

# AN OPERATIONAL APPROACH TO THE $r$ -WAY CROSSED CLASSIFICATION<sup>1</sup>

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**1. Summary.** An operational method is used to obtain known formulas [2] for the expected values of the mean squares and the variances of estimates of variance components obtained from the analysis of variance of an  $r$ -way crossed classification. The results are independent of normality assumptions.

**2. Introduction.** We begin with the results and notation of a book by Mann [4], considering an  $r$ -way classification with replication. An observation is denoted by  $x_a = x_{a_1 \dots a_{r+1}}$ ,  $a_i = 1, \dots, t_i$ , where the last subscript is used to indicate replications. Main effects and interactions are represented by  $\mu(I, a_I) = \mu(i_1, \dots, i_k; a_{i_1}, \dots, a_{i_k})$ , where  $I = (i_1, \dots, i_k)$  is a subset of  $R = (1, \dots, r)$ , and  $\mu(I, a_I) = \mu$  if  $I$  is the null set.

We now introduce two operators,  $D_i = D_{a_i}$  which drops  $i$  and  $a_i$  from  $\mu(R, a_R)$  and  $M_i = M_{a_i}$  which averages a function over  $a_i$ , if  $a_i$  appears, and otherwise leaves the function unchanged. These operators are commutative with respect to themselves and each other and all the ordinary laws of algebra, excluding division, hold. It is assumed that

$$(2.1) \quad E(x_a) = (1 + D)_R \mu(R, a_R),$$

$$(2.2) \quad M_{i_j} \mu(I, a_I) = 0, \quad j = 1, \dots, k,$$

where  $(1 + D)_R = (1 + D_1) \dots (1 + D_r)$ . It is easy to establish

LEMMA 2.1. *Independent of condition (2.2),*

$$(2.3) \quad \begin{aligned} M_i D_i &= D_i, & (1 - M_i) D_i &= 0, & M_i (1 + D_i) &= M_i + D_i, \\ (1 - M_i) (1 + D_i) &= 1 - M_i. \end{aligned}$$

*Subject to condition (2.2),*

$$(2.4) \quad (M_i + D_i) \mu(R, a_R) = D_i \mu(R, a_R), \quad (1 - M_i) \mu(R, a_R) = \mu(R, a_R),$$

*provided that these expressions are not multiplied by  $\hat{D}_i$ .*

Mann establishes an identity [4, p. 52]

$$(2.5) \quad t M_a^2 = (1 + D) SS(R + 1)$$

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where  $R + 1 = (1, \dots, r + 1)$ ,  $t = t_{h+1} = t_1 \cdots t_{r+1}$ ,  $(1 + D) = (1 + D)_{R+1}$ ,

$$(2.6) \quad \text{SS}(I) = tQ(I)/t_I = tM_I A^2(I, a_I),$$

$$(2.7) \quad A(I, a_I) = M_{R+1-I}(1 - M)_I x_a,$$

$$t_I = t_{i_1} \cdots t_{i_k}, \quad M_{R+1-I} = M_1 \cdots M_{r+1}/M_{i_1} \cdots M_{i_k}, \quad \text{and}$$

$$(1 - M)_I = (1 - M_{i_1}) \cdots (1 - M_{i_k}).$$

The following lemma is an immediate consequence of definition (2.7).

LEMMA 2.2  $A(I, a_I) = M_b(t\delta_{ab} - 1)_I x_b$  where

$$(t\delta_{ab} - 1)_I = (t_{i_1}\delta_{a_{i_1}b_{i_1}} - 1) \cdots (t_{i_k}\delta_{a_{i_k}b_{i_k}} - 1).$$

The above notation and operators can be employed to simplify considerably the usual derivations of the analysis of variance for the  $r$ -way crossed classification. As an example, we prove the identity (2.5). Making use of the equations (2.6), (2.7), and Lemma 2.2, we have

$$\begin{aligned} (1 + D)\text{SS}(R + 1) &= t(1 + D)_{a_{R+1}} M_a A^2(R + 1, a_{R+1}) \\ &= t(1 + D)_{a_{R+1}} M_a M_b M_c (t\delta_{ab} - 1)_{R+1} (t\delta_{ac} - 1)_{R+1} x_b x_c \\ &= t(1 + D)_{a_{R+1}} M_b M_c (t\delta_{bc} - 1)_{R+1} x_b x_c \\ &= tM_b M_c (1 + t\delta_{bc} - 1)_{R+1} x_b x_c = tM_b x_b^2. \end{aligned}$$

