

## RECOGNIZING HINGE-FREE LINE GRAPHS AND TOTAL GRAPHS

Jou-Ming Chang and Chin-Wen Ho

**Abstract.** In this paper, we characterize line graphs and total graphs that are hinge-free, i.e., there is no triple of vertices  $x, y, z$  such that the distance between  $y$  and  $z$  increases after  $x$  is removed. Based on our characterizations, we show that given a graph  $G$  with  $n$  vertices and  $m$  edges, determining its line graph and total graph to be hinge-free can be solved in  $O(n + m)$  time. Moreover, characterizations of hinge-free iterated line graphs and total graphs are also discussed.

### 1. INTRODUCTION

All graphs considered in this paper are undirected without self-loops and multiple edges. The vertex set and the edge set of a graph  $G$  are denoted by  $V(G)$  and  $E(G)$ , respectively. We call  $V(G) \cup E(G)$  the set of *elements* of  $G$ , and write  $n = |V(G)|$  to be the *order* of  $G$  and  $m = |E(G)|$  to be the *size* of  $G$ . Two elements are said to be *associated* if they are either adjacent or incident. The *distance*  $d_G(x, y)$  of two elements  $x, y \in V(G) \cup E(G)$  is the length (i.e., the number of edges) of a shortest path joining  $x$  and  $y$  in  $G$ , but not including  $x$  and  $y$  (if  $x \in E(G)$  or  $y \in E(G)$ ). A shortest path joining  $x$  and  $y$  is called an  *$x$ - $y$  geodesic*.

A vertex  $u$  in a graph  $G$  is called a *hinge vertex* if there exist two other vertices  $x$  and  $y$  such that  $d_{G-u}(x, y) > d_G(x, y)$ , where  $G - u$  denotes the subgraph of  $G$  induced by the vertex set  $V(G) \setminus \{u\}$ . That is,  $u$  is a hinge vertex if and only if every  $x$ - $y$  geodesic in  $G$  must pass through  $u$ . Graphs without hinge vertices are called *hinge-free graphs*. The study of hinge-free graphs arises naturally from network design [5, 6, 9]. Because many interconnection networks can be constructed using line (di)graph iterations, such as Kautz networks [10], de Bruijn networks

---

Received October 18, 1999.

Communicated by F. K. Hwang.

2001 *Mathematics Subject Classification*: 05C75, 05C85.

*Key words and phrases*: Hinge-free graph, line graph, total graph, cograph.

<sup>†</sup> Corresponding author. E-mail: [spade@mail.ntcb.edu.tw](mailto:spade@mail.ntcb.edu.tw).

[4] and Imase-Itoh networks [13], this provides with a motivation for us to study characterizations of hinge-free (iterated) line graphs.

The *line graph* of  $G$ , denoted by  $L(G)$ , is the intersection graph whose vertices correspond to the edges of  $G$ , and two vertices of  $L(G)$  are joined by an edge if and only if the corresponding edges in  $G$  are adjacent. A natural extension of line graphs is the *total graph*. The total graph  $T(G)$  is the graph whose vertex set is the set of all elements of  $G$ , and two vertices are adjacent if and only if the corresponding elements are associated in  $G$ . For example, Figure 1 shows a graph  $G$  and its line graph and total graph. More generally, the *iterated* line graphs and total graphs are defined as follows:  $L^1(G) = L(G)$  (resp.  $T^1(G) = T(G)$ ) and  $L^i(G) = L(L^{i-1}(G))$  (resp.  $T^i(G) = T(T^{i-1}(G))$ ) for  $i \geq 2$ .

In this paper, we characterize hinge-free line graphs and total graphs. Moreover, we extend these results to iterated line graphs and total graphs. Two interesting results acquired from our study are these:

**Theorem 1.** *The line graph  $L(G)$  is hinge-free if and only if  $G$  is  $P_4$ -free.*

**Theorem 2.** *The total graph  $T(G)$  is hinge-free if and only if  $G$  is both hinge-free and  $P_4$ -free.*

A graph is  $P_k$ -free if it contains no induced path of length  $k - 1$ . For the case  $k = 4$ , many structural and algorithmic properties of  $P_4$ -free graphs have been discovered (see e.g. [7, 8, 14]). A familiar synonym of  $P_4$ -free graph is *complement reducible graph* (abbreviated to *cograph*). Corneil *et al.* [8] showed that cographs can be recognized in  $O(n + m)$  time by constructing a unique tree representation. Therefore, our first result indicates that if the line graph model (i.e., the root graph)  $G$  is given, determining whether its line graph is hinge-free or not can be solved in the same time complexity.

