## Research Article

# The Generalized Projective Riccati Equations Method for Solving Nonlinear Evolution Equations in Mathematical Physics 

E. M. E. Zayed and K. A. E. Alurrfi<br>Department of Mathematics, Faculty of Science, Zagazig University, P.O. Box 44519, Zagazig, Egypt<br>Correspondence should be addressed to E. M. E. Zayed; e.m.e.zayed@hotmail.com

Received 22 March 2014; Accepted 11 August 2014; Published 6 November 2014
Academic Editor: Luiz Duarte
Copyright © 2014 E. M. E. Zayed and K. A. E. Alurrfi. This is an open access article distributed under the Creative Commons Attribution License, which permits unrestricted use, distribution, and reproduction in any medium, provided the original work is properly cited.


#### Abstract

We apply the generalized projective Riccati equations method to find the exact traveling wave solutions of some nonlinear evolution equations with any-order nonlinear terms, namely, the nonlinear Pochhammer-Chree equation, the nonlinear Burgers equation and the generalized, nonlinear Zakharov-Kuznetsov equation. This method presents wider applicability for handling many other nonlinear evolution equations in mathematical physics.


## 1. Introduction

In the recent years, investigations of exact solutions to nonlinear partial differential equations (NPDEs) play an important role in the study of nonlinear physical phenomena. Nonlinear wave phenomena appear in various scientific and engineering fields, such as fluid mechanics, plasma physics, optical fibers, biology, solid state physics, chemical kinematics, chemical physics, and geochemistry. To obtain traveling wave solutions, many powerful methods have been presented, such as the inverse scattering method [1], the tanh-function method [2-8], the Hirota bilinear transform method [9], the truncated Painleve expansion method [10-13], the Backlund transform method [14, 15], the Exp-function method [16-20], the Jacobi elliptic function expansion method [21-23], the generalized Riccati equations method [24-26], the $\left(G^{\prime} / G\right)$ expansion method [27-33], and the ( $\left.G^{\prime} / G, 1 / G\right)$-expansion method [34-36]. Conte and Musette [37] presented an indirect method to seek more solitary wave solutions of some NPDEs that can be expressed as polynomials in two elementary functions which satisfy a projective Riccati equation [38]. Using this method, many solitary wave solutions of many NPDEs are found [38, 39]. Recently, Yan [40] developed further Conte and Musette's method by introducing more generalized projective Riccati equations.

In this paper, we will use the generalized projective Riccati equations method to construct exact solutions for the following three nonlinear evolution equations with higherorder nonlinear terms:
(i) the nonlinear Pochhammer-Chree equation [41]:

$$
\begin{array}{r}
u_{t t}-u_{x x t t}-\left(\alpha u+\beta u^{n+1}+\gamma u^{2 n+1}\right)_{x x}=0  \tag{1}\\
n \geq 1
\end{array}
$$

where $\alpha, \beta$, and $\gamma$ are constants and $\gamma<0$,
(ii) the nonlinear Burgers equation [42]:

$$
\begin{equation*}
u_{t}+a\left(u^{n}\right)_{x}+b u_{x x}=0, \quad n>1, \tag{2}
\end{equation*}
$$

where $a$ and $b$ are constants;
(iii) the nonlinear generalized Zakharov-Kuznetsov equation [43]:

$$
\begin{equation*}
u_{t}+\left(A u^{p}+B u^{2 p}\right) u_{x}+C\left(u_{x x x}+u_{x y y}\right)=0, \quad p>0, \tag{3}
\end{equation*}
$$

where $A, B$, and $C$ are nonzero real constants.
Zuo [32] has applied the extended ( $G^{\prime} / G$ )-expansion method and determined the exact solutions of (1), and Hayek [33] has found the exact solutions of (2) using another form of the extended $\left(G^{\prime} / G\right)$-expansion method, while Zhang [44]
has discussed (3) using an algebraic method to find some of its exact solutions. The rest of this paper is organized as follows. In Section 2, we give the description of the generalized projective Riccati equations method. In Section 3, we apply this method to solve (1)-(3). In Section 4, physical explanations of some obtained results are obtained. In Section 5, some conclusions are given.

## 2. Description of the Generalized Projective Riccati Equations Method

Consider we have the following NPDE:

$$
\begin{equation*}
F\left(u, u_{t}, u_{x}, u_{t t}, u_{x t}, u_{x x}, \ldots\right)=0 \tag{4}
\end{equation*}
$$

where $F$ is a polynomial in $u(x, t)$ and its partial derivatives, in which the highest-order derivatives and nonlinear terms are involved. In the following, we give the main steps of this method.

Step 1. We use the wave transformation

$$
\begin{equation*}
u(x, t)=u(\xi), \quad \xi=x-c t \tag{5}
\end{equation*}
$$

where $c$ is a constant, to reduce (4) to the following ODE:

$$
\begin{equation*}
P\left(u, u^{\prime}, u^{\prime \prime}, \ldots\right)=0 \tag{6}
\end{equation*}
$$

where $P$ is a polynomial in $u(\xi)$ and its total derivatives, such that ${ }^{\prime}=d / d \xi$.

Step 2. We assume that (6) has the formal solution

$$
\begin{equation*}
u(\xi)=A_{0}+\sum_{i=1}^{m} \sigma^{i-1}(\xi)\left[A_{i} \sigma(\xi)+B_{i} \tau(\xi)\right] \tag{7}
\end{equation*}
$$

where $A_{0}, A_{i}$, and $B_{i}$ are constants to be determined later. The functions $\sigma(\xi)$ and $\tau(\xi)$ satisfy the ODEs

$$
\begin{gather*}
\sigma^{\prime}(\xi)=\varepsilon \sigma(\xi) \tau(\xi)  \tag{8}\\
\tau^{\prime}(\xi)=R+\varepsilon \tau^{2}(\xi)-\mu \sigma(\xi), \quad \varepsilon= \pm 1
\end{gather*}
$$

where

$$
\begin{equation*}
\tau^{2}(\xi)=-\varepsilon\left(R-2 \mu \sigma(\xi)+\frac{\mu^{2}-1}{R} \sigma^{2}(\xi)\right) \tag{9}
\end{equation*}
$$

where $R$ and $\mu$ are nonzero constants.
If $R=\mu=0$, (6) has the formal solution

$$
\begin{equation*}
u(\xi)=\sum_{i=0}^{m} A_{i} \tau^{i}(\xi) \tag{10}
\end{equation*}
$$

where $\tau(\xi)$ satisfies the ODE

$$
\begin{equation*}
\tau^{\prime}(\xi)=\tau^{2}(\xi) \tag{11}
\end{equation*}
$$

Step 3. We determine the positive integer $m$ in (7) by using the homogeneous balance between the highest-order
derivatives and the nonlinear terms in (6). In some nonlinear equations the balance number $m$ is not a positive integer. In this case, we make the following transformations.
(a) When $m=q / p$, where $q / p$ is a fraction in the lowest terms, we let

$$
\begin{equation*}
u(\xi)=v^{q / p}(\xi) \tag{12}
\end{equation*}
$$

and then we substitute (12) into (6) to get a new equation in the new function $v(\xi)$ with a positive integer balance number.
(b) When $m$ is a negative number, we let

$$
\begin{equation*}
u(\xi)=v^{m}(\xi) \tag{13}
\end{equation*}
$$

and then we substitute (13) into (6) to get a new equation in the new function $v(\xi)$ with a positive integer balance number.

