

SEX, LIES AND SELF-REPORTED COUNTS: BAYESIAN MIXTURE MODELS FOR HEAPING IN LONGITUDINAL COUNT DATA VIA BIRTH–DEATH PROCESSES¹

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Surveys often ask respondents to report nonnegative counts, but respondents may misremember or round to a nearby multiple of 5 or 10. This phenomenon is called heaping, and the error inherent in heaped self-reported numbers can bias estimation. Heaped data may be collected cross-sectionally or longitudinally and there may be covariates that complicate the inferential task. Heaping is a well-known issue in many survey settings, and inference for heaped data is an important statistical problem. We propose a novel reporting distribution whose underlying parameters are readily interpretable as rates of misremembering and rounding. The process accommodates a variety of heaping grids and allows for quasi-heaping to values nearly but not equal to heaping multiples. We present a Bayesian hierarchical model for longitudinal samples with covariates to infer both the unobserved true distribution of counts and the parameters that control the heaping process. Finally, we apply our methods to longitudinal self-reported counts of sex partners in a study of high-risk behavior in HIV-positive youth.

1. Introduction. When survey respondents report numeric quantities, they often recall those numbers with error. Respondents sometimes round up or down, for example, to the nearest integer, decimal place or multiple of 5 or 10. This kind of misreporting is called heaping, and when the probability of heaping depends on the true value of the unheaped variable, the mechanism is nonignorable [Heitjan and Rubin (1991)]. Heaping is a well-known problem in many survey settings, and robust inference for heaped data remains an important problem in statistical inference [Crockett and Crockett (2006), Heitjan (1989), Schneeweiss, Komlos and Ahmad (2010), Wang and Heitjan (2008), Wright and Bray (2003)]. Reporting errors

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are frequently observed for a variety of measurements, including self-reported age [Myers (1954, 1976), Stockwell and Wicks (1974)], height and weight [Rowland (1990), Schneeweiss and Komlos (2009)], elapsed time [Huttenlocher, Hedges and Bradburn (1990)] and household purchases [Browning, Crossley and Weber (2003)]. Respondents may be inclined to misreport when the survey addresses topics that seem private, embarrassing or culturally taboo [Schaeffer (1999)]. For example, there may be significant misreporting in studies of drug use [Klov Dahl et al. (1994), Roberts and Brewer (2001)], cigarette use [Brown et al. (1998), Wang and Heitjan (2008)] or number of sex acts or sexual partners [Fenton et al. (2001), Ghosh and Tu (2009), Golubjatnikov, Pfister and Tillotson (1983), Weinhardt et al. (1998), Westoff (1974), Wiederman (1997)].

Several authors have proposed approximations to correct estimates using heaped data [Schneeweiss and Augustin (2006), Schneeweiss and Komlos (2009), Sheppard (1897), Tallis (1967), Schneeweiss, Komlos and Ahmad (2010), Lindley (1950)]. Others have explored smoothing techniques for heaped data on the grounds that smoothing may have the effect of “spreading out” grouped responses [Hobson (1976), Singh, Suchindran and Singh (1994)]. Heitjan (1989) and Heitjan and Rubin (1990, 1991) provide an important unifying perspective on heaped and grouped data by introducing the concept of coarsening, in which one observes only a subset of the complete data sample space. Based on this paradigm, Wang and Heitjan (2008) formulate a model for heaped cigarette counts and apply these ideas to study impact of a drug treatment on smoking. Jacobsen and Keiding (1995) discuss extensions of the coarse data concept to more general sample spaces than those considered by Heitjan and Rubin (1991). Wright and Bray (2003) model heaped nuchal translucency measurements as samples from a mixture model and propose a Gibbs sampling scheme to draw from the joint distribution of the true counts and unknown rounding parameters. Bar and Lillard (2012) model the age at which subjects quit smoking by supposing that heaping takes place on a grid of multiples of 5 or 10.

Most attempts to disentangle heaped count responses from latent true values can be understood as mixture models. To illustrate, suppose each subject draws their latent true count x from a distribution with mass function $f(x|\phi)$ on the nonnegative integers that depends on parameters ϕ and then reports a possibly different value y from a reporting distribution with mass function $g(y|x, \theta)$ that depends on the true count x and parameters θ . Because the reporting distribution g depends on the latent true count x , the heaping mechanism is nonignorable. The likelihood contribution of an observed count y is therefore

$$(1) \quad L(\theta, \phi; y) = \sum_{x=0}^{\infty} g(y|x, \theta) f(x|\phi).$$

Figure 1 shows a graphical representation of this mixture model for heaped counts. The objects of inference are often the true counts x and the parameters ϕ underlying the true count distribution $f(x|\phi)$.

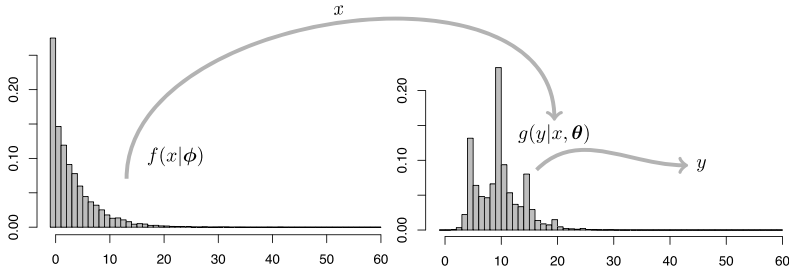


FIG. 1. Mixture model schematic for reported counts. Each subject chooses their true count x from the distribution $f(x|\phi)$, then reports the possibly different count y drawn from the distribution $g(y|x, \theta)$.

Many approaches characterize the reporting mechanism as a choice between reporting truthfully and misreporting at suspected heaping grid points [e.g., Bar and Lillard (2012), Wang and Heitjan (2008), Wang et al. (2012), Wright and Bray (2003)]. The probability of reporting a particular heaped value depends on the value of the latent true value: Wang and Heitjan (2008) use a proportional odds model for different heaping grids; Bar and Lillard (2012) propose a multinomial distribution governing the choice of different heaping rules; McLain et al. (2014) propose a semi-parametric model for heaping (digit preference) of duration-time data in which subjects are equally likely to round up or down. Most models for count data only allow exact heaping to the multiple of 5, 10 or 20 that is nearest to the latent true count, and the heaping rule is the same for all subjects. However, limiting heaped responses to the nearest grid point can produce inferences of true counts that are unrealistically constrained. For example, if the reported count is $y = 35$ and the model only allows heaping to multiples of 5, then one must infer $x \in \{33, \dots, 37\}$. Furthermore, established models do not allow for misremembering as a function of the true count or quasi-heaping to counts close to, but not equal to, the specified grid values (e.g., a subject whose true count is 93 may report 101 or 99 instead of the heaped value 100).

In this paper, we relax several of these restrictive assumptions and incorporate rigorous analysis of heaped data into a hierarchical regression model. In Section 2 we propose a novel reporting distribution by imagining the true count x as the starting point of a continuous-time Markov chain on the nonnegative integers \mathbb{N} known as a general birth–death process (BDP). The ending state of this Markov chain after a specified epoch is the reported count y . Jumps from integer state k to $k + 1$ or $k - 1$ occur with instantaneous rates λ_k and μ_k , respectively, with $\mu_0 = 0$ to keep the process on \mathbb{N} . We specify λ_k and μ_k so that the process is attracted to nearby heaping grid points. Our BDP heaping model characterizes an infinite family of reporting distributions $g(y|x, \theta)$ that is (1) indexed by the true count x ; (2) controlled by a small number of parameters θ that are readily interpretable; and (3) can be computed quickly to provide a reporting likelihood. The model permits heaping to values beyond the nearest grid point, provides for multiple heaping

grids and continuous transitions between them, allows misremembering and quasi-heaping, and accommodates subject-specific heaping intensities. In Section 3 we outline a Bayesian hierarchical model for longitudinal counts and a Metropolis-within-Gibbs scheme for drawing inference from the joint posterior distribution of the unknown parameters. We are interested in learning about the parameters ϕ underlying the true counts, the true counts x themselves and the parameters θ that govern the reporting/heaping process. Finally, in Section 5 we demonstrate our method on longitudinal self-reported counts of sexual partners from a study of HIV-positive youth.

