

COMPUTING THE NORMS OF ELEMENTARY OPERATORS

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ABSTRACT. We provide a direct proof that the Haagerup estimate on the completely bounded norm of elementary operators is best possible in the case of $\mathcal{B}(H)$ via a generalisation of a theorem of Stampfli. We show that for an elementary operator T of length ℓ , the completely bounded norm is equal to the k -norm for $k = \ell$. A C^* -algebra A has the property that the completely bounded norm of every elementary operator is the k -norm, if and only if A is either k -subhomogeneous or a k -subhomogeneous extension of an antiliminal C^* -algebra.

1. Introduction

For A a C^* -algebra, an operator $T: A \rightarrow A$ is called an *elementary operator* if T can be expressed in the form

$$(1) \quad Tx = \sum_{i=1}^{\ell} a_i x b_i$$

with a_i and b_i ($1 \leq i \leq \ell$) in the multiplier algebra $M(A)$ of A (see [17]). A well-known estimate due to Haagerup states that

$$(2) \quad \|T\| \leq \|T\|_{cb} \leq \sqrt{\left\| \sum_{j=1}^{\ell} a_j a_j^* \right\| \left\| \sum_{j=1}^{\ell} b_j^* b_j \right\|}$$

where $\|T\|_{cb}$ is the completely bounded (or CB) norm of T .

For $A = \mathcal{B}(H)$, our main result shows how to recognise equality in (2), in a way that generalises a result of Stampfli [22] dealing with special elementary operators $Tx = a_1 x 1 - 1 x b_2$. The bound on $\|T\|_{cb}$ in the estimate (2) is known to be sharp, at least in the case $A = \mathcal{B}(H)$, provided one considers all possible representations of T as $Tx = \sum_{j=1}^{\ell} a_j x b_j$ (and takes the infimum of the upper bounds obtained). We first give a direct argument to characterise

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equality of $\|T\|$, $\|T\|_{cb}$ with the right hand side of (2) for $A = \mathcal{B}(H)$ and this involves a balance condition on certain numerical ranges of the a_i and b_i (Proposition 3.1). More accurately, the numerical ranges we consider are asymmetric and involve $a_j a_i^*$ on the left and $b_j^* b_i$ on the right. These numerical ranges are not convex in general but when we apply our condition to look for equality of $\|T\|_k$, $\|T\|_{cb}$ and the right hand side of (2) we end up considering convex combinations of k elements of the numerical range we use for $k = 1$. We reach the convex hull by the time $k = \ell$ and for this k the balance condition must be satisfied for some representation of T (Theorem 3.3).

We can pass to general C^* -algebras A by considering representations and we can then conclude that $\|T\|_k = \|T\|_{cb}$ for $k = \ell$. It seems to be new to have any bound on k (except for $\ell = 1$) without conditions on A . A simple example (Example 3.5) shows that the result is optimal (that is, not true for $k = \ell - 1$ for any $\ell > 1$).

Our techniques allow us to embed the example in a continuous trace C^* -algebra as long as the algebra has an irreducible representation of large enough dimension (Theorem 4.3). This is the step we need to characterise those C^* -algebras A where $\|T\|_k = \|T\|_{cb}$ for all elementary $T: A \rightarrow A$ (with k independent of T). The remaining parts of the proof of this characterisation can be borrowed from [4] where the case $k = 1$ was settled.

We recall that there are somewhat similar results for complete positivity of elementary operators. In [23] it is shown that an elementary T (as in (1)) must be completely positive (CP) if it is k -positive for any k at least as big as the integer part of $\sqrt{\ell}$ (and again this is optimal). In [24] the class of C^* -algebras A where k -positivity implies complete positivity of elementary operators $T: A \rightarrow A$ is characterised, leading to the same class of algebras as for the CB situation. Again the case $k = 1$ was settled earlier in [4].

This difference between the optimal k in the CP and CB cases suggests looking at norms for the subclass of hermitian-preserving elementary operators. In Theorem 3.12 we establish a smaller k (that is $k < \ell$ if $\ell > 1$) for which $\|T\|_k = \|T\|_{cb}$ holds in this subclass, but examples show that the optimal k must be proportional to ℓ in general.

Notation. We are using M_n for the $n \times n$ complex matrices, or the bounded linear operators on the standard n -dimensional Hilbert space \mathbb{C}^n . Our Hilbert spaces H are all complex and H^n means the orthogonal direct sum of n copies of H , or the space of n -tuples of elements of H with the natural inner product. $\mathcal{B}(H)$ denotes the bounded linear operators on H . $M_n(A)$ means the $n \times n$ matrices with entries in A .

The CB norm of a linear map $T: A \rightarrow A$ is defined as $\|T\|_{cb} = \sup_{k \geq 1} \|T\|_k$ where $\|T\|_k = \|T^{(k)}\|$ and $T^{(k)}: M_k(A) \rightarrow M_k(A)$ is defined via

$$T^{(k)}(x_{ij})_{i,j=1}^k = (T(x_{ij}))_{i,j=1}^k.$$

If $A \subset \mathcal{B}(H)$ then we can regard $M_k(A) = A \otimes M_k$ as a C^* -subalgebra of $\mathcal{B}(H) \otimes M_k = \mathcal{B}(H \otimes \mathbb{C}^k) = \mathcal{B}(H^k)$ and in this way there is a unique

C^* norm on each $M_k(A)$ (compatible with the natural algebra structure and involution). There is an extensive literature relating to the CB norm and we cite [18], [10], [11] as general references.

We will use $\mathcal{E}\ell(A)$ for the elementary operators on A , M_n^+ for the positive semidefinite $n \times n$ matrices.

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2. Joint numerical ranges

Our terminology here is motivated by concepts of Stampfli [22] and does not follow standard terminology exactly (see [6, Chapter 7]).

DEFINITION 2.1. For a tuple $(c_1, c_2, \dots, c_\ell)$ of operators $c_i \in \mathcal{B}(H)$, we denote by $W_m(c_1, c_2, \dots, c_\ell)$ the ‘matrix numerical range’

$$W_m(c_1, c_2, \dots, c_\ell) = \{((c_j^* c_i \xi, \xi))_{i,j=1}^\ell : \xi \in H, \|\xi\| = 1\} \subset M_\ell.$$

We will also consider a subset of the closure of W_m which we call the ‘extremal matrix numerical range’ and denote by

$$W_{m,e}(c_1, c_2, \dots, c_\ell) = \left\{ \alpha \in \overline{W_m(c_1, c_2, \dots, c_\ell)} : \text{trace}(\alpha) = \left\| \sum_{i=1}^\ell c_i^* c_i \right\| \right\}.$$

Fixing any preferred linear order for the ℓ^2 entries of an $\ell \times \ell$ matrix, our W_m is the joint spatial numerical range W of [6, p. 137] for the ℓ^2 -tuple $c_j^* c_i$. For future use, note that $\langle c_j^* c_i \xi, \xi \rangle = \langle c_i \xi, c_j \xi \rangle$.

We will sometimes abbreviate $W_m(c_1, c_2, \dots, c_\ell)$ as $W_m(\mathbf{c})$ with \mathbf{c} denoting the ℓ -tuple (and usually viewed as a column).

PROPOSITION 2.2. For $c_1, c_2, \dots, c_\ell \in \mathcal{B}(H)$, $W_m(c_1, c_2, \dots, c_\ell)$ is contained in M_ℓ^+ and $W_{m,e}(c_1, c_2, \dots, c_\ell)$ is nonempty and consists of those elements of the closure $\overline{W_m}$ of maximal trace.

Proof. To show the positivity, consider $(z_1, z_2, \dots, z_n) \in \mathbb{C}^\ell$ and observe

$$\sum_{i,j} z_i \overline{z_j} \langle c_j^* c_i \xi, \xi \rangle = \left\| \sum_{i=1}^\ell z_i c_i \xi \right\|^2 \geq 0.$$

The fact that $W_{m,e}(c_1, c_2, \dots, c_\ell) \neq \emptyset$ is easy to verify, as are the other assertions. □

REMARK 2.3. Arveson [5] gives another definition of (a sequence of) matrix-valued numerical ranges associated with a fixed operator. For $T \in \mathcal{B}(H)$, $\mathcal{W}_n(T)$ is the set of all possible values $\phi(T)$ where $\phi: C^*(T) \rightarrow M_n$ is a completely positive unital map on the C^* -algebra generated by T .

