

OIL AND WATER: A TWO-TYPE INTERNAL AGGREGATION MODEL

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We introduce a two-type internal DLA model which is an example of a nonunary abelian network. Starting with n “oil” and n “water” particles at the origin, the particles diffuse in \mathbb{Z} according to the following rule: whenever some site $x \in \mathbb{Z}$ has at least 1 oil and at least 1 water particle present, it *fires* by sending 1 oil particle and 1 water particle each to an independent random neighbor $x \pm 1$. Firing continues until every site has at most one type of particles. We establish the correct order for several statistics of this model and identify the scaling limit under assumption of existence.

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1. Introduction and main results. We investigate a new interacting particle system on \mathbb{Z} that can be considered as a model of *mutual diffusion*. Two particle species, called for convenience *oil* and *water*, diffuse on \mathbb{Z} until there is no site that has both an oil and water particle. We start with n oil and n water particles at the origin. At each discrete time step, if at least 1 oil particle and at least 1 water particle are present at $x \in \mathbb{Z}$ then x *fires* by sending 1 oil particle and 1 water particle each to an independent random neighbor $x \pm 1$ with equal probability. The system fixates when no more firing is possible, that is, when every site has particles of at most one type.

How many firings are required to reach fixation? How far is the typical particle from the origin upon fixation? Our main results address these two questions.

DEFINITION 1. For $x \in \mathbb{Z}$, let $u(x)$ be the total number of times x fires before fixation. The random function $u : \mathbb{Z} \rightarrow \mathbb{N}$ is called the *odometer* of the process.

In the above informal description, we have assumed that all sites fire in parallel in discrete time, but in fact this system has an *abelian property*: the distribution of the odometer and of the particles upon fixation do not depend on the order of firings (Lemma 2.2).

Our first result concerns the order of magnitude of the odometer.

THEOREM 1.1. *There exist positive numbers ϵ, c, C such that for large enough n :*

i.

$$\mathbb{P}\left(\sup_{x \in \mathbb{Z}} u(x) > Cn^{4/3}\right) < e^{-n^\epsilon},$$

ii.

$$\mathbb{P}\left(\inf_{x: |x| \leq cn^{1/3}} u(x) < cn^{4/3}\right) < e^{-n^\epsilon}.$$

The next result shows that most particles do not travel very far: all but a vanishing fraction of the particles at the end of the process are supported on an interval of length n^α , for any exponent $\alpha > 1/3$. Formally, for $r > 0$ let $F(r)$ be the number of particles that fixate outside the interval $[-r, r]$.

THEOREM 1.2. *For sufficiently small $\epsilon > 0$, there exists $\delta > 0$ such that*

$$\mathbb{P}(F(n^{1/3+\epsilon}) > n^{1-\frac{\epsilon}{2}}) < e^{-n^\delta}.$$

Theorem 1.1 shows that the odometer function scales like $n^{4/3}$. Theorem 1.2 motivates the conjecture that the proper scaling factor in the spatial direction should be $n^{1/3}$. We conjecture that the scaling limit of the odometer exists, and under the assumption of existence we identify the limiting function. Let $\tilde{u} := \mathbb{E}u$.

CONJECTURE 1.3.

(i) *For any $\delta > 0$,*

$$(1) \quad \mathbb{P}\left(\sup_{x \in \mathbb{Z}} \left| \frac{u(x) - \tilde{u}(x)}{n^{4/3}} \right| > \delta\right) \rightarrow 0 \quad \text{as } n \rightarrow \infty.$$

(ii) *There is a function $w : \mathbb{R} \rightarrow \mathbb{R}$ such that*

$$(2) \quad \frac{\tilde{u}(\lfloor n^{1/3} \xi \rfloor)}{n^{4/3}} \rightarrow w(\xi),$$

uniformly in ξ .

Simulations support Conjecture 1.3, as shown in Figure 1. Conditionally on Conjecture 1.3, the following result identifies the limit $w(x)$ exactly.

THEOREM 1.4. *Assuming Conjecture 1.3, the function w appearing in (2) must equal*

$$(3) \quad w(x) = \begin{cases} \frac{1}{72\pi} ((18\pi)^{1/3} - |x|)^4, & |x| < (18\pi)^{1/3}, \\ 0, & |x| \geq (18\pi)^{1/3}. \end{cases}$$

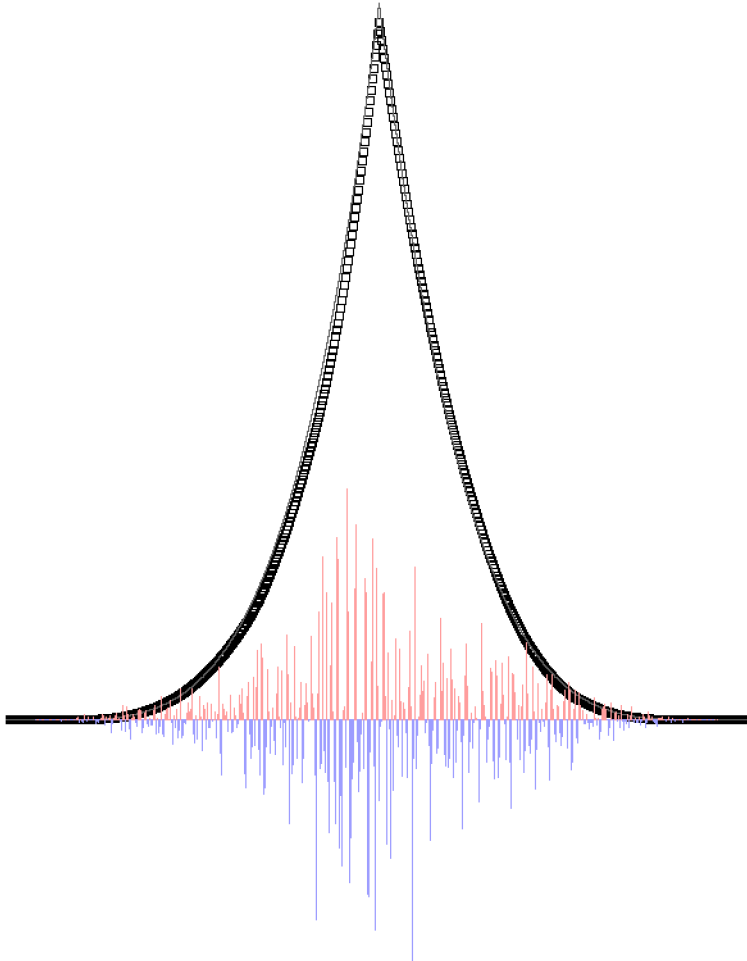


FIG. 1. Graph of the odometer function of the oil and water model in \mathbb{Z} with $n = 360,000$ particles of each type started at the origin: for each $x \in \mathbb{Z}$ a box is drawn centered at $(x, u(x))$ where $u(x)$ is the number of oil-water pairs fired from x . The curve $f(x) = \frac{1}{72\pi} ((18\pi n)^{1/3} - |x|)^4$ appears in gray. Red and blue vertical bars represent the final configuration of oil and water particles, respectively; the height of the bar is proportional to the number of particles.

The oil and water model can be defined on any graph and in particular on higher-dimensional lattices. Figure 2 shows an oil and water configuration in \mathbb{Z}^2 . In Section 7, we conjecture the relevant exponents in \mathbb{Z}^d for $d \geq 2$.

1.1. *Related models: Internal DLA and Abelian networks.* In internal DLA, each of n particles started at the origin in \mathbb{Z}^d performs a simple random walk until reaching an unoccupied site. The resulting random set of n occupied sites is close to a Euclidean ball [see Lawler, Bramson and Griffeath (1992)]. Internal DLA is

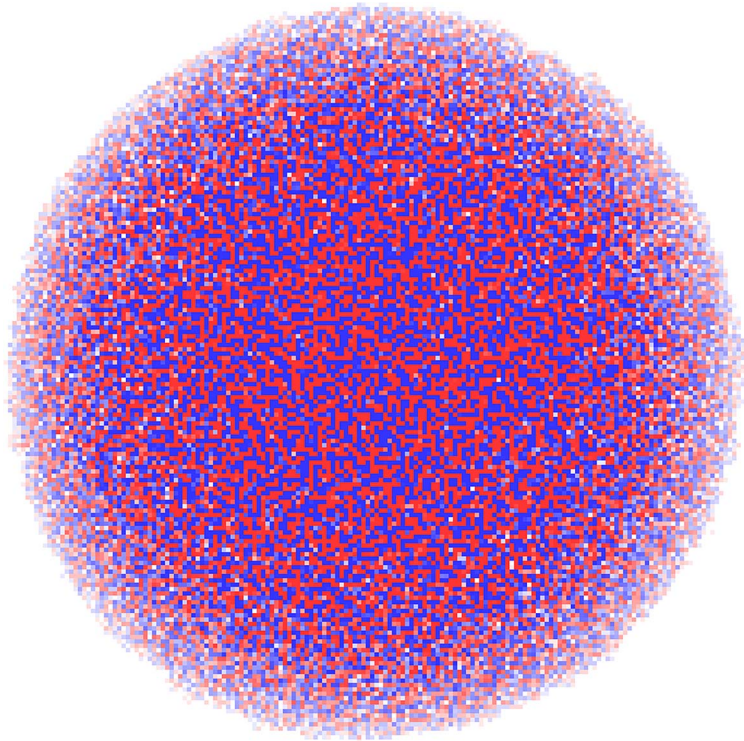


FIG. 2. Oil and water in \mathbb{Z}^2 with $n = 2^{22}$ particles of each type started at the origin. Each site where particles stop is shaded red or blue according to whether oil or water particles stopped there. The intensity of the shade indicates the number of particles. We believe that the limit shape is a disk of radius of order $n^{1/4}$.

one of several models known to have an *abelian property* according to which the order of moves does not affect the final outcome.

Dhar (1999) proposed certain collections of communicating finite automata as a broader class of models with this property. Until recently the only examples studied in this class have been *unary networks* [or their “block renormalizations” as proposed in Dhar (1999)]. Informally, a unary network is a system of local rules for moving *indistinguishable* particles on a graph, whereas a nonunary network has different types of particles. It is not as easy to construct nonunary examples with an abelian property, but they exist. Alcaraz, Pyatov and Rittenberg (2009) studied a class of nonunary examples which they termed *two-component sandpile models*, and asked whether there is a nontrivial example with two particle species such that the total number of particles of each type is conserved. Oil and water has this conservation property, but differs from the two-component sandpile models in that any number of particles of a single type may accumulate at the same vertex and be unable to fire.

Bond and Levine (2016) developed Dhar’s idea into a theory of *abelian networks* and proposed two nonunary examples, *oil and water* and *abelian mobile agents*. Can such models exhibit behavior that is “truly different” from their unary cousins? This is the question that motivates the present paper. Theorem 1.2 shows that oil and water has an entirely different behavior than internal DLA: all but a vanishing fraction of the $2n$ particles started at the origin stop within distance $n^{\frac{1}{3}+\varepsilon}$ (versus n for internal DLA).

In contrast to internal DLA where there is now a detailed picture of the fluctuations in all dimensions [see Asselah and Gaudillièrè (2013a, 2013b, 2014), Jerison, Levine and Sheffield (2012, 2013, 2014)], there is not even a limiting shape theorem yet for oil and water. Simulations in \mathbb{Z}^d indicate a spherical limit shape (Figure 2) with radius of order $n^{1/(d+2)}$.

1.2. *Main ideas behind the proofs.* In this section, we present informally the key ideas behind the proofs. We start with a definition.

DEFINITION 2. For any $x \in \mathbb{Z}$ and $t \in \{0, 1, \dots, \infty\}$, let $\eta_1(x, t)$ and $\eta_2(x, t)$ represent the number of oil and water particles, respectively, at position x at time t .

From now on, let

$$P_t = \sum_{x \in \mathbb{Z}} \min(\eta_1(x, t), \eta_2(x, t))$$

be the number of co-located oil-water pairs at time t .

The process is run in phases: we start by firing a pair at the origin and, inductively, at each time $t > 0$ we fire one pair from a vertex x_t determined according to a firing rule.⁵ By definition, $P_0 = n$ and the process stops at the first time τ for which $P_\tau = 0$. Now denote by $l_t = \eta_1(x_t - 1, t) - \eta_2(x_t - 1, t)$ the excess of oil particles over water particles at the left neighbor of x_t and by $r_t = \eta_1(x_t + 1, t) - \eta_2(x_t + 1, t)$ the excess at the right neighbor.

Conditional upon knowing the process up to time t , the random variable

$$(4) \quad Z_t := P_{t+1} - P_t$$

can have four possible distributions. To distinguish them, we denote the conditional Z_t by the random variables $\xi_1, \xi_2, \xi_3, \xi_4$ which are described Table 1.

Note that ξ_1 has mean zero, whereas ξ_2 and ξ_3 have negative means, and ξ_4 is degenerate at 0. Since all such expected values are less than or equal to zero,

P_t is a supermartingale.

⁵Lemma 2.2 shows that certain statistics of the process remain independent of the choice of the firing rule. The specific rule we use for convenience throughout the article is specified in Lemma 3.5.

TABLE 1
The four possible conditional distributions for Z_t

i	$\mathbb{P}(\xi_i = -1)$	$\mathbb{P}(\xi_i = 0)$	$\mathbb{P}(\xi_i = 1)$	Used when
1	1/4	1/2	1/4	$l_t r_t < 0$
2	1/4	3/4	0	exactly one of l_t, r_t is 0
3	1/2	1/2	0	$l_t = r_t = 0$
4	0	1	0	$l_t r_t > 0$

The main idea of the proof for the upper bound in Theorem 1.1 is as follows: Define the auxiliary random variables

$$(5) \quad N_i(t) = \#\{s \leq t : Z_s \stackrel{d}{=} \xi_i\}.$$

It is clear from the definition that

$$\sum_{i=1}^{\tau} Z_i = P_{\tau} - P_0 = -n,$$

where τ is the stopping time of the process where all oil and water have been separated ($P_{\tau} = 0$). Now, informally $\sum_{i=1}^{\tau} Z_i$ is the sum of $N_2(\tau) + N_3(\tau)$ variables with mean at most $-1/4$ and $N_1(\tau)$ variables with mean 0.

Because of the negative and zero drifts, respectively, the sum of the negative mean variables is of order $O(-(N_2(\tau) + N_3(\tau)))$, whereas the sum of the zero mean variables is roughly $O(\sqrt{N_1(\tau)})$ (by square root fluctuations of the symmetric random walk). Thus, roughly

$$\sum_{i=1}^{\tau} Z_i \leq -N_2(\tau) - N_3(\tau) + \sqrt{N_1(\tau)}.$$

We then argue by contradiction: conditional upon the event that the odometer is “very large” somewhere (i.e., larger than $Cn^{4/3}$ for a suitable big constant C), we show that it is likely that $N_2(\tau) + N_3(\tau)$ is “sufficiently large” compared to $\sqrt{N_1(\tau)}$. This in turn implies that

$$\sum_{i=1}^{\tau} Z_i < -n,$$

which is a contradiction.

To prove the lower bound we first establish a gradient bound on the odometer using the upper bound. In other words, we show that there exists a constant c such that, with high probability, for $x \in [0, cn^{1/3}]$ we have

$$u(x) - u(x+1) \geq n/2.$$

This in turn implies that with high probability,

$$u(0) = \Omega(n^{4/3}),$$

since

$$0 \leq u(\lfloor cn^{1/3} \rfloor) \leq u(0) - \frac{n}{2} \lfloor cn^{1/3} \rfloor.$$

Theorem 1.2 follows from the proof of the lower bound.

Lastly, we discuss the proof of Theorem 1.4. Clearly, by symmetry of the process about the origin the function $w(\cdot)$ is symmetric as well. We show that Conjecture 1.3 implies that the limiting function is smooth on the positive real axis and, in particular, satisfies

$$w''(x) = \sqrt{\frac{2}{\pi} w(x)},$$

with certain boundary conditions. At this point, Theorem 1.4 follows by identifying a solution of the above boundary value problem, and using uniqueness of the solution.

