## ON ADDING INDEPENDENT STOCHASTIC PROCESSES

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Let x be a stochastic process on an interval T,  $P_x$  be the probability measure it induces on the space  $\Omega$  of sample functions on T, and M be the set of functions f in  $\Omega$  such that  $P_{x+f}$  is absolutely continuous with respect to  $P_x$  (written  $P_{x+f} < P_x$ ). The functions in M are "at least as smooth as" the sample functions of x in the sense that any smoothness property possessed by almost all of the sample functions must also be possessed by each function in M. Similarly, if y is a process independent of x such that  $P_{x+y} < P_x$ , then almost all the sample functions of y must possess any smoothness property possessed by almost all the sample functions of x. This might lead one to conjecture that  $P_{x+y} < P_x$  would imply  $P_y(M) = 1$  but this fails to hold even in the Gaussian case [1]. What is true in the Gaussian case is that  $P_y(M) = 1$  if and only if the measure Q associated with the vector process (x + y, y) is absolutely continuous with respect to the measure P associated with the process (x, y). The theorem of this note generalizes this result to a large class of separable x's.

We assume that x is separable in the sense that there exists a countable subset  $(t_i)$  of T such that the closure, with respect to  $P_x$ , of the  $\sigma$ -field generated by the  $x(t_i)$  contains the  $\sigma$ -field generated by all the x(t). We also assume that the joint distribution of  $x(t_i)$ ,  $\cdots$ ,  $x(t_n)$  is given by a density  $G_n$  which is almost everywhere positive in  $R^n$  with respect to Lebesgue measure. We shall write  $x_i, y_i, f_i$ , and  $g_i$  for  $x(t_i), y(t_i), f(t_i)$ , and  $g(t_i)$  and  $S_n$  for the  $\sigma$ -field generated by  $x_1, \cdots, x_n$ . It is easily verified that the function  $D_n$  on  $\Omega \times \Omega$  defined by

$$D_n(f, g) = G_n(f_1 - g_1, \dots, f_n - g_n)/G_n(f_1, \dots, f_n)$$

is, for each fixed g in  $\Omega$ , a martingale with respect to the fields  $S_n$  and the measure  $P_x$ . It follows that  $D_n(f, g)$  converges almost everywhere  $(P_x)$  for each g to a limit D(f, g), that  $\int D(f, g) P_x(df) \leq 1$  and that  $\int D(f, g) P_x(df) = 1$  if and only if g is in M, in which case  $D(f, g) = (dP_{x+g}/dP_x)(f)$  almost everywhere  $(P_x)$ .

THEOREM. If x and y are independent processes on T and P and Q are the measures associated with (x, y) and (x + y, y) then Q < P if and only if  $P_y(M) = 1$ . In this case (dQ/dP)(f, g) = D(f, g).

PROOF. Suppose  $Q \prec P$ . For any  $S_n \times S_n$  measurable F

$$\int FD_n dP = \int \int F(f_1, \dots, f_n, g_1, \dots, g_n)$$

$$\cdot G_n(f_1 - g_1, \dots, f_n - g_n) df_1 \dots df_n P_y (dg)$$

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$$= \int \int F(f_1 + g_1, \dots, f_n + g_n, g_1, \dots, g_n)$$

$$\cdot G_n(f_1, \dots, f_n) df_1 \dots df_n P_y (dg)$$

$$= \int F dQ$$

so  $D_n = E(dQ/dP \mid S_n \times S_n)$  and hence D = dQ/dP. Thus

$$1 = \int D dP = \int P_{y} (dg) \left( \int D(f,g) P_{x} (df) \right)$$

so

$$P_y\left(\left[g\left|\int D(f,g)P_x\left(df\right)\right|=1\right]\right)=P_y(M)=1.$$

Conversely, if  $P_{\nu}(M) = 1$  then  $\int D dP = \int P_{\nu}(dg) \int D(f, g) P_{x}(df) \ge P_{\nu}(M) = 1$  and this plus the fact that for any positive  $S_{n} \times S_{n}$  measurable function F,  $\int FD dP \le \liminf_{m \to \infty} \int FD_{m} dP = \int F dQ$  implies that Q < P and D = dQ/dP.

## REFERENCE

[1] PITCHER, T. S. (1963). On the sample functions of processes which can be added to a Gaussian process. Ann. Math. Statist. 34 329-333.