

REGULARIZED INTEGRAL FORMULATION OF MIXED DIRICHLET-NEUMANN PROBLEMS

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ABSTRACT. This paper presents a theoretical discussion as well as novel solution algorithms for problems of scattering on smooth two-dimensional domains under Zaremba boundary conditions, for which Dirichlet and Neumann conditions are specified on various portions of the domain boundary. The theoretical basis of the proposed numerical methods, which is provided for the first time in the present contribution, concerns detailed information about the singularity structure of solutions of the Helmholtz operator under boundary conditions of Zaremba type. The new numerical method is based on the use of Green functions and integral equations, and it relies on the Fourier continuation method for regularization of all smooth-domain Zaremba singularities as well as newly derived quadrature rules which give rise to high-order convergence, even around Zaremba singular points. As demonstrated in this paper, the resulting algorithms enjoy high-order convergence, and they can be used to efficiently solve challenging Helmholtz boundary value problems and Laplace eigenvalue problems with high-order accuracy.

1. Introduction. This paper concerns problems of scattering on smooth two-dimensional domains under Zaremba boundary conditions, and, in particular, it presents a theoretical discussion as well as novel solution algorithms for this problem. The theoretical basis of the proposed numerical methods concerns detailed information, put forth in Section 4, regarding the singularity structure of solutions of the Helmholtz operator under boundary conditions of Zaremba type. The new numerical method, which is based on the use of Green functions

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and integral equations, incorporates use of the Fourier continuation method for regularization of all smooth-domain Zaremba singularities as well as newly derived quadrature rules which give rise to high-order convergence, even around Zaremba singular points. As demonstrated in this paper, the resulting algorithms enjoy high-order convergence, and they can be used to efficiently solve challenging Helmholtz boundary value problems and Laplace eigenvalue problems with high-order accuracy.

Hence, we consider the classical Zaremba boundary value problem

$$(1.1) \quad \begin{aligned} \Delta u(x) + k^2 u(x) &= 0, & x \in \Omega, \\ u(x) &= f(x), & x \in \Gamma_D, \\ \frac{\partial u(x)}{\partial n_x} &= g(x), & x \in \Gamma_N, \end{aligned}$$

for the Helmholtz equation, where Ω is a two-dimensional domain with boundary Γ consisting of two disjoint portions Γ_D and Γ_N , upon which Dirichlet and Neumann values are prescribed, respectively (see Figure 1), and where a Sommerfeld radiation condition [9] is prescribed in the case where Ω is an exterior domain; full details concerning the problem under consideration are provided in Section 2.

Significant challenges arise in connection with Zaremba boundary value problems in view of the singular character of its solutions: as first established by Fichera [14], Zaremba solutions are generally non-smooth, even for infinitely differentiable boundary data f and g , and smoothness of solutions can only be ensured provided f and g obey certain relations which generically are not satisfied. Wigley [28, 29] provides a detailed description of the singularity structure around Zaremba points, which includes singularities of both square-root and logarithmic type. In Section 4 of the present paper it is shown, however, that a tighter result holds in the case where the domain boundary is itself smooth.

Problems with mixed Dirichlet-Neumann boundary conditions were first considered in Zaremba's 1910 contribution [31], which established existence and uniqueness of the solution in the particular case of the Laplace equation, $k = 0$. Boundary conditions of Zaremba type arise in a number of important areas, including elasticity theory (where it appears as a model in the contexts of contact mechanics [27] and crack

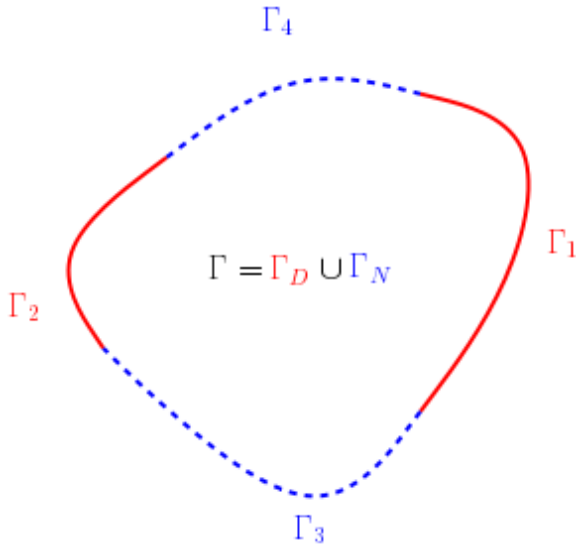


FIGURE 1. Generic smooth domain Ω with boundary partitioned into Dirichlet and Neumann regions shown in red (solid) and blue (dashed), respectively.

theory [12]); homogenization theory (as it applies to problems of steady state diffusion through perforated membranes [12]), etc. One of the main motivations for our consideration of this problem concerns computational electromagnetism: the Zaremba problem serves as a valuable stepping stone to the closely related but more complex problem of electromagnetic propagation and scattering at and around structures such as printed circuit-boards. (As in the Zaremba problem, where the boundary conditions change type at the Dirichlet-Neumann boundary, the boundary conditions for the Maxwell equations at and around circuit-boards change type, not from Dirichlet to Neumann but from dielectric transmission conditions to perfect-conductor conditions, at the edges of the perfectly conducting circuit elements.)

After the initial contribution by Zaremba, early works concerning the Zaremba boundary value problem include results by Signorini [24] (1916 solution of the Zaremba problem in the upper half plane using complex variable methods); Giraud [17] (1934 existence of solution

of Zaremba problems for general elliptic operators); Fichera [13, 14] (1949, 1952 regularity studies at Zaremba points, Zaremba-type problem for the elasticity equations in two spatial dimensions); Magenes [21] (1955 proof of existence and uniqueness, single layer potential representation); Lorenzi [20] (1975 Sobolev regularity around a corner which is also a Dirichlet-Neumann junction); and Wigley [28, 29] (1964, 1970 explicit asymptotic expansions around Dirichlet-Neumann junctions), amongst others. More recent contributions in this area include [27], which provides a valuable review in addition to a study of Zaremba singularities and theoretical results concerning Galerkin-based computational approaches; [7], which considers the Zaremba problem for the biharmonic equation; [10, 11], which study Zaremba boundary value problems for Helmholtz and Laplace-Beltrami equations; [8], which discusses the solvability of the Zaremba problem from the point of view of pseudo-differential calculus and Sobolev regularity theory; [18], which introduces a certain inverse preconditioning technique to reduce the number of linear algebra iterations for the iterative numerical solution of this problem and which gives rise to high-order convergence; and finally, [4], which successfully applies the method of difference potentials to the variable-coefficient Zaremba problem, with convergence order approximately equal to one.

The remainder of this paper is organized as follows. After some necessary preliminaries presented in Section 2, Section 3 lays down the integral equation system we use, and the equivalence between the integral equation system and the original Zaremba problem (1.1) is studied. Detailed asymptotics for the Zaremba singularities at the Dirichlet-Neumann junction are presented in Section 4. Building upon these results further, and exploiting an interesting connection of this problem with the Fourier-continuation method [3, 6], Fourier expansions for the integral densities are obtained in Section 5 which regularize all Zaremba singularities. Section 6 then introduces a numerical algorithm that incorporates the aforementioned Fourier continuation series on the basis of certain closed form integral expressions, and which thus produces numerical solutions with high-order accuracy. A variety of results in Section 7 demonstrates the quality of the solutions and Zaremba eigenfunctions produced by the proposed numerical approach, and Section 8, finally, presents a few concluding remarks.

2. Preliminaries. We consider interior and exterior boundary value problems of the form given in equation (1.1) for $u \in H^1_{\text{loc}}(\Omega)$ (with a Sommerfeld radiation condition in the case of exterior problems), where $\Omega \subset \mathbb{R}^2$ denotes either a bounded, open and simply-connected domain with a smooth boundary (which we will generically call an *interior* domain) or the complement of the closure of such a domain (an *exterior* domain), where the Dirichlet and Neumann boundary portions Γ_D and Γ_N , $\Gamma = \Gamma_D \cup \Gamma_N$, are disjoint relatively-open subsets of Γ of positive measure relative to Γ . Here, calling B_R the ball of radius R centered at the origin, we have denoted by

$$(2.1) \quad H^1_{\text{loc}}(\Omega) = \{u : u \in H^1(\Omega \cap B_R) \text{ for all } R > 0\}$$

the local Sobolev space of order 1; of course, $H^1_{\text{loc}}(\Omega) = H^1(\Omega)$ for bounded sets Ω . The Dirichlet and Neumann data f and g in (1.1), in turn, are elements of certain Sobolev spaces, cf., Remark 2.2 (ii), defined in what follows. In order to do this, we follow [22], and we first define, for a given relatively open subset $S \subseteq \Gamma$, the space

$$\tilde{H}^{1/2}(S) = \{u|_S : \text{supp } u \subseteq S, u \in H^{1/2}(\Gamma)\}.$$

The spaces associated with the Dirichlet and Neumann data f and g are then defined by

$$H^{1/2}(S) = \{u|_S : u \in H^{1/2}(\Gamma)\},$$

and, using the prime notation H' to denote the dual space of a given Hilbert space H ,

$$H^{-1/2}(S) = (\tilde{H}^{1/2}(S))',$$

respectively.

Remark 2.1. In the case where Ω is an exterior domain, problem (1.1) admits unique solutions in $H^1_{\text{loc}}(\Omega)$. On the other hand, if Ω is an interior domain, this problem is not well posed for a discrete set of real values k_j , $j = 1, \dots, \infty$, the squares of which are the Zaremba eigenvalues, that is to say, the eigenvalues of the Laplace operator under the corresponding homogeneous mixed Dirichlet-Neumann (Zaremba) boundary conditions (see [2], [22, Theorem 4.10]).

Remark 2.2. Throughout this paper,

- (i) the term *smooth* is equated to *infinitely differentiable* and, as indicated above, it is assumed that the boundary of the domain Ω is smooth.
- (ii) It is assumed that the functions f and g in equation (1.1) are smooth. In particular, it follows that $f \in H^{1/2}(\Gamma_D)$ and $g \in H^{-1/2}(\Gamma_N)$, and, thus, that existence and uniqueness of the problem (1.1) hold [22, page 231, Theorem 7.9] provided either Ω is an exterior domain or Ω is an interior domain and k^2 is not an interior eigenvalue for the Laplace operator with homogeneous Dirichlet and Neumann boundary conditions on Γ_D and Γ_N , respectively. (As is customary in the literature, λ is an eigenvalue of the Laplace operator provided $\Delta u + \lambda u = 0$ for some non-zero smooth function u .)

