k_{2, n} U_{2}(x)
$$

where $k_{1, n}^{2}+k_{2, n}^{2}=1$ and $y_{n}\left(x_{n}\right)=0$. The zeros of $y_{n}(x)$ and $z(x)$ separate to the left of $x_{n}$ by [1]. Suppose, without loss of generality, that $\lim k_{n, i}=k_{i}$ for $i=1,2$. Let

$$
y(x) \equiv k_{1} U_{1}(x)+k_{2} U_{2}(x)
$$

Since $\left\{y_{n}(x)\right\}$ converges to $y(x)$ uniformly on $\left[x_{j}, x_{j+1}\right]$, and since each $y_{n}(x)$ for $n>j+2$ changes signs on [ $x_{j}, x_{j+1}$ ], $y(x)$ must have a zero on $\left[x_{j}, x_{j+1}\right]$. Since $k_{1}{ }^{2}+k_{2}{ }^{2}=1, y(x)$ and $z(x)$ are clearly linearly independent. Thus by [1] $y(x)$ and $z(x)$ cannot have two zeros in common. Hence for $j \geqq N$ for some $N>0, y(x)$ has a zero in $\left(x_{j}, x_{j+1}\right)$.

Since $y(x)$ is a solution to (1) which is of Class II, it must change signs in $\left(x_{j}, x_{j+1}\right)$.

Suppose

$$
y\left(x_{0}\right) z^{\prime}\left(x_{0}\right)-z\left(x_{0}\right) y^{\prime}\left(x_{0}\right)=0
$$

Then the equations

$$
l_{1} y\left(x_{0}\right)+l_{2} z\left(x_{0}\right)=0, \quad l_{1} y^{\prime}\left(x_{0}\right)+l_{2} z^{\prime}\left(x_{0}\right)=0
$$

can be solved for $l_{1}$ and $l_{2}$ not both zero.
Let

$$
w(x) \equiv l_{1} y(x)+l_{2} z(x)
$$

Since $w\left(x_{0}\right)=w^{\prime}\left(x_{0}\right)=0, w(x)$ is of constant sign for $x>x_{0}$. But this is not possible since when $j \geqq N, x_{j}>x_{0}$, and $l_{2} z(x) \geqq 0$ on [ $x_{j}, x_{j+1}$ ] there is an $a \in\left(x_{j}, x_{j+1}\right)$ such that $l_{1} y(a) \geqq 0$ and $b \in\left(x_{j+1}, x_{j+2}\right)$ such that $l_{1} y(b) \leqq 0$. Thus

$$
l_{1} y(a)+l_{2} z(a) \geqq 0 \quad \text { and } \quad l_{1} y(b)+l_{2} z(b) \leqq
$$

Hence

$$
y(x) z^{\prime}(x)-z(x) y^{\prime}(x)
$$

is a nonoscillatory solution of (2).
Now

$$
\begin{aligned}
y(x) z^{\prime}(x) & -z(x) y^{\prime}(x) \\
\equiv & \left(k_{1} U_{1}(x)+k_{2} U_{2}(x)\right)\left(U_{3}^{\prime}(x)+c_{1} U_{1}^{\prime}(x)+c_{2} U_{2}^{\prime}(x)\right) \\
& \quad-\left(U_{3}(x)+c_{1} U_{1}(x)+c_{2} U_{2}(x)\right)\left(k_{1} U_{1}^{\prime}(x)+k_{2} U_{2}^{\prime}(x)\right) \\
\equiv & k\left(k_{1} u_{1}(x)+k_{1} c_{2} u_{3}(x)+k_{2} u_{2}(x)+k_{2} c_{1} u_{3}(x)\right)
\end{aligned}
$$

where $k \neq 0$. Since $k_{1}$ and $k_{2}$ are not both zero, $y(x) z^{\prime}(x)-$ $z(x) y^{\prime}(x)$ and $u_{3}(x)$ are linearly independent solutions of (2).

Theorem 4. If (1) is Class I , if some solution oscillates, and if it has a basis with two or three nonoscillatory elements, then (2) has a basis with three oscillatory elements.