Our $W_m(c_1, c_2, \dots, c_\ell)$ is contained in $\mathcal{W}_\ell(T)$ when we take $T = (c_j^*c_i)_{i,j=1}^\ell$ in $M_\ell(\mathcal{B}(H)) = \mathcal{B}(H^\ell)$. To see this note that for $\xi \in H$ of norm one, $\phi_\xi: \mathcal{B}(H) \rightarrow \mathbb{C}$ given by $\phi_\xi(x) = \langle x\xi, \xi \rangle$ is a (pure) state on $\mathcal{B}(H)$ so that it is a completely positive unital map. We have $W_m(c_1, c_2, \dots, c_\ell) = \{\phi_\xi^{(\ell)}(T) : \xi \in H, \|\xi\| = 1\}$.

If we take $e_{ij} \in M_{\ell+1}$ to be the matrix with 1 in the (i, j) place and zeros elsewhere, and $c_i = e_{1i}$ then $W_m(c_1, c_2, \dots, c_\ell)$ consists of all positive semidefinite rank one matrices of trace ≤ 1 . In this case the convex hull of W_m coincides with $\mathcal{W}_n(T)$, but because $\mathcal{W}_n(T)$ is invariant under conjugation by unitary matrices one can see that the convex hull of W_m is in general smaller than $\mathcal{W}_n(T)$.

PROPOSITION 2.4. Let $\mathbf{c} = (c_1, c_2, \dots, c_\ell)$ with $c_i \in \mathcal{B}(H)$. Denote by $c_i^{(k)} = c_i \otimes I_k \in M_k(\mathcal{B}(H)) = \mathcal{B}(H^k)$ the block diagonal $k \times k$ matrix with c_i in the diagonal blocks. Let $\mathbf{c}^{(k)}$ denote the corresponding ℓ -tuple $(c_i^{(k)})_{i=1}^\ell$. Then

$$W_m(\mathbf{c}^{(k)}) = \left\{ \sum_{j=1}^k t_j \alpha_j : \alpha_j \in W_m(\mathbf{c}), t_j \geq 0, \sum_j t_j = 1 \right\}$$

(the set of convex combinations of k elements of $W_m(\mathbf{c})$). A similar statement holds for $W_{m,e}$.

Moreover, for $k = \min(\ell, \dim(H))$, $W_m(\mathbf{c}^{(k)})$ is convex, and $W_{m,e}(\mathbf{c}^{(k)})$ is convex and closed.

Proof. A simple calculation shows that if $\xi = (\xi_1, \xi_2, \dots, \xi_k) \in H^k$ is a unit vector, then

$$\langle (c_i^{(k)})\xi, (c_j^{(k)})\xi \rangle = \sum_r t_r \langle c_i \xi'_r, c_j \xi'_r \rangle$$

where $t_r = \|\xi_r\|^2$ and ξ'_r is the unit vector in the direction of ξ_r .

Alternatively if we denote by $\xi_i^* \otimes \xi_i$ the rank one operator on H given by $\theta \mapsto \langle \theta, \xi_i \rangle \xi_i$ we can see that $y = \sum_{i=1}^k \xi_i^* \otimes \xi_i$ is a positive operator of trace $\sum_{i=1}^k \|\xi_i\|^2 = 1$ and of rank at most k . Every such y can be written in the form $\sum_{i=1}^k \xi_i^* \otimes \xi_i$. Moreover

$$\left(\left\langle (c_i^{(k)})\xi, (c_j^{(k)})\xi \right\rangle \right)_{i,j=1}^\ell = (\text{trace}(c_j^* c_i y))_{i,j=1}^\ell.$$

To show that $W_m(\mathbf{c}^{(k)})$ is convex we need only show that $W_m(\mathbf{c}^{(k+1)}) = W_m(\mathbf{c}^{(k)})$ and if $k = \dim H$ that is clearly true. For $k = \ell < \dim H$, start with

$\alpha = (\text{trace}(c_j^* c_i y_0))_{i,j=1}^\ell \in W_m(\mathbf{c}^{(k+1)})$ where $y_0 = \sum_{i=1}^{k+1} \xi_i^* \otimes \xi_i$ is positive, of trace 1 and rank at most $k + 1$. If the rank of y_0 is $< k + 1$ we are done and so we assume that the rank is $k + 1$. We will work within the span of the ξ_i , by taking P to be the orthogonal projection onto the span, temporarily restricting H to PH and considering $c_{ij} = Pc_j^* c_i P \in \mathcal{B}(PH)$ in place of $c_j^* c_i$. Note that $c_{ij}^* = c_{ji}$.

Consider

$$S_{k+1} = \{y \in \mathcal{B}(PH) : y > 0, \text{trace } y = 1, \text{trace}(c_{ij}y) = \alpha_{ij} \text{ for } 1 \leq i, j \leq \ell\}.$$

Note that this set is compact (a closed subset of the trace one and positive definite matrices). The total number of real linear equations to be satisfied by $y \in S_{k+1}$ is $1 + \ell^2$ and we are working inside the hermitian elements of $\mathcal{B}(PH)$, a space of dimension $(\dim PH)^2 = (\ell + 1)^2 > 1 + \ell^2$. More precisely we have $S_{k+1} \subset \{y = y^* \in \mathcal{B}(PH), \text{trace } y = 1\} = \Pi_{k+1}$, an affine space of dimension $(\ell + 1)^2 - 1$. S_{k+1} is the intersection of the convex set Σ_{k+1} of positive elements of Π_{k+1} with an affine subspace of Π_{k+1} of codimension ℓ^2 . $S_{k+1} \neq \emptyset$ because of y_0 . Thus S_{k+1} must contain some point y which is not a relative interior point of $\Sigma_{k+1} \subset \Pi_{k+1}$. Such a y must have rank $\leq k$ and so $\alpha = (\text{trace}(c_j^* c_i y))_{i,j=1}^\ell \in W_m(\mathbf{c}^{(k)})$.

The statement about $W_{m,e}$ now follows. □

REMARK 2.5. The argument above is a proof of a remnant of convexity for the joint (spatial) numerical range of the finite list of operators on $\mathcal{B}(H)$. The Toeplitz-Hausdorff theorem asserts that the numerical range of a single operator is convex. That is known to be false in general for the joint numerical range of two operators $\{(\langle x_1 \xi, \xi \rangle, \langle x_2 \xi, \xi \rangle) : \xi \in H, \|\xi\| = 1\}$, though it is true for two hermitian operators x_1, x_2 . The argument above shows that the set of all convex combinations of k elements of the joint numerical range of n operators $x_1, x_2, \dots, x_n \in \mathcal{B}(H)$ is convex provided $(k + 1)^2 > 1 + d$ for d the dimension of the real span of the real and imaginary parts of the x_i (or $k = \dim H$).

There is a case where the joint numerical range is known to be convex, that is for a commuting n -tuple of normal operators (x_1, x_2, \dots, x_n) (see [6, p. 137]). It follows that if $c_j^* c_i$ are commuting operators, then $W_m(\mathbf{c})$ is convex.

3. Norms of elementary operators on $\mathcal{B}(H)$

The Haagerup estimate (2) can be derived from the following matrix formulation of the representation (1)

$$Tx = [a_1, a_2, \dots, a_\ell](x \otimes I_\ell) \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_\ell \end{bmatrix} = \mathbf{a}(x \otimes I_\ell)\mathbf{b}$$

where $x \otimes I_\ell$ is the block diagonal element of $M_\ell(A) = A \otimes M_\ell$ with x 's along the diagonal. We will use this row (\mathbf{a}) and column (\mathbf{b}) notation often. From $Tx = \mathbf{a}(x \otimes I_\ell)\mathbf{b}$ ($x \in A$), $T^{(k)}(X) = \mathbf{a}^{(k)}(X \otimes I_\ell)\mathbf{b}^{(k)}$ ($X \in M_k(A)$) where

$$\mathbf{a}^{(k)} = [a_1 \otimes I_k, a_2 \otimes I_k, \dots, a_\ell \otimes I_k]$$

and $\mathbf{b}^{(k)}$ is similarly related to \mathbf{b} . We get the estimate (2) from $\|T\|_k \leq \|\mathbf{a}^{(k)}\| \|\mathbf{b}^{(k)}\| = \|\mathbf{a}\| \|\mathbf{b}\|$. From (2) we get

$$(3) \quad \|T\|_{cb} \leq \frac{1}{2} \left(\left\| \sum_{j=1}^{\ell} a_j a_j^* \right\| + \left\| \sum_{j=1}^{\ell} b_j^* b_j \right\| \right).$$

As a simple argument shows, this estimate is essentially equivalent to (2) because of the ambiguity in the choice of a_i and b_i in (1).