1.3. Outline. This article is structured as follows. In Section 2, we give a rigorous definition of the model. Furthermore, in order to facilitate our proofs, we define two different versions of the process and prove that they both terminate in finite time with probability one. We then construct a coupling between the two versions, which in particular implies that they terminate with the same odometer function and the same distribution of particles.

In Section 3, we show a polynomial bound on the stopping time τ . We start by showing that the number of pairs P_t can be stochastically dominated by a certain lazy random walk with long holding times, started and reflected at n . In order to get a rough upper bound on τ , it suffices to bound the hitting time of zero for this walk, which we show is of order n^4 . Consequently, we get direct polynomial bounds on the support and the maximum of the odometer function. We then improve the last bound, proving the upper bound in Theorem 1.1 in Section 4.

Section 5 is devoted to proving the lower bound in Theorem 1.1. As a byproduct of the proof, Theorem 1.2 follows.

In Section 6, we prove the conditional Theorem 1.4. Section 7 consists of open questions and a conjecture about the process on higher dimensional lattices.

2. Rigorous definition of the model. As the underlying randomness for our model, we will take a countable family of independent random variables

$$(6) \quad \omega = (X_k^x, Y_k^x)_{x \in \mathbb{Z}, k \in \mathbb{N}}$$

with $\mathbb{P}(X_k^x = \pm 1) = P(Y_k^x = \pm 1) = \frac{1}{2}$. For each $x \in \mathbb{Z}$, the sequences $(X_k^x)_{k \geq 1}$ and $(Y_k^x)_{k \geq 1}$ are called the *stacks at x* . Denote by Ω the set of all stacks ω .

The stacks will have the following interpretation (described formally below): On the k th firing from site x , an oil particle steps from x to $x + X_k^x$ and a water particle steps from x to $x + Y_k^x$.

For any value $K \in \mathbb{N}$, a *firing sequence* is a sequence of vertices $s = (x_0, \dots, x_{K-1})$ with each $x_k \in \mathbb{Z}$. Recall from Definition 2 that the random variables $\eta_i(x, t)$ represent the number of particles of type i (type 1 are *oil* and type 2 are *water* particles) at location x at time t . Given such a sequence and an initial state $\eta_1(\cdot, 0), \eta_2(\cdot, 0)$ we define the oil and water process $(\eta_1(\cdot, k), \eta_2(\cdot, k))_{k=0}^K$ inductively by

$$(7) \quad \eta_1(\cdot, k+1) = \eta_1(\cdot, k) - \delta(x_k) + \delta(x_k + X_{i_k}^{x_k}),$$

$$(8) \quad \eta_2(\cdot, k+1) = \eta_2(\cdot, k) - \delta(x_k) + \delta(x_k + Y_{i_k}^{x_k}),$$

where $i_k = \#\{j \leq k : x_j = x_k\}$. Here, $\delta(x)$ is the function taking value 1 at x and 0 elsewhere.

2.1. Least action principle and Abelian property.

DEFINITION 3. Let $s = (x_0, \dots, x_{K-1})$ be a firing sequence. We say that s is *legal* for $(\eta_1(\cdot, 0), \eta_2(\cdot, 0))$ if

$$\min(\eta_1(x_k, k), \eta_2(x_k, k)) \geq 1,$$

for all $k, 0 \leq k \leq K-1$. We say that s is *complete* for $(\eta_1(\cdot, 0), \eta_2(\cdot, 0))$ if the final configuration $(\eta_1(\cdot, K), \eta_2(\cdot, K))$ satisfies

$$\min(\eta_1(x, K), \eta_2(x, K)) \leq 0,$$

for all $x \in \mathbb{Z}$.

Making Definition 1 precise, we define the *odometer* of a firing sequence s to be the function $u_s : \mathbb{Z} \rightarrow \mathbb{N}$ given by

$$(9) \quad u_s(x) = \#\{0 \leq k < K : x_k = x\}.$$

How does u_s depend on s ? The least action principle for abelian networks addresses this question.

LEMMA 2.1 [Least action principle, Bond and Levine (2016)]. *Let s and s' be firing sequences. If s is legal for $(\eta_1(\cdot, 0), \eta_2(\cdot, 0))$ and s' is complete for $(\eta_1(\cdot, 0), \eta_2(\cdot, 0))$, then $u_s(x) \leq u_{s'}(x)$ for all $x \in \mathbb{Z}$.*

We remark that this statement holds pointwise for any stacks ω , even if s and s' are chosen by an adversary who knows the stacks.

In this paper, we will not use the full strength of Lemma 2.1. Only the following corollaries will be used.

LEMMA 2.2 [Abelian property, Bond and Levine (2016)]. For fixed stacks ω and fixed initial state $(\eta_1(\cdot, 0), \eta_2(\cdot, 0))$:

- (i) If there is a complete firing sequence of length K , then every legal firing sequence has length $\leq K$.
- (ii) If firing sequences s and s' are both legal and complete, then $u_s = u_{s'}$.
- (iii) Any two legal and complete firing sequences result in the same final state $(\eta_1(\cdot, K), \eta_2(\cdot, K))$.

2.2. *Constant convention.* To avoid cumbersome notation, we will often use the same letter (generally C, C', c, c', ϵ and δ) for a constant whose value may change from line to line.

3. Preliminary bound on the stopping time. We denote by $\tau \in \mathbb{N} \cup \{\infty\}$, the stopping time of the process:

$$(10) \quad \tau = \min\{k \geq 0 : \min(\eta_1(x, k), \eta_2(x, k)) = 0 \text{ for all } x \in \mathbb{Z}\}.$$

In this section, we prove a preliminary bound on the stopping time τ . The bound is very crude and will be improved in the next section where we prove the upper bound in Theorem 1.1. However, this bound will be used in several places throughout the article. Note that by Lemma 2.2, given the stacks [see (6)], the stopping time τ and the odometer function $u := u_s$ are well defined and do not depend on the firing sequence s .

PROPOSITION 3.1. *Almost surely for any realization of the stacks, τ is finite. Moreover:*

- i. For any given $\epsilon > 0$, there exists $c = c(\epsilon) > 0$ such that

$$\mathbb{P}(\tau > n^{4+2\epsilon}) \leq e^{-n^c}.$$

- ii. $\mathbb{E}(\tau) \leq 16n^4$.

This result has an immediate consequence, given by the next corollary.

COROLLARY 3.2. *Given $\epsilon > 0$, there exists a constant c such that*

$$\mathbb{P}(u(x) = 0, \forall x \in \mathbb{Z} : |x| \geq n^{4+\epsilon}) \geq 1 - e^{-n^c}.$$

Before proving Proposition 3.1, we recall from Section 1.2 that

$$(11) \quad P_t = \sum_{x \in \mathbb{Z}} \min(\eta_1(x, t), \eta_2(x, t))$$

denotes the total number of co-located oil and water pairs at time t . By definition, the process stops at τ when $P_\tau = 0$. In order to prove Proposition 3.1, we follow the four steps described in the following:

- First, we define a lazy reflected random walk R_i on $\{0, 1, \dots, n\}$ started and reflected at n , and stopped upon hitting 0. Define the following stopping time:

$$(12) \quad \tau' := \min_{i \geq 1} \{R_i = 0\}.$$

- Consequently, we use P_j to define a series of stopping times t_i , and we show that we can bound the tails of the waiting times defined as

$$(13) \quad \text{Wait}_i := t_{i+1} - t_i.$$

- Next, we show that P_{t_i} is stochastically dominated by R_i .
- Finally, we prove Proposition 3.1 by combining information about the distributions of τ' and the waiting times Wait_i .

The lazy reflected random walk R_i is defined as follows. It starts with $R_0 = n$. Inductively, if $R_i = n$ then $R_{i+1} = n$ or $n - 1$, with probability $3/4$ and $1/4$, respectively. Otherwise, if $R_i \in (0, n)$ then it performs a lazy random walk, that is,

$$R_{i+1} = \begin{cases} R_i + 1, & \text{w.p. } 1/4, \\ R_i - 1, & \text{w.p. } 1/4, \\ R_i, & \text{w.p. } 1/2. \end{cases}$$

The walk terminates at the stopping time τ' , defined in equation (12).

To perform the second and third steps, we analyze P_t and show that it is a supermartingale. This was described heuristically in Section 1.2, and here we make this concept formal, as this fact is the key to many of the subsequent arguments.

If at time t a site x emits a pair, then P_{t+1} is either $P_t - 1$, P_t , or $P_t + 1$. Moreover, the distribution of $P_{t+1} - P_t$ depends on the state of the neighbors of x at time t in a fairly simple way.

Define \mathcal{G}_t to be the filtration given by the first t firings. Recall from Definition 2 that $\eta_1(x, t)$ and $\eta_2(x, t)$ are the number of oil and water particles, respectively, at x at time t .

DEFINITION 4. Define for any $x \in \mathbb{Z}$ and nonnegative integer time t including infinity:

$$(14) \quad g_t(x) := \eta_1(x, t) - \eta_2(x, t).$$

We say that at time t a site $x \in \mathbb{Z}$ has *type oil*, 0 or *water* depending on the type of the majority of particles at the site, that is, whether $g_t(x)$ is positive, zero or negative, respectively.

We look at how P_t changes conditional on the filtration at time t . Formally, we look at

$$(15) \quad Z_t := P_{t+1} - P_t.$$

At this point, we observe that Z_t can have four possible distributions conditioned on \mathcal{G}_t . Namely, define four random variables $\xi_1, \xi_2, \xi_3, \xi_4$ as follows:

$$\xi_1 := \begin{cases} 0, & \text{w.p. } 1/2, \\ 1, & \text{w.p. } 1/4, \\ -1, & \text{w.p. } 1/4, \end{cases} \quad \xi_2 := \begin{cases} 0, & \text{w.p. } 3/4, \\ -1, & \text{w.p. } 1/4, \end{cases}$$

$$\xi_3 := \begin{cases} 0, & \text{w.p. } 1/2, \\ -1, & \text{w.p. } 1/2, \end{cases} \quad \xi_4 := 0, \quad \text{w.p. } 1.$$

REMARK 1. Every time that a vertex x fires, we divide the possible *types* of the neighbors of x into four groups which determine the law of Z_t :

$$Z_t \stackrel{\text{law}}{=} \begin{cases} \xi_1, & \text{if the neighbors have different types but neither is 0,} \\ \xi_2, & \text{if exactly one of the neighbors has type 0,} \\ \xi_3, & \text{if both neighbors have type 0,} \\ \xi_4, & \text{if the neighbors have the same nonzero type.} \end{cases}$$

DEFINITION 5. A *firing rule* is an inductive way to determine a legal firing sequence. More formally, it is a function that is defined for any t and any atom $A \subset \mathcal{G}_t$ such that $P_t > 0$. The firing rule outputs an integer z such that there is at least one pair at z at time t in A .

The stacks combined with a firing rule determine the evolution of the process. Given a firing rule, we inductively define the set of stopping times t_i . Set $t_1 = 1$.

Then, inductively, given t_1, \dots, t_i set t_{i+1} to be the first time j after t_i such that Z_j does not have distribution ξ_4 . Let t_L be the last stopping defined. Thus,

$$(16) \quad L := \#\{i \leq \tau : Z_i \stackrel{\text{law}}{\neq} \xi_4\}.$$

Note that with this definition of the stopping times we have

$$P_{t_{i+1}} = P_{t_i+1}.$$

Thus, the distribution of $P_{t_{i+1}} - P_{t_i}$ is either ξ_1, ξ_2 or ξ_3 . Finally, define the waiting times:

$$\text{Wait}_i = t_{i+1} - t_i.$$

With these definitions, we are ready to complete the second and third steps of our outline.

LEMMA 3.3. *For any firing rule the sequence R_i stochastically dominates P_{t_i} . This in particular implies that τ' stochastically dominates L .*

PROOF. The proof is by induction, and the starting configuration is given by $R_0 = P_0 = n$. If $R_i = n$, then the distribution of $R_{i+1} - R_i$ is ξ_3 , by definition of the reflected random walk.

Inductively, if $P_{t_i} \geq R_i = n$ then P_{t_i} must also be n . This means that all sites have type 0 and the distribution of $P_{t_{i+1}} - P_{t_i}$ is ξ_3 . Thus we can couple R_{i+1} and $P_{t_{i+1}}$ such that $R_{i+1} \geq P_{t_{i+1}}$.

On the other hand, if $0 < R_i < n$ then the distribution of $R_{i+1} - R_i$ is ξ_1 while the distribution of $P_{t_{i+1}} - P_{t_i}$ is either ξ_1, ξ_2 or ξ_3 . As all of ξ_1, ξ_2 and ξ_3 are stochastically dominated by ξ_1 we can couple R_{i+1} and $P_{t_{i+1}}$ such that $R_{i+1} \geq P_{t_{i+1}}$. \square

LEMMA 3.4. *For any $\epsilon > 0$, there exists δ such that*

$$\mathbb{P}(L > n^{2+\epsilon}) \leq \mathbb{P}(\tau' > n^{2+\epsilon}) < e^{-n^\delta},$$

where τ' and L are defined in (12) and (16), respectively.

PROOF. The first inequality follows from the fact that τ' stochastically dominates L . The second inequality is a standard fact about lazy random walk (stated later in Lemma 5.1). \square

LEMMA 3.5. *Let E_i be an i.i.d. sequence of random variables whose distribution is the same as the time taken by simple symmetric random walk started from the origin to hit $\pm 2n$. There exists a firing rule such that Wait_i is stochastically dominated by E_i .*

PROOF. At time 1, and at all times $j > 1$ such that Z_{j-1} does not have distribution ξ_4 , we fire the leftmost oil-water pair. For the remaining times j , either both neighbors of the site x fired at time $j - 1$ had an excess of water, in which case we fire a pair from the neighbor of x which just received an oil particle; or both neighbors of x had an excess of oil, in which case we fire a pair from the neighbor of x which just received a water particle. This neighbor has the uniform distribution on $\{x + 1, x - 1\}$ independent of the past. Thus, for each time interval $t_i < j < t_{i+1}$ (where $t_1 = 1$ and t_{i+1} is the first time $j > t_i$ that Z_j does not have distribution ξ_4) the location of the site fired at time j performs a simple random walk on \mathbb{Z} . We now show that this firing rule allows us to control the waiting times.

Let z be the location of the leftmost pair at time t_i and let $I = (a, b)$ be the interval of integers containing z where every location has at least one particle at time t_i . As there are at most $2n$ particles, we have that $I = (a, b) \subset (z - 2n, z + 2n)$.

If there are firings only in the interior of I , then there are no particles at a or b . If the site being fired reaches the boundary of I at time k , then the distribution of Z_k is not ξ_4 , as one of the neighbors of the pair to be fired (either a or b) has

no particles and is of *type 0*. Thus, $t_{i+1} \leq k$. This tells us that the distribution of the waiting time $\text{Wait}_i = t_{i+1} - t_i$ is bounded by the time taken by simple random walk started at the origin to leave the interval $(-2n, 2n)$. Since this is true for each i independently, the lemma is proven. \square

PROOF OF PROPOSITION 3.1. We first notice that by Lemma 2.2, τ defined in (10) is independent of the firing rule. For the purposes of the proof, we will fix our firing rule to be the one described in Lemma 3.5. Now by Lemmas 3.3 and 3.5,

$$\sum_{i=1}^{\tau'} E_i \text{ stochastically dominates } \tau.$$

Thus, $\mathbb{P}(\tau > n^{4+\epsilon}) \leq \mathbb{P}(\sum_{i=1}^{\tau'} E_i \geq n^{4+\epsilon})$. If $\sum_{i=1}^{\tau'} E_i \geq n^{4+\epsilon}$ then either,

$$\tau' > 0.1n^{2+\epsilon/2} \quad \text{or} \quad \sum_{i=1}^{0.1n^{2+\epsilon/2}} E_i > n^{4+\epsilon/2}.$$

Therefore,

$$\mathbb{P}(\tau > n^{4+\epsilon}) \leq \mathbb{P}(\tau' > 0.1n^{2+\epsilon/2}) + \mathbb{P}\left(\sum_{i=1}^{0.1n^{2+\epsilon/2}} E_i > n^{4+\epsilon}\right).$$

The first term is bounded by Lemma 3.4. The second is bounded using standard bounds on the distribution of the time for simple random walk started at the origin to leave a fixed interval $(-k, k)$. Both of these probabilities are bounded by e^{-n^δ} for some $\delta = \delta(\epsilon) > 0$.

