

Fractionally Differenced Gegenbauer Processes with Long Memory: A Review

G. S. Dissanayake, M. S. Peiris and T. Proietti

Abstract. The main objective of this paper is to review and promote the usefulness of generalized fractionally differenced Gegenbauer processes in time series and econometric research endeavours. In particular, theoretical and computational aspects centered around fractionally differenced Gegenbauer processes with long memory together with a number of interesting and elegant extensions will be discussed. In-depth conceptual developments and large scale simulation study results are presented for clarity and completeness. This survey highlights a number of gaps in the existing literature of this subject area and becomes a valuable reference source for time series practitioners.

Key words and phrases: Gegenbauer process, long memory, heteroskedasticity, fractional difference, volatility, spectral density, stationarity, invertibility.

1. INTRODUCTION

The origin of stochastic analysis of time series can be traced back to the seminal work of Yule (1926) and Slutsky (1927), who introduced autoregressive (AR) and moving average (MA) models. Box and Jenkins (1970) provided a systematic inferential treatment of stationary ARMA models, which became the workhorse of modern applied time series work. The next decade would set the scene for nonstationarity, integration and fractional integration. In particular, in the early 1980s the introduction of long memory by Granger and Joyeux (1980) and Hosking (1981) opened a new fruitful research avenue for time series specialists and econometricians. The class of fractionally integrated autoregressive moving average (ARFIMA or FARIMA) processes, extending the

traditional autoregressive integrated moving average (ARIMA) series with a fractional degree of differencing, is nowadays routinely applied to diverse phenomena such as energy price and demand, telecommunication, environmental time series and financial volatility. A thorough account of the developments and the various approaches to inference are reported in Beran (1992, 1994), Chan and Palma (2006), Giraitis, Koul and Surgailis (2012) and Beran et al. (2013).

The Gegenbauer processes that constitute the topic of this paper were introduced in the last paragraph of Hosking's (1981) seminal *Biometrika* article. The concept was later developed by Anděl (1986) and Gray, Zhang and Woodward (1989, 1994), who proposed the class of time series models known as Gegenbauer ARMA abbreviated as GARMA, using the theory of Gegenbauer polynomials (see also Giraitis and Leipus, 1995, and Woodward, Cheng and Gray, 1998, for further details). Their distinctive properties are long range dependence and quasi-periodic behaviour, and they provide a model for cyclical or seasonal persistent processes, whose autocorrelation function is an hyperbolically damped oscillating sequence. As a result, the autocorrelation function is not absolutely summable and the spectrum possesses a pole at the cyclical or seasonal frequencies. A detailed analysis of the long memory features of GARMA processes is in Chung

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(1996). As shown by [Oppenheim and Viano \(2004\)](#), cyclical and seasonal persistent processes can arise from the contemporaneous aggregation of stationary autoregressive processes with complex random roots. This generalized class can be used to represent long memory depicting multiple unbounded spectral peaks away from the origin, unlike in the standard long memory ARFIMA case of [Hosking \(1981\)](#), which can only show unbounded spectral density peaks at the zero frequency. A detailed analysis of the long memory features of GARMA processes is in [Chung \(1996\)](#).

In many financial time series modelling problems, it is known that heteroskedasticity plays an important role. Such models in common use are the autoregressive conditionally heteroskedastic (ARCH) model of [Engle \(1982\)](#) and its generalized ARCH (GARCH) model due to [Bollerslev \(1986\)](#). An extension of it by [Baillie, Bollerslev and Mikkelsen \(1996\)](#) resulted in a fractionally integrated GARCH (FI-GARCH) to model the conditional variance. Incorporating heteroskedasticity in ARFIMA models with GARCH errors has been studied by [Ling and Li \(1997\)](#). Another interesting development was the introduction of the Gegenbauer integrated GARCH (GIGARCH) by [Guegan \(2000\)](#) combining the attributes of long memory, seasonality and heteroskedasticity at the same time. In an attempt to capture and blend some of these established GARCH features, [Dissanayake and Peiris \(2011\)](#) introduced conceptual properties of a class of models with conditionally heteroskedastic errors. It was based on a generalized fractional operator used by [Anh, Angulo and Ruiz-Medina \(1999\)](#) and later developed by [Peiris \(2003\)](#), [Shitan and Peiris \(2008, 2013\)](#). This scaled down new operator with further applications was employed by [Peiris, Allen and Peiris \(2005\)](#) and [Peiris and Thavaneswaran \(2007\)](#) in long memory models driven by heteroskedastic GARCH errors.

Furthermore, it has become a customary practice in applied time series analysis to conduct tests to assess whether a time series is stationary or to be integrated at a suitable degree of differencing. This procedure became very popular among econometricians and was made famous under the theme of “*unit root hypothesis*” (see, e.g., [Phillips and Xiao, 1998](#); [Dolado, Gonzalo and Mayoral, 2002](#)). Such hypotheses of stationary series with respect to unit roots could be extended to fractional processes with long memory. A unit root test for fractionally integrated processes has been proposed in [Dolado, Gonzalo and Mayoral \(2002\)](#) and asymptotic results of a similar test is presented in [Wang, Lin and Gulati \(2003\)](#). Additionally, [Taylor \(2005\)](#) introduced

a set of new tests to assess constant trend stationarity against the change in persistence from trend stationarity to difference stationarity or vice versa. Furthermore, [Ohanissian, Russell and Tsay \(2008\)](#) proposed a statistical test to distinguish between true and spurious long memory. However, an extension of the unit root test based on state space methodology and Kalman filter (KF) estimates for a GARMA model is seemingly absent in the literature. [Jansson and Nielsen \(2012\)](#) proposed a nearly efficient unit root test that is applicable in such a context and assessing its power with a GARMA model becomes a worthwhile exercise.

In summary, consideration of this paper will be given to a class of Gegenbauer processes generated by Gaussian white noise and GARCH errors since most of the other models are nested within this new family. In other words, this will be a review of two topics relevant to the class known as “*fractional differencing*” and “*long memory*”. Section 2 provides preliminaries of fractionally differenced Gegenbauer processes with long memory. Gegenbauer processes and the use of truncated state space representations and KF in estimating and forecasting their long memory version will be considered in Sections 3 and 4. The state space methodology follows the work of [Anderson and Moore \(1979\)](#), [Pearlman \(1980\)](#), [Harvey \(1989\)](#), [Aoki \(1990\)](#), [Brockwell and Davis \(1996\)](#), [Chan and Palma \(1998\)](#), [Durbin and Koopman \(2001\)](#), [Harvey and Proietti \(2005\)](#), [Palma \(2007\)](#), [Grassi and Santucci de Magistris \(2014\)](#) and [Dissanayake, Peiris and Proietti \(2016\)](#). The adoption of the techniques in [Dissanayake, Peiris and Proietti \(2016, 2015\)](#) to analyze seasonality in long memory Gegenbauer series is also presented in this section. This will be followed by Section 5 on modelling of persistence and conditional variance. A model testing phase based on [Dissanayake et al. \(2015\)](#) will be presented in Section 6, and Section 7 will comprise of concluding remarks.

