

Electron. J. Probab. 18 (2013), no. 50, 1-15.
ISSN: 1083-6489 DOI: 10.1214/EJP.v18-2124

# A note on the existence of solutions to Markovian superquadratic BSDEs with an unbounded terminal condition 

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#### Abstract

In [17], the author proved the existence and the uniqueness of solutions to Markovian superquadratic BSDEs with an unbounded terminal condition when the generator and the terminal condition are locally Lipschitz. In this paper, we prove that the existence result remains true for these BSDEs when the regularity assumptions on the terminal condition is weakened.


Keywords: Backward stochastic differential equation ; Generator of superquadratic growth ; Unbounded terminal condition ; Existence result.
AMS MSC 2010: 60H10.
Submitted to EJP on June 29, 2012, final version accepted on April 12, 2013.

## 1 Introduction

Since the early nineties and the work of Pardoux and Peng [15], there has been an increasing interest for backward stochastic differential equations (BSDEs for short) because of the wide range of applications. A particular class of BSDE is studied since few years: BSDEs with generators of quadratic growth with respect to the variable $z$ (quadratic BSDEs for short). See e.g. [12, 2, 6] for existence and uniqueness results and [19, 11, 13] for applications.

Naturally, we could also wonder what happens when the generator has a superquadratic growth with respect to the variable $z$. Up to our knowledge the case of superquadratic BSDEs was firstly investigated in the recent paper [5]. In this article, the authors consider superquadratic BSDEs when the terminal condition is bounded and the generator is convex in $z$. Firstly, they show that in a general way the problem is ill-posed: given a superquadratic generator, there exists a bounded terminal condition such that the associated BSDE does not admit any bounded solution and, on the other hand, if the BSDE admits a bounded solution, there exist infinitely many bounded solutions for this BSDE. In the same paper, the authors also show that the problem becomes

[^0]well-posed in a Markovian framework: when the terminal condition and the generator are deterministic functions of a forward SDE, we have an existence result. More precisely, let us consider ( $X, Y, Z$ ) the solution to the (decoupled) forward backward system
\[

$$
\begin{aligned}
X_{t} & =x+\int_{0}^{t} b\left(s, X_{s}\right) d s+\int_{0}^{t} \sigma(s) d W_{s} \\
Y_{t} & =g\left(X_{T}\right)+\int_{t}^{T} f\left(s, X_{s}, Y_{s}, Z_{s}\right) d s-\int_{t}^{T} Z_{s} d W_{s}
\end{aligned}
$$
\]

with growth assumptions

$$
\begin{aligned}
|f(t, x, y, z)| & \leqslant C\left(1+|x|^{p_{f}}+|y|+|z|^{l+1}\right), \quad l>1 \\
|g(x)| & \leqslant C\left(1+|x|^{p_{g}}\right)
\end{aligned}
$$

In [5], the authors obtain an existence result by assuming that $p_{g}=p_{f}=0, f$ is a convex function that depends only on $z$ and $g$ is a lower (or upper) semi-continuous function. As in the quadratic case it is possible to show that the boundedness of the terminal condition is a too strong assumption: in [17], the author shows an existence and uniqueness result by assuming that $p_{g} \leqslant 1+1 / l, p_{f} \leqslant 1+1 / l, f$ and $g$ are locally Lipschitz functions with respect to $x$ and $z$. When we consider this result, two questions arise:

- Could we have an existence result when $p_{g}$ or $p_{f}$ is greater than $1+1 / l$ ?
- Could we have an existence result when $f$ or $g$ is less smooth with respect to $x$ or $z$, that is to say, is it possible to have assumptions on the growth of $g$ and $f$ but not on the growth of their derivatives with respect to $x$ and $z$ ?

For the first question, the answer is clearly "no" in the quadratic case: see e.g. [6]. In the superquadratic case, the authors of [10] have obtained the same limitation on the growth of the initial condition for the so-called generalized deterministic KPZ equation $u_{t}=u_{x x}+\lambda\left|u_{x}\right|^{q}$ and they show that this boundary is sharp for power-type initial conditions. So, it seems that the answer of the first question is also "no" in the superquadratic case.

For the second question, the answer is clearly "yes" in the quadratic case. Indeed, a smoothness assumption on $f$ is required for uniqueness results (see e.g. [3, 6]) but not for existence results (see e.g. [3, 1]). In the superquadratic case, the authors of [5] show an existence result when $g$ is only lower (or upper) semi-continuous but also bounded. Nevertheless $f(z)$ is assumed to be convex, that implies that it is a locally Lipschitz function. The aim of this note is to mix results of articles [5, 17] to obtain an existence result when the terminal condition is only lower (or upper) semi-continuous and unbounded. Let us remark that we answer only partially to the second question because we do not relax smoothness assumptions on $f$.

For completeness, in the paper [4], Cheridito and Stadje show an existence and uniqueness result for superquadratic BSDEs in a Lipschitz or bounded "path-dependent" framework: the terminal condition and the generator are Lipschitz or bounded functions of Brownian motion paths. To the best of our knowledge, [5, 17, 4] are the only papers that deal with superquadratic BSDEs.

The paper is organized as follows. In section 2 we obtain some general a priori estimates on $Y$ and $Z$ for Markovian superquadratic BSDEs whereas section 3 is devoted to the existence result described before.

Notations Throughout this paper, $\left(W_{t}\right)_{t \geqslant 0}$ will denote a $d$-dimensional Brownian motion, defined on a probability space $(\Omega, \mathcal{F}, \mathbb{P})$. For $t \geqslant 0$, let $\mathcal{F}_{t}$ denote the $\sigma$-algebra
$\sigma\left(W_{s} ; 0 \leqslant s \leqslant t\right)$, augmented with the $\mathbb{P}$-null sets of $\mathcal{F}$. The Euclidean norm on $\mathbb{R}^{d}$ will be denoted by |.|. The operator norm induced by |.| on the space of linear operators is also denoted by |.|. The notation $\mathbb{E}_{t}$ stands for the conditional expectation given $\mathcal{F}_{t}$. For $p \geqslant 2, m \in \mathbb{N}$, we denote further

- $\mathcal{S}^{p}$ the space of real-valued, adapted and càdlàg processes $\left(Y_{t}\right)_{t \in[0, T]}$ normed by $\|Y\|_{\mathcal{S}^{p}}=\mathbb{E}\left[\left(\sup _{t \in[0, T]}\left|Y_{t}\right|\right)^{p}\right]^{1 / p}$;
- $\mathcal{M}^{p}\left(\mathbb{R}^{m}\right)$, or $\mathcal{M}^{p}$, the space of all progressively measurable processes $\left(Z_{t}\right)_{t \in[0, T]}$ with values in $\mathbb{R}^{m}$ normed by $\|Z\|_{\mathcal{M}^{p}}=\mathbb{E}\left[\left(\int_{0}^{T}\left|Z_{s}\right|^{2} d s\right)^{p / 2}\right]^{1 / p}$.

In the following, we keep the same notation $C$ for all finite, nonnegative constants that appear in our computations.

In this paper we consider $X$ the solution to the SDE

$$
\begin{equation*}
X_{t}=x+\int_{0}^{t} b\left(s, X_{s}\right) d s+\int_{0}^{t} \sigma(s) d W_{s} \tag{1.1}
\end{equation*}
$$

and $(Y, Z) \in \mathcal{S}^{2} \times \mathcal{M}^{2}$ the solution to the Markovian BSDE

$$
\begin{equation*}
Y_{t}=g\left(X_{T}\right)+\int_{t}^{T} f\left(s, X_{s}, Y_{s}, Z_{s}\right) d s-\int_{t}^{T} Z_{s} d W_{s} \tag{1.2}
\end{equation*}
$$

By a solution to the BSDE (1.2) we mean a pair $\left(Y_{t}, Z_{t}\right)_{t \in[0, T]}$ of predictable processes with values in $\mathbb{R} \times \mathbb{R}^{1 \times d}$ such that $\mathbb{P}$-a.s., $t \mapsto Y_{t}$ is continuous, $t \mapsto Z_{t}$ belongs to $L^{2}([0, T]), t \mapsto f\left(t, X_{t}, Y_{t}, Z_{t}\right)$ belongs to $L^{1}([0, T])$ and $\mathbb{P}-$ a.s. the equation (1.2) is verified.

