

Remarks on spectral gaps on the Riemannian path space*

Shizan Fang[†] Bo Wu[‡]

Abstract

In this paper, we will give some remarks on links between the spectral gap of the Ornstein-Uhlenbeck operator on the Riemannian path space with lower and upper bounds of the Ricci curvature on the base manifold; this work was motivated by a recent work of A. Naber on the characterization of the bound of the Ricci curvature by analysis of path spaces.

Keywords: damped gradient; martingale representation; Ricci curvature; spectral gap; small time behaviour.

AMS MSC 2010: 58J60; 60H07; 60J60.

Submitted to ECP on March 10, 2016, final version accepted on February 27, 2017.

Supersedes arXiv:1508.07657.

Supersedes HAL:hal-01192833.

1 Introduction

Let M be a complete smooth Riemannian manifold of dimension d , and Z a C^1 -vector field on M . We will be concerned with the diffusion operator

$$L = \frac{1}{2}(\Delta_M - Z),$$

where Δ_M is the Beltrami-Laplace operator on M . Let ∇ be the Levi-Civita connection and Ric the Ricci curvature tensor on M . We will denote

$$\text{Ric}_Z = \text{Ric} + \nabla Z.$$

It is well-known that the lower bound K_2 of the symmetrized Ric_Z^s , that is,

$$\text{Ric}_Z^s(x) = \frac{1}{2}(\text{Ric}_Z(x) + \text{Ric}_Z^*(x)) \geq K_2 \text{Id}, \quad (1.1)$$

where Ric_Z^* denotes the transposed matrix of Ric_Z , gives the lower bound of constants in the logarithmic Sobolev inequality with respect to the heat measure $\rho_t(x, dy)$, associated to L ; more precisely,

$$\int_M u^2(y) \log\left(\frac{u^2(y)}{\|u\|_{\rho_t}^2}\right) \rho_t(x, dy) \leq 2 \frac{1 - e^{-K_2 t}}{K_2} \int_M |\nabla u(y)|^2 \rho_t(x, dy), \quad t > 0, \quad (1.2)$$

*Supported in part by Creative Research Group Fund of the National Natural Science Foundation of China (No. 10121101) and RFDP(20040027009).

[†]I.M.B, BP 47870, Université de Bourgogne, Dijon, France. E-mail: fang@u-bourgogne.fr

[‡]Department of Mathematics, Fudan University, Shanghai, China.

E-mail: wubo@fudan.edu.cn

where $\|u\|_{\rho_t}^2 = \int_M u^2(y) \rho_t(x, dy)$.

Given now a finite number of times $0 < t_1 < \dots < t_N$, consider the probability measure ν_{t_1, \dots, t_N} on M^N defined by

$$\int_{M^N} f d\nu_{t_1, \dots, t_N} = \int_{M^N} f(y_1, \dots, y_N) p_{t_1}(x, dy_1) p_{t_2-t_1}(y_1, dy_2) \cdots p_{t_N-t_{N-1}}(y_{N-1}, dy_N) \tag{1.3}$$

where f is a bounded measurable function on M^N . Then with respect to the correlated metric $|\cdot|_C$ on TM^N (see definition (1.10) below), the logarithmic Sobolev inequality still holds for ν_{t_1, \dots, t_N} , that is, there is a constant $C_N > 0$ such that

$$\int_{M^N} f^2 \log\left(\frac{f^2}{\|f\|_{\nu_{t_1, \dots, t_N}}^2}\right) d\nu_{t_1, \dots, t_N} \leq C_N \int_{M^N} |\nabla f|_C^2 d\nu_{t_1, \dots, t_N}, \quad f \in C^1(M^N). \tag{1.4}$$

It was proved in [20, 6] that under the hypothesis

$$\sup_{x \in M} \|\text{Ric}_Z(x)\| < +\infty, \tag{1.5}$$

where $\|\cdot\|$ denotes the norm of matrices, the constant C_N in (1.4) can be bounded, that is

$$\sup_{N \geq 1} C_N < +\infty. \tag{1.6}$$

A natural question is whether (1.6) still holds only under Condition (1.1)? In a recent work [21], A. Naber proved that if the uniform bound (1.6) holds, then the Ricci curvature of the base manifold has an upper bound. It is well-known that Inequality (1.2) implies the lower bound (1.1), therefore Condition (1.6) implies (1.5). The main purpose in [21] is to get informations on Ric_Z from the analysis of the Riemannian path space. Let's explain briefly the context.

Let $O(M)$ be the bundle of orthonormal frames and $\pi : O(M) \rightarrow M$ the canonical projection. Let H_1, \dots, H_d be the canonical horizontal vector fields on $O(M)$, consider the Stratanovich stochastic differential equation (SDE) on $O(M)$:

$$du_t(w) = \sum_{i=1}^d H_i(u_t(w)) \circ dw_t^i - \frac{1}{2} H_Z(u_t(w)) dt, \quad u_0(w) = u_0 \in \pi^{-1}(x), \tag{1.7}$$

where H_Z denotes the horizontal lift of Z to $O(M)$, that is, $\pi'(u) \cdot H_Z(u) = Z(\pi(u))$. It is well-known that under Condition (1.1), the life-time τ_x of the SDE (1.7) is infinite. Let

$$\gamma_t(w) = \pi(u_t(w)). \tag{1.8}$$

Then $\{\gamma_t(w); t \geq 0\}$ is a diffusion process on M , having L as generator. The probability measure ν_{t_1, \dots, t_N} considered in (1.3) is the law of $w \rightarrow (\gamma_{t_1}(w), \dots, \gamma_{t_N}(w))$ on M^N . Now consider the following path space

$$W_x^T(M) = \{\gamma : [0, T] \rightarrow M \text{ continuous, } \gamma(0) = x\}.$$

