## OPTIMALITY AND ALMOST OPTIMALITY OF MIXTURE STORPING RULES<sup>1</sup>

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It is shown that for a test of a composite hypothesis on the parameter  $\theta$  of an exponential family of distributions, mixture stopping rules are almost optimal with respect to certain criteria of optimality and a unique stopping rule is to be found among them which is optimal with respect to another type of optimality.

1. Introduction and summary. Let J denote an open interval of real numbers. Assume that for each  $\theta \in J$ ,  $P_{\theta}$  is a probability measure under which  $X_1, X_2, \dots$  are independent and identically distributed random variables with probability density  $h_{\theta}(x) = \exp\{\theta x - \psi(\theta)\}$  with respect to some  $\sigma$ -finite measure  $\nu$ . Let  $S_n = \sum_{k=1}^n X_k$   $(n=0,1,\dots;S_0=0)$ . For a given  $\theta_0 \in J$  and F a probability distribution on J define

(1) 
$$f(x, t) = \int_{J} \exp\{(y - \theta_0)x - t[\phi(y) - \phi(\theta_0)]\} dF(y)$$

and

(2) 
$$T = \inf \{ n | f(S_n, n) \ge \varepsilon \} \quad (\varepsilon > 1).$$

Any T of this form shall hence be referred to as a mixture stopping rule. It is shown in Robbins (1970) that

$$(3) P_{\theta_0}(T < \infty) \le \frac{1}{\varepsilon}$$

and statistical applications of such stopping rules are also discussed there. An approximation for  $E_{\theta}T$  (for  $\theta \neq \theta_0$  such that F has a derivative F' with respect to Lebesgue measure in a neighborhood of  $\theta$ , F' being positive and continuous at  $\theta$ ) is given in Pollak and Siegmund (1975): (as  $\varepsilon \to \infty$ )

(4) 
$$E_{\theta} T = \frac{1}{2I(\theta)} [2 \log \varepsilon + \log \log \varepsilon] + O(1)$$

where  $I(\theta) = (\theta - \theta_0)\psi'(\theta) - (\psi(\theta) - \psi(\theta_0))$ . (A more explicit form of O(1) can be found in Pollak and Siegmund (1975).)

The purpose of this article is to present optimality properties of mixture stopping rules.

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For statistical applications, it is desirable to choose a stopping time T such that  $E_{\theta}T$  will be as small as possible for a wide range of values of  $\theta$ . For a given  $\theta \neq \theta_0$ , by using a mixture stopping rule whose F assigns unit mass to the single point  $\theta$ , one may obtain  $E_{\theta}T = (\log \varepsilon)/I(\theta) + O(1)$ . This is smaller than (4) by a term which is  $O(\log \log \varepsilon)$ ; but it requires prior knowledge of  $\theta$  and hence is impossible to implement in general.

A natural consideration under these circumstances would be to employ a minimax approach. (4) would suggest minimizing  $\sup_{\theta \neq \theta_0} [E_{\theta}T - (\log \varepsilon)/I(\theta)]/[(\log \log \varepsilon)/2I(\theta)]$ ; or equivalently trying to minimize  $\sup_{\theta \neq \theta_0} 2I(\theta)E_{\theta}T$ . Unfortunately this is infinite:  $\lim_{\theta \to \theta_0} (\theta - \theta_0)^2 E_{\theta}T = \infty$  by Theorem 1 of Farrell (1964) and  $I(\theta) \sim (\theta - \theta_0)^2$  for  $\theta$  close to  $\theta_0$ ; also, clearly  $\lim_{\theta \to \infty} I(\theta)E_{\theta}T = \infty$ . These considerations lead to attempting to minimize  $\sup_{\alpha \leq \theta \leq b} 2I(\theta)E_{\theta}T$  under the restriction that  $P_{\theta = \theta_0}(T < \infty) \leq 1/\varepsilon$ , where  $[a, b] \subset J$  is an interval of finite length and  $\theta_0 \notin [a, b]$ .

Theorem 1 states that one cannot hope for anything substantially better than that suggested by (4), i.e.,  $\inf\sup_{a\leq\theta\leq b}2I(\theta)E_{\theta}T=2\log\varepsilon+\log\log\varepsilon+O(1)$ . Therefore the class of mixture stopping rules is asymptotically almost optimal—optimal up to a term of order O(1). Theorem 2 presents a Bayesian almost optimal property of mixture stopping rules.