## 2 Some a priori estimates on $Y$ and $Z$

For the SDE (1.1) we use standard assumption.

Assumption (F.1). Let $b:[0, T] \times \mathbb{R}^{d} \rightarrow \mathbb{R}^{d}$ and $\sigma:[0, T] \rightarrow \mathbb{R}^{d \times d}$ be continuous functions and let us assume that there exists $K_{b} \geqslant 0$ such that:
(a) $\forall t \in[0, T],|b(t, 0)| \leqslant C$,
(b) $\forall t \in[0, T], \forall\left(x, x^{\prime}\right) \in \mathbb{R}^{d} \times \mathbb{R}^{d},\left|b(t, x)-b\left(t, x^{\prime}\right)\right| \leqslant K_{b}\left|x-x^{\prime}\right|$.

Let us now consider the following assumptions on the generator and on the terminal condition of the BSDE (1.2).

Assumption (B.1). Let $f:[0, T] \times \mathbb{R}^{d} \times \mathbb{R} \times \mathbb{R}^{1 \times d} \rightarrow \mathbb{R}$ be a continuous function and let us assume that there exist five constants, $l>1,0 \leqslant r_{f}<\frac{1}{l}, \beta \geqslant 0, \gamma \geqslant 0$ and $\delta \geqslant 0$ such that:
(a) for each $\left(t, x, y, y^{\prime}, z\right) \in[0, T] \times \mathbb{R}^{d} \times \mathbb{R} \times \mathbb{R} \times \mathbb{R}^{1 \times d}$,

$$
\left|f(t, x, y, z)-f\left(t, x, y^{\prime}, z\right)\right| \leqslant \delta\left|y-y^{\prime}\right|
$$

(b) for each $\left(t, x, y, z, z^{\prime}\right) \in[0, T] \times \mathbb{R}^{d} \times \mathbb{R} \times \mathbb{R}^{1 \times d} \times \mathbb{R}^{1 \times d}$,

$$
\left|f(t, x, y, z)-f\left(t, x, y, z^{\prime}\right)\right| \leqslant\left(C+\frac{\gamma}{2}\left(|z|^{l}+\left|z^{\prime}\right|^{l}\right)\right)\left|z-z^{\prime}\right|
$$

(c) for each $\left(t, x, x^{\prime}, y, z\right) \in[0, T] \times \mathbb{R}^{d} \times \mathbb{R}^{d} \times \mathbb{R} \times \mathbb{R}^{1 \times d}$,

$$
\left|f(t, x, y, z)-f\left(t, x^{\prime}, y, z\right)\right| \leqslant\left(C+\frac{\beta}{2}\left(|x|^{r_{f}}+\left|x^{\prime}\right|^{r_{f}}\right)\right)\left|x-x^{\prime}\right|
$$

Assumption (TC.1). Let $g: \mathbb{R}^{d} \rightarrow \mathbb{R}$ be a continuous function and let us assume that there exist $0 \leqslant r_{g}<\frac{1}{l}$ and $\alpha \geqslant 0$ such that: for each $\left(t, x, x^{\prime}, y, z\right) \in[0, T] \times \mathbb{R}^{d} \times \mathbb{R}^{d} \times$ $\mathbb{R} \times \mathbb{R}^{1 \times d}$,

$$
\left|g(x)-g\left(x^{\prime}\right)\right| \leqslant\left(C+\frac{\alpha}{2}\left(|x|^{r_{g}}+\left|x^{\prime}\right|^{r_{g}}\right)\right)\left|x-x^{\prime}\right|
$$

We also use more general growth assumptions that are more natural for existence results.

Assumptions (B.2). Let $f:[0, T] \times \mathbb{R}^{d} \times \mathbb{R} \times \mathbb{R}^{1 \times d} \rightarrow \mathbb{R}$ be a continuous function and let us assume that there exist constants, $l>1,0 \leqslant r_{f}<\frac{1}{l}, \bar{\beta} \geqslant 0, \bar{\gamma} \geqslant 0, \bar{\delta} \geqslant 0,0 \leqslant \eta<l+1$, $\varepsilon>0$ such that: one of these inequalities holds, for all $(t, x, y, z) \in[0, T] \times \mathbb{R}^{d} \times \mathbb{R} \times \mathbb{R}^{1 \times d}$,
(a) $|f(t, x, y, z)| \leqslant C+\bar{\beta}|x|^{r_{f}+1}+\bar{\delta}|y|+\bar{\gamma}|z|^{l+1}$,
(b) $-C-\bar{\beta}|x|^{r_{f}+1}-\bar{\delta}|y|-\bar{\gamma}|z|^{\eta} \leqslant f(t, x, y, z) \leqslant C+\bar{\beta}|x|^{r_{f}+1}+\bar{\delta}|y|+\bar{\gamma}|z|^{l+1}$,
(c) $-C-\bar{\beta}|x|^{r_{f}+1}-\bar{\delta}|y|+\varepsilon|z|^{l+1} \leqslant f(t, x, y, z) \leqslant C+\bar{\beta}|x|^{r_{f}+1}+\bar{\delta}|y|+\bar{\gamma}|z|^{l+1}$.

Assumption (TC.2). Let $g: \mathbb{R}^{d} \rightarrow \mathbb{R}$ be a lower semi-continuous function and let us assume that there exist $0 \leqslant p_{g}<1+1 / l$ and $\bar{\alpha} \geqslant 0$ such that: for each $x \in \mathbb{R}^{d}$,

$$
|g(x)| \leqslant C+\bar{\alpha}|x|^{p_{g}}
$$

Remark 2.1. The following relations hold true:

- $(B .2)(c) \Rightarrow(B .2)(b) \Rightarrow(B .2)(a)$.
- $(B .1) \Rightarrow(B .2)(a)$.
- (TC.1) $\Rightarrow$ (TC.2) with $p_{g}=r_{g}+1$.
- We only consider superquadratic BSDEs, so $l>1$. $l=1$ corresponds to the quadratic case.

Firstly, let us recall the existence and uniqueness result shown in [17].
Proposition 2.2. We assume that (F.1), (B.1) and (TC.1) hold. There exists a solution $(Y, Z)$ of the Markovian BSDE (1.2) in $\mathcal{S}^{2} \times \mathcal{M}^{2}$ such that,

$$
\begin{equation*}
\left|Z_{t}\right| \leqslant A+B\left(\left|X_{t}\right|^{r_{g}}+(T-t)\left|X_{t}\right|^{r_{f}}\right), \quad \forall t \in[0, T] . \tag{2.1}
\end{equation*}
$$

Moreover, this solution is unique amongst solutions $(Y, Z)$ such that

- $Y \in \mathcal{S}^{2}$,
- there exists $\eta>0$ such that

$$
\mathbb{E}\left[e^{\left(\frac{1}{2}+\eta\right) \frac{\gamma^{2}}{4} \int_{0}^{T}\left|Z_{s}\right|^{2 l} d s}\right]<+\infty
$$

Remark 2.3. To be precise, in the Proposition 2.2 of the article [17] the author shows the estimate

$$
\left|Z_{t}\right| \leqslant A+B\left|X_{t}\right|^{r_{g} \vee r_{f}}, \quad \forall t \in[0, T]
$$

but it is rather easy to do the proof again to show the estimate (2.1) given in Proposition 2.2.

Such a result allows us to obtain a comparison result.

## Existence of solutions to superquadratic BSDEs

Proposition 2.4. We assume that (F.1) holds. Let $f_{1}, f_{2}$ two generators and $g_{1}, g_{2}$ two terminal conditions such that (B.1) and (TC.1) hold. Let $\left(Y^{1}, Z^{1}\right)$ and $\left(Y^{2}, Z^{2}\right)$ be the associated solutions given by Proposition 2.2. We assume that $g_{1} \leqslant g_{2}$ and $f_{1} \leqslant f_{2}$. Then we have that $Y^{1} \leqslant Y^{2}$ almost surely.