Proof. If (1) has a basis with all nonoscillatory solutions, then it clearly has one with exactly one oscillatory solution. Suppose $u_{1}(x)$, $u_{2}(x)$, and $u_{3}(x)$ is a basis for the solution space of (1) where $u_{1}(x)$ is oscillatory and $u_{2}(x)$ and $u_{3}(x)$ are nonoscillatory. Let us suppose $u_{2}(a)=u_{3}(a)>0$ for some $a \in(0,+\infty)$. Now

$$
W_{1}(x) \equiv u_{1}(x) u_{2}^{\prime}(x)-u_{2}(x) u_{1}^{\prime}(x)
$$

$$
\begin{aligned}
& W_{2}(x) \equiv u_{1}(x) u_{3}^{\prime}(x)-u_{3}(x) u_{1}^{\prime}(x) \\
& W_{3}(x) \equiv u_{2}(x) u_{3}^{\prime}(x)-u_{3}(x) u_{2}^{\prime}(x)
\end{aligned}
$$

is a basis for (2). Clearly $W_{1}(x)$ and $W_{2}(x)$ are oscillatory. Since $u_{2}(a)=u_{3}(a)$, we have

$$
y(x) \equiv u_{2}(x)-u_{3}(x)
$$

is oscillatory. Let $a<a_{1}<a_{2} \cdots$ be consecutive zeros of $y(x)$. Then $y^{\prime}\left(a_{i}\right) y^{\prime}\left(a_{i+1}\right)<0$. Thus, $W_{3}\left(a_{i}\right)=u_{2}\left(a_{i}\right)\left(u_{3}{ }^{\prime}\left(a_{i}\right)-u_{2}{ }^{\prime}\left(a_{i}\right)\right)$ must have opposite signs at consecutive zeros of $y(x)$.

An example of a differential equation satisfying the hypothesis of Theorem 4 will now be given.

Example. Consider the differential equation

$$
\begin{equation*}
y^{\prime \prime \prime}+y^{\prime}+[2 /(\exp (x)+2)]\left(y+y^{\prime \prime}\right)=0 \tag{3}
\end{equation*}
$$

whose general solution is given by

$$
y(x)=C_{1} \sin x+C_{2} \cos x+C_{3}(1+\exp (-x))
$$

Clearly $\sin x, 2(1+\exp (-x))+\cos x, 1+\exp (-x)$ is a basis for the solution space of (3) with one oscillatory and two nonoscillatory elements.

By letting $y=w \exp \left(-\frac{1}{3} \int_{0}^{t} P(s) d s\right)$, where $P(s) \equiv 2 /(\exp (x)+2)$, (3) can be transformed into an equation of the form (1), which will have the same oscillatory properties as (3) and will be of Class I if (3) is of Class I.

The equation (3) is of Class I, for if it were not there would have to exist a nontrivial solution of (3) satisfying $y(a-\delta)=y(a)=y^{\prime}(a)=0$ for some $a$ and positive $\delta$. But that is not possible since

$$
\left.\begin{array}{|ccc|}
\sin a & \cos a & 1+\exp (-a) \\
\cos a & -\sin a & -\exp (-a) \\
\sin (a-\delta) & \cos (a-\delta) & 1+\exp (-a+\delta)
\end{array} \right\rvert\,, \begin{aligned}
& =\exp (-a)[\cos \delta+\sin \delta-\exp \delta]+\cos \delta-1 \\
& <\exp (-a)[\cos \delta+\sin \delta-1-\delta] \leqq 0 .
\end{aligned}
$$

Applying Theorem 4, it is clear that the adjoint of (3) satisfies the hypotheses of Theorem 3. The next theorem shows that this is not always the case.

Theorem 5. If in (1) $q(x)>0, p(x) \leqq 0$ (consequently it is of Class I), $2 p(x) / q(x)+d^{2}\left(q(x)^{-1}\right) / d x^{2} \leqq 0$, and if some solution oscillates,
then every basis for (1) is of one of the types of Theorem 1.
The proof of the theorem follows directly from a result due to Lazer [2, p. 444].

## References

1. M. Hanan, Oscillation criteria for third-order linear differential equations, Pacific J. Math. 11 (1961), 919-944. MR 26 \#2695.
2. A. C. Lazer, The behavior of solutions of the differential equation $y^{\prime \prime \prime}+p(x) y^{\prime}+q(x) y=0$, Pacific J. Math. 17 (1966), 435-466. MR 33 \#1552.
3. W. R. Utz, Oscillating solutions of third order differential equations, Proc. Amer. Math. Soc. 26 (1970), 273-276. MR 41 \#7208.

Murray State University, Murray, Kentucky 42071