The law $\mu_{x,T}$ on $W_x^T(M)$ of $w \rightarrow \gamma_t(w)$ is called the Wiener measure on $W_x^T(M)$. The integration by parts formula for $\mu_{x,T}$ was first established in the seminal book [5], then developed in [16, 10]; the Cameron-Martin type quasi-invariance of $\mu_{x,T}$ was first proved by B. Driver [9], completed and simplified in [18, 19, 13]. We consider the Cameron-Martin space

$$\mathbb{H} = \left\{ h : [0, T] \rightarrow \mathbb{R}^d \text{ absolutely continuous; } h(0) = 0, |h|_{\mathbb{H}}^2 = \int_0^T |\dot{h}(s)|_{\mathbb{R}^d}^2 ds < +\infty \right\}$$

where the dot denotes the derivative with respect to the time t . Let $F : W_x^T(M) \rightarrow \mathbb{R}$ be a cylindrical function in the form: $F(\gamma) = f(\gamma(t_1), \dots, \gamma(t_N))$ for some $N \geq 1, 0 \leq t_1 < t_2 < \dots < t_N \leq 1$, and $f \in C_b^1(M^N)$. The usual gradient of F in Malliavin calculus is defined by

$$D_\tau F(\gamma(w)) = \sum_{j=1}^N u_{t_j}(w)^{-1} (\partial_j f)(\gamma_{t_1}(w), \dots, \gamma_{t_N}(w)) \mathbf{1}_{(\tau \leq t_j)}, \quad (1.9)$$

where ∂_j is the gradient with respect to the j -th component. The correlated norm of ∇f is

$$|\nabla f|_C^2 = \sum_{j,k=1}^N \langle u_{t_j}(w)^{-1} (\partial_j f), u_{t_k}(w)^{-1} (\partial_k f) \rangle t_j \wedge t_k, \quad (1.10)$$

where $t_j \wedge t_k$ denotes the minimum between t_j and t_k . Notice that the norm $|\nabla f|_C$ is random. The generator \mathcal{L}_T^x associated to the Dirichlet form

$$\mathcal{E}(F, F) = \int_{W_x^T(M)} \left(\int_0^T |D_\tau F|^2(\gamma) d\tau \right) d\mu_{x,T}(\gamma)$$

is called the Ornstein-Uhlenbeck operator. The powerful tool of Γ_2 of Bakry and Emery [3] is not applicable to \mathcal{L}_T^x , the reason for this is the geometry of $W_x^T(M)$ inherited from \mathbb{H} is quite complicated, the associated ‘‘Ricci tensor’’ being a divergent object (see [7, 8, 12]). When the base manifold M is compact, the existence of the spectral gap for \mathcal{L}_T^x has been proved in [14]. The logarithmic Sobolev inequality for $D_\tau F$ defined in (1.9) has been established in [2], as well as in [20] or [6] where the constant was estimated using the bound of Ricci curvature tensor of the base manifold M . The method used in [14] is the martingale representation, which takes advantage the Itô filtration; this method has been developed in [12] to deal with the problem of vanishing of harmonic forms on $W_x^T(M)$. The purpose in [21] is to proceed in the opposite direction, to get the bound for Ricci curvature tensor of the base manifold M from the analysis of the path space $W_x^T(M)$.

The organization of the paper is as follows. In section 2, we will recall briefly basic objects in Analysis of $W_x^T(M)$. On the path space $W_x^T(M)$, there exist two type of gradients: the usual one is more related to the geometry of the base manifold, while the damped one is easy to be handled. In section 3, we will make estimation of the spectral gap of \mathcal{L}_T^x as explicitly as possible in function of lower bound K_2 and upper bound K_1 of Ric. In section 4, we will study the behaviour of the spectral gap $SG(\mathcal{L}_T^x)$ as $T \rightarrow 0$. Roughly speaking, we will get the following result:

$$1 - \frac{K_1 T}{2} + o(T) \leq SG(\mathcal{L}_T^x) \leq 1 + \frac{K_2 T}{2} + o(T), \quad \text{as } T \rightarrow 0$$

under the following condition (4.1).

2 Framework of the Riemannian path space

We shall keep the notations of Section 1, and throughout this section, $u_t(w)$ denotes always the solution of (1.7) and $\gamma_t(w)$ the path defined in (1.8). For any $h \in \mathbb{H}$, we introduce first the usual gradient on the path space $W_x^T(M)$, which gives Formula (1.9) when the functional F is a cylindrical function. To this end, let

$$q(t, h) = \int_0^t \Omega_{u_s(w)} \left(h(s), \circ dw(s) - \frac{1}{2} u_s(w)^{-1} Z_{\gamma_s(w)} ds \right) \quad (2.1)$$

where Ω_u is the equivariant representation of the curvature tensor on M . Let \mathbf{ric}_Z be the equivariant representation of Ric_Z , that is,

$$\mathbf{ric}_Z(u) = u^{-1} \circ \text{Ric}_Z(\pi(u)) \circ u, \quad u \in O(M).$$

Consider $\hat{h}(w) \in \mathbb{H}$ defined by

$$\dot{\hat{h}}_t(w) = \dot{h}(t) + \frac{1}{2} \mathbf{ric}_Z(u_t(w)) h(t). \tag{2.2}$$

Let $F : W_x^T(M) \rightarrow \mathbb{R}$ be a functional, we denote $\tilde{F}(w) = F(\gamma.(w))$. Then according to [16], we define

$$(D_h F)(\gamma.(w)) = \left\{ \frac{d}{d\varepsilon} \tilde{F} \left(\int_0^{\cdot} e^{\varepsilon q(s,h)} dw(s) + \varepsilon \hat{h} \right) \right\}_{\varepsilon=0}. \tag{2.3}$$

By [5, 16], if F is a cylindrical function on $W_x^T(M)$, then

$$(D_h F)(\gamma.(w)) = \int_0^T \langle D_\tau F(\gamma.(w)), \dot{h}(\tau) \rangle d\tau$$

where $D_\tau F$ was given in (1.9). Consider the following resolvent equation

$$\frac{dQ_{t,s}}{dt} = -\frac{1}{2} \mathbf{ric}_Z(u_t(w)) Q_{t,s}, \quad t \geq s, \quad Q_{s,s} = \text{Id}. \tag{2.4}$$

For a cylindrical function F on $W_x^T(M)$ given by $F(\gamma) = f(\gamma(t_1), \dots, \gamma(t_N))$ with $f \in C_b^1(M^N)$, following [16], we define the damped gradient $\tilde{D}_\tau F$ of F by

$$\tilde{D}_\tau F(\gamma.(w)) = \sum_{j=1}^N Q_{t_j, \tau}^* (u_{t_j}(w)^{-1} \partial_j f) \mathbf{1}_{(\tau \leq t_j)}, \tag{2.5}$$

where $Q_{\tau,s}^*$ is the transpose matrix of $Q_{\tau,s}$. The damped gradient $\tilde{D}_\tau F$ on the path space $W_x^T(M)$ plays a basic role in analysis of $W_x^T(M)$. Let $(v_t)_{t \geq 0}$ be a \mathbb{R}^d -valued process, adapted to the Itô filtration \mathcal{F}_t generated by $\{w(s); s \leq t\}$ such that $\mathbb{E}(\int_0^T |v_t|^2 dt) < +\infty$. Consider two maps $v \rightarrow \tilde{v}$ and $v \rightarrow \hat{v}$ defined respectively by

$$\tilde{v}_t = v_t - \frac{1}{2} \mathbf{ric}_{u_t(w)} \int_0^t Q_{t,s} v_s ds, \tag{2.6}$$

and

$$\hat{v}_t = v_t + \frac{1}{2} \mathbf{ric}_{u_t(w)} \int_0^t v_s ds. \tag{2.7}$$

