

## Research Article

# An Unfitted Discontinuous Galerkin Method for Elliptic Interface Problems

Qiuliang Wang<sup>1,2</sup> and Jinru Chen<sup>1</sup>

<sup>1</sup> Jiangsu Key Laboratory for NSLSCS, School of Mathematical Sciences, Nanjing Normal University, Nanjing 210023, China

<sup>2</sup> School of Mathematics and Information Science, Shangqiu Normal University, Shangqiu 476000, China

Correspondence should be addressed to Jinru Chen; jrchen@njnu.edu.cn

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An unfitted discontinuous Galerkin method is proposed for the elliptic interface problems. Based on a variant of the local discontinuous Galerkin method, we obtain the optimal convergence for the exact solution  $u$  in the energy norm and its flux  $\mathbf{p}$  in the  $L^2$  norm. These results are the same as those in the case of elliptic problems without interface. Finally, some numerical experiments are presented to verify our theoretical results.

## 1. Introduction

Elliptic interface problems are often encountered in many multiphysics and multiphase applications in science computing and engineering. For example, second order elliptic equations with discontinuous coefficients are often used to model problems in material sciences and fluid dynamics when two or more distinct materials or fluids with different conductivities, densities, or permeability are involved. It is well known that, when the interface is smooth enough, the solution of elliptic interface problems has higher regularity in individual material or fluid region than in the entire physical domain.

To numerically solve such interface problems, first we need to generate a mesh. One approach is to use a body fitted mesh. However, for those problems where the interface moves with time, repeated remeshing of the domain to obtain a fitted mesh is very costly. Another one is to use an unfitted grid independent of the location of the interface. This technique is particularly preferred to simulate time-dependent problems with moving interfaces. The major advantage for using an unfitted mesh is that it avoids repeatedly remeshing the domain for fitting the moving interfaces.

As for fitted mesh method for elliptic problems with interface, Chen and Zou in [1] considered the finite element method for solving elliptic and parabolic interface problems, and almost-optimal error estimates in the  $L^2$  norm and

energy norm were obtained. In [2], the authors studied a class of discontinuous Galerkin method for elliptic interface problems, which was shown to be optimally convergent in  $L^2$  norm. Recently, a high-order HDG method was presented to solve elliptic interface problems by Huynh et al. in [3], which was extended to solve Stokes interface flow in [4].

Various unfitted grid methods for interface problems have been proposed in the literature. Finite difference methods are very popular unfitted grid methods due to their simplicity, for example, the immersed interface method [5, 6], the immersed boundary method [7], the boundary condition capturing method [8], and many others. And there exist many works for finite element methods on unfitted grid as well. Babuška in [9] studied the elliptic interface problem on unfitted mesh and derived suboptimal convergence behavior. Li et al. proposed an immersed interface finite element method in [10], which modified the basis functions near interface to satisfy the homogeneous jump conditions. Later, this method was applied to elliptic and elasticity interface problems with nonhomogeneous jump conditions in [11, 12]. Recently, an unfitted finite element method based on Nitsche's method was presented by A. Hansbo and P. Hansbo in [13] and optimal order of convergence was proved without restrictions on the location of the interface relative to the mesh, which was used to solve incompressible elasticity with discontinuous modulus in [14]. More recently, Massjung in [15] considered an  $hp$  unfitted discontinuous Galerkin

method which was viewed as a generalization of Hansbo's method in [13]. An optimal convergence rate with respect to  $h$  and a suboptimal convergence rate with respect to  $p$  in energy norm were proved. Later, Wu and Xiao also presented an unfitted  $hp$  interface penalty finite element method, which was extended to the three dimensional case in [16].

The local discontinuous Galerkin (LDG) method was proposed by Cockburn and Shu in [17] to solve general time-dependent convection-diffusion problems. Later, the method was carried to elliptic problems for mixed discontinuous Galerkin formulation by Castillo et al. in [18]. The purpose of this paper is to extend the LDG method to a class of elliptic problems with a smooth interface. However, employing an unfitted mesh method, the interface can divide regular grid cells into degenerated subcells. If this situation happens, the standard inverse estimates can no longer be valid. In this paper, we use the weighted average instead of the arithmetic average in the classic LDG method to retrieve the inverse estimates (see Lemmas 8 and 10). Thus, we propose an unfitted discontinuous Galerkin method, based on a variant of LDG method. We prove the optimal convergence rate of the method for the exact solution  $u$  in the energy norm and its flux  $\mathbf{p}$  in the  $L^2$  norm, respectively.

The rest of this paper is organized as follows. In Section 2 we propose our DG method and present some necessary preliminaries. We prove optimal order error estimates for our DG method in Section 3. In Section 4, some numerical experiments are presented to justify our theoretical results. Finally, conclusions are given in Section 5.

Let us now end this section with some notation to be used in this paper. We will use the standard notations for Sobolev spaces and norms in this paper (see [19, 20]). In particular, for a bounded open set  $\Omega$  in  $\mathbb{R}^2$ , if  $\Omega = \bigcup_{i=1}^m \Omega_i$  and  $\Omega_i \cap \Omega_j = \emptyset$  ( $i \neq j$ ), we denote by  $H^k(\bigcup_{i=1}^m \Omega_i)$  the Sobolev space of functions  $u$  such that  $u|_{\Omega_i} \in H^k(\Omega_i)$ , where  $H^k(\Omega_i)$  denotes the standard Sobolev space with norm  $\|\cdot\|_{k,\Omega_i}$ . As usual we define the broken norm:  $\|\cdot\|_{k,\Omega} = (\sum_{i=1}^m \|\cdot\|_{k,\Omega_i}^2)^{1/2}$ . Throughout the paper, the generic constant  $C$  is always independent of the mesh parameter  $h$ .

## 2. Discontinuous Galerkin Method and Preliminaries

Let  $\Omega$  be a bounded domain in  $\mathbb{R}^2$  with convex polygonal boundary  $\partial\Omega$  and  $\Omega^+ \subset \Omega$  an open domain with  $C^2$  boundary  $\Gamma = \partial\Omega^+ \subset \Omega$ . Let  $\Omega^- = \Omega \setminus \Omega^+$  (see Figure 1). We consider the following elliptic interface problem:

$$\begin{aligned} -\nabla \cdot (\beta \nabla u) &= f && \text{in } \Omega^+ \cup \Omega^-, \\ u &= 0 && \text{on } \partial\Omega, \\ [u] &= 0 && \text{on } \Gamma, \\ \left[ \beta \frac{\partial u}{\partial \mathbf{n}} \right] &= g && \text{on } \Gamma, \end{aligned} \quad (1)$$

where  $\mathbf{n}$  is the outward pointing unit normal to  $\Omega^+$  and  $[u] := u^+|_{\Gamma} - u^-|_{\Gamma}$  is the jump of  $u$  across the interface  $\Gamma$ , where  $u^\pm$  is the restrictions of  $u$  on  $\Omega^\pm$ . For the sake of

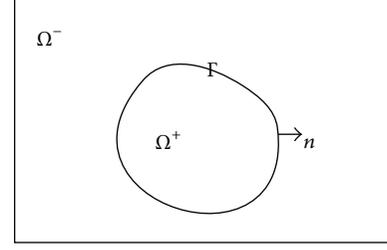


FIGURE 1: Domain  $\Omega$ , its subdomains  $\Omega^+$ ,  $\Omega^-$ , and interface  $\Gamma$ .

simplicity, we assume that the coefficient  $\beta$  is a positive and piecewise constant; that is,  $\beta|_{\Omega^\pm} = \beta^\pm > 0$ .

Regarding the regularity for the solution of the interface problem (1), we state without proof the following theorem.

