

formly in λ . However, this approach may not succeed in controlling the asymptotic *level* of the confidence set. The problem is that the relevant asymptotic expansions may not converge uniformly over all λ , especially when λ is infinite dimensional.

An interesting strategy, proposed by Loh (1985) in a testing context, is to pick critical values so as to control the apparent level of the confidence set for θ over a confidence set for λ of level $1 - \epsilon_n$, where ϵ_n is small. When feasible, this construction ensures that the level of the confidence set for θ is at least $1 - \alpha - \epsilon_n$. One difficulty is finding a good confidence set for λ . If the latter is too large, then the induced confidence set for θ is likely to be inefficient. Perhaps the notion of controlling level of a confidence set for θ is too strong. On the other hand, controlling asymptotic coverage probability only pointwise in λ is clearly too weak.

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I found Professor Hall's unified treatment of bootstrap bounds and confidence intervals very valuable. I was particularly interested by his exploration of the relation between the accelerated bias correction bootstrap bounds and the Studentized bounds, a relationship which I also studied, but only in the parametric framework, in my discussion of Efron (1987). In my discussion I want to:

1. Argue at least heuristically that, in the nonparametric context, the second order equivalence of $\hat{\theta}_{ABC}$ and $\hat{\theta}_{STUD}$ holds quite generally for $\theta(F)$ a sufficiently smooth von Mises functional, provided that we Studentize properly. For example, it holds if the estimate $\hat{\theta} = \theta(\hat{F})$, where \hat{F} is the empirical d.f., is an M estimate corresponding to a nice ψ function; see Huber [(1981), Chapter 2] for examples.
2. Suggest that quite generally in a parametric, nonparametric or semiparametric context, $\hat{\theta}_{ABC}$ and $\hat{\theta}_{STUD}$ are second order equivalent provided again that $\hat{\theta}$ is efficient and we Studentize properly, that is, by an efficient estimate of the asymptotic standard deviation of $\hat{\theta}$.

Since, modulo regularity conditions, checking equivalence of the theoretical points $\hat{\theta}_{abc}$ and $\hat{\theta}_{Stud}$ and of the corresponding bootstrap points $\hat{\theta}_{AB}$ and $\hat{\theta}_{STUD}$ is the same thing, we restrict ourselves to the former. Suppose H and K are as in Hall the d.f.'s of $T \equiv \sqrt{n}(\hat{\theta} - \theta(F))/(\sigma(F))$ and $\tilde{T} \equiv \sqrt{n}(\hat{\theta} - \theta(F))/\hat{\sigma}$ and admit Edgeworth expansions,

$$H(x) = \Phi(x) - \phi(x) \left(K_{1n} + \frac{K_{3n}}{6}(x^2 - 1) \right) + O(n^{-1}),$$

$$K(x) = \Phi(x) - \phi(x) \left(\tilde{K}_{1n} + \frac{\tilde{K}_{3n}}{6}(x^2 - 1) \right) + O(n^{-1}),$$

where $K_{in}, \tilde{K}_{in} = O(n^{-1/2}), i = 1, 3$, are asymptotic cumulants of T, \tilde{T} ; see Bickel (1974) for a precise formulation. In this notation, Hall shows that $\hat{\theta}_{abc} = \hat{\theta}_{Stud} + O(n^{-3/2})$ provided that

$$(1) \quad m = \Phi^{-1}H(0) + O(n^{-1}) = K_{1n} - \frac{K_{3n}}{6} = \tilde{K}_{1n} - \frac{\tilde{K}_{3n}}{6} + O(n^{-1})$$

and

$$(2) \quad a = -\frac{1}{6}(K_{3n} + \tilde{K}_{3n}) + O(n^{-1}).$$

Note that without any further calculation, the corresponding quantities for $\hat{\theta}_{ABC}$, not only \hat{m} but also \hat{a} can be estimated (but not in an invariant way) directly. In particular, we can take $\hat{a} = -\frac{1}{6}(\hat{K}_{3n} + \tilde{\hat{K}}_{3n})$, where the K_{3n}, \tilde{K}_{3n} are the bootstrap cumulants of appropriately truncated versions of T and \tilde{T} . For the fully nonparametric model and special $\theta(F)$ and exponential families Hall, following Efron (1987), derives a further approximation for a , if $\hat{\theta}$ is an efficient estimate of $\theta(F)$ and $\hat{\sigma}$ is an efficient estimate of $\sigma(F)$, the asymptotic s.d. of $\sqrt{n}\hat{\theta}$.

To extend Hall's approach in the fully nonparametric model, suppose $\hat{\theta}$ admits a von Mises (stochastic) expansion

$$\hat{\theta} = \theta(F) + \int \psi(x, F) d\hat{F}(x) + \frac{1}{2} \int \gamma(x, y, F) d\hat{F}(x) d\hat{F}(y) + o_p(n^{-1}),$$

where

$$\int \Phi(x, F) d\hat{F}(x) = 0,$$

γ is symmetric and

$$\int \gamma(x, y, F) dF(y) = 0 \quad \text{for all } x.$$

Compare Withers (1983). The efficient estimate of $\sigma^2(F) = \int \psi^2(x, F) dF(x)$ is $\sigma^2(\hat{F}) = \int \psi^2(x, \hat{F}) d\hat{F}(x)$. Under additional regularity conditions we can check $\sigma^2(\hat{F}) = \sigma^2(F) + \int v(x, F) d\hat{F} + O_p(n^{-1})$, where

$$v(X, F) = 2 \int \psi(y, F) \gamma(x, y, F) dF(y) + \psi^2(x, F) - \sigma^2(F).$$

Since

$$\tilde{T} = T \left(1 - \frac{\sigma^{-2}}{2} (F)(\hat{\sigma}^2(F) - \sigma^2(F)) \right) + O_p(n^{-1})$$

if we take K_{3n}, \tilde{K}_{3n} to be the cumulants of the appropriate linear or quadratic approximations to T, \tilde{T} , we get

$$(3) \quad \tilde{K}_{3n} - K_{3n} = -3n^{-1/2} \left[\text{SKEW}(\psi) + \sigma^{-3}(F) \right. \\ \left. \times \int \int \psi(x, F)\psi(y, F)\gamma(x, y, F) dF(x) dF(y) \right] \\ + O(n^{-1})$$

and from Withers (1983),

$$(4) \quad K_{3n} = n^{-1/2} \left[\text{SKEW}(\psi) + \frac{3}{2}\sigma^{-3}(F) \right. \\ \left. \times \int \psi(x)\psi(y)\gamma(x, y) dF(x) dF(y) \right] + O(n^{-1}).$$

From (3) and (4) we get

$$(5) \quad K_{3n} + \tilde{K}_{3n} = -\text{SKEW}(\psi)$$

and hence

$$(6) \quad a = \frac{\text{SKEW}}{6}(\psi).$$

These computations and Efron [(1987), Section 6] suggest that if \mathbf{P} is any model (parametric, fully nonparametric or semiparametric), the map $F \rightarrow \theta(F)$ is sufficiently smooth, $\hat{\theta}$ is an efficient (on \mathbf{P}) estimate of $\theta(F)$ and $\hat{\sigma}$ is an efficient (on \mathbf{P}) estimate of the asymptotic variance of $n^{1/2}\hat{\theta}$, then (6) should hold. Of course, to make any such assertions precise we need to assume existence of stochastic (von Mises) and Edgeworth expansions for T and \tilde{T} . For appropriate conditions and the necessary formulae, see Pfanzagl [(1985), Chapter 10], where an extensive discussion of questions such as those treated in Section 4 may also be found.

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