**3. The Type I model.** We define  $\epsilon_a$  by the equation  $x_a = E(x_a) + \epsilon_a$  and make the usual assumptions for the Type I model [1, p. 348] save that we do not assume that the  $\epsilon_a$  are normally distributed. It will be sufficient if they are independently distributed with zero means, a common variance,  $\sigma^2$ , and such other moments as we require. In addition to the sum of squares  $\text{SS}(I)$ , we will be interested in the error sum of squares, SSE, which is obtained by summing all  $\text{SS}(I)$  for which the last index is  $r + 1$ . It is easy to verify, using the operators, that

$$(3.1) \quad \text{SSE} = tM[(1 - M_{r+1})x_a]^2.$$

The corresponding mean sums of squares,  $\text{MS}(I)$  and  $\text{MSE}$ , are obtained by dividing the above sums of squares by their degrees of freedom which are  $(t - 1)_I$  and  $t_r(t_{r+1} - 1)$ , respectively. In the case where  $t_{r+1} = 1$ , it is necessary to assume that the  $\mu(R, a_R)$  are zero. In this case the value of  $\text{SS}(I)$  is unchanged, but SSE is  $\text{SS}(R)$  and the corresponding degrees of freedom are  $(t - 1)_R$ .

We now state and prove two lemmas.

LEMMA 3.1. *For the Type I model*

$$(3.2) \quad A(I, a_I) = \mu(I, a_I) + M_{R+1-I}(1 - M)_I \epsilon_a.$$

PROOF. We deduce from (2.7), and (2.1) that we must prove

$$\mu(I, a_I) = M_{R+1-I}(1 - M)_I(1 + D)_{I\mu}(R, a_R).$$

By (2.3), (2.4), and (2.2)

$$\begin{aligned} M_{R+1-I}(1-M)_I(1+D)_{R\mu}(R, a_R) &= M_{R-I}(1-M)_I(1+D)_{R-I\mu}(R, a_R) \\ &= (1-M)_I(M+D)_{R-I\mu}(R, a_R) \\ &= (1-M)_I D_{R-I\mu}(R, a_R) = (1-M)_I \mu(I, a_I) = \mu(I, a_I). \end{aligned}$$

LEMMA 3.2. *For the Type I model*

$$(3.3) \quad E[M_{R+1-I}(1-M)_I \epsilon_a]^2 = (t-1)I\sigma^2/t.$$

PROOF. The desired expected value is necessarily of the form  $c\sigma^2$  where  $c$  is a constant which does not depend upon the form of the distribution of the  $\epsilon_a$ , which we may assume to be NID(0,  $\sigma^2$ ). Under these conditions,  $SS(I)$  is distributed as  $\chi^2 \sigma^2$  when the  $\mu(I, a_I) = 0$  and the result (3.3) is easily established.

As an almost immediate consequence of these lemmas we obtain:

THEOREM 3.1. *For the Type I model*

$$(3.4) \quad E[MS(I)] = \sigma^2 + t\sigma^2(I)/t_I$$

where  $\sigma^2(I) = t_I M_I \mu^2(I, a_I)/(t-1)_I$ . When  $t_{r+1} = 1$ ,  $E(\text{MSE}) = \sigma^2 + \sigma^2(R)$ , and, otherwise,  $E(\text{MSE}) = \sigma^2$ .

Assuming that  $t_{r+1} > 1$  and equating mean squares to their expected values, we obtain the unbiased estimates of the variance components

$$\widehat{\sigma^2}(I) = t_I[MS(I) - \text{MSE}]/t, \quad \widehat{\sigma^2} = \text{MSE}.$$

Examination of  $(\text{SSE})^2$  indicates that  $E(\text{SSE})^2 = k_1\mu_4 + k_2\mu_2^2$  where  $k_1$  and  $k_2$  are independent of the distribution of the  $\epsilon_a$ . Accordingly, we may assume that the  $\epsilon_a$  are NID(0,  $\sigma^2$ ) and obtain a linear relationship between  $k_1$  and  $k_2$  since  $\text{SSE}$  is then distributed as  $\chi^2 \sigma^2$ . A little computation determines  $k_1$  and leads to the conclusion that  $\text{var}(\widehat{\sigma^2}) = (\mu_4 - 3\mu_2^2)/t + 2\mu_2^2/t_R(t_{r+1} - 1)$ .