The boundary Γ can be expressed in the form

$$(2.2) \quad \Gamma = \bigcup_{q=1}^{Q_N+Q_D} \Gamma_q,$$

where Q_D and Q_N denote the numbers of smooth *connected* Dirichlet and Neumann boundary portions, and where, for $1 \leq q \leq Q_D$ (respectively, for $Q_D + 1 \leq q \leq Q_D + Q_N$), Γ_q denotes a Dirichlet (respectively, Neumann) portion of the boundary curve Γ , see e.g., Figure 1). Clearly, letting

$$J_D = \{1, \dots, Q_D\} \quad \text{and} \quad J_N = \{Q_D + 1, \dots, Q_D + Q_N\}$$

we have that

$$\Gamma_D = \bigcup_{q \in J_D} \Gamma_q \quad \text{and} \quad \Gamma_N = \bigcup_{q \in J_N} \Gamma_q$$

are the subsets of Γ upon which Dirichlet and Neumann boundary conditions are enforced, respectively. Note that consecutive values of the index q do not necessarily correspond to consecutive boundary segments. Throughout this paper, it is assumed, however, that no Dirichlet-Dirichlet or Neumann-Neumann junctions occur, and, thus, that every endpoint of a segment Γ_q coincides with a Dirichlet-Neumann junction. Clearly, this is not a restriction: consecutive Dirichlet (respectively, Neumann) segments can be combined to produce a partition which verifies the above assumptions.

3. Boundary integral equation formulation. In what follows, we seek solutions of problem (1.1) on the basis of the single-layer potential representation

$$(3.1) \quad u(x) = \int_{\Gamma} G_k(x, y) \psi(y) ds_y,$$

where $G_k(x, y) = (i/4)H_0^1(k|x - y|)$ is the Helmholtz-Green function in two-dimensional space. Taking into account well-known expressions [9, page 40] for the jump of the single layer potential and its normal derivative across Γ , the boundary conditions for the exterior (respectively, interior) boundary value problem (1.1) give rise to the integral equations

$$(3.2) \quad \int_{\Gamma} G_k(x, y) \psi(y) ds_y = f(x), \quad x \in \Gamma_D,$$

and

$$\gamma \frac{\psi(x)}{2} + \int_{\Gamma} \frac{\partial G_k(x, y)}{\partial n_x} \psi(y) ds_y = g(x), \quad x \in \Gamma_N,$$

with $\gamma = -1$ (respectively, $\gamma = 1$).

Important properties of *both the interior and exterior* integral equation problems (3.2) relate to existence of eigenvalues of certain *interior* problems for the Laplace operator under either Dirichlet or Zaremba boundary conditions. As shown in what follows, for example,

- (i) in the case where Ω is an exterior domain, the integral equation system (3.2) admits unique solutions if and only if k^2 is not a Dirichlet eigenvalue of the Laplace operator in $\mathbb{R}^2 \setminus \Omega$.
- (ii) For such an exterior domain Ω , the PDE problem (1.1) admits unique solutions for any real value of k^2 in spite of the lack of uniqueness implied in point i for certain wavenumbers k . A procedure is presented in Appendix A which extends applicability of the proposed integral formulation to such values of k .
- (iii) In the case where Ω is an interior domain, in turn, the integral equation system is uniquely solvable, provided k^2 is not a Zaremba eigenvalue of the Laplace operator in Ω .
- (iv) The PDE problem (1.1) in such an interior domain Ω does not admit unique solutions, of course, for values of k for which k^2 is a Zaremba eigenvalue in Ω . In this case, the eigenfunctions

of the Zaremba Laplace operator can be expressed in terms of the representation formula (3.1) for a certain density ψ which satisfies (3.2) with $f = 0$ and $g = 0$.

A detailed treatment concerning points i, iii and iv above is presented in the remainder of this section (Theorems 3.3, 3.4 and Definition 3.1). A corresponding discussion concerning point ii, in turn, is put forth in Appendix A.

Definition 3.1. Given an interior (respectively, exterior) domain Ω and a solution u of (1.1) in $H_{\text{loc}}^1(\Omega)$, a function $w \in H_{\text{loc}}^1(\mathbb{R}^2 \setminus \Omega)$ is said to be a solution *conjugate* to u if it satisfies

$$(3.3) \quad \begin{aligned} \Delta w + k^2 w &= 0, & x \in \mathbb{R}^2 \setminus \Omega, \\ w(x) &= u(x), & x \in \Gamma, \end{aligned}$$

as well as in the case where $\mathbb{R}^2 \setminus \Omega$ is an exterior domain, Sommerfeld's condition of radiation at infinity. Throughout this paper, the conjugate solution w in the case $\mathbb{R}^2 \setminus \Omega$ is an exterior (respectively, interior) domain will be denoted by $u_e = w$ (respectively, $u_i = w$).

Lemma 3.2. *The conjugate solutions mentioned in Definition 3.1 exist and are uniquely determined in each one of the following two cases:*

- (i) $\mathbb{R}^2 \setminus \Omega$ is an exterior domain; and
- (ii) $\mathbb{R}^2 \setminus \Omega$ is an interior domain and k^2 is not a Dirichlet eigenvalue of the Laplace operator in $\mathbb{R}^2 \setminus \Omega$.

Proof. For both point i and point ii, we rely on the fact that the solution u of problem (1.1) is in $H_{\text{loc}}^1(\Omega)$ (see Remark 2.1), and, therefore, by the trace theorem, e.g., [22, Theorem 3.37], its boundary values lie in $H^{1/2}(\Gamma)$. For point i, we then invoke [22, Theorem 9.11] to conclude that a uniquely determined conjugate solution $w \in H_{\text{loc}}^1(\mathbb{R}^2 \setminus \Omega)$ exists, as needed. Point ii follows similarly using [22, Theorem 4.10] under the assumption that k^2 is not a Dirichlet eigenvalue in the interior domain $\mathbb{R}^2 \setminus \Omega$. \square

Theorem 3.3. *Let Ω be an exterior domain, and let $k \in \mathbb{R}$ be such that k^2 is not a Dirichlet eigenvalue of the Laplace operator in the interior domain $\mathbb{R}^2 \setminus \Omega$. Then, the exterior integral equation system (3.2)*

($\gamma = -1$, see also Remark 2.2 (ii)) admits a unique solution given by

$$(3.4) \quad \psi = \frac{\partial u_i}{\partial n} - \frac{\partial u}{\partial n},$$

where u is the solution of the exterior mixed problem (1.1), and where u_i is the (uniquely determined) corresponding conjugate solution (Definition 3.1 and Lemma 3.2).

Proof. In order to obtain (3.4), we first consider the Green representation formula for the functions u_i and u ,

$$(3.5) \quad \begin{aligned} u_i(x) &= \int_{\Gamma} \left(G_k(x, y) \frac{\partial u_i}{\partial n}(y) - u_i(y) \frac{\partial G_k(x, y)}{\partial n_y} \right) ds_y, & x \in \mathbb{R}^2 \setminus \Omega, \\ u(x) &= \int_{\Gamma} \left(u(y) \frac{\partial G_k(x, y)}{\partial n_y} - G_k(x, y) \frac{\partial u}{\partial n}(y) \right) ds_y, & x \in \Omega, \end{aligned}$$

which, in view of the jump relations for the single and double layer potential operators, in the limit $x \rightarrow \Gamma$, leads to the relations

$$(3.6) \quad \begin{aligned} \frac{u_i(x)}{2} &= \int_{\Gamma} \left(G_k(x, y) \frac{\partial u_i}{\partial n}(y) - u_i(y) \frac{\partial G_k(x, y)}{\partial n_y} \right) ds_y, & x \in \Gamma \\ \frac{u(x)}{2} &= \int_{\Gamma} \left(u(y) \frac{\partial G_k(x, y)}{\partial n_y} - G_k(x, y) \frac{\partial u}{\partial n}(y) \right) ds_y, & x \in \Gamma. \end{aligned}$$

Since, for $x \in \Gamma_D$, we have $u(x) = u_i(x) = f(x)$, the sum of the two equations in (3.6) yields

$$(3.7) \quad f(x) = \int_{\Gamma} G_k(x, y) \left(\frac{\partial u_i}{\partial n}(y) - \frac{\partial u}{\partial n}(y) \right) ds_y, \quad x \in \Gamma_D,$$

and, thus, in view of (3.4),

$$(3.8) \quad f(x) = \int_{\Gamma} G_k(x, y) \psi(y) ds_y, \quad x \in \Gamma_D.$$

Similarly, in the limit $x \rightarrow \Gamma$, the normal derivatives of the integrals

in (3.5) give rise to the relations

$$(3.9) \quad \begin{aligned} \frac{1}{2} \frac{\partial u_i}{\partial n}(x) &= \frac{\partial}{\partial n} \int_{\Gamma} \left(G_k(x, y) \frac{\partial u_i}{\partial n}(y) - u_i(y) \frac{\partial G_k(x, y)}{\partial n_y} \right) ds_y, \quad x \in \Gamma \\ \frac{1}{2} \frac{\partial u}{\partial n}(x) &= \frac{\partial}{\partial n} \int_{\Gamma} \left(u(y) \frac{\partial G_k(x, y)}{\partial n_y} - G_k(x, y) \frac{\partial u}{\partial n}(y) \right) ds_y, \quad x \in \Gamma. \end{aligned}$$

The sum of the equations in (3.9) results in the identity

$$(3.10) \quad \frac{1}{2} \frac{\partial u_i}{\partial n}(x) + \frac{1}{2} \frac{\partial u}{\partial n}(x) = \int_{\Gamma} \frac{\partial G_k(x, y)}{\partial n_x} \left(\frac{\partial u_i}{\partial n}(y) - \frac{\partial u}{\partial n}(y) \right) ds_y, \quad x \in \Gamma,$$

or, equivalently,

$$(3.11) \quad \begin{aligned} \frac{\partial u}{\partial n}(x) &= -\frac{1}{2} \left(\frac{\partial u_i}{\partial n}(x) - \frac{\partial u}{\partial n}(x) \right) \\ &+ \int_{\Gamma} \frac{\partial G_k(x, y)}{\partial n_x} \left(\frac{\partial u_i}{\partial n}(y) - \frac{\partial u}{\partial n}(y) \right) ds_y, \quad x \in \Gamma. \end{aligned}$$

However, for $x \in \Gamma_N$, we have

$$\frac{\partial u}{\partial n}(x) = g(x),$$

and, thus, equation (3.11) can be made to read

$$(3.12) \quad g(x) = -\frac{\psi(x)}{2} + \int_{\Gamma} \frac{\partial G_k(x, y)}{\partial n_x} \psi(y) ds_y, \quad x \in \Gamma_N.$$

Equations (3.8) and (3.12) tell us that the density ψ is a solution of the exterior integral equation system (3.2), as claimed.