Then $\hat{\tilde{v}} = \hat{v} = v$. The two gradients $D_t F$ and $\tilde{D}_t F$ are linked by the following formula

$$\int_0^T \langle \tilde{D}_t F, v_t \rangle dt = \int_0^T \langle D_t F, \tilde{v}_t \rangle dt. \tag{2.8}$$

The good feature of the damped gradient is that it admits a nice martingale representation

$$F = \mathbb{E}(F) + \int_0^T \langle \mathbb{E}^{\mathcal{F}_t}(\tilde{D}_t F), dw_t \rangle$$

where $\mathbb{E}^{\mathcal{F}_t}$ denotes the conditional expectation with respect to \mathcal{F}_t . The following logarithmic Sobolev inequality holds ([11, 17]):

$$\mathbb{E} \left(F^2 \log \frac{F^2}{\|F\|_{L^2}^2} \right) \leq 2 \mathbb{E} \left(\int_0^T |\tilde{D}_t F|^2 dt \right). \tag{2.9}$$

3 Precise lower bound on the spectral gap

The inconvenient of Inequality (2.9) is that the geometric information of the base manifold M is completely hidden. Now we use the usual gradient $D_t F$ to make involving the geometry of M . By (2.9), the matter is now to estimate $\int_0^T |\tilde{D}_t F|^2 dt$ by $|D_t F|$. We assume that

$$K_2 \text{Id} \leq \mathbf{ric}_Z^s, \quad \|\mathbf{ric}_Z\| \leq K_1 \quad (3.1)$$

for two constants K_1, K_2 with $K_1 \geq 0$ and $K_1 + K_2 \geq 0$.

Theorem 3.1. *Let $0 < t \leq T$. Set*

$$\begin{aligned} \Lambda(t, T) = & 1 + \frac{K_1}{K_2} \left(1 - e^{-\frac{K_2(T-t)}{2}}\right) + \frac{K_1}{K_2} \left(1 - e^{-\frac{K_2 t}{2}}\right) \\ & + \left(\frac{K_1}{K_2}\right)^2 \left[\left(1 - e^{-\frac{K_2 t}{2}}\right) + \frac{1}{2} \left(e^{-\frac{K_2(T+t)}{2}} - e^{-\frac{K_2(T-t)}{2}}\right) \right]. \end{aligned} \quad (3.2)$$

Then we have the relation:

$$\int_0^T |\tilde{D}_t F|^2 dt \leq \int_0^T \Lambda(t, T) |D_t F|^2 dt. \quad (3.3)$$

Proof. From (2.5) and (2.8), we have

$$\tilde{D}_t F = D_t F - \frac{1}{2} \int_t^T Q_{s,t}^* \text{ric}_{u_s}^* D_s F ds. \quad (3.4)$$

Thus,

$$\begin{aligned} |\tilde{D}_t F|^2 &= |D_t F|^2 - \left\langle D_t F, \int_t^T Q_{s,t}^* \text{ric}_{u_s}^* D_s F ds \right\rangle + \frac{1}{4} \left| \int_t^T Q_{s,t}^* \text{ric}_{u_s}^* D_s F ds \right|^2 \\ &:= I_1 + I_2 + I_3 \text{ respectively.} \end{aligned}$$

In the following we will estimate the term of I_2 and I_3 . Under the lower bound in (3.1),

$$\|Q_{s,t}^*\| \leq e^{-\frac{K_2(s-t)}{2}}, \quad s \geq t.$$

Let

$$\Lambda_1(t, T) := \int_t^T \left(e^{-\frac{K_2(s-t)}{4}} \right)^2 ds.$$

Then

$$\begin{aligned} |I_2| &\leq |D_t F| \int_t^T e^{-\frac{K_2(s-t)}{2}} K_1 |D_s F| ds \\ &\leq |D_t F| \sqrt{K_1 \int_t^T \left(e^{-\frac{K_2(s-t)}{4}} \right)^2 ds} \sqrt{K_1 \int_t^T e^{-\frac{K_2(s-t)}{2}} |D_s F|^2 ds} \\ &= |D_t F| \sqrt{K_1 \Lambda_1(t, T)} \sqrt{K_1 \int_t^T e^{-\frac{K_2(s-t)}{2}} |D_s F|^2 ds} \\ &\leq \frac{1}{2} \left\{ |D_t F|^2 K_1 \Lambda_1(t, T) + K_1 \int_t^T e^{-\frac{K_2(s-t)}{2}} |D_s F|^2 ds \right\}. \end{aligned}$$

and

$$\begin{aligned} |I_3| &\leq \frac{1}{4} \left| \int_t^T e^{-\frac{K_2(s-t)}{2}} K_1 |D_s F| ds \right|^2 \\ &\leq \frac{1}{4} K_1^2 \Lambda_1(t, T) \int_t^T e^{-\frac{K_2(s-t)}{2}} |D_s F|^2 ds. \end{aligned}$$

Combining all the above inequalities, we get

$$\begin{aligned} |\tilde{D}_t F|^2 &\leq \left(1 + \frac{K_1}{2} \Lambda_1(t, T)\right) |D_t F|^2 + \left(1 + \frac{K_1}{2} \Lambda_1(t, T)\right) \frac{K_1}{2} \int_t^T e^{-\frac{K_2(s-t)}{2}} |D_s F|^2 ds \\ &= \left(1 + \frac{K_1}{2} \Lambda_1(t, T)\right) \left(|D_t F|^2 + \frac{K_1}{2} \int_t^T e^{-\frac{K_2(s-t)}{2}} |D_s F|^2 ds\right). \end{aligned}$$

Therefore, we obtain

$$\begin{aligned} \int_0^T |\tilde{D}_t F|^2 dt &\leq \int_0^T \left(1 + \frac{K_1}{2} \Lambda_1(t, T)\right) |D_t F|^2 dt \\ &\quad + \int_0^T \left(1 + \frac{K_1}{2} \Lambda_1(t, T)\right) \frac{K_1}{2} \int_t^T e^{-\frac{K_2(s-t)}{2}} |D_s F|^2 ds dt \\ &= \int_0^T \left(1 + \frac{K_1}{2} \Lambda_1(s, T)\right) |D_s F|^2 ds \\ &\quad + \int_0^T |D_s F|^2 ds \int_0^s \frac{K_1}{2} \left(1 + \frac{K_1}{2} \Lambda_1(t, T)\right) e^{-\frac{K_2(s-t)}{2}} dt \\ &:= \int_0^T \left(1 + \frac{K_1}{2} \Lambda_1(s, T)\right) |D_s F|^2 ds + \int_0^T (J_1(s) + J_2(s)) |D_s F|^2 ds, \end{aligned}$$

where

$$J_1(s) := \int_0^s \frac{K_1}{2} e^{-\frac{K_2(s-t)}{2}} dt, \quad J_2(s) := \int_0^s \left(\frac{K_1}{2}\right)^2 \Lambda_1(t, T) e^{-\frac{K_2(s-t)}{2}} dt.$$