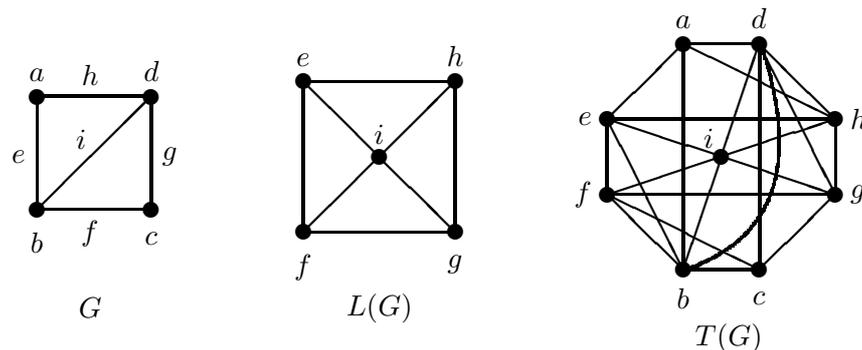


FIG. 1.

Due to the fact that  $T(G)$  always contains both  $G$  and  $L(G)$  as induced subgraphs, if  $T(G)$  is  $P_k$ -free then  $G$  and  $L(G)$  are also  $P_k$ -free, but the converse is not true. The second result seems to be not intuitive since, unlike the  $P_k$ -free property, the hinge-free property is not hereditary, i.e., not every induced subgraph of a hinge-free graph is hinge-free. It is well-known that cographs are properly contained in a class of graphs called *distance-hereditary graphs*, i.e., graphs in which every pair of vertices has the same distance in every connected induced subgraph containing them. Distance-hereditary graphs were first introduced by Howorka [12] and further characterized by Bandelt and Mulder [1]. It is obvious from the definition that every hinge vertex in a distance-hereditary graph must be a cut vertex. Thus, the depth-first search algorithm on graphs (see e.g. [3]) can be used for finding all hinge vertices of a distance-hereditary graph (cograph). An immediate consequence obtained from Theorem 2 is that the hinge-free total graph recognition problem can be solved in linear time once its root graph is given.

## 2. PRELIMINARIES

Throughout the rest of this paper, we assume that a graph  $G$  is connected and nontrivial. For a vertex  $u \in V(G)$ , the *neighborhood*  $N_G(u)$  is the set of all vertices of  $G$  adjacent to  $u$ . When no ambiguity arises, the subscript  $G$  can be omitted. Note that the term “path” always refers to a simple path, i.e., no vertex appears more than once. In particular, a path is called *trivial* if it has a single vertex. Two nontrivial paths joining  $x$  and  $y$  are *vertex-disjoint* (resp. *edge-disjoint*) if they have no vertices (resp. edges), excluding  $x$  and  $y$ , in common. Notations and terminologies not given here may be found in any standard textbook on graphs.

A point of view proposed in [6] showed that to identify a hinge vertex of an arbitrary graph, we only need to inspect the neighborhood of this vertex instead of examining the distances among all the vertex-pairs. Based on this property, linear-time algorithms for finding all hinge vertices for some special graphs were found [5, 11].

**Lemma 1.** (Chang *et al.* [6]) *A vertex  $v$  in a graph  $G$  is a hinge vertex if and only if there exist two nonadjacent vertices  $x, y \in N(v)$  such that  $N(x) \cap N(y) = \{v\}$ .*

An undirected graph  $G$  is  *$k$ -connected* if the removal of at least  $k$  vertices is necessary to disconnect  $G$  or reduce it to a single vertex. In [9], Entringer et al. defined that a graph  $G$  is  *$k$ -geodetically connected* ( *$k$ -GC* for short) if  $G$  is  $k$ -connected and the removal of at least  $k$  vertices is required to increase the distance of at least two vertices. That is, the structure of  $k$ -GC graphs can tolerate any  $k - 1$  vertices failures without increasing the distance among all the remaining vertices.

In fact, the class of hinge-free graphs is identical to the class of 2-GC graphs. A necessary and sufficient condition for a graph to be hinge-free (see Lemma 2) was proved in [5]. This result suggests that a hinge-free graph recognition algorithm can easily be implemented in  $O(nm)$  time. Indeed, a characterization which generalizes the result of Lemma 2 for  $k$ -GC graphs,  $k \geq 2$ , was also provided in [5].

**Lemma 2.** (Chang and Ho [5]) *A graph  $G$  is hinge-free if and only if every pair of nonadjacent vertices in  $G$  are joined by at least two vertex-disjoint geodesics.*

### 3. HINGE-FREE LINE GRAPHS

It is well-known that a line graph does not contain  $K_{1,3}$  (claw) as an induced subgraph. A complete list of the forbidden induced subgraphs for the family of line graphs was characterized by Beineke [2]. In this section, we characterize hinge-free (iterated) line graphs.

We first give some observations which can easily be derived from the definition of a line graph. For an arbitrary graph  $G$ , there is a one-to-one correspondence between the nontrivial paths of  $G$  and the induced paths of  $L(G)$ ; i.e., if  $G$  contains a path  $P = v_0v_1 \dots v_k$  of length  $k \geq 1$  which consists of edges  $e_i = v_{i-1}v_i$ , then the corresponding vertices of  $e_i$  in  $L(G)$  form an induced path  $P' = e_1e_2 \dots e_k$  of length  $k - 1$ , and vice versa. Further,  $P$  is a  $v_0$ - $v_k$  geodesic in  $G$  if and only if  $P'$  is an  $e_1$ - $e_k$  geodesic in  $L(G)$ , and two geodesics in  $G$  are edge-disjoint if and only if the corresponding induced geodesics in  $L(G)$  are vertex-disjoint. Thus, we have the following properties.