2. Constructing the reporting distributions. Let x be the true count for a subject and let y be their reported count. Let $g(y|x, \theta)$ be the probability of reporting y , given that their true count is x under the parameter vector θ . To parameterize $g(y|x, \theta)$ to allow heaping, suppose y represents the state of an unbounded continuous-time Markov random walk, taking values on \mathbb{N} , starting at x and evolving for a finite arbitrary time. We accomplish this task by defining the birth and death rates λ_k and μ_k of a general BDP in a novel way so that the process is attracted to grid points on which we expect heaping to occur. The transition probabilities of this process give rise to the family of reporting distributions $g(y|x, \theta)$. We extend the proportional odds framework of Wang and Heitjan (2008) to allow heaping to different grid values depending on the magnitude of the count. First we present background on general BDPs and show how to use the transition probabilities of a general BDP to model heaping.

2.1. General birth–death processes. A general BDP is a continuous-time Markov random walk on the nonnegative integers \mathbb{N} [Feller (1971)]. Let $U(t) \in \mathbb{N}$ be the location of the walk at time t . Define the transition probability $P_{ab}(t) = \Pr(U(t) = b | U(0) = a)$ to be the probability that the process is in state b at time t , given that it started at state a at time 0. A general BDP obeys the Kolmogorov forward equations

$$(2) \quad \frac{dP_{ab}(t)}{dt} = \lambda_{b-1}P_{a,b-1}(t) + \mu_{b+1}P_{a,b+1}(t) - (\lambda_b + \mu_b)P_{ab}(t),$$

for all $a, b \in \mathbb{N}$, where $P_{ab}(0) = 1$ if $a = b$, $P_{ab}(0) = 0$ if $a \neq b$, and $\mu_0 = \lambda_{-1} = 0$ to keep the BDP on \mathbb{N} . In this setting, t is arbitrary; for example, halving t and multiplying all birth and death rates by two does not change the distribution of $U(t)|U(0)$. The forward equations (2) form an infinite sequence of ordinary differential equations describing the probability flow into and out of state b within a small time interval $(t, t + dt)$. Karlin and McGregor (1957) provide a detailed derivation of properties of general BDPs. Unfortunately, it remains notoriously difficult to find analytic expressions for the transition probabilities in almost all general BDPs, and often one must resort to numerical techniques [Novozhilov, Karev and Koonin (2006), Renshaw (2011)]. Appendix A gives an overview of the Laplace transform technique we use to numerically compute the transition probabilities efficiently.

In our heaping parameterization, we model the true count $U(0) = x$ as the starting state of a BDP and $U(t) = y$ as the ending state. We therefore set $t = 1$ and define $g(y|x, \theta) = P_{xy}(1)$ so that P_{xy} is a function of the unknown parameter vector θ , where the $\{\lambda_k\}$ and $\{\mu_k\}$ are all functions of θ . We emphasize that the time parameter t is meaningless in this context, because scaling t by a constant and dividing the birth and death rates by the same constant does not change the transition probabilities.

2.2. *Specifying the jumping rates λ_k and μ_k .* Grunwald et al. (2011) and Lee, Weiss and Suchard (2014) model under- and over-dispersion in count data using a simple linear BDP with $\lambda_x = \mu_x = \lambda x$, but do not address heaping. In addition to modeling dispersion, BDPs can be used to parameterize general families of probability measures on \mathbb{N} [Klar, Parthasarathy and Henze (2010)]. In our heaping model, we imagine errors in self-reported counts to come from two sources: dispersion due to misremembering and heaping. Misremembering adds variance by spreading reported counts around the true count. Heaping results in preference for reporting certain counts, for example, on a grid of values such as multiples of 5 or 10. We specify both of these sources of misreporting error using a BDP with jumping rates $\{\lambda_k\}$ and $\{\mu_k\}$ that are modeled as functions of the finite-dimensional parameter vector θ .

To motivate development of our general BDP model for heaping, suppose for now that heaping occurs at multiples of 5. We wish to define a random walk on \mathbb{N} that is dispersed around its starting point and attracted to multiples of 5, with this attraction increasing with proximity to each multiple of 5. For example, if the true count is $x = 49$, then the reported count y is more strongly attracted to 50 than 45, because 49 is closer to 50. Here, *attraction* to a given multiple means that the likelihood of the BDP moving toward that multiple is greater than the likelihood of moving in the other direction. Informally, we wish to assign birth and death rates such that

$$(3) \quad \begin{aligned} \lambda_k &= (\text{dispersion around } k) + (\text{attraction to multiple of 5 above}), \\ \mu_k &= (\text{dispersion around } k) + (\text{attraction to multiple of 5 below}). \end{aligned}$$

One way to quantify the strength of attraction to the multiple of 5 immediately above k is $(k \bmod 5)$. Likewise, the attraction to the multiple of 5 immediately below k is $(-k \bmod 5)$, which is equal to $5 - (k \bmod 5)$. In both directions, the closer k is to the nearby multiple of 5, the greater its attraction to it.

Subjects whose true number of sex partners is greater than 100, for example, may be less able to accurately recall this number than subjects whose true count is less than 10. We therefore model dispersion around the true count in the reported counts due to misremembering as increasing the true count. Consider a general BDP with jumping rates

$$(4) \quad \begin{aligned} \lambda_k &= \theta_{\text{disp}}(1 + k) + \theta_{\text{heap}}(k \bmod 5), \\ \mu_k &= \theta_{\text{disp}}k + \theta_{\text{heap}}(-k \bmod 5), \end{aligned}$$

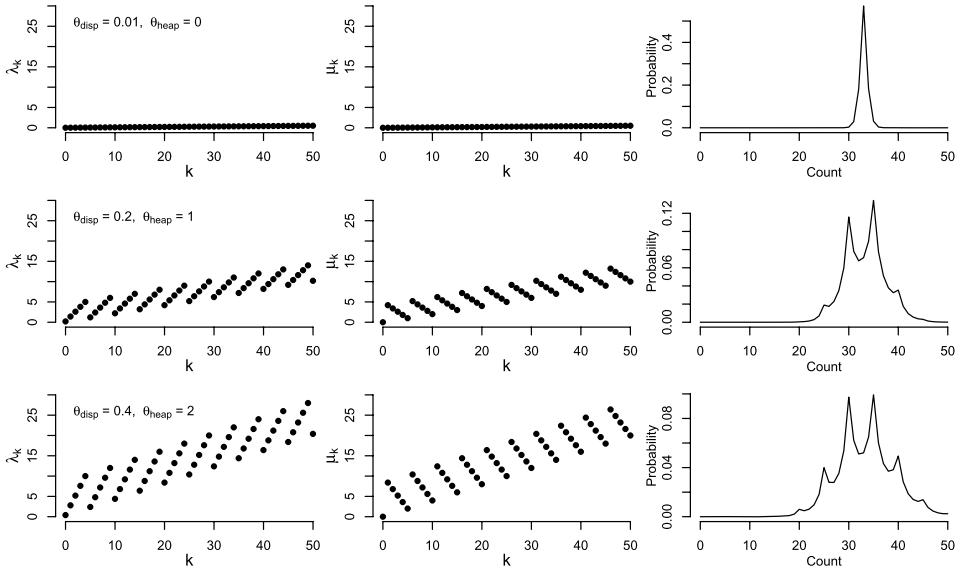


FIG. 2. Birth rates λ_k (left), death rates μ_k (center) and reporting probabilities for true count $x = 33$ (right) in the heaping model (4) for different values of the dispersion parameter θ_{disp} and heaping intensity θ_{heap} . Larger values of θ_{disp} result in more dispersion about the true count. Larger values of θ_{heap} result in more heaping to nearby multiples of 5.

where the $(1 + k)$ in the birth rate arises because we wish to allow the BDP to escape from zero with positive rate. In this formulation of the birth and death rates, the dispersion parameter $\theta_{\text{disp}} \geq 0$ is the propensity to over- or under-report and $\theta_{\text{heap}} \geq 0$ is the propensity of rounding up or down to multiples of 5. Figure 2 shows the birth rates λ_k , death rates μ_k and reporting probabilities with true count $x = 33$ for this heaping model. The complexity of the reporting distributions generated by the heaping model is evident in Figure 2; the BDP tends toward multiples of 5 and the magnitude of θ_{heap} controls the severity of heaping. The BDP heaping model exhibits subtler behavior than a dispersion distribution with added mass at the heaping points.

Figure 3 shows reporting distributions for the true count $x = 7$. When $\theta_{\text{heap}} = 0$, the reporting distribution only adds variance to the true count. As θ_{heap} becomes larger, the peaks in the reporting distribution at the heaping points become more pronounced. When θ_{heap} is large and θ_{disp} is small, the reporting distribution is sharply peaked at nearby multiples of 5 and the values between heaping points have little probability mass.

In general, suppose that heaping occurs at equally-spaced grid points mk where $m \in \mathbb{N}$ is the grid spacing; for example, m could be one of 5, 10, 20, 25 or 100.