**Theorem 1** (cf. [1]). *Assume that  $f \in L^2(\Omega)$  and  $g \in H^{1/2}(\Gamma)$ . Then problem (1) has a unique solution  $u \in H^2(\Omega^+ \cup \Omega^-)$ , and the following a priori estimate holds:*

$$\|u\|_{2,\Omega^+ \cup \Omega^-} \leq C (\|f\|_{0,\Omega} + \|g\|_{1/2,\Gamma}). \quad (2)$$

By introducing the flux  $\mathbf{p} = \beta \nabla u$ , the interface problem (1) can be rewritten into a first order system as

$$\begin{aligned} \frac{1}{\beta} \mathbf{p} &= \nabla u && \text{in } \Omega^+ \cup \Omega^-, \\ -\nabla \cdot \mathbf{p} &= f && \text{in } \Omega^+ \cup \Omega^-, \\ [u] &= 0 && \text{on } \Gamma, \\ [\mathbf{p} \cdot \mathbf{n}] &= g && \text{on } \Gamma, \\ u &= 0 && \text{on } \partial\Omega. \end{aligned} \quad (3)$$

Let  $\mathcal{T}_h$  be a shape regular and locally quasi-uniform simplicial triangulation of  $\Omega$ , generated independently of the location of the interface  $\Gamma$ . For the definition of shape regular and locally quasi-uniform, we refer to [20, 21]. Suppose  $\mathcal{T}_h$  to be made of straight triangles  $T$  with diameter  $h_T$ . As usual, let  $h := \max_{T \in \mathcal{T}_h} h_T$ . The set of edges of the triangulation  $\mathcal{T}_h$  is denoted by  $\mathcal{E}_h$ , and  $\mathcal{E}_h^o$  is the set of interior edges of  $\mathcal{T}_h$ . For any element  $T \in \mathcal{T}_h$ , denote the part of  $T$  in  $\Omega^\pm$  by  $T^\pm$ ; that is,  $T^\pm = T \cap \Omega^\pm$ . For any edge  $e \in \mathcal{E}_h$ , let  $e^\pm = e \cap \Omega^\pm$ . We call the elements whose interiors are cut through by  $\Gamma$  ‘‘interface elements’’, and denote the set of the interface elements by  $\mathcal{T}_h^o$ . For an interface element  $T \in \mathcal{T}_h^o$ , assume that  $\Gamma_T$  is the part of interface  $\Gamma$  intersecting  $T$ . For the geometrical features of the interface  $\Gamma$ , we give the following plausible assumptions (cf. [13, 15]).

*Assumption 2.* We assume that  $\Gamma$  intersects the boundary  $\partial T$  of an element  $T \in \mathcal{T}_h^o$  exactly twice and each (open) edge at most once.

*Assumption 3.* Let  $\Gamma_{T,h}$  be the straight line segment connecting the points of intersection between  $\Gamma$  and  $\partial T$ . We assume that  $\Gamma_T$  is a function of length on  $\Gamma_{T,h}$ , in local coordinates:

$$\begin{aligned} \Gamma_{T,h} &= \{(\xi, \eta) : 0 < \xi < |\Gamma_{T,h}|, \eta = 0\}, \\ \Gamma_T &= \{(\xi, \eta) : 0 < \xi < |\Gamma_{T,h}|, \eta = \delta(\xi)\}. \end{aligned} \quad (4)$$

*Assumption 4.* Suppose that  $e = T_1 \cap T_2$  with  $T_1, T_2 \in \mathcal{T}_h$ ; then there exist triangles  $S_1^\pm \subset T_1^\pm$  and  $S_2^\pm \subset T_2^\pm$  such that  $e^\pm = S_1^\pm \cap S_2^\pm$  and

$$|S_1^\pm| + |S_2^\pm| \geq C|e^\pm|^2. \quad (5)$$

To formulate our numerical scheme, first we define two usual discontinuous finite element spaces as

$$\begin{aligned} \widetilde{V}_h &= \{v_h \in L^2(\Omega) : v_h|_T \in P_k(T), \forall T \in \mathcal{T}_h\}, \\ \widetilde{\mathbf{W}}_h &= \{\mathbf{q}_h \in (L^2(\Omega))^2 : \mathbf{q}_h|_T \in P_k(T)^2, \forall T \in \mathcal{T}_h\}, \end{aligned} \quad (6)$$

where  $P_k(T)$  denotes the space of polynomials of degree less than or equal to  $k$  ( $k \geq 1$ ) on each element  $T$ .

We define our discontinuous finite element spaces as

$$\begin{aligned} V_h &= \{v_h : v_h|_{\Omega^\pm} = v_h^\pm, \text{ where } v_h^\pm \in \widetilde{V}_h\}, \\ \mathbf{W}_h &= \{\mathbf{q}_h : \mathbf{q}_h|_{\Omega^\pm} = \mathbf{q}_h^\pm, \text{ where } \mathbf{q}_h^\pm \in \widetilde{\mathbf{W}}_h\}. \end{aligned} \quad (7)$$

Following the notation of [22], let  $e$  be an interior edge shared by two triangles  $T_1$  and  $T_2$  in  $\mathcal{T}_h$ . For a scalar valued function  $v$ , piecewise smooth on  $\mathcal{T}_h$  with  $v_j = v|_{T_j}$ , we define the jump and the weighted average of  $v$  as

$$\begin{aligned} \llbracket v^\pm \rrbracket &= v_1^\pm \mathbf{n}_1 + v_2^\pm \mathbf{n}_2, \quad \{\{v^\pm\}\}_w = \mu_1^\pm v_1^\pm + \mu_2^\pm v_2^\pm, \\ \{\{v^\pm\}\}^w &= \mu_2^\pm v_1^\pm + \mu_1^\pm v_2^\pm \quad \text{on } e \in \mathcal{E}_h^o. \end{aligned} \quad (8)$$

Similarly, for a vector valued function  $\mathbf{w}$ , piecewise smooth on  $\mathcal{T}_h$  with  $\mathbf{w}_j = \mathbf{w}|_{T_j}$ , we set

$$\begin{aligned} \llbracket \mathbf{w}^\pm \rrbracket &= \mathbf{w}_1^\pm \cdot \mathbf{n}_1 + \mathbf{w}_2^\pm \cdot \mathbf{n}_2, \quad \{\{\mathbf{w}^\pm\}\}_w = \mu_1^\pm \mathbf{w}_1^\pm + \mu_2^\pm \mathbf{w}_2^\pm, \\ \{\{\mathbf{w}^\pm\}\}^w &= \mu_2^\pm \mathbf{w}_1^\pm + \mu_1^\pm \mathbf{w}_2^\pm \quad \text{on } e \in \mathcal{E}_h^o, \end{aligned} \quad (9)$$

where  $\mathbf{n}_j$  is the unit normal of  $e$  pointing towards the outside of  $T_j$  and  $\mu_j^\pm = |S_j^\pm|/(|S_1^\pm| + |S_2^\pm|)$ ,  $j = 1, 2$ . If  $e$  is an edge on the boundary of  $\Omega$ , we define on  $e$

$$\llbracket v \rrbracket = v\mathbf{n}, \quad \{\{\mathbf{w}\}\}_w = \mathbf{w}, \quad (10)$$

where  $\mathbf{n}$  denotes the unit outer normal of  $e$  pointing towards the outside of  $\Omega$ .

For the weight average across interface  $\Gamma$  of any piecewise smooth function  $v$  discontinuous on  $\Gamma$ , we set

$$\{v\}_w = \lambda^+ v^+ + \lambda^- v^-, \quad \{v\}^w = \lambda^- v^+ + \lambda^+ v^-, \quad (11)$$

where  $\lambda^+ + \lambda^- = 1$  whose specific definitions will be given in Lemma 10.

