

Uncomputably Noisy Ergodic Limits

Jeremy Avigad

Abstract V'yugin has shown that there are a computable shift-invariant measure on $2^{\mathbb{N}}$ and a simple function f such that there is no computable bound on the rate of convergence of the ergodic averages $A_n f$. Here it is shown that in fact one can construct an example with the property that there is no computable bound on the complexity of the limit; that is, there is no computable bound on how complex a simple function needs to be to approximate the limit to within a given ε .

Let $2^{\mathbb{N}}$ denote Cantor space, the space of functions from \mathbb{N} to the discrete space $\{0, 1\}$ under the product topology. Viewing elements of this space as infinite sequences, for any finite sequence σ of 0's and 1's let $[\sigma]$ denote the set of elements of $2^{\mathbb{N}}$ that extend σ . The collection \mathcal{B} of Borel sets in the standard topology are generated by the set of such $[\sigma]$. For each k , let \mathcal{B}_k denote the finite σ -algebra generated by the partition $\{[\sigma] \mid \text{length}(\sigma) = k\}$. If a function f from $2^{\mathbb{N}}$ to \mathbb{Q} is measurable with respect to \mathcal{B}_k , I will call it a *simple function with complexity at most k* .

Let μ be any probability measure on $(2^{\mathbb{N}}, \mathcal{B})$, and let f be any element of $L^1(\mu)$. Say that a function k from \mathbb{Q}^+ to \mathbb{N} is a *bound on the complexity of f* if, for every $\varepsilon > 0$, there is a simple function g of complexity at most $k(\varepsilon)$ such that $\|f - g\| < \varepsilon$. If (f_n) is any convergent sequence of elements of $L^1(\mu)$ with limit f , say that $r(\varepsilon)$ is a *bound on the rate of convergence of (f_n)* if, for every $n \geq r(\varepsilon)$, $\|f_n - f\| < \varepsilon$. (One can also consider rates of convergence in any of the L^p -norms for $1 < p < \infty$, or in measure. Since all the sequences considered below are uniformly bounded, this does not affect the results.)

Now suppose that μ is a computable measure on $2^{\mathbb{N}}$ in the sense of computable measure theory (see Hoyrup [1], Weihrauch [4]). Then if f is any computable element of $L^1(\mu)$, there is a computable sequence (f_n) of simple functions that approaches f with a computable rate of convergence $r(\varepsilon)$; this is essentially what it *means* to be a computable element of $L^1(\mu)$. In particular, setting $k(\varepsilon)$ equal to the

Received May 3, 2011; accepted October 17, 2011

2010 Mathematics Subject Classification: Primary 03F60; Secondary 37A25

Keywords: ergodic theorems, computable analysis

© 2012 by University of Notre Dame 10.1215/00294527-1716757

complexity of $f_{r(\epsilon)}$ provides a computable bound on the complexity of f . But the converse need not hold: if r is any noncomputable real number and f is the constant function with value r , then f is not computable, even though there is a trivial bound on its complexity.

It is not hard to compute a sequence of simple functions (f_n) that converges to a function f even in the L^∞ -norm, with the property that there is no computable bound on the complexity of the limit, with respect to the standard coin-flipping measure on $2^\mathbb{N}$. Notice that this is stronger than saying that there is no computable bound on the rate of convergence of (f_n) to f ; it says that there is no way of computing bounds on the complexity of *any* sequence of good approximations to f .

To describe such a sequence, for each k , let h_k be the \mathcal{B}_k -measurable Rademacher function defined by

$$h_k = \sum_{\{\sigma \mid \text{length}(\sigma)=k\}} (-1)^{\sigma_{k-1}} 1_{[\sigma]},$$

where σ_{k-1} denotes the last bit of σ and $1_{[\sigma]}$ denotes the characteristic function of the cylinder set $[\sigma]$. Intuitively, h_k is a “noisy” function of complexity k . Finally, let $f_n = \sum_{i \leq n} 4^{-\varphi(i)} h_i$, where φ is an injective enumeration of any computably enumerable set, like the halting problem, that is not computable. Given any m , if n is large enough so that $\varphi(j) > m$ whenever $j > n$, then for every $i > n$ and every x we have $|f_i(x) - f_n(x)| \leq \sum_{j \geq m} 4^{-j} < 1/(3 \cdot 4^m)$. Thus the sequence (f_n) converges in the L^∞ -norm. At the same time, it is not hard to verify that if f is the L^1 -limit of this sequence and g is a simple function of complexity at most n such that $\mu(\{x \mid |g(x) - f(x)| > 4^{-(m+1)}\}) < 1/2$, then m is in the range of φ if and only if $\varphi(j) = n$ for some $j < n$. Thus one can compute the range of φ from any bound on the complexity of f .