Next, then we compute the term $J_1(s)$ and $J_2(s)$. By direct computation, we have

$$J_1(s) = \frac{K_1}{K_2} \left(1 - e^{-\frac{K_2 s}{2}}\right)$$

and

$$\begin{aligned} J_2(s) &= \left(\frac{K_1}{2}\right)^2 \int_0^s \frac{2}{K_2} \left(1 - e^{-\frac{K_2(T-t)}{2}}\right) e^{-\frac{K_2(s-t)}{2}} dt \\ &= \left(\frac{K_1}{2}\right)^2 \frac{2}{K_2} \left[\int_0^s e^{-\frac{K_2(s-t)}{2}} dt - e^{-\frac{K_2(T+s)}{2}} \int_0^s e^{K_2 t} dt \right] \\ &= \left(\frac{K_1}{2}\right)^2 \frac{2}{K_2} \left[\frac{2}{K_2} \left(1 - e^{-\frac{K_2 s}{2}}\right) - \frac{1}{K_2} e^{-\frac{K_2(T+s)}{2}} (e^{K_2 s} - 1) \right] \\ &= \left(\frac{K_1}{2}\right)^2 \frac{2}{K_2} \left[\frac{2}{K_2} \left(1 - e^{-\frac{K_2 s}{2}}\right) + \frac{1}{K_2} e^{-\frac{K_2(T+s)}{2}} - \frac{1}{K_2} e^{-\frac{K_2(T-s)}{2}} \right]. \end{aligned}$$

Adding $J_1(s)$ to $J_2(s)$ implying that

$$\begin{aligned} J_1(s) + J_2(s) &= \frac{K_1}{K_2} \left(1 - e^{-\frac{K_2 s}{2}}\right) + \left(\frac{K_1}{K_2}\right)^2 \left[\left(1 - e^{-\frac{K_2 s}{2}}\right) + \frac{1}{2} \left(e^{-\frac{K_2(T+s)}{2}} - e^{-\frac{K_2(T-s)}{2}}\right) \right] := \Lambda_2(s, T) \end{aligned}$$

Thus,

$$\int_0^T |\tilde{D}_t F|^2 dt \leq \int_0^T \Lambda(t, T) |D_t F|^2 dt,$$

with

$$\begin{aligned} \Lambda(t, T) &= 1 + \frac{K_1}{2} \Lambda_1(t, T) + \Lambda_2(t, T) \\ &= 1 + \frac{K_1}{K_2} \left(1 - e^{-\frac{K_2(T-t)}{2}}\right) + \frac{K_1}{K_2} \left(1 - e^{-\frac{K_2 t}{2}}\right) \\ &\quad + \left(\frac{K_1}{K_2}\right)^2 \left[\left(1 - e^{-\frac{K_2 t}{2}}\right) + \frac{1}{2} \left(e^{-\frac{K_2(T+t)}{2}} - e^{-\frac{K_2(T-t)}{2}}\right) \right]. \end{aligned}$$

The proof is completed. \square

Notice that as $K_2 \rightarrow 0$, by expression (3.2),

$$\Lambda(t, T) \rightarrow 1 + \frac{K_1 T}{2} + K_1^2 \left(\frac{Tt}{4} - \frac{t^2}{8} \right).$$

Now we study the variation of the function $t \rightarrow \Lambda(t, T)$. It is quite interesting to remark that its monotonicity is dependent of the sign of K_2 .

Proposition 3.2. (i) If $K_2 < 0$, then $t \rightarrow \Lambda(t, T)$ is strictly increasing over $[0, T]$. (ii) If $K_2 > 0$, then the maximum is attained at a point t_0 in $(0, T)$.

Proof. Taking the derivative of $t \rightarrow \Lambda(t, T)$ gives

$$\begin{aligned} \Lambda'(t, T) &= -\frac{K_1}{2} e^{-\frac{K_2(T-t)}{2}} + \frac{K_1}{2} e^{-\frac{K_2 t}{2}} \\ &\quad + \frac{K_1^2}{2K_2} e^{-\frac{K_2 t}{2}} - \frac{K_1^2}{4K_2} e^{-\frac{K_2(T+t)}{2}} - \frac{K_1^2}{4K_2} e^{-\frac{K_2(T-t)}{2}}. \end{aligned}$$

In addition, we have

$$\Lambda(0, T) = 1 + \frac{K_1}{K_2} \left(1 - e^{-\frac{K_2 T}{2}} \right)$$

and

$$\begin{aligned} \Lambda(T, T) &= 1 + \frac{K_1}{K_2} \left(1 - e^{-\frac{K_2 T}{2}} \right) + \left(\frac{K_1}{K_2} \right)^2 \left[\left(1 - e^{-\frac{K_2 T}{2}} \right) + \frac{1}{2} \left(e^{-K_2 T} - 1 \right) \right] \\ &= 1 + \frac{K_1}{K_2} \left(1 - e^{-\frac{K_2 T}{2}} \right) + \frac{1}{2} \left(\frac{K_1}{K_2} \right)^2 \left(1 - e^{-\frac{K_2 T}{2}} \right)^2 \\ &= \frac{1}{2} + \frac{1}{2} \left[1 + \frac{K_1}{K_2} \left(1 - e^{-\frac{K_2 T}{2}} \right) \right]^2 = \frac{1}{2} + \frac{1}{2} \Lambda^2(0, T). \end{aligned}$$