Furthermore, by Lemma 3.5 we have that the E_i 's are all i.i.d., hence we can apply Wald's identity [see, e.g., Section 3.1 in Durrett (2010)] and get that

$$\mathbb{E}(\tau) \leq \mathbb{E}(\tau')\mathbb{E}(E_1) \leq 16n^4,$$

which completes the proof. \square

For definiteness, throughout the rest of the article we run the process according to the firing rule described in the proof of Lemma 3.5. We remark that any other firing rule would work as well.

4. Proof of Theorem 1.1 (upper bound).

4.1. *Notation.* In order to proceed, we need to introduce some further notation. Let

$$\|u\|_\infty = \max\{u(x) : x \in \mathbb{Z}\}.$$

In this section, we will bound from below the probability of the event

$$(17) \quad \mathcal{G} = \{\|u\|_\infty \leq Cn^{4/3}\}$$

for some large constant C . To this purpose, we define

$$\text{Returns}(x) := \#\{t \leq \tau : \eta_1(x, t) = \eta_2(x, t), x_t \in \{x - 1, x + 1\}\},$$

(x_t is the location of firing at time t). Thus, $\text{Returns}(x)$ is the number of times such that:

1. x has type 0, (the same number, possibly 0 of oil and water particles), and
2. a pair of particles is emitted from $x - 1$ or $x + 1$.

Then define

$$(18) \quad \text{Returns} = \sum_{x \in \mathbb{Z}} \text{Returns}(x).$$

Recall the definition of $N_i(t)$ from equation (5) and notice that

$$(19) \quad \text{Returns} = N_2(\tau) + 2N_3(\tau).$$

Our goal is to show that Returns is large. The advantage of the decomposition in (18) is that it will allow us to show the relationship between Returns and the odometer function.

Finally, recall that \mathcal{G}_t is the σ -algebra generated by the movement of the first t pairs that are emitted and notice that, from the definition of P_t (11) we have that

$$P_t = \sum_{x \in \mathbb{Z}} \min[\eta_1(x, t), \eta_2(x, t)]$$

is the number of pairs at the time of the t th emission. We recall that P_t is a supermartingale with respect to \mathcal{G}_t .

4.2. *Outline.* In order to show that it is unlikely that $\|u\|_\infty$ is greater than a big constant times $n^{4/3}$, we rely on three main ideas.

- (i) *The odometer is fairly regular.* Typically,

$$|u(x) - u(x + 1)| \leq 2n + u(x)^{1/2}.$$

This regularity implies that under the assumption that $u(x_0)$ is much bigger than $n^{4/3}$ then it is likely that $u(x)$ is much bigger than $n^{4/3}$ for all x such that $|x - x_0| < n^{1/3}$.

(ii) *The variable Returns can be expressed approximately in term of the odometer function.* Fix $x \in \mathbb{Z}$ and consider $\eta_1(x, k) - \eta_2(x, k)$ (difference of number of oil particles and water particles) as a function of k . This function performs

a lazy random walk that takes about

$$(u(x - 1) + u(x + 1)) \approx 2u(x)$$

steps, (the approximation is because of the previously mentioned regularity). Thus, we expect $\text{Returns}(x)$ to be on the order of $u(x)^{1/2}$. Summing up over all x , we expect

$$(20) \quad \text{Returns} = \sum_{x \in \mathbb{Z}} \text{Returns}(x) \approx \sum_{x \in \mathbb{Z}} u(x)^{1/2}.$$

Combined with the previous paragraph this implies that if $\|u\|_\infty$ is much larger than $n^{4/3}$ then it is likely that Returns is much larger than n .

(iii) *The process P_t is a supermartingale.* The sum of the negative drifts until the process terminates is, by equation (19),

$$-\frac{1}{4}(N_2(\tau) + 2N_3(\tau)) = -\frac{1}{4}\text{Returns}.$$

Since P_t starts at n and stops when it hits 0, the typical value of Returns should be around $4n$.

We use the Azuma–Hoeffding inequality to show that the probability of the event “ Returns is much larger than $4n$ ” is decaying very rapidly. By the previous paragraphs, we also will get that the probability that $\|u\|_\infty$ is much larger than $n^{4/3}$ is decaying very rapidly.

The main difficulty in implementing this outline comes in the second step as the odometer function and Returns are correlated in a complicated way.

4.3. *The bad events.* To make our outline formal, we now define our set of bad events. The first three of these deal with the odometer function. But first we use the odometer function to define

$$\text{Base} = \{x : u(x) > 0\} \subset \mathbb{Z}.$$

(0) $\mathcal{B}_0 = \{\text{Base} \not\subset [-n^5, n^5]\}.$

(i) $\mathcal{B}_1 = \{\|u\|_\infty \geq n^{4.05}\}.$

(ii) *Gradient of the Odometer.* It is natural to expect the odometer to decrease as one goes away from the origin (see Figure 1). The next event \mathcal{B}_2 is the event where the *gradient* of the odometer function, $u(x) - u(x + 1)$, is too large or has the wrong sign.

Let

$$m(x) = \begin{cases} \min\left\{n, \min_{0 \leq y \leq x} u(y)\right\}, & \text{for } x > 0 \text{ and} \\ \min\left\{n, \min_{x \leq y \leq 0} u(y)\right\}, & \text{for } x \leq 0. \end{cases}$$

We define:

$$\begin{aligned} \mathcal{B}_2 := & \{ \exists x \in [-n^5, n^5] : u(x) \geq n^{0.5} \text{ and} \\ & |u(x + 1) - u(x)| > 2m(x) + \max(u(x), u(x + 1))^{0.51} \} \\ & \cup \{ \exists x \in [0, n^5] : u(x) \geq n^{0.5} \text{ and} \\ & (u(x + 1) - u(x)) > \max(u(x), u(x + 1))^{0.51} \} \\ & \cup \{ \exists x \in [-n^5, 0] : u(x) \geq n^{0.5} \text{ and} \\ & (u(x - 1) - u(x)) > \max(u(x), u(x + 1))^{0.51} \}. \end{aligned}$$

In all the three events above, the $\max(u(x), u(x + 1))^{0.51}$ corrections are an upper bound on the fluctuations. The definition of the events are then based on the fact that ignoring corrections due to fluctuation, for any $x > 0$, one has $0 < u(x) - u(x + 1) \leq 2m$ as $u(x) - u(x + 1)$ represents the number of particles eventually to the right of x . More details are provided in the proof of Lemma 4.5.

REMARK 2. While the definition of \mathcal{B}_2 is quite technical, we now give one consequence of it that is representative of how we will use it. Let $\mathcal{B}_0^c \cap \mathcal{B}_2^c$ occur and consider the set of x such that $n < u(x) < n^{1.96}$ [or equivalently $1 < \log_n(u(x)) < 1.96$]. Then

$$(21) \quad |u(x) - u(x + 1)| < 2m(x) + u(x)^{0.51} \leq 2n + (n^{1.96})^{0.51} \leq 3n.$$

For any x and y in a connected component of this set, then (21) implies

$$\text{if } |\log_n(u(x)) - \log_n(u(y))| \geq 0.05 \quad \text{then } |x - y| > \frac{1}{6}n^{0.05}.$$

This is because our conditions on x and y imply $|u(x) - u(y)| \geq n^{1.05} - n > 0.5n^{1.05}$. So between x and y the odometer changes by at least $0.5n^{1.05}$ in increments of at most $3n$.

Our proof makes heavy use of this and similar estimates that follow from $\mathcal{B}_0^c \cap \mathcal{B}_2^c$. Much of the complication of our proof comes from the fact that we need to use different estimates depending on whether $m(x) = n$ or $m(x) < n$ and whether $\log_n(u(x))$ is greater than 1.96, between 1 and 1.96 or less than 1. These estimates are used in Lemmas 4.12 and 4.13 which are used to prove Lemma 4.14. The conclusion of Lemma 4.14 is useful in showing that Returns is large because of our next bad event.

(iii) *Regularity of returns*

$$\mathcal{B}_3 = \left\{ \exists i, j, k : |i|, |j| \leq n^5, k \in [n^{0.5}, n^5], j - i > 0.1n^{0.01}, \right. \\ \left. \text{and } u(x) \geq k \ \forall x \in [i, j], \text{ and } \sum_{x=i+1}^{j-1} \text{Returns}(x) < 0.01(j - i)\sqrt{k} \right\}.$$

Finally, define the event

$$(22) \quad \mathcal{B}_4 = \{ \text{Returns} \geq 20(n + \tau^{0.51}) \}.$$

To complete our outline, we show that:

- $\mathcal{G}^c \subset \bigcup_{i=0}^4 \mathcal{B}_i$ and
- $\mathbb{P}(\mathcal{B}_i)$ are small for $i = 1, \dots, 4$.

4.4. P_t is a supermartingale. Recall from (4) that

$$Z_k := P_{k+1} - P_k.$$

Recall from Remark 1 that conditional on the past, each Z_k has one of four possible distributions ξ_1, \dots, ξ_4 .

LEMMA 4.1. P_t is a supermartingale and

$$\sum_{t=1}^{\infty} \mathbb{E}(Z_{t+1} | \mathcal{F}_t) = -\frac{1}{4} \text{Returns}.$$

PROOF. This follows from the discussion in Section 1.2. The summands on the left-hand side are all 0, $-\frac{1}{4}$ or $-\frac{1}{2}$. By (19) and (5), Returns is the sum of the number of $-\frac{1}{4}$ terms in the sum plus twice the number of $-\frac{1}{2}$ terms. \square

LEMMA 4.2. There exist C, C' such that $\mathbb{P}(\mathcal{B}_4) < Ce^{-n^{C'}}$.

PROOF. As $\text{Returns} \leq \tau$, we have that

$$\mathcal{B}_4 = \bigcup_{r \geq 20n} \mathcal{B}_4 \cap \{ \tau = r \}.$$

Note that by Lemma 4.1 and because $P_\tau = 0$ (i.e., $\sum_{i=1}^r Z_i = -n$), for every $r \geq 20n$,

$$\mathcal{B}_4 \cap \{ \tau = r \} \subset \left\{ \sum_{i=1}^r Z_i - \mathbb{E}(Z_i | \mathcal{F}_{i-1}) \geq 4n + 5r^{0.51} \right\}.$$

Also note that $Z_t - \mathbb{E}(Z_t | \mathcal{F}_{t-1})$ are the increments of a martingale and are bounded by 1. Thus, we can apply the Azuma–Hoeffding inequality to get the bound $\mathbb{P}(\mathcal{B}_4 \cap \{\tau = r\}) \leq e^{-r^{0.02}}$. The lemma follows from the union bound. \square

Now define the new event

$$(23) \quad \mathcal{E} = \mathcal{G}^c \cap \mathcal{B}_0^c \cap \mathcal{B}_1^c \cap \mathcal{B}_2^c,$$

where all the events are defined in Section 4.3. Remember the event \mathcal{G} is that the odometer at the origin is less than a large constant times $n^{4/3}$ and the events \mathcal{B}_0^c , \mathcal{B}_1^c and \mathcal{B}_2^c are regularity conditions on the odometer. The key lemma needed for the proof of the upper bound is the following.

LEMMA 4.3.

$$(24) \quad \mathcal{E} \cap \mathcal{B}_3^c \subset \mathcal{B}_4,$$

where \mathcal{B}_4 was defined in (22). Thus,

$$(25) \quad \mathbb{P}(\mathcal{G}^c) \leq \mathbb{P}(\mathcal{B}_0) + \mathbb{P}(\mathcal{B}_1) + \mathbb{P}(\mathcal{B}_2) + \mathbb{P}(\mathcal{B}_3) + \mathbb{P}(\mathcal{B}_4).$$

Assuming (24), (25) follows by taking the union bound. We postpone the proof of (24) to Section 4.8 and proceed to completing the proof of the upper bound in Theorem 1.1.

LEMMA 4.4. *There exist positive constants D, C' and γ such that*

$$\mathbb{P}(\mathcal{B}_0), \mathbb{P}(\mathcal{B}_1), \mathbb{P}(\mathcal{B}_2), \mathbb{P}(\mathcal{B}_3), \mathbb{P}(\mathcal{B}_4) < D e^{-C' n^\gamma}.$$

PROOF. $\mathbb{P}(\mathcal{B}_0)$ and $\mathbb{P}(\mathcal{B}_1)$ are bounded by Proposition 3.1. $\mathbb{P}(\mathcal{B}_4)$ is bounded by Lemma 4.2. The bounds for $\mathbb{P}(\mathcal{B}_2)$ and $\mathbb{P}(\mathcal{B}_3)$ appear as Lemmas 4.5 and 4.10, which appear in Sections 4.6 and 4.7, respectively. \square

4.5. *Proof of the upper bound.* Thus, by (25) and Lemma 4.4, there exists $\epsilon > 0$, such that for large enough n ,

$$(26) \quad \mathbb{P}(\mathcal{G}) > 1 - e^{-n^\epsilon},$$

where G was defined in (17). The proof of the upper bound is hence complete.

In the following sections, we bound $\mathbb{P}(\mathcal{B}_2)$ and $\mathbb{P}(\mathcal{B}_3)$.

4.6. *The probability of the bad events.*

LEMMA 4.5. *There exist positive constants C, C' and γ such that*

$$\mathbb{P}(\mathcal{B}_2) < C e^{-C' n^\gamma}.$$

We first introduce a definition.

DEFINITION 6. Let $\Delta^x(k)$ denote the quantity such that, after k pairs have been emitted from x , there are $k + \Delta^x(k)$ particles that moved to the right (i.e., to $x + 1$) and $k - \Delta^x(k)$ particles that have moved to the left (i.e., to $x - 1$). Notice that this is just a function of the stack of variables X_i^x, Y_i^x at the site x .

PROOF OF LEMMA 4.5. Without loss of generality, we assume that $x \geq 0$. Recall from Section 4.3(ii) that

$$m(x) = \min\left\{n, \min_{0 \leq y \leq x} u(y)\right\}.$$

Suppose that at some time t exactly k pairs have been emitted from x , and exactly k' pairs have been emitted from $x + 1$. Then the number of particles to the right of x is

$$k + \Delta^x(k) - (k' - \Delta^{x+1}(k')).$$

This holds for all times t , in particular for the time when the process stops [at which time $k = u(x)$ and $k' = u(x + 1)$]. Let $\Delta^x = \Delta^x(u(x))$ and $\Delta^{x+1} = \Delta^{x+1}(u(x + 1))$. Since for any $0 \leq y \leq x$, the number of particles that settle to the right of x is at most the number $2u(y)$ of particles emitted from y (recall u counts emitted pairs), we have

$$0 \leq u(x) + \Delta^x - (u(x + 1) - \Delta^{x+1}) \leq 2m(x).$$

Rearranging, we get

$$-\Delta^x - \Delta^{x+1} \leq u(x) - u(x + 1) \leq 2m(x) - \Delta^x - \Delta^{x+1}.$$

Then the event \mathcal{B}_2 implies that

$$\exists x \in [-n^5, n^5] \text{ and } k, \quad n^{0.5} \leq k \leq n^{4.1} : |\Delta^x(k)| > 0.5k^{0.51}.$$

The result follows from standard concentration results of random walks (cf. Appendix A.1) and union bounding over all possible values of x and k . Thus, the result holds for some appropriate C, C' and γ . We omit the details. \square

We bound the probability of \mathcal{B}_3 next. However, we need a few preliminary results first. Furthermore, in this context we work with a slightly modified but an equivalent setting.

4.7. *Merged stacks.* We describe another process $(\eta'_1(\cdot, \cdot), \eta'_2(\cdot, \cdot))$ which has the same law as the process $(\eta_1(\cdot, \cdot), \eta_2(\cdot, \cdot))$ defined in Definition 2.