With respect to a different criterion mixture stopping rules form a complete class. Since (4) is exact up to order O(1), multiplying  $\varepsilon$  by a constant will not change the right-hand side of (4). Thus if T is defined as the first crossing time of a boundary in the  $(n, S_n)$  plane, one would suspect a similar minimax result if one changes  $(P_{\theta_0}(T < \infty), E_{\theta}T)$  to the expected  $(\theta_0, \theta)$  number of times the process  $(n, S_n)$  remains (above, below) the stopping boundary respectively. Theorem 3 states that the (unique) minimax solution is a mixture stopping rule.

2. Almost optimality. Without loss of generality it may be assumed that  $0 = \psi(0) = \psi'(0)$ .

LEMMA 1. Let  $0 < a \le b < \infty$  satisfy  $\psi'(a) > \psi(b)/b$ ,  $[a, b] \subset J$ . For any  $\xi > 1$  and probability measure G on [a, b] define  $N(\xi; a; b; G) = \inf\{n \mid \int_a^b \exp\{yS_n - n\psi(y)\} dG(y) \ge \xi\}$ . There exist constants 0 < A,  $B < \infty$  independent of  $\xi$ , G such that  $E_{\theta}N(\xi; a; b; G) \le A \log \xi + B$  for all  $\theta \in [a, b]$  and  $\xi > 1$ .

PROOF. Define  $M(\gamma) = \inf\{n \mid \exp\{\gamma S_n - n\phi(\gamma)\} \ge \xi\}$ . It follows from Theorem 1 of Lorden (1970) that there exists  $0 < D < \infty$  such that  $E_{\theta}\{S_{M(\gamma)} - [M(\gamma)\phi(\gamma) + \log \xi]/\gamma\} \le D$  uniformly in  $\theta \in [a, b], \ \gamma \in [a, b], \ \xi > 1$  and so (by Wald's lemma) for all  $\theta, \gamma \in [a, b]$ 

(5) 
$$E_{\theta} M(\gamma) \leq \left[ (\log \xi)/\gamma + D \right] / \left[ \psi'(\theta) - \psi(\gamma)/\gamma \right]$$
$$\leq \left[ (\log \xi)/a + D \right] / \left[ \psi'(a) - \psi(b)/b \right].$$

From  $\int_a^b \exp\{yS_n - n\psi(y)\} dG(y) \ge \min(\exp\{aS_n - n\psi(a)\}, \exp\{bS_n - n\psi(b)\})$  it follows that  $N(\xi; a; b; G) \le \max(M(a), M(b)) \le M(a) + M(b)$ . This and (5) complete the proof of Lemma 1.

Lemma 2. Let  $\gamma \in (0, 1)$ , let  $F_0$  be the probability measure wholly concentrated at  $\{0\}$ , let G be a probability on [a, b],  $0 < a \le b < \infty$ ,  $[a, b] \subset J$ ,  $\psi'(a) > \psi(b)/b$  and denote  $F = \gamma F_0 + (1 - \gamma)G$ . Consider the optimal stopping problem defined by a prior distribution F on  $\theta$  when  $X_1, X_2, \cdots$  are i.i.d.— $P_\theta$  and each observation costs c > 0 if  $\theta \ne 0$ , zero if  $\theta = 0$ , with loss = 1 for stopping if  $\theta = 0$ . There exists a constant  $0 < M < \infty$  independent of c, F such that a Bayes procedure (with probability one) continues sampling whenever the posterior risk of stopping is at least Mc.

PROOF. That a Bayes rule exists can be seen from considerations similar to those of page 108 and Theorem 4.5' (page 82) of Chow, Robbins and Siegmund (1971).

Let  $\infty > Q > A/e$  where A is defined in Lemma 1 and define  $T_{Qe}$  to be the first time  $n \leq \infty$  that the posterior risk of stopping is at most Qc. It is sufficient to prove for some  $Q < M < \infty$  that the (integrated) risk of  $T_{Qe}$  is less than  $\gamma$  if  $\gamma \geq Mc$ . Since the (integrated) risk of any generalized stopping time T is the expected posterior risk of stopping plus  $c(1-\gamma)\int_a^b E_\theta T \, dG(\theta)$  it is sufficient to prove for some  $0 < M < \infty$  that  $(1-\gamma)\int_a^b E_\theta T \, dG(\theta) < \gamma/c - Q$  if  $\gamma \geq Mc$ .