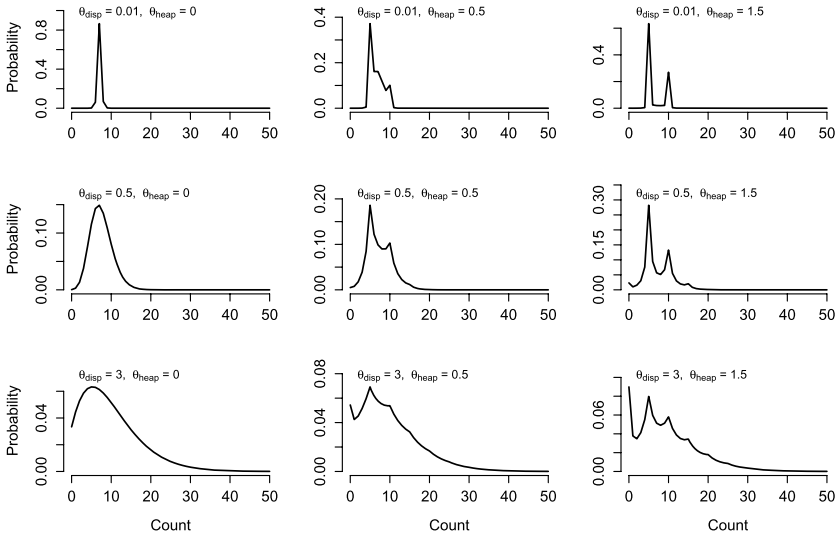


FIG. 3. Reporting probabilities for heaping at multiples of 5 with true count $x = 7$ using different values of the dispersion parameter θ_{disp} and the heaping parameter θ_{heap} . Larger values of θ_{disp} allow reports closer to zero; when θ_{heap} is positive, heaping occurs at zero, providing a mechanism for zero-inflated reports.

Analogous to (4), the birth and death rates become

$$\begin{aligned}
 \lambda_k &= \theta_{\text{disp}}(1 + k) + \theta_{\text{heap}}(k \bmod m), \\
 \mu_k &= \theta_{\text{disp}}k + \theta_{\text{heap}}(-k \bmod m).
 \end{aligned}
 \tag{5}$$

Figure 4 shows birth and death rates for several heaping grid spacings m .

We can analytically characterize the properties of the reporting distribution when θ_{heap} is zero. Given the true count x , the mean and variance of the reported count y are

$$\begin{aligned}
 \mathbb{E}[y|x] &= x + \theta_{\text{disp}} \quad \text{and} \\
 \text{Var}[y|x] &= (2x + 1)\theta_{\text{disp}} + \theta_{\text{disp}}^2.
 \end{aligned}
 \tag{6}$$

Appendix B provides a derivation of these expressions. It is evident that both the mean and variance of $y|x$ increase linearly with the true count x , consistent with our belief that the severity of misremembering scales in proportion to the magnitude of the true count.

2.3. Heaping regimes. As true counts become larger, coarseness often increases; small counts appear to be heaped at multiples of 5, then 10, and finally 50 or 100 for larger counts. Models such as (4) that enforce heaping to the same grid regardless of the magnitude of the count may provide insufficient rounding

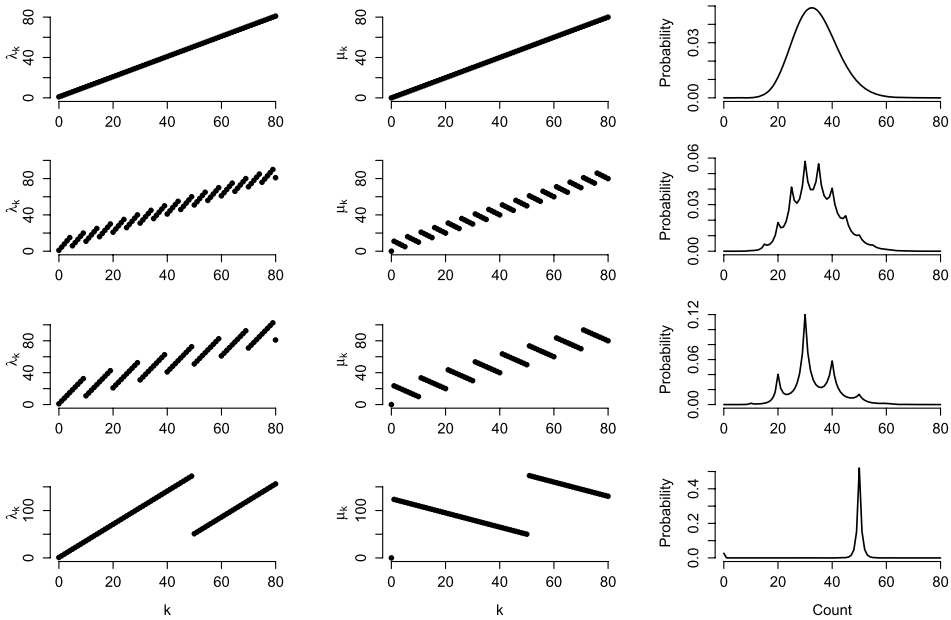


FIG. 4. Birth rates λ_k (left), death rates μ_k (center) and reporting probabilities (right) for different heaping grids with true count $x = 33$ and $\theta_{\text{disp}} = 1$. The first row shows the reporting distribution for $\theta_{\text{heap}} = 0$. Subsequent rows show the birth and death rates and reporting probabilities with $\theta_{\text{heap}} = 2.5$ with heaping at multiples of 5, 10 and 50. When heaping is to multiples of 50 (bottom row), reporting is concentrated at $y = 50$.

behavior when the coarseness increases with x . Consider J distinct heaping grids and suppose m_j is the grid spacing for regime j , where $j = 1, \dots, J$. Let $v_j(x)$ be the intensity of regime j as a function of the true count x . Regime 0, with intensity $v_0(x)$, is the probability of accurately reporting the true count. Regime j , with intensity $v_j(x)$, corresponds to heaping at multiples of m_j . We follow Wang and Heitjan (2008) to develop a proportional odds model for smooth transitions between heaping grids.

Define birth and death rates

$$\lambda_k = \theta_{\text{disp}}(1 + k) + \theta_{\text{heap}} \sum_{j=1}^J v_j(x)(k \bmod m_j),$$

$$\mu_k = \theta_{\text{disp}}k + \theta_{\text{heap}} \sum_{j=1}^J v_j(x)(-k \bmod m_j),$$

where the heaping regime probabilities are

$$v_0(x) = (1 + e^{\gamma_1 + \gamma_0 x})^{-1},$$

$$v_1(x) = (1 + e^{\gamma_2 + \gamma_0 x})^{-1} - (1 + e^{\gamma_1 + \gamma_0 x})^{-1},$$

$$v_2(x) = (1 + e^{\gamma_3 + \gamma_0 x})^{-1} - (1 + e^{\gamma_2 + \gamma_0 x})^{-1},$$

$$\vdots$$

$$v_J(x) = 1 - (1 + e^{\gamma_J + \gamma_0 x})^{-1},$$

and we restrict the regime transition parameters $\gamma_0 > 0$ and $\gamma_1 > \gamma_2 > \dots > \gamma_J$. We have, by construction,

$$(9) \quad \sum_{j=1}^J v_j(x) = 1,$$

for every $x \in \mathbb{N}$. In this proportional odds model, γ_0 determines the transition rate between regimes and γ_j/γ_0 controls the midpoint of the transition between regimes $j - 1$ and j . Figure 5 shows the heaping regime model defined above. Each row shows a different heaping regime model and reporting distribution $g(y|x, \theta, \boldsymbol{\gamma})$, where $\boldsymbol{\gamma} = (\gamma_0, \dots, \gamma_J)$ for $x = 14, 23, 53$ and $\theta = (0.5, 1.5)$.