For simplicity, for  $T^\pm = T \cap \Omega^\pm$  and  $e^\pm = e \cap \Omega^\pm$ , we define

$$\begin{aligned} \langle v, w \rangle_T &:= (v^+, w^+)_{T^+} + (v^-, w^-)_{T^-}, \\ \langle v, w \rangle_e &:= (v^+, w^+)_{e^+} + (v^-, w^-)_{e^-}. \end{aligned} \quad (12)$$

Following [18], testing the problem (3) by  $\mathbf{q}_h \in \mathbf{W}_h$  and  $v_h \in V_h$ , respectively, using integration by parts and noting the identities  $\llbracket \mathbf{q}v \rrbracket = \llbracket v \rrbracket \{\{\mathbf{q}\}\}_w + \{\{v\}\}^w \llbracket \mathbf{q} \rrbracket$  and  $\langle v\mathbf{w} \rangle =$

$\{w\}_w [v] + \{v\}^w [w]$ , we obtain our DG method: find  $(\mathbf{q}_h, u_h) \in \mathbf{W}_h \times V_h$ , such that

$$\begin{aligned} &\sum_{T \in \mathcal{T}_h} \left\langle \frac{1}{\beta} \mathbf{p}_h, \mathbf{q}_h \right\rangle_T + \sum_{T \in \mathcal{T}_h} \langle u_h, \nabla \cdot \mathbf{q}_h \rangle_T \\ &\quad - \sum_{e \in \mathcal{E}_h^o} \langle \{\{u_h\}\}^w, \llbracket \mathbf{q}_h \rrbracket \rangle_e - \sum_{T \in \mathcal{T}_h^o} (\{u_h\}^w, [\mathbf{q}_h \cdot \mathbf{n}])_{\Gamma_T} = 0, \\ &\sum_{T \in \mathcal{T}_h} \langle \mathbf{p}_h, \nabla v_h \rangle_T - \sum_{e \in \mathcal{E}_h} \langle \{\{\mathbf{p}_h\}\}_w, \llbracket v_h \rrbracket \rangle_e \\ &\quad - \sum_{T \in \mathcal{T}_h^o} (\{\mathbf{p}_h \cdot \mathbf{n}\}_w, [v_h])_{\Gamma_T} \\ &\quad + \sum_{e \in \mathcal{E}_h} \left\langle \frac{\gamma}{|e^\pm|} \llbracket u_h \rrbracket, \llbracket v_h \rrbracket \right\rangle_e + \sum_{T \in \mathcal{T}_h^o} \frac{\gamma}{h_T} (\llbracket u_h \rrbracket, [v_h])_{\Gamma_T} \\ &= \sum_{T \in \mathcal{T}_h} \langle f, v_h \rangle_T + \sum_{T \in \mathcal{T}_h^o} (g, \{v_h\}^w)_{\Gamma_T}, \end{aligned} \quad (13)$$

for all  $(\mathbf{q}_h, v_h) \in \mathbf{W}_h \times V_h$ , where  $\gamma > 0$  is the stabilization parameter.

We define the bilinear and linear forms

$$\begin{aligned} a(\mathbf{p}_h, \mathbf{q}_h) &= \sum_{T \in \mathcal{T}_h} \left\langle \frac{1}{\beta} \mathbf{p}_h, \mathbf{q}_h \right\rangle_T, \\ b(v_h, \mathbf{p}_h) &= \sum_{T \in \mathcal{T}_h} \langle \mathbf{p}_h, \nabla v_h \rangle_T - \sum_{e \in \mathcal{E}_h} \langle \{\{\mathbf{p}_h\}\}_w, \llbracket v_h \rrbracket \rangle_e \\ &\quad - \sum_{T \in \mathcal{T}_h^o} (\{\mathbf{p}_h \cdot \mathbf{n}\}_w, [v_h])_{\Gamma_T}, \\ c(u_h, v_h) &= \sum_{e \in \mathcal{E}_h} \left\langle \frac{\gamma}{|e^\pm|} \llbracket u_h \rrbracket, \llbracket v_h \rrbracket \right\rangle_e \\ &\quad + \sum_{T \in \mathcal{T}_h^o} \frac{\gamma}{h_T} (\llbracket u_h \rrbracket, [v_h])_{\Gamma_T}, \\ F(v_h) &= \sum_{T \in \mathcal{T}_h} \langle f, v_h \rangle_T + \sum_{T \in \mathcal{T}_h^o} (g, \{v_h\}^w)_{\Gamma_T}. \end{aligned} \quad (14)$$

And integral by parts yields that

$$\begin{aligned} b(u_h, \mathbf{q}_h) &= - \sum_{T \in \mathcal{T}_h} \langle u_h, \nabla \cdot \mathbf{q}_h \rangle_T + \sum_{e \in \mathcal{E}_h^o} \langle \{\{u_h\}\}^w, \llbracket \mathbf{q}_h \rrbracket \rangle_e \\ &\quad + \sum_{T \in \mathcal{T}_h^o} (\{u_h\}^w, [\mathbf{q}_h \cdot \mathbf{n}])_{\Gamma_T}. \end{aligned} \quad (15)$$

Hence, our DG approximation can be written as the following mixed variational problem: find  $(\mathbf{q}_h, u_h) \in \mathbf{W}_h \times V_h$ , such that

$$\begin{aligned} a(\mathbf{p}_h, \mathbf{q}_h) - b(u_h, \mathbf{q}_h) &= 0 \quad \forall \mathbf{q}_h \in \mathbf{W}_h, \\ b(\mathbf{p}_h, v_h) + c(u_h, v_h) &= F(v_h) \quad \forall u_h \in V_h. \end{aligned} \quad (16)$$

For the exact  $u$  of the interface problem (1) and  $\mathbf{p} = \beta \nabla u$ , using Theorem 1, we have  $\llbracket u \rrbracket = 0$ ,  $\llbracket \mathbf{p} \rrbracket = 0$  on  $e \in \mathcal{E}_h^o$ , and  $[u] = 0$ ,  $[\mathbf{p} \cdot \mathbf{n}] = g$  across  $\Gamma$ . Then the following consistency property holds:

$$\begin{aligned} a(\mathbf{p}, \mathbf{q}_h) - b(u, \mathbf{q}_h) &= 0, \\ b(\mathbf{p}, v_h) + c(u, v_h) &= F(v_h). \end{aligned} \quad (17)$$

Let the mesh-dependent norm  $\|\cdot\|_h$  be defined by

$$\begin{aligned} \|v_h\|_h^2 &= \sum_{T \in \mathcal{T}_h} \|\nabla v_h\|_{0,T^\pm}^2 + \sum_{e \in \mathcal{E}_h} \frac{1}{|e^\pm|} \|\llbracket v_h \rrbracket\|_{0,e^\pm}^2 \\ &\quad + \sum_{T \in \mathcal{T}_h^o} \frac{1}{h_T} \|\llbracket v_h \rrbracket\|_{0,\Gamma_T}^2. \end{aligned} \quad (18)$$

**Theorem 5.** *Suppose that the stabilization parameter  $\gamma$  is positive; then the DG method (16) defines a unique approximate solution  $(\mathbf{p}_h, u_h) \in \mathbf{W}_h \times V_h$ .*

*Proof.* Since (16) is a square system, it is enough to show uniqueness. Let  $f = 0$ ,  $g = 0$ . Setting  $\mathbf{q}_h = \mathbf{p}_h$  and  $v_h = u_h$ , adding the two equations of (16), we have

$$a(\mathbf{p}_h, \mathbf{p}_h) + c(u_h, u_h) = 0, \quad (19)$$

which deduces  $\mathbf{p}_h \equiv 0$ ,  $\llbracket u_h \rrbracket = 0$  on  $\mathcal{E}_h$  and  $[u_h] = 0$  across  $\Gamma$ . As a consequence, the first equation of (16) becomes

$$\sum_{T \in \mathcal{T}_h} \langle \nabla u_h, \mathbf{q}_h \rangle = 0 \quad \forall \mathbf{q}_h \in \mathbf{W}_h. \quad (20)$$

Hence, taking  $\mathbf{q}_h = \nabla u_h$  implies  $\nabla u_h = 0$ . Since  $\llbracket u_h \rrbracket = 0$  on  $\mathcal{E}_h$  and  $[u_h] = 0$  across  $\Gamma$ , we conclude that  $u_h \equiv 0$ . This completes the proof.  $\square$

The following lemma comes from the famous Stein's extension theorem.