Step 4. Substitute (7) along with (8)-(9) into (6) or (10) along with (11) into (6). Collect all terms of the same order of $\sigma^{j}(\xi) \tau^{i}(\xi)(j=0,1, \ldots, i=0,1)\left(\right.$ or $\left.\tau^{j}(\xi), j=0,1, \ldots\right)$. Setting each coefficient to zero yields a set of algebraic equations which can be solved to find the values of $A_{0}, A_{i}$, $B_{i}, c, \mu$, and $R$.

Step 5. It is well known [24] that (8) admits the following solutions.
(i) If $\varepsilon=-1, R \neq 0$,

$$
\begin{array}{ll}
\sigma_{1}(\xi)=\frac{R \operatorname{sech}(\sqrt{R} \xi)}{\mu \operatorname{sech}(\sqrt{R} \xi)+1}, & \tau_{1}(\xi)=\frac{\sqrt{R} \tanh (\sqrt{R} \xi)}{\mu \operatorname{sech}(\sqrt{R} \xi)+1} \\
\sigma_{2}(\xi)=\frac{R \operatorname{csch}(\sqrt{R} \xi)}{\mu \operatorname{csch}(\sqrt{R} \xi)+1}, & \tau_{2}(\xi)=\frac{\sqrt{R} \operatorname{coth}(\sqrt{R} \xi)}{\mu \operatorname{csch}(\sqrt{R} \xi)+1} \tag{14}
\end{array}
$$

(ii) If $\varepsilon=1, R \neq 0$,

$$
\begin{array}{ll}
\sigma_{3}(\xi)=\frac{R \sec (\sqrt{R} \xi)}{\mu \sec (\sqrt{R} \xi)+1}, & \tau_{3}(\xi)=\frac{\sqrt{R} \tan (\sqrt{R} \xi)}{\mu \sec (\sqrt{R} \xi)+1} \\
\sigma_{4}(\xi)=\frac{R \csc (\sqrt{R} \xi)}{\mu \csc (\sqrt{R} \xi)+1}, & \tau_{4}(\xi)=-\frac{\sqrt{R} \cot (\sqrt{R} \xi)}{\mu \csc (\sqrt{R} \xi)+1} \tag{15}
\end{array}
$$

(iii) If $R=\mu=0$,

$$
\begin{equation*}
\sigma_{5}(\xi)=\frac{C}{\xi}, \quad \tau_{5}(\xi)=\frac{1}{\varepsilon \xi}, \tag{16}
\end{equation*}
$$

where $C$ is nonzero constant.
Step 6. Substituting the values of $A_{0}, A_{i}, B_{i}, c, \mu$, and $R$ as well as the solutions (14)-(16) into (7), we obtain the exact solutions of (4).

We close this section with the remark that without loss of generality we take $\varepsilon=-1$ (similarly the case $\varepsilon=1$ can be done which is omitted here for simplicity).

## 3. Applications

In this section, we will apply the proposed method described in Section 2 to find the exact traveling wave solutions of the nonlinear equations (1)-(3).

Example 1 (the nonlinear Pochhammer-Chree equation (1)). In this example, we find the exact solutions of (1). To this end, we see that the traveling wave variable (5) permits us to convert (1) into the following ODE:

$$
\begin{equation*}
c^{2} u^{\prime \prime}-c^{2} u^{\prime \prime \prime \prime}-\left(\alpha u+\beta u^{n+1}+\gamma u^{2 n+1}\right)^{\prime \prime}=0 \tag{17}
\end{equation*}
$$

Integrating (17) twice with respect to $\xi$ and vanishing the constants of integration, we get

$$
\begin{equation*}
\left(c^{2}-\alpha\right) u-c^{2} u^{\prime \prime}-\beta u^{n+1}-\gamma u^{2 n+1}=0 \tag{18}
\end{equation*}
$$

By balancing $u^{\prime \prime}$ with $u^{2 n+1}$ in (18) we get $m=1 / n$. According to Step 3, we use the transformation

$$
\begin{equation*}
u(\xi)=v^{1 / n}(\xi) \tag{19}
\end{equation*}
$$

where $v(\xi)$ is a new function of $\xi$. Substituting (19) into (18), we get the new ODE

$$
\begin{align*}
& \left(c^{2}-\alpha\right) n^{2} v^{2}-c^{2} n v v^{\prime \prime}  \tag{20}\\
& \quad-c^{2}(1-n)\left(v^{\prime}\right)^{2}-\beta n^{2} v^{3}-\gamma n^{2} v^{4}=0
\end{align*}
$$

Balancing $v v^{\prime \prime}$ with $v^{4}$ in (20), we get $m=1$. Consequently, we get

$$
\begin{equation*}
v(\xi)=A_{0}+A_{1} \sigma(\xi)+B_{1} \tau(\xi) \tag{21}
\end{equation*}
$$

where $A_{0}, A_{1}$, and $B_{1}$ are constants to be determined later.
Substituting (21) into (20) and using (8)-(9) with $\varepsilon=-1$, the left-hand side of (20) becomes a polynomial in $\sigma$ and $\tau$. Setting the coefficients of this polynomial to be zero yields the following system of algebraic equations:

$$
\begin{aligned}
& \sigma^{4}:- n^{2} \gamma A_{1}^{4} R^{2} \\
&+R\left(c^{2} n A_{1}^{2}-c^{2} n \mu^{2} A_{1}^{2}-c^{2} \mu^{2} A_{1}^{2}\right. \\
&\left.+c^{2} A_{1}^{2}-6 \gamma n^{2} \mu^{2} A_{1}^{2} B_{1}^{2}+6 \gamma n^{2} A_{1}^{2} B_{1}^{2}\right) \\
&+2 c^{2} n \mu^{2} B_{1}^{2}-c^{2} n \mu^{4} B_{1}^{2}-c^{2} n B_{1}^{2}-c^{2} \mu^{4} B_{1}^{2} \\
&+2 c^{2} \mu^{2} B_{1}^{2}-c^{2} B_{1}^{2}-\gamma n^{2} \mu^{4} B_{1}^{4} \\
&+2 \gamma n^{2} \mu^{2} B_{1}^{4}-\gamma n^{2} B_{1}^{4}=0 \\
& \sigma^{3}: 2 c^{2} \mu^{3} B_{1}^{2}-2 c^{2} \mu B_{1}^{2}+2 c^{2} n A_{0} A_{1} \\
&+4 n^{2} \gamma \mu^{3} B_{1}^{4}+2 R c^{2} \mu A_{1}^{2}-R n^{2} \beta A_{1}^{3} \\
&-3 c^{2} n \mu B_{1}^{2}-4 n^{2} \gamma \mu B_{1}^{4}+3 n^{2} \beta A_{1} B_{1}^{2}+3 c^{2} n \mu^{3} B_{1}^{2}
\end{aligned}
$$

$$
\begin{align*}
& +12 n^{2} \gamma A_{0} A_{1} B_{1}^{2}-3 n^{2} \beta \mu^{2} A_{1} B_{1}^{2}+R c^{2} n \mu A_{1}^{2} \\
& -4 R n^{2} \gamma A_{0} A_{1}^{3}-2 c^{2} n \mu^{2} A_{0} A_{1} \\
& +12 R n^{2} \gamma \mu A_{1}^{2} B_{1}^{2}-12 n^{2} \gamma \mu^{2} A_{0} A_{1} B_{1}^{2}=0, \\
& \sigma^{3} \tau:-2 c^{2} n \mu^{2} A_{1} B_{1}+2 c^{2} n A_{1} B_{1}-2 c^{2} \mu^{2} A_{1} B_{1} \\
& +2 c^{2} A_{1} B_{1}-4 \gamma n^{2} \mu^{2} A_{1} B_{1}^{3}-4 R \gamma n^{2} A_{1}^{3} B_{1} \\
& +4 \gamma n^{2} A_{1} B_{1}^{3}=0, \\
& \sigma^{2}: R^{2}\left(-c^{2} A_{1}^{2}-6 \gamma n^{2} A_{1}^{2} B_{1}^{2}\right) \\
& +R\left(3 c^{2} n \mu A_{0} A_{1}+2 c^{2} n B_{1}^{2}-c^{2} \mu^{2} B_{1}^{2}\right. \\
& -6 \gamma n^{2} \mu^{2} B_{1}^{4}+24 \gamma n^{2} \mu A_{0} A_{1} B_{1}^{2} \\
& +6 \beta n^{2} \mu A_{1} B_{1}^{2}-6 \gamma n^{2} A_{0}^{2} A_{1}^{2}-3 \beta n^{2} A_{0} A_{1}^{2} \\
& \left.-\alpha n^{2} A_{1}^{2}+2 \mu n^{2} B_{1}^{4}+c^{2} n^{2} A_{1}^{2}-3 c^{2} n \mu^{2} B_{1}^{2}\right) \\
& +c^{2} n^{2} \mu^{2} B_{1}^{2}-c^{2} n^{2} B_{1}^{2}-6 \gamma n^{2} \mu^{2} A_{0}^{2} B_{1}^{2} \\
& -3 \beta n^{2} \mu^{2} A_{0} B_{1}^{2}-\alpha n^{2} \mu^{2} B_{1}^{2}+6 \gamma n^{2} A_{0}^{2} B_{1}^{2} \\
& +3 \beta n^{2} A_{0} B_{1}^{2}+\alpha n^{2} B_{1}^{2}=0, \\
& \sigma^{2} \tau: n^{2} \beta B_{1}^{3}+2 c^{2} n A_{0} B_{1}-n^{2} \beta \mu^{2} B_{1}^{3} \\
& +4 n^{2} \gamma A_{0} B_{1}^{3}+2 R c^{2} \mu A_{1} B_{1}-4 n^{2} \gamma \mu^{2} A_{0} B_{1}^{3} \\
& -3 R n^{2} \beta A_{1}^{2} B_{1}-2 c^{2} n \mu^{2} A_{0} B_{1}-12 R n^{2} \gamma A_{0} A_{1}^{2} B_{1} \\
& +2 R c^{2} n \mu A_{1} B_{1}+8 R n^{2} \gamma \mu A_{1} B_{1}^{3}=0, \\
& \sigma: 2 c^{2} n^{2} A_{0} A_{1}-2 n^{2} \alpha A_{0} A_{1}+2 n^{2} \alpha \mu B_{1}^{2} \\
& -3 n^{2} \beta A_{0}^{2} A_{1}-4 n^{2} \gamma A_{0}^{3} A_{1}-2 c^{2} n^{2} \mu B_{1}^{2} \\
& -R c^{2} n A_{0} A_{1}+12 n^{2} \gamma \mu A_{0}^{2} B_{1}^{2}+R c^{2} n \mu B_{1}^{2} \\
& +4 R n^{2} \gamma \mu B_{1}^{4}-3 R n^{2} \beta A_{1} B_{1}^{2}+6 n^{2} \beta \mu A_{0} B_{1}^{2} \\
& -12 R n^{2} \gamma A_{0} A_{1} B_{1}^{2}=0, \\
& \sigma \tau: 2 c^{2} n^{2} A_{1} B_{1}-2 n^{2} \alpha A_{1} B_{1}+2 n^{2} \beta \mu B_{1}^{3} \\
& -12 n^{2} \gamma A_{0}^{2} A_{1} B_{1}-R c^{2} n A_{1} B_{1}+c^{2} n \mu A_{0} B_{1} \\
& -6 n^{2} \beta A_{0} A_{1} B_{1}-4 R n^{2} \gamma A_{1} B_{1}^{3}+8 n^{2} \gamma \mu A_{0} B_{1}^{3}=0, \\
& \tau: 2 c^{2} n^{2} A_{0} B_{1}-4 \gamma n^{2} A_{0}^{3} B_{1}-3 \beta n^{2} A_{0}^{2} B_{1} \\
& -4 R \gamma n^{2} A_{0} B_{1}^{3}-2 \alpha n^{2} A_{0} B_{1}-R \beta n^{2} B_{1}^{3}=0, \\
& \sigma^{0}: c^{2} n^{2} A_{0}^{2}-n^{2} \alpha A_{0}^{2}-n^{2} \beta A_{0}^{3}-n^{2} \gamma A_{0}^{4} \\
& -R n^{2} \alpha B_{1}^{2}+R c^{2} n^{2} B_{1}^{2}-R^{2} n^{2} \gamma B_{1}^{4} \\
& -6 R n^{2} \gamma A_{0}^{2} B_{1}^{2}-3 R n^{2} \beta A_{0} B_{1}^{2}=0 . \tag{22}
\end{align*}
$$

On solving the above algebraic equations using the Maple or Mathematica, we get the following results.