From the second equality in the above, we observe that $\Lambda(T, T) \geq \Lambda(0, T)$. Moreover,

$$\begin{aligned} \Lambda'(0, T) &= -\frac{K_1}{2} e^{-\frac{K_2 T}{2}} + \frac{K_1}{2} + \frac{K_1^2}{2K_2} - \frac{K_1^2}{4K_2} e^{-\frac{K_2 T}{2}} - \frac{K_1^2}{4K_2} e^{-\frac{K_2 T}{2}} \\ &= \frac{K_1}{2} \left(1 - e^{-\frac{K_2 T}{2}} \right) + \frac{K_1^2}{2K_2} \left(1 - e^{-\frac{K_2 T}{2}} \right) \\ &= \frac{K_1}{2} (K_1 + K_2) \frac{1 - e^{-\frac{K_2 T}{2}}}{K_2} \geq 0; \end{aligned} \tag{3.5}$$

and

$$\begin{aligned} \Lambda'(T, T) &= -\frac{K_1}{2} + \frac{K_1}{2} e^{-\frac{K_2 T}{2}} + \frac{K_1^2}{2K_2} e^{-\frac{K_2 T}{2}} - \frac{K_1^2}{4K_2} e^{-K_2 T} - \frac{K_1^2}{4K_2} \\ &= -\frac{K_1}{2} + \frac{K_1}{2} e^{-\frac{K_2 T}{2}} - \frac{K_1^2}{4K_2} \left(1 - 2e^{-\frac{K_2 T}{2}} + e^{-K_2 T} \right) \\ &= -\frac{K_1}{2} \left(1 - e^{-\frac{K_2 T}{2}} \right) - \frac{K_1^2}{4K_2} \left(1 - e^{-\frac{K_2 T}{2}} \right)^2. \end{aligned} \tag{3.6}$$

We see that

$$\begin{cases} \Lambda'(T, T) > 0 & \text{if } K_2 < 0, \\ \Lambda'(T, T) < 0 & \text{if } K_2 > 0. \end{cases} \tag{3.7}$$

Now we look for $t \in [0, T]$ such that $\Lambda'(t, T) = 0$. We have

$$\begin{aligned} \Lambda'(t, T) &= 0 \\ \Leftrightarrow \left(-\frac{K_1}{2} e^{-\frac{K_2 T}{2}} - \frac{K_1^2}{4K_2} e^{-\frac{K_2 T}{2}} \right) e^{K_2 t} + \left(\frac{K_1}{2} + \frac{K_1^2}{2K_2} - \frac{K_1^2}{4K_2} e^{-\frac{K_2 T}{2}} \right) &= 0 \\ \Leftrightarrow -\frac{K_1}{4} e^{-\frac{K_2 T}{2}} \left(2 + \frac{K_1}{K_2} \right) e^{K_2 t} + \frac{K_1}{4} \left(2 + \frac{2K_1}{K_2} - \frac{K_1}{K_2} e^{-\frac{K_2 T}{2}} \right) &= 0 \\ \Leftrightarrow e^{-\frac{K_2 T}{2}} \left(2 + \frac{K_1}{K_2} \right) e^{K_2 t} &= \left(2 + \frac{2K_1}{K_2} - \frac{K_1}{K_2} e^{-\frac{K_2 T}{2}} \right). \end{aligned} \quad (3.8)$$

Therefore there exists at most one t such that $\Lambda'(t, T) = 0$. For the case where $K_2 < 0$, if there exists $t_0 \in (0, T)$ such that $\Lambda(t_0, T) < 0$. Then by (3.5) and (3.7), the equation $\Lambda'(t, T) = 0$ has at least two solutions, it is impossible. Therefore for $K_2 < 0$, $\Lambda'(t, T) \geq 0$. For $K_2 > 0$, we suppose t_0 such that $\Lambda'(t_0, T) = 0$. Let $\beta = \frac{K_1}{K_2}$, then by (3.8)

$$e^{K_2 t_0} = \left(1 + \frac{\beta}{2 + \beta} \left(1 - e^{-\frac{K_2 T}{2}} \right) \right) e^{\frac{K_2 T}{2}},$$

or $t_0 \in (0, T)$ is such that

$$e^{\frac{K_2 t_0}{2}} = \sqrt{1 + \frac{\beta}{2 + \beta} \left(1 - e^{-\frac{K_2 T}{2}} \right)} e^{\frac{K_2 T}{4}}. \quad (3.9)$$

The proof is completed. \square

Proposition 3.3. Let $\beta = \frac{K_1}{K_2}$, then (i) if $K_2 > 0$,

$$\begin{aligned} \sup_{t \in [0, T]} \Lambda(t, T) &= (1 + \beta)^2 - \left(\beta + \frac{\beta^2}{2} \right) \sqrt{1 + \frac{\beta}{2 + \beta} \left(1 - e^{-\frac{K_2 T}{2}} \right)} e^{-\frac{K_2 T}{4}} \\ &\quad - \frac{\left(\beta + \beta^2 - \frac{\beta^2}{2} e^{-\frac{K_2 T}{2}} \right)}{\sqrt{1 + \frac{\beta}{2 + \beta} \left(1 - e^{-\frac{K_2 T}{2}} \right)}} e^{-\frac{K_2 T}{4}}. \end{aligned} \quad (3.10)$$

(ii) if $K_2 < 0$,

$$\sup_{t \in [0, T]} \Lambda(t, T) = \frac{1}{2} + \frac{1}{2} \left(1 + \frac{K_1}{K_2} \left[1 - e^{-\frac{K_2 T}{2}} \right] \right)^2. \quad (3.11)$$

Proof. For $K_2 > 0$, we have

$$\begin{aligned} \Lambda(t_0, T) &= 1 + \beta \left(1 - e^{-\frac{K_2 T}{2}} \cdot e^{\frac{K_2 t_0}{2}} \right) + \beta \left(1 - e^{\frac{K_2 t_0}{2}} \right) \\ &\quad + \beta^2 \left[\left(1 - e^{-\frac{K_2 t_0}{2}} \right) + \frac{1}{2} \left(e^{-\frac{K_2 T}{2}} \cdot e^{-\frac{K_2 t_0}{2}} - e^{-\frac{K_2 T}{2}} \cdot e^{\frac{K_2 t_0}{2}} \right) \right] \\ &= 1 + 2\beta + \beta^2 - \left(\beta + \frac{\beta^2}{2} \right) e^{-\frac{K_2 T}{2}} \cdot e^{\frac{K_2 t_0}{2}} - \left(\beta + \beta^2 - \frac{\beta^2}{2} e^{-\frac{K_2 T}{2}} \right) e^{-\frac{K_2 t_0}{2}}. \end{aligned}$$

Using (3.9) yields (3.10). For $K_2 < 0$, $\sup_{t \in [0, T]} \Lambda(t, T) = \Lambda(T, T)$, which gives (3.11). \square

Combining (2.9) and (3.3), we get

Theorem 3.4. Let $C(T, K_1, K_2) = \sup_{t \in [0, T]} \Lambda(t, T)$; then it holds

$$\mathbb{E} \left(F^2 \log \frac{F^2}{\|F\|_{L^2}^2} \right) \leq 2C(T, K_1, K_2) \mathbb{E} \left(\int_0^T |D_t F|^2 dt \right) \quad (3.12)$$

for any cylindrical function F on $W_x^T(M)$.