**Lemma 6** (cf. [19]). *There exist two extension operators  $E^\pm : H^k(\Omega^\pm) \rightarrow H^k(\Omega)$  for all nonnegative integers  $k$  such that*

$$(E^\pm v)|_{\Omega^\pm} = v, \quad \|E^\pm v\|_{H^k(\Omega)} \leq C \|v\|_{H^k(\Omega^\pm)}, \quad (21)$$

where  $v \in H^k(\Omega^\pm)$ .

Next, we state a standard approximation lemma.

**Lemma 7** (cf. [20, 21]). *Let  $u \in H^{k+1}(T)$ . Then for  $m = 0, 1$  there exists a linear continuous operator  $\Pi_T : H^{k+1}(T) \rightarrow P_k(T)$  such that*

$$\|u - \Pi_T u\|_{m,T} \leq Ch_T^{k+1-m} \|u\|_{k+1,T}, \quad (22)$$

$$\|u - \Pi_T u\|_{L^\infty(T)} \leq Ch_T^k \|u\|_{k+1,T}, \quad (23)$$

$$\|u - \Pi_T u\|_{0,\partial T} \leq Ch_T^{k+1/2} \|u\|_{k+1,T}. \quad (24)$$

The following two lemmas are variant inverse estimates involving interface  $\Gamma$  which play important role in our analysis.

**Lemma 8** (cf. [15]). *For  $e \in \mathcal{E}_h$  let  $e = T_1 \cap T_2$ ; then for  $\mathbf{q} \in \mathbf{W}_h$  the following inverse inequality holds:*

$$\|\{\{\mathbf{q}\}\}_w\|_{0,e^\pm}^2 \leq C |e^\pm|^{-1} \sum_{i=1}^2 \|\mathbf{q}\|_{0,T_i}^2. \quad (25)$$

**Lemma 9** (cf. [15, 16]). *The following estimate holds for either  $i = +$  or  $i = -$ , for any  $v \in P_k(T)$ :*

$$\|v\|_{0,\Gamma_T} \leq Ch_T^{-1/2} \|v\|_{0,T^i}. \quad (26)$$

By Lemma 9, we can immediately obtain the following result.

**Lemma 10.** *Let  $T \in \mathcal{T}_h^o$ ; then there exists a positive constant  $C$  such that*

$$\lambda^\pm \|v\|_{0,\Gamma_T} \leq Ch_T^{-1/2} \|v\|_{0,T^\pm}, \quad \forall v \in P_k(T), \quad (27)$$

where

$$\lambda^\pm = \begin{cases} \frac{1}{2} & \text{if (26) holds for both } T^\pm \text{ and } T^\mp, \\ 1 & \text{if (26) holds only for } T^\pm, \\ 0 & \text{if (26) holds only for } T^\mp. \end{cases} \quad (28)$$

**Lemma 11.** *Let  $T \in \mathcal{T}_h^o$  and  $v \in H^1(T)$ ; then we have*

$$\|v\|_{0,\Gamma_T} \leq C (h_T^{-1/2} \|v\|_{0,T} + h_T^{1/2} |v|_{1,T}). \quad (29)$$

*Proof.* Under Assumptions 2 and 3, the trace inequality (29) follows from Lemma 3 in [13] and a scaling argument.  $\square$

### 3. Error Estimate of Our DG Method

Now, we define interpolation operator  $\Pi$  by  $\Pi|_T := \Pi_T$  and  $\Pi := (\Pi, \Pi)$ . Let  $\xi_p^\pm = \mathbf{p}^\pm - \Pi E^\pm \mathbf{p}^\pm$ ,  $\eta_p^\pm = \Pi E^\pm \mathbf{p}^\pm - \mathbf{p}_h^\pm$  and  $\xi_u^\pm = u^\pm - \Pi E^\pm u^\pm$ ,  $\eta_u^\pm = \Pi E^\pm u^\pm - u_h^\pm$ . To obtain the convergence result, we need to show the following approximate error estimates.

**Lemma 12.** *Suppose that  $u \in H^{k+1}(\Omega^+ \cup \Omega^-)$  and  $\mathbf{p} \in (H^{k+1}(\Omega^+ \cup \Omega^-))^2$ ; then the following approximate estimates hold:*

$$\sum_{T \in \mathcal{T}_h} \|\xi_u\|_{0,T^\pm}^2 + \sum_{e \in \mathcal{E}_h} \frac{1}{|e^\pm|} \|\llbracket \xi_u \rrbracket\|_{0,e^\pm}^2 \quad (30)$$

$$+ \sum_{T \in \mathcal{T}_h^o} \frac{1}{h_T} \|\llbracket \xi_u \rrbracket\|_{0,\Gamma_T}^2 \leq Ch^{2k} \|u\|_{k+1,\Omega^+ \cup \Omega^-}^2,$$

$$\sum_{T \in \mathcal{T}_h} \|\xi_p\|_{0,T^\pm}^2 + \sum_{e \in \mathcal{E}_h} |e^\pm| \|\{\{\xi_p\}\}_w\|_{0,e^\pm}^2 \quad (31)$$

$$+ \sum_{T \in \mathcal{T}_h^o} h_T \|\{\xi_p \cdot \mathbf{n}\}_w\|_{0,\Gamma_T}^2 \leq Ch^{2k} \|\mathbf{p}\|_{k,\Omega^+ \cup \Omega^-}^2.$$

*Proof.* We only need to show inequality (30); inequality (31) can be shown similarly. For the first term on the left-hand side of (30), by the inequality (22) from Lemma 7 we obtain

$$\begin{aligned} \|\xi_u\|_{0,T^\pm}^2 &= \|E^\pm u^\pm - \Pi E^\pm u^\pm\|_{0,T^\pm}^2 \\ &\leq \|E^\pm u^\pm - \Pi E^\pm u^\pm\|_{0,T}^2 \leq Ch^{2k+2} \|E^\pm u^\pm\|_{k+1,T}^2. \end{aligned} \quad (32)$$

Summing over all triangles, it follows by Lemma 6 that

$$\sum_{T \in \mathcal{T}_h} \|\xi_u\|_{0,T^\pm}^2 \leq Ch^{2k+2} \|u\|_{k+1,\Omega^+ \cup \Omega^-}^2. \quad (33)$$

Next, we estimate the second term on the left-hand side of (30) as follows. Suppose that  $e = T_1 \cap T_2$  with  $T_1, T_2 \in \mathcal{T}_h$ ; using the inequality (23) from Lemma 7 yields

$$\begin{aligned} \frac{1}{|e^\pm|} \|\llbracket \xi_u \rrbracket\|_{0,e^\pm}^2 &= \frac{1}{|e^\pm|} \|\llbracket E^\pm u^\pm - \Pi E^\pm u^\pm \rrbracket\|_{0,e^\pm}^2 \\ &\leq \|\llbracket E^\pm u^\pm - \Pi E^\pm u^\pm \rrbracket\|_{L^\infty(e^\pm)}^2 \\ &\leq Ch^{2k} \|E^\pm u^\pm\|_{k+1, T_1 \cup T_2}^2. \end{aligned} \quad (34)$$

Summing over all edges, using Lemma 6 implies that

$$\sum_{e \in \mathcal{E}_h} \frac{1}{|e^\pm|} \|\llbracket \xi_u \rrbracket\|_{0,e^\pm}^2 \leq Ch^{2k} \|u\|_{k+1, \Omega^+ \cup \Omega^-}^2. \quad (35)$$

Similarly, due to the inequality (24) from Lemma 7 and Lemmas 6 and 11, we find

$$\sum_{T \in \mathcal{T}_h} \frac{1}{h_T} \|\llbracket \xi_u \rrbracket\|_{0, \Gamma_T}^2 \leq Ch^{2k} \|u\|_{k+1, \Omega^+ \cup \Omega^-}^2. \quad (36)$$

Thus the inequality (30) follows combining (33)–(36), which completes the proof.  $\square$

Next we present a priori error estimate of the exact solution  $u$  in the energy norm  $\|\cdot\|_h$  and its flux  $\mathbf{p}$  in the  $L^2$ -norm.