Choose M > Q such that (1 - A/(Qe))M - (B + A/e) > Q where A, B are the constants defined by Lemma 1. It is enough to look at c for which Qc < 1. Notice that

$$T_{Qc} = \inf \{ n \mid Qc \ge \gamma h_0(x_1) \cdots h_0(x_n) / [\gamma h_0(x_1) \cdots h_0(x_n) + (1 - \gamma) \int_a^b h_0(x_1) \cdots h_0(x_n) dG(\theta) \}$$

$$= \inf \left\{ n \mid \int_a^b \exp\{yS_n - n\phi(y)\} dG(y) \ge \frac{\gamma}{1 - \gamma} \frac{1 - Qc}{Qc} \right\}$$

$$\le \inf \left\{ n \mid \int_a^b \exp\{yS_n - n\phi(y)\} dG(y) \ge \frac{\gamma}{(1 - \gamma)Qc} \right\}.$$

Noticing that  $\sup_{0 < y < 1} -y(\log y) = 1/e$ , apply Lemma 1 to get that if  $1 > \gamma \ge Mc$ 

$$(1 - \gamma) \int_a^b E_\theta T_{Qc} dG(\theta) \leq (1 - \gamma) \left[ A \left( \log \frac{\gamma}{Qc} + \log \frac{1}{1 - \gamma} \right) + B \right]$$

$$\leq \frac{\gamma}{c} \frac{A}{Q} \frac{Qc}{\gamma} \log \frac{\gamma}{Qc} + B + A(1 - \gamma) \log \frac{1}{1 - \gamma}$$

$$\leq \frac{\gamma}{c} \frac{A}{Qe} + B + \frac{A}{e}$$

$$\leq \frac{\gamma}{c} - \left( 1 - \frac{A}{Qe} \right) M + B + \frac{A}{e}$$

$$< \frac{\gamma}{c} - Q.$$

This completes the proof of Lemma 2.

Lemma 3. Let  $0 < a_1 < a < b < b_1 < \infty$  and let G be a probability on  $[a_1, b_1] \subset J$ 

with derivative g(x) = dG(x)/dx which is positive and continuous on  $[(a_1 + a)/2, (b_1 + b)/2]$ . Let  $T = \inf\{n \mid \int_{a_1}^{b_1} \exp\{yS_n - n\phi(y)\} dG(y) \ge \varepsilon\}$ . Then for all  $\theta \in [a, b]$ 

(7) 
$$E_{\theta} T = \frac{1}{2I(\theta)} [2 \log \varepsilon + \log \log \varepsilon] + O_{\theta}(1)$$

where  $\limsup_{\epsilon \to \infty} \sup_{a \le \theta \le b} |O_{\theta}(1)| < \infty$ .

PROOF. Notice that Theorem 1 of Pollak and Siegmund (1975) holds uniformly for  $\theta \in [a, b]$  so that the right-hand side of (7) is a lower bound for  $E_{\theta}T$ . Similar manipulations show the right-hand side of (7) to be an upper bound for  $E_{\theta}T$  uniformly for  $\theta \in [a, b]$ . See also Lai and Siegmund (1977).

Theorem 1. Let  $\theta_0 < a < b < \infty$ ,  $[a, b] \subset J$ ,  $\theta_0 \in J$ .

(8) 
$$\inf_{\{T|P_{\theta_0}(T<\infty)\leq 1/\varepsilon\}} \sup_{\alpha\leq\theta\leq b} 2I(\theta)E_{\theta}T = 2\log\varepsilon + \log\log\varepsilon + O(1)$$

where  $\limsup_{\epsilon \to \infty} |O(1)| < \infty$ , and equality is attained by a mixture stopping rule.

PROOF. Without loss of generality assume  $\theta_0 = 0$  and  $\psi'(a) > \psi(b)/b$ . That the equality is attained by a mixture stopping rule is the content of Lemma 3. To see that the right side of (8) is a lower bound of the left side of (8), consider the Bayesian problem defined in Lemma 2 when  $\gamma = \frac{1}{2}$  and  $dG(y)/dy = I(y)/\int_a^b I(y) dy$  on [a, b]. Let M be the constant derived in Lemma 2 and let  $T_{Mc}$  be  $T_{Qc}$  for Q = M where  $T_{Qc}$  is defined in (6).  $T_{Mc}$  is a mixture stopping rule defined by G and  $\varepsilon = (1 - Mc)/(Mc)$ . By virtue of Lemma 2 there exists a Bayes rule which continues sampling at least as long as  $T_{Mc}$ . Hence the Bayes risk is at least the sampling cost of  $T_{Mc}$ , whence for any stopping rule T

$$P_{\theta_0}(T<\infty)+c\int_a^b E_{\theta}T\,dG(\theta)\geq c\int_a^b E_{\theta}T_{Mc}\,dG(\theta)$$
.