**Proposition 1.** *The line graph  $L(G)$  is  $P_k$ -free if and only if  $G$  contains no path of length  $k$ .*

**Proposition 2.** *Let  $G$  be a graph and  $l \geq 2$  be an integer. Two vertices of  $L(G)$  are joined by  $k$  vertex-disjoint geodesics of length  $l$  if and only if the corresponding edges in  $G$  are joined by  $k$  edge-disjoint geodesics of length  $l - 1$ .*

*Proof of Theorem 1.* By Lemma 2, if  $L(G)$  is hinge-free then every pair of nonadjacent vertices in  $L(G)$  are joined by at least two vertex-disjoint geodesics. It follows from Proposition 2 that every pair of nonadjacent edges in  $G$  is joined by at least two edge-disjoint geodesics. Let  $wxyz$  be any path of  $G$ . Since edges  $wx$  and  $yz$  are joined by at least two edge-disjoint geodesics, at least one of edges  $wy$ ,  $wz$ , and  $xz$  must exist. Thus  $G$  contains no induced  $P_4$ .

Conversely, suppose that  $w$  is a hinge vertex of  $L(G)$ . By Lemma 1, there exist two nonadjacent vertices  $x, y \in N_{L(G)}(w)$  such that  $N_{L(G)}(x) \cap N_{L(G)}(y) = \{w\}$ .

That is,  $xwy$  is the unique  $x$ - $y$  geodesic in  $L(G)$ . Let  $x = ab$  and  $y = cd$  be two such corresponding edges of  $G$ . Since  $ab$  and  $cd$  are nonadjacent, by Proposition 2, they are joined by only one edge  $w$ . Hence, in  $G$ ,  $w$  must be one of the following:  $ac$ ,  $bd$ ,  $ad$ , or  $bc$ . Therefore,  $a, b, c, d$  induce a  $P_4$  in  $G$ . ■

Given a connected graph  $G$ , we write  $kG$  for the graph with  $k$  components each isomorphic with  $G$ . For two vertex-disjoint graphs  $G_1$  and  $G_2$ , the union of  $G_1$  and  $G_2$ , denoted by  $G_1 \cup G_2$ , is the graph having  $V(G_1 \cup G_2) = V(G_1) \cup V(G_2)$  and  $E(G_1 \cup G_2) = E(G_1) \cup E(G_2)$ . The join of  $G_1$  and  $G_2$ , denoted by  $G_1 + G_2$ , is the graph consisting of the union  $G_1 \cup G_2$  together with  $\{uv : u \in V(G_1) \text{ and } v \in V(G_2)\}$ . Define  $H_k$  as the star  $K_{1,k+2}$  with one additional edge added, i.e.,  $H_k \cong K_1 + (kK_1 \cup K_2)$ . Note that  $H_0 \cong K_3$  and each  $H_k$  for  $k \geq 2$  contains a claw as an induced subgraph.

In what follows, the hinge-free iterated line graphs will be characterized. Obviously, for every graph  $G$  of order  $n < 3$ ,  $L^i(G)$ ,  $i \geq 2$ , does not exist. By Proposition 1 and Theorem 1,  $L^2(G)$  is hinge-free if and only if every path of  $G$  has length at most 3. Thus, if  $G$  has order 4 or less,  $L^2(G)$  is trivially hinge-free.

**Theorem 3.** *Let  $G$  be a graph of order at least 5. Then  $L^2(G)$  is hinge-free if and only if  $G$  is a tree of diameter at most 3 or one of the graphs  $H_k$  for  $k \geq 2$ .*

*Proof.* Clearly, if  $G$  is a tree of diameter no more than 3 then  $G$  contains no path of length 4. We now consider the graphs with order at least 5 and containing a cycle. Let  $G$  be a graph of order  $n \geq 5$  and let  $C$  be a longest cycle of  $G$  (without induced). Since  $G$  is connected and  $n \geq 5$ , if  $|V(C)| \geq 4$  then  $G$  contains a path of length 4. For  $|V(C)| = 3$ , it is easy to verify that if  $G \notin \{H_k : k = 2, 3, \dots\}$ , then  $G$  contains an induced subgraph isomorphic to  $W_1, W_2$  or  $W_3$  (see Figure 2), and in each case  $G$  always contains a path of length 4. On the contrary, if  $G \in \{H_k : k = 2, 3, \dots\}$  then  $G$  has no path of length 4. Thus, the graphs  $L^2(H_k)$  for  $k \geq 2$  are hinge-free. ■

From above, the family of graphs with order  $n \geq 3$  containing no path of length 4 is precisely  $\{T : T \text{ is a tree of diameter 2 or 3}\} \cup \{H_k : k = 0, 1, 2, \dots\} \cup \{C_4, K_4, K_4 - e\}$ , where  $K_4 - e$  is a 4-vertex complete graph by deleting any edge.