**Theorem 13.** *Let  $(\mathbf{p}, u)$  be the solution of (3) and  $(\mathbf{p}_h, u_h)$  the solution of (16), respectively. Then, for  $(\mathbf{p}, u) \in (H^k(\Omega^+ \cup \Omega^-))^2 \times H^{k+1}(\Omega^+ \cup \Omega^-)$ , the following error estimate holds:*

$$\begin{aligned} \|\mathbf{p} - \mathbf{p}_h\|_{0, \Omega^+ \cup \Omega^-} + \|u - u_h\|_h \\ \leq Ch^k (\|\mathbf{p}\|_{k, \Omega^+ \cup \Omega^-} + \|u\|_{k+1, \Omega^+ \cup \Omega^-}). \end{aligned} \quad (37)$$

*Proof.* By using the consistency property (17), we have

$$\begin{aligned} a(\boldsymbol{\eta}_p, \mathbf{q}_h) - b(\eta_u, \mathbf{q}_h) &= a(\boldsymbol{\xi}_p, \mathbf{q}_h) - b(\xi_u, \mathbf{q}_h), \\ b(\boldsymbol{\eta}_p, v_h) + c(\eta_u, v_h) &= b(\boldsymbol{\xi}_p, v_h) + c(\xi_u, v_h). \end{aligned} \quad (38)$$

Set  $\mathbf{q}_h = \boldsymbol{\eta}_p$ ,  $v_h = \eta_u$  in (38) to give

$$\begin{aligned} a(\boldsymbol{\eta}_p, \boldsymbol{\eta}_p) + c(\eta_u, \eta_u) \\ = a(\boldsymbol{\xi}_p, \boldsymbol{\eta}_p) - b(\xi_u, \boldsymbol{\eta}_p) + b(\boldsymbol{\xi}_p, \eta_u) + c(\xi_u, \eta_u). \end{aligned} \quad (39)$$

Using (31) in Lemma 12 and  $\varepsilon$ -Cauchy-Schwartz inequality, we estimate the first term on the right-hand side of (39) as

$$\begin{aligned} a(\boldsymbol{\xi}_p, \boldsymbol{\eta}_p) &= \sum_{T \in \mathcal{T}_h} \langle \boldsymbol{\xi}_p, \boldsymbol{\eta}_p \rangle_T = \sum_{T \in \mathcal{T}_h} (\boldsymbol{\xi}_p, \boldsymbol{\eta}_p)_{T^\pm} \\ &\leq \left( \sum_{T \in \mathcal{T}_h} \|\boldsymbol{\xi}_p\|_{0, T^\pm}^2 \right)^{1/2} \left( \sum_{T \in \mathcal{T}_h} \|\boldsymbol{\eta}_p\|_{0, T^\pm}^2 \right)^{1/2} \\ &\leq Ch^{2k} \|\mathbf{p}\|_{k, \Omega^+ \cup \Omega^-}^2 + \varepsilon \sum_{T \in \mathcal{T}_h} \|\boldsymbol{\eta}_p\|_{0, T^\pm}^2. \end{aligned} \quad (40)$$

For the second term on the right-hand side of (39), by using (30) in Lemma 12 and trace inequalities from Lemmas 8 and 10, we obtain

$$\begin{aligned} b(\xi_u, \boldsymbol{\eta}_p) &= \sum_{T \in \mathcal{T}_h} \langle \boldsymbol{\eta}_p, \nabla \xi_u \rangle_T - \sum_{e \in \mathcal{E}_h} \langle \{\{\boldsymbol{\eta}_p\}\}_w, \llbracket \xi_u \rrbracket \rangle_e \\ &\quad - \sum_{T \in \mathcal{T}_h^o} (\{\boldsymbol{\eta}_p \cdot \mathbf{n}\}_w, [\xi_u])_{\Gamma_T} \\ &= \sum_{T \in \mathcal{T}_h} (\boldsymbol{\eta}_p, \nabla \xi_u)_{T^\pm} - \sum_{e \in \mathcal{E}_h} (\{\{\boldsymbol{\eta}_p\}\}_w, \llbracket \xi_u \rrbracket)_{e^\pm} \\ &\quad - \sum_{T \in \mathcal{T}_h^o} (\{\boldsymbol{\eta}_p \cdot \mathbf{n}\}_w, [\xi_u])_{\Gamma_T} \\ &\leq \left( \sum_{T \in \mathcal{T}_h} \|\boldsymbol{\eta}_p\|_{0, T^\pm}^2 \right)^{1/2} \left( \sum_{T \in \mathcal{T}_h} \|\nabla \xi_u\|_{0, T^\pm}^2 \right)^{1/2} \\ &\quad + \left( \sum_{e \in \mathcal{E}_h} |e^\pm| \|\{\{\boldsymbol{\eta}_p\}\}_w\|_{0, e^\pm}^2 \right)^{1/2} \\ &\quad \times \left( \sum_{e \in \mathcal{E}_h} \frac{1}{|e^\pm|} \|\llbracket \xi_u \rrbracket\|_{0, e^\pm}^2 \right)^{1/2} \\ &\quad + \left( \sum_{T \in \mathcal{T}_h^o} h_T \|\{\boldsymbol{\eta}_p \cdot \mathbf{n}\}_w\|_{0, \Gamma_T}^2 \right)^{1/2} \left( \sum_{T \in \mathcal{T}_h^o} \frac{1}{h_T} \|\llbracket \xi_u \rrbracket\|_{0, \Gamma_T}^2 \right)^{1/2} \\ &\leq Ch^{2k} \|u\|_{k+1, \Omega^+ \cup \Omega^-}^2 + \varepsilon \sum_{T \in \mathcal{T}_h} \|\boldsymbol{\eta}_p\|_{0, T^\pm}^2. \end{aligned} \quad (41)$$

Similarly, by using the approximate estimation (31), the third term on (39) can be estimated as

$$\begin{aligned} b(\boldsymbol{\xi}_p, \eta_u) &= \sum_{T \in \mathcal{T}_h} \langle \boldsymbol{\xi}_p, \nabla \eta_u \rangle_T - \sum_{e \in \mathcal{E}_h} \langle \{\{\boldsymbol{\xi}_p\}\}_w, \llbracket \eta_u \rrbracket \rangle_e \\ &\quad - \sum_{T \in \mathcal{T}_h^o} (\{\boldsymbol{\xi}_p \cdot \mathbf{n}\}_w, [\eta_u])_{\Gamma_T} \\ &= \sum_{T \in \mathcal{T}_h} (\boldsymbol{\xi}_p, \nabla \eta_u)_{T^\pm} - \sum_{e \in \mathcal{E}_h} (\{\{\boldsymbol{\xi}_p\}\}_w, \llbracket \eta_u \rrbracket)_{e^\pm} \\ &\quad - \sum_{T \in \mathcal{T}_h^o} (\{\boldsymbol{\xi}_p \cdot \mathbf{n}\}_w, [\eta_u])_{\Gamma_T} \\ &\leq \left( \sum_{T \in \mathcal{T}_h} \|\boldsymbol{\xi}_p\|_{0, T^\pm}^2 \right)^{1/2} \left( \sum_{T \in \mathcal{T}_h} \|\nabla \eta_u\|_{0, T^\pm}^2 \right)^{1/2} \\ &\quad + \left( \sum_{e \in \mathcal{E}_h} |e^\pm| \|\{\{\boldsymbol{\xi}_p\}\}_w\|_{0, e^\pm}^2 \right)^{1/2} \\ &\quad \times \left( \sum_{e \in \mathcal{E}_h} \frac{1}{|e^\pm|} \|\llbracket \eta_u \rrbracket\|_{0, e^\pm}^2 \right)^{1/2} \\ &\quad + \left( \sum_{T \in \mathcal{T}_h^o} h_T \|\{\boldsymbol{\xi}_p \cdot \mathbf{n}\}_w\|_{0, \Gamma_T}^2 \right)^{1/2} \end{aligned}$$