2.4. *Justification for the BDP heaping model.* We formulate the heaping model as a continuous-time Markov process for three reasons: mathematical con-

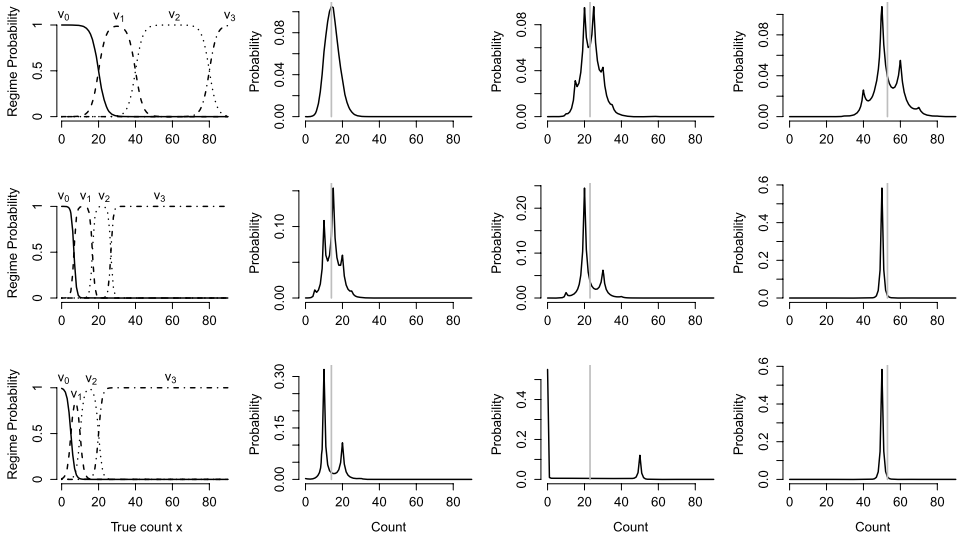


FIG. 5. *Heaping regimes.* Each row shows a different heaping regime model with reporting probabilities for $\theta_{\text{disp}} = 0.5$ and $\theta_{\text{heap}} = 1.5$. A gray line denotes the true counts $x = 14, 23, 53$. In the first row, the regime intensities are shown with regime parameters $\boldsymbol{\gamma} = (0.5, -10, -20, -40)$. For $x = 14$, the reporting distribution is dominated by regime 0, which specifies no heaping. For $x = 23$, the reporting distribution is dominated by regime 1, so rounding to nearby multiples of 5 is evident. At $x = 53$, regime 2 is dominant, and the reporting distribution is peaked at multiples of 10. In the second row, $\boldsymbol{\gamma} = (1.5, -10, -25, -40)$, and the reporting distribution for $x = 53$ is dominated by regime 3, so the model exhibits heaping to multiples of 50. In the third row, $\boldsymbol{\gamma} = (1, -5, -10, -20)$.

venience, diversity of reporting distributions, and parsimony in parameterization. First, the theory of general BDPs is well developed and efficient methods now exist for computing transition probabilities for any specification of the birth and death rates [Crawford and Suchard (2012)]. The heaping probability mass function $g(y|x)$ is automatically normalized to integrate to one (since it is the likelihood of a Markov process), so the mixture model (1) is always well defined. Second, the model described in (7) and (8) exhibits a great diversity in reporting distributions, from no heaping to always heaping, under a wide variety of magnitude-based regimes (see Figures 2–5, e.g.). Third, the general BDP achieves this complex behavior using only two parameters for the heaping process and four in the regimes specification. Additionally, the specification of heaping regimes via (7) and (8) results in an appealing property: the reporting distribution can be highly asymmetrical when the true count is subject to two heaping regimes. For example, the third row of Figure 5 shows how the true count $x = 14$ can be pulled toward 10 and 20 with very different probabilities.

3. A hierarchical model for longitudinal counts. We describe a generalized linear mixed model (GLMM) for longitudinal counts. Label subjects $i = 1, \dots, N$, with each subject’s true count X_{it} and self-reported count Y_{it} at real calendar timepoints t_{ij} for $j = 1, \dots, n_i$. We record d -dimensional covariates \mathbf{W}_{it} and c -dimensional \mathbf{Z}_{it} for each subject at each timepoint. Consider the following hierarchical model:

$$(10) \quad X_{it} \sim \text{Poisson}(\eta_{it}),$$

$$(11) \quad \log \eta_{it} = \mathbf{W}_{it}\boldsymbol{\alpha} + \mathbf{Z}_{it}\boldsymbol{\beta}_i$$

and

$$(12) \quad \boldsymbol{\beta}_i \sim \text{Normal}(\mathbf{0}, \boldsymbol{\Sigma}_\beta),$$

where the vector of regression coefficients $\boldsymbol{\alpha}$ is $d \times 1$, the subject-specific random effect $\boldsymbol{\beta}_i$ is $c \times 1$ with the covariance matrix $\boldsymbol{\Sigma}_\beta$ is $c \times c$, and η_{it} is the subject-timepoint-specific mean of the outcome distribution in the GLMM.

A model without heaping arises when we set $Y_{it} = X_{it}$ for all i and t . To incorporate heaping, let

$$(13) \quad Y_{it} \sim \text{BDP}(X_{it}, \boldsymbol{\theta}, \boldsymbol{\gamma}).$$

We allow the BDP heaping model to have a separate heaping intensity parameter $\theta_{\text{heap},i}$ for each subject. If $X_{it} = x$, the birth and death rates for subject i are

$$(14) \quad \begin{aligned} \lambda_k &= \theta_{\text{disp}}(1+k) + \theta_{\text{heap},i} \sum_{j=1}^3 v_j(x)(k \bmod m_j) \quad \text{and} \\ \mu_k &= \theta_{\text{disp}}k + \theta_{\text{heap},i} \sum_{j=1}^3 v_j(x)(m_j - ((k-1) \bmod m_j)), \end{aligned}$$

where $m_1 = 5, m_2 = 10, m_3 = 50$, and $v_1(x), v_2(x)$, and $v_3(x)$ are defined above in (8). The subject-specific heaping intensity is

$$(15) \quad \log \theta_{\text{heap},i} = \mathbf{H}_i \boldsymbol{\omega} + \xi_i,$$

where \mathbf{H}_i is a heaping covariate vector for subject i , $\boldsymbol{\omega}$ is an unknown parameter vector of corresponding dimension, and ξ_i is a subject-specific random effect, with distribution

$$(16) \quad \xi_i \sim \text{Normal}(\mathbf{0}, \sigma_\xi).$$

To complete our Bayesian hierarchical model for longitudinal studies, we specify conditionally conjugate prior distributions for $\boldsymbol{\alpha}$ and $\boldsymbol{\Sigma}_\beta$:

$$(17) \quad \begin{aligned} \boldsymbol{\alpha} &\sim \text{Normal}(\mathbf{0}, \mathbf{V}_\alpha), \\ \theta_{\text{disp}} &\sim \text{Inverse-Gamma}(a, b), \\ \boldsymbol{\omega} &\sim \text{Normal}(\mathbf{0}, \boldsymbol{\Sigma}_\omega), \\ \boldsymbol{\gamma} &\sim \text{Normal}(\mathbf{0}, \mathbf{V}_\gamma) \quad \text{subject to } \gamma_0 < \dots < \gamma_J \quad \text{and} \\ \boldsymbol{\Sigma}_\beta &\sim \text{Inverse-Wishart}(A_\beta, \mathbf{m}_\beta), \end{aligned}$$

where $\mathbf{V}_\alpha, a, b, \mathbf{V}_\gamma, A_\beta$ and \mathbf{m}_β are fixed hyperparameters of corresponding dimension that we specify in Section 5.

Finally, we fit an alternative model of Wang and Heitjan (2008) in which responses not equal to a heaping point are assumed to be reported accurately. The model for the latent counts X_{it} is identical to (10)–(12), but the heaping distribution is different. If x is the true count, then y is reported as

$$(18) \quad y = \begin{cases} x, & \text{with probability } v_0(x), \\ \text{nearest multiple of 5,} & \text{with probability } v_1(x), \\ \text{nearest multiple of 10,} & \text{with probability } v_2(x), \\ \text{nearest multiple of 50,} & \text{with probability } v_3(x). \end{cases}$$

Once the heaping regime in (18) has been determined, the reported count y arises deterministically.

3.1. *Posterior inference.* We estimate the joint posterior distribution with Markov chain Monte Carlo (MCMC). We describe standard Gibbs and Metropolis–Hastings samplers for the full conditional distributions of $\boldsymbol{\alpha}, \boldsymbol{\beta} = (\boldsymbol{\beta}_1, \dots, \boldsymbol{\beta}_N), \boldsymbol{\theta}, \boldsymbol{\gamma}$ and $\boldsymbol{\Sigma}_\beta$ in the supplemental material [Crawford, Weiss and Suchard (2015)]. Sampling from the conditional posterior distribution of the true counts is more challenging because of the lack of conjugacy between $\Pr(X_{it} | \mathbf{Z}_{it}, \mathbf{W}_{it}, \boldsymbol{\alpha}, \boldsymbol{\beta}_i)$ and $g(Y_{it} | X_{it}, \boldsymbol{\theta})$. Fortunately, the discrete nature of count data makes some simplifications possible. The conditional distribution of the unobserved true count X_{it}

is

$$(19) \quad \begin{aligned} & \Pr(X_{it}|Y_{it}, \mathbf{Z}_{it}, \mathbf{W}_{it}, \mathbf{H}_i, \boldsymbol{\theta}, \boldsymbol{\alpha}, \boldsymbol{\beta}_i) \\ & \propto g(Y_{it}|X_{it}, \boldsymbol{\theta}) \Pr(X_{it}|\mathbf{Z}_{it}, \mathbf{W}_{it}, \mathbf{H}_i, \boldsymbol{\alpha}, \boldsymbol{\beta}_i). \end{aligned}$$

It is computationally costly to evaluate $g(y|x, \boldsymbol{\theta})$ hundreds of times to construct the distribution of X_{it} . In the [Appendix](#) we present a method for approximating this density by a discretized normal distribution derived from the dynamics of the BDP with $\theta_{\text{heap}} = 0$, allowing efficient sampling. We then employ a Metropolis–Hastings accept/reject step to sample from the correct posterior.