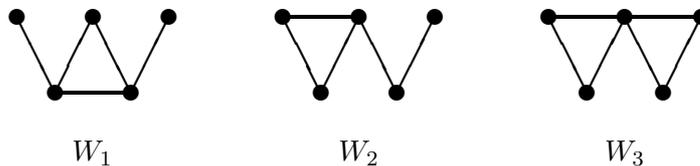


FIG. 2.

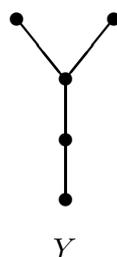


FIG. 3.

Furthermore, by Proposition 1 and Theorem 1,  $L^3(G)$  is hinge-free if and only if  $L(G)$  contains no path of length 4. Thus, we can characterize  $L^3(G)$  to be hinge-free by considering those graphs whose corresponding line graphs appear in the above family.

Obviously, not every graph containing no path of length 4 is the line graph of some graph. Note that, except for  $K_{1,3}$ , every forbidden induced subgraph of a line graph (provided by Beineke [2]) contains a path of length 4. Thus, we only need to restrict our attention to the  $K_{1,3}$  inspection in the above family when we consider line graphs without a path of length 4. Since a line graph that is a tree must be a path if it has no claw, and since each  $H_k$  for  $k \geq 2$  contains an induced claw, we characterize  $L^3(G)$  to be hinge-free as follows:  $L(P_4) \cong P_3$ ,  $L(P_5) \cong P_4$ ,  $L(K_3) \cong L(K_{1,3}) \cong K_3 \cong H_0$ ,  $L(Y) \cong H_1$  (see Figure 3 for the graph  $Y$ ),  $L(C_4) \cong C_4$ ,  $L(K_{1,4}) \cong K_4$  and  $L(H_1) \cong K_4 - e$ . Therefore, we have the following theorem.

**Theorem 4.**  $L^3(G)$  is hinge-free if and only if  $G \in \{P_4, P_5, K_3, K_{1,3}, Y, C_4, K_{1,4}, H_1\}$ .

#### 4. HINGE-FREE TOTAL GRAPHS

In this section, the hinge-free and  $P_k$ -free properties for total graphs are considered. Let  $P$  be an induced path of  $T(G)$ . We say that  $P$  is *vertex-unified* (resp. *edge-unified*) if all the corresponding elements of the vertices in  $P$  are vertices (resp. edges) of  $G$ . For convenience, we say that  $P$  is *unified* if it is either vertex-unified or edge-unified. Clearly, every trivial path is unified. If  $P$  is not unified, then it can be divided into maximal unified subpaths such that vertex-unified subpaths and edge-unified subpaths alternate along  $P$ . The following properties are directly obtained from the fact that  $T(G)$  contains  $G$  (resp.  $L(G)$ ) as an induced subgraph.

**Proposition 3.** Let  $P$  be a vertex-unified induced path in  $T(G)$  of length  $l$ . Then  $V(P)$  induces a path of the same length in  $G$ .

**Proposition 4.** *Let  $P$  be an edge-unified induced path in  $T(G)$  of length  $l$ . Then the corresponding edges of  $V(P)$  constitute a path of length  $l + 1$  in  $G$ .*

Let  $P$  be an induced path of  $T(G)$  having  $L_1, \dots, L_j$  as its maximal unified subpaths. By Propositions 3 and 4, for each  $L_i$ , there is a corresponding path  $L'_i$  in  $G$ . Since  $P$  is an induced path, the collection of paths  $L'_i$  in  $G$  still forms a path. For instance, we consider an induced path  $P = abfg$  of  $T(G)$  in Figure 1. Then  $P$  can be divided into  $ab$  and  $fg$  maximal unified subpaths. The vertex set  $\{a, b\}$  in  $G$  induces a path of length 1 and the edge set  $\{f = bc, g = cd\}$  in  $G$  yields a path of length 2. Consequently, the elements  $a, b, f, g$  in  $G$  produce a path  $abcd$  of length 3. We now prove three geodesic properties related to the graphs  $G$  and  $T(G)$ , which are helpful to establish the main result for hinge-free total graphs.

**Lemma 3.** *Two nonadjacent vertices of a graph  $G$  are joined by  $k$  vertex-disjoint geodesics of length  $l$  if and only if their corresponding vertices in  $T(G)$  are joined by  $k$  vertex-disjoint geodesics with the same length.*

*Proof.* The “only if” part follows immediately from the fact that  $G$  is an induced subgraph of  $T(G)$ . Conversely, we show that for any two nonadjacent vertices  $x$  and  $y$  in  $G$ , every  $x$ - $y$  geodesic in  $T(G)$  must be vertex-unified. Thus the result follows from Proposition 3.