This ambiguity extends at least to the bilinearity of $x \mapsto axb$ in a and b and we can say that every $T \in \mathcal{E}\ell(A)$ can be represented in the form (1) with linearly independent $(a_i)_{i=1}^\ell$ and $(b_i)_{i=1}^\ell$. For general A , further ambiguity can arise (for example from the centre of the multiplier algebra $M(A)$ —see [1], [8]) but if we simplify to the case of $A = \mathcal{B}(H)$ then no further ambiguity can arise.

An argument using polar decompositions given in [11, Lemma 9.2.3] shows that the infimum of the right hand side of (3) over all possible representations (1) of T is the same as the infimum with $(a_i)_{i=1}^\ell$ and $(b_i)_{i=1}^\ell$ assumed linearly independent. In the case of $A = \mathcal{B}(H)$ we can relate all such linearly independent representations of T to one another via an invertible matrix $\alpha = (\alpha_{ij})_{i,j=1}^\ell$ of scalars:

$$Tx = \sum_{i=1}^{\ell} a'_i x b'_i = \mathbf{a}'(x \otimes I_\ell)\mathbf{b}' = \mathbf{a}\alpha^{-1}(x \otimes I_\ell)\alpha\mathbf{b}.$$

We have

$$(4) \quad W_m(\mathbf{b}') = \alpha W_m(\mathbf{b})\alpha^*,$$

$$(5) \quad W_m((\mathbf{a}')^*) = (\alpha^{-1})^* W_m(\mathbf{a}^*)\alpha^{-1}$$

by simple calculations. If we assume that α is unitary, then the trace is invariant and we have similar relations for $W_{m,e}$, the elements of $\overline{W_m}$ of maximal trace:

$$(6) \quad W_{m,e}((\mathbf{a}')^*) = \alpha W_{m,e}(\mathbf{a}^*)\alpha^*, \quad W_{m,e}(\mathbf{b}') = \alpha W_{m,e}(\mathbf{b})\alpha^* \quad (\alpha^* = \alpha^{-1}).$$

An important fact we will use is that there is a representation of T with the right hand side of (3) attaining the minimum possible. A more general statement is shown in [11, Lemma 9.2.7], but the fact we use can be shown by elementary means.

PROPOSITION 3.1. *Let $A = \mathcal{B}(H)$ and let $T \in \mathcal{E}\ell(\mathcal{B}(H))$ be given by (1). Then we have equality in*

$$\|T\| \leq \|T\|_{cb} \leq \frac{1}{2} \left(\left\| \sum_{j=1}^{\ell} a_j a_j^* \right\| + \left\| \sum_{j=1}^{\ell} b_j^* b_j \right\| \right)$$

if and only if the intersection

$$W_{m,e}(a_1^*, a_2^*, \dots, a_\ell^*) \cap W_{m,e}(b_1, b_2, \dots, b_\ell)$$

is nonempty.

Proof. Consider first the case when H is finite-dimensional and the intersection is non-empty. Thus there exist unit vectors $\xi, \eta \in H$ with $\langle a_j a_j^* \xi, \xi \rangle = \langle b_j^* b_j \eta, \eta \rangle$ for $1 \leq j \leq \ell$ and

$$\sum_i \langle a_i a_i^* \xi, \xi \rangle = \left\| \sum_i a_i a_i^* \right\| = \left\| \sum_i b_i^* b_i \right\|.$$

Then $u(b_j \eta) = a_j^* \xi$ specifies a unique unitary map u from the span of $b_j \eta$ to the span of $a_j \xi$. (To make the argument more easy to follow we can assume that $(\langle b_j^* b_i \eta, \eta \rangle)_{i,j}$ is a diagonal matrix by using a unitary matrix α and replacing $\mathbf{a} = (a_1, a_2, \dots, a_\ell)$ by $\mathbf{a}\alpha^*$ and $\mathbf{b} = [b_1, b_2, \dots, b_\ell]^t$ by $\alpha\mathbf{b}$.)

We can then extend u to a unitary (or unitary times orthogonal projection) map on H and compute that

$$\langle T(u)\eta, \xi \rangle = \sum_{i=1}^{\ell} \langle u b_i \eta, a_i^* \xi \rangle = \sum_{i=1}^{\ell} \langle a_i a_i^* \xi, \xi \rangle = \|\mathbf{a}\| = \|\mathbf{b}\|.$$

Thus we have

$$\|T\| \geq (1/2)(\|\mathbf{a}\| + \|\mathbf{b}\|) \geq \|T\|_{cb} \geq \|T\|_1 = \|T\|,$$

forcing equality all around in this case.

When H is infinite dimensional we have to modify the argument only slightly to take account of that fact that we can only find unit ξ and η so as to get arbitrarily close approximations $\langle a_j a_i^* \xi, \xi \rangle \cong \langle b_j^* b_i \eta, \eta \rangle$ for $1 \leq i, j \leq \ell$ and

$$\sum_i \langle a_i a_i^* \xi, \xi \rangle \cong \left\| \sum_i a_i a_i^* \right\| = \left\| \sum_i b_i^* b_i \right\|.$$

We can then say that our u will have norm approximately 1.

For the converse, if $\|\sum_i a_i a_i^*\| \neq \|\sum_i b_i^* b_i\|$, then we have strict inequality between the right hand sides of (2) and (3). So we may suppose equality and normalise $\|\sum_i a_i a_i^*\| = \|\sum_i b_i^* b_i\| = 1$.

We know that $\|T\| = \sup \|T(u)\|$ over u unitary (by the Russo-Dye theorem [21], [12], or the more elementary fact that the each element of the open

unit ball of $\mathcal{B}(H)$ is an average of unitaries [15, p. 253]). Now $\|T(u)\| = \sup \Re \langle T(u)\eta, \xi \rangle$ over unit vectors $\xi, \eta \in H$ and we note that

$$\Re \langle T(u)\eta, \xi \rangle = \sum_{i=1}^{\ell} \Re \langle ub_i\eta, a_i^*\xi \rangle.$$

Let $\zeta_i = ub_i\eta$ and $\theta_i = a_i^*\xi$. Now

$$(\langle \zeta_i, \zeta_j \rangle)_{ij} = (\langle b_j^*b_i\eta, \eta \rangle)_{ij} \in W_m(\mathbf{b})$$

while $(\langle \theta_i, \theta_j \rangle)_{ij} \in W_m(\mathbf{a}^*)$.

Clearly

$$\begin{aligned} \Re \langle T(u)\eta, \xi \rangle &= \sum_{i=1}^{\ell} \Re \langle \zeta_i, \theta_i \rangle \leq \sum_{i=1}^{\ell} \|\zeta_i\| \|\theta_i\| \\ &\leq \sqrt{\sum_{i=1}^{\ell} \|\zeta_i\|^2} \sqrt{\sum_{i=1}^{\ell} \|\theta_i\|^2} \leq 1 \end{aligned}$$

and we have strict inequality unless $\zeta_i = \theta_i$ for all i and $\sum_{i=1}^{\ell} \|\zeta_i\|^2 = \sum_{i=1}^{\ell} \|\theta_i\|^2 = 1$, which forces the desired condition

$$(\langle \zeta_i, \zeta_j \rangle)_{ij} = (\langle \theta_i, \theta_j \rangle)_{ij} \in W_{m,e}(\mathbf{a}^*) \cap W_{m,e}(\mathbf{b}) \neq \emptyset.$$

Our aim is to quantify the inequality when the intersection is empty and show $\sum_{i=1}^{\ell} \Re \langle \zeta_i, \theta_i \rangle < 1 - \varepsilon$ where $\varepsilon > 0$ depends on $W_m(\mathbf{a}^*)$ and $W_m(\mathbf{b})$. The following argument is essentially a proof of the Cauchy-Schwarz estimate just above. With an eye to reusing this argument later, we prove a little more than we need just now. Applying the lemma to the closures $W_\theta = \overline{W_m(\mathbf{a}^*)}$ and $W_\zeta = \overline{W_m(\mathbf{b})}$ gives the desired inequality. \square