4. Simulation study. To validate the proposed heaping model and the associated Bayesian inference framework, we simulate data under a simplification of the hierarchical model described in Section 3:

$$(20) \quad \begin{aligned} Y_{it} & \sim \text{BDP}(X_{it}, \boldsymbol{\theta}, \boldsymbol{\gamma}), \\ X_{it} & \sim \text{Poisson}(\eta_{it}), \\ \log \eta_{it} & = \alpha + \beta_i \quad \text{and} \\ \beta_i & \sim \text{Normal}(0, \sigma_\beta^2), \end{aligned}$$

for subjects $i = 1, \dots, n$ and repeated measures $t = 1, \dots, 5$, with α and β_i scalars. The heaping parameter $\theta_{\text{heap},i} = \theta_{\text{heap}}$ is constant for every subject. Setting $\alpha = 2$, $\sigma_\beta^2 = 1.21$, $\boldsymbol{\gamma} = (0.5, -5, -10, -20)$, and $\theta_{\text{disp}} = 0.5$ and $\theta_{\text{heap}} = 2$ yields observed counts qualitatively similar to those we observe in the application section below. From this model, we simulate data sets with $N = 100, 250$ and 500 total observations from $n = N/5$ subjects. Using 100 replicates, [Table 1](#) reports true parameter values, average posterior means, average posterior variances and mean squared error (MSE) for each data set. Standard deviations are given in parentheses. As expected, simulations with larger N give, in general, more accurate parameter estimates, with posterior variance and MSE decreasing with N . Posterior mean estimates of the heaping regimes parameters γ_2 and γ_3 are close to their true values, but their MSE does not appear to decrease monotonically with N . The regime parameters may be only weakly identified in data sets with few large reported counts. Since these parameters control the midpoints of transitions between heaping regimes, they may be highly variable unless many counts fall near these transitions. In addition to larger N , it may be necessary to observe a greater proportion of heaped counts near regime transitions in order to achieve a substantial reduction in posterior variance for γ_2 and γ_3 .

5. Application to self-reported counts of sex partners. To illustrate the effectiveness of our mixture model and general BDP characterization of the reporting distributions $g(y|x, \boldsymbol{\theta})$, we analyze a survey of HIV-positive youth regarding their

TABLE 1

Summary of estimated parameters from 100 simulated datasets of size $N = 100, 250$ and 500 under the heaping model given by (20). Averages of the posterior means, averages of the posterior variances and mean squared errors are shown with standard deviations in parentheses

	True	$N = 100$			$N = 250$			$N = 500$		
		Mean	Var	MSE	Mean	Var	MSE	Mean	Var	MSE
α	2.00	1.991 (0.28)	0.059 (0.03)	0.078	1.970 (0.14)	0.026 (0.01)	0.021	2.030 (0.12)	0.013 (0.00)	0.014
σ_β^2	1.21	1.368 (0.32)	0.210 (0.12)	0.123	1.270 (0.22)	0.081 (0.03)	0.052	1.211 (0.16)	0.037 (0.01)	0.027
θ_{disp}	0.50	0.516 (0.17)	0.026 (0.01)	0.030	0.508 (0.09)	0.011 (0.00)	0.008	0.492 (0.08)	0.006 (0.00)	0.007
θ_{heap}	2.00	2.013 (1.11)	0.572 (0.68)	1.220	2.288 (0.89)	0.615 (0.90)	0.858	2.157 (0.71)	0.368 (0.61)	0.527
γ_0	0.50	0.494 (0.08)	0.004 (0.01)	0.007	0.497 (0.07)	0.003 (0.00)	0.005	0.492 (0.06)	0.003 (0.00)	0.004
γ_1	-5.00	-5.022 (1.37)	0.840 (0.56)	1.867	-5.204 (0.92)	0.657 (0.48)	0.881	-5.231 (0.86)	0.616 (0.46)	0.790
γ_2	-10.00	-9.677 (1.70)	1.617 (1.31)	2.949	-9.916 (1.41)	1.516 (0.98)	1.985	-10.282 (1.50)	1.418 (0.91)	2.290
γ_3	-20.00	-19.603 (2.21)	2.343 (2.05)	4.969	-19.388 (2.17)	3.126 (2.58)	5.050	-19.351 (2.26)	3.250 (2.09)	5.486

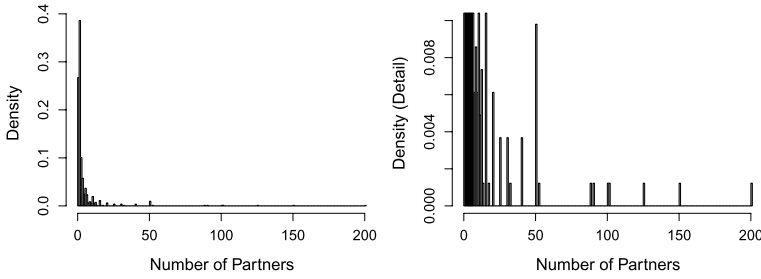


FIG. 6. Summary of self-reported counts of sex partners. At left, the histogram shows the aggregate reported number of partners in the previous three months, for all subjects, at all timepoints. At right is the same histogram with the vertical axis limited to (0, 0.01) to show greater detail. There is an apparent preference for reporting counts in multiples of 5, 10 and 50.

sexual behavior from the Choosing Life: Empowerment, Action Results (CLEAR) longitudinal three-arm randomized intervention study designed to reduce HIV transmission and improve quality of life [Rotheram-Borus et al. (2001)]. Respondents (175, interviewed between 2 and 5 times for 816 total observations) report the number of unique sex partners they had during the previous three months. Figure 6 summarizes the reported counts. There are several striking features of the reported counts: (1) a fair proportion (27%) of the counts are zero; (2) the histogram shows peaks at integer multiples of 10; and (3) a few counts are very large.

We let \mathbf{W}_{it} in (11) be an 8×1 vector of covariates for subject i at time t by including subject baseline age, gender (1 for male, 0 for female), an indicator for men who have sex with men (MSM), an indicator for injection drug use, time since baseline interview, an indicator for post-baseline educational intervention and an indicator for use of methamphetamine or other stimulant drugs. Time since baseline interview, use of drugs and post-baseline intervention, depend on the time-point t . To facilitate comparison of estimated effects, subject age and time since baseline interview were standardized by subtracting the mean and dividing by the standard deviation. We let $\mathbf{Z}_{it} = 1$, making β_i a scalar; this provides a subject-specific random intercept. We fit two subject-specific heaping models. In the first, we let $\mathbf{H}_i = 1$ so that $\theta_{\text{heap},i}$ is a subject-specific random intercept. In the second, $\mathbf{H}_i = (1, \text{gender})$. Based on the histogram of aggregate counts in Figure 6, we use the BDP rate model in equation (7) with $J = 3$ regimes corresponding to heaping at grid points at multiples of 5, 10 or 50.

We assign hyperparameters as follows: for the fixed effects α , $\alpha_0 = \mathbf{0}$ and $\Sigma_\alpha = 10\mathbf{I}$ where \mathbf{I} is the identity matrix; for the heaping parameters θ , $a = 0.001$ and $b = 0.001$, such that each has a prior expectation of 1 and variance 1000; for γ , $\sigma_\gamma^2 = 100$. Since the subject-specific random effects β_i are scalars, β_i has inverse gamma distribution with parameters $A_\beta = 4$ and $\mathbf{m}_\beta = 5$.