In order to establish solution uniqueness, let ξ be a solution of equation (3.2) with $f = 0$ and $g = 0$. Since, as mentioned above, the exterior mixed problem is uniquely solvable, the corresponding single layer potential

$$(3.13) \quad v(x) = \int_{\Gamma} G_k(x, y) \xi(y) ds_y = 0$$

everywhere in Ω . It then follows from the continuity of the single layer potential that v satisfies the Dirichlet problem in the interior domain $\mathbb{R}^2 \setminus \Omega$ with zero boundary values. Since, by assumption, k^2 is not a Dirichlet eigenvalue of the Laplace operator in $\mathbb{R}^2 \setminus \Omega$, it follows that

$v = 0$ in that region as well. Thus, both the interior and exterior normal derivatives vanish, and therefore, so does their difference ξ . The proof is now complete. □

Theorem 3.4. *Let Ω be an interior domain. Then:*

- (i) *if k^2 is not a Zaremba eigenvalue, see Remark 2.1, then the interior integral equation system (3.2) ($\gamma = 1$, also see Remark 2.2 (ii)) admits a unique solution, given by*

$$(3.14) \quad \psi = \frac{\partial u}{\partial n} - \frac{\partial u_e}{\partial n}.$$

Here, u is the solution of the interior mixed problem (1.1), and u_e is the solution conjugate to u (Definition 3.1 and Lemma 3.2).

- (ii) *If k^2 is a Zaremba eigenvalue, in turn, any eigenfunction u satisfying (1.1) with $f = 0$ and $g = 0$ can be expressed by means of a single-layer representation*

$$(3.15) \quad u(x) = \int_{\Gamma} G_k(x, y) \left(\frac{\partial u}{\partial n}(y) - \frac{\partial u_e}{\partial n}(y) \right) ds_y, \quad x \in \Omega \cup \Gamma,$$

where u_e denotes the conjugate solution corresponding to the eigenfunction u (Definition 3.1 and Lemma 3.2).

Proof. We first consider properties that are common to Zaremba solutions and eigenfunctions and which, therefore, relate to both points (i) and (ii) in Theorem 3.4. For any given solution u of the interior mixed problem (1.1) (u can either be the unique solution of the interior mixed problem in the case k^2 is not an eigenvalue, or any eigenfunction satisfying (1.1) with $f = 0$ and $g = 0$) the conjugate solution u_e is uniquely defined (Lemma 3.2). Letting

$$(3.16) \quad w(x) = \int_{\Gamma} G_k(x, y) \left(\frac{\partial u}{\partial n}(y) - \frac{\partial u_e}{\partial n}(y) \right) ds_y,$$

using the Green representation formula for u and u_e ,

$$(3.17) \quad \begin{aligned} u(x) &= \int_{\Gamma} \left(G_k(x, y) \frac{\partial u}{\partial n}(y) - u(y) \frac{\partial G_k(x, y)}{\partial n_y} \right) ds_y, & x \in \Omega, \\ u_e(x) &= \int_{\Gamma} \left(u_e(y) \frac{\partial G_k(x, y)}{\partial n_y} - G_k(x, y) \frac{\partial u_e}{\partial n}(y) \right) ds_y, & x \in \mathbb{R}^2 \setminus \Omega, \end{aligned}$$

and taking into account the jump relations for the double layer potential as well as the fact that $u_e(x) = u(x)$ for $x \in \Gamma$, we obtain

$$(3.18) \quad u(x) = \int_{\Gamma} G_k(x, y) \left(\frac{\partial u}{\partial n}(y) - \frac{\partial u_e}{\partial n}(y) \right) ds_y = w(x), \quad x \in \Gamma.$$

Similarly, taking normal derivatives of both sides of each equation in (3.17) at a point $x \in \Gamma$, we obtain the equations

$$(3.19) \quad \begin{aligned} \frac{1}{2} \frac{\partial u}{\partial n}(x) &= \frac{\partial}{\partial n} \int_{\Gamma} \left(G_k(x, y) \frac{\partial u}{\partial n}(y) - u(y) \frac{\partial G_k(x, y)}{\partial n_y} \right) ds_y, \quad x \in \Gamma, \\ \frac{1}{2} \frac{\partial u_e}{\partial n}(x) &= \frac{\partial}{\partial n} \int_{\Gamma} \left(u_e(y) \frac{\partial G_k(x, y)}{\partial n_y} - G_k(x, y) \frac{\partial u_e}{\partial n}(y) \right) ds_y, \quad x \in \Gamma, \end{aligned}$$

whose sum yields

$$(3.20) \quad \begin{aligned} \frac{\partial u}{\partial n}(x) &= \frac{1}{2} \left(\frac{\partial u}{\partial n}(x) - \frac{\partial u_e}{\partial n}(x) \right) \\ &\quad + \int_{\Gamma} \frac{\partial G_k(x, y)}{\partial n_x} \left(\frac{\partial u}{\partial n}(y) - \frac{\partial u_e}{\partial n}(y) \right) ds_y = \frac{\partial w}{\partial n}(x), \quad x \in \Gamma. \end{aligned}$$

We now conclude the proof by applying these concepts to points (i) and (ii) in Theorem 3.4.

- (i) In the case where k^2 is not an eigenvalue for the Laplace-Zaremba problem (1.1), equations (3.18) and (3.20) evaluated for $x \in \Gamma_D$ and $x \in \Gamma_N$, respectively, show that the density ψ given by (3.14) satisfies the integral equation system (3.2) with $\gamma = 1$, as desired.
- (ii) In the case where k^2 is an eigenvalue for the Laplace-Zaremba problem (1.1), in turn, let u denote a corresponding eigenfunction. Equations (3.18) and (3.20) along with the Green representation formula show that $u(x) = w(x)$ for all $x \in \Omega$. In other words, equation (3.15) is satisfied, and the proof follows in this case as well.

The proof is now complete. □

4. Singularities of the solutions of equations (1.1) and (3.2).

With reference to equation (2.2), let $y^0 = (y_1^0, y_2^0) \in \Gamma$ be a point which separates Dirichlet and Neumann regions Γ_{q_1} and Γ_{q_2} ($q_1 \in J_D$

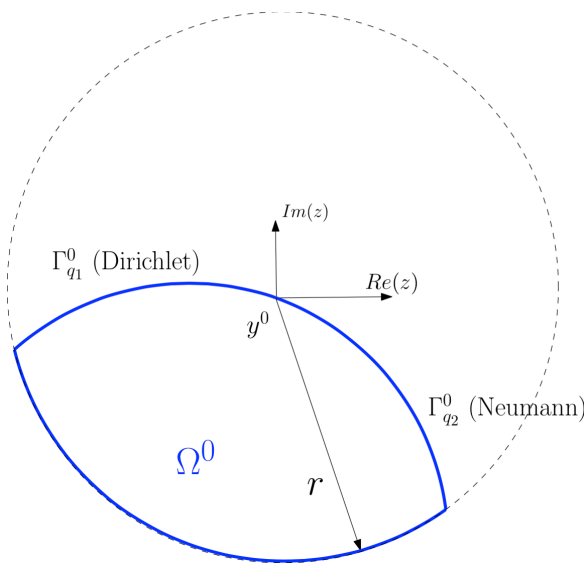


FIGURE 2. Singular point y^0 .

and $q_2 \in J_N$) within Γ . In order to express the singular character around y^0 of both the solution $u(y)$ of problem (1.1), $y = (y_1, y_2) \in \Omega$, and the corresponding integral equation density $\psi(y)$ in equation (3.2), $y = (y_1, y_2) \in \Gamma$, we consider the neighborhoods

$$(4.1) \quad \begin{aligned} \Omega^0 &= \overline{\Omega \cap B(y^0, r)}, \\ \Gamma_{q_1}^0 &= \overline{\Gamma_{q_1} \cap B(y^0, r)} \quad \text{and} \quad \Gamma_{q_2}^0 = \overline{\Gamma_{q_2} \cap B(y^0, r)} \end{aligned}$$

of the singular point y^0 relative to Ω , Γ_{q_1} and Γ_{q_2} , respectively. Here, for a set $A \subset \mathbb{R}^2$, \overline{A} denotes the topological closure of A in \mathbb{R}^2 , $B(y^0, r)$ denotes the circle centered at y^0 of radius r , and $r > 0$ is sufficiently small such that $B(y^0, r)$ has only nonempty intersections with $\overline{\Gamma}_q$ for the Dirichlet index $q = q_1$ and the Neumann index $q = q_2$. Additionally, we use certain functions $\widehat{u}_{y^0} = \widehat{u}_{y^0}(z)$, $\widehat{\psi}_{y^0}^1 = \widehat{\psi}_{y^0}^1(d)$ and $\widehat{\psi}_{y^0}^2 = \widehat{\psi}_{y^0}^2(d)$, where the Dirichlet (respectively, Neumann) function $\widehat{\psi}_{y^0}^1$ (respectively, $\widehat{\psi}_{y^0}^2$) is the density as a function of the distance d to the point y^0 in $\Gamma_{q_1}^0$ (respectively, $\Gamma_{q_2}^0$), and where $z = (y_1 - y_1^0) + i(y_2 - y_2^0)$ is a complex

variable, see Figure 2. The functions \widehat{u}_{y^0} , $\widehat{\psi}_{y^0}^1$ and $\widehat{\psi}_{y^0}^2$ are given by

$$\begin{aligned}
 \widehat{u}_{y^0}(z) &= u(y), \\
 \psi(y) &= \widehat{\psi}_{y^0}^1(d(y)), \quad y \in \Gamma_{q_1}^0, \\
 \psi(y) &= \widehat{\psi}_{y^0}^2(d(y)), \quad y \in \Gamma_{q_2}^0,
 \end{aligned}
 \tag{4.2}$$

where, as mentioned above,

$$z = (y_1 - y_1^0) + i(y_2 - y_2^0) \quad \text{and} \quad d(y) = \sqrt{(y_1 - y_1^0)^2 + (y_2 - y_2^0)^2}.
 \tag{4.3}$$

It is known [28, 29] that, under our assumption that the curve Γ be globally smooth, for any given integer \mathcal{N} the function $\widehat{u}_{y^0}(z)$ can be expressed in the form

$$\widehat{u}_{y^0}(z) = \log(z)P_{y^0}^{1,\mathcal{N}} + \log(\bar{z})P_{y^0}^{2,\mathcal{N}} + P_{y^0}^{3,\mathcal{N}} + o(z^\mathcal{N})
 \tag{4.4}$$

for all z in a neighborhood of the origin, where $P_{y^0}^{1,\mathcal{N}}$, $P_{y^0}^{2,\mathcal{N}}$ and $P_{y^0}^{3,\mathcal{N}}$ are \mathcal{N} -dependent polynomial functions of z , \bar{z} , $z^{1/2}$, $\bar{z}^{1/2}$, $z \log(z)$, $\bar{z} \log(\bar{z})$.