LEMMA 3.2. *Let W_θ and W_ζ be two closed subsets of M_ℓ^+ , where the maximum value of the trace on each set is 1 and $W_\theta \cap W_\zeta$ has no elements of trace 1. Then there are $\varepsilon > 0$ and open subsets U_θ and U_ζ of the positive definite $\ell \times \ell$ matrices with $W_\theta \subset U_\theta$ and $W_\zeta \subset U_\zeta$ so that for any vectors θ_i, ζ_i in any Hilbert space H such that $(\langle \theta_i, \theta_j \rangle)_{i,j=1}^{\ell} \in U_\theta$, $(\langle \zeta_i, \zeta_j \rangle)_{i,j=1}^{\ell} \in U_\zeta$ we always have*

$$\Re \sum_{i=1}^{\ell} \langle \theta_i, \zeta_i \rangle < 1 - \varepsilon.$$

Proof. Let $W_{\theta,e}$ be the intersection of W_θ with the matrices of trace 1, and similarly for $W_{\zeta,e}$. There is a positive shortest distance $\delta_0 > 0$ between points of the sets of $W_{\theta,e}$ and $W_{\zeta,e}$. (We measure the distance in the L^2 or Hilbert-Schmidt norm $\|\cdot\|_2$ on M_ℓ .) We can find $r_0 < 1$ so that

$$\alpha \in W_\theta, \text{trace}(\alpha) \geq r_0 \Rightarrow \text{dist}(\alpha, W_{\theta,e}) < \delta_0/4.$$

(If not, a compactness argument produces extra points in $W_{\theta,e}$.) We can make a similar claim for $W_{\zeta,e}$ and we choose r_0 to work for both. Of course

$$\alpha, \beta \in M_\ell^+, \text{dist}(\alpha, W_{\theta,e}) < \frac{\delta_0}{4}, \text{dist}(\beta, W_{\zeta,e}) < \frac{\delta_0}{4} \Rightarrow \|\alpha - \beta\|_2 > \delta_0/2.$$

We can further find $r_1 < 1$ so that $r_1 < t \leq 1$ implies

$$\min(\|\alpha - t^2\beta\|_2, \|t^2\alpha - \beta\|_2) > \delta_1 = \delta_0/4$$

for all such α and β . Choose $\varepsilon_1 > 0$ with

$$1 + \varepsilon_1 < \min\left(\frac{1}{r_0}, \frac{1}{r_1}, 2\right) \text{ and } (1 + \varepsilon_1)(1 + \varepsilon_1 - \delta_1^2/8) < 1.$$

We take

$$\begin{aligned} U_\theta &= \{\alpha \in M_\ell^+ : \text{trace}(\alpha) < r_0\} \\ &\cup \{\alpha \in M_\ell^+ : \text{trace}(\alpha) < 1 + \varepsilon_1 \text{ and } \text{dist}(\alpha, W_{\theta,e}) < \frac{\delta_0}{4}\} \\ U_\zeta &= \{\beta \in M_\ell^+ : \text{trace}(\beta) < r_0\} \\ &\cup \{\beta \in M_\ell^+ : \text{trace}(\beta) < 1 + \varepsilon_1 \text{ and } \text{dist}(\beta, W_{\zeta,e}) < \frac{\delta_0}{4}\} \end{aligned}$$

and we claim these open sets have the desired properties.

By the choice of r_0 , we have $W_\theta \subset U_\theta$ and $W_\zeta \subset U_\zeta$.

Consider now vectors θ_i, ζ_i in any Hilbert space H such that

$$\alpha = (\langle \theta_i, \theta_j \rangle)_{i,j=1}^\ell \in U_\theta \text{ and } \beta = (\langle \zeta_i, \zeta_j \rangle)_{i,j=1}^\ell \in U_\zeta.$$

By the symmetry of the situation so far, it is enough to verify the claim in the case $\text{trace}(\alpha) = \sum_i \|\theta_i\|^2 \leq \text{trace}(\beta) = \sum_i \|\zeta_i\|^2$. If $\text{trace}(\alpha) \leq r_0$ we can use $\text{trace}(\beta) < 1 + \varepsilon_1$ to get $\sum_{i=1}^\ell \Re\langle \theta_i, \zeta_i \rangle < \sqrt{r_0(1 + \varepsilon_1)} < 1$.

Let

$$t = \frac{\sum_{i=1}^\ell \Re\langle \theta_i, \zeta_i \rangle}{\sum_i \|\zeta_i\|^2}.$$

From $\text{trace}(\alpha) \leq \text{trace}(\beta)$ we must have $t \leq 1$. Note that if $t \leq r_1$ we have $\sum_{i=1}^\ell \Re\langle \theta_i, \zeta_i \rangle \leq r_1 \sum_i \|\zeta_i\|^2 \leq r_1(1 + \varepsilon_1) < 1$.

Finally for $t > r_1$, $\text{trace}(\alpha) > r_0$ (and hence $\text{trace}(\beta) > r_0$) we must have $\text{dist}(\alpha, W_{\theta,e}) < \delta_0/4$ and $\text{dist}(\beta, W_{\theta,e}) < \delta_0/4$ and hence

$$\begin{aligned} \delta_1^2 &\leq \|(\langle \theta_i, \theta_j \rangle)_{ij} - t^2(\langle \zeta_i, \zeta_j \rangle)_{ij}\|_2^2 \\ &= \sum_{ij} |\langle \theta_i, \theta_j \rangle - t^2 \langle \zeta_i, \zeta_j \rangle|^2 \\ &= \sum_{ij} |\langle \theta_i - t\zeta_i, \theta_j \rangle + \langle t\zeta_i, \theta_j - t\zeta_j \rangle|^2 \\ &\leq 2 \left(\sum_{ij} |\langle \theta_i - t\zeta_i, \theta_j \rangle|^2 + |\langle t\zeta_i, \theta_j - t\zeta_j \rangle|^2 \right) \\ &\leq 2 \left(\sum_i \|\theta_i\|^2 + t^2 \|\zeta_i\|^2 \right) \sum_j \|\theta_j - t\zeta_j\|^2 \\ &\leq 4(1 + \varepsilon_1) \left(\sum_j \|\theta_j\|^2 - t^2 \sum_j \|\zeta_j\|^2 \right) \end{aligned}$$

(using our choice of t). Hence

$$\begin{aligned} \left(\Re \sum_{i=1}^{\ell} \langle \theta_i, \zeta_i \rangle \right)^2 &< \left(1 + \varepsilon_1 - \frac{\delta_1^2}{8} \right) \sum_i \|\zeta_i\|^2 \\ &\leq \left(1 + \varepsilon_1 - \frac{\delta_1^2}{8} \right) (1 + \varepsilon_1) \\ &= 1 - \varepsilon_2 < 1 \end{aligned}$$

in this case. In all cases, we have

$$\Re \sum_{i=1}^{\ell} \langle \theta_i, \zeta_i \rangle \leq \max \left(\sqrt{1 - \varepsilon_2}, r_1(1 + \varepsilon_1), \sqrt{r_0(1 + \varepsilon_1)} \right) = 1 - \varepsilon,$$

as claimed. □

THEOREM 3.3. *Let $A = \mathcal{B}(H)$ and let $T \in \mathcal{E}\ell(\mathcal{B}(H))$ be given by (1). Then we have equality in (3) if and only if the intersection of the convex hulls of $W_{m,e}(a_1^*, a_2^*, \dots, a_\ell^*)$ and $W_{m,e}(b_1, b_2, \dots, b_\ell)$ is nonempty.*

Moreover $\|T\|_{cb} = \|T\|_k$ with $k = \min(\ell, \dim(H))$.

Proof. It follows from Propositions 2.4 and 3.1 that for $k = \min(\ell, \dim(H))$, $\|T\|_k = \|T\|_{cb}$ = the right hand side of (3) if the convex hulls intersect.