In this version, analogous to (6) the source of randomness is a set of independent variables (modified stacks):

$$(27) \quad \omega' = (X_i^x, Y_i^x, \bar{X}_i^x, \bar{Y}_i^x)_{x \in 3\mathbb{Z}, i \in \mathbb{N}}$$

with $\mathbb{P}(X_i^x = \pm 1) = P(Y_i^x = \pm 1) = \mathbb{P}(\bar{X}_i^x = \pm 1) = \mathbb{P}(\bar{Y}_i^x = \pm 1) = \frac{1}{2}$. Denote by Ω' the set of all stacks ω' . Note that stacks are located only at every $x \in 3\mathbb{Z}$.

Informally, the i th firing from $x \in 3\mathbb{Z}$ uses moves X_i^x and Y_i^x as before, but the i th firing from the set $\{x - 1, x + 1\}$ uses moves $\pm \bar{X}_i^x$ and $\pm \bar{Y}_i^x$ according to whether the firing was from $x - 1$ or $x + 1$, respectively. We refer to $(\bar{X}_i^x, \bar{Y}_i^x)_{i \geq 1}$ as the *merged stacks* of $x - 1$ and $x + 1$.

Formally, given a firing sequence $s = (x_0, \dots, x_{K-1})$, we define the pair $(\eta'_1(\cdot, k), \eta'_2(\cdot, k))$ inductively as follows. If $x_k \in 3\mathbb{Z}$, then

$$\begin{aligned} \eta'_1(\cdot, k + 1) &= \eta'_1(\cdot, k) - \delta(x_k) + \delta(x_k + X_{i_k}^{x_k}), \\ \eta'_2(\cdot, k + 1) &= \eta'_2(\cdot, k) - \delta(x_k) + \delta(x_k + Y_{i_k}^{x_k}), \end{aligned}$$

where $i_k = \#\{j \leq k : x_j = x_k\}$. If $x_k \in 3\mathbb{Z} \pm 1$, then

$$\begin{aligned} \eta'_1(\cdot, k + 1) &= \eta'_1(\cdot, k) - \delta(x_k) + \delta(x_k \mp \bar{X}_{i'_k}^{x_k \mp 1}), \\ \eta'_2(\cdot, k + 1) &= \eta'_2(\cdot, k) - \delta(x_k) + \delta(x_k \mp \bar{Y}_{i'_k}^{x_k \mp 1}), \end{aligned}$$

where $i'_k = \#\{j \leq k : x_j \in \{x_k, x_k \mp 2\}\}$.

To compare the modified process to the original, we use the following proposition.

PROPOSITION 4.6. *Let $(Z_i)_{i \in I}$ be independent uniform ± 1 -valued random variables indexed by a countable set I . Let $i_1, i_2, \dots \in I$ be a sequence of distinct random indices and ξ_1, ξ_2, \dots a sequence of ± 1 -valued random variables such that for all $k \geq 1$ both i_k and ξ_k are measurable with respect to $\mathcal{F}_{k-1} := \sigma(Z_{i_\ell})_{1 \leq \ell \leq k-1}$. Then $(\xi_k Z_{i_k})_{k \geq 1}$ is an i.i.d. sequence.*

PROOF. We proceed by induction on ℓ to show that $(\xi_k Z_{i_k})_{1 \leq k \leq \ell}$ is i.i.d. Since ξ_ℓ and i_ℓ are $\mathcal{F}_{\ell-1}$ -measurable, and i_ℓ is distinct from $i_1, \dots, i_{\ell-1}$, we have

$$\mathbb{E}(\xi_\ell Z_{i_\ell} | \mathcal{F}_{\ell-1}) = \xi_\ell \mathbb{E}(Z_{i_\ell} | \mathcal{F}_{\ell-1}) = 0.$$

Since $\xi_\ell Z_{i_\ell}$ is ± 1 -valued the proof is complete. \square

Recall Ω the set of all stacks ω defined by the original process, and Ω' , the set of all stacks ω' defined by the modified process. Let $\tau(\omega)$ denote the stopping time of the sequence ω , and similarly $\tau(\omega')$. Furthermore, denote by $(o_\tau, w_\tau)(\omega)$ the final configuration after performing ω , and by $(o'_\tau, w'_\tau)(\omega')$ the final configuration of the process after performing ω' .

LEMMA 4.7. *There is a measure-preserving map $\phi : \Omega' \rightarrow \Omega$ such that with the firing rule described in the proof of Lemma 3.5,*

$$(\eta'_1(\cdot, \cdot), \eta'_2(\cdot, \cdot)) \stackrel{d}{=} (\eta_1(\cdot, \cdot), \eta_2(\cdot, \cdot)).$$

In particular, $\tau(\phi(\omega')) = \tau(\omega')$, $(o'_\tau, w'_\tau)(\omega') = (o_\tau, w_\tau)(\phi(\omega'))$ and the odometer counts in both the processes are same.

PROOF. Given $\omega' \in \Omega'$, let x_1, x_2, \dots be the resulting sequence following the firing rule described in the proof of Lemma 3.5, and let $u(x)$ be the number of firings performed at x in the modified process. We set $\phi(\omega') = (X_i^x, Y_i^x)_{x \in \mathbb{Z}, i \in \mathbb{N}}$ where if $i \leq u(x)$ then X_i^x (resp., Y_i^x) is the direction in which the i th oil (resp., i th water) exited x in the modified process.

If $i > u(x)$, then we make an arbitrary choice (e.g., split the unused portion of each merged stack into even and odd indices).

It is important to note, that each x_k is measurable with respect to the σ -algebra \mathcal{F}'_{k-1} generated by the stack variables in ω' used before time k , and that each stack variable in ω' is used at most once. The stack variables used at time k have the form $\xi X, \xi Y$ where X, Y are stack variables not yet used and $\xi = \mathbf{1}_{x_k \in 3\mathbb{Z} \cup (3\mathbb{Z}+1)} - \mathbf{1}_{x_k \in 3\mathbb{Z}-1}$ is a random sign that is measurable with respect to \mathcal{F}'_{k-1} . Conditional on \mathcal{F}'_{k-1} , ξX and ξY are independent uniform ± 1 random variables, and ϕ is measure-preserving by Proposition 4.6. \square

Lemma 4.7 allows us to switch between events defined in one version to the other. For $x \in 3\mathbb{Z}$, let

$$W^x(\ell) = \frac{\bar{X}_\ell^x - \bar{Y}_\ell^x}{2},$$

where $\bar{X}_\ell^x, \bar{Y}_\ell^x$ are defined in (27). This represents the change in the difference of oil and water particles at x when the ℓ th firing takes place from the set $\{x - 1, x + 1\}$. Clearly, $W^x(\ell)$ has the same distribution as one step of a symmetric lazy random walk. Now define

$$\tilde{R}^x(k) = \# \left\{ 0 \leq j \leq k : \sum_{\ell=1}^j W^x(\ell) = 0 \right\}.$$

Define \mathcal{B}'_3 to be the event that there exist three integers i, j, k such that:

- (i) $|i|, |j| \leq n^5$,
- (ii) $j - i \geq 0.1n^{0.01}$,
- (iii) $k \in [n^{0.5}, n^5]$ and
- (iv) $\sum_{x \in (i, j), 3|x} \tilde{R}^x(0.9k) < 0.01\sqrt{k}(j - i)$.

We now state a standard fact about number of returns to origin for the simple random walk on \mathbb{Z} .

LEMMA 4.8. *Let $\{S_i\}_{i \geq 0}$ be a lazy simple random walk on \mathbb{Z} started at the origin. Let*

$$\text{Zeros}(l) = \#\{i : 0 \leq i \leq l \text{ and } S_i = 0\}.$$

Then for all l ,

$$\mathbb{P}(\text{Zeros}(0.9l) > 0.1\sqrt{l}) \geq \frac{1}{2}.$$

PROOF. See Chapter III, Section 5 of [Feller \(1968\)](#). \square

LEMMA 4.9. *There exist positive constants C, C' and γ such that*

$$\mathbb{P}(\mathcal{B}'_3) < Ce^{-C'n^\gamma}.$$

PROOF. Fix i, j, k and $x \in (i, j)$. Then, from Lemma 4.8 it follows

$$\mathbb{P}(\tilde{R}^x(0.9k) > 0.1\sqrt{k}) \geq \frac{1}{2}.$$

Now using the independence of the stacks at the multiples of three, we get

$$\begin{aligned} & \mathbb{P}\left(\sum_{x \in (i, j), 3|x} \tilde{R}^x(0.9k) < 0.01\sqrt{k}(j - i)\right) \\ & < \mathbb{P}\left(\#\{x \in (i, j), 3|x : \tilde{R}^x(0.9k) > 0.1\sqrt{k}\} < \frac{1}{10}(j - i)\right) \\ & < ce^{-c'n^{0.1}}, \end{aligned}$$

where c, c' are positive constants.

As there are at most $4n^{15}$ choices of i, j and k there exists positive constants c, c' and γ' such that

$$\mathbb{P}(\mathcal{B}'_3) < 4n^{15}ce^{-c'n^{\gamma'}}$$

so the lemma is true for some choice of C, C' and γ . \square

The bound on $\mathbb{P}(\mathcal{B}_3)$ is now a corollary.

LEMMA 4.10. *There exist positive constants C, C' and γ such that*

$$\mathbb{P}(\mathcal{B}_3) < Ce^{-C'n^\gamma}.$$

PROOF. Consider the map ϕ defined in Lemma 4.7 and the event $\phi^{-1}(\mathcal{B}_3)$. By the measure preserving property of ϕ , we have $\mathbb{P}(\mathcal{B}_3) = \mathbb{P}(\phi^{-1}(\mathcal{B}_3))$ where the two probabilities are in the two different probability spaces mentioned in the

statement of Lemma 4.7. Note that the event $\phi^{-1}(\mathcal{B}_3)$ implies \mathcal{B}'_3 . This is because (iv) in the definition of \mathcal{B}'_3 says

$$\sum_{x \in (i, j), 3|x} \tilde{R}^x(0.9k) < 0.01\sqrt{k}(j - i)$$

whereas in the definition of \mathcal{B}_3 we have

$$\sum_{x \in (i, j)} \tilde{R}^x(0.9k) < 0.01\sqrt{k}(j - i).$$

The proof now follows from Lemma 4.9. \square

The rest of this section is devoted to the key technical proof of Lemma 4.3, which is all that remains to finish off the proof of the upper bound in Theorem 1.1.

4.8. *Proof of Lemma 4.3.* We split the proof of Lemma 4.3 into several lemmas. In particular, it will suffice to show that

$$(28) \quad \frac{1}{2}\text{Returns} > 20n,$$

$$(29) \quad \frac{1}{2}\text{Returns} > 20\tau^{0.51}.$$

Recall that on the event \mathcal{E} [see (23)], the height is much bigger than $n^{4/3}$ but less than $n^{4.05}$, the odometer is supported inside $[-n^5, n^5]$ and gradient of the odometer is such that \mathcal{B}_2^c occurs.

LEMMA 4.11. *If the event \mathcal{E} occurs, then*

$$(30) \quad \tau \geq n^{5/3}$$

and if $\mathcal{E} \cap \mathcal{B}_3^c$ occurs, then

$$\frac{1}{2}\text{Returns} > 20n.$$

PROOF. As usual, we choose to give a direct proof with explicit constants (which might be far from optimal), for sake of exposition.

If \mathcal{B}_0^c occurs, then there exists

$$x_* \in [-n^5, n^5], \quad \text{such that } u(x_*) = \|u\|_\infty.$$

We now consider two cases.

Case 1: If $\|u\|_\infty^{0.51} \leq 2n$, then the events \mathcal{G}^c and \mathcal{B}_2^c imply that

$$(31) \quad u(x) > 700,000n^{4/3} > (800n^{2/3})^2,$$

for all x in the interval,

$$X_0 := [x_* - 100n^{1/3}, x_* + 100n^{1/3}] \cap [-n^5, n^5].$$

This follows from the event $\mathcal{B}_0^c \cap \mathcal{B}_2^c$ by the same argument as in Remark 2. Then $|X_0| \geq 100n^{1/3}$, because by \mathcal{B}_0^c , we have $x_* \in [-n^5, n^5]$ so at least one of the intervals

$$[x_* - 100n^{1/3}, x_*] \quad \text{or} \quad [x_*, x_* + 100n^{1/3}]$$

is entirely contained in $[-n^5, n^5]$. Thus, looking at the volume of the odometer in X_0 , we have

$$(32) \quad \tau \geq \sum_{x \in X_0} u(x) \geq 700,000n^{4/3}|X_0| \geq n^{5/3}$$

and

$$\text{Returns} \geq \sum_{x \in X_0} \text{Returns}(x) \geq (100n^{1/3})(0.01)(800n^{2/3}) \geq 40n.$$

The next to last inequality is by (31), the size of X_0 and the definition of \mathcal{B}_3^c . Thus, we have obtained inequality (28).

Case 2: If $\|u\|_\infty^{0.51} > 2n$, then one expects Returns to be even larger. Note that by \mathcal{B}_2^c every gradient is at most $2\|u\|_\infty^{0.51}$. Thus, the odometer is at least $\|u\|_\infty/2$ over an interval of length $\|u\|_\infty^{0.49}/2 \geq n^{0.1}$. We take X_0 to be this interval. Thus, by \mathcal{B}_3^c ,

$$\text{Returns} \geq \sum_{x \in X_0} \text{Returns}(x) \geq (\|u\|_\infty^{0.49}/2)(0.01)(\|u\|_\infty^{0.5}) \geq 40n. \quad \square$$

4.9. *Partitioning Base.* Inequality (29) is more involved to verify. However, it relies on the observation that at most sites, $\text{Returns}(x) \approx \sqrt{u(x)}$, [since the number of returns to the origin for a random walk in $u(x)$ steps is roughly about $\sqrt{u(x)}$]. Now if the value of $u(x)$ does not change sharply (this is where the gradient bounds in the definition of \mathcal{B}_2 are used) this then implies that

$$\text{Returns} = \sum_x \text{Returns}(x) \gg \sqrt{\sum_x u(x)} = \sqrt{\tau}.$$

Thus, the proof proceeds by showing that there is a subset of Z which can be written as the union of not too small intervals, where the odometer is uniformly high and not too rough and contributes a constant fraction of $\sum_x u(x)$. On this set, the above inequality can be made precise.

Formally, we partition Base up into smaller intervals:

$$\text{Base} = \bigcup_{i=-K'}^K \text{Base}_i,$$

where, for each i , we set each $\text{Base}_i = [a_i, b_i]$ for some a_i and b_i which we describe in the following. We inductively define the Base_i in a way so that on the event \mathcal{E} and for most i we have

$$(33) \quad b_i - a_i > 0.1n^{0.01}.$$

This will involve a series of estimates like in Remark 2. Define $h_j = n^{4.05-0.05j}$ for $j = 0$ to $j = 68$ and $h_{69} = 0$. Let

$$H = \{h_j : j = 1, \dots, 68\}.$$

Let j' be such that $h_{j'}$ is the closest value in H to $u(0)$. Let

$$b_0 = \inf\{x : x \geq 0 \text{ and } u(x + 1) \notin (h_{j'+1}, h_{j'-1})\}.$$

We say that Base_0 starts at height $h_{j'}$ and ends at height $h_{j''} \in H$ where j'' is defined so that $h_{j''}$ is the closest element of H to $u(b_0 + 1)$.

Now we inductively define Base_{i+1} . Suppose we have defined $\text{Base}_i = [a_i, b_i]$ which ends at height h_k . We will inductively define $\text{Base}_{i+1} = [a_{i+1}, b_{i+1}]$. We let $a_{i+1} = 1 + b_i$ and say Base_{i+1} starts at height $h_k \in H$. Then we define

$$b_{i+1} = \inf\{x : x \geq a_i \text{ and } u(x + 1) \notin (h_{k+1}, h_{k-1})\}.$$

We say the block Base_{i+1} ends at height $h_{k'} \in H$ where $h_{k'}$ is the closest element of H to $u(b_i + 1)$ and $h_{k'}$ is the closest element of H to $u(b_i + 1)$.

