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The reliability of statistical functions in four software packages freely used in numerical computation

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Abstract. This work presents a comparison of results about the accuracy of statistical routines from four statistical software packages that are freely used: Octave, academic Ox, Python, and R. Having extensive functional libraries for statistical computing with applications in image processing, these software packages are useful for data analysis and visualization. The National Institute of Standards and Technology datasets and McCullough's methodology are used for assessing these packages. As to the statistical analysis herein performed, R yielded the best results and had the most comprehensive library.

1 Introduction

Estimators with good properties are only half the way to the practice of good data analysis. They need to be implemented with care in order to provide dependable results on a variety of situations. This requirement is valid even for simple estimators as, for example, measures of the mean, standard deviation, and autocorrelation coefficient.

These estimators may be used in principal component analysis (PCA) or in computing statistical distances (Fukunaga (1990)). They are also commonly employed in texture extraction, image segmentation, and image classification. Autocorrelation functions and histogram features are some examples of the measures used to classify textures.

The importance of accuracy in statistical packages can be observed in ecosystem monitoring software, which uses remote sensing imagery to assess the impact of global changes on land surface attributes. Most of these changes are digitally detected using satellite images that determine the type and extent of the damage to the environment (Coppin et al. (2004)). Satellite imagery is more efficient than visual determination since, among other reasons, the visual assessment of changes is difficult to replicate: different interpreters usually produce different results. Furthermore, visual detection is costly. Differently, digital methods can incorporate features from the nonoptical parts of the electromagnetic spectrum.

Change detection methods pose some challenges, such as detecting modifications, monitoring rapid or abrupt changes, and understanding and correcting statistical estimates derived from remote sensing data at different spatial resolutions.

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These challenges require accurate software in order to obtain good and reliable results. There is a wide variety of change detection algorithms for ecosystem monitoring. They usually combine procedures for change extraction (change detection algorithms) and change classification routines. Algorithms applied to change detection are based on methods that use per-pixel classifiers and pixel-based change information contained in the domains of the images so as to pinpoint changes between images.

Coppin et al. (2004) present a survey comparing algorithms for change detection and highlight the need for accurate software. Some have suggested reducing scene-dependent effects and using band-to-band normalization before differentiating data in order to yield bands with comparable means and standard deviations. Other algorithm proposals use linear data transformation techniques based on PCA. Most of the proposals in Coppin et al. (2004) suggest taking into account the accuracy of statistical measures used to produce the results.

In view of the importance of accuracy in any quantitative research, such as in image processing and remote sensing, this sort of analysis is crucial.

In order to measure the accuracy of statistical functions, McCullough (1998) and Knüsel (1989, 1998) developed the first thorough studies in this field. Their work has lent support to several other studies aimed at finding accuracy errors in statistical computation and proposing guidelines for the selection of reliable statistical software (see, for instance, McCullough and Wilson (1999); McCullough (2000); Altman (2002); McCullough and Wilson (2002); McCullough and Wilson (2005); Bustos and Frery (2006); Keeling and Pavur (2007); Yalta and Yalta (2007); Yalta (2007)). All of these authors illustrate the need for improved accuracy and pinpoint situations in which packages failed.

Recent works by McCullough and Heiser (2008) and Yalta (2008) conduct accuracy tests in Microsoft Excel 2007. They show that Excel 2007 keeps failing to give good answers and advises that each new version must be tested since Microsoft did not correct the errors of older tested versions (McCullough and Wilson (1999, 2002, 2005)).

We analyzed the numeric quality of four well-known software packages that can be freely used. These software packages are Octave (version 2.9.12), Ox (free academic version 4.10a), Python (version 2.5.2), and R (version 2.6.2). This approach differs from previous studies in that it shows the results of assessing the accuracy of statistical routines in four packages widely used for numerical computation and that are compatible with most operating systems (Windows, Unix-like, and Macintosh). Some older versions have already been tested for accuracy. We used the latest stable versions available for each package.

In order to assess the reliability of the packages, McCulloughs' procedures were employed in three kinds of tests: linear and nonlinear models, random number generation, and statistical distributions. It must be emphasized that only predefined routines were considered when determining the statistical measures: mean, standard deviation, autocorrelation coefficient, ANOVA, and linear and nonlinear

regressions. We did not implement any routine to certify the fidelity of the platform analysis.