Case 1. We have

$$
\begin{gather*}
A_{0}=0, \quad A_{1}=-\frac{\beta(n+1)\left(\mu^{2}-1\right)}{\mu \gamma R(n+2)}, \\
B_{1}=0, \quad c= \pm \frac{\beta n}{\mu(n+2)} \sqrt{-\frac{(n+1)\left(\mu^{2}-1\right)}{\gamma R}},  \tag{23}\\
\mu=\mu, \quad \alpha=\frac{\left(R-n^{2}\right)(n+1)\left(\mu^{2}-1\right)}{\mu^{2} \gamma R(n+2)^{2}} .
\end{gather*}
$$

From (14), (19), (21), and (23), we deduce the following exact solutions:

$$
\begin{align*}
& u_{11}=\left[-\frac{\beta(n+1)\left(\mu^{2}-1\right)}{\mu \gamma(n+2)}\left(\frac{\operatorname{sech}(\sqrt{R} \xi)}{\mu \operatorname{sech}(\sqrt{R} \xi)+1}\right)\right]^{1 / n},  \tag{24}\\
& u_{12}=\left[-\frac{\beta(n+1)\left(\mu^{2}-1\right)}{\mu \gamma(n+2)}\left(\frac{\operatorname{csch}(\sqrt{R} \xi)}{\mu \operatorname{csch}(\sqrt{R} \xi)+1}\right)\right]^{1 / n}, \tag{25}
\end{align*}
$$

where $\xi=x \pm(\beta n / \mu(n+2)) \sqrt{-\left((n+1)\left(\mu^{2}-1\right) / \gamma R\right)} t$.
Case 2. We have

$$
\begin{gather*}
A_{0}=-\frac{\beta(n+1)}{2 \gamma(n+2)}, \quad A_{1}=0 \\
B_{1}= \pm \frac{\beta(n+1)}{2 \gamma(n+2) \sqrt{R}}, \quad c= \pm \frac{\beta n}{2(n+2)} \sqrt{-\frac{(n+1)}{\gamma R}}  \tag{26}\\
\mu=0, \quad \alpha=\frac{\beta^{2}\left(4 R-n^{2}\right)(n+1)}{4 \gamma R(n+2)^{2}} .
\end{gather*}
$$

In this case, we deduce the following exact solutions:

$$
\begin{align*}
& u_{21}=\left[\frac{\beta(n+1)}{2 \gamma(n+2)}(-1 \pm \tanh (\sqrt{R} \xi))\right]^{1 / n},  \tag{27}\\
& u_{22}=\left[\frac{\beta(n+1)}{2 \gamma(n+2)}(-1 \pm \operatorname{coth}(\sqrt{R} \xi))\right]^{1 / n}, \tag{28}
\end{align*}
$$

where $\xi=x \pm(\beta n / 2(n+2)) \sqrt{-((n+1) / \gamma R)} t$.
Case 3. We have

$$
\begin{gather*}
A_{0}=-\frac{\beta(n+1)}{2 \gamma(n+2)}, \quad A_{1}= \pm \frac{\beta(n+1) \sqrt{\mu^{2}-1}}{2 \gamma R(n+2)}, \\
B_{1}= \pm \frac{\beta(n+1)}{2 \gamma(n+2) \sqrt{R}}, \quad \mu=\mu, \\
c= \pm \frac{\beta n}{(n+2)} \sqrt{-\frac{(n+1)}{\gamma R}}, \quad \alpha=\frac{\beta^{2}\left(R-n^{2}\right)(n+1)}{\gamma R(n+2)^{2}} . \tag{29}
\end{gather*}
$$

In this case, we deduce the following exact solutions:

$$
\begin{align*}
u_{31}= & {\left[\frac{\beta(n+1)}{2 \gamma(n+2)}\right.} \\
& \left.\times\left(-1 \pm \frac{\sqrt{\mu^{2}-1} \operatorname{sech}(\sqrt{R} \xi)+\tanh (\sqrt{R} \xi)}{\mu \operatorname{sech}(\sqrt{R} \xi)+1}\right)\right]^{1 / n},  \tag{30}\\
u_{32}= & {\left[\frac{\beta(n+1)}{2 \gamma(n+2)}\right.} \\
& \left.\times\left(-1 \pm \frac{\sqrt{\mu^{2}-1} \operatorname{csch}(\sqrt{R} \xi)+\operatorname{coth}(\sqrt{R} \xi)}{\mu \operatorname{csch}(\sqrt{R} \xi)+1}\right)\right]^{1 / n} \tag{31}
\end{align*}
$$

where $\xi=x \pm(\beta n /(n+2)) \sqrt{-((n+1) / \gamma R)} t$.
Example 2 (the nonlinear Burgers equation (2)). In this example, we study the Burgers equation with power-law nonlinearity (2). To this end, we see that the traveling wave variable (4) permits us to convert (2) into the following ODE:

$$
\begin{equation*}
-c u^{\prime}+a\left(u^{n}\right)^{\prime}+b u^{\prime \prime}=0 . \tag{32}
\end{equation*}
$$

Integrating (32) once with respect $\xi$ and setting the constant of integration to be zero yield

$$
\begin{equation*}
-c u+a u^{n}+b u^{\prime}=0 . \tag{33}
\end{equation*}
$$

By balancing $u^{\prime}$ with $u^{n}$ in (33) we get $m=1 /(n-1)$. According to Step 3, we use the transformation

$$
\begin{equation*}
u(\xi)=v^{1 /(n-1)}(\xi) \tag{34}
\end{equation*}
$$

where $v(\xi)$ is a new function of $\xi$. Substituting (34) into (33), we get the new ODE

$$
\begin{equation*}
-c(n-1) v+a(n-1) v^{2}+b v^{\prime}=0 \tag{35}
\end{equation*}
$$

Balancing $v^{\prime}$ with $v^{2}$ in (35), we get $m=1$. Consequently, we get

$$
\begin{equation*}
v(\xi)=A_{0}+A_{1} \sigma(\xi)+B_{1} \tau(\xi) \tag{36}
\end{equation*}
$$

where $A_{0}, A_{1}$, and $B_{1}$ are constants to be determined later.
Substituting (36) into (35) and using (8)-(9) with $\varepsilon=-1$, the left-hand side of (35) becomes a polynomial in $\sigma$ and $\tau$.