Let  $P$  be an  $x$ - $y$  geodesic of length  $l$  in  $T(G)$ . Suppose that  $P$  is not vertex-unified. Then  $P$  contains at least one maximal edge-unified subpath. We may assume that  $P = x \cdots v_0 e_1 e_2 \cdots e_j v_j \cdots y$ , where  $v_0, v_j \in V(G)$ ,  $e_i = v_{i-1} v_i \in E(G)$  and  $j \geq 1$ . This means that  $e_1 \cdots e_j$  is a maximal edge-unified subpath of  $P$ . It is easy to see that  $x \cdots v_0 v_1 \cdots v_{j-1} v_j \cdots y$  forms another path in  $T(G)$  of length  $l - 1$ . This contradicts the fact that  $P$  is an  $x$ - $y$  geodesic in  $T(G)$ . ■

**Lemma 4.** *Two nonadjacent edges of a graph  $G$  are joined by  $k$  edge-disjoint geodesics of length  $l$  if and only if their corresponding vertices in  $T(G)$  are joined by  $k$  vertex-disjoint geodesics of length  $l + 1$ .*

*Proof.* The “only if” part follows immediately from the fact that  $L(G)$  is an induced subgraph of  $T(G)$ . Conversely, a similar proof of Lemma 3 can show that every  $x$ - $y$  geodesic in  $T(G)$  is edge-unified, where  $x$  and  $y$  are any two nonadjacent edges in  $G$ . Thus the result follows from Proposition 4. ■

**Lemma 5.** *For any two nonassociated elements  $x \in V(G)$  and  $y = uv \in E(G)$ , the corresponding vertices of  $x$  and  $y$  in  $T(G)$  are joined by at least two vertex-disjoint geodesics.*

*Proof.* Since  $G$  is connected, without loss of generality, we may assume that  $P = w_1w_2 \cdots w_k$  is an  $x$ - $y$  geodesic of  $G$  where  $w_1 = x$ ,  $w_k = y$  and  $k \geq 2$ . Let  $e_i = w_iw_{i+1}$ . Then we can find two vertex-disjoint paths of length  $k$  joining  $x$  and  $y$  in  $T(G)$ , namely,  $P' = w_1w_2w_3 \cdots w_ky$  and  $P'' = w_1e_1e_2 \cdots e_{k-1}y$ . Also, if  $T(G)$  contains another  $x$ - $y$  path of length less than  $k$ , then  $P$  cannot be an  $x$ - $y$  geodesic in  $G$ . Thus  $P'$  and  $P''$  are vertex-disjoint geodesics in  $T(G)$ . ■

Now, we complete the proof of Theorem 2.

*Proof of Theorem 2.* Suppose that  $T(G)$  is hinge-free. By Lemma 2, every pair of nonadjacent vertices in  $T(G)$  are joined by at least two vertex-disjoint geodesics. Since two vertices  $x, y \in V(G)$  are nonadjacent if and only if the corresponding vertices of  $x$  and  $y$  in  $T(G)$  are also nonadjacent, it follows from Lemma 3 that every two nonadjacent vertices of  $G$  are joined by at least two vertex-disjoint geodesics. Thus, by Lemma 2,  $G$  is hinge-free. To show that  $G$  is  $P_4$ -free, by Theorem 1 it suffices to show that  $L(G)$  is hinge-free. Let  $x$  and  $y$  be nonadjacent vertices in  $L(G)$ . Since  $T(G)$  contains  $L(G)$  as an induced subgraph,  $x$  and  $y$  are also nonadjacent in  $T(G)$ . Since  $T(G)$  is hinge-free, there exist at least two vertex-disjoint geodesics joining  $x$  and  $y$  in  $T(G)$ . By Lemma 4, the corresponding edges of  $x$  and  $y$  in  $G$  are joined by at least two edge-disjoint geodesics. Thus, by Proposition 2 and Lemma 2, we conclude that  $L(G)$  is hinge-free.

Conversely, let  $G$  be a  $P_4$ -free and hinge-free graph and assume that  $T(G)$  contains a hinge vertex  $w$ . By Lemma 1, there exist two nonadjacent vertices  $x, y \in N_{T(G)}(w)$  such that  $N_{T(G)}(x) \cap N_{T(G)}(y) = \{w\}$ . That is, the corresponding elements of  $x$  and  $y$  in  $G$  are nonassociated, and the induced path  $xwy$  in  $T(G)$  is the unique  $x$ - $y$  geodesic. We now consider all possible cases about the elements  $x$  and  $y$  to be either vertices or edges of  $G$  as follows.

Case 1:  $x$  and  $y$  are nonadjacent vertices of  $G$ . Since  $xwy$  is the unique  $x$ - $y$  geodesic in  $T(G)$ , by Lemma 3, there is only one geodesic with length 2 between  $x$  and  $y$  in  $G$ . Thus, by Lemma 2,  $G$  is not hinge-free, a contradiction.

Case 2:  $x = ab$  and  $y = cd$  are nonadjacent edges of  $G$ . Since  $xwy$  is the unique  $x$ - $y$  geodesic in  $T(G)$ , by Lemma 4,  $ab$  and  $cd$  in  $G$  must be joined by only one edge. Thus,  $G$  contains an induced  $P_4$ , a contradiction.

Case 3:  $x \in V(G)$  and  $y \in E(G)$  or  $x \in E(G)$  and  $y \in V(G)$  are nonassociated elements. By Lemma 5,  $x$  and  $y$  in  $T(G)$  are joined by at least two vertex-disjoint geodesics. This violates the fact that  $xwy$  is the unique  $x$ - $y$  geodesic in  $T(G)$ . ■

As immediate consequences, we obtain the following corollaries.