2. PRELIMINARIES

Let $\{X_t, t = 1, 2, \dots\}$ be a stationary random process with autocovariance function $\gamma(k) = \text{Cov}(X_t, X_{t+|k|})$, and autocorrelation function (acf) $\rho(k) = \gamma(k)/\gamma(0)$, where $k = 0, 1, 2, \dots$. We denote the normalized spectrum or spectral density function (sdf) by

$$f(\omega) = \frac{1}{2\pi} \sum_{k=-\infty}^{\infty} \rho(k)e^{-i\omega k}, \quad -\pi \leq \omega \leq \pi,$$

where ω is the Fourier frequency.

According to the behaviour of the spectral density and/or the acf, we can characterise the notion of long range dependence. The following details of a long memory process will be adopted in the sequel. As it is illustrated by Guégan (2005) and Giraitis, Koul and Surgailis (2012), Chapter 3, there are several alternative characterisations of the notion of long memory. In this paper, we will adopt a definition that is based on the second-order properties, and in particular on the asymptotic properties of the autocorrelation according to which $\{X_t, t = 1, \dots, T\}$ is said to be long memory if $\sum_{k=0}^{T-1} |\rho(k)| \rightarrow \infty$ as $T \rightarrow \infty$. The following definition specializes the role of decay of $\rho(k)$ at infinity.

Long Memory Cyclical Process: $\{X_t\}$ is a long memory process at the frequency $\omega_0 \in [0, \pi]$ if $\rho(k) \sim C_\rho k^{2\delta-1} \cos(k\omega_0)$ as $k \rightarrow \infty$, where $\delta \in (0, 0.5)$ is called the memory parameter and $C_\rho > 0$.

Here, given two sequences a_k and b_k , $a_k \sim b_k$ means $\lim_{k \rightarrow \infty} \frac{a_k}{b_k} = 1$. By Lemma 7.3.1 in Giraitis, Koul and Surgailis (2012), if the spectral density of $\{X_t\}$ takes the form $f(\omega) \sim C(\omega)|\omega - \omega_0|^{-2\delta}$, where $C(\omega)$ is a regularly varying function with $\lim_{\omega \rightarrow \omega_0} h(\omega) = h(\omega_0) > 0$, and derivative satisfying $\int_{-\pi}^{\pi} \frac{dC(\omega)}{d\omega} d\omega < \infty$ and $(\omega - \omega_0) \frac{dC(\omega)}{d\omega} d\omega = 0$, for $\omega \rightarrow \omega_0$. Then $\{X_t\}$ is long memory according to the above definition with $C_\rho = 2C(\omega_0)\Gamma(1 - 2\delta) \sin(\pi\delta)$.

We focus on the class of linear causal processes, according to which X_t can be represented as $X_t = \sum_{j=0}^{\infty} \psi_j \epsilon_{t-j}$, where $\epsilon_t \sim \text{WN}(0, \sigma^2)$ (WN stands for white noise), and the coefficients ψ_j decay hyperbolically, $\psi_j \sim C_\psi j^{\delta-1}$, $j \rightarrow \infty$, $C_\psi \neq 0$. This class could be obtained by introducing the fractional differencing operator and nests important models, such as the autoregressive fractionally integrated moving average (ARFIMA) model, the Gegenbauer ARMA (GARMA) model and the fractional exponential (FEXP) model. The ARFIMA class was introduced by Granger and Joyeux (1980) and Hosking (1981), while Robinson (1991) and Beran (1993) introduced the FEXP model.

The most elementary fractional linear process featuring long memory at the zero frequency is $(I - B)^\delta X_t = \epsilon_t$, $0 < \delta < 0.5$, which is generalised by replacing ϵ_t by a short memory ARMA(p, q) process, or by a process with a logarithmic spectrum that can be represented by a finite trigonometric polynomial (FEXP model). The operator $(I - B)^\delta$ is the fractional differencing operator and for $\delta > -1$ it is defined according to the binomial expansion

$$(I - B)^\delta = \sum_{j=0}^{\infty} \frac{\Gamma(j - d)}{\Gamma(j + 1)\Gamma(-d)} B^j,$$

where $\Gamma(z) = \int_0^\infty x^{z-1} e^{-x} dx$ is the Gamma function.

3. GEGENBAUER PROCESSES AND THEIR PROPERTIES

A *Gegenbauer* process is a long memory process generated by the dynamic equation

$$(1) \quad (1 - 2uB + B^2)^\delta X_t = \epsilon_t,$$

where $|u| < 1$, $\delta \in (0, 0.5)$, and ϵ_t is a short memory process characterised by a positive and bounded spectral density $f_\epsilon(\omega)$. If $\epsilon_t \sim \text{WN}(0, \sigma^2)$, (1) is a well-known Gegenbauer process of order δ or a GARMA(0, δ , 0) process. Some authors use the notation GARMA(0, δ , 0; u) to represent the process in (1). See, for example, Peiris and Asai (2016). As we shall see below, (1) complies with the definition given in Section 2 of a long memory process at the frequency $\omega_0 = \arccos(u)$. According to (1), X_t arises from filtering the process ϵ_t by the infinite impulse response filter

$$(1 - 2uB + B^2)^{-\delta} = \sum_{j=0}^{\infty} C_j^\delta(u) B^j,$$

which we now characterise.

The *Gegenbauer* or *ultraspherical polynomial* $C_j^\delta(u)$ is defined in terms of its generating function as follows:

$$(2) \quad \frac{1}{(1 - 2uz + z^2)^\delta} = \sum_{j=0}^{\infty} C_j^\delta(u) z^j,$$

where

$$C_j^\delta(u) = \sum_{k=0}^{[j/2]} (-1)^k \frac{\Gamma(j - k + \delta)}{\Gamma(\delta)\Gamma(j + 1)\Gamma(j - 2k + 1)} (2u)^{j-2k}$$

and $[j/2]$ stands for the integer part of $\frac{j}{2}$ (see Erdelyi et al., 1953, 10.9).

It is possible to show (see Gould, 1974, Gradshteyn and Ryzhik, 1980 and Rainville, 1960, for details) that $C_j^\delta(u)$ satisfies the recursion

$$C_j^\delta(u) = \frac{1}{j} [2u(j + \delta - 1)C_{j-1}^\delta(u) - (j + 2\delta - 2)C_{j-2}^\delta(u)],$$

for $j \geq 2$, with $C_0^\delta(u) = 1$ and $C_1^\delta(u) = 2\delta u$.

For large j , the coefficients $C_j^\delta(u)$ can be approximated by (see Chung, 1996)

$$(3) \quad C_j^\delta \sim \left(\frac{j}{2}\right)^{\delta-1} \frac{\cos[(j + \delta)\omega_0 - (\delta\pi/2)]}{\Gamma(\delta) \sin^\delta(\omega_0)}.$$

As we have assumed $|u| < 1$, the polynomial $1 - 2uz + z^2$ has complex zeros which are on the unit circle. Therefore, we need the additional restriction $\delta < 1/2$ to ensure the square summability of $C_j^\delta(u)$, or $\sum_{j=0}^{\infty} \{C_j^\delta(u)\}^2 < \infty$.

If $\epsilon_t \sim \text{WN}(0, \sigma^2)$, the spectral density of X_t is

$$(4) \quad \begin{aligned} f(\omega) &= \frac{\sigma^2}{\pi} \{2|\cos(\omega) - \cos(\omega_0)|\}^{-2\delta} \\ &= \frac{\sigma^2}{\pi} \left| 4 \sin\left(\frac{\omega + \omega_0}{2}\right) \sin\left(\frac{\omega - \omega_0}{2}\right) \right|^{-2\delta} \end{aligned}$$

so that, as $\omega \rightarrow \omega_0$,

$$f(\omega) \sim \frac{\sigma^2}{\pi} \{2(\omega - \omega_0) \sin(\omega_0)\}^{-2\delta}.$$

Since $\sin(\omega_0)$ is bounded, it is clear that the spectral density is unbounded as $\omega \rightarrow \omega_0$. Therefore, it can be shown that a stationary Gegenbauer process contains an unbounded spectrum at ω_0 and is long memory when $0 < \delta < \frac{1}{2}$. This special frequency ω_0 is called the Gegenbauer or G -frequency.