Proof of Proposition 2.4. The proof is the same than the classical one that can be found in [7] for example. Let us set $\delta Y:=Y^{1}-Y^{2}$ and $\delta Z:=Z^{1}-Z^{2}$. The usual linearization trick gives us
$\delta Y_{t}=g_{1}\left(X_{T}\right)-g_{2}\left(X_{T}\right)+\int_{t}^{T} f_{1}\left(s, X_{s}, Y_{s}^{1}, Z_{s}^{1}\right)-f_{2}\left(s, X_{s}, Y_{s}^{1}, Z_{s}^{1}\right)+\delta Y_{s} U_{s}+\delta Z_{s} V_{s} d s-\int_{t}^{T} \delta Z_{s} d W_{s}$,
with $\left|U_{s}\right| \leqslant \delta$ and

$$
\left|V_{s}\right| \leqslant C+\frac{\gamma}{2}\left(\left|Z_{s}^{1}\right|^{l}+\left|Z_{s}^{2}\right|^{l}\right) \leqslant C\left(1+\left|X_{s}\right|^{\left(r_{g} \vee r_{f}\right) l}\right)
$$

Since $\left(r_{g} \vee r_{f}\right) l<1$, Novikov's condition is fulfilled and we are allowed to apply Girsanov's transformation:

$$
\begin{aligned}
\delta Y_{t} & =\mathbb{E}_{t}^{\mathrm{Q}}\left[e^{\int_{t}^{T} U_{u} d u}\left(g_{1}\left(X_{T}\right)-g_{2}\left(X_{T}\right)\right)+\int_{t}^{T} e^{\int_{t}^{s} U_{u} d u}\left(f_{1}\left(s, X_{s}, Y_{s}^{1}, Z_{s}^{1}\right)-f_{2}\left(s, X_{s}, Y_{s}^{1}, Z_{s}^{1}\right)\right) d s\right] \\
& \leqslant 0
\end{aligned}
$$

with

$$
\frac{d \mathbb{Q}}{d \mathbb{P}}=\exp \left(\int_{0}^{T} V_{s} d W_{s}-\frac{1}{2} \int_{0}^{T}\left|V_{s}\right|^{2} d s\right)
$$

Now we are ready to prove estimates on $Y$ and $Z$.
Proposition 2.5. Let us assume that (F.1), (B.1), (B.2), (TC.1) and (TC.2) hold. Let $(Y, Z)$ be the solution of the BSDE (1.2) given by Proposition 2.2. Then we have, for all $t \in[0, T]$,

$$
\left|Y_{t}\right| \leqslant C\left(1+\left|X_{t}\right|^{p_{g}}+(T-t)\left|X_{t}\right|^{r_{f}+1}\right)
$$

with a constant $C$ that depends on constants that appear in assumptions (F.1), (B.2) and (TC.2) but not in assumptions (B.1) and (TC.1).

Proof of Proposition 2.5. Let us consider the terminal condition

$$
\bar{g}(x)=C+\bar{\alpha}(|x|+1)^{p_{g}},
$$

and the generator

$$
\bar{f}(t, x, y, z)=C+\bar{\beta}|x|^{r_{f}+1}+\bar{\delta}|y|+\bar{\gamma}|z|^{l+1}
$$

with $C$ such that $g \leqslant \bar{g}$ and $f \leqslant \bar{f}$. (B.1) holds for $\bar{f}$ and (TC.1) holds for $\bar{g}$, so, according to Proposition 2.2, there exists a unique solution $(\bar{Y}, \bar{Z})$ to the BSDE

$$
\bar{Y}_{t}=\bar{g}\left(X_{T}\right)+\int_{t}^{T} \bar{f}\left(s, X_{s}, \bar{Y}_{s}, \bar{Z}_{s}\right) d s-\int_{t}^{T} \bar{Z}_{s} d W_{s}
$$

Thanks to Proposition 2.4, we know that

$$
Y \leqslant \bar{Y}, \quad \text { and } \quad \bar{Y} \geqslant 0
$$

Moreover, since $\left|\bar{Z}_{s}\right| \leqslant C\left(1+\left|X_{s}\right|^{\left(p_{g}-1\right) \vee r_{f}}\right),\left(p_{g}-1\right) l<1$ and $r_{f} l<1$, we have

$$
\begin{aligned}
\bar{Y}_{t} & \leqslant \mathbb{E}_{t}\left[e^{\bar{\delta}(T-t)}\left(C+\bar{\alpha}\left(\left|X_{t}\right|+1\right)^{p_{g}}\right)+\int_{t}^{T} e^{\bar{\delta}(s-t)}\left(C+\bar{\beta}\left|X_{s}\right|^{r_{f}+1}+\bar{\gamma}\left|\bar{Z}_{s}\right|^{l+1}\right) d s\right] \\
& \leqslant C\left(1+\mathbb{E}_{t}\left[\sup _{t \leqslant s \leqslant T}\left|X_{s}\right|^{p_{g}}\right]+(T-t) \mathbb{E}_{t}\left[\sup _{t \leqslant s \leqslant T}\left|X_{s}\right|^{r_{f}+1}\right]\right) .
\end{aligned}
$$

Let us remark that the constant $C$ in the a priori estimate for $\bar{Z}$ depends on constants that appear in assumptions (F.1), (B.2) and (TC.2) but not in assumptions (B.1) and (TC.1). Thanks to classical estimates on SDEs we have, for all $p \geqslant 1$,

$$
\mathbb{E}_{t}\left[\sup _{t \leqslant s \leqslant T}\left|X_{s}\right|^{p}\right] \leqslant C\left(1+\left|X_{t}\right|^{p}\right)
$$

so we obtain

$$
Y_{t} \leqslant \bar{Y}_{t} \leqslant C\left(1+\left|X_{t}\right|^{p_{g}}+(T-t)\left|X_{t}\right|^{r_{f}+1}\right)
$$

By the same type of argument we easily show that

$$
-C\left(1+\left|X_{t}\right|^{p_{g}}+(T-t)\left|X_{t}\right|^{r_{f}+1}\right) \leqslant Y_{t},
$$

and this concludes the proof.
Proposition 2.6. Let us assume that (F.1), (B.1), (B.2)(c), (TC.1) and (TC.2) hold. Let $(Y, Z)$ be the solution of the BSDE (1.2) given by Proposition 2.2. Then, for all $t \in[0, T]$, we have

$$
\mathbb{E}_{t}\left[\int_{t}^{T}\left|Z_{s}\right|^{l+1} d s\right] \leqslant C\left(1+\left|X_{t}\right|^{p_{g}}+(T-t)\left|X_{t}\right|^{r_{f}+1}\right)
$$

with a constant $C$ that depends on constants that appear in assumptions (F.1), (B.2)(c) and (TC.2) but not in assumptions (B.1) and (TC.1).
Proof of Proposition 2.6. To show the proposition we just have to write

$$
\begin{aligned}
\mathbb{E}_{t}\left[\int_{t}^{T}\left|Z_{s}\right|^{l+1} d s\right] & \leqslant \frac{1}{\varepsilon}\left(\mathbb{E}_{t}\left[\int_{t}^{T} f\left(s, X_{s}, Y_{s}, Z_{s}\right) d s+\int_{t}^{T}\left(C+\bar{\beta}\left|X_{s}\right|^{r_{f}+1}+\bar{\delta}\left|Y_{s}\right|\right) d s\right]\right) \\
& \leqslant \frac{1}{\varepsilon}\left(\mathbb{E}_{t}\left[Y_{t}-g\left(X_{T}\right)+\int_{t}^{T} C+\bar{\beta}\left|X_{s}\right|^{r_{f}+1}+\bar{\delta}\left|Y_{s}\right| d s\right]\right) \\
& \leqslant C\left(1+(T-t)\left|X_{t}\right|^{r_{f}+1}+\left|X_{t}\right|^{p_{g}}\right)
\end{aligned}
$$

thanks to Proposition 2.5.
Remark 2.7. Proposition 2.6 stays true if we replace assumption (B.2)(c) by

$$
-C-\bar{\beta}|x|^{r_{f}+1}-\bar{\delta}|y|-\bar{\gamma}|z|^{l+1} \leqslant f(t, x, y, z) \leqslant C+\bar{\beta}|x|^{r_{f}+1}+\bar{\delta}|y|-\varepsilon|z|^{l+1}
$$

Remark 2.8. In Propositions 2.5 and 2.6 we insist on the fact that $C$ does not depend on constants that appear in assumptions (B.1) and (TC.1) when the local Lipschitzianity of the coefficients is stated. Thanks to this property, we can use these a priori estimates on $Y$ and $Z$ in the following section where we obtain an existence result when the terminal condition is not locally Lipschitz.