The sequence (f_n) just constructed is contrived, and one can ask whether similar sequences arise “in nature.” Letting $A_n f$ denote the ergodic average $\frac{1}{n} \sum_{i < n} f \circ T_n$, the mean ergodic theorem implies that for every measure μ on $2^\mathbb{N}$ and f in $L^1(\mu)$, the sequence $(A_n f)$ converges in the L^1 -norm. However, V’yugin [2], [3] has shown that there is a computable shift-invariant measure μ on Cantor space such that there is no computable bound on the rate of convergence of $(A_n 1_{[1]})$. In V’yugin’s construction, the limit does not have the property described in the last paragraph; in fact, it is very easy to bound the complexity of the limit in question, which places a noncomputable mass on the string of 0’s and the string of 1’s, and is otherwise homogeneous. The next theorem shows, however, that there are computable measures μ such that the limit does have this stronger property.

Theorem *There is a computable shift-invariant measure μ on $2^\mathbb{N}$ such that if $f = \lim_n A_n 1_{[1]}$, the halting problem can be computed from any bound on the complexity of f .*

Proof If σ is any finite binary sequence, let σ^* denote the element $\sigma\sigma\sigma\dots$ of Cantor space. For each e , define a measure μ_e as follows. If Turing machine e halts in s steps, let μ_e put mass uniformly on these $8s$ elements:

- all $4s$ shifts of $(1^s 0^{3s})^*$,
- all $4s$ shifts of $(1^{3s} 0^s)^*$.

Otherwise, let μ_e divide mass uniformly between 0^* and 1^* . Each measure μ_e is shift invariant, by construction. I will show, first, that μ_e is computable uniformly

in e , which is to say, there is a single algorithm that, given e , σ , and $\varepsilon > 0$, computes $\mu_e([\sigma])$ to within ε . I will then show that information as to the complexity needed to approximate f in $(2^\omega, \mathcal{B}, \mu_e)$ allows one to determine whether or not Turing machine e halts. The desired conclusion is then obtained by defining $\mu = \sum_e 2^{-(e+1)} \mu_e$.

If Turing machine e does not halt, $\mu_e([\sigma]) = 1/2$ if σ is a string of 0's or a string of 1's, and $\mu_e([\sigma]) = 0$ otherwise. Suppose, on the other hand, that Turing machine e halts in s steps, and suppose that $k < s$. Then there are $2(k - 1)$ additional strings σ with length k such that $\mu_e([\sigma]) > 0$, each consisting of a string of 1's followed by a string of 0's or vice versa. For each of these σ , $\mu_e([\sigma]) = 1/4s$, and if σ is a string of 0's or a string of 1's of length k , $\mu_e([\sigma]) = 1/2 - (k - 1)/4s$. Thus when s is large compared to k , the nonhalting case provides a good approximation to $\mu_e([\sigma])$ when $\text{length}(\sigma) \leq k$, even though e eventually halts. Thus, to compute $\mu_e([\sigma])$ to within ε , it suffices to simulate the e th Turing machine $O(k/\varepsilon)$ steps. If it halts before then, that determines μ_e exactly; otherwise, the nonhalting approximation is close enough.

Now consider $f = \lim_n A_n 1_{[1]}$ in $(2^\omega, \mathcal{B}, \mu_e)$. Note that $(A_n 1_{[1]})(\omega)$ counts the density of 1's among the first n bits of ω . If Turing machine e does not halt, $f(\omega) = 1$ if ω is the sequence of 1's, and $f(\omega) = 0$ if ω is the sequence of 0's. Up to a.e. equivalence, these are all that matters, since the mass concentrates on these two elements of Cantor space. If Turing machine e halts in s steps, then $f(\omega) = 1/4$ on the shifts of $(1^s 0^{3s})^*$, and $f(\omega) = 3/4$ on the shifts of $(1^{3s} 0^s)^*$.