5.1. Results. To evaluate the usefulness of our heaping distributions and to compare to previous approaches, we fit six hierarchical Bayesian models: (1) Pois-

son mixed effects (PME) with $X_{it} = Y_{it}$ and no heaping; (2) the model of Wang and Heitjan (2008) (WH08) as defined by (18); (3) BDP with dispersion and no heaping; (4) BDP model with dispersion and global heaping parameter θ_{heap} ; (5) BDP model with subject-specific heaping intensity; and (6) BDP model with subject-specific heaping intensity and a fixed effect controlling heaping propensity for male and female subjects. In each case, the model for the underlying true count is identical to (10)–(12). The priors on equivalent parameters are also the same for all models.

Table 2 shows posterior summaries for each model. The first eight rows are regression coefficients for the fixed effects α . Estimates of fixed effects in the WH08 model are similar to those found in the PME model without heaping. In general, fixed effects estimates all have larger variance in the heaping models because the BDP reporting distribution induces over-dispersion. Use of stimulants is positively associated with increased true count. While the intervention is not significantly associated with decreased reported counts in the model without heaping and in the Wang and Heitjan (2008) model, the intervention has a clear association with reduced true counts in the BDP heaping models. This result suggests that heaping in reported counts may obscure important associations between covariates and count outcomes. Figure 7 plots the posterior distribution of true counts X_{it} versus their corresponding reported values Y_{it} . The points are slightly jittered to show the density of samples. The gray dashed line traces $X_{it} = Y_{it}$. Larger reported counts often correspond to smaller estimated true counts, possibly because the same subjects also reported very low counts at other timepoints.

Estimates of θ_{disp} are similar for all BDP models with heaping, suggesting that dispersion or misremembering carries information that is distinct from heaping or rounding in the data. The regime parameters $\gamma_0, \dots, \gamma_3$ are similar for all the BDP heaping models, but likely not comparable to the WH08 model, as the heaping mechanism is different. Estimates of the regime parameters can be interpreted by transforming them into their regime transition midpoints $-(\gamma_1, \gamma_2, \gamma_3)/\gamma_0$. For example, the posterior mean estimates for the “heaping” model indicate that the “no heaping” regime dominates when the true count is between 0 and $-\gamma_1/\gamma_0 = 10.7$ (posterior mean), and heaping to multiples of 50 dominates when the true count is greater than $-\gamma_3/\gamma_0 = 16.2$. Between these values, heaping to multiples of 5 or 10 dominates. Estimates of $\gamma_1, \gamma_2, \gamma_3$ exhibit fairly large posterior variance, and posterior intervals for γ_1 and γ_2 show substantial overlap. This indicates that there is not strong evidence of heaping to multiples of 5 and 10 in the data; rather, small counts exhibit little heaping, and large counts show strong heaping to multiples of 50.

We find that there is no significant difference in heaping by gender under our model: the gender-specific effect ω in the last model is not significantly different from zero. This finding is in contrast to those of other researchers who see a strong effect of gender on reporting of sexual behaviors [Wiederman (1997)]. One of the

TABLE 2

Parameter estimates, intervals, and goodness-of-fit measures of the CLEAR data. We fit six models, each using the basic Bayesian Poisson regression setup (10) for the true counts. In the model without heaping, the reported counts are assumed to be equal to true counts. In the dispersion-only model, the BDP allows misremembering but not heaping. The Wang and Heitjan (2008) model involves deterministic heaping under different regimes (18). The BDP heaping model has global dispersion and heaping parameters, the subject-specific BDP heaping model allows subject-specific effects (15), and the subject-specific model with covariates includes a fixed effect for the influence of gender on heaping behavior. Parameter estimates (posterior means) and 95% posterior quantiles are shown for each parameter. The fixed effects are age, gender, men who have sex with men (MSM), injection drug user, intervention, stimulant use and trading sex. The random intercept variance σ_{β}^2 is also shown. The heaping parameters θ_{disp} and θ_{heap} control dispersion and heaping for the BDP models. The heaping regime parameters $\gamma_0, \gamma_1, \gamma_2$ and γ_3 are shown for the heaping models. The heaping random intercept variance σ_{ξ}^2 and the gender-specific heaping fixed effect ω are also shown. Finally, we provide two measures of goodness of fit for each model: deviance information criterion (DIC) and the sum of squared mean prediction errors, and the sum of squared prediction errors (SSPE)

	No heaping		WH08		Dispersion-only		Heaping		Subject-specific heaping		Subject-specific heaping + gender	
Age	-0.11	(-0.27, 0.08)	-0.07	(-0.25, 0.1)	-0.15	(-0.56, 0.25)	-0.20	(-0.58, 0.14)	-0.12	(-0.55, 0.23)	-0.14	(-0.43, 0.22)
Male	-0.26	(-0.78, 0.25)	-0.24	(-0.74, 0.28)	-1.48	(-2.77, -0.27)	-0.85	(-1.81, 0.12)	-1.01	(-2.16, -0.01)	-0.98	(-2.05, -0.02)
MSM	0.82	(0.33, 1.32)	0.81	(0.3, 1.32)	0.57	(-0.59, 1.75)	0.89	(-0.06, 1.85)	0.99	(0.03, 1.99)	0.92	(-0.06, 1.95)
Inject	-0.37	(-0.88, 0.11)	-0.29	(-0.72, 0.18)	-0.38	(-1.45, 0.65)	-0.29	(-1.2, 0.56)	-0.35	(-1.3, 0.55)	-0.38	(-1.54, 0.44)
Time	-0.89	(-1.06, -0.72)	-0.85	(-1.03, -0.66)	-1.72	(-2.27, -1.18)	-1.02	(-1.46, -0.6)	-1.09	(-1.51, -0.67)	-1.06	(-1.5, -0.61)
Intv	-0.24	(-0.57, 0.05)	-0.18	(-0.5, 0.1)	-1.29	(-2.05, -0.6)	-1.07	(-1.76, -0.45)	-1.09	(-1.85, -0.32)	-1.16	(-2.06, -0.47)
Stim	1.00	(0.88, 1.12)	0.97	(0.84, 1.1)	1.51	(1.14, 1.88)	1.09	(0.82, 1.39)	1.15	(0.83, 1.47)	1.05	(0.77, 1.36)
Trade	1.32	(1.2, 1.45)	1.21	(1.08, 1.35)	2.49	(1.98, 3)	1.81	(1.41, 2.21)	1.79	(1.44, 2.15)	2.00	(1.65, 2.34)
σ_{β}^2	1.15	(0.88, 1.48)	1.07	(0.82, 1.36)	3.63	(2.2, 5.66)	2.77	(1.75, 4.47)	2.93	(1.79, 4.81)	2.93	(1.93, 4.45)
θ_{disp}					1.57	(1.4, 1.75)	1.04	(0.86, 1.22)	1.08	(0.9, 1.27)	1.06	(0.91, 1.24)
θ_{heap}							0.82	(0.59, 1.12)				
γ_0			0.07	(0.05, 0.11)			0.42	(0.26, 0.84)	0.29	(0.21, 0.4)	0.45	(0.28, 0.79)
γ_1			-2.37	(-2.86, -1.95)			-4.51	(-6.09, -3.46)	-4.66	(-5.78, -3.68)	-5.50	(-8.43, -4.16)
γ_2			-2.90	(-3.47, -2.42)			-5.44	(-8.75, -3.95)	-5.40	(-6.87, -4.21)	-7.23	(-10.11, -5)
γ_3			-4.07	(-4.9, -3.39)			-6.81	(-12.47, -4.75)	-6.22	(-7.68, -5.1)	-8.40	(-11.55, -6.36)
σ_{ξ}^2									0.74	(0.61, 0.98)	0.94	(0.87, 1)
ω											-0.03	(-0.69, 0.54)
DIC		4585		524		3329		3214		3195		3175
SSPE		47,773		55,078		28,005		25,371		25,336		24,364

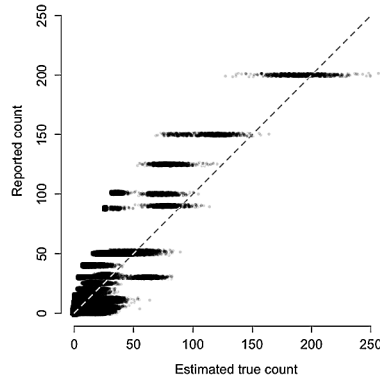


FIG. 7. Posterior samples of true counts on the horizontal axis versus reported counts on the vertical axis for the CLEAR data under the BDP heaping model. The points have been slightly jittered to show the density of posterior samples. A gray dashed line is shown on the diagonal.

goals of the CLEAR study was to show that educational intervention for HIV-positive youth could reduce risky behaviors. While heaping behavior may differ with respect to gender among subjects in the CLEAR study, the small number of reported counts per subject does not permit us to detect such a difference under the BDP heaping model. The intervention tended to reduce true counts, and $\Pr(\alpha_{\text{intv}} < 0) > 0.95$ for every model.