**Corollary 1.** *The total graph  $T(G)$  is hinge-free if and only if both  $G$  and  $L(G)$  are hinge-free.*

**Corollary 2.** *The following statements are equivalent for a graph  $G$ :*

- (1)  $T(L(G))$  is hinge-free.
- (2)  $L(G)$  is both hinge-free and  $P_4$ -free.
- (3) Both  $G$  and  $L(G)$  are  $P_4$ -free.
- (4)  $G$  is  $P_4$ -free and every path of  $G$  has length at most 3.
- (5)  $G \in \{C_4, K_4, K_4 - e\} \cup \{H_k : k = 0, 1, 2, \dots\} \cup \{K_{1,n} : n = 1, 2, 3, \dots\}$ .

*Proof.* The equivalences of statements (1), (2), (3) and (4) are established by Theorems 2, 1 and Proposition 1. (4) $\Leftrightarrow$ (5) can be proved similarly to Theorem 3 by restricting  $G$  without an induced  $P_4$ . ■

In what follows, we present some properties of total graphs without induced  $P_k$  and then use these properties to characterize the hinge-free iterated total graphs. Let  $P$  be an induced path of a total graph  $T(G)$ . We first show that the number of maximal unified subpaths with respect to  $P$  has a bound.

**Lemma 6.** *Every induced path of length  $k - 1$  in  $T(G)$  can be divided into at most  $\lfloor \frac{k}{2} \rfloor + 1$  maximal unified subpaths.*

*Proof.* Let  $P = x_1x_2 \cdots x_k$  be an induced path of  $T(G)$  which consists of  $j$  maximal unified subpaths  $L_1, \dots, L_j$ . Consider three consecutive vertices  $x_i, x_{i+1}$  and  $x_{i+2}$  in  $P$ , where  $i = 1, \dots, k - 2$ . Clearly, if the corresponding elements of these three vertices in  $G$  satisfy  $x_i, x_{i+2} \in V(G)$  and  $x_{i+1} \in E(G)$  or  $x_i, x_{i+2} \in E(G)$  and  $x_{i+1} \in V(G)$ , then  $x_i$  and  $x_{i+2}$  are two associated elements of  $G$  (corresponding to two adjacent vertices of  $T(G)$ ). This implies that  $P$  is not an induced path of  $T(G)$ . Thus, each subpath  $L_i$ , excluding  $L_1$  and  $L_j$ , contains at least two vertices. So  $P$  has  $k \geq 2(j - 2) + 2$  vertices. Since  $j$  must be an integer, we have  $j \leq \lfloor \frac{k}{2} \rfloor + 1$ . ■

**Theorem 5.** *Let  $G$  be a graph and let  $k \geq 2$ . Then  $T(G)$  is  $P_k$ -free if  $G$  contains no path of length  $\lceil \frac{3k}{4} \rceil - 1$ .*

*Proof.* We will show that if  $T(G)$  is not  $P_k$ -free, then  $G$  contains a path of length at least  $\lceil \frac{3k}{4} \rceil - 1$ . Assume that there is an induced path  $P = x_1x_2 \cdots x_k$  of length  $k - 1$  in  $T(G)$  which is divided into  $L_1, \dots, L_j$  maximal unified subpaths such that  $x_1 \in V(L_1)$  and  $x_k \in V(L_j)$ . For  $i = 1, \dots, j$ , let  $L'_i$  be the corresponding path of  $L_i$  in  $G$ . By Propositions 3 and 4, the length of  $L'_i$  can be determined by the

length of  $L_i$ . Let  $P'$  be the path in  $G$  that is constituted from the set of subpaths  $L'_1, \dots, L'_j$ . Then  $|P'| = \sum_{i=1}^j |L'_i|$ , where  $|P'|$  denotes the length of  $P'$ . We claim that  $|P'| \geq \lceil \frac{3k}{4} \rceil - 1$ . Consider elements  $x_1$  and  $x_k$  to be either vertices or edges of  $G$  by the following three cases:

Case 1:  $x_1, x_k \in V(G)$ . In this case,  $j$  is odd and each subpath  $L_i$  for  $i$  even (resp. odd) is edge-unified (resp. vertex-unified). Thus we have

$$|P'| = \sum_{i=1}^{\frac{j+1}{2}} (|V(L_{2i-1})| - 1) + \sum_{i=1}^{\frac{j-1}{2}} |V(L_{2i})| = \sum_{i=1}^j |V(L_i)| - \frac{j+1}{2} = k - \frac{j+1}{2}.$$

Case 2:  $x_1, x_k \in E(G)$ . In this case,  $j$  is odd and each subpath  $L_i$  for  $i$  even (resp. odd) is vertex-unified (resp. edge-unified). Thus we have

$$|P'| = \sum_{i=1}^{\frac{j-1}{2}} (|V(L_{2i})| - 1) + \sum_{i=1}^{\frac{j+1}{2}} |V(L_{2i-1})| = k - \frac{j-1}{2}.$$