## 3 An existence result

Let us now introduce new assumptions.

Assumption (F.2). $b$ is differentiable with respect to $x$ and $\sigma$ is differentiable with respect to $t$. There exists $\lambda \in \mathbb{R}^{+}$such that $\forall \eta \in \mathbb{R}^{d}$

$$
\left|{ }^{t} \eta \sigma(s)\left[^{t} \sigma(s)^{t} \nabla b(s, x)-{ }^{t} \sigma^{\prime}(s)\right] \eta\right| \leqslant \lambda\left|{ }^{t} \eta \sigma(s)\right|^{2}, \quad \forall(s, x) \in[0, T] \times \mathbb{R}^{d}
$$

Remark 3.1. It is shown in part 5.5.1 of [18] that if $\sigma$ does not depend on time, assumption (F.2) is equivalent to this kind of commutativity assumption:

- there exist $A:[0, T] \times \mathbb{R}^{d} \rightarrow \mathbb{R}^{d \times d}$ and $B:[0, T] \rightarrow \mathbb{R}^{d \times d}$ such that $A$ is differentiable with respect to $x, \nabla_{x} A$ is bounded and $\forall x \in \mathbb{R}^{d}, \forall s \in[0, T], b(s, x) \sigma=\sigma A(s, x)+$ $B(s)$.

It is also noticed in [18] that this assumption allows us to reduce assumption on the regularity of $b$ by a standard smooth approximation of $A$.

Assumption (B.3). $\quad f$ is differentiable with respect to $z$ and for all $(t, x, y, z) \in[0, T] \times$ $\mathbb{R}^{d} \times \mathbb{R} \times \mathbb{R}^{1 \times d}$,

$$
f(t, x, y, z)-\left\langle\nabla_{z} f(t, x, y, z), z\right\rangle \leqslant C-\varepsilon|z|^{l+1}
$$

Remark 3.2. Let us give some substantial examples of functions such that (B.3) holds. If we assume that $f(t, x, y, z):=f_{1}(t, x, y, z)+f_{2}(t, x, y, z)$ with $f_{1}$ a differentiable function with respect to $z$ such that, $\exists p \in\left[0, l\left[, \forall(t, x, y, z) \in[0, T] \times \mathbb{R}^{d} \times \mathbb{R} \times \mathbb{R}^{1 \times d}\right.\right.$,

$$
\left|\nabla_{z} f_{1}(t, x, y, z)\right| \leqslant\left(1+|z|^{p}\right)
$$

and $f_{2}$ is a twice differentiable function with respect to $z$ such that, $\forall(t, x, y, z) \in[0, T] \times$ $\mathbb{R}^{d} \times \mathbb{R} \times \mathbb{R}^{1 \times d}, \forall u \in \mathbb{R}^{d}$,

$$
{ }^{t} u \nabla_{z z}^{2} f_{2}(t, x, y, z) u \geqslant\left(-C+\varepsilon|z|^{l-1}\right)|u|^{2},
$$

then we easily see that

$$
f_{1}(t, x, y, z)-\left\langle\nabla_{z} f_{1}(t, x, y, z), z\right\rangle \leqslant C+C|z|^{p+1}
$$

and a direct application of Taylor expansion with integral form gives us

$$
f_{2}(t, x, y, z)-\left\langle\nabla_{z} f_{2}(t, x, y, z), z\right\rangle \leqslant C-C^{\prime}|z|^{l+1}
$$

so (B.3) holds. For example, (B.3) holds for the function $z \mapsto C|z|^{l+1}+h\left(|z|^{l+1-\eta}\right)$ with $C>0,0<\eta \leqslant l+1$ and $h$ a differentiable function with a bounded derivative.

Proposition 3.3. Let us assume that (F.1), (F.2), (B.1), (B.3), (TC.1) and (TC.2) hold. Let $(Y, Z)$ be the solution of the BSDE (1.2) given by Proposition 2.2. If we assume that $0 \leqslant p_{g} l<1$, then we have, for all $t \in[0, T[$,

$$
\left|Z_{t}\right| \leqslant \frac{C\left(1+\left|X_{t}\right|^{p_{g} /(l+1)}\right)}{(T-t)^{1 /(l+1)}}+C\left|X_{t}\right|^{\frac{r_{f}+1}{l+1}}
$$

The constant $C$ depends on constants that appear in assumptions (F.1), (F.2), (B.1), (B.3) and (TC.2) but not in assumption (TC.1).

Proof of Proposition 3.3. Firstly we approximate our Markovian BSDE by another one. Let $\left(Y^{M}, Z^{M}\right)$ the solution of the BSDE

$$
\begin{equation*}
Y_{t}^{M}=g_{M}\left(X_{T}\right)+\int_{t}^{T} f_{M}\left(s, X_{s}, Y_{s}^{M}, Z_{s}^{M}\right) d s-\int_{t}^{T} Z_{s}^{M} d W_{s} \tag{3.1}
\end{equation*}
$$

with $g_{M}=g \circ \rho_{M}$ and $f_{M}=f\left(., \rho_{M}(),. .,.\right)$ where $\rho_{M}$ is a smooth modification of the projection on the centered Euclidean ball of radius $M$ such that $\left|\rho_{M}\right| \leqslant M,\left|\nabla \rho_{M}\right| \leqslant 1$ and $\rho_{M}(x)=x$ when $|x| \leqslant M-1$. It is now easy to see that $g_{M}$ and $f_{M}$ are Lipschitz functions with respect to $x$. Proposition 2.3 in [17] gives us that $Z^{M}$ is bounded by a constant $C_{0}$ that depends on $M$. So, $f_{M}$ is a Lipschitz function with respect to $z$ and BSDE (3.1) is a classical Lipschitz BSDE. Now we use the following Lemma that will be shown afterwards.

Lemma 3.4. Let us assume that (F.1), (F.2), (B.1), (B.3), (TC.1) and (TC.2) hold. We also assume that $0 \leqslant p_{g} l<1$. Then we have, for all $t \in[0, T[$,

$$
\left|Z_{t}^{M}\right| \leqslant \frac{A_{n}+B_{n}\left|X_{t}\right|^{p_{g} /(l+1)}}{(T-t)^{1 /(l+1)}}+D_{n}\left|X_{t}\right|^{\frac{r_{f}+1}{l+1}}
$$

with $\left(A_{n}, B_{n}, D_{n}\right)_{n \in \mathbb{N}}$ defined by recursion: $B_{0}=0, D_{0}=0, A_{0}=C_{0} T^{1 /(l+1)}$,

$$
A_{n+1}=C\left(1+A_{n}^{a l}+B_{n}^{a l p}+D_{n}^{a l \bar{p}}\right), \quad B_{n+1}=C, \quad D_{n+1}=C
$$

where $a:=\left(p_{g} \vee\left(r_{f}+1\right)\right) /(l+1), p>1, \bar{p}>1$ and $C$ is a constant that does not depend on $M$ and constants in assumption (TC.1).

Since al $<1$, the recursion function that define the sequence $\left(A_{n}\right)_{n \geqslant 0}$ is a contractor function, so $A_{n} \rightarrow A_{\infty}$ when $n \rightarrow+\infty$, with $A_{\infty}$ that does not depend on $M$ and constants in assumption (TC.1). Finally, we have, for all $t \in[0, T[$,

$$
\left|Z_{t}^{M}\right| \leqslant \frac{C\left(1+\left|X_{t}\right|^{p_{g} /(l+1)}\right)}{(T-t)^{1 /(l+1)}}+C\left|X_{t}\right|^{\frac{r_{f}+1}{l+1}}
$$

The constant $C$ depends on constants that appear in assumptions (F.1), (F.2), (B.1), (B.3) and (TC.2) but not in assumption (TC.1). Moreover $C$ does not depends on $M$. Now, we want to come back to the initial BSDE (1.2). It is already shown in the proof of Proposition 2.2 of the article [17] that $\left(Y^{n}, Z^{n}\right) \rightarrow(Y, Z)$ in $\mathcal{S}^{2} \times \mathcal{M}^{2}$. So our estimate on $Z^{M}$ stays true for a version of $Z$.