Making use of (3.2), we find that  $\widehat{\sigma^2}(I) = \sigma^2(I) + D + F$  where

$$D = 2t_I M_b \mu(I, b_I) \epsilon_b / (t-1)_I,$$

$$F = t_I M_b M_c [(t\delta_{bc} - 1)/(t-1)_I - (t_{r+1}\delta_{b_{r+1}c_{r+1}} - 1)\delta_{bcR}/(t_{r+1} - 1)] \epsilon_b \epsilon_c.$$

We note that the quadratic form  $F$  contains no squared terms,  $E(D) = E(DF) = E(F) = 0$ ,  $E(D^2) = 4t_I^2 M_b M_c \mu(I, b_I) \mu(I, c_I) \delta_{bc} \sigma^2 / (t-1)_I^2 = 4t_I \sigma^2 \sigma^2(I) / t(t-1)_I$ , and a similar, but longer, calculation gives

$$E(F^2) = 2t_I^2 [1/(t-1)_I + 1/t_R(t_{r+1} - 1)] \mu_2^2 / t^2.$$

These results lead to the conclusion that

$$(3.5) \quad \begin{aligned} \text{var}[\widehat{\sigma^2}(I)] &= 4t_I \sigma^2 \sigma^2(I) / t(t-1)_I \\ &+ 2t_I^2 [1/(t-1)_I + 1/t_R(t_{r+1} - 1)] \sigma^4 / t^2 \end{aligned}$$

**4. The Type II model.** The usual assumptions are made for a Type II model [3] save that we make no normality assumptions. We recall that equation (2.2) no longer holds. We state

LEMMA 4.1. *For any model,*

$$A(I, a_I) = M_{R-I}(1 - M)_I(1 + D)_{R-I}\mu(R, a_R) + M_{R+I-I}(1 - M)_{I\epsilon_a}.$$

PROOF. This relation was established in the proof of Lemma 3.1.

This lemma and the method used to prove Theorem 3.1 leads at once to:

THEOREM 4.1. *For the Type II model,*

$$(4.1) \quad E[\text{MS}(I)] = \sigma^2 + t(1 + D)_{R-I}[\sigma^2(R)/t_R],$$

where  $\sigma^2(R)$  is the variance of the  $\mu(R, a_R)$ .

Equating mean squares to their expected values and solving we obtain:

LEMMA 4.2. *For a Type II model, without normality assumptions,*

$$\widehat{\sigma}^2(I) = (-1)^{r-k}(1 - D)_{R-I}[\text{MS}(R)]/t_{R+I-I} \quad (k < r),$$

and

$$\widehat{\sigma}^2(R) = [\text{MS}(R) - \text{MSE}]/t_{r+1}.$$

The estimates are given in a more convenient form in

LEMMA 4.3. *For a Type II model, without normality assumptions,  $\widehat{\sigma}^2(I) = A + B + C$  ( $k < r$ ), where*

$$A = t_R M_{b_R} M_{c_R} (t\delta_{bc} - 1)_I (1 - \delta_{bc})_{R-I} w_{b_R} w_{c_R} / (t - 1)_k,$$

$$B = 2t_R M_{b_R} M_c (t\delta_{bc} - 1)_I (1 - \delta_{bc})_{R-I} w_{b_R} \epsilon_c / (t - 1)_R,$$

$$C = t_R M_b M_c (t\delta_{bc} - 1)_I (1 - \delta_{bc})_{R-I} \epsilon_b \epsilon_c / (t - 1)_R,$$

$$w_{b_R} = (1 + D)_{R-I}\mu(R, b_R).$$

It will be noted that the coefficients of  $w_{b_R}^2$  and  $\epsilon_b^2$  are equal to zero and it follows that  $E[\widehat{\sigma}^2(I)]^2 = E(A^2 + B^2 + C^2)$ , and computation gives us

$$(4.2) \quad \begin{aligned} \text{var}[\widehat{\sigma}^2(I)] &= [\mu_4(I) - 3\sigma^4(I)]/t_I \\ &+ 2t_I \sum_{X, Y \subset R-I} \sigma^2(I + X)\sigma^2(I + Y)/t_I(t - 1)_{I t_{XY}}(t - 1)_{XY t_{X-XY} t_{Y-XY}} \\ &+ 4t_I \sigma^2(1 + D)_{R-I}[\sigma^2(R)/(t - 1)_R]/t + 2t_I t_R \sigma^4/t^2(t - 1)_R \quad (k < r), \end{aligned}$$

where  $XY$  is the set of numbers common to  $X$  and  $Y$ .