Octave (www.octave.org) is an interpreted programming language. It is available as Free Software under the terms of the Free Software Foundation's GNU General Public License in source code. It provides a command line interface for performing numerical experiments. It has extensive tools for solving common numerical linear algebra problems, finding the roots of nonlinear equations, integrating ordinary functions, manipulating polynomials, and integrating ordinary differential and differential-algebraic equations. It is easily extensible and customizable via user-defined functions written in Octave's own language, or using dynamically loaded modules written in other languages like C++, C, and Fortran.

Ox (www.doornik.com) is an object-oriented language. It is considered a powerful matrix platform and includes a library containing comprehensive mathematical and statistical functions. Some of its best features are high performance, well-designed syntax, and graphical facilities. Ox syntax is very similar to C, C++, and Java. It can be used as a front end for languages such as C and C++. Most versions are free for educational purposes and academic research.

Python (www.python.org) is a remarkably dynamic programming language. It can be used in numerical work, statistical computing, and visualization. It has an open source license by the Python Software Foundation. It can be freely used and distributed, even for commercial purposes. Python's syntax is clear, with an indented structure and an interface with languages such as C and C++. The code can interact with R functions, allowing data to be manipulated using its tools.

R (www.r-project.org) is a well-known environment for statistical computing and graphics. Like Octave, it is also available as Free Software under the terms of the Free Software Foundation's GNU General Public License in source code. A wide variety of statistical and graphical functions are provided by this platform, including storage facilities and a suite of operators on arrays functions, especially on matrices. It has its own programming language. R can call C, C++, and Fortran code at runtime.

The next section presents the methodology adopted for the purpose of this paper. Section 3 brings the main results, as follows: Section 3.1 presents the results on univariate summary statistics, while Sections 3.2 and 3.3 discuss the results on analysis of variance and regression, respectively. The quantiles for tail probabilities of the Gaussian, χ^2 , F, and t-student distributions are analyzed in Section 3.4. Section 3.5 briefly discusses the pseudorandom number generators and their algorithms. Finally, Section 4 discusses the results and lays down some general remarks.

2 Methodology

In order to assess the reliability of each software, we have followed the methodology suggested by McCullough (1998, 2000) and by McCullough and Wilson

(1999, 2002). The Statistical Reference Data sets (StRD) used were provided by the National Institute of Standards and Technology (NIST (2000)). Each dataset includes either generated or "real world" data and certified (correct) values of mean, standard deviation, first lag correlation, etc. These datasets are classified in three levels of difficulty denoted in the tables by 'L' (low), 'A' (average), and 'H' (high).

The statistical measures of interest are the mean, the standard deviation, the coefficient of autocorrelation (first lag), and the ANOVA *F*-statistic. Additionally, linear regression, nonlinear least squares regression, and the quantiles for the tail probabilities of frequently used distributions are computed. When performing regression on multiple variables several coefficients are estimated. We adopt the metodology employed by McCullough and Wilson (1999) and by Bustos and Frery (2006), which consists of a pessimistic assessment based on the worst estimated parameter. The pseudorandom number generators are also discussed.

For the univariate summary statistics, NIST provides real world data: Lew, Lottery, Mavro, and Michelso. They differ from each other in the number of observations and in their range. Lew has 200 integer observations ranging from -579 to 300, Lottery 218 integer observations ranging from 4 to 999, Mavro 50 observations with five leading digits ranging from 2.00130 to 2.00270, and Michelso 100 observations ranging from 299.620 to 300.070.

Generated data for univariate summary statistics are NumAcc1, NumAcc2, NumAcc3, NumAcc4, and PiDigits. The dataset NumAcc1 has only the values 10000001, 10000003, and 10000002. In NumAcc2 there are 1001 observations arranged as follows: the value 1.2, 500 occurrences of the value 1.1 alternating with 500 occurrences of the value 1.3. In NumAcc3 there is one value 1000000.2, 500 occurrences of the value 1000000.1 alternating with 500 occurrences of the value 1000000.3. NumAcc4 has the value 10000000.2, 500 occurrences of the value 10000000.1 alternating with 500 occurrences of the value 10000000.3. Finally, dataset PiDigits is made up of the first 5000 digits of the number π .