Remark 4.1. In the asymptotic expansion (4.4), and, indeed, in all similar asymptotic expansions in this paper, it is assumed that none of the right hand side polynomials contain terms that, multiplied by the relevant factors, could be included in the error term.

Under our standing assumption of smoothness of the domain boundary, the following two theorems provide 1) finer details on the asymptotics (4.4), as well as 2) a corresponding asymptotic expression around y^0 for the solutions $\widehat{\psi}_{y^0}^1(d)$ and $\widehat{\psi}_{y^0}^2(d)$ of the integral-equation system (3.2).

Theorem 4.2. *Let y^0 be a Dirichlet-Neumann point as described above in this section. Then, given an arbitrary integer \mathcal{N} , the function $\widehat{u}_{y^0}(z)$ can be expressed in the form*

$$\widehat{u}_{y^0}(z) = P_{y^0}^\mathcal{N}(z^{1/2}, \bar{z}^{1/2}) + o(z^\mathcal{N})
 \tag{4.5}$$

around y^0 , where $P_{y^0}^\mathcal{N}$ is an \mathcal{N} -dependent polynomial function of its arguments, see Remark 4.1.

Theorem 4.3. *Let y^0 be a Dirichlet-Neumann point. Then, given an arbitrary integer \mathcal{N} , the functions $\widehat{\psi}_{y^0}^1(d)$ and $\widehat{\psi}_{y^0}^2(d)$ can be expressed in the forms*

$$(4.6) \quad \begin{aligned} \widehat{\psi}_{y^0}^1(d) &= d^{-1/2} Q_{y^0}^{1,\mathcal{N}}(d^{1/2}) + o(d^{\mathcal{N}-1}) \quad \text{and} \\ \widehat{\psi}_{y^0}^2(d) &= d^{-1/2} Q_{y^0}^{2,\mathcal{N}}(d^{1/2}) + o(d^{\mathcal{N}-1}) \end{aligned}$$

around $d = 0$, where $Q_{y^0}^{1,\mathcal{N}}$ and $Q_{y^0}^{2,\mathcal{N}}$ are \mathcal{N} -dependent polynomial functions of their arguments, see Remark 4.1.

Note, in particular, that Theorem 4.2 shows that, under our assumptions of boundary smoothness, all logarithmic terms in equation (4.4) actually drop out. The proofs of these theorems (given in Sections 4.2 and 4.3, respectively) utilize a certain conformal map introduced in Section 4.1 that transforms Ω^0 into a semicircular region.

4.1. Conformal mapping. Following [28], in order to establish Theorem 4.2, we identify \mathbb{R}^2 with the complex plane \mathbb{C} via the aforementioned relationship

$$z = (y_1 - y_1^0) + i(y_2 - y_2^0) \longleftrightarrow (y_1 - y_1^0, y_2 - y_2^0),$$

and we utilize a conformal map $z = w(\xi)$ which maps the semi-circular region

$$D_A = \{\xi \in \mathbb{C} : |\xi| \leq A \text{ and } \text{Im}(\xi) \leq 0\}$$

in the complex ξ -plane, Figure 3, onto the domain Ω^0 (4.1) in the complex z -plane. We assume, as we may, that w maps the origin to itself and that the intervals

$$\{\text{Im}(\xi) = 0, 0 \leq \text{Re}(\xi) \leq A\}$$

and

$$\{\text{Im}(\xi) = 0, -A \leq \text{Re}(\xi) \leq 0\}$$

are mapped onto the boundary segments $\Gamma_{q_1}^0$ and $\Gamma_{q_2}^0$, respectively.

Letting

$$(4.7) \quad U(\xi) = \widehat{u}_{y^0}(w(\xi)),$$

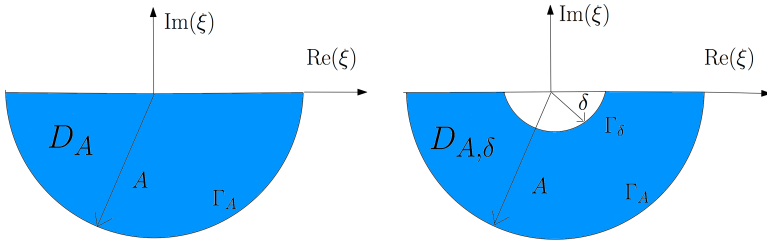


FIGURE 3. Semi-circular and semi-annular Green-identity regions.

we note that, in view of the relation

$$\Delta_\xi U(\xi) = \Delta_z \widehat{u}_{y^0}(w(\xi)) \cdot |w'(\xi)|^2$$

satisfied by a complex analytic function w (see [15, equation 5.4.17]), U satisfies the second order elliptic equation

$$(4.8) \quad \Delta U(\xi) + K(\xi)U(\xi) = 0 \quad \text{for } \xi \in \text{int}(D_A),$$

$$(4.9) \quad U(\xi) = F(\xi) \quad \text{for } \text{Im}(\xi) = 0, \text{Re}(\xi) > 0,$$

$$(4.10) \quad \frac{\partial U(\xi)}{\partial n} = G(\xi) \quad \text{for } \text{Im}(\xi) = 0, \text{Re}(\xi) < 0, \quad \text{and}$$

$$(4.11) \quad U(\xi) = M(\xi) \quad \text{for } |\xi| = A.$$

Here, $F(\xi) = f(w(\xi))$, $G(\xi) = g(w(\xi))$ and $M(\xi) = u(w(\xi))$. (The function M is thus obtained from the restriction of the solution u to the set $\partial\Omega^0 \setminus (\Gamma_{q_1}^0 \cup \Gamma_{q_2}^0)$, see equation (4.1) and Figure 2.)

4.2. Proof of Theorem 4.2. The proof of this theorem, which, under the present scope of smooth-domain problems, establishes a result stronger than [28, Theorem 3.2], does incorporate some of the lines of the proof provided in that reference. In what follows, we use the Laplace-Zaremba Green function

$$(4.12) \quad H(t, \xi) = -\frac{1}{2\pi} \left\{ \log |t - \xi| + \log |t - \bar{\xi}| - 2 \log |\sqrt{t} + \sqrt{\xi}| - 2 \log |\sqrt{t} - \sqrt{\xi}| \right\}$$

for the lower half-plane

$$\mathbb{C}^- = \{ \xi \in \mathbb{C} : \text{Im}(\xi) \leq 0 \}, \quad t = t_1 + it_2 = (t_1, t_2) \in \mathbb{C}^-,$$

and

$$\xi = \xi_1 + i\xi_2 = (\xi_1, \xi_2) \in \mathbb{C}^-,$$

with homogeneous Dirichlet (respectively, Neumann) boundary conditions on the positive (respectively, negative) real axis. The branches of the square roots in (4.12) are given by

$$\sqrt{t} = \sqrt{\rho_t e^{i\theta_t}} = \sqrt{\rho_t} e^{i\theta_t/2}$$

and

$$\sqrt{\xi} = \sqrt{\rho_\xi e^{i\theta_\xi}} = \sqrt{\rho_\xi} e^{i\theta_\xi/2}$$

where (ρ_t, θ_t) and (ρ_ξ, θ_ξ) denote polar coordinates in the complex t - and ξ -planes, respectively $(-\pi \leq \theta_t, \theta_\xi < \pi)$. Note that, with these conventions, the domain D_A in the t variables is given by $\rho_t \leq A$ and $-\pi \leq \theta_t \leq 0$.

The next lemma establishes certain important properties of the aforementioned Green function.

Lemma 4.4. *The function $H = H(t, \xi)$ (4.12) is indeed a Laplace-Zaremba Green function for the lower half plane with a Dirichlet-Neumann junction at the origin, that is, we have*

$$\Delta_t H(t, \xi) = -\delta(t - \xi)$$

for t, ξ in the lower half-plane, and H satisfies

$$(4.13) \quad H(t, \xi) = 0 \quad \text{for } \theta_t = 0$$

and

$$\frac{\partial H}{\partial n_t}(t, \xi) = 0 \quad \text{for } \theta_t = -\pi.$$

In addition, for a certain constant C , we have

$$(4.14) \quad \int_0^A \left| \frac{\partial}{\partial n_t}(H(t, \xi)) \right| dt \leq C_A$$

for all ξ in the lower half-plane.