Given the spectral density $f(\omega)$, one can compute the autocovariance function $\gamma(j)$ for a stationary long memory Gegenbauer process. For the case $|u| < 1$, Gray, Zhang and Woodward (1989) have shown that

$$(5) \quad \begin{aligned} \gamma(j) &= \frac{\sigma^2}{2\sqrt{\pi}} \Gamma(1 - 2\delta) [2 \sin(\omega_0)]^{1/2 - 2\delta} \\ &\cdot [P_{j-1/2}^{2\delta-1/2}(u) + (-1)^j P_{j-1/2}^{2\delta-1/2}(-u)], \end{aligned}$$

where $P_a^b(x)$ are associated Legendre functions that can be calculated using the recursion

$$P_a^b(x) = \frac{2a-1}{a-b} x P_{a-1}^b(x) - \frac{a+b-1}{a-b} P_{a-2}^b(x),$$

with initial terms

$$\begin{aligned} P_{-1/2}^{2\delta-1/2}(u) &= [(1+u)/(1-u)]^{\delta-1/4} [1/\Gamma(3/2-2\delta)] \\ &\cdot F(1/2, 1/2; 3/2-2\delta; (1-u)/2), \\ P_{1/2}^{2\delta-1/2}(u) &= [(1+u)/(1-u)]^{\delta-1/4} [1/\Gamma(3/2-2\delta)] \\ &\cdot F(-1/2, 1/2; 3/2-2\delta; (1-u)/2), \end{aligned}$$

and

$$F(a, b; c; w) = \sum_{n=1}^{\infty} \frac{\Gamma(c)\Gamma(a+n)\Gamma(b+n)}{\Gamma(a)\Gamma(b)\Gamma(c+n)\Gamma(n+1)} w^n$$

is the hypergeometric function. This leads towards the following approximation on autocovariances:

$$(6) \quad \begin{aligned} \gamma(j) &= \frac{2^{1-2\delta}\sigma^2}{\pi} \sin^{-2\delta}(\omega_0) \sin(\delta\pi) \\ &\cdot \Gamma(1-2\delta) \cos(j\omega_0) \frac{\Gamma(j+2\delta)}{\Gamma(j+1)}. \end{aligned}$$

The acf of $\{X_t\}$ can be approximated by $\rho(j) \sim K \cos(j\omega_0) j^{2\delta-1}$ as $j \rightarrow \infty$, where K is a real constant that depends on δ and ω_0 ; see Chung (1996).

When $|u| = 1$, that is, $\omega_0 = 0, \pi$, then

$$C_j^\delta(u) = (-1)^j \frac{\Gamma(j+2\delta)}{\Gamma(2\delta)\Gamma(j+1)};$$

the roots of the polynomial $1 - 2uz + z^2$ are ± 1 with multiplicity 2 and δ must satisfy $\delta < \frac{1}{4}$ to ensure the square summability of the coefficients. In this case, $\rho(j) \sim K j^{4\delta-1}$ as $j \rightarrow \infty$.

3.1 GARMA(p, δ, q) Process

A process $\{X_t\}$ generated by the following equation is called a GARMA(p, δ, q) or GARMA($p, \delta, q; u$):

$$\phi(B)(1 - 2uB + B^2)^\delta X_t = \theta(B)\epsilon_t,$$

where $\phi(B)$, and $\theta(B)$ are stationary AR and invertible MA operators, respectively, with no common zeros, δ is the memory parameter and $|u| \leq 1$ is a constant to satisfy (a) $|u| < 1$ for $\delta < 1/2$ or (b) $|u| = 1$ for $\delta < 1/4$.

3.2 The k -Factor Gegenbauer Processes

Extending the process in 1, a k -factor Gegenbauer process is given by

$$(7) \quad \prod_{j=1}^k (1 - 2u_j B + B^2)^{\delta_j} X_t = \epsilon_t.$$

Woodward, Cheng and Gray (1998) illustrate many important properties of this k -factor Gegenbauer process. In particular, the spectrum of (18) is given by

$$(8) \quad \begin{aligned} f(\omega) &= \frac{\sigma^2}{2\pi} \prod_{j=1}^k |1 - 2u_j \exp(-i\omega) \\ &+ \exp(-2i\omega)|^{-2\delta_j}, \end{aligned}$$

where $0 < \omega < \pi$.

By trigonometric identities, we can write

$$(9) \quad f(\omega) = \sigma^2/2\pi \prod_{j=1}^k \{4[\cos(\omega) - \cos(\omega_0j)]^2\}^{-\delta_j},$$

where $\cos(\omega_{0j}) = u_j, j = 1, 2, \dots, k$. Hence, the spectrum has k unbounded peaks at corresponding Gegenbauer frequencies $\omega_{0j}, j = 1, \dots, k$. In summary, the k -factor Gegenbauer process is:

- stationary if (a) $|u_i| < 1$ and $\delta_i < 1/2$ or (b) $|u_i| = 1$ and $\delta_i < 1/4$, for each $i = 1, \dots, k$;
- stationary with long memory if (a) $|u_i| < 1$ and $0 < \delta_i < 1/2$ or (b) $|u_i| = 1$ and $0 < \delta_i < 1/4$, for each $i = 1, \dots, k$.

Woodward, Cheng and Gray (1998) pointed out that the true autocorrelation structure of a k -factor Gegenbauer process could be obtained through the inverse Fourier transform of its spectrum $f(\omega)$. Forecasting with the k -factor Gegenbauer processes is dealt with in Ferrara and Guegan (2001), whereas Guégan (2005) provides further insight on the properties of the k -factor GARMA(0, δ , 0) process. The estimation of time-varying long memory parameters of a locally stationary k -factor Gegenbauer process utilizing the wavelet method is presented in Lu and Guegan (2011).

3.2.1 *Other generalized fractional processes.* The first generalization of traditional ARMA models has dealt with fractional powers of the AR and MA operators. Two processes in particular have emerged as first- and second-order generalized fractional operators and their applications to time series.

- Consider the process $\{X_t\}$ generated by

$$(10) \quad (I - \alpha B)^\delta X_t = \epsilon_t; \\ -1 < \alpha < 1; \delta > 0; \{\epsilon_t\} \sim \text{WN}(0, \sigma^2).$$

This process has been introduced by Spolia, Chandler and O'Connor (1980) under the name 'fractional order equal root autoregressive model', as mentioned by Hosking (1981). The theory was further developed by Gonçalves (1987), Anh, Lunney and Peiris (1997) and Shitan and Peiris (2008, 2013). Clearly, (10) encompasses the standard first-order autoregressive model when $\delta = 1$, as well as the fractional noise process when $\alpha = 1$ and $0 < \delta < 1/2$.