Proof of Lemma 3.4. Let us prove the result by recursion. For $n=0$ we have already shown the result. Let us assume that the result is true for some $n \in \mathbb{N}$ and let us show that it stays true for $n+1$. In a first time we suppose that $f$ and $g$ are differentiable with respect to $x$ and $y$. Then $\left(Y^{M}, Z^{M}\right)$ is differentiable with respect to $x$ and $\left(\nabla Y^{M}, \nabla Z^{M}\right)$ is the solution of the BSDE

$$
\begin{aligned}
\nabla Y_{t}^{M}= & \nabla g_{M}\left(X_{T}\right) \nabla X_{T}-\int_{t}^{T} \nabla Z_{s}^{M} d W_{s}+\int_{t}^{T} \nabla_{x} f_{M}\left(s, X_{s}, Y_{s}^{M}, Z_{s}^{M}\right) \nabla X_{s} d s \\
& +\int_{t}^{T} \nabla_{y} f_{M}\left(s, X_{s}, Y_{s}^{M}, Z_{s}^{M}\right) \nabla Y_{s}^{M}+\nabla_{z} f_{M}\left(s, X_{s}, Y_{s}^{M}, Z_{s}^{M}\right) \nabla Z_{s}^{M} d s
\end{aligned}
$$

and a version of $Z^{M}$ is given by $\left(\nabla Y_{t}^{M}\left(\nabla X_{t}\right)^{-1} \sigma(t)\right)_{t \in[0, T]}$. Let us introduce some notations: we set

$$
\begin{aligned}
d \tilde{W}_{t} & :=d W_{t}-\nabla_{z} f_{M}\left(t, X_{t}, Y_{t}^{M}, Z_{t}^{M}\right) d t \\
\alpha_{t} & :=\int_{0}^{t} e^{\int_{0}^{s} \nabla_{y} f_{M}\left(u, X_{u}, Y_{u}^{M}, Z_{u}^{M}\right) d u} \nabla_{x} f_{M}\left(s, X_{s}, Y_{s}^{M}, Z_{s}^{M}\right) \nabla X_{s} d s\left(\nabla X_{t}\right)^{-1} \sigma(t), \\
\tilde{Z}_{t}^{M} & :=e^{\int_{0}^{t} \nabla_{y} f_{M}\left(s, X_{s}, Y_{s}^{M}, Z_{s}^{M}\right) d s} Z_{t}^{M}+\alpha_{t}
\end{aligned}
$$

By applying Girsanov's theorem we know that there exists a probability $\mathbb{Q}^{M}$ under which $\tilde{W}$ is a Brownian motion with

$$
\frac{d \mathbb{Q}^{M}}{d \mathbb{P}}=\exp \left(\int_{0}^{T} \nabla_{z} f_{M}\left(t, X_{t}, Y_{t}^{M}, Z_{t}^{M}\right) d W_{t}-\frac{1}{2} \int_{0}^{T}\left|\nabla_{z} f_{M}\left(t, X_{t}, Y_{t}^{M}, Z_{t}^{M}\right)\right|^{2} d t\right)
$$

Then, exactly as in the proof of Theorem 3.3 in [16], we can show the following lemma.
Lemma 3.5. $\left|e^{\lambda t} \tilde{Z}_{t}^{M}\right|^{2}$ is a $\mathbb{Q}^{M}$-submartingale.
For the reader's convenience, we recall this proof in the appendix. It results that $\left|e^{\lambda t} \tilde{Z}_{t}^{M}\right|^{l+1}$ is also a $\mathbb{Q}^{M}$-submartingale and we have:

$$
\begin{aligned}
\mathbb{E}_{t}^{\mathrm{Q}^{M}}\left[\int_{t}^{T} e^{2 \lambda s}\left|\tilde{Z}_{s}^{M}\right|^{l+1} d s\right] & \geqslant e^{2 \lambda t}\left|\tilde{Z}_{t}^{M}\right|^{l+1}(T-t) \\
& \geqslant e^{2 \lambda t}\left|e^{\int_{0}^{t} \nabla_{y} f_{M}\left(s, X_{s}, Y_{s}^{M}, Z_{s}^{M}\right) d s} Z_{t}^{M}+\alpha_{t}\right|^{l+1}(T-t)
\end{aligned}
$$

which implies

$$
\begin{align*}
& \left|Z_{t}^{M}\right|^{l+1}(T-t) \\
\leqslant & C\left(e^{2 \lambda t}\left|e^{\int_{0}^{t} \nabla_{y} f_{M}\left(s, X_{s}, Y_{s}^{M}, Z_{s}^{M}\right) d s} Z_{t}^{M}+\alpha_{t}\right|^{l+1}+\left|\alpha_{t}\right|^{l+1}\right)(T-t) \\
\leqslant & C\left(\mathbb{E}_{t}^{\mathrm{Q}^{M}}\left[\int_{t}^{T} e^{2 \lambda s}\left|\tilde{Z}_{s}^{M}\right|^{l+1} d s\right]+(T-t)\left(1+\left|X_{t}\right|^{(l+1) r_{f}}\right)\right) \\
\leqslant & C\left(1+\mathbb{E}_{t}^{\mathrm{Q}^{M}}\left[\int_{t}^{T}\left|Z_{s}^{M}\right|^{l+1} d s\right]+\mathbb{E}_{t}^{\mathrm{Q}^{M}}\left[\int_{t}^{T}\left|X_{s}\right|^{(l+1) r_{f}} d s\right]+(T-t)\left|X_{t}\right|^{(l+1) r_{f}}\right) . \tag{3.2}
\end{align*}
$$

Let us recall that $\left(Y^{M}, Z^{M}\right)$ is solution of BSDE

$$
Y_{t}^{M}=g_{M}\left(X_{T}\right)+\int_{t}^{T} \tilde{f}_{M}\left(s, X_{s}, Y_{s}^{M}, Z_{s}^{M}\right) d s-\int_{t}^{T} Z_{s}^{M} d \tilde{W}_{s}
$$

with

$$
\tilde{f}_{M}(s, x, y, z):=f_{M}(s, x, y, z)-\left\langle z, \nabla_{z} f_{M}(s, x, y, z)\right\rangle
$$

Since assumption (B.3) holds for $f$, assumption (B.2)(c) holds for $-\tilde{f}_{M}$ with constants that do not depend on $M$. Then we can mimic the proof of Proposition 2.6 (see also Remark 2.7) to show that
$\mathbb{E}_{t}^{\mathrm{Q}^{M}}\left[\int_{t}^{T}\left|Z_{s}^{M}\right|^{l+1} d s\right] \leqslant C\left(1+\mathbb{E}_{t}^{\mathrm{Q}^{M}}\left[\left|X_{T}\right|^{p_{g}}\right]+\int_{t}^{T}\left(\mathbb{E}_{t}^{\mathrm{Q}^{M}}\left[\left|X_{s}\right|^{p_{g}}\right]+\mathbb{E}_{t}^{\mathrm{Q}^{M}}\left[\left|X_{s}\right|^{r_{f}+1}\right]\right) d s\right)$,
with a constant $C$ that does not depend on $M$ and constants that appear in assumption (TC.1). Then, by putting (3.3) in (3.2), we see that we just have to obtain an a priori estimate for $\mathbb{E}_{t}^{Q^{M}}\left[\left|X_{s}\right|^{c}\right]$ with $c \in \mathbb{R}^{+*}$. We have

$$
\begin{aligned}
\left|X_{s}\right| & =\left|X_{t}+\int_{t}^{s} b\left(u, X_{u}\right) d u+\int_{t}^{s} \sigma(u) d \tilde{W}_{u}+\int_{t}^{s} \sigma(u) \nabla_{z} f_{M}\left(u, X_{u}, Y_{u}^{M}, Z_{u}^{M}\right) d u\right| \\
& \leqslant\left|X_{t}\right|+C+C \int_{t}^{s}\left|X_{u}\right| d u+\left|\int_{t}^{s} \sigma(u) d \tilde{W}_{u}\right|+C \int_{t}^{s}\left|Z_{u}^{M}\right|^{l} d u
\end{aligned}
$$