$$\begin{aligned}
& \times \left( \sum_{T \in \mathcal{T}_h^o} \frac{1}{h_T} \|\llbracket \eta_u \rrbracket\|_{0,\Gamma_T}^2 \right)^{1/2} \\
& \leq Ch^{2k} \|\mathbf{p}\|_{k,\Omega^+ \cup \Omega^-}^2 \\
& + \varepsilon \left( \sum_{e \in \mathcal{E}_h} \frac{1}{|e^\pm|} \|\llbracket \eta_u \rrbracket\|_{0,e^\pm}^2 + \sum_{T \in \mathcal{T}_h^o} \frac{1}{h_T} \|\llbracket \eta_u \rrbracket\|_{0,\Gamma_T}^2 \right. \\
& \quad \left. + \sum_{T \in \mathcal{T}_h} \|\nabla \eta_u\|_{0,T^\pm}^2 \right). \tag{42}
\end{aligned}$$

Then, by virtue of inequality (30) in Lemma 12, we bound the fourth term on (39) as

$$\begin{aligned}
c(\xi_u, \eta_u) &= \sum_{e \in \mathcal{E}_h} \left\langle \frac{\gamma}{|e^\pm|} \llbracket \xi_u \rrbracket, \llbracket \eta_u \rrbracket \right\rangle_e + \sum_{T \in \mathcal{T}_h^o} \frac{\gamma}{h_T} (\llbracket \xi_u \rrbracket, \llbracket \eta_u \rrbracket)_{\Gamma_T} \\
&= \sum_{e \in \mathcal{E}_h} \left( \frac{\gamma}{|e^\pm|} \llbracket \xi_u \rrbracket, \llbracket \eta_u \rrbracket \right)_{e^\pm} + \sum_{T \in \mathcal{T}_h^o} \frac{\gamma}{h_T} (\llbracket \xi_u \rrbracket, \llbracket \eta_u \rrbracket)_{\Gamma_T} \\
&\leq \left( \sum_{e \in \mathcal{E}_h} \frac{\gamma}{|e^\pm|} \|\llbracket \xi_u \rrbracket\|_{0,e^\pm}^2 \right)^{1/2} \\
&\quad \times \left( \sum_{e \in \mathcal{E}_h} \frac{\gamma}{|e^\pm|} \|\llbracket \eta_u \rrbracket\|_{0,e^\pm}^2 \right)^{1/2} \\
&\quad + \left( \sum_{T \in \mathcal{T}_h^o} \frac{\gamma}{h_T} \|\llbracket \xi_u \rrbracket\|_{0,\Gamma_T}^2 \right)^{1/2} \\
&\quad \times \left( \sum_{T \in \mathcal{T}_h^o} \frac{\gamma}{h_T} \|\llbracket \eta_u \rrbracket\|_{0,\Gamma_T}^2 \right)^{1/2} \\
&\leq Ch^{2k} \|u\|_{k+1,\Omega^+ \cup \Omega^-}^2 + \varepsilon c(\eta_u, \eta_u). \tag{43}
\end{aligned}$$

Thus, combining (39)–(43) yields

$$\begin{aligned}
& a(\boldsymbol{\eta}_p, \boldsymbol{\eta}_p) + c(\eta_u, \eta_u) \\
& \leq Ch^{2k} (\|\mathbf{p}\|_{k,\Omega^+ \cup \Omega^-}^2 + \|u\|_{k+1,\Omega^+ \cup \Omega^-}^2) \\
& \quad + \varepsilon \sum_{T \in \mathcal{T}_h} \|\nabla \eta_u\|_{0,T^\pm}^2. \tag{44}
\end{aligned}$$

By using the triangle inequality, we have

$$\begin{aligned}
& \|\mathbf{p} - \mathbf{p}_h\|_{0,\Omega^+ \cup \Omega^-}^2 + c(\eta_u, \eta_u) \\
& \leq Ch^{2k} (\|\mathbf{p}\|_{k,\Omega^+ \cup \Omega^-}^2 + \|u\|_{k+1,\Omega^+ \cup \Omega^-}^2) + \varepsilon \sum_{T \in \mathcal{T}_h} \|\nabla \eta_u\|_{0,T^\pm}^2. \tag{45}
\end{aligned}$$

At the other hand, setting  $\mathbf{q}_h = \nabla \eta_u$  in the first equality of (38), we obtain

$$a(\boldsymbol{\eta}_p, \nabla \eta_u) - b(\eta_u, \nabla \eta_u) = a(\boldsymbol{\xi}_p, \nabla \eta_u) - b(\xi_u, \nabla \eta_u). \tag{46}$$

By the definition of  $b(\cdot, \cdot)$ , an integration by parts implies that

$$\begin{aligned}
\sum_{T \in \mathcal{T}_h} \|\nabla \eta_u\|_{0,T^\pm}^2 &= a(\mathbf{p} - \mathbf{p}_h, \nabla \eta_u) + b(\xi_u, \nabla \eta_u) \\
& \quad + \sum_{e \in \mathcal{E}_h} \langle \{\{\nabla \eta_u\}\}_w, \llbracket \eta_u \rrbracket \rangle_e \\
& \quad + \sum_{T \in \mathcal{T}_h^o} (\{\nabla \eta_u \cdot \mathbf{n}\}_w, \llbracket \eta_u \rrbracket)_{\Gamma_T}. \tag{47}
\end{aligned}$$

Using Lemmas 8 and 10 yields

$$\begin{aligned}
\sum_{T \in \mathcal{T}_h} \|\nabla \eta_u\|_{0,T^\pm}^2 &\leq C \|\mathbf{p} - \mathbf{p}_h\|_{0,\Omega^+ \cup \Omega^-}^2 \\
& \quad + Ch^{2k} \|u\|_{k+1,\Omega^+ \cup \Omega^-} + c(\eta_u, \eta_u) \\
& \quad + \varepsilon \sum_{T \in \mathcal{T}_h} \|\nabla \eta_u\|_{0,T^\pm}^2. \tag{48}
\end{aligned}$$

Combining (45) and (48), choosing  $\varepsilon$  enough small, from the definition  $\|\cdot\|_h$  and the triangle inequality, we can arrive at

$$\begin{aligned}
& \|\mathbf{p} - \mathbf{p}_h\|_{0,\Omega^+ \cup \Omega^-}^2 + \|u - u_h\|_h^2 \\
& \leq Ch^{2k} (\|\mathbf{p}\|_{k,\Omega^+ \cup \Omega^-}^2 + \|u\|_{k+1,\Omega^+ \cup \Omega^-}^2), \tag{49}
\end{aligned}$$

which completes the proof.  $\square$

Using the standard duality argument, we can obtain the following error estimate in the  $L^2$  norm.