- Similarly, the second-order fractional autoregressive model arises from generalizing the AR(2) and is given by

$$(11) \quad (1 - \alpha_1 B - \alpha_2 B^2)^\delta X_t = \epsilon_t, \\ \{\epsilon_t\} \sim \text{WN}(0, \sigma^2),$$

where $1 - \alpha_1 z - \alpha_2 z^2 \neq 0$ for all $|z| \leq 1, \delta > 0$ (see Shitan and Peiris, 2009, for details).

In (11), it is known that, for $\delta = 1$ conditions $\alpha_2 + \alpha_1 < 1, \alpha_2 - \alpha_1 < 1$ and $-1 < \alpha_2 < 1$ must be satisfied by α_1 and α_2 to ensure stationary solutions.

Let $1 - \alpha_1 B - \alpha_2 B^2 = (1 - \xi_1 B)(1 - \xi_2 B)$, where $\xi_1 + \xi_2 = \alpha_1$ and $\xi_1 \xi_2 = -\alpha_2$.

By writing (11) as

$$[(1 - \xi_1 B)(1 - \xi_2 B)]^\delta X_t = \epsilon_t,$$

and following Shitan and Peiris (2009), it can be shown that the solution to (11) can be expressed as

$$X_t = \sum_{k=0}^{\infty} \sum_{l=0}^{\infty} \frac{\Gamma(k + \delta)\Gamma(l + \delta)\xi_1^k \xi_2^l}{\Gamma(k + 1)\Gamma(l + 1)\Gamma^2(\delta)} \epsilon_{t-k-l},$$

where $\Gamma(\cdot)$ is the gamma function satisfying $\Gamma(k) = (k - 1)!$ for integers $k \geq 1$.

The model in (11) is called the generalized second-order autoregression with index δ . For simplicity, we call it Generalized Autoregressive of order 2 [GAR(2)] model. It is clear that the class generated by (11) is more flexible than the standard AR(2) model. Although the autocorrelation function of the GAR(2) model can be obtained, it is not mathematically tractable as there is no closed form solution. The spectral density $f(\omega)$ is given by

$$f(\omega) = \frac{\sigma^2}{2\pi} [(1 + \alpha_1^2 + \alpha_2^2) - 2\alpha_1(1 - \alpha_2)\cos \omega - 2\alpha_2 \cos 2\omega]^{-\delta}.$$

See Shitan and Peiris (2009) for details.

It is clear that when $\alpha_2 = -1$ [in (11)], the roots of $1 - \alpha_1 z - \alpha_2 z^2 = 0$ do not lie in the stationary region. In particular, when $\alpha_1 = 2u, |u| < 1$ and $\alpha_2 = -1$, the zeros of $1 - \alpha_1 z - \alpha_2 z^2$ are a pair of complex conjugate roots having unit modulus with phase $\pm \arccos(u)$ and the process becomes stationary only for particular values of δ . This leads to Gegenbauer processes and extends to a mathematically elegant class of time series models with very useful applications. Now we look at this new class of models.

4. STATE SPACE REPRESENTATION OF GARMA MODELS

Consider the Wold representation of a Gaussian GARMA(0, δ , 0) process in (1) with $\epsilon_t \sim \text{IID } N(0, \sigma^2)$ given by

$$(12) \quad X_t = C(B)\epsilon_t = \sum_{j=0}^{\infty} C_j \epsilon_{t-j}, \quad C_0 = 1,$$

where $C(B) = (1 - 2uB + B^2)^{-\delta}$ and C_j are the Gegenbauer coefficients as defined by (2), where we drop reference to δ and u for notational simplicity.

The m th order moving average approximation is obtained by truncating the right-hand side of (12) at lag m such that

$$(13) \quad X_{t,m} = \sum_{j=0}^m C_j \epsilon_{t-j}, \quad \epsilon_t \sim \text{i.i.d. } N(0, \sigma_m^2),$$

where $\{X_{t,m}\}$ is the truncated Gegenbauer process that will vary with the chosen finite truncation lag order $m = 1, 2, \dots, M < \infty$.

Following Chan and Palma (1998), Dissanayake, Peiris and Proietti (2016) focus on the following state space representation of the above m th order MA approximation:

$$(14) \quad \begin{aligned} X_{t,m} &= Z\alpha_t + \epsilon_t, \\ \alpha_{t+1} &= T_0\alpha_t + H\epsilon_t, \end{aligned}$$

where $\alpha_{t+1} = [X(t+1|t), X(t+2|t), X(t+3|t), \dots, X(t+m|t)]'$ is the $m \times 1$ state vector with elements $X(t+j|t) = E(X_{t+j,m}|\mathcal{F}_t)$, $j = 1, 2, \dots, m$, $\mathcal{F}_t = \{X_{t,m}, X_{t-1,m}, \dots\}$, and

$$Z = [1, 0, \dots, 0],$$

$$T_0 = \begin{bmatrix} 0 & 1 & 0 & \dots & 0 \\ 0 & 0 & 1 & \dots & 0 \\ \vdots & \vdots & \ddots & \ddots & 0 \\ \vdots & \dots & \dots & 0 & 1 \\ 0 & 0 & \dots & \dots & 0 \end{bmatrix}, \quad H = \begin{bmatrix} C_1 \\ C_2 \\ \vdots \\ \vdots \\ C_m \end{bmatrix}.$$

The measurement equation is essentially $X_{t,m} = E(X_{t,m}|\mathcal{F}_{t-1}) + \epsilon_t$, whereas the transition equation provides the predictors $X(t+j|t) = X(t+j-1|t) + C_j\epsilon_t$, $j = 1, \dots, m$. The distribution of the initial state vector is $\alpha_1 \sim N(0, P_1)$, where P_1 is the Toeplitz matrix with elements $p_{hk} = \sigma_m^2 \sum_j C_j C_{j+|h-k|}$.

Alternatively, the MA approximation could be obtained by applying the innovations algorithm, following Brockwell and Davis (1991). A different asymptotically equivalent approximation can be obtained using the corresponding truncated AR(m') approximation $\sum_{j=0}^{m'} \pi_j X_{m,t-j} = \epsilon_t$, arising from truncating the infinite AR polynomial $\pi(B) = (1 - 2uB + B^2)^\delta$ at lag m' . Details can be found in Chan and Palma (1998) and Grassi and Santucci de Magistris (2014), together with a comparison of these two approximations for fractionally integrated processes at the zero frequency. An alternative AR approximation can also be obtained by

applying the Durbin–Levinson algorithm to the autocovariance matrix of the process.

4.1 Estimation and Prediction

The Kalman filter, Kalman (1961) and Kalman and Bucy (1961), produces recursively the one-step-ahead predictor of X_{tm} , given a particular value of the parameter vector, and computes the innovations $v_t = X_{tm} - X(t|t-1)$, the prediction error variance and the one-step-ahead predictor of the states, as well as their mean square error matrix. Therefore, it enables the evaluation of the likelihood function of the approximating model. The latter can be maximised with respect to the unknown parameters u and δ (the parameter σ_m^2 can be concentrated out of the likelihood function). Let $\{x_t, t = 1, \dots, T\}$ be a time series generated by a Gegenbauer process. The maximiser can be characterised as a quasi maximum likelihood estimator (QMLE) as it converges to the MLE, under regularity assumptions that are detailed below and that entail letting m increase as T increases, at a suitable rate, so that $m/T \rightarrow 0$.