It is well-known that the above logarithmic Sobolev inequality implies that the spectral gap of \mathcal{L}_T^x , denoted by $SG(\mathcal{L}_T^x)$, has the following lower bound

$$SG(\mathcal{L}_T^x) \geq \frac{1}{C(T, K_1, K_2)}.$$

Theorem 3.5. Assume (3.1) holds, then (i) if $K_2 > 0$, we have

$$SG(\mathcal{L}_T^x)^{-1} \leq \left(1 + \frac{K_1}{K_2} \right)^2 - \frac{K_1}{K_2} \sqrt{\left(2 + \frac{K_1}{K_2} \right) \left(2 + 2\frac{K_1}{K_2} - \frac{K_1}{K_2} e^{-\frac{K_2 T}{2}} \right)} e^{-\frac{K_2 T}{4}}; \quad (3.13)$$

(ii) if $K_2 < 0$, we have

$$SG(\mathcal{L}_T^x)^{-1} \leq \frac{1}{2} + \frac{1}{2} \left(1 + \frac{K_1}{K_2} \left[1 - e^{-\frac{K_2 T}{2}} \right] \right)^2. \quad (3.14)$$

Proof. Using the elementary inequality: $A + B \geq 2\sqrt{AB}$ to the last two terms in (3.10) yields (3.13). Inequality (3.14) is obvious. \square

It is quite interesting to remark that

Proposition 3.6. Let $\psi(T, K_1, K_2)$ be the right hand side of (3.13) when $K_2 > 0$ and the right hand side of (3.14) for $K_2 < 0$, then

$$\psi(T, K_1, K_2) \rightarrow 1 + \frac{K_1 T}{2} + \frac{K_1^2 T^2}{8} \quad \text{as } K_2 \rightarrow 0. \quad (3.15)$$

Proof. It is easy to see that the right hand side of (3.14) tends to $1 + \frac{K_1 T}{2} + \frac{K_1^2 T^2}{8}$ as $K_2 \rightarrow 0$. For the right hand side of (3.13), we first remark that

$$(a) \quad \frac{K_1}{K_2} e^{-\frac{K_2 T}{4}} = \frac{K_1}{K_2} - \frac{K_1 T}{4} + \frac{K_1 K_2 T^2}{32} + o(K_2).$$

Secondly

$$\begin{aligned} & \left(2 + \frac{K_1}{K_2} \right) \left(2 + 2\frac{K_1}{K_2} - \frac{K_1}{K_2} e^{-\frac{K_2 T}{2}} \right) \\ &= \left(2 + \frac{K_1}{K_2} \right) \left(2 + \frac{K_1}{K_2} + \frac{K_1 T}{2} - \frac{K_1 K_2 T^2}{8} + o(K_2) \right) \\ &= \left(2 + \frac{K_1}{K_2} \right)^2 \left(1 + \frac{\frac{K_1 T}{2} - \frac{K_1 K_2 T^2}{8} + o(K_2)}{2 + \frac{K_1}{K_2}} \right). \end{aligned}$$

Therefore

$$\begin{aligned} & \sqrt{\left(2 + \frac{K_1}{K_2} \right) \left(2 + 2\frac{K_1}{K_2} - \frac{K_1}{K_2} e^{-\frac{K_2 T}{2}} \right)} \\ &= \left(2 + \frac{K_1}{K_2} \right) \left(1 + \frac{\frac{K_1 T}{2} - \frac{K_1 K_2 T^2}{8} + o(K_2)}{2 + \frac{K_1}{K_2}} - \frac{K_1 K_2 T^2}{32} + o(K_2^2) \right) \\ &= \left(2 + \frac{K_1}{K_2} \right) + \frac{K_1 T}{4} - \frac{3K_1 K_2 T^2}{32} + o(K_2). \end{aligned}$$

Combining this with (a), we get

$$\begin{aligned} & \frac{K_1}{K_2} e^{-\frac{K_2 T}{4}} \sqrt{\left(2 + \frac{K_1}{K_2}\right) \left(2 + 2\frac{K_1}{K_2} - \frac{K_1}{K_2} e^{-\frac{K_2 T}{2}}\right)} \\ &= \left(2 + \frac{K_1}{K_2}\right) \frac{K_1}{K_2} - \frac{K_1 T}{2} - \frac{K_1^2 T^2}{8} + o(K_2). \end{aligned}$$

Then (3.15) follows from the right hand side of (3.13). \square

Corollary 3.7. Assume (3.1) holds.

(1) If $K_1 = K_2 = K > 0$, then

$$\psi(T, K, K) = 4 - \sqrt{3\left(4 - e^{-\frac{KT}{2}}\right)} e^{-\frac{KT}{4}} \rightarrow 1 \text{ as } K \rightarrow 0.$$

(2) If $K_2 = -K_1 = -K$, then

$$\psi(T, K, -K) = \frac{1}{2}(1 + e^{KT}).$$

Remark 3.8. Our results improve estimates obtained in [1].

4 Behaviour of $SG(\mathcal{L}_T^x)$ as $T \rightarrow 0$

In this section, we consider the case where $Z = 0$. Then Condition (3.1) can be readed as

$$K_2 \text{Id} \leq \mathbf{ric} \leq K_1 \text{Id}, \quad \text{with } K_1 + K_2 \geq 0 \quad (4.1)$$

and SDE (1.7) is reduced to

$$du_t(w) = \sum_{i=1}^d H_i(u_u(w)) \circ dw_t^i, \quad u_0(w) = u_0 \in \pi^{-1}(x). \quad (4.2)$$

The path $\gamma_t(w) = \pi(u_t(w))$ is called Brownian motion path on M . Let $\rho(x, y)$ be the Riemannian distance. By [22, p. 199], there is $\varepsilon > 0$ such that

$$\sup_{t \in [0, T]} \mathbb{E} \left(\exp \left(\varepsilon \frac{\rho(x, \gamma_t)^2}{2t} \right) \right) < +\infty. \quad (4.3)$$

Assume that the curvature tensor satisfies the following growth condition

$$\|\Omega_u\| + \sum_{i=1}^d \|(L_{H_i} \Omega)_u\| \leq C(1 + \rho(x, \pi(u))^2) \quad (4.4)$$

where L_{H_i} denotes the Lie derivative with respect to H_i .