**Theorem 14.** *Under the condition of Theorem 13, we have*

$$\|u - u_h\|_{0,\Omega^+ \cup \Omega^-} \leq Ch^{k+1} (\|\mathbf{p}\|_{k,\Omega^+ \cup \Omega^-} + \|u\|_{k+1,\Omega^+ \cup \Omega^-}). \tag{50}$$

*Proof.* Consider the following so-called adjoint problem

$$\begin{aligned}
-\nabla \cdot (\beta \nabla \phi) &= u - u_h \quad \text{in } \Omega_1 \cup \Omega_2, \\
\phi &= 0 \quad \text{on } \partial\Omega, \\
[\phi] &= 0 \quad \text{on } \Gamma, \\
\left[ \beta \frac{\partial \phi}{\partial \mathbf{n}} \right] &= 0 \quad \text{on } \Gamma. \tag{51}
\end{aligned}$$

Using Theorem 1, we get

$$\|\phi\|_{2,\Omega^+ \cup \Omega^-} \leq C \|u - u_h\|_{0,\Omega^+ \cup \Omega^-}. \tag{52}$$

By introducing an auxiliary variable  $\mathbf{q} = \beta \nabla \phi$ , we obtain

$$\begin{aligned}
\frac{1}{\beta} \mathbf{q} &= \nabla \phi \quad \text{in } \Omega^+ \cup \Omega^-, \\
-\nabla \cdot \mathbf{q} &= u - u_h \quad \text{in } \Omega^+ \cup \Omega^-, \\
\phi &= 0 \quad \text{on } \partial\Omega, \\
[\phi] &= 0 \quad \text{on } \Gamma, \\
[\mathbf{q} \cdot \mathbf{n}] &= 0 \quad \text{on } \Gamma. \tag{53}
\end{aligned}$$

Since  $[\phi] = 0$  on  $\Gamma$  and  $[[\phi]] = 0$  on  $\mathcal{E}_h$ , using integration by parts and the consistency property (17), we deduce

$$\begin{aligned}
\|u - u_h\|_{0,\Omega^+\cup\Omega^-}^2 &= (u - u_h, u - u_h) \\
&= a(\mathbf{q}, \mathbf{p} - \mathbf{p}_h) - b(\phi, \mathbf{p} - \mathbf{p}_h) \\
&\quad + b(u - u_h, \mathbf{q}) + c(\phi, u - u_h) \\
&= \sum_{T \in \mathcal{T}_h} \left\langle \frac{1}{\beta} \xi_{\mathbf{q}}, \mathbf{p} - \mathbf{p}_h \right\rangle_T \\
&\quad - \sum_{T \in \mathcal{T}_h} \langle \nabla \xi_{\phi}, \mathbf{p} - \mathbf{p}_h \rangle_T \\
&\quad + \sum_{e \in \mathcal{E}_h} \langle \{\{\mathbf{p} - \mathbf{p}_h\}\}_w, [[\xi_{\phi}]] \rangle_e \\
&\quad + \sum_{T \in \mathcal{T}_h^o} (\{\{\mathbf{p} - \mathbf{p}_h\} \cdot \mathbf{n}\}_w, [\xi_{\phi}])_{\Gamma_T} \\
&\quad + \sum_{T \in \mathcal{T}_h} \langle \xi_{\mathbf{q}}, \nabla(u - u_h) \rangle_T \\
&\quad - \sum_{e \in \mathcal{E}_h} \langle \{\{\xi_{\mathbf{q}}\}\}_w, [[u - u_h]] \rangle_e \\
&\quad - \sum_{T \in \mathcal{T}_h^o} (\{\{\xi_{\mathbf{q}} \cdot \mathbf{n}\}_w, [u - u_h])_{\Gamma_T} \\
&\quad + \sum_{e \in \mathcal{E}_h} \left\langle \frac{1}{|e^{\pm}|} [[\xi_{\phi}]], [[u - u_h]] \right\rangle_e \\
&\quad + \sum_{T \in \mathcal{T}_h^o} \frac{1}{h_T} ([\xi_{\phi}], [u - u_h])_{\Gamma_T} \\
&= \sum_{i=1}^9 E_i.
\end{aligned} \tag{54}$$

Due to  $\mathbf{q} = \beta \nabla \phi$ , as in the proof of Theorem 13, an application of Theorem 1 implies that

$$\begin{aligned}
|E_1| + |E_2| + \sum_{i=5}^9 |E_i| \\
\leq Ch \|\phi\|_{2,\Omega^+\cup\Omega^-} (\|\mathbf{p} - \mathbf{p}_h\|_{0,\Omega^+\cup\Omega^-} + \|u - u_h\|_h).
\end{aligned} \tag{55}$$

Now we estimate  $E_3$  as follows:

$$\begin{aligned}
E_3 &= \sum_{e \in \mathcal{E}_h} \langle \{\{\xi_{\mathbf{p}}\}\}_w, [[\xi_{\phi}]] \rangle_e + \sum_{e \in \mathcal{E}_h} \langle \{\{\eta_{\mathbf{p}}\}\}_w, [[\xi_{\phi}]] \rangle_e \\
&= \left( \sum_{e \in \mathcal{E}_h} |e^{\pm}| \|\{\{\xi_{\mathbf{p}}\}\}_w\|_{0,e^{\pm}}^2 \right)^{1/2} \left( \sum_{e \in \mathcal{E}_h} \frac{1}{|e^{\pm}|} \|[[\xi_{\phi}]]\|_{0,e^{\pm}}^2 \right)^{1/2} \\
&\quad + \left( \sum_{e \in \mathcal{E}_h} |e^{\pm}| \|\{\{\eta_{\mathbf{p}}\}\}_w\|_{0,e^{\pm}}^2 \right)^{1/2} \left( \sum_{e \in \mathcal{E}_h} \frac{1}{|e^{\pm}|} \|[[\xi_{\phi}]]\|_{0,e^{\pm}}^2 \right)^{1/2} \\
&\leq Ch (h^k \|\mathbf{p}\|_{k,\Omega^+\cup\Omega^-} + \|\mathbf{p} - \mathbf{p}_h\|_{0,\Omega^+\cup\Omega^-}) \|\phi\|_{2,\Omega^+\cup\Omega^-}.
\end{aligned} \tag{56}$$

Similarly,

$$|E_4| \leq Ch (h^k \|\mathbf{p}\|_{k,\Omega^+\cup\Omega^-} + \|\mathbf{p} - \mathbf{p}_h\|_{0,\Omega^+\cup\Omega^-}) \|\phi\|_{2,\Omega^+\cup\Omega^-}. \tag{57}$$

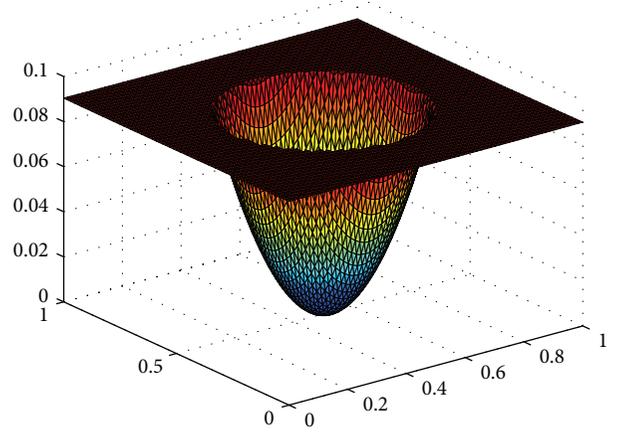


FIGURE 2: The numerical solution on a  $64 \times 64$  uniform mesh for  $\beta_1 : \beta_2 = 1 : 1000$ .

We now combine (54)–(57) and use (52) and Theorem 13 to obtain

$$\|u - u_h\|_{0,\Omega^+\cup\Omega^-} \leq Ch^{k+1} (\|\mathbf{p}\|_{k,\Omega^+\cup\Omega^-} + \|u\|_{k+1,\Omega^+\cup\Omega^-}), \tag{58}$$

which completes the proof.  $\square$

## 4. Numerical Experiments

In this section, we consider the following nontrivial example with a homogeneous jump condition (from [10, 13]). The exact solution is given by

$$u(x, y) = \begin{cases} r^2 & \text{if } r \leq r_0, \\ \frac{r^2}{\beta_2} - \frac{r_0^2}{\beta_2} + \frac{r_0^2}{\beta_1}, & \text{if } r > r_0, \end{cases} \tag{59}$$

where  $r = \sqrt{(x - 0.5)^2 + (y - 0.5)^2}$ , and on the domain  $\Omega = (0, 1) \times (0, 1)$  we choose  $r_0 = 0.3$ . A simple calculation shows that  $\mathbf{p}(x, y) = (x, y)^T$ .