The KF recursions for the approximating MA(m) model considered in the previous subsection are, for $t = 1, \dots, T$:

$$(15) \quad \begin{aligned} v_t &= x_t - Za_t, \\ f_t &= ZP_tZ' + \sigma_m^2, \\ K_t &= (T_0P_tZ' + \sigma_m^2H)/f_t, \\ a_{t+1} &= T_0a_t + K_tv_t, \\ P_{t+1} &= T_0P_tT_0' + HH' - f_tK_tK_t', \end{aligned}$$

where K_t is the Kalman gain, and f_t the one-step-ahead prediction error variance. The KF returns the pseudo-innovations v_t , such that if the MA(m) approximation were the true model, $v_t \sim \text{IID } N(0, \sigma_m^2 f_t)$, so that the quasi log-likelihood of (δ, u, σ_m^2) is (apart from a constant term)

$$(16) \quad \begin{aligned} \ell(\delta, u, \sigma_m^2) &= -\frac{1}{2} \left(T \ln \sigma_m^2 + \sum_{t=1}^T \ln f_t + \frac{1}{\sigma_m^2} \sum_{t=1}^T \frac{v_t^2}{f_t} \right). \end{aligned}$$

The scale parameter σ_m^2 can be concentrated out of the likelihood function, giving the MLE

$$\hat{\sigma}_m^2 = \sum_t \frac{v_t^2}{f_t}.$$

The profile log-likelihood

$$(17) \quad \ell_{\sigma_m^2}(\delta, u) = -\frac{1}{2} \left[T(\ln \hat{\sigma}_m^2 + 1) + \sum_{t=1}^T \ln f_t \right]$$

is a function of parameters (δ, u) .

The maximisation of (17) can be performed by a quasi-Newton algorithm, after a reparameterization which constrains δ and u in the subset of $\mathbb{R}^2[0, 0.5) \times [0, 1)$.

4.2 An Illustrative Example

We illustrate the above state space approach by fitting a Gaussian Gegenbauer process by QMLE to a time series of length $T = 512$ generated according to the following mechanism. We simulate $T + m_0$ draws from an i.i.d. sequence $\epsilon_t \sim N(0, 1), t = -m_0 + 1, -1, 0, 1, \dots, T$, and we construct the series $\{X_t\}; t = 1, 2, \dots, T$, using (13), with $u = 0.8, \delta = 0.4, \sigma^2 = 1$. The generated series (for a reasonably large m_0 , such as $m_0 = 10^3$) can be thought as a realisation of the stochastic process in (12).

The simulated series is plotted in Figure 1 along with its sample autocorrelation function. The latter is a damped sinusoidal with a period of about 10 observations. Figure 2 shows the true spectral density of the Gegenbauer process, $f(\omega)$, which is unbounded at $\omega = \cos^{-1}(u) = \cos^{-1}(0.8)$, along with the periodogram of the simulated series, $I(\omega_j) = \frac{1}{2\pi} [\hat{\gamma}(0) + 2 \sum_{k=1}^{T-1} \hat{\gamma}(k) \cos(\omega_j t)]$, where $\hat{\gamma}(k)$ is the sample autocovariance function at lag k and $\omega_j = 2\pi j/T, j = 0, \dots, \lfloor T/2 \rfloor$, are the Fourier frequencies.

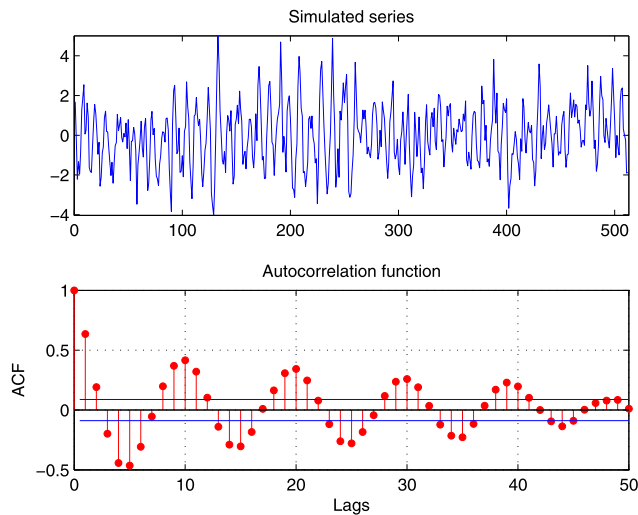


FIG. 1. Simulated series from a Gaussian Gegenbauer process with $\delta = 0.4, u = 0.8, \sigma^2 = 1$ and corresponding acf.

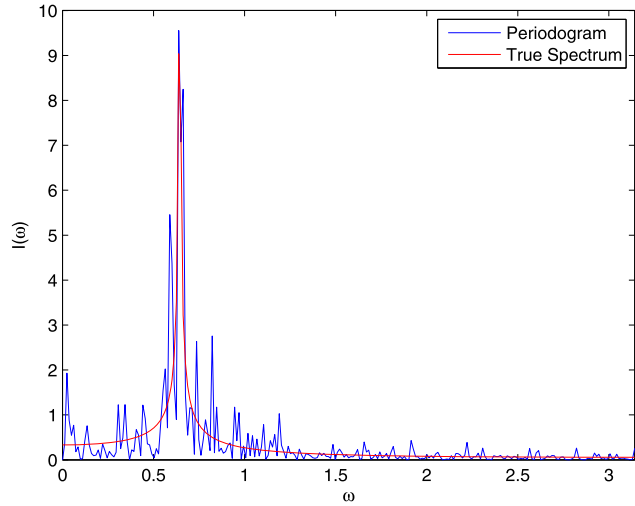


FIG. 2. Sample spectrum (periodogram) and true spectrum of a simulated GARMA(0, δ , 0) model.

Various m th order truncated MA approximating models have been fitted to the series by the approximate maximum likelihood method outlined in the previous section. The QMLEs of δ, u and σ^2 are reported in Table 1. The likelihood is a monotonically increasing function of m , whereas the estimated prediction error variance decreases with m . On the other hand, $\hat{\delta}$ and \hat{u} vary sensibly with m .

Figure 3 displays the implied spectral density of $X_{t,m}$ corresponding to the above parameter estimates. For $m > 1$, they are characterised by a spectral peak around the frequency $\cos^{-1}(\hat{u})$. Another distinguishing feature is the presence of side lobes, due to the truncation of the MA filter (this is referred to as the *Gibbs phenomenon*).

If the autoregressive approximation is used in lieu of the MA one, the estimated spectral density do not suffer from the Gibbs phenomenon. This is illustrated in Figure 4, which displays the AR spectrum estimates for the same values of m .