Proof. The function $H(t, \xi)$ can be reexpressed in the form

$$(4.15) \quad H(t, \xi) = -\frac{1}{2\pi} \left\{ \log |\sqrt{t} - \sqrt{\xi}| - \log |\sqrt{t} + \sqrt{\xi}| \right. \\ \left. + \log |\sqrt{t} + \sqrt{\xi}| - \log |\sqrt{t} - \sqrt{\xi}| \right\}.$$

The first statement in equation (4.13) follows from the relations $|\sqrt{t} - \sqrt{\xi}| = |\sqrt{t} - \sqrt{\bar{\xi}}|$ and $|\sqrt{t} + \sqrt{\xi}| = |\sqrt{t} + \sqrt{\bar{\xi}}|$, which hold for $\theta_t = 0$, $t > 0$, since, in view of our selection of branch cuts, we have

$$(4.16) \quad \sqrt{\bar{\xi}} = \overline{\sqrt{\xi}}.$$

In order to establish the second statement in (4.13) and equation (4.14), we consider the relations

$$(4.17) \quad \frac{\partial}{\partial t_2} \log |\sqrt{t} - (z_1 + iz_2)| = \frac{z_1}{2\sqrt{-t_1}(z_1^2 + (\sqrt{-t_1} + z_2)^2)} \quad \text{for } \theta_t = -\pi,$$

and

$$\frac{\partial}{\partial t_2} \log |\sqrt{t} - (z_1 + iz_2)| = -\frac{z_2}{2\sqrt{t_1}((z_1 - \sqrt{t_1})^2 + z_2^2)} \quad \text{for } \theta_t = 0,$$

which are valid for all complex numbers $z = z_1 + iz_2$, and we note that, on the axis $t_2 = 0$ we have $\partial/\partial n_t = \partial/\partial t_2$. Thus, the second statement in (4.13) follows from application of the first equation in (4.17) to each one of the four logarithmic terms in equation (4.15). In order to establish a bound of the form (4.14), finally, we use the second equation in (4.17) to obtain the expression

$$(4.18) \quad \left| \frac{\partial}{\partial n_t} (H(t, \xi)) \right| \\ = \frac{|\text{Im}(\sqrt{\xi})|}{2\pi\sqrt{t}} \left(\frac{1}{(\sqrt{t} + \text{Re}(\sqrt{\xi}))^2 + \text{Im}(\sqrt{\xi})^2} + \frac{1}{(\sqrt{t} - \text{Re}(\sqrt{\xi}))^2 + \text{Im}(\sqrt{\xi})^2} \right)$$

for the absolute value of the derivative of (4.15) with respect to t_2 . It

is then easy to check that

$$(4.19) \quad \int_0^A \left| \frac{\partial}{\partial n_t} (H(t, \xi)) \right| dt \\ = -\frac{1}{\pi} \left(\arctan \frac{\sqrt{A} - \operatorname{Re}(\sqrt{\xi})}{\operatorname{Im}(\sqrt{\xi})} + \arctan \frac{\sqrt{A} + \operatorname{Re}(\sqrt{\xi})}{\operatorname{Im}(\sqrt{\xi})} \right)$$

for all ξ in the lower half-plane. Since the right-hand side of equation (4.19) is uniformly bounded for ξ not in $[0, A]$ and, since, for $\xi \in [0, A]$ the integrand in (4.14) vanishes, in view of the second expression in (4.17), we see that there exists a constant C_A such that equation (4.14) holds for all ξ in the lower half-plane, as needed, and the proof is thus complete. \square

The proof of Theorem 4.2 is based on a bootstrapping argument which is initiated by the simple but suboptimal asymptotic relation put forth in the following lemma.

Lemma 4.5. *The solution U of the problem (4.8)–(4.11) is bounded near $\xi = 0$, and thus, in particular, it satisfies the asymptotic relation*

$$(4.20) \quad U(\xi) = o(\xi^\mu), \quad \xi \rightarrow 0$$

for all $\mu < 0$.

Proof. In order to establish this relation we consider the Green formula

$$(4.21) \quad U(\xi) = \iint_{D_A} H(t, \xi) \Delta U(t) dx_t dy_t \\ + \int_{\partial D_A} \left\{ U(t) \frac{\partial}{\partial n_t} H(t, \xi) - H(t, \xi) \frac{\partial}{\partial n_t} U(t) \right\} ds_t.$$

Since H satisfies (4.13) as it befits a Green function for (4.8)–(4.11), denoting by Γ_A the radius- A part of ∂D_A , it follows that

$$(4.22) \quad |U(\xi)| \leq \left| \iint_{D_A} H(t, \xi) K(t) U(t) dx_t dy_t \right| \\ + \left| \int_0^A F(x) \frac{\partial}{\partial n_t} H(t, \xi) dt \right|$$

$$\begin{aligned}
 & + \left| \int_0^A G(-t)H(-t, \xi) dt \right| \\
 & + \left| \int_{\Gamma_A} \left\{ U(t) \frac{\partial}{\partial n_t} H(t, \xi) - H(t, \xi) \frac{\partial}{\partial n_t} U(t) \right\} ds_t \right|.
 \end{aligned}$$

For the integral over the outer arc Γ_A in (4.22), we have

$$(4.23) \quad \left| \int_{\Gamma_A} \left\{ U(t) \frac{\partial}{\partial n_t} H(t, \xi) - H(t, \xi) \frac{\partial}{\partial n_t} U(t) \right\} ds_t \right| \leq C \quad \text{for } |\xi| < A/2,$$

as it can be easily checked in view of the boundedness of the integrands for ξ near the origin. Taking into account that $u \in H^1_{loc}(\Omega)$, see Remark 2.1, on the other hand, it easily follows that $U \in H^1(D_A)$, and thus, bounding the absolute value of the first integral in (4.22) by means of the Cauchy-Schwarz inequality, for ξ near 0, we obtain the uniform estimate

$$(4.24) \quad \left| \iint_{D_A} H(t, \xi) K(t) U(t) dx_t dy_t \right| \leq \|H\|_{L^2} \|U\|_{L^2} \max(K).$$

In order to estimate the second and third integrals in (4.22), we note that the integrals of the absolute values of H and $\partial H/\partial n_t$ are uniformly bounded, as can be easily verified for the former, and as it is established in Lemma 4.4 of the latter. The boundedness of F and G (which are smooth functions in view of Remark 2.2) thus implies the claimed uniform boundedness of the function U near the origin. Relation (4.20) therefore follows for all $\mu < 0$, and the proof is complete. \square

Corollary 4.6. *Let h denote a positive integer. Then, the h -order derivative $D^h U$ of the solution U of the problem (4.8)–(4.11) with respect to ξ satisfies the asymptotic relation*

$$(4.25) \quad D^h U = o(\xi^{\mu-h}), \quad \xi \rightarrow 0$$

for all $\mu < 0$.

Proof. See [28, Section 4]. \square

A key element in the bootstrapping algorithm mentioned at the beginning of this section is a representation formula for the function U that is presented in the next lemma.

Lemma 4.7. *The solution U of equations (4.8)–(4.11) admits the representation*

$$\begin{aligned}
 U(\xi) = & -\frac{1}{2\pi} \{ \Lambda_1(-K(t)U(t), \xi, 1) + \Lambda_1(-K(t)U(t), \bar{\xi}, 1) \\
 & - 2\Lambda_1(-K(t)U(t), \xi, 2) - 2\Lambda_1(-K(t)U(t), \bar{\xi}, 2) \\
 & - \Lambda_3(F(t), \xi, 1) - \Lambda_3(F(t), \bar{\xi}, 1) \\
 (4.26) \quad & + 2\Lambda_3(F(t), \xi, 2) + 2\Lambda_3(F(t), \bar{\xi}, 2) \\
 & - \Lambda_2(G(-t), -\xi, 1) - \Lambda_2(G(-t), -\bar{\xi}, 1) \\
 & + 2\Lambda_2(G(-t), -\xi, 2) + 2\Lambda_2(G(-t), -\bar{\xi}, 2) \} \\
 & + p_1(\sqrt{\xi}) + p_2(\sqrt{\bar{\xi}}),
 \end{aligned}$$

where

$$\begin{aligned}
 \Lambda_1(q(t), \xi, \eta) & := \int_{-\pi}^0 \int_0^A q(t) \log |t^{1/\eta} - \xi^{1/\eta}| \rho_t \, d\rho_t d\theta_t, \\
 (4.27) \quad \Lambda_2(q(t), \xi, \eta) & := \int_0^A q(t) \log |t^{1/\eta} - \xi^{1/\eta}| \, dt, \\
 \Lambda_3(q(t), \xi, \eta) & := \int_0^A q(t) \frac{1}{t} \frac{\partial}{\partial \theta_t} \log |t^{1/\eta} - \xi^{1/\eta}| \, dt,
 \end{aligned}$$

and where p_1 and p_2 denote power series with positive radii of convergence.

Proof. Applying the Green formula on the set

$$(4.28) \quad D_{A,\delta} = \{ \xi \in \mathbb{C} : \delta \leq |\xi| \leq A \text{ and } \text{Im}(\xi) \leq 0 \}$$

(the right side of Figure 3), we obtain the expression

$$\begin{aligned}
 U(\xi) = & \iint_{D_{A,\delta}} H(t, \xi) \Delta U(t) \, dx_t dy_t \\
 (4.29) \quad & + \int_{\partial D_{A,\delta}} \left\{ U(t) \frac{\partial}{\partial n_t} H(t, \xi) - H(t, \xi) \frac{\partial}{\partial n_t} U(t) \right\} \, ds_t.
 \end{aligned}$$

Further, for fixed $\xi \neq 0$, we have

$$(4.30) \quad H(t, \xi) = \mathcal{O}(\sqrt{t}) \quad \text{as } t \rightarrow 0,$$

and therefore, in view of Lemma 4.5 and (4.25), for any μ satisfying $-1/2 < \mu < 0$, we have

$$(4.31) \quad \begin{aligned} &U(t)H(t, \xi) = o(t^\mu), \\ &U(t)\frac{\partial}{\partial \rho_t}H(t, \xi) - H(t, \xi)\frac{\partial}{\partial \rho_t}U(t) = o(t^{\mu-1/2}). \end{aligned}$$

Letting Γ_δ denote the radius- δ arc within the boundary $\partial D_{A,\delta}$ of $D_{A,\delta}$ (Figure 3), and noting that, for $t \in \Gamma_\delta$, we have $\partial/\partial \rho_t = \partial/\partial n_t$, in view of (4.31) we obtain

$$(4.32) \quad \int_{\Gamma_\delta} \left\{ U(t)\frac{\partial}{\partial n_t}H(t, \xi) - H(t, \xi)\frac{\partial}{\partial n_t}U(t) \right\} ds_t \rightarrow 0 \text{ as } \delta \rightarrow 0.$$

Further, exploiting the fact that the Green function (4.12) is a jointly analytic function of $\sqrt{\xi}$ and $\sqrt{\bar{\xi}}$ for $t \in \Gamma_A$ and ξ around $\xi = 0$, we obtain

$$(4.33) \quad \int_{\Gamma_A} \left\{ U(t)\frac{\partial}{\partial n_t}H(t, \xi) - H(t, \xi)\frac{\partial}{\partial n_t}U(t) \right\} ds_t = p_1(\sqrt{\xi}) + p_2(\sqrt{\bar{\xi}}),$$

where p_1 and p_2 denote the power series with positive radii of convergence.