Setting the coefficients of this polynomial to be zero yields the following system of algebraic equations:

$$
\begin{align*}
& \sigma^{2}: b B_{1}+a B_{1}^{2}-a \mu^{2} B_{1}^{2}-R a A_{1}^{2} \\
& -a n B_{1}^{2}-b \mu^{2} B_{1}+a n \mu^{2} B_{1}^{2}+\operatorname{RanA} A_{1}^{2}=0,  \tag{43}\\
& \sigma: b \mu B_{1}-(n-1) c A_{1}+2(n-1) a A_{0} A_{1} \\
& -2(n-1) a \mu B_{1}^{2}=0,  \tag{37}\\
& \sigma \tau: 2(n-1) a A_{1} B_{1}-b A_{1}=0, \\
& \tau: 2(n-1) a A_{0} B_{1}-(n-1) c B_{1}=0, \\
& \sigma^{0}:(n-1) a A_{0}^{2}-(n-1) c A_{0}+(n-1) R a B_{1}^{2}=0 .
\end{align*}
$$

In this case, we deduce the following exact solutions:

$$
\begin{align*}
& u_{21}=\left[\frac{b \sqrt{R}}{a(n-1)}(\tanh (\sqrt{R} \xi) \pm 1)\right]^{1 /(n-1)}  \tag{42}\\
& u_{22}=\left[\frac{b \sqrt{R}}{a(n-1)}(\operatorname{coth}(\sqrt{R} \xi) \pm 1)\right]^{1 /(n-1)}
\end{align*}
$$

where $\xi=x \pm(2 b \sqrt{R} /(n-1)) t$.
Example 3 (the nonlinear generalized Zakharov-Kuznetsov equation (3)). In this example, we study the generalized Zakharov-Kuznetsov equation with power-law nonlinearity (3). To this end, we use the traveling wave variable

$$
\begin{equation*}
u(x, y, t)=u(\xi), \quad \xi=x+k y+s t, \tag{44}
\end{equation*}
$$

where $k$ and $s$ are nonzero constants, to reduce (3) to the following ODE:

$$
\begin{equation*}
s u^{\prime}+\left(A u^{p}+B u^{2 p}\right) u^{\prime}+C\left(1+k^{2}\right) u^{\prime \prime \prime}=0 . \tag{45}
\end{equation*}
$$

By balancing $u^{\prime \prime \prime}$ with $u^{2 p} u^{\prime}$ in (45) we get $m=1 / p$. According to Step 3, we use the transformation

$$
\begin{equation*}
u(\xi)=v^{1 / p}(\xi) \tag{46}
\end{equation*}
$$

where $v(\xi)$ is a new function of $\xi$. Substituting (46) into (45), we get the new ODE

$$
\begin{align*}
& C p^{2}\left(1+k^{2}\right) v^{2} v^{\prime \prime \prime}+3 C\left(-p^{2}+p-k^{2} p^{2}+k^{2} p\right) v v^{\prime} v^{\prime \prime} \\
& \quad+C\left(1-3 p-3 k^{2} p+2 p^{2}+k^{2}+2 k^{2} p^{2}\right)\left(v^{\prime}\right)^{3} \\
& \quad+\left(A v+s+B v^{2}\right) p^{2} v^{2} v^{\prime}=0 . \tag{47}
\end{align*}
$$

Balancing $v^{2} v^{\prime \prime \prime}$ with $v^{4} v^{\prime}$ in (47), we get $m=1$. Consequently, we get

$$
\begin{equation*}
v(\xi)=A_{0}+A_{1} \sigma(\xi)+B_{1} \tau(\xi), \tag{48}
\end{equation*}
$$

where $A_{0}, A_{1}$, and $B_{1}$ are constants to be determined later.
Substituting (48) into (47) and using (8)-(9) with $\varepsilon=-1$, the left-hand side of (47) becomes a polynomial in $\sigma$ and $\tau$. Setting the coefficients of this polynomial to be zero yields a system of algebraic equations in $A_{0}, A_{1}, B_{1}, \mu$, and $c$, which can be solved using the Maple or Mathematica; we get the following results.

Case 1. We have

$$
\begin{gather*}
A_{0}=0, \quad A_{1}=-\frac{A(2 p+1)\left(\mu^{2}-1\right)}{\mu B R(p+2)}, \\
B_{1}=0, \quad \mu=\mu, \quad s=\frac{A^{2}(2 p+1)\left(\mu^{2}-1\right)}{\mu^{2} B(p+2)^{2}(p+1)},  \tag{49}\\
k= \pm \sqrt{-\frac{A^{2} p^{2}(2 p+1)\left(\mu^{2}-1\right)}{\mu^{2} R B C(p+2)^{2}(p+1)}-1}
\end{gather*}
$$

From (14), (46), (48), and (49), we deduce the following exact solutions:

$$
\begin{align*}
& u_{11}=\left[-\frac{A(2 p+1)\left(\mu^{2}-1\right)}{\mu B(p+2)}\left(\frac{\operatorname{sech}(\sqrt{R} \xi)}{\mu \operatorname{sech}(\sqrt{R} \xi)+1}\right)\right]^{1 / p},  \tag{50}\\
& u_{12}=\left[-\frac{A(2 p+1)\left(\mu^{2}-1\right)}{\mu B(p+2)}\left(\frac{\operatorname{csch}(\sqrt{R} \xi)}{\mu \operatorname{csch}(\sqrt{R} \xi)+1}\right)\right]^{1 / p}, \tag{51}
\end{align*}
$$

where $\xi=x+k y+s t, k=$ $\pm \sqrt{-\left(A^{2} p^{2}(2 p+1)\left(\mu^{2}-1\right) / \mu^{2} R B C(p+2)^{2}(p+1)\right)-1}$, $s=\left(A^{2}(2 p+1)\left(\mu^{2}-1\right) / \mu^{2} B(p+2)^{2}(p+1)\right)$.