TABLE 1
Fitting a GARMA(0, δ , 0) model to a simulated series using different MA(m) approximating state space models. Quasi maximum likelihood estimates of the parameters (true values are $\delta = 0.4, u = 0.8, \sigma^2 = 1$)

	Values of m				
	1	5	15	25	50
$\hat{\delta}$	0.32	0.41	0.50	0.44	0.43
\hat{u}	0.98	0.80	0.75	0.78	0.78
$\hat{\sigma}_m^2$	1.31	1.06	0.97	0.95	0.96

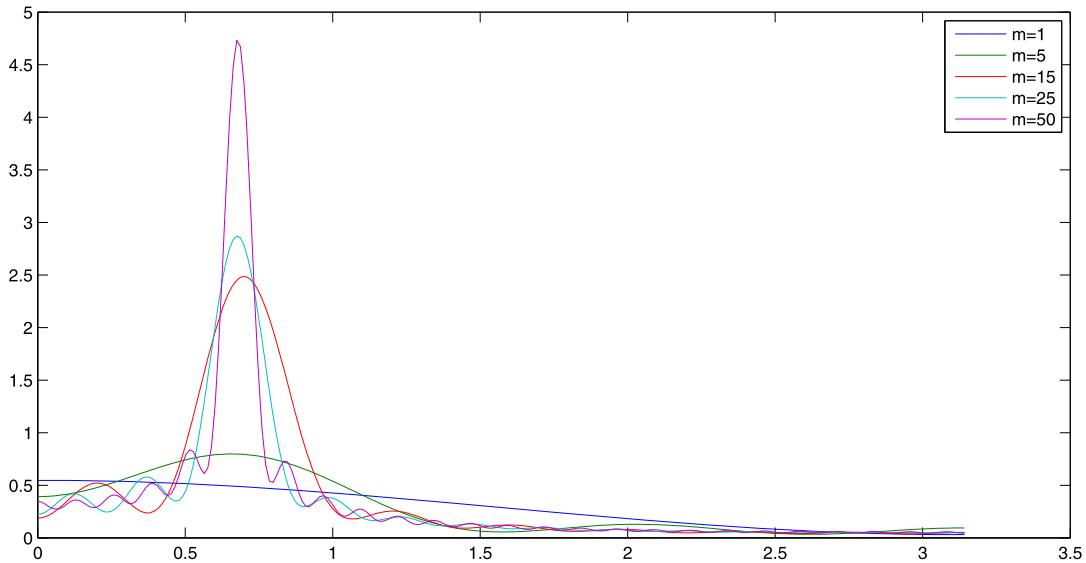


FIG. 3. Spectral densities of estimated MA approximating GARMA(0, δ , 0) models with different lag orders.

Dissanayake, Peiris and Proietti (2016) present the results of an extensive Monte Carlo experiment, which enabled them to conclude that the optimal order of the MA approximation falls in the range [29, 35], whereas for the AR approximation the optimal truncation is in the range [9, 13]. The optimality is assessed with respect to the total parameter estimation mean squared

error and by the mean square forecast error. Their study also confirmed that the variance of the QMLE of the long memory parameter δ is $\frac{\pi^2}{24T}$. A further development illustrated that the QMLE approach based on the truncated MA or AR representation outperformed traditional ARIMA and AR models for time series, such

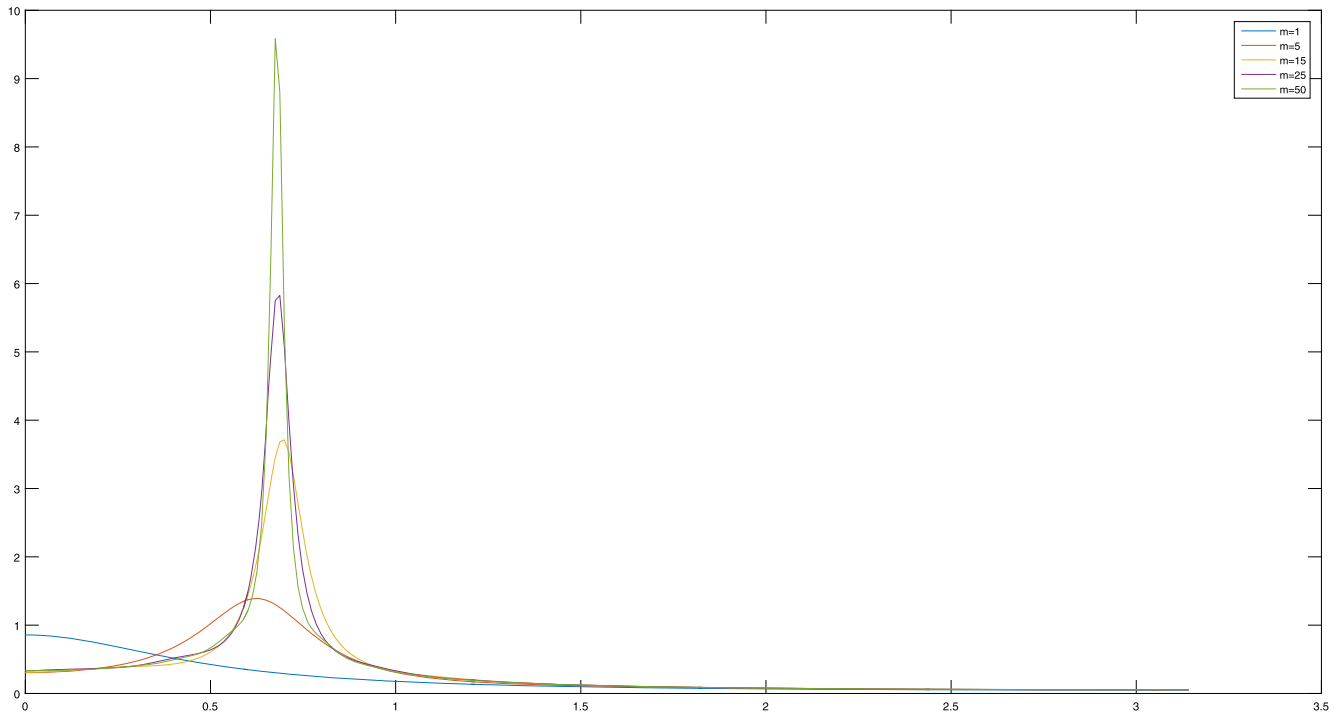


FIG. 4. Spectral densities of estimated AR approximating GARMA(0, δ , 0) models with different lag orders.

as the Wolfer’s sunspots numbers. The meta-analytical comparison was performed with established model results available in the literature; the optimal m value was established by performing a rolling pseudo-real time forecasting experiment and by choosing the value that minimised the one-step-ahead mean square forecast error (see [Dissanayake, Peiris and Proietti, 2016](#), for further details). These developments motivated the authors to apply the methodology to seasonal processes, which is the topic of Section 4.3.

4.3 Seasonal Fractional Gegenbauer Processes

The presence of long range dependence in the seasonal behaviour is a well-established phenomenon for environmental and economic time series. It has been observed in riverflows ([Montanari, Rosso and Taqqu, 2000](#)), monetary aggregates (see [Porter-Hudak, 1990](#)), time series of revenues ([Ray, 1993](#)), inflation rates ([Hassler and Wolters, 1995](#)), quarterly gross national product and shipping data ([Ooms, 1995](#)).

Several statistical modelling methodologies have been developed, among which we mention the fractional Gaussian noise process of [Abrahams and Dempster \(1979\)](#), the seasonal fractionally integrated autoregressive moving average (SARFIMA) model of [Porter-Hudak \(1990\)](#), the flexible seasonal fractionally integrated process (flexible ARFISMA) of [Hassler \(1994\)](#), the k -GARMA process of [Woodward, Cheng and Gray \(1998\)](#), the seasonal long range dependent process of [Palma and Chan \(2005\)](#), the seasonal fractionally integrated process of [Reisen, Rodrigues and Palma \(2006\)](#) and the seasonal ARFIMA model of [Bisognin and Lopes \(2009\)](#). Statistical inference for seasonal long memory processes has been dealt with by [Giraitis and Leipus \(1995\)](#), [Chung \(1996\)](#), [Arteche and Robinson \(2000\)](#), [Velasco and Robinson \(2000\)](#), [Giraitis, Hidalgo and Robinson \(2001\)](#), [Palma \(2007\)](#), [Arteche \(2007\)](#), [Koopman, Ooms and Carnero \(2007\)](#), [Bisognin and Lopes \(2009\)](#), [Hsu and Tsai \(2009\)](#) and [Arteche \(2012\)](#).