We know we can represent T in such a way as to get the minimum possible on the right hand side of (3). Fix $k = \min(\ell, \dim(H))$. We claim that in that

case $W_{m,e}((\mathbf{a}^{(k)})^*) \cap W_{m,e}(\mathbf{b}^{(k)}) \neq \emptyset$. Assume we have normalised T so that

$$\left\| \sum_i a_i a_i^* \right\| = \left\| \sum_i b_i^* b_i \right\| = 1.$$

As the sets $W_{m,e}((\mathbf{a}^{(k)})^*)$ and $W_{m,e}(\mathbf{b}^{(k)})$ are convex and closed by Proposition 2.4, if they do not intersect they can be separated by an \mathbb{R} -linear functional ρ on the hermitian matrices. That is,

$$\sup\{\rho(\alpha) : \alpha \in W_{m,e}((\mathbf{a}^{(k)})^*)\} < \inf\{\rho(\beta) : \beta \in W_{m,e}(\mathbf{b}^{(k)})\}.$$

As the trace is constant on these sets, we can subtract a multiple of the trace from ρ and assume there is $\delta > 0$ with

$$\sup\{\rho(\alpha) : \alpha \in W_{m,e}(\mathbf{a}^*)\} \leq -\delta < \delta \leq \inf\{\rho(\beta) : \beta \in W_{m,e}(\mathbf{b})\}.$$

Such an \mathbb{R} -linear functional can be written as

$$\rho(\alpha) = \sum_{i,j=1}^{\ell} \gamma_{ji} \alpha_{ij} = \text{trace}(\gamma\alpha)$$

with $\gamma^* = \gamma$. Arguing as in the proof of Lemma 3.2 we can find $r < 1$ so that

$$\alpha \in W_m(\mathbf{a}^*), \text{trace}(\alpha) \geq r \Rightarrow \rho(\alpha) < -\frac{\delta}{2}$$

and

$$\beta \in W_m(\mathbf{b}), \text{trace}(\beta) \geq r \Rightarrow \rho(\beta) > \frac{\delta}{2}.$$

Now consider a new representation of T as $Tx = \sum_i a'_i x b'_i$ where

$$\mathbf{a}' = \mathbf{a}e^{t\gamma}, \quad \mathbf{b}' = e^{-t\gamma}\mathbf{b}$$

and $t > 0$ is very small. From (4), elements of $W_m(\mathbf{b}')$ have the form

$$\beta' = e^{-t\gamma}\beta e^{-t\gamma}$$

with $\beta \in W_m(\mathbf{b})$. For $\text{trace}(\beta) \leq r$ we can assume t is small enough that $\text{trace}(\beta') \leq (1+r)/2 < 1$. For $\text{trace}(\beta) \geq r$ we have

$$\left. \frac{d}{dt} \right|_{t=0} \text{trace}(e^{-t\gamma}\beta e^{-t\gamma}) = -\text{trace}(\gamma\beta + \beta\gamma) = -2\text{trace}(\gamma\beta) = -2\rho(\beta) < -\delta.$$

Thus, by uniform continuity of the derivative as a function of t at such $\beta \in W_m(\mathbf{b})$, for t small enough $\text{trace}(\beta') < 1 - (\delta/2)t$. Similarly for small t , $\text{trace}(\alpha') < 1 - (\delta/2)t$ if $\text{trace}(\alpha) \geq r$ while $\text{trace}(\alpha) \leq (1+r)/2$ for $\text{trace}(\alpha) \leq r$. Thus, when $t > 0$ is small we have

$$\|(\mathbf{a}')^*\| < \|\mathbf{a}^*\| \text{ and } \|\mathbf{b}'\| < \|\mathbf{b}\|,$$

contradicting the choice of \mathbf{a} and \mathbf{b} to minimise the right hand side of (3). \square

REMARK 3.4. For $T \in \mathcal{E}\ell(\mathcal{B}(H))$ the above gives a more constructive proof that $\|T\|_{cb}$ is the infimum of the estimates (3) or (2) than those in [20, Theorem 4.3], [7, Corollary 2] and (for the finite dimensional case) [10, p. 418]. The result is due to Haagerup [14] and his proof is published in [2, §5.4].

EXAMPLE 3.5. Consider the map $T: M_n \rightarrow M_n$ where Tx has its first column the same as the transpose x^t/\sqrt{n} but zeros in all other columns. Then

$$Tx = \sum_{i=1}^n e_{i1}x(e_{i1}/\sqrt{n})$$

where e_{ij} is as before (Remark 2.3). So in this case $a_i = \sqrt{n}b_i = e_{i1}$, $a_j a_i^* = e_{ji}$, $b_j b_i^* = \delta_{ij}e_{11}/n$ (where δ_{ij} is the Kronecker symbol). Thus the estimate (2) says $\|T\|_{cb} \leq 1$.

Taking the element of $M_n(M_n)$ with e_{1i} in the $(i, 1)$ block and zeros elsewhere, shows that $\|T\|_n = 1$. One can check that $W_m(\mathbf{a}^*)$ consists of rank one projections while $W_{m,e}(\mathbf{b})$ is exactly $\{I_n/n\}$ ($I_n =$ the $n \times n$ identity matrix). It is clear then that for $k < n$, $W_{m,e}((\mathbf{a}^{(k)})^*)$ contains only matrices of rank at most k and does not intersect $W_{m,e}(\mathbf{b}^{(k)})$. Hence $\|T\|_k < \|T\|_{cb} = \|T\|_n$ for $k < n$.

This example shows that the value $k = \ell$ in the theorem cannot be reduced (that is, with large $\dim(H)$).

EXAMPLE 3.6. We can relate our results to those of Stampfli [22] for the ‘generalised derivations’ $Tx = ax - xb$. To have a balance between the left and right, we prefer to have it expressed as

$$Tx = (a/\sqrt{\|a\|})x\sqrt{\|a\|} + \sqrt{\|b\|}x(-b/\sqrt{\|b\|}) = a_1xb_1 + a_2xb_2.$$

Then the estimate (3) becomes $\|T\|_{cb} \leq \|a\| + \|b\|$. In this case the matrices in $W_{m,e}(\mathbf{a}^*)$ and $W_{m,e}(\mathbf{b})$ have diagonals $(\|a\|, \|b\|)$ and Stampfli shows that the off-diagonal entries form convex sets. The criterion that $W_{m,e}(\mathbf{a}^*) \cap W_{m,e}(\mathbf{b}) \neq \emptyset$ reduces to Stampfli’s criterion [22, Theorem 7] for $\|T\| = \|a\| + \|b\|$. Stampfli shows that this equality is satisfied for some alternative representation of T as $Tx = (a - \lambda)x - x(b - \lambda)$ with $\lambda \in \mathbb{C}$.

COROLLARY 3.7. Let $A = \mathcal{B}(H)$ and let $T \in \mathcal{E}\ell(\mathcal{B}(H))$. Then there is a choice of $a_i, b_i \in \mathcal{B}(H)$ so that T is given by (1), each of $(a_i)_{i=1}^\ell$ and $(b_i)_{i=1}^\ell$ is linearly independent and for $k = \min(\ell, \dim(H))$

$$W_{m,e}((a_1^{(k)})^*, (a_2^{(k)})^*, \dots, (a_\ell^{(k)})^*) \cap W_{m,e}(b_1^{(k)}, b_2^{(k)}, \dots, b_\ell^{(k)}) \neq \emptyset.$$

Proof. We showed this in the course of the proof of the theorem. □

COROLLARY 3.8. *Let $A = \mathcal{B}(H)$ and let $T \in \mathcal{E}l(\mathcal{B}(H))$ be given by (1). Let $k = \min(\ell, \dim(H))$. Then*

$$\|T\|_{cb} = \|T\|_k = \sup\{\|T^{(k)}(u)\| : u \in \mathcal{B}(H^k), \|u\| \leq 1, \text{rank}(u) \leq \ell\}.$$

Proof. Choose a_i and b_i so that the conclusions of the previous corollary hold. Recall $T^{(k)}(x) = \sum_i a_i^{(k)} x b_i^{(k)}$. In the proof of Proposition 3.1 we found that the norm of $T^{(k)}$ is the supremum in the statement. \square

COROLLARY 3.9. *Let $A = \mathcal{B}(H)$ and let $T \in \mathcal{E}l(\mathcal{B}(H))$ be given by (1). Let $k \geq 1$. Then*

$$\|T\|_k = \sup \Re \sum_{i=1}^{\ell} \langle \zeta_i, \theta_i \rangle$$

where the supremum is taken over all choices of vectors $\theta_i, \zeta_i \in H^k$ such that

$$(\langle \theta_i, \theta_j \rangle)_{ij} \in W_m(\mathbf{a}^{(k)*}), \quad (\langle \zeta_i, \zeta_j \rangle)_{ij} \in W_m(\mathbf{b}^{(k)}).$$

Proof. This is part of the proof of Proposition 3.1, when we apply it to $T^{(k)}(X) = \sum_{i=1}^{\ell} a_i^{(k)} X b_i^{(k)}$. We had $\theta_i = (a_i^{(k)})^* \xi$, $\zeta_i = u b_i^{(k)} \eta$. \square

EXAMPLE 3.10. One may wonder whether the results can be improved if one restricts to $T \in \mathcal{E}l(\mathcal{B}(H))$ with the self-adjointness property $T^*(x) = T(x^*)^* = T(x)$, and indeed we present improved bounds on k for this case below. Here are some examples with $T = T^*$.