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with $C$ that does not depend on $M$. Now we use the recursion assumption to obtain
$\int_{t}^{s}\left|Z_{u}^{M}\right|^{l} d u \leqslant C \int_{t}^{s}\left(\frac{A_{n}^{l}}{(T-u)^{l /(l+1)}}+\frac{B_{n}^{l}}{(T-u)^{l /(l+1)}}\left|X_{u}\right|^{l p_{g} /(l+1)}+D_{n}^{l}\left|X_{u}\right|^{\left(r_{f}+1\right) l /(l+1)}\right) d u$.
Obviously we have $\int_{t}^{T} \frac{A_{n}^{l}}{(T-u)^{l}(l+1)} d u \leqslant C A_{n}^{l}$. For the other terms we use Young inequality: Since $l p_{g} /(l+1)<1$ and $\left(r_{f}+1\right) l /(l+1)<1$, we have

$$
\int_{t}^{s}\left|Z_{u}^{M}\right|^{l} d u \leqslant C A_{n}^{l}+C \int_{t}^{s}\left(\frac{B_{n}^{l p}}{(T-u)^{l p /(l+1)}}+D_{n}^{l \bar{p}}+\left|X_{u}\right|\right) d u
$$

with $p=1 /\left(1-l p_{g} /(l+1)\right)$ and $\bar{p}>1$. Since we assume that $l p_{g}<1$, then $l p /(l+1)<1$ and $\int_{t}^{s} \frac{B_{n}^{l_{p}}}{(T-u)^{l_{p /(l+1)}}} d u \leqslant C B_{n}^{l p}$. Finally, we obtain

$$
\int_{t}^{s}\left|Z_{u}^{M}\right|^{l} d u \leqslant C A_{n}^{l}+C B_{n}^{l p}+C D_{n}^{l \bar{p}}+C \int_{t}^{s}\left|X_{u}\right| d u
$$

and

$$
\left|X_{s}\right| \leqslant\left|X_{t}\right|+C+C \int_{t}^{s}\left|X_{u}\right| d u+\sup _{t \leqslant r \leqslant T}\left|\int_{t}^{r} \sigma(u) d \tilde{W}_{u}\right|+C A_{n}^{l}+C B_{n}^{l p}+C D_{n}^{l \bar{p}}
$$

Gronwall's lemma gives us

$$
\left|X_{s}\right| \leqslant C\left(1+\sup _{t \leqslant r \leqslant T}\left|\int_{t}^{r} \sigma(u) d \tilde{W}_{u}\right|+A_{n}^{l}+B_{n}^{l p}+D_{n}^{l \bar{p}}+\left|X_{t}\right|\right)
$$

that implies

$$
\begin{equation*}
\mathbb{E}_{t}^{\mathrm{Q}^{M}}\left[\left|X_{s}\right|^{c}\right] \leqslant C\left(1+A_{n}^{c l}+B_{n}^{c l p}+D_{n}^{c l \bar{p}}+\left|X_{t}\right|^{c}\right) . \tag{3.4}
\end{equation*}
$$

By putting (3.4) in (3.3) and (3.2), we obtain

$$
\begin{aligned}
\left|Z_{t}^{M}\right|^{l+1}(T-t) & \leqslant C\left(1+\mathbb{E}_{t}^{\mathrm{Q}^{M}}\left[\left|X_{T}\right|^{p_{g}}\right]+\int_{t}^{T} \mathbb{E}_{t}^{\mathrm{Q}^{M}}\left[\left|X_{s}\right|^{p_{g} \vee\left(r_{f}+1\right)}\right] d s+(T-t)\left|X_{t}\right|^{(l+1) r_{f}}\right) \\
& \leqslant C\left(1+A_{n}^{(l+1) a l}+B_{n}^{(l+1) a l p}+D_{n}^{(l+1) a l \bar{p}}+\left|X_{t}\right|^{p_{g}}+(T-t)\left|X_{t}\right|^{r_{f}+1}\right),
\end{aligned}
$$

with $a=\left(p_{g} \vee\left(r_{f}+1\right)\right) /(l+1)$ and $C$ that does not depend on $M$ and constants that appear in assumption (TC.1). So, we easily see that we can take

$$
A_{n+1}=C\left(1+A_{n}^{a l}+B_{n}^{a l p}+D_{n}^{a l \bar{p}}\right), \quad B_{n+1}=C, \quad D_{n+1}=C,
$$

and then the result is proved.
When $f$ and $g$ are not differentiable we can prove the result by a standard approximation and stability results for BSDEs with linear growth.

Since the estimate on $Z$ given by Proposition 3.3 does not depend on constants that appear in assumption (TC.1), we can use it to show an existence result for superquadratic BSDEs with a quite general terminal condition.

Theorem 3.6 (Existence result for superquadratic BSDEs). Let assume that (F.1), (F.2), (B.1), (B.2)(b), (B.3) and (TC.2) hold. We also assume that $0 \leqslant p_{g} l<1$, then there exists a solution $(Y, Z)$ to the $B S D E$ (1.2) such that $(Y, Z) \in \mathcal{S}^{2} \times \mathcal{M}^{2}$. Moreover, we have for all $t \in[0, T[$,

$$
\begin{equation*}
\left|Z_{t}\right| \leqslant \frac{C\left(1+\left|X_{t}\right|^{p_{g} /(l+1)}\right)}{(T-t)^{1 /(l+1)}}+C\left|X_{t}\right|^{\frac{r_{f}+1}{l+1}} \tag{3.5}
\end{equation*}
$$

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and, if we assume that (B.2)(c) holds,

$$
\mathbb{E}\left[\int_{0}^{T}\left|Z_{s}\right|^{l+1} d s\right]<+\infty
$$

Proof of Theorem 3.6. The proof is based on the proof of Proposition 4.3 in [5]. For each integer $n \geqslant 0$, we construct the sup-convolution of $g$ defined by

$$
g_{n}(x):=\sup _{u \in \mathbb{R}^{d}}\{g(u)-n|x-u|\} .
$$

Let us recall some well-known facts about sup-convolution:
Lemma 3.7. For $n \geqslant n_{0}$ with $n_{0}$ big enough, we have,

- $g_{n}$ is well defined,
- (TC.1) holds for $g_{n}$ with $r_{g}=0$,
- (TC.2) holds for $g_{n}$ with same constants $C$ and $\bar{\alpha}$ than for $g$ (they do not depend on $n)$,
- $\left(g_{n}\right)_{n}$ is decreasing,
- $\left(g_{n}\right)_{n}$ converges pointwise to $g$.

Since (TC.1) holds, we can consider $\left(Y^{n}, Z^{n}\right)$ the solution given by Proposition 2.2. It follows from Propositions 2.4 and 2.5 that, for all $n \geqslant n_{0}$,
$-C\left(1+\left|X_{t}\right|^{p_{g}}+(T-t)\left|X_{t}\right|^{r_{f}+1}\right) \leqslant Y_{t}^{n+1} \leqslant Y_{t}^{n} \leqslant Y_{t}^{n_{0}} \leqslant C\left(1+\left|X_{t}\right|^{p_{g}}+(T-t)\left|X_{t}\right|^{r_{f}+1}\right)$,
with $C$ that does not depend on $n$ : indeed, the constant in Proposition 2.5 just depends on the growth of the terminal condition and here the growth of $g_{n}$ can be chosen independently of $n$ (see previous lemma). So $\left(Y_{n}\right)_{n}$ converges almost surely and we can define

$$
Y=\lim _{n \rightarrow+\infty} Y^{n}
$$

Passing to the limit into (3.6), we obtain that the estimate of Proposition 2.5 stays true for $Y$. Now the aim is to show that $\left(Z_{n}\right)_{n}$ converges in the good space. For any $\left.T^{\prime} \in\right] 0, T$, $\left(Y^{n}, Z^{n}\right)$ satisfies

$$
\begin{equation*}
Y_{t}^{n}=Y_{T^{\prime}}^{n}+\int_{t}^{T^{\prime}} f\left(s, X_{s}, Y_{s}^{n}, Z_{s}^{n}\right) d s-\int_{t}^{T^{\prime}} Z_{s}^{n} d W_{s}, \quad 0 \leqslant t \leqslant T^{\prime} \tag{3.7}
\end{equation*}
$$