Case 2. We have

$$
\begin{gather*}
A_{0}=-\frac{A(2 p+1)}{2 B(p+2)}, \quad A_{1}=0 \\
B_{1}= \pm \frac{A(2 p+1)}{2 B(p+2) \sqrt{R}}, \quad \mu=1 \\
\quad s=\frac{A^{2}(2 p+1)}{B(p+2)^{2}(p+1)}  \tag{52}\\
k= \pm \sqrt{-\frac{A^{2} p^{2}(2 p+1)}{R B C(p+2)^{2}(p+1)}-1}
\end{gather*}
$$

In this case, we have the exact solutions

$$
\begin{align*}
& u_{21}=\left[\frac{A(2 p+1)}{2 B(p+2)}\left(-1 \pm \frac{\tanh (\sqrt{R} \xi)}{\operatorname{sech}(\sqrt{R} \xi)+1}\right)\right]^{1 / p}  \tag{53}\\
& u_{22}=\left[\frac{A(2 p+1)}{2 B(p+2)}\left(-1 \pm \frac{\operatorname{coth}(\sqrt{R} \xi)}{\operatorname{csch}(\sqrt{R} \xi)+1}\right)\right]^{1 / p}, \tag{54}
\end{align*}
$$

where $\xi=x+k y+s t, k$ $\pm \sqrt{-\left(A^{2} p^{2}(2 p+1) / R B C(p+2)^{2}(p+1)\right)-1}, \quad s$ $\left(A^{2}(2 p+1) / B(p+2)^{2}(p+1)\right)$.

Case 3. We have

$$
\begin{gathered}
A_{0}=-\frac{A(2 p+1)}{2 B(p+2)}, \quad A_{1}=0 \\
B_{1}= \pm \frac{A(2 p+1)}{2 B(p+2) \sqrt{R}} \\
\mu=-1, \quad s=\frac{A^{2}(2 p+1)}{B(p+2)^{2}(p+1)} \\
k= \pm \sqrt{-\frac{A^{2} p^{2}(2 p+1)}{R B C(p+2)^{2}(p+1)}-1}
\end{gathered}
$$

In this case, we have the exact solutions

$$
\begin{align*}
& u_{31}=\left[\frac{A(2 p+1)}{2 B(p+2)}\left(-1 \pm \frac{\tanh (\sqrt{R} \xi)}{1-\operatorname{sech}(\sqrt{R} \xi)}\right)\right]^{1 / p},  \tag{56}\\
& u_{32}=\left[\frac{A(2 p+1)}{2 B(p+2)}\left(-1 \pm \frac{\operatorname{coth}(\sqrt{R} \xi)}{1-\operatorname{csch}(\sqrt{R} \xi)}\right)\right]^{1 / p}, \tag{57}
\end{align*}
$$

where $\xi=x+k y+s t, k=$ $\pm \sqrt{-\left(A^{2} p^{2}(2 p+1) / R B C(p+2)^{2}(p+1)\right)-1}, \quad s=$ $\left(A^{2}(2 p+1) / B(p+2)^{2}(p+1)\right)$.

Case 4. We have

$$
\begin{gather*}
A_{0}=-\frac{A(2 p+1)}{2 B(p+2)}, \quad A_{1}=0, \\
B_{1}= \pm \frac{A(2 p+1)}{2 B(p+2) \sqrt{R}}, \\
\mu=0, \quad s=\frac{A^{2}(2 p+1)}{B(p+2)^{2}(p+1)}  \tag{58}\\
k= \pm \sqrt{-\frac{A^{2} p^{2}(2 p+1)}{4 R B C(p+2)^{2}(p+1)}-1 .}
\end{gather*}
$$

In this case, we have the exact solutions

$$
\begin{align*}
& u_{41}=\left[\frac{A(2 p+1)}{2 B(p+2)}(-1 \pm \tanh (\sqrt{R} \xi))\right]^{1 / p}  \tag{59}\\
& u_{42}=\left[\frac{A(2 p+1)}{2 B(p+2)}(-1 \pm \operatorname{coth}(\sqrt{R} \xi))\right]^{1 / p} \tag{60}
\end{align*}
$$

where $\xi=x+k y+s t, k=$
$\pm \sqrt{-\left(A^{2} p^{2}(2 p+1) / 4 R B C(p+2)^{2}(p+1)\right)-1}$,
$=\left(A^{2}(2 p+1) / B(p+2)^{2}(p+1)\right)$.
Case 5. We have

$$
\begin{gather*}
A_{0}=-\frac{A(2 p+1)}{2 B(p+2)}, \quad A_{1}= \pm \frac{A(2 p+1) \sqrt{\mu^{2}-1}}{2 B R(p+2)}, \\
B_{1}= \pm \frac{A(2 p+1)}{2 B(p+2) \sqrt{R}}, \quad \mu=\mu \\
s=\frac{A^{2}(2 p+1)}{B(p+2)^{2}(p+1)},  \tag{61}\\
k= \pm \sqrt{-\frac{A^{2} p^{2}(2 p+1)}{R B C(p+2)^{2}(p+1)}-1}
\end{gather*}
$$



Figure 1: The plot of solution (24) with $\beta=R=1, \mu=n=2$, and $\gamma=-1$.


Figure 2: The plot of solution (27) with $\beta=R=n=1$, and $\gamma=-1$.

In this case, we have the exact solutions

$$
\begin{align*}
u_{51}= & \frac{A(2 p+1)}{2 B(p+2)} \\
& \left.\quad \times\left(-1 \pm \frac{\sqrt{\mu^{2}-1} \operatorname{sech}(\sqrt{R} \xi)+\tanh (\sqrt{R} \xi)}{\mu \operatorname{sech}(\sqrt{R} \xi)+1}\right)\right]^{1 / p}, \tag{62}
\end{align*}
$$



Figure 3: The plot of solution (30) with $\beta=R=1, \mu=n=2$, and $\gamma=-1$.

$$
\begin{align*}
u_{52}= & {\left[\frac{A(2 p+1)}{2 B(p+2)}\right.} \\
& \left.\times\left(-1 \pm \frac{\sqrt{\mu^{2}-1} \operatorname{csch}(\sqrt{R} \xi)+\operatorname{coth}(\sqrt{R} \xi)}{\mu \operatorname{csch}(\sqrt{R} \xi)+1}\right)\right]^{1 / p}, \tag{63}
\end{align*}
$$

where $\xi=x+k y+s t, k=$ $\pm \sqrt{-\left(A^{2} p^{2}(2 p+1) / R B C(p+2)^{2}(p+1)\right)-1}, \quad s=$ $\left(A^{2}(2 p+1) / B(p+2)^{2}(p+1)\right)$.