Suppose that g is \mathcal{B}_k -measurable. If Turing machine e halts in s steps and k is much less than s , then roughly $3/4$ of the shifts of $(1^s 0^{3s})^*$ lie in $[0^k]$ and roughly $1/4$ lie in $[1^k]$; and roughly $3/4$ of the shifts of $(1^{3s} 0^s)^*$ lie in $[1^k]$ and roughly $1/4$ lie in $[0^k]$. But $f(\omega)$ only takes on the values $1/4$ and $3/4$, and g is constant on $[0^k]$ and $[1^k]$. So if k is much less than s , $\mu_e(\{\omega \mid |f(\omega) - g(\omega)| > 1/8\}) > 1/4$. Turning this around, given the information that $\mu_e(\{\omega \mid |f(\omega) - g(\omega)| > 1/8\}) \leq 1/4$ for some g of complexity at most k enables one to determine whether or not Turing machine e halts; namely, one simulates the Turing machine for $O(k)$ steps, and if it has not halted by then, it never will.

Set $\mu = \sum_e 2^{-(e+1)} \mu_e$. Since, for any g ,

$$\mu_e(\{\omega \mid |f(\omega) - g(\omega)| > 1/8\}) \leq \mu(\{\omega \mid |f(\omega) - g(\omega)| > 1/(8 \cdot 2^{e+1})\}),$$

knowing a k_e for each e with the property that $\mu(\{\omega \mid |f(\omega) - g(\omega)| > 1/(8 \cdot 2^{e+1})\}) < 1/4$ for some g of complexity at most k_e enables one to solve the halting problem. But such a k_e can be obtained from a bound on the complexity of f . Thus μ satisfies the statement of the theorem. □

The proof above relativizes, so for any set X there is a measure μ on $2^{\mathbb{N}}$, computable from X , such that no bound on the rate of complexity of f can be computed from X . As the following corollary shows, this implies that $\lim_n A_n 1_{[1]}$ can have arbitrarily high complexity.

Corollary *For any $v : \mathbb{Q}^+ \rightarrow \mathbb{N}$ there is a measure μ on $2^{\mathbb{N}}$ such that if $f = \lim_n A_n 1_{[1]}$ and $k(\varepsilon)$ is a bound on the complexity of f , then $\limsup_{\varepsilon \rightarrow 0} k(\varepsilon)/v(\varepsilon) = \infty$.*

Proof Let μ be such that no bound on the complexity of f can be computed from v . If the conclusion failed for some k , then there would be a rational $\varepsilon' > 0$ and N such that for every $\varepsilon < \varepsilon'$, $k(\varepsilon) < N \cdot v(\varepsilon)$. But then $k'(\varepsilon) = N \cdot v(\min(\varepsilon, \varepsilon'))$ would

be a bound on the complexity of f that is computable from v , contrary to our choice of μ . \square

References

- [1] Hoyrup, M., and C. Rojas, “Computability of probability measures and Martin-Löf randomness over metric spaces,” *Information and Computation*, vol. 207 (2009), pp. 830–847. [Zbl 1167.68023](#). [MR 2519075](#). [347](#)
- [2] V’yugin, V. V., “Ergodic convergence in probability, and an ergodic theorem for individual random sequences,” *Rossiiskaya Akademiya Nauk: Teoriya Veroyatnostei i ee Primeneniya*, vol. 42 (1997), pp. 39–50. [Zbl 0917.60039](#). [MR 1453328](#). [348](#)
- [3] V’yugin, V. V., “Ergodic theorems for individual random sequences,” *Theoretical Computer Science*, vol. 207 (1998), pp. 343–361. [Zbl 0915.68092](#). [MR 1643426](#). [348](#)
- [4] Weihrauch, K., “Computability on the probability measures on the Borel sets of the unit interval,” *Theoretical Computer Science*, vol. 219 (1999), pp. 421–437. [Zbl 0916.68043](#). [MR 1694441](#). [347](#)

Acknowledgments

Work partially supported by National Science Foundation grant DMS-1068829. I am grateful to an anonymous referee for comments and suggestions.

Departments of Philosophy and Mathematical Sciences
Carnegie Mellon University
Pittsburgh, Pennsylvania 15213
USA
avigad@cmu.edu