The example of Choi [9] gives an elementary operator T of length n^2 (on M_n , $n \geq 2$) which is $(n - 1)$ -positive but not n -positive (and is unital up to scaling: $T(x) = (n - 1)(\text{trace } x)I - x$, $T(I) = (n(n - 1) - 1)I$). Thus for $m < n$ we have $\|T\|_m = \|T(I)\| < \|T\|_n$. One may check that in this case T can be written $Tx = \sum_{j=1}^{n^2-1} b_j^* x b_j - b_{n^2}^* x b_{n^2}$.

Modifying Example 3.5 consider $T: M_{n+1} \rightarrow M_{n+1}$ where

$$Tx = \sum_{j=2}^{n+1} e_{j1} x (e_{j1} / \sqrt{n}) + \sum_{j=2}^{n+1} (e_{1j} / \sqrt{n}) x e_{1j}.$$

One may check that $\|T\|_{cb} \leq 1$ by the Haagerup estimate and $\|T\|_n \geq 1$ by taking the element of $M_n(M_{n+1})$ with $e_{1,i+1}$ in the $(i, 1)$ block and zeros elsewhere. A calculation with $W_{m,e}$ shows that $\|T\|_{n-1} < 1$. One can check that in this case we can rewrite T in the form $\sum_{j=1}^n b_j^* x b_j - \sum_{j=n+1}^{2n} b_j^* x b_j$.

LEMMA 3.11. *If $T \in \mathcal{E}l(\mathcal{B}(H))$ has $T^* = T$ then T can be written as $Tx = \sum_{j=1}^m b_j^* x b_j - \sum_{j=m+1}^{\ell} b_j^* x b_j$ (for $0 \leq m \leq \ell =$ the length of T) with $\|T\|_{cb} = \left\| \sum_{j=1}^{\ell} b_j^* b_j \right\|$.*

Proof. We begin by expressing $Tx = \sum_{j=1}^{\ell} \tilde{a}_j x \tilde{b}_j$ so as to have equality in the Haagerup estimate and linearly independent sets $\{\tilde{a}_j\}$ and $\{\tilde{b}_j\}$. In [17, 4.9] it is shown that we can use a unitary rewriting (so it leaves the Haagerup estimate unchanged) to get a representation of T with $\tilde{a}_j = \lambda_j \tilde{b}_j^*$ for some real scalars λ_j . We may assume that the terms are ordered so that the positive λ_j (if any) come first and the negative ones later. We then take $b_j = \sqrt{|\lambda_j|} \tilde{b}_j$. With $\varepsilon_j = \lambda_j/|\lambda_j|$ we then have the desired form of the representation $Tx = \sum_{j=1}^{\ell} \varepsilon_j b_j^* x b_j$ and it remains to establish that the Haagerup bound is sharp in this representation.

$$\begin{aligned} \|T\|_{cb} &\leq \left\| \sum_{j=1}^{\ell} b_j^* b_j \right\| = \sup_{\xi \in H, \|\xi\|=1} \sum_{j=1}^{\ell} |\lambda_j| \langle \tilde{b}_j \xi, \tilde{b}_j \xi \rangle \\ &\leq \sup_{\xi \in H, \|\xi\|=1} \sqrt{\sum_{i=1}^{\ell} |\lambda_i|^2 \langle \tilde{b}_i \xi, \tilde{b}_i \xi \rangle \sum_{j=1}^{\ell} \langle \tilde{b}_j \xi, \tilde{b}_j \xi \rangle} \\ &\leq \sqrt{\left\| \sum_{i=1}^{\ell} \tilde{a}_i \tilde{a}_i^* \right\| \left\| \sum_{j=1}^{\ell} \tilde{b}_j^* \tilde{b}_j \right\|} = \|T\|_{cb} \quad \square \end{aligned}$$

THEOREM 3.12. *Suppose $T \in \mathcal{E}l(\mathcal{B}(H))$ has $T^* = T$ and length ℓ . Let $k = \lceil \sqrt{1 + 2m(\ell - m)} \rceil$ where m is as in Lemma 3.11. Then $\|T\|_k = \|T\|_{cb}$.*

Proof. If we represent T as in Lemma 3.11 we have $Tx = \mathbf{a}(x \otimes I_{\ell})\mathbf{b}$ with $\mathbf{a} = [\varepsilon_1 b_1^*, \varepsilon_2 b_2^*, \dots, \varepsilon_{\ell} b_{\ell}^*]$, $\mathbf{b} = [b_1, b_2, \dots, b_{\ell}]^t$ and $\varepsilon_j = 1$ ($1 \leq j \leq m$), $\varepsilon_j = -1$ ($m < j \leq \ell$). If $m = \ell$ then T is completely positive and $\|T\| = \|T\|_{cb}$. Similarly if $m = 0$, $-T$ is completely positive.

Consider the finite dimensional case $\dim H < \infty$ first. Then we know that the extremal numerical ranges $W_{m,e}(\mathbf{a})$ and $W_{m,e}(\mathbf{b})$ correspond to the joint numerical ranges of the compressions $pa_j^* a_i p$ and $pb_j^* b_i p$ to the subspace pH where $pH = \left\{ \xi \in H : \sum_{j=1}^{\ell} b_j^* b_j \xi = \left\| \sum_{j=1}^{\ell} b_j^* b_j \right\| \xi \right\}$ is the eigenspace of the maximal eigenvalue (and p is the orthogonal projection). We can also see a simple relationship between $W_{m,e}(\mathbf{a})$ and $W_{m,e}(\mathbf{b})$ —to get from a matrix $\alpha = (\alpha_{ij})_{i,j=1}^{\ell} \in W_{m,e}(\mathbf{a})$ change α_{ij} to $-\alpha_{ij}$ in the blocks $\{(i, j) : i \leq m, j > m\} \cup \{(i, j) : i > m, j \leq m\}$. As the convex hulls of $W_{m,e}(\mathbf{a})$ and $W_{m,e}(\mathbf{b})$ intersect (by Theorem 3.3) it follows that there is an α in the intersection of the convex hulls with $(\alpha_{ij})_{i=1, j=m+1}^m = 0$.

By Remark 2.5, if $(k + 1)^2 > 1 + d$ with

$$d = \dim \operatorname{span}_{\mathbb{R}} \{ (pb_j^* b_i p + pb_i^* b_j p)/2, (pb_j^* b_i p - pb_i^* b_j p)/(2i) \}$$

(and here $1 \leq i \leq m, m < j \leq \ell$), then there is such an α which is a convex combination of at most k elements of the joint numerical ranges of the $pb_j^*b_i p$. As $d \leq 2m(\ell - m)$, the result follows.

Now consider $\dim(H) = \infty, Tx = T^*x = \sum_{j=1}^{\ell} a_j x c_j$. We can see fairly easily that $\|T\|_k = \sup_p \|T_p\|_k$ where the supremum is over all finite dimensional projections p on H and $T_p(x) = pT(pxp)p = \sum_{j=1}^{\ell} (pa_j p)x(pc_j p)$. Given unit vectors $\xi = (\xi_i)_{i=1}^k \in H^k, \eta = (\eta_i)_{i=1}^k \in H^k$ and a unitary $u \in \mathcal{B}(H^k)$ choose p so that $\langle T^{(k)}(u)\eta, \xi \rangle$ is not changed when T is replaced by T_p . This means the range of p should contain all $\xi_i, \eta_i, b_j \eta_i, c_j^* \xi_i$ and all components of $ub_j^{(k)} \eta$.