## 4. Physical Explanations of Some Obtained Solutions

In this section, we have presented some graphs of the obtained solutions constructed by taking suitable values of involved unknown parameters to visualize the underlying mechanism of the original equation. Using mathematical software Maple, three-dimensional plots of some obtained exact solutions have been shown in Figures 1, 2, 3, 4, 5, 6, 7, and 8.
4.1. The Nonlinear Pochhammer-Chree Equation (1). The obtained solutions for this equation are hyperbolic. From these explicit results it is easy to say that the solution (24) is a bell shaped soliton solution; (25) is a singular bell shaped soliton solution; (27) is a kink shaped soliton solution; (28) is a singular kink shaped soliton solution; (30) is a bell-kink shaped soliton solution; and (31) is a singular bell-kink shaped soliton solution.
4.2. The Nonlinear Burgers Equation (2). From the obtained solutions for the nonlinear Burgers equation (2) we observe


Figure 4: The plot of solution (31) with $\beta=R=2, \mu=3, n=1$, and $\gamma=-1$.


Figure 5: The plot of solution (39) with $a=n=\mu=2, b=R=1$.
that the solution (39) is a bell-kink shaped soliton solution; (40) is a singular bell-kink shaped soliton solution; (42) is a kink shaped soliton solution; and (43) is a singular kink shaped soliton solution.

### 4.3. The Generalized Nonlinear Zakharov-Kuznetsov Equation

(3). From the obtained solutions for the generalized nonlinear Zakharov-Kuznetsov equation (3) we can easily conclude that the solution (50) is a bell shaped soliton solution; (51) is a singular bell shaped soliton solution; (53), (56), and (62) are bell-kink shaped solitons solutions; (54), (57), and (63) are singular bell-kink shaped solitons solutions; (59) is a kink shaped soliton solution; and (60) is a singular kink shaped soliton solution.


Figure 6: The plot of solution (42) with $a=b=1, R=n=2$.


Figure 7: The plot of solution (51) with $p=1, A=R=2, B=\mu=3$, and $k=0$.

## 5. Conclusions

The generalized projective Riccati equations method is used in this paper to obtain some new exact solutions of some nonlinear evolution equations with any-order nonlinear terms, namely, the nonlinear Pochhammer-Chree equation, the nonlinear Burgers equation, and the generalized ZakharovKuznetsov equation. On comparing our results in this paper with the well-known results obtained in [32, 33, 41-44] we deduce that our results are different and new and are not published elsewhere. The proposed method of this paper


Figure 8: The plot of solution (60) with $p=1, A=6 \sqrt{2}, R=B=3$, and $k=0$.
is effective and can be applied to many other nonlinear equations in mathematical physics.

## Conflict of Interests

The authors declare that there is no conflict of interests regarding the publication of this paper.