We report two goodness-of-fit measures. The first is deviance information criterion (DIC), computed by conditioning on posterior samples of the parameters that directly affect the outcome Y_{it} . For the “no heaping” model, these parameters are α and β ; for the WH08 model, the X_{it} ’s and γ ; for the “dispersion-only” model, the X_{it} ’s and θ_{disp} ; for the “heaping” model, the X_{it} ’s, θ_{disp} , θ_{heap} and γ ; for the “subject-specific heaping” model, the X_{it} ’s, θ_{disp} , γ and σ_{ξ}^2 ; and for the “subject-specific heaping + gender” model, the X_{it} ’s, θ_{disp} , γ , σ_{ξ}^2 and ω . The second goodness-of-fit measure is the sum of squared mean prediction errors, $\text{SSPE} = \sum_{i=1}^n \sum_{t=1}^{n_i} (Y_{it} - \hat{Y}_{it})^2$, where \hat{Y}_{it} is the mean posterior predictive value of Y_{it} , calculated by conditioning on the same parameters as used to calculate the DIC. The Wang and Heitjan (2008) model is unique because $Y_{it}|X_{it}$ depends only on the four rounding regimes parameters γ , so the DIC is low, and the heaping models all show similar DIC. The SSPE tells a different story: the dispersion-only model shows the worst fit, and the BDP heaping models outperform the WH08 model. These goodness-of-fit measures should be interpreted carefully since the WH08 and BDP heaping models have a somewhat different structure.

The proportional odds model for different heaping regimes (rounding to 5, 10 and 50) introduced by WH08 proves to be an essential ingredient in our analysis. The apparent heaping pattern observed in the CLEAR counts of sex partners suggests that heaping to multiples of 50 happens often as counts become larger than 30 or 40. We find that heaping models that required rounding to multiples

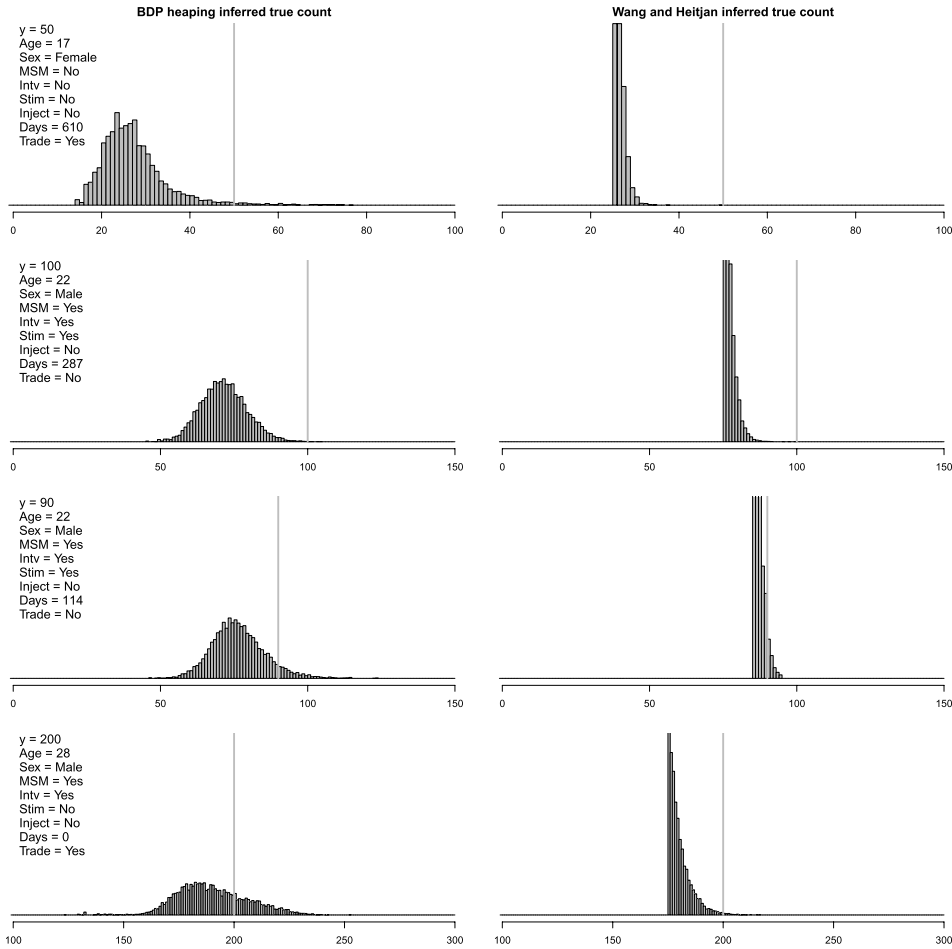


FIG. 8. Marginal posterior distributions of true counts X_{it} for individual subjects under the BDP heaping model with subject-specific heaping parameters and the model of Wang and Heitjan (2008). The subject- and timepoint-specific covariate values are listed with each plot. A gray vertical line denotes the reported count $Y_{it} = y$. Not all inferred true count distributions are centered at the reported count. Moreover, the inferred true counts become more dispersed as the reported count increases. The Wang and Heitjan (2008) model does not allow responses beyond the nearest heaping point and effectively puts a uniform prior distribution on responses that fall within this window. This results in inferred true counts whose posterior distribution is a truncated version of the predictive distribution of X_{it} .

of 5, even for large counts, provide a very poor fit (results not shown). However, in our analyses, the model of WH08 has a serious drawback: when only one heaping regime is in effect, it places a nearly uniform distribution on the true count. The inferred true count distribution is proportional to the product of this uniform distribution and the posterior predictive distribution of the true count. Figure 8 il-

illustrates the problem for specific subjects. Both the WH08 model and the subject-specific BDP heaping model have similar predictive distributions $f(x|\alpha, \beta)$ for the latent true count x , and in both cases only the v_3 regime (rounding to the nearest multiple of 50) is in effect. But the rounding model of WH08 assumes that rounding is always to the *nearest* grid point, so, for example, a reported value of $y = 200$ means that $x \in \{175, \dots, 225\}$ with probability one. The heaping distribution $g(y = 200|x, \theta, \gamma)$ implicitly places a nearly uniform distribution on this set, so the inferred posterior distribution of the true count x is a truncated version of $f(x|\alpha, \beta)$. In contrast, the BDP heaping model provides a reporting distribution $g(y = 200|x, \gamma, \theta)$ that has support on all of \mathbb{N} and preferentially places more mass on those x that are most likely to deliver the reported count y . In settings where the true counts themselves might be the objects of inference, we believe the BDP heaping model provides more realistic and useful estimates.

6. Discussion. In this paper we have illustrated how researchers can infer the posterior distribution of true integer counts from reported counts using a general BDP reporting distribution within a hierarchical modeling framework. Our most substantial innovation is the novel reporting distribution $g(y|x, \theta)$ based on the BDP with specially defined jumping rates that make the Markov chain attracted to heaping grid points. Use of simple linear BDPs to model over-dispersion or reporting error has been proposed before [Grunwald et al. (2011), Lee, Weiss and Suchard (2014)]. However, we have substantially expanded the possibilities for general birth–death models of reporting error to explicitly incorporate both over-dispersion and heaping, while providing a computational method to evaluate likelihoods and sample from the posterior distribution of the true counts. This approach has the benefit of providing a sophisticated and highly configurable family of reporting distributions indexed by the true count and just a few unknown parameters θ and γ .

Statisticians may understandably be wary of parametric assumptions about the way study participants report data. However, applied and methodological research in public health offers some clues into reporting mechanisms. Researchers in this field often address the problem of reporting error in surveys related to sexuality and other taboo topics [Schaeffer (1999)]. Wang and Heitjan (2008) discuss validation of reported counts of cigarettes smoked by measuring tobacco products in the blood. In related work, Wang et al. (2012) compare instantaneous and retrospective self-reports of cigarette consumption under a similar model for heaping. Other survey methods are possible, including using diary-like surveys or repeated questionnaires to assess reporting error. Studies like these can provide useful information about the parameters θ and γ in our BDP heaping model. Armed with prior information about rounding propensities, perhaps stratified by personal attributes such as gender, age or sexual orientation, public health researchers could proceed with a Bayesian analysis similar to the one outlined in this paper to jointly estimate

true counts and regression parameters. Designing a model that accommodates various assumptions about both the mechanism generating the true counts and the cognitive processes that give rise to the reported counts can be challenging. The BDP model for heaped counts presented in this paper is one promising step in this direction.