To assess the accuracy of ANOVA (*F*-statistic) calculations, NIST provides eleven datasets, nine generated and two observed ("real world" data) ordered by level of difficulty (Low, Average, and High). NIST also provides several datasets to evaluate linear and nonlinear regression functions that have been used in each package. For linear regression, the datasets differ from each other in the convergence level of difficulty (Low, Average, and High) and in the class of the model (3 linear, 1 quadratic, 6 polynomial, and 1 multilinear). Similarly, there are datasets with different convergence levels of difficulty and different classes of models (16 exponential, 7 miscellaneous, and 4 rational) to evaluate nonlinear regression. Tables 4, 5, and 6 show the results for ANOVA, linear regression, and nonlinear regression, respectively.

The datasets for nonlinear least squares evaluation have two sets of starting values in addition to the certified solution: start 1, far from the certified solution, making the problem more difficult to solve, and start 2, near to the certified solution, making the problem easier to solve. Only start 1 values were used to arrive

at the solution, since these values represent the worst case. Following McCullough and Wilson (1999), the start 2 set is used only when start 1 does not converge to an approximate solution.

Several statistical tests, such as hypothesis testing, need exact values of the tail probabilities and quantiles of cumulative distribution functions, the Gaussian, F, χ^2 , and t-student laws among them. As the significance level decreases, the critical region is reduced. This can lead to numerical difficulties in obtaining the quantiles (p-values) and the equivalent tail probabilities. These numbers are usually obtained through routines which compute the quantile functions of the above laws. The ELV program (Knüsel (1989)) computes probabilities and quantiles for cumulative distribution functions, among others. It provides certified values that can be used to assess the accuracy of the routines computed by each package analyzed herein. Six significant digits are used to compute tail probabilities at 2.10^{-7} .

It is suggested in McCullough (1998) that *LRE* (base-10 logarithm of the relative error) and *LAR* (base-10 logarithm of the absolute error) be computed so as to assess the accuracy of the functions. *LRE* indicates the number of significant digits that match when one compares certified values to those obtained for each evaluated function.

Let x be the result of evaluation function and c the correspondent certified value. LRE, when $c \neq 0$, is given by

$$LRE(x, c) = -\log_{10}\left(\frac{|x - c|}{|c|}\right).$$

The notation "NA", which appears in some tables, indicates that the function did not return any numeric value. When the certified value is zero, we apply the *LAR* function defined as

$$LAR(x) = -\log_{10}|x|.$$

For expositional ease, as in McCullough's works, no distinction will be made between *LRE* and *LAR*, referring to both or either as *LRE*, since *LRE* and *LAR* values are comparable.

Although the results of LRE usually yield a real number, only its integer part is considered to indicate the number of matching digits. LRE = 0 means that no correct digit was found. The symbol "–" was employed to indicate that the result is very far from the certified value and that LRE function cannot be used.

All the tests were implemented on the same hardware platform: an i386 computer with a 32-bit processor running the GNU/Linux Ubuntu 7.10 (Kernel 2.6.22-14-generic) operating system was used to perform the calculations.

3 Results

The following subsections show the results obtained in this study. One should notice that, except for univariate analysis, some tables do not contain all the software

evaluation. This is due to the absence of such a function in the official site of the software. The best function results for each table are highlighted using boldface font.

3.1 Univariate summary statistics

Tables 1, 2, and 3 present the *LREs* for the univariate summary statistics. The accuracy results for the mean can be seen in Table 1, and it is noticeable that the packages provide excellent accuracy for computed mean functions. The functions that compute the mean are all termed "mean" and in Python it is provided by the stats library of scipy package.

For standard deviation accuracy, as shown in Table 2, Ox presented poor behavior as opposed to the other ones which yielded very good results. This could mean that for the second-order or higher moments, the Ox function moments used to compute standard deviation was not accurate. Octave, Python, and R provide the functions std, stdev (from scipy.stats library), and sd (from stats package), respectively.

| Table 1 | LREs | for | comp | outed | mean |
|---------|------|-----|------|-------|------|
|---------|------|-----|------|-------|------|

| Dataset | Octave | Ox | Python | R |
|--------------|--------|----|--------|----|
| Lew (L) | 15 | 15 | 15 | 15 |
| Lottery (L) | 15 | 15 | 15 | 15 |
| Mavro (L) | 15 | 15 | 15 | 15 |
| Michelso (L) | 15 | 15 | 15 | 15 |
| NumAcc1 (L) | 15 | 15 | 15 | 15 |
| PiDigits (L) | 15 | 15 | 15 | 15 |
| NumAcc2 (A) | 15 | 15 | 14 | 15 |
| NumAcc3 (A) | 15 | 15 | 15 | 15 |
| NumAcc4 (H) | 14 | 15 | 14 | 15 |
| | | | | |