Let s denote the seasonal period (e.g., $s = 7$ for a weekly seasonal component in daily data). The seasonal changes are defined as $X_t - X_{t-s} = (1 - B^s)X_t$. The seasonal lag polynomial $(1 - B^s)$ has s' roots,

$$(18) \quad \zeta_k = \cos(\omega_k) + \iota \sin(\omega_k),$$

where $\omega_k = 2k\pi/s, k = 0, 1, 2, \dots, s' - 1$.

This implies the following factorization:

$$\begin{aligned} (1 - B^s) &= (-1)^{s+1} \prod_{k=0}^{s-1} (\zeta_k - B) \\ &= \begin{cases} (1 - B) \prod_{k=1}^{(s-1)/2} (1 - 2 \cos(\omega_k)B + B^2) & s \text{ is odd,} \\ (1 - B)(1 + B) \prod_{k=1}^{(s/2)-1} (1 - 2 \cos(\omega_k)B + B^2) & s \text{ is even.} \end{cases} \end{aligned}$$

A seasonal fractional Gegenbauer process of order δ_s is defined as

$$(19) \quad (1 - B^s)^{\delta_s} X_t = \epsilon_t, \quad \epsilon_t \sim \text{WN}(0, \sigma^2).$$

The seasonal behaviour is due to the presence of $\lfloor s/2 \rfloor$ factors representing Gegenbauer polynomials defined at the frequencies $\omega_k = 2\pi k/s, k = 1, \dots, \lfloor s/2 \rfloor$, characterised by the same fractional integration order. A possible generalization allows for a Gegenbauer factor with angular frequency ω_0 :

$$(1 - B^s)^{\delta_s} (1 - 2uB + B^2)^{\delta} X_t = \epsilon_t.$$

The extension of the state space modelling approach to seasonal GARMA processes can be performed by considering the AR(m) or MA(m) approximations to (4.3), obtained by truncating at m th lag the infinite polynomials

$$(1 - B^s)^{\delta_s} (1 - 2uB + B^2)^{\delta} = \sum_{j=0}^{\infty} \pi_j B^j,$$

and

$$(1 - B^s)^{-\delta_s} (1 - 2uB + B^2)^{-\delta} = \sum_{j=0}^{\infty} \psi_j B^j.$$

5. MODELLING THE PERSISTENCE IN THE CONDITIONAL VARIANCE

An important generalization of GARMA processes aims at modelling the conditional heteroscedasticity of the error process. This is relevant for the analysis and interval and density forecasting of electricity prices.

Most econometric models dealing with the persistence in the conditional variance are based on the

class of generalized autoregressive conditional heteroscedasticity (GARCH) models. When the conditional mean is modelled via a GARMA(p, δ, q) process, as in [Dissanayake and Peiris \(2011\)](#), the following GARMA(p, δ, q)–GARCH(r, s) representation arises:

$$\begin{aligned}
 &\phi(B)(1 - 2uB + B^2)^\delta X_t = \theta(B)\epsilon_t, \\
 &\epsilon_t = \sigma_t \varepsilon_t, \quad \varepsilon_t \sim \text{i.i.d. } N(0, 1), \\
 &\sigma_t^2 = \alpha_0 + \sum_{j=1}^r \alpha_j \epsilon_{t-j}^2 + \sum_{j=1}^s \beta_j \sigma_{t-j}^2,
 \end{aligned}
 \tag{20}$$

with $\alpha_0 > 0$, $\alpha_j \geq 0$, $j = 1, \dots, r$, $\beta_j \geq 0$, $j = 1, \dots, s$.

A unique member of this class, named as the ARFIMA($0, 2\delta, 0$)–GARCH(r, s) model, was studied in detail by [Ling and Li \(1997\)](#), who have shown that there exists a unique \mathcal{F}_t -measurable second-order stationary solution $\{\varepsilon_t, X_t\}$, where \mathcal{F}_t is the filtration generated by the history of the process.

[Dissanayake, Peiris and Proietti \(2014\)](#) extended the theory to the more general GARMA($0, \delta, 0$)–GARCH(r, s) case, showing that, under the assumptions $|u| < 1$, $0 < \delta < \frac{1}{2}$ and $\sum_{i=1}^r \alpha_i + \sum_{j=1}^s \beta_j < 1$, there exists an \mathcal{F}_t -measurable second-order stationary solution $\{\epsilon_t, X_t\}$ with causal representations

$$\epsilon_t = \varepsilon_t \left\{ \alpha_0 + \sum_{j=1}^{\infty} D^T \left(\prod_{i=1}^j A_{t-i} \right) \mathcal{E}_{t-j} \right\}^{1/2} \quad \text{a.s.},$$

and

$$\begin{aligned}
 X_t &= \sum_{k=0}^{\lfloor M/2 \rfloor} (-1)^k \\
 &\cdot \frac{(2u)^{M-2k} (\delta + M - k)!}{k!(\delta - 1)!(M - 2k)!} \epsilon_{t-k} \quad \text{a.s.},
 \end{aligned}
 \tag{22}$$

where $\mathcal{E}_t = (\alpha_0 \varepsilon_t^2, 0, \dots, 0, \alpha_0, 0, \dots, 0)'$, an $(r + s) \times 1$ vector with nonzero first and $(r + 1)$ th components, M is a fixed integer based on the required number of binomial coefficients, $D = (\alpha_1, \dots, \alpha_r, \beta_1, \dots, \beta_s)'$, and

$$A_t = \left[\begin{array}{ccc|ccc}
 \alpha_1 \varepsilon_t^2 & \cdots & \alpha_r \varepsilon_t^2 & \beta_1 \varepsilon_t^2 & \cdots & \beta_s \varepsilon_t^2 \\
 \hline
 I_{(r-1) \times (r-1)} & & O_{(r-1) \times 1} & & O_{(r-1) \times s} & \\
 \hline
 \alpha_1 & \cdots & \alpha_r & \beta_1 & \cdots & \beta_s \\
 \hline
 O_{(s-1) \times r} & & & I_{(s-1) \times (s-1)} & & O_{(s-1) \times 1}
 \end{array} \right],$$

and $I_{r \times r}$ is the $r \times r$ identity matrix.

Additionally, letting $\{X_{t,m}\}$ denote the MA(m) approximating process, $X_{t,m} = \sum_{k=0}^m C_k \epsilon_{t-k}$. Under the above assumptions and suitable regularity conditions,

[Dissanayake, Peiris and Proietti \(2014\)](#) show the convergence of $X_{t,m}$ to X_t . This opens the way to inference via the state space approach discussed in Section 4, suitably extended to handle conditional heteroscedasticity. Table 2 reports the results of a Monte Carlo experiment aiming at assessing the accuracy of the quasi maximum likelihood estimates based on the state space approach. The results are based on 1000 replications from a GARMA($0, \delta, 0$)–GARCH($1, 1$) process with $\delta = 0.3$, $u = 0.8$, $\alpha_0 = 0.4$, $\alpha_1 = 0.3$, $\beta_1 = 0.3$. The order of the MA and AR approximation have been chosen each time according to a rolling forecasting experiment as the value that is optimal for out of sample predictability.