If  $t_{r+1} > 1$ ,

$$\begin{aligned} \text{var}[\widehat{\sigma}^2(R)] &= [\mu_4(R) - 3\sigma^4(R)]/t_R + 2\sigma^4(R)/(t - 1)_R + 4\sigma^2\sigma^2(R)/t_{r+1}(t - 1)_R \\ &+ 2[1/(t - 1)_R + 1/t_R(t_{r+1} - 1)]\sigma^4/t_{r+1}^2. \end{aligned}$$

**5. The Type III model.** We assume that the  $t_I$  expressions of the form  $\mu(I, a_I)$  are a sample from a finite population,  $P(I)$ , consisting of  $T_I$  members with zero

mean and variance

$$(5.1) \quad \sigma^2(I) = T_I \mathfrak{M}_I \mu^2(I, a_I) / (T - 1)_I$$

where  $\mathfrak{M}_i = \mathfrak{M}_{a_i}$  is an operator which averages a function over  $a_i$  when the range of  $a_i$  is from 1 to  $T_i$ . We also assume that

$$(5.2) \quad \mathfrak{M}_{i_j; \mu}(I, a_I) = 0, \quad j = 1, \dots, k,$$

and that random variables from different populations are independent. We draw our sample from  $P(I)$  by selecting  $t_{i_j}$  numbers at random from the set  $1, \dots, T_{i_j}$  ( $j = 1, \dots, k$ ). Lemma 4.1 holds under these conditions, so our problem reduces to finding the expected value of expressions of the form

$$[M_{R-I}(1 - M)_{I\mu}(R, a_R)]^2.$$

We will require the following lemmas.

LEMMA 5.1. *For a Type III model*

$$E[\mu(I, a_I)\mu(I, b_I)] = (\delta_{ab} - 1/T)_I \sigma^2(I)$$

where  $\delta_{a_i, b_i} = 1$  if  $a_i = b_i$ , and is zero otherwise.

LEMMA 5.2. *For the Type III model*

$$E[M_{R-I}(1 - M)_{I\mu}(R, a_R)]^2 = (1 - 1/t)_I (1/t - 1/T)_{R-I} \sigma^2(R) \quad (k \leq r).$$

The application of the above lemmas leads to the following theorem which has also been stated by Bennett and Franklin [1].

THEOREM 5.1. *For the Type III model*

$$E MS(I) = \sigma^2 + t(1 + D)_{R-I} (1 - t/T)_{R-I} \sigma^2(R) / t_R.$$

Equating mean squares to their expected values and solving we obtain

THEOREM 5.2. *For the Type III model*

$$\widehat{\sigma^2}(I) = [(D - 1)_{R-I} (1 - t/T)_{R-I} MS(R) - t_{R-I} MSE / T_{R-I}] / t_{R+1-I} \quad (k \leq r).$$

Computations which are too long to be included in this paper lead to the conclusion that

$$(5.3) \quad E[\widehat{\sigma^2}(I)]^2 = A + B + C + D$$

where

$$A = 4(t_I/t)\sigma^2(1 + D)_{R-I} [(1 - 1/T)_{R-I} (1 - t/T)_{R-I} \sigma^2(R) / (t - 1)_R],$$

$$B = 2t_R t_I \{ [(t - 1)/T^2 + (1 - 1/T)_{R-I}^2] + (t - 1)_R / t_I (t_{r+1} - 1) T_{R-I}^2 \} \sigma^4 / t^2,$$

$$C = 2 \sum_{\substack{X, Y \subseteq R-I \\ X \neq Y}} (1 - t/T)_{X+Y} \sigma^2(I + X) \sigma^2(I + Y) / (t - 1)_I (t - 1)_{X+Y-X-Y},$$