 Table 2
 LREs for computed standard deviation

| Dataset | Octave | Ox | Python | R |
|--------------|--------|----|--------|----|
| Lew (L) | 15 | 2 | 15 | 15 |
| Lottery (L) | 15 | 2 | 15 | 15 |
| Mavro (L) | 15 | 1 | 13 | 15 |
| Michelso (L) | 15 | 2 | 13 | 15 |
| NumAcc1 (L) | 15 | 0 | 15 | 15 |
| PiDigits (L) | 14 | 4 | 14 | 15 |
| NumAcc2 (A) | 15 | 3 | 14 | 15 |
| NumAcc3 (A) | 9 | 3 | 9 | 15 |
| NumAcc4 (H) | 8 | 3 | 8 | 15 |

| Table 3 | LREs for | computed | auto correlation | coeffi- |
|---------|----------|----------|------------------|---------|
| cient | | | | |

| Dataset | Octave | Ox | Python | R |
|--------------|--------|----|--------|----|
| Lew (L) | 5 | 14 | 2 | 15 |
| Lottery (L) | 4 | 14 | 2 | 15 |
| Mavro (L) | 4 | 13 | 1 | 13 |
| Michelso (L) | 8 | 13 | 3 | 13 |
| NumAcc1 (L) | 0 | 15 | _ | 15 |
| PiDigits (L) | 3 | 15 | 3 | 13 |
| NumAcc2 (A) | 7 | 15 | 3 | 14 |
| NumAcc3 (A) | 3 | 12 | _ | 14 |
| NumAcc4 (H) | 3 | 11 | 2 | 14 |

 Table 4
 ANOVA: F-statistic

| Dataset | Octave | Python | R |
|-------------|--------|--------|----|
| SiRstv (L) | 12 | 8 | 13 |
| SmLs01 (L) | 14 | 13 | 15 |
| SmLs02 (L) | 13 | 11 | 15 |
| SmLs03 (L) | 12 | 11 | 15 |
| AtmWtAg (A) | 8 | 0 | 9 |
| SmLs04 (A) | 8 | 0 | 10 |
| SmLs05 (A) | 8 | _ | 10 |
| SmLs06 (A) | 6 | _ | 10 |
| SmLs07 (H) | 2 | _ | 4 |
| SmLs08 (H) | 2 | _ | 4 |
| SmLs09 (H) | - | _ | 4 |

Table 3 shows the results for the autocorrelation coefficient. Ox presents very good results as opposed to Octave function corrcoef and Python function pearsonr (from scipy.stats). R provides for this measure the acf (from stats) function. It should be noted that R gives the best results for all three measures.

3.2 Analysis of variance

Table 4 shows the ANOVA results. One notes that Python produces unacceptable results with the function f_{oneway} way (from scipy.stats) while Octave (anova function) and R (aov function from stats) presented very good results, except for SmLs07 (H), SmLs08 (H), and SmLs09 (H) datasets, which pose considerable difficulty for this measure. However, if one compares these last results to the ones given in other commercial platforms (Keeling and Pavur (2007)), they are

competitive. It should also be noted that the R version used here provides better results to those obtained with version 1.9.1 in the previous cited work.

3.3 Regression

In this section, the results obtained for linear and nonlinear regression are presented. It should be mentioned that the datasets provided by NIST for linear regression are different from the datasets provided for nonlinear regression, and the models are linear, quadratic, polynomial, and multilinear. For nonlinear regression NIST provides the exponential and rational models among others. Moreover, the degree of difficulty for each dataset may be Low, Average, or High.

3.3.1 *Linear regression*. Table 5 shows the results for linear regression. It can be noted that only the R package produces good results for the residual standard deviation, except for dataset Filip. R uses the function 1m that belongs to library stats in order to fit linear models.

Octave uses the function regress. This is the only high-level Octave available function for the computation of linear regression. This function shows serious problems when it is used to calculate the residual standard deviation, giving values blatantly far from the best results obtained with other commercial packages evaluated in previous studies.