Let $v \in \mathbb{H}$, consider the functional $F_T : W_x^T(M) \rightarrow \mathbb{R}$ defined by

$$F_T(\gamma(w)) = \int_0^T \langle \dot{v}(t), dw_t \rangle.$$

Let $h \in \mathbb{H}$; then by (2.3), we have (see also [15])

$$(D_h F_T)(\gamma(w)) = \int_0^T \langle \dot{v}(t), q(t, h) dw_t \rangle + \int_0^T \langle \dot{v}(t), \dot{h}_t(w) \rangle dt. \quad (4.5)$$

Let $a \in \mathbb{R}^d$ and consider $v(t) = ta$ with $|a| = 1$ in (4.5), we have

$$(D_h F_T)(\gamma(w)) = - \int_0^T \langle q(t, h) a, dw_t \rangle + \int_0^T \langle a, \dot{h}_t(w) \rangle dt. \quad (4.6)$$

Let $\{e_1, \dots, e_d\}$ be an orthonormal basis of \mathbb{R}^d ; define

$$C_i(w, t, \tau) = - \int_{\tau}^t \Omega_{u_s(w)}(e_i, \circ dw(s)) \mathbf{1}_{(\tau < t)}.$$

Then by Fubini theorem, the term $q(t, h)$ has the expression

$$q(t, h) = - \sum_{i=1}^d \int_0^T \dot{h}^i(\tau) C_i(w, t, \tau) d\tau.$$

According to (4.6), the gradient $D_{\tau} F_T$ has the following expression:

$$(D_{\tau} F_T)(\gamma(w)) = \sum_{i=1}^d \left(\int_{\tau}^T \langle C_i(w, s, \tau) a, dw_s \rangle \right) e_i + a + \frac{1}{2} \int_{\tau}^T \mathbf{ric}_Z(u_s) a ds. \tag{4.7}$$

We have

$$\text{Var}(F_T) = \mathbb{E}(F_T^2) - \mathbb{E}(F_T)^2 = |a|^2 T = T. \tag{4.8}$$

Proposition 4.1. Assume (4.4). Let

$$\chi_T = \frac{\mathbb{E} \left(\int_0^T |D_{\tau} F|^2 d\tau \right)}{\text{Var}(F_T)}.$$

Then

$$\chi_T = 1 + \frac{T}{2} \langle \mathbf{ric}_Z(u_0) a, a \rangle + o(T) \quad \text{as } T \rightarrow 0 \tag{4.9}$$

where u_0 is the initial frame of (4.2).

Proof. We have, using (4.7),

$$\begin{aligned} |D_{\tau} F_T|^2 &= \sum_{i=1}^d \left(\int_{\tau}^T \langle C_i(w, s, \tau) a, dw_s \rangle \right)^2 + |a|^2 + \frac{1}{4} \left| \int_{\tau}^T \mathbf{ric}(u_s) a ds \right|^2 \\ &+ \left\langle a, \int_{\tau}^T \mathbf{ric}(u_s) a ds \right\rangle + 2 \sum_{i=1}^d \int_{\tau}^T \langle C_i(w, s, \tau) a, dw_s \rangle a^i \\ &+ 2 \int_0^d \int_{\tau}^T \langle C_i(w, s, \tau) a, dw_s \rangle \cdot \int_{\tau}^T \langle \mathbf{ric}(u_s) a, e_i \rangle ds. \end{aligned}$$

Put respectively

$$\mathbb{E} \left(\int_0^T |D_{\tau} F_T|^2 d\tau \right) = I_1(T) + I_2(T) + I_3(T) + I_4(T) + I_5(T) + I_6(T).$$

It is obvious that $I_2(T) = |a|^2 T = T$ and $I_5(T) = 0$. We have

$$I_1(T) = \sum_{i=1}^d \int_0^T \left(\int_{\tau}^T \mathbb{E}(|C_i(w, s, \tau) a|^2) ds \right) d\tau.$$

Now by growth condition (4.4) and (4.3), there is a constant $\delta > 0$ such that

$$\mathbb{E}(|C_i(w, s, \tau) a|^2) \leq \delta (s - \tau). \tag{4.10}$$

So that $I_1(T) \leq \delta T^3/6$. By condition (4.1), it is easy to see that $I_3(T) \leq \frac{K_1^2 T^3}{12}$. It follows that $I_6(T) \leq \frac{\sqrt{\delta} K_1}{6} T^3$. Now for $I_4(T)$, we have

$$\lim_{T \rightarrow 0} \frac{I_4(T)}{T^2} = \frac{1}{2} \langle \mathbf{ric}(u_0) a, a \rangle.$$

Combining these estimates together with (4.8), we get (4.9). □

Theorem 4.2. Assume (4.1) and (4.4). Let $K_2(x)$ be the lower bound of Ric_x . Then as $T \rightarrow 0$,

$$1 - \frac{K_1 T}{2} + o(T) \leq SG(\mathcal{L}_T^x) \leq 1 + \frac{K_2(x)T}{2} + o(T). \quad (4.11)$$

Proof. For $K_2 > 0$, set $\beta = \frac{K_1}{K_2}$. As $T \rightarrow 0$, we have

$$\begin{aligned} & \sqrt{(2 + \beta)(2 + 2\beta - \beta e^{-\frac{K_2 T}{2}})} = \sqrt{(2 + \beta)^2 \left(1 + \frac{\beta}{2 + \beta} \left(1 - e^{-\frac{K_2 T}{2}}\right)\right)} \\ &= (2 + \beta) \sqrt{1 + \frac{\beta}{2 + \beta} \frac{K_2 T}{2} + o(T)} \\ &= (2 + \beta) \left(1 + \frac{\beta}{2 + \beta} \frac{K_2 T}{4} + o(T)\right). \end{aligned}$$

So, for $K_2 > 0$, as $T \rightarrow 0$,

$$\begin{aligned} & \beta \sqrt{(2 + \beta)(2 + 2\beta - \beta e^{-\frac{K_2 T}{2}})} e^{-\frac{K_2 T}{4}} \\ &= \beta(2 + \beta) \left(1 + \frac{\beta}{2 + \beta} \frac{K_2 T}{4} + o(T)\right) \left(1 - \frac{K_2 T}{4} + o(T)\right) \\ &= \beta(2 + \beta) \left[1 + \frac{T}{4} \left(\frac{K_1}{2 + \beta} - K_2\right) + o(T)\right] \\ &= \beta(2 + \beta) \left[1 - \frac{K_2 T}{2(2 + \beta)} + o(T)\right]. \end{aligned}$$