and

$$\begin{aligned}
 t_R(t-1)_R D &= \sum_{X \subset R-I} t_{R-I-X}(t-1)_{R-I-X}(1-t/T)_X / \\
 & [T(T-1)(T-2)(T-3)]_{I+X} \times \sum_{f_{I+X}} \sum_{g_{I+X}} \sum_{h_{I+X}} \sum_{m_{I+X}} \\
 & \{[(t-1)^2 T^2 - (3t-1)(t-1)T + t^2 + t] \delta_{f_g} \delta_{hm} \\
 & + (T-t)(T-t-1)(\delta_{fh} \delta_{gm} + \delta_{fm} \delta_{gh}) \\
 & + T(T-t)\{(t-1)T - t - 1\} \delta_{fg} \delta_{gh} \delta_{hm}]_I \\
 & \times [(3-t-t/T-1/T) \delta_{fg} \delta_{hm} + (T-1)^2(T-t-1) \\
 & (\delta_{fh} \delta_{gm} + \delta_{fm} \delta_{gh})/T + \{-2T^2 + (3t+1)T - t - 1\} \\
 & \delta_{fg} \delta_{gh} \delta_{hm}]_X \times \mu(I+X, f_{I+X}) \\
 & \mu(I+X, g_{I+X}) \mu(I+X, h_{I+X}) \mu(I+X, m_{I+X}).
 \end{aligned}$$

The following formula which is used in the derivative of the expression for  $D$  may be of interest:

$$\begin{aligned}
 & [T(T-1)(T-2)(T-3)]_R E[\mu(R, b_R) \mu(R, c_R) \mu(R, d_R) \mu(R, e_R)] \\
 & = \sum_{f_R} \sum_{g_R} \sum_{h_R} \sum_{m_R} [(A_1 T^2 + A_2 T + A_3) \delta_{fg} \delta_{hm} + (B_1 T^2 + B_2 T + B_3) \delta_{fh} \delta_{gm} \\
 & + (C_1 T^2 + C_2 T + C_3) \delta_{fm} \delta_{gh} + (D_1 T^3 + D_2 T^2 + D_3 T - 6) \delta_{fg} \delta_{gh} \delta_{hm}]_R \\
 & \cdot \mu(R, f_R) \mu(R, g_R) \mu(R, h_R) \mu(R, m_R)
 \end{aligned}$$

where

$$\begin{aligned}
 A_1 &= \delta_{bc} \delta_{de} - C(3, 4), \quad A_2 = C(2, 3) + C(3, 4) - \delta_{bc} - \delta_{de} - 3\delta_{bc} \delta_{de}, \\
 A_3 &= 1 + 3\delta_{bc} + 3\delta_{de} - C(1, 2) - C(2, 3) + C(2, 4), \quad B_1 = \delta_{bd} \delta_{ce} - C(3, 4), \\
 B_2 &= C(2, 3) + C(3, 4) - \delta_{bd} - \delta_{ce} - 3\delta_{bd} \delta_{ce}, \\
 B_3 &= 1 + 3\delta_{bd} + 3\delta_{ce} - C(1, 2) - C(2, 3) + C(2, 4), \quad C_1 = \delta_{be} \delta_{cd} - C(3, 4) \\
 C_2 &= C(2, 3) + C(3, 4) - \delta_{be} - \delta_{cd} - 3\delta_{be} \delta_{cd}, \\
 C_3 &= 1 + 3\delta_{be} + 3\delta_{cd} - C(1, 2) - C(2, 3) + C(2, 4), \quad D_1 = C(3, 4), \\
 D_2 &= C(3, 4) - C(2, 3) - C(2, 4), \quad D_3 = 2C(1, 2) - C(2, 3) + C(2, 4), \\
 C(1, 2) &= \delta_{bc} + \delta_{bd} + \delta_{be} + \delta_{cd} + \delta_{ce} + \delta_{de}, \\
 C(2, 3) &= \delta_{bc} \delta_{cd} + \delta_{bc} \delta_{ce} + \delta_{bd} \delta_{de} + \delta_{cd} \delta_{de}. \\
 C(2, 4) &= \delta_{bc} \delta_{de} + \delta_{bd} \delta_{ce} + \delta_{be} \delta_{cd}, \\
 C(3, 4) &= \delta_{bc} \delta_{cd} \delta_{de}.
 \end{aligned}$$

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