Thus if  $P_{\theta_0}(T < \infty) \leq 1/\varepsilon = Mc/(1 - Mc)$ 

(9) 
$$\int_a^b E_\theta T dG(\theta) \ge \int_a^b E_\theta T_{Mc} dG(\theta) - M/(1 - Mc).$$

There exist  $a_1$ ,  $b_1$  such that  $0 < a_1 < a < b < b_1 < \infty$  and  $\psi'(a_1) > \psi(b_1)/b_1$ . Define  $\Lambda = \inf\{n \mid \int_{a_1}^{b_1} \exp\{yS_n - n\psi(y)\}I(y)\,dy/\int_a^b I(y)\,dy \ge \varepsilon\}$ . By definition,  $T_{Mc} \ge \Lambda$ .  $\Lambda$  is a mixture stopping rule defined by  $dF(y)/dy = I(y)/\int_{a_1}^{b_1} I(y)\,dy$  on  $[a_1, b_1]$  and  $\varepsilon' = \varepsilon \int_a^b I(y)\,dy/\int_{a_1}^{b_1} I(y)\,dy$ . Thus by Lemma 3

(10) 
$$E_{\theta} T_{Me} \geq E_{\theta} \Lambda = \frac{1}{2I(\theta)} [2 \log \varepsilon + \log \log \varepsilon] + O_{\theta}(1)$$

where  $\limsup_{\epsilon \to \infty} \sup_{\alpha \le \theta \le b} |O_{\theta}(1)| < \infty$ . Combining (9) and (10) yields

$$\int_a^b E_\theta T dG(\theta) \ge \int_a^b \left[ 2 \log \varepsilon + \log \log \varepsilon + O(1) \right] d\theta / \left( 2 \int_a^b I(y) dy \right)$$

whence by definition of G

$$\int_a^b \left[ 2I(\theta) E_\theta T - (2 \log \varepsilon + \log \log \varepsilon) \right] d\theta \ge O(1)$$

for all T satisfying  $P_{\theta_0}(T < \infty) \leq 1/\varepsilon$ , thus completing the proof of (8).

THEOREM 2. Let F be a probability on J with  $F\{(0,\infty)\} > 0$ ,  $T(\varepsilon) = \inf\{n \mid \int_J \exp\{yS_n - n\phi(y)\} dF(y) \ge \varepsilon\}$  and let  $0 < \gamma < 1$ . There exists an interval  $[a,b] \subset J$  with  $0 < a \le b < \infty$ ,  $\phi'(a) < \phi(b)/b$  such that  $T(\varepsilon)$  is a  $\delta$ -Bayes solution of the optimal stopping problem described in Lemma 2 (with  $dG(y) = dF(y)/F\{[a,b]\}$  for  $y \in [a,b]$  and with c defined by  $\varepsilon = [\gamma/(1-\gamma)][(1-Mc)/(Mc)]/F\{[a,b]\}$  where M is defined in Lemma 2) where the Bayes solution has a risk of order  $(\log \varepsilon)/\varepsilon$  and  $\delta = O(1/\varepsilon)$  as  $\varepsilon \to \infty$ .

PROOF. There exist a, b satisfying  $0 < a \le b < \infty$ ,  $[a, b] \subset J$ ,  $\psi'(a) \le \psi(b)/b$ ,  $F\{[a, b]\} > 0$ . Let G, c be defined as above and consider the optimal stopping problem described in Lemma 2. Let  $T_{Mc}$  be  $T_{Qc}$  for Q = M as defined in (6). Clearly  $T_{Mc} \ge T(\varepsilon)$ . Therefore and by virtue of Lemma 2 there exists a Bayes solution which samples at least as many observations as  $T(\varepsilon)$  and so the Bayes risk of  $T(\varepsilon)$  cannot exceed that of the Bayes solution by more than  $\gamma P_0(T(\varepsilon) < \infty) \le \gamma/\varepsilon$ . Since c is of the order  $1/\varepsilon$  and  $ET(\varepsilon)$  is of the order  $\log \varepsilon$ , the order of the risk of sampling of the Bayes solution is  $(\log \varepsilon)/\varepsilon$  and the proof is complete.