We compute the order of convergence for  $e_u = u - u_h$  and  $\mathbf{e}_p = \mathbf{p} - \mathbf{p}_h$ , when piecewise linear polynomials are used to approximate  $u$  and  $\mathbf{p}$ , respectively. In Figure 2, we plot the numerical solution for this example on a  $64 \times 64$  uniform mesh for  $\beta_1 : \beta_2 = 1 : 1000$ . Figures 3, 4, 5, and 6 show the computed order of convergence for  $\|e_u\|_{0,\Omega_1 \cup \Omega_2}$  and  $\|\mathbf{e}_p\|_{0,\Omega_1 \cup \Omega_2}$  when the jump in the coefficient is taken as  $\beta_1 : \beta_2 = 1 : 10, 1 : 1000, 10 : 1, 1000 : 1$ , respectively, in the log-log scale. These computed results coincide with the theoretical results in Theorems 13 and 14.

## 5. Conclusions

In this paper, we have discussed an unfitted discontinuous Galerkin method for elliptic problems with a smooth interface. Based on a variant of local discontinuous Galerkin method, we have obtained the optimal order error estimates

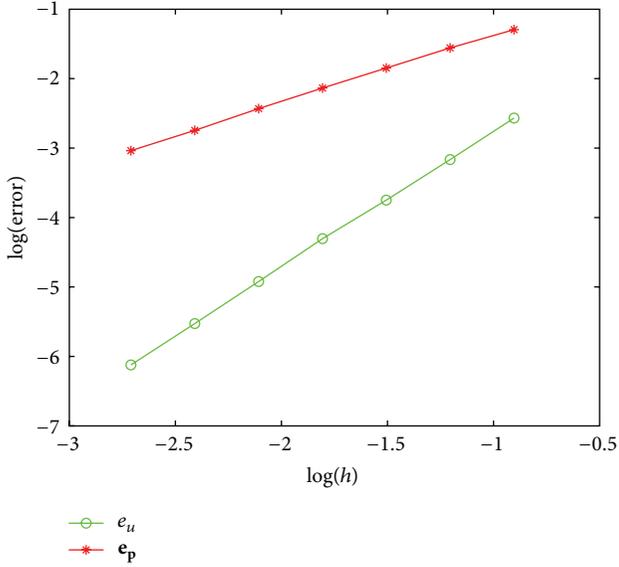


FIGURE 3: The convergence rates of  $L^2$  norm in the exact  $u$  and its flux  $\mathbf{p}$  for  $\beta_1 : \beta_2 = 1 : 10$ .

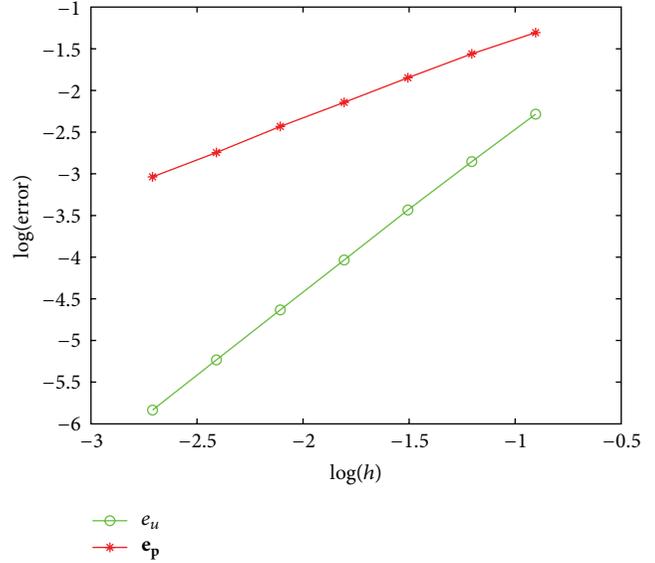


FIGURE 5: The convergence rates of  $L^2$  norm in the exact  $u$  and its flux  $\mathbf{p}$  for  $\beta_1 : \beta_2 = 10 : 1$ .

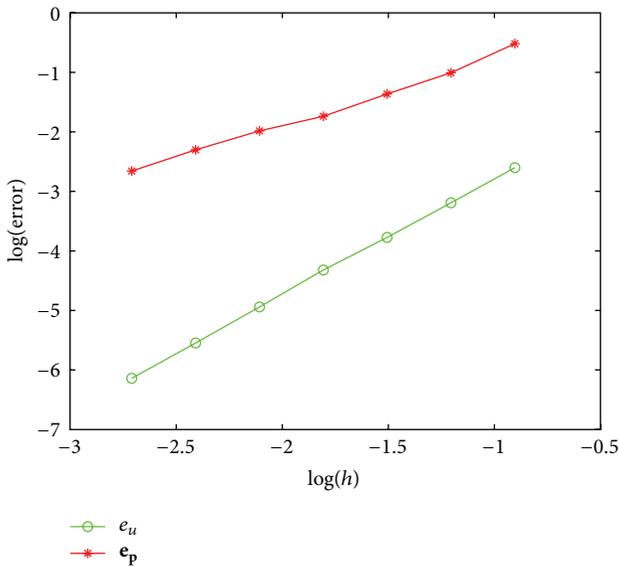


FIGURE 4: The convergence rates of  $L^2$  norm in the exact  $u$  and its flux  $\mathbf{p}$  for  $\beta_1 : \beta_2 = 1 : 1000$ .

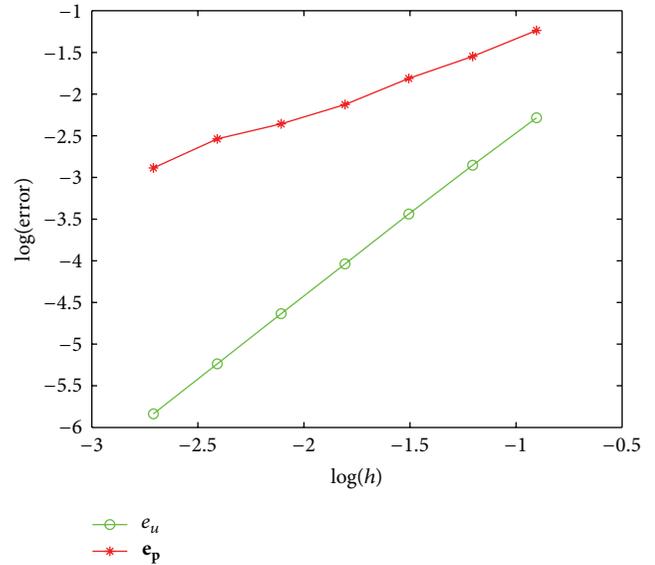


FIGURE 6: The convergence rates of  $L^2$  norm in the exact  $u$  and its flux  $\mathbf{p}$  for  $\beta_1 : \beta_2 = 1000 : 1$ .

in the energy norm in  $u$  and its flux  $\mathbf{p}$ . And by using the standard duality argument the optimal convergence rate in  $L^2$  norm for  $u$  has also been derived. These presented results are the same as that of elliptic problems without interface. Finally, numerical experiments are given to confirm our theoretical results. We note that the convergence behavior in most existing works concerning the elliptic interface problems depends on the jump in the discontinuous coefficients. It will be one of our future subjects to design an efficient numerical scheme that is robust with respect to the jump in the discontinuous coefficients.

### Conflict of Interests

The authors declare that there is no conflict of interests regarding the publication of this paper.

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