Let us denote $\delta Y^{n, m}:=Y^{n}-Y^{m}$ and $\delta Z^{n, m}:=Z^{n}-Z^{m}$. The classical linearization method gives us that ( $\delta Y^{n, m}, \delta Z^{n, m}$ ) is the solution of BSDE

$$
\delta Y_{t}^{n, m}=\delta Y_{T^{\prime}}^{n, m}+\int_{t}^{T^{\prime}} U_{s}^{n, m} \delta Y_{s}^{n, m}+V_{s}^{n, m} \delta Z_{s}^{n, m} d s-\int_{t}^{T^{\prime}} \delta Z_{s}^{n, m} d W_{s}
$$

where $\left|U^{n, m}\right| \leqslant C$ and, by using estimates of Proposition 3.3,

$$
\begin{equation*}
\left|V^{n, m}\right| \leqslant C\left(1+\left|Z^{n}\right|^{l}+\left|Z^{m}\right|^{l}\right) \leqslant C\left(1+|X|^{p}\right) \tag{3.8}
\end{equation*}
$$

with $p<1$ and $C$ that depends on $T^{\prime}$ but does not depend on $n$ and $m$. Since $p<$ 1, Novikov's condition is fulfilled and we can apply Girsanov's theorem: there exists a probability $\mathbb{Q}^{n, m}$ such that $d \tilde{W}_{t}:=d W_{t}-V_{t}^{n, m} d t$ is a Brownian motion under this probability. By classical transformations, we have that ( $\delta Y^{n, m}, \delta Z^{n, m}$ ) is the solution of the BSDE

$$
\delta Y_{t}^{n, m}=\delta Y_{T^{\prime}}^{n, m} e^{\int_{t}^{T^{\prime}} U_{s}^{n, m} d s}-\int_{t}^{T^{\prime}} e^{\int_{t}^{s} U_{u}^{n, m} d u} \delta Z_{s}^{n, m} d \tilde{W}_{s}
$$

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Since $U^{n, m}$ is bounded, classical estimates on BSDEs give us (see e.g. [7])

$$
\begin{equation*}
\mathbb{E}^{\mathbb{Q}^{n, m}}\left[\left(\int_{0}^{T^{\prime}}\left|\delta Z_{s}^{n, m}\right|^{2} d s\right)^{2}\right] \leqslant C \mathbb{E}^{\mathbb{Q}^{n, m}}\left[\left|\delta Y_{T^{\prime}}^{n, m}\right|^{4}\right] . \tag{3.9}
\end{equation*}
$$

Now, we would like to have the same type of estimate than (3.9), but with the classical expectation instead of $\mathbb{E}^{\mathbb{Q}^{n, m}}$. To do so, we define the exponential martingale

$$
\mathcal{E}_{T^{\prime}}^{n, m}:=\exp \left(\int_{0}^{T^{\prime}} V_{s}^{n, m} d W_{s}-\frac{1}{2} \int_{0}^{T^{\prime}}\left|V_{s}^{n, m}\right|^{2} d s\right)
$$

Then, for all $p \in \mathbb{R}$,

$$
\begin{equation*}
\mathbb{E}\left[\left(\mathcal{E}_{T^{\prime}}^{n, m}\right)^{p}\right]<C_{p}, \tag{3.10}
\end{equation*}
$$

with $C_{p}$ that does not depend on $n$ and $m$ : indeed, by applying (3.8) and Gronwall's lemma we have

$$
\begin{aligned}
& \mathbb{E}\left[e^{p \int_{0}^{T^{\prime}} V_{s}^{n, m} d W_{s}-\frac{p}{2} \int_{0}^{T^{\prime}}\left|V_{s}^{n, m}\right|^{2} d s}\right] \\
= & \mathbb{E}\left[e^{\frac{1}{2}\left(\int_{0}^{T^{\prime}} 2 p V_{s}^{n, m} d W_{s}-\frac{1}{2} \int_{0}^{T^{\prime}}\left|2 p V_{s}^{n, m}\right|^{2} d s\right)+\left(p^{2}-\frac{p}{2}\right) \int_{0}^{T^{\prime}}\left|V_{s}^{n, m}\right|^{2} d s}\right] \\
\leqslant & \mathbb{E}\left[e^{\int_{0}^{T^{\prime}} 2 p V_{s}^{n, m} d W_{s}-\frac{1}{2} \int_{0}^{T^{\prime}}\left|2 p V_{s}^{n, m}\right|^{2} d s}\right]^{1 / 2} \mathbb{E}\left[e^{\left(2 p^{2}-p\right) \int_{0}^{T^{\prime}}\left|V_{s}^{n, m}\right|^{2} d s}\right]^{1 / 2} \\
\leqslant & \mathbb{E}\left[e^{C\left|2 p^{2}-p\right|\left(1+\sup _{0 \leqslant s \leqslant T}\left|X_{s}\right|^{2 p}\right)}\right]^{1 / 2} \\
< & +\infty,
\end{aligned}
$$

because $2 p<2$. By applying Cauchy Schwarz inequality and by using (3.10) and (3.9), we obtain

$$
\begin{aligned}
\mathbb{E}\left[\int_{0}^{T^{\prime}}\left|\delta Z_{s}^{n, m}\right|^{2} d s\right] & =\mathbb{E}\left[\left(\mathcal{E}_{T^{\prime}}^{n, m}\right)^{-1 / 2}\left(\mathcal{E}_{T^{\prime}}^{n, m}\right)^{1 / 2} \int_{0}^{T^{\prime}}\left|\delta Z_{s}^{n, m}\right|^{2} d s\right] \\
& \leqslant \mathbb{E}\left[\left(\mathcal{E}_{T^{\prime}}^{n, m}\right)^{-1}\right]^{1 / 2} \mathbb{E}^{\mathbb{Q}^{n, m}}\left[\left(\int_{0}^{T^{\prime}}\left|\delta Z_{s}^{n, m}\right|^{2} d s\right)^{2}\right]^{1 / 2} \\
& \leqslant C \mathbb{E}^{\mathbb{Q}^{n, m}}\left[\left|\delta Y_{T^{\prime}}^{n, m}\right|^{4}\right]^{1 / 2} \\
& \leqslant C \mathbb{E}\left[\left(\mathcal{E}_{T^{\prime}}^{n, m}\right)^{2}\right]^{1 / 2} \mathbb{E}\left[\left|\delta Y_{T^{\prime}}^{n, m}\right|^{8}\right]^{1 / 4} \\
& \leqslant C \mathbb{E}\left[\left|\delta Y_{T^{\prime}}^{n, m}\right|^{8}\right]^{1 / 4} \xrightarrow{n, m \rightarrow 0} 0
\end{aligned}
$$

Since $\mathcal{M}^{2}$ is a Banach space, we can define

$$
Z=\lim _{n \rightarrow+\infty} Z^{n}, \quad d \mathbb{P} \times d t \text {-a.e.. }
$$

If we apply Proposition 2.6 , we have that $\left\|Z^{n}\right\|_{\mathcal{M}^{2}}<C$ with a constant $C$ that does not depend on $n$. So, Fatou's lemma gives us that $Z \in \mathcal{M}^{2}$. Moreover, the estimate on $Z^{n}$ given by Proposition 3.3 stays true for $Z$ and, if we assume that (B.2)(c) holds, then Proposition 2.6 gives us that

$$
\mathbb{E}\left[\int_{0}^{T}\left|Z_{s}^{n}\right|^{l+1} d s\right]<C
$$

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with a constant $C$ that does not depend on $n$ and so

$$
\mathbb{E}\left[\int_{0}^{T}\left|Z_{s}\right|^{l+1} d s\right]<C
$$

Finally, by passing to the limit when $n \rightarrow+\infty$ in (3.7) and by using the dominated convergence theorem, we obtain that for any fixed $T^{\prime} \in[0, T[,(Y, Z)$ satisfies

$$
\begin{equation*}
Y_{t}=Y_{T^{\prime}}+\int_{t}^{T^{\prime}} f\left(s, X_{s}, Y_{s}, Z_{s}\right) d s-\int_{t}^{T^{\prime}} Z_{s} d W_{s}, \quad 0 \leqslant t \leqslant T^{\prime} \tag{3.11}
\end{equation*}
$$