By (3.13), we get

$$SG(\mathcal{L}_T^x)^{-1} \leq (1 + \beta)^2 - \beta(2 + \beta) \left[1 - \frac{K_2 T}{2(2 + \beta)} + o(T)\right] = 1 + \frac{K_1 T}{2} + o(T),$$

which implies that

$$SG(\mathcal{L}_T^x) \geq 1 - \frac{K_1 T}{2} + o(T).$$

For $K_2 < 0$, by (3.14),

$$\begin{aligned} SG(\mathcal{L}_T^x)^{-1} &\leq \frac{1}{2} + \frac{1}{2} \left(1 + K_1 \frac{1 - e^{-\frac{K_2 T}{2}}}{K_2}\right)^2 = \frac{1}{2} + \frac{1}{2} \left(1 + \frac{K_1}{K_2} \left(\frac{K_2 T}{2} + o(T)\right)\right)^2 \\ &= 1 + \frac{K_1 T}{2} + o(T), \end{aligned}$$

which implies again

$$SG(\mathcal{L}_T^x) \geq 1 - \frac{K_1 T}{2} + o(T).$$

Now in (4.9), taking the vector a such that $\mathbf{ric}(u_0)a = K_2(x)a$ yields

$$SG(\mathcal{L}_T^x) \leq 1 + \frac{K_2(x)T}{2} + o(T).$$

The proof of (4.11) is completed. \square

Corollary 4.3. Assume (4.4). In the case where $\text{Ric} = -K_1 \text{Id}$ with $K_1 \geq 0$, we have

$$\left|SG(\mathcal{L}_T^x) - 1 + \frac{K_1 T}{2}\right| = o(T) \quad \text{as } T \rightarrow 0.$$

References

- [1] S. Aida, Gradient estimates of harmonic functions and the asymptotics of spectral gaps on path spaces, *Interdisciplinary Information Sciences*, 2 (1996), 75-84. MR-1398102
- [2] S. Aida and D. Elworthy, Differential calculus on path and loop spaces I. logarithmic Sobolev inequalities on path spaces, *C. R. Acad. Sci. Paris*, 321 (1995), 97-102. MR-1340091
- [3] D. Bakry and M. Emery, Diffusion hypercontractivities, *Sém. de Probab.*, XIX, Lect. Notes in Math., 1123 (1985), 177-206, Springer.
- [4] D. Bakry and M. Ledoux, A logarithmic Sobolev form of the Li-Yau parabolic inequality, *Rev. Mat. Iberoamericana*, 22 (2006), 683-702. MR-2294794
- [5] J. M. Bismut, Large deviation and Malliavin Calculus, *Birkhäuser, Boston/Basel*, 1984.
- [6] B. Capitaine, E. P. Hsu and M. Ledoux, Martingale representation and a simple proof of logarithmic Sobolev inequalities on path spaces, *Elect. Comm. Probab.* 2(1997), 71-81. MR-1484557
- [7] A. B. Cruzeiro and P. Malliavin, Renormalized Differential Geometry on path space: Structural equation, Curvature, *J. Funct. Anal.* 139 (1996), p.119-181. MR-1399688
- [8] A. B. Cruzeiro and S. Fang, Weak Levi-Civita connection for the damped metric on the Riemannian path space and Vanishing of Ricci tensor in adapted differential geometry, *J. Funct. Anal.* 185 (2001), 681-698. MR-1856279
- [9] B. Driver, A Cameron-Martin type quasi-invariant theorem for Brownian motion on a compact Riemannian manifold, *J. Funct. Anal.* 110 (1992), 272-376. MR-1194990
- [10] D. Elworthy and X.M. Li, Formulae for the derivatives of heat semi-group. *J. Funct. Anal.* 125 (1994), 252-287. MR-1297021
- [11] K.D. Elworthy, Y. Le Jan and X.M. Li, On the geometry of diffusion operators and stochastic flow, *Lect. notes in Math.* 1720 (1999), Springer. MR-1735806
- [12] K.D. Elworthy and Y. Yang, The Vanishing of harmonic one-forms on base path spaces, *J. Funct. Anal.* 264 (2013), 1168-1196. MR-3010018
- [13] O. Enchev and D. Stroock, Towards a Riemannian geometry on the path space over a Riemannian manifold, *J. Funct. Anal.* 134 (1995), 392-416. MR-1363806
- [14] S. Fang, Inégalité du type de Poincaré sur l'espace des chemins riemanniens, *C.R. Acad. Sci. Paris* 318 (1994), 257-260. MR-1262907
- [15] S. Fang, Stochastic anticipative integrals on a Riemannian manifold, *J. Funct. Anal.* 131 (1995), 228-253. MR-1343165
- [16] S. Fang and P. Malliavin, Stochastic analysis on the path space of a Riemannian manifold, *J. Funct. Anal.* 131 (1993), 249-274. MR-1245604
- [17] S. Fang, F.Y. Wang and B. Wu, Transportation-cost inequality on path spaces with uniform distance, *Stoch. Proc. Appl.* 118 (2008), no. 12, 2181-2197. MR-2474347
- [18] E. P. Hsu, Quasi-invariance of the Wiener measure on the pathspace over a compact Riemannian manifold, *J. Funct. Anal.* 134 (1995), 417-450. MR-1363807
- [19] E. P. Hsu, Quasi-invariance of the Wiener measure on path spaces: Noncompact case, *J. Funct. Anal.* 193 (2002), 278-290. MR-1929503
- [20] E. P. Hsu, Logarithmic Sobolev inequalities on path spaces over Riemannian manifolds, *Comm. Math. Phys.* 189 (1997), 9-16. MR-1478528
- [21] A. Naber, Characterizations of bounded Ricci curvature on smooth and nonsmooth spaces, *arXiv:1306.651*.
- [22] D. Stroock, An introduction to the analysis of paths on a Riemannian manifold, *Math. Survey and Monographs* vol. 74, AMS, 2000. MR-1715265

Electronic Journal of Probability

Electronic Communications in Probability

Advantages of publishing in EJP-ECP

- Very high standards
- Free for authors, free for readers
- Quick publication (no backlog)
- Secure publication (LOCKSS¹)
- Easy interface (EJMS²)

Economical model of EJP-ECP

- Non profit, sponsored by IMS³, BS⁴, ProjectEuclid⁵
- Purely electronic

Help keep the journal free and vigorous

- Donate to the IMS open access fund⁶ (click here to donate!)
- Submit your best articles to EJP-ECP
- Choose EJP-ECP over for-profit journals

¹LOCKSS: Lots of Copies Keep Stuff Safe <http://www.lockss.org/>

²EJMS: Electronic Journal Management System <http://www.vtex.lt/en/ejms.html>

³IMS: Institute of Mathematical Statistics <http://www.imstat.org/>

⁴BS: Bernoulli Society <http://www.bernoulli-society.org/>

⁵Project Euclid: <https://projecteuclid.org/>

⁶IMS Open Access Fund: <http://www.imstat.org/publications/open.htm>