For the case of negative indices, the procedure is totally analogous. Finally, for all $j \in \{0, \dots, 68\}$ define

$$(34) \quad B_j := \text{the union of all } \text{Base}_i \text{ that start at } h_j \text{ and have } |\text{Base}_i| > 0.1n^{0.01}.$$

LEMMA 4.12. *If a block Base_i with $i \geq 0$ starts at height h_j and ends at height $h_{j'}$ then $j' \neq j$. On the event \mathcal{E} and $j' < j < 68$, then*

$$b_i - a_i > 0.1n^{0.01}.$$

PROOF. The first statement is true because

$$u(1 + b_i) \notin (h_{k+1}, h_{k-1})$$

so the closest element of H to $u(1 + b_i)$ is not h_k . Consider an interval Base_i with $i \geq 0$ where Base_i starts at height h_j and ends at height $h_{j'}$ with $j' < j$. Over the course of such an interval the odometer increased by at least $0.49h_{j-1}$, going from less than $0.5(h_j + h_{j-1})$ to at least h_{j-1} . Since $j < 68$, we have

$$u(x) > h_{j+1} \geq h_{68} = n^{0.65} > n^{0.5}$$

for all $x \in \text{Base}_i$. Thus, the event \mathcal{E} implies

$$u(x + 1) - u(x) < u(x)^{0.51} < (h_{j-1})^{0.51}.$$

Thus, by the choice of the h_i these intervals must have width at least

$$b_i - a_i \geq \frac{0.49h_{j-1}}{(h_{j-1})^{0.51}} \geq 0.49(h_{j-1})^{0.49} \geq 0.49n^{0.3} > 0.1n^{0.01}.$$

The next to last inequality follows because $j < 68$ so $h_{j-1} \geq n^{0.7}$. \square

LEMMA 4.13. *If \mathcal{E} occurs and a block Base_i with $i > 0$ starts at height h_j and ends at height $h_{j'}$ with $j' > j$ then:*

1. $b_i - a_i > 0.1n^{0.01}$ or
2. $68 \geq j \geq 60$ and for no $k, 0 \leq k < i$ the block Base_k starts at h_j and ends at a height $h_{k'}$ with $k' > j$.

PROOF. Consider an interval Base_i with $i \geq 0$ where Base_i starts at height h_j and ends at height $h_{j'}$ with $j' > j$. Over the course of such an interval, the odometer decreased by at least $0.49h_j$, going from at least $0.5(h_j + h_{j+1})$ to at most h_{j+1} .

First, we consider the case that $j < 60$. We have

$$u(x) > h_{j+1} \geq h_{60} = n^{1.05}$$

for all $x \in \text{Base}_i$. Thus, the event \mathcal{E} implies

$$u(x) - u(x + 1) < 2m(x) + u(x)^{0.51} = 2n + u(x)^{0.51} < 3(h_j)^{0.96}.$$

Thus, by the choice of the h_i these intervals must have width at least

$$b_i - a_i \geq \frac{0.49h_j}{3(h_j)^{0.96}} \geq 0.15(h_j)^{0.04} > 0.1n^{0.01}.$$

Next, we consider the case that Base_i ends at h_j with $60 \leq j \leq 68$. Suppose there exists $k < i$ such that Base_k starts at h_j and ends at a height $h_{k'}$ with $k' > j$. This implies that $j < 68$ and

$$m(x) \leq h_{j+1} \leq (h_j)n^{-0.05}$$

for all $x \in \text{Base}_i$. Thus, the event \mathcal{E} and $j \leq 67$ implies $u(x) > n^{0.65}$ and

$$u(x) - u(x + 1) < 2m(x) + u(x)^{0.51} < 3h_j n^{-0.05}.$$

Thus, these intervals must have width at least

$$b_i - a_i \geq \frac{0.49h_j}{3(h_j)n^{-0.05}} \geq 0.15n^{0.05} > 0.1n^{0.01}. \quad \square$$

REMARK 3. We need to only worry about the case $j' > j$ since otherwise the odometer does not decrease and only helps us in our arguments. The reason for separating the study of the case $j' > j$ into $j < 60$ and $68 \geq j \geq 60$ is that a priori

we have not ruled out that most of the contribution to $\tau = \sum_x u(x)$ comes from small values of $u(x)$. In the gradient bound of $m(x) = \min\{n, \min_{0 \leq y \leq x} u(y)\}$ for $x > 0$ (see definition of \mathcal{B}_2), we use n as an upper bound for $m(x)$ when $u(x)$ is large ($j < 60$) and we use $\min_{0 \leq y \leq x} u(y)$ as an upper bound for $m(x)$ when $u(x)$ is small ($68 \geq j \geq 60$).

4.10. *Consequences of a regular gradient.* Recall the definition of B_i from (34).

LEMMA 4.14. *On the event \mathcal{E} , there exists $i \in \{1, \dots, 68\}$ such that*

$$\sum_{x \in B_i} u(x) \geq 0.01\tau.$$

PROOF. Define

$$B^* = \bigcup_{i: |\text{Base}_i| \leq 0.1n^{0.01}} \text{Base}_i.$$

We first show that

$$(35) \quad \sum_{x \in B^*} u(x) \leq 20n^{1.2}.$$

The lemma will follow easily from (30), (35) and the pigeonhole principle.

Let $I = \{i : |\text{Base}_i| \leq 0.1n^{0.01}\}$. First, we show that $|I| \leq 20$. By Lemmas 4.12 and 4.13 for every $i \in I$, there exists j , $60 \leq j \leq 68$ such that Base_i starts at height h_j . From this, we draw two conclusions. First, by the definitions of B^* and the Base_i we have $u(x) < n^{1.15}$ on B^* . Also for each such j , Lemma 4.13 implies there exist at most two $i \in I$ with Base_i starting at height h_j , at most one with $i \geq 0$ and at most one with $i \leq 0$. These two facts combine to establish (35) which completes the proof. \square

REMARK 4. If we perform the analysis in the previous lemma to nonempty intervals Base_i that start at $h_j \geq n^{1.4}$, we get that $|\text{Base}_i| \geq 0.1n^{0.4}$. This implies

$$\tau \geq 0.1n^{0.4}h_{j+1} = 0.1n^{0.3}h_{j-1}.$$

LEMMA 4.15. *If $B_j \neq \emptyset$ and \mathcal{E} occurs, then*

$$\frac{\tau^{0.49}}{(h_{j-1})^{0.5}} \geq n^{0.1}.$$

PROOF. If $h_j \leq n^{1.35}$, then the result follows from the first part of Lemma 4.11. If $h_j \geq n^{1.4}$, then it follows from the previous remark. \square

4.11. *Consequences of regular returns.* Recall the sequence h_i defined in Section 4.9.

LEMMA 4.16. *For every $j \in \{1, \dots, 68\}$, the set B_j satisfies*

$$\sum_{x \in B_j} u(x) \leq |B_j|h_{j-1}.$$

Conditional on $\mathcal{E} \cap \mathcal{B}_3^c$ for every $j \in \{0, \dots, 67\}$ the set B_j satisfies

$$\sum_{x \in B_j} \text{Returns}(x) \geq 0.01|B_j|(h_{j+1})^{1/2}.$$

PROOF. From the choice of the intervals Base_j and B_i , we have that

$$h_{i+1} \leq u(x) \leq h_{i-1},$$

for all $x \in B_i$. Also, by definition, B_i consists of a union of intervals of width at least $0.1n^{0.01}$ [cf. equation (34)]. Therefore, the second statement follows from the definition of \mathcal{B}_3^c . \square

LEMMA 4.17. *For all sufficiently large n conditional on $\mathcal{E} \cap \mathcal{B}_3^c$, we have*

$$\frac{1}{2}\text{Returns} > 20\tau^{0.51}.$$

PROOF. As \mathcal{E} occurs, by Lemma 4.14 we obtain that there exists a j such that

$$\sum_{x \in B_j} u(x) \geq 0.01\tau.$$

First, consider the case that $j \in \{1, \dots, 67\}$. In this case, from Lemma 4.16 it follows that

$$(36) \quad |B_j|h_{j-1} \geq \sum_{x \in B_j} u(x) > 0.01\tau.$$

Conditional on the event \mathcal{B}_3^c , the set B_j satisfies $\sum_{x \in B_j} \text{Returns}(x) \geq 0.01|B_j|(h_{j+1})^{1/2}$, which implies

$$\begin{aligned} \sum_{x \in B_j} \text{Returns}(x) &\geq 0.01|B_j|(h_{j+1})^{1/2} \\ &\stackrel{(36)}{\geq} 0.01\left(\frac{0.01\tau}{h_{j-1}}\right)(h_{j+1})^{1/2} \\ &= 0.0001\left(\frac{h_{j+1}}{h_{j-1}}\right)^{1/2} \frac{\tau^{0.49}}{(h_{j-1})^{0.5}} \tau^{0.51} \\ &\geq 0.0001n^{-0.05}n^{0.1}\tau^{0.51} \\ &\geq 40\tau^{0.51}. \end{aligned}$$

The next to last line follows from Lemma 4.15, together with the definition of h_{j+1} and h_{j-1} , whereas the last inequality holds whenever n is sufficiently large.

Now consider $j = 68$. In this case, by Lemma 4.11 we have $\tau > n^{5/3}$ so $\tau^{0.49} > n^{0.8}$ and

$$\sum_{x \in B_{68}} \text{Returns}(x) \geq |B_{68}| \geq \frac{0.01\tau}{n^{0.7}} = \frac{0.01\tau^{0.51}\tau^{0.49}}{n^{0.7}} \geq 40\tau^{0.51},$$

which completes the proof. \square

PROOF OF LEMMA 4.3. The proof is an easy consequence of Lemmas 4.11 and 4.17. \square

5. Proofs of Theorem 1.1 (lower bound) and Theorem 1.2. The goal of this section is to prove part ii of Theorem 1.1. Theorem 1.2 will follow. The proof begins by using the upper bound (part i) of Theorem 1.1 to deduce a lower bound on the gradient of the odometer: Namely, there exists a constant ϵ such that, with high probability, for $x \in [0, \epsilon n^{1/3}]$ we have

$$u(x) - u(x + 1) \geq n/4.$$

This in turn implies the lower bound (part ii) of Theorem 1.1: since $u(\epsilon n^{1/3}) \geq 0$, we have $u(x) \geq \frac{1}{8}\epsilon n^{4/3}$ for all $x \in [0, \frac{1}{2}\epsilon n^{4/3}]$.

5.1. *Maximum of lazy random walk.* We collect here a few standard results about the running maximum of R_i , the lazy simple symmetric random walk on \mathbb{Z} whose increments $R_{i+1} - R_i$ are ± 1 with probability $\frac{1}{4}$ each and 0 with probability $\frac{1}{2}$. Let

$$(37) \quad M(t) = \sup_{i < t} |R_i|.$$

LEMMA 5.1.

(i) Given $\epsilon > 0$, for all large $t > 0$,

$$\mathbb{P}(M(t) > t^{1/2+\epsilon}) < e^{-t^{\epsilon/2}}.$$

(ii) Given $\epsilon > 0$, for all large $t > 0$,

$$(38) \quad \mathbb{P}(M(t^{2+\epsilon}) < 2t) < e^{-t^{\epsilon/2}}.$$

(iii) $\mathbb{E}(M(t)) = \Theta(\sqrt{t})$.

(iv) $\mathbb{E}(M(t)^2) = \Theta(t)$.

(v) $\lim_{t \rightarrow \infty} t^{-1/2} \mathbb{E}|R_t| = \sqrt{\frac{1}{\pi}}$.

PROOF. The proofs of parts (i)–(iv) are standard. We refer the reader to Sections 21 and 23 in Spitzer (1976). By the central limit theorem, $t^{-1/2}R_t \xrightarrow{d} Z$ where $Z \sim N(0, \frac{1}{2})$, hence $\mathbb{E}|Z| = \sqrt{1/\pi}$. Part (v) follows since the random variables $t^{-1/2}R_t$ are uniformly integrable; see, for instance, Theorem 3.5 of Billingsley (1999). \square

LEMMA 5.2. *Let*

$$\{M^i(n^{\frac{4}{3}})\}_{i=1}^{n^{1/3}}$$

be a sequence of i.i.d. random variables with the same law as $M(n^{\frac{4}{3}})$. Then there exist positive constants D, γ such that

$$\mathbb{P}\left(\sum_{i=1}^{n^{1/3}} M^i(n^{\frac{4}{3}}) < Dn\right) > 1 - e^{-n^\gamma}.$$

Proof of Lemma 5.2 is deferred to the Appendix.

5.2. *Lower bound on the gradient of the odometer.* For $x \in \mathbb{Z}$ and a positive integer i , we define the variable

$$(39) \quad D^x(i) = \mathbf{1}_{(X_i^x=1)} - \mathbf{1}_{(Y_i^x=1)},$$

where the variables X_i^x, Y_i^x appear in (6) in Section 2. Clearly,

$$D^x(i) = \begin{cases} -1, & \text{w.p. } 1/4, \\ 0, & \text{w.p. } 1/2, \\ 1, & \text{w.p. } 1/4. \end{cases}$$

Let C be the constant appearing in the upper bound (part i) of Theorem 1.1. For $x \in \mathbb{Z}$, let

$$(40) \quad S_x = \sup_{i \leq Cn^{4/3}} \left| \sum_{j=0}^i D^x(j) \right|,$$

$$(41) \quad T_x = \sup_{i \leq Cn^{4/3}} \left| \sum_{j=0}^i \frac{X_j^x}{2} \right| + \sup_{i \leq Cn^{4/3}} \left| \sum_{j=0}^i \frac{Y_j^x}{2} \right|.$$

Recall from (14) that $g_\tau(x)$ is the signed count of particles at x at the end of the oil and water process. Since one side of the origin has at least $n/2$ particles at the end of the process, without loss of generality we assume that

$$(42) \quad \sum_{x=0}^\infty |g_\tau(x)| \geq n/2.$$

Next, we claim that for any $x \in \mathbb{Z}$,

$$(43) \quad g_\tau(x) = \sum_{i=1}^{u(x-1)} D^{x-1}(i) - \sum_{i=1}^{u(x+1)} D^{x+1}(i),$$

where $D^x(\cdot)$ is defined in (39). To see this, note that the right-hand side is the difference between the number of oil particles sent to x and the number of water particles sent to x , whereas the emission of an oil-water pair from x does not change the signed count of particles at x .

Recall \mathcal{G} defined in (17). Also given $\epsilon > 0$ define the following events:

$$(44) \quad \mathcal{G}_1 = \left\{ \sum_{x=-\epsilon n^{1/3}}^{\epsilon n^{1/3}} S_x \leq \frac{n}{12} \right\},$$

$$(45) \quad \mathcal{G}_2 = \left\{ \sum_{x=-\epsilon n^{1/3}}^{\epsilon n^{1/3}} T_x \leq \frac{n}{12} \right\},$$

where S_x and T_x are defined in (40) and (41). We suppress the dependence on ϵ, n in the notation for brevity.

LEMMA 5.3. *For small enough ϵ , there exists $c > 0$ such that*

$$(46) \quad \mathbb{P}(\mathcal{G} \cap \mathcal{G}_1 \cap \mathcal{G}_2) \geq 1 - e^{-n^c}.$$

PROOF. The proof follows from (26) and Lemma 5.2. \square

We now state the following lemma establishing a lower bound on the gradient of the odometer function.

LEMMA 5.4. *Assume (42). There exists a constant $\epsilon > 0$ such that*

$$u(j) - u(j + 1) \geq \frac{n}{4}$$

for all $0 \leq j \leq \epsilon n^{1/3}$, with failure probability at most e^{-n^c} for some positive constant c .