An interesting fact that was observed is that the performance of the estimator of the memory parameter and the selection of the optimal m th order approximation is unaffected by the volatility clustering in ε_t .

Another use of Gegenbauer processes is in modelling the long range dependence of the volatility of financial time series. Several studies report evidence of long memory in empirical volatility returns, as illustrated by [Robinson \(1991\)](#), [Shephard \(1996\)](#), [Lobato and Savin \(1998\)](#) and [Baillie \(1996\)](#). A new class of GIGARCH was introduced by [Guegan \(2000\)](#) to model volatility with generalized fractional integration. [McAleer and Medeiros \(2008\)](#) proposed a flexible model to describe nonlinearities and long memory in time series dynamics for the purpose of forecasting volatility. [Lieberman and Phillips \(2008\)](#) have provided some analytical explanations for long memory behaviour that has been observed in realized volatility. An elegant and parsimonious way of approximating the long memory behaviour of time series of realized volatility measures through a restricted autoregressive model was proposed by [Corsi \(2009\)](#).

6. TESTING GARMA(0, δ, 0) PROCESSES

A stochastic process X_t is said to be integrated of order δ , denoted $X_t \sim I(\delta)$, if $(1 - B)^\delta X_t$ is a stationary process with absolutely summable autocorrelation function. This definition encompasses that of an $I(1)$ process, which is such that $(1 - B)X_t$ is stationary and short memory. Also, a stationary short memory process will be said to be integrated of order zero, denoted $X_t \sim I(0)$.

The problem of testing whether $X_t \sim I(1)$ versus the alternative $X_t \sim I(0)$ is illustrated by [Phillips and Xiao \(1998\)](#). It is often found that both the null and the alternative hypotheses are rejected, suggesting that many

TABLE 2

Monte Carlo simulation of a GARMA(0, δ , 0)–GARCH(1, 1) process with $\delta = 0.3$, $u = 0.8$, $\alpha_0 = 0.4$, $\alpha_1 = 0.3$, $\beta = 0.3$. Accuracy of the QMLE parameter estimates, based on 1000 replications (SE = Standard Error, MSE = Mean Square Error)

T = 1000										
	MA approximation					AR approximation				
	$\hat{\delta}$	\hat{u}	$\hat{\alpha}_0$	$\hat{\alpha}_1$	$\hat{\beta}_1$	$\hat{\delta}$	\hat{u}	$\hat{\alpha}_0$	$\hat{\alpha}_1$	$\hat{\beta}_1$
Mean	0.306	0.788	0.430	0.264	0.296	0.305	0.792	0.424	0.273	0.293
SE	0.082	0.130	0.149	0.180	0.098	0.081	0.126	0.148	0.184	0.096
MSE	0.006	0.017	0.023	0.033	0.009	0.006	0.016	0.022	0.034	0.009
T = 2000										
Mean	0.299	0.804	0.403	0.296	0.300	0.299	0.804	0.403	0.296	0.299
SE	0.018	0.022	0.050	0.063	0.034	0.020	0.028	0.052	0.065	0.034
MSE	0.0004	0.0008	0.002	0.004	0.001	0.0003	0.0005	0.002	0.004	0.001

series are not well represented by both the $I(0)$ and $I(1)$ hypotheses.

The definition can be extended to allow for integration at any frequency in the range $(0, \pi)$. In particular, we will say that X_t is integrated of order δ at the frequency ω_0 , denoted $I(\delta, \omega_0)$ if $(1 - 2uB + B^2)^\delta X_t$ admits a stationary short memory representation, where $u = \cos(\omega_0)$.

We will focus on the following testing problems:

1. Test $H_0 : X_t \sim I(2\delta, 0)$, versus $H_1 : X_t \sim I(\delta, \omega_0)$, $\omega_0 \in (0, \pi)$.
2. Test $H_0 : X_t \sim I(0.5, \omega_0)$ versus $H_1 : X_t \sim I(\delta, \omega_0)$, $\delta < 0.5$.

We can equivalently reparameterize the first case in terms of u , with $H_0 : u = 1$ and $H_1 : |u| < 1$. Under the null, the process is a standard long memory process with fractional integration order 2δ , whereas under the alternative it is a Gegenbauer process integrated at an angular frequency different from zero. Hence, the first case is a test for the presence of a stochastic persistent cycle. In the second case, we test whether the Gegenbauer process nonstationary at the frequency ω_0 , versus the alternative that it is stationary, with fractional order $\delta < 0.5$.

Chung (1996) performed these testing problems, basing the inference on a conditional sum of squares estimation method. The approach that is taken by Dissanayake, Peiris and Proietti (2015) and Dissanayake et al. (2015) is based on the quasi-likelihood ratio (QLR) test arising from the maximized likelihood of the MA or AR approximations both under the null and the alternative. The QLR approach can

be justified by the theoretical constructs of equations (13), (14) and the description of Section 4.1.

Consider the GARMA(0, δ , 0) process model defined in (1), with $\epsilon_t \sim \text{i.i.d. } N(0, \sigma^2)$. The Gegenbauer polynomial could be written as

$$1 - 2uB + B^2 = [2(u - 1)\varphi(\Delta - 1) + \Delta^2],$$

where $\Delta = (1 - B)$, so that we can reparameterize the process as follows:

$$[2(u - 1)(\Delta - 1) + \Delta^2]^\delta X_t = \epsilon_t.$$

The test of $H_0 : u = 1$ (under which the true model is $\Delta^{2\delta} X_t = \epsilon_t$), versus $H_1 : u < 1$ [under which the process is integrated of order δ at the frequency $\omega_0 = \arccos(u)$], is

$$LR_T^u = \max[\ell_{\sigma_m^2}(\delta, u)] - \max[\ell_{\sigma_m^2}(\delta, 1)],$$

where the profile likelihood is given in (17). The distribution of the test statistic is nonstandard, as u lies on the boundary of the parameter space; see Dissanayake, Peiris and Proietti (2015) for more details.

As far as the test of nonstationarity is concerned, $H_0 : \delta = 0.5$, the quasi-likelihood ratio test statistic is

$$LR_T^\delta = \max[\ell_{\sigma_m^2}(\delta, u)] - \max[\ell_{\sigma_m^2}(1/2, u)],$$

Again, the distribution of the test statistic is nonstandard and we refer to Dissanayake et al. (2015) for further details.

Following Jansson and Nielsen (2012), Dissanayake, Peiris and Proietti (2015) and Dissanayake et al. (2015) explore the power properties of their quasi-likelihood ratio test. Their evidence is that the power of the tests are reasonable and comparable with those presented in

Beaumont and Ramachandran (2001). For testing the fractional order of seasonal and nonseasonal unit roots of long memory processes, see Ferrara, Guegan and Lu (2010).

The QMLE rests on the Gaussian assumption and the ability to select the optimal order of the approximation. In the case of GARMA processes with GARCH disturbances, an important issue would be assessing the robustness of the estimation and the testing of deviation procedures from Gaussianity. It does not come under the purview of this paper and would be a worthwhile exercise for a proactive researcher in statistics or econometrics.

7. CONCLUDING REMARKS

The facts provided in this review highlight certain gaps in the literature linked with fractionally differenced long memory Gegenbauer processes. Relevant model formulation, state space based estimation and a related nearly efficient unit root testing procedure have been investigated. New results have been presented in the discussion of this paper to encourage further research within the statistical and econometric communities.

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