To conclude, we just have to prove that we can pass to the limit when $T^{\prime} \rightarrow T$ in (3.11). Let us show that $Y_{T^{\prime}} \xrightarrow{T^{\prime} \rightarrow T} g\left(X_{T}\right)$ a.s.. Firstly, we have

$$
\varlimsup_{s \rightarrow T} Y_{s} \leqslant \varlimsup_{s \rightarrow T} Y_{s}^{n}=g_{n}\left(X_{T}\right) \text { a.s. } \quad \text { for any } n \geqslant n_{0},
$$

which implies $\varlimsup_{s \rightarrow T} Y_{s} \leqslant g\left(X_{T}\right)$, a.s.. On the other hand, we use assumption (B.2)(b) and we apply Propositions 2.5 and 3.3 to deduce that, a.s.,

$$
\begin{aligned}
Y_{t}^{n} & =g_{n}\left(X_{T}\right)+\int_{t}^{T} f\left(s, X_{s}, Y_{s}^{n}, Z_{s}^{n}\right) d s-\int_{t}^{T} Z_{s}^{n} d W_{s} \\
& \geqslant g_{n}\left(X_{T}\right)-C \int_{t}^{T} 1+\left|X_{s}\right|^{r_{f}+1}+\left|Y_{s}^{n}\right|+\left|Z_{s}^{n}\right|^{\eta} d s-\int_{t}^{T} Z_{s}^{n} d W_{s} \\
& \geqslant \mathbb{E}_{t}\left[g_{n}\left(X_{T}\right)-C \int_{t}^{T} 1+\left|X_{s}\right|^{\left(r_{f}+1\right) \vee p_{g}}+\frac{1+\left|X_{s}\right|^{\eta p_{g} /(l+1)}}{(T-s)^{\eta /(l+1)}} d s\right] \\
& \geqslant \mathbb{E}_{t}\left[g_{n}\left(X_{T}\right)\right]-C(T-t)\left(1+\left|X_{t}\right|^{\left(r_{f}+1\right) \vee p_{g}}\right)-C(T-t)^{1-\eta /(l+1)}\left(1+\left|X_{t}\right|^{\eta p_{g} /(l+1)}\right),
\end{aligned}
$$

and
$Y_{t}=\lim _{n \rightarrow+\infty} Y_{t}^{n} \geqslant \mathbb{E}_{t}\left[g\left(X_{T}\right)\right]-C(T-t)\left(1+\left|X_{t}\right|^{\left(r_{f}+1\right) \vee p_{g}}\right)-C(T-t)^{1-\eta /(l+1)}\left(1+\left|X_{t}\right|^{\eta^{p} /(l+1)}\right)$, which implies

$$
\underline{\lim }_{t \rightarrow T} Y_{t} \geqslant \underline{\lim }_{t \rightarrow T} \mathbb{E}_{t}\left[g\left(X_{T}\right)\right]=g\left(X_{T}\right)
$$

Hence, $\lim _{t \rightarrow T} Y_{t}=g\left(X_{T}\right)$ a.s. .
Now, let us come back to BSDE (3.11). Since we have

$$
\int_{t}^{T}\left|f\left(s, X_{s}, Y_{s}, Z_{s}\right)\right| d s \leqslant \int_{t}^{T} C\left(1+\left|X_{s}\right|^{r_{f}+1}+\left|Y_{s}\right|+\left|Z_{s}\right|^{l+1}\right) d s<+\infty \text { a.s. }
$$

then

$$
\int_{t}^{T^{\prime}} f\left(s, X_{s}, Y_{s}, Z_{s}\right) d s \xrightarrow{T^{\prime} \rightarrow T} \int_{t}^{T} f\left(s, X_{s}, Y_{s}, Z_{s}\right) d s<+\infty \text { a.s.. }
$$

Finally, passing to the limit when $T^{\prime} \rightarrow T$ in (3.11), we conclude that $(Y, Z)$ is a solution to BSDE (1.2).

Remark 3.8. The function $z \mapsto C|z|^{l+1}+h\left(|z|^{l+1-\eta}\right)$ with $C>0,0<\eta \leqslant l+1$ and $h$ a differentiable function with a bounded derivative is an example of generator such that (B.1), (B.2)(b) and (B.3) hold.

Remark 3.9. The estimate

$$
\left|Z_{t}\right| \leqslant \frac{C\left(1+\left|X_{t}\right|^{p_{g}}\right)}{\sqrt{T-t}}+C\left|X_{t}\right|^{r_{f}+1}
$$

## Existence of solutions to superquadratic BSDEs

is already known in the Lipschitz framework as a consequence of the Bismut-Elworthy formula (see e.g. [8]). For the superquadratic case, the same estimate was obtained when $p_{g}=0$ and $f$ does not depend on $x$ and $y$ in [5] (see also [16] for the quadratic case). In [5], Remark 4.4. gives the same type of estimate than (3.5) for the example $f(z)=|z|^{l}$. This result was already obtained by Gilding et al. in [9] using Bernstein's technique when $f(z)=|z|^{l}, b=0$ and $\sigma$ is the identity.

Remark 3.10. In this article, estimate (3.5) for the process $Z$ allows us to obtain an existence result. But this type of deterministic bound is also interesting for numerical approximation of BSDEs (see e.g. [16]) or for studying stochastic optimal control problems in infinite dimension (see e.g. [14]).

## A Appendix

Proof of Lemma 3.5. Let us set
$F_{t}^{M}:=e^{\int_{0}^{t} \nabla_{y} f_{M}\left(s, X_{s}, Y_{s}^{M}, Z_{s}^{M}\right) d s} \nabla Y_{t}^{M}+\int_{0}^{t} e^{\int_{0}^{s} \nabla_{y} f_{M}\left(u, X_{u}, Y_{u}^{M}, Z_{u}^{M}\right) d u} \nabla_{x} f_{M}\left(s, X_{s}, Y_{s}^{M}, Z_{s}^{M}\right) \nabla X_{s} d s$,
and

$$
\tilde{F}_{t}^{M}:=e^{\lambda t} F_{t}^{M}\left(\nabla X_{t}\right)^{-1} .
$$

Since $d \nabla X_{t}=\nabla b\left(t, X_{t}\right) \nabla X_{t} d t$, then $d\left(\nabla X_{t}\right)^{-1}=-\left(\nabla X_{t}\right)^{-1} \nabla b\left(t, X_{t}\right) d t$ and thanks to ItÃt's formula,

$$
d \tilde{Z}_{t}^{M}=d F_{t}^{M}\left(\nabla X_{t}\right)^{-1} \sigma(t)-F_{t}^{M}\left(\nabla X_{t}\right)^{-1} \nabla b\left(t, X_{t}\right) \sigma(t) d t+F_{t}^{M}\left(\nabla X_{t}\right)^{-1} \sigma^{\prime}(t) d t
$$

and

$$
d\left(e^{\lambda t} \tilde{Z}_{t}^{M}\right)=\tilde{F}_{t}^{M}\left(\lambda I d-\nabla b\left(t, X_{t}\right)\right) \sigma(t) d t+\tilde{F}_{t}^{M} \sigma^{\prime}(t) d t+e^{\lambda t} d F_{t}^{M}\left(\nabla X_{t}\right)^{-1} \sigma(t)
$$

Finally,

$$
\left.d\left|e^{\lambda t} \tilde{Z}_{t}^{M}\right|^{2}=d\langle N\rangle_{t}+2\left[\lambda\left|\tilde{F}_{t}^{M} \sigma(t)\right|^{2}-\tilde{F}_{t}^{M} \sigma(t) t^{t} \sigma(t)^{t} \nabla b\left(t, X_{t}\right)-{ }^{t} \sigma^{\prime}(t)\right]^{t} \tilde{F}_{t}^{M}\right] d t+d N_{t}^{*}
$$

with $N_{t}:=\int_{0}^{t} e^{\lambda s} d F_{s}^{M}\left(\nabla X_{s}\right)^{-1} \sigma(s)$ and $N_{t}^{*}$ a $\mathbb{Q}^{M}$-martingale. Thanks to the assumption (F.2) we are able to conclude that $\left|e^{\lambda t} \tilde{Z}_{t}^{M}\right|^{2}$ is a $\mathbb{Q}^{M}$-submartingale.

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Acknowledgments. The authors would like to thank the two referees and the associate editor for their helpful comments and remarks. The second author thanks the Università di Milano Bicocca for its hospitality at the time when this research began.


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