PROOF. Recalling Definition 6 notice that

$$u(j) + \Delta^j(u(j)) - u(j + 1) + \Delta^{j+1}(u(j + 1)) = \sum_{y=j+1}^{\infty} |g_\tau(y)|.$$

We claim that for any $x \in \mathbb{Z}$,

$$|\Delta^x(u(x))| \mathbf{1}(\mathcal{G}) \leq T_x,$$

where T_x is defined in (41). This follows from definitions and the observation that

$$\begin{aligned} \Delta^x(u(x)) &= \sum_{i=1}^{u(x)} [\mathbf{1}(X_i^x = 1) - 1/2] + \sum_{i=1}^{u(x)} [\mathbf{1}(Y_i^x = 1) - 1/2] \\ &= \sum_{i=1}^{u(x)} \frac{X_i^x}{2} + \sum_{i=1}^{u(x)} \frac{Y_i^x}{2}. \end{aligned}$$

Thus, we have

$$(47) \quad [u(j) - u(j + 1)]\mathbf{1}(\mathcal{G}) \geq \sum_{y=j+1}^{\infty} |g_{\tau}(y)|\mathbf{1}(\mathcal{G}) - (T_j + T_{j+1})\mathbf{1}(\mathcal{G}).$$

Now on the event $\mathcal{G} \cap \mathcal{G}_1 \cap \mathcal{G}_2, \forall j < \epsilon n^{1/3}$,

$$(48) \quad \sum_{i=j}^{\infty} |g_{\tau}(i)| \geq n/3.$$

To show this, we upper bound $\sum_{i=1}^j |g_{\tau}(i)|$. By (43), on the event \mathcal{G} we have for all $0 < i \leq \epsilon n^{1/3}$,

$$(49) \quad |g_{\tau}(i)| \leq S_{i-1} + S_{i+1},$$

where S_i is defined in (40). Hence, on the event $\mathcal{G} \cap \mathcal{G}_1 \cap \mathcal{G}_2$,

$$\sum_{i=0}^j |g_{\tau}(i)| \leq 2 \sum_{i=-1}^{\epsilon n^{1/3}} S_i \leq \frac{n}{6}.$$

Thus, by (42) we have for all $0 < j < \epsilon n^{1/3}$,

$$\sum_{i=j}^{\infty} |g_{\tau}(i)| \geq \frac{n}{2} - \sum_{i=0}^j |g_{\tau}(i)| \geq \frac{n}{3}.$$

Therefore, by (47) and (48), on the event $\mathcal{G} \cap \mathcal{G}_1 \cap \mathcal{G}_2$ we have for all $0 \leq j < \epsilon n^{1/3}$

$$u(j) - u(j + 1) \geq \frac{n}{3} - \sum_{x=1}^k T_x \geq \frac{n}{4}. \quad \square$$

5.3. *Lower bound on the odometer.* The proof of the lower bound in Theorem 1.1 follows readily.

PROOF OF THEOREM 1.1(II). Since $u \geq 0$, Lemma 5.4 implies that for all large enough n and $j \leq \frac{1}{2}\epsilon n^{1/3}$, we have

$$u(j) \geq \frac{1}{8}\epsilon n^{4/3}.$$

Hence, by (46) it follows

$$(50) \quad \mathbb{P}\left(\inf_{0 \leq j \leq \frac{1}{2}\epsilon n^{1/3}} u(j) \leq \frac{1}{8}\epsilon n^{4/3}\right) \leq e^{-n^c}.$$

To complete the proof, we use the symmetric version of (47) to get the following bound: For $j \leq 0$,

$$u(j) - u(j - 1) - \Delta^j(u(j)) - \Delta^{j-1}(u(j - 1)) = \sum_{y=-\infty}^{j-1} |g_\tau(y)|.$$

The following bound

$$\sum_{y=-\infty}^i |g_\tau(y)| \leq 2n$$

is trivial since the total number of particles is $2n$. Using the above and the definition of \mathcal{G}_2 , we get for all $-\epsilon n^{1/3} < j < 0$

$$u(0) - u(j) \leq j\left(2n + \frac{n}{6}\right).$$

Thus, $u(0) \geq \frac{1}{4}\epsilon n^{4/3}$ implies that for all $j \leq \frac{1}{16}\epsilon n^{1/3}$

$$u(-j) \geq \frac{1}{12}\epsilon n^{4/3},$$

which together with (50) completes the proof. \square

5.4. *Upper bound on the number of accumulated particles.* The next lemma will be used in the proof of Theorem 1.2.

LEMMA 5.5. *There exists a constant $C > 0$ such that*

$$(51) \quad \sup_{x \in \mathbb{Z}} \mathbb{E}(|g_\tau(x)|) < Cn^{\frac{2}{3}}.$$

Moreover, for any $\epsilon > 0$ there exists $c > 0$

$$(52) \quad \mathbb{P}\left[\sup_{x \in \mathbb{Z}} |g_\tau(x)| \geq n^{\frac{2}{3} + \epsilon}\right] \leq e^{-n^c}.$$

PROOF. For any $x \in \mathbb{Z}$, we have

$$(53) \quad |g_\tau(x)| \leq [S_{x-1} + S_{x+1}]\mathbf{1}(\mathcal{G}) + 2n\mathbf{1}(\mathcal{G}^c),$$

where the event \mathcal{G} is defined in (17). The first term follows from (49) and the second term is obvious since the total number of particles is $2n$. The proof of (51) now

follows from (iii) of Lemma 5.1 and (26). Additionally, using (i) of Lemma 5.1 we get that for any $x \in \mathbb{Z}$ there exists $c > 0$ such that

$$(54) \quad \mathbb{P}(|g_\tau(x)| \geq n^{\frac{2}{3}+\epsilon}) \leq e^{-n^c}.$$

Corollary 3.2 says that with probability at least $1 - e^{-n^c}$ for all $|x| \geq n^5$

$$|g_\tau(x)| = 0,$$

and (52) now follows from (54) by union bound over all $x \in [-n^5, n^5]$. \square

REMARK 5. For small enough ϵ and $k = \epsilon n^{1/3}$, by (46) and (53)

$$\mathbb{P}\left[\sum_{i=-k}^k |g_\tau(i)| \leq n\right] \geq 1 - e^{-n^c}$$

for some positive constant c . Thus, at least n particles are supported outside the interval $[-\epsilon n^{1/3}, \epsilon n^{1/3}]$ with probability at least $1 - e^{-n^c}$.

5.5. *Proof of Theorem 1.2.* Let $x = n^{1/3+\epsilon}$. Under the assumption that there are at least $n^{1-\epsilon/2}$ many particles to the right of x , for all $\ell \leq x$,

$$\sum_{i=\ell}^\infty |g_\tau(i)| \geq n^{1-\epsilon/2}.$$

Recalling (47), we have

$$(u(0) - u(x))\mathbf{1}(\mathcal{G}) \geq \sum_{i=1}^x \sum_{y=i}^\infty |g_\tau(y)|\mathbf{1}(\mathcal{G}) - 2 \sum_{i=0}^x T_i \mathbf{1}(\mathcal{G}).$$

Now by part (i) of Lemma 5.1 and union bound over $1 \leq \ell \leq x$ there exists a $c > 0$ such that with probability at least $1 - e^{-n^c}$,

$$\sum_{\ell=1}^x T_\ell = O(n^{1+2\epsilon}).$$

Thus, on the event that there are at least $n^{1-\epsilon/2}$ many particles to the right of x we have

$$u(0) - u(x) \geq x n^{1-\epsilon/2} - O(n^{1+\epsilon}),$$

except on a set of measure at most e^{-n^c} . However, this implies that

$$u(0) \geq n^{4/3+\epsilon/2} - O(n^{1+\epsilon}).$$

Hence, by the upper bound in Theorem 1.1 we conclude that the probability of the event that there are at least $n^{1-\epsilon/2}$ many particles to the right of $x = n^{1/3+\epsilon}$ is less than e^{-n^c} for some positive $c > 0$. The argument for $x = -n^{1/3+\epsilon}$ is symmetric.

6. Scaling limit for the odometer. The goal of this section is to prove Theorem 1.4. The first step will be to show that Conjecture 1.3 implies some regularity of the limiting function: we will argue that $w(\cdot)$ is decreasing and three times differentiable on the positive real axis. Moreover, it is the solution of the boundary value problem:

$$w'' = \sqrt{\frac{2}{\pi}} w,$$

$$\lim_{h \rightarrow 0^+} \frac{w(h) - w(0)}{h} = -1,$$

$$\lim_{h \rightarrow \infty} w(h) = 0.$$

At this point, Theorem 1.4 follows by identifying an explicit solution to the above problem and arguing that it is the unique solution.

6.1. *Properties of the expected odometer.* We first make some easy observations about the expected odometer function, denoted by

$$\tilde{u}(x) := \mathbb{E}(u(x)).$$

Existence of $\tilde{u}(x)$ follows from (ii) of Proposition 3.1 which says that the stopping time of the process τ has finite expectation, and clearly for all $x \in \mathbb{Z}$

$$u(x) \leq \tau.$$

We first make the following easy observation.

LEMMA 6.1. *For $x \in \mathbb{Z}$, we have*

$$\tilde{u}(x) - \tilde{u}(x + 1) = \mathbb{E}[\#\{\text{particles moving from } x \text{ to } x + 1\}] \leq n \quad \text{for } x \geq 0,$$

$$\tilde{u}(x) - \tilde{u}(x - 1) = \mathbb{E}[\#\{\text{particles moving from } x \text{ to } x - 1\}] \leq n \quad \text{for } x \leq 0.$$

Clearly, every time there is an emission at a site $x \in \mathbb{Z}$, on average one particle moves to $x - 1$ and another to $x + 1$. Also by symmetry, the number of particles to the right of any positive x is on an average at most n . It is straightforward to make this formal and we omit the details. Similar arguments yield the following as well, whose proof we omit, too.

LEMMA 6.2. *$\tilde{u}(x)$ satisfies the following properties:*

- (i) $\tilde{u}(x)$ is an even function,
- (ii) restricted to \mathbb{Z}_+ , $\tilde{u}(x)$ is strictly decreasing,

(iii) for every $x \neq 0$,

$$\Delta \tilde{u}(x) = \mathbb{E} \left(\sum_{y=x}^{\infty} |g_{\tau}(y)| - \sum_{y=x+1}^{\infty} |g_{\tau}(y)| \right) = \mathbb{E}(|g_{\tau}(x)|) > 0,$$

where Δ is the discrete Laplacian, that is,

$$(55) \quad \Delta \tilde{u}(x) = \tilde{u}(x - 1) + \tilde{u}(x + 1) - 2\tilde{u}(x).$$

6.2. *The differential equation $w'' = \sqrt{2w/\pi}$.* In this section, we work toward the proof of Theorem 1.4. We recall Conjecture 1.3 stated in the Introduction. Note that we have not assumed a priori that w is continuous. Proving this is our first order of business.

LEMMA 6.3. *w is continuous, (in fact, 1-Lipschitz) on \mathbb{R} . Moreover, it is non-increasing on the positive real axis.*

PROOF. (i) of Lemma 6.2 implies that w is an even function. Hence, it suffices to prove that w is 1-Lipschitz on $[0, \infty)$. By Lemma 6.1, for any $x, k \in \mathbb{Z}_{\geq 0}$ we have

$$0 \leq \tilde{u}(x) - \tilde{u}(x + k) = \sum_{j=0}^{k-1} [\tilde{u}(x + j) - \tilde{u}(x + j + 1)] \leq kn.$$

Now let $x = \lfloor n^{1/3} \xi \rfloor$ and $k = \lfloor n^{1/3}(\xi + h) \rfloor - \lfloor n^{1/3} \xi \rfloor$. Dividing by $n^{4/3}$ and taking $n \rightarrow \infty$, we obtain

$$0 \leq w(\xi) - w(\xi + h) \leq h$$

thus completing the proof of the lemma. \square

Recall the set of random variables

$$X_i^x, Y_i^x$$

defined in (6). To go further, we define the following quantities: For $y = x \pm 1$,

$$O_{x,y}^k := \sum_{i=0}^k \mathbf{1}(X_i^x = \pm 1),$$

$$W_{x,y}^k := \sum_{i=0}^k \mathbf{1}(Y_i^x = \pm 1).$$

In other words,

$$O_{x,y}^k := \#\{\text{oil particles sent from } x \text{ to } y \text{ within the first } k \text{ firings at } x\},$$

$$W_{x,y}^k := \#\{\text{water particles sent from } x \text{ to } y \text{ within the first } k \text{ firings at } x\}.$$

To relate these sums to our earlier notation, recalling Definition 6 we have $O_{x,x+1}^k + W_{x,x+1}^k = k + \Delta^x(k)$, and the signed count of particles remaining at x is given by

$$(56) \quad g_\tau(x) = O_{x-1,x}^{u(x-1)} + O_{x+1,x}^{u(x+1)} - W_{x-1,x}^{u(x-1)} - W_{x+1,x}^{u(x+1)},$$

where $g_\tau(\cdot)$ was defined in (14).

Consider now the analogous expression using a deterministic portion of each stack [recall $\tilde{u}(x) = \mathbb{E}u(x)$]:

$$(57) \quad \tilde{g}_\tau(x) := O_{x-1,x}^{\lfloor \tilde{u}(x-1) \rfloor} + O_{x+1,x}^{\lfloor \tilde{u}(x+1) \rfloor} - W_{x-1,x}^{\lfloor \tilde{u}(x-1) \rfloor} - W_{x+1,x}^{\lfloor \tilde{u}(x+1) \rfloor}.$$

Because \tilde{u} is deterministic the four terms on the right-hand side are independent. Moreover, each term $O_{x,y}^k$ and $W_{x,y}^k$ for $|x - y| = 1$ is a sum of k independent Bernoulli(1/2) random variables. So the right-hand side is a sum of $\lfloor \tilde{u}(x - 1) \rfloor + \lfloor \tilde{u}(x + 1) \rfloor$ independent random variables with the same law as a single step of a lazy symmetric random walk as defined in (39). Setting $x = \lfloor n^{1/3} \xi \rfloor$ for a real number $\xi > 0$, by (ii) in Conjecture 1.3 we have

$$\lim_{n \rightarrow \infty} \frac{\lfloor \tilde{u}(x - 1) \rfloor + \lfloor \tilde{u}(x + 1) \rfloor}{n^{4/3}} = \lim_{n \rightarrow \infty} \frac{2\tilde{u}(x)}{n^{4/3}} = 2w(\xi).$$

This is because by Lemma 6.1, $|\tilde{u}(x) - \tilde{u}(x + 1)|$ and $|\tilde{u}(x - 1) - \tilde{u}(x)|$ are both less than n . As $n \rightarrow \infty$ by the central limit theorem, since each variable in (39) has variance 1/2, we obtain

$$(58) \quad n^{-2/3} \tilde{g}_\tau(x) \xrightarrow{d} N(0, w(\xi)).$$

By Lemma 5.1(v), we also have

$$(59) \quad n^{-2/3} \mathbb{E}|\tilde{g}_\tau(x)| \longrightarrow \sqrt{\frac{2}{\pi} w(\xi)}.$$

Next, we observe that under (i) in Conjecture 1.3, the same kind of central limit theorem holds for g_τ itself.

LEMMA 6.4. *Let $\xi \geq 0$. For $x = \lfloor n^{1/3} \xi \rfloor$, we have as $n \rightarrow \infty$*

(i)

$$n^{-2/3} g_\tau(x) \xrightarrow{d} N(0, w(\xi))$$

(ii)

$$n^{-2/3} \mathbb{E}|g_\tau(x)| \longrightarrow \sqrt{\frac{2}{\pi} w(\xi)}.$$

REMARK 6. (ii) along with (55) implies

$$(60) \quad \lim_{n \rightarrow \infty} \frac{\Delta \tilde{u}(x)}{n^{2/3}} \rightarrow \sqrt{\frac{2}{\pi} w(\xi)}.$$

To prove Lemma 6.4, we need the next two results.

LEMMA 6.5. $\mathbb{E}[\tau \mathbf{1}(\tau > n^5)] = O(1)$ where τ is defined in (10).

COROLLARY 6.6. *There exists a constant $C_1 > 0$ such that*

$$\sup_{x \in \mathbb{Z}} \tilde{u}(x) \leq C_1 n^{4/3},$$

where $\tilde{u} = \mathbb{E}(u)$.

The proofs of the above two results are deferred to the [Appendix](#).