Letting $\delta \rightarrow 0$ in (4.29) and using (4.32) and (4.33), we finally obtain

$$(4.34) \quad \begin{aligned} U(\xi) &= \int_{-\pi}^0 \int_0^A H(t, \xi)(-K(t)U(t))\rho_t d\rho_t d\theta_t \\ &- \int_0^A F(t)\frac{1}{t}\frac{\partial}{\partial \theta_t}H(t, \xi) dt \\ &- \int_0^A G(-t)H(-t, \xi) dt + p_1(\sqrt{\xi}) + p_2(\sqrt{\bar{\xi}}). \end{aligned}$$

Using the definitions (4.27) for the functions Λ_1 , Λ_2 and Λ_3 , equation (4.34) is equivalent to equation (4.26), and the proof is complete. □

In order to determine the singular character of $U(\xi)$ around $\xi = 0$ (and therefore that of $\widehat{u}_{y^0}(z)$ around $z = 0$) we study the corresponding asymptotic behavior of each one of the Λ -terms in equation (4.26). An important part of this discussion is the next lemma, which presents certain regularity properties of the operators Λ_1 , Λ_2 and Λ_3 .

Lemma 4.8. *Let $\alpha \geq 0$, $\beta > -1$ and $\gamma > -1$, and let $\eta = 1$ or $\eta = 2$. Then*

$$(4.35) \quad \Lambda_1(t^{\beta}\bar{t}^{\gamma}, \xi, \eta) = C_1\xi^{\beta+\gamma+2} + C_2\bar{\xi}^{\beta+\gamma+2} + C_3\xi^{\beta+1}\bar{\xi}^{\gamma+1} + p_1(\xi^{1/\eta}) + p_2(\bar{\xi}^{1/\eta}),$$

$$(4.36) \quad \Lambda_2(t^{\beta}, \xi, \eta) = C_4\xi^{\beta+1} + C_5\bar{\xi}^{\beta+1} + p_3(\xi^{1/\eta}) + p_4(\bar{\xi}^{1/\eta})$$

and

$$(4.37) \quad \Lambda_3(t^{\alpha}, \xi, \eta) = C_6\xi^{\alpha} + C_7\bar{\xi}^{\alpha} + p_5(\xi^{1/\eta}) + p_6(\bar{\xi}^{1/\eta}).$$

For general functions $g(t) \in C^{\ell}(D_A)$ and $h(t) \in C^{\ell}((0, A])$ satisfying $g(t) = o(t^{\gamma})$ and $h(t) = o(t^{\alpha})$ as $t \rightarrow 0$, further, we have

$$(4.38) \quad \Lambda_1(g(t), \xi, \eta) = q_1(\xi^{1/\eta}) + q_2(\bar{\xi}^{1/\eta}) + o(\xi^{\gamma+2}),$$

$$(4.39) \quad \Lambda_2(g(t), \xi, \eta) = q_3(\xi^{1/\eta}) + q_4(\bar{\xi}^{1/\eta}) + o(\xi^{\gamma+1})$$

and

$$(4.40) \quad \Lambda_3(h(t), \xi, \eta) = q_5(\xi^{1/\eta}) + q_6(\bar{\xi}^{1/\eta}) + o(\xi^{\alpha}),$$

see Remark 4.1. Here, p_i (respectively, q_i), $i = 1, \dots, 6$, are power series with positive radii of convergence (respectively, polynomials), C_i , $i = 1 \dots 7$, are complex constants, and the expansions are ℓ -times differentiable as $\xi \rightarrow 0$. In the sense of Wigley: the derivatives of the left hand sides in (4.38) through (4.40) are equal to the corresponding derivatives of the first two terms of the right hand sides, with error terms given by the “formal” derivatives of the corresponding error terms, e.g.,

$$d/d\xi(o(\xi^{\alpha})) = o(\xi^{(\alpha-1)}).$$

Proof of Lemma 4.8. The proof follows by specializing the proofs of [28, Lemmas 7.1, 7.2, 8.1, 8.6]. □

We are now ready to provide the main proof of this section.

Proof of Theorem 4.2. Since the solutions $\widehat{u}_{j,0}$ and U are related by equation (4.7), using the classical result [26, Theorem IV] (which establishes, in particular, that the conformal mapping w is smooth up to and including the boundary for any smooth segment of the domain

boundary, see also, [25]) and expanding $w(\xi)$ in Taylor series around $\xi = 0$, we see that it suffices to prove that, for an arbitrary integer \mathcal{M} , we have the asymptotic relation

$$(4.41) \quad U(\xi) = \mathcal{Q}^{\mathcal{M}}(\xi^{1/2}, \bar{\xi}^{1/2}) + o(\xi^{\mathcal{M}})$$

for the solution $U(\xi)$ of problem (4.8)–(4.11), where $\mathcal{Q}^{\mathcal{M}} = \mathcal{Q}^{\mathcal{M}}(r, s)$ is a polynomial function of the independent variables r and s .

The proof now proceeds inductively. The induction basis is given by the asymptotics (4.20) of the function U . In order to complete the proof, we thus need to establish the following inductive step: *provided that*, for some integer \mathcal{L} the function U can be expressed in the form:

$$(4.42) \quad U(\xi) = \mathcal{P}^{\mathcal{L}}(\xi^{1/2}, \bar{\xi}^{1/2}) + o(\xi^{\mathcal{L}-\lambda}) \quad \text{as } \xi \rightarrow 0,$$

for some $0 < \lambda < 1$, where $\mathcal{P}^{\mathcal{L}} = \mathcal{P}^{\mathcal{L}}(r, s)$ is a polynomial function of the independent variables r and s , *then* a similar relation holds for U with an error of order $o(\xi^{\mathcal{L}+1-\lambda})$ and for a certain polynomial $\mathcal{P}^{\mathcal{L}+1}(\xi^{1/2}, \bar{\xi}^{1/2})$:

$$(4.43) \quad U(\xi) = \mathcal{P}^{\mathcal{L}+1}(\xi^{1/2}, \bar{\xi}^{1/2}) + o(\xi^{\mathcal{L}+1-\lambda}).$$

To do this, we apply Lemma 4.8 to each term on the right hand side of equation (4.26). For terms including the operator Λ_1 , for example, such an asymptotic representation with error of the order $o(\xi^{\mathcal{L}+1-\lambda})$ can be obtained by using the assumption (4.42) and the \mathcal{L} th order Taylor expansion of the smooth function $K(t)$ around $t = 0$, and by applying equations (4.35) with $\beta = 0, 1/2, 1, \dots, \mathcal{L}$, $\gamma = 0, 1/2, 1, \dots, \mathcal{L}$ and equation (4.38) with $\gamma = \mathcal{L} - \lambda$ to the resulting polynomial and error terms for the product $K(t)U(t)$. The terms that contain the operators Λ_2 and Λ_3 can be treated similarly on the basis of Taylor expansions of the functions $F(t)$ and $G(t)$ around $t = 0$ and application of equations (4.36) and (4.37) with $\beta = 1, \dots, \mathcal{L}$, $\alpha = 1, \dots, \mathcal{L}$, and equations (4.39) and (4.40) with $\gamma = \mathcal{L} - \lambda$ and $\alpha = \mathcal{L} - \lambda + 1$. The inductive step, and therefore the proof of Theorem 4.2, are thus complete. \square

4.3. Proof of Theorem 4.3. The relationship between the density ψ and the PDE solution u is given by equation (3.4) if Ω is an exterior domain and by equation (3.14) if Ω is an interior domain. Throughout this section, we assume that Ω is an interior domain, and, thus, that ψ is given by equation (3.14); the proof for exterior domains is analogous.

In order to establish the singular character of the density ψ , we first seek an asymptotic expression for the conjugate solution u_e near $z = 0$ (see Definition 3.1). Using a conformal mapping approach for u_e similar to that used in subsection 4.1 for the solution u of problem (1.1); in this case, we employ a conformal map $z = v(\xi)$ which maps the semi-circular region D_A depicted in Figure 3 in the complex ξ -plane onto the domain $B(y^0, r) \setminus \Omega^0$ in the complex z -plane, see Figure 2. We assume, as we may, that v maps the origin to itself and that the intervals

$$\{\text{Im}(\xi) = 0, 0 \leq \text{Re}(\xi) \leq A\}$$

and

$$\{\text{Im}(\xi) = 0, -A \leq \text{Re}(\xi) \leq 0\}$$

are mapped onto the boundary segments $\Gamma_{q_1}^0$ and $\Gamma_{q_2}^0$, respectively, see equation (4.1). Following subsection 4.1, in this case, we introduce the function $V(\xi) = u_e(v(\xi))$, and we note that V satisfies the second order elliptic problem, cf., [15, equation 5.4.17]

$$(4.44) \quad \Delta V(\xi) + K_1(\xi)V(\xi) = 0 \quad \text{for } \xi \in \text{int}(D_A),$$

$$(4.45) \quad V(\xi) = M_1(\xi) \quad \text{for } \xi \in \partial D_A,$$

where M_1 is given by $M_1(\xi) = u_e(v(\xi))$.

The next lemma parallels Lemma 4.5.

Lemma 4.9. *The solution V of the problem (4.44)–(4.45) is bounded near $\xi = 0$, and thus, in particular, it satisfies the asymptotic relation*

$$(4.46) \quad V(\xi) = o(\xi^\mu), \quad \xi \rightarrow 0$$

for all $\mu < 0$.