Ox uses the PcFiml class which provides methods for obtaining some specific values other than the residual standard deviation value. For this reason, one cannot extract the displayed values (with 6 digits) and compare them to the certified ones. Unfortunately, it was not possible to evaluate Python due to the fact that it does not furnish specific functions for linear regression. In general, R gives the best

| | LKEs for the teast acci lard deviation RSD | ırate сое <i></i> ∏ісіє | ent p ana resia- |
|-----------|---|-------------------------|------------------|
| uai siana | iara deviation KSD | | |
| | Octave | Ox | R |

| | O | Octave | | Ox | | R | |
|--------------|-------------|--------|-------------|-----|-------------|-----|--|
| Datasets | \hat{eta} | RSD | \hat{eta} | RSD | \hat{eta} | RSD | |
| Norris (L) | 12 | 1 | 13 | 5 | 12 | 13 | |
| Pontius (L) | 11 | 1 | 1 | 0 | 12 | 12 | |
| NoInt1 (A) | 14 | 2 | 14 | 5 | 14 | 14 | |
| NoInt2 (A) | 15 | 2 | 15 | 4 | 15 | 15 | |
| Filip (H) | 7 | 1 | NA | NA | NA | NA | |
| Longley (H) | 7 | 0 | 12 | 4 | 12 | 14 | |
| Wampler1 (H) | 8 | 8 | NA | NA | 9 | 9 | |
| Wampler2 (H) | 12 | 12 | NA | NA | 12 | 14 | |
| Wampler3 (H) | 8 | 0 | 9 | 4 | 9 | 14 | |
| Wampler4 (H) | 7 | 0 | 9 | 4 | 8 | 14 | |
| Wampler5 (H) | 5 | 0 | 9 | 4 | 6 | 14 | |

| Datasets | \hat{eta} | RSD | Datasets | \hat{eta} | RSD |
|--------------|-------------|-----|---------------|-------------|-----|
| Chwirut1 (L) | 5 | 6 | Mgh17* (A) | 5 | 5 |
| Chwirut2 (L) | 4 | 5 | Misra1c (A) | 8 | 6 |
| Danwood (L) | 8 | 7 | Misra1d (A) | 6 | 6 |
| Gauss1 (L) | 6 | 6 | Roszman1 (A) | 5 | 6 |
| Gauss2 (L) | 6 | 6 | Nelson* (A) | 5 | 5 |
| Lanczos3 (L) | 6 | 4 | Bennett5 (H) | 5 | 4 |
| Misra1a (L) | 6 | 6 | Boxbod* (H) | 5 | 5 |
| Misra1b (L) | 6 | 6 | Eckerle4* (H) | 7 | 7 |
| Enso (A) | 4 | 5 | Mgh09 (H)* | 4 | 4 |
| Gauss3 (A) | 6 | 5 | Mgh10 (H)* | 6 | 6 |
| Hahn1 (A) | 6 | 6 | Rat42* (H) | 7 | 6 |
| Kirby2 (A) | 6 | 6 | Rat43* (H) | 5 | 5 |
| Lanczos1 (A) | NA | NA | Thurber (H) | 5 | 4 |
| Lanczos2 (A) | 7 | _ | | | |

Table 6 LREs for the least acurate coefficient $\hat{\beta}$ and residual standard deviation RSD in R

results and Octave the worst. In some models, Ox and R could not compute the numeric values.

3.3.2 Nonlinear regression. Table 6 shows the results for nonlinear regression. Unfortunately, Octave, Ox, and Python have no predefined functions that compute nonlinear regression. Only R provides a function (nls from stats) to this end. McCullough (1998) says that reasonable values for *LRE* have a four or five-digit accuracy. Table 6 shows that R yields very good results for nearly all datasets, except for Lanczos1 (A), in which the value could not be computed, and for the standard deviation of dataset Lanczos2 (A). Most of them were computed from the start 1 value while eight datasets (the ones marked with an "*") were computed from the start 2 value.