6.2.1. *Proof of Lemma 6.4.* By (58) and (59), it suffices to show

$$(61) \quad \lim_{n \rightarrow 0} n^{-2/3} \mathbb{E}|g_\tau(x) - \tilde{g}_\tau(x)| = 0.$$

Referring to the definitions of g and \tilde{g} in (56) and (57), respectively, this will be accomplished if we show that as $n \rightarrow \infty$ for $y = x \pm 1$:

$$n^{-2/3} \mathbb{E} |(O_{y,x}^{\lfloor \tilde{u}(y) \rfloor} - W_{y,x}^{\lfloor \tilde{u}(y) \rfloor}) - (O_{y,x}^{u(y)} - W_{y,x}^{u(y)})|$$

tend to 0. For $y = x \pm 1$, the above differences have identical distributions. Hence, it suffices to look at any one. The quantity $(O_{y,x}^{\tilde{u}(y)} - W_{y,x}^{\tilde{u}(y)}) - (O_{y,x}^{u(y)} - W_{y,x}^{u(y)})$ is a sum of

$$N = |[\tilde{u}(y)] - u(y)|$$

independent random variables X_1, \dots, X_N with the same law as in (39). By Conjecture 1.3(i), $N/n^{4/3} \rightarrow 0$ in distribution. Fix $\epsilon \geq 0$. Let

- $A_1 = \mathbf{1}(N \leq \epsilon n^{4/3}) \sup_{1 \leq m \leq \epsilon n^{4/3}} |\sum_{i=1}^m X_i|$,
- $A_2 = \mathbf{1}(N \geq \epsilon n^{4/3}) \mathbf{1}(\mathcal{G}) \sup_{1 \leq m \leq (C+C_1)n^{4/3}} |\sum_{i=1}^m X_i|$,
- $A_3 = 2n^5 \mathbf{1}(\mathcal{G}^c) \mathbf{1}(\tau \leq n^5)$,
- $A_4 = 2\tau \mathbf{1}(\mathcal{G}^c) \mathbf{1}(\tau > n^5)$,

where C and C_1 are the constants appearing in the statement of Theorem 1.1 and Corollary 6.6, respectively, τ is defined in (10) and \mathcal{G} is defined in (17). We now claim that

$$(62) \quad |(O_{y,x}^{\lfloor \tilde{u}(y) \rfloor} - W_{y,x}^{\lfloor \tilde{u}(y) \rfloor}) - (O_{y,x}^{u(y)} - W_{y,x}^{u(y)})| \leq A_1 + A_2 + A_3 + A_4.$$

The first two terms correspond to the cases:

- $N \leq \epsilon n^{4/3}$,
- $\{N \geq \epsilon n^{4/3}\} \cap \mathcal{G}$.

For the last two terms, we use the naive bound that

$$(63) \quad \left| \sum_{i=1}^N X_i \right| \leq N \leq \sup_{x \in \mathbb{Z}} \tilde{u}(x) + \sup_{x \in \mathbb{Z}} u(x) \leq C_1 n^{4/3} + \tau,$$

where the last inequality uses Corollary 6.6. Using the above bound and looking at the events $\{\tau \leq n^5\} \cap \mathcal{G}^c$ and $\{\tau > n^5\} \cap \mathcal{G}^c$ gives us (62).

- By Lemma 5.1(iii), $\mathbb{E}(A_1) = O(\sqrt{\epsilon} n^{2/3})$.
- By the Cauchy–Schwarz inequality and Lemma 5.1(iv)

$$\mathbb{E}(A_2) = O(n^{2/3}) \sqrt{\mathbb{P}(N \geq \epsilon n^{4/3})}.$$

- $\mathbb{E}(A_3 + A_4) = O(1)$ by Theorem 1.1 and Lemma 6.5, respectively.

Thus, for any $\epsilon > 0$

$$\mathbb{E}|g_\tau(x) - \tilde{g}_\tau(x)| \leq \sum_{i=1}^4 \mathbb{E}(A_i) = n^{2/3} (O(\sqrt{\epsilon} + \sqrt{\mathbb{P}(N \geq \epsilon n^{4/3})}).$$

Hence, (61) follows using the above and Conjecture 1.3(i) ($N/n^{4/3}$ goes to 0 in distribution) and we are done.

REMARK 7. Note that we actually prove (61) uniformly over x , that is,

$$\lim_{n \rightarrow 0} \sup_{x \in \mathbb{Z}} n^{-2/3} \mathbb{E}|g_\tau(x) - \tilde{g}_\tau(x)| = 0.$$

We now prove an uniform version of (60).

LEMMA 6.7. Given $\epsilon > 0$ and $x < y$ such that $w(x), w(y) > 0$, for large enough n ,

$$\sup_{\lfloor xn^{1/3} \rfloor \leq j \leq \lfloor yn^{1/3} \rfloor} \left| \frac{\Delta \tilde{u}(j)}{n^{2/3}} - \sqrt{\frac{2}{\pi}} w\left(\frac{j}{n^{1/3}}\right) \right| \leq \epsilon.$$

PROOF. Since w is continuous by Lemma 6.3, and hence uniformly continuous on $[x, y]$, for $\epsilon > 0$ there exists real numbers:

$$x = x_0 < x_1 < \dots < x_k = y$$

such that

$$\sup_{1 \leq i \leq k} (x_i - x_{i-1}) \leq \epsilon,$$

$$\sup_{1 \leq i \leq k} (w(x_{i-1}) - w(x_i)) \leq \epsilon.$$

By Conjecture 1.3(ii) and (60), we have for large enough n :

$$(64) \quad \sup_{1 \leq i \leq k} \left| \frac{\tilde{u}(\lfloor n^{1/3} x_i \rfloor)}{n^{4/3}} - w(x_i) \right| \leq \epsilon,$$

$$(65) \quad \sup_{1 \leq i \leq k} \left| \frac{\Delta \tilde{u}(\lfloor n^{1/3} x_i \rfloor)}{n^{2/3}} - \sqrt{\frac{2}{\pi} w(x_i)} \right| \leq \epsilon.$$

Now for any $\lfloor x n^{1/3} \rfloor \leq j \leq \lfloor y n^{1/3} \rfloor$ find $0 \leq i < k$ such that

$$\lfloor x_i n^{1/3} \rfloor \leq j \leq \lfloor x_{i+1} n^{1/3} \rfloor.$$

Clearly, it suffices to show

$$|\Delta \tilde{u}(j) - \Delta \tilde{u}(\lfloor x_i n^{1/3} \rfloor)| = O(\sqrt{\epsilon} n^{2/3})$$

or by (55)

$$|\mathbb{E}|g_\tau(j)| - \mathbb{E}|g_\tau(\lfloor x_i n^{1/3} \rfloor)|| = O(\sqrt{\epsilon} n^{2/3}).$$

Notice that by (61) and Remark 7 we have

$$(66) \quad |\mathbb{E}|g_\tau(j)| - \mathbb{E}|\tilde{g}_\tau(j)|| = o(n^{2/3}),$$

$$(67) \quad |\mathbb{E}|g_\tau(\lfloor n^{1/3} x_i \rfloor)| - \mathbb{E}|\tilde{g}_\tau(\lfloor n^{1/3} x_i \rfloor)|| = o(n^{2/3}).$$

Hence, it suffices to show

$$(68) \quad |\mathbb{E}|\tilde{g}_\tau(j)| - \mathbb{E}|\tilde{g}_\tau(\lfloor n^{1/3} x_i \rfloor)|| = O(\sqrt{\epsilon} n^{2/3}),$$

$$(69) \quad |\mathbb{E}|\tilde{g}_\tau(\lfloor n^{1/3} x_{i+1} \rfloor)| - \mathbb{E}|\tilde{g}_\tau(j)|| = O(\sqrt{\epsilon} n^{2/3}).$$

By (64)

$$\begin{aligned} \tilde{u}(j) - \tilde{u}(\lfloor n^{1/3} x_i \rfloor) &\leq \epsilon n^{4/3}, \\ \tilde{u}(\lfloor n^{1/3} x_{i+1} \rfloor) - \tilde{u}(j) &\leq \epsilon n^{4/3}. \end{aligned}$$

Now by (57) the quantities on the left-hand side of (68) and (69) are absolute values of a lazy symmetric random walk run for time $\tilde{u}(j) - \tilde{u}(\lfloor n^{1/3} x_i \rfloor)$ and $\tilde{u}(\lfloor n^{1/3} x_{i+1} \rfloor) - \tilde{u}(j)$, respectively. The result now follows from Lemma 5.1(v). □

COROLLARY 6.8.

$$\int_0^\infty \sqrt{\frac{2}{\pi} w(\zeta)} d\zeta \leq 1,$$

which in particular implies

$$\lim_{x \rightarrow \infty} w(x) = 0.$$

PROOF. By Lemma 6.1,

$$(70) \quad \mathbb{E} \left(\sum_{y=1}^{\infty} |g_{\tau}(y)| \right) = \sum_{y=1}^{\infty} \Delta \tilde{u}(y) = \tilde{u}(0) - \tilde{u}(1) \leq n.$$

Thus, for any positive number A

$$\sum_{y=1}^{\lfloor An^{1/3} \rfloor} \Delta \tilde{u}(y) \leq n.$$

By Lemma 6.7 and the approximation of an integral by Riemann sum, we have

$$1 \geq \lim_{n \rightarrow \infty} \sum_{y=1}^{An^{1/3}} \frac{1}{n^{1/3}} \frac{\Delta \tilde{u}(y)}{n^{2/3}} = \int_0^A \sqrt{\frac{2}{\pi}} w(\zeta) d\zeta.$$

Since w is nonnegative, it follows that

$$\int_0^{\infty} \sqrt{\frac{2}{\pi}} w(\zeta) d\zeta \leq 1.$$

By Lemma 6.3 w is nonincreasing, hence this implies that

$$\lim_{x \rightarrow \infty} w(x) = 0. \quad \square$$

REMARK 8. Note that we assumed only convergence of \tilde{u} in Conjecture 1.3(ii) but were able to use a special feature of the oil and water model [namely, the identity $\Delta \tilde{u}(x) = \mathbb{E}|g_{\tau}(x)|$] to obtain something stronger, convergence of the discrete Laplacian $\Delta \tilde{u}$.

Next, we use this to argue that the scaling limit $w(\xi)$ is actually a twice differentiable function of $\xi > 0$.

For any $\epsilon > 0$ by Conjecture 1.3(i) and the above corollary, we can choose L large enough so that for large enough n ,

$$\sup_{|\xi| \geq L} \tilde{u}(\lfloor n^{1/3} \xi \rfloor) < \epsilon^2 n^{4/3}$$

for all $|\xi| > L$.

LEMMA 6.9. *Given $\epsilon > 0$, let L be as chosen above. Then*

$$\sum_{|x| > n^{1/3} L} \Delta \tilde{u}(x) \leq \epsilon^{1/2} n.$$

PROOF. Since the $n^{1/3}\varepsilon$ differences $\tilde{u}(x) - \tilde{u}(x + 1)$ for $x = \lfloor n^{1/3}L \rfloor, \dots, \lfloor n^{1/3}(L + \varepsilon) \rfloor - 1$ are nonnegative and sum to at most $\tilde{u}(\lfloor n^{1/3}L \rfloor) \leq \varepsilon^2 n^{4/3}$, the smallest of them (which is the last one) must be at most εn . Therefore,

$$\sum_{|x| > n^{1/3}(L + \varepsilon)} \Delta \tilde{u}(x) \leq \varepsilon n.$$

Now the fact that

$$\sum_{x = \lfloor n^{1/3}L \rfloor}^{\lfloor n^{1/3}(L + \varepsilon) \rfloor} \Delta \tilde{u}(x) \leq O(\varepsilon)n$$

follows from Lemma 5.5 and the fact that $\Delta \tilde{u}(x) = \mathbb{E}|g_\tau(x)|$ [see (55)]. Combining the above two results the proof follows. \square

LEMMA 6.10. *w is differentiable on the positive real line, and for any $\xi > 0$,*

$$(71) \quad w'(\xi) = - \int_{\xi}^{\infty} \sqrt{\frac{2}{\pi} w(\zeta)} d\zeta.$$

PROOF. By summation by parts, for positive integers x, k ,

$$(72) \quad \frac{1}{kn} [\tilde{u}(x) - \tilde{u}(x + k)] = \frac{1}{kn} \sum_{j=1}^{\infty} \min(j, k) \Delta \tilde{u}(x + j).$$

For positive real numbers ξ, L, h let $x = \lfloor \xi n^{1/3} \rfloor, Z = \lfloor Ln^{1/3} \rfloor, k = \lfloor hn^{1/3} \rfloor$ and consider the first part of the sum in (72):

$$\frac{1}{h} \sum_{j=1}^Z \frac{1}{n^{1/3}} \frac{\min(j, k)}{n^{1/3}} \frac{\Delta \tilde{u}(x + j)}{n^{2/3}}.$$

Now given $\delta > 0$, by Lemma 6.7 for large enough n :

$$\left| \frac{1}{h} \sum_{j=1}^Z \frac{1}{n^{1/3}} \frac{\min(j, k)}{n^{1/3}} \frac{\Delta \tilde{u}(x + j)}{n^{2/3}} - \frac{1}{h} \sum_{j=1}^Z \frac{1}{n^{1/3}} \min\left(\frac{j}{n^{1/3}}, h\right) \sqrt{\frac{2}{\pi} w\left(\xi + \frac{j}{n^{1/3}}\right)} \right| \leq \delta L.$$

Notice that

$$\frac{1}{h} \sum_{j=1}^Z \frac{1}{n^{1/3}} \min\left(\frac{j}{n^{1/3}}, h\right) \sqrt{\frac{2}{\pi} w\left(\xi + \frac{j}{n^{1/3}}\right)}$$

is a Riemann sum approximation of the integral

$$\frac{1}{h} \int_{\xi}^{L + \xi} \min(\zeta - \xi, h) \sqrt{\frac{2}{\pi} w(\zeta)} d\zeta.$$

Thus, as n goes to ∞ we see that

$$\frac{1}{h} \sum_{j=1}^Z \frac{1}{n^{\frac{1}{3}}} \frac{\min(j, k)}{n^{\frac{1}{3}}} \frac{\Delta \tilde{u}(x + j)}{n^{\frac{2}{3}}} \rightarrow \frac{1}{h} \int_{\xi}^{L+\xi} \min(\zeta - \xi, h) \sqrt{\frac{2}{\pi}} w(\zeta) d\zeta.$$

Fixing $\epsilon > 0$ and choosing the same L as in the statement of Lemma 6.9, we get that the sum of the remaining terms in (72) $\frac{1}{kn} \sum_{j=Z+1}^{\infty}$ is at most $\epsilon^{1/2}$ by Lemma 6.9. Hence, as $n \rightarrow \infty$ we get from (72):

$$\frac{w(\xi) - w(\xi + h)}{h} = \frac{1}{h} \int_{\xi}^L \min(\zeta - \xi, h) \sqrt{\frac{2}{\pi}} w(\zeta) d\zeta + O(\epsilon^{1/2}).$$

Sending h to 0 followed by ϵ to 0 (L to ∞), we are done. \square

The right-hand side of (71) is manifestly a differentiable function of ξ , so we obtain the following.

COROLLARY 6.11. *Under Conjecture 1.3, the function w restricted to the positive real axis is twice continuously differentiable and obeys the differential equation:*

$$(73) \quad w'' = \sqrt{\frac{2}{\pi}} w.$$

LEMMA 6.12. *w is compactly supported. Moreover, on the positive region of support,*

$$w(x) = \left(-\frac{1}{4} \left(\frac{32}{9\pi} \right)^{1/4} x + b \right)^4$$

for some $b > 0$.

Before proving the above, we quote the well known Picard existence and uniqueness result for ODEs.