If we further assume that p is large enough to ensure that $\{pa_j p : 1 \leq j \leq \ell\}$ and $\{pc_j p : 1 \leq j \leq \ell\}$ are each linearly independent, then we can show as follows that $(m, \ell - m)$ must be the same for T_p as for T . Given any two representations of T as $Tx = \sum_{j=1}^{\ell} \varepsilon_j b_j^* x b_j = \sum_{j=1}^{\ell} \tilde{\varepsilon}_j \tilde{b}_j^* x \tilde{b}_j$ ($\varepsilon_j, \tilde{\varepsilon}_j \in \{\pm 1\}$) there must be an invertible $\ell \times \ell$ matrix β with

$$[\tilde{b}_1, \tilde{b}_2, \dots, \tilde{b}_\ell]^t = \tilde{\mathbf{b}} = \beta^{-1}[b_1, b_2, \dots, b_\ell]^t = \beta^{-1}\mathbf{b}$$

and

$$[\tilde{\varepsilon}_1 \tilde{b}_1^*, \tilde{\varepsilon}_2 \tilde{b}_2^*, \dots, \tilde{\varepsilon}_\ell \tilde{b}_\ell^*] = \tilde{\mathbf{b}}^* \text{diag}(\tilde{\varepsilon}_1, \tilde{\varepsilon}_2, \dots, \tilde{\varepsilon}_\ell) = \mathbf{b}^* \text{diag}(\varepsilon_1, \varepsilon_2, \dots, \varepsilon_\ell) \beta.$$

It follows that

$$\text{diag}(\tilde{\varepsilon}_1, \tilde{\varepsilon}_2, \dots, \tilde{\varepsilon}_\ell) = \beta^* \text{diag}(\varepsilon_1, \varepsilon_2, \dots, \varepsilon_\ell) \beta$$

and so the number of j with $\varepsilon_j = 1$ must be the same as the number where $\tilde{\varepsilon}_j = 1$.

From the finite dimensional case (T_p is essentially an operator on $\mathcal{B}(pH)$) we get

$$\|T\|_{cb} = \|T\|_\ell = \sup_p \|T_p\|_\ell = \sup_p \|T_p\|_k = \|T\|_k. \quad \square$$

REMARK 3.13. The examples 3.10 suggest that the optimal k for Theorem 3.12 must be at least proportional to $\sqrt{m(\ell - m)}$, or about $\ell/2$ in the worst case. But the Theorem requires k to be about $\sqrt{2}$ times what the examples indicate.

One may check that for $\ell = 3, m = 1$ it is necessary to have $k = 2$ in some cases. For example $T \in \mathcal{E}\ell(M_2), Tx = b_1^* x b_1 - (b_2^* x b_2 + b_3^* x b_3)$ where

$$b_1 = \begin{pmatrix} 1/\sqrt{2} & 0 \\ 0 & 1 \end{pmatrix}, b_2 = \begin{pmatrix} 1/\sqrt{2} & 0 \\ 0 & -1 \end{pmatrix}, b_3 = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}.$$

In this case $\sum_{j=1}^3 b_j^* b_j = 2I$ and the joint numerical range of $(b_1^* b_2, b_1^* b_3)$ consists of $\{(|\xi_1|^2/2 - |\xi_2|^2, \xi_1 \xi_2) : |\xi_1|^2 + |\xi_2|^2 = 1\}$. This does not contain $(0, 0)$ but its convex hull does. Hence $\|T\|_{cb} = 2$ by Theorem 3.3, but $W_m(b_1, -b_2, -b_3) \cap W_m(b_1, b_2, b_3) = \emptyset$ and so $\|T\| < 2$ by Proposition 3.1.

In a recent preprint [16] it is shown that for $T \in \mathcal{E}\ell(\mathcal{B}(H))$ of the form $Tx = a^*xb + b^*xa$, $\|T\| = \|T\|_{cb}$ (which also follows from Theorem 3.12 for $\ell = 2, m = 1$).

4. Elementary operators on C^* -algebras

To transfer our methods from the case $A = \mathcal{B}(H)$ to general C^* -algebras A we can rely on the irreducible representations $\pi : A \rightarrow \mathcal{B}(H_\pi)$ of A . As is customary we take \hat{A} to denote the unitary equivalence classes of irreducible representations of A , $P(A)$ to be the pure states of A , $S(A)$ all the states. We denote the unitary equivalence class of an irreducible representation π by $[\pi]$. For $\phi \in P(A)$, there is an associated (irreducible) cyclic representation π_ϕ . We call the equivalence class $[\pi_\phi]$ the ‘support’ of ϕ in \hat{A} . We let $F_k(A)$ ($k = 1, 2, \dots$) denote the k -factorial states of A , which are finite convex combinations $\phi = \sum_{j=1}^k t_j \phi_j$ of $\phi_j \in P(A)$, all with the same support.

It is well known and easy to verify that for $T \in \mathcal{E}\ell(A)$ given as in (1), we have $\|T\| = \sup_{\pi \in \hat{A}} \|T^\pi\|$ where $T^\pi : \mathcal{B}(H_\pi) \rightarrow \mathcal{B}(H_\pi)$ is given by

$$T^\pi(x) = \sum_{i=1}^{\ell} \pi(a_i)x\pi(b_i).$$

(There is a technicality involved here when $a_i, b_i \in M(A)$ and then we must know that π can be extended to a representation of $M(A)$.) It is also well known that $\|T\|_k = \sup_{\pi} \|T^\pi\|_k$ and $\|T\|_{cb} = \sup_{\pi} \|T^\pi\|_{cb}$.

From this and Corollary 3.8 we can deduce immediately that $\|T\|_\ell = \|T\|_{cb}$ for $T \in \mathcal{E}\ell(A)$ of length ℓ . Using Remark 2.5 we can also assert that if each of the sets $\{a_j^*a_i : 1 \leq i, j \leq \ell\}$ and $\{b_j^*b_i : 1 \leq i, j \leq \ell\}$ is commutative, then $\|T\| = \|T\|_{cb}$. (For this one must observe that the commutativity assumption is preserved when passing to $\pi(a_i), \pi(b_j)$ and still preserved when passing to a representation of T^π minimising the Haagerup estimate.)

For an ℓ -tuple $\mathbf{c} = (c_1, c_2, \dots, c_\ell)$ of elements $c_i \in M(A)$ and $\pi \in \hat{A}$ we define

$$W_m^\pi(\mathbf{c}) = W_m(\pi(\mathbf{c})), \quad W_{m,e}^\pi(\mathbf{c}) = W_{m,e}(\pi(\mathbf{c}))$$

(where by $\pi(\mathbf{c})$ we mean $(\pi(c_1), \pi(c_2), \dots, \pi(c_\ell))$). From Proposition 2.4, we know that $W_m^\pi(\mathbf{c}^{(k)})$ (strictly we should use $\pi^{(k)}$ here) is the set of convex combinations of k elements of $W_m^\pi(\mathbf{c})$, and it is convex for $k \geq \ell$. Similarly for $W_{m,e}^\pi(\mathbf{c}^{(k)})$ and $k \geq \ell$.

We also define

$$V_m^\pi(\mathbf{c}) = \{t\alpha : \alpha \in W_m^\pi(\mathbf{c}), 0 \leq t \leq 1\}.$$

LEMMA 4.1. *For an ℓ -tuple \mathbf{c} of elements of $M(A)$ and $\pi \in \hat{A}$*

$$W_m^\pi(\mathbf{c}) = \{(\phi(c_j^*c_i))_{i,j=1}^\ell : \phi \in P(A), [\pi_\phi] = [\pi]\}.$$

The convex combinations of k elements of $W_m^\pi(\mathbf{c})$ are representable as the set of all $(\phi(c_j^*c_i))_{i,j=1}^\ell \in M_\ell$ where $\phi \in F_k(A)$ and ϕ is a convex combination of pure states supported at $[\pi]$.

The convex combinations of k elements of $V_m^\pi(\mathbf{c})$ form

$$V_m^\pi(\mathbf{c}^{(k)}) = \{t(\phi(c_j^*c_i))_{i,j=1}^\ell : 0 \leq t \leq 1, \phi \in F_k(A) \text{ supported by } [\pi]\}.$$

Proof. Observe that those $\phi \in P(A)$ with $[\pi_\phi] = [\pi]$ take the form $\phi(x) = \langle \pi(x)\xi, \xi \rangle$ with $\xi \in H_\pi$ a unit vector. The result follows. \square

On \hat{A} we can take the usual topology obtained via the hull-kernel topology on the primitive ideal space $\text{Prim}(A)$ (see [19, 4.1.2] for example). In the case we deal with continuous trace algebras there is a bijection between \hat{A} and $\text{Prim}(A)$ since elements of \hat{A} are characterised by their kernels (see [19, 6.1.5]).

LEMMA 4.2. *If A is a continuous trace C^* -algebra, and \mathbf{c} is an ℓ -tuple of elements of A , then the map*

$$[\pi] \mapsto V_m^\pi(\mathbf{c}^{(k)})$$

is an upper semicontinuous set-valued map on \hat{A} with values in the compact subsets of M_ℓ^+ .