3.4 Quantiles functions

Table 7 shows the results for quantiles of tail probabilities. The assessment was based on the predefined functions given by each package. The values used for tail probabilities were the same for all packages: 2.10^{-7} for Gaussian, χ^2 (1 degree of freedom), and t-student (1 degree of freedom) distributions and 10^{-5} for F (1 and 1 degrees of freedom). Python does not provide any predefined functions to compute quantiles and was not evaluated in this case. The other packages presented good results regarding the inverse gaussian and χ^2 distributions. R and Ox also have produced good results for the t-student and F inverse cumulative distributions functions. Unlikewise, Octave presented numerical problems for these last two distributions. These results led us to conclude that, for applications like hypothesis testing, the most adequate packages are R and Ox.

| Octav | /e | Ox | | R | |
|----------|-----|----------|-----|----------|-----|
| Function | LRE | Function | LRE | Function | LRE |
| norminv | 6 | quann | 6 | qnorm | 6 |
| probit | 6 | quanf | 6 | qf | 6 |
| tinv | 0 | quant | 4 | qt | 6 |
| chi2inv | 0 | quanchi | 3 | qchisq | 3 |

 Table 7
 LREs for the packages quantiles functions

3.5 Pseudorandom number generation

The packages analyzed in this paper provide several algorithms for pseudorandom number generation. According to Marsaglia (Marsaglia and Tsang (2002)) most of them would pass in quite a few difficult randomness tests. R gives the user the choice between several kinds of algorithms with the Mersenne-Twister generator (MT, Matsumoto and Nishimura (1998)) as the default. The classical Wichman–Hill algorithm (Wichmann and Hill (1982, 1984)) is also available. The user can also supply his self-developed algorithm. MT is a 623-dimensionally equidistributed uniform pseudorandom number generator that has a period of 2^{19937} and a 624-dimensional set of 32-bit integers seed. It passes the Diehard tests (Marsaglia (1998)).

Octave, Ox, and Python also provide the MT algorithm. Ox provides the user with KISS and a multiply-with-carry (MWC) generator (Marsaglia (2003)) with periods of 2^{31} , 2^{60} , and 2^{8222} . The MWC with a period of 2^{31} is a modified version of Park and Miller generator (Park and Miller (1988)). The number of seeds depends on the generator used. One of the main advantages of MWC is its high speed. All of them have passed the Diehard tests. These algorithms do not suffer from problems of undesired structures in high dimensionality found in linear congruential and Fibonacci generators. Although the latter fail to pass hard randomness tests, they can be useful when combined with some of the above algorithms (MWC, MT, or KISS).

4 Conclusions

One of the main goals of this paper was to assess the reliability of statistical computing in a completely free software environment, including the operating system and software applications themselves. Given the fundamental role of statistical software in image processing, this article analyzes the accuracy of four well-known freely used tools which are frequently used by practitioners of image and signal processing and analysis. The choice of a platform that is the most suitable for a

specific application depends on the measures that each researcher is more interested in.

In a brief overview of univariate summary statistical functions, all software applications yield reliable values computing the sample mean. The Ox moments function shows the poorest results when employed to compute standard deviation. Octave corrcoef and Python pearsonr functions do not provide good accuracy when computing the autocorrelation coefficient. The Python f_oneway function has serious problems with the *F*-statistic of ANOVA in nearly all average and highly complex datasets. Differently, Octave anova and R aov functions give good results. R 2.6.2 introduces improvements over previous versions (see Keeling and Pavur (2007)). For linear regression, Octave regress function presents unacceptable results; bad results were also obtained with Ox (with the PcFiml class), although slightly better. As expected when using high quality software, R offers no local solutions for nonlinear regression when the initialized parameters are substandard. In this latter case, the software needs a new start point closer to the solution. If we proceed accordingly, wrong results are avoided.

We must emphasize that only the R package has presented predefined functions obtained from the official site (www.r-project.org) to all the measures used for accuracy evaluation, yielding satisfactory results in most cases. Octave also produces good results in most cases, but with problems in quantile functions. Octave has no predefined functions for nonlinear regression. Phyton also lacks several important predefined functions as, for instance, for nonlinear regression and quantiles. We found it extremely difficult to uncover freely official documentation about functions in Octave, Ox, and Python, as opposed to the well-documented R platform. The pseudorandom number generators used by all the packages were deemed reliable and did pass the most difficult tests of randomness.

This research will be useful for future developments of new versions of statistical functions. It helps users choose among the statistical free software packages currently available. In order to improve the platforms, some functions not yet supported by the official sites should be added in the next versions as, for instance, nonlinear regression in Octave, Ox, and Python.

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