THEOREM 6.13 [Kelley and Peterson (2010), Theorem 8.13]. *Consider an initial value problem (IVP):*

$$(74) \quad y'(x) = f(y(x), x),$$

$$(75) \quad y(x_0) = y_0$$

with the point (x_0, y_0) belonging to some rectangle $(a, b) \times (A, B)$, that is, $a < a_0 < b$ and $A < y_0 < B$. Also assume that f is M -Lipschitz for some $M \geq 0$, that is,

$$|f(z, x) - f(w, x)| \leq M|z - w|$$

for all $x \in (a, b)$ $z, w \in (A, B)$. Then there exists a $h = h(x_0, y_0, M) > 0$ such that:

- Existence: *There exists a solution to the IVP on the interval $(x_0 - h, x_0 + h)$.*
- Uniqueness: *Any two solutions of the IVP agree on the interval $(x_0 - h, x_0 + h)$.*

PROOF OF LEMMA 6.12. Multiplying (73) by w' on both sides, we get

$$w'w'' = \sqrt{\frac{2}{\pi}}ww'.$$

Integrating both sides from ξ to ∞ and using the fact that

$$\lim_{x \rightarrow \infty} w(x) = \lim_{x \rightarrow \infty} w'(x) = 0$$

(from Corollary 6.8 and Lemma 6.10) and that w' is nonpositive we see that $w(x)$ satisfies the first-order ODE:

$$(76) \quad f' = -\left(\frac{32}{9\pi}\right)^{1/4} f^{3/4}.$$

Now suppose w is positive on the entire real axis. Given any $z \in \mathbb{R}_+$, then $w(z)$ and $w'(z)$ are both nonzero. Thus, we can find a, b such that

$$\begin{aligned} (az + b)^4 &= w(z), \\ 4a(az + b)^3 &= w'(z). \end{aligned}$$

By (76),

$$4a = -\left(\frac{32}{9\pi}\right)^{1/4}.$$

Because of the particular choice of a and b the function $(ax + b)^4$ also satisfies (76). Now since $w(z)$ and $w'(z)$ are both nonzero the function $w^{3/4}(z)$ is Lipschitz in a neighborhood of z . Hence, by Theorem 6.13 ODE (76) has a unique solution in some neighborhood of z . Thus, the functions $w(x)$ and $(ax + b)^4$ are equal in a neighborhood of z . Now looking at the biggest interval I containing z such that $w(x) = (ax + b)^4$ on I we conclude that $w(x) = (ax + b)^4$ on $\mathbb{R}_+ \cap \text{supp}(w)$. In particular, since $(ax + b)^4$ is positive only on a compact set this implies that $w(x)$ has compact support. \square

Now we find the value for b which completely determines w .

LEMMA 6.14.

$$-4ab^3 = \lim_{h \rightarrow 0^+} \frac{w(0) - w(h)}{h} = 1.$$

In particular,

$$b = \left(\frac{9\pi}{32}\right)^{1/12}.$$

PROOF. That $-4ab^3 = \lim_{h \rightarrow 0^+} \frac{w(0) - w(h)}{h}$ follows from Lemma 6.12. To see that, the quantity equals 1 fix $h > 0$. Consider the telescopic sum:

$$\tilde{u}(0) - \tilde{u}(hn^{1/3}) = \sum_{i=0}^{hn^{1/3}} \tilde{u}(i) - \tilde{u}(i + 1).$$

Now $\tilde{u}(i) - \tilde{u}(i + 1)$ is the expected number of particles on the right of i by Lemma 6.1. By symmetry of the process about the origin and Lemma 5.5,

$$\sum_{x>0} |g_\tau(x)| = n - O(n^{2/3}).$$

Moreover, for any $i > 0$

$$\tilde{u}(i) - \tilde{u}(i + 1) = n - O(n^{2/3})i.$$

Summing over i , we get

$$\tilde{u}(0) - \tilde{u}(\lfloor hn^{1/3} \rfloor) = hn^{4/3} - h^2 O(n^{4/3}).$$

Dividing throughout by $n^{4/3}$ and taking limit as n goes to infinity, we get

$$w(0) - w(h) = h + O(h^2).$$

Thus, dividing by h and sending h to 0 we are done. \square

6.3. *Proof of Theorem 1.4.* From Lemmas 6.12 and 6.14 and using the symmetry of w about the origin, we get

$$w(x) = \left(\left(\frac{9\pi}{32} \right)^{1/12} - \left(\frac{32}{9\pi} \right)^{1/4} \frac{|x|}{4} \right)^4$$

on the region of support. Rearranging we get

$$(77) \quad w(x) = \begin{cases} \frac{1}{72\pi} ((18\pi)^{1/3} - |x|)^4, & |x| < (18\pi)^{1/3}, \\ 0, & |x| \geq (18\pi)^{1/3}. \end{cases}$$

7. Open questions. Conjecture 1.3 is an obvious target. In this concluding section, we collect some additional open questions.

7.1. *Location of the rightmost particle.* For the oil and water process with n particles of each type started at the origin \mathbb{Z} , let R_n be the location of the rightmost particle upon fixation. Is the sequence of random variables $R_n/n^{1/3}$ tight? Does it converge in distribution to a constant? If it does, then Theorem 1.4 suggests that the limit should be at least $(18\pi)^{1/3}$ (and perhaps equal to this value).

7.2. *Order of the variance.* We believe that the standard deviation of the odometer u is of order $n^{7/6}$ in the bulk. Note that Conjecture 1.3 asserts something weaker, namely $o(n^{4/3})$.

Here is a heuristic argument for the exponent $7/6$. The total number of particle exits from x is $2u(x)$; let N_x be the total number of particle *entries* to x . Equating entries minus exits with the number of particles left behind, we find that

$$(78) \quad \Delta u(x) := u(x - 1) + u(x + 1) - 2u(x) = Z(x) + |g_\tau(x)| - 2n\delta_0(x),$$

where $Z(x) = u(x - 1) + u(x + 1) - N_x$, and $g_\tau(x)$ is the signed count of particles remaining at x in the final state (counting oil as positive, water as negative). Both $Z(x)$ and $g_\tau(x)$ (without the absolute value!) are expressible as sums of independent indicators involving the stack elements at $x \pm 1$. The limits of summation are $u(x \pm 1)$. Assuming Conjecture 1.3 and arguing as in Lemma 6.4, we can replace the limits of summation by their expected values $\tilde{u}(x \pm 1)$, incurring only a small error. The resulting sums \tilde{Z} and \tilde{g}_τ are asymptotically normal with mean zero and variance of order $n^{4/3}$ [assuming x is in the bulk, $|x| < ((18\pi)^{1/3} - \varepsilon)n^{1/3}$]. Moreover, the function $\tilde{Z} + |\tilde{g}_\tau|$ is *2-dependent*: its values at x and y are independent if $|x - y| > 2$. By summation by parts,

$$u(x) = \sum_{j=1}^{\infty} j \Delta u(x + j).$$

Since most of the support of u is on an interval of length $O(n^{1/3})$, truncating this sum at $Cn^{1/3}$ for a large constant C should not change its variance by much. Replacing Δu by its approximation $\tilde{Z} + |\tilde{g}_\tau|$ and using the 2-dependence, we arrive at

$$\text{Var } u(x) = \sum_{j=1}^{Cn^{1/3}} j^2 O(n^{4/3}) = O(n^{7/3}).$$

7.3. *Conjectured exponents in higher dimensions.* For the oil and water model in \mathbb{Z}^d starting with n oil and n water particles at the origin, we believe that the typical order of the odometer (away from 0 and the boundary) is $n^{4/(d+2)}$ and the radius of the occupied cluster is of order $n^{1/(d+2)}$. The reason is by analogy with Section 6.2: if $w : \mathbb{R}^d \rightarrow \mathbb{R}$ solves the PDE:

$$(79) \quad \Delta w = -\delta_0 + \sqrt{\frac{2}{\pi}} w$$

then its rescaling

$$v(x) = t^4 w(x/t)$$

satisfies

$$\Delta v = -t^{d+2} \delta_0 + \sqrt{\frac{2}{\pi}} v.$$

If the odometer for n particles has a scaling limit w that satisfies (79), then v is the scaling limit of the odometer for $t^{d+2}n$ particles. So increasing the number of particles a factor of t^{d+2} increases the radius by a factor of t and the odometer by a factor of t^4 . This motivates the following conjecture.

CONJECTURE 7.1. *Let u be the odometer for the oil and water model started from n particles of each type at the origin in \mathbb{Z}^d . There exists a deterministic function $w : \mathbb{R}^d \rightarrow \mathbb{R}$ such that for all $\xi \in \mathbb{R} - \{0\}$ we have almost surely,*

$$\frac{u(\lfloor n^{1/(d+2)}\xi \rfloor)}{n^{4/(d+2)}} \rightarrow w(\xi).$$

Moreover, w is rotationally symmetric, twice differentiable on $\mathbb{R}^d - \{0\}$ and satisfies

$$\Delta w = \sqrt{\frac{2}{\pi}} w,$$

on $\mathbb{R}^d - \{0\}$ and $\lim_{\xi \rightarrow 0} \frac{w(\xi)}{g(\xi)} = 1$ where g is the Green function for the Laplacian on \mathbb{R}^d .

The fourth power scaling is reflected in the even spacing between contour lines of the odometer function in Figure 3.

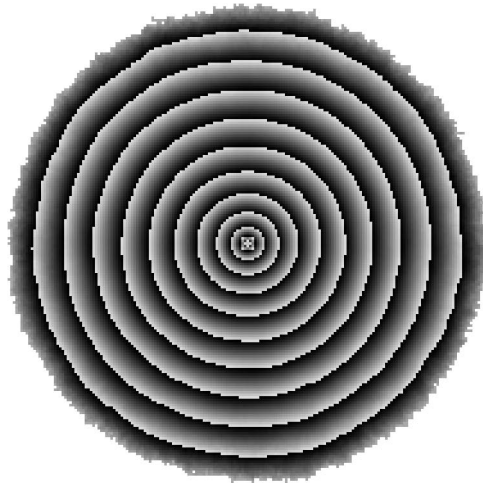


FIG. 3. Contour lines of the odometer function u of the oil and water model in \mathbb{Z}^2 with $n = 2^{22}$ particles of each type started at the origin. Each site is shaded according to the fractional part of $\frac{1}{5}u^{1/4}$.

APPENDIX

A.1. Concentration estimates.

LEMMA A.1. *Suppose for all $x \in \mathbb{Z}$ we have*

$$\begin{aligned} &X_1^x, Y_1^x \\ &X_2^x, Y_2^x \\ &\vdots \end{aligned}$$

a sequence of independent uniform ± 1 valued random variables. The sequences across x are also independent of each other. Then there exists constants $C, C', \gamma > 0$ such that for n large enough, with probability at least $1 - C \exp(-C'n^\gamma)$ for all $k > \sqrt{n}$ and $-n^5 < j < n^5$ we have:

- (i) $|\sum_{i=1}^k \mathbf{1}_{(X_i^j=1)} - k/2| < k^{1/2+\epsilon};$
- (ii) $|\sum_{i=1}^k \mathbf{1}_{(Y_i^j=1)} - k/2| < k^{1/2+\epsilon};$
- (iii) $|\sum_{i=1}^k \mathbf{1}_{(X_i^j=1)} \mathbf{1}_{(Y_i^j=1)} - k/4| < k^{1/2+\epsilon};$
- (iv) $|\sum_{i=1}^k \mathbf{1}_{(X_i^j=-1)} \mathbf{1}_{(Y_i^j=-1)} - k/4| < k^{1/2+\epsilon}.$

PROOF. Proof follows by standard bounds from Azuma–Hoeffding’s inequality for Bernoulli random variables and union bound over $k \geq \sqrt{n}$ followed by $j \in [-n^5, n^5]$. \square

A.2. Proof of Lemma 5.2. Let us define the truncated variable:

$$Y = M(n^{4/3}) \mathbf{1}(M(n^{4/3}) < n^{2/3+\epsilon})$$

for some small but a priori fixed ϵ . Let Y_i be i.i.d. copies of Y . Now by using Azuma’s inequality,

$$\mathbb{P}\left(\sum_{i=1}^{n^{1/3}} (Y_i - \mathbb{E}(Y_i)) > t\right) \leq e^{-\frac{t^2}{n^{1/3}n^{4/3+2\epsilon}}}.$$

Taking $t^2 = n^{5/3+3\epsilon}$, we get that

$$\mathbb{P}\left(\sum_{i=1}^{n^{1/3}} (Y_i - \mathbb{E}(Y_i)) > t\right) < e^{-n^\epsilon}.$$

Now by (iv) Lemma 5.1 $\mathbb{E}(Y) = O(n^{2/3})$. Thus,

$$n^{1/3}\mathbb{E}(Y) + t < Dn$$

for some large D as $t = n^{5/6+2\epsilon}$. Hence,

$$\mathbb{P}\left(\sum_{i=1}^{n^{1/3}} Y_i > Dn\right) \leq e^{-n^\epsilon}.$$

This implies that

$$\mathbb{P}\left(\sum_{i=1}^{n^{1/3}} M^i(n^{4/3}) > Dn\right) \leq C e^{-n^\gamma}$$

since by (i) Lemma 5.1 and union bound, there exists a positive constant $c > 0$ such that

$$\mathbb{P}(\exists 1 \leq i \leq n^{1/3} \text{ such that } Y_i \neq M^i) \leq e^{-n^c}.$$

A.3. Proof of Lemma 6.5. We use the variables E_i defined in the statement of Lemma 3.5. Let

$$Y = \sum_{i=1}^{\tau'} E_i,$$

where τ' was defined in (12). As mentioned in proof of Proposition 3.1 by Lemmas 3.3 and 3.5 τ is stochastically dominated by Y . Thus,

$$\mathbb{E}[\tau \mathbf{1}(\tau > n^5)] \leq \mathbb{E}[Y \mathbf{1}(Y > n^5)].$$

Hence, to prove the lemma it suffices to show the right-hand side is $O(1)$. Now

$$(80) \quad \mathbb{E}[Y \mathbf{1}(Y > n^5)] \leq \mathbb{E}[Y \mathbf{1}(\tau' > n^{5/2})] + \mathbb{E}[Y \mathbf{1}(\tau' \leq n^{5/2}) \mathbf{1}(Y > n^5)]$$

$$(81) \quad \leq \mathbb{E}[Y \mathbf{1}(\tau' > n^{5/2})] + \mathbb{E}\left[\sum_{i=1}^{n^{5/2}} E_i \mathbf{1}\left(\sum_{i=1}^{n^{5/2}} E_i \geq n^5\right)\right]$$

$$(82) \quad \leq \mathbb{E}[Y \mathbf{1}(\tau' > n^{5/2})] + \mathbb{E}\left[\sum_{i=1}^{n^{5/2}} E_i\right] \mathbb{E}\left[\sum_{i=1}^{n^{5/2}} \mathbf{1}(E_i \geq n^{5/2})\right],$$

where the last inequality follows from the easy fact

$$\mathbf{1}\left(\sum_{i=1}^{n^{5/2}} E_i \geq n^5\right) \leq \sum_{i=1}^{n^{5/2}} \mathbf{1}(E_i \geq n^{5/2}).$$

We use the following tail estimate for E_1 and τ' : there exists a constant $c < 1$ such that for $k \geq n^2$:

$$(83) \quad \max(\mathbb{P}(\tau' \geq k), \mathbb{P}(E_1 \geq k)) \leq (1 - c)^{\lfloor \frac{k}{n^2} \rfloor},$$

which easily follows from the fact that starting from any point in $[-2n, 2n]$ there exists a constant chance c for the random walk to exit the interval in the next n^2 steps. Using (83), independence of τ' , E_i^s , the theorem now follows from (82). The details are omitted.

A.4. Proof of Corollary 6.6. The proof follows from the following observation:

$$(84) \quad u(x) \leq Cn^{4/3}\mathbf{1}(\mathcal{G}) + n^5\mathbf{1}(\mathcal{G}^c)\mathbf{1}(\tau \leq n^5) + \tau\mathbf{1}(\tau \geq n^5)\mathbf{1}(\mathcal{G}^c),$$

where C is the constant appearing in the statement of Theorem 1.1, τ is defined in (10) and \mathcal{G} is defined in (17). The first term follows from the definition of \mathcal{G} . For the second and third term, we use the trivial bound that

$$u(x) \leq \tau.$$

Taking expectation, we get

$$\tilde{u}(x) \leq Cn^{4/3} + n^5\mathbb{P}(\mathcal{G}^c) + \mathbb{E}(\tau\mathbf{1}(\tau \geq n^5)).$$

The last two terms are $O(1)$ by Theorem 1.1 and Lemma 6.5, respectively. Hence, we are done.

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