Proof. Employing the Laplace Green function

$$(4.47) \quad G_1(t, \xi) = -\frac{1}{2\pi} \{\log |t - \xi| - \log |t - \bar{\xi}|\}$$

for the Dirichlet problem (4.44)–(4.45) and applying the Green formula

to the functions V and G_1 on the domain D_A , we obtain

$$(4.48) \quad \begin{aligned} V(\xi) = & \iint_{D_A} G_1(t, \xi) \Delta V(t) dx_t dy_t \\ & + \int_{\partial D_A} \left\{ V(t) \frac{\partial}{\partial n_t} G_1(t, \xi) - G_1(t, \xi) \frac{\partial}{\partial n_t} V(t) \right\} ds_t. \end{aligned}$$

Since $G_1(t, \xi) = 0$ for $\text{Im}(\xi) = 0$, and since $\partial D_A = [-A, A] \cup \Gamma_A$, the triangle inequality yields

$$(4.49) \quad \begin{aligned} |V(\xi)| \leq & \left| \iint_{D_A} G_1(t, \xi) K_1(t) V(t) dx_t dy_t \right| \\ & + \left| \int_{-A}^A V(t) \frac{\partial}{\partial n_t} G_1(t, \xi) dt \right| \\ & + \left| \int_{\Gamma_A} \left\{ V(t) \frac{\partial}{\partial n_t} G_1(t, \xi) - G_1(t, \xi) \frac{\partial}{\partial n_t} V(t) \right\} ds_t \right|. \end{aligned}$$

For the integral over the outer arc Γ_A in (4.49), we have

$$(4.50) \quad \left| \int_{\Gamma_A} \left\{ V(t) \frac{\partial}{\partial n_t} G_1(t, \xi) - G_1(t, \xi) \frac{\partial}{\partial n_t} V(t) \right\} ds_t \right| \leq C_1 \quad \text{for } |\xi| < A/2,$$

where C_1 is a nonnegative constant, as it can be easily checked in view of the boundedness of the integrands for ξ near the origin. From Lemma 3.2, further, it easily follows that $V \in H^1(D_A)$, and thus, bounding the absolute value of the first integral in equation (4.49) by means of the Cauchy-Schwarz inequality, we obtain the bound

$$(4.51) \quad \left| \iint_{D_A} G_1(t, \xi) K_1(t) V(t) dx_t dy_t \right| \leq \|G_1\|_{L^2(D_A)} \|V\|_{L^2(D_A)} \max_{t \in D_A} (K_1(t))$$

for all $\xi \in D_A$. As is well known, finally, double layer potentials for bounded densities are uniformly bounded in all of space, see e.g., [16, Lemma 3.20]). It follows that the second integral in equation (4.49), and therefore $V(\xi)$ itself, is uniformly bounded for $\xi \in \mathbb{R}^2$ since, in view of (4.45), Definition 3.1 and Theorem 4.2, $V(t)$ is a bounded function for $t_2 = \text{Im}(t) = 0$. The boundedness of $V(\xi)$ in a neighborhood of the origin has therefore been established, and relation (4.46) then follows directly for all $\mu < 0$. The proof is now complete. \square

Corollary 4.10. *Let h denote a positive integer. Then, the h -order derivative $D^h V$ of the solution V of problem (4.44)–(4.45) with respect to ξ satisfies the asymptotic relation*

$$(4.52) \quad D^h V = o(\xi^{\mu-h}), \quad \xi \rightarrow 0,$$

for all $\mu < 0$.

Proof. See [28, Section 4]. □

We now proceed with the main proof of this section, which is based on an inductive argument similar to that used in the proof of Theorem 4.2.

Proof of Theorem 4.3. Applying the Green formula on the set $D_{A,\delta}$, equation (4.28) and letting $\delta \rightarrow 0$, we obtain

$$(4.53) \quad \begin{aligned} V(\xi) = & \iint_{D_A} (-K_1(t)V(t))G_1(t, \xi) dt \\ & - \int_{-A}^A V(t) \frac{\partial}{\partial n_t} G_1(t, \xi) dt + p_1(\xi) + p_2(\bar{\xi}), \end{aligned}$$

where p_1 and p_2 denote the power series with positive radii of convergence. In view of equation (4.45), Definition 3.1 and Theorem 4.2, on the other hand, we see that, for any given integer \mathcal{L} , the boundary values of V at $\xi_2 = 0$ satisfy

$$(4.54) \quad V(\xi_1, 0) = V(\xi) = u_e(\xi) = \mathcal{P}_{y_0}^{\mathcal{L}}(\xi^{1/2}, \bar{\xi}^{-1/2}) + o(\xi^{\mathcal{L}})$$

for $\xi_2 = \text{Im}(\xi) = 0$, see (4.5). Relying on equations (4.53) and (4.54) as well as Lemma 4.8, an inductive argument similar to that used in the proof of Theorem 4.2 shows that, for any integer \mathcal{N} , the function V satisfies an asymptotic relation of the form

$$(4.55) \quad V(\xi) = \mathcal{P}^{\mathcal{N}}(\xi^{1/2}, \bar{\xi}^{-1/2}) + o(\xi^{\mathcal{N}}) \quad \text{as } \xi \rightarrow 0,$$

where $\mathcal{P}^{\mathcal{N}}$ is an \mathcal{N} -dependent polynomial. In view of corollaries (4.6) and (4.10), substitution of the normal derivatives of equations (4.5) and (4.55) for $\text{Im}(\xi) = 0$ into equation (3.14) yields

$$(4.56) \quad \psi(\xi) = \xi^{-1/2} \mathcal{Q}_1^{\mathcal{N}}(\xi^{1/2}, \bar{\xi}^{-1/2}) + \bar{\xi}^{-1/2} \mathcal{Q}_2^{\mathcal{N}}(\xi^{1/2}, \bar{\xi}^{-1/2}) + o(\xi^{\mathcal{N}-1})$$

for $\xi_2 = \text{Im}(\xi) = 0$, where $\mathcal{Q}_i^{\mathcal{N}}$ are \mathcal{N} -dependent polynomials. The desired asymptotic relations (4.6) now follow by reexpressing (4.56) in terms of the distance function d , and the proof is thus complete. □

5. Singularity resolution via Fourier continuation. Theorem 4.2 tells us that the solutions of the Zaremba problem (1.1) possess a very specific singularity structure near the Dirichlet-Neumann junctions which, as shown in Theorem 4.3, are inherited by the solutions of the corresponding integral equation system (3.2). In particular, equation (4.6) shows that the integral equation solutions can be expressed as a product of the function $1/\sqrt{d}$ and a smooth function of \sqrt{d} , where d denotes the distance to the Dirichlet-Neumann junction.

The question thus arises as to how to incorporate the singular characteristics of the integral equation solutions in order to design a numerical integration method of a high order of accuracy for the numerical discretization of the integral equation system (3.2). A relevant reference in these regards is provided by the contribution [5], also see [30], which provides a high-order solver for the problem of scattering by open arcs. As is well known, open-arc integral equation solutions possess singularities around the end-points; they can be expressed as a product of the function $1/\sqrt{d}$ and a smooth function of d or, in other words, the asymptotics of the integral solutions are functions which *only contain powers of \sqrt{d} with exponents equal to $(2n - 1)$ for $n \geq 0$* . In particular [5], a change of variables of the form $t = \cos s$, $0 \leq s \leq \pi$, in parameter space completely regularizes the problem, and it thus gives rise to spectrally accurate numerical approximations of the form

$$(5.1) \quad \psi(s) \sim \sum_{j=0}^n C_j \cos(js), \quad 0 \leq s \leq \pi$$

for the integral-equation solutions ψ .

As shown in Theorem 4.3, on the other hand, the asymptotic expansions of the integral-equation solutions ψ considered in this paper contain *all integer powers of \sqrt{d}* , and therefore, as established in [2], a cosine change of variables such as the one considered above leads to a full Fourier series containing all 2π -periodic cosines and sines,

$$(5.2) \quad \psi(s) \sim \sum_{j=0}^n C_j \cos(js) + D_j \sin(js), \quad 0 \leq s \leq \pi,$$

even though values for ψ can only be determined for $0 \leq s \leq \pi$. The key element which allows such expansions in the extended interval $[0, 2\pi]$

is the Fourier continuation (FC) method introduced in [3, 6] and first suitably generalized to the present context in [2]. This leads to a Fourier series that converges with high-order accuracy to the integral density ψ in the interval $[0, \pi]$.

Exploiting such rapidly convergent Fourier expansions, a numerical method for Zaremba boundary value problems is presented in the next section.

6. Numerical algorithms. Closed form expressions (derived in collaboration with Reitich) are presented in [1] for the integrals of products, trigonometric functions and logarithms that appear in equation (3.2) upon substitution of the expansion (5.2); as shown in [2], use of such expressions leads to highly accurate approximations of the integral operators in equation (3.2). In particular, these algorithms rely on Nyström discretization of the solution ψ ; in view of the structure of the integrand, the discretization points used are given as the image of a uniform mesh in s variable under the change of variables $t = \cos(s)$. The Fourier series (5.2) is obtained via application of the Fourier continuation method in the s variable, and a discrete version of the integral equation system is thus obtained on the basis of a resulting matrix \mathcal{A} .

These discrete operators were used in reference [2] as important building blocks of an efficient algorithm for evaluation of eigenvalues and eigenfunctions of the Laplace operator under Zaremba boundary conditions. Figure 4 presents high-frequency Zaremba eigenfunctions obtained by means of that solver. In what follows, we use these discrete operators as well as the vector \mathbf{f} of values of given functions f and g at the aforementioned discretization points to produce solutions of the Zaremba problem (1.1). For simplicity, we rely on an LU -decomposition applied to the linear system $\mathcal{A}\mathbf{c} = \mathbf{f}$ to obtain a discrete approximation \mathbf{c} of the solution ψ . Note, however, that, as mentioned in Theorem 3.3, the integral equation system (3.2) is not invertible for a certain discrete set of values of k (spurious resonances) that correspond to Dirichlet eigenvalues on the complementary set $\mathbb{R}^2 \setminus \Omega$. A numerical methodology described in Appendix A extends applicability of the proposed solvers to all frequencies, including spurious resonances. A variety of numerical results obtained by means of the aforementioned Zaremba boundary-value solvers are presented in the following section.

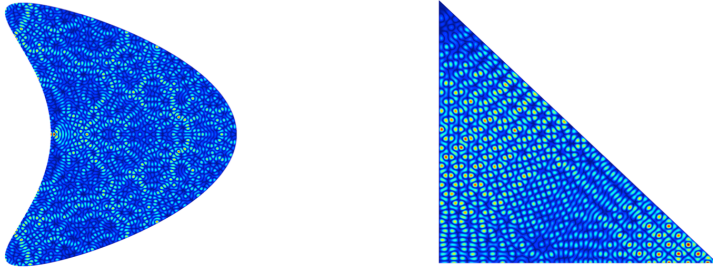


FIGURE 4. High frequency Zaremba eigenfunctions.