## References

[1] M. J. Ablowitz and P. A. Clarkson, Solitons, Nonlinear Evolution Equations and Inverse Scattering Transform, vol. 149 of New York, NY, USA, Cambridge University Press, 1991.
[2] E. M. E. Zayed and M. A. M. Abdelaziz, "Exact solutions for the nonlinear Schrödinger equation with variable coefficients using the generalized extended tanh-function, the sine-cosine and the exp-function methods," Applied Mathematics and Computation, vol. 218, no. 5, pp. 2259-2268, 2011.
[3] E. M. E. Zayed, H. A. Zedan, and K. A. Gepreel, "Group analysis and modified extended tanh-function to find the invariant solutions and soliton solutions for nonlinear Euler equations," International Journal of Nonlinear Sciences and Numerical Simulation, vol. 5, no. 3, pp. 221-234, 2004.
[4] A. M. Wazwaz, "The extended tanh method for abundant solitary wave solutions of nonlinear wave equations," Applied Mathematics and Computation, vol. 187, no. 2, pp. 1131-1142, 2007.
[5] E. M. E. Zayed and M. A. M. Abdelaziz, "The tanh function method using a generalized wave transformation for nonlinear equations," International Journal of Nonlinear Sciences and Numerical Simulation, vol. 11, no. 8, pp. 595-601, 2010.
[6] S. A. El-Wakil and M. A. Abdou, "New exact travelling wave solutions using modified extended tanh-function method," Chaos, Solitons \& Fractals, vol. 31, no. 4, pp. 840-852, 2007.
[7] E. Fan, "Extended tanh-function method and its applications to nonlinear equations," Physics Letters $A$, vol. 277, no. 4-5, pp. 212-218, 2000.
[8] S. Zhang and T. Xia, "A further improved tanh-function method exactly solving the $(2+1)$-dimensional dispersive long wave equations," Applied Mathematics E-Notes, vol. 8, pp. 58-66, 2008.
[9] R. Hirota, "Exact solution of the korteweg-de vries equation for multiple collisions of solitons," Physical Review Letters, vol. 27, no. 18, pp. 1192-1194, 1971.
[10] J. Weiss, M. Tabor, and G. Carnevale, "The Painlevé property for partial differential equations," Journal of Mathematical Physics, vol. 24, no. 3, pp. 522-526, 1983.
[11] N. A. Kudryashov, "Exact soliton solutions of a generalized evolution equation of wave dynamics," Journal of Applied Mathematics and Mechanics, vol. 52, pp. 361-365, 1988.
[12] N. A. Kudryashov, "Exact solutions of the generalized Kuramoto-Sivashinsky equation," Physics Letters A, vol. 147, no. 5-6, pp. 287-291, 1990.
[13] N. A. Kudryashov, "On types of nonlinear nonintegrable equations with exact solutions," Physics Letters. A, vol. 155, no. 4-5, pp. 269-275, 1991.
[14] M. R. Miura, Backlund Transformation, Springer, Berlin, Germany, 1978.
[15] C. Rogers and W. F. Shadwick, Backlund Transformations and Their Applications, Academic Press, New York, NY, USA, 1982.
[16] J.-H. He and X.-H. Wu, "Exp-function method for nonlinear wave equations," Chaos, Solitons \& Fractals, vol. 30, no. 3, pp. 700-708, 2006.
[17] E. Yusufoglu, "New solitonary solutions for the MBBM equations using Exp-function method," Physics Letters A, vol. 372, no. 4, pp. 442-446, 2008.
[18] S. Zhang, "Application of Exp-function method to highdimensional nonlinear evolution equation," Chaos, Solitons and Fractals, vol. 38, no. 1, pp. 270-276, 2008.
[19] A. Bekir, "The exp-function method for Ostrovsky equation," International Journal of Nonlinear Sciences and Numerical Simulation, vol. 10, no. 6, pp. 735-739, 2009.
[20] A. Bekir, "Application of the exp-function method for nonlinear differential-difference equations," Applied Mathematics and Computation, vol. 215, no. 11, pp. 4049-4053, 2010.
[21] Y. Chen and Q. Wang, "Extended Jacobi elliptic function rational expansion method and abundant families of Jacobi elliptic function solutions to ( $1+1$ )-dimensional dispersive long wave equation," Chaos, Solitons and Fractals, vol. 24, no. 3, pp. 745-757, 2005.
[22] S. Liu, Z. Fu, and Q. Zhao, "Jacobi elliptic function expansion method and periodic wave solutions of nonlinear wave equations," Physics Letters A, vol. 289, no. 1-2, pp. 69-74, 2001.
[23] D. Lü, "Jacobi elliptic function solutions for two variant Boussinesq equations," Chaos, Solitons and Fractals, vol. 24, no. 5, pp. 1373-1385, 2005.
[24] B. Li and Y. Chen, "Nonlinear partial differential equations solved by projective riccati equations ansatz," Zeitschrift für Naturforschung, vol. 58, no. 9-10, pp. 511-519, 2003.
[25] B. Li and Y. Chen, "On exact solutions of the nonlinear Schrödinger equations in optical fiber," Chaos, Solitons and Fractals, vol. 21, no. 1, pp. 241-247, 2004.
[26] D. Lu, B. Hong, and L. Tian, "New explicit exact solutions for the generalized coupled Hirota-Satsuma KdV system," Computers
\& Mathematics with Applications, vol. 53, no. 8, pp. 1181-1190, 2007.
[27] M. Wang, X. Li, and J. Zhang, "The $\left(G^{\prime} / G\right)$-expansion method and travelling wave solutions of nonlinear evolution equations in mathematical physics," Physics Letters A, vol. 372, no. 4, pp. 417-423, 2008.
[28] S. Zhang, J. L. Tong, and W. Wang, "A generalized ( $\mathrm{G}^{\prime} / \mathrm{G}$ )expansion method for the mKdV equation with variable coefficients," Physics Letters A, vol. 372, pp. 2254-2257, 2008.
[29] E. M. E. Zayed and K. A. Gepreel, "The $\left(G^{\prime} / G\right)$-expansion method for finding traveling wave solutions of nonlinear partial differential equations in mathematical physics," Journal of Mathematical Physics, vol. 50, no. 1, Article ID 013502, 12 pages, 2009.
[30] E. M. E. Zayed, "The $G^{\prime} / G$-expansion method and its applications to some nonlinear evolution equations in the mathematical physics," Journal of Applied Mathematics and Computing, vol. 30, no. 1-2, pp. 89-103, 2009.
[31] A. Bekir, "Application of the $\left(G^{\prime} / G\right)$-expansion method for nonlinear evolution equations," Physics Letters $A$, vol. 372, no. 19, pp. 3400-3406, 2008.
[32] J.-M. Zuo, "Application of the extended $\left(G^{\prime} / G\right)$-expansion method to solve the Pochhammer-Chree equations," Applied Mathematics and Computation, vol. 217, no. 1, pp. 376-383, 2010.
[33] M. Hayek, "Constructing of exact solutions to the KdV and Burgers equations with power-law nonlinearity by the extended $\left(G^{\prime} / G\right)$-expansion method," Applied Mathematics and Computation, vol. 217, no. 1, pp. 212-221, 2010.
[34] L. Li, E. Li, and M. Wang, "The ( $\left.\mathrm{G}^{\prime} / \mathrm{G}, 1 / \mathrm{G}\right)$-expansion method and its application to travelling wave solutions of the Zakharov equations," Applied Mathematics, vol. 25, no. 4, pp. 454-462, 2010.
[35] E. M. E. Zayed and M. A. M. Abdelaziz, "The two-variable ( $G^{\prime} / G, 1 / G$ )-expansion method for solving the nonlinear KDVmKDV Equation," Mathematical Problems in Engineering, vol. 2012, Article ID 725061, 14 pages, 2012.
[36] E. M. E. Zayed, S. A. H. Ibrahim, and M. A. M. Abdelaziz, "Traveling wave solutions of the nonlinear $(3+1)$ dimensional Kadomtsev-Petviashvili equation using the two variables $\left(G^{\prime} / G, 1 / G\right)$-expansion method," Journal of Applied Mathematics, vol. 2012, Article ID 560531, 8 pages, 2012.
[37] R. Conte and M. Musette, "Link between solitary waves and projective Riccati equations," Journal of Physics A: Mathematical and General, vol. 25, no. 21, pp. 5609-5623, 1992.
[38] T. C. Bountis, V. Papageorgiou, and P. Winternitz, "On the integrability of systems of nonlinear ordinary differential equations with superposition principles," Journal of Mathematical Physics, vol. 27, no. 5, pp. 1215-1224, 1986.
[39] G. X. Zhang, Z. B. Li, and Y. S. Duan, "Exact solitary wave solutions of nonlinear wave equations," Science in China A, vol. 44, no. 3, pp. 396-401, 2001.
[40] Z. Y. Yan, "Generalized method and its application in the higher-order nonlinear Schrodinger equation in nonlinear optical fibres," Chaos, Solitons and Fractals, vol. 16, no. 5, pp. 759-766, 2003.
[41] A. M. Wazwaz, "The tanh-coth and the sine-cosine methods for kinks, solitons, and periodic solutions for the PochhammerChree equations," Applied Mathematics and Computation, vol. 195, no. 1, pp. 24-33, 2008.
[42] A.-M. Wazwaz, "Tavelling wave solutions of generalized forms of Burgers, Burgers-KdV and Burgers-Huxley equations," Applied Mathematics and Computation, vol. 169, no. 1, pp. 639656, 2005.
[43] N. Hongsit, M. A. Allen, and G. Rowlands, "Growth rate of transverse instabilities of solitary pulse solutions to a family of modified Zakharov-Kuznetsov equations," Physics Letters A, vol. 372, no. 14, pp. 2420-2422, 2008.
[44] L. Zhang, "Travelling wave solutions for the generalized Zakharov-Kuznetsov equation with higher-order nonlinear terms," Applied Mathematics and Computation, vol. 208, no. 1, pp. 144-155, 2009.