APPENDIX A: NUMERICAL EVALUATION OF REPORTING PROBABILITIES

We efficiently find the transition probabilities $P_{ab}(t)$ by first applying the Laplace transform to both sides of the forward equations [Karlin and McGregor (1957), Murphy and O’Donohoe (1975)]. This turns the infinite system of differential equations (2) into a recurrence relation whose solution yields an expression for the Laplace transform of the transition probability $P_{ab}(t)$. To illustrate, let the Laplace transform $h_{ab}(s)$ of the transition probability $P_{ab}(t)$ be

$$(21) \quad h_{ab}(s) = \int_0^\infty e^{-st} P_{ab}(t) dt.$$

Then differentiating $h_{ab}(s)$ with respect to t and setting $a = b = 0$, (2) becomes

$$(22) \quad \begin{aligned} sh_{00}(s) - P_{00}(0) &= \mu_1 h_{01}(s) - \lambda_0 h_{00}(s) \quad \text{and} \\ sh_{0b}(s) - P_{0,b}(0) &= \lambda_{b-1} h_{0,b-1}(s) + \mu_{b+1} h_{0,b+1}(s) - (\lambda_b + \mu_b) h_{0b}(s) \end{aligned}$$

for $b \geq 1$. Rearranging (22), we find the recurrence

$$(23) \quad \begin{aligned} h_{00}(s) &= \frac{1}{s + \lambda_0 - \mu_1(h_{01}(s)/h_{00}(s))} \quad \text{and} \\ \frac{h_{0b}(s)}{h_{0,b-1}(s)} &= \frac{\lambda_{b-1}}{s + \mu_b + \lambda_b - \mu_{b+1}(h_{0,b+1}(s)/h_{0,b}(s))}. \end{aligned}$$

From this recurrence, we arrive at the well-known continued fraction representation for $h_{00}(s)$,

$$(24) \quad h_{00}(s) = \frac{1}{s + \lambda_0 - \lambda_0 \mu_1 / (s + \lambda_1 + \mu_1 - \lambda_1 \mu_2 / (s + \lambda_2 + \mu_2 - \dots))}$$

[see Crawford and Suchard (2012), Murphy and O’Donohoe (1975) for further details]. This is the Laplace transform of the transition probability $P_{00}(t)$. From (24), we can derive similar continued fraction representations for $h_{ab}(s)$ for any $U(0) = a$ and $U(t) = b$. These expressions are given in the supplemental material [Crawford, Weiss and Suchard (2015)]. Crawford and Suchard (2012) present a numerical method for inverting transforms (24) to compute the transition probabilities in any general BDP with arbitrary jumping rates $\{\lambda_k\}_{k=0}^\infty$ and $\{\mu_k\}_{k=1}^\infty$. The supplementary material of Crawford, Minin and Suchard (2014) shows how numerical error is controlled in the computation. Section B of this appendix gives an approximation to the reporting distribution that is useful for sampling.

APPENDIX B: APPROXIMATION OF REPORTING PROBABILITIES

In this appendix we derive an approximation to the conditional distribution of the reported count given the true count, $Y_{it}|X_{it}$. The full conditional distribution of the i th subject’s true count X_{it} at timepoint j is

$$\begin{aligned}
 & \Pr(X_{it} = x|Y_{it}, \mathbf{Z}_i, \mathbf{W}_{it}, \boldsymbol{\alpha}, \boldsymbol{\beta}_i, \boldsymbol{\theta}) \\
 & \quad \propto \Pr(Y_{it}|X_{it} = x, \boldsymbol{\theta}) \Pr(X_{it} = x|\mathbf{W}_{it}, \mathbf{Z}_i, \boldsymbol{\alpha}, \boldsymbol{\beta}_i) \\
 (25) \quad & = P_{x, Y_{it}}(\boldsymbol{\theta}) \frac{\eta_{it}^x e^{-\eta_{it}}}{x!} \\
 & = g(y|x, \boldsymbol{\theta}) f(x|\eta_{it}),
 \end{aligned}$$

where $\eta_{it} = \exp(\mathbf{W}_{it}\boldsymbol{\alpha} + \mathbf{Z}_{it}\boldsymbol{\beta}_i)$ and $P_{xy}(\boldsymbol{\theta}) = g(y|x, \boldsymbol{\theta})$ is the general BDP transition probability under the model described in Section 2.2. Under a Metropolis–Hastings scheme, we need to propose a new value of X_{it} efficiently; we approximate the density $P_{xy}(\boldsymbol{\theta})$ as normal. Let $\theta_{\text{heap}} = 0$ and $\theta_{\text{disp}} > 0$. Then this simplified BDP has birth and death rates

$$(26) \quad \lambda_k = \theta_{\text{disp}} + \theta_{\text{disp}}k \quad \text{and} \quad \mu_k = \theta_{\text{disp}}k.$$

This is a linear process with immigration that has an asymptotically normal distribution. Similar to Section 2.1, let $U(t)$ be a BDP starting at $U(0) = a$. Following Lange (2010), we form the probability generating function (PGF)

$$(27) \quad H(s, t) = \sum_{b=0}^{\infty} s^b P_{ab}(t),$$

where s is a “dummy” variable and $P_{ab}(t) = \Pr(U(t) = b|U(0) = a)$ is the transition probability. Although $H(s, t)$ has a closed-form solution that can be inverted to obtain the $P_{ab}(t)$ in analytic form, the details are somewhat complicated, and we only require a normal approximation to this density. The mean $m_a(t) = \mathbb{E}(U(t)|U(0) = a)$ is given by

$$(28) \quad \left. \frac{\partial H(s, t)}{\partial s} \right|_{s=1} = \sum_{b=0}^{\infty} b P_{ab}(t) = \mathbb{E}[U(t)] = m_a(t),$$

and likewise the second factorial moment $e_a(t)$ is given by

$$(29) \quad \left. \frac{\partial^2 H(s, t)}{\partial s^2} \right|_{s=1} = \sum_{b=1}^{\infty} b(b-1) P_{ab}(t) = \mathbb{E}[U(t)^2] - \mathbb{E}[U(t)] = e_a(t),$$

where the expectations are conditional on the process beginning in state $U(0) = a$. This suggests that we can determine the mean and variance of $U(t)|\{U(0) = a\}$ by finding the partial derivatives of H with respect to the dummy variable s . To

derive these quantities, we form a partial differential equation for the solution of the PGF

$$(30) \quad \frac{\partial H(s, t)}{\partial t} = \theta_{\text{disp}} \left[(s - 1)^2 \frac{\partial H(s, t)}{\partial s} + (s - 1)H(s, t) \right].$$

See Lange (2010), Bailey (1964) and Renshaw (2011) for the details of deriving this generating function. Now, the time-derivative of the mean falls out as

$$(31) \quad \frac{dm_a(t)}{dt} = \left. \frac{\partial^2 H(s, t)}{\partial t \partial s} \right|_{s=1} = \theta_{\text{disp}},$$

and the time-derivative of the second factorial moment is

$$(32) \quad \frac{de_a(t)}{dt} = \left. \frac{\partial^3 H(s, t)}{\partial t \partial^2 s} \right|_{s=1} = 4\theta_{\text{disp}}(a + \theta_{\text{disp}}t).$$

Solving these differential equations with the initial conditions $m_a(0) = a$ and $e_i(0) = a^2 - a$ yields

$$(33) \quad m_a(t) = a + \theta_{\text{disp}}t \quad \text{and} \quad e_a(t) = a(a - 1) + 4a\theta_{\text{disp}}t + 2\theta_{\text{disp}}^2t^2.$$

From these, we determine that

$$(34) \quad \begin{aligned} \mathbb{E}[U(t)|U(0) = a] &= a + \theta_{\text{disp}}t \quad \text{and} \\ \text{Var}[U(t)|U(0) = a] &= (2a + 1)\theta_{\text{disp}}t + \theta_{\text{disp}}^2t^2, \end{aligned}$$

where the second line arises because $\text{Var}[U(t)|U(0) = i] = e_a(t) + m_a(t) - m_a(t)^2$. Therefore, a reasonable approximation to the probability mass function of $U(t)|\{U(0) = a\}$ is the normal distribution with the mean and variance above. This approximation serves as an effective proposal within a Metropolis–Hastings accept/reject step.

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SUPPLEMENTARY MATERIAL

Supplemental article (DOI: [10.1214/15-AOAS809SUPP](https://doi.org/10.1214/15-AOAS809SUPP); .pdf). We provide a derivation of the Laplace transform of transition probabilities for a general BDP, the full posterior distribution and an outline of Monte Carlo sampling procedures for unknown parameters.

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