Case 3:  $x_1 \in V(G)$  and  $x_k \in E(G)$  or  $x_1 \in E(G)$  and  $x_k \in V(G)$ . In this case,  $j$  is even. Without loss of generality, we assume that  $x_1 \in V(G)$  and  $x_k \in E(G)$ . Thus we have

$$|P'| = \sum_{i=1}^{\frac{j}{2}} (|V(L_{2i-1})| - 1) + \sum_{i=1}^{\frac{j}{2}} |V(L_{2i})| = k - \frac{j}{2}.$$

Since  $j \leq \lfloor \frac{k}{2} \rfloor + 1$  by Lemma 6, the length of  $P'$  in the above three cases is at least

$$k - \frac{j+1}{2} \geq k - \frac{\lfloor \frac{k}{2} \rfloor + 1}{2} - 1 \geq \frac{3k}{4} - 1.$$

Thus,  $G$  contains a path of length  $\lceil \frac{3k}{4} \rceil - 1$ . ■

A necessary condition for  $T(G)$  to be  $P_k$ -free can readily be made as follows. Since  $T(G)$  contains both  $G$  and  $L(G)$  as induced subgraphs, if  $T(G)$  is  $P_k$ -free then both  $G$  and  $L(G)$  are  $P_k$ -free. By Proposition 1, this implies that  $G$  contains no path of length  $k$  and no induced path of length  $k - 1$ . The following theorem improves this bound.

**Theorem 6.** *Let  $G$  be a graph and let  $k \geq 2$ . If  $T(G)$  is  $P_k$ -free, then*

- (1)  $G$  contains no path of length  $k - 1$ , and
- (2)  $G$  contains no induced path of length  $\lceil \frac{3k-2}{4} \rceil$ .

*Proof.* (1) Assume that  $G$  contains a path  $v_1v_2 \cdots v_k$  of length  $k - 1$ . For  $i = 1, \dots, k - 1$ , let  $e_i = v_iv_{i+1}$ . Then  $e_1 \cdots e_{k-1}v_k$  forms an induced path of length  $k - 1$  in  $T(G)$ . Thus,  $T(G)$  is not  $P_k$ -free.

(2) Assume that  $G$  has an induced path  $P = v_0v_1 \cdots v_p$  with  $p \geq \lceil \frac{3k-2}{4} \rceil$ . We will show that  $T(G)$  is not  $P_k$ -free. Let  $e_i = v_{i-1}v_i$  for  $i = 1, \dots, p$  and let  $S = \{v_0, e_1, v_1, e_2, \dots, v_{p-1}, e_p, v_p\}$  be the set of elements of  $P$ . Denote  $G_S$  as the subgraph of  $T(G)$  induced by the corresponding vertices of the elements of  $S$ . We claim that  $G_S$  contains an induced path of length at least  $k - 1$ .

To simplify the description, we use  $f(i)$  for  $i = 1, 2, \dots, 2p + 1$  to denote the vertices of  $G_S$ , where

$$f(i) = \begin{cases} v_{\frac{i-1}{2}} & \text{if } i \text{ is odd,} \\ e_{\frac{i}{2}} & \text{if } i \text{ is even.} \end{cases}$$

Since  $P$  is an induced path of  $G$ , distinct vertices  $f(i)$  and  $f(j)$  in  $G_S$  are adjacent for  $|i - j| \leq 2$ , and are nonadjacent for  $|i - j| \geq 3$ . Let  $X = x_0, x_1, \dots, x_h$  be an increasing sequence from the set  $\{1, 2, \dots, 2p + 1\}$ . Obviously, if  $x_{i+1} - x_i \leq 2$  for all  $i = 0, \dots, h - 1$ , then  $f(x_0) \cdots f(x_h)$  forms a path of length  $h$  in  $G_S$ . Moreover, if additional conditions  $x_{i+2} - x_i \geq 3$  hold for all  $i = 0, \dots, h - 2$ , then  $f(x_0) \cdots f(x_h)$  is an induced path of length  $h$  in  $G_S$ .

Let  $q = \lceil \frac{2p+1}{3} \rceil$  and  $r = (2p + 1) \bmod 3$ . We now consider a  $v_0$ - $v_p$  induced path  $P'$  in  $G_S$  that is constructed from an increasing sequence  $X$  such that all the terms of  $X$  satisfy the conditions:

$$x_{i+1} - x_i \leq 2 \quad \text{and} \quad x_{i+2} - x_i \geq 3.$$

Case 1:  $r = 0$ . In this case, we have  $2p + 1 = 3q$  and  $p \equiv 1 \pmod{3}$ . We select  $X = 1, 3, 4, 6, 7, 9, \dots, 3q - 2, 3q$ . Then  $|P'| = 2q - 1 = \frac{4p-1}{3}$ .

Case 2:  $r = 1$ . In this case, we have  $2p + 1 = 3q - 2$  and  $p \equiv 0 \pmod{3}$ . Select  $X = 1, 3, 4, 6, 7, 9, \dots, 3q - 5, 3q - 3, 3q - 2$ . Then  $|P'| = 2q - 2 = \frac{4p}{3}$ .