3. Exact optimality. Let  $h_{\theta}^{*n}$  be the *n*-fold convolution of  $h_{\theta}$  with itself with respect to  $\nu$ ; let  $H_{\theta}^{*n}$  be the measure whose derivative with respect to  $\nu$  is  $h_{\theta}^{*n}$ , and understand  $H_{\theta}^{*n}(z) = H_{\theta}^{*n}\{(-\infty, z]\}$ . Let  $0 \in J$ . Denote:  $\mathbf{c} = (c_1, c_2, \cdots)$  where  $-\infty \leq c_j \leq \infty$ ,  $j = 1, 2, \cdots$ . Denote

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\chi(A) = \text{ the indicator function of the event} \quad A;
\mathscr{C}_{\varepsilon} = \{(\mathbf{c}, \mathbf{\alpha}) \mid 0 \leq \alpha_{j} \leq 1 \text{ for all } j,
\sum_{j=1}^{\infty} [1 - (H_{0}^{*j}(c_{j}) - \alpha_{j}H_{0}^{*j}\{\{c_{j}\}\})] = 1/\varepsilon\}, \quad \varepsilon > 1;
\mathscr{G} = \{G \mid G \text{ is a probability on } \{\theta \mid a \leq \theta \leq b\}\};
\mathscr{M}_{\varepsilon} = \{\mu \mid \mu \text{ is a probability measure on } \{\mathbf{z} \mid \sum_{i=1}^{\infty} (1 - z_{i}) = 1/\varepsilon\}\};
\mathscr{E}_{\varepsilon} = \{W \mid W = \sum_{j=1}^{\infty} [\chi(S_{j} \leq c_{j}^{w}) - \alpha_{j}^{w}\chi(S_{j} = c_{j}^{w})], (\mathbf{c}^{w}, \mathbf{\alpha}^{w}) \in \mathscr{C}_{\varepsilon}\};
\mathscr{R}_{\varepsilon} = \{T \mid T \text{ is a stopping variable defined by } (2), \quad \varepsilon > 1 \text{ fixed}\};
\mathscr{R} = \bigcup_{\varepsilon > 1} \mathscr{R}_{\varepsilon};
\mathscr{Q}_{\varepsilon} = \{T \mid T \text{ is a stopping variable for } \{S_{k}\}_{k=1,2,\dots} \text{ whose stopping boundary is concave, } P_{0}(T < \infty) = 1/\varepsilon \text{ (where randomization on the boundary is permitted to let this equality hold)}.
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 $A_T(j)$  is the stopping boundary defining  $T \in \mathcal{Q}_{\epsilon}$ .

THEOREM 3. Let  $r(\theta)$  be any continuous nonnegative function of  $\theta$  in  $[a, b] \subset J$ ,  $0 < a < b < \infty$ , such that r is not identically zero in the interval. Then:  $\inf_{w \in \mathscr{C}_{\varepsilon}} \sup_{a \le \theta \le b} r(\theta) E_{\theta} W$  is attained by a unique (up to probability one)  $L \in \mathscr{C}_{\varepsilon}$  defined by coordinates  $c_i^L$  which are boundary values defining some  $T \in \mathscr{R}$ .

Sketch of Proof. Suppose that the closure of the support of  $\nu$  is convex (otherwise minor changes must be made in the following). Denote  $z_j{}^{\theta} = H_{\theta}{}^{*j}(c_j) - \alpha_j H_{\theta}{}^{*j}\{\{c_j\}\}$ . Clearly, there is a 1:1 correspondence between  $z_j{}^{\theta}$  and  $(\mathbf{c}, \boldsymbol{\alpha})$ , and  $z_j{}^{\theta}$  is a continuous and increasing function of  $z_j{}^{\theta}$ . Denote:

 $g(\theta, \mathbf{z}^0) = \sum_{j=1}^{\infty} z_j^{\theta}$ . By the minimax theorem (cf. Fan (1952)) there exist  $\mu_0 \in \mathcal{M}_{\epsilon}$ ,  $G_0 \in \mathcal{G}$  such that

$$\inf_{(\mathbf{c},\mathbf{a})\in\mathscr{C}_{\varepsilon}}\sup_{\mathbf{a}\leq\theta\leq b}r(\theta)g(\theta,\mathbf{z}^{0})$$

$$=\inf_{(\mathbf{c},\mathbf{a})\in\mathscr{C}_{\varepsilon}}\sup_{\mathbf{c}\in\mathscr{C}}\int r(\theta)g(\theta,\mathbf{z}^{0})\ dG(\theta)$$

$$\geq\inf_{\mu\in\mathscr{M}_{\varepsilon}}\sup_{\mathbf{c}\in\mathscr{C}}\int\int r(\theta)g(\theta,\mathbf{z}^{0})\ dG(\theta)\ d\mu(\mathbf{z}^{0})$$

$$=\max_{G\in\mathscr{G}}\min_{\mu\in\mathscr{M}_{\varepsilon}}\int\int r(\theta)g(\theta,\mathbf{z}^{0})\ dG(\theta)\ d\mu(\mathbf{z}^{0})$$

$$=\min_{u\in\mathscr{M}_{\varepsilon}}\int\int r(\theta)g(\theta,\mathbf{z}^{0})\ dG_{0}(\theta)\ d\mu(\mathbf{z}^{0})\ .$$

Clearly, any  $\mu \in \mathscr{M}_{\varepsilon}$  attaining this minimum must give all of its mass to points  $\mathbf{z}^0$  for which  $\int r(\theta)g(\theta, \mathbf{z}^0) dG_0(\theta)$  reaches its minimum. Since

$$\int r(\theta)g(\theta, \mathbf{z}^0) dG_0(\theta) = \int r(\theta) \sum_{j=1}^{\infty} z_j dG_0(\theta)$$

and

$$\frac{dz_{j}^{\theta}}{dz_{i}^{\theta}} = \exp\{\theta c_{j} - j\psi(\theta)\}\$$

where  $c_j$  is that corresponding to  $z_j^0$ , one can minimize  $\int r(\theta)g(\theta, \mathbf{z}^0) dG_0(\theta)$  subject to the constraint  $\sum_{i=1}^{\infty} (1-z_i^0) = 1/\varepsilon$  by the method of Lagrange multipliers (cf. Luenberger (1969) page 186). By differentiating  $[\int r(\theta)g(\theta, \mathbf{z}^0) dG_0(\theta) + \lambda(\sum_{i=1}^{\infty} (1-z_i^0) - 1/\varepsilon)]$  with respect to  $z_j^0$ , one gets that extremum points  $\mathbf{z}^0$  must satisfy

for the corresponding  $\mathbf{c}$ . Here  $c_j$  increases if  $\lambda$  is increased. So, because of the constraint, corresponding to  $\lambda$  there exists a unique solution  $\mathbf{c}^*$  to (12). Because of the constraint, there can be only one  $\lambda$  for which a solution to (12) exists. Thus there is a unique  $\lambda$  and a unique  $\mathbf{c}^*$  satisfying (12), and so  $\mathbf{z}^{0*}$  corresponding to  $c^*$  must be the unique point of minimum. Therefore there is equality in (11) and the proof is complete.

- 4. Remarks. (a) Lemmas 1 and 2 and Theorem 2 are modeled after Lemmas 2.1 and 2.2 and Theorem 2.1 of Lorden (1967). Obviously, the condition  $\phi'(a) < \phi(b)/b$  appearing in Lemma 1 (and in the sequel) can be dispensed with. Theorem 2 can be reformulated to be an analog of Theorem 2.1 of Lorden (1967).
- (b) Under certain conditions one can show that  $\lambda$  of (12) is of the order of magnitude of  $\varepsilon$  as  $\varepsilon \to \infty$ .
- (c) Theorems and lemmas similar to these presented in this article can be formulated for Brownian motion; denote standard Brownian motion by  $\omega(t)$  and set  $X(t) = \theta t + \omega(t)$ , let  $I(\theta) = \theta^2/2$ , let

$$T_{Qc} = \inf \left\{ t \mid \int_a^b \exp\{yS_t - t\phi(y)\} dG(y) \ge \frac{\gamma}{1 - \gamma} \frac{1 - Qc}{Qc} \right\}$$

replace  $T_{qc}$  of (6) and let c be the cost of sampling per unit time if  $\theta \in [a, b]$ . An invariance argument leads to an analog of Theorem 3.

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