7. Numerical results. This section presents results of applications of the new solvers to problems of scattering by smooth obstacles under boundary conditions of Zaremba type. This entails solution of problem (1.1) for exterior domains Ω and for which the right hand sides f and g are given by

$$(7.1) \quad \begin{aligned} f(x) &= e^{ik\alpha \cdot x} = e^{ik(\cos(\alpha)x_1 + \sin(\alpha)x_2)} \\ g(x) &= n_x \cdot \nabla e^{ik\alpha \cdot x}, \end{aligned}$$

where α is the angle of incidence.

In our first experiment, we apply the solver to a kite-shaped domain whose boundary is given by the parametrization

$$(7.2) \quad x_1(t) = \cos(t) + 0.65 \cos(2t) - 0.65 \quad \text{and} \quad x_2(t) = 1.5 \sin(t),$$

assuming the Neumann and Dirichlet boundary portions Γ_N and Γ_D corresponding to $t \in [\pi/2; 3\pi/2]$ and its complement, respectively. Figure 5 depicts the scattered and total fields that result as a wave with wavenumber $k = 40$ and incidence angle $\alpha = \pi/8$ impinges on the object. Figure 6 demonstrates the high-order convergence results for the value of the scattered field $u(x_0)$ at the point $x_0 = (1, 2)$ in the exterior of the domain.

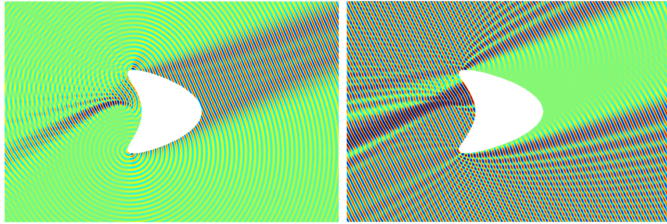


FIGURE 5. Scattering from a kite-shaped domain under Zaremba boundary conditions. Left: Scattered field. Right: Total field.

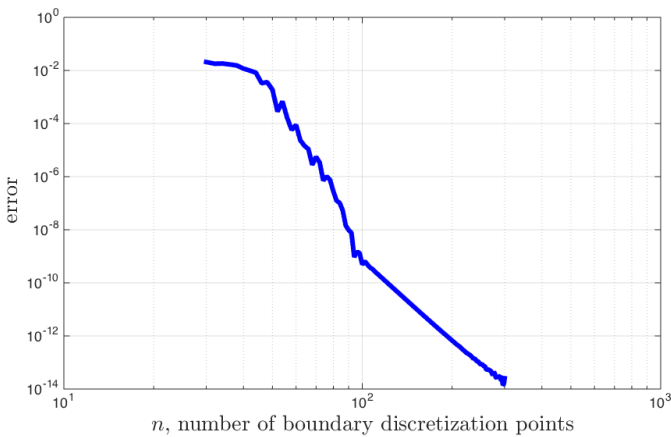


FIGURE 6. Convergence of the value $u(x_0)$ ($x_0 = (1, 2)$) for a kite shaped domain with $k = 10$.

A similar example concerns scattering by the unit disc under Dirichlet and Neumann boundary conditions prescribed on the left and right halves of the disc boundary, respectively. Figure 7 displays the scattered and total fields that result as a wave with wavenumber $k = 50$ and incidence angle $\alpha = \pi/8$ impinges on the disc.

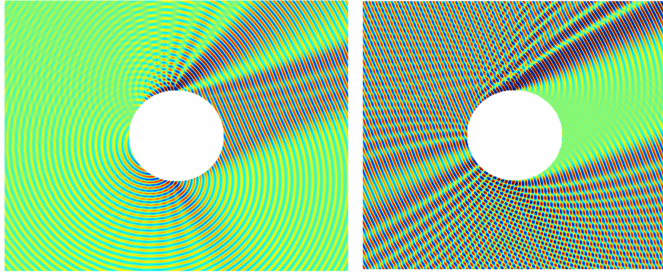


FIGURE 7. Scattering from a disc under Zaremba boundary conditions. Left: Scattered field. Right: Total field.

To conclude this section, we present a brief comparison of the proposed solvers with one of the most efficient Zaremba solvers previously available [18, 19]. This method, based on iterative inverse preconditioning and which applies to a variety of singular problems, has been implemented in a numerical MATLAB package which is freely available [19]. Unfortunately, Zaremba boundary conditions are not implemented in that package. At any rate, numerical experiments suggest that the execution times required by the algorithm [19] are not as favorable as those required by the solvers proposed in this paper. Indeed, the solver [19] (which is applicable to domains with corners) required a computing time of 0.46 seconds to solve the Dirichlet problem for Helmholtz equation with wavenumber $k = 2$ on the unit disc (whose boundary was partitioned into two Dirichlet arcs) by means of GMRES iterations with a GMRES residual of 10^{-13} , while a GMRES-based implementation of the FC-based solver presented in this paper runs in 0.06 seconds for the significantly more challenging Zaremba problem for the Helmholtz equation on the same domain, with the same incident wave frequency and with the same GMRES residual. (These and all other numerical results presented in this section were obtained on a single core of a 2.4 GHz Intel E5-2665 processor.) Such time differences, a factor of eight in this case, can be very significant in practice, in contexts where thousands or even tens of thousands of solutions are necessary, as is the case in inverse problems as well as in our own solution [2] of high-frequency eigenvalue problems, etc. The main reason for the difference in execution times is that, although the iterative solver [19] requires a limited number of iterations, certain iteration-

dependent matrix entries occur in this solver (in view of corresponding iteration dependent discretization points it uses), which require a large number of evaluations of expensive Hankel functions at each iteration, and, thus, a significant computing cost per iteration.

8. Conclusions. This paper presented, for the first time, detailed asymptotic expansions near Dirichlet-Neumann junctions for solutions of Zaremba problems on smooth two-dimensional domains. By precisely accounting for singularities of the boundary densities and kernels on the basis of Fourier-continuation expansions, further discretizations of high-order accuracy were obtained for relevant boundary integral operators. The resulting integral-equation solver allows for accurate and efficient approximation of the highly-singular Zaremba solutions at both the low- and high-frequency regimes.

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APPENDIX

A. Exterior solution at interior resonances. This appendix describes an algorithm for evaluation of the solution of the problem (1.1) for an exterior domain Ω , and for a value of k^2 that either equals or is close to an interior Dirichlet eigenvalue of the Laplace operator in the bounded set $\mathbb{R}^2 \setminus \Omega$. As mentioned in Section 3, in this case, the system of integral equations (3.2) does not have a unique solution. However, the solution of the PDE is uniquely solvable for any value of k .

The non-invertibility of the aforementioned continuous systems of integral equations at a wavenumber $k = k^*$ manifests itself at the discrete level in non-invertibility or ill-conditioning of the system matrix $\mathcal{A} := \mathcal{A}(k)$ for values of k close to k^* . Therefore, for k near k^* the numerical solution of the Zaremba problems under consideration (which, in what follows, will be denoted by $\tilde{u} := \tilde{u}_k(x)$ to make explicit the solution dependence on the parameter k) cannot be obtained via direct solution of the linear system $\mathcal{A}(k) \cdot \mathbf{c} = \mathbf{f}$. As is well known, however, the solutions $u = u_k$ of the continuous boundary value problem are analytical functions of k for all real values of k , including, in particular, for k equal to any one of the spurious resonances mentioned

above, and therefore, the approximate values $\tilde{u}_k(x)$ for k sufficiently far from k^* can be used, via analytic continuation, to obtain corresponding approximations around $k = k^*$ and even at a spurious resonance $k = k^*$.

In order to implement this strategy for a given value of $k = k_0$, it is necessary for our algorithm to possess a capability of performing two steps:

1. to determine whether k_0 is “sufficiently far” from any one of the spurious resonances k^* .
2. (a) If k_0 is “sufficiently far,” then simply invert the linear system by means of either an LU decomposition or the usually already available singular value decomposition (which is used to determine the “distance from resonance”).
- (b) If k_0 is not “sufficiently far” from one of the spurious resonances k^* , then obtain the PDE solution at k_0 by analytic continuation from solutions for values of k in a neighborhood of k_0 which are “sufficiently far” from k^* .

Here, k is said to be “sufficiently far” from the set of spurious resonances provided the corresponding linear system can be inverted without significant error amplifications. It has been noticed in practice [23] that the regions within which inversion is not possible are very small indeed, in such a way that analytic continuation from “sufficiently far” can be performed to the singular or nearly singular frequency k_0 with any desired accuracy. For full details in these regards see [23].

Numerical results confirming highly accurate evaluation of the PDE solution even for resonant frequencies are presented in Figure 8 for the case of the FC-based solver applied to the Zaremba boundary value problem on the unit disc. The solution errors are displayed for two frequencies: $k = 11$ (where the solutions are obtained using an LU decomposition) and the resonant frequency $k = 11.791534439014281$ (with solutions obtained by means of analytic continuation based on fifth order Chebyshev expansions). Note that a total of $(m+1)$ integral equation solutions are necessary to obtain a Chebyshev expansion of order m ($m = 5$ in the experiment mentioned above), and thus, the cost of solution at resonant frequencies is increased by a factor of $(m+1)$. Clearly, the proposed approach can tackle the spurious-resonance problem without difficulty.

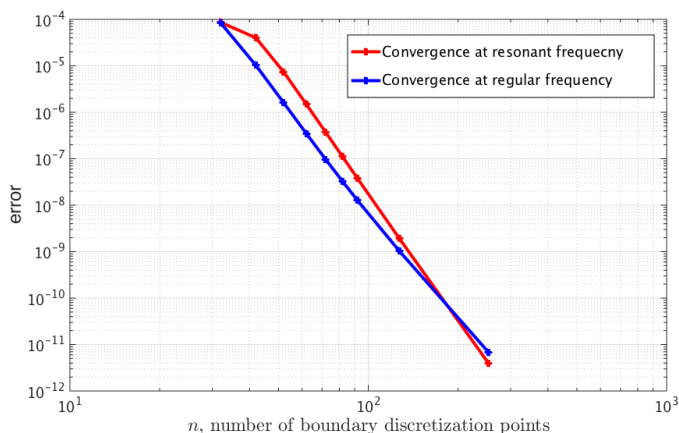


FIGURE 8. Convergence comparison at a regular and a resonant frequency.

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