Proof. When A has continuous trace and $\pi: A \rightarrow \mathcal{B}(H_\pi)$ is an irreducible representation, then $\pi(A) = \mathcal{K}(H_\pi) =$ the compact operators [19, 6.1.11, 6.1.6]. The pure states of A supported at $[\pi] \in \hat{A}$ are then vector states $\phi(x) = \langle \pi(x)\xi, \xi \rangle$ (with $\xi \in H_\pi$ a unit vector). As the closed unit ball of H_π is weakly compact, any net of unit vectors has a subnet $(\xi_\gamma)_\gamma$ that converges weakly to a vector $\theta \in H_\pi$ of norm at most 1. It follows that $\langle \pi(x)\xi_\gamma, \xi_\gamma \rangle$ also converges to $\langle \pi(x)\theta, \theta \rangle$ when $\pi(x)$ has finite rank. The same conclusion for all $\pi(x) \in \mathcal{K}(H_\pi)$ follows by norm density of the finite ranks in $\mathcal{K}(H_\pi)$. This allows us to show that $V_m^\pi(\mathbf{c})$ is compact. It follows that $V_m^\pi(\mathbf{c}^{(k)})$ is compact by considering it as made up of convex combinations of k matrices in V_m^π .

By upper semicontinuity we mean that for any open subset U of M_ℓ the set of $\pi \in \hat{A}$ where $V_m^\pi(\mathbf{c}^{(k)}) \subset U$ is an open subset of \hat{A} . Fix $\pi = \pi_0$ with the corresponding $V_m^{\pi_0}(\mathbf{c}^{(k)}) \subset U$. If $[\pi_0]$ fails to be an interior point of such $[\pi] \in \hat{A}$, we can find a net $(\phi_\gamma)_\gamma$ of elements of $F_k(A)$, a net $(t_\gamma)_\gamma$ in the unit interval $[0, 1]$ so that the supports of ϕ_γ in \hat{A} converge to $[\pi_0]$ but the matrices $(t_\gamma\phi_\gamma(c_j^*c_i))_{i,j=1}^\ell$ all lie outside U .

When A has continuous trace, \hat{A} is Hausdorff (see [19, 6.1.11]). The weak*-closure of $P(A)$ is contained in the multiples of $P(A)$ by numbers $t \in [0, 1]$ [13, Theorem 6], and this set of multiples of pure states is weak*-compact. If a net of pure states $(\psi_\gamma)_\gamma$ converges weak* to a nonzero multiple $t\psi$ of a pure state ψ ($0 < t \leq 1$), then the supports of ψ_γ converge to the support of ψ in

\hat{A} (see [19, 4.3.3] for an argument). Using these facts it is easy to see that we can extract a subnet from $(\phi_\gamma)_\gamma$ which converges weak* to a multiple of some $\phi \in F_k(A)$ supported at $[\pi_0]$. (A similar argument is given in [3, Lemma 4.2].) Passing to a further subnet ensures t_γ converges, and then the limit of the above matrices is an element of $V_m^{\pi_0}(\mathbf{c}^{(k)})$ outside U —a contradiction. \square

THEOREM 4.3. *If $k \geq 1$ and A is a continuous trace C^* -algebra which is not k -subhomogeneous, then there exists an elementary operator $T \in \mathcal{E}\ell(A)$,*

$$T(x) = \sum_{i=1}^{k+1} a_i x b_i \quad (a_i, b_i \in A \text{ for } 1 \leq i \leq k+1)$$

with $\|T\|_k < \|T\|_{cb}$.

Proof. If A is not k -subhomogeneous, then there exists an irreducible representation π of A on a Hilbert space H_π of dimension at least $k+1$. The basic idea of the proof is to construct T so that T^π looks like Example 3.5.

Fix $k+1$ orthonormal vectors $\xi_1, \xi_2, \dots, \xi_{k+1}$ in H_π . We use the notation $\xi^* \otimes \eta$ for the operator $\langle \cdot, \xi \rangle \eta$ in $\mathcal{B}(H_\pi)$ (when $\xi, \eta \in H_\pi$). Let e_{ij} denote the operator $\xi_j^* \otimes \xi_i$. Our aim is to construct T so that $T^\pi(x) = \sum_{i=1}^{k+1} e_{i1} x (e_{i1} / \sqrt{k+1})$ and $\|T\|_k < 1 = \|T^\pi\|_{k+1} \leq \|T\|_{cb}$.

Since $\pi(A) = \mathcal{K}(H_\pi)$ we can find $a'_i \in A$ with $\pi(a'_i) = e_{i1}$. Let $b'_i = a'_i / \sqrt{k+1}$. Apply Lemma 3.2 to $W_\theta = V_m^\pi(((\mathbf{a}')^*)^{(k)})$ and $W_\zeta = V_m^\pi((\mathbf{b}')^{(k)})$. We then find open neighbourhoods U_θ and U_ζ of these sets, to which we can apply the upper semicontinuity Lemma 4.2 to produce an open neighbourhood \mathcal{N} of $[\pi]$ in \hat{A} so that for $s \in \mathcal{N}$ and π_s a representative of s we have

$$V_m^{\pi_s}(((\mathbf{a}')^*)^{(k)}) \subset U_\theta, \quad V_m^{\pi_s}((\mathbf{b}')^{(k)}) \subset U_\zeta.$$

By Urysohn’s lemma, we can find a continuous functions $f: \hat{A} \rightarrow [0, 1]$ supported in \mathcal{N} so that $f([\pi]) = 1$. From the Dauns Hofmann theorem we can multiply a'_i and b'_i by f to get a_i and b_i in A . That is $\pi_s(a_i) = f(s)\pi_s(a'_i)$ and $\pi_s(b_i) = f(s)\pi_s(b'_i)$. Thus

$$\begin{aligned} V_m^{\pi_s}((\mathbf{a}^*)^{(k)}) &= f(s)^2 V_m^{\pi_s}(((\mathbf{a}')^*)^{(k)}) \subseteq V_m^{\pi_s}(((\mathbf{a}')^*)^{(k)}) \subset U_\theta, \\ V_m^{\pi_s}(\mathbf{b}^{(k)}) &= f(s)^2 V_m^{\pi_s}((\mathbf{b}')^{(k)}) \subseteq V_m^{\pi_s}((\mathbf{b}')^{(k)}) \subset U_\zeta \end{aligned}$$

for $s \in \mathcal{N}$. For other $s \in \hat{A}$ we have

$$V_m^{\pi_s}((\mathbf{a}^*)^{(k)}) = V_m^{\pi_s}(\mathbf{b}^{(k)}) = 0.$$

Taking T as in the statement, for all s we have $\|T^{\pi_s}\|_k < 1 - \varepsilon$ by the method of proof for Proposition 3.1. On the other hand $\|T\|_{cb} \geq \|T^\pi\|_{k+1} = 1$. \square

THEOREM 4.4. *Suppose a C^* -algebra A has the property (for some $k \geq 1$) that $\|T\|_{cb} = \|T\|_k$ for each $T \in \mathcal{E}\ell(A)$ as in (1) with $a_i, b_i \in A$. Then A is*

either k -subhomogeneous or a k -subhomogeneous extension of an antiliminal C^* -algebra.

Proof. As shown in [4], the assumption on A implies that the same is true of any ideal of A , including the maximal postliminal ideal J of A . J has an essential continuous trace ideal J_c [19, 2.2.11] and by Theorem 4.3, J_c must be k -subhomogeneous. The set ${}_k\hat{J}$ of those $s \in \hat{J}$ where the corresponding representation acts on a Hilbert space of dimension $\leq k$ is closed in \hat{J} [19, 4.4.10, 6.1.5]. It is also dense because it contains \hat{J}_c . Hence J is k -subhomogeneous. \square

COROLLARY 4.5. *Let A be a C^* -algebra. Then the following are equivalent properties for A :*

- (i) $\|T\|_{cb} = \|T\|_k$ for each $T \in \mathcal{E}\ell(A)$;
- (ii) $\|T\|_{cb} = \|T\|_k$ for each $T \in \mathcal{E}\ell(A)$ as in (1) with $a_i, b_i \in A$;
- (iii) A is either k -subhomogeneous or an antiliminal extension of a k -subhomogeneous C^* -algebra.

Proof. (i) clearly implies (ii) and we have proved that (ii) implies (iii) in Theorem 4.4 above. If A is k -subhomogeneous, then it is easy to see that (i) holds by using representations and [18, Proposition 7.9]. See [4] for the remaining details of a proof that (iii) implies (i). \square

In [4], this result is proved for $k = 1$. See [3] for an early reference to this class of C^* -algebras and see [24] for a further list of equivalent conditions including some dealing with k -positivity implying complete positivity of elementary operators.

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