Case 3:  $r = 2$ . In this case, we have  $2p + 1 = 3q - 1$  and  $p \equiv 2 \pmod{3}$ . Select  $X = 1, 2, 4, 5, 7, 8, \dots, 3q - 5, 3q - 4, 3q - 2, 3q - 1$ . Then  $|P'| = 2q - 1 = \frac{4p+1}{3}$ .

In the above three cases, the length of  $P'$  can be expressed in term  $\lceil \frac{4p-1}{3} \rceil$  by considering the congruence of  $p$ . Since  $p \geq \lceil \frac{3k-2}{4} \rceil \geq \frac{3k-2}{4}$ , we have

$$\lceil \frac{4p-1}{3} \rceil \geq \frac{4p-1}{3} \geq k - 1.$$

From the above argument, we obtain that the induced subgraph  $G_S$  of  $T(G)$  contains an induced path of length at least  $k - 1$ . Thus,  $T(G)$  is not  $P_k$ -free. ■

**Corollary 3.** *The following statements are equivalent for a graph  $G$ :*

- (1)  $T(G)$  is  $P_4$ -free.
- (2)  $L(T(G))$  is hinge-free.
- (3)  $T(G)$  is both hinge-free and  $P_4$ -free.
- (4)  $T^2(G)$  is hinge-free.

Moreover, the only connected graph  $G$  for which  $T(G)$  is  $P_4$ -free are  $K_2$  and  $K_3$ .

*Proof.* The equivalences (1) $\Leftrightarrow$ (2) and (3) $\Leftrightarrow$ (4) follow directly from Theorems 1 and 2, respectively. (3) $\Rightarrow$ (1) is trivial. We prove (1) $\Rightarrow$ (3) as follows.

By Theorem 6, if  $T(G)$  is  $P_4$ -free then  $G$  has no path of length 3. The nontrivial connected graphs containing a path of length at most 2 are  $K_2$ ,  $K_3$ ,  $P_3$ , and  $K_{1,n}$  for  $n \geq 3$ . Clearly,  $T(P_3)$  is not  $P_4$ -free. Since every  $T(K_{1,n})$  for  $n > 3$  contains  $T(P_3)$  as an induced subgraph, it is not  $P_4$ -free. Also, it is easy to check that  $T(K_2)$  and  $T(K_3)$  are both  $P_4$ -free and hinge-free. ■

#### REFERENCES

1. H. J. Bandelt and H. M. Mulder, Distance-hereditary graphs, *J. Combin. Theory Ser. B* **41** (1986), 182-208.
2. L. W. Beineke, Derived graphs and digraphs, *Beiträge Graphentheorie* (Teubner, Leipzig, 1968).
3. G. Brassard and P. Bratley, *Algorithmics: theory and practice*, Prentice-Hall, Englewood Cliffs, 1988.
4. N. G. de Bruijn, A combinatorial problem, *Proc. Konink. Nederl. Akad. Wetensch. Ser. A* **49** (1946), 758-764.
5. J. M. Chang and C. W. Ho, The recognition of geodetically connected graphs, *Inform. Process. Lett.* **65** (1998), 81-88.
6. J. M. Chang, C. W. Ho, C. C. Hsu and Y. L. Wang, The characterizations of hinge-free networks, in: *Proc. International Computer Symposium on Algorithms*, 1996, pp. 105-112.
7. D. G. Corneil, H. Lerchs and L. Stewart Burlingham, Complement reducible graphs, *Discrete Appl. Math.* **3** (1981), 163-174.
8. D. G. Corneil, Y. Perl and L. K. Stewart, A linear recognition algorithm for cographs, *SIAM J. Comput.* **14** (1985), 926-934.
9. R. C. Entringer, D. E. Jackson and P. J. Slater, Geodetic connectivity of graphs, *IEEE Trans. Circuits Systems CAS* **24** (1977), 460-463.

10. M. A. Fiol, J. L. A. Yebra and I. Alegre, Line digraph iterations and the  $(d, k)$  digraph problem, *IEEE Trans. Comput.* **33** (1984), 400-403.
11. T. Y. Ho, Y. L. Wang and M. T. Juan, A linear time algorithm for finding all hinge vertices of a permutation graph, *Inform. Process. Lett.* **59** (1996), 103-107.
12. E. Howorka, A characterization of distance-hereditary graphs, *Quart. J. Math. Oxford Ser. (2)* **28** (1977), 417-420.
13. M. Imase and M. Itoh, A design for directed graph with minimum diameter, *IEEE Trans. Comput.* **32** (1983), 782-784.
14. L. Stewart, Cographs, a class of tree representable graphs, TR 126/78, Department of Computer Science, University of Toronto, 1978.

Jou-Ming Chang<sup>\*,†</sup> and Chin-Wen Ho<sup>\*</sup>

<sup>\*</sup> Institute of Computer Science and Information Engineering, National Central University, Chung-Li, Taiwan 320, R.O.C.

<sup>†</sup> Department of Information Management, National Taipei College of Business, Taipei, Taiwan 100, R.O.C.

E-mail: spade@mail.ntcb.edu.tw.